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Zone-based verification of timed automata: Extrapolations, simulations and what next?

Patricia Bouyer

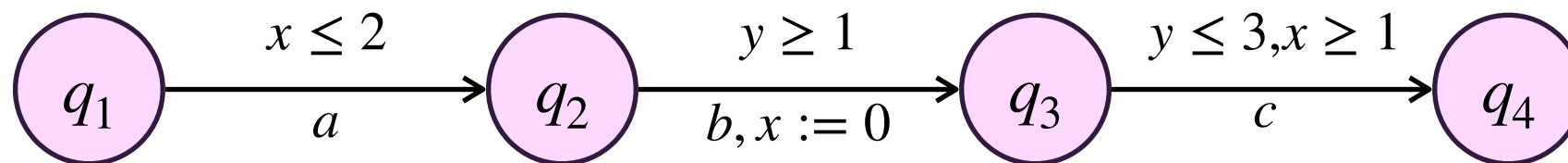
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France

Based on a survey paper written with Paul Gastin,
Frédéric Herbreteau, Ocan Sankur and B. Srivathsan

Partly supported by ANR projet Ticktac

Timed Automata

[AD90,AD94]

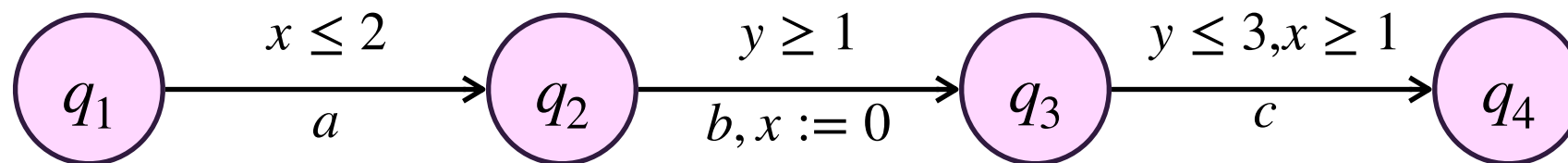


[AD90] Alur, Dill: Automata For Modeling Real-Time Systems (ICALP'90)

[AD94] Alur, Dill: A Theory of Timed Automata (TCS)

Timed Automata

[AD90,AD94]



- ▶ Infinitely many configurations!
- ▶ Decidability proven using regions
- ▶ Reachability is PSPACE-complete



Zones and DBMs

Enumerative approach: not possible
Region construction: not feasible in general
Alternative: **zone-based symbolic computation**

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Zones and DBMs

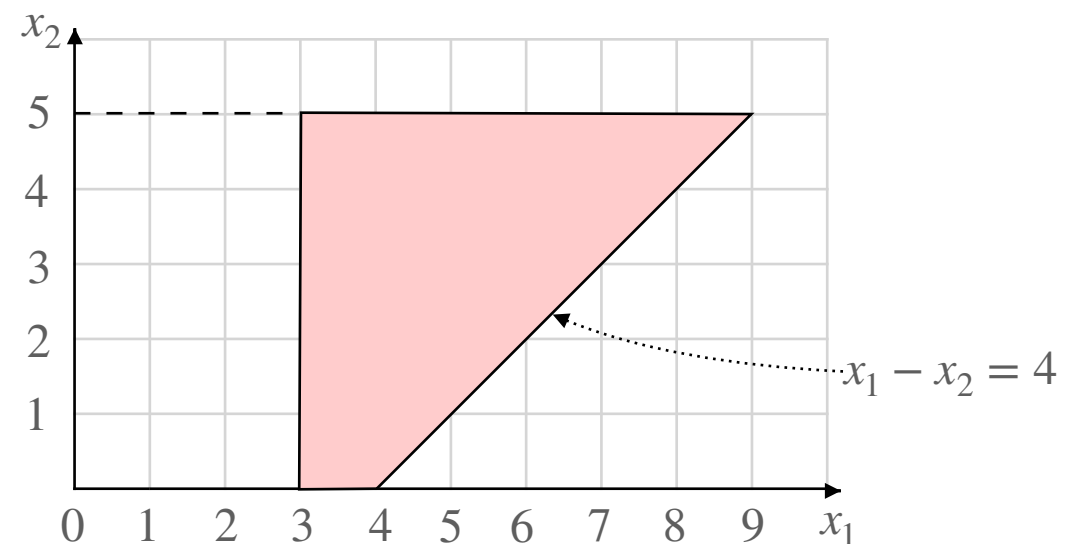
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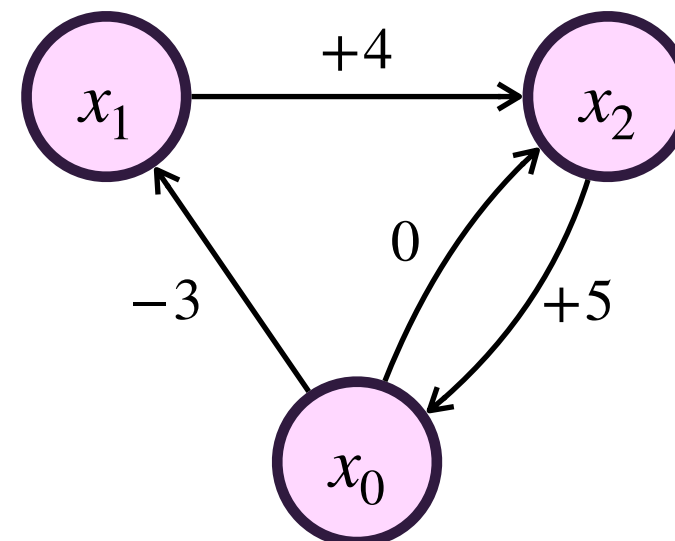
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x_1	$+\infty$	$+\infty$	4
x_2	5	$+\infty$	$+\infty$



Zones and DBMs

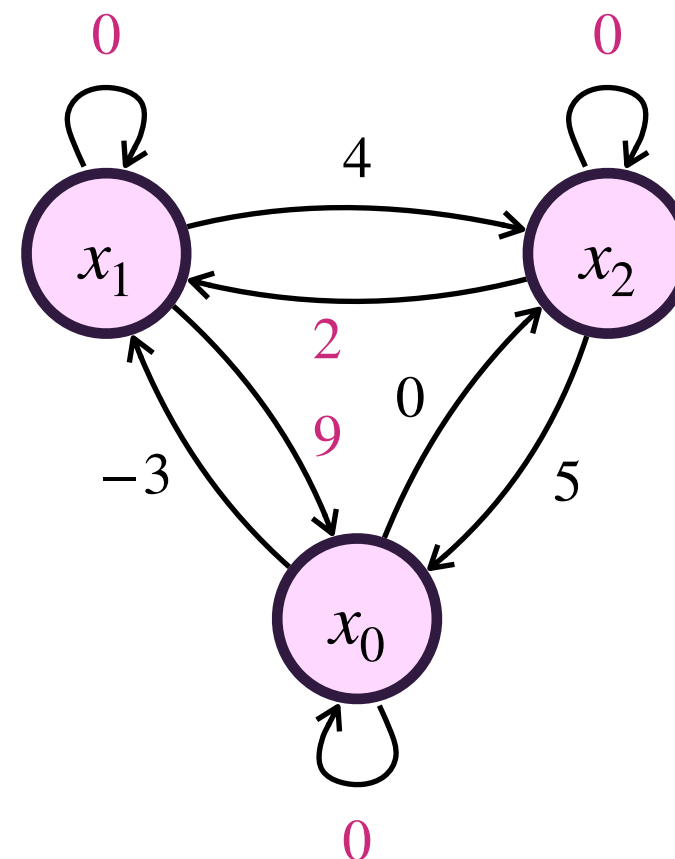
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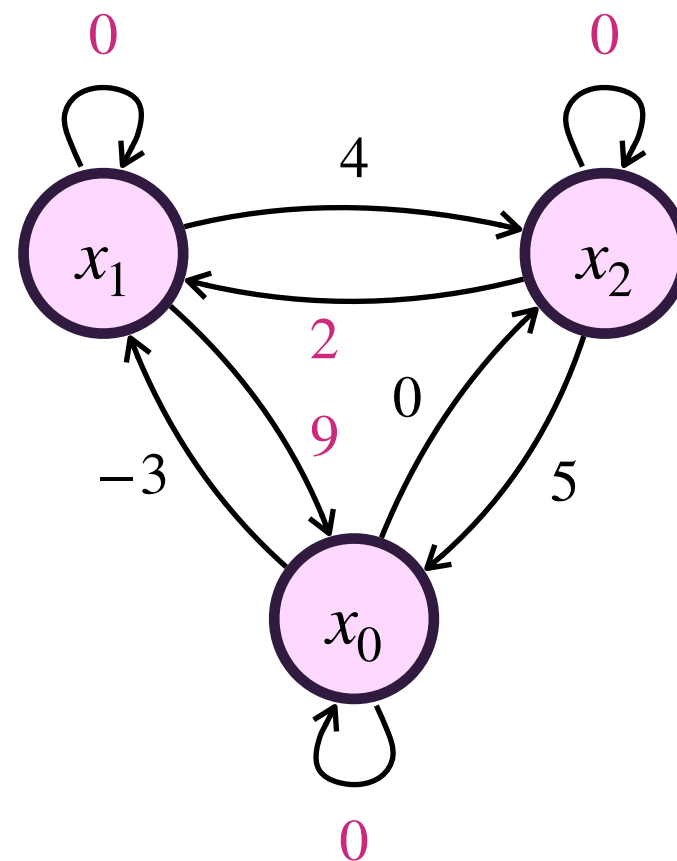
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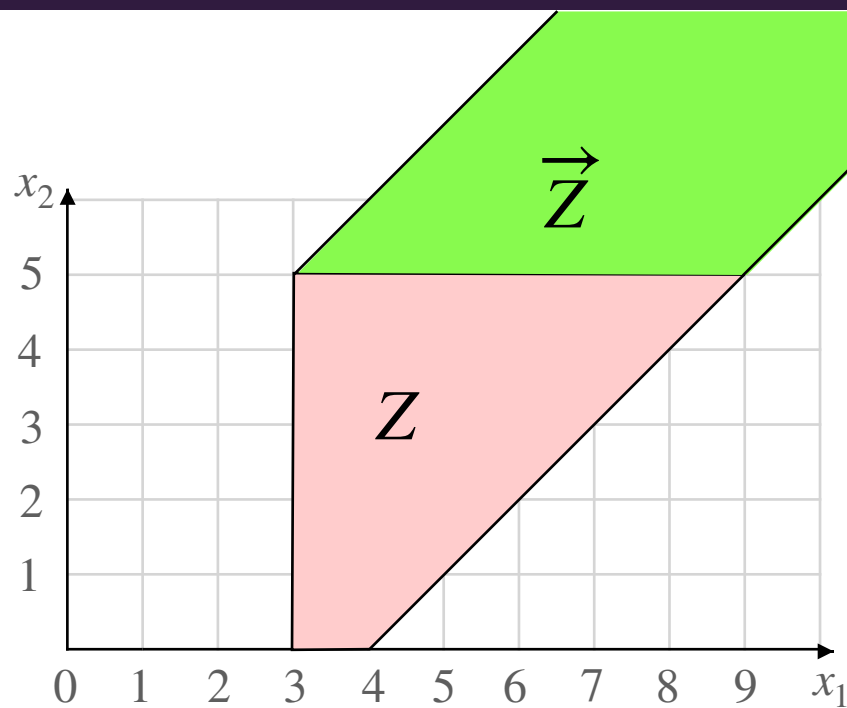
- ▶ DBM = data structure

$$\begin{matrix} & x_0 & x_1 & x_2 \\ x_0 & \left(\begin{array}{ccc} 0 & -3 & 0 \\ 9 & 0 & 4 \\ 5 & 2 & 0 \end{array} \right) \\ x_1 & & & \\ x_2 & & & \end{matrix}$$

Normal form



Operations on zones

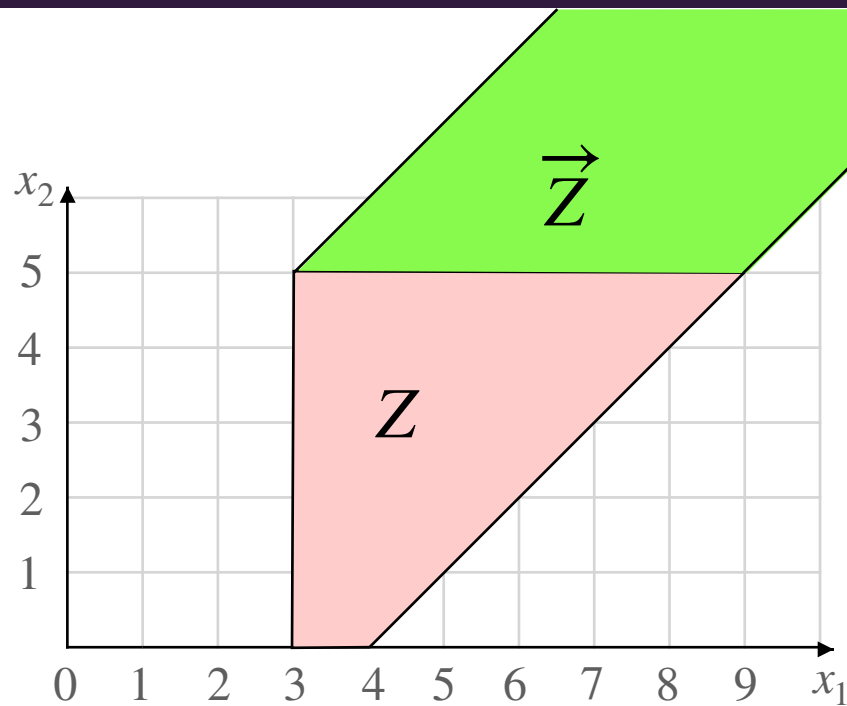


$$\begin{array}{c}
 x_0 \\
 x_1 \\
 x_2
 \end{array}
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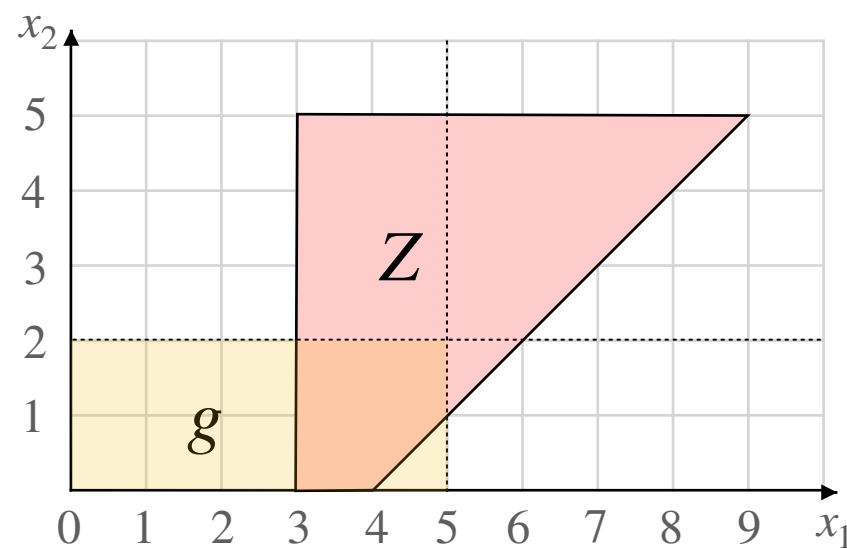
\rightsquigarrow

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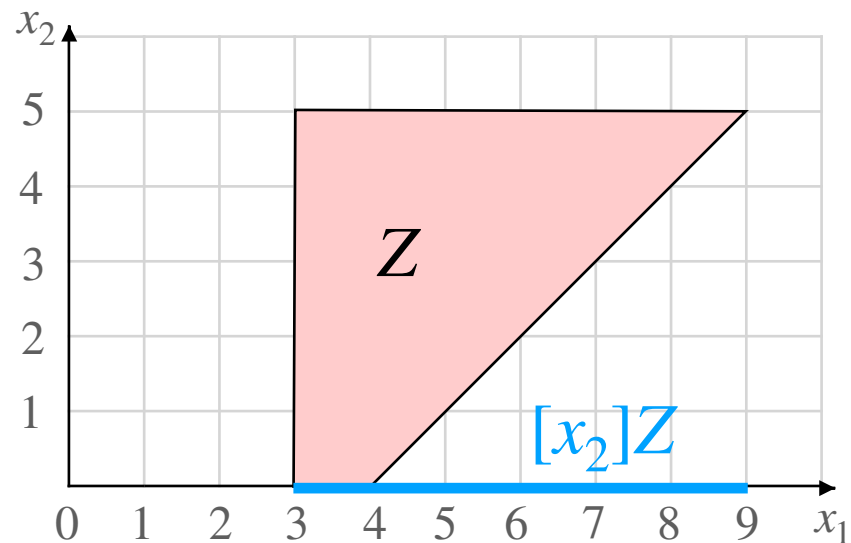


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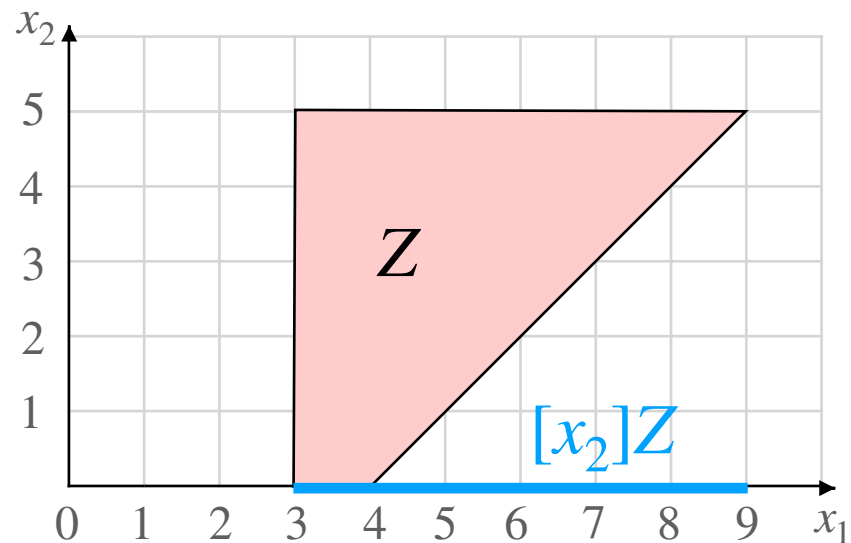
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Operations on zones



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If Z is a zone, then $Z' = \overrightarrow{[Y](Z \cap g)}$ is a zone

The computation can be made in $\mathcal{O}(|X|^2 \cdot |g|)$

Standard forward computation

- ▶ Initialize \mathcal{S} with $(q_0, \vec{0})$
- ▶ Repeat until saturation:
 - If $(q, Z) \in \mathcal{S}$, then add (q', Z') to \mathcal{S} ,
where $Z' = \overrightarrow{[Y](Z \cap g)}$ is the successor via $q \xrightarrow{g, Y} q'$
unless there is $(q', Z'') \in \mathcal{S}$ s.t. $Z' \subseteq Z''$

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Inclusion test
Can be made in $\mathcal{O}(|X|^2)$

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Three properties

- ▶ Soundness: for every $(q, Z) \in \mathcal{S}$, there is $v \in Z$ s.t. (q, v) reachable

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- ▶ Termination: saturation eventually happens

Standard forward computation

- ▶ Initialize \mathcal{S} with $(q_0, \vec{0})$
- ▶ Repeat until saturation:
 - If $(q, Z) \in \mathcal{S}$ and (q, v) is reachable, then $(q, Z \cup \{v\}) \in \mathcal{S}$ unless $v \in Z$.



The computation does not terminate in general

INCLUSION TEST
Can be made in $\mathcal{O}(|X|^2)$

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Two approaches

- ▶ Extrapolation
- ▶ Simulation



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The extrapolation approach

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- ▶ Initialize \mathcal{S} with $(q_0, \vec{0})$
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be computed in $\mathcal{O}(|X|^3)$

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Inclusion can be decided in $\mathcal{O}(|X|^2)$

Operator **extra** defined s.t.

- ▶ Termination is ensured (**extra** has finite range)
- ▶ Completeness is obvious
- ▶ *Soundness is challenging*

Extrapolation

Remove « irrelevant »
constants w.r.t. the automaton
↔ syntactic on the DBM

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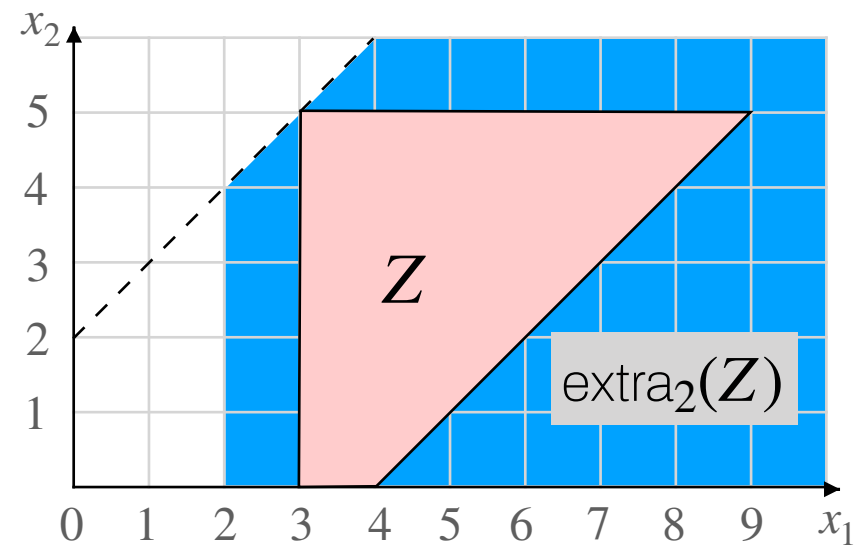
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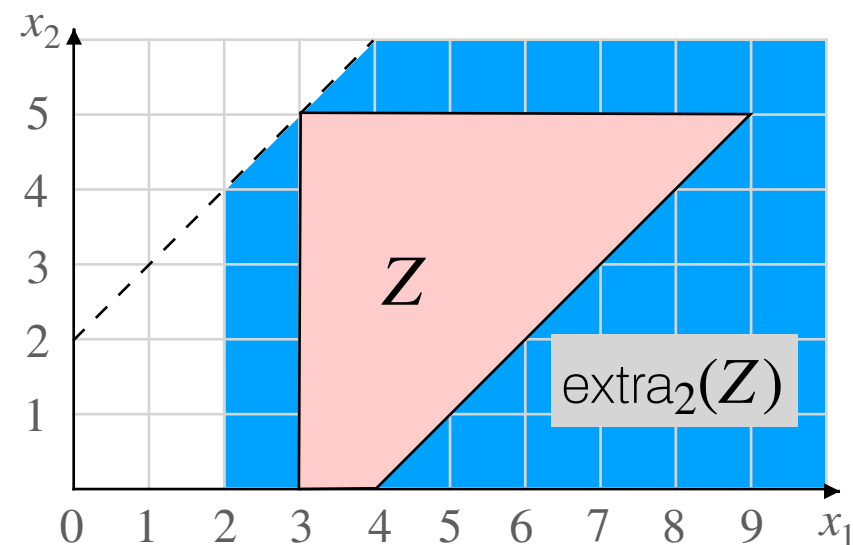
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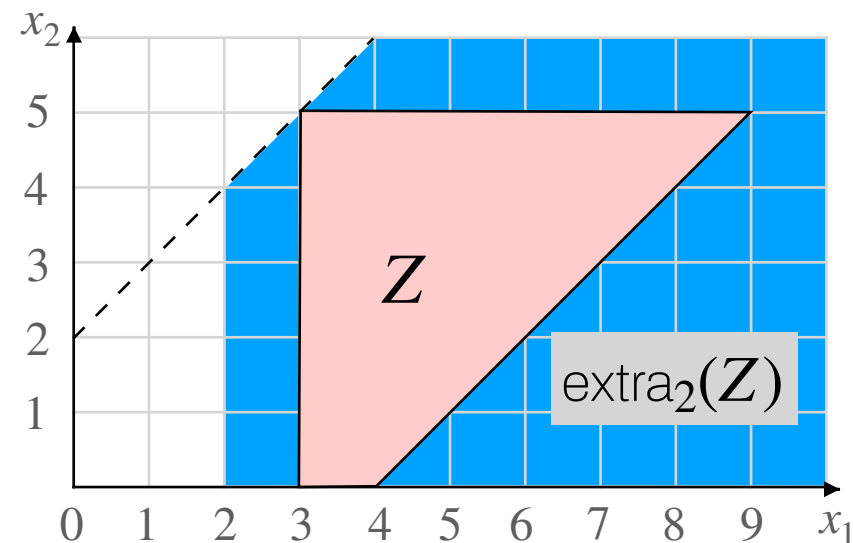
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- ▶ LU-extrapolation [BBLP04, BBLP06]

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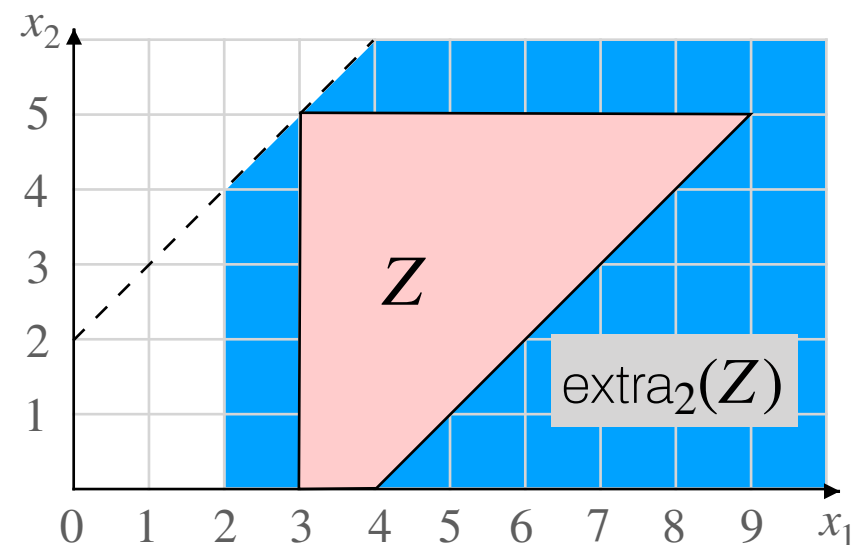
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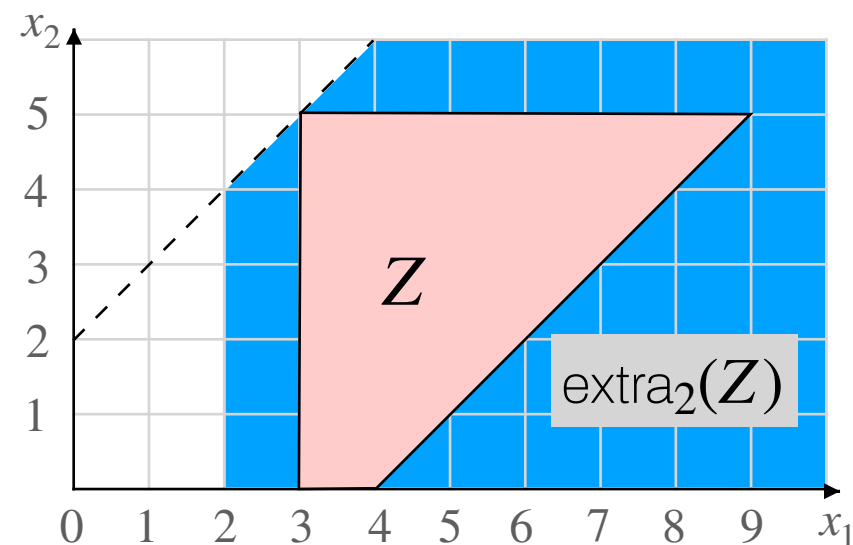
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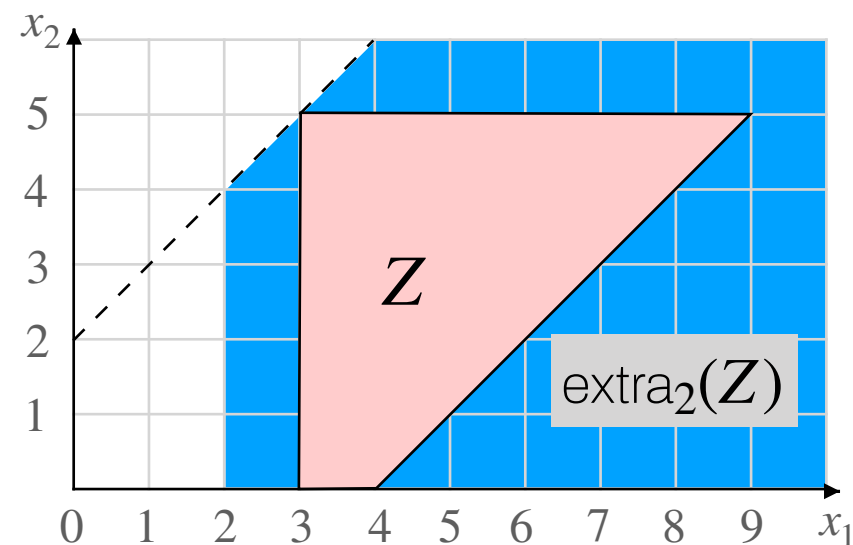
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[DT98] Daws, Tripakis: Model-checking of real-time reachability properties using abstractions (TACAS'98)

[Bou03] Bouyer: Untameable timed automata! (STACS'03)

[Bou04] Bouyer: Forward analysis of updatable timed automata (FMSSD)

[BBFL03] Behrmann, Bouyer, Fleury, Larsen: Static guard analysis in timed automata verification (TACAS'03)

[BBLP04] Behrmann, Bouyer, Larsen, Pelánek: Lower and upper bounds in zone based abstractions of timed automata (TACAS'04)

[BBLP06] Behrmann, Bouyer, Larsen, Pelánek: Zone-based abstractions for timed automata exploiting lower and upper bounds (STTT)

Limits of the extrapolation approach

[Bou03] Bouyer: Untameable timed automata! (STACS'03)

[BBLP06] Behrmann, Bouyer, Larsen, Pelánek: Zone-based abstractions for timed automata exploiting lower and upper bounds (STTT)

[HKSW11] Herbreteau, Kini, Srivathsan, Walukiewicz: Using non-convex approximations for efficient analysis of timed automata (FSTTCS'11)

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Limits of the extrapolation approach

- ➔ The extrapolation is required to transform a zone into a zone
- ➔ It does not benefit from the coarsest abstractions of zones [HKSW11]
 - The region closure would in principle be sound, but it is not convex
 - The LU-abstraction $\mathbf{a}_{LU}(Z) = \{v' \mid \exists v \in Z \text{ s.t. } v' \preceq_{LU} v\}$ would in principle be sound [BBLP06], but it is not convex

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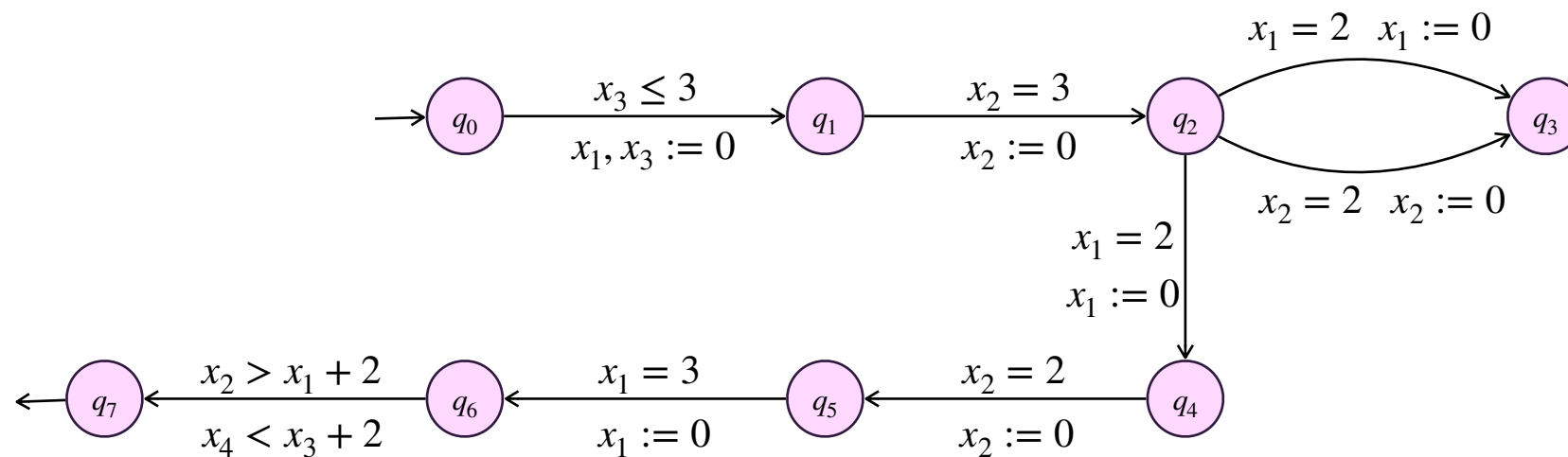
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- ➔ The approach does not apply to timed automata with diagonal constraints [Bou03]

[Bou03] Bouyer: Untameable timed automata! (STACS'03)

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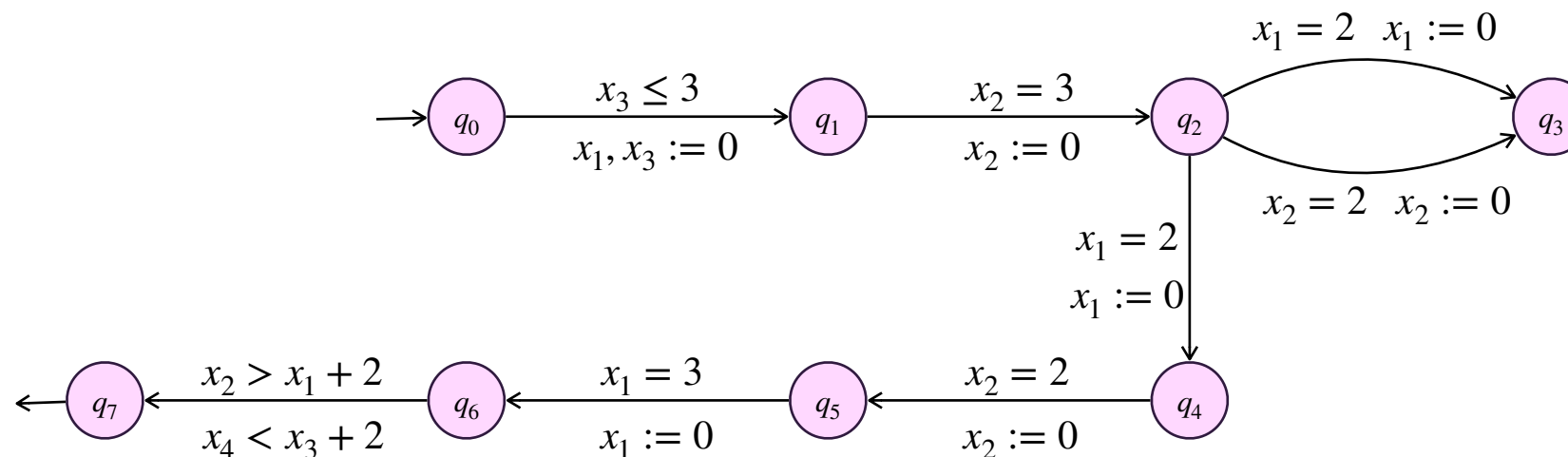
The buggy automaton



[Bou03] Bouyer. Untameable timed automata! (STACS'03).

[Bou04] Bouyer. Forward analysis of updatable timed automata (Formal Methods in System Design).

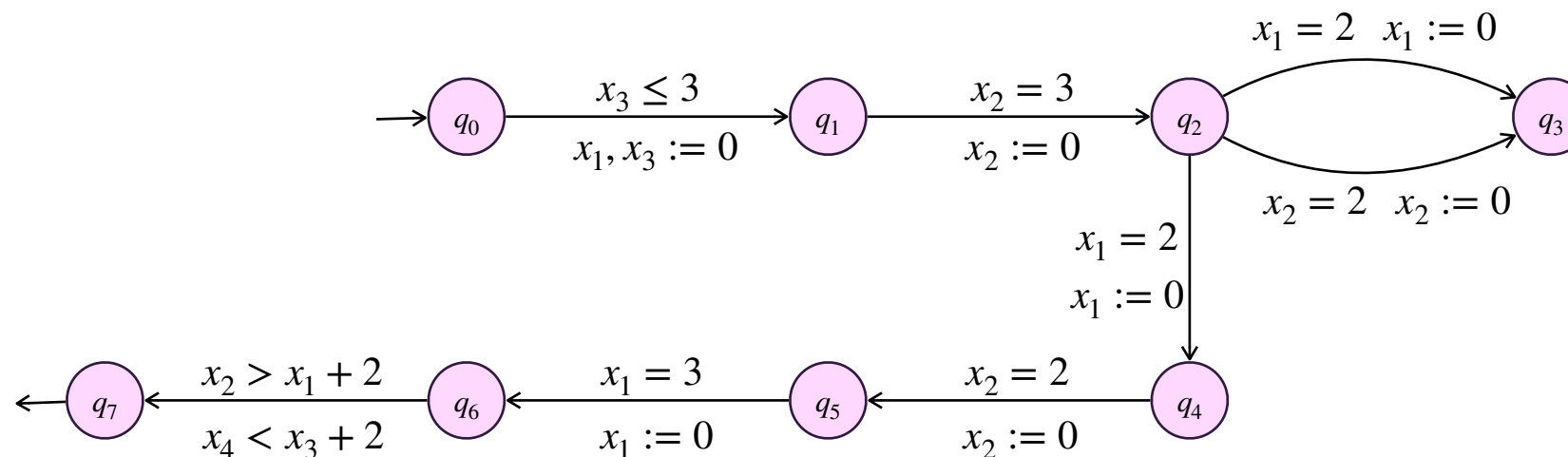
The buggy automaton



After α loops, the zone which is reached at q_6 is

$$Z_\alpha := (1 \leq x_2 - x_1 \leq 3) \wedge (1 \leq x_4 - x_3 \leq 3) \wedge (x_4 - x_2 = x_3 - x_1 = 2\alpha + 5)$$

The buggy automaton



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- There is no extrapolation, which preserves zones, which is sound and finite for this timed automaton with diagonal constraints.



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The simulation approach

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δ ↓

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Inclusion « up-to » simulation

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- ▶ Note: $(q, Z_1) \preceq (q, Z_2)$ iff $Z_1 \subseteq \text{Closure}_{\preceq}(Z_2)$
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[HKSW11] Herbreteau, Kini, Srivathsan, Walukiewicz: Using non-convex approximations for efficient analysis of timed automata (FSTTCS'11)

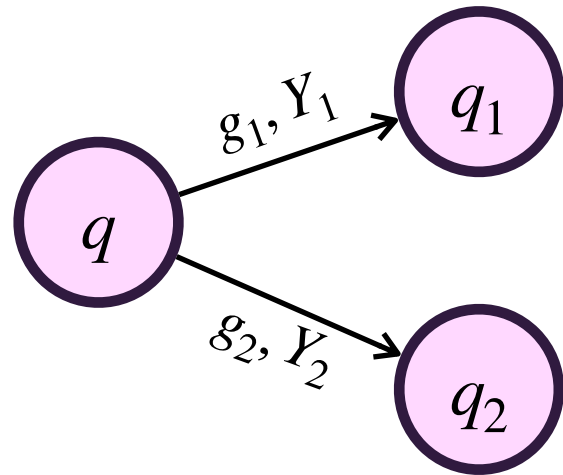
[HSW12] Herbreteau, Srivathsan, Walukiewicz: Better Abstractions for Timed Automata (LICS'12)

[GMS18] Gastin, Mukherjee, Srivathsan: Reachability in Timed Automata with Diagonal Constraints (CONCUR'18)

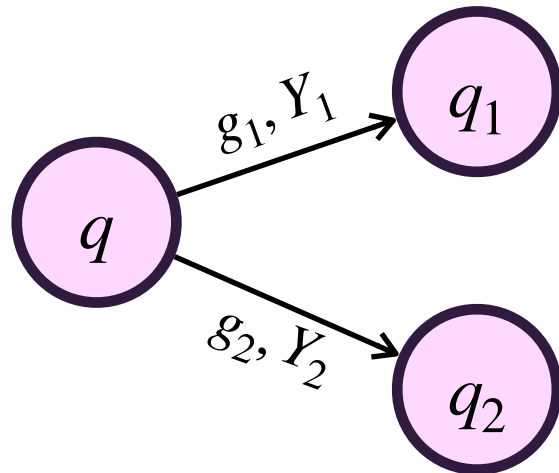
[GMS19] Gastin, Mukherjee, Srivathsan: Fast Algorithms for Handling Diagonal Constraints in Timed Automata (CAV'19)

[GMS20] Gastin, Mukherjee, Srivathsan: Reachability for Updatable Timed Automata Made Faster and More Effective (FSTTCS'20)

Constraints relevant at q : $\mathcal{G}(q)$

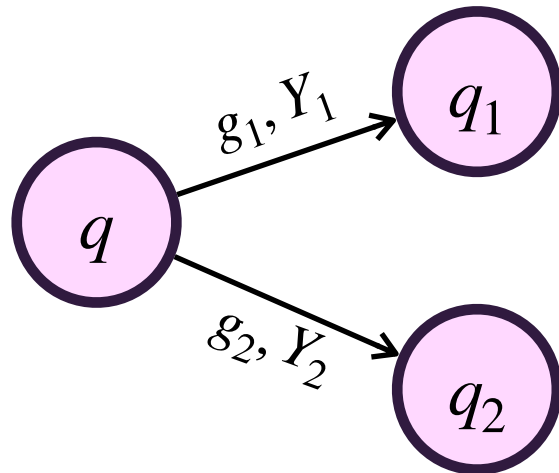


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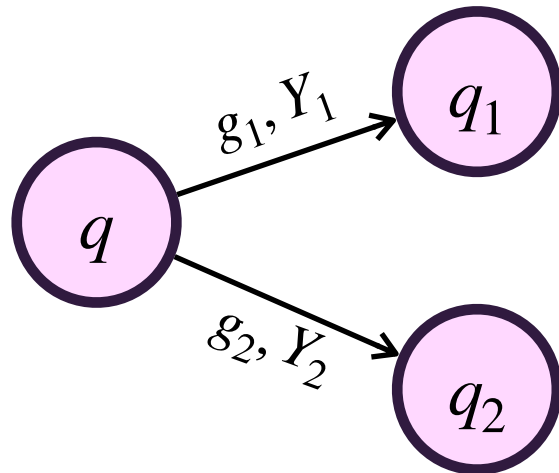


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- Fixpoint computation terminates for timed automata; it also terminates for known decidable classes of updatable timed automata

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Let \mathcal{G} be the previous mapping

- ▶ We say that $(q, v) \leq_{\mathcal{G}} (q, v')$ whenever for every $\varphi \in \mathcal{G}$, for every $\delta \geq 0$, $v + \delta \models \varphi$ implies $v' + \delta \models \varphi$

The \mathcal{G} -simulation

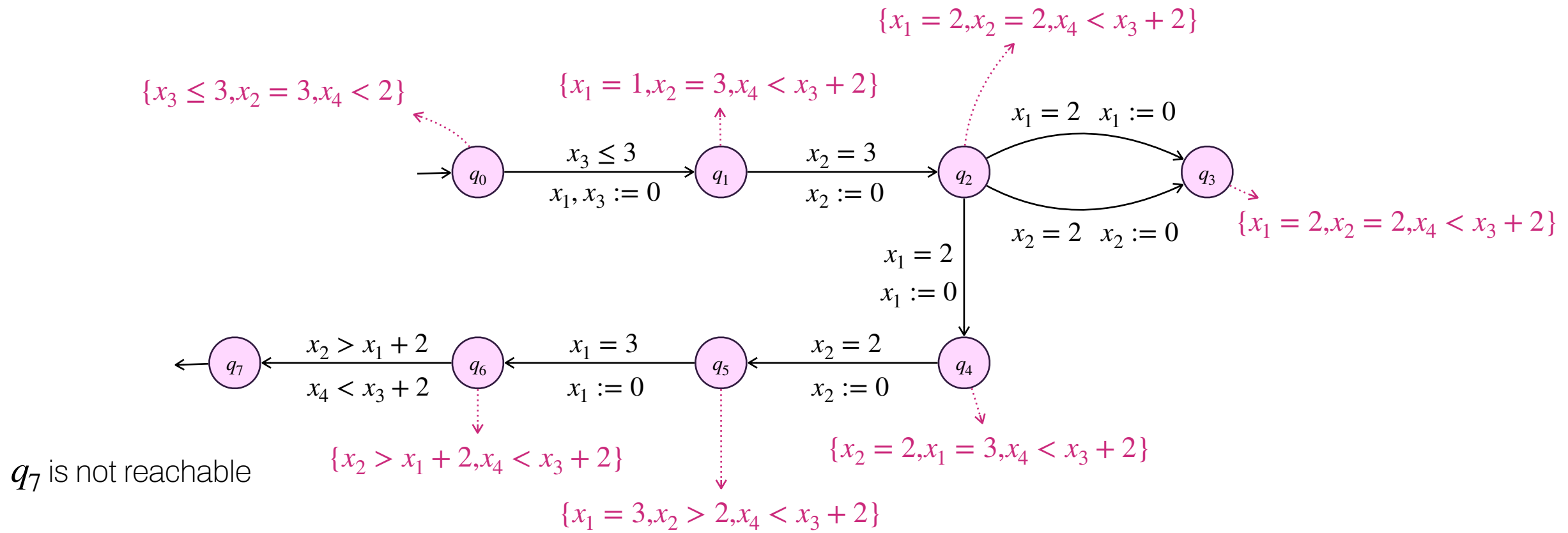
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Theorem

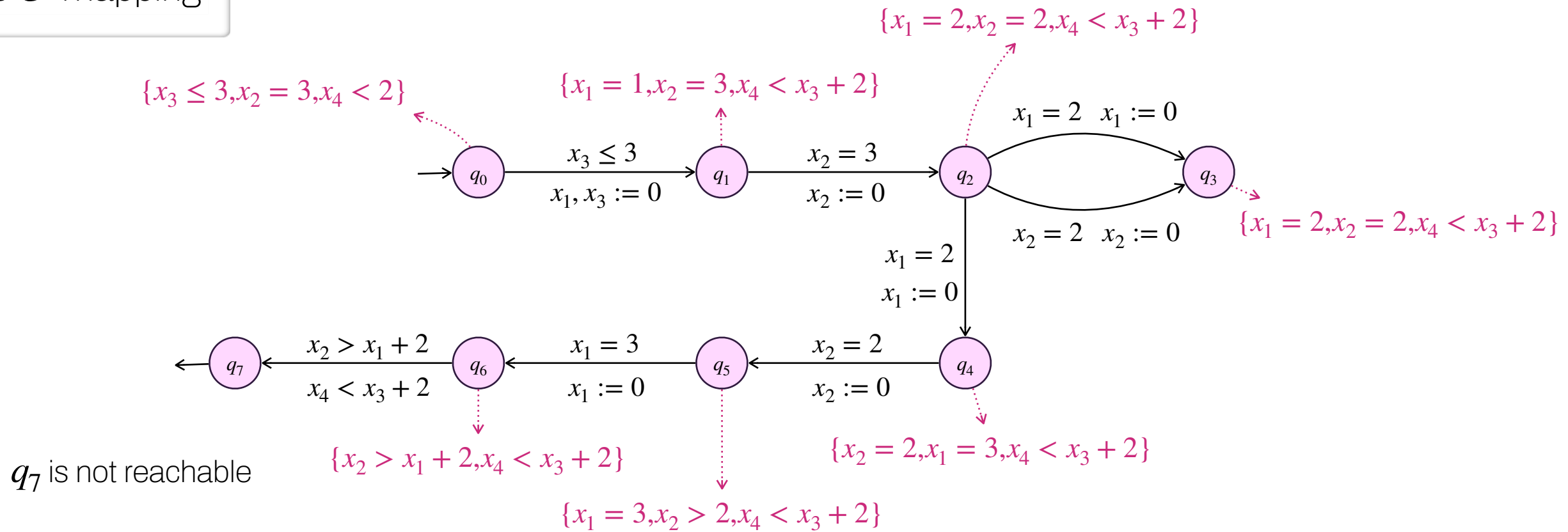
- ▶ $\preceq_{\mathcal{G}}$ is a simulation relation
- ▶ It satisfies the finite-chain property on zones

An example



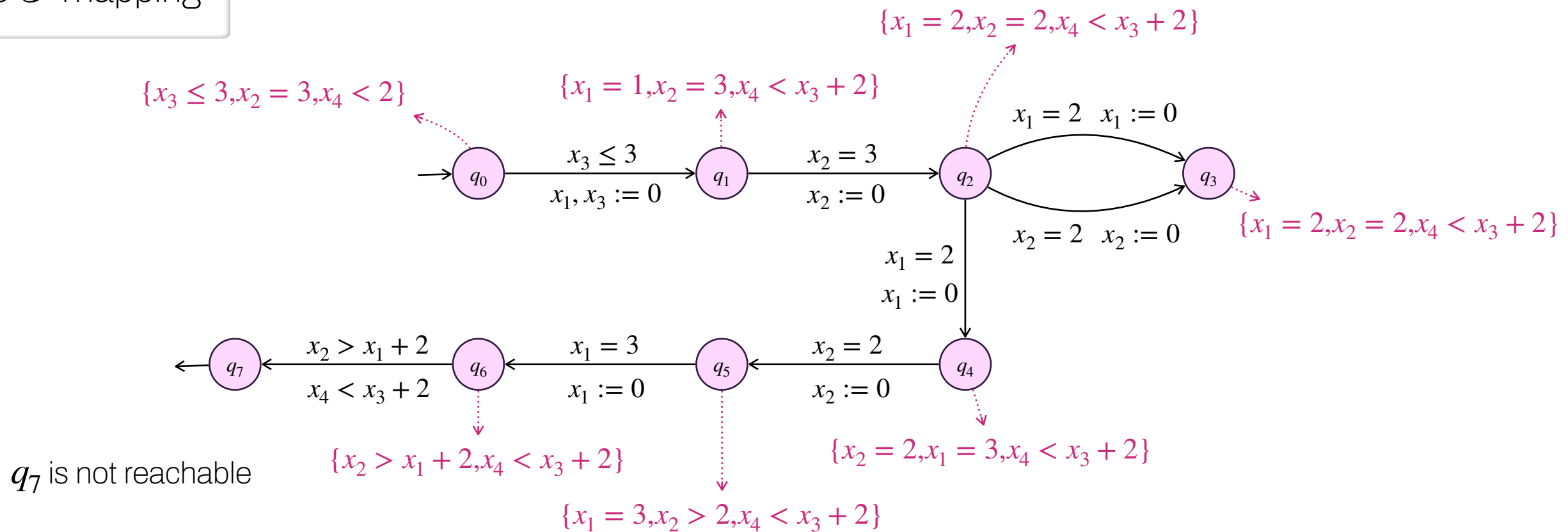
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The \mathcal{G} mapping



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The \mathcal{G} mapping



- ▶ On this automaton, any extrapolation-based method fails [Bou04]
- ▶ The $\preceq_{\mathcal{G}}$ -simulation approach terminates at the second iteration

Going further

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[BCM16] Bouyer, Colange, Markey: Symbolic Optimal Reachability in Weighted Timed Automata (CAV'16)

[HSTW20] Herbreteau, Srivathsan, Tran, Walukiewicz: Why Liveness for Timed Automata Is Hard, and What We Can Do About It (ACM Trans. Comput. Log)

[AGP21] Akshay, Gastin, Prakash: Fast Zone-Based Algorithms for Reachability in Pushdown Timed Automata (CAV'21)

[AGGS22] Akshay, Gastin, Govind, Srivathsan: Simulations for Event-Clock Automata (CONCUR'22)



Tools

- Uppaal <https://uppaal.org>
- Tchecker <https://github.com/ticktac-project/tchecker>
- Red <https://sites.google.com/site/redlibtw/>
- Pat <https://pat.comp.nus.edu.sg>
- Rabbit <https://www.sosy-lab.org/people/beyer/Rabbit/>
- MCTA <http://gki.informatik.uni-freiburg.de/tools/mcta/>
- ...

Tool UPPAAL

<https://uppaal.org>

- ▶ Developed since 1995
- ▶ Successfully used in the industry, with many case studies
- ▶ Many extensions:
 - games, weighted timed automata, testing, statistical model-checking, ...
- ▶ Implements extrapolation-based algorithms

Tool TChecker

<https://github.com/ticktac-project/tchecker>

- ▶ Developed since a couple of years, under development
- ▶ Fully open-source verification tool for timed automata
- ▶ Implements extrapolation and simulation-based algorithms
- ▶ Made also as a framework to develop new verification algorithms or data structures



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Conclusion

What next?

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- ▶ Much **algorithmic effort** has been made to reduce the impact of the timing aspects (reduce the number of zones to visit)
 - Need to push the ideas to larger classes of models
 - In each case, one of the the difficulties lies in the proof of efficiency of inclusion « up-to »

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- ▶ Much **algorithmic effort** has been made to reduce the impact of the timing aspects (reduce the number of zones to visit)
 - Need to push the ideas to larger classes of models
 - In each case, one of the the difficulties lies in the proof of efficiency of inclusion « up-to »
- ▶ A major bottleneck: the **state explosion** due to control states
 - Use of BDD/SAT technics, bounded model-checking, ...
→ No technics overwrites the other, they are useful and complementary
 - Local-time semantics + POR (talk of Sri at SNR) [GHSW22]

What next?

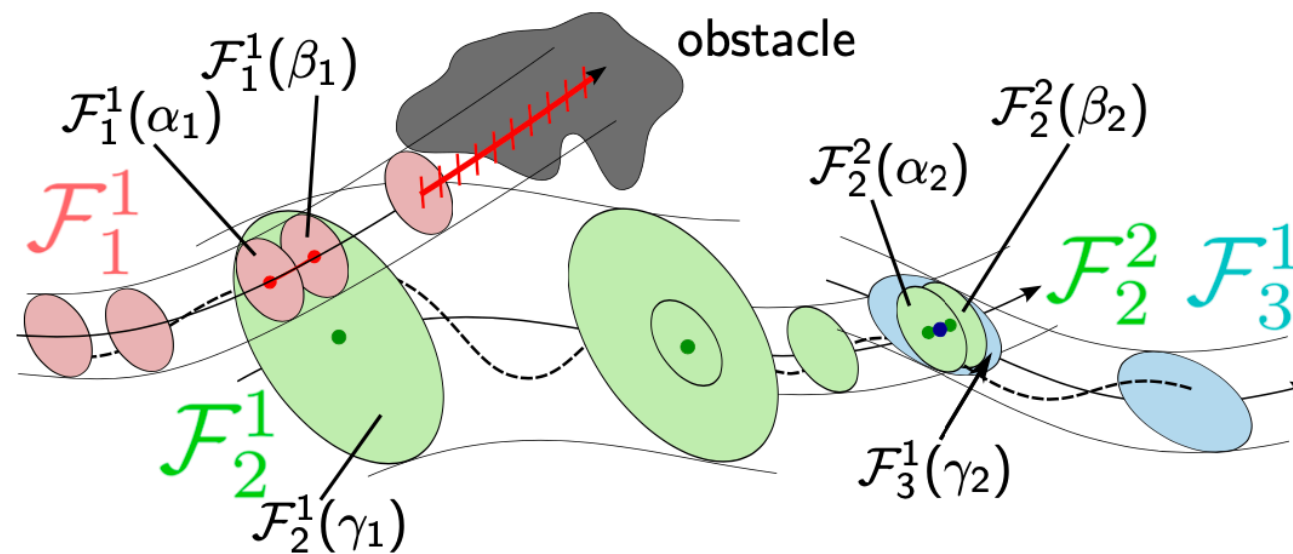
- ▶ **Domain-specific** algorithms:
 - Funnel automata for robotic systems [BMPS15,BMPS17]

[BMPS15] Bouyer, Markey, Perrin, Schlehuber-Caissier: Timed-Automata Abstraction of Switched Dynamical Systems Using Control Funnels (FORMATS'15)

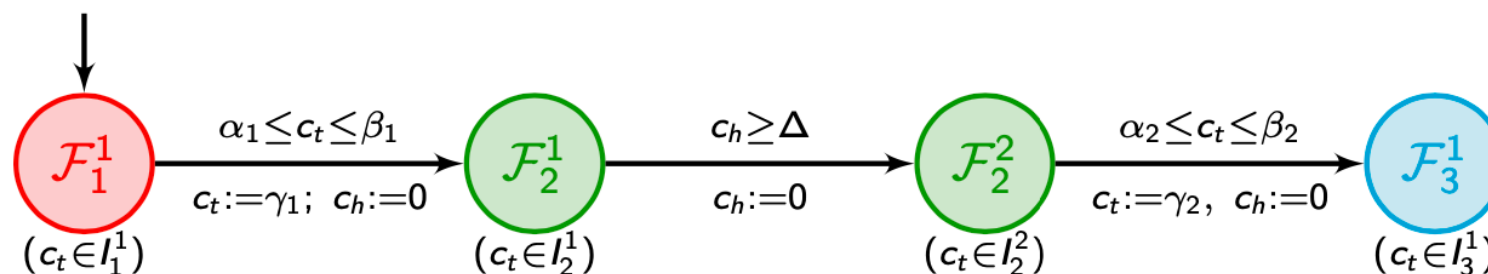
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c_t : positional clock; c_h : local clock



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Thank you for your attention!

