Logical Aspects of AI: Knowledge Logics Correction of the exam – January 13th, 2021, 2pm-6pm, online

The correction below for the exercices 1-5 is more detailed than what was expected in the copies. Moreover, the subject (exercises 1 to 4, bonus exercise 5) was a bit too long for a two-hour exam but this has been taken into account in the grading.

Solution for the exercise 1.

- 1. We have $\mathcal{T} \not\models A_0 \sqsubseteq \exists r.A_1$ iff there is some interpretation $\mathcal{I} = (\Delta^{\mathcal{I}}, \cdot^{\mathcal{I}})$ such that $\mathcal{I} \models \mathcal{T}$ and there is $\mathfrak{a} \in \Delta^{\mathcal{I}}$ such that $\mathfrak{a} \in A_0^{\mathcal{I}}$ and $\mathfrak{a} \notin (\exists r.A_1)^{\mathcal{I}}$. Let $\mathcal{I} = (\Delta^{\mathcal{I}}, \cdot^{\mathcal{I}})$ with $\Delta^{\mathcal{I}} = \{0\}, r^{\mathcal{I}} = \emptyset$ for all role names $r, A_0^{\mathcal{I}} \stackrel{\text{def}}{=} \{0\}, A_3^{\mathcal{I}} \stackrel{\text{def}}{=} \{0\}, A_5^{\mathcal{I}} \stackrel{\text{def}}{=} \{0\}$, and $B^{\mathcal{I}} = \emptyset$ for all other concept names B.
 - We have $0 \in A_0^{\mathcal{I}}$ and $0 \notin \exists r. A_1^{\mathcal{I}}$.
 - $\mathcal{I} \models A_0 \sqsubseteq \forall r.A_1 \text{ because } A_0^{\mathcal{I}} = (\forall r.A_1)^{\mathcal{I}} = \{0\}.$
 - $\mathcal{I} \models A_1 \sqsubseteq \neg A_4$ because $A_1^{\mathcal{I}} = \emptyset$.
 - $\mathcal{I} \models A_0 \sqsubseteq A_2 \sqcup A_3$ because $A_0^{\mathcal{I}} = (A_2 \sqcup A_3)^{\mathcal{I}} = \{0\}.$
 - $\mathcal{I} \models A_2 \sqsubseteq \exists r.A_4 \text{ because } A_2^{\mathcal{I}} = \emptyset.$
 - $\mathcal{I} \models \exists r. \neg A_1 \sqsubseteq A_5$ because $(\exists r. \neg A_1)^{\mathcal{I}} = \emptyset$ and $A_5^{\mathcal{I}} = \{0\}$.
 - $\mathcal{I} \models A_3 \sqsubseteq A_5$ because $A_3^{\mathcal{I}} = A_5^{\mathcal{I}} = \{0\}$.

Consequently, $\mathcal{I} \models \mathcal{T}$ and therefore $\mathcal{T} \models A_0 \sqsubseteq \exists r.A_1 \text{ does not hold.}$

- 2. *Ad absurdum*, suppose that \mathcal{K} is consistent. So, there is an interpretation \mathcal{I} such that $\mathcal{I} \models \mathcal{T}$ and $\mathcal{I} \models \mathcal{A}$ and in particular
 - (a) $(a^{\mathcal{I}}, b^{\mathcal{I}}) \in r^{\mathcal{I}}$,
 - (b) $a^{\mathcal{I}} \in A_0^{\mathcal{I}}$,
 - (c) $b^{\mathcal{I}} \in A_4^{\mathcal{I}}$,
 - (d) $\mathcal{I} \models \{A_0 \sqsubseteq \forall r.A_1, A_1 \sqsubseteq \neg A_4\}.$

As (a) and (b), $\mathcal{I} \models A_0 \sqsubseteq \forall r.A_1$ entails $b^{\mathcal{I}} \in A_1^{\mathcal{I}}$. As $\mathcal{I} \models A_1 \sqsubseteq \neg A_4$, we conclude $b^{\mathcal{I}} \notin A_4^{\mathcal{I}}$, which is in contradiction with (c). Consequently, \mathcal{K} is not consistent.

Solution for the exercise 2.

1. In order to use the tableaux calculus for \mathcal{ALC} introduced in the course, the concepts in \mathcal{K} need to be in NNF and, the GCIs should be of the form $\top \sqsubseteq C$. The knowledge base \mathcal{K} can be transformed into the logically equivalent $\mathcal{K}' = (\mathcal{T}', \mathcal{A}')$ with

$$\mathcal{T}' = \{ \top \sqsubseteq \neg A \sqcup \exists r.A \} \quad \mathcal{A}' = \{ a : (A \sqcap (\exists r.B)) \sqcap \exists r. \neg B \}$$

In order to show that \mathcal{K} is consistent, it is sufficient to derive from \mathcal{A}' an ABox \mathcal{A}'' (i.e. $\mathcal{A}' \xrightarrow{*} \mathcal{A}''$) using the tableaux rule for \mathcal{ALC} with the \sqsubseteq -rule parameterised by \mathcal{T}' such that \mathcal{A}'' is clash-free and complete when the blocking technique is used. We provide a derivation of \mathcal{A}'' from the leftmost branch of the tableaux in Figure 1 such that \mathcal{A}'' is made of all the concept assertions and role assertions from that leftmost branch. Note that \mathcal{A}'' is clash-free and complete. Other branches leading to clashes are shown on the tableau but are not strictly speaking needed.

2. $(\mathcal{T}, \mathcal{A})$ and $(\mathcal{T}', \mathcal{A}')$ have exactly the same interpretations because transforming a concept into an equivalent concept in NNF preserves the semantics and similarly $C \sqsubseteq C'$ and $\top \sqsubseteq \neg C \sqcup C'$ are satisfied by exactly the same interpretations.

According to the soundness proof with blocking, an interpretation \mathcal{I} such that $\mathcal{I} \models (\mathcal{T}', \mathcal{A}')$ can be built from \mathcal{A}'' such that

- Δ^{*I*} is the set of individual names occurring in *A*" except the blocked ones,
- $(A^*)^{\mathcal{I}}$ is equal to the set of individual names a in $\Delta^{\mathcal{I}}$ such that $a: A^* \in \mathcal{A}''$,
- For all individual names $a, b \in \Delta^{\mathcal{I}}$, $(a, b) \in r^{\mathcal{I}}$ iff either $(a, b) : r \in \mathcal{A}''$ or there is a blocked individual names b'' in \mathcal{A}'' such that $(a, b'') : r \in \mathcal{A}''$ and b'' is blocked by b.

Consequently, an interpretation \mathcal{I} satisfying $(\mathcal{T}', \mathcal{A}')$ (and therefore satisfying also $(\mathcal{T}, \mathcal{A})$) is defined as follows.

• $\Delta^{\mathcal{I}} \stackrel{\text{\tiny def}}{=} \{a, b_1, b_2\}.$



Figure 1: A "tableaux" for deriving the complete and clash-free A"

- *A*^{*I*} ^{def} = {*a*}, *B*^{*I*} ^{def} = {*b*₂}, and the interpretation of the other concept names is arbitrary.
- *r*[⊥] ^{def} = {(a, b₁), (a, b₂), (b₁, b₁)} and the interpretation of the other role names is arbitrary.

The soundness proof guarantees that $\mathcal{I} \models \mathcal{K}$ but this could be also checked directly.

Solution for the exercise 3. Let us show that $\langle\!\langle A \rangle\!\rangle G\varphi \Rightarrow (\varphi \land \langle\!\langle A \rangle\!\rangle X \langle\!\langle A \rangle\!\rangle G\varphi)$ is valid for ATL, that is for all CGS \mathfrak{M} and states *s*, we have $\mathfrak{M}, s \models \langle\!\langle A \rangle\!\rangle G\varphi$ implies $\mathfrak{M}, s \models \varphi \land \langle\!\langle A \rangle\!\rangle X \langle\!\langle A \rangle\!\rangle G\varphi$.

Let \mathfrak{M} and s be such that $\mathfrak{M}, s \models \langle \langle A \rangle \rangle \mathbf{G} \varphi$. Below, we shall show that $\mathfrak{M}, s \models \varphi \land \langle \langle A \rangle \rangle \mathbf{X} \langle \langle A \rangle \rangle \mathbf{G} \varphi$. By definition of the semantics for ATL, there is a strategy F for the coalition A such that for all computations $\lambda \in \text{Comp}(s, F)$, for all positions $i \in \mathbb{N}$, we have $\mathfrak{M}, \lambda(i) \models \varphi$. As Comp(s, F) is non-empty (the action manager always returns a non-empty set of actions for each pair (a, s)), there is a computation $\lambda \in \text{Comp}(s, F)$ and therefore $\mathfrak{M}, \lambda(0) \models \varphi$. But $\lambda(0)$ is precisely s, whence $\mathfrak{M}, s \models \varphi$. It remains to show that $\mathfrak{M}, s \models \langle \langle A \rangle \rangle \mathbf{X} \langle \langle A \rangle \rangle \mathbf{G} \varphi$.

Let $\mathfrak{f} = F(s)$ be the joint action for the coalition A and we know that $\operatorname{out}(s,\mathfrak{f}) \subseteq \llbracket \varphi \rrbracket^{\mathfrak{M}}$ since $\mathfrak{M}, s \models \langle\!\langle A \rangle\!\rangle \mathsf{G}\varphi$. Suppose that $\operatorname{out}(s,\mathfrak{f}) = \{s_1^*, \ldots, s_{\alpha}^*\}$ for some $\alpha \ge 1$.

For each $i \in [1, \alpha]$, let F_i^* be a strategy such that for each history $s'_0 \cdots s'_n$ with $s'_0 = s_i^*$, we have $F_i^*(s'_0 \cdots s'_n) \stackrel{\text{def}}{=} F(ss'_0 \cdots s'_n)$. Consequently, for all $\lambda \in \text{Comp}(s_i^*, F_i^*)$, $s \cdot \lambda \in \text{Comp}(s, F)$ (here we use the fact that $\mathfrak{f} = F(s)$ and $s_i^* \in \text{out}(s, \mathfrak{f})$). Hence, for all positions $j \in \mathbb{N}$, we have $\mathfrak{M}, \lambda(j) \models \varphi$ and therefore $\mathfrak{M}, s_i^* \models \langle\!\langle A \rangle\!\rangle \mathsf{G}\varphi$. This means that $\text{out}(s, \mathfrak{f}) \subseteq [\![\langle\!\langle A \rangle\!\rangle \mathsf{G}\varphi]\!]^{\mathfrak{M}}$. However, $\mathfrak{M}, s \models \langle\!\langle A \rangle\!\rangle \mathsf{G}\varphi]^{\mathfrak{M}}$. Hence, $\mathfrak{M}, s \models \langle\!\langle A \rangle\!\rangle \mathsf{G}\varphi$.

Solution for the exercise 4.

1. Here is the derivation of $A_1 \sqsubseteq A_2$.

$$\frac{A_1 \sqsubseteq B_2}{A_1 \sqsubseteq B_2} \in \frac{A_1 \sqsubseteq \exists r.A_1}{B_1 \sqcap B_2 \sqsubseteq A_2} \in \frac{A_1 \sqsubseteq \exists r.A_1}{A_1 \sqsubseteq B} \stackrel{\neg}{=} \frac{A_1 \sqsubseteq B}{A_1 \sqsubseteq B} \stackrel{\neg}{=} \frac{A_1 \sqsubseteq B}{A_1 \sqsubseteq B_1} \stackrel{\neg}{=} \frac{A_1 \sqsubseteq B_1}{A_1 \sqsubseteq B_1} \stackrel{\neg}{=} \frac{A_1 \sqsubseteq B_1}{A_1 \sqsubseteq A_2}$$

2. First, suppose that $S(\mathcal{T}) \subseteq \{A_1^*, \ldots, A_{\alpha}^*\} \cup \{r_1, \ldots, r_{\beta}\}$ for some $\alpha, \beta \geq 1$ where each A_i^* is a concept name and each r_i is a role name. As \mathcal{T} is finite, α and β always exist. Let us define \mathcal{T}^c as $\{C \sqsubseteq D \mid \mathcal{T} \vdash C \sqsubseteq D\}$. Thanks to the \in -rule, $\mathcal{T} \subseteq \mathcal{T}^c$ and \mathcal{T}^c is simple and complete. The fact that \mathcal{T}^c is simple is only due to the property that all the conclusions in inference rules are authorised GCIs in simple TBoxes. Note that completeness is a consequence of the property: $\mathcal{T}^c \vdash C \sqsubseteq D$ implies $\mathcal{T} \vdash C \sqsubseteq D$. Furthermore, observe that the set of GCIs of the form

$$A \sqsubseteq B \quad A_1 \sqcap A_2 \sqsubseteq B \quad A \sqsubseteq \exists r.B \quad \exists r.A \sqsubseteq B$$

built from $S(\mathcal{T})$ is finite and actually cubic in $\alpha + \beta$. Consequently, \mathcal{T}^c is finite. Hence, \mathcal{T}^c is a simple and complete TBox with $\mathcal{T} \subseteq \mathcal{T}^c$. In order to establish that \mathcal{T}^c is the smallest such a set, *ad absurdum*, suppose that $\mathcal{T} \subseteq \mathcal{T}' \subset \mathcal{T}^c$, and \mathcal{T}' is simple and complete. So, there is $C \sqsubseteq D$ such that $\mathcal{T} \vdash C \sqsubseteq D$ and $C \sqsubseteq D \notin \mathcal{T}'$. As $\mathcal{T} \subseteq \mathcal{T}'$, we can also conclude that $\mathcal{T}' \vdash C \sqsubseteq D$. However, we have just seen that $C \sqsubseteq D \notin \mathcal{T}'$, which is in contradiction with the completeness of \mathcal{T}' .

In order to compute \mathcal{T}^c , we proceed as follows (saturation algorithm). Given a simple TBox \mathcal{T} , we write $C(\mathcal{T})$ to denote the set of GCIs obtained from \mathcal{T} by applying one inference rule from premisses in \mathcal{T} . As each rule involves at most three premisses, and each rule inference can be checked in linear time in the size of its premisses, computing $C(\mathcal{T})$ requires cubic time in the size of \mathcal{T} . Here is the saturation algorithm.

- $X = \mathcal{T};$
- While $C(X) \neq X$ do X := C(X);
- return X.

The while loop is visited a number of times at most cubic in $\alpha + \beta$ and the size of *X* is also at most cubic in $\alpha + \beta$. Hence, the returned value *X* is computed in cubic time in \mathcal{T} and is equal to \mathcal{T}^c .

3. The proof is on the length of the derivation to establish $\mathcal{T} \vdash C \sqsubseteq D$. In order to provide a complete formal treatment, let us introduce the notion \mathcal{T} -derivation. A \mathcal{T} -derivation is a sequence ($C_1 \sqsubseteq$

 $D_1, \ldots, C_K \sqsubseteq D_K$ ($K \ge 1$) such that for all $i \in [1, K]$, at least one of the conditions below holds.

- (a) $C_i \sqsubseteq D_i \in \mathcal{T}$ (use of the \in -rule).
- (b) $C_i \sqsubseteq D_i$ is of the form $A \sqsubseteq A$ for some concept name A in $\mathcal{S}(\mathcal{T})$ (use of the id-rule).
- (c) $C_i \sqsubseteq D_i$ is of the form $A \sqsubseteq \top$ for some concept name A in $\mathcal{S}(\mathcal{T})$ (use of the \top -rule).
- (d) there are $i_1, i_2 < i$ such that $C_{i_1} = C_i, D_{i_1} = C_{i_2}, D_{i_2} = D_i$ (use of the trans-rule).
- (e) Similarly (and we omit the very details herein), there are GCIs that occur strictly before $C_i \sqsubseteq D_i$ in the sequence that can be used as premisses for either the \exists -rule or the \sqcap -rule leading exactly to the conclusion $C_i \sqsubseteq D_i$.

So, $\mathcal{T} \vdash C \sqsubseteq D$ iff there is a \mathcal{T} -derivation $(C_1 \sqsubseteq D_1, \ldots, C_K \sqsubseteq D_K)$ such that $C_K \sqsubseteq D_K$ is equal to $C \sqsubseteq D$. It remains to show that for all the \mathcal{T} -derivations $(C_1 \sqsubseteq D_1, \ldots, C_K \sqsubseteq D_K)$, we have $\mathcal{T} \models C_K \sqsubseteq D_K$ (which guarantees that for all interpretations \mathcal{I} , we have $\mathcal{I} \models \mathcal{T}$ iff $\mathcal{I} \models \mathcal{T} \cup \{C_K \sqsubseteq D_K\}$).

The proof is by induction on *i*. For the base case, $C_1 \sqsubseteq D_1$ satisfies one condition among (a), (b), (c). As $A \sqsubseteq A$ and $A \sqsubseteq \top$ hold in all interpretations, the cases for (b) and (c) are immediate. Similarly, obviously $\mathcal{T} \models C_1 \sqsubseteq D_1$. Indeed, $\mathcal{I} \models \mathcal{T}$ implies for all $C \sqsubseteq D \in \mathcal{T}$, we have $\mathcal{I} \models C \sqsubseteq D$. In particular, this leads to $\mathcal{I} \models C_1 \sqsubseteq D_1$ as $C_1 \sqsubseteq D_1 \in \mathcal{T}$ in the case (a).

For the induction step, we only treat the cases with the trans-rule and the \exists -rule, the case with the \sqcap -rule is omitted but very similar.

Suppose that

$$\frac{\mathcal{T} \vdash C_i \sqsubseteq D_{i_1}, \ \mathcal{T} \vdash D_{i_1} \sqsubseteq D_i}{\mathcal{T} \vdash C_i \sqsubseteq D_i}$$

with $i_1, i_2 < i$ and $C_{i_1} = C_i, D_{i_1} = C_{i_2}, D_{i_2} = D_i$. By (IH), $\mathcal{T} \models C_i \sqsubseteq D_{i_1}$ and $\mathcal{T} \models D_{i_1} \sqsubseteq D_i$. Let \mathcal{I} be an interpretation such that $\mathcal{I} \models \mathcal{T}$. So $\mathcal{I} \models \{C_i \sqsubseteq D_{i_1}, D_{i_1} \sqsubseteq D_i\}$, which leads to $C_i^{\mathcal{I}} \subseteq D_i^{\mathcal{I}}$ by transitivity of

set-inclusion and therefore $\mathcal{I} \models C_i \sqsubseteq D_i$. Consequently $\mathcal{T} \models C_i \sqsubseteq D_i$ as \mathcal{I} above were arbitrary.

Consider now the case of the \exists -rule.

$$\frac{\mathcal{T} \vdash \overbrace{A \sqsubseteq \exists r.A_1}^{= C_{i_1} \sqsubseteq D_{i_1}}, \quad \mathcal{T} \vdash \overbrace{A_1 \sqsubseteq B_1}^{= C_{i_2} \sqsubseteq D_{i_2}}}{\mathcal{T} \vdash \underbrace{A \sqsubseteq \exists r.B_1}_{= C_i \sqsubseteq D_i}} \exists \text{-rule}$$

Let \mathcal{I} be an interpretation such that $\mathcal{I} \models \mathcal{T}$. By (IH), $\mathcal{I} \models \{A \sqsubseteq \exists r.A_1, A_1 \sqsubseteq B_1\}$. In particular, this entails that $\mathcal{I} \models \exists r.A_1 \sqsubseteq \exists r.B_1$ as $\mathcal{I} \models A_1 \sqsubseteq B_1$. Indeed, $(\mathfrak{a}, \mathfrak{b}) \in r^{\mathcal{I}}$ and $\mathfrak{b} \in A_1^{\mathcal{I}}$ imply $(\mathfrak{a}, \mathfrak{b}) \in r^{\mathcal{I}}$ and $\mathfrak{b} \in B_1^{\mathcal{I}}$ as $A_1^{\mathcal{I}} \subseteq B_1^{\mathcal{I}}$. Now $\mathcal{I} \models \{A \sqsubseteq \exists r.A_1, \exists r.A_1 \sqsubseteq \exists r.B_1\}$ implies $\mathcal{I} \models A \sqsubseteq \exists r.B_1$ by transitivity of set-inclusion. Consequently $\mathcal{T} \models C_i \sqsubseteq D_i$ as \mathcal{I} above were arbitrary.

To conclude, suppose that $C \sqsubseteq D \in \mathcal{T}^c$. By definition of \mathcal{T}^c , we have $\mathcal{T} \vdash C \sqsubseteq D$. According to the developments above, we get $\mathcal{T} \models C \sqsubseteq D$.

4. First, let us check that $\top^{\mathcal{I}} = \Delta^{\mathcal{I}}$. By definition, $\top^{\mathcal{I}}$ is equal to $\{A \in \Delta^{\mathcal{I}} \mid A \sqsubseteq \top \in \mathcal{T}^c\}$. Since \mathcal{T}^c is complete, by application of the \top -rule, for all concept names in $\mathcal{S}(\mathcal{T})$, we have $A \sqsubseteq \top \in \mathcal{T}^c$. Hence $\top^{\mathcal{I}}$ is equal to the set of all concept names in $\mathcal{S}(\mathcal{T})$ (including \top), which is precisely $\Delta^{\mathcal{I}}$ by definition.

Let us show that $\mathcal{I} \models \mathcal{T}^c$. We make a case analysis and we use the fact that \mathcal{T}^c is complete.

- $A \sqsubseteq B \in \mathcal{T}^c$. Suppose that $A' \in A^{\mathcal{I}}$. By definition, $A' \sqsubseteq A \in \mathcal{T}^c$. As \mathcal{T}^c is complete, by application of the trans-rule, we get $A' \sqsubseteq B \in \mathcal{T}^c$. By definition of $\mathcal{I}, A' \in B^{\mathcal{I}}$. In conclusion, $\mathcal{I} \models A \sqsubseteq B$.
- $A \sqsubseteq \exists r.B \in \mathcal{T}^c$. Suppose that $A' \in A^{\mathcal{I}}$. By definition, $A' \sqsubseteq A \in \mathcal{T}^c$. As \mathcal{T}^c is complete, by application of the trans-rule, we get $A' \sqsubseteq \exists r.B \in \mathcal{T}^c$. By definition of $r^{\mathcal{I}}$, we have $(A', B) \in r^{\mathcal{I}}$. Moreover, $B \in B^{\mathcal{I}}$ as $B \sqsubseteq B \in \mathcal{T}^c$ by completeness of \mathcal{T}^c and thanks to the id-rule. Hence, $A' \in (\exists r.B)^{\mathcal{I}}$. In conclusion, $\mathcal{I} \models A \sqsubseteq \exists r.B$.
- $\exists r.A \sqsubseteq B \in \mathcal{T}^c$. Suppose that $A' \in (\exists r.A)^{\mathcal{I}}$. So, there is A'' such that $(A', A'') \in r^{\mathcal{I}}$ and $A'' \in A^{\mathcal{I}}$. By definition of $r^{\mathcal{I}}, A' \sqsubseteq \exists r'.A'' \in \mathcal{T}^c$.

By definition of $A^{\mathcal{I}}$, $A'' \sqsubseteq A \in \mathcal{T}^c$. By completeness of \mathcal{T}^c and the \exists -rule, we have $A' \sqsubseteq \exists r.A \in \mathcal{T}^c$. By completeness of \mathcal{T}^c and the trans-rule, $A' \sqsubseteq B \in \mathcal{T}^c$. By definition of $B^{\mathcal{I}}$, we get $A' \in B^{\mathcal{I}}$. In conclusion, $\mathcal{I} \models \exists r.A \sqsubseteq B$.

- $A_1 \sqcap A_2 \sqsubseteq B \in \mathcal{T}^c$. Suppose that $A' \in (A_1 \sqcap A_2)^{\mathcal{I}}$. So $A' \in A_1^{\mathcal{I}}$ and $A' \in A_2^{\mathcal{I}}$ and by definition, $A' \sqsubseteq A_1 \in \mathcal{T}^c$ and $A' \sqsubseteq A_2 \in \mathcal{T}^c$ As \mathcal{T}^c is complete, by application of the \sqcap -rule, we get $A' \sqsubseteq B \in \mathcal{T}^c$. By definition of $\mathcal{I}, A' \in B^{\mathcal{I}}$. In conclusion, $\mathcal{I} \models A \sqsubseteq B$.
- 5. Suppose that $A \sqsubseteq B \notin \mathcal{T}^c$. By definition of $B^{\mathcal{I}}$, $A \notin B^{\mathcal{I}}$. Moreover, $A \in A^{\mathcal{I}}$ as $A \sqsubseteq A \in \mathcal{T}^c$ thanks to the id-rule. Consequently, $\mathcal{I} \models \mathcal{T}$ (since $\mathcal{I} \models \mathcal{T}^c$ and $\mathcal{T} \subseteq \mathcal{T}^c$), and $\mathcal{I} \not\models A \sqsubseteq B$. So, $\mathcal{T} \not\models A \sqsubseteq B$.
- 6. By combining the answers for the questions 3. and 5., we get that A ⊆ B ∈ T^c iff T ⊨ A ⊆ B. By the question 2., T^c can be computed in polynomial time in the size of T. Here is the simple polynomial-time algorithm to check whether for all interpretations I, (I ⊨ T implies I ⊨ A ⊆ B).
 - (a) compute \mathcal{T}^c from \mathcal{T} ;
 - (b) check whether $A \sqsubseteq B$ belongs to \mathcal{T}^c .

Solution for the exercise 5.

- 1. Figure 2 contains a graphical representation of the CGS $\mathfrak{M}_{T,n}$ with $T = \{t_0, t_1\}$ and n = 3. Note that for any T and n, for all infinite computations λ starting from $(0, 0, t_0)$, for all $i, j \in [0, n 1]$, there is a unique position I such that $\lambda(I)$ is of the form (i, j, t).
- 2. The path formula $Error^{H}(i, j)$ is defined as

$$\bigvee_{t \in T} \left((\mathsf{F}((i,j) \mapsto t) \land \bigvee_{t',(t',t) \notin H} \mathsf{F}((i-1,j) \mapsto t') \right)$$

3. The path formula $Error^{V}(i, j)$ is defined as

$$\bigvee_{t \in T} \left((\mathsf{F}((i,j) \mapsto t) \land \bigvee_{t',(t',t) \not\in V} \mathsf{F}((i,j-1) \mapsto t') \right)$$

$$\begin{array}{c} 0, 0, t_{0} \\ (\epsilon_{1}, \epsilon_{0}) \\ (\epsilon_{1}, \epsilon_{0}) \\ 0, 1, t_{0} \\ (\epsilon_{1}, \epsilon_{0}) \\ 0, 1, t_{0} \\ (\epsilon_{1}, \epsilon_{0}) \\ (\epsilon_{1}, \epsilon_{0}) \\ (\epsilon_{1}, \epsilon_{0}) \\ (\epsilon_{1}, \epsilon_{1}) \\ (\epsilon_{1},$$

Figure 2: CGS $\mathfrak{M}_{T,n}$ with $T = \{t_0, t_1\}$ and n = 3

4. The formula $\varphi_{T,n}$ is defined as follows, taking advantage of the property (that would need to be proved) that strategies for Player 2 in the $(n \times n)$ -tiling game problem correspond to strategies for agent 2 in $\mathfrak{M}_{T,n}$ as far as the infinite computations from $(0,0,t_0)$ are concerned.

$$\langle\!\langle 2 \rangle\!\rangle \left(\underbrace{\bigwedge_{i \in [1, n-1]}^{Player 2 \text{ does not lose immediately on row 0}}_{i \in [1, n-1]} \wedge \right.$$

$$\bigwedge_{j \in [1,n-1]} \left(\underbrace{\bigvee_{i \in [1,n-1]} (Error^{H}(i,j) \lor Error^{V}(i,j))}_{i \in [1,n-1]} \Rightarrow \underbrace{\bigvee_{j' \in [1,j]} Error^{V}(0,j')}_{then \ Player \ 1 \ loses \ immediately \ before} \right) \right)$$

As $\mathfrak{M}_{T,n}$ is of polynomial size in the size of T and n, and $\varphi_{T,n}$ is of polynomial size in the size of T and n, the above developments correspond to key steps to establish that the model-checking problem for ATL[†] is PSPACE-hard.