

Parameterized model-checking problems

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Plan of the talk

1. State explosion problem.
2. Parameterized complexity.
3. Parameterized Turing machine problems.
4. Parameterized reachability problems.
5. Parameterized logical model-checking problems.
6. Parameterized behavioral equivalence problems.

Symbolic model-checking

- Model-checking: $\mathcal{M} \models \phi$?
- Symbolic model-checking: $\mathcal{M} \models \phi$?
 - with \mathcal{M} represented succinctly (not in extension);
 - symbolic algorithms have no explicit representation of the state space of \mathcal{M} .
- In practice, composition of subsystems is natural (by synchronization of actions/variables/clocks).
- Examples of succinct representation:
 - $\mathcal{M} = \mathcal{M}_1 \times \dots \times \mathcal{M}_k$ synchronized product.
 - Graphs represented as OBDDs.

Succinct makes complex

- Graph Accessibility Problem (GAP)
 - is NLOGSPACE-complete [Jones 75].
 - is PSPACE-complete with graphs represented as OBDDs [Feigenbaum et al 98].

- Finite automaton intersection problem
 - $L(\mathcal{A}_1 \cap \mathcal{A}_2) = \emptyset?$ is NLOGSPACE-complete.
 - $L(\mathcal{A}_1 \cap \dots \cap \mathcal{A}_k) = \emptyset?$ is PSPACE-complete (even with deterministic automata)

- Succinct representation may cause an increase of complexity.

Verification of non-flat systems

Logic	$\mathcal{M} \models \phi?$	$\mathcal{M}_1 \times \dots \times \mathcal{M}_k \models \phi?$
LTL	PSPACE-complete	PSPACE-complete
CTL	P-complete	PSPACE-complete
CTL*	PSPACE-complete	PSPACE-complete
μ -cal.	in $\text{NP} \cap \text{coNP}$	EXPTIME-complete

See e.g., [Rabinovich 97], [Esparza 98], [Kupferman et al. 00].

In practice, the source of intractability is the size of the model, not the size of the property.

Time complexity

Logic	$\mathcal{M} \models \phi?$
LTL	$2^{\mathcal{O}(\phi)} \times \mathcal{M} $
CTL	$\mathcal{O}(\phi \times \mathcal{M})$
CTL*	$2^{\mathcal{O}(\phi)} \times \mathcal{M} $
μ -calculus	$\mathcal{O}((\phi \times \mathcal{M})^{ \phi })$

- With $\mathcal{M} = \mathcal{M}_1 \times \dots \times \mathcal{M}_k$, $|\mathcal{M}| = |\mathcal{M}_1| \times \dots \times |\mathcal{M}_k|$.
- Size of the input product model: $n = \sum_i |\mathcal{M}_i|$.
- $|\mathcal{M}| \in \mathcal{O}(n^k)$ and $|\mathcal{M}| \in \mathcal{O}(2^n)$.

Behavioral equivalences

Bisimulation is a typical example.

- $\mathcal{M}, s \stackrel{?}{\sim} \mathcal{M}', s'$ is P-complete [Balcàzar et al 92].
- $\mathcal{M}_1 \times \dots \times \mathcal{M}_k, \bar{s} \stackrel{?}{\sim} \mathcal{M}'_1 \times \dots \times \mathcal{M}'_k, \bar{s}'$ is EXPTIME-complete.

See e.g.,

- [Jategaonkar & Meyer 96]
- [Harel et al 97]
- [Rabinovich 97]
- [Laroussinie & Schnoebelen 00]

Any hope to tame intractability?

The state explosion problem seems inescapable in the classical worst-case complexity paradigm.

How Downey & Fellows'
parameterized complexity framework
can cope with it?

A basic problem

Can $\mathcal{M}_1 \times \dots \times \mathcal{M}_k \models \phi$ be solved in time $\mathcal{O}(f(k) \times p(|\phi| + \sum_i |\mathcal{M}_i|))$ with f recursive & p polynomial?

Parameterized complexity

- Primary framework for problem analysis and algorithm design.
- Still a worst-case complexity paradigm.
- Analyses of problems in e.g.
 - graph theory, see e.g. [Downey & Fellows 99],
 - database queries [Papamitriou & Yannakakis 99],
 - logic programming [Lonc & Truszczynski 02],
 - model-checking for first-order logic [Flum & Grohe 01],
 - infinite games [Björklund et al 03],
 - verification of non-flat systems [DLS02],
 - etc.

A few basic definitions

Parameterized language: L subset of $\Sigma^* \times \mathbb{N}$.

k th slice: $L_k = \{\langle x, k \rangle \in \Sigma^* \times \mathbb{N} : \langle x, k \rangle \in L\}$.

x : main part k : parameter.

Assumption: k varies less than the size of x .

Fixed-parameter tractable: L is FPT, $\stackrel{\text{def}}{\iff}$ there exist a recursive function $f : \mathbb{N} \mapsto \mathbb{N}$ and a constant $c \in \mathbb{N}$ such that the question $\langle x, k \rangle \in L$ can be solved in time

$$f(k) \times |x|^c.$$

$f(k)$ as a factor not as an exponent.

$f(k) = 2^{2^{2^k}}$ is allowed.

Parameterized m -reduction (I)

$L \leq_m^{\text{fp}} L'$: $\stackrel{\text{def}}{\iff}$ there exist recursive total functions

- $f_1 : k \mapsto k'$,
- $f_2 : k \mapsto k''$,
- $f_3 : \langle x, k \rangle \mapsto x'$, and
- a constant $c \in \mathbb{N}$

such that

- $\langle x, k \rangle \mapsto x'$ is computable in time $k''|x|^c$, and
- $\langle x, k \rangle \in L$ iff $\langle x', k' \rangle \in L'$.

Parameterized m -reduction (II)

- Classical reductions carry less structure than parameterized reductions.
- $L \leq_m^{\text{fp}} L'$: each k th slice of L is reduced to the $f_1(k)$ th slice of L' .
- Adding parameters to a problem makes it easier in the parameterized sense: $L(k, k') \leq_m^{\text{fp}} L(k)$.
- $[X]^{\text{FPT}} = \{L : L \leq_m^{\text{fp}} L', \text{ for some } L' \in X\}$.
(X set of parameterized languages)
- FPT is closed under m -reductions.

A non-parameterized reduction (I)

- WEIGHTED CNF SATISFIABILITY

Instance: a propositional formula ϕ in CNF;

Parameter: integer k ;

Question: Does ϕ have a satisfying valuation such that exactly k variables are set to true?

- WEIGHTED 3CNF SAT. defined as WEIGHTED CNF SAT. except each clause in ϕ has at most 3 literals.

- $\text{SAT} \leq_m^P \text{3SAT}$ but what about

$\text{WEIGHTED CNF SAT.} \leq_m^{\text{fp}} \text{WEIGHTED 3CNF SAT.}?$

A non-parameterized reduction (II)

- $\phi = C_1 \wedge \dots \wedge C_n$ with C_i of length l_i .
- $f(\phi)$ in 3CNF obtained from ϕ (by renaming of pairs of literals) with $v \models \phi$ implies $v' \models f(\phi)$ such that v is of weight k implies v' is of weight $g(k, l_1, \dots, l_n)$.
- To be a parameterized reduction, the weight of v' should only depend on k .

A parameterized reduction

INDEPENDENT SET

Instance: a graph $G = \langle V, E \rangle$;

Parameter: k ;

Question: Is there $V' \subseteq V$ of cardinality k such that for all $u, v \in V'$,
 $\langle u, v \rangle \notin E$?

CLIQUE

Instance: a graph $G = \langle V, E \rangle$;

Parameter: k ;

Question: Is there $V' \subseteq V$ of cardinality k such that for all $u, v \in V'$,
 $\langle u, v \rangle \in E$?

$\langle V, E \rangle, k \longmapsto \langle V, (V \times V) \setminus E \rangle, k.$

Hierarchies of classes

- W[1]-hardness of L : first evidence that L is likely not to be FPT.
- XP: $L \in XP \stackrel{\text{def}}{\Leftrightarrow}$ for every k , L_k is in P.
Languages tractable “by the slice”.

originally defined with decision circuits

$$\text{FPT} \subseteq \overbrace{\text{W}[1] \subseteq \text{W}[2] \subseteq \dots \subseteq \text{W}[\text{SAT}] \subseteq \text{W}[\text{P}]} \subseteq$$

$$\subseteq \underbrace{\text{AW}[1] \subseteq \text{AW}[\text{SAT}] \subseteq \text{AW}[\text{P}]} \subseteq \text{XP}$$

defined with PARAMETERIZED QBFSAT

- Few problems complete for each class below:

$$\text{AW}[1] = \text{AW}[*] = \bigcup_t \text{AW}[t], \quad \text{AW}[\text{SAT}], \quad \text{AW}[\text{P}].$$

A definition of $W[t]$

$$\exists x_{11} \cdots \exists x_{1k_1} \forall x_{21} \cdots \forall x_{2k_2} \cdots Q x_{t1} \cdots Q x_{tk_t} \phi$$

- ϕ quantifier-free formula built over atomic formulae of the form $x = y$ and $R(x_1, \dots, x_r)$,
- $Q = \forall$ if t is even, $Q = \exists$ otherwise,

$\Sigma_{t,u}$: Σ_t + all quantifier blocks after the leading \exists block have length $\leq u$.

W[t] and model-checking problems

- P-MC(GRAPH, $\Sigma_{t,u}$)

Instance: a graph $G = \langle V, E \rangle$ and $\phi \in \Sigma_{t,u}$;

Parameter: $|\phi|$;

Question: $G \models \phi$?

- **Theorem.** [Chen & Flum 2003] $W[t] = [\{\text{P-MC}(\text{GRAPH}, \Sigma_{t,u}) : u \geq 1\}]^{\text{FPT}}$
- Other parameterized classes can be characterized by other model-checking problems.

Example - VERTEX COVER

- PARAMETERIZED VERTEX COVER

Instance: a graph $G = \langle V, E \rangle$;

Parameter: k ;

Question: Is there $V' \subseteq V$ with $|V'| \leq k$ such that for every $\langle u, v \rangle \in E$, either $u \in V'$ or $v \in V'$?

- VERTEX COVER is NP-complete but

Theorem. [Balasubramanian et al 98]

PARAMETERIZED VERTEX COVER is in FPT and can be solved in time $\mathcal{O}((53/40)^k \times k^2 + k \times n)$.

Example - INDEPENDENT SET

- INDEPENDENT SET is NP-complete.
- **Theorem.** PARAMETERIZED INDEPENDENT SET is $W[1]$ -complete.
- INDEPENDENT SET with graphs represented as OBDDs is NEXPTIME-complete [Feigenbaum et al 98].

Time as a parameter in TMs

- SHORT NDTM COMPUTATION

Instance: a single-tape non-deterministic Turing machine M and a positive integer k (unary);

Parameter: k ;

Question: Is there a computation of M on the empty string input that reaches a final accepting state in at most k steps?

- SHORT NDTM COMPUTATION is $W[1]$ -complete [Downey et al 94].
- SHORT DTM COMPUTATION is FPT.
- The multi-tape version of SHORT NDTM COMPUTATION is $W[2]$ -complete [Cesati 03].

SHORT ATM COMPUTATION

- **Theorem.** [DLS02] SHORT ATM COMPUTATION is AW[1]-complete.

→ very high in the hierarchy

- Other problems with ATMs complete for classes of the W/AW hierarchies can be found in [Chen & Flum 03, Chen & Flum & Grohe 03].
- We show fp-equivalence with $\text{PARAMETERIZED QBFSAT}_t$.

An AW[1]-complete problem

- PARAMETERIZED QBFSAT_t

Instance: $\psi = \exists^{=k_1} X_1 \forall^{=k_2} X_2 \dots \forall^{=k_{2p}} X_{2p} \phi$

ϕ positive Boolean combination of literals with at most t alternations of \wedge and \vee ;

Parameter: $\langle k_1, \dots, k_{2p} \rangle$;

Question: Is ψ true?

$\exists^{=k_i} X_i$ is interpreted by “does there exist an valuation of weight k_i over X_i such that ...”.

$\forall^{=k_i} X_i$ is interpreted by “for all valuations of weight k_i over X_i , ...”.

- **Theorem.** [Downey & Fellows 99] PARAMETERIZED QBFSAT_t is AW[1]-complete $\forall t \geq 1$.

- $AW[*] = AW[1] = AW[t]$ for all $t \geq 2$.

Reduction to SHORT ATM COMP.

- $\psi = \exists^{=k_1} X_1 \forall^{=k_2} X_2 \dots \forall^{=k_{2p}} X_{2p} \phi.$

- Construction of the ATM $M_\psi.$

M_ψ picks $k_1 + \dots + k_{2p}$ variables in $X_1 \cup \dots \cup X_{2p}.$

Structure of ϕ reflected by the transition table of $M_\psi.$

Universal states encode both $\forall^{=k_i}$ and conjunctions.

Existential states encode both $\exists^{=k_i}$ and disjunctions.

- M_ψ answers in time $\mathcal{O}(k + t),$ i.e. $\mathcal{O}(k).$

Space as a parameter in TMs

- COMPACT NDTM COMPUTATION

Instance: a single-tape non-deterministic Turing machine M and a positive integer k ;

Question: Is there a computation of M on the empty string input that reaches a final accepting state using at most k work tape squares?

- COMPACT NDTM COMPUTATION is AW[SAT]-hard [Chen & Flum & Grohe 03].

- **Theorem.** COMPACT ATM COMPUTATION is XP-complete.

PARAMETERIZED PEBBLE GAME (I)

PARAMETERIZED PEBBLE GAME

Instance: A pebble game $\langle N, R, S, T \rangle$;

Parameter: $|S|$;

Question: Does the player I has winning strategy?

N : set of nodes

S : set of initial nodes

$T \in N$: terminal node

$R \subseteq N^3$: set of moves

Move: $\overset{x}{\blacksquare} \ \overset{y}{\blacksquare} \ \square \Rightarrow \square \ \overset{y}{\blacksquare} \ \overset{z}{\blacksquare}$ if $R(x, y, z)$.

Player I wins if he can reach T or if Player II cannot move.

PARAMETERIZED PEBBLE GAME (II)

Theorem. [Adachi & Iwata & Kasai 79]

PARAMETERIZED PEBBLE GAME is XP-complete.

The reduction showing PEBBLE GAME is EXPTIME-hard turns out to show also that

COMPACT ATM COMP. $\leq_{\substack{\text{fp} \\ \text{m}}}^{\text{m}}$ PAR. PEBBLE GAME.

PAR. PEBBLE GAME (III)

- PARAMETERIZED PEBBLE GAME $\stackrel{\text{fp}}{\leq}_{\text{m}}$ COMPACT ATM COMPUTATION.

$$PG = \langle N, R, S, T \rangle ; |S| = k.$$

- Construction of the ATM M_{PG} .

Alphabet: N . k work-tape squares.

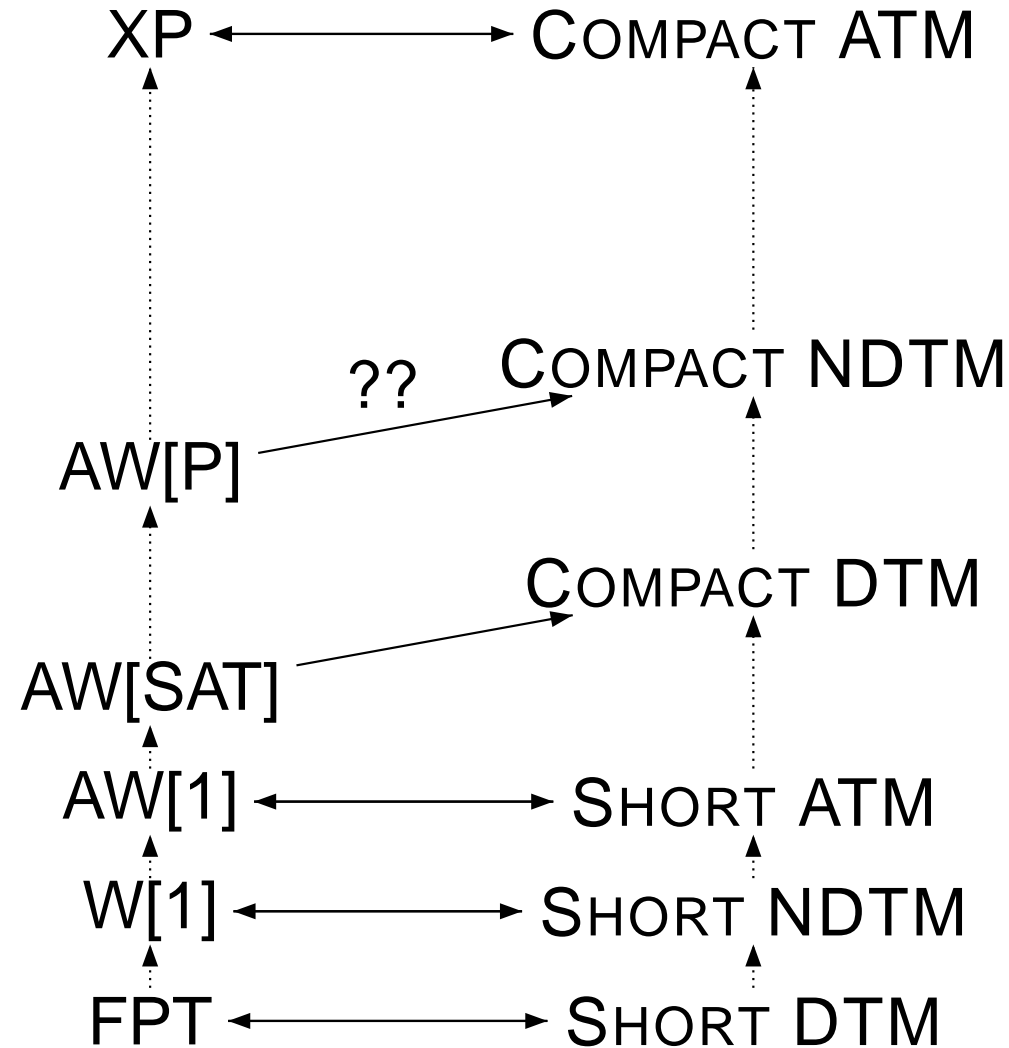
Moves of Player I emulated by existential states.

Moves of Player II emulated by universal states.

R and S encoded in the transition table.

- $|M_{PG}|$ is in $\mathcal{O}(|PG|)$ and $k' = k$.

Parameterized classes and TM pbs



LTSs

- Labeled transition system (LTS): $\mathcal{A} = \langle Q, \Sigma, \rightarrow \rangle$.
- $\rightarrow \subseteq Q \times \Sigma \times Q$.
- $|\mathcal{A}| = |Q| + |\Sigma| + |\rightarrow|$.
- Product LTS $\mathcal{A}_1 \times \dots \times \mathcal{A}_n$ with set of states $\prod_{i=1}^n Q_i$ and alphabet $\bigcup_{i=1}^k \Sigma_i$.

Synchronization protocols

Strong synchronization

all components move at the same time:

$\langle s_1, \dots, s_k \rangle \xrightarrow{a}_{\text{str}} \langle t_1, \dots, t_k \rangle$ iff $s_i \xrightarrow{a}_i t_i$ for all $i = 1, \dots, k$.

Binary synchronization

two components synchronize while the rest does not move.

$\langle s_1, \dots, s_k \rangle \xrightarrow{a}_{\text{bin}} \langle t_1, \dots, t_k \rangle$ iff there exist i and j ($i \neq j$) s.t. $s_i \xrightarrow{a}_i t_i$ and $s_j \xrightarrow{a}_j t_j$ while $s_l = t_l$ for all $l \notin \{i, j\}$.

Parameterized Exact Reachability

Reachability problems are fundamental in model-checking.

Exact Reachability (EXACT-REACH)

Instance: k LTSs $\mathcal{A}_1, \dots, \mathcal{A}_k$,
two configurations \bar{s} and \bar{t} of $\mathcal{A}_1 \times \dots \times \mathcal{A}_k$;

Parameter: k ;

Question: $\bar{s} \xrightarrow{*} \bar{t}$?

Parameterized Local Reachability

Local Reachability (LOCAL-REACH)

Instance: k LTSs $\mathcal{A}_1, \dots, \mathcal{A}_k$,
sets F_1, \dots, F_k of states with $F_i \subseteq Q_i$,
a configuration \bar{s} of $\mathcal{A}_1 \times \dots \times \mathcal{A}_k$;

Parameter: k ;

Question: Does $\bar{s} \xrightarrow{*} \bar{t}$ for some $\bar{t} \in \bar{F}$
where $\bar{F} = F_1 \times \dots \times F_k$?

Parameterized Repeated Reachability

Repeated Reachability (REP-REACH)

Instance: k LTSs $\mathcal{A}_1, \dots, \mathcal{A}_k$,
sets F_1, \dots, F_k of states with $F_i \subseteq Q_i$,
a configuration \bar{s} of $\mathcal{A}_1 \times \dots \times \mathcal{A}_k$;

Parameter: k ;

Question: Does $\bar{s} \xrightarrow{*} \bar{t} \xrightarrow{+} \bar{t}$ for some $\bar{t} \in \bar{F}$
where $\bar{F} = F_1 \times \dots \times F_k$?

(Büchi acceptance condition)

Parameterized Fair Reachability

Fair Reachability (FAIR-REACH)

Instance: k LTSs $\mathcal{A}_1, \dots, \mathcal{A}_k$,

sets $(F_i^j)_{i=1, \dots, k}^{j=1, \dots, p}$ with $F_i^j \subseteq Q_i$ for all i, j ,

a configuration \bar{s} of $\mathcal{A}_1 \times \dots \times \mathcal{A}_k$.

For all j , we write \bar{F}^j for $F_1^j \times \dots \times F_k^j$.

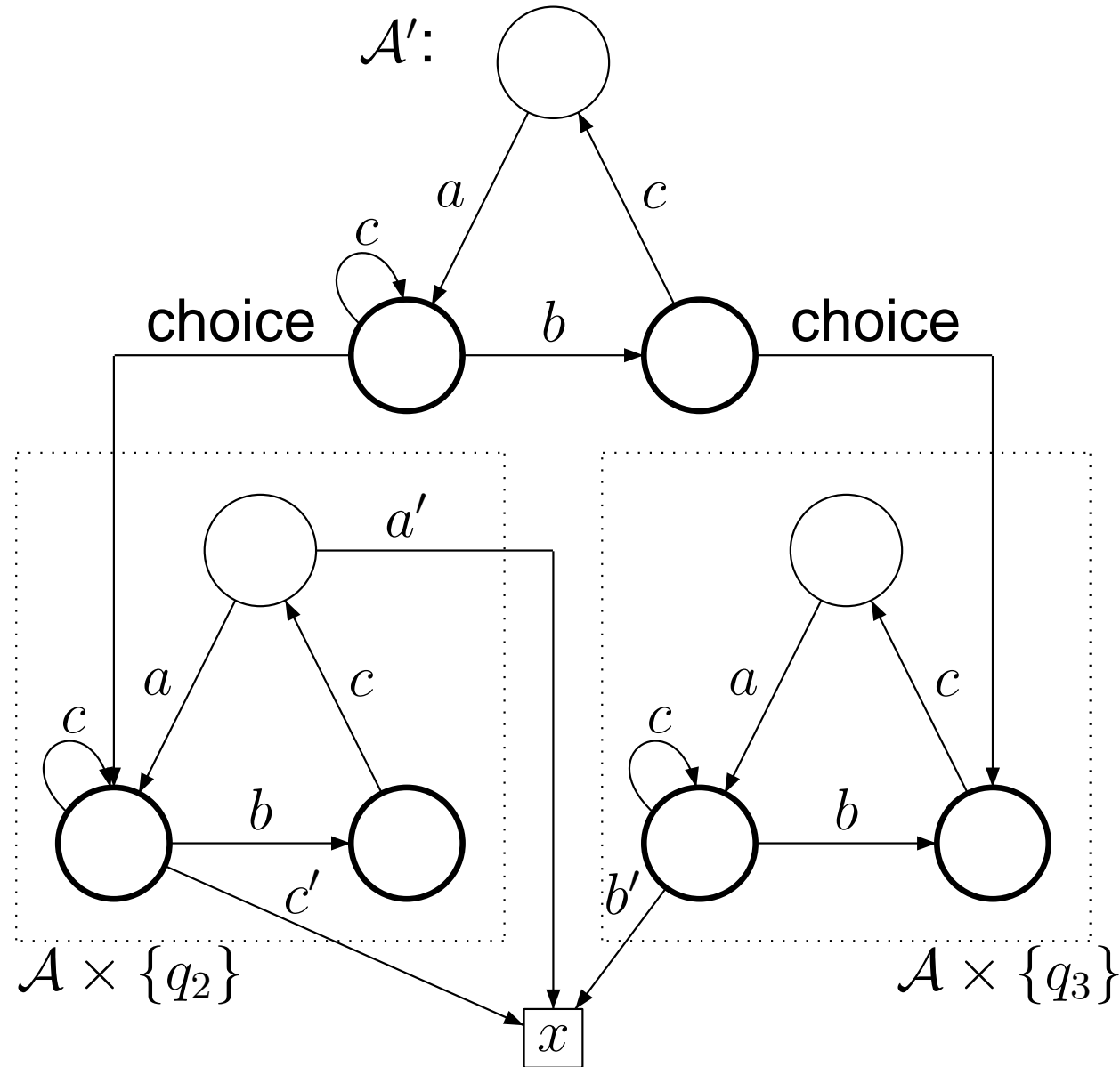
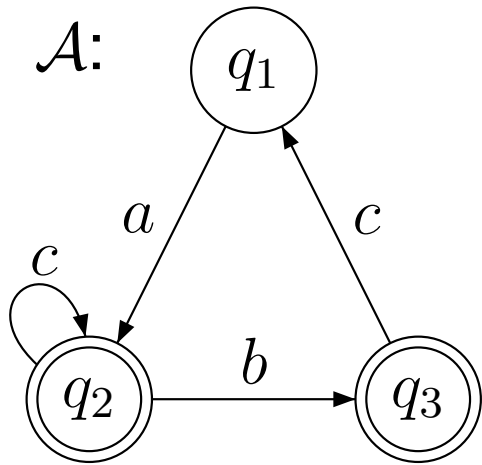
Parameter: k ;

Question: Does $\bar{s} \xrightarrow{*} \bar{t}_1 \xrightarrow{*} \bar{t}_2 \dots \xrightarrow{*} \bar{t}_p \xrightarrow{+} \bar{t}_1$ for some $\bar{t}_1, \dots, \bar{t}_p \in \bar{F}^1, \dots, \bar{F}^p$?

Equivalence

- **Theorem.** The four parameterized reachability problems are fp-equivalent.
- k -*-REACH: any of the four problems.
- By way of example, we sketch the construction to show k -REP-REACH $\leq_{\text{m}}^{\text{fp}}$ k -EXACT-REACH:

Sketch of the proof (I)



Sketch of the proof (II)

Equivalence between

1. $\bar{s} = \langle q_1, \dots, q_k \rangle \xrightarrow{*} \bar{t} \xrightarrow{+} \bar{t}$ in $\mathcal{A}_1 \times \dots \times \mathcal{A}_k$;

2. $\langle q_1^0, \dots, q_k^0 \rangle \xrightarrow{* \text{ choice}} \langle f_1^{j_1}, \dots, f_k^{j_k} \rangle \xrightarrow{+} \langle x_1, \dots, x_k \rangle$ in $\mathcal{A}'_1 \times \dots \times \mathcal{A}'_k$;

3. $\langle q_1^0, \dots, q_k^0 \rangle \xrightarrow{*} \langle x_1, \dots, x_k \rangle$.

$$\bar{t} = \langle f_{1,j_1}, \dots, f_{k,j_k} \rangle \in F_1 \times \dots \times F_k.$$

Cost of the reduction

- $|\mathcal{A}'_i|$ in $\mathcal{O}((|F_i| + 1) \times |\mathcal{A}_i|)$.
- $k' = k$.
- $|\Sigma'| = 2 \times |\Sigma| + 1$.
- $n' \in \mathcal{O}(n^2)$.
- Simpler reductions exist but we want also to preserve determinism.

fp-equivalence (I)

Theorem. k -*-REACH is fp-equivalent to COMPACT NDTM COMPUTATION.

Proof sketch of

COMPACT NDTM COMPUTATION \leq_m^{fp} k -LOCAL-REACH.

With an NDTM M and an integer k we associate a product $\mathcal{A}_1 \times \cdots \times \mathcal{A}_k \times \mathcal{A}_{\text{state}} \times \mathcal{A}_{\text{head}}$ of $k + 2$ LTSs that emulate the behaviour of M on a k -bounded tape.

- each \mathcal{A}_i stores the current contents of the i -th tape square,
- $\mathcal{A}_{\text{state}}$ stores the current control-state of M ,
- $\mathcal{A}_{\text{head}}$ stores the position of the TM head.

fp-equivalence (II)

- Synchronization on labels of the form $\langle t, i \rangle$ that stand for “rule t of M is fired while head is in position i ”.
- Successful acceptance by M is directly encoded as a local reachability criterion.
- Finally we translated our instance to a k -LOCAL-REACH instance with $k' = k + 2$ and $n' = O(kn^2)$.
- See also [Kozen 77] and [Papadimitriou 94] for the PSPACE-hardness proof of reachable deadlock for a system of communicating processes.

Robustness of the equivalence

Variants fp-equivalent to k -*-REACH:

Binary synchronization:

$$k\text{-*-REACH}_{bin} \quad k, \Sigma\text{-*-REACH}_{bin}$$

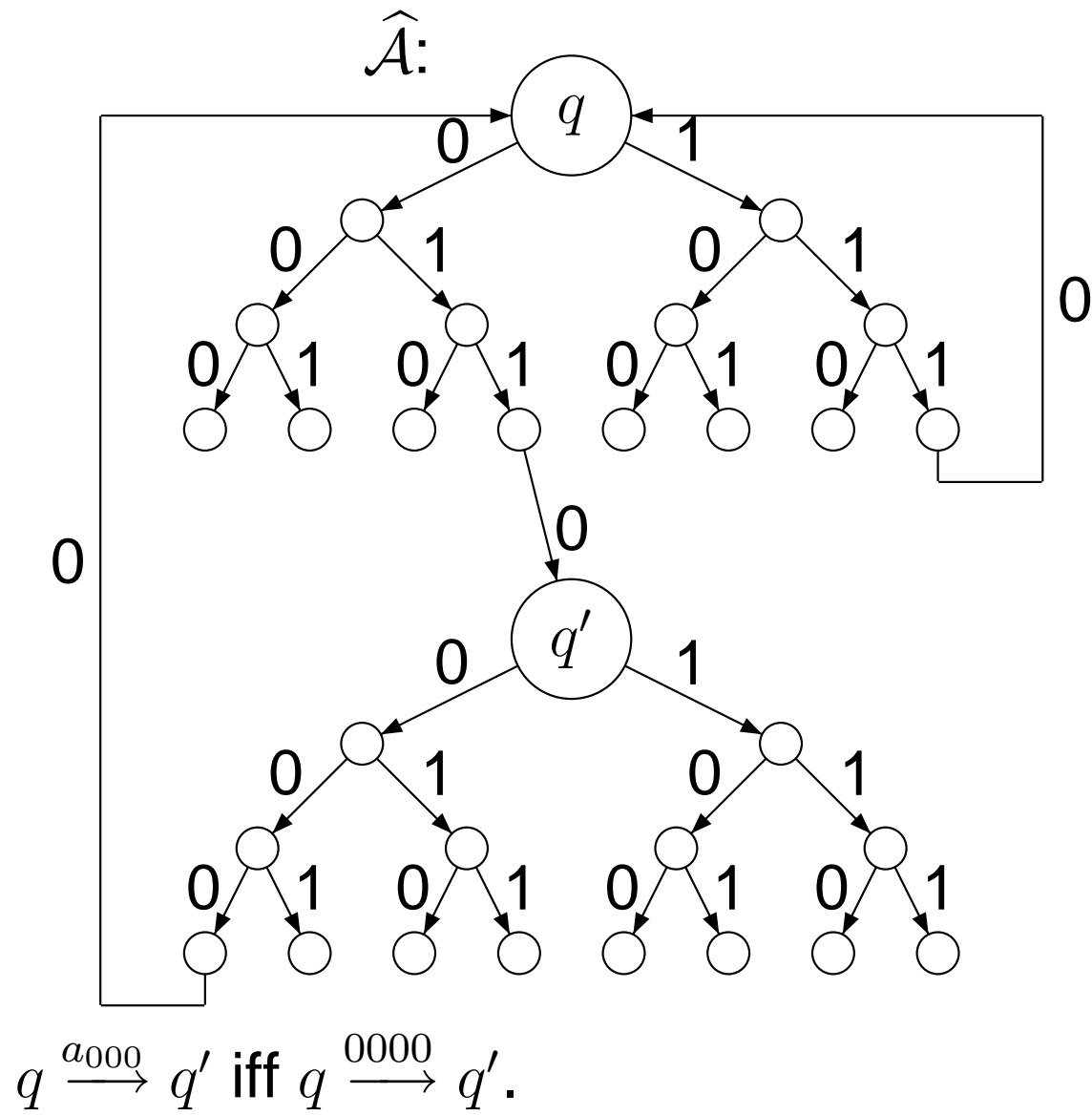
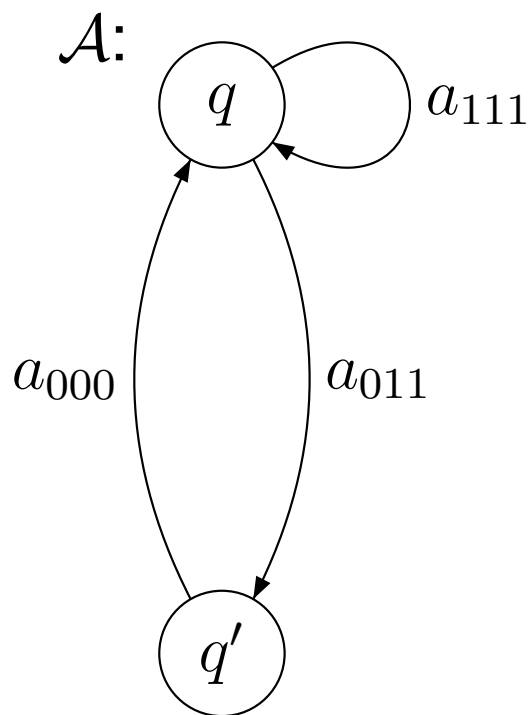
Bounded size alphabet:

$$k, \Sigma\text{-*-REACH} \quad k\text{-*-REACH}_{|\Sigma|=2}$$

Determinism:

$$k, \Sigma\text{-*-REACH}_{det} \quad k\text{-*-REACH}_{|\Sigma|=2, det}$$

Bounding $|\Sigma|$



Parameterized temporal logic pbs.

- **Kripke structure** $\mathcal{M} = \langle \mathcal{A}, m \rangle$
 \mathcal{A} LTS, $m \subseteq Q \times AP$.
 $\langle \mathcal{A}_1, m_1 \rangle \times \cdots \times \langle \mathcal{A}_k, m_k \rangle = \langle \mathcal{A}_1 \times \cdots \times \mathcal{A}_k, \bigoplus_i m_i \rangle$
- Sometimes, the labels are used only for the synchronization and not in the product models.
- **Parameterized model checking for logic L (MC_L)**
Instance: Kripke structures $\mathcal{M}_1, \dots, \mathcal{M}_k$,
a configuration \bar{s} ,
an L -formula ϕ ;
Parameter: $k, |\phi|$;
Question: $\mathcal{M}_1 \times \cdots \times \mathcal{M}_k, \bar{s} \models \phi?$

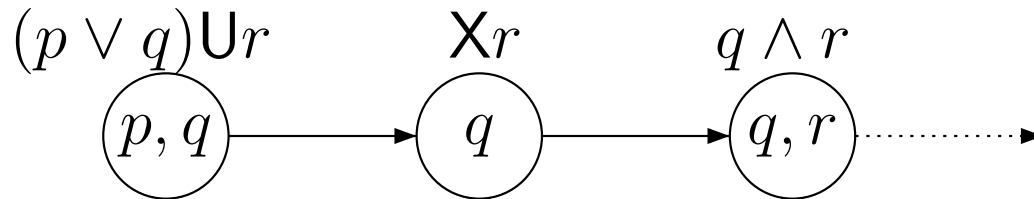
LTL

- Linear-time temporal logic for the specification of critical systems.

$$\phi ::= p \mid \neg\phi \mid \phi \wedge \phi' \mid X\phi \mid \phi U \phi'.$$

- Models: $\sigma : \mathbb{N} \rightarrow 2^{AP}$.

Satisfiability relation: $\sigma, i \models \phi$



- Model-checking: $\mathcal{M}, s \models \phi?$

Is there a path σ starting at s such that $\sigma, 0 \models \phi?$

Par. model checking for LTL

- **Theorem.** k, ϕ -MC_{LTL} is fp-equivalent to COMPACT NDTM COMPUTATION (and hence is AW[SAT]-hard).
- COMPACT NDTM COMPUTATION \leq_m^{fp} k, ϕ -MC_{LTL} because LTL can express reachability questions.
- k, ϕ -MC_{LTL} \leq_m^{fp} COMPACT NDTM COMPUTATION reduces to a repeated reachability question on $\mathcal{M}_1 \times \cdots \times \mathcal{M}_k \times \mathcal{B}_\phi$.

W[1]-completeness

LTL0: poor fragment of LTL that cannot express reachability.

$$\phi := p \mid \phi \vee \phi' \mid X\phi.$$

Theorem. k, ϕ -MC_{LTL0} is $W[1]$ -complete, even with only using a single atomic proposition.

Modal μ -calculus

- **Theorem.** k, ϕ -MC $_{\mu}$ is XP-complete.

Writing n for $\sum_i |\mathcal{M}_i|$, k, ϕ -MC $_{\mu}$ can be solved in time $\mathcal{O}((|\phi| \cdot n^k)^{|\phi|})$.

- XP-hardness is proved by a reduction from non-flat bisimilarity. Equivalence between
 - \mathcal{A} and \mathcal{B} are bisimilar;
 - $\mathcal{A} \parallel \mathcal{B}' \models \nu X. \bigwedge_{a \in \Sigma} ([a] \langle a' \rangle X \wedge [a'] \langle a \rangle X)$.
 $\mathcal{A} \parallel \mathcal{B}'$ interleaved product with \mathcal{B}' obtained from \mathcal{B} by renaming the actions $a \in \Sigma$ by a' .
- Non-flat bisimilarity is XP-hard already when $|\Sigma| = 2$.
→ we can bound the size of the μ -formula and have an fp-reduction.

$$\phi ::= p \mid \phi \vee \phi' \mid \phi \wedge \phi' \mid \Box\phi \mid \Diamond\phi.$$

- **Theorem.** $k, \phi\text{-MC}_{\text{HML}}$ is AW[1]-complete.
- Idea of the proof: $k, \phi\text{-MC}_{\text{HML}}$ is fp-equivalent to SHORT ATM COMPUTATION.
- Use of the standard correspondence between \Box and \Diamond and the behaviour of the ATMs with univ. states and exist. states, resp.

Computation Tree Logic CTL

- CTL can express reachability questions:
- **Theorem.** $\text{COMPACT NDTM COMPUTATION} \leq_m^{\text{fp}} k, \phi\text{-MC}_{\text{CTL}}$.
- Hence $k, \phi\text{-MC}_{\text{CTL}}$ is AW[SAT]-hard.
- **Open question:** Do we have $k, \phi\text{-MC}_{\text{CTL}} \leq_m^{\text{fp}} \text{COMPACT NDTM COMPUTATION}$?

Parameterized bisimulation

Parameterized Bisimulation (BISIM)

Instance: $2k$ LTSs $\mathcal{A}_1, \dots, \mathcal{A}_k, \mathcal{A}'_1, \dots, \mathcal{A}'_k$,
a configuration \bar{s} of $\mathcal{A}_1 \times \dots \times \mathcal{A}_k$,
a configuration \bar{s}' of $\mathcal{A}'_1 \times \dots \times \mathcal{A}'_k$.

Question: Is $\langle \mathcal{A}_1 \times \dots \times \mathcal{A}_k, \bar{s} \rangle$ (strongly) bisimilar to
 $\langle \mathcal{A}'_1 \times \dots \times \mathcal{A}'_k, \bar{s}' \rangle$?

Similar definition for other behavioral equivalence R between trace inclusion \subseteq_{tr} and bisimulation.

XP-complete problems

- **Theorem.** k -BISIM is XP-complete.
- k -BISIM is in XP since bisimilarity of flat systems is in P.
- XP-hardness is by observing that the reduction in the proof of Theorem 4.1 in [Laroussinie & Schnoebelen 00] can be seen as an fp-reduction from COMPACT ATM COMPUTATION to k -BISIM.
- **Theorem.** k -BISIM and k -BISIM $_{|\Sigma|=2}$ are fp-equivalent.

Other behavioral equivalences

- **Theorem.** For any relation R lying between the simulation preorder and bisimilarity, k - R -CHECKING is XP-hard.
- Consequence of [Laroussinie & Schnoebelen 00].
- Another hardness result:

Theorem. For any relation R lying between trace inclusion and bisimilarity, coCOMPACT NDTM COMPUTATION is fp-reducible to k - R -CHECKING, i.e. the problem of checking whether $\langle \mathcal{A}_1 \times \cdots \times \mathcal{A}_k, \bar{s} \rangle R \langle \mathcal{A}'_1 \times \cdots \times \mathcal{A}'_k, \bar{s}' \rangle$.

Sketch of the proof

Reduction of $\overline{k\text{-EXACT-REACH}}$ to $k\text{-R-CHECKING}$.

$\mathcal{A}_1, \dots, \mathcal{A}_k, \bar{s}, \bar{t}$ instance of $k\text{-EXACT-REACH}$ where $\bar{t} = \langle t_1, \dots, t_k \rangle$.

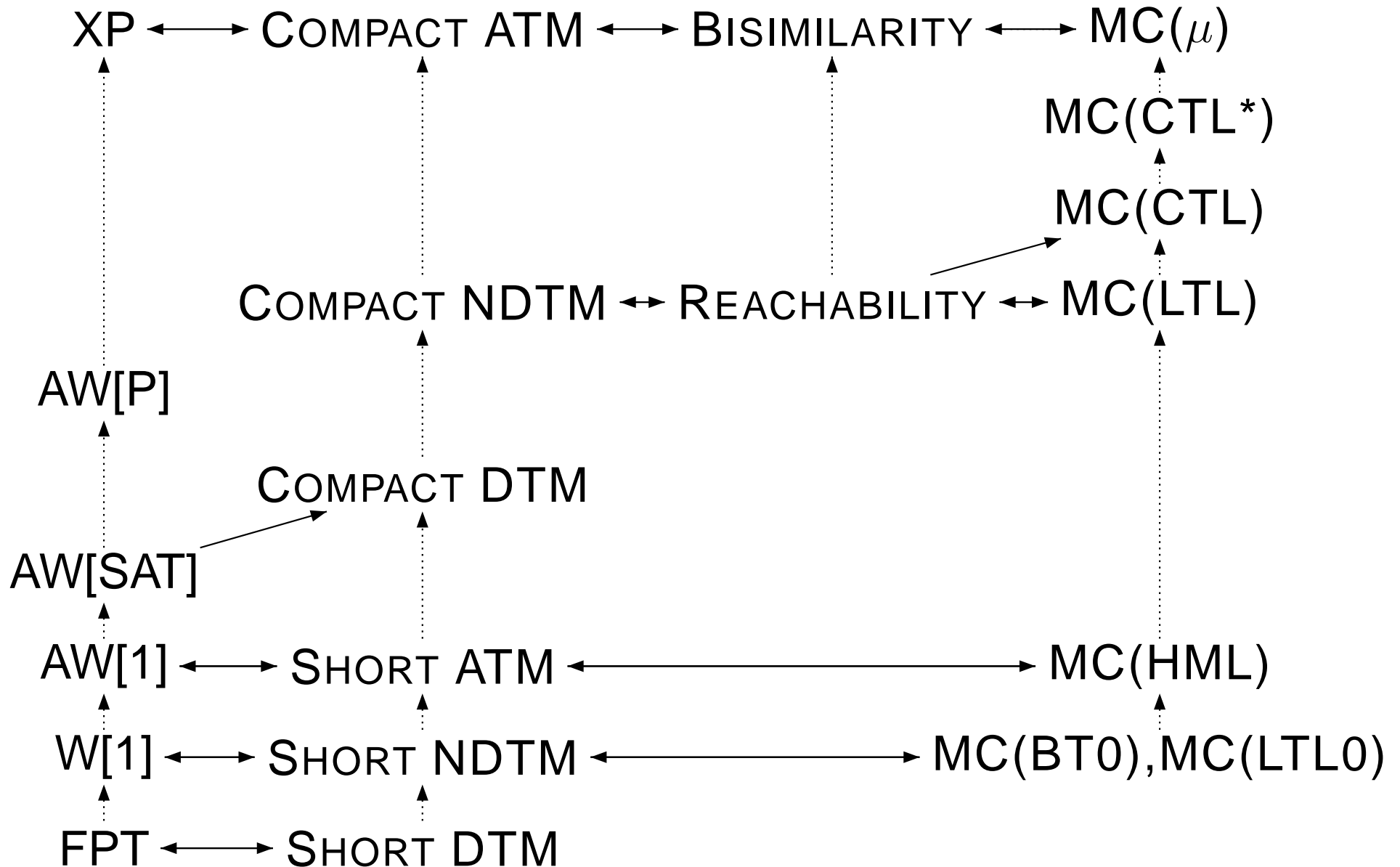
\mathcal{A}'_i : \mathcal{A}_i + a loop $t_i \xrightarrow{\#} t_i$, $\#$ new label.

$\mathcal{S} = \mathcal{A}_1 \times \dots \times \mathcal{A}_k$, $\mathcal{S}' = \mathcal{A}'_1 \times \dots \times \mathcal{A}'_k$

(1) $\langle \mathcal{S}, \bar{s} \rangle \sim \langle \mathcal{S}', \bar{s} \rangle$ iff (2) $\langle \mathcal{S}', \bar{s} \rangle \subseteq_{\text{tr}} \langle \mathcal{S}, \bar{s} \rangle$ iff (3) not $\bar{s} \xrightarrow{*} \bar{t}$ in \mathcal{S} .

Consequently, for $\sim \subseteq R \subseteq \subseteq_{\text{tr}}$, $\langle \mathcal{S}, \bar{s} \rangle R \langle \mathcal{S}', \bar{s} \rangle$ iff not $\bar{s} \xrightarrow{*} \bar{t}$.

Summary



Some concluding remarks

- Parameterized complexity framework is not yet in a stable condition. (see e.g. the introduction of the class MINI[1]).
- There are plenty of complexity issues related to verification problems in this framework (timed automata, Rabin automata, etc ...).
- Many problems from formal verification can be naturally parameterized but how parameterized complexity can be used to induce improvements in practice?
(mainly dark side presented during this talk)