

Alpaga

A Tool for Solving Parity Games with
Imperfect Information

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Why imperfect
information ?

Example

```
void main () {
    int got_lock = 0;
    do {
1:         if (*) {
2:             lock ();
3:             got_lock++;
            }
4:         if (got_lock != 0) {
5:             unlock ();
            }
6:         got_lock--;
    } while (*);
}
```

```
void lock () {
    assert(L == 0);
    L = 1;
}
```

```
void unlock () {
    assert(L == 1);
    L = 0;
}
```

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```

Wrong!

```
void lock () {  
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Example

```
void main () {
    int got_lock = 0;
    do {
1:         if (*) {
2:             lock ();
3:             s0 | s1 | inc | dec;
           }
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5:             unlock ();
           }
6:         s0 | s1 | inc | dec;
    } while (*);
}
```

s0 ≡ got_lock = 0
s1 ≡ got_lock = 1
inc ≡ got_lock++
dec ≡ got_lock--

```
void lock () {
    assert(L == 0);
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void unlock () {
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```

Repair/synthesis as a game:

- System vs. Environment
- Turn-based game graph
- ω -regular objective

```
void lock () {
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```

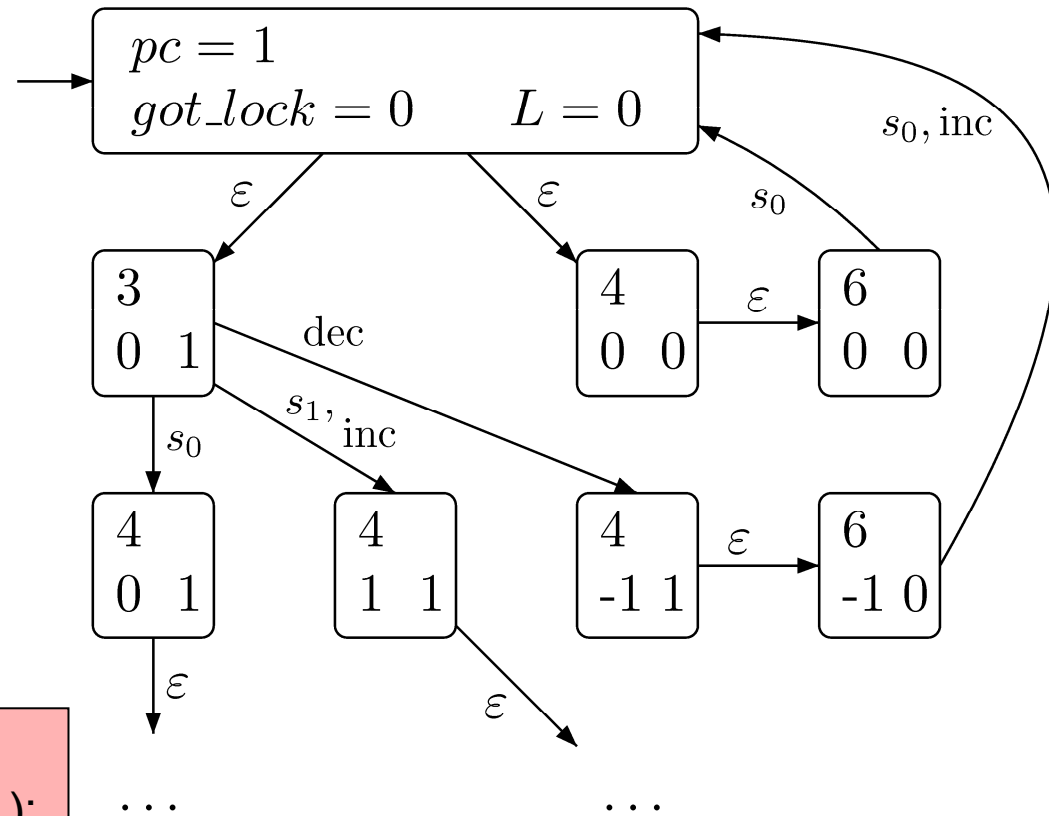
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Example

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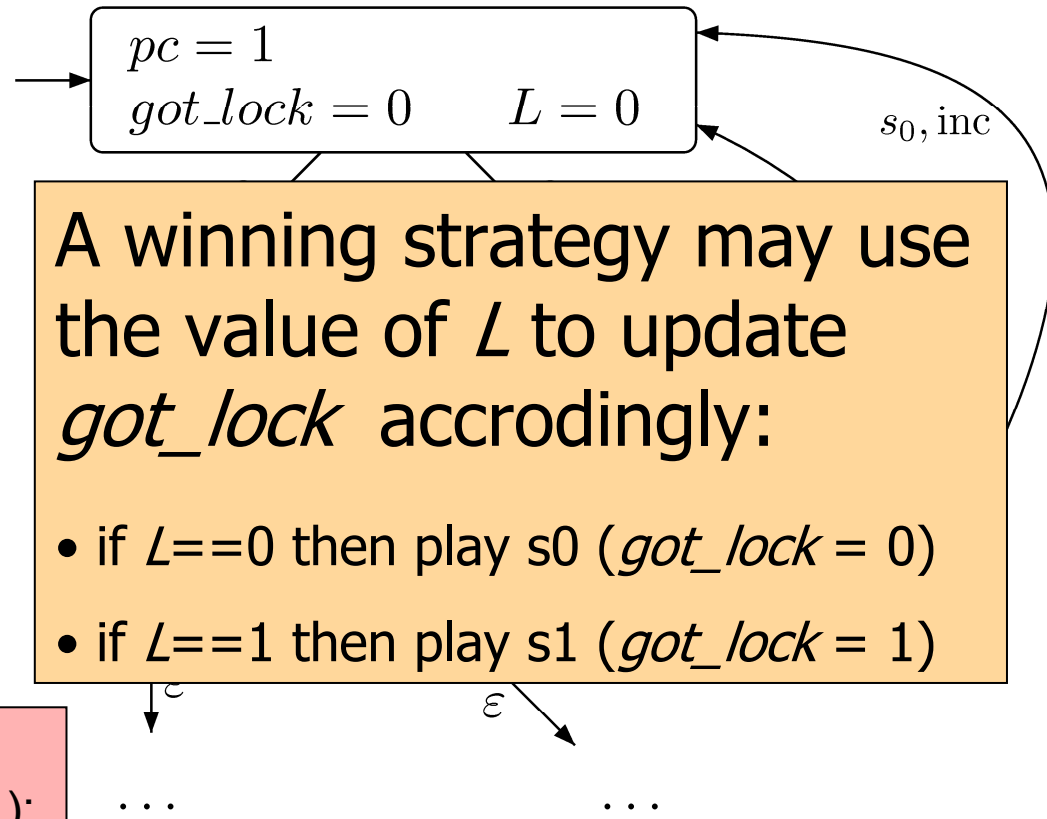


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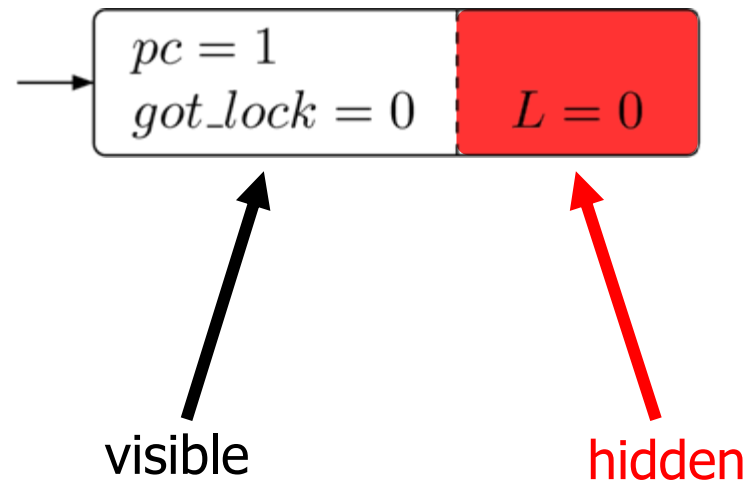
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Repair/synthesis as a game of **imperfect information**:



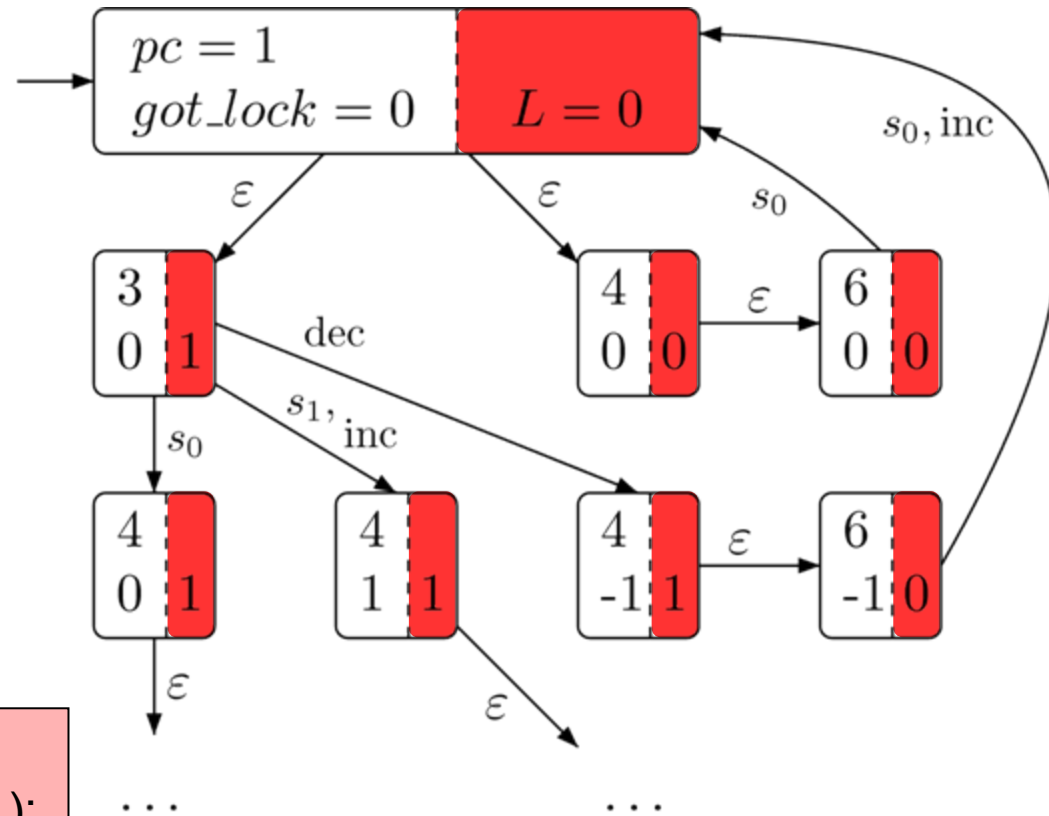
States that differ only by the value of L have the same observation

Example

```
void main () {  
  int got_lock = 0;  
  do {  
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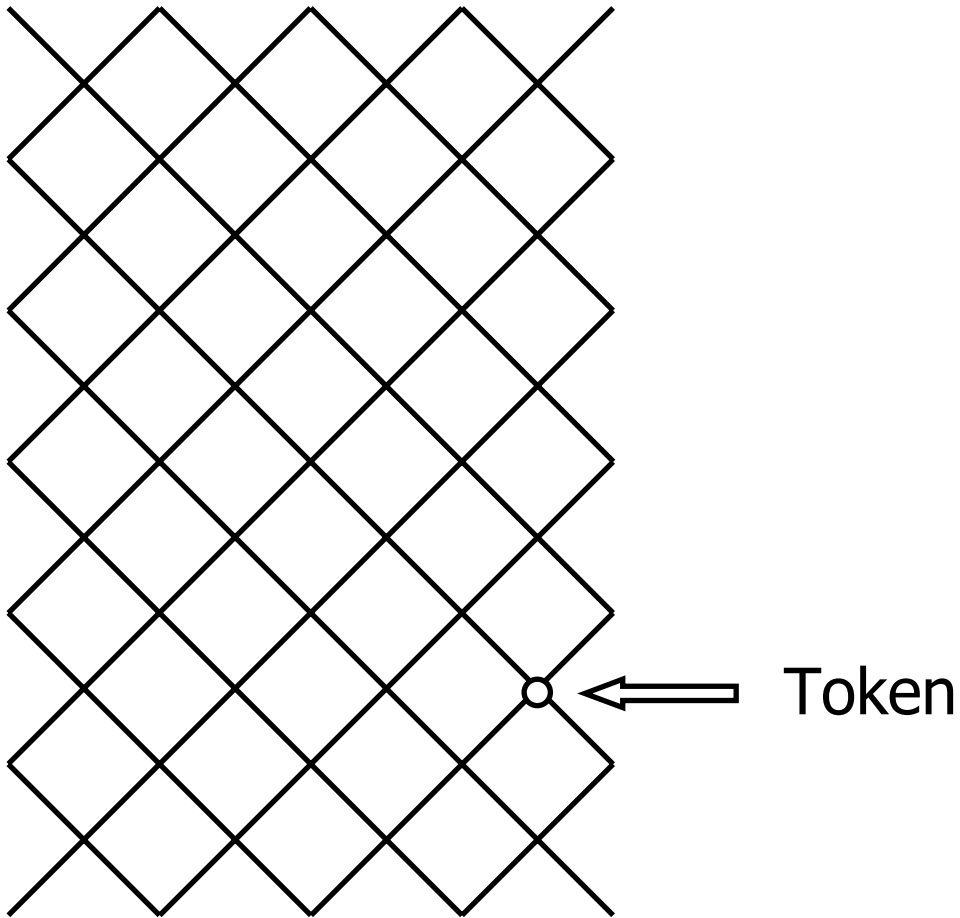


Why Imperfect Information ?

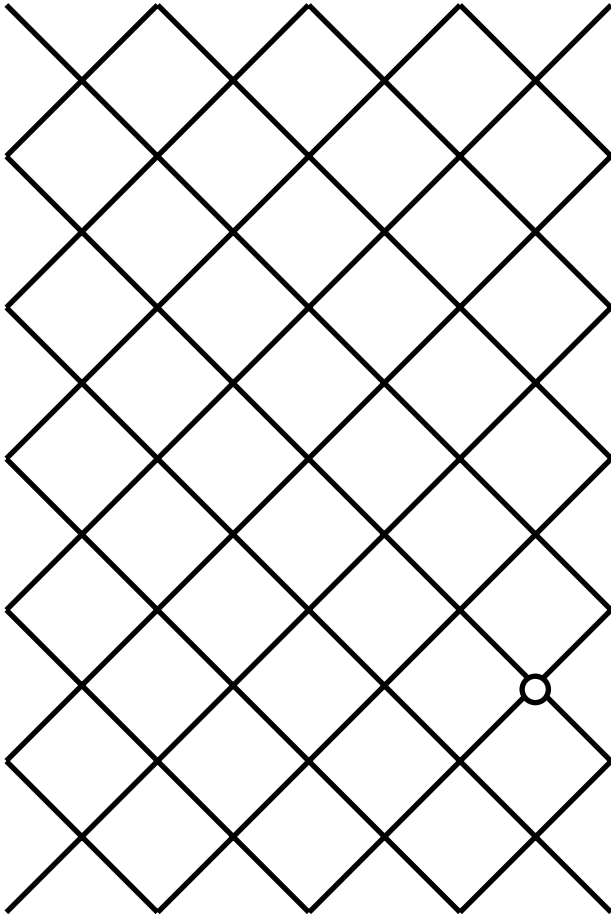
- Program repair/synthesis
- Distributed synthesis of processes with public/private variables
- Synthesis of robust controllers
- Synthesis of automata specifications
- Decision problems in automata theory
- Planning with partial observability, information flow secrecy, ...

A model of imperfect information

Imperfect information

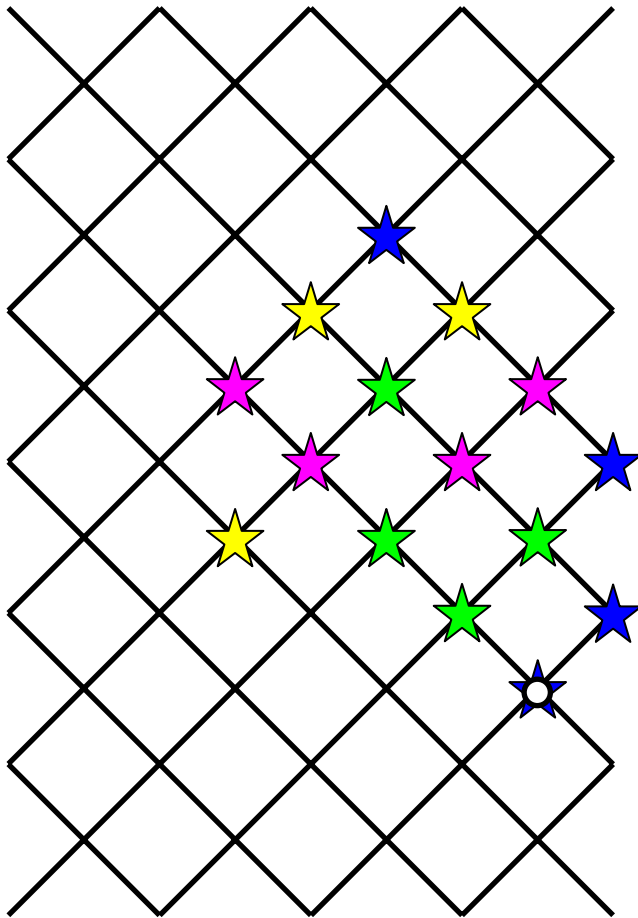


Imperfect information



System: actions \downarrow, \uparrow

Imperfect information

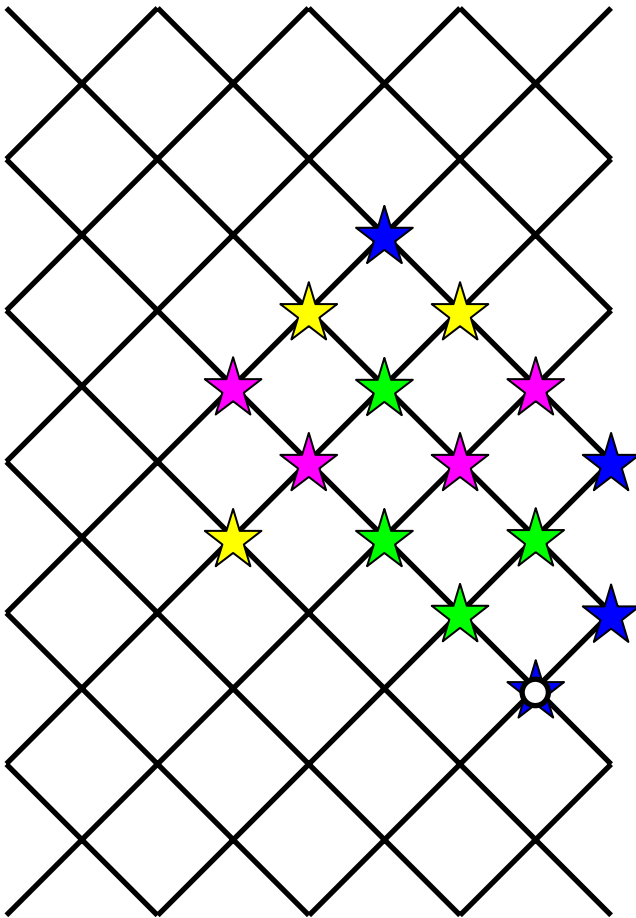


System: actions \downarrow, \uparrow

Environment: observations

★, ★, ★, ★

Imperfect information



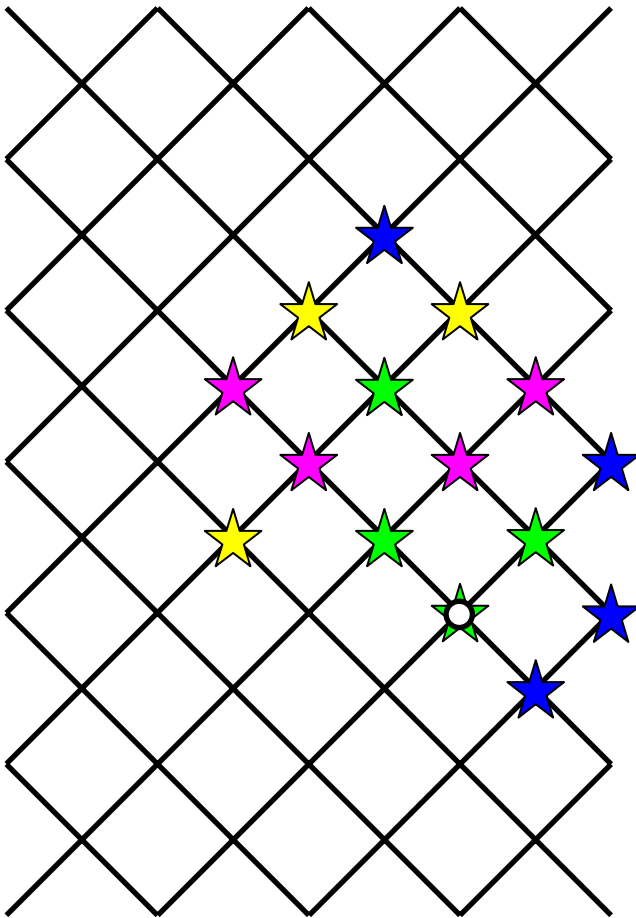
System: actions \downarrow, \uparrow

Environment: observations

★, ★, ★, ★

A play: ★

Imperfect information



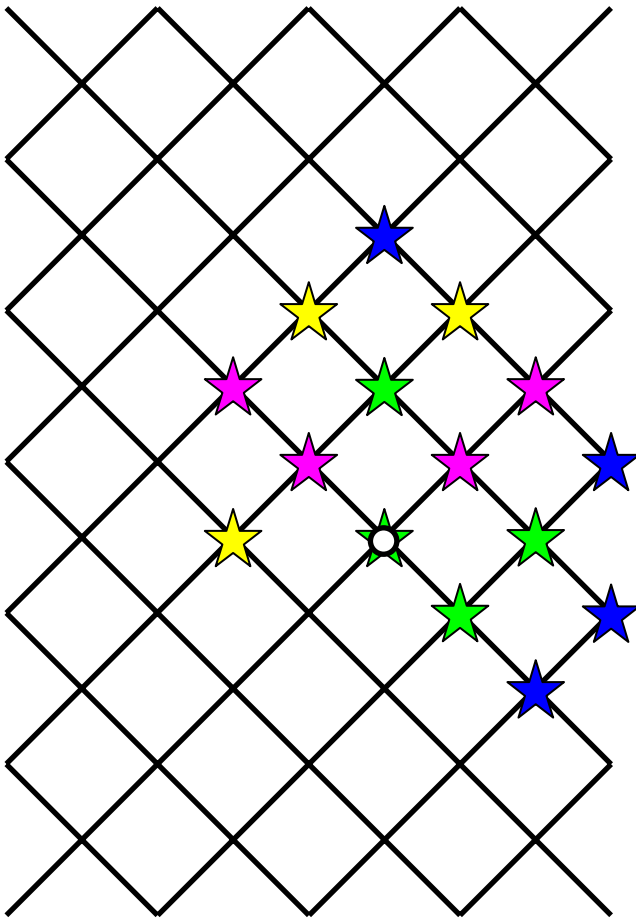
System: actions \downarrow, \uparrow

Environment: observations

★, ★, ★, ★

A play: ★ \uparrow ★

Imperfect information



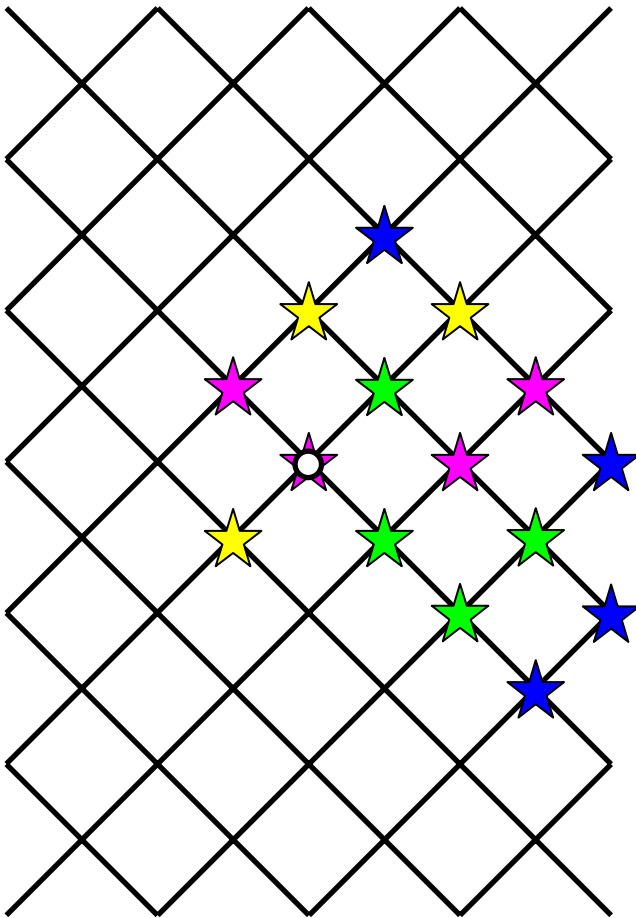
System: actions \downarrow, \uparrow

Environment: observations

$\star, \star, \star, \star$

A play: $\star \uparrow \star \uparrow \star$

Imperfect information



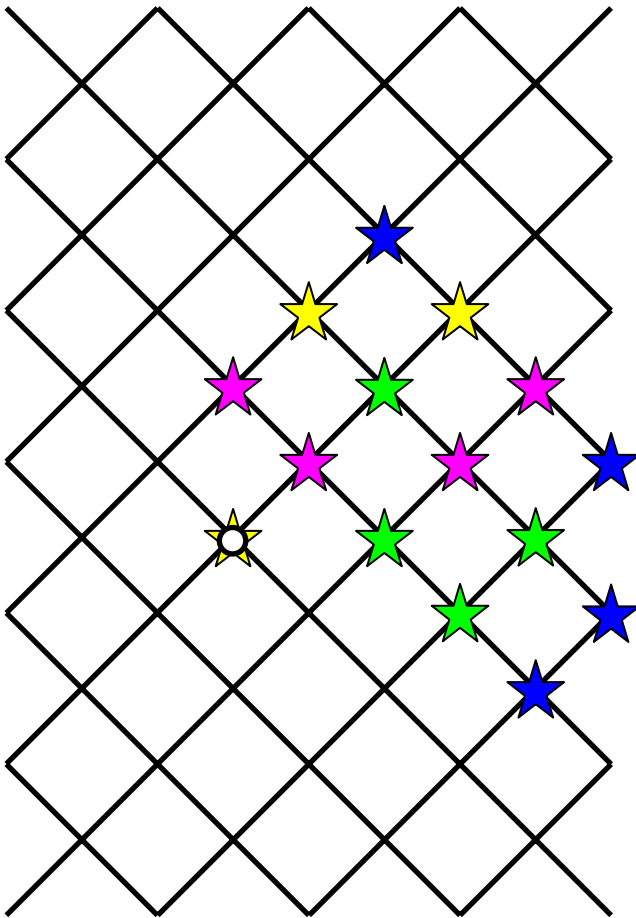
System: actions \downarrow, \uparrow

Environment: observations

$\star, \star, \star, \star$

A play: $\star \uparrow \star \uparrow \star \uparrow \star$

Imperfect information



System: actions \downarrow, \uparrow

Environment: observations

$\star, \star, \star, \star$

A play: $\star \uparrow \star \uparrow \star \uparrow \star \downarrow \star$

Objectives

- **Reachability**: eventually observe a good event
- **Safety**: never observe a bad event
- **Parity**: observation priorities – least one seen infinitely often is even
 - nested reachability & safety
 - generic for ω -regular specifications

Parity games with imperfect information

Questions:

- **decide** if System wins from the initial state
- **construct** a winning strategy

Assumptions:

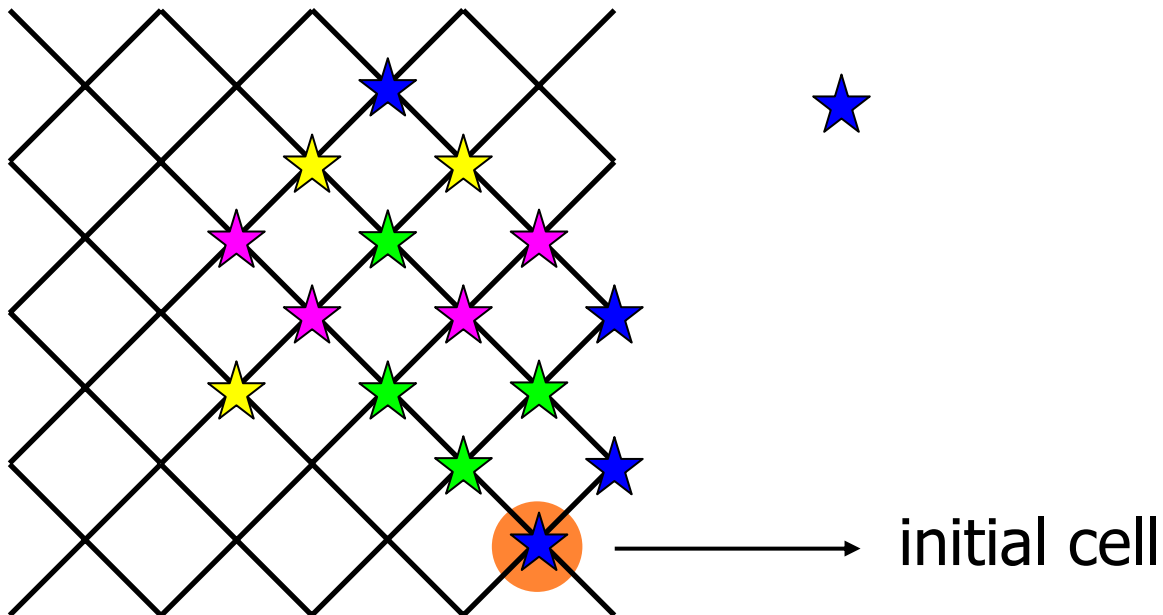
- Visible objective
- Sure-winning

Algorithms

Classical solution

Powerset construction [Reif84]:

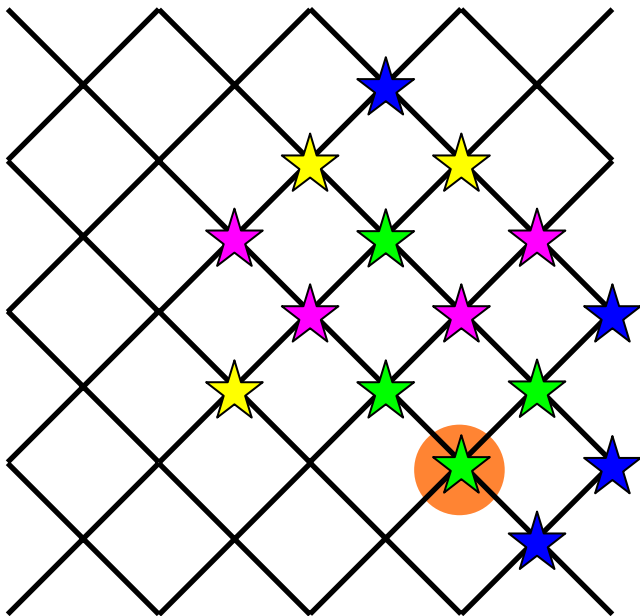
- keeps track of the knowledge of System
- yields equivalent game of perfect information



Classical solution

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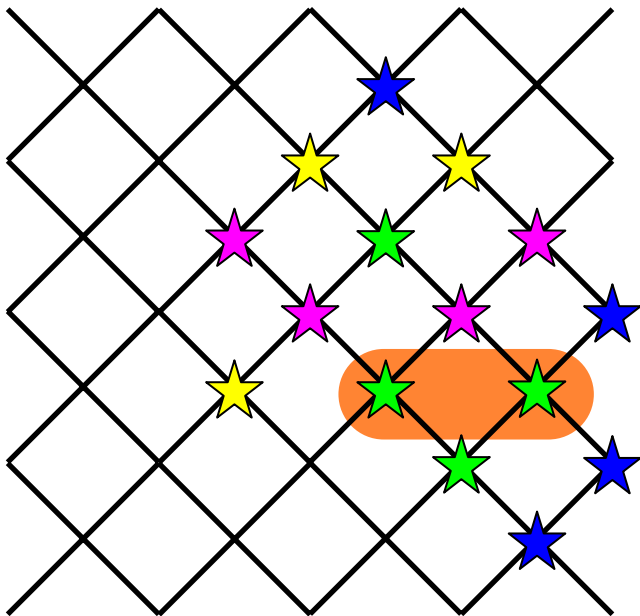
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Classical solution

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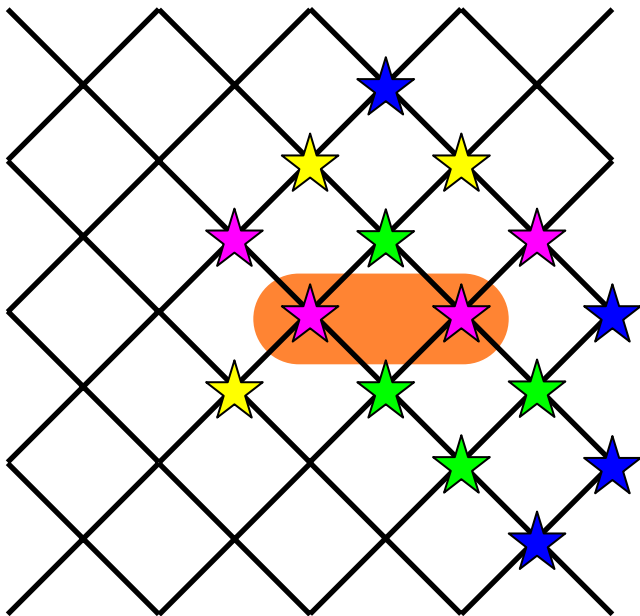
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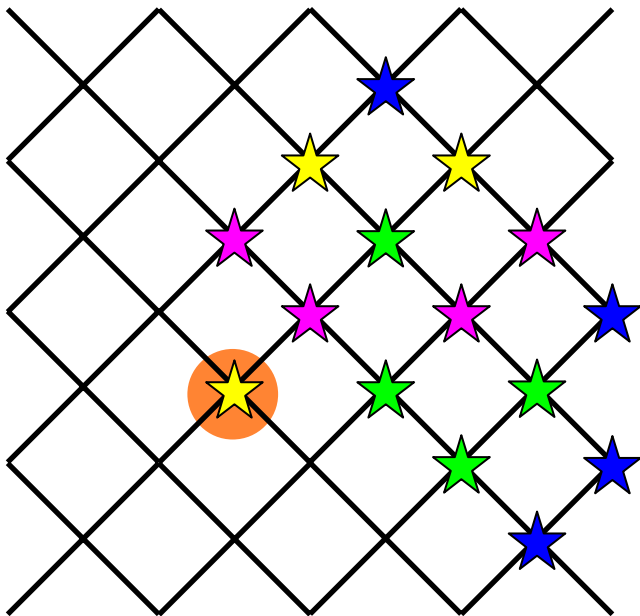
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Classical solution

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Classical solution

Powerset construction [Reif84]:

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Memoryless strategies (in perfect-information)
translate to **finite-memory strategies**

(memory automaton tracks set of possible positions)

Complexity

- Problem is **EXPTIME**-complete
(even for safety and reachability)
- **Exponential memory** might be needed

The powerset solution [Reif84]

- is an exponential construction
- is not on-the-fly
- is independent of the objective

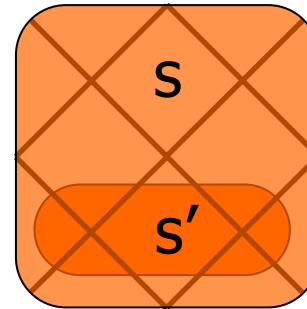
Can we do better ?

Antichains

Antichains

- Winning knowledge-sets are **downward-closed**:

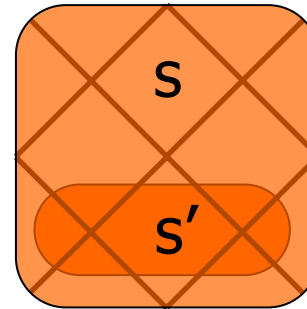
If System wins from s , then she also wins from s'



Antichains

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If System wins from s , then she also wins from s'



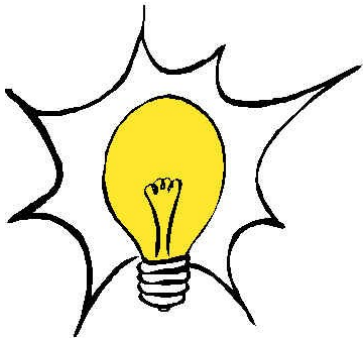
- Useful operations **preserve** downward-closedness

\cap, \cup, Cpre

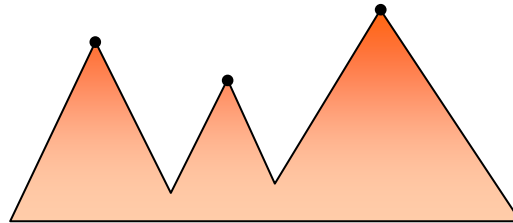
$\text{Cpre}(X) = \{Y \text{ from which System can force the play into } X\}$

Antichains

- Winning knowledge-sets are **downward-closed**
- Useful operations **preserve** downward-closedness



Compact representation using maximal elements → **Antichains**



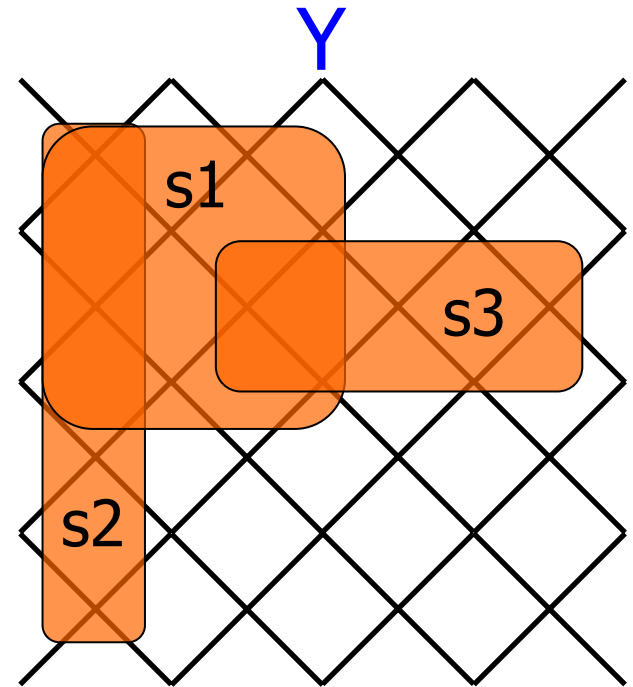
Antichain algorithm

- [CSL'06] computes **winning sets** of positions as a μ -calculus formula over the lattice of antichains

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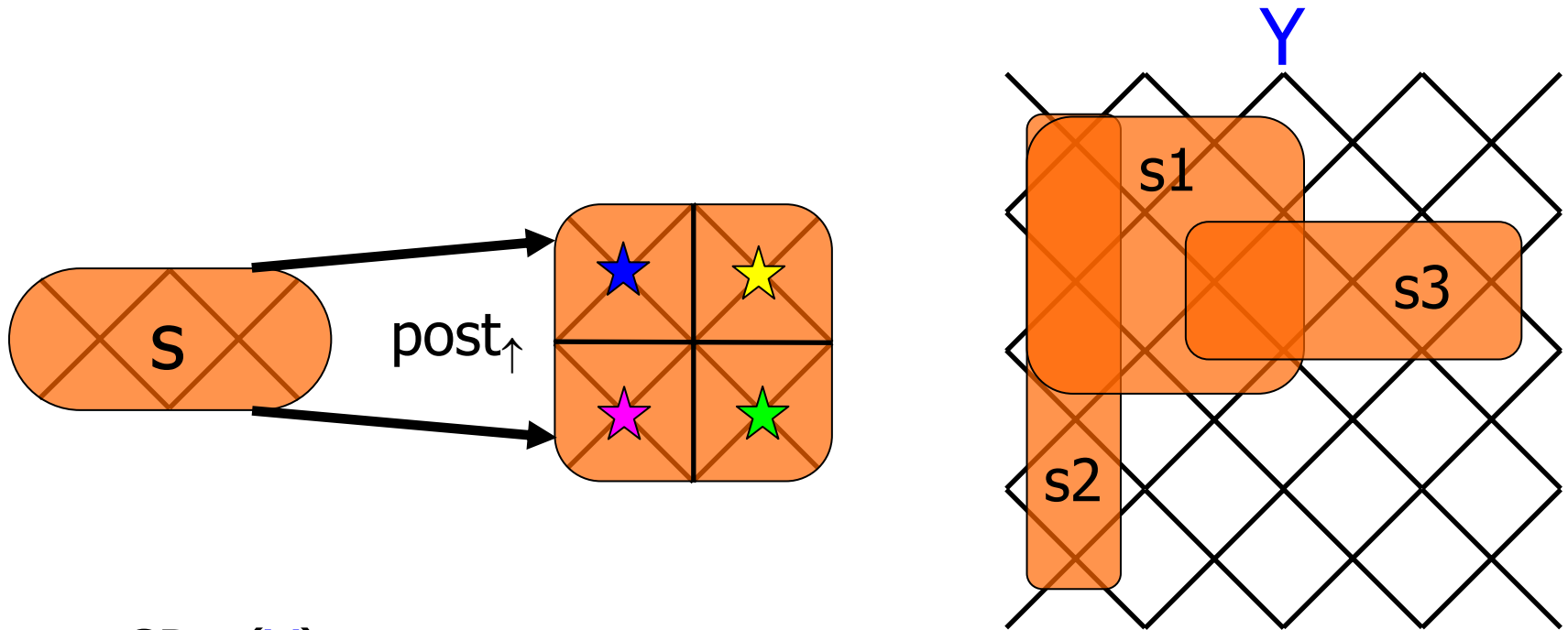
$CPre(Y) = ?$



$Y = \{s1, s2, s3\}$ set of winning positions so far

Antichain algorithm

- [CSL'06] computes **winning sets** of positions as a μ -calculus formula over the lattice of antichains

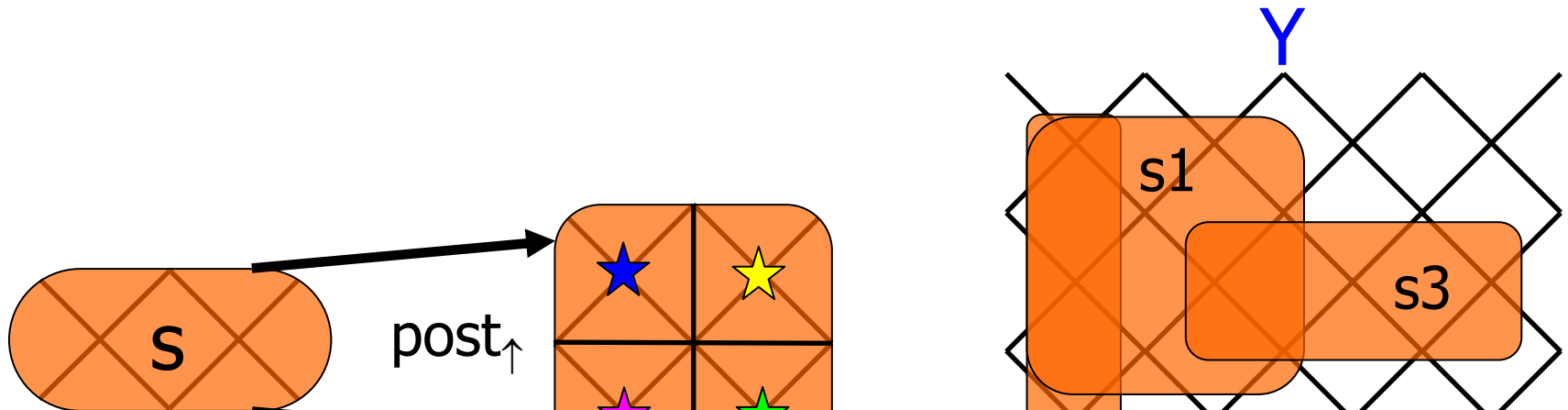


$s \in \text{CPre}(Y)$

if **for all** \star , **there exists** a set in Y that contains $\text{post}_\uparrow(s) \cap \star$

Antichain algorithm

- [CSL'06] computes **winning sets** of positions as a μ -calculus formula over the lattice of antichains



- combinatorially **hard** to compute
- implemented using **BDDs**

$s \in \text{CPre}(Y)$

if **for all** \star , **there exists** a set in Y that contains $\text{post}_\uparrow(s) \cap \star$

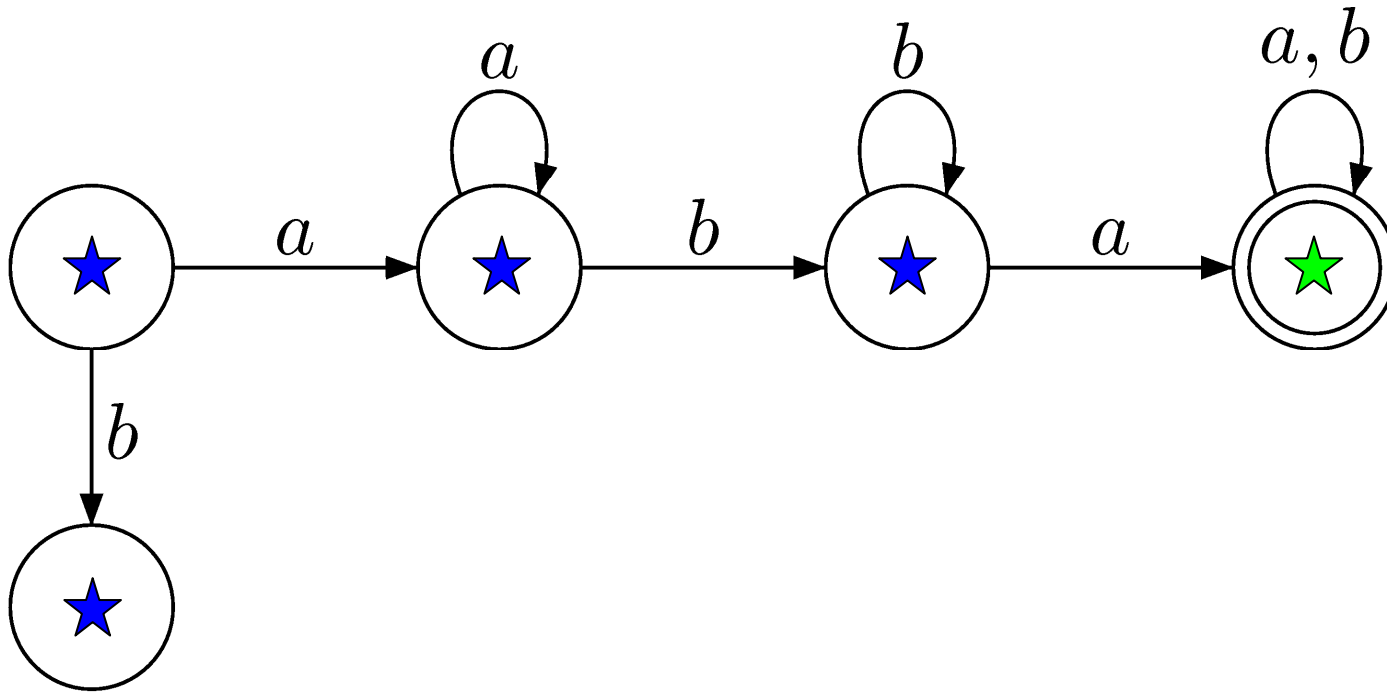
Antichain algorithm

- [CSL'06] computes **winning sets** of positions as a μ -calculus formula over the lattice of antichains
- [Concur'08] computes **winning strategy** recursively for a combination of safety & reachability objectives

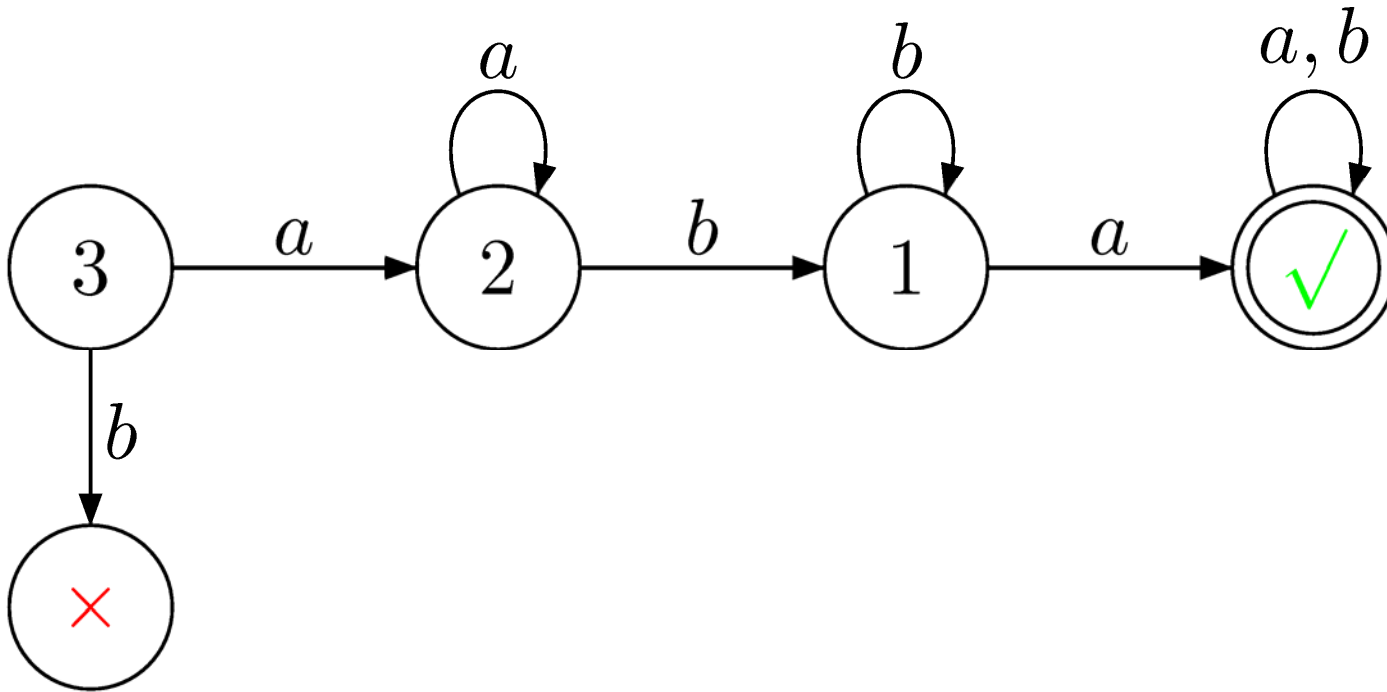
Antichain algorithm

- [CSL'06] computes **winning sets** of positions as a μ -calculus formula over the lattice of antichains
- [Concur'08] computes **winning strategy** recursively for a combination of safety & reachability objectives
 - **Safety**: extract strategy from fixpoint
 - **Reachability**: fixpoint is not sufficient

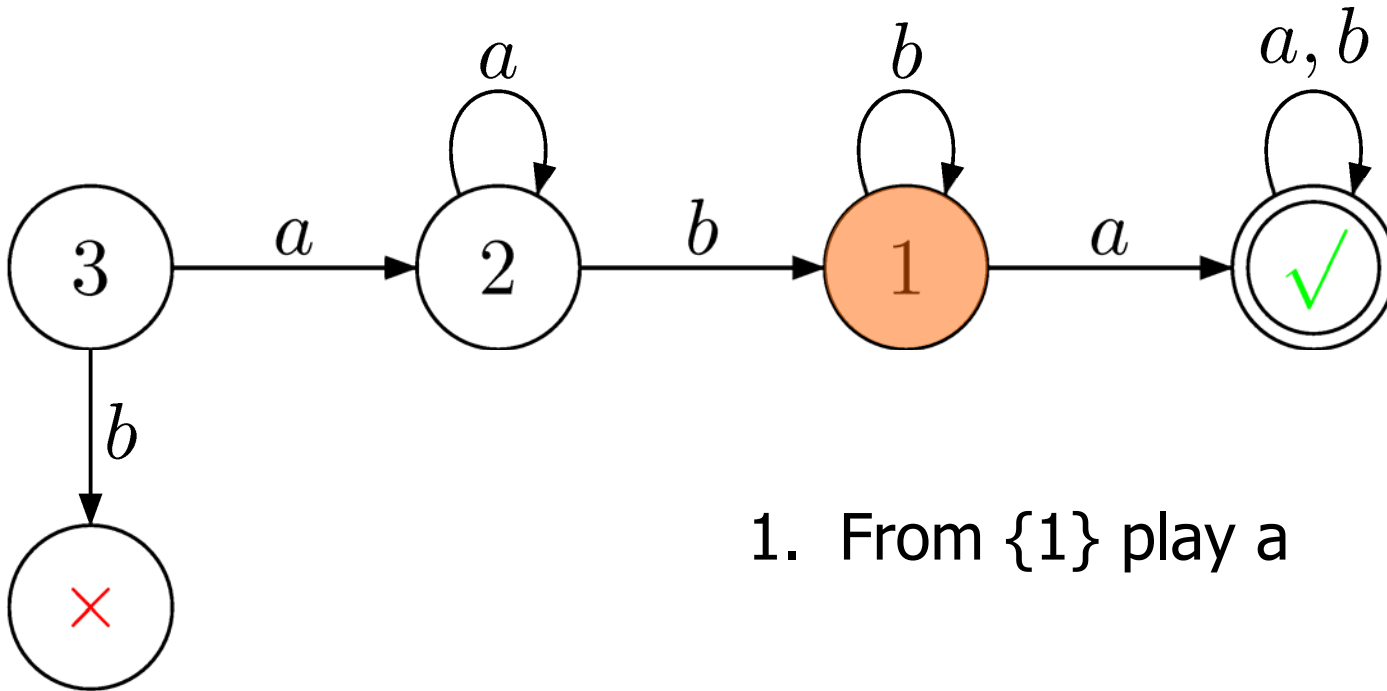
Reachability



Reachability

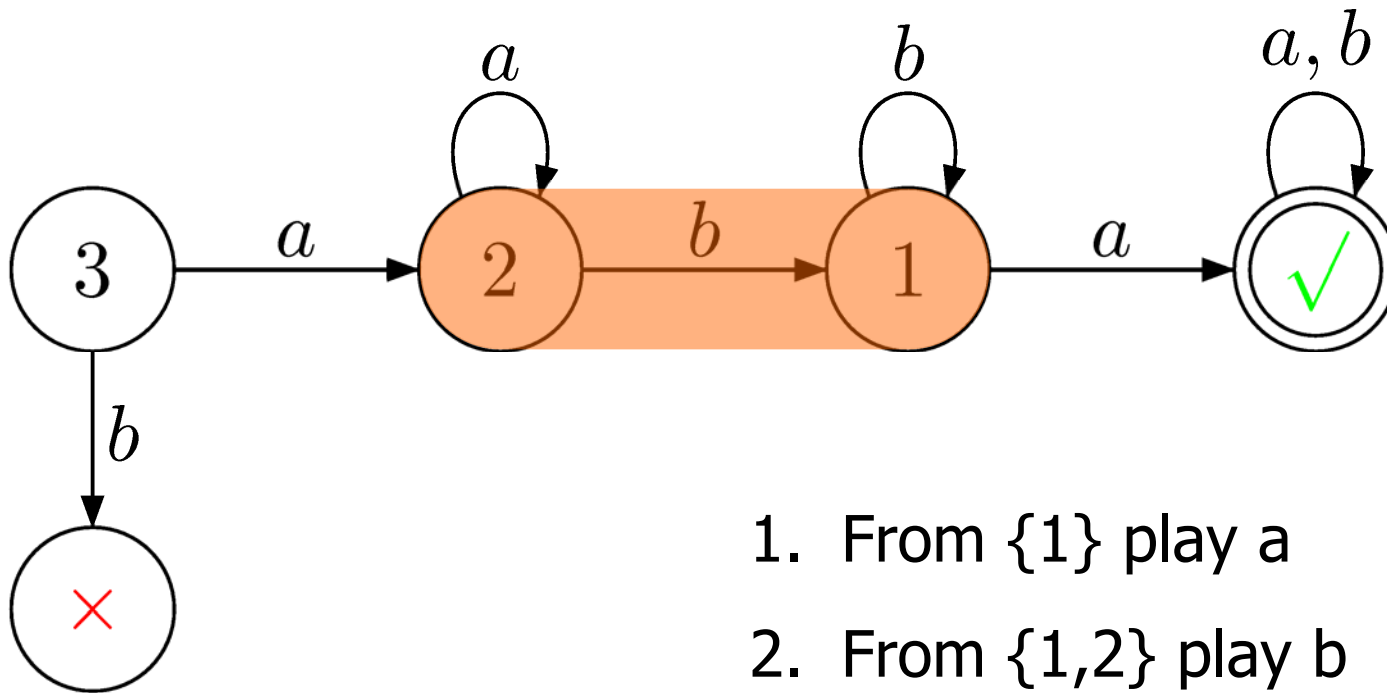


Reachability

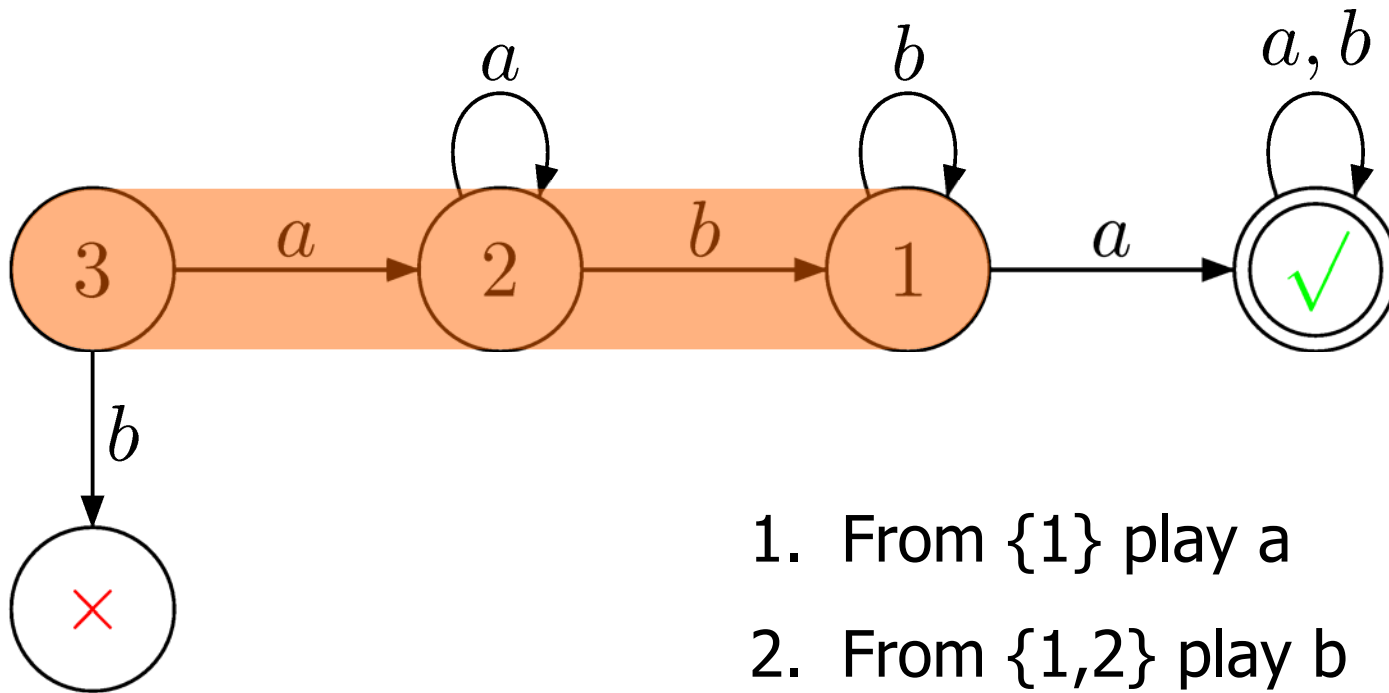


1. From $\{1\}$ play a

Reachability

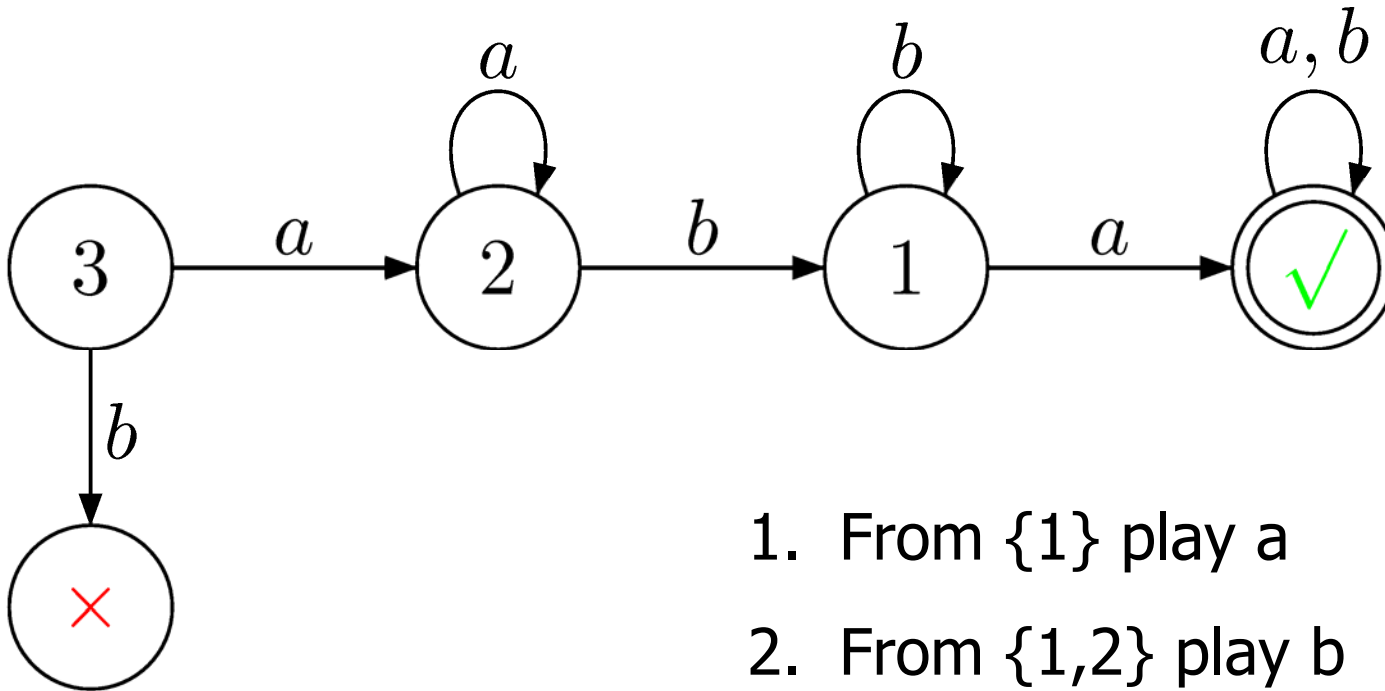


Reachability



1. From $\{1\}$ play a
2. From $\{1,2\}$ play b
3. From $\{1,2,3\}$ play a

Reachability

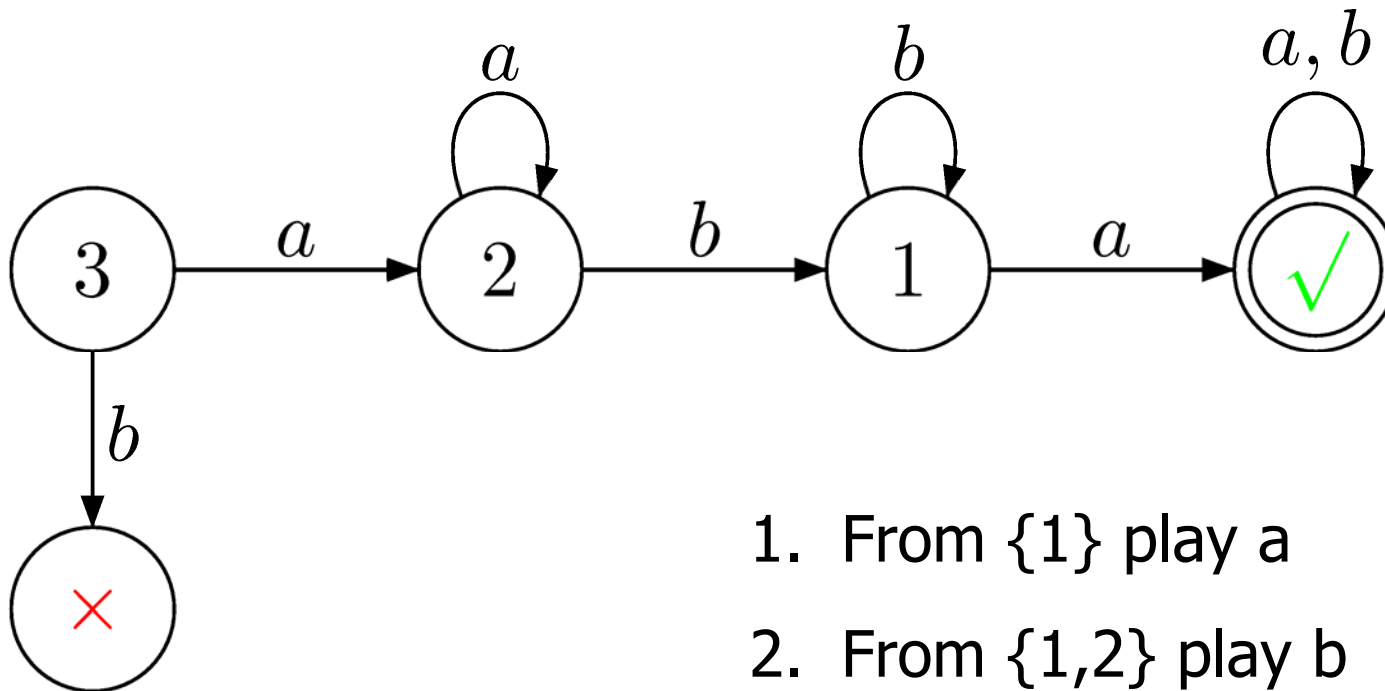


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Fixpoint of winning cells: $\{\{1,2,3\}\}$

Winning strategy ??

Reachability

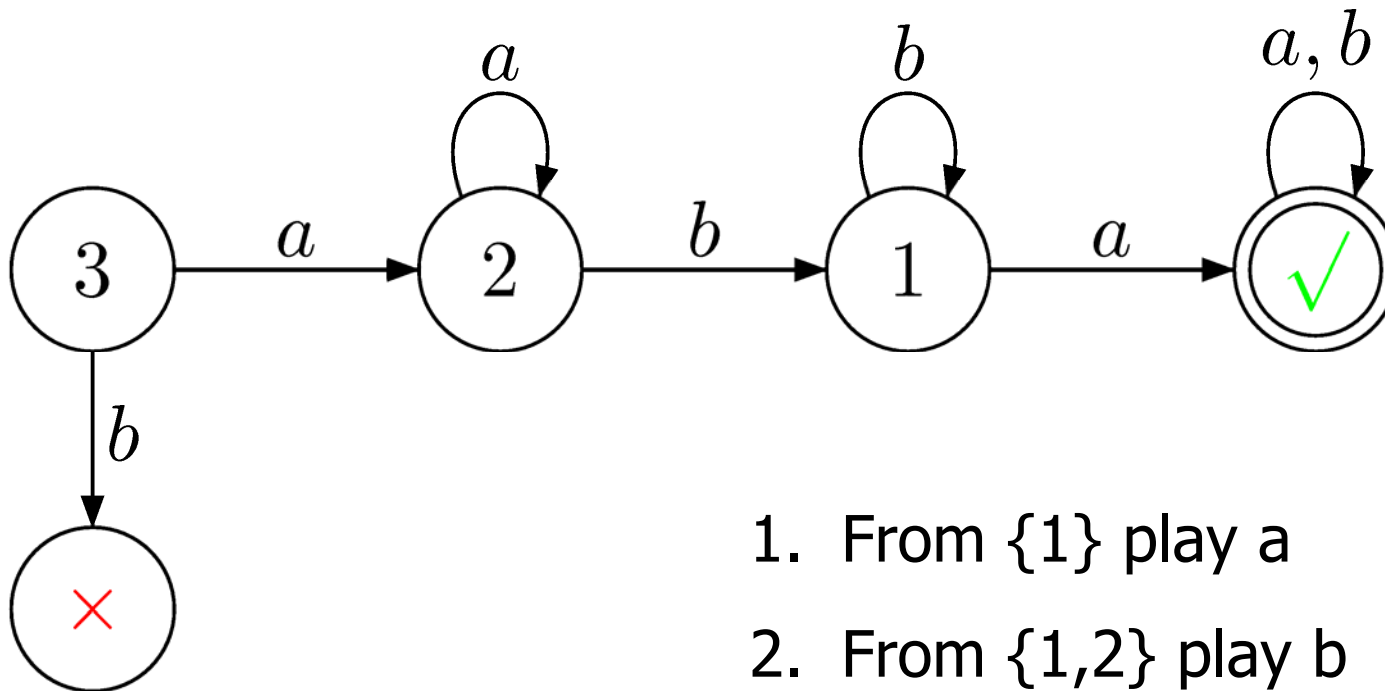


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Fixpoint of winning (cell, action): $\{\{1,2,3\}_a, \{1,2\}_b\}$

Winning strategy ??

Reachability



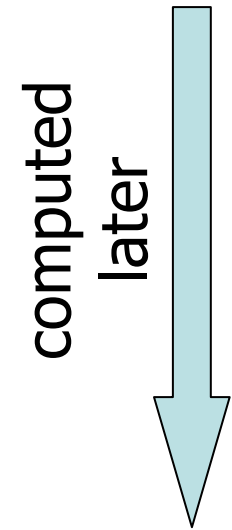
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Winning strategy

Current knowledge K : select earliest (**cell,action**)

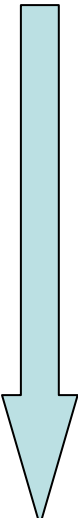
such that $K \subseteq$ **cell**, play **action**

Strategy simplification #1



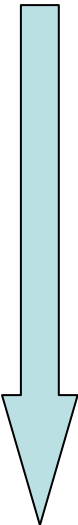
1. From $\{1,2,3\}$ play a
2. From ... play ...
3. From ... play ...
4. From ... play ...
5. From $\{2\}$ play a

Strategy simplification #1

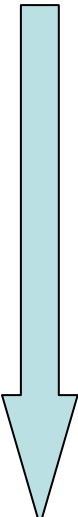
- computed
later
- 
1. From $\{1,2,3\}$ play a
 2. From ... play ...
 3. From ... play ...
 4. From ... play ...
 5. ~~From $\{2\}$ play a~~ Not necessary !

Rule 1: delete subsumed pairs computed later

Strategy simplification #2

- computed
later
- 
1. From $\{1,2\}$ play a
 2. From $\{3,4\}$ play ...
 3. From $\{1,3\}$ play a
 4. From $\{3,5\}$ play ...
 5. From $\{1,2,3\}$ play a

Strategy simplification #2

- computed
later
- 
1. ~~From {1,2} play a~~
 2. From {3,4} play ...
 3. From {1,3} play a
 4. From {3,5} play ...
 5. From {1,2,3} play a

Not necessary !

Rule 2: delete strongly-subsumed pairs

Alpaga

First prototype for solving parity games of imperfect information

- Use antichains as compact representation of winning sets of positions
- Compute Controllable Predecessor with BDDs
- Publish Reachability/Safety attractor moves to compose the strategy (earlier published move sticks)
- Strategy simplification



Alpaga

First prototype for solving parity games of imperfect information

- Implemented in Python + CUDD
- ≤ 1000 LoC
- Solves 50 states, 28 observations, 3 priorities (explicit game graph)

<http://www.antichains.be/alpaga>



Some experiments

	Size	Obs	Priorities	Time (s)
Game1	4	4	Reach.	.1
Game2	3	2	Reach.	.1
Game3	6	3	3	.1
Game4	8	5	5	1.4
Game5	8	5	7	9.4
Game6	11	9	10	50.7
Game7	11	8	10	579.0
Locking	22	14	Safety	.6
Mutex	50	28	3	57.7

<http://www.antichains.be/alpaga>



Alpaga

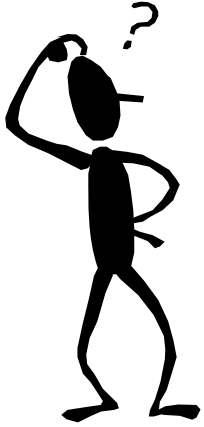
First prototype for solving parity games of imperfect information

Outlook

- Symbolic game graph
- Compact representation of strategies
- Almost-sure winning
- Relaxing visibility



Thank you !



Questions ?



<http://www.antichains.be/alpaga>

References

- [Reif84] J. H. Reif. The Complexity of Two-Player Games of Incomplete Information. *J. Comput. Syst. Sci.* 29(2): 274-301, 1984
- [CSL'06] K. Chatterjee, L. Doyen, T. A. Henzinger, and J.-F. Raskin. Algorithms for Omega-regular Games of Incomplete Information. *Proc. of CSL, LNCS 4207*, Springer, 2006, pp. 287-302
- [Concur'08] D. Berwanger, K. Chatterjee, L. Doyen, T. A. Henzinger, and S. Raje. Strategy Construction for Parity Games with Imperfect Information. *Proc. of Concur, LNCS 5201*, Springer, 2008, pp. 325-339

Alpaga demo

- Login on mtcserver
- Cd `research/2008/StrategyConstruction/CodeMartin/Alpaga-2008-Aug-20/alpaga`
- Help: `python src/alpaga.py -h`
- Locking example: `python src/alpaga.py -t -i examples/locking.gii`
 - Interactive mode: `>> go`