TD: Logical Aspects of Artificial Intelligence $ATL^+ + ATL$ -like logics with resources (26/10/2022)

Exercise 1. Let \mathfrak{M} be a CGS with resources, $s \in S$ and $\langle\!\langle A^{\vec{b}} \rangle\!\rangle \Phi$ be a formula in ATL(Agt, r) (ATL with r resources). Show that the set $\{\vec{b} \in \mathbb{N}^r \mid \mathfrak{M}, s \models \langle\!\langle A^{\vec{b}} \rangle\!\rangle \Phi\}$ is upward-closed.

Exercise 2. Below, we present a CGS one resource \mathfrak{M} with two agents, the transitions are labelled by pairs of actions with the respective weights. For instance, the total weight of the transition from s_1 to s_2 is -2.



- 1. Characterise the set $\{n \in \mathbb{N} \mid \mathfrak{M}, s_1 \models \langle \langle \{1\}^n \rangle \rangle (\mathsf{G}p_1 \vee \mathsf{F}p_2) \}$.
- 2. Characterise the set of natural numbers $n \in \mathbb{N}$ such that there is a positional and *n*-consistent strategy σ w.r.t. s_1 for the coalition $\{1\}$ such that for all $\lambda \in \text{Comp}(s_1, \sigma)$, we have $\mathfrak{M}, \lambda \models (\mathsf{G}p_1) \lor (\mathsf{F}p_2)$.

Exercise 3. Design a CGS with one ressource \mathfrak{M} , $s \in S$ and $b \in \mathbb{N}$ such that \mathfrak{M} , $s \models \langle\!\langle A^b \rangle\!\rangle Fp$ but there is no *positional b*-strategy σ such that for all computations $\lambda \in \text{Comp}(s, \sigma)$, we have \mathfrak{M} , $\lambda \models Fp$.

Exercise 4. Let \mathfrak{M} be a CGS with one resource, $s \in S$, a coalition $A \subseteq Agt$, $b \in \mathbb{N}$ and σ be a *b*-consistent strategy from *s* for the coalition *A* such that for all computations $\lambda \in \text{Comp}(s, \sigma)$, we have $\mathfrak{M}, \lambda \models \mathsf{G}p$.

1. Show that for all $\lambda \in \text{Comp}(s, \sigma)$ with

$$RAV(b,\lambda) = (s_0, v_0) \rightarrow (s_1, v_1) \cdots (s_i, v_i) \cdots,$$

for all $i \ge 0$, we have $\mathfrak{M}, s_i \models p$ and $v_i \ge 0$.

- 2. We assume a total ordering on $\bigcup_{s \in S} D_A(s)$ (unspecified here). We write $D_A(s)$ to denote the set of joint actions for the coalition *A* from the state *s*. Let us define a positional strategy σ' as follows.
 - If a state s' does not occur in any computation of $Comp(s, \sigma)$, then $\sigma'(s') \stackrel{\text{def}}{=} \min D_A(s')$ (dummy value).
 - Now, assume that s' occurs in some computation of $\mathtt{Comp}(s,\sigma).$ Let $\min_{s'}$ be

$$min_{s'} \stackrel{\text{\tiny der}}{=} \min\{v \mid \exists \lambda \in \text{Comp}(s, \sigma) \text{ s.t. } (s', v) \text{ occurs in } RAV(b, \lambda)\}$$

Then,

$$\sigma'(s') \stackrel{\text{def}}{=} \min\{(\mathfrak{f}_j)|_A \mid \exists \ \lambda = s_0 \stackrel{\underline{\uparrow}_0}{\to} s_1 \dots \in \operatorname{Comp}(s, \sigma) \text{ with} \\ RAV(b, \lambda) = (s_0, v_0) \to (s_1, v_1) \dots, \ j \in \mathbb{N} \text{ s.t. } (s_j, v_j) = (s', \min_{s'}) \}$$

 $(\mathfrak{f}_j)_{|A}$ denotes the restriction of the joint action \mathfrak{f}_j to the agents in A. (considering the minimal value among all the $(\mathfrak{f}_j)_{|A}$'s is just a technical means to pick an arbitrary joint action) Show that all the states occurring in some computation in $\mathtt{Comp}(s,\sigma')$ satisfy the propositional variable p.

- 3. Show that for all computations $\lambda' = s'_0 \xrightarrow{f'_0} s'_1 \cdots \in \operatorname{Comp}(s, \sigma')$ with $RAV(b, \lambda') = (s'_0, v'_0) \to (s'_1, v'_1) \cdots$, for all $i' \in \mathbb{N}$, there is a computation $\lambda = s_0 \xrightarrow{f_0} s_1 \cdots \in \operatorname{Comp}(s, \sigma)$ with $RAV(b, \lambda) = (s_0, v_0) \to (s_1, v_1) \cdots$ and $i \in \mathbb{N}$ such that $s'_{i'} = s_i$ and $v'_{i'} \ge v_i$.
- 4. Conclude $\mathfrak{M}, s \models \langle\!\langle A^b \rangle\!\rangle \mathbf{G}p$ iff there is a *positional b*-strategy σ such that for all computations $\lambda \in \mathsf{Comp}(s, \sigma)$, we have $\mathfrak{M}, \lambda \models \mathbf{G}p$.

Exercise 5. Complete the proof of undecidability of ATL'(2) by showing that M reaches the instruction n iff $\mathfrak{M}, 1 \models \langle \langle \{1\}^{\vec{0}} \rangle \mathsf{F} p$.