FAST: Theory and practice of acceleration

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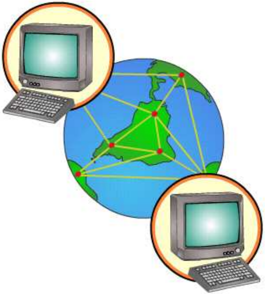
LSV - CNRS & ÉNS de Cachan

6 mars 2006

Verification of reactive systems



Reactive systems

- Software and/or hardware
- Autonomous
- Critical

The TTP protocol

Processors embedded in cars

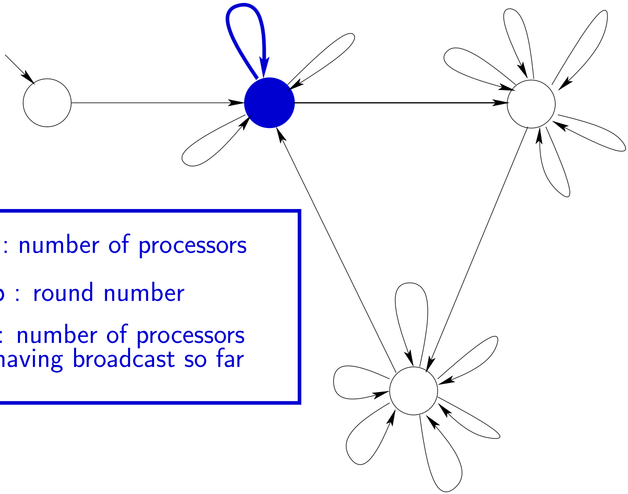
The TTP protocol

- fault tolerance
- ensure no fault will propagate

TTP is supported by Audi, PSA, Renault, ...

A model of the TTP [Bouajjani-Merceron 2002]

If d<N Do
  d:=d+1;Cp:=Cp+1
End Do



N : number of processors

Cp : round number

d : number of processors having broadcast so far

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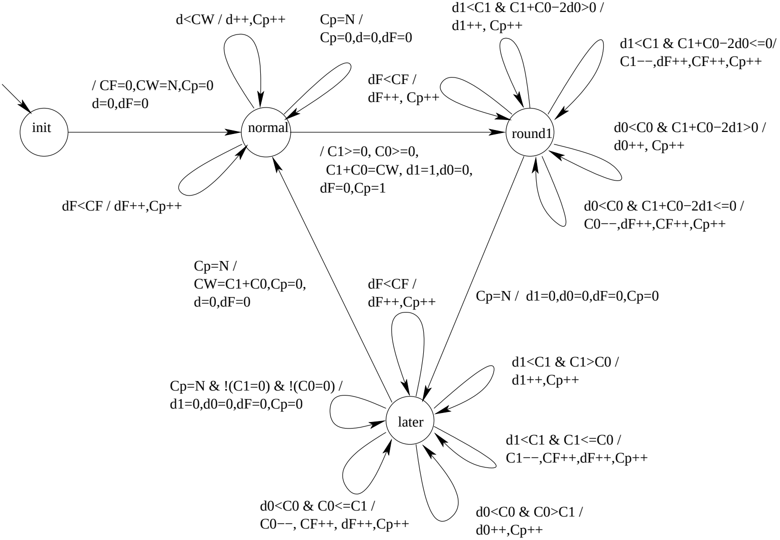

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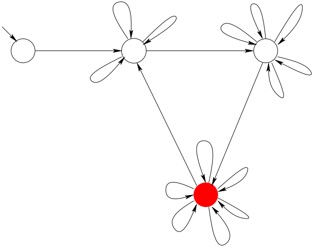


Question

In the red location , does
$C_p = N \Rightarrow (C_0 = 0 \vee C_1 = 0)$?

Objective

Automatic verification for any value of N

Our problem: counter system verification

Counter systems

- we study mathematical models of concrete systems
- automata extended with unbounded integer variables

Properties to check

Reachability properties = properties of reachable configurations.

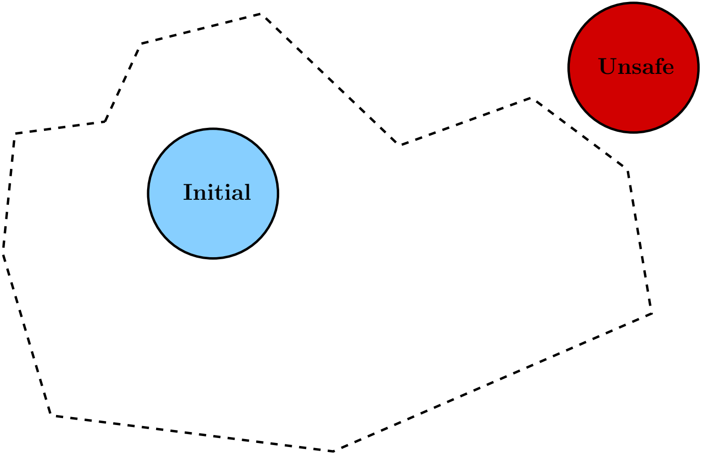
- useful: mutual exclusion, deadlock freedom, ...
- easy to check from the reachability set.

Our problem: counter system verification

Problems

- Undecidable for two counters with $(+1, -1, \stackrel{?}{=} 0)$
- One of the issues: infinite reachability set

Back to the finite case



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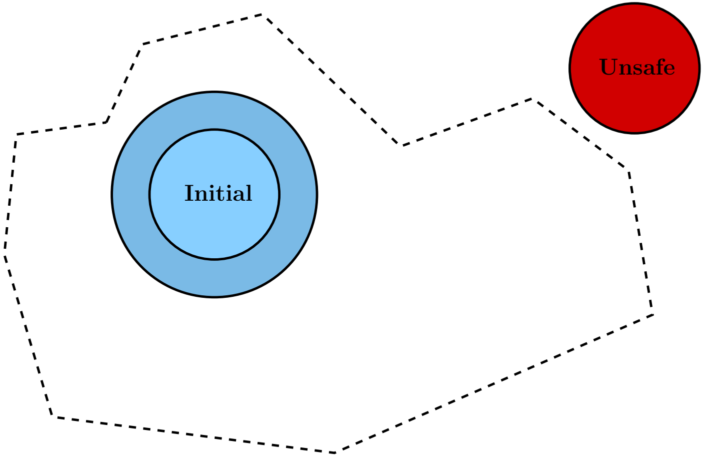

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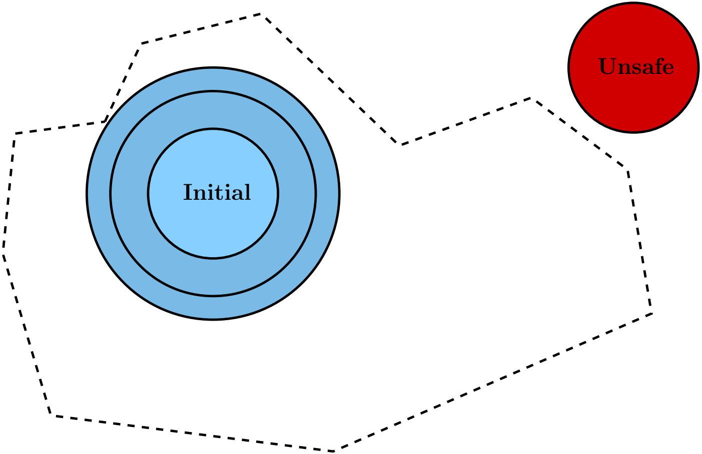

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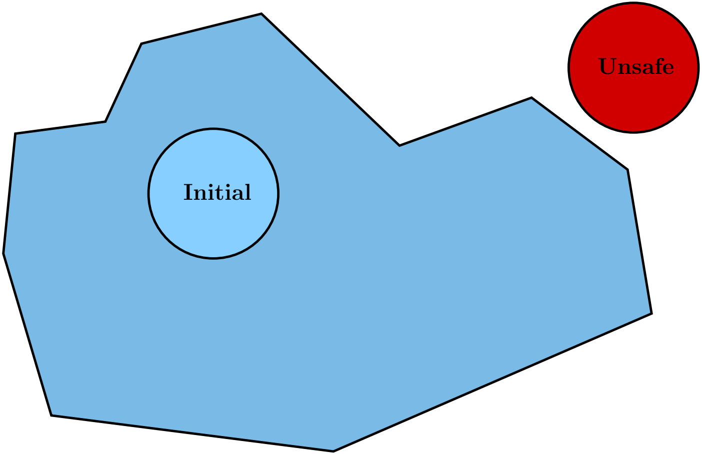

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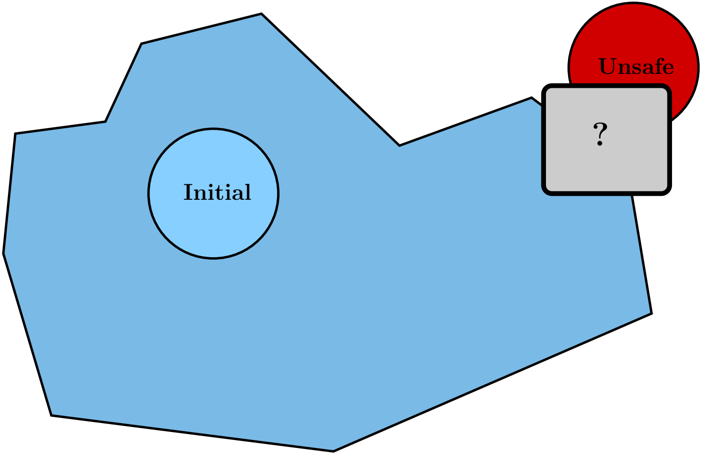

Extend verification to infinite systems

Enumerative methods do not work any more

Algorithms for decidable subclasses

- Petri nets,
- timed automata, ...

or Semi-algorithms to compute the reachability set

- more expressive/realistic systems
- no guarantee of termination, we hope practical termination
- Extend iterative computation for infinite sets
- (symbolic model-checking)

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- (symbolic model-checking)

Symbolic model-checking framework

Issue 1: infinite set of reachable configurations.

Idea = manipulate infinite sets of configurations

- sets are represented symbolically.
- need basic symbolic operations $\textsc{post}$, $\sqcup$, $\sqsubseteq$.

Example: intervals of integers

- Formula $\phi_X : \{x > 5\}$ means that x ranges over all integers greater than 5
- After transition $\xrightarrow{\text{y:=x+1}}$, the possible values of y are exactly represented by $\phi_Y = \{y > 6\}$

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First (and basic) symbolic procedure

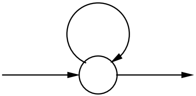
Iterative computation of $\mathrm{post}_S^*(X_0)$

1. $X \leftarrow X_0$
2. If $\textsc{post}(X) \sqsubseteq X$ Goto 5
3. $\quad X \leftarrow \textsc{post}(X) \sqcup X$
4. $\quad$ Goto 2
5. Return X

Issue 2: termination is scarce

because of circuits in the control graph ...

If $x \geq 0$ Do $x \leftarrow x + 2$



If $X_0 = \{0\}$ then

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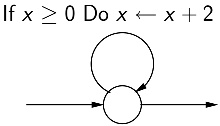

If $X_0 = \{0\}$ then $X = \{0\}$

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Iterative computation of $\mathrm{post}^*_S(X_0)$

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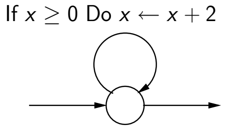

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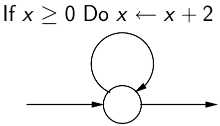
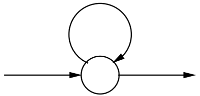


If $X_0 = \{0\}$ then $X = \{0, 2, \ldots, 2k\}$

Principle of circuit acceleration

Circuit acceleration

Enhance the convergence of the iterative symbolic procedure by computing in one step the iteration of a sequence of transitions (circuit).



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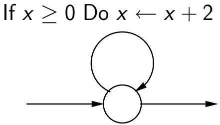

If $X_0 = \{0\}$ then $\text{post}^*(X_0) = 2.\mathbb{N}$, in one step.

About acceleration of counter systems

State-of-the-art in 2002

(*Karp-Miller 1969*)

(*Fribourg 1990*)

[Boigelot-Wolper 1994],

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Remarks

1. very different techniques, no unifying view (comparison?)
2. still a gap between acceleration algorithm and fixpoint computation (how to select circuits?)

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Symbolic computation in counter systems, 2002

- A symbolic representation: automata
  - DFA [Boudet-Comon 1996],
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- Various circuit acceleration algorithms
  - $f(x) = M.x + v$, with *finite monoid* and convex guard [Boigelot 1998]
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Issues / Results

Issue : Various acceleration techniques

Results : Unifying framework encompassing most of acceleration theorems [ATVA'05]

Issue : How to select circuits?

Results : Maximal heuristic, efficient in practice [CAV'03,ATVA'05]

Issue : Improve practical efficiency of acceleration

Results : "Convex acceleration" algorithm [TACAS'04]

Issue : Experimentations

Results : implementation of FAST [CAV'03],
Verification of the TTP [TACAS'04] and others

These works have been partially supported by ACI PERSÉE.

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Outline

Reminder

Presburger arithmetics

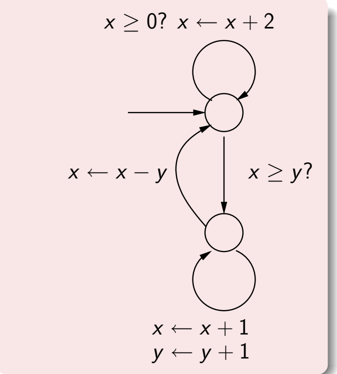
First order arithmetics without $\times$-operator

$$\phi ::= t \leq t | \neg\phi | \phi \vee \phi | \exists k.\phi | true$$
$$t ::= 0 | 1 | y | t - t | t + t.$$

Presburger set = set of solutions of a Presburger formula.

Counter systems

- finite set of m variables $x, y, z, \ldots$ over $\mathbb{N}$
- finite set of P-affine functions $f = (M, v, G)$
  - $G \subseteq \mathbb{N}^m$ Presburger guard
  - M square matrix
  - v vector
- $\overrightarrow{var}' = f(\overrightarrow{var})$ iff
  - $\overrightarrow{var} \in G$
  - and $\overrightarrow{var}' = M.\overrightarrow{var} + v$



Symbolic representations: Automata

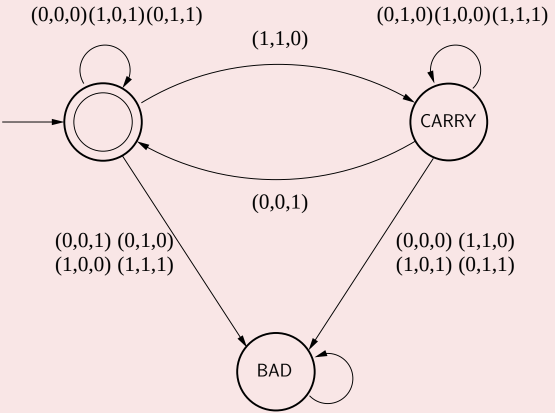
Automata to recognize sets of integer vectors

- a non-negative integer in basis 2 is a word over $\{0, 1\}$
- automata recognize sets of words
- extensions
  - any integer: 2-complement encoding
  - vectors: tuples of letters, or variables entanglement

Presburger sets (and a little bit more) are recognized by automata.

Common operations on sets $\longrightarrow$ standard operations on automata

Symbolic representations: Automata



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Outline

Standard Acceleration

Monoid of a function $f = (M, v, G)$: $\{1, M, M^2, \ldots, M^n, \ldots\}$

Theorem [Finkel-Leroux 2002]

Let $f = (M, v, G)$ a P-affine function with finite monoid. Then f^* is effectively defined by a Presburger formula

$$f^* = \{(x, x') | x \in G \wedge \exists k \geq 0 . x' = \bar{f}^k(x) \wedge \forall i . 0 \leq i < k, \bar{f}^i(x) \in G\}$$

Building the formula is 3-EXP in $|\mathcal{A}(G)|$, $|v|_{max}$, $|M|_{max}$ et m.

Idea of the algorithm

- $f = (M, v, G)$ with finite monoid $< M >$.
- $\bar{f} : \mathbb{Z}^m \to \mathbb{Z}^m, \forall x \in \mathbb{Z}^m, \bar{f}(x) = M.x + v$

- $< M >$ finite, then $\exists (a, b) \in \mathbb{N} \times \mathbb{N}$ such that $M^{a+b} = M^a$
- We deduce that $\forall n \in \mathbb{N}, \forall x \in \mathbb{Z}^m, \bar{f}^{a+n.b} = \bar{f}^a(x) + n.M^a.\bar{f}^b(0)$
- It comes that $\bar{F} = \{(i, x, x') \in \mathbb{N} \times \mathbb{Z}^m \times \mathbb{Z}^m, x' = \bar{f}^i(x)\} \Longleftrightarrow$ $\bigvee_{r=0}^{a-1}\{(i, x, x') | x' = \bar{f}^r(x) \wedge i = r\} \bigvee_{r=0}^{b-1}\{(i, x, x') | \exists n \geq 0 (x' = \bar{f}^{a+r}(x) + n.M^{a+r}.\bar{f}^b(0)) \wedge (i = a + r + n.b)\}$

$f^* = \{(x, x'), \exists i \geq 0, x' = f^i(x)\} \Longleftrightarrow$
$\{(x, x'), \exists i \geq 0[(i, x, x') \in \bar{F} \wedge (\forall k(0 \leq k < i), \exists x'' \in G, (k, x, x'') \in \bar{F})]\}$

Faster acceleration ...

Convex translations [TACAS'04]

$f = (I_m, v, G)$ where I_m is the identity matrix and G convex

- No need to test if the predecessors are in the guard.
- The construction can be simplified.

Theorem [TACAS'04]

Convex acceleration is quadratic in $|\mathcal{A}(G)|$.

Faster acceleration ... complexity

parameter	magnitude	standard algorithm	convex algorithm
$\vert\mathcal{A}(G)\vert$	100.000	3-EXP	quadratic
m	5-50	3-EXP	EXP
$\vert v\vert_{max}$	≤ 10	3-EXP	poly. in m
$\vert M\vert_{max}$	≤ 10	3-EXP	$= 1$

Faster acceleration ... practice

$\mathcal{A}(f^*)$ = automaton representing f^* (transductor)

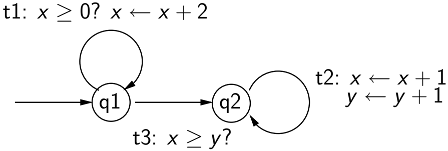
$\lvert\mathcal{A}(f^*)\rvert$	Time (seconds) Standard/Convex	Memory (MB) Standard/Convex
16,766	10/7	31/13
26,409	5/2	17/18
41,950	18/10	52/30
190,986 (TTP)	50/9	400/140
380,332 (TTP)	$\uparrow\uparrow\uparrow$/34	$\uparrow\uparrow\uparrow$/534
?	$\uparrow\uparrow\uparrow$/ >900	$\uparrow\uparrow\uparrow$/ >500

Outline

What is computable with circuit acceleration?

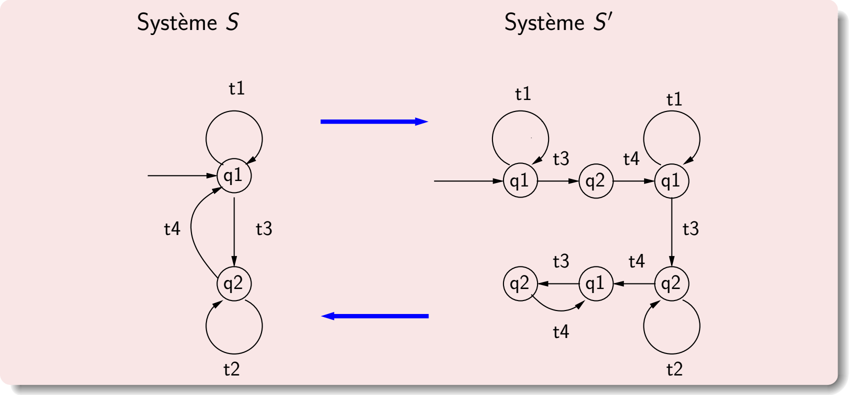
First answer

Flat system = at most 1 elementary circuit on each control node



Circuit acceleration + flat S = computation of $\mathrm{post}_S^*(X_0)$

Flattenings of non-flat systems



S' is a flattening of S iff
S' is flat and S simulates S'

Flattable Systems

(S, X_0) is flattable iff $\exists S'$ such that

- S' is a flattening of S
- S and S' are equivalent for reachability.

Theorem 1 [ATVA'05]

$\text{post}^*(X_0)$ is computable by circuit acceleration iff (S, X_0) is flattable.

Other characterization

A restricted linear regular expression (rlre) over T

$$\rho = w_1^* w_2^* \dots w_n^*, \text{ where } w_i \in T^*.$$

$\mathrm{post}(\rho, X)$ = configurations reachable following transitions in ρ

Theorem 2 [ATVA'05]

$\mathrm{post}^*(X_0)$ is computable by circuit acceleration iff $\exists$ a rlre ρ over T such that $\mathrm{post}^*(X_0) = \mathrm{post}(\rho, X_0)$.

Remark: $\mathrm{post}(\rho, X)$ is computable with circuit acceleration

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Selection Heuristic (I)

Input: (S, X_0)

1. $X \leftarrow X_0$; $k \leftarrow 0$
2. $k \leftarrow k + 1$
3. **Lunch**
4. If $\mathrm{post}(X) \subseteq X$ Goto 10
5. Enumerate the next ρ rlre over T
6. $X \leftarrow \mathrm{post}(\rho, X)$
7. Goto 4
8. **In parallel with**
9. **When** *Watchdog* stops **Goto** 2
10. Return X

maximal procedure: terminates iff (S, X_0) is flattable

PB1(time) find quickly a good rlre

PB2(space) avoid as much as possible unnecessary expensive steps of computations

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1. $X \leftarrow X_0$; $k \leftarrow 0$
2. $k \leftarrow k+1$
3. **Lunch**
4. If $\text{post}(X) \subseteq X$ Goto 10
5. *Choose* fairly $w \in T^{\leq k}$
6. $X \leftarrow \text{post}(w^*, X)$
7. Goto 4
8. **In parallel with**
9. **When** *Watchdog* stops **Goto** 2
10. Return X

The procedure is still maximal

PB1(time) partitioning + *Watchdog*

PB2(space) *Choose*

Selection Heuristic (II)

Results

The selection heuristic design is reduced to designing

- *Choose* (a standard solution is given)
- *Watchdog* (a standard solution is given)

The obtained procedure is then

- maximal
- efficient : good results on counter systems (cf. FAST)

Reductions

$|T|^{\leq k}$ may be exponential in k.

Idea = reduce $|T|^{\leq k}$ by removing redundant functions.

Three reductions:

- union-reduction [Finkel-Leroux 2002]
  - if $f = (M, v, G_1)$ and $g = (M, v, G_2)$,
  - let $h = (M, v, G_1 \vee G_2)$
  - then $(f+g)^* = h^*$
- commutation-reduction [CAV'03]
  - if f and g commute then $f^*g^* = (f \cdot g)^* = (g \cdot f)^*$
- conjugacy-reduction [ATVA'05]
  - $(f_2 \cdot f_3 \cdot f_1)^* = I_d + f_2 \cdot f_3 \cdot (f_1 \cdot f_2 \cdot f_3)^* \cdot f_1$

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Practical results

system	$\|T\|$	k	$\|C^{\leq k}\|$	U	Cm	Cj	U+Cm
csm	13	1	14	14	14	14	14
	13	**2**	183	**103**	**57**	**99**	35
consistency	8	1	9	9	9	9	9
	8	2	68	45	44	39	30
	8	**3**	484	**172**	**299**	**178**	98
swimming pool	6	1	7	7	7	7	7
	6	2	43	21	24	25	16
	6	3	259	56	114	97	28
	6	**4**	1555	**126**	**614**	**421**	47
	6	5	9331	252	3591	1977	86

U, Cm ,Cj : reductions (union, commutation, conjugacy)

Outline

The previous results are implemented in Fast

Fast works well in practice

- successfully verify 80% of 40 infinite systems [CAV'03].
- first automatic verification of TTP [TACAS'04]
- first automatic verification of CES

Technological comparison

	Alv	Lash	Fast	TReX
system	relational	affine		restricted
symb. rep	automata			arith. + pdbm *(undec.* $\sqsubseteq$*)*
acceleration	no	circuits		circuits *(partial.rec.)*
circuit selection		no	yes	yes, $\leq k$

Practical comparison

System	ALV	LASH	FAST	k	TREX
RTP (bounded)	T	T	T	1	T
Lamport (bounded)	T	T	T	1	T
Dekker (bounded)	T	T	T	1	T
ticket 2	T	T	T	1	T
kanban	↑	T	T	1	T
multipoll	↑	T	T	1	↑
prod/cons (2)	↑	T	T	1	-
ttp	↑	T	T	1	-
prod/cons (N)	↑	↑	T	2	-
lift control, N	↑	↑	T	2	T
train	↑	↑	T	2	T
csm, N	↑	↑	T	2	↑
consistency	↑	↑	T	3	-
swimming pool	↑	↑	T	4	↑
pncsa	↑	↑	↑	?	↑
incdec	↑	↑	↑	?	↑
bigjava	↑	↑	↑	?	↑

T: success within 20 minutes

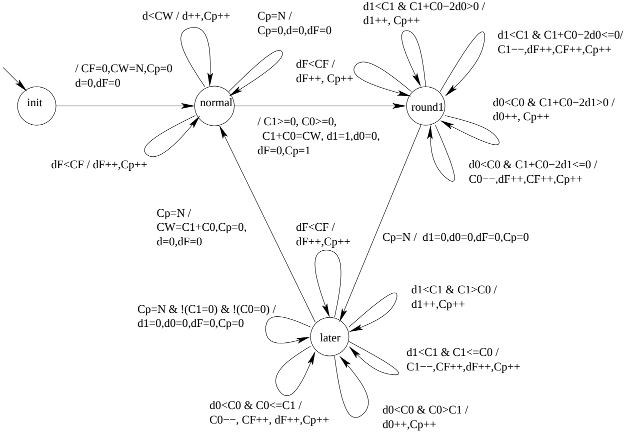
↑: no success within 20 minutes

k: circuit length for FAST

-: not an input of TREX

Outline

Verification of TTP by FAST



Verification of TTP by FAST

1 error [TACAS'04]

16 transitions, 9 variables, complex guards

- automatic verification
- Pentium 4 2.4 GHz, 1 Gbyte RAM : 940 sec. and 73 Mbytes.

Other tools:

- ALV does not terminate
- LASH terminates when good circuits are provided
- TTP does not fit TREX input model.

2 errors [TACAS'04]

20 transitions, 18 variables, even more complex guards

- standard acceleration does not work
- convex acceleration + overapproximation.

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The CES protocol - presentation

- Supported by Philips
- multimedia streaming
- ensures reliable communications over lossy channels

Jonathan Billington and Lin Liu [Billington-Liu 2002]

- Colored Petri net modeling of the CES,
- infinite system, counters and queues of parameterized length
- (complex) proofs of many properties of the CES (ex: size of the reachability set w.r.t. the buffer lengths)

The CES protocol - verification with FAST

Modeling issues

FAST does not handle queues.

- queues simulated by counters,
- correctness of the simulation is expressed as a reachability property of the counter system, and it is checked by FAST automatically.

Results

Properties proved in [Billington-Liu 2002] are checked easily.

Verification of pointer systems (work in progress)

Manual management of memory ressources (language C)

- memory heap = collection of memory cells
- a cell contains: data or address
- addresses $\in$ {valid, invalid, NULL}
- primitives: `new`, `free`, successor

Common errors

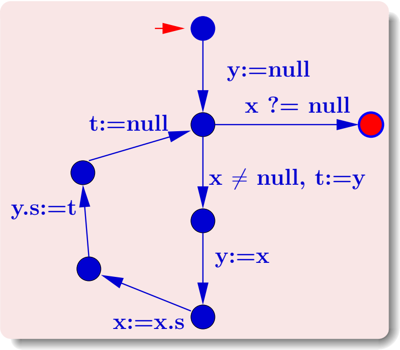
- memory violation
- memory leak

Work supported by EDF (2002-2004),
and by RNTL AVÉRILES (2005-2008)

Programs:

- only one successor (lists, no trees)
- no data, only pointers

```
List reverse(List x) {
  List y,t;
  y =NULL;
  while (x!=NULL) {
    t=y;
    y=x;
    x=x->n;
    y->n=t;
    t=NULL;
  }
  return y;
}
```



FAST and pointers

Verification of pointer systems [AVIS'06,AVIS'04]

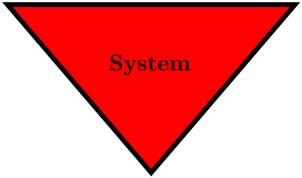
- Encode infinite sets of memory graphs by Presburger sets
- bisimulation between the pointer system and a counter system
- verification by FAST

A prototype is in progress (with A. Sangnier and É. Lozes)

- Works well for $\approx$ 10 small standard examples
- Both qualitative and quantitative properties
- Allows to check programs with counters + pointers

Outline

Our methodology



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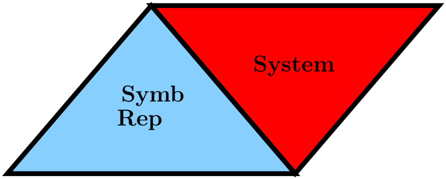

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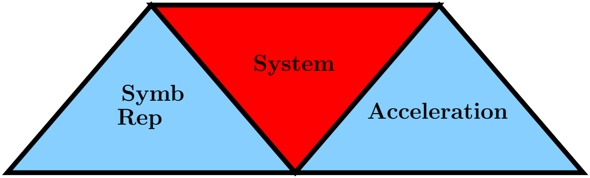

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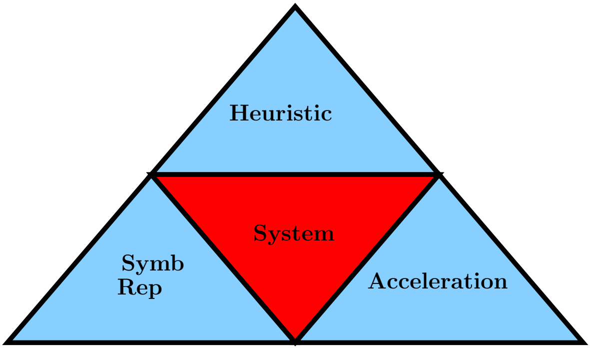

Results

1. Generic methodology [ATVA'05]
   - unified acceleration framework
   - power and limits (flattable systems)
   - maximal circuit selection
   - generic optimizations (reductions)
2. Instantiation to counter systems
   - two acceleration algorithms
     - *[Finkel-Leroux 2002]*
     - [TACAS'04]
   - *a reduction fit to counters [Finkel-Leroux 2002]*
   - The tool FAST

Results

3. Many experimentations
   - Counter systems
     - 40 infinite systems [CAV'03]
     - TTP [TACAS'04]
   - Counters + queues
     - CES (in my PhD thesis, work with Laure Petrucci)
     - *Stop and Wait Protocol [Billington-Gallasch-Petrucci 2005]*
   - Pointer systems
     - translation into counter systems [AVIS'06, AVIS'04]
     - prototype, works on 10 standard examples (work with Étienne Lozes and Arnaud Sangnier)

Perspectives

Short term

A new version FASTER is released [submission CAV'06]

- acceleration engine totally independent of the Presburger library
- a Presburger package based on shared automata and cache computation (Couvreur)
- a richer user language

Future works

Scale-up our methods: abstract-refine and checks methods

Timed counter systems? (TPN, TA + counters, ...)