

Almost-Sure Model Checking of Infinite Paths in One-Clock Timed Automata

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Outline

1. Introduction
2. A probabilistic semantics
3. Solving the qualitative model-checking problem
4. Conclusion

Motivations

- Timed automata, [an idealized mathematical model](#) for real-time systems

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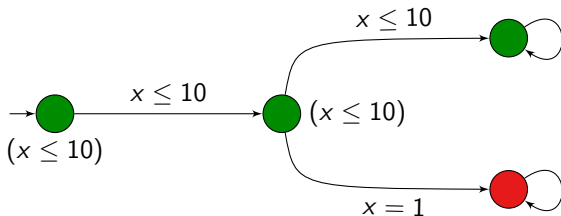
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Our aim:

Use probabilities to “relax” the semantics of timed automata

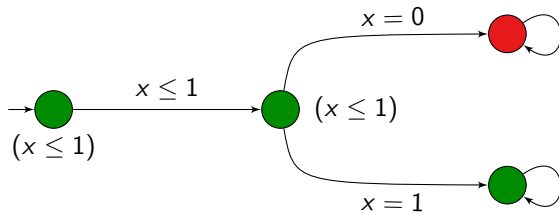
Initial example



Intuition: from the initial state,

this automaton *almost-surely* satisfies “G green”

A maybe less intuitive example



Does it *almost-surely* satisfy “G green”?

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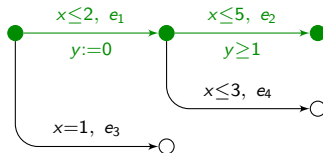
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Our proposition

- $\pi(s \xrightarrow{e_1} \dots \xrightarrow{e_n})$: symbolic path from s firing edges e_1, \dots, e_n

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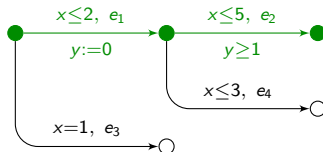
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- Example:



$$\pi(s_0 \xrightarrow{e_1} \xrightarrow{e_2}) = \{s_0 \xrightarrow{\tau_1, e_1} s_1 \xrightarrow{\tau_2, e_2} s_2 \mid \tau_1 \leq 2, \tau_1 + \tau_2 \leq 5, \tau_2 \geq 1\}$$

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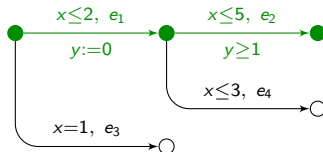
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Idea:

From state s_0 :

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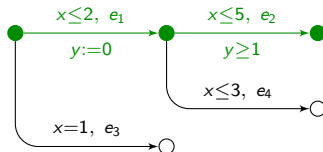
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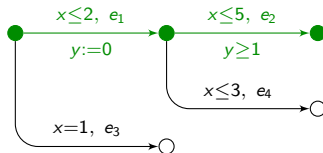
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Symbolic path: $\pi(s \xrightarrow{e_1} \dots \xrightarrow{e_n}) = \{s \xrightarrow{\tau_1, e_1} s_1 \dots \xrightarrow{\tau_n, e_n} s_n\}$

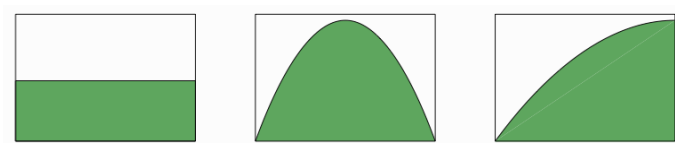
$$\mathbb{P}\left(\pi\left(s \xrightarrow{e_1} \dots \xrightarrow{e_n}\right)\right) = \int_{t \in I(s, e_1)} p_{s+t}(e_1) \mathbb{P}\left(\pi\left(s_t^{e_1} \xrightarrow{e_2} \dots \xrightarrow{e_n}\right)\right) d\mu_s(t)$$

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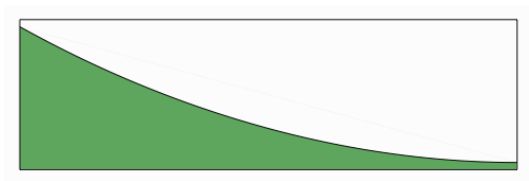


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- Easy extension to constrained symbolic paths

$$\pi_{\mathcal{C}}(s \xrightarrow{e_1} \dots \xrightarrow{e_n}) = \{s \xrightarrow{\tau_1, e_1} s_1 \dots \xrightarrow{\tau_n, e_n} s_n \mid (\tau_1, \dots, \tau_n) \models \mathcal{C}\}$$

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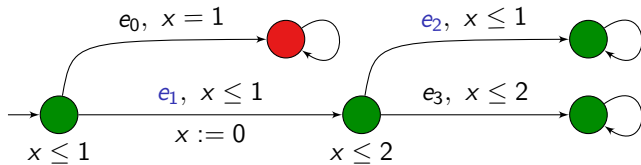
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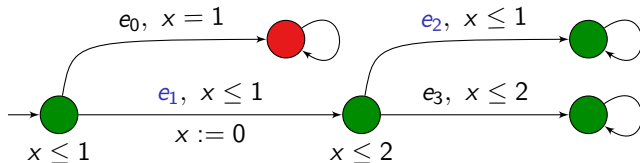
$$\bullet \text{ Zeno}(s) = \bigcup_{M \in \mathbb{N}} \bigcap_{n \in \mathbb{N}} \bigcup_{(e_1, \dots, e_n) \in E^n} \text{Cyl}(\pi_{\sum_i \tau_i \leq M}(s \xrightarrow{e_1} \dots \xrightarrow{e_n}))$$

An example of computation (with uniform distributions)



The probability of the symbolic path $\pi(s_0 \xrightarrow{e_1} \xrightarrow{e_2})$ is $\frac{1}{4}$.

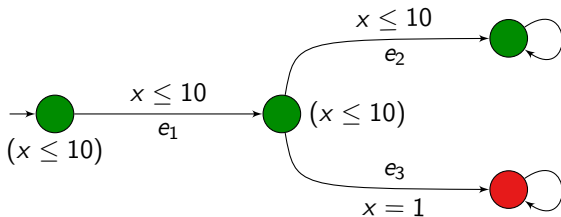
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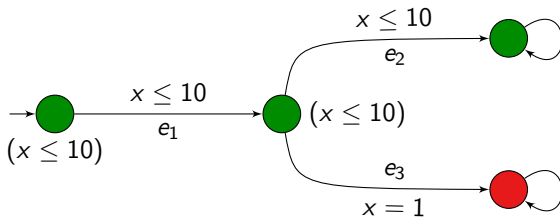
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$$\begin{aligned}
 \mathbb{P}(\pi(s_0 \xrightarrow{e_1} \xrightarrow{e_2})) &= \int_0^1 \mathbb{P}(\pi(s_1 \xrightarrow{e_2})) d\mu_{s_0}(t) + \int_1^1 \frac{\mathbb{P}(\pi(s_1 \xrightarrow{e_2}))}{2} d\mu_{s_0}(t) \\
 &= \int_0^1 \int_0^1 \left(\frac{\mathbb{P}(\pi(s_2))}{2} d\mu_{s_1}(u) \right) d\mu_{s_0}(t) \\
 &= \int_0^1 \int_0^1 \left(\frac{1}{2} \frac{du}{2} \right) dt = \frac{1}{4}
 \end{aligned}$$

Back to the first example

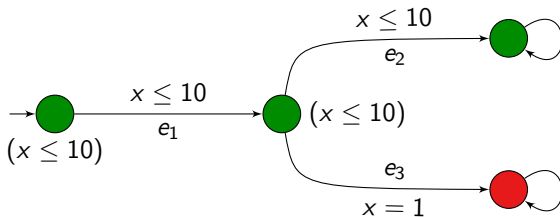


Back to the first example



- $\mathbb{P}\left(\pi\left(s_0 \xrightarrow{e_1} \xrightarrow{e_2} \right)\right) = 1$

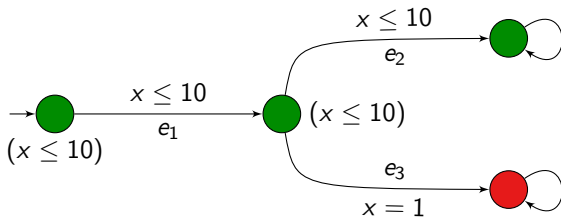
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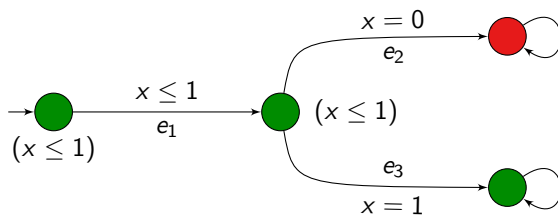
- $\mathbb{P}\left(\pi\left(s_0 \xrightarrow{e_1} \xrightarrow{e_3} \right)\right) = 0$

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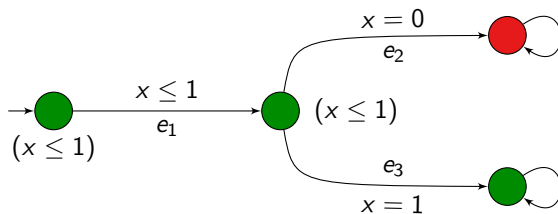


- $\mathbb{P}\left(\pi(s_0 \xrightarrow{e_1} \xrightarrow{e_2})\right) = 1$
- $\mathbb{P}\left(\pi(s_0 \xrightarrow{e_1} \xrightarrow{e_3})\right) = 0$
- $\mathbb{P}\left(\mathbf{G} \text{ green}\right) = 1$

Back to the second example

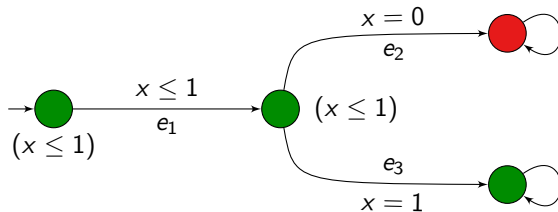


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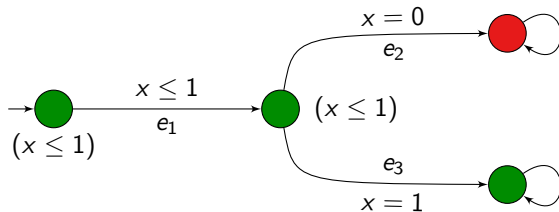
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Almost-sure model-checking

If φ is an LTL (or ω -regular) property,

$$s \models \varphi \stackrel{\text{def}}{\iff} \mathbb{P}\left(\{\varrho \in \text{Runs}(s) \mid \varrho \models \varphi\}\right) = 1$$

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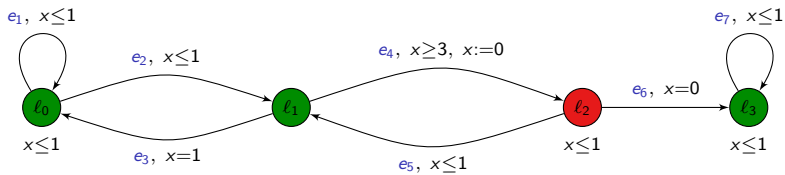
We want to decide the almost-sure model-checking...

(This is a **qualitative** model-checking question)

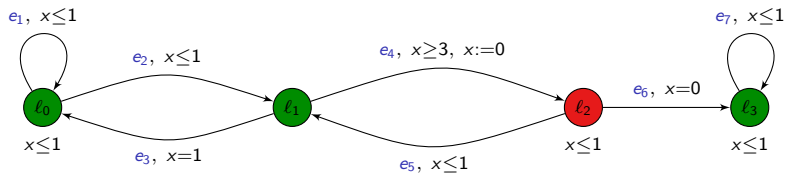
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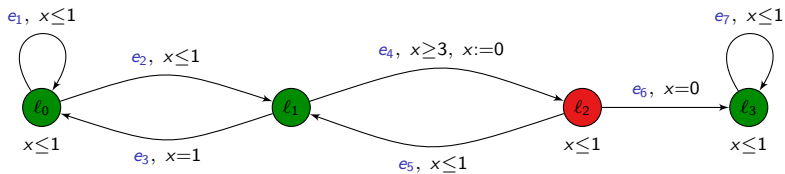


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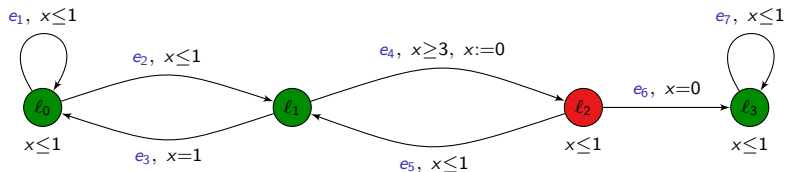
$$\mathcal{A} \not\models \mathbf{G}(\text{green} \Rightarrow \mathbf{F} \text{red})$$

An example



$\mathcal{A} \not\models \mathbf{G}(\text{green} \Rightarrow \mathbf{F} \text{ red})$ but $\mathcal{A} \models \mathbf{G}(\text{green} \Rightarrow \mathbf{F} \text{ red})$

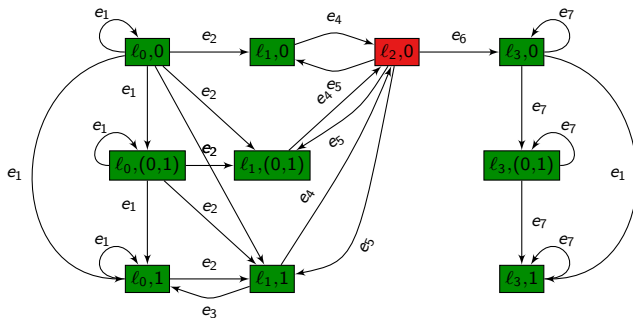
An example



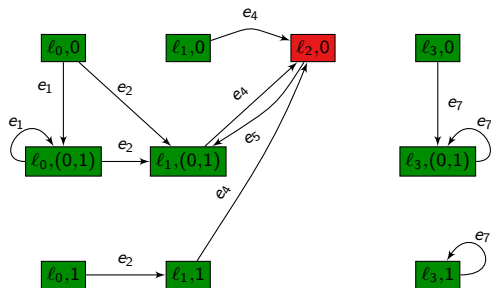
$$\mathcal{A} \not\models \mathbf{G}(\text{green} \Rightarrow \mathbf{F} \text{ red}) \quad \text{but} \quad \mathcal{A} \approx \mathbf{G}(\text{green} \Rightarrow \mathbf{F} \text{ red})$$

Indeed, almost surely, paths are of the form $e_1^* e_2 (e_4 e_5)^\omega$

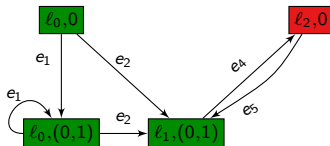
The classical region automaton



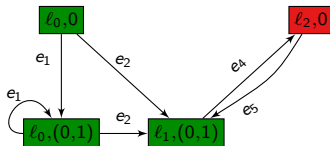
The pruned region automaton



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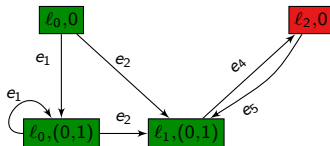


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Theorem

For **single-clock** timed automata,

$$\mathcal{A} \approx \varphi \quad \text{iff} \quad \mathbb{P}(MC(\mathcal{A}) \models \varphi) = 1$$

Result

Theorem

For **single-clock** timed automata, the almost-sure model-checking

- of LTL is PSPACE-Complete
- of ω -regular properties is NLOGSPACE-Complete

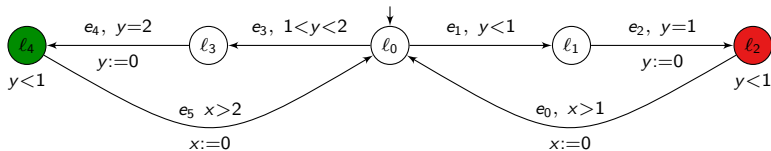
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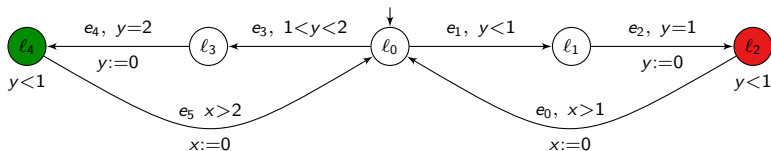
For **single-clock** timed automata, the almost-sure model-checking

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-
- **Complexity:**
 - size of single-clock region automata = polynomial [LMS04]
 - apply result of [CSS03] to the finite Markov chain
 - **Correctness:** the proof is rather involved
 - requires the definition of a topology over the set of paths
 - notions of largeness (for proba 1) and meagerness (for proba 0)
 - link between probabilities and topology thanks to the topological games called **Banach-Mazur games**

An example with two clocks

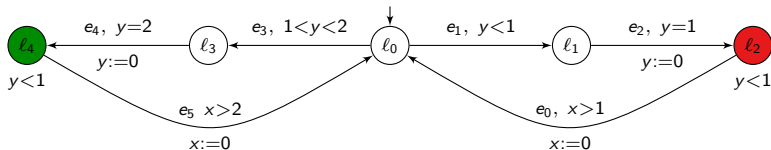


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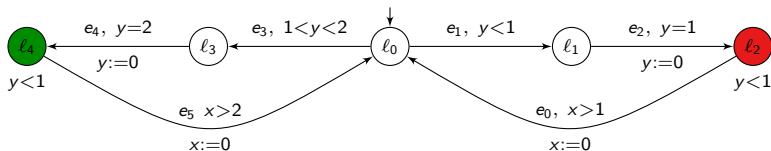
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An example with two clocks



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- However, we can prove that $\mathbb{P}(\mathbf{G} \neg \text{red}) > 0$
- There is a *strange convergence phenomenon*: along an execution, if $\delta_i > 0$ is the delay in location ℓ_4 , then we have that $\sum_i \delta_i \leq 1$

A note on Zeno behaviours

- The set of Zeno behaviours is measurable:

$$\text{Zeno}(s) = \bigcup_{M \in \mathbb{N}} \bigcap_{n \in \mathbb{N}} \bigcup_{(e_1, \dots, e_n) \in E^n} \text{Cyl}(\pi(s \xrightarrow{e_1} \dots \xrightarrow{e_n}))$$

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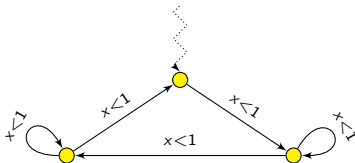
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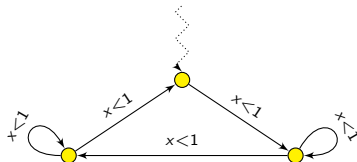


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- an interesting notion of non-Zeno timed automata

$$x \leq 1, \ x := 0$$



Outline

1. Introduction
2. A probabilistic semantics
3. Solving the qualitative model-checking problem
4. Conclusion

Conclusions

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 \leadsto extend continuous-time Markov chains
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Ongoing work

- our semantics can be viewed as a $\frac{1}{2}$ -player game
 $1\frac{1}{2}$ - and $2\frac{1}{2}$ -player games
 \leadsto further interesting (un)decidability results