

Model checking for LTL

Definition: Model checking problem

Input: A Kripke structure $M = (S, T, I, AP, \ell)$
A formula $\varphi \in \text{LTL}(AP, Y, S, X, U)$

Question: Does $M \models \varphi$?

- ▶ **Universal MC:** $M \models \forall \varphi$ if $\ell(\sigma), 0 \models \varphi$ for all initial infinite run of M .
- ▶ **Existential MC:** $M \models \exists \varphi$ if $\ell(\sigma), 0 \models \varphi$ for some initial infinite run of M .

$$M \models \forall \varphi \quad \text{iff} \quad M \not\models \exists \neg \varphi$$

Theorem [11, Sistla, Clarke 85], [12, Lichtenstein & Pnueli 85]

The Model checking problem for LTL is PSPACE-complete

Satisfiability for LTL

Let AP be the set of atomic propositions and $\Sigma = 2^{AP}$.

Definition: Satisfiability problem

Input: A formula $\varphi \in \text{LTL}(AP, Y, S, X, U)$

Question: Existence of $w \in \Sigma^\omega$ and $i \in \mathbb{N}$ such that $w, i \models \varphi$.

Definition: Initial Satisfiability problem

Input: A formula $\varphi \in \text{LTL}(AP, Y, S, X, U)$

Question: Existence of $w \in \Sigma^\omega$ such that $w, 0 \models \varphi$.

Remark: φ is satisfiable iff $F \varphi$ is *initially* satisfiable.

Theorem (Sistla, Clarke 85, Lichtenstein et. al 85)

The satisfiability problem for LTL is PSPACE-complete

Definition: (Initial) validity

φ is valid iff $\neg \varphi$ is **not** satisfiable.

Decision procedure for LTL

Definition: The core

From a formula $\varphi \in \text{LTL}(AP, \dots)$, construct a Büchi automaton \mathcal{A}_φ such that

$$\mathcal{L}(\mathcal{A}) = \mathcal{L}(\varphi) = \{w \in \Sigma^\omega \mid w, 0 \models \varphi\}.$$

Satisfiability (initial)

Check the Büchi automaton \mathcal{A}_φ for emptiness.

Model checking

Construct a synchronized product $\mathcal{B} = M \otimes \mathcal{A}_{\neg \varphi}$ so that the successful runs of \mathcal{B} correspond to the initial runs of M satisfying $\neg \varphi$.

Then, check \mathcal{B} for emptiness.

Theorem:

Checking Büchi automata for emptiness is NLOGSPACE-complete.

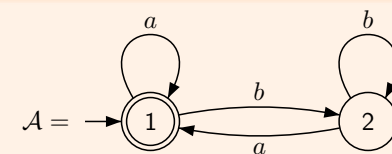
Büchi automata

Definition:

$\mathcal{A} = (Q, \Sigma, I, T, F)$ where

- ▶ Q : finite set of states
- ▶ Σ : finite set of labels
- ▶ $I \subseteq Q$: set of initial states
- ▶ $T \subseteq Q \times \Sigma \times Q$: transitions
- ▶ $F \subseteq Q$: set of accepting states (repeated, final)

Example:



$$\mathcal{L}(\mathcal{A}) = \{w \in \{a, b\}^\omega \mid |w|_a = \omega\}$$

Büchi automata for some LTL formulae

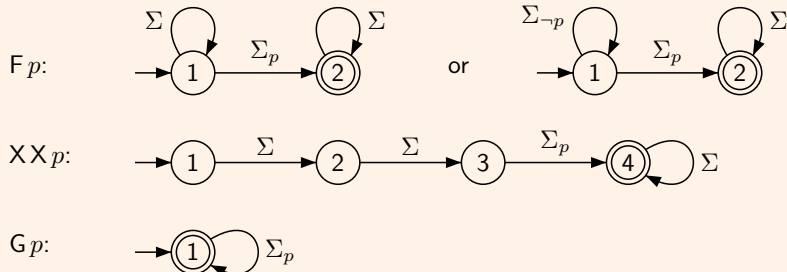
Definition:

Recall that $\Sigma = 2^{AP}$. For $\psi \in \mathbb{B}(AP)$ we let $\Sigma_\psi = \{a \in \Sigma \mid a \models \psi\}$.

For instance, for $p, q \in AP$,

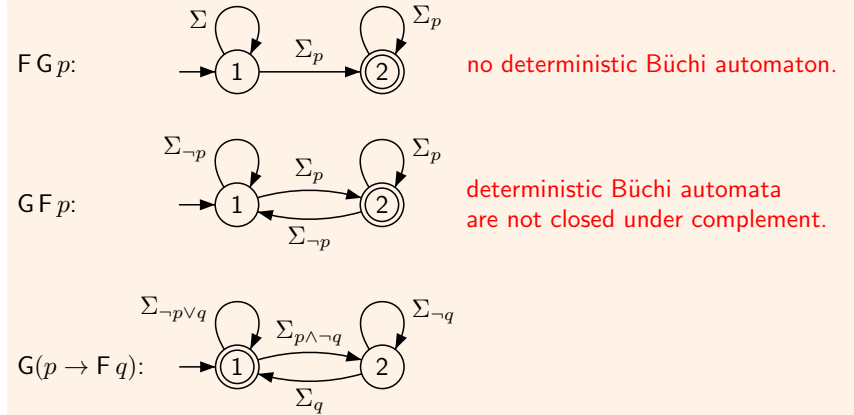
- $\Sigma_p = \{a \in \Sigma \mid p \in a\}$ and $\Sigma_{\neg p} = \Sigma \setminus \Sigma_p$
- $\Sigma_{p \wedge q} = \Sigma_p \cap \Sigma_q$ and $\Sigma_{p \vee q} = \Sigma_p \cup \Sigma_q$
- $\Sigma_{p \wedge \neg q} = \Sigma_p \setminus \Sigma_q \dots$

Examples:



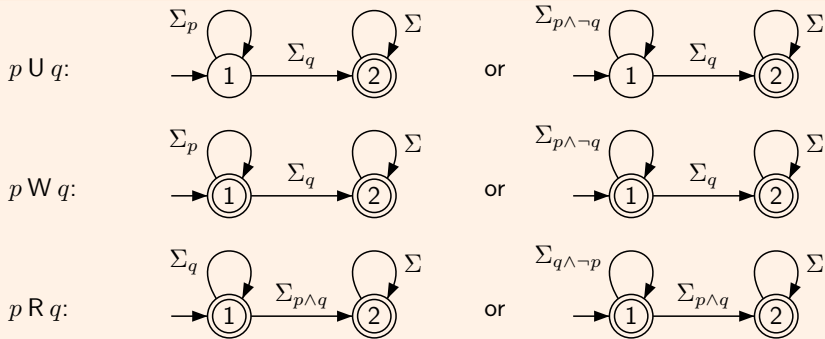
Büchi automata for some LTL formulae

Examples:



Büchi automata for some LTL formulae

Examples:



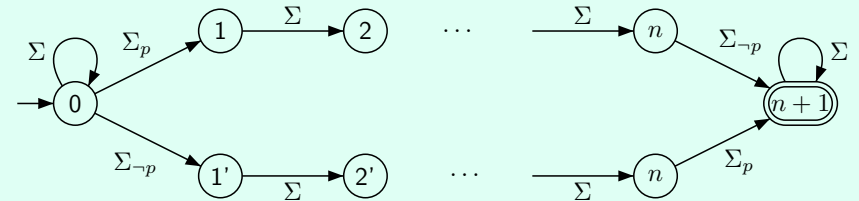
Büchi automata

Properties

Büchi automata are closed under union, intersection, complement.

- Union: trivial
- Intersection: easy (exercice)
- complement: hard

Let $\varphi = F((p \wedge X^n \neg p) \vee (\neg p \wedge X^n p))$



Any non deterministic Büchi automaton for $\neg\varphi$ has at least 2^n states.

Büchi automata

Exercise:

Given Büchi automata for φ and ψ ,

- Construct a Büchi automaton for $X\varphi$ (trivial)
- Construct a Büchi automaton for $\varphi \cup \psi$

This gives an inductive construction of \mathcal{A}_φ from $\varphi \in \text{LTL}(\text{AP}, X, U) \dots$

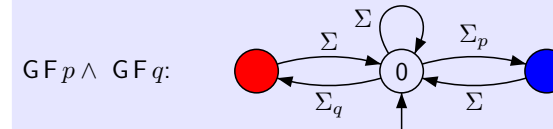
... but the size of \mathcal{A}_φ might be non-elementary in the size of φ .

Generalized Büchi automata

Definition: acceptance on states

$\mathcal{A} = (Q, \Sigma, I, T, F_1, \dots, F_n)$ with $F_i \subseteq Q$.

An infinite run σ is successful if it visits infinitely often each F_i .



Definition: acceptance on transitions

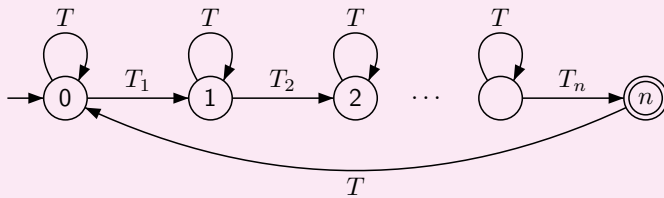
$\mathcal{A} = (Q, \Sigma, I, T, T_1, \dots, T_n)$ with $T_i \subseteq T$.

An infinite run σ is successful if it uses infinitely many transitions from each T_i .



GBA to BA

Proof: Synchronized product with \mathcal{B}



Transitions: $\frac{t = s_1 \xrightarrow{a} s'_1 \in \mathcal{A} \wedge s_2 \xrightarrow{t} s'_2 \in \mathcal{B}}{(s_1, s_2) \xrightarrow{a} (s'_1, s'_2)}$

Accepting states: $Q \times \{n\}$

Negative normal form

Definition: Syntax ($p \in \text{AP}$)

$\varphi ::= \top \mid \perp \mid p \mid \neg p \mid \varphi \vee \psi \mid \varphi \wedge \psi \mid X\varphi \mid \varphi \cup \psi \mid \varphi \text{R} \psi$

Proposition: Any formula can be transformed in NNF

$\neg(\varphi \vee \psi) \equiv (\neg\varphi) \wedge (\neg\psi)$ $\neg(\varphi \wedge \psi) \equiv (\neg\varphi) \vee (\neg\psi)$
 $\neg(\varphi \cup \psi) \equiv (\neg\varphi) \text{R} (\neg\psi)$ $\neg(\varphi \text{R} \psi) \equiv (\neg\varphi) \cup (\neg\psi)$
 $\neg X\varphi \equiv X\neg\varphi$ $\neg\neg\varphi \equiv \varphi$

This does not increase the number of Temporal subformulae.

Temporal formulae

Definition: Temporal formulae

- literals
- formulae with outermost connective X, U or R.

Reducing the number of temporal subformulae

$$\begin{aligned} (X\varphi) \wedge (X\psi) &\equiv X(\varphi \wedge \psi) & (X\varphi) \cup (X\psi) &\equiv X(\varphi \cup \psi) \\ (\varphi R \psi_1) \wedge (\varphi R \psi_2) &\equiv \varphi R (\psi_1 \wedge \psi_2) & (\varphi_1 R \psi) \vee (\varphi_2 R \psi) &\equiv (\varphi_1 \vee \varphi_2) R \psi \\ (G\varphi) \wedge (G\psi) &\equiv G(\varphi \wedge \psi) & GF\varphi \vee GF\psi &\equiv GF(\varphi \vee \psi) \end{aligned}$$

From LTL to BA [6, Demri & Gastin 10]

Definition:

- $Z \subseteq \text{NNF}$ is **consistent** if $\perp \notin Z$ and $\{p, \neg p\} \not\subseteq Z$ for all $p \in \text{AP}$.
- For $Z \subseteq \text{NNF}$, we define $\bigwedge Z = \bigwedge_{\psi \in Z} \psi$.
Note that $\bigwedge \emptyset = \top$ and if Z is inconsistent then $\bigwedge Z \equiv \perp$.

Intuition for the BA $\mathcal{A}_\varphi = (Q, \Sigma, I, T, (T_\alpha)_{\alpha \in U(\varphi)})$

Let $\varphi \in \text{NNF}$ be a formula.

- $\text{sub}(\varphi)$ is the set of **sub-formulae** of φ .
- $U(\varphi)$ the set of **until** sub-formulae of φ .
- We construct a BA \mathcal{A}_φ with $Q = 2^{\text{sub}(\varphi)}$ and $I = \{\varphi\}$.
- A state $Z \subseteq \text{sub}(\varphi)$ is a **set of obligations**.
- If $Z \subseteq \text{sub}(\varphi)$, we want $\mathcal{L}(\mathcal{A}_\varphi^Z) = \{u \in \Sigma^\omega \mid u, 0 \models \bigwedge Z\}$ where \mathcal{A}_φ^Z is \mathcal{A}_φ using Z as unique initial state.

Reduced formulae

Definition: Reduced formulae

- A formula is **reduced** if it is a literal (p or $\neg p$) or a next-formula ($X\beta$).
- $Z \subseteq \text{NNF}$ is **reduced** if all formulae in Z are reduced,

For $Z \subseteq \text{NNF}$ **consistent and reduced**, we define

$$\begin{aligned} \text{next}(Z) &= \{\alpha \mid X\alpha \in Z\} \\ \Sigma_Z &= \bigcap_{p \in Z} \Sigma_p \cap \bigcap_{\neg p \in Z} \Sigma_{\neg p} \end{aligned}$$

Lemma: Next step

Let $Z \subseteq \text{NNF}$ be **consistent and reduced**.

Let $u = a_0 a_1 a_2 \dots \in \Sigma^\omega$ and $n \geq 0$. Then

$$u, n \models \bigwedge Z \quad \text{iff} \quad u, n+1 \models \bigwedge \text{next}(Z) \text{ and } a_n \in \Sigma_Z$$

- \mathcal{A}_φ will have transitions $Z \xrightarrow{\Sigma_Z} \text{next}(Z)$.

Note that $\emptyset \xrightarrow{\Sigma} \emptyset$.

- Problem:** $\text{next}(Z)$ is not reduced in general (it may even be inconsistent).

Reduction rules

Definition: Reduction of obligations to literals and next-formulae

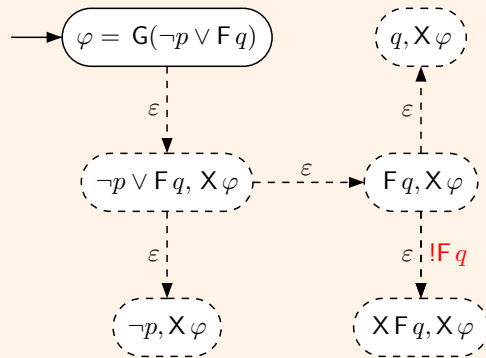
Let $Y \subseteq \text{NNF}$ and let $\psi \in Y$ **maximal not reduced**.

$$\begin{aligned} \text{If } \psi &= \psi_1 \wedge \psi_2: & Y &\xrightarrow{\varepsilon} (Y \setminus \{\psi\}) \cup \{\psi_1, \psi_2\} \\ \text{If } \psi &= \psi_1 \vee \psi_2: & Y &\xrightarrow{\varepsilon} (Y \setminus \{\psi\}) \cup \{\psi_1\} \\ & & Y &\xrightarrow{\varepsilon} (Y \setminus \{\psi\}) \cup \{\psi_2\} \\ \text{If } \psi &= \psi_1 R \psi_2: & Y &\xrightarrow{\varepsilon} (Y \setminus \{\psi\}) \cup \{\psi_1, \psi_2\} \\ & & Y &\xrightarrow{\varepsilon} (Y \setminus \{\psi\}) \cup \{\psi_2, X\psi\} \\ \text{If } \psi &= G\psi_2: & Y &\xrightarrow{\varepsilon} (Y \setminus \{\psi\}) \cup \{\psi_2, X\psi\} \\ \text{If } \psi &= \psi_1 U \psi_2: & Y &\xrightarrow{\varepsilon} (Y \setminus \{\psi\}) \cup \{\psi_2\} \\ & & Y &\xrightarrow[\!|\psi\!]{\varepsilon} (Y \setminus \{\psi\}) \cup \{\psi_1, X\psi\} \\ \text{If } \psi &= F\psi_2: & Y &\xrightarrow{\varepsilon} (Y \setminus \{\psi\}) \cup \{\psi_2\} \\ & & Y &\xrightarrow[\!|\psi\!]{\varepsilon} (Y \setminus \{\psi\}) \cup \{X\psi\} \end{aligned}$$

Note the mark $|\psi$ on the second transitions for U and F.

Reduction rules

Example: $\varphi = G(p \rightarrow F q)$



State = set of obligations.

Reduce obligations to literals and next-formulae.

Note again the mark $!F q$ on the last edge

Reduction

Lemma: Soundness

- if there is only one rule $Y \xrightarrow{\varepsilon} Y_1$ then $\bigwedge Y \equiv \bigwedge Y_1$
- if there are two rules $Y \xrightarrow{\varepsilon} Y_1$ and $Y \xrightarrow{\varepsilon} Y_2$ then $\bigwedge Y \equiv \bigwedge Y_1 \vee \bigwedge Y_2$

Definition:

For $Y \subseteq \text{NNF}$ and $\alpha \in \mathcal{U}(\varphi)$, let

$$\text{Red}(Y) = \{Z \text{ consistent and reduced} \mid \text{there is a path } Y \xrightarrow{\varepsilon_*} Z\}$$

$$\text{Red}_\alpha(Y) = \{Z \text{ consistent and reduced} \mid \text{there is a path } Y \xrightarrow{\varepsilon_*} Z \text{ without using an edge marked with } !\alpha\}$$

Lemma: Soundness

- Let $Y \subseteq \text{NNF}$, then $\bigwedge Y \equiv \bigvee_{Z \in \text{Red}(Y)} \bigwedge Z$
- Let $u = a_0 a_1 a_2 \dots \in \Sigma^\omega$ and $n \geq 0$ with $u, n \models \bigwedge Y$. Then, $\exists Z \in \text{Red}(Y)$ such that $u, n \models \bigwedge Z$ and $Z \in \text{Red}_\alpha(Y)$ for all $\alpha = \alpha_1 \cup \alpha_2 \in \mathcal{U}(\varphi)$ such that $u, n \models \alpha_2$.

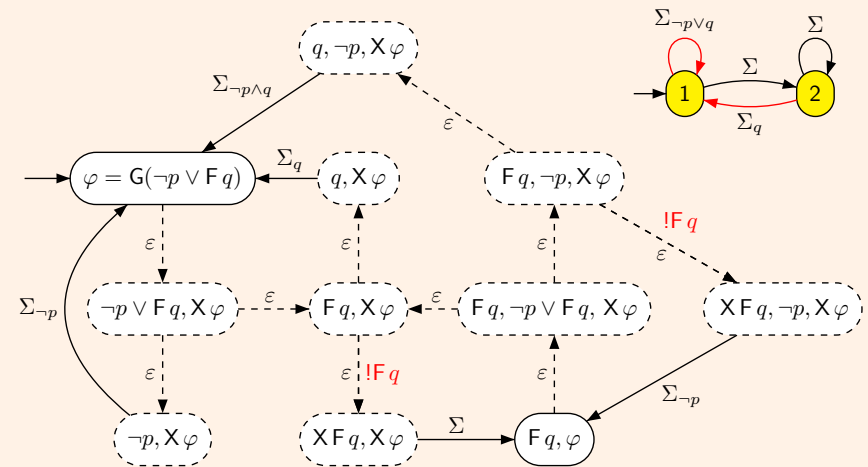
Automaton \mathcal{A}_φ

Definition: Automaton \mathcal{A}_φ

- States: $Q = 2^{\text{sub}(\varphi)}$, $I = \{\varphi\}$
- Transitions: $T = \{Y \xrightarrow{a} \text{next}(Z) \mid Y \in Q, a \in \Sigma_Z \text{ and } Z \in \text{Red}(Y)\}$
- Acceptance: $T_\alpha = \{Y \xrightarrow{a} \text{next}(Z) \mid Y \in Q, a \in \Sigma_Z \text{ and } Z \in \text{Red}_\alpha(Y)\}$ for each $\alpha \in \mathcal{U}(\varphi)$.

Automaton \mathcal{A}_φ

Example: $\varphi = G(p \rightarrow F q)$



Transition = check literals and move forward.

Simplification