On the Complexity of VAS Reachability

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based on joint works with D. Figueira, S. Figueira, J. Leroux, and Ph. Schnoebelen











Centre Fédéré en Vérification, February 22, 2019

OUTLINE

well-quasi-orders (wqo):

proving algorithm termination

a toolbox for wqo complexity

- upper bounds
- ▶ lower bounds
- complexity classes

this talk: focus on one problem

reachability in vector addition systems

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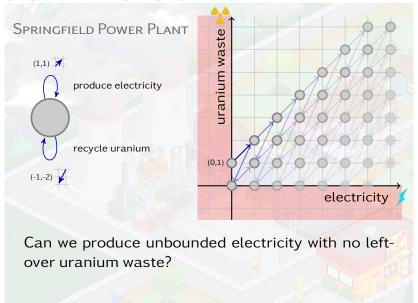
- upper bounds
- lower bounds
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this talk: focus on one problem

reachability in vector addition systems

Vector Addition Systems





SPRINGFIELD POWER PLANT uranium waste (1,1) 1 produce electricity recycle uranium (0,1)electricity Can we produce unbounded electricity with no left-

over uranium waste? Yes, $(\infty, 0)$ is reachable

REACHABILITY PROBLEM

input: a vector addition system and two configurations source and target

question: source \rightarrow * target?

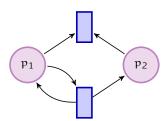
DISCRETE RESOURCES

- ▶ modelling: items, money, energy, molecules, . . .
- distributed computing: active threads in thread pool
- data: isomorphism types in data logics and data-centric systems

EXAMPLE: PETRI NETS



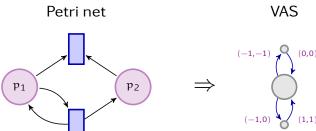
Petri net



VAS

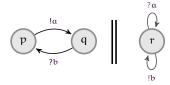
EXAMPLE: PETRI NETS





EXAMPLE: UNORDERED CFSM

Communicating Finite-State Machine

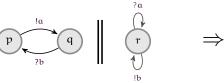


unordered channel:



EXAMPLE: UNORDERED CFSM

Communicating Finite-State Machine



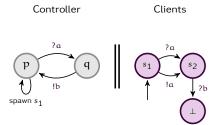
unordered channel:

VAS $(-1,0) \qquad (-1,0)$ $p \qquad (1,0) \qquad q$ $r \qquad (0,-1) \qquad (0,1)$

counters:

a3 2b

EXAMPLE: ASYNCHRONOUS RENDEZ-VOUS [German & Prasad Sistla'92]

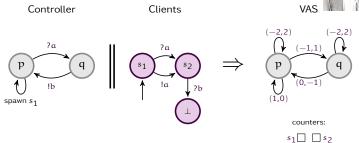




Example: Asynchronous Rendez-vous

[German & Prasad Sistla'92]





CENTRAL DECISION PROBLEM [S.'16]

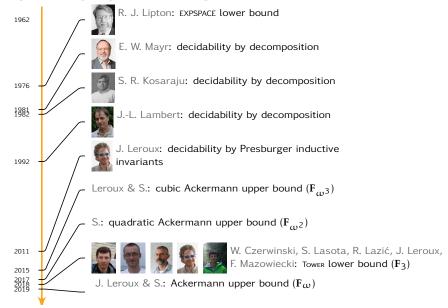
Large number of problems interreducible with reachability in vector addition systems

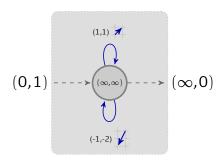


THEOREM (Minsky'67)

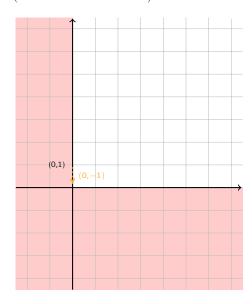
Reachability is undecidable in 2-dimensional Minsky machines (vector addition systems with zero tests).





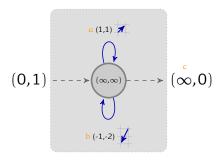


Vector Addition Systems



"SIMPLE RUNS" (Θ CONDITION)

[Mayr'81, Kosaraju'82, Lambert'92]



CHARACTERISTIC SYSTEM

$$0+1 \cdot a - 1 \cdot b = c$$

$$1+1 \cdot a - 2 \cdot b = 0$$

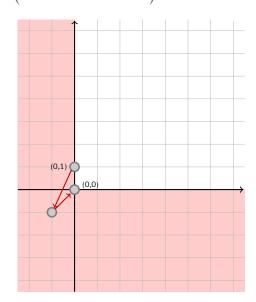
SOLUTION PATH



Vector Addition Systems

solution path



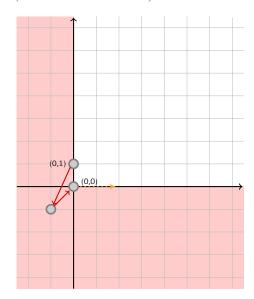


"Simple Runs" (Θ Condition)

[Mayr'81, Kosaraju'82, Lambert'92]

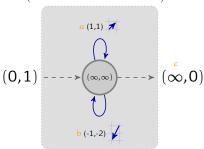
solution path

 $\times 1$



"SIMPLE RUNS" (Θ CONDITION)

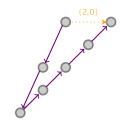
[Mayr'81, Kosaraju'82, Lambert'92]



HOMOGENEOUS SYSTEM

$$1 \cdot \mathbf{a} - 1 \cdot \mathbf{b} = \mathbf{c}$$
$$1 \cdot \mathbf{a} - 2 \cdot \mathbf{b} = 0$$

Unbounded Path



"SIMPLE RUNS" (Θ CONDITION)

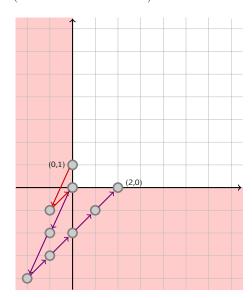
[Mayr'81, Kosaraju'82, Lambert'92]

solution path

 $\times 1$

unbounded path

× × :

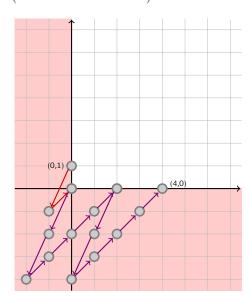


solution path



unbounded path





"SIMPLE RUNS" (Θ CONDITION)

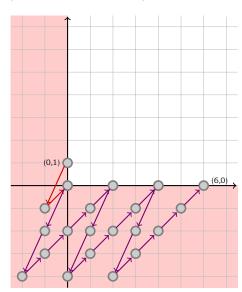
[Mayr'81, Kosaraju'82, Lambert'92]

solution path

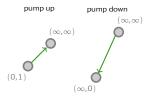


unbounded path



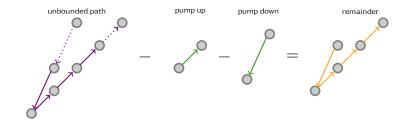


Pumpable Paths



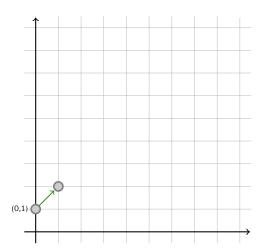
classically: uses coverability trees [Karp & Miller'69] in [Leroux & S.'19] Rackoff-style witnesses

PUMPABLE PATHS



Vector Addition Systems

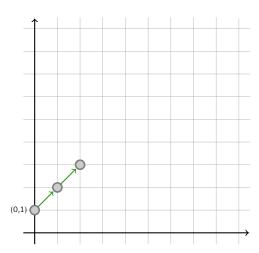
pump up



"SIMPLE RUNS" (Θ CONDITION)

[Mayr'81, Kosaraju'82, Lambert'92]

 $\mathbf{x}^{\text{pump up}} \times 2$



"SIMPLE RUNS" (Θ CONDITION)

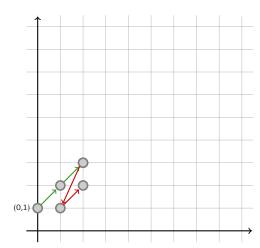
[Mayr'81, Kosaraju'82, Lambert'92]

pump up



solution path





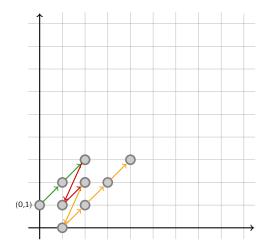
pump up



solution path



remainder



"SIMPLE RUNS" (Θ CONDITION)

[Mayr'81, Kosaraju'82, Lambert'92]

pump up

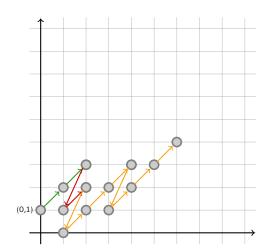


solution path



remainder





[Mayr'81, Kosaraju'82, Lambert'92]

pump up



solution path

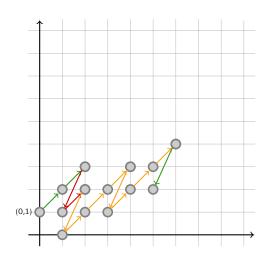


remainder



pump down





"SIMPLE RUNS" (Θ CONDITION)

[Mayr'81, Kosaraju'82, Lambert'92]

pump up



solution path

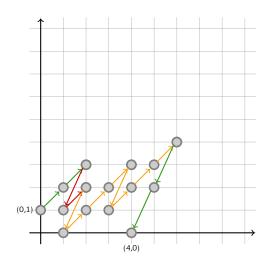


remainder



pump down





[Mayr'81, Kosaraju'82, Lambert'92]

pump up



solution path

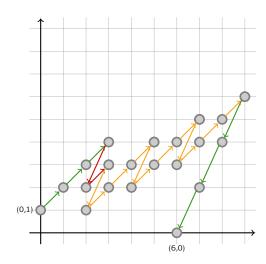


remainder



pump down





[Mayr'81, Kosaraju'82, Lambert'92]

can we build a "simple run"?

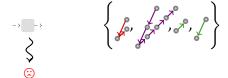
[Mayr'81, Kosaraju'82, Lambert'92]

can we build a "simple run"? yes



[Mayr'81, Kosaraju'82, Lambert'92]

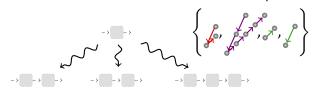
can we build a "simple run"? no



decompose

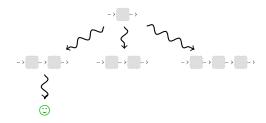
[Mayr'81, Kosaraju'82, Lambert'92]

can we build a "simple run"? no

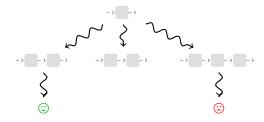


decompose

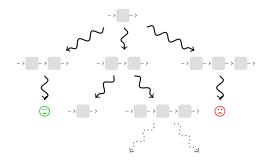
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TERMINATION

"Finally the checker has to verify that the process comes to an end. Here again he should be assisted by the programmer giving a further definite assertion to be verified. This may take the form of a quantity which is asserted to decrease continually and vanish when the machine stops."



[Turing'49]

TERMINATION

"Finally the checker has to verify that the process comes to an end. Here again he should be assisted by the programmer giving a further definite assertion to be verified. This may take the form of a quantity which is asserted to decrease continually and vanish when the machine stops. To the pure mathematician it is natural to give an ordinal number."

[Turing'49]





TERMINATION OF THE DECOMPOSITION

ALGORITHM

[Mayr'81, Kosaraju'82, Lambert'92, Leroux & S.'19]

RANKING FUNCTION



 (ω^{d+1}) in dim. d)



 α_0

TERMINATION OF THE DECOMPOSITION

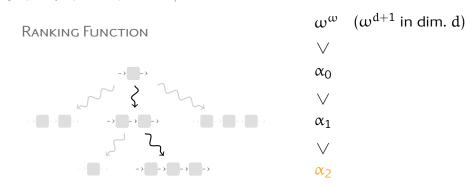
ALGORITHM

[Mayr'81, Kosaraju'82, Lambert'92, Leroux & S.'19]



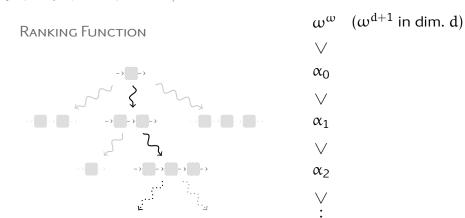
TERMINATION OF THE DECOMPOSITION ALGORITHM

[Mayr'81, Kosaraju'82, Lambert'92, Leroux & S.'19]



TERMINATION OF THE DECOMPOSITION ALGORITHM

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UPPER BOUNDS

How to bound the running time of algorithms with ordinal-based termination proofs?

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How to bound the running time of algorithms with wqo-based termination proofs?

How to bound the running time of algorithms with wgo-based termination proofs?

wqos ubiquitous in infinite-state verification

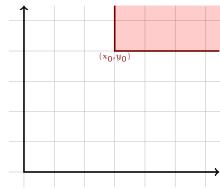


How to bound the running time of algorithms with wgo-based termination proofs?

wqos ubiquitous in infinite-state verification

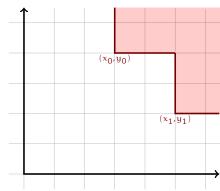


- over $\mathbb{Q}_{\geqslant 0} \times \mathbb{Q}_{\geqslant 0}$
- given initially (x_0, y_0)
- ► Eloise plays (x_j, y_j) s.t. $\forall 0 \le i < j, x_i > x_j$ or $y_i > y_j$



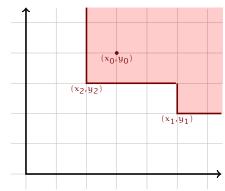
- ► Can Eloise win, i.e. play indefinitely?
- ▶ If not, how long can she last?

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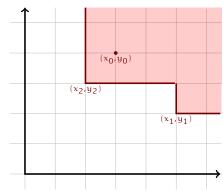
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- ► Can Eloise win, i.e. play indefinitely?
- ▶ If not, how long can she last?

If
$$(x_0,y_0) \neq (0,0)$$
, then choosing $(x_j,y_j) = (\frac{x_0}{2^j},\frac{y_0}{2^j})$ wins.

- over $\mathbb{N} \times \mathbb{N}$
- given initially (x_0, y_0)
- ► Eloise plays (x_j, y_j) s.t. $\forall 0 \le i < j, x_i > x_j$ or $y_i > y_j$



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Vector Addition Systems

Assume there exists an infinite sequence $(x_j, y_j)_j$ of moves over \mathbb{N}^2 .

Assume there exists an infinite sequence $(x_j, y_j)_j$ of moves over \mathbb{N}^2 . Consider the pairs of indices i < j: color (i,j)

purple if
$$x_i > x_j$$
 but $y_i \leqslant y_j$,

red if $x_i > x_j$ and $y_i > y_j$,

orange if $y_i > y_j$ but $x_i \leqslant x_j$.

(3,4) (5,2) (2,3) ...

Assume there exists an infinite sequence $(x_j, y_j)_j$ of moves over \mathbb{N}^2 . Consider the pairs of indices i < j: color (i,j)

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(3,4) (5,2) (2,3) ...

By the infinite Ramsey Theorem, there exists an infinite monochromatic subset of indices.

Assume there exists an infinite sequence $(x_i, y_i)_i$ of moves over \mathbb{N}^2 . Consider the pairs of indices i < j: color (i,j)

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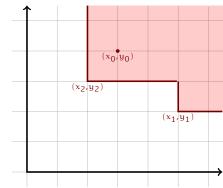
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(3,4) (5,2) (2,3) ...

By the infinite Ramsey Theorem, there exists an infinite monochromatic subset of indices. In all cases, it implies the existence of an infinite decreasing sequence in \mathbb{N} , a contradiction.

- over $\mathbb{N} \times \mathbb{N}$
- given initially (x_0, y_0)
- ► Eloise plays (x_j, y_j) s.t. $\forall 0 \leq i < j, x_i > x_j$ or $y_i > y_j$



- ► Can Eloise win, i.e. play indefinitely?
- ▶ If not, how long can she last?

BAD SEQUENCES

Over a go (X, \leq)

- ▶ $x_0, x_1,...$ is bad if $\forall i < j . x_i \not\leq x_j$
- \triangleright (X, \leqslant) wgo iff all bad sequences are finite

BAD SEQUENCES

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CONTROLLED BAD SEQUENCES

Over a qo (X, \leq) with norm $\|\cdot\|$

- ▶ $x_0, x_1,...$ is bad if $\forall i < j . x_i \not\leq x_j$
- (X, \leq) wqo iff all bad sequences are finite
- ▶ controlled by $g: \mathbb{N} \to \mathbb{N}$ monotone and inflationary and $n_0 \in \mathbb{N}$ if $\forall i. \|x_i\| \leqslant g^i(n_0)$

[Cichoń & Tahhan Bittar'98]

CONTROLLED BAD SEQUENCES

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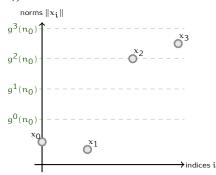
Over a qo (X, \leq) with norm $\|\cdot\|$

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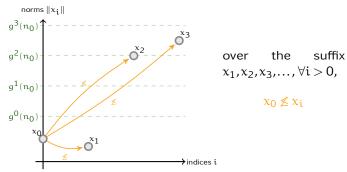
PROPOSITION

Over (X, \leq) , assuming $\forall n \{x \in X \mid ||x|| \leq n\}$ finite, (g, n_0) -controlled bad sequences have a maximal length, noted $L_{q,X}(n_0)$.

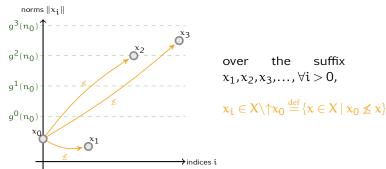
 (q,n_0) -controlled bad sequence $x_0,x_1,x_2,x_3,...$ over a wqo (X, \leq) :



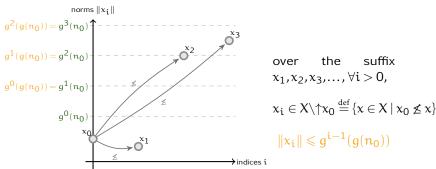
 (g,n_0) -controlled bad sequence $x_0,x_1,x_2,x_3,...$ over a wqo (X,\leqslant) :



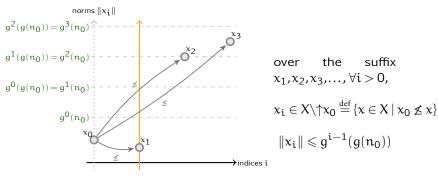
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 (q, n_0) -controlled bad sequence $x_0, x_1, x_2, x_3, \dots$ over a wqo (X, \leq) :

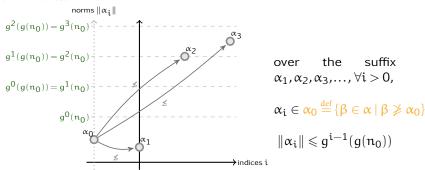


 (q,n_0) -controlled bad sequence $x_0,x_1,x_2,x_3,...$ over a wgo (X, \leq) :



$$L_{g,X}(\mathfrak{n}_0) = \max_{x_0 \in X, \|x_0\| \leqslant \mathfrak{n}_0} 1 + L_{g,X \setminus \uparrow x_0}(g(\mathfrak{n}_0))$$

 (q, n_0) -controlled bad sequence $\alpha_0, \alpha_1, \alpha_2, \alpha_3, \dots$ over an ordinal α:



$$L_{g,\alpha}(n_0) = \max_{\alpha_0 \in \alpha, \|\alpha_0\| \leqslant n_0} 1 + L_{g,\alpha_0}(g(n_0))$$

[S.'14]

▶ Cantor Normal Form (CNF) for ordinals $\alpha < \varepsilon_0$:

$$\alpha = \omega^{\alpha_1} \cdot c_1 + \dots + \omega^{\alpha_k} \cdot c_k$$

$$\alpha > \alpha_1 > \dots > \alpha_k \text{ in CNF , } \qquad 0 < c_1, \dots, c_k < \omega$$

$$\|\alpha\| \stackrel{\text{def}}{=} \max_{1 \leqslant i \leqslant k} (\max(\|\alpha_i\|, c_i))$$

$$\|\omega^{\omega^2}\| = 2$$
$$\|\omega^{\omega \cdot 5} + \omega^2 \cdot 3\| = 5$$

[S.'14]

▶ Cantor Normal Form (CNF) for ordinals $\alpha < \varepsilon_0$:

$$\begin{split} \alpha &= \omega^{\alpha_1} \cdot c_1 + \dots + \omega^{\alpha_k} \cdot c_k \\ \alpha &> \alpha_1 > \dots > \alpha_k \text{ in CNF , } \qquad 0 < c_1, \dots, c_k < \omega \end{split}$$

▶ Norm of ordinals $\alpha < \varepsilon_0$: "maximal constant"

$$\|\alpha\| \stackrel{\text{def}}{=} \max_{1 \leqslant i \leqslant k} (\max(\|\alpha_i\|, c_i))$$

EXAMPLE

$$\|\omega^{\omega^2}\| = 2$$
$$\|\omega^{\omega \cdot 5} + \omega^2 \cdot 3\| = 5$$

[S.'14]

Recall the descent equation:

$$L_{g,\alpha}(n_0) = \max_{\alpha_0 \in \alpha, \|\alpha_0\| \leqslant n_0} 1 + L_{g,\alpha_0}(g(n_0))$$

Upper Bounds

PROPOSITION (variant of [Buchholtz, Cichoń & Weiermann'94]) Let $0 < \alpha < \varepsilon_0$ and $\|\alpha\| \le n_0$. Then

$$L_{g,0}(n_0) = 0$$
 $L_{g,\alpha}(n_0) = 1 + L_{g,P_{n_0}(\alpha)}(g(n_0))$

Recall the descent equation:

$$L_{g,\alpha}(n_0) = \max_{\alpha_0 \in \alpha, \|\alpha_0\| \leqslant n_0} 1 + L_{g,\alpha_0}(g(n_0))$$

PROPOSITION (variant of [Buchholtz, Cichoń & Weiermann'94]) Let $0 < \alpha < \varepsilon_0$ and $\|\alpha\| \le n_0$. Then

$$L_{g,0}(n_0) = 0 \qquad L_{g,\alpha}(n_0) = 1 + L_{g, \textcolor{red}{P_{n_0}(\alpha)}}(g(n_0))$$

 $P_x(\alpha)$ denotes the predecessor at x of $\alpha>0$: "maximal ordinal $\beta<\alpha$ s.t. $\|\beta\|\leqslant x$ "

[S.'14]

 $P_x(\alpha)$ denotes the predecessor at x of $\alpha > 0$: "maximal ordinal $\beta < \alpha$ s.t. $\|\beta\| \leqslant x$ "

EXAMPLE

$$P_3(\omega^2) = \omega \cdot 3 + 3$$

$$P_{3}(\omega^{\omega^{2}}) = \omega^{\omega \cdot 3+3} \cdot 3 + \omega^{\omega \cdot 3+2} \cdot 3 + \omega^{\omega \cdot 3+1} \cdot 3 + \omega^{\omega \cdot 3} \cdot 3 + \omega^{\omega \cdot 2+3} \cdot 3 + \omega^{\omega \cdot 2+2} \cdot 3 + \omega^{\omega \cdot 2+1} \cdot 3 + \omega^{\omega \cdot 2} \cdot 3 + \omega^{\omega + 3} \cdot 3 + \omega^{\omega + 2} \cdot 3 + \omega^{\omega + 1} \cdot 3 + \omega^{\omega} \cdot 3 + \omega^{3} \cdot 3 + \omega^{2} \cdot 3 + \omega \cdot 3 + 3$$

 $P_x(\alpha)$ denotes the predecessor at x of $\alpha > 0$: "maximal ordinal $\beta < \alpha$ s.t. $\|\beta\| \leqslant x$ "

EXAMPLE

$$\begin{split} P_3(\omega^2) &= \omega \cdot 3 + 3 \\ P_3(\omega^{\omega^2}) &= \omega^{\omega \cdot 3 + 3} \cdot 3 + \omega^{\omega \cdot 3 + 2} \cdot 3 + \omega^{\omega \cdot 3 + 1} \cdot 3 + \omega^{\omega \cdot 3} \cdot 3 \\ &+ \omega^{\omega \cdot 2 + 3} \cdot 3 + \omega^{\omega \cdot 2 + 2} \cdot 3 + \omega^{\omega \cdot 2 + 1} \cdot 3 + \omega^{\omega \cdot 2} \cdot 3 \\ &+ \omega^{\omega + 3} \cdot 3 + \omega^{\omega + 2} \cdot 3 + \omega^{\omega + 1} \cdot 3 + \omega^{\omega} \cdot 3 \\ &+ \omega^3 \cdot 3 + \omega^2 \cdot 3 + \omega \cdot 3 + 3 \end{split}$$

Proposition (variant of [Buchholtz, Cichoń & Weiermann'94]) Let $0 < \alpha < \varepsilon_0$ and $\|\alpha\| \le n_0$. Then

$$L_{g,0}(n_0) = 0 \qquad L_{g,\alpha}(n_0) = 1 + L_{g,P_{n_0}(\alpha)}(g(n_0))$$

These functions were already known in the literature as the Cichón hierarchy

LENGTH FUNCTION THEOREM (FOR ORDINALS)

Let $\alpha < \epsilon_0$ and $\mathfrak{n}_0 \geqslant \|\alpha\|$. Then the longest $(\mathfrak{g},\mathfrak{n}_0)$ -controlled descending sequence over α is of length $L_{\mathfrak{g},\alpha}(\mathfrak{n}_0)$ in the Cichón hierarchy.

[Cichoń & Tahhan Bittar'98]

Recall the definition of the Cichoń Hierarchy:

$$L_{g,0}(x)\stackrel{\text{def}}{=} 0$$
 $L_{g,\alpha}(x)\stackrel{\text{def}}{=} 1 + L_{g,P_x(\alpha)}(g(x))$ for $\alpha > 0$

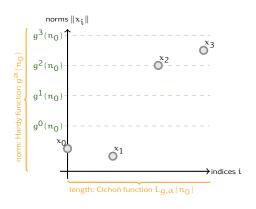
DEFINITION (Hardy Hierarchy)

For $g: \mathbb{N} \to \mathbb{N}$, define $(g^{\alpha}: \mathbb{N} \to \mathbb{N})_{\alpha}$ by

$$g^0(x) \stackrel{\text{def}}{=} x$$
 $g^{\alpha}(x) \stackrel{\text{def}}{=} g^{P_x(\alpha)}(g(x))$ for $\alpha > 0$

RELATING NORM AND LENGTH

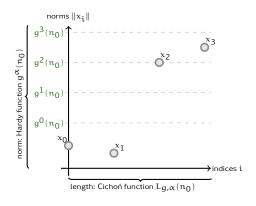
[Cichoń & Tahhan Bittar'98]



$$g^{\alpha}(x) = g^{L_{g,\alpha}(x)}(x)$$
$$g^{\alpha}(x) \geqslant L_{g,\alpha}(x) + x$$

RELATING NORM AND LENGTH

[Cichoń & Tahhan Bittar'98]

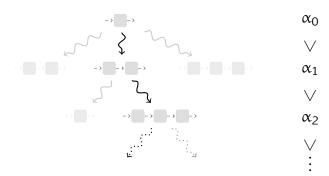


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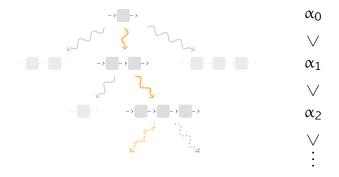
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Vector Addition Systems

THE LENGTH OF DECOMPOSITION BRANCHES



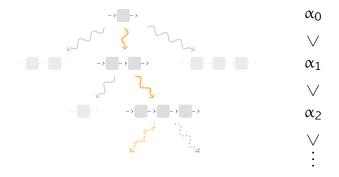
THE LENGTH OF DECOMPOSITION BRANCHES



CONSEQUENCE OF (LEROUX & S.'19)

An elementary control q and n the size of the reachability instance fit. Thus the decomposition algorithm runs in $SPACE(q^{\omega^{\omega}}(n))$, and $SPACE(q^{\omega^{d+1}}(n))$ in fixed dimension d.

THE LENGTH OF DECOMPOSITION BRANCHES



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RESTATING THE RESULT

"SPACE $(g^{\omega^{d+1}}(n))$ " is unreadable!

$$H^0(x) = x$$

$$H^{w}(x) = H^{w+1}(x) = H^{w+1}(x) = H^{w}(x) = H^{w}$$

RESTATING THE RESULT

How
$$(x) = x$$
 $H^{\omega}(x) = X + 1$
 $H^{\omega}(x) = H^{\omega}(x) = H^{\omega}(x+1) = H^{\omega}(x) = H^{\omega}$

How
$$(x) = x$$
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 $H^{\omega}(x) = x$
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$$H^{0}(x) = x$$

$$H^{k}(x) = H^{0} \cdot \cdot \cdot \cdot \cdot H(x) = x + k$$

$$H^{\omega}(x) = H^{x+1}(x) = H^{0} \cdot \cdot \cdot \cdot \cdot H(x) = 2x + 1$$

$$H^{\omega^{2}}(x) = H^{\omega \cdot (x+1)} = H^{\omega} \cdot \cdot \cdot \cdot \cdot H^{\omega}(x) \approx 2^{x}$$

$$H^{\omega^{3}}(x) = H^{\omega^{2} \cdot (x+1)} = H^{\omega^{2}} \cdot \cdot \cdot \cdot \cdot \cdot H^{\omega^{2}}(x) \approx \text{tower}(x)$$

$$\vdots$$

$$H^{\omega^{\omega}}(x) = H^{\omega^{x+1}}(x) \approx \text{ack}(x)$$

Define coarse-grained classes:

$$\begin{split} \mathscr{F}_{<\alpha} &\stackrel{\mathrm{def}}{=} \bigcup_{\beta < \omega^{\alpha}} \mathsf{FDTIME}(\mathsf{H}^{\beta}(\mathfrak{n})) \\ \mathbf{F}_{\alpha} &\stackrel{\mathrm{def}}{=} \bigcup_{f \in \mathscr{F}_{<\alpha}} \mathsf{DTIME}(\mathsf{H}^{\omega^{\alpha}}(\mathsf{f}(\mathfrak{n}))) \end{split}$$

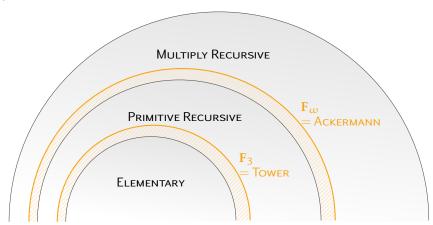
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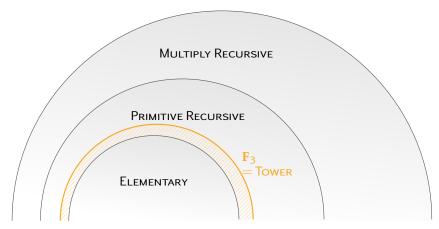
Consequence of (S.'16, Thm. 4.4)

VAS Reachability is in F_{ω} , and in F_{d+4} in fixed dimension d.

[S.'16]



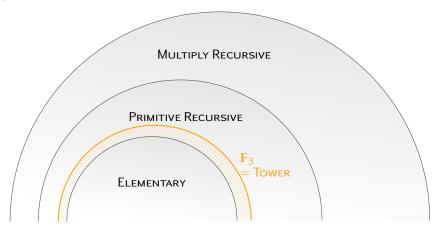
[S.'16]



Upper Bounds

$$\mathbf{F}_3 \stackrel{\text{\tiny def}}{=} \bigcup_{e \text{ elementary}} \mathsf{DTIME}(\mathsf{tower}(e(\mathsf{n})))$$

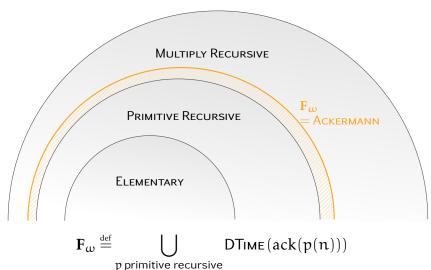
[S.'16]



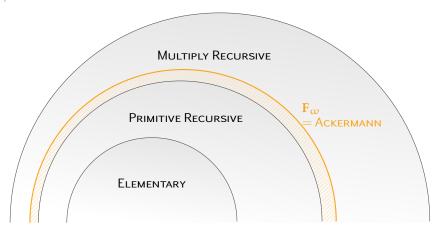
EXAMPLES OF TOWER-COMPLETE PROBLEMS:

- satisfiability of first-order logic on words [Meyer'75]
- \triangleright β-equivalence of simply typed λ terms [Statman'79]
- model-checking higher-order recursion schemes [Ong'06]

[S.'16]



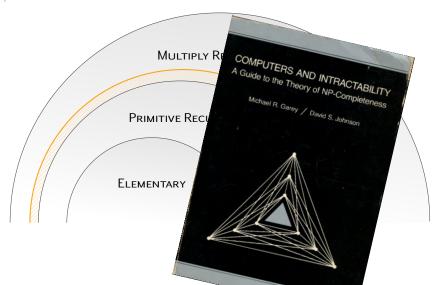
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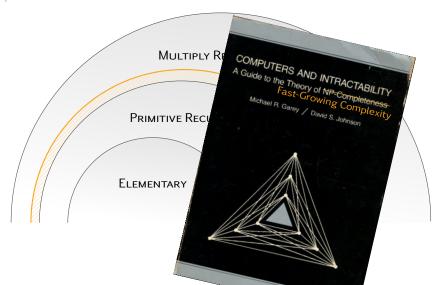
EXAMPLES OF ACKERMANN-COMPLETE PROBLEMS:

- reachability in lossy Minsky machines [Urquhart'98, Schnoebelen'02]
- ▶ satisfiability of safety Metric Temporal Logic [Lazić et al.'16]
- satisfiability of Vertical XPath [Figueira and Segoufin'17]

[S.'16]



[S.'16]



A RELATED PROBLEM

labelled VAS transitions carry labels from some alphabet

L(V, source, target) the language of labels in runs from source to target

 $\downarrow \! L$ the set of scattered subwords of the words in the language L

DOWNWARDS LANGUAGE INCLUSION PROBLEM

input: two labelled VAS V and V' and configurations

source, target, source', target'

question: $\downarrow L(\mathcal{V}, \mathbf{source}, \mathbf{target}) \subseteq \downarrow L(\mathcal{V}', \mathbf{source}', \mathbf{target}')$?

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THEOREM (Habermehl, Meyer & Wimmel'10)

Given a labelled VAS V and configurations **source** and **target** and its decomposition, one can construct a finite automaton for $\downarrow L(V, \mathbf{source}, \mathbf{target})$ in polynomial time.

COROLLARY

The Downwards Language Inclusion is in Ackermann

A RELATED PROBLEM

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COROLLARY

The Downwards Language Inclusion is in Ackermann.

THEOREM (Zetzsche'16)

The Downwards Language Inclusion is Ackermann-hard.

well-quasi-orders (wqo):

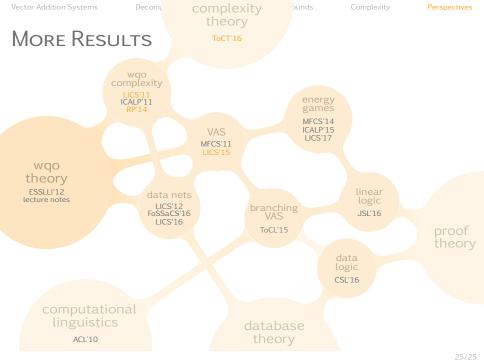
proving algorithm termination

a toolbox for wqo-based complexity

- upper bounds: length function theorems (for ordinals, Dickson's Lemma, Higman's Lemma, and combinations)
- lower bounds
- complexity classes: $(\mathbf{F}_{\alpha})_{\alpha}$

this talk: focus on one problem

ightharpoonup reachability in vector addition systems in F_{ω}



Perspectives

1. complexity gap for VAS reachability

- ► Tower-hard [Czerwinski et al.'18]
- because downward language inclusion is F_{ω} -hard [Zetzsche'16]

reachability in VAS extensions

- decidable in VAS with hierarchical zero tests [Reinhardt'08]
- what about
 - branching VAS
 - unordered data Petri nets
 - pushdown VAS

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Perspectives

1. complexity gap for VAS reachability

- ► Tower-hard [Czerwinski et al.'18]
- decomposition algorithm: requires $F_{\omega}=$ Ackermann time, because downward language inclusion is F_{ω} -hard [Zetzsche'16]

2. reachability in VAS extensions

- decidable in VAS with hierarchical zero tests [Reinhardt'08]
- what about
 - branching VAS
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 - pushdown VAS

DEMYSTIFYING REACHABILITY IN VECTOR ADDITION SYSTEMS

[Leroux & S.'15]

IDEAL DECOMPOSITION THEOREM

The Decomposition Algorithm computes the ideal decomposition of the set of runs from source to target.

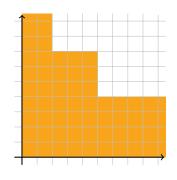
UPPER BOUND THEOREM
Reachability in vector addition systems is in cubic Ackermann.

Ideals of Well-Quasi-Orders (X, \leq)

 Canonical decompositions [Bonnet'75]
 if D ⊂ X is ↓-closed, then

$$D=I_1\cup\dots\cup I_n$$

for (maximal) ideals $I_1, ..., I_n$



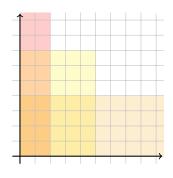
```
Example (over \mathbb{N}^2)
D = (\{0, \dots, 2\} \times \mathbb{N}) \cup (\{0, \dots, 5\} \times \{0, \dots, 7\}) \cup (\mathbb{N} \times \{0, \dots, 4\})
```

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Example (over
$$\mathbb{N}^2$$
)
$$D = (\{0,...,2\} \times \mathbb{N}) \cup (\{0,...,5\} \times \{0,...,7\}) \cup (\mathbb{N} \times \{0,...,4\})$$

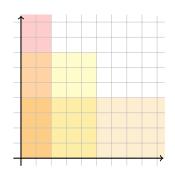
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► Effective representations [Goubault-Larrecq et al.'17]



Example (over
$$\mathbb{N}^2$$
)
$$D = \llbracket (2,\infty) \rrbracket \cup \llbracket (5,7) \rrbracket \cup \llbracket (\infty,4) \rrbracket$$

Well-Quasi-Order on Runs

combination of Dickson's and Higman's lemmata

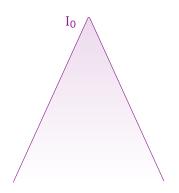




SYNTAX



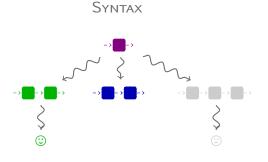


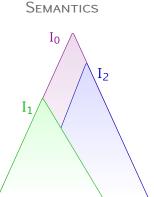


Well-Quasi-Order on Runs combination of Dickson's and Higman's lemmata







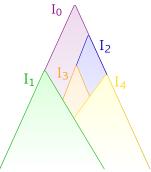


Well-Quasi-Order on Runs combination of Dickson's and Higman's lemmata





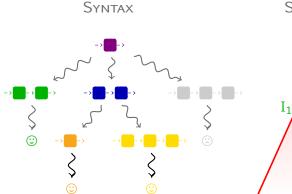


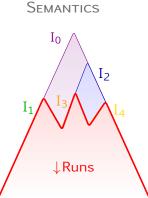


Well-Quasi-Order on Runs combination of Dickson's and Higman's lemmata

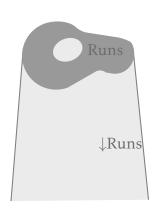




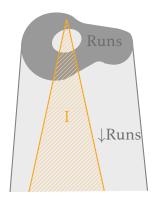




- ► I is adherent to Runs if $I \subseteq \bigcup (I \cap Runs)$
- semantic equivalent toΘ condition
- undecidable for arbitrary ideals
- decidable for the ideals arising in the decomposition algorithm

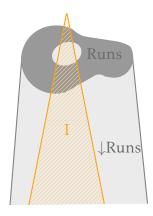


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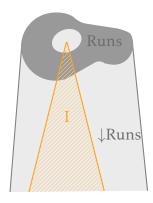
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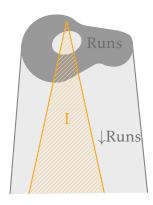
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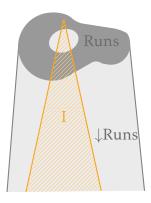
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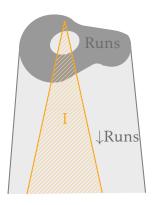
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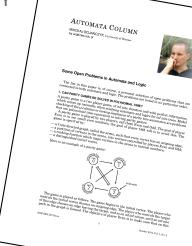
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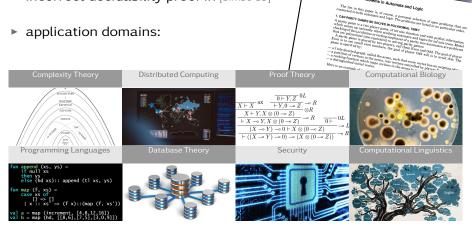


I adherent

- ▶ important open problem [Bojańczyk'14]
- ▶ incorrect decidability proof in [Bimbó'15]
- application domains:



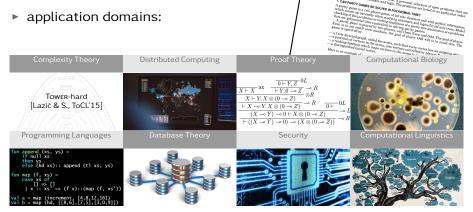
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 $A_{UTOMATA} \; \mathrm{Co}_{LUMN}$ MIKOŁAJ BOJAŃCZYK, Ustrowiej of Women

Some Open Problems in Automata and Logic

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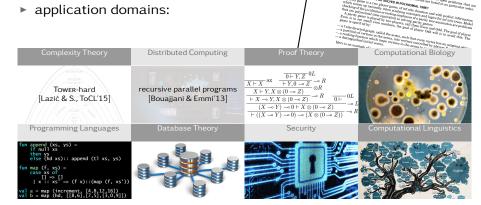


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Some Open Problems in Automata and Logic

The list in this paper is, of course, a personal solection of open problems that are summerted to both automate and layer. The problems are listed in no particular order. I. CAN PARITY GAMES BE SOLVED IN POLYNOMIAL TIME?

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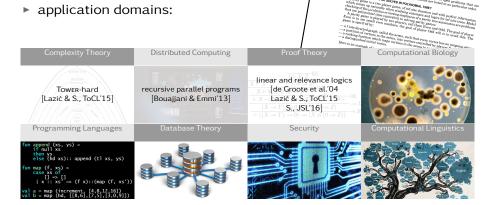


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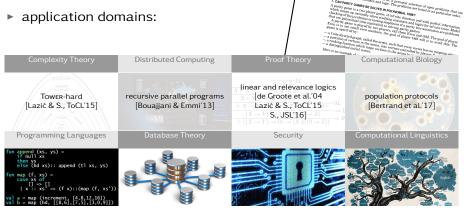
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or monotonic perfect infinite contents of the perfect infinite contents of the perfect infinite contents of the perfect infinite perfect infinite contents of the perfe . Buttle game is a ree player game, of an disk duration and with perfect information.

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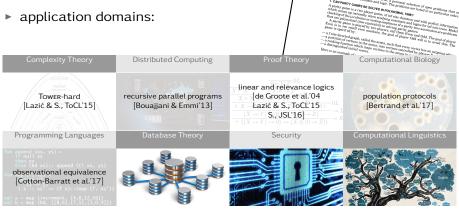


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Some Open Problems in Automata and Logic

The list in this paper is, of course, a personal selection of open problems that are connected to both automate and large. The problems are listed in no particular order. I. CAN PARITY GAMES BE SOLVED IN POLYNOMIAL TIME?

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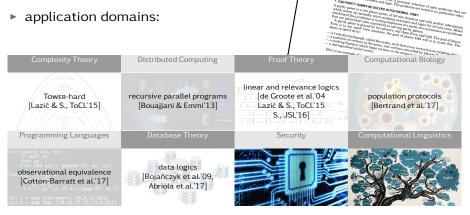


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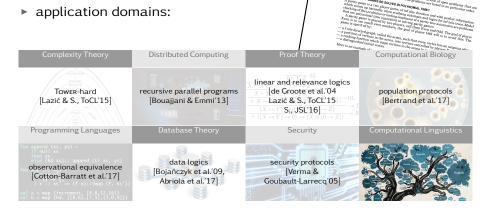


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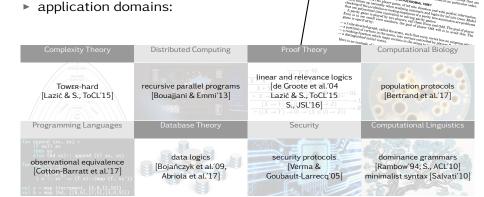


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