



Complexity Bounds for Ordinal-Based Termination

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OUTLINE

termination proofs using ranking functions into ordinals

complexity bounds on termination times

- ▶ exact bounds
- ▶ “simple” case compared to well-quasi-orders

application: VAS Reachability



TERMINATION PROOFS

multiset path orderings for term rewriting systems

lexicographic path orderings for term rewriting systems

size-change abstractions for first-order programs

disjunctive termination arguments (aka Ramsey-based)

ranking functions



COMPLEXITY FROM TERMINATION PROOFS

multiset path orderings for term rewriting systems

Hofbauer (1992): primitive-recursive

lexicographic path orderings for term rewriting systems

Weiermann (1995): multiply-recursive

size-change abstractions for first-order programs

Ben-Amram (2002): multiply-recursive

disjunctive termination arguments (aka Ramsey-based)

Figueira et al. (2011): primitive-recursive

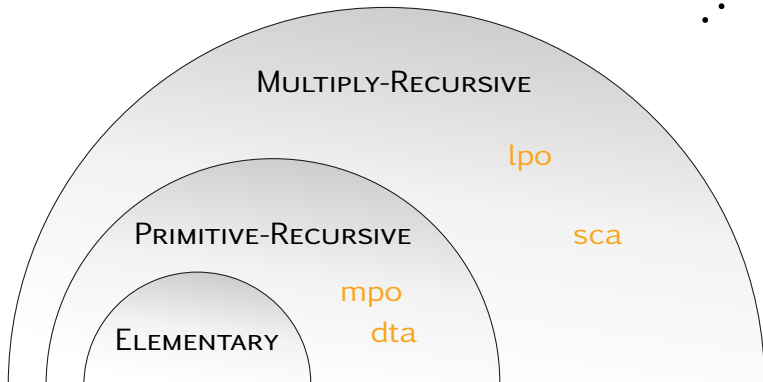
also Berardi, Oliva, and Steila (2014) **tomorrow morning**

ranking functions **this talk**



COMPLEXITY CLASSIFICATION

Hofbauer (1992); Weiermann (1995); Ben-Amram (2002); Figueira et al. (2011); Berardi et al. (2014)





RANKING FUNCTIONS

Turing (1949)

“Finally the checker has to verify that the process comes to an end. Here again he should be assisted by the programmer giving a further definite assertion to be verified. This may take the form of **a quantity which is asserted to decrease continually and vanish when the machine stops.**”



Source: Beryl Turing and King's College Library, Cambridge



RANKING FUNCTIONS

operational semantics of programs using
transition systems $\mathcal{S} = \langle \text{Conf}, \rightarrow_{\mathcal{S}} \rangle$

well-order (wo) $\langle A, \leq \rangle$, aka well-founded linear
order: no infinite decreasing sequence
 $x_0 > x_1 > \dots$ over A , e.g.

- ▶ $\langle \mathbb{N}, \leq \rangle$
- ▶ $\langle A \times B, \leq_{\text{lex}} \rangle$ for wo's $\langle A, \leq_A \rangle$ and $\langle B, \leq_B \rangle$, where $(n, m) \leq_{\text{lex}} (n', m')$ iff $n <_A n' \vee (n = n' \wedge m \leq_B m')$



RANKING FUNCTIONS

operational semantics of programs using
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well-order (wo) $\langle A, \leq \rangle$, aka well-founded linear
order: no infinite decreasing sequence
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ranking function $f: \text{Conf} \rightarrow A$:
 $c \rightarrow_{\mathcal{S}} c'$ implies $f(c) > f(c')$



EXAMPLE

Program:

```
 $\ell_0$ : while x  $\geq$  0 and y > 0 do  
  if x > 0 then  
    a: x := x-1; n := 2n;  
  else  
    b: x := n; y := y-1; n := 2n;  
done
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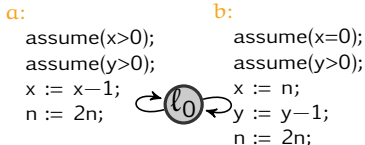


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Program:

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l0: while x >= 0 and y > 0 do
  if x > 0 then
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Transition system:





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l0: while x >= 0 and y > 0 do
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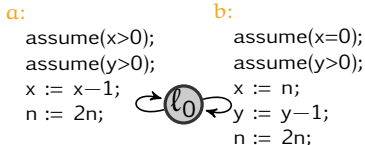
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Ranking function:

$$f: \{l_0\} \times \mathbb{Z}^3 \rightarrow \langle \mathbb{N}^2, \leq_{\text{lex}} \rangle$$

$$f(l_0, x, y, n) = (y, x)$$

Transition system:





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 n := 2n;

Termination time:

steps	x	y	n
	3	3	3
a a a	0	3	$2^3 \cdot 3$
b	$2^3 \cdot 3$	2	$2^4 \cdot 3 = 48$
a $2^{2^3 \cdot 3}$	0	2	$2^{2^{2^3 \cdot 3}} \cdot 48$
b	$2^{2^3 \cdot 3} \cdot 48$	1	$2^{2^{2^3 \cdot 3}} \cdot 96$
a $2^{2^{2^3 \cdot 3} \cdot 48}$	0	1	...
b	...	0	...



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Termination time:

non-elementary

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“Finally the checker has to verify that the process comes to an end. Here again he should be assisted by the programmer giving a further definite assertion to be verified. This may take the form of a quantity which is asserted to decrease continually and vanish when the machine stops. To the pure mathematician it is natural to give an **ordinal number**.”



Source: Beryl Turing and King's College Library, Cambridge



ORDINALS

- ▶ isomorphism classes of wo's

$$o(\langle \mathbb{N}, \leq \rangle) = \omega$$

$$o(\langle A \times B, \leq_{\text{lex}} \rangle) = o(\langle A, \leq_A \rangle) \cdot o(\langle B, \leq_B \rangle)$$

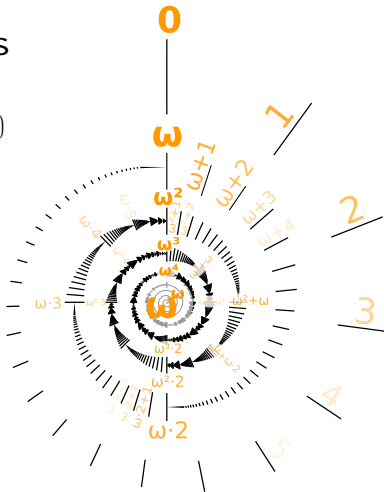
- ▶ set-theoretic construction

$$\alpha = \{\beta \mid \beta < \alpha\}$$

- ▶ Cantor normal form (CNF) below ε_0

$$\alpha = \omega^{\alpha_1} \cdot c_1 + \dots + \omega^{\alpha_m} \cdot c_m$$

with $\alpha > \alpha_1 > \dots > \alpha_m$ and
 $0 < c_1, \dots, c_m < \omega$



Public domain image (source: Wikipedia)



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$$f: \{\ell_0\} \times \mathbb{Z}^3 \rightarrow \omega^2$$

$$f(\ell_0, x, y, n) = \omega \cdot y + x$$



COMPLEXITY BOUNDS

- ▶ the existence of a ranking function $f: Conf \rightarrow \alpha$ proves termination
- ▶ two main ingredients:
 - ▶ the ordinal α used as range
 - ▶ the function f itself
- ▶ goal: bound the length of program executions
- ▶ idea: bound the length of decreasing sequences in α



THE LENGTH OF DECREASING SEQUENCES

- ▶ no upper bound in general
e.g. in $\langle \mathbb{N}, \leq \rangle$:

$$N > N - 1 > N - 2 > \dots > 1 > 0$$

- ▶ even with a bound on the first element
e.g. in $\langle \mathbb{N}^2, \leq_{\text{lex}} \rangle$:

$$(1, 1) > (1, 0) > (0, N) > \dots > (0, 1) > (0, 0)$$



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$$\begin{array}{ccccccccccc} (1,1) & > & (1,0) & > & (0,N) & > & \dots & > & (0,1) & > & (0,0) \\ \omega + 1 & > & \omega & > & N & > & \dots & > & 1 & > & 0 \end{array}$$



ORDINAL NORM

Buchholz et al. (1994)

$$N(\omega^{\alpha_1} \cdot c_1 + \dots + \omega^{\alpha_m} \cdot c_m) = \max_{1 \leq i \leq m} (\max(N(\alpha_i), c_i))$$

In the case of ω^d , corresponds to infinite norm over \mathbb{N}^d :

$$\|(c_1, \dots, c_d)\|_{\infty} = \max_{1 \leq i \leq d} c_i$$



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CONTROLLED SEQUENCES

- ▶ $g: \mathbb{N} \rightarrow \mathbb{N}$ monotone a **control function**
- ▶ $n_0 \in \mathbb{N}$ an **initial norm** and $\iota: Conf \rightarrow \mathbb{N}$ a **norm function** on configurations
- ▶ a sequence β_0, β_1, \dots over α is (g, n_0) -controlled if

$$\forall i. N(\beta_i) \leq g^i(n_0)$$

- ▶ $f: Conf \rightarrow \alpha$ is (ι, g) -controlled if, for every execution $c_0 \rightarrow_s c_1 \rightarrow_s \dots$ in $\langle Conf, \rightarrow_s \rangle$, the sequence $f(c_0), f(c_1), \dots$ is $(\iota(c_0), g)$ -controlled, i.e. if

$$\forall i. N(f(c_i)) \leq g^i(\iota(c_0))$$



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Ranking function:

$$f: \{\ell_0\} \times \mathbb{Z}^3 \rightarrow \omega^2$$

$$f(\ell_0, x, y, n) = \omega \cdot y + x$$

Control:

$$\iota(\ell_0, x, y, n) = \max(x, y, n)$$

$$g(x) = 2x$$



LENGTH FUNCTIONS

- ▶ (g, n_0) -controlled decreasing sequences over α are bounded; we note their maximal length $L_{\alpha, g}(n_0)$
- ▶ Descent Equation

$$L_{\alpha, g}(n) = \max_{\beta < \alpha, N(\beta) \leq n} 1 + L_{\beta, g}(g(n))$$

Proof idea.

Let $\beta_0 > \beta_1 > \beta_2 > \dots$ be (g, n) -controlled over α . Then $\beta_1 > \beta_2 > \dots$ is $(g, g(n))$ -controlled over β_0 . The longest sequence is thus obtained by maximising $\beta_0 < \alpha$ among those with $N(\beta_0) \leq n$. \square



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SUBRECURSIVE FUNCTIONS

- ▶ goal: obtain explicit bounds for $L_{\alpha,g}$
- ▶ goal: classification in complexity hierarchies
- ▶ use subrecursive functions indexed with ordinal numbers

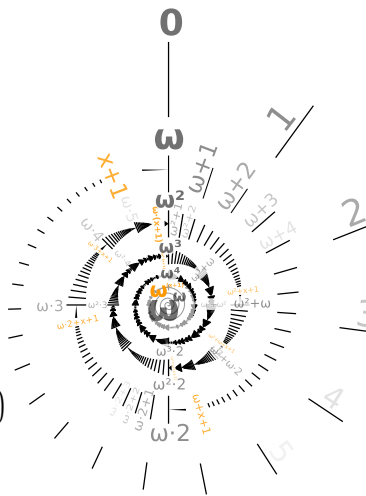


FUNDAMENTAL SEQUENCES

- ▶ for limit ordinals
 $\lambda = \gamma + \omega^\beta$ for $\beta > 0$.
- ▶ sequence $(\lambda(x))_{x < \omega}$ s.t.
 $\forall x. \lambda(x) < \lambda$ and
 $\sup_x \lambda(x) = \lambda$
- ▶ syntactic definition on Cantor normal forms:

$$(\gamma + \omega^{\beta+1})(x) = \gamma + \omega^\beta \cdot (x + 1)$$

$$(\gamma + \omega^\lambda)(x) = \gamma + \omega^{\lambda(x)}$$





HARDY HIERARCHY

- ▶ fix $h: \mathbb{N} \rightarrow \mathbb{N}$ monotone.
- ▶ **Hardy hierarchy** $(h^\alpha: \mathbb{N} \rightarrow \mathbb{N})_\alpha$
 $h^0(x) = x$, $h^{\alpha+1}(x) = h^\alpha(h(x))$, $h^\lambda(x) = h^{\lambda(x)}(x)$.
- ▶ “transfinite iteration”
- ▶ examples for $H(x) = x + 1$:
 $H^k(x) = x + k$, $H^\omega(x) = 2x + 1$,
 $H^{\omega^2}(x) = 2^{x+1} \cdot (x + 1) - 1$,
 $H^{\omega^3} \approx \text{tower}$, $H^{\omega^\omega} \approx \text{ackermann}$



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CICHOŃ HIERARCHY

Cichoń and Tahhan Bittar (1998)

- ▶ **Cichoń hierarchy** $(h_\alpha: \mathbb{N} \rightarrow \mathbb{N})_\alpha$

$$h_0(x) = 0, \quad h_{\alpha+1}(x) = 1 + h_\alpha(h(x)), \quad h_\lambda(x) = h_{\lambda(x)}(x)$$

- ▶ “counts” iterations in Hardy functions:

$$h^\alpha(x) = h^{h_\alpha(x)}(x)$$

- ▶ for h strictly monotone,

$$h_\alpha(x) \leq h^\alpha(x) + x$$



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In the case of ω^d , corresponds to infinite norm over \mathbb{N}^d :

$$\|(c_1, \dots, c_d)\|_{\infty} = \max_{1 \leq i \leq d} c_i$$

Monotonicity: if $N(\beta) \leq x$ and $\beta < \beta'$, then

$$h_{\beta}(x) \leq h_{\beta'}(x) \quad h^{\beta}(x) \leq h^{\beta'}(x)$$



PREDECESSORS

- ▶ of ordinals > 0 :

$$P_x(\alpha + 1) = \alpha, \quad P_x(\lambda) = P_x(\lambda(x)).$$

- ▶ for $\alpha > 0$:

$$h_\alpha(x) = 1 + h_{P_x(\alpha)}(h(x)).$$

- ▶ if $N(\alpha) \leq x$, then

$$P_x(\alpha) = \max\{\beta < \alpha \mid N(\beta) \leq x\}$$

- ▶ if $N(\alpha) \leq x$, then

$$h_\alpha(x) = \max_{\beta < \alpha, N(\beta) \leq x} 1 + h_\beta(h(x))$$



PREDECESSORS

- ▶ of ordinals > 0 :

$$P_x(\alpha + 1) = \alpha, \quad P_x(\lambda) = P_x(\lambda(x)).$$

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LENGTH FUNCTION THEOREM

Theorem

If $N(\alpha) \leq n$, then $L_{\alpha,g}(n) = g_{\alpha}(n)$.

Corollary

If $f: Conf \rightarrow \alpha$ is a (ι, g) -controlled ranking function for $\mathcal{S} = \langle Conf, \rightarrow_{\mathcal{S}} \rangle$, and c_0 is an initial configuration in $Conf$, then \mathcal{S} terminates from c_0 in time $O(g_{\alpha}(\iota(c_0)))$.



EXAMPLE

Program:

```
 $\ell_0$ : while x >= 0 and y > 0 do
  if x > 0 then
    a: x := x-1; n := 2n;
  else
    b: x := n; y := y-1; n := 2n;
done
```

Ranking function:

$$f: \{\ell_0\} \times \mathbb{Z}^3 \rightarrow \omega^2$$

$$f(\ell_0, x, y, n) = \omega \cdot y + x$$

Control:

$$\iota(\ell_0, x, y, n) = \max(x, y, n)$$

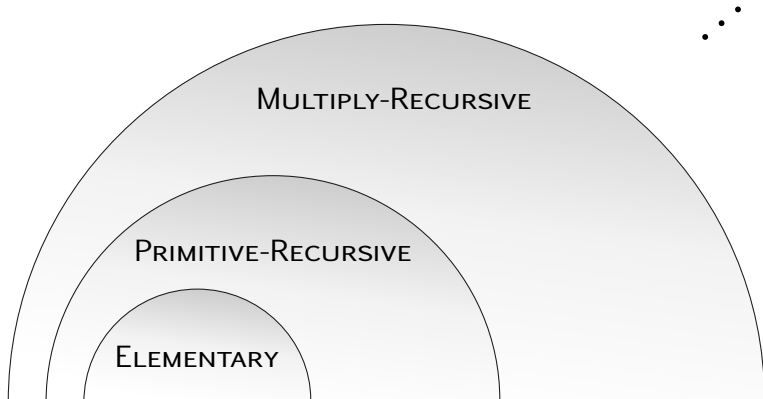
$$g(x) = 2x$$

Actual complexity:

$$g_{\omega \cdot y + x}(n) \leq g_{\omega^2}(\iota(\ell_0, x, y, n))$$



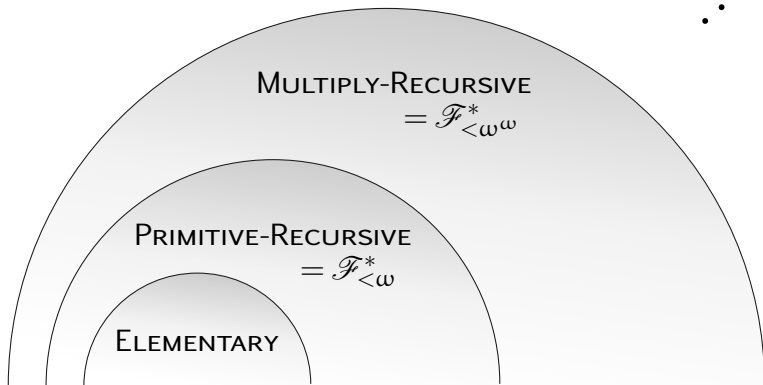
COMPLEXITY CLASSIFICATION





COMPLEXITY CLASSIFICATION

Wainer (1970)

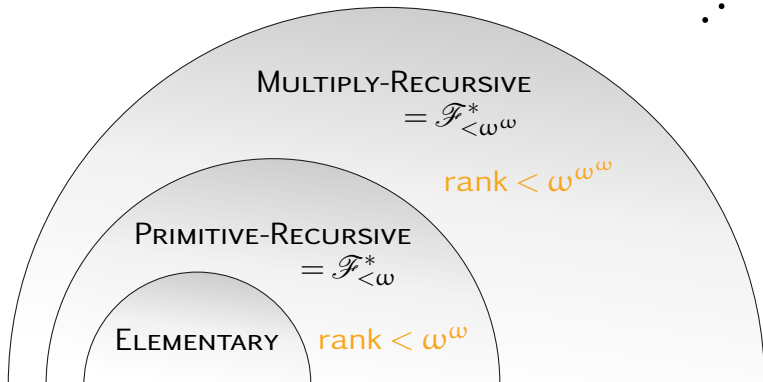


$$\mathcal{F}_{<\alpha}^* \stackrel{\text{def}}{=} \bigcup_{\beta < \omega^\alpha} \text{DTIME}(H^\beta(n))$$



COMPLEXITY CLASSIFICATION

Wainer (1970)



$$\mathcal{F}_{< \alpha} \stackrel{\text{def}}{=} \bigcup_{\beta < \omega^\alpha} \text{DTIME}(H^\beta(n)) \quad \text{assuming prim. rec. } (\iota, g)$$



AN APPLICATION

- ▶ very high bounds in general: interesting for complex algorithms
- ▶ provide the **first** known upper bound on VAS Reachability through the decomposition algorithms of Mayr (1981); Kosaraju (1982); Lambert (1992)
- ▶ **work in progress** with Jérôme Leroux



VECTOR ADDITION SYSTEMS

- ▶ a VAS $\mathcal{V} = \langle d, T, \mathbf{v}_0 \rangle$
 - ▶ $d \in \mathbb{N}$ dimension
 - ▶ $T \subseteq \mathbb{Z}^d$ finite set of transitions
 - ▶ $\mathbf{v}_0 \in \mathbb{N}^d$ initial vector
- ▶ operational semantics: $\langle \mathbb{N}^d, \rightarrow_{\mathcal{V}} \rangle$ where $\mathbf{v} \rightarrow \mathbf{v}'$ if $\mathbf{v}' - \mathbf{v} \in T$.
- ▶ reachability problem: given \mathcal{V} and $\mathbf{v}_f \in \mathbb{N}^d$, does $\mathbf{v}_0 \rightarrow_{\mathcal{V}}^* \mathbf{v}_f$?



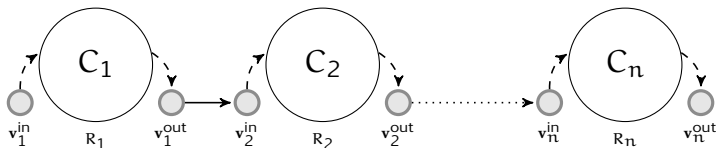
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VAS CHAINS (INFORMALLY)

Kosaraju (1982)

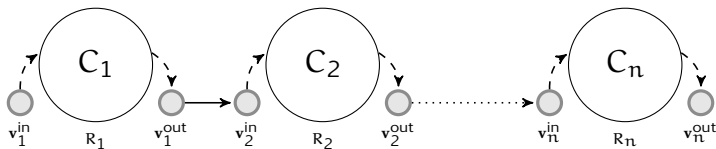


- ▶ strongly connected components C_i
- ▶ input vector v_i^{in} and output vector v_i^{out} in $(\mathbb{N} \uplus \{\star\})^d$
- ▶ labelled using transitions from T
- ▶ **rigid** set R_i s.t. $\forall \mathbf{u}$ label in C_i and $\forall 1 \leq j \leq d$, $\mathbf{u}(j) = 0$



VAS CHAINS (INFORMALLY)

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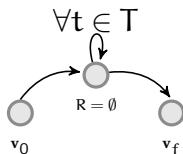
- ▶ **θ conditions** to ensure existence of a run, among which
 - ▶ transition counts unbounded
 - ▶ \star -components of input/output vectors unbounded
 - ▶ ...



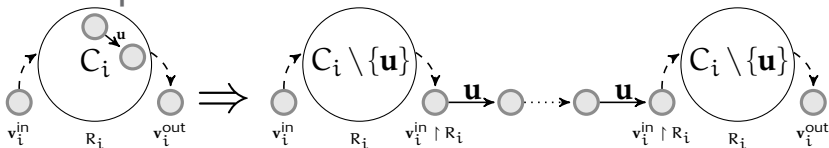
DECOMPOSING VAS CHAINS

Kosaraju (1982)

Initial



Example: Bounded Transition





TERMINATION

Kosaraju (1982)

- ▶ associate with each component C_i a triple in $[d] \times \mathbb{N} \times [2d]$
 1. $d - |R_i|$ the number of non-rigid components
 2. $|C_i|$ the number of arcs
 3. total number of \star 's in \mathbf{v}_i^{in} and $\mathbf{v}_i^{\text{out}}$
- ▶ associate with a VAS chain the corresponding multiset of triples
- ▶ ranking function into $\omega^{d \cdot \omega \cdot 2d}$



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CONTROLLING DECOMPOSITIONS

Figueira et al. (2011)

Use Length Function Theorem for Dickson's Lemma (Figueira et al., 2011) to control bounded values during decomposition:

$$h(x) = H^{\omega^{d+1}}(x)$$

Then overall bound on complexity

$$(H^{\omega^{d+1}})^{\omega^{d \cdot \omega \cdot 2d}}(\|\mathbf{v}_0\| + \|\mathbf{v}_f\|) \leq H^{\omega^{\omega^2}}(e(n))$$

for some elementary function e and an instance of size n .



REGARDING VAS REACHABILITY

cons

- ▶ huge gap with ExpSpace lower bound
- ▶ non primitive-recursive upper bound, even for fixed dimension d

pros

- ▶ very simple complexity argument: the algorithm and the ranking function were already provided by Kosaraju (1982)
- ▶ illustrates the power of length function theorems



CONCLUDING REMARKS

- ▶ Length Function Theorem for ordinals below ε_0
- ▶ crucial use of the Cichoń hierarchy and ordinal norms
- ▶ bounds on complexity of programs with ordinal ranking functions
- ▶ beyond ordinals: well-quasi-orders
 - ▶ many results already: McAloon (1984); Clote (1986); Weiermann (1994); Cichoń and Tahhan Bittar (1998); Figueira et al. (2011); S. and Schnoebelen (2011); Abriola et al. (2012)
 - ▶ how to relate maximal order types to length functions in general?



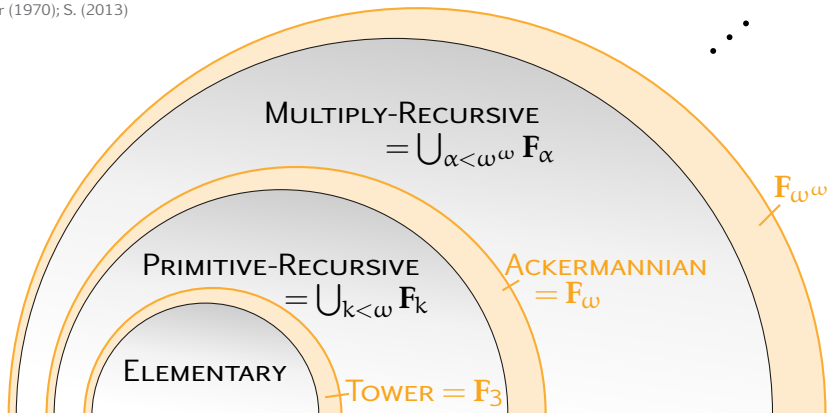
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COMPLEXITY CLASSIFICATION

Wainer (1970); S. (2013)



$$\mathcal{F}_{<\alpha} \stackrel{\text{def}}{=} \bigcup_{\beta < \omega^\alpha} \text{FDTIME}(H^\beta(n)), \quad F_\alpha \stackrel{\text{def}}{=} \bigcup_{p \in \mathcal{F}_{<\alpha}} \text{DTIME}(H^{\omega^\alpha}(p(n)))$$



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