

From timed to complex systems

— Stochastic timed games —

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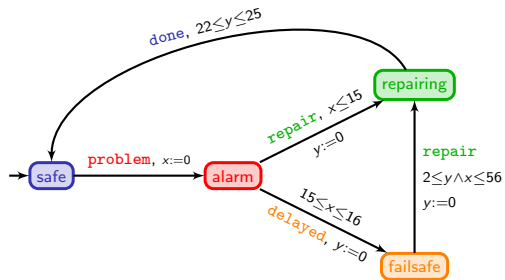
Based on joint works with Christel Baier, Nathalie Bertrand, Thomas Brihaye,
Vojtěch Forejt, Marcus Größer and Nicolas Markey.

I am grateful to Vojtěch Forejt for some of the slides in this presentation.

Outline

1. Timed automata
2. Timed games
3. A hint into stochastic timed games
 - Some informal description
 - A more formal view of the semantics
 - Summary of the results
 - Qualitative analysis of $\frac{1}{2}$ -player games
 - Quantitative analysis of $2\frac{1}{2}$ -player games
 - Quantitative analysis of $\frac{1}{2}$ -player games
4. Conclusion

An example of a timed automaton



	safe	$\xrightarrow{23}$	safe	$\xrightarrow{\text{problem}}$	alarm	$\xrightarrow{15.6}$	alarm	$\xrightarrow{\text{delayed}}$	failsafe	
x	0		23		0		15.6		15.6	...
y	0		23		23		38.6		0	
	failsafe	$\xrightarrow{2.3}$	failsafe	$\xrightarrow{\text{repair}}$	repairing	$\xrightarrow{22.1}$	repairing	$\xrightarrow{\text{done}}$	safe	
...	15.6		17.9		17.9		40		40	
	0		2.3		0		22.1		22.1	

Verification

Emptiness problem

Is the language accepted by a timed automaton empty?

- basic reachability/safety properties (final states)
- basic liveness properties (ω -regular conditions)

Verification

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- **Problem:** the set of configurations is infinite
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Theorem [AD90,AD94]

The emptiness problem for timed automata is decidable and PSPACE-complete.

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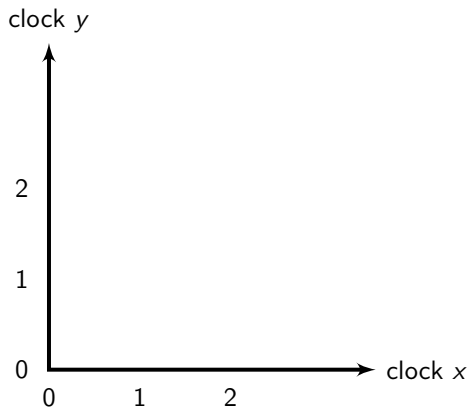
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Method: construct a finite abstraction

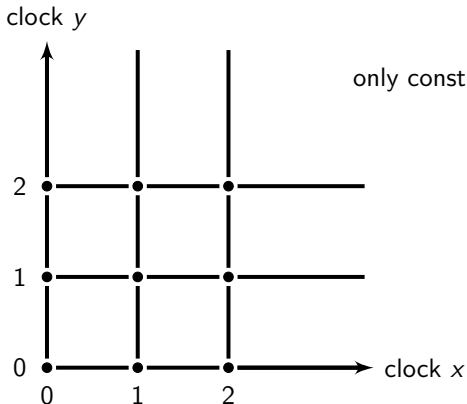
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The region abstraction



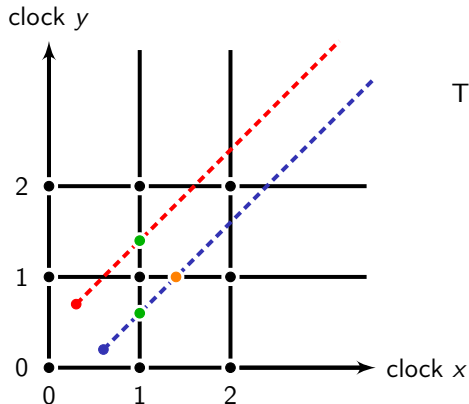
The region abstraction



only constraints: $x \sim c$ with $c \in \{0, 1, 2\}$
 $y \sim c$ with $c \in \{0, 1, 2\}$

- “compatibility” between regions and constraints

The region abstraction

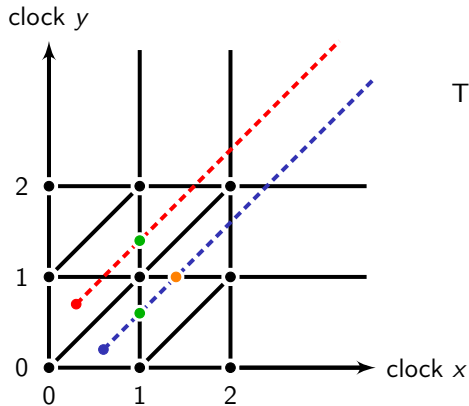


The path $\circ \xrightarrow{x=1} \circ \xrightarrow{y=1} \circ$

- can be fired from ●
- cannot be fired from ●

- “compatibility” between regions and constraints
- “compatibility” between regions and time elapsing

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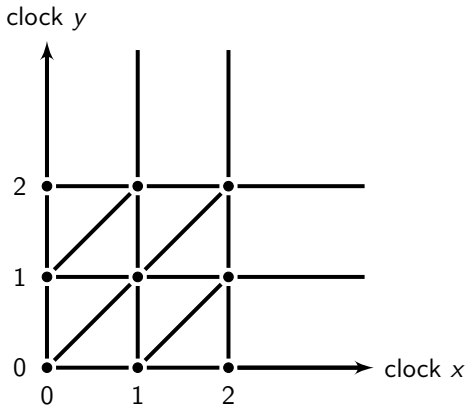


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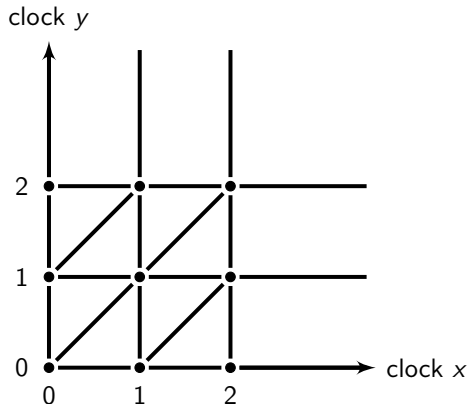
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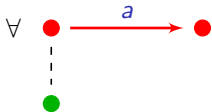
\leadsto an equivalence of finite index
 a time-abstract bisimulation

Time-abstract bisimulation

This is a relation between \bullet and \bullet such that:

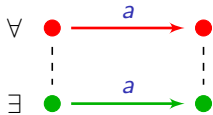
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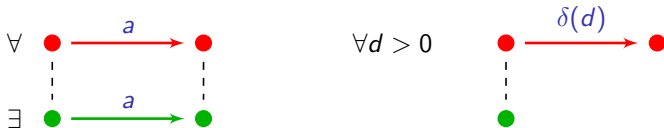
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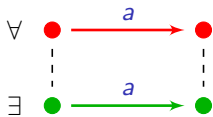
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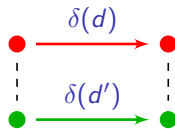
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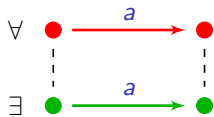
$$\forall d > 0$$

$$\exists d' > 0$$



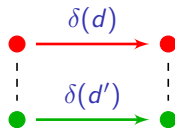
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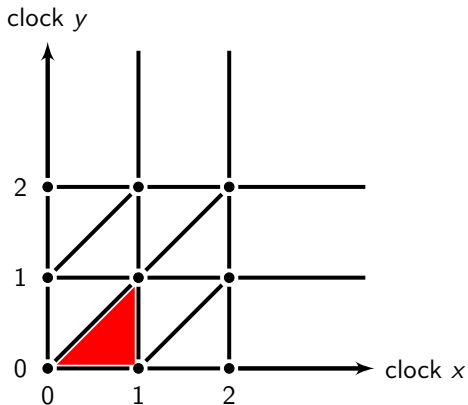
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... and vice-versa (swap \bullet and \bullet).

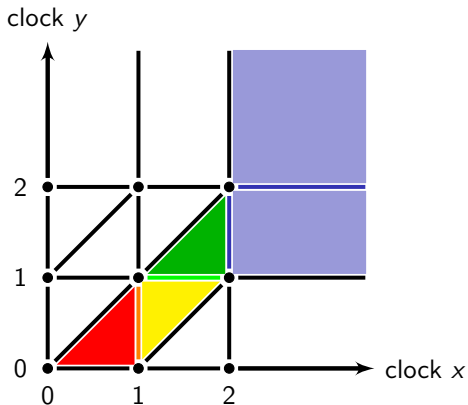
The region abstraction (2)



- region R defined by:

$$\begin{cases} 0 < x < 1 \\ 0 < y < 1 \\ y < x \end{cases}$$

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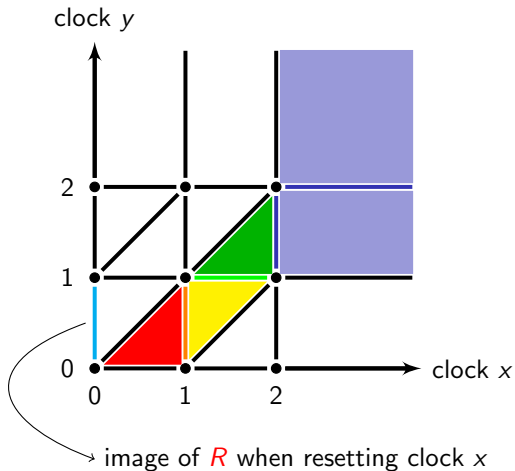


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- time successors of R

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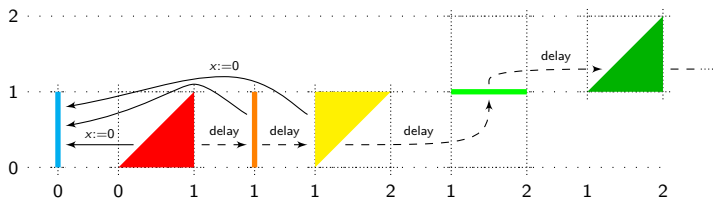
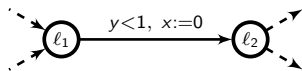
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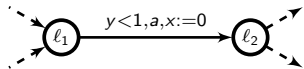
- time successors of R

The construction of the region graph

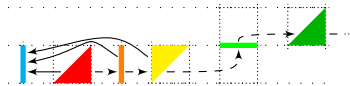
It “mimics” the behaviours of the clocks.



Region automaton \equiv finite bisimulation quotient

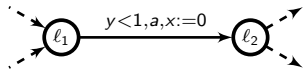


timed automaton

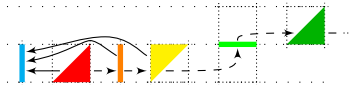


region graph

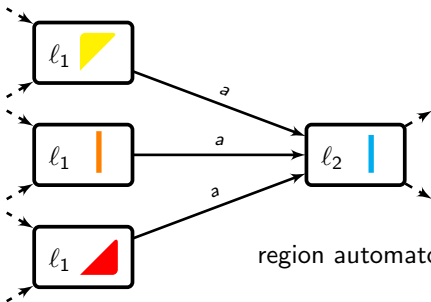
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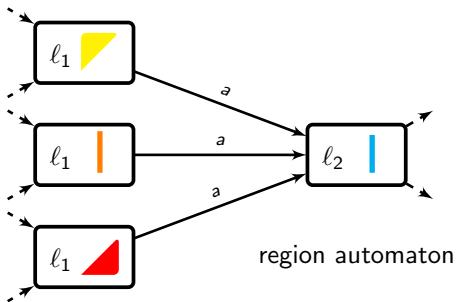


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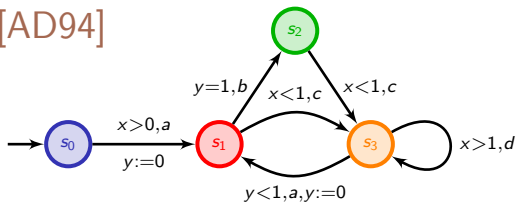
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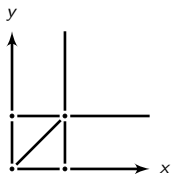
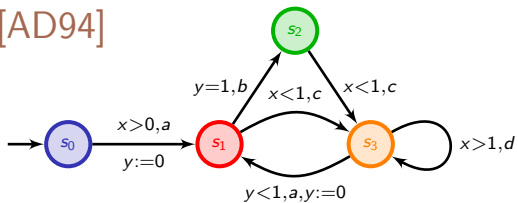


$$\mathcal{L}(\text{reg. aut.}) = \text{UNTIME}(\mathcal{L}(\text{timed aut.}))$$

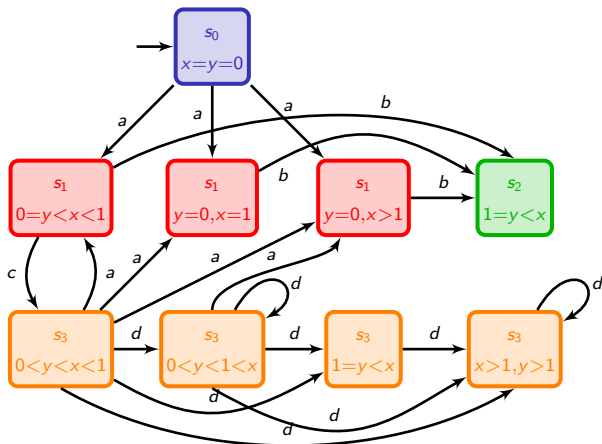
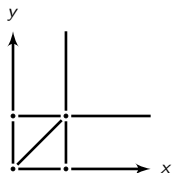
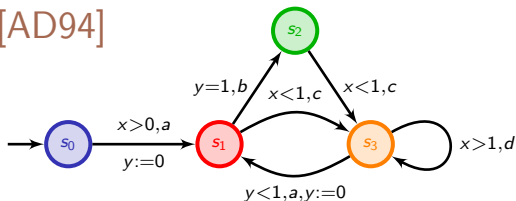
An example [AD94]

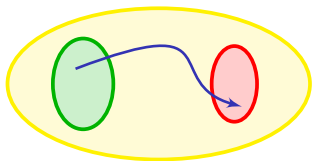


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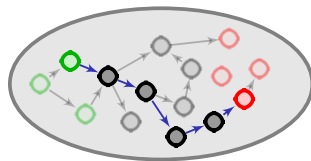
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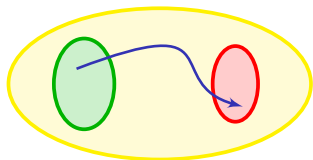




timed automaton

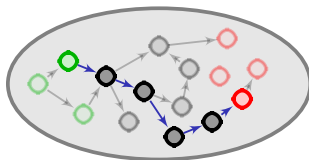
finite bisimulation
quotient

large (but finite) automaton
(region automaton)



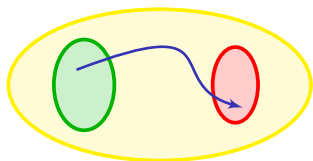
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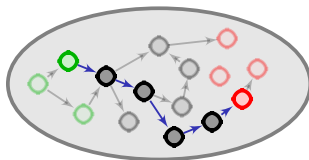
- **large**: exponential in the number of clocks and in the constants (if encoded in binary). The number of regions is:

$$\prod_{x \in X} (2M_x + 2) \cdot |X|! \cdot 2^{|X|}$$



timed automaton

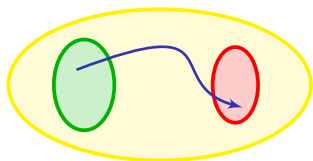
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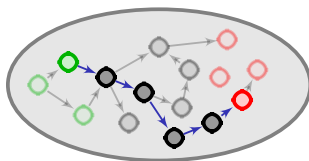
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- It can be used to check for:



timed automaton

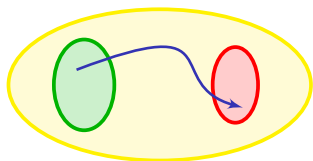
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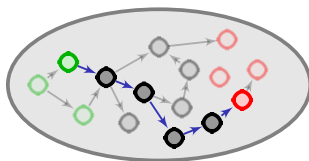
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- It can be used to check for:
 - reachability/safety properties
 - liveness properties (like Büchi properties)

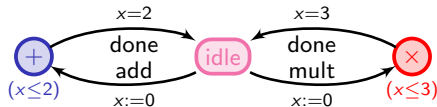
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Why (timed) games?

- to model uncertainty

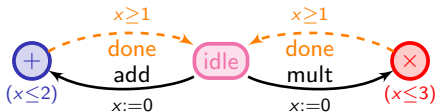
Example of a processor in the taskgraph example



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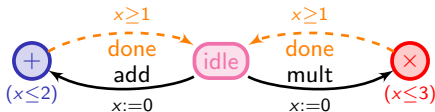
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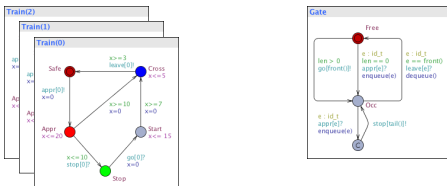
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Example of a processor in the taskgraph example



- to model an interaction with an environment

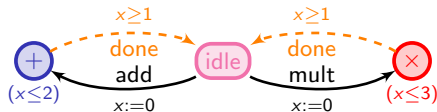
Example of the gate in the train/gate example



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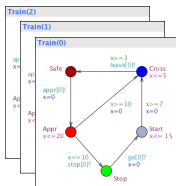
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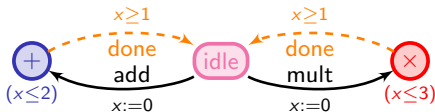


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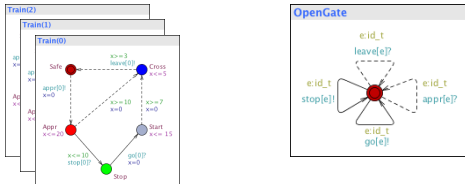
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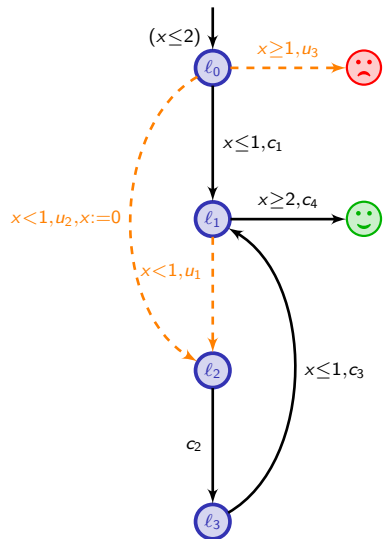


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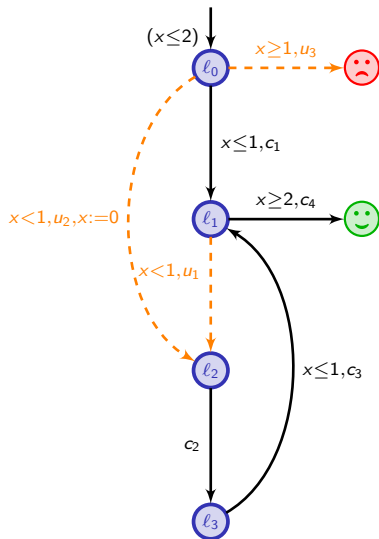
An example of a timed game



Rule of the game

- Aim: avoid 😞 and reach 😊

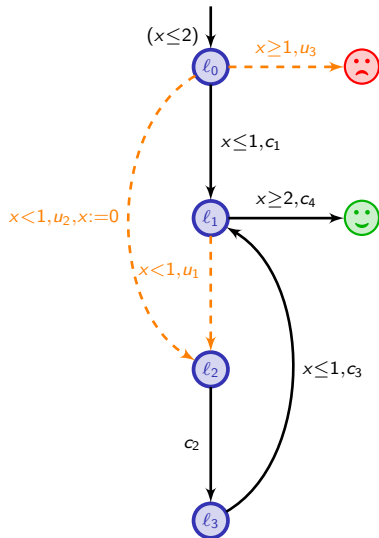
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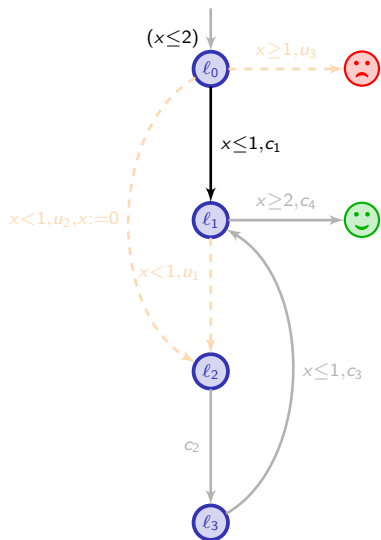


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$$f : \text{history} \mapsto (\text{delay, cont. transition})$$

An example of a timed game



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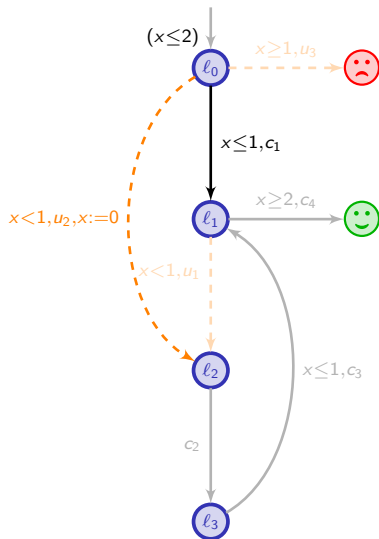
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- from $(l_0, 0)$, play $(0.5, c_1)$

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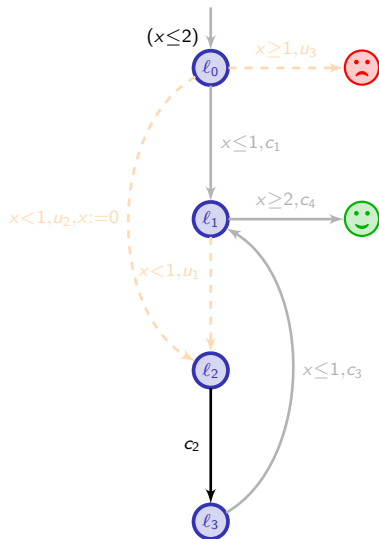
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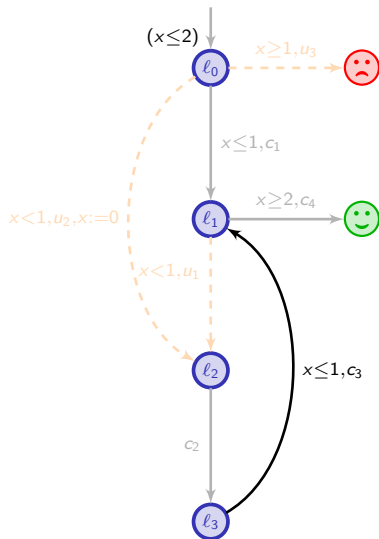
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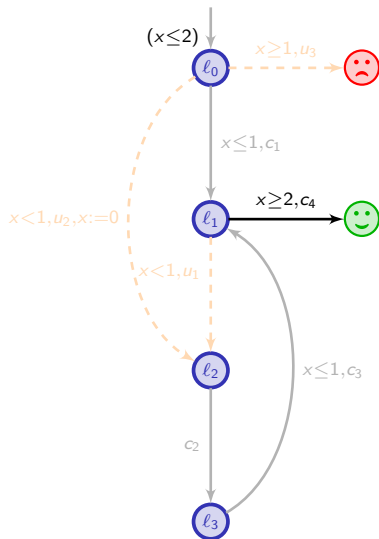
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- from $(l_3, 1)$, play $(0, c_3)$

An example of a timed game



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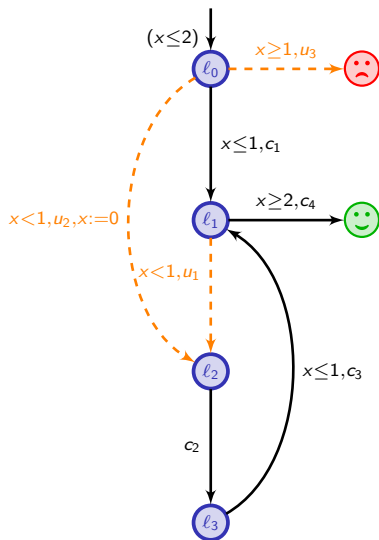
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- from $(l_3, 1)$, play $(0, c_3)$
- from $(l_1, 1)$, play $(1, c_4)$

An example of a timed game



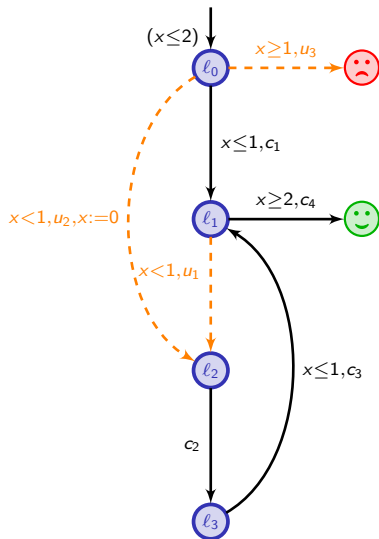
Rule of the game

- Aim: avoid 😞 and reach 😊
- How do we play? According to a strategy:

$$f : \text{history} \mapsto (\text{delay, cont. transition})$$

Problems to be considered

An example of a timed game



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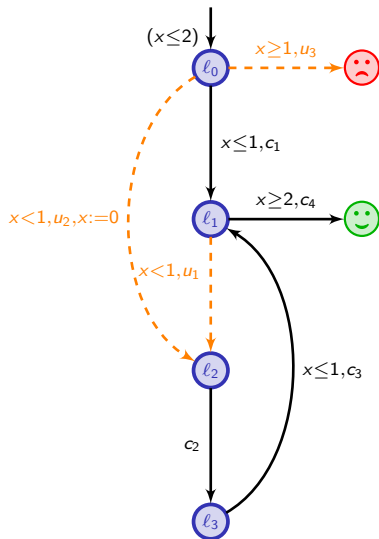
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$$f : \text{history} \mapsto (\text{delay}, \text{cont. transition})$$

Problems to be considered

- Does there exist a winning strategy?
- If yes, compute one (as simple as possible).

Decidability of timed games

Theorem [AMPS98,HK99]

Reachability and safety timed games are decidable and EXPTIME-complete. Furthermore memoryless and “region-based” strategies are sufficient.

[AMPS98] Asarin, Maler, Pnueli, Sifakis. Controller synthesis for timed automata (*HSSC'98*).

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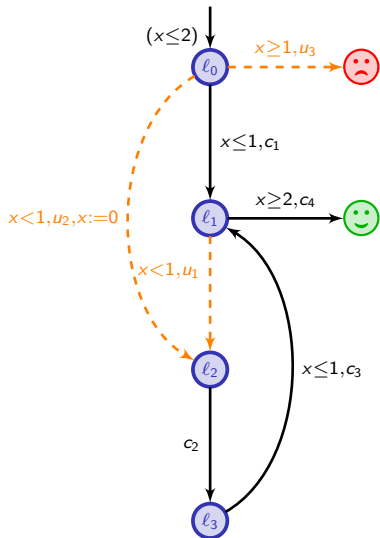
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~> classical regions are sufficient for solving such problems
(one only needs to compute the so-called attractor)

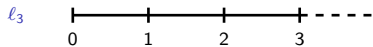
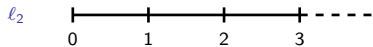
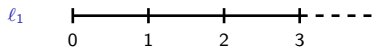
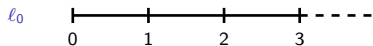
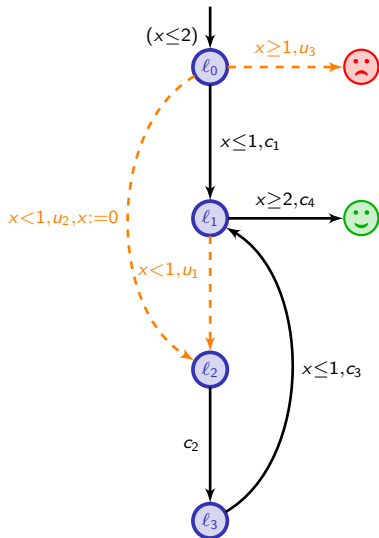
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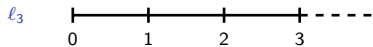
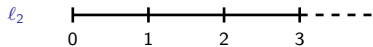
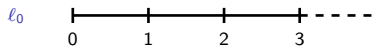
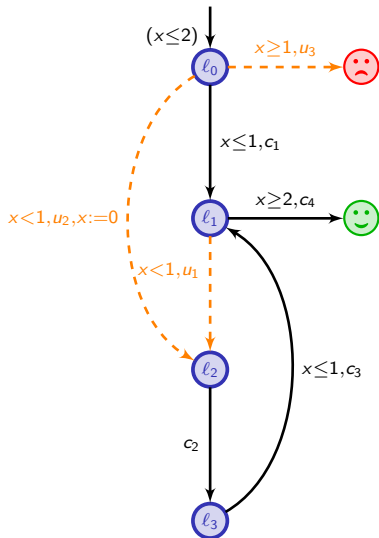
Back to the example: computing winning states



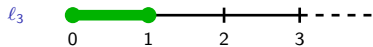
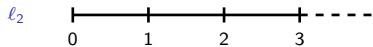
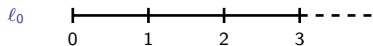
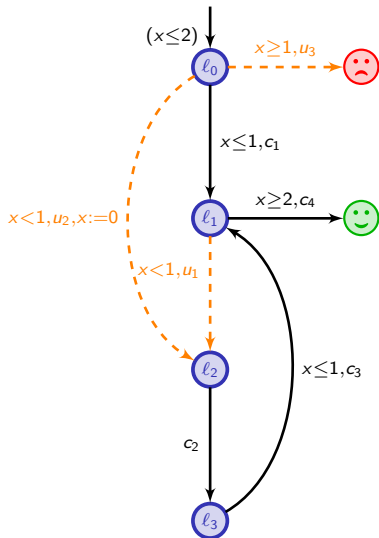
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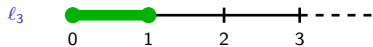
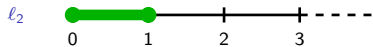
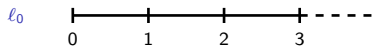
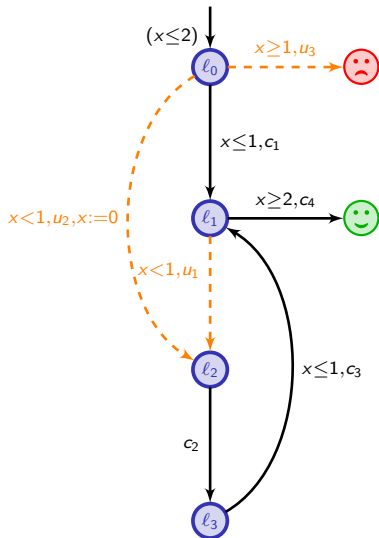
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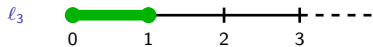
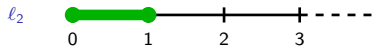
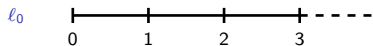
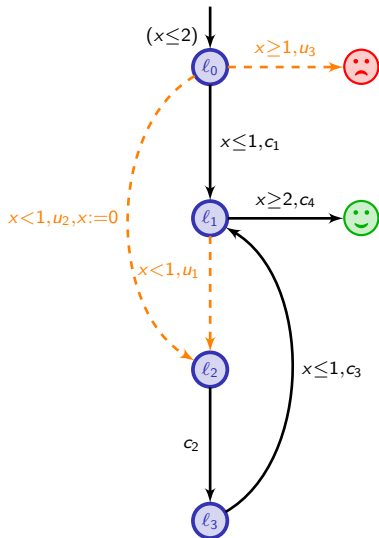
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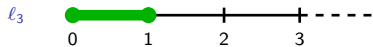
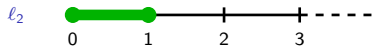
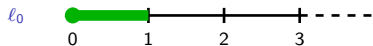
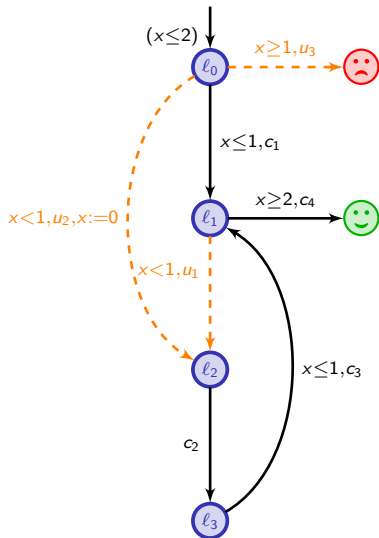
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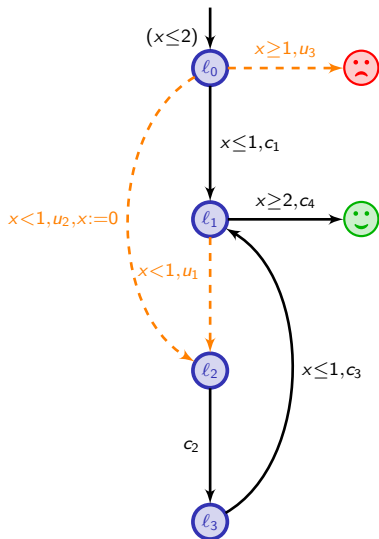
Back to the example: computing winning states



Back to the example: computing winning states



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Winning states

Losing states



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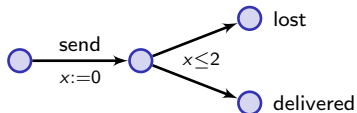
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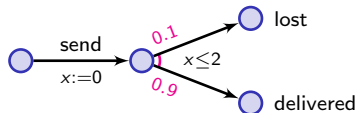
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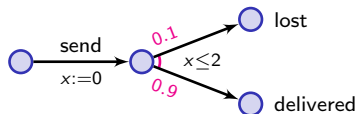
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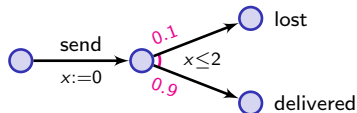
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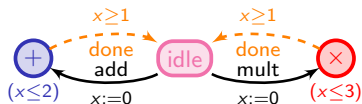


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Example of a processor in the taskgraph example

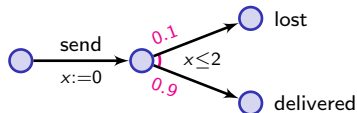


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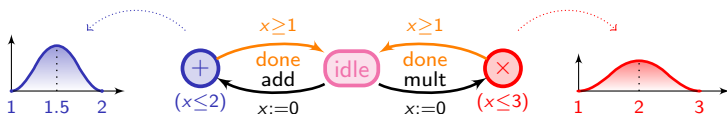


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~ the stochastic timed automata model [BBB+08,BF09]

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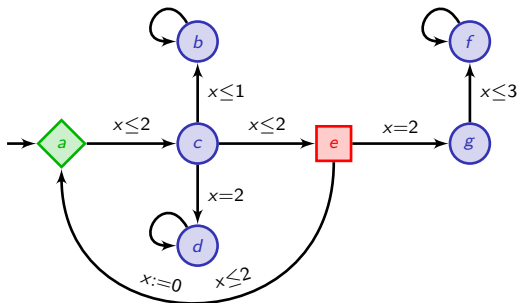
[BBB+08] Baier, Bertrand, Bouyer, Brihaye, Größer. Almost-sure model checking of infinite paths in one-clock timed automata (*LICS'08*).

[BF09] Bouyer, Forejt. Reachability in stochastic timed games (*ICALP'09*).

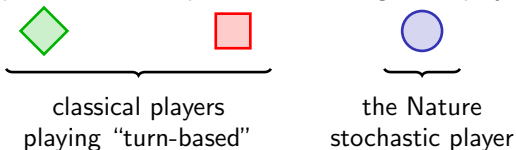
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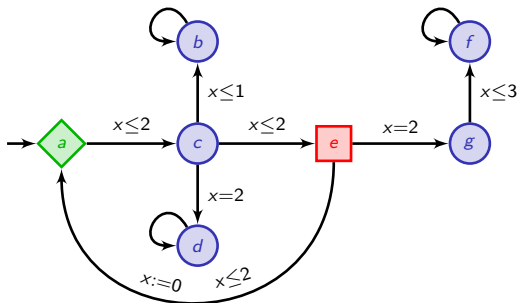
Stochastic timed game: an example



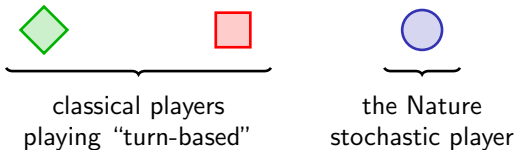
- Timed graph with vertices partitioned among three players:



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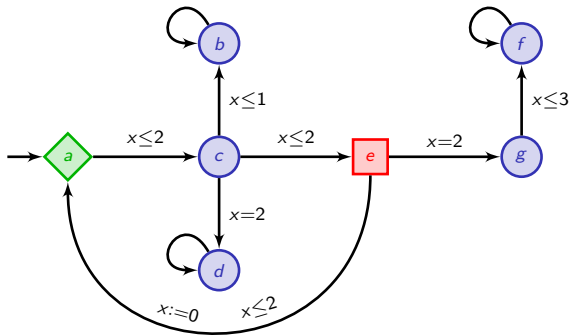


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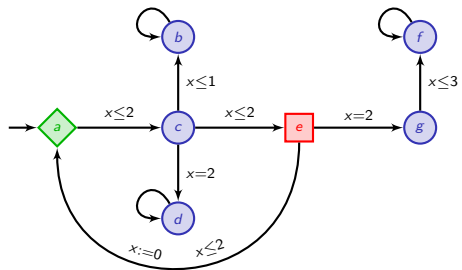
- There are prescribed probability distributions from \circ vertices.

How is this game played?

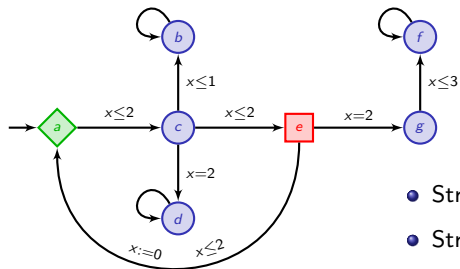


- Players \diamond and \square play according to standard strategies
- Player \circ plays according to the prescribed probability distributions:
 - choose a delay according to some distribution
 - choose an action according to some discrete distribution

Play, an example

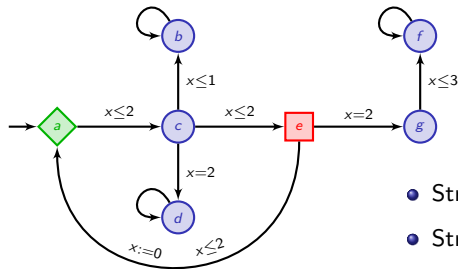


Play, an example



- Strategy for \diamond : go to c when $x = 1$
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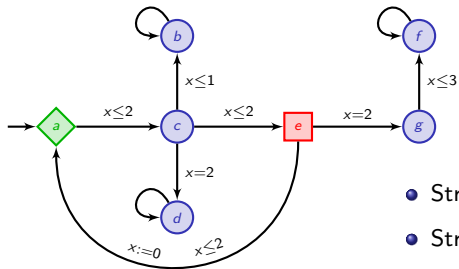
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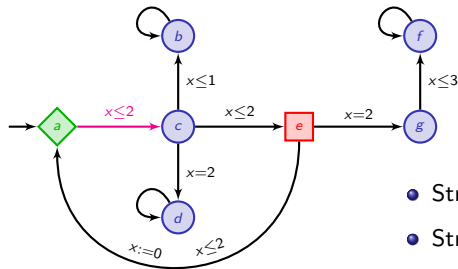


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$(a, 0)$

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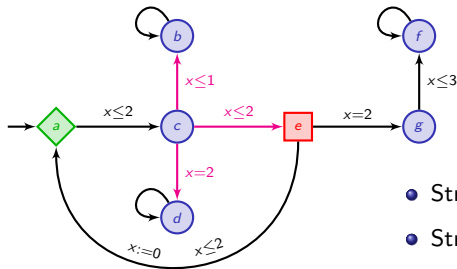


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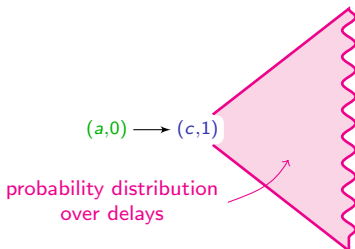
$$(a,0) \longrightarrow (c,1)$$

Play, an example

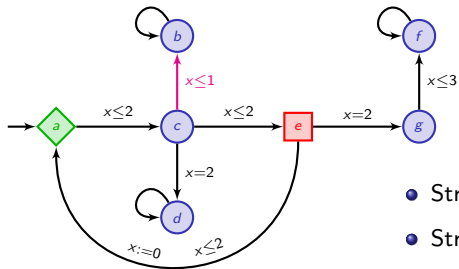


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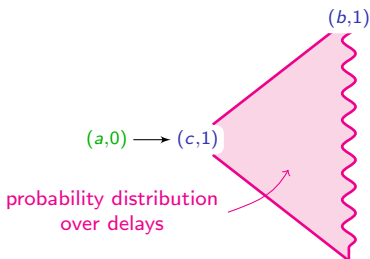


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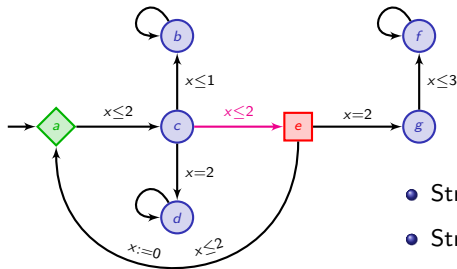


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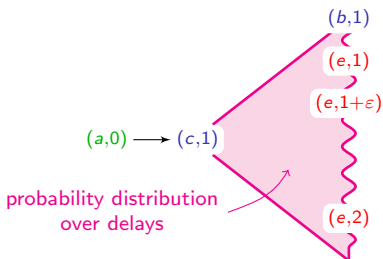


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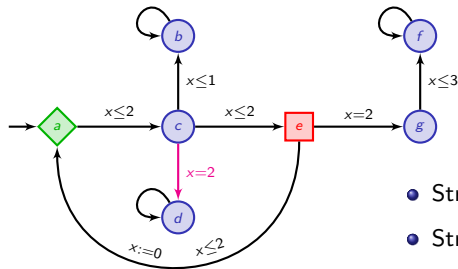


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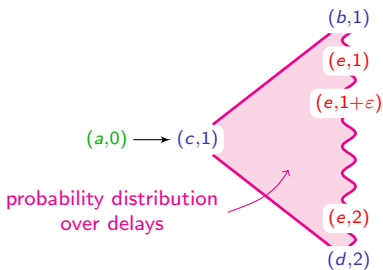


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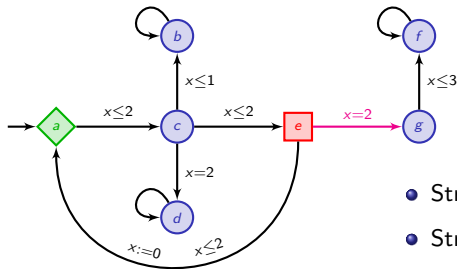


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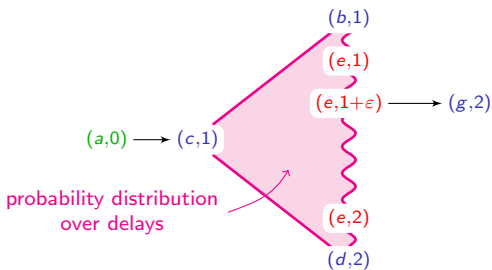


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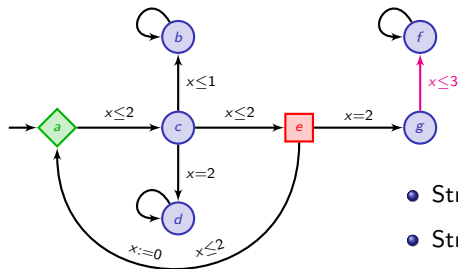


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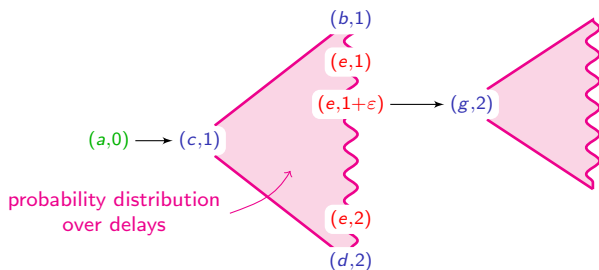


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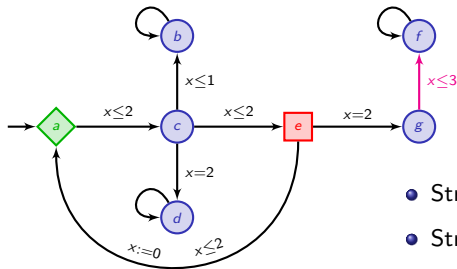


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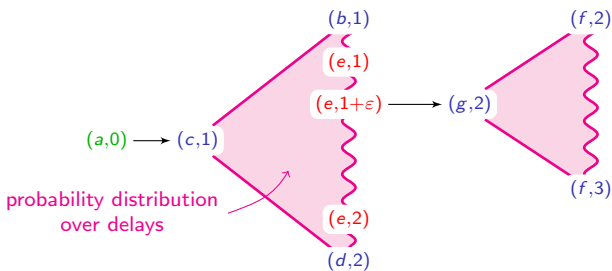


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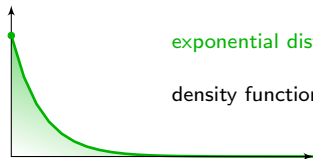


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How can we attach probabilities to delays?

- The example of continuous-time Markov chains

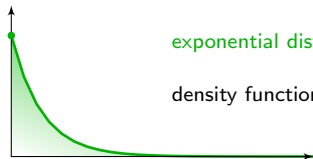


exponential distribution

$$\text{density function } t \mapsto \begin{cases} \lambda \cdot \exp(-\lambda t) & \text{if } t \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

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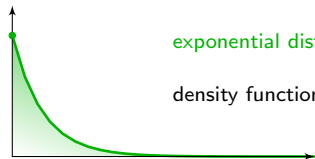
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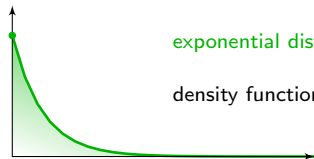
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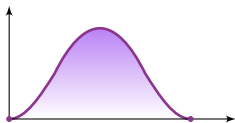


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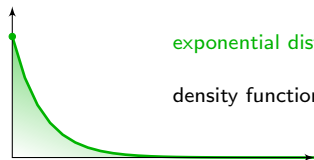
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truncated normal distribution

How can we attach probabilities to delays?

- The example of continuous-time Markov chains

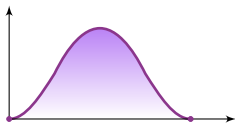


exponential distribution

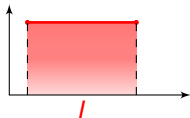
$$\text{density function } t \mapsto \begin{cases} \lambda \cdot \exp(-\lambda t) & \text{if } t \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

~ this is ok if delays are in $[0, +\infty)$

- But what if bounded intervals?



truncated normal distribution




uniform distribution

$$\text{density function } t \mapsto \begin{cases} \frac{1}{|I|} & \text{if } t \in I \\ 0 & \text{otherwise} \end{cases}$$

How does the semantics formalize?

- We will explain it more formally when all vertices belong to player \bigcirc . Those are called $\frac{1}{2}$ -player games.

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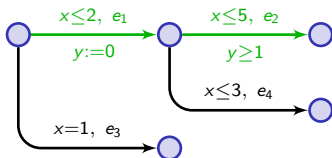
- We will explain it more formally when all vertices belong to player . Those are called $\frac{1}{2}$ -player games.
- We will then extend it using standard strategies for the two other players, which need however satisfy some measurability assumption

The $\frac{1}{2}$ -player game model

- $\pi(s \xrightarrow{e_1} \dots \xrightarrow{e_n})$: symbolic path from s firing edges e_1, \dots, e_n

The $\frac{1}{2}$ -player game model

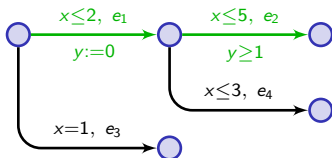
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- Example:



$$\pi(s_0 \xrightarrow{e_1} \xrightarrow{e_2}) = \{s_0 \xrightarrow{\tau_1, e_1} s_1 \xrightarrow{\tau_2, e_2} s_2 \mid \tau_1 \leq 2, \tau_1 + \tau_2 \leq 5, \tau_2 \geq 1\}$$

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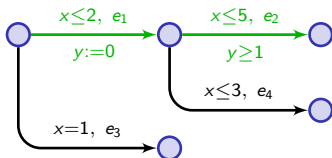
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From state s :

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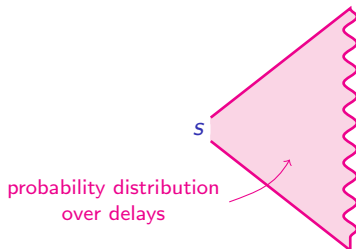


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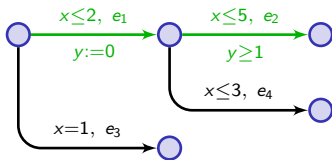
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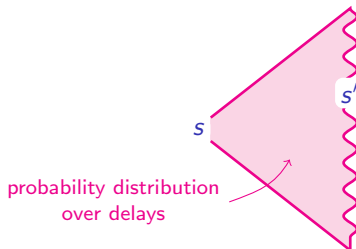


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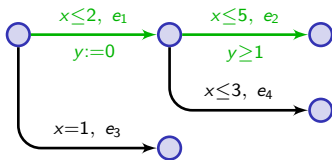
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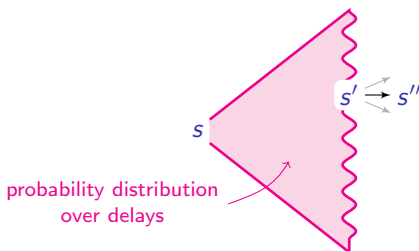


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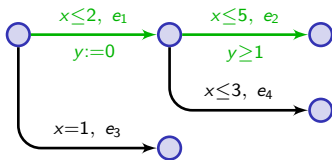
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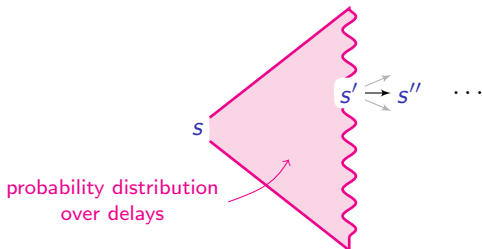


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From state s :

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- then randomly select an edge
- then continue



The $\frac{1}{2}$ -player game model

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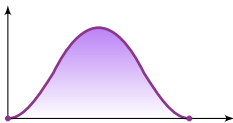
$$\mathbb{P}(\pi(s \xrightarrow{e_1} \dots \xrightarrow{e_n})) = \int_{t \in I(s, e_1)} p_{s+t}(e_1) \mathbb{P}(\pi(s_t \xrightarrow{e_2} \dots \xrightarrow{e_n})) d\mu_s(t)$$

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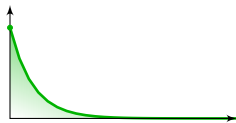
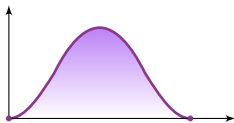


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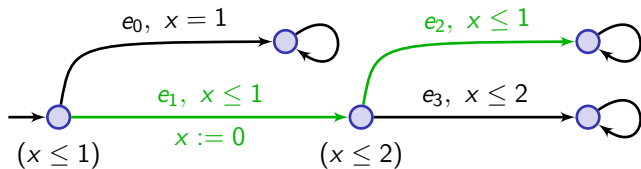
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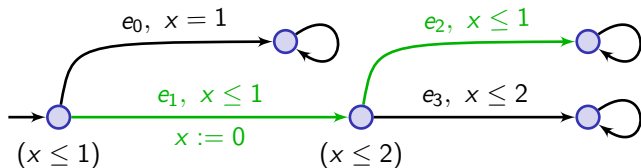
- $\text{Zeno}(s) = \bigcup_{M \in \mathbb{N}} \bigcap_{n \in \mathbb{N}} \bigcup_{(e_1, \dots, e_n) \in E^n} \text{Cyl}(\pi_{\sum_i \tau_i \leq M}(s \xrightarrow{e_1} \dots \xrightarrow{e_n}))$

An example of computation (with uniform distributions)



The probability of the symbolic path $\pi(s_0 \xrightarrow{e_1} \xrightarrow{e_2})$ is $\frac{1}{4}$.

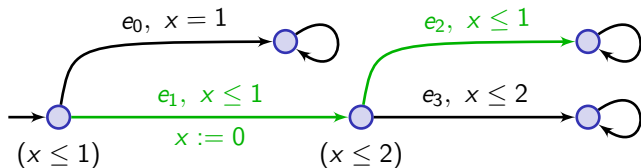
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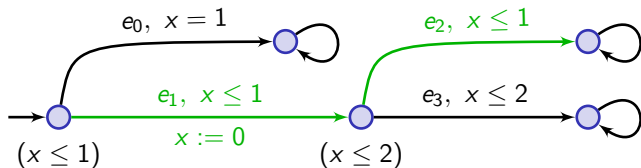
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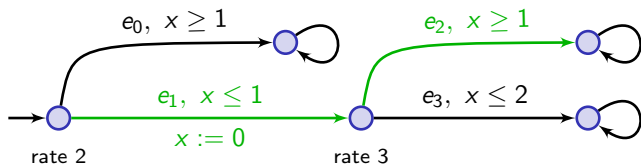
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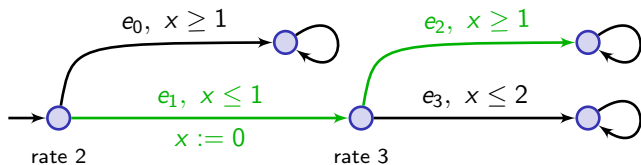
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 &= \int_0^1 \int_0^1 \left(\frac{1}{2} \frac{du}{2} \right) dt = \frac{1}{4}
 \end{aligned}$$

An example of computation (with exponential distrib.)



The probability of the symbolic path $\pi(s_0 \xrightarrow{e_1} e_2)$ is $e^{-3} - e^{-5} \approx 0.043$

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 \mathbb{P}(\pi(s_0 \xrightarrow{e_1} \xrightarrow{e_2})) &= \int_0^1 \mathbb{P}(\pi(s_1 \xrightarrow{e_2})) d\mu_{s_0}(t) = \int_0^1 \mathbb{P}(\pi(s_1 \xrightarrow{e_2})) 2 \exp(-2t) dt \\
 &= \int_0^1 \left(\int_1^{+\infty} 3 \exp(-3u) du \right) 2 \exp(-2t) dt \\
 &= [-\exp(-2t)]_{t=0}^1 \cdot [-\exp(-3u)]_{u=1}^{+\infty} \\
 &= (1 - e^{-2}) \cdot e^{-3} = e^{-3} - e^{-5}
 \end{aligned}$$

Some remarks

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- **Continuous-time Markov chains** = timed automata with a single “useless” clock which is reset on all transitions. The distributions on delays are exponential distributions with a rate per location.
- The semantics can be extended in a natural way to several players:

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mass distribution given by the strategy
if s is a player  vertex

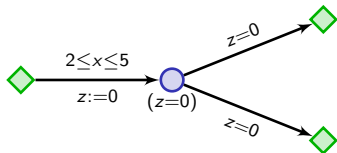
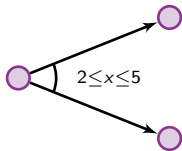
Some remarks

- This defines a purely stochastic process ($\frac{1}{2}$ -player game).
- **Continuous-time Markov chains** = timed automata with a single “useless” clock which is reset on all transitions. The distributions on delays are exponential distributions with a rate per location.
- The semantics can be extended in a natural way to several players:

$$\mathbb{P}(\pi(s \xrightarrow{e_1} \dots \xrightarrow{e_n})) = \int_{t \in I(s, e_1)} p_{s+t}(e_1) \mathbb{P}(\pi(s_t \xrightarrow{e_2} \dots \xrightarrow{e_n})) d\mu_s(t)$$

mass distribution given by the strategy
if s is a player \diamond vertex

- **Probabilistic timed automata** = a subclass of the $1\frac{1}{2}$ -player games

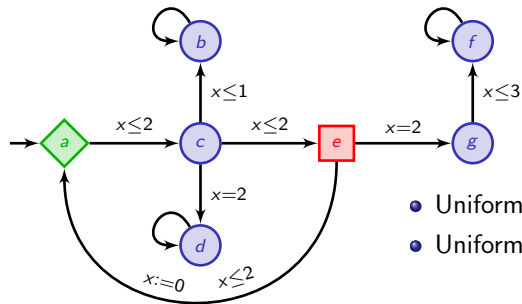


The synthesis problem

Problem statement

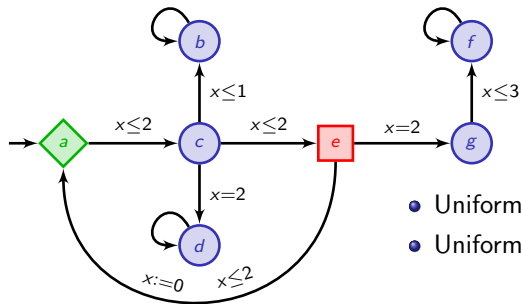
Given a game G , a (linear-time) property φ , a rational threshold $\bowtie r$,
 is there a strategy f_{\blacklozenge} for player \blacklozenge s.t.
 for all strategies f_{\blacksquare} of player \blacksquare , $\mathbb{P}(G_{f_{\blacklozenge}, f_{\blacksquare}} \models \varphi) \bowtie r$?

Reachability problem – Example



- Uniform distribution over delays
- Uniform distribution over edges

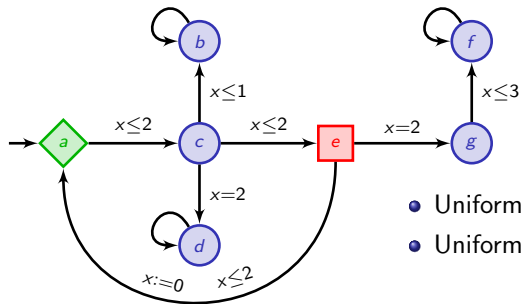
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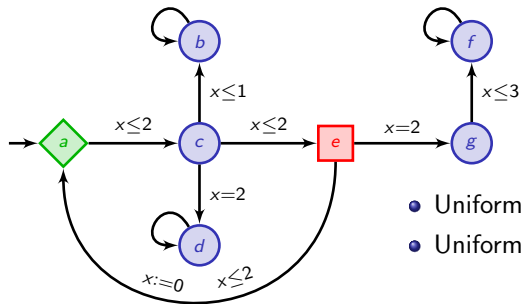
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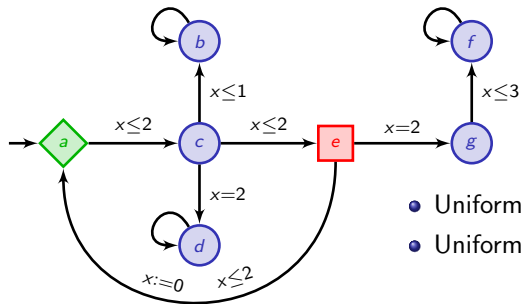
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 - No.







What kind of games will we play?

Number of players

- $2\frac{1}{2}$ -player games:   
- $1\frac{1}{2}$ -player games:   ("Markov decision process")
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Winning objective

The winning objective will be an ω -regular condition, or some LTL property, or some more restrictive condition like a reachability condition.

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Rough summary of the results

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under some assumptions...

- 1 reactive automata $I(s) = \mathbb{R}_+$, exponential distributions and resets on every cycle
- 2 reactive automata $I(s) = \mathbb{R}_+$ and exponential distributions
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- 4 even for reachability properties, exponential (or uniform) distributions

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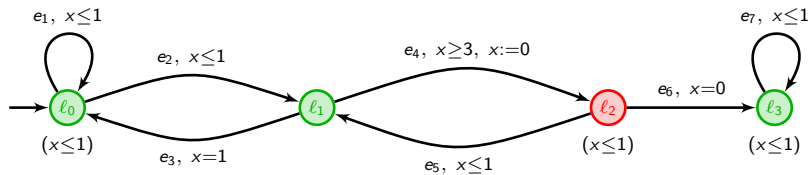
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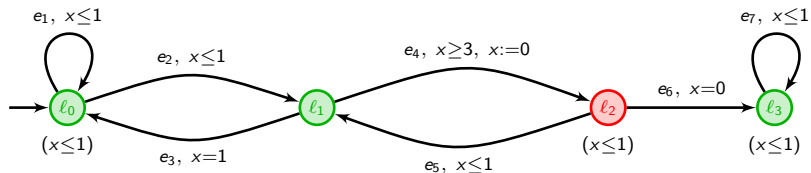
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There are only  vertices, but we will use extra colors to represent atomic propositions.

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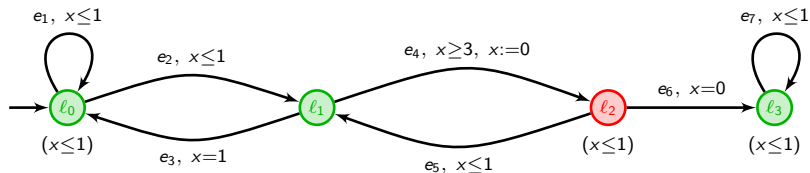


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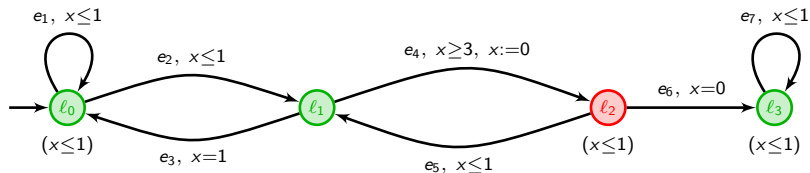
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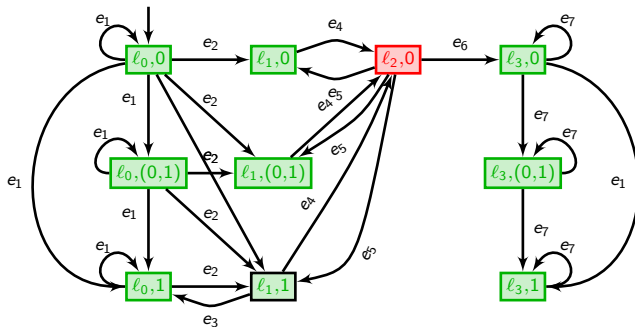
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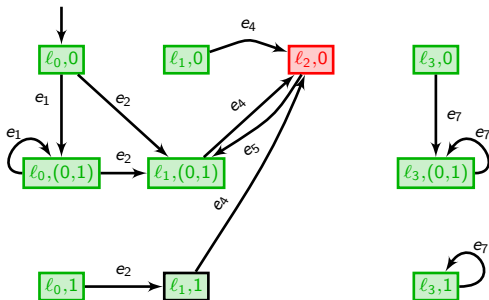
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Indeed, almost surely, paths are of the form $e_1^* e_2 (e_4 e_5)^\omega$

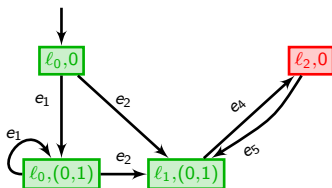
The classical region automaton



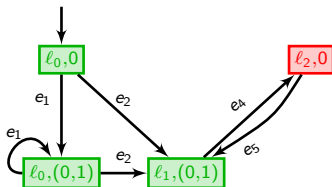
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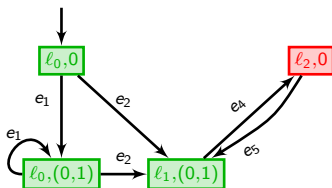


The pruned region automaton



... viewed as a finite Markov chain $MC(\mathcal{A})$

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Proposition

For single-clock timed automata,

$$\mathbb{P}(\mathcal{A} \models \varphi) = 1 \quad \text{iff} \quad \mathbb{P}(MC(\mathcal{A}) \models \varphi) = 1$$

(this is independent of the choice of the distributions...)

Result

Theorem [BBB+08]

For **single-clock** timed automata, the almost-sure model-checking

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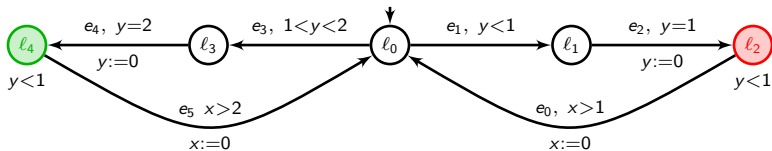
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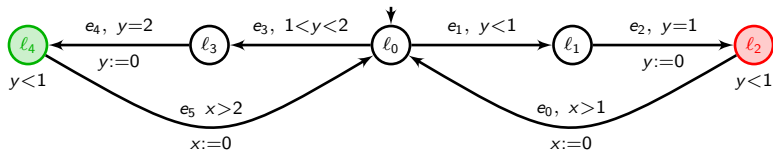
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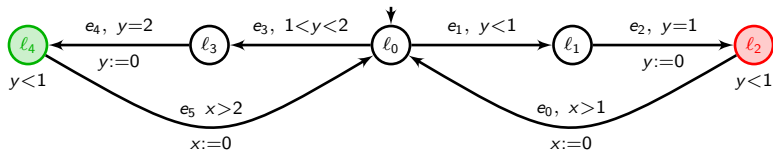


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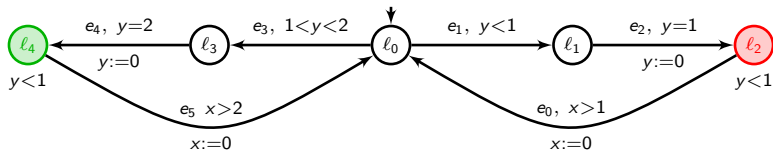
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- There is a *strange convergence phenomenon*: along an execution, if $\delta_i > 0$ is the delay in locations l_2 or l_4 , then we have that $\sum_i \delta_i \leq 1$

A note on Zeno behaviours

- The set of Zeno behaviours is measurable:

$$\text{Zeno}(s) = \bigcup_{M \in \mathbb{N}} \bigcap_{n \in \mathbb{N}} \bigcup_{(e_1, \dots, e_n) \in E^n} \text{Cyl}(\pi(s \xrightarrow{e_1} \dots \xrightarrow{e_n}))$$

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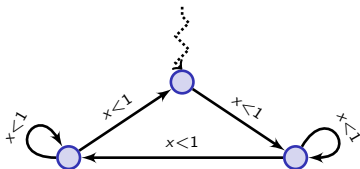
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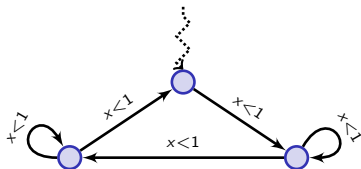


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- an interesting notion of non-Zeno timed automata

$$x \leq 1, x := 0$$



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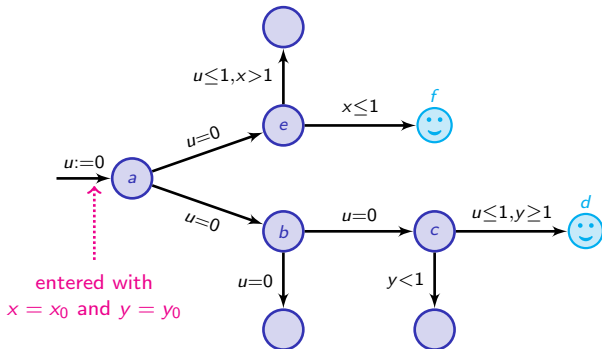
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 -  simulates a computation of the two-counter machine and encodes counter values in clock values
 -  stores counter values c_1 and c_2 as $\frac{1}{2^{c_1}3^{c_2}}$
 -  will check that  is not cheating using the power of the probabilities

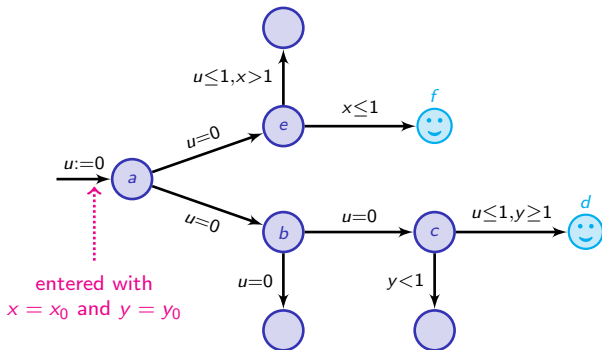
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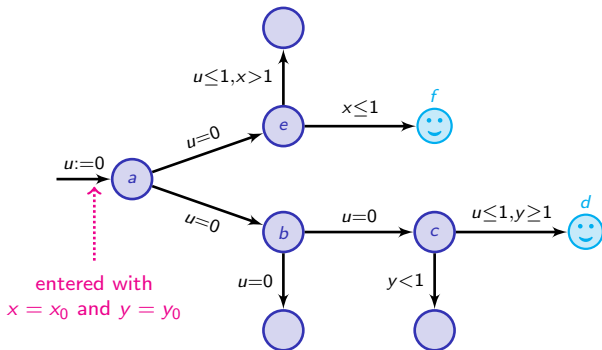
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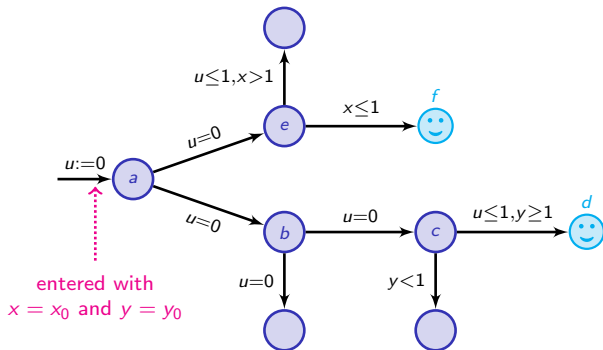


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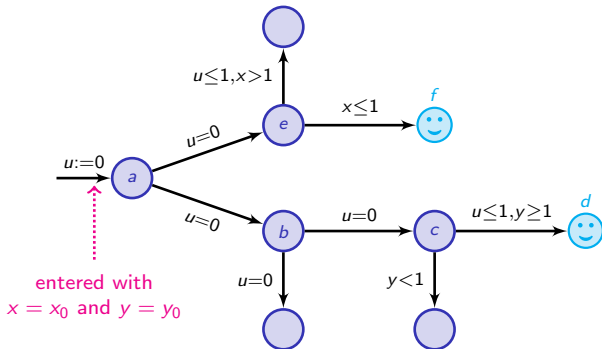


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Undecidability – Comparing counter values

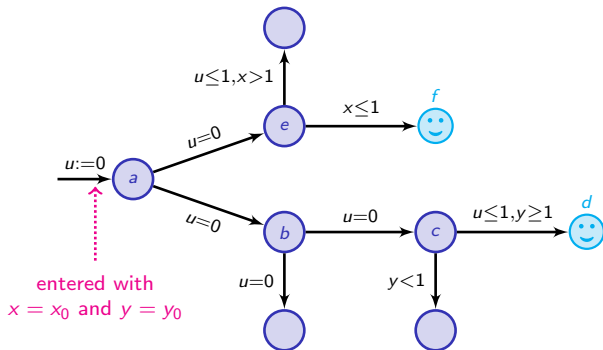
- Check clock y stores $(c_1 + 1, c_2)$, assuming that x stores (c_1, c_2)



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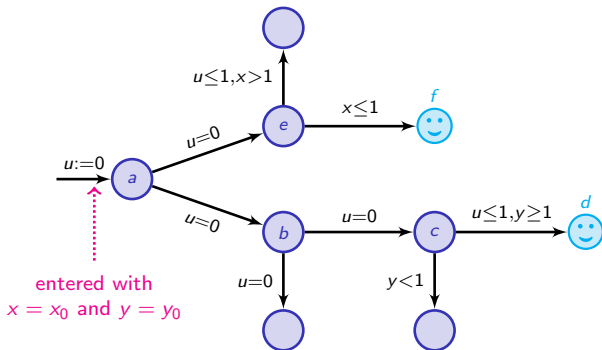
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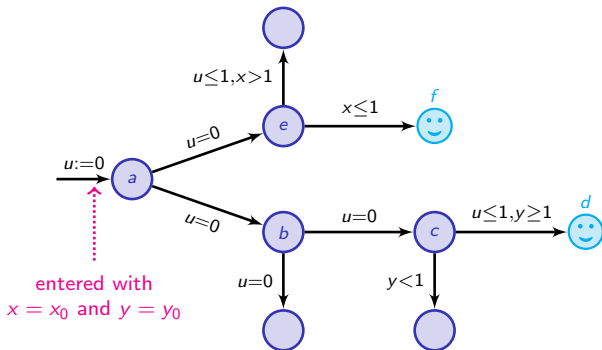


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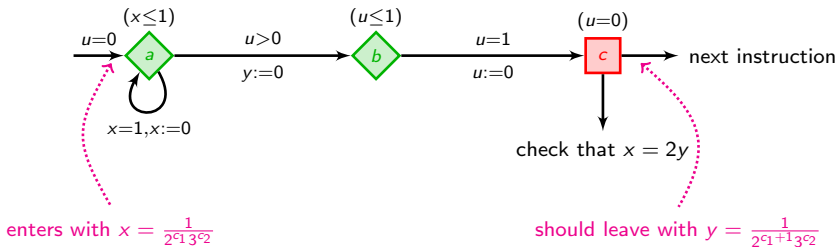


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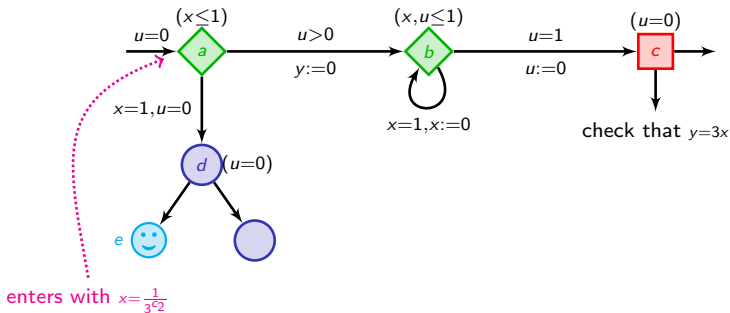
Undecidability – Incrementation

How do we properly increment the first counter?



Undecidability – Zero test

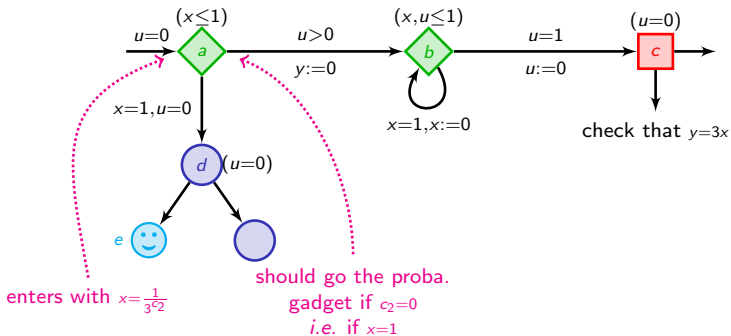
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Player  has a strategy to reach  with proba. $\frac{1}{2}$ iff c_1 is initially zero.

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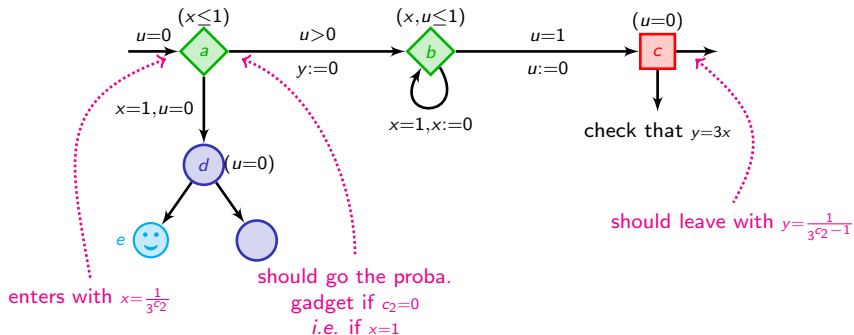
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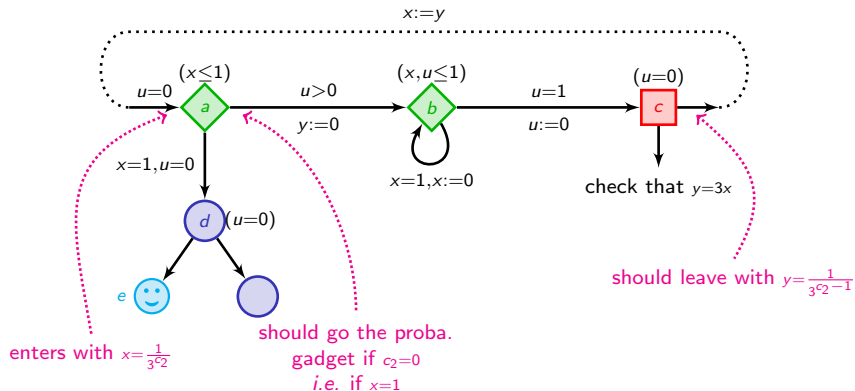
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Summary of the results

Model		Qualitative	Quantitative
$\frac{1}{2}$ -player game	1 clock	decidable [BBB+08]	decidable [BBBM08]
	n clocks	decidable?	?
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[BBB+08] Baier, Bertrand, Bouyer, Brihaye, Größer. Almost-sure model checking of infinite paths in one-clock timed automata (*LICS'08*).

[BBBM08] Bertrand, Bouyer, Brihaye, Markey. Quantitative model-checking of one-clock timed automata under probabilistic semantics (*QEST'08*).

[BF09] Bouyer, Forejt. Reachability in stochastic timed games (*ICALP'09*).

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- we will be able to **decide** the threshold problem

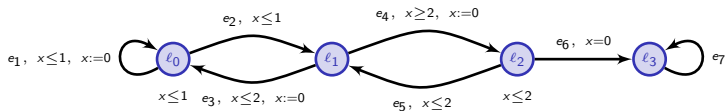
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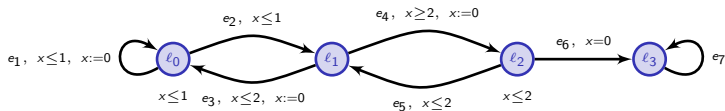
- we will be able to **decide** the threshold problem:
 “Given \mathcal{A} , φ , $c \in \mathbb{Q}$, and $\sim \in \{<, \leq, =, \geq, >\}$,
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An example



- + distributions $\mu_s: t \mapsto e^{-t}$ when $I(s) = \mathbb{R}_+$
 μ_s uniform distribution when $I(s)$ is bounded
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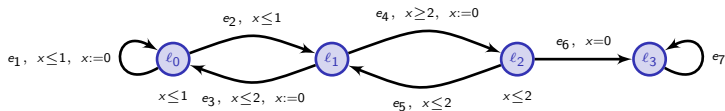
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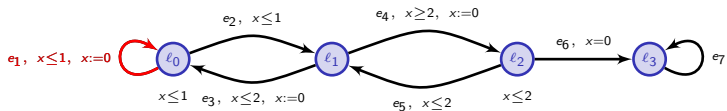


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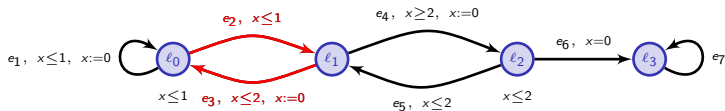


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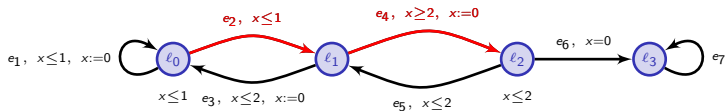


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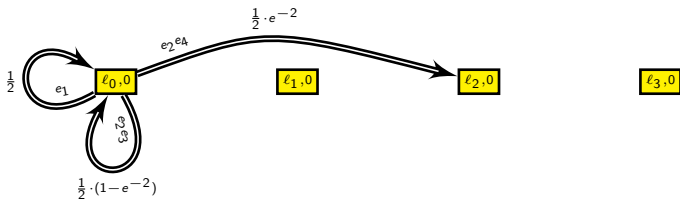


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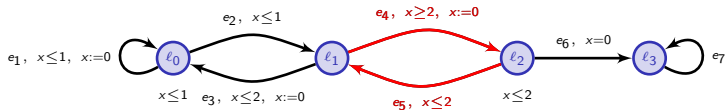


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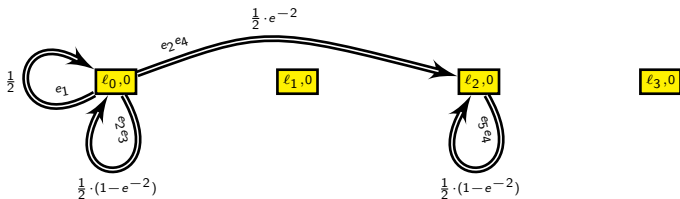


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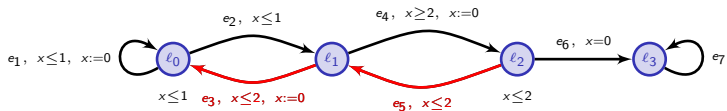


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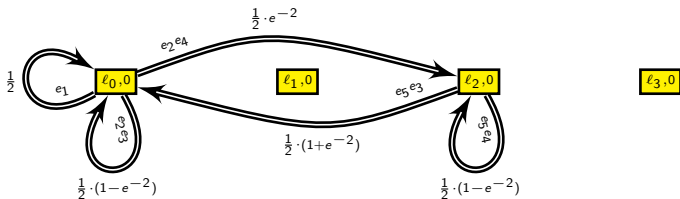


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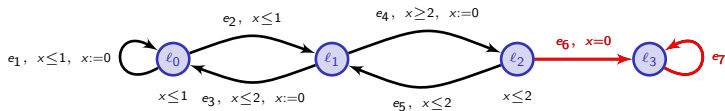


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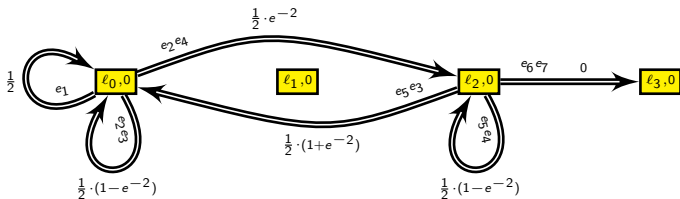


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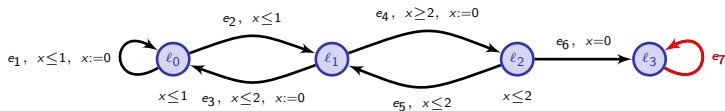
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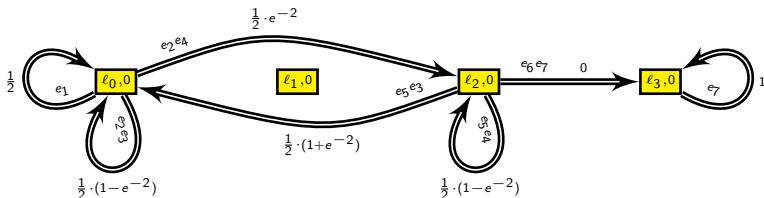


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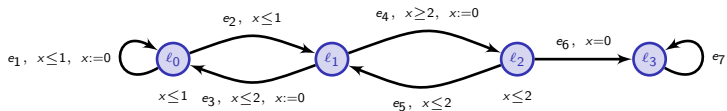
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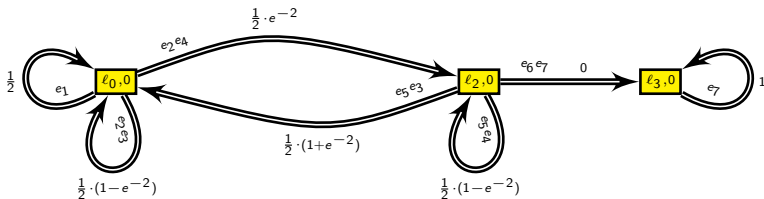


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- **Limits of the abstraction:** there may be no closed form for the values labelling the edges of $MC'(\mathcal{A})$.

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- When $(a_N, b_N) \subseteq (\alpha, \beta)$, the two sequences $(f(a_i))_{i \geq N}$ and $(f(b_i))_{i \geq N}$ are monotonic and converge to $f(e^{-r})$

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$\frac{1}{2}$ -player game	1 clock	decidable [BBB+08]	decidable ¹ [BBBM08]
	n clocks	decidable? ²	?
$1\frac{1}{2}$ -player game	1 clock	decidable ³ [BF09]	?
	n clocks	?	?
$2\frac{1}{2}$ -player game	1 clock	?	?
	n clocks	?	undecidable ⁴ [BF09]

- **Not much has been done so far!**

- even for simple untimed objectives, few is known
- nothing about more involved quantitative objectives (e.g. expected time, timed properties, ...)

Conclusion and perspectives

- We have presented a **general model** for **stochastic timed games**:

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- probabilistic features
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 - what about approximate probabilities?
 - compositionality problems
- **Probabilistic timed automata** (PRISM and UPPAAL-PRO model)
 - the questions considered in this presentation can be “trivially” answered (because they reduce to similar questions on discrete-time Markov decision processes)
 - quantitative objectives should be investigated