



Playing (Almost-)Optimally in Concurrent Büchi and co-Büchi Games

Benjamin Bordais, Patricia Bouyer, Stéphane Le Roux

Laboratoire Méthodes Formelles Université Paris-Saclay, CNRS, ENS Paris-Saclay France

Context

- Two-player games on graphs as a tool for formal verification (e.g. controller synthesis)
- Win/lose games: the objectives of the two players are opposite
- **Concurrent games**, as opposed to turn-based games





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Martin's determinacy theorem for Blackwell games

Concurrent games with Borel objectives have values:

$$v(q) = \sup_{\sigma_{A}} \inf_{\sigma_{B}} \mathbb{P}_{\sigma_{A},\sigma_{B}}(W) = \inf_{\sigma_{B}} \sup_{\sigma_{A}} \mathbb{P}_{\sigma_{A},\sigma_{B}}(W)$$

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 - Parity games require infinite memory for both optimal and almost-optimal strategies

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- (Infinite) Memory is sometimes needed by optimal and almost-optimal strategies
 - Parity games require infinite memory for both optimal and almost-optimal strategies
- Note: this is specific to concurrent games! (as compared to turn-based)



« The snowball game »

[AH00] L. De Alfaro, T. Henzinger. Concurrent omega-regular games (LICS'00)



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- ► Objective is to visit T infinitely often
- $\bullet \quad \text{Value of the game is } 1$
- Player A (rows) has no optimal strat.
- Every finite-memory strat. has value 0
- Player A needs infinite memory to play ε -optimal for every $\varepsilon > 0$:
 - Play first row with probability $1 \varepsilon_k$ and second row with probability ε_k
 - k is the number of visits to op
 - $(\varepsilon_k)_k$ quickly decreases to 0

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- $\sigma_{\rm A}$ is positional if it depends only on the last visited state
The approach of this work

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Our approach: focus on interactions, and characterize well-behaved interactions





Game form

 $\begin{bmatrix} x & y \\ y & z \end{bmatrix}$



Elementary brick





Elementary brick







Game form

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Games on graphs with good properties

Game forms with good properties

 $\bullet \ \ \, {\cal S} \ {\rm set} \ {\rm of} \ {\rm game \ forms}$



- \mathcal{I} set of game forms
- Identify properties of \mathscr{I} so that all concurrent games built using game forms \mathscr{I} behave well



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Behave well = positional (almost-)optimal strategies are sufficient



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- Determinacy of deterministic games [BBL21]
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 - Local determinacy condition on game forms
- Reachability objectives [BBL22]
 - Optimal and almost-optimal strategies can be chosen positional (when they exist)
 - Local condition (called RM) on game forms to ensure existence (and therefore positionality) of optimal strategies everywhere

• One can associate to each state q of the game its value v(q), and these values satisfy local optimality equations

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Game in normal form

$$\begin{bmatrix} 1/2 & 1/4 \\ 1/2 & 3/4 \end{bmatrix}$$

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- All globally optimal strategies (in the graph) are locally optimal
- Locally optimal strategies may not be globally optimal (in the graph)











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- What is wrong?
 - In the MDP generated by $\sigma_{\rm A},$ there is an end-component which is losing

Characterize positional (almost-)optimal strategies using locally (almost-)optimal strategies (applies to tail objectives)

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Büchi objectives

- Optimal strategies may not exist (known)
- When optimal strategies exist from all states, they can be chosen positional (inherited from reachability games)
- Almost-optimal strategies may require infinite memory (known)
- Characterization of nice game forms (aBM) for ensuring:
 - Positional almost-optimal strategies

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co-Büchi objectives

- Optimal strategies may not exist (known)
- When optimal strategies exist, they may require infinite memory
- Almost-optimal strategies can be chosen positional (known [CDAH06])
- Characterization of nice game forms (coBM) for ensuring:
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From bricks to nice constructions

• Recall: there exist Büchi games where infinite memory is required to play arepsilon-optimally



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How should we restrict interactions to avoid this phenomenon?
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$$\mathscr{F} = \begin{bmatrix} x & y \\ y & z \end{bmatrix}$$

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Definition of aBM (almost-Büchi maximizable)

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Characterization

- If all game forms used in a concurrent game \mathscr{G} are aBM, then \mathscr{G} admits positional ε -optimal strategies for every $\varepsilon > 0$
- If a game form is not aBM, then there is a concurrent game which does not admit a positional ϵ -optimal strategy for some $\epsilon > 0$.

	Positional opt. strat.		Positional almost-opt. strat.	
	Target	Not target	Target	Not target
Safety obj.	No restr.	No restr.	No restr.	No restr.
Reach. obj.	No restr.	RM	No restr.	No restr.
Büchi obj.	No restr.	RM	No restr.	aBM
co-Büchi obj.	RM	coBM	No restr.	No restr.

Existence of positional optimal or ϵ -optimal strategies under the following restrictions on game forms:

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If game forms at states not in target are coBM and in targets are RM, then optimal strategies exist and can be chosen positional





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- $coBM \subseteq RM \subseteq aBM$
- These game forms are coBM:
 - « Turn-based » game forms:
 - Two-variable game forms:

$$\begin{bmatrix} x & y & z \\ x & y & z \end{bmatrix}$$

$$\begin{bmatrix} x & y & x \\ y & x & x \end{bmatrix}$$

• Permutation game forms:

$$\begin{bmatrix} x & y & z \\ z & x & y \\ y & z & x \end{bmatrix}$$

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- Identify interactions (game forms) that are well-behaved (with a property in mind)
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- Going further:
 - Understand beyond (co-)Büchi conditions, e.g. parity conditions
 - (Ongoing work) A different approach, which should be able to deal with parity conditions





