# Averaging in LTL

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Introduction Average-LTL Results Conclusion

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Outline
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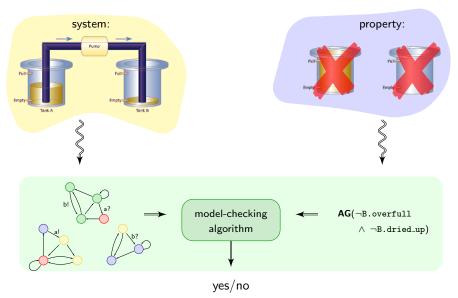
1 Introduction







# Model-checking

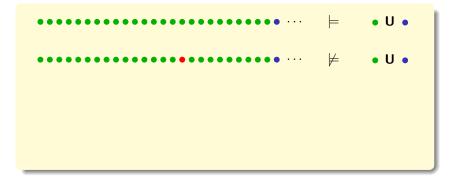


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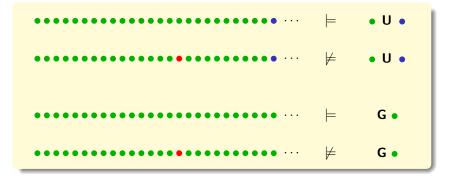
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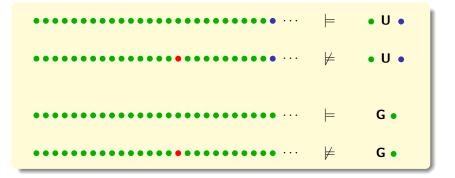


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Strict dichotomy between correct and incorrect systems



 $\rightsquigarrow$  this Boolean approach might be too crude

Quantitative model-checking

Measure the accuracy of a system w.r.t. a property.

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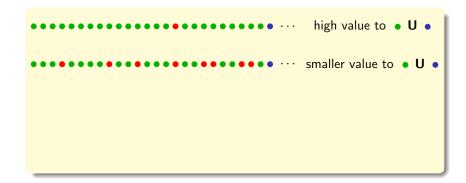
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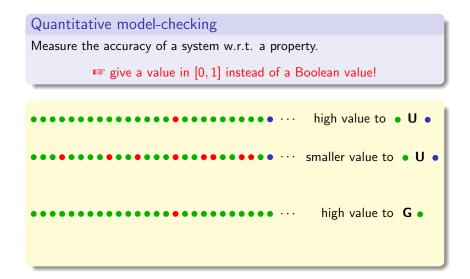


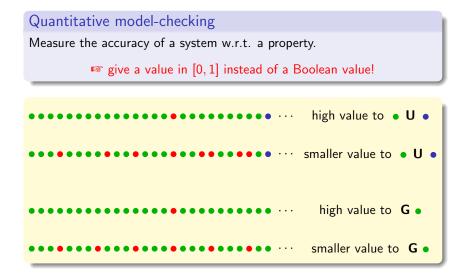
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### Related work

#### Quantitative verification

- value of executions given by weighted automata [DCH10,...]
- accuracy of a model given by a distance to another model or to a specification (e.g. simulation distance [CHR12], model measuring [HO13])
- quantitative specification languages/logics: standard in probabilistic model-checking (e.g. CSL and PCTL logics)

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- Logics yielding finitely many values
  - min/max extension of LTL to quant. Kripke structures [FLS08]
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- Discounted LTL [ABK14]
  - the until modality discounts over the future









$$\varphi ::= \mathbf{p} \mid \neg \mathbf{p} \mid \varphi \lor \varphi \mid \varphi \land \varphi \mid \mathbf{X} \varphi \mid \varphi \mathbf{U} \varphi \mid \mathbf{G} \varphi \mid \varphi \widetilde{\mathbf{U}} \varphi \mid \widetilde{\mathbf{G}} \varphi.$$

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 $\begin{bmatrix} \pi, \psi_1 \lor \psi_2 \end{bmatrix} = \max(\llbracket \pi, \psi_1 \rrbracket, \llbracket \pi, \psi_2 \rrbracket)$  $\begin{bmatrix} \pi, \psi_1 \land \psi_2 \end{bmatrix} = \min(\llbracket \pi, \psi_1 \rrbracket, \llbracket \pi, \psi_2 \rrbracket)$ 

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For a Kripke structure  $\ensuremath{\mathcal{K}}$  ,

$$[\![\mathcal{K},\varphi]\!] = \sup_{\pi \text{ path in } \mathcal{K}} [\![\pi,\varphi]\!]$$

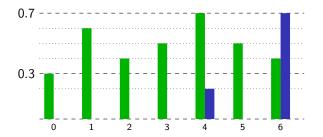
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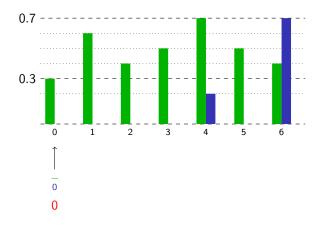
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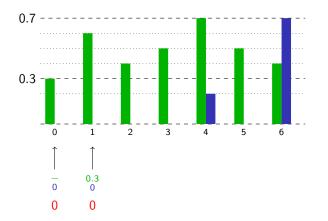
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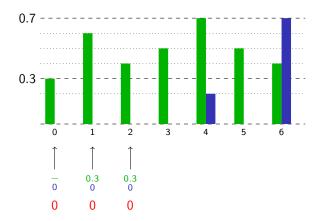
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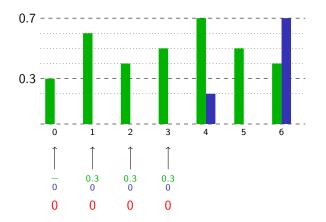
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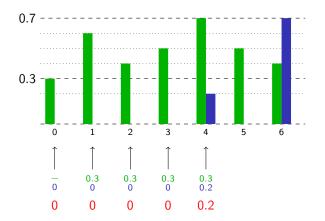
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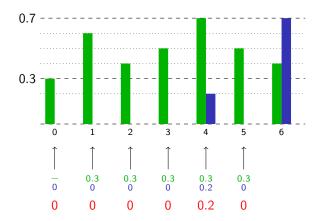
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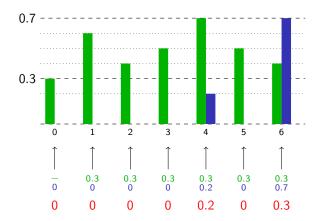
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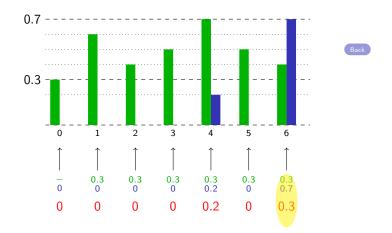
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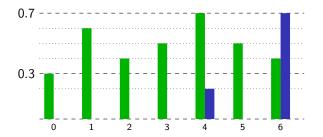
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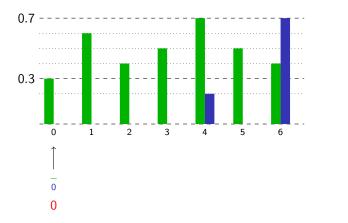
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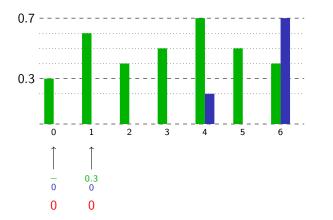
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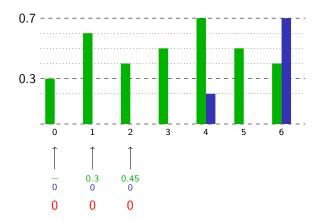
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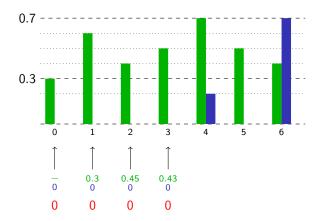
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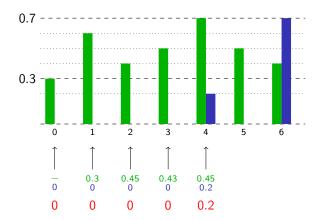
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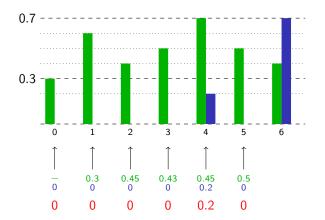
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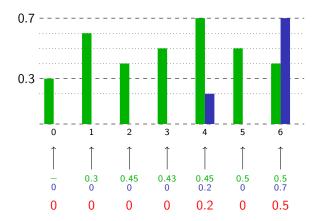
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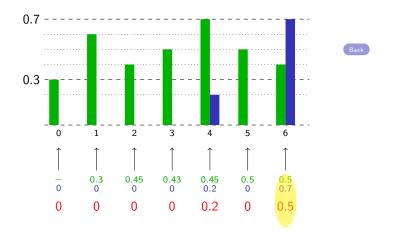
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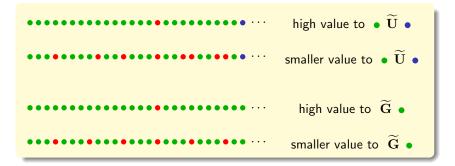
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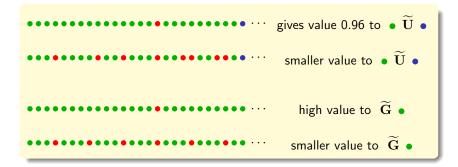


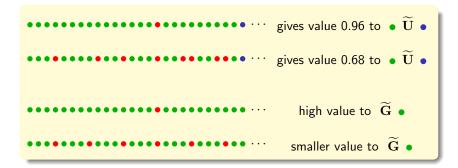
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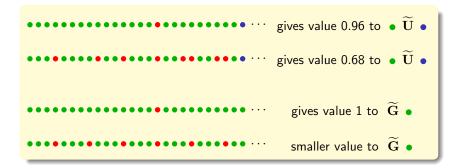


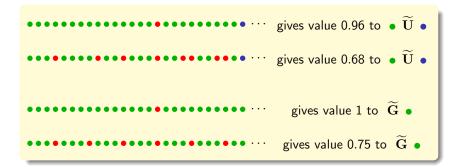
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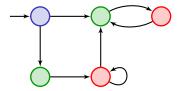






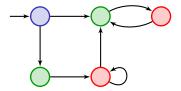






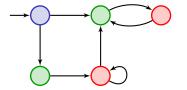
 $[\![\mathcal{K}, \bullet \, \widetilde{\mathbf{U}} \, \bullet]\!] = ?$ 

Formula • Ũ •:
[● • • • • <sup>ω</sup>, • Ũ •]] = 1



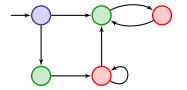
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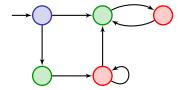
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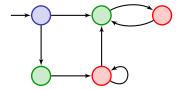
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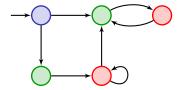


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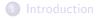
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Outline
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#### For any threshold $\bowtie c$ :

- Existence problem: given  $\mathcal{K}$ ,  $\varphi$ , is there  $\pi$  in  $\mathcal{K}$  s.t.  $[\![\pi, \varphi]\!] \bowtie c$ ?
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  - $\llbracket \mathcal{K}, \varphi \rrbracket = 1/2$  iff there exists a sequence  $(\pi^n)_{n \in \mathbb{N}}$  s.t.  $\llbracket \pi^n, \varphi \rrbracket \le 1/2$  for every n, and  $\lim_{n \to \infty} \llbracket \pi^n, \varphi \rrbracket = 1/2$

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# Undecidability of the existence problem

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I.e.

$$\llbracket q \bullet^{n_0} \bullet^{n_1} q' \bullet^{n'_0} \bullet^{n'_1} q'', \psi_\alpha \widetilde{\mathbf{U}} Q \rrbracket = \frac{1}{2}$$

where  $\psi_{\alpha} = q' \lor \bullet \lor \bullet$  when  $\alpha = 1 + n_0 + n'_1$ 

# Undecidability of the existence problem (cont'd)

## Global reduction

• Formula to be checked:

$$\texttt{halt}_\mathcal{M} = \textbf{F} \; q_{\textit{halt}} \land \textbf{G} \; \texttt{consec}_\mathcal{M}$$

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  - $\rightsquigarrow$  This yields the undecidability of the existence problem for threshold = 1/2

## What about the value problem?

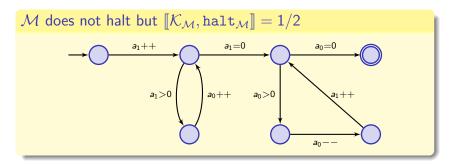
 $\bullet~\mbox{If}~\mathcal{M}~\mbox{halts, then}~[\![\mathcal{K}_{\mathcal{M}}, \mbox{halt}_{\mathcal{M}}]\!] = 1/2$ 

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We need to be careful with machines having such a converging phenomenon

# Arguments for the undecidability proof

### **Technical lemmas**

For a finite invalid run, if the first invalid consecution assigns a value smaller than 1/2 - 1/n to consec<sub>M</sub>, then the value of formula G consec<sub>M</sub> along the run is smaller than 1/2 - 1/n.

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We assume two halting states: accept and reject.

• If  $[\![\mathcal{K}_{\mathcal{M}}, \texttt{accept}_{\mathcal{M}}]\!] = 1/2$  but no run gives value 1/2 to formula  $\texttt{accept}_{\mathcal{M}}$ , then the unique valid run is infinite.

*B* det. Turing machine can either accept, reject, or not halt

 $\rightarrow \quad \mathcal{M}(B)$  two-counter machine which simulates B on B

 $\begin{array}{ll} B \mbox{ det. Turing machine can either accept, reject, or not halt} \\ \rightarrow & \mathcal{M}(B) \mbox{ two-counter machine which simulates } B \mbox{ on } B \end{array}$ 

We define the program

$$\mathcal{H}: B \mapsto \begin{cases} accept & \text{if } \llbracket \mathcal{K}_{\mathcal{M}(B)}, \texttt{accept}_{\mathcal{M}(B)} \rrbracket = 1/2 \\ reject & \text{otherwise} \end{cases}$$

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The function  $\ensuremath{\mathcal{H}}$  is not computable.

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Therefore,  $\mathcal{H}$  is not computable.

# Outline

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2 Average-LTL





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