

Refinements and Abstractions of Signal-Event (Timed) Languages

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Outline

1 Introduction

Signal-Event (Timed) Words and Automata

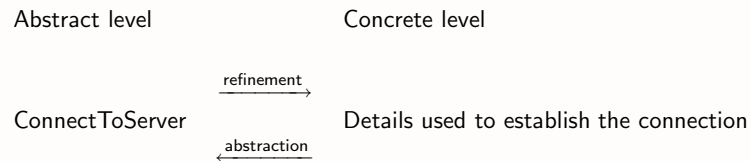
Signal-Event (Timed) Substitutions

Closure under substitutions

Closure under inverse substitutions

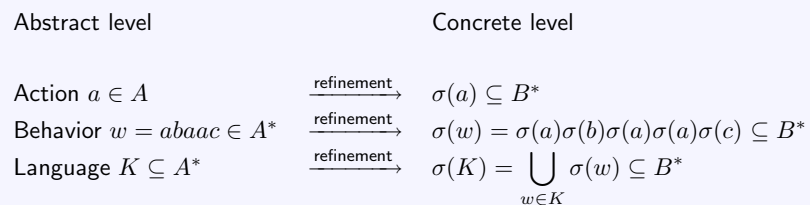
Conclusion

Refinements and Abstractions

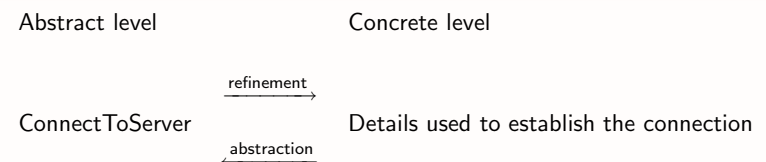


Formalisation of refinement

Let $\sigma : A \rightarrow \mathcal{P}(B^*)$ be a substitution.

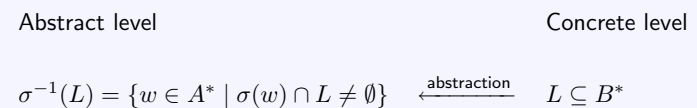


Refinements and Abstractions



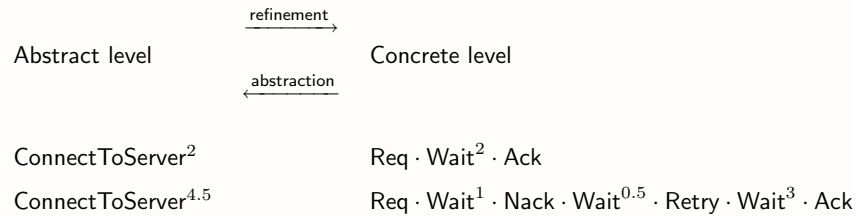
Formalisation of abstraction

Let $\sigma : A \rightarrow \mathcal{P}(B^*)$ be a substitution.



Adding time to the picture

Timed refinement



An abstract action a with duration d should be replaced by a concrete execution (word) w with the same duration $\|w\| = d$.

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Signal-Event (Timed) Words

Asarin - Caspi - Maler 2002

- Σ_e finite set of (instantaneous) events
- Σ_s finite set of signals
- \mathbb{T} time domain, $\overline{\mathbb{T}} = \mathbb{T} \cup \{\infty\}$
- $\Sigma = \Sigma_e \cup (\Sigma_s \times \mathbb{T})$
- Notation: a^d for $(a, d) \in \Sigma_s \times \overline{\mathbb{T}}$
- Σ^∞ set of **signal-event (timed) words**
Example: $a^3 f f g b^{1.5} a^2 f$
- Signal stuttering: $a^2 a^3 \approx a^5$, $a^\infty = a^2 a^2 a^2 \dots$

Signal-Event (Timed) Words

Unobservable signal τ

- Useful to hide signals:

Signal-event word $\xrightarrow{\text{hiding signals}}$ Classical timed words

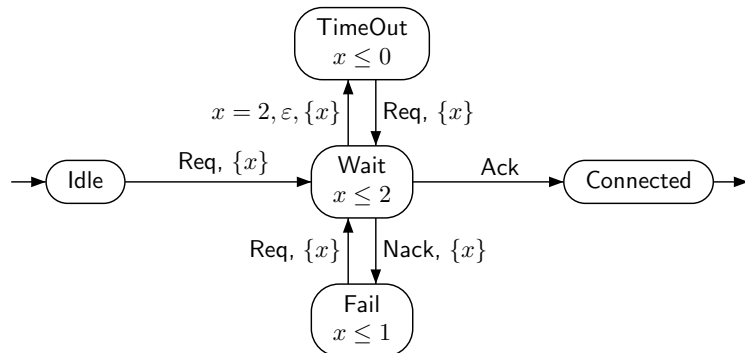
$$a^3 f b^1 g f a^2 f$$

$$\tau^3 f \tau^1 g f \tau^2 f = (f, 3)(g, 4)(f, 4)(f, 6)$$

- $\tau^0 \approx \varepsilon$: an hidden signal with zero duration is not observable.
- $a^0 \not\approx \varepsilon$: a signal, even of zero duration, is observable.
- $\tau^2 \not\approx \varepsilon$: we still observe a time delay but the actual signal has been hidden.
Example: $a^2 \tau^0 a^1 f \tau^0 g \tau^1 f b^2 b^2 \dots \approx a^3 f g \tau^1 f b^\infty$
- Signal-event words $SE(\Sigma) = \Sigma^\infty / \approx$

Signal-Event (Timed) automata

- States emit signals
- Transitions emit (instantaneous) events



- Run : Idle³ · Req · Wait² · TimeOut⁰ · Req · Wait¹ · Ack · Connected⁸
- SEL : languages accepted by SE-automata without ε-transitions.
- SEL_ε : languages accepted by SE-automata with ε-transitions.

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Signal-Event (Timed) Substitutions

Definition

- Abstract alphabet : Σ_e and Σ_s
- Concrete alphabet : Σ'_e and Σ'_s
- Substitution σ from $SE(\Sigma)$ to $SE(\Sigma')$ defined by:

$$a \in \Sigma_e : L_a \subseteq (\Sigma'_e \cup \Sigma'_s \times \{0\})^*$$

$$\sigma(a) = L_a$$

$a \in \Sigma_s \setminus \{\tau\} : L_a \subseteq SE(\Sigma')$ not containing Zeno words.

$$\sigma(a^d) = \{w \in L_a \mid \|w\| = d\}$$

$$a = \tau : L_\tau = \{\tau\} \times \overline{\mathbb{T}}$$

$$\sigma(\tau^d) = \{\tau^d\}$$

Remark

If we allow Zeno words in L_a then we may get transfinite words as refinements.
 Example: if $b^1 f b^{1/2} f b^{1/4} f \dots \in L_a$ and $L_g = \{g\}$ then $\sigma(a^2 g)$ is transfinite.

Signal-Event (Timed) Substitutions

Remark

In general, SE-substitutions are not morphisms

Example: if $L_a = \{b^2\}$ then $\sigma(a^1) = \emptyset$ and $\sigma(a^2) \neq \sigma(a^1)\sigma(a^1)$

Substitutions are applied to SE-words in normal form:

$$\sigma(a^2 \tau^0 a^1 f \tau^0 g \tau^1 f b^2 b^2 b^2 \dots) = \sigma(a^3)\sigma(f)\sigma(g)\tau^1\sigma(f)\sigma(b^\infty)$$

Proposition

Let σ be a timed substitution, given by a family $(L_a)_{a \in \Sigma_e \cup \Sigma_s}$.
 Then, σ is a morphism if and only if for each signal $a \in \Sigma_s$ we have

- L_a is closed under concatenation:
for all $u, v \in L_a$ with $\|u\| < \infty$, we have $uv \in L_a$,
- L_a is closed under decomposition:
for each $v \in L_a$ with $\|v\| = d$, for all $d_1 \in \mathbb{T}$, $d_2 \in \overline{\mathbb{T}}$ such that $d = d_1 + d_2$, there exist $v_i \in L_a$ with $\|v_i\| = d_i$ such that $v = v_1 v_2$.

Recognizable substitutions

Definition

Let σ be a substitution defined by $(L_a)_{a \in \Sigma_e \cup \Sigma_s}$. Then,

- σ is a *SEL* – substitution if each L_a is in *SEL*
- σ is a *SEL $_\epsilon$* – substitution if each L_a is in *SEL $_\epsilon$*

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Closure under substitutions

SEL is not closed under *SEL* – substitution

- $L = \{a^0 f\}$ is recognized by
- $L_a = \{b\} \times \mathbb{T}$ is recognized by
- $L_f = \{c^0 g\}$ is recognized by
- $\sigma(L) = \{b^0 c^0 g\}$ cannot be accepted without ϵ -transitions.

Theorem

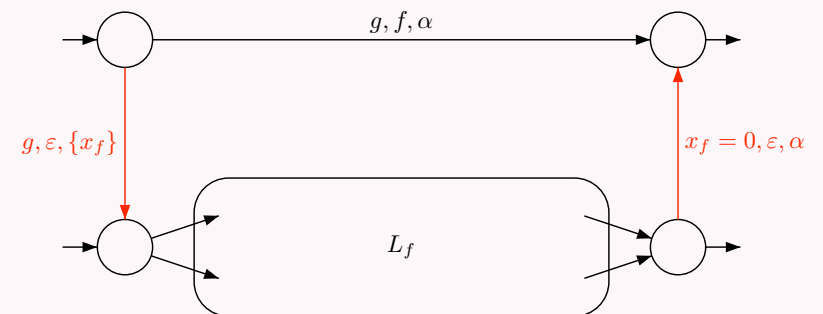
- The class *SEL $_\epsilon$* is closed under *SEL $_\epsilon$* -substitutions.
- The class *SEL* is closed under *SEL*-substitution satisfying $L_f \subseteq \Sigma'_e((\Sigma'_s \times \{0\})\Sigma'_e)^*$ for each $f \in \Sigma_e$, i.e., each word in L_f must start and end with an instantaneous event.

Closure under substitutions

Theorem

- The class *SEL $_\epsilon$* is closed under *SEL $_\epsilon$* -substitutions.
- The class *SEL* is closed under *SEL*-substitution satisfying $L_f \subseteq \Sigma'_e((\Sigma'_s \times \{0\})\Sigma'_e)^*$ for each $f \in \Sigma_e$.

Handling **events** is easy for *SEL $_\epsilon$* -substitutions.

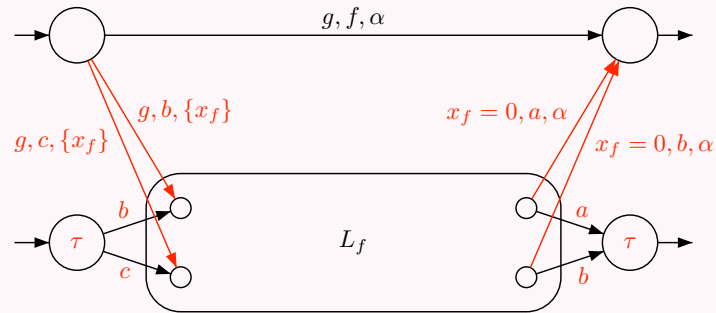


Closure under substitutions

Theorem

1. The class SEL_ε is closed under SEL_ε -substitutions.
2. The class SEL is closed under SEL -substitution satisfying $L_f \subseteq \Sigma'_e((\Sigma'_s \times \{0\})\Sigma'_e)^*$ for each $f \in \Sigma_e$.

Handling **events** is easy for SEL -substitutions.

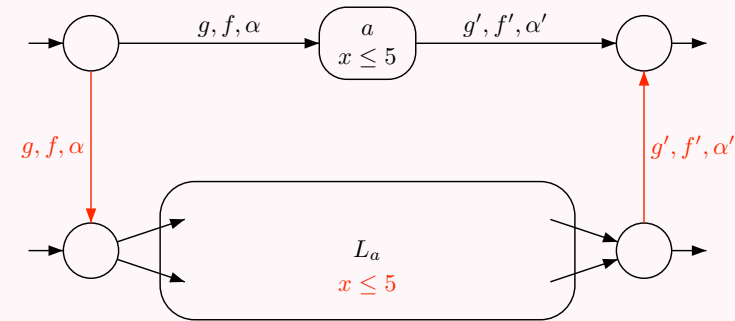


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Handling **signals** is easy for SEL -substitutions.

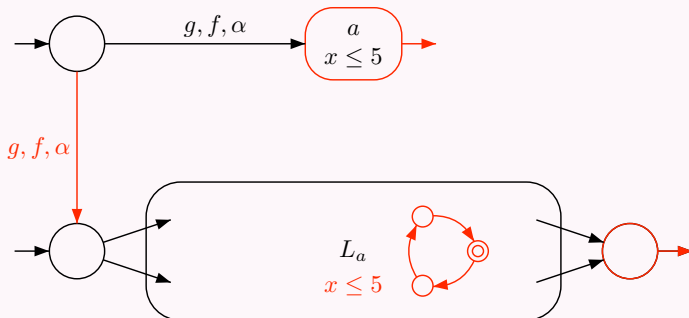


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Handling **signals** is easy for SEL -substitutions.



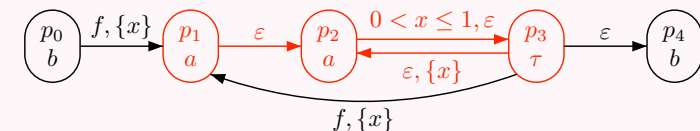
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Handling **signals** for SEL_ε -substitutions is **harder**.

Remember that substitutions are applied to SE-words in **normal form**.



A possible run gives : $f a^{0.3} a^{0.6} \tau^0 a^{0.5} \tau^1 a^{0.6} \tau^0 a^{0.5} \tau^0 b^3 \approx f a^{1.4} \tau^1 a^{1.1} b^3$

We have to synchronize a -blocks of \mathcal{A} with the automaton \mathcal{A}_a taking into account τ -states that may be crossed instantaneously.

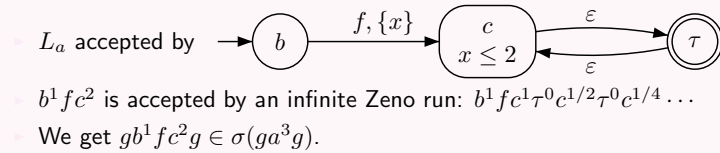
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Handling signals for SEL_ε -substitutions is harder.

Zeno runs in \mathcal{A}_a must be removed.



We have to replace the Zeno run of \mathcal{A}_a by a finite run.

Normal form for SE-automata

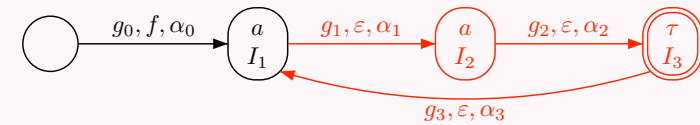
Theorem

Let \mathcal{A} be a SE-automaton. We can effectively construct an equivalent SE-automaton \mathcal{A}' such that:

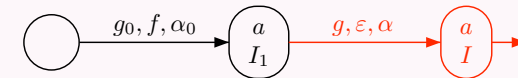
1. no infinite run of \mathcal{A}' accepts a finite word with finite duration, and
2. no finite run of \mathcal{A}' accepts a word with infinite duration.

Main problem

We have to replace infinite accepting ε -loops



by finite accepting runs.



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Closure under inverse substitutions

Theorem

1. The class SEL_ε is closed under inverse SEL_ε -substitution.
2. The class SEL is closed under inverse SEL -substitution acting only on events: $L_a = \{a\} \times \mathbb{T}$ for all $a \in \Sigma_s$.

The class SEL is not closed under arbitrary inverse SEL -substitution

Let $\Sigma_s = \Sigma'_s = \{a, b\}$ and $\Sigma_e = \Sigma'_e = \{f\}$.

Let σ be the SEL -substitution defined by $L_a = \{a^1 f\}$, $L_b = \{b^0\}$ and

$L_f = \{f\}$.

$L = \{a^1 f b^0\}$ is a SEL .

$\sigma^{-1}(L) = \{a^1 b^0\}$ is not a SEL .

Closure under inverse substitutions

Theorem

1. The class SEL_ε is closed under inverse SEL_ε -substitution.
2. The class SEL is closed under inverse SEL -substitution acting only on events:
 $L_a = \{a\} \times \overline{\mathbb{T}}$ for all $a \in \Sigma_s$.

Proof: word case

- Let $\sigma : A \rightarrow \mathcal{P}(B^*)$ be a rational substitution
- Let $\Pi_A : (A \uplus B)^* \rightarrow A^*$ and $\Pi_B : (A \uplus B)^* \rightarrow B^*$ be the projections
- Let $M = \left(\bigcup_{a \in A} a\sigma(a) \right)^* \subseteq (A \uplus B)^*$ is rational.
- Then, $\sigma^{-1}(L) = \Pi_A(\Pi_B^{-1}(L) \cap M)$

Closure under inverse substitutions

Theorem

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 $L_a = \{a\} \times \overline{\mathbb{T}}$ for all $a \in \Sigma_s$.

Proof: Signal-event words

- Let $\hat{\Sigma}_e = \Sigma_e \uplus \Sigma'_e$ and $\hat{\Sigma}_s = \Sigma_s \times \Sigma'_s$.
- Let $\Pi_1 : SE(\hat{\Sigma}) \rightarrow SE(\Sigma)$ and $\Pi_2 : SE(\hat{\Sigma}) \rightarrow SE(\Sigma')$ be the natural projections
- $\sigma^{-1}(L) = \Pi_1(\Pi_2^{-1}(L) \cap M)$ for a suitable language M , in the class SEL_ε .
 if $f \in \Sigma_e$ then $f \cdot \sigma(f)$ is replaced by
 $f \cdot \{w \in SE(\hat{\Sigma}) \mid w = (\tau, b_0)^0 f_1 (\tau, b_1)^0 f_2 \cdots (\tau, b_n)^0 \text{ with } b_0^0 f_1 b_1^0 f_2 \cdots b_n^0 \in \sigma(f)\}$
- if $a \in \Sigma_s$ then $a \cdot \sigma(a)$ is replaced by
 $\{w \in SE(\hat{\Sigma}) \mid w = (a, b_0)^{d_0} f_1 (a, b_1)^{d_1} f_2 \cdots \text{ with } b_0^{d_0} f_1 b_1^{d_1} f_2 \cdots \in \sigma(a^{d_0+d_1+\cdots})\}$
- If L is in the class SEL_ε , then so is $\Pi_2^{-1}(L)$.
- The class SEL_ε is closed under intersection.

Closure under intersection

Remark

- Easy for the class SEL or for classical timed languages.
- More difficult with signals and ε -transitions due to stuttering and unobservability of τ^0 .
- Asarin, Caspi and Maler 97 did not deal with these difficulties and considered finite runs only.
 Asarin, Caspi and Maler 02 deals with the intersection of classical timed automata only.
- Dima 00 gives a construction to remove stuttering for automata with a single clock.
- Durand-Lose 04 gives a construction for intersection taking stuttering into account but restricted to finite runs and without zero-duration signals.
 His approach do not extend to infinite runs since it would introduce Zeno runs leading to transfinite problems

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