

Local testing of MSCs

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Joint work with

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Plan

1 MSC

HMSC

Local testing of HMSC

Undecidability of 1-testability for 2 processes

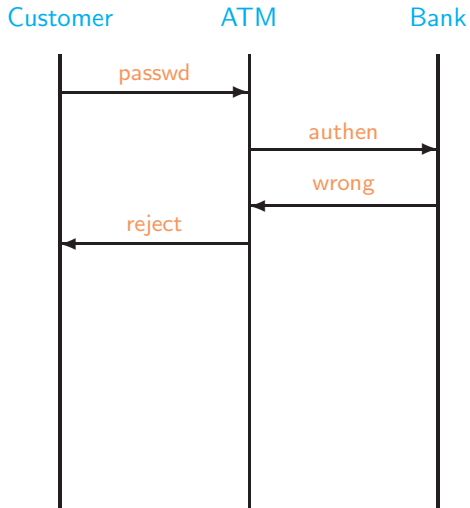
Undecidability of k -testability

Decidability of 1-testability without message contents

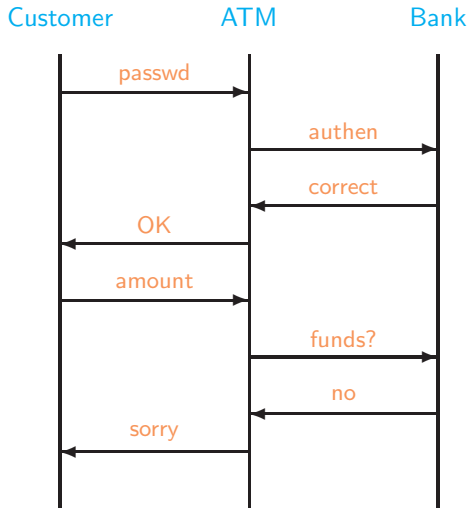
Scenarios

- ▶ A scenario describes a pattern of interaction
- ▶ Attractive visual formalism
- ▶ Telecommunications
 - ▶ Message sequence charts (MSC)
 - ▶ Messages sent between communicating agents
- ▶ UML
 - ▶ Sequence diagrams
 - ▶ Interaction between objects
e.g., method invocations etc

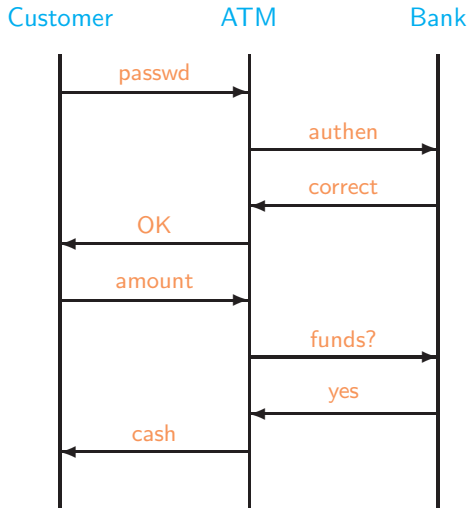
An ATM



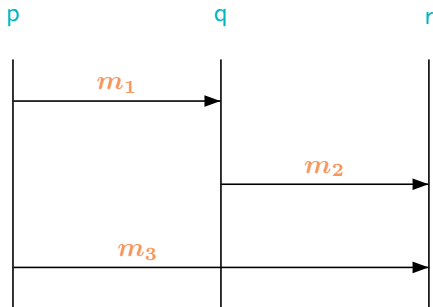
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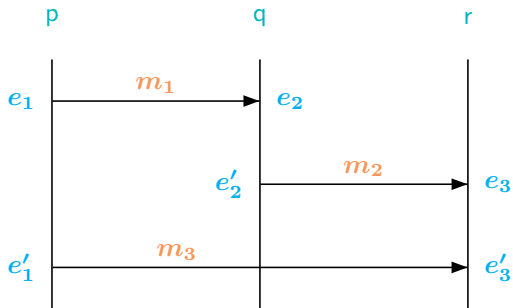
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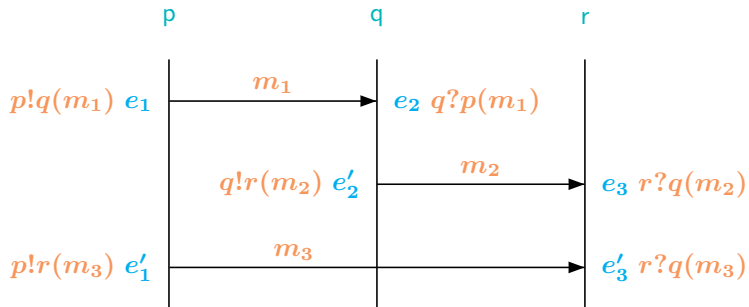
How do we formalize MSCs?



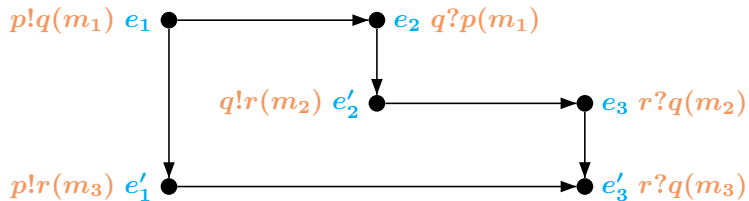
An MSC with events



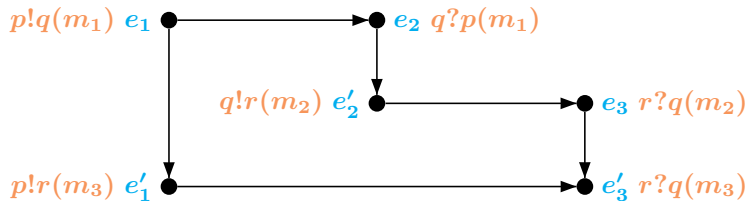
An MSC with labelled events



MSCs as labelled partial orders



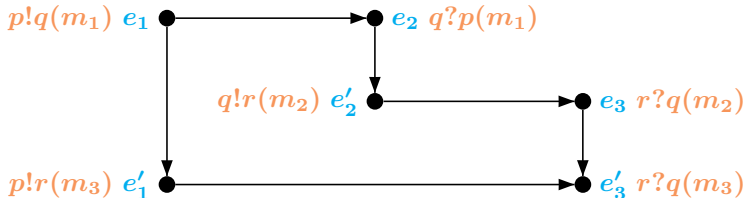
MSCs as labelled partial orders



- ▶ Linearizations give a word language

$p!q(m_1) p!r(m_3) q?p(m_1) q!r(m_2) r?q(m_2) r?q(m_3),$
 $p!q(m_1) q?p(m_1) q!r(m_2) p!r(m_3) r?q(m_2) r?q(m_3), \dots$

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 $p!q(m_1) q?p(m_1) q!r(m_2) p!r(m_3) r?q(m_2) r?q(m_3), \dots$

- ▶ A single linearization is sufficient to reconstruct MSC

Plan

MSC

2 HMSC

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Collections of MSCs

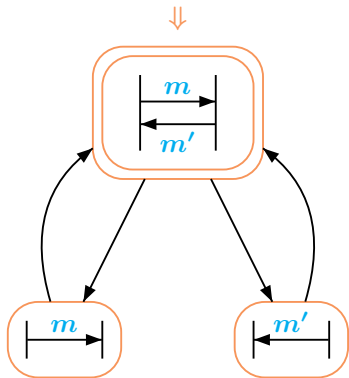
- ▶ Often need to specify a collection of scenarios
- ▶ Finite collection can be exhaustively enumerated
- ▶ Infinite collection needs a generating mechanism

High level MSCs (HMSCs)

- ▶ A finite state automaton
- ▶ Each state is labelled by an MSC
- ▶ Each (legal) path in the automaton generates an MSC

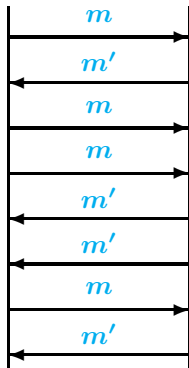
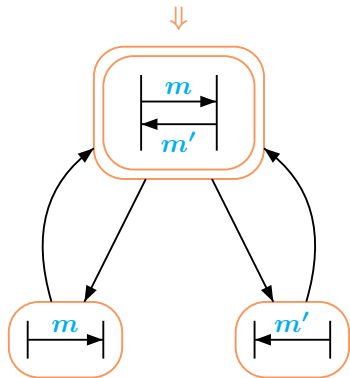
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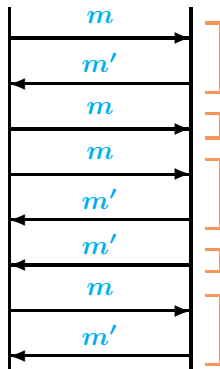
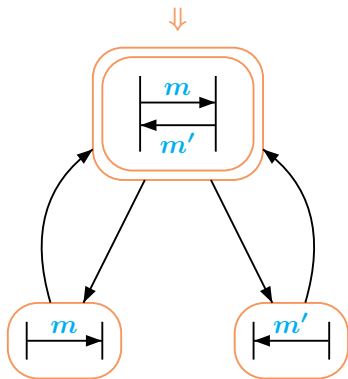
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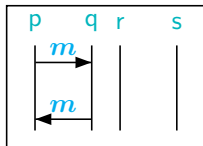
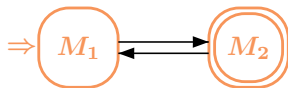
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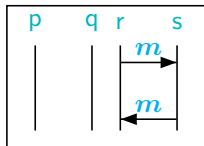
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HMSC semantics

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- ▶ ... but processes move asynchronously
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M_1



M_2

- ▶ After k iterations, we could have r and s in the final copy of M_2 while p and q are in the first copy of M_1

Regular MSC languages

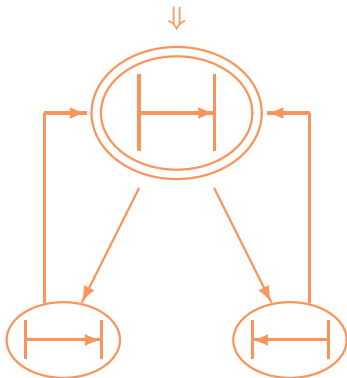
- ▶ An MSC is (uniquely) determined by its linearizations
 - ▶ Set of strings over send actions $p!q(m)$ and receive actions $p?q(m)$
- ▶ Collection of MSCs \Leftrightarrow
word language over send/receive actions
- ▶ Regular collection of MSCs $\stackrel{\Delta}{\equiv}$
linearizations form a regular language

HMSCs and regularity

- ▶ HMSC specifications may not be regular

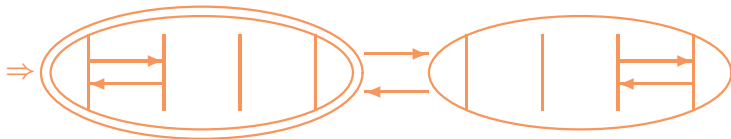
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- ▶ Sufficient structural conditions on HMSCs to guarantee regularity

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[AY99,MP99]

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HMSCs and regularity

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... [AY99,MP99]
 - ▶ **Locally synchronized**
- ▶ ... but checking if an HMSC specification is regular is undecidable [HMNST05]
- ▶ Every regular MSC language can be implemented as network of communicating finite-state automata with bounded channels [HMNST05]

Plan

MSC

HMSC

3 Local testing of HMSC

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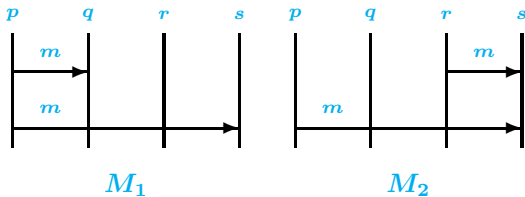
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 - ▶ For each process p , local observer records sequence of events at p
 - ▶ If each local observation is consistent with some MSC defined by the HMSC, the implementation passes the test

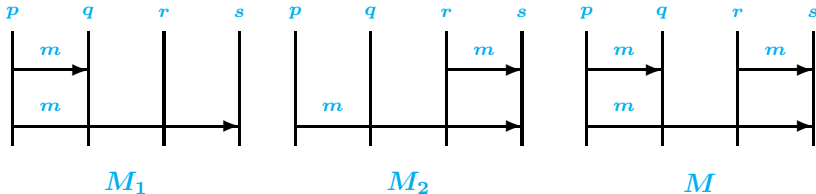
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- ▶ Does local testing suffice to check conformance of (regular) HMSC languages?

Implied scenarios [AEY00]

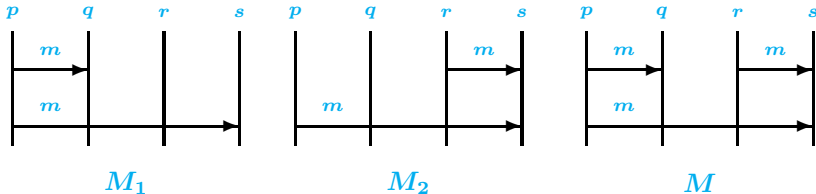


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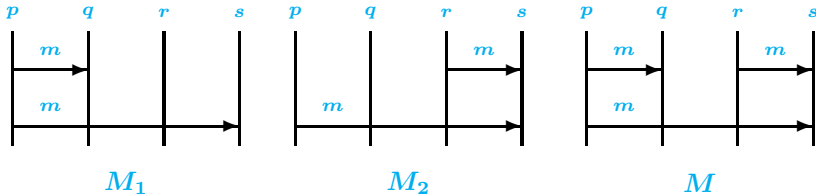
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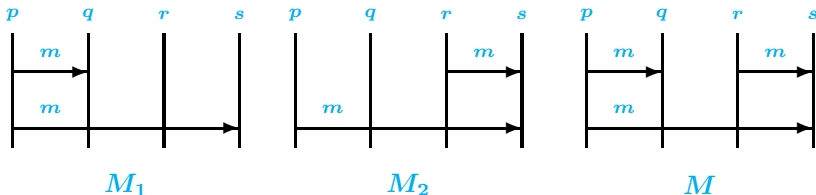
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- ▶ Originally studied in context of **realizability**

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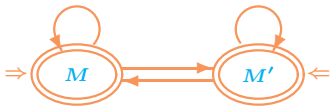
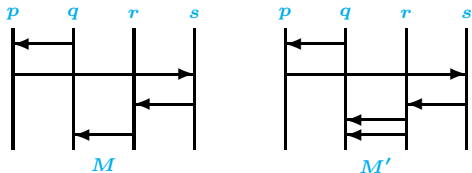
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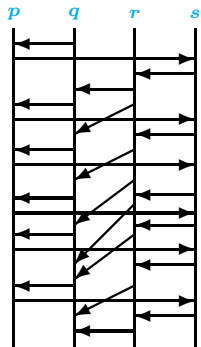
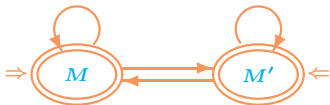
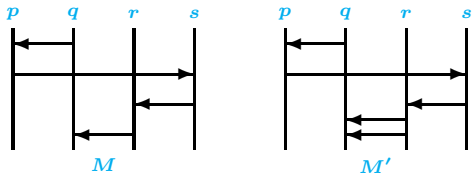
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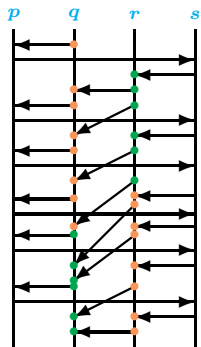
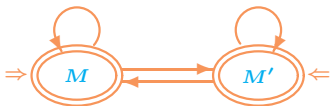
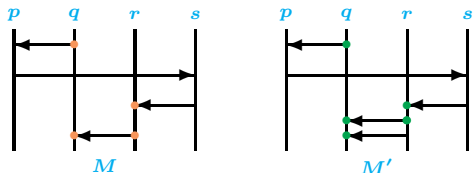
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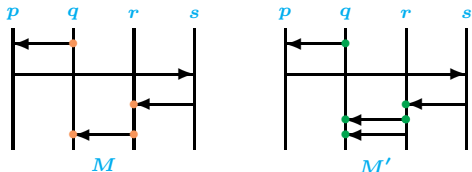
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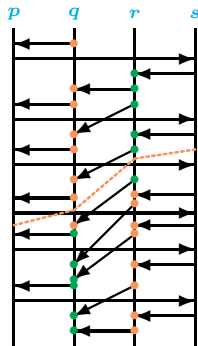


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Confusing $M^{2k}M'^k$ and M'^kM^{2k} generates upto k messages in $p \rightarrow s$ channel

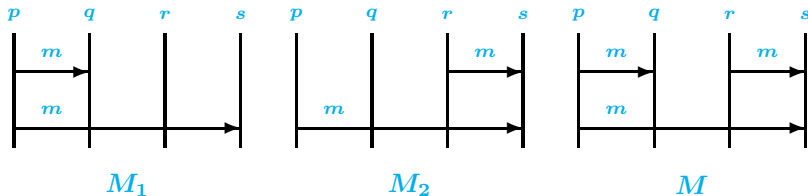


Joint observations

- ▶ What if we have observers who can record the behaviours of **sets** of processes?

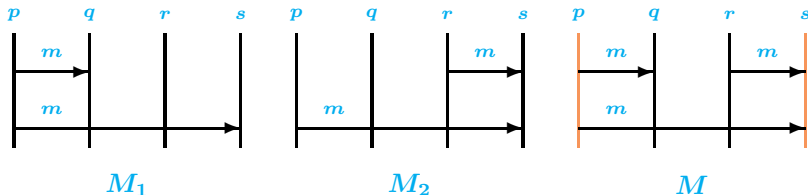
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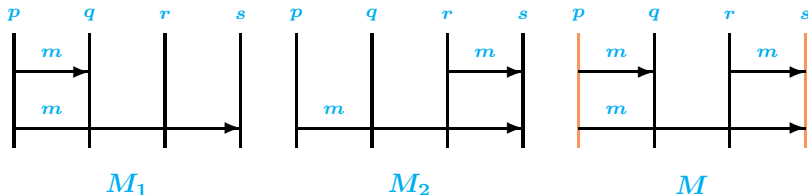
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- ▶ M is detected as an illegal MSC by $\{p, s\}$.
- ▶ Joint observers have more discriminating power.

Joint observations . . .

- ▶ Fix some *observers* P_1, P_2, \dots, P_r
- ▶ Each observer records the events on the processes in the set P_i

Joint observations ...

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Given a HMSC G , is its language testable with observers P_1, P_2, \dots, P_r ?

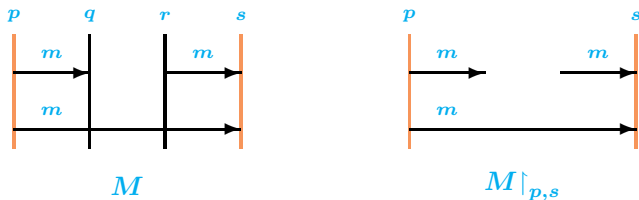
P-Observations

M an MSC, P a set of processes

P -observation of $M \triangleq$ tuple of projections of M on each process in P

$M \upharpoonright_P$: P -observation of M .

$L \upharpoonright_P = \{M \upharpoonright_P \mid M \in L\}$: P -observation of a language L



$$M \upharpoonright_{p,s} = \langle p!q(m)p!s(m), s?r(m)s?p(m) \rangle.$$

k -testability

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- ▶ Scenario k -implied by $L \triangleq$ MSC in the k -closure of L but not in L

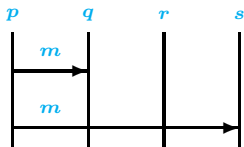
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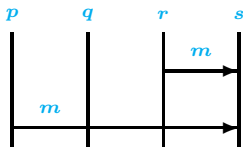
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- ▶ Local testability is 1 -testability

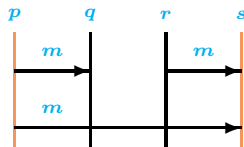
k -testability ...



M_1



M_2



M

The set $\{M_1, M_2\}$ is **2**-testable but not **1**-testable.

k -testability . . .

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- ▶ What about k -testability for $1 < k < n$?
- ▶ What is the smallest $k \leq n$ such that k -testability is decidable?

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Plan

MSC

HMSC

Local testing of HMSC

4 Undecidability of 1-testability for 2 processes

Undecidability of k -testability

Decidability of 1-testability without message contents

1-testability for 2 processes

Theorem : 2 processes

For $n \geq 2$, 1-testability is undecidable for regular 4-bounded MSG-definable languages over n processes.

Proof :

Reduction to Modified Post Correspondence Problem (MPCP).

Modified Post Correspondence Problem

Definition : MPCP

Instance: sequence $(v_1, w_1), (v_2, w_2), \dots, (v_r, w_r)$ of pairs of words such that

- ▶ $1 \leq |v_i| \leq 4$ and $1 \leq |w_i| \leq 4$ for $1 \leq i \leq r$,
- ▶ $w_1 < v_1$ and is shorter by at least 2 letters.

Solution: sequence $1 = i_1, i_2, i_3, \dots, i_m$ of indices from $\{1, 2, \dots, r\}$ such that

$$w_{i_1} w_{i_2} \cdots w_{i_m} = v_{i_1} v_{i_2} \cdots v_{i_m}$$

and for $k < m$,

$$w_{i_1} w_{i_2} \cdots w_{i_k} < v_{i_1} v_{i_2} \cdots v_{i_k}$$

Theorem : MPCP

The Modified Post Correspondence Problem is undecidable.

Undecidability: Reduction

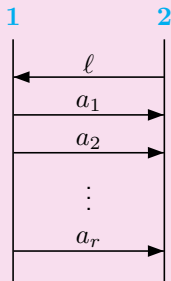
Proof :

Let $\Delta = (v_1, w_1), (v_2, w_2), \dots, (v_t, w_t)\}$ be an instance of the MPCP.

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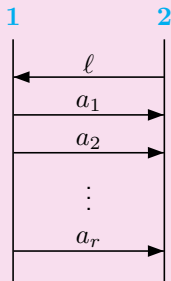


M_{v_ℓ} with $v_\ell = a_1 a_2 \dots a_r$

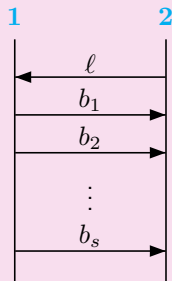
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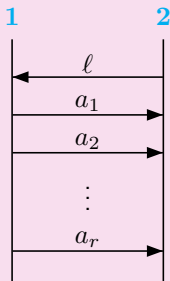


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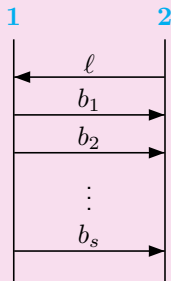
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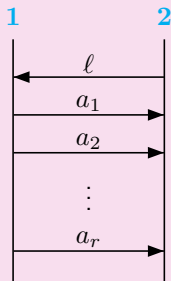
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$$L_\Delta = M_{v_1} \cdot \{M_{v_1}, \dots, M_{v_t}\}^* + M_{w_1} \cdot \{M_{w_1}, \dots, M_{w_t}\}^*$$

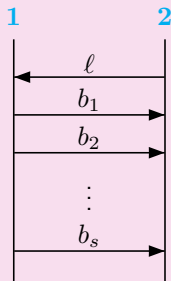
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Lemma :

The MPCP Δ has a solution iff L_Δ has some 1-implied scenario.

Undecidability: Reduction

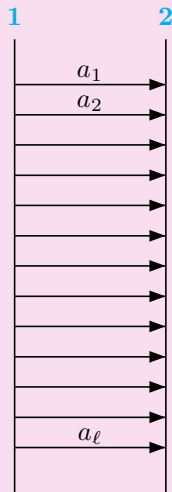
Proof : Let $1 = i_1, i_2, \dots, i_m$ be a solution of MPCP

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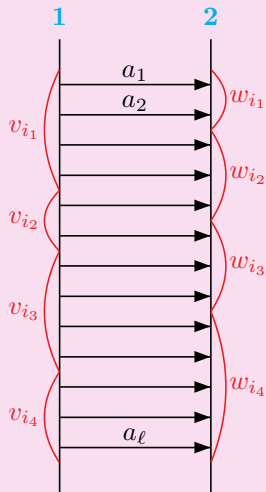
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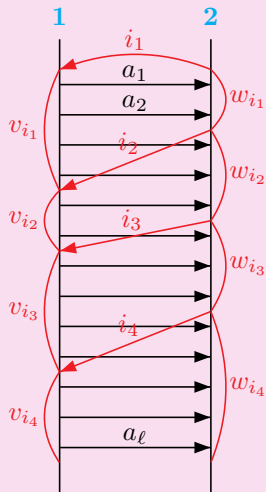
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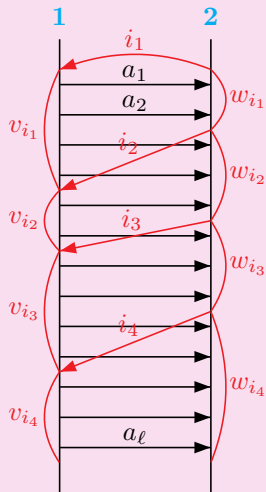
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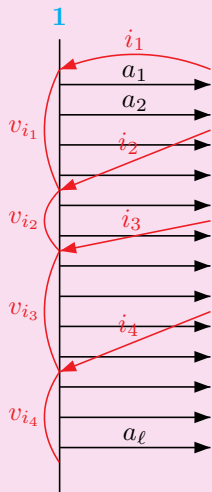
$$L = M_{v_1} \cdot \{M_{v_1}, \dots, M_{v_t}\}^* + M_{w_1} \cdot \{M_{w_1}, \dots, M_{w_t}\}^*$$

► $M \notin L$

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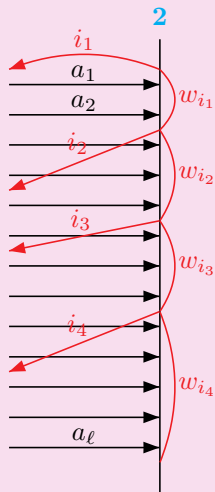
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- ▶ $M \upharpoonright_1 = (M_{v_{i_1}} M_{v_{i_2}} \dots M_{v_{i_m}}) \upharpoonright_1 \in L \upharpoonright_1$

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- ▶ $M \upharpoonright_2 = (M_{w_{i_1}} M_{w_{i_2}} \dots M_{w_{i_m}}) \upharpoonright_2 \in L \upharpoonright_2$

Plan

MSC

HMSC

Local testing of HMSC

Undecidability of 1-testability for 2 processes

5 Undecidability of k -testability

Decidability of 1-testability without message contents

k -testability

Theorem : k -testability

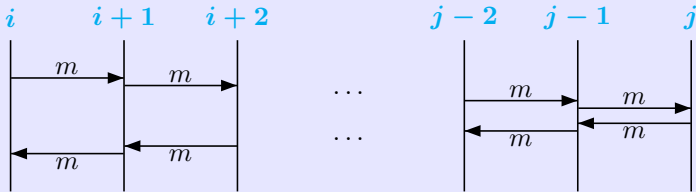
For $1 < k < n$, k -testability is undecidable for regular 1-bounded MSG-definable languages over n processes.

Proof :

Reduction to Modified Post Correspondence Problem (MPCP).

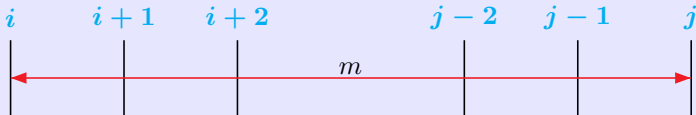
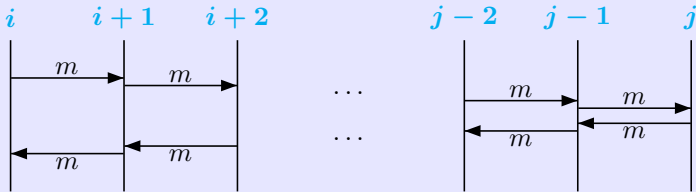
Undecidability: Reduction

A basic MSC



Undecidability: Reduction

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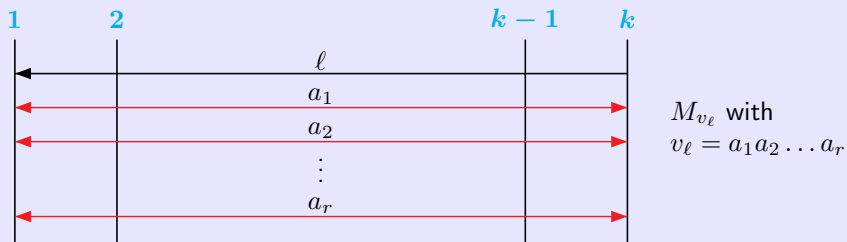


Undecidability: Reduction

Let $\Delta = (v_1, w_1), (v_2, w_2), \dots, (v_t, w_t)$ be an instance of the MPCP.

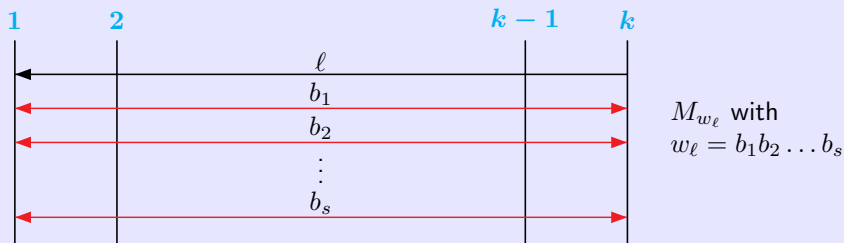
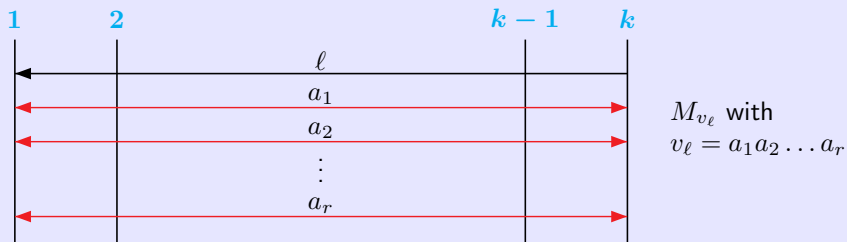
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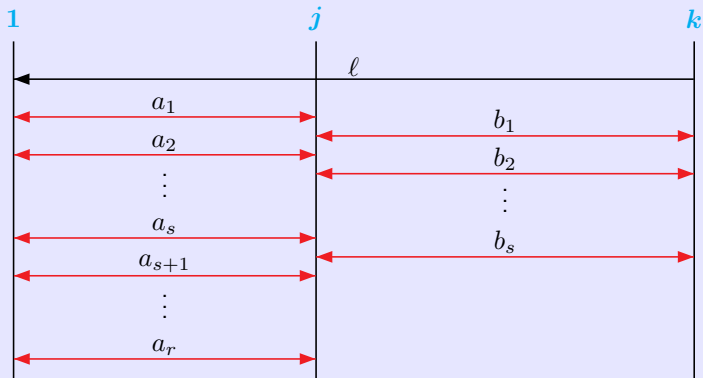
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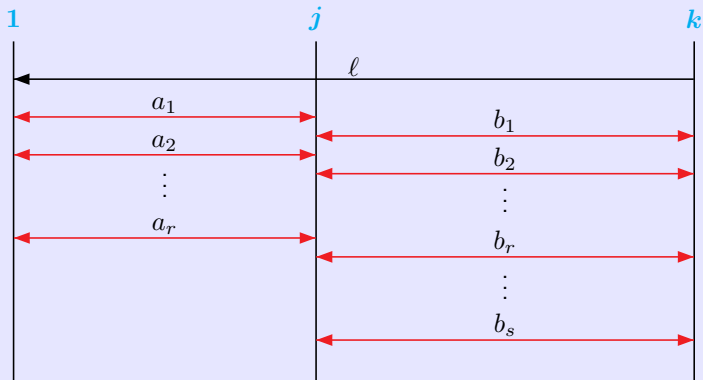
Let $\Delta = (v_1, w_1), (v_2, w_2), \dots, (v_t, w_t)$ be an instance of the MPCP.



M_{v_ℓ, w_ℓ}^j with $v_\ell = a_1 a_2 \dots a_r$ and $w_\ell = b_1 b_2 \dots b_s$

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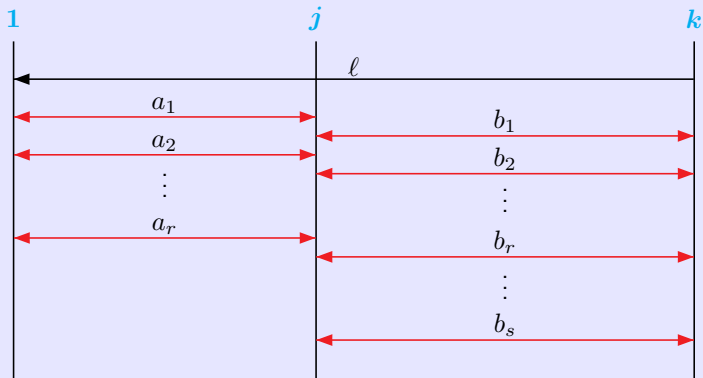
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$$L_\Delta = M_{v_1} \cdot \{M_{v_1}, \dots, M_{v_t}\}^* \cup M_{w_1} \cdot \{M_{w_1}, \dots, M_{w_t}\}^* \\ \cup \bigcup_j M_{v_1, w_1}^j \{M_{v_1, w_1}^j, \dots, M_{v_t, w_t}^j\}^*$$

Undecidability: Reduction

Lemma :

The MPCP Δ has a solution iff L_Δ has some $(k-1)$ -implied scenario.

Proof : Let $1 = i_1, i_2, \dots, i_m$ be a solution of MPCP

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We build an MSC $M \notin L_\Delta$ which is $(k-1)$ -implied by L_Δ .

Undecidability: Reduction

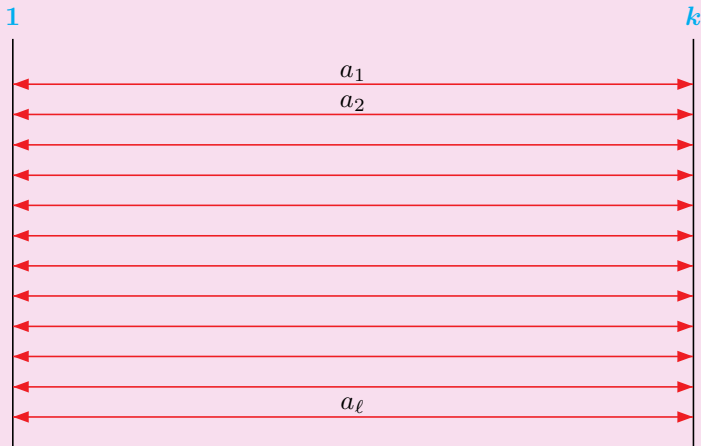
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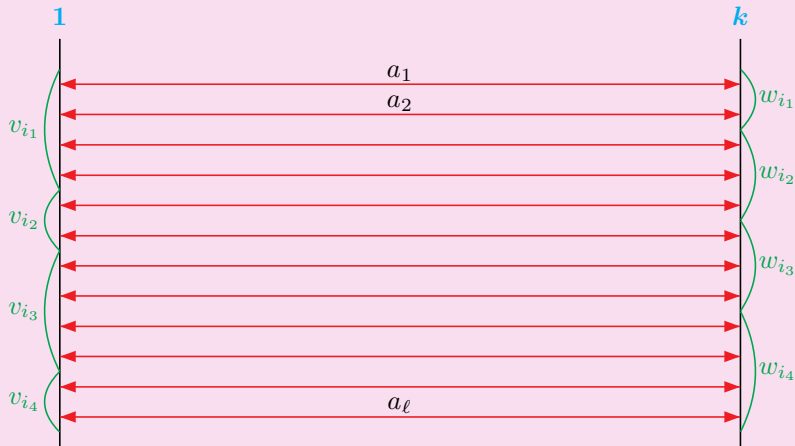
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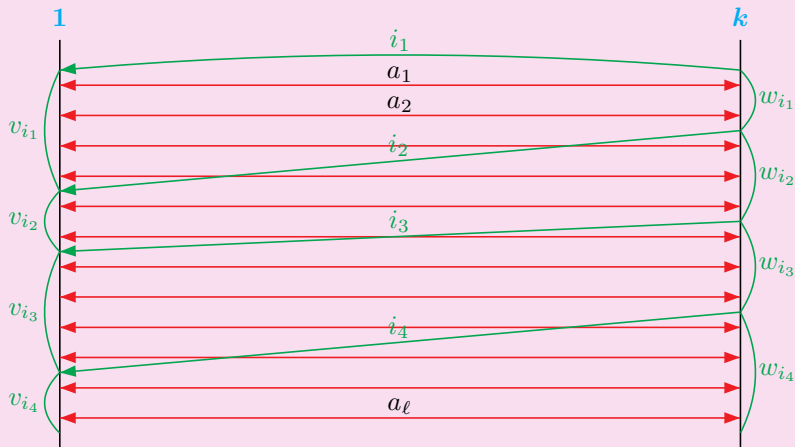
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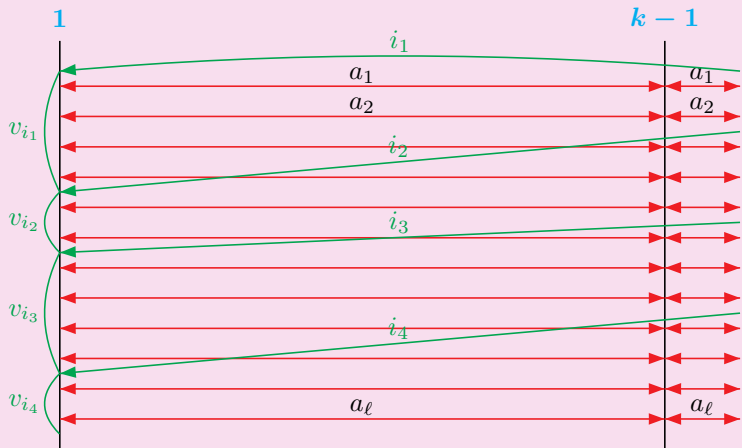


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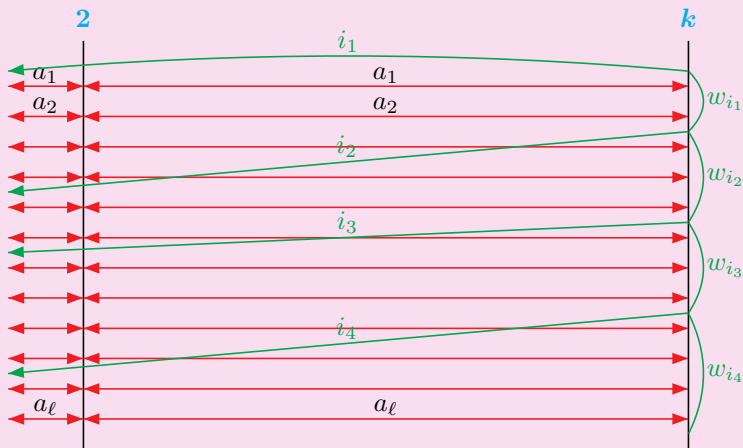


$$M \upharpoonright_{1, \dots, k-1} = (M_{v_{i_1}} M_{v_{i_2}} \dots M_{v_{i_m}}) \upharpoonright_{1, \dots, k-1}$$

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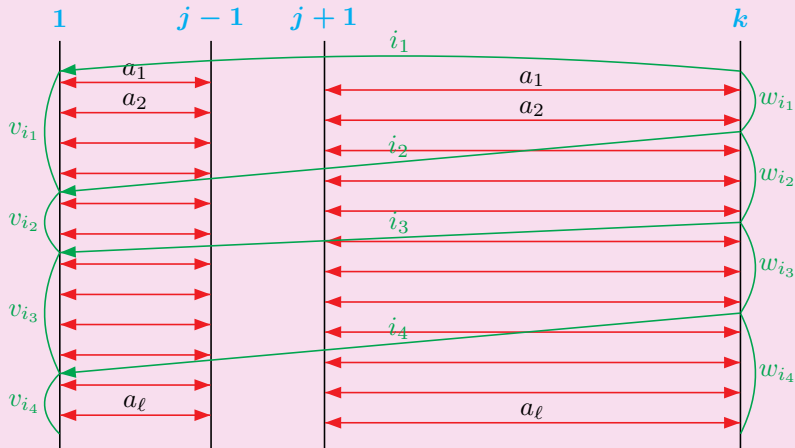


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$$M \upharpoonright_{1, \dots, j-1, j+1, \dots, k} = (M_{v_{i_1}, w_{i_1}}^j M_{v_{i_2}, w_{i_2}}^j \dots M_{v_{i_m}, w_{i_m}}^j) \upharpoonright_{1, \dots, j-1, j+1, \dots, k}$$

Plan

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6 Decidability of 1-testability without message contents

1-testability over the singleton alphabet

- ▶ Each channel behaves as counter

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- ▶ Special case of a result due to Morin [M02]

Future work

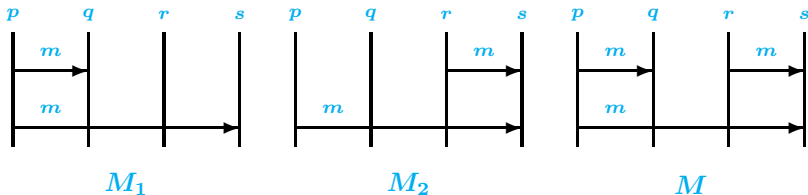
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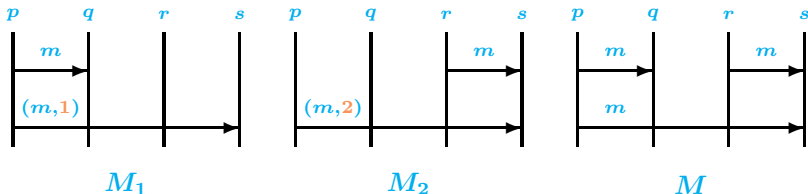
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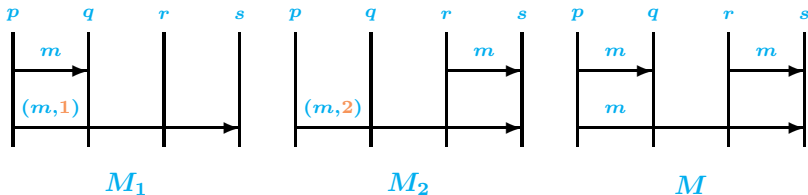
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By tagging auxiliary information to m ,
 p informs s whether it has sent a message to q
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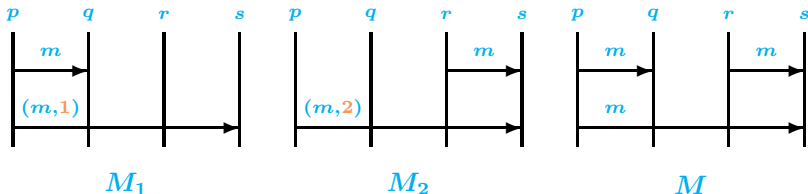


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- ▶ Can we piggyback a bounded amount of auxiliary information to ensure testability?
- ▶ Bounded auxiliary information suffices to check causal closure [AMNN05]