Automated verification of cryptographic protocols: privacy-type properties

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Chapter 1

Introduction

1.1 Security challenge

Successfully exchanging secret information has always been a difficult and important task. Several issues arise when secretly communicating with someone from a distance. Can the sender be sure that the expected receiver of a message actually receives it? Was someone able to intercept the message, and if there is one, was he able to understand the message? Ensuring that such communication successfully holds can have a huge impact. For example, during the second world war, the German army used a machine, called Enigma, for the generals to encrypt and decrypt the orders they convey to their army. The allied forces spent huge amount of resources to gather information, codenamed Ultra by the British army, by breaking many messages that had been enciphered using the Enigma. Winston Churchill told King George VI after the war: “It was thanks to Ultra that we won the war”.

With the emergence of personal computers in the eighties and the internet in the nineties, privately and secretly conveying informations has become a problem in our daily life. All the international economy now goes through internet, most of the transactions of the stock market are done online and all banks provide services that allow a client to access his bank account, make transaction... over the internet.

This last decade also witnesses the raise of wireless technology. The number of electronic devices that communicate wirelessly in a single house increased drastically (e.g. smartphone, electronic tablet, computer, printer, internet box). Even though users profit from the multiple interactions between all the different devices, they also present serious security risks that are regularly reported by the media. For instance, in 2009, during the creation of the French governmental organisation Hadopi, concerns were raised in the public opinion about the capability of one to protect and prove the security of his wireless internet connection.

The emergence of small communication devices (e.g. RFID tags, mobile phone) that we carry almost all the time also raises the issue of traceability. Although the traceability of mobile phones is already part of the cinematographic folklore, recent work reveals that the current communication protocols between a mobile phone and its operator present major security flaws [AMR+12].

Even simple electronic devices might present a security risk. For example, the current paper passports also contain a RFID chip that stores the critical information printed on the passport. Such a passport is called an electronic passport or e-passport. It facilitates the checks at the airport border and also ensures the authenticity of the passport. Although there exists an international specification for such an electronic passport, parts of the implementation only depend on the country that delivers the passport. Hence, recent studies have highlighted that the first versions of the French electronic passports could be easily traced [ACRR10] whereas the English electronic passports were not subject to such a flaw.

The previous examples are not of course an exhaustive list of applications whose security are critical for the privacy of their users. In fact, new applications are still emerging in order to face
the society needs and present new security challenges. It is therefore crucial to ensure that the applications we use are indeed secured.

1.2 Cryptographic protocols

1.2.1 Cryptographic primitives

Until few decades ago, the transmission of secret information consisted of modifying a message using small algorithms so that it becomes unreadable to anyone but the sender and the intended receiver of this message by relying on a secret key that they agreed on before hand. A symmetric encryption algorithm allows the sender to encrypt his message using the shared secret key, whereas a symmetric decryption algorithm allows the reader to decrypt the cipher using the shared secret key (see Figure 1.1). Ideally, a third party cannot understand (or decrypt) the cipher if he does not know the secret key shared between the sender and the receiver. Several symmetric encryption schemes were invented over the years. One of the oldest is the Caesar cipher which was supposed to be used by Julius Caesar. Typically, this encryption scheme consists of replacing the letters in the text by shifting letters in the alphabet, the length of the shift being the encryption key. Hence, "hello world" would be encrypted into "khoor zrug" with the key 3, i.e. A → D, B → E, ..., Z → C. To decrypt this message, it suffices to reverse the shift of letters, i.e. D → A, E → B, ..., C → Z. This encryption scheme and the slightly more sophisticated methods were shown to be easily breakable by using statistical analysis.

\[
\text{the plain text} \rightarrow \text{encrypt} \rightarrow \text{the cipher text} \rightarrow \text{decrypt} \rightarrow \text{the plain text}
\]

\[M \rightarrow \text{encrypt} \rightarrow C \rightarrow \text{decrypt} \rightarrow M\]

\[k \rightarrow \text{the shared key} \rightarrow k\]

Figure 1.1: Symmetric encryption scheme

The security of a symmetric encryption scheme relies on the length of the key. Indeed, with the advent of powerful computers, an intruder might guess the shared secret key by trying every possibility, called a brute-force attack. In 1977, the United States Federal Information Processing Standard adopted the Data Encryption Standard (DES). While this encryption scheme was internationally used, this encryption method was shown to be vulnerable to brute-force attack due to the length of the keys. This encryption scheme was later on replaced by the AES (Advanced Encryption Standard) but DES is still used nowadays in several applications (e.g. ATM, email) usually in combination with an other encryption schemes.

One of the downsides of the symmetric encryption schemes is the key-management. Indeed, each pair of network members has to share a secret key, hence the number of required keys increases quadratically with the number of network members. Moreover, when two new members want to communicate, they first have to agree on the shared key, which can only be done if they already share some secret key or have access to a secure channel (e.g. by meeting face-to-face). Hence, this leads to the problem of "a dog chasing its tail". In 1976, W. Diffie and M. Hellman invented the notion of asymmetric encryption schemes. In such encryption schemes, each member of the network possesses a pair of keys, one private only known by the owner and used to decrypt ciphers, and the other one public shared to anyone in the network and used to encrypt messages (see Figure 1.2). Even though the keys are mathematically related, an intruder cannot deduce the private key of a member from its public key. For example, in the Diffie-Hellman asymmetric encryption...
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This encryption scheme, this property is ensured by the fact that the discrete logarithm problem is considered as difficult.

\[ M \xrightarrow{\text{encrypt}} C \xrightarrow{\text{decrypt}} M \]

\[ \text{the plain text} \quad \text{the cipher text} \quad \text{the plain text} \]

\[ \text{pk} \quad \text{sk} \]

\[ \text{the public key} \quad \text{the private key} \]

Figure 1.2: Asymmetric encryption scheme

This encryption scheme has the advantage to solve the problem of key-management since on the one hand, the number of required keys increases linearly in the number of network members and, on the other hand, two members do not have to agree on a shared key beforehand (they only have to send each other their own public key). Over the time, new asymmetric encryption schemes have been proposed such as RSA, invented by R. Rivest, A. Shamir, and L. Adleman in 1978.

However, the computational cost of most of the existing asymmetric encryption schemes is too high to be used in all applications (e.g., nobody would want to wait several minutes to get a 20 euros bill at the ATM). Thus, key-establishment protocols have been developed such as the Diffie-Hellman key exchange protocol [DH76]. In such protocols, two members of the network first communicate using an asymmetric encryption scheme in order to establish a fresh secret key for a symmetric encryption scheme e.g. AES. Once the shared key is established, the two members can communicate using the symmetric encryption scheme. These fresh secret keys are called symmetric session keys.

While the encryption schemes are designed to prevent anyone to understand a message unless the decryption key is known, another cryptographic primitive called digital signature was designed to demonstrate the authenticity of message. A valid signature gives some reason to believe that the message was created by a known sender, and was not altered during the communication. In 1985, T. Elgamal proposed a signature scheme based on discrete logarithms [Gam85], which is also based on a pair of public and private keys. Typically, a participant can sign a document using his private signing key and anyone can verify the signed document using the public key of the participant (see Figure 1.3). In contrast to the asymmetric encryption scheme, a signed document does not necessarily hide the content of the message.

\[ M \xrightarrow{\text{signature}} M_s \xrightarrow{\text{verification}} \text{ok} \]

\[ \text{the message} \quad \text{the signed message} \]

\[ \text{sk} \quad \text{pk} \]

\[ \text{the private key} \quad \text{the public key} \]

Figure 1.3: Digital signature scheme

Another cryptographic primitive called cryptographic hash function was designed to demon-
strate the integrity of a message. Typically, a hash function is a one-way function that takes an arbitrary message and returns a fixed-size bitstring, i.e., a sequence of 0 and 1. Ideally, one cannot recover the content of a message from its hash value. Moreover, an hash function should be collision resistant, i.e., it should be difficult to find two messages with the same hash value. Of course, this last property depends on the length of the bitstring returned by the hash function. Typical examples of hash functions used nowadays are the MD5 and SHA-1. Similar cryptographic primitives exist, called message authentication codes (or MAC), that allow one to authenticate the hash value thanks to a secret key.

The cryptographic primitives previously described are probably the most common primitives used in practice. In fact, these primitives are also the ones that will be used the most in this thesis. There exist several other primitives that are specific to an application such as blind signatures and trap door commitments for the electronic voting.

1.2.2 Protocols

Although it is essential to develop cryptographic primitives that are unbreakable, it is not sufficient to ensure the security of the whole communications between members of the networks. Even if an intruder is not able to break the cryptographic primitives, he can still gain some crucial knowledge or mislead a participant by intercepting, modifying and comparing the messages that are sent over the network. Hence it is crucial to analyse and verify not only the cryptographic primitives but also the complete communications between members of the network.

To that extend, we rely on cryptographic protocols that describe the computations and communications between the different participants. For illustration purposes, we consider the communication protocols specified by the International Civil Aviation Organisation (ICAO) standard [ICA04] and used for the electronic passports. In particular, the ICAO standard indicates that before anything else, the reader (e.g., a customs officer) has to recover some keys $ke$ and $km$ that are printed on the passport at the same page as the personal data and picture (usually, the customs officer recovers them by optically scanning the passport). Then the reader and the e-passport must execute the Basic Access Control (BAC) protocol in order to establish session keys to prevent skimming and eavesdropping on the subsequent communications with the e-passport. The Alice & Bob representation of this protocol is given in Figure 1.4.

![Figure 1.4: Basic Access Control protocol](image)

$senc(m, k)$ represents the application of a symmetric encryption scheme on the message $m$ with the secret key $k$. The choice of the symmetric encryption scheme is not relevant, as long
as it satisfies the desired properties. In fact, in the ICAO standard, the choice of the symmetric encryption scheme is up to the state implementing the electronic passport. $\text{mac}(m, k)$ represents a message authentication code of the message $m$ with the secret key $k$. $\langle m_1, \ldots, m_n \rangle$ represents the pairing of messages.

In this protocol, the participants proceed as follows: The reader starts by sending a challenge to the passport. Upon receipt of such a challenge, the passport creates a fresh nonce, i.e., a random bitstring, denoted $n_T$, and sends it to the reader. Once the reader receives $n_T$, he also creates two fresh nonces, denoted $n_R$ and $k_R$, and encrypts the pairing of the three nonces with the secret key $ke$. The reader then creates a MAC of the cipher using the secret key $km$ and sends both MAC and cipher to the passport. The passport first verifies the integrity of the message he received by computing himself a MAC of the cipher he received with the secret $km$ and comparing with the received MAC. Then it decrypts the cipher using the secret key $ke$ and retrieves the three nonces from the result of the decryption. After checking that the first nonce indeed corresponds to the nonce $n_T$ that it generated at the beginning, the passport generates a fresh nonce $k_T$ and sends back to the reader the encryption of the three nonces $n_T, n_R$ and $k_T$ by the secret key $ke$ with the MAC of such an encryption using the secret key $km$. After checking the integrity of the MAC, the reader checks the nonce $n_R$ and retrieves the nonce $k_T$ by decrypting the cipher with the secret key $ke$.

Hence at the end of such a protocol, both participants, i.e., the reader and the passport, know the values of the nonces $k_T$ and $k_R$ that will be used later on to extract key sessions. The security of such a protocol should be ensured by the checks of the MACs and the nonces $n_T$ and $n_R$ respectively by the passport and the reader.

### 1.2.3 Security properties

Verifying the security of a cryptographic protocol depends on the goal of such a protocol. For example, the ICAO standard indicates that the data in the e-passport cannot be accessed except by an authorised person or organisation. Hence, when describing a cryptographic protocol, it is crucial to properly describe the security properties that such a protocol is supposed to achieve. Although each cryptographic protocol might have its own security properties, there exist classical security properties that are grouped into two different families: the trace properties and the equivalence properties. Intuitively, the trace properties, such as authentication, specify that the protocols cannot reach a bad state, whereas the equivalence properties specify the indistinguishability of some instances of the protocols. In the literature, most of the work and tools focused on the trace properties. Fewer works focus on equivalence properties and even fewer tools can automatically verify equivalence properties. In this thesis, we will focus on equivalence properties and more specifically on the following ones:

**Anonymity** In most of protocols, there is no guarantee concerning the privacy of the participants. Typically, a participant disclosing his identity to an intruder is not considered as a flaw in the protocol. However, for some applications such as electronic voting, requiring that the identity of the voters cannot be disclosed is a necessity. Informally defined by the ISO/IEC standard 15408 [ISO09], anonymity is the property ensuring that a user may use a service or a resource without disclosing the his/her identity. The private authentication protocol [AF04], was specifically designed to ensure mutual authentication between participants but also to ensure the anonymity of the participants.

**Unlinkability** A protocol satisfying the anonymity property may still disclose informations on a user by allowing an intruder to track several uses of this protocol by the same user. Such informations might at the end allow the intruder to deduce or at least restrict the possible identities of a user. Unlinkability is the property ensuring that a user may make multiple uses of a service or a resource without others being able to link these uses together. For example, being able to track the different purchases of a user on an online-shop may reveal the habits of a user. In an
other area, the French subway company of Paris provides cards that contain RFID chip to their clients in place of the underground tickets. However, if the protocol used to communicate with the RFID chip does not satisfy the unlinkability property then an intruder might be able to track the daily movement of a user thus deducing for example his place of residence or workplace. The Basic Access Control protocol on e-Passports was designed, according to the ICAO standard, to make the passports unlinkable.

1.3 Difficulties of security verification

Verifying the security of a cryptographic protocol is a difficult task. Compared to trace properties, verifying equivalence properties is even more difficult.

1.3.1 General difficulties

The degree of security that we verify on a protocol is directly correlated to the capabilities (or power) that we give to the intruder. As such, verifying a security property for a passive intruder (i.e. when the intruder can only eavesdrop the communications between the participants) provides less guarantees on the security than the case where we consider an active intruder (i.e. when the intruder can intercept and modify the communications between the participants). However, the more capabilities we give to the intruder, the more difficult it is to verify some security property on a protocol. In fact, in the general case, deciding whether a protocol satisfies some security property is undecidable ([DLMS99, AC02]) which is mainly due to the many sources of unboundedness in the modelling of the capabilities of the intruder. We describe below some of these sources.

Number of sessions When verifying the security of a protocol, it is reasonable to consider that the attacker can interact with any number of sessions of the protocol. In the case of the e-passport protocol, the number of sessions would correspond to the number of people going through customs which is usually a lot in any airport. However, since considering unbounded number of sessions usually leads to undecidability, many works present decidability result for verification of security properties for a bounded number of sessions of the protocol [MS01, Bau05, CD09a]. Note that even when considering a bounded number of sessions, verifying the security of a protocol is still difficult since an intruder can intercept messages and replace them by any message that he can compute himself, which represent an infinite number of messages.

Cryptographic primitives As previously mentioned, there exists many different cryptographic primitives, all of them having different behaviours, and some being more difficult to model than others. For example, it is more difficult to verify some security property on a protocol that relies on blind signatures rather than a protocol relying on symmetric encryption only. As such, decision procedures usually fix or at least limit the number of cryptographic primitives they can handle.

Environment Most of the time, security properties are ensured when considering the cryptographic protocol in isolation. Indeed, no one can predict all the protocols that are running on a network at the same time. Furthermore, real life protocols are usually complex and composed of several sub-protocols that rely on the same cryptographic material. For example, the UMTS standard [3GP11, 3GP10a, 3GP10b] specifies tens of sub-protocols running in parallel in 3G mobile phone systems. And, while one may hope to automatically verify each of these sub-protocols in isolation, it is unrealistic to expect that the whole suite of protocols can be automatically checked.

On the other hand, we still want some guarantees on the security of the protocols when placed in an environment with other protocols running at the same time, hence the need for secure composition of cryptographic protocols. Whereas securely composing protocols when they do not share any secret is an easy task, it is unrealistic to assume that a user always uses a different password for each protocol. Even if it was the case, some applications rely, as previously mentioned, on several sub-protocols that share passwords by construction.
1.3.2 Specificities of equivalence properties

As previously mentioned, equivalence properties intuitively indicate the indistinguishability of some instances of the protocol whereas trace properties indicate that the protocol cannot reach a bad state. More formally, when verifying a trace property, we have to verify that any execution of the protocol cannot reach a bad state. On the other hand, when verifying an equivalence property, we have to verify that for any execution of one of the instances of the protocol there exists an indistinguishable execution of the other instance of the protocol. Hence, the alternation of quantifiers makes even more difficult the verification of equivalence properties.

Even the modelling of indistinguishability is a difficult task and requires an extensive knowledge of the capabilities of the intruder. Indeed, depending on what a real intruder can observe (e.g. messages sent over the network, internal computation of honest participants), two executions might not always be considered as indistinguishable. Therefore in the literature, several notions of indistinguishability have been proposed (e.g. trace equivalence, may-equivalence, observational equivalence [MNP02, AG99, AF01]) and the question of knowing which notion is best-suited to model an intruder is disputable.

1.4 Automatic verification using symbolic models

One of the first tasks when verifying the security of a cryptographic protocol is to create a model that represents the behaviour of the protocol and also the behaviour of an intruder.

1.4.1 Existing models

Early in the eighties, two different kinds of models emerge. This first ones, called computational models, consider the messages sent over the network as bitstrings. Moreover, the behaviour of the intruder is modelled as any probabilistic polynomial-time Turing machine. The cryptographic primitives are also represented as polynomial algorithms. These models, since they are close to the reality, offer strong guarantees on the security of cryptographic protocols. However, the proofs are usually difficult, error prone and are almost impossible to automate.

In the second kind of models, called symbolic models, the behaviour of the protocols and intruders are abstracted. Typically, the messages are abstracted by terms and the cryptographic primitives, assumed to be perfect (i.e. unbreakable), are abstracted by function symbols, hence symbolic models are much simpler than computational models. As such, the verification of security properties on a protocol using a symbolic model also becomes simpler and can be automated. In the literature, there exists dozens of symbolic models, (e.g. spi-calculus [AG99], strand space [FHG99]) that usually correspond to the need of a specific application or a theoretical result. For example, symbolic models based on constraint systems (e.g. [MS01, CLS03]) were shown to be well-adapted to deal with a bounded number of sessions whereas symbolic models based on Horn clauses (e.g. [Wei99, Bla01, CLC03]) are more adapted to an unbounded number of sessions.

However, because of these abstractions, the guarantees provided by the verification of a security property using symbolic models is usually weaker than the guarantees provided by the verification of the same security property using computational models. Typically, whereas an attack in symbolic models implies an attack in computational models, the converse is not necessary true. Hence when creating a cryptographic protocol, one could first rely on the automatic tools offered by symbolic models to quickly detect possible attacks and so modify accordingly the protocol. Then when no more attack is detected by symbolic models, one can rely on a computational model to conclude. Recently, several works have attempted to derive conditions under which the symbolic security implies the computational security, starting with M. Abadi and Ph. Rogaway in 2000 [AR00]. Although the first results mainly targeted trace properties, H. Comon-Lundh and V. Cortier [CC08] showed that computational indistinguishability in presence of an active intruder is implied by the observational equivalence of the corresponding symbolic protocol. This research area is crucial since it allows one to use the automatic tools developed in the symbolic models to obtain the strong securities of the computational models.
1.4.2 Existing results

As previously mentioned, verifying the security of a cryptographic protocol is a difficult task even in symbolic models. Thus, all existing decidability results always consider restrictions of some sort. The most common one consists of bounding the number of sessions of the protocol. Other restrictions consist of fixing the cryptographic primitives that are considered or even studying stronger notions of indistinguishability than the one modelling the capabilities of the intruder (e.g. by giving too much power to the intruder) in the case of equivalence properties.

Automating the decision of equivalence properties. The automated verification of equivalence properties for security protocols was first considered in [Hut02] (within the spi-calculus). [Bau05, CD09a] gives a decision procedure for the trace equivalence of bounded deterministic processes. In particular, the processes are restricted to be determinate and do not contain (non trivial) conditional branching. Furthermore, the procedure seems not be well-suited for an implementation. [CR12] gives a decision procedure for the trace equivalence of bounded processes for a class of primitives (that are defined by a subterm convergent rewrite system). The procedure is probably not well-suited for an implementation. Furthermore, again only determinate processes and trivial conditional branching are allowed.

Tools. Several techniques and tools have been designed for the formal verification of cryptographic protocols. For instance CSP/FDR [RSC+00], ProVerif [Bla01], Scyther [Cre08], AVISPA [Vig06] and others. However, most results and tools only consider trace properties. To our knowledge, there are only three tools that can handle equivalence properties: ProVerif [Bla01], SPEC [TD10] and AKiSS [Cio11]. Note that the last two tools were built in parallel of this thesis thus ProVerif was the only existing tool at the beginning of this thesis.

The tool ProVerif [Bla01] originally was designed to prove trace properties but it can also check some equivalence properties (so-called diff-equivalence) [BAF08] that are usually too strong to model a real intruder. Note that this is the only tool that can handle an unbounded number of sessions of a protocol with a large class of cryptographic primitives in practice. However, ProVerif is not a decision procedure in the sense that it may not terminate, especially if the equational theory modelling the cryptographic primitives is complex such as exclusive-or. Nevertheless, this tool was used by several researchers to prove the security properties of protocols (e.g. proving the absence of guessing attacks in EKE or proving the core security of JFK [BAF08], privacy properties for electronic voting protocol [DKR09]).

The tool SPEC [TD10] gives a decision procedure for open-bisimulation for bounded processes in the spi calculus. This procedure has been implemented. The scope is however limited: open-bisimulation coincides with trace equivalence for determinate processes only and the procedure also assumes a fixed set of primitives (symmetric encryption and pairing), and a pattern based message passing, hence, in particular, no non-trivial conditional branching.

More recently, the tool AKiSS [Cio11] was developed in order to decide the trace-equivalence of bounded processes that do not contain non-trivial conditional branching. Although this tool was proved to be sound and complete, the algorithm was only conjectured to terminate for subterm convergent equational theory.

Composition results. As previously mentioned, verifying some security property when considering several protocols running at the same time is usually too difficult, even when relying on the automatic tools previously presented. Indeed, each tool requires a lot of computation time to prove some equivalence properties, without taking into consideration the cases of non-termination. Hence, there are a number of papers studying the secure composition of security protocols in symbolic models (e.g. [GT00, CC10]) and in computational models (e.g. Can01, KT11). Actually, a lot of results have been established for trace-based security properties, e.g. [GT00, ACS+08, MV09, CC10].
1.5. LIMITATIONS OF EXISTING RESULTS

Regarding equivalence-based properties, it has been shown that composition works for resistance against guessing attacks in the passive case without any additional hypothesis [DKR08], and in the active case when the protocols are tagged [DKR08, CDK11].

Other works study universal composability of protocols [Can01]. This approach consists of defining for each sub-protocol an ideal functionality and then showing that a certain implementation securely emulates the ideal functionality. Since this initial work, the universal composability framework has been improved in several ways, e.g. with joint states [BCNP04], without pre-established session identifiers [KT11].

1.5 Limitations of existing results

Despite all the existing results, none of them can decide equivalence properties such as unlinkability on the Basic Access Control protocol described in Section 1.2.2. Moreover, the ICAO standard indicates that after a successful execution of the BAC protocol, several other sub-protocols can be executed in any order. However, no existing composition result can handle unlinkability for such sub-protocols. Indeed, the previous composition results in symbolic models [DKR08, CDK11] assume that passwords are the only shared secrets and are not well-suited to analyse privacy-type properties such as unlinkability. Hence the need to study the secure composition of protocols for privacy-type properties.

Furthermore, from all the decision procedures (implemented or not) we described in the previous section, only ProVerif is able to handle non-trivial conditional branching. However, coming back to the Basic Access Control (BAC) protocol, the ICAO standard indicates that if the passport fails to check the MAC or the value of the nonce $n_T$ then it must output an error message. On the other hand, it does not specify what the error message should be. Since the output of an error message implies some non-trivial conditional branching in the protocol, only ProVerif can take as input the Basic Access Control protocol.

One could argue that such error messages could be dismissed of the BAC protocol when verifying some security properties but [ACRR10] showed that the early versions of French passports did not satisfy the unlinkability property due to these error messages.

**Attack on the French e-passport.** [ACRR10] experimented on French, English, German, Russian and Irish e-passports and discovered that for all of these passports but the French ones, an error code "6300" is sent over the network when the check of the MAC or the nonce $n_T$ fails. However, in the case of the French passports, [ACRR10] indicates that an error code "6300" is sent when the check of the MAC fails and a different error code "6A80" is sent when the check of the value of $n_T$ fails. The difference between these two error codes yields an attack on the unlinkability property. The intruder proceeds as follows:

First the intruder eavesdrops an execution of the BAC protocol between a reader and the passport he wants to track. Thus, from this execution, he obtains the message $\langle m, \text{mac}(m, km_p) \rangle$ that was send by the reader to the passport where $m = \text{senc}(\langle n_R, n_T, k_{R_p} \rangle, ke_p), ke_p, km_p$ being the keys of the targeted passport and $n_T$ is the random nonce generated by this passport. Then, when a new passport comes along, the intruder plays the role of a reader by sending a challenge to this passport. After discarding the freshly generated nonce that the passport sent and denoted $n'_T$, the intruder replays the message $\langle m, \text{mac}(m, km_p) \rangle$. When receiving this message, the new passport will necessary send an error message since either this passport is not the targeted passport (i.e the check of the MAC will fail) or the check of the nonce $n'_T$ will fail ($n_T$ being different from $n'_T$). However, in the case of French passports, if the error code "6A80" is outputted then it means that the check of the MAC succeeds and so the key used to compute the MAC is the key $km_p$ of the targeted passport. Thus by checking if the error code is either "6A80" or "6300", the intruder can determine when the targeted passport executes the BAC protocol.

[ACRR10] showed that English passports satisfy the unlinkability property. It is therefore crucial to include the error message in the description of the protocol thus to consider non-trivial
conditional branching, which discards all the existing procedures other than ProVerif. However, the notion of equivalence decided by ProVerif is stronger than the usual behavioural equivalence used to model the unlinkability property. Thus, ProVerif will fail to prove unlinkability on English passports and yield a false attack. Even in the case of French passports, ProVerif also yields a false attack.

In fact, these limitations are not specific to the e-passport protocol and can be found in several case studies, e.g. the private authentication protocol [AF04] and the mobile telecommunication protocols [AMR+12].

1.6 Contributions

This thesis is organised in three parts. In Part I, we study the privacy-type properties in the applied pi calculus which are modelled by an equivalence between processes and we show that the equivalence between processes compose well, provided some conditions on the protocols. In Part II, we show that deciding the equivalence between processes is possible for a class of bounded protocols with standard primitives. At last, in Part III we propose an extension to the existing tool ProVerif that removes some specific false attacks. We detail our contributions below.

1.6.1 Privacy-type properties in the applied pi calculus

In Chapter 3 we show how equivalence properties of cryptographic protocols can be expressed in the applied pi calculus [AF01] by means of a behavioural equivalence on processes. More specifically, we formalise the resistance to guessing attack, strong secrecy, anonymity and unlinkability properties, and we provide with concrete examples of cryptographic protocols to illustrate the equivalence properties. In particular, we describe in detail the different protocols that compose the e-passport protocol and show how anonymity and unlinkability are expressed in this protocol.

We also show the relations between classical behavioural equivalences, i.e. trace equivalence, observational equivalence and may-testing equivalence. More specifically, we show that although may-testing equivalence and trace equivalence are two very close notions, they are not equivalent. We prove that trace equivalence indeed implies may-testing equivalence but we provide with an example of processes that are may-testing equivalent but not trace equivalent. However, we show that trace equivalence and may-testing equivalence coincide for image-finite processes (e.g. processes without replication).

1.6.2 Composing trace equivalence in a modular way

The last chapter of Part II is devoted to the study of the preservation of trace equivalence under parallel composition of processes. We identify sufficient conditions of disjointness, under which protocols can “safely” be executed in parallel. We first state a composition result that also allows the protocols to share the usual cryptographic primitives of symmetric and asymmetric encryption, hashing, and signing, provided that these primitives are tagged and that public and verification shared keys are not derivable. In this setting, we are able to establish a strong result that basically says that the disjoint scenario, i.e. where protocols do not share any secret, is equivalent to the shared one, i.e. where protocols share some secrets. This allows us to go back to the disjoint case for which composition works unsurprisingly well.

Then, we further relax this condition. A second theorem shows that it is possible to compose protocols that share public and verification keys even if those are known by the attacker, provided that they are given to him from the beginning. However, in our setting such a sequence has to be finite, and thus our result can only be applied in presence of a bounded number of public shared keys. This is not a real limitation for the analysis of the e-passport application, but this could lead us to an unrealistic situation for some other applications.
1.6.3 A decision procedure for trace equivalence

Part II is dedicated to a decision procedure for the trace equivalence between bounded processes. We allow processes with non-trivial else branches and non-deterministic choice. Our procedure is sound, complete and always terminate. In contrast to the tools ProVerif and AKiSs, our algorithm only accepts a fixed set of primitives other than one-way functions, namely symmetric and asymmetric encryption, digital signature and pairing. In addition, any one-way function is accepted such as hash function. The behaviour of our cryptographic primitives are expressed using rewriting systems and we assume that our destructors may fail.

In Chapter 6, we reduce the problem of trace equivalence to the problem of symbolic equivalence between sets of constraint systems. A similar reduction is done in Chapter 4 for the applied pi calculus. Due to the restricted sets of cryptographic primitives we consider, we show, in Chapter 6 that it is possible to refine the symbolic equivalence by only considering canonical actions of the intruder. In Chapter 7 we detail the procedure for deciding the symbolic equivalence between sets of constraint systems. The general idea of our algorithm consists of simplifying the constraint systems until we reach sets of constraint systems that are simple enough to easily decide the symbolic equivalence. Chapter 5 is dedicated to the proofs of soundness, completeness and termination of our decision procedure of symbolic equivalence between sets of constraint systems.

Thanks to our algorithm, we are now able to automatically prove the anonymity and unlinkability properties on the e-passport protocol [ACRR10], or the anonymity property on the private authentication protocol [AF04] for a bounded number of sessions. An Ocaml implementation of an early version of the procedure described in Part II has already been completed and concludes within a few minutes for the private authentication protocol. The final implementation of the decision procedure is still ongoing.

1.6.4 Proving more observational equivalences with ProVerif

As previously mentioned, due to the presence of non-trivial conditional branchings in the BAC protocol and the private authentication protocol, ProVerif yields false attacks when verifying the unlinkability and anonymity properties respectively on such protocols. However, since ProVerif is currently the only tool that can handle an unbounded number of sessions, we address the issue of these particular false attacks and propose an extension of the ProVerif tool in Chapter 9.

The general idea of our extension is to transform before hand the input processes by simplifying their control structure. To do so, we extend the behaviour of destructor function symbols so that the tests previously performed by conditional branchings will now be performed directly inside terms. We show in Chapter 9 how the original algorithm of ProVerif [BAF08] is adapted to our new framework. Moreover, we propose an algorithm to automatically simplify the input processes when such a simplification is possible.

Relying on an ongoing implementation of our extension, we can now automatically prove that the private authentication protocol satisfies its desired anonymity property for an unbounded number of sessions. However, even with our extension, ProVerif still cannot prove the unlinkability property for the BAC protocol and yields a new false attack.

1.7 Research Publications

Almost all the results obtained in this thesis have been published or submitted for publication. The results on ProVerif (Chapter 9) should be submitted this fall.

Journals

CHAPTER 1. INTRODUCTION

Conferences


Other


Tools

• V. Cheval. ADECS, a tool for deciding symbolic equivalence between two constraint systems for a fixed set of cryptographic primitives
  
  [http://www.lsv.ens-cachan.fr/~cheval/program/adecs/](http://www.lsv.ens-cachan.fr/~cheval/program/adecs/)

  The implementations of the extension of ProVerif (Chapter 9) and the decision procedure for trace equivalence described in Part II are still under development.
Chapter 2

Preliminaries

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In this chapter, we review several standard definitions and concepts that we will use in this thesis.

2.1 Term Algebra

One starts with an infinite set of names, denoted \( \mathcal{N} = \{ a, b, \ldots, sk, n, m \ldots \} \), which are used to model atomic data, e.g. random numbers. We also define an infinite set of variables, denoted \( \mathcal{X} = \{ x, y, \ldots, X, Y, \ldots \} \).

Let \( \mathcal{F} \) be a signature, i.e. a finite set of function symbols. Let \( \text{ar} : \mathcal{F} \to \mathbb{N} \) be the function that associates to a function symbol a natural number, called arity. We call constant any function symbol of arity 0.

We define a set of types, sometimes called sorts, denoted \( \text{Type} = \{ \text{base, channel, key, \ldots} \} \). We define a type system that associates to each variable and each name a type, and that associates to each function symbol the types of its arguments and return value, denoted \( n : s, x : s \) and \( f : s_1 \times \ldots \times s_k \to s \), where \( n \in \mathcal{N}, x \in \mathcal{X}, f \in \mathcal{F} \) with \( \text{ar}(f) = k \), and \( s, s_1, \ldots, s_k \in \text{Type} \).

Terms are defined as names, variables, and function symbols applied to other terms. Let \( \mathcal{N} \subseteq \mathcal{N}, \mathcal{X} \subseteq \mathcal{X} \) and \( \mathcal{F} \subseteq \mathcal{F} \) the set of terms built from \( \mathcal{N} \) and \( \mathcal{X} \) by applying the function symbols in \( \mathcal{F} \) is denoted by \( \mathcal{T}(\mathcal{F}, \mathcal{N} \cup \mathcal{X}) \). Formally, \( \mathcal{T}(\mathcal{F}, \mathcal{N} \cup \mathcal{X}) \) is the smallest set such that:

- \( \mathcal{X} \cup \mathcal{N} \subseteq \mathcal{T}(\mathcal{F}, \mathcal{N} \cup \mathcal{X}) \)
- for all \( f \in \mathcal{F} \), if \( \text{ar}(f) = k \) and \( f : s_1 \times \ldots \times s_k \to s \) then for all \( t_1 : s_1, \ldots, t_k : s_k \in \mathcal{T}(\mathcal{F}, \mathcal{N} \cup \mathcal{X}) \), we have that \( f(t_1, \ldots, t_k) : s \in \mathcal{T}(\mathcal{F}, \mathcal{N} \cup \mathcal{X}) \).

We say that the set \( \mathcal{T}(\mathcal{F}, \mathcal{N} \cup \mathcal{X}) \) is untyped when each term in the set have the same type. In such a case, the types are omitted for the sake of simplicity.

The size of a term \( t \), denoted \(|t|\) is defined recursively as follows:

- if \( t \in \mathcal{N} \cup \mathcal{X} \) then \(|t| = 1\)
- if \( t = f(t_1, \ldots, t_k) \) with \( f \in \mathcal{F} \) and \( \text{ar}(f) = k \) then \(|t| = 1 + \sum_{i=1}^{k} |t_i|\)
CHAPTER 2. PRELIMINARIES

Example 2.1. Consider the following untyped signature

$$\mathcal{F} = \{\text{senc}/2, \text{sdec}/2, \text{pk}/1, (\cdot)/2, \pi_1/1, \pi_2/1, h/1\}$$

that contains function symbols for asymmetric encryption, decryption and pairing, each of arity 2, as well as projection symbols and the function symbol \(\text{pk}\), each of arity 1. The ground term \(\text{pk}(sk)\) represents the public counterpart of the private key \(sk\).

Let \(a, b, ska \in \mathcal{N}\), we have that \((\text{senc}(a, \text{pk}(ska)), b)\) is a ground term of \(\mathcal{T}(\mathcal{F}, \mathcal{N})\).

The set of positions of \(t\), denoted \(\mathcal{P}\os{os}(t)\), is a set of word over the alphabet of positive integers, defined recursively such that:

- if \(t \in \mathcal{N} \cup \mathcal{X}\) then \(\mathcal{P}\os{os}(t) = \{\varepsilon\}\)
- if \(t = f(t_1, \ldots, t_k)\) with \(f \in \mathcal{F}\), then \(\mathcal{P}\os{os}(t) = \{\varepsilon\} \cup \bigcup_{i=1}^{k} \{i \cdot p \mid p \in \mathcal{P}\os{os}(t_i)\}\)

where \(\cdot\) is the concatenation operator. For all \(p \in \mathcal{P}\os{os}(t)\), we denote by \(t|_p\) the subterm defined by induction on the length of \(p\) such that:

- if \(p = \varepsilon\) then \(t|_p = t\)
- if \(p = i \cdot q\) and \(t = f(t_1, \ldots, t_k)\) then \(t|_p = t_i q\)

We denote by \(\text{root}\) the function that associates to each term \(t \in \mathcal{T}(\mathcal{F}, \mathcal{N} \cup \mathcal{X})\) the function symbol at position \(\varepsilon\) (root position) in \(t\). For \(t \in \mathcal{N} \cup \mathcal{X}\), we define \(\text{root}(t) = \bot\), where \(\bot\) is a new symbol.

The set of subterms of a term \(t\), denoted \(\mathcal{S}\os{t}(t)\), is the set such that

$$\mathcal{S}\os{t}(t) = \{u \mid \text{there exists } p \in \mathcal{P}\os{os}(t) \text{ such that } t|_p = u\}$$

The set of variables of a term \(t\), denoted \(\mathcal{V}\os{ars}(t)\), is the set such that

$$\mathcal{V}\os{ars}(t) = \{x \in \mathcal{X} \mid \text{there exists } p \in \mathcal{P}\os{os}(t) \text{ such that } t|_p = x\}$$

We say that \(t\) is a ground term when \(\mathcal{V}\os{ars}(t) = \emptyset\). The set of names of a term \(t\), denoted \(\mathcal{N}\os{ames}(t)\), is the set such that

$$\mathcal{N}\os{ames}(t) = \{n \in \mathcal{N} \mid \text{there exists } p \in \mathcal{P}\os{os}(t) \text{ such that } t|_p = n\}$$

These sets can be extended to any structure that contain terms.

A \((k-)\)-context \(C\) is a term in \(\mathcal{T}(\mathcal{F}, \mathcal{N} \cup \mathcal{X}) \cup \{-_1, \ldots, -_k\}\) such that for all \(i \in \{1, \ldots, k\}\), \(-_i\) appears at most once in \(C\). Given a \(k\)-context \(C\), and \(t_1, \ldots, t_k\) terms, we denote by \(C[t_1, \ldots, t_k]\) the terms \(C\) where we replace \(-_i\) by \(t_i\) for each \(i \in \{1, \ldots, k\}\).

2.2 Unification

A substitution is a function \(\sigma : \mathcal{X} \rightarrow \mathcal{T}(\mathcal{F}, \mathcal{N} \cup \mathcal{X})\). Given a variable \(x\) and a substitution \(\sigma\), we denote by \(x \sigma\) the application of \(\sigma\) on \(x\). We extend the application of a substitution to term or any structure that contains variables in the expected manner. Given two substitutions \(\sigma_1\) and \(\sigma_2\), we denote by \(\sigma_1 \sigma_2\) the composition of \(\sigma_1\) and \(\sigma_2\), i.e. for all \(x \in \mathcal{X}\), \(x \sigma_1 \sigma_2 = (x \sigma_1) \sigma_2\).

The domain of a substitution \(\sigma\) is the set \(\{x \in \mathcal{X} \mid x \sigma \neq \sigma\}\), denoted \(\text{dom}(\sigma)\). The image of a substitution \(\sigma\) is the set \(\{x \sigma \mid x \in \text{dom}(\sigma)\}\). The identity substitution, denoted \(\text{id}\), is the only substitution with empty domain.

Let \(\mathcal{X} \subset \mathcal{X}\) and a substitution \(\sigma\). The restriction of \(\sigma\) to \(\mathcal{X}\) is the substitution denoted \(\sigma|_{\mathcal{X}}\) (or \(\sigma|_{\mathcal{X}}\)) such that \(\text{dom}(\sigma|_{\mathcal{X}}) = \mathcal{X} \cap \text{dom}(\sigma)\) and for all \(x \in \text{dom}(\sigma|_{\mathcal{X}})\), \(x \sigma = x \sigma|_{\mathcal{X}}\).

We adopt the notations \(\{x_1 \mapsto t_1; \ldots; x_n \mapsto t_n\}\) and \(\{t_1/x_1; \ldots; t_n/x_n\}\) to represent a substitution \(\sigma\) of domain \(\{x_1, \ldots, x_n\}\) and such that \(x_i \sigma = t_i\), for \(i = 1 \ldots n\).
A variable renaming is a bijection $\rho$ from $\mathcal{X}$ to $\mathcal{X}$. Note that a variable renaming is a substitution such that $\text{img}(\rho) = \text{dom}(\rho)$.

A name renaming is a bijection $\sigma$ from $\mathcal{N}$ to $\mathcal{N}$. Similarly to substitutions, the application of $\rho$ on a name $n$ is denoted $n\rho$. We extend the application of a renaming to any structure that contains names in the expected manner. The domain of a name renaming $\sigma$, denoted $\text{dom}(\sigma)$, is the set $\{ n \in \mathcal{N} \mid n\sigma \neq n \}$. The image of a name renaming $\rho$, denoted $\text{img}(\rho)$, is the set $\{ x\rho \mid x \in \text{dom}(\rho) \}$. Note that $\text{img}(\rho) = \text{dom}(\rho)$.

Two terms $t_1, t_2 \in T(\mathcal{F}, \mathcal{N} \cup \mathcal{X})$ are unifiable if there exists a substitution $\sigma$ such that $t_1\sigma = t_2\sigma$. In such a case, the substitution $\sigma$ is a unifier of $t_1$ and $t_2$.

Given a finite set of equation between terms $S = \{ t_1 = s_1; \ldots; t_n = s_n \}$, we say that a substitution $\sigma$ is a unifier of $S$ if $t_i\sigma = s_i\sigma$ for $i = 1 \ldots n$. Moreover, a substitution $\sigma$ is the most general unifier of $S$, denoted $\text{mgu}(S)$, if

- $\text{vars}(\text{img}(\sigma)) \subseteq \text{vars}(S)$; and
- $\sigma$ is a unifier of $S$; and
- for all substitution $\sigma'$, $\sigma'$ is a unifier of $S$ implies that there exists a substitution $\tau$ such that $\sigma' = \sigma'\tau$.

In case $S$ contains only one equation, i.e. $S = \{ t = s \}$, we might denote the most general unifier of $S$ by $\text{mgu}(t = s)$ or $\text{mgu}(t, s)$. Moreover, we might sometimes use the symbol $\equiv$ instead of $=$.

### 2.3 Equational theory

An equational theory is an equivalence relation on terms of $T(\mathcal{F}, \mathcal{X} \cup \mathcal{N})$ that is closed under application of contexts, closed under substitutions of terms for variables and closed under name renaming. In most cases, an equational theory is derived from a finite set $E$ of equations between terms of $T(\mathcal{F}, \mathcal{X})$. In such a case, we denote by $=_E$ the smallest equational theory containing $E$.

A slight abuse of language is usually done and we say that $E$ is an equational theory. Given two terms $s$ and $t$, we say $s$ and $t$ are equal modulo the equation theory $E$ when $t_1 =_E t_2$.

**Example 2.2.** Consider the signature $\mathcal{F}$ of Example 2.1. We define the equational theory $E_{\text{aenc}}$ by the following equations:

$$\text{aenc}(\text{aenc}(x, \text{pk}(y)), y) = x \quad \pi_i(\langle x_1, x_2 \rangle) = x_i \text{ for } i \in \{1, 2\}.$$

The first equation represents asymmetric decryption whereas the second one represents the first and second projections of the pair. For example, we have that $\pi_1(\text{aenc}(\text{aenc}(\langle n_1, n_2 \rangle, \text{pk}(sk)), sk)) =_{E_{\text{aenc}}} n_1$.

In this thesis, we always consider that an equation theory is $E$ is consistent, i.e. there exist terms $s$ and $t$ such that $s \neq_E t$.

### 2.4 Rewriting systems

A rewriting system $\mathcal{R}$ is a set of rewrite rules $\ell \rightarrow r$ such that $\ell \in T(\mathcal{F}, \mathcal{X}) \cup \mathcal{X}$ and $r \in T(\mathcal{F}, \text{vars}(\ell))$. A term $s$ is rewritten into $t$ by a rewriting system $\mathcal{R}$, denoted $s \rightarrow_\mathcal{R} t$ if the there exists a rewrite rule $\ell \rightarrow r \in \mathcal{R}$, a position $p \in \text{Pos}(s)$ and a substitution $\sigma$ such that $s|_p = \ell\sigma$ and $t = s |_{\sigma(p)}$. The reflexive transitive closure of the relation $\rightarrow_{\mathcal{R}}$ is denoted by $\rightarrow_{\mathcal{R}}^\ast$.

A rewriting system $\mathcal{R}$ is subterm if for all $\ell \rightarrow r \in \mathcal{R}$, $r$ is a subterm of $\ell$, i.e. $r \in \text{st}(\ell)$.

A rewriting system $\mathcal{R}$ is confluent if for all terms $s, u, v$ such that $s \rightarrow_{\mathcal{R}}^\ast u$ and $s \rightarrow_{\mathcal{R}}^\ast v$, there exists a term $t$ such that $u \rightarrow_{\mathcal{R}}^\ast t$ and $v \rightarrow_{\mathcal{R}}^\ast t$. Moreover, we say that $\mathcal{R}$ is convergent if $\mathcal{R}$ is confluent and terminate.
A term \( t \) is in normal form (w.r.t. to a rewrite system \( \mathcal{R} \)) if there is no term \( s \) such that \( t \rightarrow_{\mathcal{R}} s \). Moreover, if \( t \rightarrow^*_{\mathcal{R}} s \) and \( s \) is in normal form then we say that \( s \) is a normal form of \( t \). When the rewriting system \( \mathcal{R} \) is convergent, the normal form of a term \( t \) is unique and is denoted \( t \downarrow \).
Part I

Equivalence properties in the applied pi calculus
Chapter 3

Modelling of cryptographic protocols

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When verifying any security properties on a cryptographic protocol in a symbolic model, one first have to properly define the model in which the cryptographic protocol and the security property will be expressed. As mentioned in the introduction, there exist dozen of symbolic models in the literature, but we focus our attention on the applied pi calculus [AF01], an expressive model in which several results on trace and equivalence properties can be found in the literature e.g. [BMU08, DKR07, ABF04]. As any symbolic model, the applied pi calculus abstracts the messages by terms and the cryptographic primitives by function symbols. To model the properties of such cryptographic primitives, the applied pi calculus relies on equational theories which are most of the time represented by a set of equations between terms.

Since equivalence properties are expressed by the means of behavioural equivalence, we focus in Section 3.2 on four main definitions of equivalence (observational equivalence, labeled bisimilarity, may-testing equivalence, trace equivalence) and present the relations between these equivalences. In particular, we show that may-testing does not imply trace equivalence. The difference between the two notions is subtle. We exhibit a counter-example that relies on the fact that may-testing equivalence requires the attacker to commit in advance on part of its behaviour, yielding a slightly weaker attacker. We further show that may-testing equivalence does imply trace equivalence in case the processes have finitely many successors (e.g. for processes without replication): trace equivalence and may-testing equivalence coincide for image-finite processes.
At last, we detail in this chapter the private authentication protocol [AF04] and some sub-protocols that are described in the ICAO standard [ICA04] for the e-passport protocol, namely Basic Access Control protocol, Passive Authentication protocol and Active Authentication protocol. The last two protocols will be used in Chapter 5 to illustrate our result about composition of trace equivalence. Moreover, all these protocols will be part of our benchmark for the implementation of the decision algorithm of trace equivalence presented in Part II. At last, the private authentication along with the BAC protocol will also serve as guidelines for our work on the tool ProVerif [Bla01] (see Chapter 9).

3.1 The applied pi calculus

The applied pi calculus [AF01] is a derivative of the pi calculus that is specialised for modelling cryptographic protocols. Participants in a protocol are modelled as processes, and the communication between them is modelled by means of message passing.

3.1.1 Syntax

To describe processes in the applied pi calculus, we rely on a sort system for terms defined in Section 2.1. More specifically, we rely on two subsets of types: base types and channel types. The details of the sort system are unimportant, as long as base types differ from channel types. As such, we will denote $\mathcal{N}_b \subset \mathcal{N}$ and $\mathcal{X}_b \subset \mathcal{X}$ the infinite sets of names and variables of base type. Similarly, we denote by $\mathcal{N}_{ch} \subset \mathcal{N}$ and $\mathcal{X}_{ch} \subset \mathcal{X}$ the infinite sets of names and variables of channel type.

In the applied pi calculus, the function symbols only operate on and return terms of base type. It implies that any term of channel type is either a variable in $\mathcal{X}_{ch}$ or a name in $\mathcal{N}_{ch}$.

<table>
<thead>
<tr>
<th>Plain Processes</th>
<th>Extended Processes</th>
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<tr>
<td>$P, Q, R := 0$</td>
<td>$A, B, C := P$</td>
</tr>
<tr>
<td>$P</td>
<td>Q$</td>
</tr>
<tr>
<td>$!P$</td>
<td>$\nu n.A$</td>
</tr>
<tr>
<td>$\nu n.P$</td>
<td>$\nu x.A$</td>
</tr>
<tr>
<td>if $u = v$ then $P$ else $Q$</td>
<td>${u/x}$</td>
</tr>
<tr>
<td>$\text{in}(c, x).P$</td>
<td></td>
</tr>
<tr>
<td>$\text{out}(c, u).P$</td>
<td></td>
</tr>
</tbody>
</table>

where $u$ and $v$ are terms of any type, $n$ is a name, $x$ is a variable and $c$ is a term of channel type, i.e. a name or a variable.

Figure 3.1: Syntax of processes

The applied pi calculus defines plain processes, denoted by $P, Q, R$, and extended processes, denoted by $A, B, C$. Plain processes are built up in a similar way to processes in pi calculus except that messages can contain terms rather than just names. Extended processes add active substitutions and restriction on variables (see Figure 3.1). The substitution $\{u/x\}$ is an active substitution that replaces the variable $x$ with the term $u$. Active substitutions generalize the “let” construct: $\nu x.(\{u/x\} | P)$ corresponds exactly to “let $x = u$ in $P$”.

Example 3.1. Let $F_{\text{senc}} = \{\text{senc}/2, \text{sdec}/2, f/1\}$ be the signature composed of the symmetric encryption/decryption and a unary function $f$. Consider the Handshake protocol [GML+ 93, DJ06] described in the Alice & Bob representation as follows:

0. $A \rightarrow B$: senc($N, k_{AB}$)
1. $B \rightarrow A$: senc($f(N), k_{AB}$)

In this protocol, we consider that the two participants $A$ and $B$ share a secret key $k_{AB}$. 
3.1. THE APPLIED PI CALCULUS

1. A starts by creating a fresh nonce $N$, i.e. a random number, and then sends to $B$ this nonce encrypted with the secret key $k_{AB}$.

2. $B$ recovers $N$ by decrypting the message received, then applies a certain function $f$ on $N$ and sends the result to $A$ encrypted with the same secret key $k_{AB}$.

3. At last, $A$ also applies $f$ on $N$, compares the result with the decryption of the message received and then executes a certain protocol $P$ if the test is successful.

We model this protocol using the applied pi calculus as follows:

$$\nu k_{AB}. (\nu N. \text{out}(c, \text{senc}(N, k_{AB})), \text{in}(c, x), \text{if sdec}(x, k_{AB}) = f(N) \text{ then } P \text{ else } 0.\mid \text{in}(c, y), \text{out}(c, \text{senc}(f(sdec(y, k_{AB})), k_{AB})))$$

where $c$ represents the public channel on which $A$ and $B$ communicate.

As usual, names and variables have scopes, which are delimited by restrictions and by inputs. We write $\text{fvars}(A)$, $\text{bvars}(A)$, $\text{fnames}(A)$ and $\text{bnames}(A)$ for the sets of free and bound variables and free and bound names of $A$, respectively. We say that an extended process is closed if all its variables are either bound or defined by an active substitution. An evaluation context $C[\_\_\_]$ is an extended process with a hole instead of an extended process.

Active substitutions are useful because they allow us to map an extended process $A$ to its frame, denoted $\Phi(A)$, by replacing every plain process in $A$ with $0$. Hence, a frame is an extended process built up from $0$ and active substitutions by parallel composition and restriction. The frame $\Phi(A)$ accounts for the set of terms statically possessed by the intruder (but does not take into account for $A$'s dynamic behavior). The domain of a frame $\Phi$, denoted by $\text{dom}(\Phi)$, is the set of variables for which $\Phi$ defines a substitution (those variables $x$ for which $\Phi$ contains a substitution $\{x/\cdot\}$ not under a restriction on $x$).

**Example 3.2.** Consider the signature $F_{\text{senc}}$ of Example 3.2 and the following process $A$ made up of three components in parallel:

$$\nu s. \nu sk. \nu x\_1. (\text{out}(c\_1, x\_1) \mid \text{in}(c\_1, y). \text{out}(c\_2, \text{sdec}(y, sk)) \mid \{\text{senc}(s, sk)/x\_1\}).$$

Its first component publishes the message $\text{senc}(s, sk)$ stored in $x\_1$ by sending it on $c\_1$. The second receives a message on $c\_1$, uses the secret key $sk$ to decrypt it, and forwards the result on $c\_2$. We have $\Phi(A) = \nu s. \nu sk. \nu x\_1. \{\text{senc}(s, sk)/x\_1\}$ and $\text{dom}(\Phi(A)) = \emptyset$ (since $x\_1$ is under a restriction).

3.1.2 Semantics

We briefly recall the operational semantics of the applied pi calculus (see [AF01] for details). First, we associate an equational theory $E$ to the signature $F$. The purpose of this equational theory is to represent the behaviour of the cryptographic primitives. We require the equational theory to be closed under one-to-one renaming.

*Structural equivalence*, noted $\equiv$, is the smallest equivalence relation on extended processes that is closed under $\alpha$-conversion of names and variables, by application of evaluation contexts, and satisfying some further basic structural rules such as $A \mid 0 \equiv A$ and $!A \equiv !A \mid A$, associativity and commutativity of $\mid$, binding-operator-like behavior of $\nu$, and when $u =_E v$ the equivalences:

$$\nu x. \{u/x\} \equiv 0 \quad \{u/x\} \equiv \{v/x\} \quad \{u/x\} \mid A \equiv \{v/x\} \mid A\{v/x\}$$

**Example 3.3.** Let $P$ be the following process:

$$\nu s. \nu sk. (\text{out}(c\_1, \text{senc}(s, sk)) \mid \text{in}(c\_1, y). \text{out}(c\_2, \text{sdec}(y, sk))).$$

The process $P$ is structurally equivalent to the process $A$ given in Example 3.2. We have that $\Phi(P) = 0 \equiv \Phi(A)$. 
The operational semantics of processes in the applied pi calculus is defined by structural rules defining two relations: structural equivalence (described above) and internal reduction, noted $\xrightarrow{\ell}$. Internal reduction is the smallest relation on extended processes closed under structural equivalence and application of evaluation contexts such that:

$$\text{out}(a, u). P \mid \text{in}(a, x). Q \xrightarrow{\ell} P \mid Q\{u/x\}$$

if $u = v$ then $P$ else $Q \xrightarrow{\ell} P$ if $u =_{E} v$

if $u = v$ then $P$ else $Q \xrightarrow{\ell} Q$ if $u, v$ ground terms such that $u \neq_{E} v$

The operational semantics is extended by a labeled operational semantics enabling us to reason about processes that interact with their environment. Labeled operational semantics defines the relation $\xrightarrow{\ell}$ where $\ell$ is a label in$(c, u)$ where $u$ is a term that may contain names and variables and $c$ is a term of channel type; a label out$(c, u)$ or $\nu u.\text{out}(c, u)$, where $u$ is a variable of base type or a name of channel type. The scopes of names and variables are only delimited by restrictions, i.e. the input label in$(c, u)$ does not restrict variables contrary to the plain process in$(c, x)$.

We adopt the following rules in addition to the internal reduction rules. Below, the names $a$ and $c$ are channel names whereas $x$ is a variable of base type and $y$ is a variable of any type.

| IN | $\text{in}(a, y).P \xrightarrow{\nu in(a,u)} P\{u/y\}$ |
| OUT-CH | $\text{out}(a, c).P \xrightarrow{\nu c.\text{out}(a,c)} P$ |
| OPEN-CH | $\nu c. A \xrightarrow{\nu c.\text{out}(a,c)} A'$ if $c \neq a$ |
| OUT-T | $\text{out}(a, M).P \xrightarrow{\nu x.\text{out}(a,x)} P \mid \{^M/x\}$ |

**SCOPE** $A \xrightarrow{\ell} A'$ $u$ does not occur in $\ell$

**BNAMES** $\nu u. A \xrightarrow{\ell} \nu u. A'$

**FVARS** $\text{bvars}(\ell) \cap \text{fvars}(B) = \emptyset$

**STRUCT** $A \equiv B \Rightarrow B' \equiv A' \Rightarrow A \xrightarrow{\ell} A'$

Let $\mathcal{A}$ be the alphabet of actions (in our case this alphabet is infinite) where the special symbol $\tau \in \mathcal{A}$ represents an unobservable action. For every $w \in \mathcal{A}^*$ the relation $\xrightarrow{w}$ on extended processes is defined in the usual way. By convention $A \xrightarrow{\epsilon} A$ where $\epsilon$ denotes the empty word.

For every $s \in (\mathcal{A} \setminus \{\tau\})^*$, the relation $\xrightarrow{\gamma}$ on extended processes is defined by: $A \xrightarrow{\nu s} B$ if, and only if, there exists $w \in \mathcal{A}^*$ such that $A \xrightarrow{w} B$ and $s$ is obtained from $w$ by erasing all occurrences of $\tau$. Intuitively, $A \xrightarrow{\nu s} B$ means that $A$ transforms into $B$ by experiment $s$. We also consider the relation $A \equiv B \Rightarrow A \xrightarrow{\nu s} B$ and $A \equiv B \Rightarrow A \xrightarrow{w}$ on closed extended processes.

Note that the labeled transition is not closed under application of evaluation contexts. Moreover, the output of a term $u$ needs to be made “by reference” using a restricted variable and an active substitution. The rules differ slightly from those described in [AP01] but it has been shown in [DKR07] that the two underlying notions of observational equivalence coincide.

**Example 3.4.** Consider the protocol $P$ in Example 3.3. One possible sequence of transitions for $P$ is the following:

$$P \xrightarrow{\nu x.\text{out}(c_1, x)} \nu s.\text{vsk}.\{(\text{in}(c_1, y).\text{out}(c_2, \text{adec}(y, sk)) \mid \{\text{aenc}(s, \text{pk}(sk))/x\})\}$$

$$\xrightarrow{\text{in}(c_1, x)} \nu s.\text{vsk}.\{(\text{out}(c_2, \text{adec}(\text{senc}(s, \text{pk}(sk)), sk)) \mid \{\text{aenc}(s, \text{pk}(sk))/x\})\}$$

$$\xrightarrow{\nu y.\text{out}(c_2, y)} \nu s.\text{vsk}.\{(s/y) \mid \{\text{aenc}(s, \text{pk}(sk))/x\})\}$$

Note that all transitions in this sequence are visible actions. However, the two first transitions only result on passing through a message. Hence, it is possible to apply an internal reduction:

$$P \xrightarrow{\tau} \nu s.\text{vsk}.\text{out}(c_2, \text{adec}(\text{senc}(s, \text{pk}(sk)), sk))$$

$$\xrightarrow{\nu y.\text{out}(c_2, y)} \nu s.\text{vsk}.\text{out}(c_2, \text{adec}(\text{senc}(s, \text{pk}(sk)), sk))$$

$$\xrightarrow{\nu x.\text{out}(c_1, x)} \nu s.\text{vsk}.\{(\text{in}(c_1, y).\text{out}(c_2, \text{adec}(y, sk)) \mid \{\text{aenc}(s, \text{pk}(sk))/x\})\}$$
Note that the frame is "smaller" than the frame in the previous sequence of transitions. It was predictable by the fact that we replaced some labeled actions (visible for the attacker) by an internal reduction (invisible action for the attacker).

3.2 Behavioural equivalences and their relations

Behavioural equivalences intuitively define the fact that no observer can see the difference between two processes. They can be used to formalise many interesting security properties, in particular privacy related properties, as such as those studied in [AF04, DKR02, ACRR10, BCdH10]. Slightly more specifically, two processes can be said equivalent if an observer, whatever how he behaves, observes the same (or equivalent) outputs from the two processes. This can be formally defined as trace equivalence as introduced in [MNP02]. An alternative definition is testing equivalence as defined for example by M. Abadi and A. Gordon [AG99]. In the context of the pi calculus, may-testing and trace equivalences are known to be difficult to prove. Therefore, a stronger notion has been proposed: observational equivalence, which requires in addition the two processes to be (weakly) bisimilar.

This section is devoted to the definition of these three notions and the study of their relations in the context of the applied pi calculus. We first introduce the notion of static equivalence that compares sequences of messages, a notion of intruder’s knowledge that has been extensively studied, for example in [AC00].

Definition 3.1 (static equivalence $\sim$). Two terms $u$ and $v$ are equal in the frame $\Phi$, written $(u =_E v)\Phi$, if there exists $\bar{n}$ and a substitution $\sigma$ such that $\Phi \equiv \nu\bar{n}.\sigma$, $\bar{n} \cap (\text{frames}(u) \cup \text{frames}(v)) = \emptyset$, and $u\sigma =_E v\sigma$.

Two closed frames $\Phi_1$ and $\Phi_2$ are statically equivalent, written $\Phi_1 \sim \Phi_2$, when:

- $\text{dom}(\Phi_1) = \text{dom}(\Phi_2)$, and
- for all terms $u, v$, $(u =_E v)\Phi_1$ if and only if $(u =_E v)\Phi_2$.

Example 3.5. Consider the theory $E_{\text{aenc}}$ (see Example 2.2), $\Phi_a = \{\text{aenc}(a,\text{pk}(sk))/_{x_1}\}$, and $\Phi_b = \{\text{aenc}(b,\text{pk}(sk))/_{x_1}\}$. We have that $(\text{aenc}(x_1,sk) =_{E_{\text{aenc}}} a)\Phi_a$ whereas $(\text{aenc}(x_1,sk) \neq_{E_{\text{aenc}}} a)\Phi_b$, thus $\Phi_a \not\sim \Phi_b$. Note that $\Phi_a$ and $\Phi_b$ do not restrict $sk$, a nor $b$ hence they are accessible to the attacker.

However, $\nu sk.\varphi \sim \nu sk.\varphi'$. This is a non trivial equivalence. Intuitively, since $sk$ is now restricted, it can not appear in the tests which also implies that $\text{pk}(sk)$, the encryption key, can not appear directly in the tests. Thus, there is no test that allows one to distinguish the two frames.

3.2.1 Trace equivalence

For every closed extended process $A$, we define its set of traces, each trace consisting in a sequence of actions together with the sequence of sent messages:

$$\text{trace}(A) = \{(s,\delta(B)) \mid A \xrightarrow{\delta} B \text{ for some } B\}.$$  

Note that, in the applied pi calculus, the sent messages of base type are exclusively stored in the frame and not in the sequence $s$ (the outputs are made by “reference”).

Two processes are trace equivalent if, whatever the messages they received (built upon previously sent messages), the resulting frames are in static equivalence.

Definition 3.2 (trace equivalence $\approx_t$). Let $A$ and $B$ be two closed extended processes, $A \subseteq_t B$ if for every $(s, \Phi) \in \text{trace}(A)$ such that $\text{frames}(s) \cap \text{frames}(B) = \emptyset$, there exists $(s', \Phi') \in \text{trace}(B)$ such that $s = s'$ and $\Phi \approx \Phi'$.

Two closed extended processes $A$ and $B$ are trace equivalent, denoted by $A \approx_t B$, if $A \subseteq_t B$ and $B \subseteq_t A$. 

As previously explained, proving trace equivalence of two protocols is very difficult. Indeed the set of possible traces of a protocol is usually infinite hence one has to compute and compare two sets of infinite traces. Furthermore, given two traces, one still need to prove the static equivalence which also consist of evaluating and comparing an infinite set pair of terms.

Example 3.6. Consider $A$ and $B$ the two following protocols:

\[
A \overset{\text{def}}{=} \text{out}(c_1, \text{aenc}(a, \text{pk}(sk))).\text{out}(c_2, b)
\]

\[
B \overset{\text{def}}{=} \text{out}(c_1, \text{aenc}(b, \text{pk}(sk))) \mid \text{out}(c_2, b)
\]

We have that $A \not\approx B$. Indeed, we can find several traces that can’t be matched in both protocols. For example, $B$ can be reduced as follows:

\[
B \xrightarrow{\nu x. \text{out}(c_2, x)} \text{out}(c_1, \text{aenc}(b, \text{pk}(sk))) \mid \{b/\_x\}
\]

However, to output on the public channel $c_2$, the protocol $A$ must first output on the public channel $c_1$ and so such trace can’t be matched in $A$, hence the non-equivalence.

This trace is not the only witness of the non-equivalence. Indeed, one can reduce $A$ and $B$ as follows:

\[
A \xrightarrow{\nu x. \text{out}(c_1, x)} \text{out}(c_2, b) \mid \{\text{aenc}(a, \text{pk}(sk))/x\} \overset{\text{def}}{=} A'
\]

\[
B \xrightarrow{\nu x. \text{out}(c_1, x)} \text{out}(c_2, b) \mid \{\text{aenc}(b, \text{pk}(sk))/x\} \overset{\text{def}}{=} B'
\]

In such a case, we have that $\Phi(A') = \{\text{aenc}(a, \text{pk}(sk))/x\}$ and $\Phi(B') = \{\text{aenc}(b, \text{pk}(sk))/x\}$. These frames correspond to the frame in Example 3.5 and we already showed that $\Phi(A') \not\approx \Phi(B')$, hence the non-equivalence.

3.2.2 May-testing equivalence

We write $A \mid c$ when $A$ can send a message on $c$, that is, when $A \xrightarrow{\_} C[\text{out}(c, M).P]$ for some evaluation context $C$ that does not bind $c$. A test consists of any evaluation context $C$ and any channel name $c$. A closed extended process $A$ passes the test if and only if $C[A] \mid c$. The notion of testing gives rise to a may-testing preorder $\sqsubseteq_m$ and to a may-testing equivalence $\approx_m$ on the set of closed extended processes.

Definition 3.3 (may-testing equivalence). Let $A$ and $B$ be two closed extended processes such that $\text{dom}(A) = \text{dom}(B)$, $A \sqsubseteq_m B$ if for any test $(C,c)$ such that $C$ is a closing evaluation context for $A$ and $B$ we have that $C[A] \mid c$ implies that $C[B] \mid c$. Two closed extended processes $A$ and $B$ are in may-testing equivalence, denoted by $A \approx_m B$, if $A \sqsubseteq_m B$ and $B \sqsubseteq_m A$.

The idea of may-testing equivalence comes from the work of R. De Nicola and M. Hennessy [NHS4]. Our definition is similar to their notion of may-testing equivalence. Since then, this notion of may-testing equivalence has been used in several cryptographic calculi, e.g. spi-calculus [AC99]. This notion is usually shown to be equivalent to a notion of trace equivalence (as the one given in Definition 3.2) that is easier to manipulate since the universal quantification over all contexts has been removed.

Example 3.7. Coming back to the protocols $A$ and $B$ in Example 3.6, we can find back the two witnesses of the non-equivalence brought to light using the notion of may-testing equivalence. Indeed, we have that $B \mid c_2$ while $A \not\mid c_2$. Furthermore, let $C$ the following evaluation context:

\[
C \overset{\text{def}}{=} \_ \mid \text{in}(c_1, x), \text{if adec}(x, sk) = a \text{ then out}(bad, a) \text{ else 0}
\]

where bad is a public channel. $C$ is closing for $A$ and $B$. Furthermore, we have that $C[A] \mid \text{bad}$ and $C[B] \not\mid \text{bad}$. Note that the test performed in the if then else part of $C$ corresponds exactly to the test used to show that $\Phi(A')$ and $\Phi(B')$ are not statically equivalent in Example 3.5.
3.2.3 Relations between may-testing and trace equivalence

People usually consider that may-testing equivalence coincide with trace equivalence. Actually, this result has been proved in two variants of the spi-calculus [MNP02, DSV03] and is in the spirit of the main theorem stated in [AF01]. We tried to adapt their proof, but it happens that the two notions do not coincide in the applied pi calculus setting. We indeed exhibit two processes that are may-testing equivalent but not trace equivalent. However, these two notions are similar and try to capture the same concept. We show that trace equivalence implies may-testing equivalence (without any additional restriction) and the other implication holds as soon as we consider processes without replication. More precisely, this last implication holds for processes that are image-finite (up to static equivalence).

3.2.3.1 Trace equivalence implies may-testing equivalence

**Theorem 3.1.** For all $A$ and $B$ two closed extended processes,

$$A \approx_{t} B \text{ implies that } A \approx_{m} B.$$  

The proof of Theorem 3.1 requires to characterize any evolution of the contextualized process $A$, that is, any evolution of $C[A]$.

Given a closed extended process $A$ and an evaluation context $C[\_ ]$, the proposition below allows us to map a derivation issued from $C[A]$ to a labeled trace issued from $A$. Note that we only consider evaluation contexts having a special shape (there is no restriction in front of the hole). This additional assumption is actually fulfilled when proving Theorem 3.1.

**Proposition 3.1.** Let $A$ and $B$ be two closed extended process with $\text{dom}(A) = \text{dom}(B)$, and $C[\_ ] = \nu n.(D \mid \_ )$ be an evaluation context closing for $A$. If $C[A] \triangleright \triangleright A''$ for some process $A''$, then there exist a closed extended process $A'$, an evaluation context $C' = \nu n'.(D' \mid \_ )$ closing for $A'$, and a trace $\text{tr} \in (A \setminus \{\tau\})^*$ such that $A'' \equiv C'[A']$, $A \triangleright A'$, and for all closed extended process $B'$,

$$B \triangleright A' \text{ and } \Phi(B') \sim \Phi(A') \text{ imply that } C[B] \triangleright C'[B'].$$

**Proof (sketch).**Proving Proposition 3.1 is quite technical thus the full proof can be found in Appendix A.1.

The proof of Proposition 3.1 works by induction on the length $\ell$ of the derivation of $C[A] \triangleright \triangleright A''$. The initial case (i.e. $\ell = 0$) is almost trivial by defining $C' = C$ thus we focus on the inductive case (i.e. $\ell > 0$):

The length of the derivation being strictly bigger than 0, we know that $C[A] \triangleright \triangleright A''$ implies $C[A] \triangleright \triangleright A''$ for some closed extended process $A_1$. Since the length of the derivation $C[A] \triangleright \triangleright A_1$ is strictly smaller than $\ell$, we apply our inductive hypothesis: There exist a closed extended process $A_1'$, an evaluation context $C_1'[\_ ] = \nu n_1'.(D'_1 \mid \_ )$ closing for $A_1'$, and a labeled sequence $\text{tr}_1 \in (A \setminus \{\tau\})^*$ such that $A_1 \equiv C_1'[A_1']$, $A \triangleright A_1$, and for all closed extended processes $B_1'$, we have that $B \triangleright B_1'$ and $\Phi(B_1') \sim \Phi(A_1')$ imply that $C[B] \triangleright C'[B'_1]$.

Then, the proof consists of matching the internal reduction $\nu n_1'.(D'_1 \mid A_1') \triangleright A''$ either to a labeled transition applied on $A'_1$ or to a modification of the evaluation context $C$.

Typically, if the internal derivation is applied solely on $A'_1$, then we have $C' = C'_1$, $A'_1 \triangleright A'$ for some $A'$. On the other hand, if the internal derivation is applied solely on $D'_1$ then only the evaluation context is modified, i.e. $C'_1[\_ ] = \nu n_2.(D'_2 \mid \_ )$, $A' = A'_1$ and $D'_1 \triangleright D'_2$ for some $D'_2$. The last possible case of internal reduction is a communication between $D'_1$ and $A'_1$. But then, two cases must be distinguished: either the output was part of $D'_1$ and the input part of $A'_1$; or the output was part of $A'_1$ and the input part of $D'_1$. Intuitively, if the input was part of $A'_1$ then it will be matched by the labeled transition $A'_1 \xrightarrow{in(c,M)} A'$ where $M$ is determined by the output.
in $\mathcal{D}'$. Else the internal reduction will be matched by the labeled transition $A'_1 \xrightarrow{\nu.x.\text{out}(c,z)} A'$ for some $c$.

The proof of Theorem 3.3 also relies on the fact that trace equivalence is closed by one-to-one renamings of free names. This is formally stated in the lemma below:

**Lemma 3.1.** Let $A$ and $B$ be two closed extended processes such that $A \approx_t B$ and $u$ be a name (resp. variable) that occurs in $\text{fnames}(A) \cup \text{bvars}(A) \cup \text{fnames}(B) \cup \text{bvars}(B)$ and not in $\text{bnames}(A) \cup \text{bvars}(A) \cup \text{bnames}(B) \cup \text{bvars}(B)$, and $u'$ be a fresh name (resp. variable). We have that $A[u'/u] \approx_t B[u'/u]$.

We are now able to prove Theorem 3.3.

**Proof of Theorem 3.3.** Let $A, B$ be two closed extended processes such that $A \approx_t B$. Let $C[\_\_\_]$ be an evaluation context closing for $A$ (and $B$), and $c$ be a channel name. We assume w.l.o.g. that $C[\_\_\_] = \nu\tilde{\eta}.(D | \nu\tilde{\eta}.\_\_\_)$ for some extended process $D$ and for some sequences of names and variables $\tilde{n}$ and $\tilde{\eta}$. We assume w.l.o.g. that $\tilde{\eta} \cap (\text{bnames}(A) \cup \text{bvars}(A)) = \emptyset$ and $\tilde{n} \cap (\text{bnames}(B) \cup \text{bvars}(B)) = \emptyset$. Let $A_2 = A\{\tilde{\eta}/\tilde{n}\}$ and $B_2 = B\{\tilde{\eta}/\tilde{n}\}$ where $\tilde{\eta}$ is a sequence of fresh names and variables. Thanks to Lemma 3.1, we have that $A_2 \approx_t B_2$. Let $C_2[\_\_\_] = \nu\tilde{\eta}.\nu\tilde{\eta}'.(D | \_\_]$. We have that $C[A] \equiv C_2[A_2]$ and $C[B] \equiv C_2[B_2]$.

Assume now that $C[A]\|c$. This means that there exist a closing evaluation context $C_1$ that does not bind $c$, a term $M$, and a plain process $P$ such that $C[A] \equiv C_2[A_2] \Rightarrow C_1[\text{out}(c, M), P]$. Applying Proposition 3.3 on $A_2$, $B_2$ and $C_2[\_\_]$, we know that there exist a closed extended process $A'_2$, a closing evaluation context $C'_2[\_\_\_] = \nu\tilde{r}.(E | \_\_]$ for $A'_2$ and $\tilde{r} \in (A \times \{\tau\})^*$ such that $C_2[\text{out}(c, M), P] \equiv C'_2[A'_2]$, and $A_2 \xrightarrow{\nu \cdot \tilde{r}} A'_2$, and for all closed extended process $B'_2$ such that $B_2 \xrightarrow{\nu \cdot \tilde{r}} B'_2$ and $\Phi(B'_2) \sim \Phi(A'_2)$, we have that $C_2[B_2] \Rightarrow C'_2[B'_2]$. Moreover, we assume w.l.o.g. that $\text{bnames}(\text{tr}) \cap \text{fnames}(B_2) = \emptyset$.

Since $C'_2 = \nu\tilde{r}.(E | \_\_]$, we can deduce from $C_1[\text{out}(c, M), P] \equiv C'_2[A'_2]$ that the output $\text{out}(c, M)$ comes either from the process $E$ or from $A'_2$. We distinguish these two cases:

- **The output $\text{out}(c, M)$ comes from $E$.** Since, we have that $A_2 \approx_t B_2$, we know that that there exists $B'_2$ such that $B_2 \xrightarrow{\nu \cdot \tilde{r}} B'_2$ and $\Phi(B'_2) \sim \Phi(B'_2)$. Therefore, we have that $C_2[B_2] \Rightarrow C'_2[B'_2] \equiv \nu\tilde{r}.(E | B'_2)$. But by hypothesis, we know that the output $\text{out}(c, M)$ comes from $E$ and $c \notin \tilde{r}$. Hence we have that $C_2[B_2]\|\tilde{c}$, and since $C[B] \equiv C_2[B_2]$, we conclude that $C[B]\|\tilde{c}$.

- **The output $\text{out}(c, M)$ comes from $A'_2$.** Thus, we have that $A'_2 \equiv \nu\tilde{r}.(\text{out}(c, M), P | A_3)$ with $c \notin \tilde{r}, \tilde{\eta}$. Thus, we have that $A'_2 \xrightarrow{\nu \cdot \tilde{r}.(\text{out}(c, z))} \nu\tilde{r}.(P | A_3 | \{M/z\})$ (if $M$ is a term of channel type, the transition is different but the proof can be done in a similar way.) Let $A'' = \nu\tilde{r}.(P | A_3 | \{M/z\})$ and $\text{tr}' = \text{tr} \cdot \nu\tilde{z}.\text{out}(c, z)$, we have that $A'_2 \xrightarrow{\text{tr}'} A''$. Since we have that $A_2 \approx_t B_2$, we have that there exists $B'_2$ such that $B_2 \xrightarrow{\nu \cdot \tilde{r}} B'_2$ and $\Phi(B'_2) \sim \Phi(B'_2)$. Thus, we can deduce that there exists $B'$ such that $B_2 \xrightarrow{\nu \cdot \tilde{r}} B' \xrightarrow{\nu \cdot \tilde{r}.(\text{out}(c, z))} B'_2$. Therefore, we have that there exist a term $N$, an evaluation context $C_3$ and a process $Q$ such that $B' \equiv C_3[\text{out}(c, N), Q]$ and $c$ is not bound by $C_3$. Furthermore, we have that $\Phi(A'_2) \sim \Phi(B')$ which means that $C_2[B_2] \Rightarrow C'_2[B'_2]$, and thus $C_2[B_2] \Rightarrow C'_2[C_3[\text{out}(c, N), Q]]$. Hence, we have that $C_2[B_2]\|\tilde{c}$, and since $C[B] \equiv C_2[B_2]$, we conclude that $C[B]\|\tilde{c}$. \(\square\)

**3.2.3.2 May-testing equivalence does not imply trace equivalence**

While may-testing and trace equivalences seem to be two very similar notions, may-testing equivalence actually does not imply trace equivalence. Roughly, in may-testing equivalence, the attacker is allowed to perform a sequence of inputs/outputs followed by a finite number of tests, but he has to commit on these tests before knowing how the communication actions will be used. In trace equivalence, all the tests are considered through static equivalence. The attacker does not have
to commit on the tests he wants to use in advance. So, the attacker is more adaptive in trace equivalence and this gives him more power.

We describe two processes \( A \) and \( B \) such that \( A \not\equiv \tau B \) whereas \( A \approx_m B \). Let \( A \) and \( B \) be the two following processes:

- \( A = \nu b. \nu c_1. (\text{out}(c_1, \text{token}) \mid \text{in}(c_1, x). \text{out}(c, b) \mid \text{in}(c_1, x). B) \); and
- \( B = \nu c_2. (\text{out}(c_2, h(a)) \mid \text{in}(c_2, x). \text{out}(c, x) \mid \text{in}(c_2, x). \text{out}(c_2, h(x))) \).

We consider the empty equational theory and a signature which only contains the symbol \( h \) of arity 1 (with no equation). The private channel \( c_1 \) in \( A \) is used to model the choice operator. The behavior of \( A \) consists of outputting a fresh name \( b \) or executing the process \( B \). The processes \( B \) relies also on a private channel, namely \( c_2 \), whose purpose is to model the choice operator. An execution of \( B \) will output a message of the form \( h(\ldots h(a) \ldots) \) on the public channel \( c \), for an arbitrary number of \( h \). In the remaining, we denote by \( h^n(a) \) the term obtained by applying \( n \) times \( h \) on top of \( a \).

Regarding trace equivalence, we have that:

- \( \text{trace}(A) = \{(e, 0); (\text{tr}, \nu b. \{b/x\}); (\text{tr}, \{h(a)/x\}); \ldots; (\text{tr}, \{h^n(a)/x\}); \ldots) \)
- \( \text{trace}(B) = \{(e, 0); (\text{tr}, \{h(a)/x\}); \ldots; (\text{tr}, \{h^n(a)/x\}); \ldots) \)

with \( \text{tr} = \nu x. \text{out}(c, x) \). We can easily see that \( A \not\equiv \tau B \): the frame \( \nu b. \{b/x\} \) is not statically equivalent to any other frame in \( \text{trace}(B) \).

On the other hand, we have that \( A \approx_m B \). This is a non trivial equivalence that is not easy to prove. Below, we only give an intuition. First, it seems clear that \( B \subseteq_m A \) since \( A \) can easily mimic the process \( B \) by performing first an internal communication and giving the token to the last part of the process. Regarding the other inclusion, consider a test \( (C, c) \) such that \( C \) is a closing evaluation context for \( A \). The most interesting case is when \( C[A] \) outputs the fresh name \( b \) on the channel \( c \) and then performs some tests on this message. However, since the execution trace that leads to the output on \( c \) is fixed, we know the tests that have been performed in such a situation, and we can compute \( n_0 \) such that the same tests will be satisfied if the outputted message was \( h^n(a) \) instead of \( b \) (for instance, we can choose for \( n_0 \) the number of occurrences of \( h \) in the tests plus one).

3.2.3.3 Case of image-finite processes

As illustrated in Section 3.2.3.2, may-testing equivalence does not imply trace equivalence in general. However, the implication holds as soon as we consider processes without replication. More precisely, this implication holds for processes that are image-finite (up to static equivalence).

**Definition 3.4** (image-finite). An extended process \( A \) is image-finite if for each sequence of actions \( \text{tr} \), the set of equivalence classes \( \{\Phi(A') \mid A \stackrel{\Delta}{=} A'\}/\sim \) is finite.

Any process without replication is image-finite. Indeed, if a process \( A \) does not contain a replication then we have that \( \{\Phi(A') \mid A \stackrel{\Delta}{=} A'\} \) is a finite set up to structural equivalence, thus so is \( \{\Phi(A') \mid A \approx A'\}/\sim \).

Note that the processes defined in Subsection 3.2.3.2 are not image-finite.

**Theorem 3.2.** Let \( A \) and \( B \) two closed extended processes with \( \text{dom}(A) = \text{dom}(B) \) and such that \( A \) and \( B \) are image-finite. We have that:

\[ A \approx_m B \implies A \approx \tau B \]

**Proof.** Assume that \( A \not\equiv \tau B \). We assume w.l.o.g. that \( A \not\subseteq \tau B \). In such a case, there exists a witness for the non equivalence. This means that there exists \((\text{tr}, \phi) \in \text{trace}(A)\) such that \( \text{bnames(tr)} \cap \text{fnames}(B) = \emptyset \), and
1. either there does not exist \( \Phi' \) such that \( (\text{tr}, \Phi') \in \text{trace}(B) \);
2. or for all \( (\text{tr}, \Phi') \in \text{trace}(B) \), we have that \( \Phi' \not\sim \Phi \).

Moreover, we assume that no name in \( \text{tr} \) is bounded twice (i.e. \( \nu a \) cannot occur twice in \( \text{tr} \)) and bounded names in \( \text{tr} \) are distinct from free names that occur in \( A, B \), and \( \text{tr} \).

We build an evaluation context \( C \) according to the trace \( \text{tr} \) and also the tests that witness the fact that static equivalence does not hold. Let \( S_{\text{tr}} = \{ \Phi' \mid (\text{tr}, \Phi') \in \text{trace}(B) \} \). Since \( B \) is image-finite, we know that \( S_{\text{tr}} / \sim \) is finite. Let \( \{ \Phi_1', \ldots, \Phi_m' \} = S_{\text{tr}} / \sim \). If we are in the first case, i.e. \( S_{\text{tr}} = \emptyset \), we have that \( m = 0 \).

We know that \( \{1, \ldots, m\} = T^+ \sqcup T^- \) with:

- for each \( i \in T^+ \), there exist two terms \( M_i \) and \( N_i \) such that \( \text{fvars}(M_i) \cup \text{fvars}(N_i) \subseteq \text{dom}(\Phi) \), \( (M_i =_E N_i)\Phi \), and \( (M_i \not=_{E} N_i)\Phi' \); and
- for each \( i \in T^- \), there exist two terms \( M_i \) and \( N_i \) such that \( \text{fvars}(M_i) \cup \text{fvars}(N_i) \subseteq \text{dom}(\Phi) \), \( (M_i \not=_{E} N_i)\Phi \), and \( (M_i =_{E} N_i)\Phi' \).

Let \( \text{bad} \) be a fresh channel name that does not occur in \( A \) and \( B \). Let \( P_1, \ldots, P_m, P_{m+1} \) be the plain processes defined as follows:

- \( P_{m+1} \overset{\text{def}}{=} \text{out}(\text{bad}, \text{bad}).0 \)
- for \( 1 \leq i \leq m \), we define \( P_i \) as follows:
  \[
  P_i \overset{\text{def}}{=} \begin{cases} 
  M_i = N_i & \text{then } P_{i+1} \text{ else } 0 & \text{when } i \in T^+ \\
  M_i \not=_{E} N_i & \text{then } 0 \text{ else } P_{i+1} & \text{when } i \in T^- 
  \end{cases}
  \]

Let \( \{a_1, \ldots, a_k\} \) be channel names that occur free in \( A, B \), and \( \text{tr} \). Let \( X_{ch}^0 = \{a_1, \ldots, a_k\} \) be a set of variables of channel type, and \( \sigma = \{a_1 \mapsto a_1, \ldots, a_k \mapsto a_k\} \). We define \( C \) such that \( C = Q(\text{tr}, X_{ch}^0) \mid _{x} \) where \( Q(\text{tr}, X_{ch}) \) is defined by recurrence on \( \text{tr} \) as follows:

- if \( \text{tr} = \epsilon \) then \( Q(\text{tr}, X_{ch}) = P_1 \);
- if \( \text{tr} = \text{in}(a, M), \text{tr}' \) then \( Q(\text{tr}, X_{ch}) = \text{out}(x_a\sigma, M, Q(\text{tr}', X_{ch})) \);
- if \( \text{tr} = \text{out}(a, c), \text{tr}' \) then \( Q(\text{tr}, X_{ch}) = \text{in}(x_a\sigma, y) \) if \( y = x_c\sigma \) then \( Q(\text{tr}', X_{ch}) \) else 0 where \( y \) is fresh variable of channel type; and
- if \( \text{tr} = \nu c.\text{out}(a, c) \) then \( Q(\text{tr}, X_{ch}) = \text{in}(x_a\sigma, x_c) \) if \( x_c \in X_{ch}\sigma \) then 0 else \( Q(\text{tr}', X_{ch}) \) where \( X_{ch}' = X_{ch} \sqcup \{x_c\} \).

We use the conditional if \( u \in \{u_1, \ldots, u_k\} \) then 0 else \( P \) as a shortcut for

\[
\text{if } u = u_1 \text{ then } 0 \text{ else (if } u = u_2 \text{ then } 0 \text{ else (.... (if } u = u_k \text{ then } 0 \text{ else } P)).}
\]

We can see that \( C[A] \parallel_{\text{bad}} \) since \( (\text{tr}, \Phi) \in \text{trace}(A) \) and \( \Phi \) satisfies by definition all the tests that are tested in \( P_m \). However, by construction of \( C \), we have that \( C[B] \) does not emit on \( \text{bad} \).

The class of image-finite processes is not the only class of processes where the may-testing equivalence implies the trace equivalence. In [MNP12], they proved that the may-testing equivalence implies the trace equivalence using a property of their equational theory. They provide an equational theory \( E \) such that any frame could be characterized by a finite formula on terms modulo \( E \), i.e. for all frames \( \Phi \), a formula \( \phi \) is the characteristic formula of \( \Phi \) if for all frames \( \Phi', \Phi' \sim \Phi \) is equivalent to \( \Phi' \) (as substitution) satisfies \( \phi \). With such property on the equational theory, one can show that may-testing equivalence implies trace equivalence using a proof similar to the proof of Theorem 3.2. Typically, given a closed extended process \( A \) and a trace \( (\text{tr}, \Phi) \in \text{trace}(A) \), we build the same context \( C \) as in the proof of Theorem 3.2 except that the processes \( P_k \) will be defined following the characteristic formula of \( \Phi \).
3.3. SOME SECURITY PROPERTIES

3.2.4 Observational equivalence

Observational equivalence has been initially introduced as a mean for proving may-testing or trace equivalence. Comparing to may-testing and trace equivalence, the observation equivalence also checks the bisimilarity of the two processes.

**Definition 3.5** (observational equivalence). Observational equivalence is the largest symmetric relation \( R \) between closed extended processes with the same domain such that \( A R B \) implies:

1. if \( A \Downarrow c \), then \( B \Downarrow c \);
2. if \( A \Downarrow A' \), then \( B \Downarrow B' \) and \( A' R B' \) for some \( B' \);
3. \( C[A] R C[B] \) for all closing evaluation contexts \( C \).

However, proofs of observational equivalences are difficult because of the universal quantification over all contexts. Therefore, an alternative definition has been proposed, considering labeled transitions for the processes.

**Definition 3.6** (labeled bisimilarity \( \approx \)). Labeled bisimilarity is the largest symmetric relation \( R \) on closed extended processes such that \( A R B \) implies

1. \( \phi(A) \sim \phi(B) \),
2. if \( A \Downarrow A' \), then \( B \Downarrow B' \) and \( A' R B' \) for some \( B' \),
3. if \( A \Downarrow A' \) and \( \text{bnames}(\ell) \cap \text{fnames}(B) = \emptyset \), then \( B \Downarrow B' \) and \( A' R B' \) for some \( B' \).

**Example 3.8.** Consider the theory \( E_{aenc} \) and the two processes \( P_a = \text{out}(c, a\text{enc}(a, pk(sk))) \) and \( P_b = \text{out}(c, a\text{enc}(b, pk(sk))) \). We have that \( \nu sk.P_a \approx \nu sk.P_b \) whereas \( P_a \not\approx P_b \). These results are direct consequences of the static (in)equivalence relations stated and discussed in Example 3.5.

It has been shown that observational equivalence coincides with labeled bisimilarity [AF01, Liu11]. In the literature, one can also find several results about the relation between observational and trace equivalence. As expected, observational equivalence is strictly stronger than trace equivalence. J. Engelfriet has shown that observational equivalence and trace equivalence actually coincide in a general model of parallel computation with atomic actions, when processes are determinate [Eng85]. In [CD09], the authors generalise this result to the applied pi calculus and show that a large class of processes, named simple processes, enjoys the determinacy property.

3.3 Some security properties

We presented different behavioural equivalences in Section 3.2 which typically differ from the power we give to the attacker. When describing the security properties we will use the trace equivalence, i.e. \( \approx \), however all these security properties are still valid when replacing the trace equivalence by an other behavioural equivalence. Of course, since some behavioural equivalences are stronger than others (see Section 3.2), one protocol might satisfy a security property for one behavioural equivalence and not for an other equivalence. We present in this section some security properties that has been studied in the literature and we provide small examples to illustrate them.

3.3.1 Guessing attacks

In our model, we assume that all cryptographic primitives are perfect. For example, an intruder cannot obtain \( a \) from \( a\text{enc}(a, k) \) without knowing the secret key \( k \). Typically, this assumption relies on the length of the key to ensure that an intruder cannot try all possible passwords, i.e. break the cipher using a brute force attack. However, in many applications such as mail, online bank account, etc, a human user will usually use a password whose length is at most 20 characters.
Thanks to the power of nowadays computers, an intruder may be able deduce these passwords using a brute force attack. These short passwords are called *weak secret*.

However, a weak secret is not necessary a flaw in the security of a protocol. Indeed, during a brute force attack, an intruder still has to distinguish the cases where he guessed the correct key or not. Hence the notion of *guessing attack* was introduced to represent the capability of an intruder to deduce weak secret and obtain relevant information from it. Typically, a guessing attack works as follows: The intruder first interacts with several sessions of a protocol (usually small number of sessions since most of online protocols allow only a small number of fail attempts on your password) then in a next phase the intruder may try *offline* all possible passwords on the message he previously received, i.e. *guessing a key is done without interaction with the protocols*.

Although guessing attacks are considered as equivalence properties, they are not modelled by equivalence of processes but equivalence of frames instead. The is formalise by the following definition [DKR08 Bau05].

**Definition 3.7.** Let $vk.\Phi$ be a closed frame. Assume that $k$ is a weak secret. We say that $vk.\Phi$ is resistant to guessing attacks on $k$ if, and only if, $vk.(\Phi \mid \{x/x\}) \approx vn.vk.(\Phi \mid \{n/n\})$ where $x \notin \text{dom}(\Phi)$ and $n$ is a fresh name.

An extended process $A$ is resistant to guessing attacks on $k \in \text{bnames}(A)$ if for every $(tr, B) \in \text{trace}(A)$, $B(\Phi)$ is resistant to guessing attacks on $k$.

**Example 3.9.** Consider the Handshake protocol given in Example 3.1. We show that the handshake protocol is not resistant to guessing attacks on $k$. Indeed, let’s denote $A$ the process from Example 3.7.

Hence $(tr, vk\_AB.\Phi) \in \text{trace}(A)$ where $tr = \nu w_1.\text{out}(c, w_1).\text{in}(c, w_1).\nu w_2.\text{out}(c, w_2)$ and $\Phi = \nu N.\nu l.\{(\text{senc}(N, k, n)/w_1) \mid \{\text{senc}(f(N), k, n)/w_2\}\}$. However, one can note that $vk\_AB.(\Phi \mid \{k/n\}) \neq vk\_AB.vk(\Phi \mid \{k/n\})$. Indeed, the test $\text{sdec}(w_2, w_3) = \exists f(\text{sdec}(w_1, w_3))$ can distinguish the two frames. This attacks is well known and can be found in the literature [GML+93].

### 3.3.2 Strong secrecy

When two honest agents exchange a secret during the execution of a protocol, we usually want that this secret may never be deduce by an intruder. This security property, called *simple secrecy*, is in fact a reachability property and do not require behavioural equivalence to be modelled.

On the other hand, there exists a stronger security property, called *strong secrecy* and introduced in [Bla04], where an intruder must not notice when the value of the secret changes. The strong secrecy can be model as follows:

**Definition 3.8.** Let $A$ be a closed extended process such that $A \equiv C[A' \mid \{M/x\}]$ for some evaluation context $C$, extended process $A'$, term $M$. We say that $A$ preserves the strong secrecy of $M$ if we have:

$$C[A' \mid \{M/x\}] \approx_t nk.C[A' \mid \{k/x\}]$$

The original definition of strong secrecy can be found in [Bla04] and is slightly stronger that the one we provide. Indeed, instead of checking the strong secrecy of a specific message, they check the strong secrecy of a free variable which can be replaced by any message. While these two notions do not coincide in general, they do coincide for many usual equational theories.

### 3.3.3 Anonymity

Anonymity is informally defined by the ISO/IEC standard 15408 [ISO99] as the property ensuring that a user may use a service or a resource without disclosing the user’s identity. Formally, anonymity has been defined to hold [ACRR10] when an outside observer cannot tell the difference between a system in which the user with a publicly known identity $id_0$ executes the analysed protocol, from the system where $id_0$ is not present at all.
3.3. SOME SECURITY PROPERTIES

Definition 3.9. Let $P$ be a closed extend process. Let $\nu k$ stands for $\nu k_1 \ldots \nu k_n$ where $k_1, \ldots, k_n$ are long term secrets used in $P$. We say that $P$ satisfies anonymity if the following equivalence holds:

$$\nu k.((\nu \text{id}. \nu P | \nu P\{id_0/\text{id}\}) \approx_{\nu} \nu k.((\nu \text{id}. \nu P$$

where id might be contained in $P$ and $id_0$ is a fresh free name.

Intuitively, anonymity is satisfied if an observer cannot tell if the user $id_0$ (known to the attacker) has been executing the protocol $P$ or not. Note that if $P$ does not contain id, the anonymity trivially holds.

If we look at, as it is often done in automatic protocol verification, a bounded number of sessions of the protocol $P$, the above formal property needs to be adapted. In the case of one session for example, we will say that $P$ preserves anonymity if the following equivalence holds

$$\nu k. P\{id_1/\text{id}\} \approx \nu k. P\{id_2/\text{id}\}$$

Informally, this corresponds to the fact that an attacker cannot tell if a session of $P$ is executed by $id_1$ or by some other user $id_2$.

Example 3.10. We consider a simplified version of a protocol given in [AF04] designed for transmitting a secret without revealing its identity to other participants. In this protocol, $A$ wishes to engage in communication with $B$ whereas $B$ is willing to talk to $A$. However, $A$ does not want to compromise its privacy by revealing its identity or the identity of $B$ more broadly. The participants $A$ and $B$ proceed as follows:

$A \rightarrow B : \text{aenc}\langle N_a, pk_A, pk_B \rangle$

$B \rightarrow A : \text{aenc}\langle N_b, (N_b, pk_B), pk_A \rangle$

First $A$ sends to $B$ a nonce $N_a$ and its public key encrypted with the public key of $B$. If the message is of the expected form then $B$ sends to $A$ the nonce $N_a$, a freshly generated nonce $N_b$ and its public key, all of this being encrypted with the public key of $A$. Otherwise, $B$ sends out a “decoy” message: $\text{aenc}(N_b, pk_B)$. This message should basically look like $B$’s other message from the point of view of an outsider. This is important since the protocol is supposed to protect the identity of the participants.

When $A$ receives a message from $B$, $A$ tries to decrypt it and checks that the second component of the decryption corresponds to the nonce $N_a$ he first created. He also checks that the third component corresponds to the public key of $B$. If the checks fail then $A$ does nothing. After a successful execution of this protocol, $A$ and $B$ will be able to use $N_A$ and $N_b$ as shared secrets. However for the sake of simplicity, we will consider here that they do nothing.

In this protocol, we assume that the association between principals and their public keys is known, even to the intruder. This might be model in the applied pi calculus by a server that outputs the public key of a principal associated with its identification.

A session of role $B$ played by agent $b$ with $a$ can be modelled by the plain process $B(b, a)$ where $N = \text{aenc}(y, sk_b)$. Note that $B$ is not given the value $sk_a$ but is directly given the public key $pk(sk_a)$, that is the public key corresponding to $A$’s private key. Similarly, a session of role $A$ played by agent $a$ with $b$ can be modeled by the plain process $A(a, b)$ where $M = \text{aenc}(z, sk_a)$.

$$A(a, b) \equiv \nu n_a. \text{out}(c, \text{aenc}\langle n_a, pk_A, pk_B \rangle). \text{in}(c, z).0$$

$$B(b, a) \equiv \nu n_b. \text{in}(c, y). \text{if proj}_2(N) = pk(sk_a) \text{ then out}(c, \text{aenc}\langle proj_1(N), \langle n_b, pk_B \rangle, pk_A \rangle).0 \text{ else out}(c, \text{aenc}\langle n_b, pk_B \rangle).0$$

Intuitively, this protocol preserves anonymity of the participant $a$ if an attacker cannot distinguish whether $b$ is willing to talk to $a$ (represented by the process $B(b, a)$) or willing to talk to $a'$
(represented by the process \(B(b, a')\)), provided that \(a, a'\) and \(b\) are honest participants. This can be modeled by the following equivalence:

\[
\nu_{sk_a} . \nu_{sk_{a'}} . \nu_{sk_b} . (S \mid B(b, a) \mid A(a, b)) \approx_t \nu_{sk_a} . \nu_{sk_{a'}} . \nu_{sk_b} . (S \mid B(b, a') \mid A(a', b))
\]

where \(S\) represents the server that associates principals and their public keys, i.e.

\[
S \overset{\text{def}}{=} \{ (a, \nu_{pk}(sk_a)) / z_1 \} \cup \{ (a', \nu_{pk}(sk_{a'})) / z_2 \} \cup \{ (b, \nu_{pk}(sk_b)) / z_3 \}
\]

This is a non-trivial equivalence however the “decoy” message plays an important role. Indeed, considering now the process \(B^-(b, a)\) where, instead of sending a decoy message when the test fails, the process does nothing:

\[
B^-(b, a) \overset{\text{def}}{=} \nu_{n_b}.\text{in}(c, y), \text{if} \ \text{proj}_2(N) = \nu_{pk}(sk_a) \text{ then } \text{out}(c, \text{aenc}(\langle \text{proj}_1(N), (n_b, \nu_{pk}(sk_b)), \nu_{pk}(sk_a) \rangle)), 0 \\
\text{else } 0
\]

In such a case, the trace equivalence does not hold anymore. This can be easily shown by considering the sequence of actions \(s = \text{in}(c, \text{aenc}(\langle n_1, \text{proj}_1(z_1), \text{proj}_2(z_2) \rangle)), \text{v.x.out}(c, x)\). We have that \((s, \Phi) \in \text{trace}(\nu_{sk_a} . \nu_{sk_{a'}} . \nu_{sk_b} . (S \mid B^-(b, a) \mid A(a, b)))\) for some \(\Phi\). However, this sequence does not have a corresponding trace for the process \(\nu_{sk_a} . \nu_{sk_{a'}} . \nu_{sk_b} . (S \mid B^-(b, a') \mid A(a', b))\).

### 3.3.4 Unlinkability

Unlinkability is informally defined by the ISO/IEC standard 15408 [ISO09] as the property ensuring that a user may make multiple uses of a service or a resource without others being able to link these uses together. Formally, unlinkability has been defined to hold [ACRR10] when a system in which the analysed protocol can be executed by each user multiple times looks the same to an outside observer that the system in which the analysed protocol can be executed by each user at most once.

**Definition 3.10.** Let \(P\) be a closed extend process. Let \(\nu \bar{\nu}\) stands for \(\nu k_1, \ldots, \nu k_n\) where \(k_1, \ldots, k_n\) are long term secrets used in \(P\). We say that \(P\) satisfies unlinkability if the following equivalence holds:

\[
\nu \bar{\nu} . \text{vid} . !P \approx_t \nu \bar{\nu} . \text{vid} . P
\]

where \(id\) might be contained in \(P\).

In other words, unlinkability is satisfied if an observer cannot tell if the users can execute multiple or at most once the protocol \(P\). Note that if \(P\) does not contain \(id\) then the equivalence trivially holds.

Now one can also look at a bounded number of sessions of the protocol. In this case we need to consider at least two sessions. Consider two sessions of the protocol, we will say that \(P\) preserves unlinkability if the following equivalence holds

\[
\nu \bar{\nu} . \text{vid} . (P \mid P) \approx_t \nu \bar{\nu} . (\text{vid}.P \mid \text{vid}.P)
\]

Informally, this corresponds to the fact that an attacker cannot tell if the two sessions of \(P\) are executed by the same user, or by two different users.

Note that if we consider more than two sessions, several equivalences are possible to express unlinkability. For example, if you consider three sessions of the protocol, one might consider that the three sessions are executed by the same user and one might also consider that two out of three sessions are executed by the same user while the third session is executed by another user. Section 3.4 illustrates this security property on the e-passport protocol.
3.4 The e-passport protocol

One of the purposes of this thesis is to apply our results (practical and theoretical) on concrete protocols such as the e-passport protocol. Indeed, passports now contain a chip that stores additional information such as pictures and fingerprints of its holder. In order to ensure privacy, these chips include a mechanism that do not let the passport disclose private information to external users. Section 3.3 formally describes the e-passport protocol that was partially studied in [ACRR10] and the security properties we are interested in, i.e. anonymity and unlinkability.

An electronic passport (or e-passport) is a paper passport with an RFID chip that stores the critical information printed on the passport. The International Civil Aviation Organisation (ICAO) standard [ICA04] specifies the communication protocols that are used to access these information.

3.4.1 Protocols description

The information stored in the chip is organised in data groups ($dg_1$ to $dg_{19}$). For example, $dg_5$ contains a JPEG copy of the displayed picture, and $dg_7$ contains the displayed signature. The verification key $vk(skp)$ of the passport, together with its certificate $\text{sign}(vk(skp), sk_DS)$ issued by the Document Signer authority are stored in $dg_{15}$. The corresponding signing key $sk_P$ is stored in a tamper resistant memory, and cannot be read or copied. For authentication purposes, a hash of all the $dgs$ together with a signature on this hash value issued by the Document Signer authority are stored in a separate file, the Security Object Document:

$$sod \overset{\text{def}}{=} \langle \text{sign}(h(dg_1, \ldots, dg_{19}), sk_DS), h(dg_1, \ldots, dg_{19}) \rangle.$$

The ICAO standard specifies several protocols through which these information can be accessed. First, the Basic Access Control (BAC) protocol establishes session keys $ksenc$ and $ksmac$ to prevent skimming and eavesdropping on the subsequent communication with the e-passport. Once the BAC protocol has been successfully executed, the reader gains access to the information stored in the RFID tag through the Passive Authentication and the Active Authentication protocols that can be executed in any order.

The Basic Access Control (BAC) protocol is a key establishment protocol (see Figure 3.2). It relies on the keys $ke$ and $km$ that are printed on the passport at the same page as your personal data and your picture (usually, the customs officer get the key $ke$ and $km$ by optically scanning your passport). These keys are usually composed of some of your personal data and some small random number, hence these keys are easily broken if the intruder knows some basic data of its target or if he had once access to its passport.

When the verification of a mac or the verification of the nonces $n_T$ and $n_R$ fail then an error message is outputted. [ACRR10] showed that the unlinkability of the BAC protocol is broken if the error messages are different (case of the french passport) hence we will consider that the errors messages outputted are the same (case of the english passport).

The detail of the functions $f_1$ and $f_2$ are not important. We use them to illustrate the fact that the key sessions that will be used in the next two protocols are derived from $k_T$ and $k_R$.

The Active Authentication (AA) protocol is an authentication mechanism that prevents cloning of the passport chip (see Figure 3.3). It relies on the fact that the secret key $sk_p$ of the passport cannot be read or copied. The reader sends a random challenge to the passport, that has to return a signature on this challenge using its private signature key $sk_p$. The reader can then verify using the verification key $vk(skp)$ that the signature was built using the expected passport key.

The Passive Authentication (PA) protocol is an authentication mechanism that proves that the content of the RFID chip is authentic (see Figure 3.4). Through PA the reader retrieves the information stored in the $dgs$ and the $sod$. It then verifies that the hash value stored in the $sod$ corresponds to the one signed by the Document Signer authority. It further checks that this hash value is consistent with the received $dgs$. 
3.4.2 Security analysis

The protocols BAC, PA and AA rely on symmetric encryption, message authentication codes, signatures and the verification key generation function, to meet their security requirements.

According to the ICAO standard, once the keys ksenc and ksmac have been established using the BAC protocol, the reader can decide to execute PA and/or AA in any order. Formally, it corresponds to the parallel composition of PA and AA. Note that the execution of PA and AA occurring only when BAC succeed implies that the processes modeling BAC are in fact contexts on which the processes of PA and AA are plugged. However, instead of considering the three protocols at the same time, we might want to analyze first the privacy of BAC in isolation. Then, after considering that the keys ksenc and ksmac are “securely” pre-shared, we analyze the privacy of the parallel composition of PA and AA. Hence, in this section, we will provide the equivalences that model anonymity and unlinkability for BAC protocol in isolation, and also for the the parallel composition of PA and AA under securely pre-shared ksenc and ksmac.

3.4.2.1 Security of BAC

We consider an arbitrary number of passports, each running an arbitrary number of times the BAC protocol. This situation can be modelled in our calculus as follows:

\[ P \overset{def}{=} !\nu ke. \nu km. !BAC \]

where the subprocess BAC model one session of the BAC protocol respectively. Typically, each successful session of BAC create fresh session keys ksenc and ksmac that will be used in the PA and AA protocols.
To express unlinkability discussed in Section 3.3.4, we need on one hand to consider a system in which e-passports can execute the BAC protocol multiple times, and on the other hand a system in which e-passports can execute the BAC protocol at most once. This is modeled by the following equivalence:

\[ \nu \text{ke. } \nu \text{km. } BAC \approx \nu \text{ke. } \nu \text{km. } BAC \]

Normally, to express anonymity discussed in Section 3.3, we would need to consider a victim’s e-passport but in the BAC protocol, the only data that can relevantly identify an e-passport
are the keys \( ke \) and \( km \). However, if we allow the intruder to know the value of \( ke \) and \( km \) of the victim’s passport then it trivially breaks the anonymity of the protocol (he only has to try decrypting messages, if the decryption succeed then it is the victim’s passport else it is not). On the other, if we do not allow the intruder to know the value of the keys \( ke \) and \( km \) of the victim’s passport then the equivalence would be trivial, i.e. \( !\text{vke} . \text{vkm} . !\text{BAC} \equiv_1 !\text{vke} . \text{vkm} . !\text{BAC} \), and so the anonymity is trivially preserved.

### 3.4.2.2 Security of the parallel composition of \( PA \) and \( AA \)

This case is very similar to the privacy of the BAC protocol. However, there is a lot more information (i.e. nonces) that is used in the \( PA \) and \( AA \) protocols, hence one should be be careful about the names that depend on the passport itself and the one that depend on a session of the protocols. We consider an arbitrary number of passports, each running an arbitrary number of times the \( PA \) and the \( AA \) protocols. This situation can be modelled in our calculus as follows:

\[
P \stackrel{\text{def}}{=} \nu_{sk_{DS}}. !\nu_{skp} \cdot \nu_{vid} \cdot \nu_{vsig} \cdot \nu_{vpic} \cdot \ldots \cdot !\nu_{ksenc} \cdot \nu_{vksmac} \cdot (PA \parallel AA)
\]

where \( id, sig, pic, \ldots \) represent the name, the signature, the displayed picture, etc. of the e-passport owner, i.e. the data stored in the \( dgs \) (1-14) and (16-19). The subprocesses \( PA \) and \( AA \) model one session of the \( PA \) and \( AA \) protocol respectively. The name \( sk_{DS} \) models the signing key of the Document Signing authority used in all passports. Each passport (identified by its signing key \( sk_p \), the owner’s name, picture, signature, ...) can run multiple times and in any order the \( PA \) and \( AA \) protocols, but with different secret session keys \( ksenc \) and \( ksmac \), that should be established through execution of the BAC protocol (but that we have abstracted from).

#### Anonymity

To formally express anonymity discussed in Section 3.3.3 we will need to consider a victim’s e-passport, whose name \( id_0 \), signature \( sig_0 \), picture \( pic_0 \), etc. are known to the attacker. The victim’s e-passport follows like any other e-passport the \( PA \) and \( AA \) protocols which can be respectively modelled by the following processes:

\[
PA_0 \stackrel{\text{def}}{=} PA[\{id_0/id, sig_0/sig, pic_0/pic, \ldots, sk_{P0}\}]
\]
\[
AA_0 \stackrel{\text{def}}{=} AA[\{id_0/id, sig_0/sig, pic_0/pic, \ldots, sk_{P0}\}]
\]

To formally express anonymity, we will consider the following contexts:

\[
C[\ldots]_1, \ldots}_2 \stackrel{\text{def}}{=} !\nu_{skp} \cdot \nu_{vid} \cdot \nu_{vsig} \cdot \nu_{vpic} \cdot \ldots \cdot !\nu_{ksenc} \cdot \nu_{vksmac}._1 \\
| !\nu_{sk_{P0}} \cdot !\nu_{ksenc} \cdot \nu_{vksmac}._2
\]

where the second hole will be filled with the process modelling the victim’s e-passport, while the first hole will be filled with the processes modelling any other e-passport. Note that the signing key \( sk_{P0} \) of the victim’s passport is not known to the attacker. The latter may know the verification key \( \nu_{k}(sk_{P0}) \) (accessible from \( d_{g15} \)) but not the signing key which is stored in a tamper resistant memory.

This system will be compared to the one where the victim’s e-passport is not present at all. For this we consider the following context:

\[
C'[]_1 \stackrel{\text{def}}{=} !\nu_{skp} \cdot \nu_{vid} \cdot \nu_{vsig} \cdot \nu_{vpic} \cdot \ldots \cdot !\nu_{ksenc} \cdot \nu_{vksmac}._1
\]

whose unique hole will be filled with the processes modelling any e-passport but the victim’s. Hence the anonymity of the \( PA \) and the \( AA \) protocols is modelled by the following equivalence:

\[
\nu_{sk_{DS}} \cdot C[PA \parallel AA, PA_0 \parallel AA_0] \equiv_1 \nu_{sk_{DS}} \cdot C'[PA \parallel AA]
\]
Unlinkability. To express unlinkability discussed in Section 3.3.3 we need on one hand to consider a system in which e-passports can execute the PA and AA protocols multiple times, and on the other hand a system in which e-passports can execute the PA and AA protocols at most once. For this we consider the two following contexts:

\[ C[\_\_] \text{ def } \nu skp. \nu id. \nu sig. \nu pic. \ldots \nu ksenc. \nu ksmac. \]

\[ C'[\_\_] \text{ def } \nu skp. \nu id. \nu sig. \nu pic. \ldots \nu ksenc. \nu ksmac. \]

These two contexts differ on the replication before the generation of the session keys \( ksenc \) and \( ksmac \), modelling in the first case an unbounded number of executions of the process that will fill the unique hole, and in the second case a unique session of the filling process. Hence the unlinkability of the PA and the AA protocols is modelled by the following equivalence:

\[ \nu sk_{DS}.C[PA \mid AA] \equiv_t \nu sk_{DS}.C'[PA \mid AA] \]
Chapter 4

Towards deciding trace equivalence

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In the previous chapter, we presented several definitions of behavioural equivalence that can be used to model the observational capabilities of an intruder. Hence, when verifying an equivalence property on a cryptographic protocol, the choice of the behavioural equivalence that we have to check is crucial. As mentioned in the introduction, the question of knowing which equivalence is best-suited to model an intruder is disputable. Although the may-testing equivalence is, in our opinion, the most appropriate equivalence to model the observational capabilities of an intruder, we prefer the trace equivalence that is easier to manipulate. This choice does not matter when considering bounded number of sessions since both equivalences coincide in such a case (see Section 3.2.3).

Moreover, the proof of [CC08] indicates that standard cryptographic definitions for security, based on indistinguishable games, are soundly abstracted by trace equivalence, with no need for observational equivalence. Conversely, two processes may not be observationally equivalent and yet be cryptographically indistinguishable.

The main contribution of this chapter is to adapt, from existing results, a proof technique for deciding trace equivalence. Since replication very quickly yields to undecidability even in the simpler case of accessibility properties [DLMS99, AC02], we focus here on processes without replication.

We show a reduction result for general processes without replication and for arbitrary equational theories. We reduce the decidability of trace equivalence (for bounded processes) to deciding symbolic equivalence between sets of constraint systems. To transfer executions from the applied pi
As mentioned in [DKR07], the semantics of the applied pi calculus is not well-suited for defining a symbolic semantics. One of the main reasons is the presence of the structural equivalence in the semantics. It leads to too many traces for the same sequence of actions that are not necessary when studying behavioural equivalence and in particular the trace equivalence. On the other hand, the semantics of intermediate processes are more linear than the applied pi calculus semantics.

### 4.1 Intermediate calculus

We consider a new infinite subset of $\mathcal{X}$, called parameters, $\mathcal{AX} = \{ax_1, ax_2, \ldots, ax_n, \ldots\}$. Typically, the parameters will be used to express the domain of a frame and will avoid the possible confusion with the variables inside a process.

**Definition 4.1 (intermediate process).** An intermediate process is a triple $(E; P; \Phi)$ where:

- $E$ is a set of names that represents the names restricted in $P$;
- $\Phi = \{ax_1 \triangleright t_1, \ldots, ax_n \triangleright t_n\}$ where $t_1, \ldots, t_n$ are ground terms, and $ax_1, \ldots, ax_n \in \mathcal{AX}$ are parameters;
- $P$ is a multiset of plain processes such that null processes are removed and $\text{fvars}(P) = \emptyset$.

Additionally, we require intermediate processes to be variable distinct, i.e. any variable is at most bound once.

Given a sequence $\Phi = \{ax_1 \triangleright t_1, \ldots, ax_n \triangleright t_n\}$ where $t_1, \ldots, t_n$ are terms, we also denote by $\Phi$ its associated frame, i.e. $\{t_1/ax_1\} \mid \ldots \mid \{t_n/ax_n\}$.

Given a closed extended process $A$ of the original applied pi, we can easily transform it into an intermediate process $\tilde{A} = (E; P; \Phi)$ such that $A$ is structurally equivalent to $E.(P | \Phi)$ up to a renaming of the variables in $\text{dom}(\Phi)$. The idea is to rename names and variables to avoid clashes, to apply the active substitutions, to remove the restrictions on variables, and finally to push the restrictions on names, that define the scope of active substitutions with free variable, in front of the process.

**Example 4.1.** Consider the extended process $A$ described below ($M$ and $N$ are some terms that do not contain $n$):

$$\nu sk.\nu x.(\text{out}(c, \text{aenc}(x, \text{pk}(sk)))).\nu n.\text{out}(c, n).\text{out}(c, y) | \{M/x\} | \{N/y\}).$$

An intermediate process $A'$ associated to $A$ is:

$$A' = (E; P; \Phi) = ([sk]; \text{out}(c, \text{aenc}(M, \text{pk}(sk))).\nu n.\text{out}(c, n).\text{out}(c, N); \{ax_1 \triangleright N\}).$$

We have that $A[y \mapsto ax_1] \equiv \nu E.(P | \Phi)$. 

---

calculus to constraint systems, we introduce an intermediate calculus inspired by [DKR07, Liu11]. But contrary to their work, we allow replication in the process. This is useful when we want to prove some theoretical results such as our work on composition of trace equivalence (see Chapter 5).
4.1. INTERMEDIATE CALCULUS

4.1.2 Semantics

The semantics for intermediate processes is given in Figure 4.1. The rules OPEN-Chi, OUT-Chi, INi, OUT-Ti, and Pari correspond respectively to the rules OPEN-Ch, OUT-Ch, IN, OUT-T and PAR in the semantic of the applied pi calculus. The rules Commi, Theni, and Elsei correspond to the internal reduction of the applied pi calculus. The rules Newi and REPLi do not appear explicitly in the applied pi calculus but correspond in fact to the rule Struct.

For the rule OPEN-Chi, we consider a new infinite subset of \( \mathcal{N}_{\text{ch}} \), i.e. set of name of channel type, denoted \( \mathcal{C}h \) such that \( \mathcal{C}h = \{ c_1, \ldots, c_n, \ldots \} \). Hence, when in the rules in Figure 4.1 we indicate "\( c_m \) is a fresh channel name", it implies that the last application of the rule OPEN-Chi in the derivation used the name \( c_{m-1} \). Intuitively, we use this set of channel names to dismiss the sequence of actions \( tr \) equivalent through renaming of the bounded names of channel type in \( tr \). Note that one of the purpose of using the parameters in \( \mathcal{A}X \) is similar to the purpose of using the channel names in \( \mathcal{C}h \).

Let \( \mathcal{A}_i \) be the alphabet of actions for the intermediate semantics. For every \( w \in \mathcal{A}_i \) the relation \( \overset{w}{\Rightarrow}_i \) on intermediate processes is defined in the usual way. For \( s \in (\mathcal{A}_i \setminus \{ \tau \})^*, \) the relation \( \overset{\tau}{\Rightarrow}_i \) on intermediate processes is defined by: \( A \overset{\tau}{\Rightarrow}_i B \) if, and only if there exists \( w \in \mathcal{A}_i \) such that \( A \overset{w}{\Rightarrow}_i B \) and \( s \) is obtained by erasing all occurrences of \( \tau \). Note that by definition, intermediate processes are closed.

\[
\begin{align*}
(\mathcal{E}; \{ \text{if } u = v \text{ then } Q_1 \text{ else } Q_2 \} \uplus P; \Phi) & \overset{\tau}{\Rightarrow}_i (\mathcal{E}; \{ Q_1 \} \uplus P; \Phi) & (\text{THEN}) \\
(\mathcal{E}; \{ \text{if } u = v \text{ then } Q_1 \text{ else } Q_2 \} \uplus P; \Phi) & \overset{\tau}{\Rightarrow}_i (\mathcal{E}; \{ Q_2 \} \uplus P; \Phi) & (\text{ELSE}) \\
(\mathcal{E}; \{ \text{out}(p, u).Q_1; \text{in}(p, x).Q_2 \} \uplus P; \Phi) & \overset{\tau}{\Rightarrow}_i (\mathcal{E}; \{ Q_1; Q_2(x \mapsto u) \} \uplus P; \Phi) & (\text{COMM}) \\
(\mathcal{E}; \{ \text{out}(p, u).Q \} \uplus P; \Phi) & \overset{\text{out}(p,c)}{\Rightarrow}_i (\mathcal{E}; \{ Q \} \uplus P; \Phi) & (\text{OUT-Ch}) \\
(\mathcal{E}; \{ \text{out}(p, c).Q \} \uplus P; \Phi) & \overset{\nu c_m \cdot \text{out}(p,c_m)}{\Rightarrow}_i (\mathcal{E}; \{ \{ Q \} \uplus P \{ c \mapsto c_m \} \}; \Phi) & (\text{OPEN-Ch}) \\
(\mathcal{E}; \{ v.K \} \uplus P; \Phi) & \overset{\tau}{\Rightarrow}_i (\mathcal{E}; \{ n \}; Q \{ k \mapsto n \} \uplus P; \Phi) & (\text{New}) \\
(\mathcal{E}; \{ \tau \} \uplus P; \Phi) & \overset{\tau}{\Rightarrow}_i (\mathcal{E}; \{ Q \} \uplus P; \Phi) & (\text{REPL}) \\
(\mathcal{E}; \{ P_1 | P_2 \} \uplus P; \Phi) & \overset{\tau}{\Rightarrow}_i (\mathcal{E}; \{ P_1 \}; \Phi) & (\text{PAR})
\end{align*}
\]

where \( p, c \) are channel names, \( u, v \) are ground terms, and \( x \) is a variable.

Figure 4.1: Intermediate semantics

Example 4.2. Consider the P the following protocol:

\[
\nu v.\nu sk. \text{(out}(c_1, \text{senc}(s, sk)) \mid \text{in}(c_1, y).\text{out}(c_2, \text{sdec}(y, sk))).
\]

P is a plain process hence its associated intermediate process is \( \tilde{P} = (\emptyset; \{ P \}; \emptyset) \). Consider now the sequence of transitions for \( P \) described in Example 4.3. We had \( P \overset{\tau}{\Rightarrow} P' = \nu v.\nu sk. [\{ y / \emptyset \} \mid \{ \text{senc}(s, sk) \}/x] \) with \( tr = \text{vax}_1.\text{out}(c_1, ax_1).\text{in}(c_1, ax_1).\text{vax}_2.\text{out}(c_2, ax_2) \). The corresponding
trace of $P$ is obtained as follows:

$$
\begin{align*}
\tilde{P} & \xrightarrow{\tau_1} \xrightarrow{\tau_2} \xrightarrow{\tau_3} \tilde{P} \\
& \xrightarrow{\nu ax_1. out(c_1, ax_1)} \\
& \xrightarrow{\nu ax_2. out(c_2, ax_2)} \\
& = \{s', \text{sk}'\}; \{out(c_1, ax_1. adec(y, sk'))\}; \{\text{in}(c_1, y). out(c_2, ax_2. adec(y, sk'))\}; \emptyset \\
& \{s', \text{sk}'\}; \{\text{in}(c_1, y). out(c_2, ax_2. adec(y, sk'))\}; \{\text{ax}_1 \triangleright \text{adec}(s', \text{pk}(sk'))\} \\
& \{s', \text{sk}'\}; \emptyset; \{\text{ax}_1 \triangleright \text{adec}(s', \text{pk}(sk'))\}; \{ax_2 \triangleright M\}
\end{align*}
$$

with $M = \text{adec}(\text{senc}(s', \text{pk}(sk'))).$ Note that $M =_{E} s'.$ If we denote by $(\varepsilon_1; \mathcal{P}_1; \Phi_1)$ the last intermediate process in the derivation and $\tilde{t}' = \nu ax_1. out(c_1, ax_1). \text{in}(c_1, ax_1). \nu y. out(c_2, ax_2),$ we have that $\tilde{P} \xrightarrow{\nu ax_1. out(c_1, ax_1)} (\varepsilon_1; \mathcal{P}_1; \Phi_1).$ Furthermore, if we denote $\sigma$ the substitution $\{x \mapsto ax_1; y \mapsto ax_2\},$ we also have $\nu \varepsilon_1. \Phi_1 \equiv \Phi(P')\sigma$ and $\tilde{t}' = tr\sigma.$

In Example 3.4, we also consider a sequence of transitions with an internal reduction, i.e., $P = \nu s. \nu sk.(\{s'/y\})$ with $tr = \nu y. out(c_2, y).$ The corresponding trace of $P'$ is obtained as follows:

$$
\begin{align*}
\tilde{P} & \xrightarrow{\tau_1} \xrightarrow{\tau_2} \xrightarrow{\tau_3} \tilde{P} \\
& \xrightarrow{\nu ax_1. out(c_1, ax_1)} \\
& \xrightarrow{\nu ax_2. out(c_2, ax_2)} \\
& = \{s', \text{sk}'\}; \{out(c_1, ax_1. adec(y, sk'))\}; \{\text{in}(c_1, y). out(c_2, ax_2. adec(y, sk'))\}; \emptyset \\
& \{s', \text{sk}'\}; \{\text{in}(c_1, y). out(c_2, ax_2. adec(y, sk'))\}; \emptyset \\
& \{s', \text{sk}'\}; \emptyset; \{\text{ax}_1 \triangleright \text{adec}(s', \text{pk}(sk'))\}; \{ax_2 \triangleright M\}
\end{align*}
$$

with $M = \text{adec}(\text{senc}(s', \text{pk}(sk'))).$ Once again, if we denote by $(\varepsilon_1; \mathcal{P}_1; \Phi_1)$ the last intermediate process in the derivation and $\tilde{t}' = \nu ax_1. out(c_1, ax_1) ,$ then $\tilde{P} \xrightarrow{\nu ax_1. out(c_1, ax_1)} (\varepsilon_1; \mathcal{P}_1; \Phi_1).$ Furthermore, if we denote $\sigma$ the substitution $\{y \mapsto ax_1\},$ we also have $\nu \varepsilon_1. \Phi_1 \equiv \Phi(P')\sigma$ and $\tilde{t}' = tr\sigma.$

In both sequences of transitions, the rule New, creates fresh names $s'$ and $\text{sk}'$ while we could have kept $s$ and $\text{sk}$. It is important to create fresh names each time to avoid clashes between names, especially when the name restriction is under a replication.

### 4.1.3 Equivalence

Let $A = (\varepsilon_1; \mathcal{P}_1; \Phi_1)$ be an intermediate process. We define the set of its traces as follows:

$$\text{trace}_e(A) = \{s, \nu \varepsilon_2. \Phi_2 | (\varepsilon_1; \mathcal{P}_1; \Phi_1) \xrightarrow{\tau_i} (\varepsilon_2; \mathcal{P}_2; \Phi_2) \text{ for some } (\varepsilon_2; \mathcal{P}_2; \Phi_2)\}$$

Two intermediate processes are in (intermediate trace) equivalence if for any trace, the two corresponding frames are statically equivalent.

**Definition 4.2** ($\approx_i$ for intermediate processes). Let $A$ and $B$ be two intermediate processes having the same set of restricted names, i.e., $A = (\varepsilon_1; \mathcal{P}_1; \Phi_1),$ $B = (\varepsilon_2; \mathcal{P}_2; \Phi_2)$ and $\varepsilon_1 = \varepsilon_2.$

The processes $A$ and $B$ are intermediate trace equivalent, denoted by $A \approx_i B,$ if for every $(s, \nu \varepsilon. \Phi) \in \text{trace}_e(A)$ such that $\text{bnames}(s) \cap \text{frames}(B) = \emptyset$ there exists $(s', \nu \varepsilon'. \Phi') \in \text{trace}_e(B)$ such that $s = s'$ and $\nu \varepsilon. \Phi \sim \nu \varepsilon'. \Phi'$ (and conversely).

Despite the differences between the two semantics, it can be shown (see Proposition 4.11) that the two notions of trace equivalence coincide.

**Proposition 4.1.** Let $A$ and $B$ be two processes without replication. Consider the two associated intermediate processes: $(\varepsilon; \mathcal{P}; \Phi_A)$ and $(\varepsilon; \mathcal{P}; \Phi_B).$

The processes $A$ and $B$ are trace equivalent (i.e., $A \approx_i B$ in the original applied pi calculus semantics) if, and only if, $(\varepsilon; \mathcal{P}; \Phi_A) \approx_i (\varepsilon; \mathcal{P}; \Phi_B)$.

**Example 4.3.** Coming back to Example 3.10 the anonymity of the private authentication protocol is given by the following equivalence.

$$\nu sk_a. \nu sk_{a'}. \nu sk_b.(S \mid B(b, a) \mid A(a, b)) \approx_i \nu sk_a. \nu sk_{a'}. \nu sk_b.(S \mid B(b, a') \mid A(a', b))$$
where \( S \) represent the server that associates principals and their public keys, i.e.

\[
S \stackrel{\text{def}}{=} \{ \langle a, \text{pk}(sk_a) \rangle |_z_1 \} \cup \{ \langle a', \text{pk}(sk_{a'}) \rangle |_z_2 \} \cup \{ \langle b, \text{pk}(sk_b) \rangle |_z_3 \}
\]

where the processes \( B \) and \( A \) are both plain processes. This equivalence can also be expressed with intermediate processes. The server \( S \) will be put directly in the frame while the names \( sk_a, sk_{a'} \) and \( sk_b \) will be put into the set of restricted names:

\[
(\mathcal{E}; \{ B(b, a) \mid A(a, b) \}; \Phi_0) \approx \approx_1 (\mathcal{E}; \{ B(b, a') \mid A(a', b) \}; \Phi_0)
\]

where:

- \( \mathcal{E} = \{ ska, ska', skb \} \); and
- \( \Phi_0 = \{ ax_1 \triangleright \langle a, \text{pk}(sk_a) \rangle, ax_2 \triangleright \langle a', \text{pk}(sk_{a'}) \rangle, ax_3 \triangleright \langle b, \text{pk}(sk_b) \rangle \} \).

### 4.1.4 Bounded intermediate processes

As mentioned earlier, our intermediate semantics was inspired by [DKR07]. However, in their semantics, they do not have a rule for replication (since they consider processes without replication) but they also do not have a rule for name restriction. Indeed, [DKR07] considers a class of protocol where the restricted names where all pushed inside \( \mathcal{E} \).

**Example 4.4.** Consider the extended process \( A \) and its associated intermediate process \( A' \) in Example 4.1:

\[
A' = \{ \langle sk, n \rangle; \text{out}(c, a\text{enc}(M, \text{pk}(sk))) \}.\nu n. \text{out}(c, n). \text{out}(c, N); \{ ax_1 \triangleright N \}
\]

where \( M \) and \( N \) do not contain \( n \). We can build a similar intermediate process \( A' \) where we push \( n \) inside the set of restricted names:

\[
A'' = \{ \langle sk, n \rangle; \text{out}(c, a\text{enc}(M, \text{pk}(sk))) \}.\nu n. \text{out}(c, n). \text{out}(c, N); \{ ax_1 \triangleright N \}
\]

Note that \( A' \) and \( A'' \) are not in structural equivalence but we have \( A' \approx_1 A'' \). Indeed, structural equivalence does not allow one to push all the restrictions in front of a process.

Given an intermediate process \( A = (\mathcal{E}; P; \Phi) \) without replication and a fixed sequence of actions \( tr \), the presence of name restrictions in \( P \) yields necessary an infinite set of traces with this specific sequence of actions \( tr \) due to the infinite choice of name \( n \) in the rule \( \text{NEW} \). However, most of the frames of these traces only differ by renaming of bound variables. Intuitively, pushing the name inside the set of restricted names is similar to only considering one representative frame of \( \{ \Phi | (tr, \Phi) \in \text{trace}_e(A) \} \).

From now on, we will say that an intermediate process \( (\mathcal{E}; P; \Phi) \) is **bounded** if \( P \) do not contain replication nor name restriction. Given a process \( A = (\mathcal{E}; P; \Phi) \) without replication such that names are bound only once and there is no clash between free and bound variables, we will say that the process \( (\mathcal{E'; P'; \Phi'}) \) is its associated bounded intermediate process if \( \Phi = \Phi', \mathcal{E'} = \mathcal{E}, \cup \text{bnames}(P) \) and \( P' \) is the multiset \( P \) where any name restriction, i.e. \( vn \), are removed.

**Example 4.5.** Coming back to Example 4.1, the anonymity of the private authentication protocol can be expressed with bounded processes by the following equivalence:

\[
(\mathcal{E'}; \{ B'(b, a) \mid A'(a, b) \}; \Phi_0) \approx_1 (\mathcal{E'}; \{ B'(b, a') \mid A'(a', b) \}; \Phi_0)
\]

where \( \mathcal{E'} = \mathcal{E} \cup \{ n_a, n_b \} \) and \( A'(a, b), B'(b, a) \) are defined such that:

\[
A'(a, b) \stackrel{\text{def}}{=} \text{out}(c, a\text{enc}((n_a, \text{pk}(sk_a)), \text{pk}(sk_b))).\text{in}(c, z).0
\]

\[
B'(b, a) \stackrel{\text{def}}{=} \text{in}(c, y).\text{if } \text{proj}_2(N) = \text{pk}(sk_a)
\]

then \( \text{out}(c, a\text{enc}((\text{proj}_2(N), (n_b, \text{pk}(sk_b)), \text{pk}(sk_a))), 0
\]

else \( \text{out}(c, a\text{enc}(n_b, \text{pk}(sk_b))).0
\]
4.2 Symbolic calculus

In this section, we propose a symbolic semantics for our calculus similar to [Bau07, DKR07, RT01, CZ06]. By treating inputs symbolically, our symbolic semantics avoids potentially infinite branching of execution trees due to inputs from the environment. Correctness is maintained by associating with each process a set of constraints on terms. As mentioned in the previous section, we will only consider bounded intermediate processes in the rest of this chapter.

4.2.1 Constraint system

We consider a new set $\mathcal{X}^2$ of variables called second order variables $X, Y, \ldots$. In order to avoid conflict between the variables in $\mathcal{X}^2$ and the one we already used to described the protocol and the processes, we consider a new set $\mathcal{X}^1$ of variables, called first order variables, for the variables used in the processes. Note that $\mathcal{X}^1, \mathcal{X}^2, \mathcal{A}X$ are all disjoint subsets of $\mathcal{X}$. We call recipe, usually denoted $\xi$, the terms in $T(\mathcal{F}, \mathcal{N} \cup \mathcal{X}^2 \cup \mathcal{AX})$. We say that a recipe $\xi$ is closed (or ground) if $\xi \in T(\mathcal{F}, \mathcal{N} \cup \mathcal{AX})$. Given a recipe $\xi \in T(\mathcal{F}, \mathcal{N} \cup \mathcal{X}^2 \cup \mathcal{AX})$, we denote $\text{param}(\xi)$ the set of parameter in $\xi$, i.e. $\text{vars}(\xi) \cap \mathcal{AX}$.

A constraint system represents the possible executions of a protocol once an interleaving has been fixed.

**Definition 4.3** (constraint system). A constraint system is a tuple $(\mathcal{E}; \Phi; D; Eq)$ where

- $\mathcal{E}$ is a set of names (names that are initially unknown to the attacker);
- $\Phi$ is a sequence of the form $\{ax_1 \triangleright t_1, \ldots, ax_n \triangleright t_n\}$ where $t_i$ are terms and $ax_i$ are variables of $\mathcal{AX}$.
- $D$ is a set of deducible constraints of the form $X, i \triangleright x$ with $i \leq n$, $X \in \mathcal{X}^2$, $x \in \mathcal{X}^1$.
- $Eq$ is a set of equations and inequations of the form $s \equiv s'$ or $s \not\equiv s'$ where $s, s'$ are first-order terms of same type.

Intuitively, the terms $t_i$ represent the terms sent on the network, their variables represent messages sent by the attacker. Moreover, a constraint $X, i \triangleright x$ is meant to ensure that $x$ will be replaced by a deducible term. The size of $\Phi$, denoted $|\Phi|$ is its length $n$. Given a set $D$ of constraints, we denote by $\text{vars}^1(D)$ (resp. $\text{vars}^2(D)$) the first order (resp. second order) variables of $D$, that is $\text{vars}^1(D) = \text{feats}(D) \cap \mathcal{X}^1$ (resp. $\text{vars}^2(D) = \text{feats}(D) \cap \mathcal{X}^2$).

We also assume the following conditions are satisfied on a constraint system:

1. for every $x \in \text{vars}^1(D)$, there exists a unique $X$ such that $(X, i \triangleright x) \in D$, and each variable $X$ occurs at most once in $D$.

2. for every $1 \leq k \leq n$, for every $x \in \text{vars}^2(t_k)$, there exists $(X, i \triangleright x) \in D$ such that $i < k$.

The last property implies that any variables in $\Phi$ must be previously introduced by a deducible constraint in $D$. Given a recipe $\xi$ with parameters included in $ax_1, \ldots, ax_k$ and $\Phi = \{ax_1 \triangleright t_1, \ldots, ax_n \triangleright t_n\}$, $n \geq k$, $\xi \Phi$ denotes the term $\xi$ where each $ax_i$ has been replaced by $t_i$. The structure of a constraint system $\mathcal{C} = (\mathcal{E}; \Phi; D; Eq)$ is given by $\mathcal{E}$, $|\Phi|$ and $\{(X, i) \mid (X, i \triangleright x) \in D\}$. A positive constraint system is a constraint system that does not contain any inequation.

**Example 4.6.** The tuple $\mathcal{C}_1 = (\mathcal{E}; \Phi_0 \cup \{ax_4 \triangleright t\}; D_1; Eq_1)$ where

- $\mathcal{E} = \{sk_a, sk_{a'}, sk_b, n_b, n_a\}$,
- $\Phi_0 = \{ax_1 \triangleright \langle a, pk(sk_a) \rangle, ax_2 \triangleright \langle a', pk(sk_{a'}) \rangle, ax_3 \triangleright \langle b, pk(sk_b) \rangle\}$. 

4.2. SYMBOLIC CALCULUS

- \( t = a\text{enc}(\langle \pi_1(\text{adec}(y, sk_b)), \langle n_b, \text{pk}(sk_a) \rangle ), \text{pk}(sk_a)) \),
- \( D_1 = \{ Z_1, 3 \vdash z_1x; Y, 3 \vdash y; Z_2, 3 \vdash z_2 \}; \) and
- \( Eq_1 = \{ z_1 \overset{\sigma}{=} c; \text{proj}_2(\text{adec}(y, sk_b)) \overset{\sigma}{=} \text{pk}(sk_a); z_2 \overset{\sigma}{=} c \}. \)

is a constraint system. We will see that it corresponds to an execution of the process \( B'(b, a) \) presented in Example 4.3.

**Definition 4.4** (solution). A solution of a constraint system \( \mathcal{C} = (\mathcal{E}; \Phi; D; Eq) \) is a pair of substitutions \( (\sigma, \theta) \) such that \( \sigma \) is a mapping from \( \text{vars}^1(\mathcal{C}) \) to \( T(\mathcal{F}, \mathcal{N}) \) and \( \theta \) is a mapping from \( \text{vars}^2(\mathcal{C}) \) to \( T(\mathcal{F}, \mathcal{N}) \) such that:

1. for every \( (X, k \mapsto x) \in D \), we have that \( (X, k \mapsto x)(\Phi \sigma) = x \sigma \) and \( \text{param}(X, k \mapsto x) \subseteq \{ ax_1, \ldots, ax_k \} \);
2. for every \( (s \overset{\sigma}{=} s') \in Eq \), we have that \( s \sigma =_E s' \sigma \);
3. for every \( (s \not\overset{\sigma}{=} s') \in Eq \), we have that \( s \sigma \neq_\mathcal{E} s' \sigma \).

The substitution \( \theta \) is called second-order solution of \( \mathcal{C} \), and the substitution \( \sigma \) is called the first-order solution of \( \mathcal{C} \) associated to \( \theta \). The set of solutions of a constraint system \( \mathcal{C} \) is denoted \( \text{Sol}(\mathcal{C}) \). A constraint system \( \mathcal{C} \) is satisfiable if \( \text{Sol}(\mathcal{C}) \neq \emptyset \).

Intuitively, in the preceding definition the substitution \( \theta \) stores the computation done by the adversary in order to compute the messages he sends (stored in \( \sigma \)) during the execution.

**Example 4.7.** Continuing Example 4.6, a solution to \( \mathcal{C}_1 = (\mathcal{E}_1; \Phi_1; D_1; Eq_1) \) is \( (\sigma, \theta) \) where \( \text{dom}(\theta) = \{ Z_1, Z_2, Y \} \), \( Z_1 \theta = Z_2 \theta = c \), and \( \mathcal{Y} \theta = a\text{enc}(\langle n_1, \text{proj}_2(ax_1) \rangle, \text{proj}_2(ax_2)) \) with \( n_1 \) a public name of base type (i.e. \( n_1 \notin \mathcal{E}_1 \)). Furthermore, \( \sigma \) is the substitution whose domain is \( \{ z_1, z_2, y \} \) and such that \( z_1 \sigma = z_2 \sigma = c \), and \( y \sigma = a\text{enc}(\langle n_1, \text{pk}(sk_a) \rangle, \text{pk}(sk_b)) \).

Note that given a constraint system and a substitution \( \theta \), there exists at most one substitution \( \sigma \) such that \( (\sigma, \theta) \) is a solution of this constraint system. On the other hand, given a substitution \( \sigma \), there might exist several substitutions \( \theta \) such that \( (\sigma, \theta) \) is a solution. Intuitively, this due to the fact that there might exist several ways, i.e. recipes, to deduce a term. For example, we can deduce a from \( \langle a, a \rangle \) by applying the first or the second projection. This is why one can find works in the literature (e.g. [Handy?] where the solutions of a constraint system are only described trough the second-order solution. However, having both substitutions as representation of a solution is, in our opinion, more intuitive and facilitate manipulation of solutions in proofs.

As for processes in the applied-pi calculus, it is also possible to define equivalence of (sets of) constraint systems. Two sets of constraint systems \( \Sigma \) and \( \Sigma' \) are in equivalence if for any solution of a constraint system in \( \Sigma \), there exists a constraint system in \( \Sigma' \) that has the same solution and such that the resulting frames are in static equivalence.

**Definition 4.5** (symbolic equivalence). Let \( \Sigma \) and \( \Sigma' \) be two sets of constraint systems that contain constraint systems having the same structure. We say that \( \Sigma \) and \( \Sigma' \) are in symbolic equivalence, denoted by \( \Sigma \approx \Sigma' \), if for all \( \mathcal{C} \in \Sigma \), for all \( (\sigma, \theta) \in \text{Sol}(\mathcal{C}) \), there exist \( \mathcal{C}' \in \Sigma' \) and a substitution \( \sigma' \) such that \( (\sigma', \theta) \in \text{Sol}(\mathcal{C}') \) and \( \nu.\Phi \sigma \sim \nu.\Phi' \sigma' \) (and conversely) where \( \mathcal{C} = (\mathcal{E}; \Phi; D; Eq) \) and \( \mathcal{C}' = (\mathcal{E}; \Phi'; D'; Eq') \).

**Example 4.8.** Consider the sets of constraint systems \( \Sigma = \{ \mathcal{C}_1, \mathcal{C}_2, \mathcal{C}_3 \} \) and \( \Sigma' = \{ \mathcal{C}_1', \mathcal{C}_2', \mathcal{C}_3' \} \) as defined in Example 4.6. These two sets are in symbolic equivalence whereas the sets \( \{ \mathcal{C}_1 \} \) and \( \{ \mathcal{C}_1' \} \) are not in symbolic equivalence. Indeed, consider the substitutions \( (\sigma, \theta) \) given in Example 4.6. We obtain that \( (\sigma, \theta) \in \text{Sol}(\mathcal{C}_1) \) whereas \( \theta \not\in \text{Sol}(\mathcal{C}_1') \). Indeed, we have that \( \theta = \{ Z_1 \mapsto c, Z_2 \mapsto c, Y \mapsto a\text{enc}(\langle n_1, \text{proj}_2(ax_1) \rangle, \text{proj}_2(ax_2)) \} \). Thus, in order to satisfy item 1 of Definition 4.4, the substitution \( \sigma' \) should be \( \sigma' = \{ z_1 \mapsto c, z_2 \mapsto c, y \mapsto a\text{enc}(\langle n_1, \text{pk}(sk_a) \rangle, \text{pk}(sk_b)) \} \). However, such a substitution \( \sigma' \) will not satisfy item 2 since the equality \( x \sigma' = \text{adec}(y \sigma', sk_b) \) does not hold. This allows us to conclude that \( \{ \mathcal{C}_1 \} \not\approx \{ \mathcal{C}_1' \} \).
4.2.2 Syntax and semantics

From a bounded intermediate process \((E; P; \Phi)\), we can compute the set of constraint systems capturing its possible executions, starting from the symbolic process \((\mathcal{E}; P; \Phi; D; Eq)\) and applying the rules defined in Figure 4.2.

**Definition 4.6** (symbolic process). A symbolic process is a tuple \((\mathcal{E}; P; \Phi; D; Eq)\) where:

- \(\mathcal{E}\) is a set of names;
- \(\mathcal{P}\) is a multiset of plain processes that do not contain name restriction, replication, where null processes are removed and such that \(\text{fears}(\mathcal{P}) \subseteq \{x \mid X \vdash x \in D\}\);
- \((\mathcal{E}; \Phi; D; Eq)\) is a constraint system.

The rules of Figure 4.2 define the semantics of symbolic processes. This relation transforms a symbolic process into a symbolic process. The aim of this symbolic semantics is to avoid the infinite branching due to the inputs of the environment. This is achieved by keeping variables rather than the input terms. The constraint system gives a finite representation of the value these variables are allowed to take.

\[
(\mathcal{E}; \{\text{if } u = v \text{ then } P_1 \text{ else } P_2\} \uplus \mathcal{P}; \Phi; D; Eq) \xrightarrow{\text{THEN}_s} (\mathcal{E}; \{P_1\} \uplus \mathcal{P}; \Phi; D; Eq \cup \{u \overset{?}{=} v\})
\]

(THEN)

\[
(\mathcal{E}; \{\text{if } u = v \text{ then } P_1 \text{ else } P_2\} \uplus \mathcal{P}; \Phi; D; Eq) \xrightarrow{\text{ELSE}_s} (\mathcal{E}; \{P_2\} \uplus \mathcal{P}; \Phi; D; Eq \cup \{u \not\overset{?}{=} v\})
\]

(ELSE)

\[
(\mathcal{E}; \{\text{out}(p, u).Q; \text{in}(q, x).Q_2\} \uplus \mathcal{P}; \Phi; D; Eq) \xrightarrow{\text{COMM}_s} (\mathcal{E}; \{Q_1; Q_2[x \rightarrow u]\} \uplus \mathcal{P}; \Phi; D; Eq \cup \{p \overset{?}{=} q\})
\]

(COMM)

\[
(\mathcal{E}; \{P \mid Q\} \uplus \mathcal{P}; \Phi; D; Eq) \xrightarrow{\text{PAR}_s} (\mathcal{E}; \{P, Q\} \uplus \mathcal{P}; \Phi; D; Eq)
\]

(PAR)

\[
(\mathcal{E}; \{\text{in}(p, x).Q\} \uplus \mathcal{P}; \Phi; D; Eq) \xrightarrow{\text{IN}_s} (\mathcal{E}; \{Q[x \rightarrow y]\} \uplus \mathcal{P}; \Phi; D \cup \{Y, n \overset{?}{=} y; Z, n \overset{?}{=} z\}; Eq \cup \{z \overset{?}{=} p\})
\]

(IN)

\[
\begin{align*}
(\mathcal{E}; \{Q\} \uplus \mathcal{P}; \Phi \uplus \{ax_{n+1} \triangleright u\}; D \cup \{Z, n \overset{?}{=} z\}; Eq \cup \{z \overset{?}{=} p\}) \\
\text{if } ax_{n+1} \in AX \text{ such that } n = |\Phi|, Z, z \text{ are fresh variables (OUT-T)}
\end{align*}
\]

(OUT-T)

\[
(\mathcal{E}; \{\text{out}(p, u).Q\} \uplus \mathcal{P}; \Phi; D; Eq) \xrightarrow{\text{OUT}_s} (\mathcal{E}; \{Q\} \uplus \mathcal{P}; \Phi \uplus \{ax_{n+1} \triangleright u\}; D \cup \{Z, n \overset{?}{=} z\}; Eq \cup \{z \overset{?}{=} p\})
\]

(OUT)

\[
\begin{align*}
(\mathcal{E}; \{Q\} \uplus \mathcal{P}; \Phi; D \cup \{Z, n \overset{?}{=} z; Y, n \overset{?}{=} y\}; Eq \cup \{z \overset{?}{=} p; y \overset{?}{=} c\}) \\
\text{if } c \not\in \mathcal{E} \text{ and } Y, y, Z, z \text{ are fresh variables, } n = |\Phi| \text{ (OUT-CH)}
\end{align*}
\]

(OUT-CH)

\[
\begin{align*}
(\mathcal{E}; \{\text{out}(p, c).Q\} \uplus \mathcal{P}; \Phi; D; Eq) \xrightarrow{\text{OPEN}_s} (\mathcal{E}; \{Q\} \uplus \mathcal{P}; \Phi \uplus \{ax_{n+1} \triangleright c\}; D \cup \{Z, n \overset{?}{=} z\}; Eq \cup \{z \overset{?}{=} p\})
\end{align*}
\]

(OPEN-CH)

\[
\begin{align*}
\text{u, v are terms having the same type, } x \text{ is a variable of any type, and } p, q, c \text{ are terms of channel type, i.e. names or variables.}
\end{align*}
\]

Figure 4.2: Symbolic semantics

The **THEN** (resp. **ELSE**) rule allows the process to pass a conditional. The corresponding constraint is added in the set of equations and inequations \(Eq\). When a process is ready to input a term on a public channel \(p\), a deducible constraint is added in the set \(D\) (rule **IN**). When a
process is ready to output a term \( u \) on a public channel \( p \), the outputted term is added to the frame \( \Phi \) (rule \( \text{OUT-}T_p \)), which means that this term is made available to the attacker. Note that when this term is actually a channel name, say \( c \), the situation is slightly different. We distinguish two cases depending on whether \( c \) is restricted or not. In particular, in case of an output of a bound channel name, the rule \( \text{OPEN-CH}_b \) requires renaming the channel name (as this is done in the rule \( \text{OUT-}T_p \)). This is needed for our symbolic trace equivalence relation since we require both the left- and right-hand processes to use the same label without allowing \( \alpha \)-conversion.

The relations \( \xrightarrow{s} \) and \( \xrightarrow{a} \) are defined as for our intermediate semantics.

**Example 4.9.** Continuing Examples 4.3, the constraint system \( C_1 = (E; \Phi_0 \cup \{ ax_4 \triangleright t \}; D_1; Eq_1) \) (see Example 4.7) is one of the constraint systems obtained by applying our symbolic rules on the process \( (E; (B'(b, a) | A'(a, b)); \Phi_0; \emptyset) \) and considering the following symbolic trace \( tr_s = in(Z_1, Y). var_4. out(Z_2, ax_4) \). But there is two more possible constraint systems for the same sequence \( tr_s \). The first one is \( C_2 = (E; \Phi_2; D_2; Eq_2) \) where:

- \( \Phi_2 = \Phi_0 \cup \{ ax_4 \triangleright aenc(n_b, pk(s_b)) \}; \) and
- \( D_2 = \{ Z_1, 3 \vdash z_1; Y, 3 \vdash y; Z_2, 3 \vdash z_2 \}; \) and
- \( Eq_2 = \{ z_1 \vdash c; \text{proj}_2(adec(y, s_b)) \neq pk(s_b); z_2 \vdash c \}. \)

This constraint system corresponds to the execution of \( B'(b, a) \) but in the else branch. The second one is \( C_3 = (E; \Phi_3; D_3; Eq_3) \) where:

- \( \Phi_3 = \Phi_0 \cup \{ ax_4 \triangleright aenc((n_a, pk(s_k)), pk(s_b)) \}; \) and
- \( D_3 = \{ Z_1, 3 \vdash z_1; Y, 3 \vdash y; Z_2, 3 \vdash z_2 \}; \) and
- \( Eq_3 = \{ z_1 \vdash c; z_2 \vdash c \}. \)

This last constraint system corresponds to the first input of \( B'(b, a) \) but then the output of \( A'(a, b) \). This is why there is no restriction on the variable \( y \) in \( C_3 \).

For the same sequence \( tr_s \), similar constraint systems, denoted \( C'_1, C'_2 \) and \( C'_3 \), can be derived for the process \( (E; (B'(b, a') | A'(a', b)); \Phi_0) \). The occurrences of \( sk_a \) will be replaced by \( sk_{a'} \) (except the occurrence in \( \Phi_0 \)).

We show that the set of symbolic processes obtained from a symbolic process \( (E; P; \Phi; \emptyset) \) exactly captures the set of intermediate traces of the intermediate process \( (E; P; \Phi) \). More specifically, we show that each solution of the symbolic processes corresponds to a trace of the intermediate process (Proposition 4.2.2) and reciprocally for each trace of the intermediate process there exists a corresponding solution of the symbolic process (Proposition 4.2.3). Figure 4.3 represents the relations between the intermediate and symbolic semantics.

The soundness of \( \xrightarrow{s} \) w.r.t. \( \xrightarrow{a} \) is given by the following proposition (proof in Appendix A.2).

**Proposition 4.2** (soundness). Let \( (E_1; P_1; \Phi_1; D_1; Eq_1) \), and \( (E_2; P_2; \Phi_2; D_2; Eq_2) \) be two symbolic processes such that

- \( (E_1; P_1; \Phi_1; D_1; Eq_1) \xrightarrow{s} (E_2; P_2; \Phi_2; D_2; Eq_2) \), and
- \((\sigma_2, \theta_2) \in \text{Sol}((E_2; P_2; D_2; Eq_2))\).

Let \( \theta_1 = \theta_2|_{\text{vars}^2(D_1)} \) and \( \sigma_1 = \sigma_2|_{\text{vars}^1(D_1)} \). We have that:

1. \((\sigma_1, \theta_1) \in \text{Sol}((E_1; P_1; D_1; Eq_1)), \) and
2. \((E_1; P_1 \sigma_1; \Phi_1 \sigma_1) \xrightarrow{\theta_2 \sigma_2} (E_2; P_2 \sigma_2; \Phi_2 \sigma_2)\).
Figure 4.3: Relations between symbolic and intermediate semantics

The completeness of the symbolic semantics w.r.t. the intermediate one is given by the following proposition (proof in Appendix A.2).

**Proposition 4.3 (completeness).** Let \((E_1; P_1; \Phi_1; D_1; Eq_1)\) be a symbolic process. Let \((\sigma_1, \theta_1) \in Sol((E_1; P_1; \Phi_1; D_1; Eq_1))\). Let \((E; P; \Phi)\) be an intermediate process such that \((E_1; P_1; \Phi_1 \sigma_1) \overset{\alpha_1}{\leadsto} (E; P; \Phi)\). There exist a symbolic process \((E_2; P_2; \Phi_2; D_2; Eq_2)\), a pair of substitutions \((\sigma_2, \theta_2)\), and a symbolic action \(\alpha_s\) such that:

1. \((E_1; P_1; \Phi_1; D_1; Eq_1) \overset{\alpha_s}{\leadsto} (E_2; P_2; \Phi_2; D_2; Eq_2)\);
2. \((\sigma_2, \theta_2) \in Sol((E_2; P_2; D_2; Eq_2))\);
3. \((E; P; \Phi) = (E_2; P_2 \sigma_2; \Phi_2 \sigma_2)\); and
4. \(\alpha_s \theta_2 = \alpha\).

**Example 4.10.** Continuing Example 4.9 and 4.10, the constraint system \(C_1 = (E; \Phi_0 \cup \{ax_4 \triangleright t\}; D_1; Eq_1)\) was shown to be obtained by applying our symbolic rules on the process \((E; \{B'(b, a) | A'(a, b)\}; \Phi_0; \emptyset; \emptyset)\) and considering the following symbolic trace \(tr_s = in(Z_1, Y), \text{var}4, \text{out}(Z_2, ax_4)\):

\[
(E; \{B'(b, a) | A'(a, b)\}; \Phi_0; \emptyset; \emptyset) \overset{tr_s}{\leadsto} (E; \{A'(a, b)\}; \Phi_0 \cup \{ax_4 \triangleright t\}; D_1; Eq_1)
\]

Furthermore, in Example 4.7 we exhibited a solution of \(C_1\): \((\sigma, \theta)\) where \(\text{dom}(\theta) = \{Z_1, Z_2, Y\}\), \(Z_1 \theta = Z_2 \theta = c, Y \theta = \text{aenc}(n_1, \text{proj}_2(ax_1)), \text{proj}_2(ax_3))\) with \(n_1\) a public name of base type (i.e. \(n_1 \notin \mathbb{E}_1\)), \(\sigma\) is the substitution whose domain is \(\{z_1, z_2, y\}\) and such that \(z_1 \sigma = z_2 \sigma = c, \) and \(y \sigma = \text{aenc}(n_1, \text{pk}(sk_a)), \text{pk}(sk_b))\). Thus:

\[
(E; \{B'(b, a) | A'(a, b)\}; \Phi_0) \overset{tr_s}{\leadsto} (E; \{A'(a, b)\}; \Phi_0 \cup \{ax_4 \triangleright t'\})
\]

where \(tr = tr_s \theta\) and \(t' = t \sigma\).

Given an intermediate bounded process, there exists only a finite number of symbolic traces (up to renaming of the second variables of the trace). In this section, we will use this property to show how to reduce the problem of deciding the trace equivalence to the problem of deciding the symbolic equivalence of sets of constraint systems.

**4.2.3 Symbolic trace equivalence**

Due to Proposition 4.11 it is sufficient to establish the link between symbolic equivalence and intermediate trace equivalence of intermediate processes.
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Following the approach of \[\text{Bau07}\], we compute from an intermediate process \(A = (\mathcal{E}; \mathcal{P}; \Phi)\) the set of constraint systems capturing the possible executions of \(A\), starting from its associated symbolic process \(A_s \overset{\text{def}}{=} (\mathcal{E}; \mathcal{P}; \Phi; \emptyset)\) and applying the rules defined in Figure 4.2. Formally, we define the set of traces of a symbolic process as follows:

\[
\text{trace}_s(A_s) = \{(\text{tr}_s, (E_2; \mathcal{P}_2; D_2; Eq_2)) \mid A_s \overset{s}{\Rightarrow}(E_2; \mathcal{P}_2; \Phi_2; D_2; Eq_2) \text{ for some } E_2, \mathcal{P}_2, \Phi_2, D_2, Eq_2\}
\]

When \(\text{tr}_s\) is fixed, we also write \((\text{tr}_s, \Sigma) \in \text{trace}_s(A_s)\) to define the set \(\Sigma\) as the set of constraint systems \(\{C \mid (\text{tr}_s, C) \in \text{trace}_s(A_s)\}\).

Two intermediate bounded processes are in intermediate trace equivalence if and only if, for any symbolic trace, their corresponding sets of constraints are in symbolic equivalence, which we call symbolic trace equivalence.

**Definition 4.7** (symbolic trace equivalence). Let \(A\) and \(B\) be two intermediate bounded processes. They are in symbolic trace equivalence if for every sequence \(\text{tr}_s\) of symbolic actions, we have that:

\[
\{C \mid (\text{tr}_s, C) \in \text{trace}_s(A_s)\} \approx_s \{C \mid (\text{tr}_s, C) \in \text{trace}_s(B_s)\}
\]

where \(A_s\) and \(B_s\) are the symbolic processes associated to \(A\) and \(B\).

By relying on Propositions 4.2 and 4.3, we are now capable of establishing that trace equivalence coincide with symbolic trace equivalence. Figure 4.3 presents a sketch of proof of Proposition 4.4.

![Symbolic trace equivalence and trace equivalence coincide](image)

The steps of the proof that symbolic trace equivalence implies trace equivalence are represented by the simple arrows, whereas the steps of the proof that trace equivalence implies symbolic trace equivalence are represented by the double arrows.

**Figure 4.4:** Symbolic trace equivalence and trace equivalence coincide

**Proposition 4.4.** Let \(A\) and \(B\) be two intermediate bounded processes: \(A \approx_s B\) if, and only if \(A\) and \(B\) are in symbolic trace equivalence.

**Proof.** We show the two directions separately. Let \(A = (\mathcal{E}; \mathcal{P}_A; \Phi_A)\) and \(B = (\mathcal{E}; \mathcal{P}_B; \Phi_B)\).

**Case (\(\Rightarrow\)).** We have to show that for every \((\text{tr}, \Phi'_A) \in \text{trace}_s(A)\) there exists \((\text{tr}, \Phi'_B) \in \text{trace}_s(B)\) such that \(\nu\mathcal{E}.\Phi'_A \sim \nu\mathcal{E}.\Phi'_B\) (and reciprocally). Let \((\text{tr}, \Phi'_A) \in \text{trace}_s(A)\). By definition of \(\text{trace}_s(A)\), this means that there exists \(\mathcal{P}'_A\) such that \((\mathcal{E}; \mathcal{P}_A; \Phi_A) \overset{\Sigma}{\Rightarrow} (\mathcal{E}; \mathcal{P}'_A; \Phi'_A)\). Let \(A_s = (\mathcal{E}; \mathcal{P}_A; \Phi_A; \emptyset)\) and \(\sigma, \theta\) be the substitutions identity. We have that \((\sigma, \theta) \in \text{Sol}(\mathcal{E}; \Phi_A; \emptyset))\). Thanks to Proposition 4.3, a simple induction on \[\text{tr}\] allows us to deduce that there exist a symbolic process \(A'_s = (\mathcal{E}; \mathcal{P}_A; \Phi'_A; D'_A; Eq'_A)\), a pair of substitution \((\sigma'_A, \theta')\), and a sequence \(\text{tr}_s\) of symbolic actions such that:
1. \((\mathcal{E}; \mathcal{P}_A; \Phi_A; \emptyset; \emptyset) \models_s (\mathcal{E}; \mathcal{P}_A'; \Phi_A'; D_A'; \text{Eq}_A')\);

2. \((\sigma_A, \theta') \in \text{Sol}((\mathcal{E}; \Phi_A'; D_A'; \text{Eq}_A'))\);

3. \((\mathcal{E}; \mathcal{P}_A'; \Phi_A') = (\mathcal{E}; \mathcal{P}_A'; \Phi_A'; \sigma_A'; \text{Eq}_A'); \) and

4. \(\text{tr}_s \theta' = \text{tr}\).

Let \(C'_A = (\mathcal{E}; \Phi_A'; D_A'; \text{Eq}_A').\) By definition of trace\(_s\)(\(A_s\)), we have that \((\text{tr}_s, C'_A) \in \text{trace}_s(A_s)\). Since \(A\) and \(B\) are in symbolic trace equivalence, we deduce that there exist a substitution \(\sigma_B'\) and \(C'_B = (\mathcal{E}; \Phi_B'; D_B'; \text{Eq}_B')\) such that \((\text{tr}_s, C'_B) \in \text{trace}_s(B_s)\) with \(\sigma_B' \in \text{Sol}(C'_B)\) and \(\nu \mathcal{E}. \Phi_A' \sigma_A' \sim \nu \mathcal{E}. \Phi_B' \sigma_B'\). By definition of trace\(_s\)(\(B_s\)), we have that \((\mathcal{E}; \mathcal{P}_B; \Phi_B; \emptyset; \emptyset) \models_s (\mathcal{E}; \mathcal{P}_B'; \Phi_B'; D_B'; \text{Eq}_B')\) for some \(\mathcal{P}_B\). Now, thanks to Proposition 4.3, a simple induction on \(|\text{tr}_s|\) allows us to deduce that 
\((\mathcal{E}; \mathcal{P}_B; \Phi_B) \models S_{\text{tr}}^{\theta'}(\mathcal{E}; \mathcal{P}_B'; \Phi_B'; \mathcal{P}_B' \sigma_B')\). If we denote \(\Phi'_B = \Phi_B' \sigma_B'\) and since \(\text{tr} = \text{tr} \theta'\), we clearly have that \((\text{tr}, \nu \mathcal{E}. \Phi'_B) \in \text{trace}_s(B)\). At last, we already showed that \(\nu \mathcal{E}. \Phi'_A \sigma_A' \sim \nu \mathcal{E}. \Phi'_B \sigma_B'\) and so \(\nu \mathcal{E}. \Phi_A' \sim \nu \mathcal{E}. \Phi'_B\). Hence the result holds. The other inclusion can be shown in a similar way.

**Case** \((\Rightarrow)\): We have to show that \(A\) and \(B\) are in symbolic trace equivalence, i.e. for every sequence \(\text{tr}_s\) of symbolic actions,

\[
\{C \mid (\text{tr}, C) \in \text{trace}_s(A_s)\} \approx \{C \mid (\text{tr}, C) \in \text{trace}_s(B_s)\}
\]

Let \((\text{tr}_s, C'_A) \in \text{trace}_s(A_s)\) and \((\sigma_A, \theta) \in \text{Sol}(C'_A)\). By definition of trace\(_s\)(\(A_s\)), we know that there exists \(\mathcal{P}_A\) such that \(A_s \models S_{\text{tr}}^{\text{tr}}(\mathcal{E}; \mathcal{P}_A'; \Phi_A'; D_A'; \text{Eq}_A')\) and \(C'_A = (\mathcal{E}; \Phi_A'; D_A'; \text{Eq}_A')\).

Thanks to Proposition 4.3, we have that \(A \models S_{\text{tr}}^{\sigma_A}(\mathcal{E}; \mathcal{P}_A'; \Phi_A'; \sigma_A)\). Since \(A\) and \(B\) are in trace equivalence, we deduce that there exists \((\mathcal{E}; \mathcal{P}_B; \Phi_B)\) such that \(B \models S_{\text{tr}}^{\sigma_B}(\mathcal{E}; \mathcal{P}_B'; \Phi_B'; \sigma_B)\) and \(\nu \mathcal{E}. \Phi_A' \sigma_A \sim \nu \mathcal{E}. \Phi_B' \sigma_B\). Thanks to Proposition 4.4, we deduce that there exist \((\mathcal{E}; \mathcal{P}_B; \Phi_B'; D_B'; \text{Eq}_B')\), a pair of substitutions \((\sigma_B, \theta')\), and a sequence \(\text{tr}'_s\) of symbolic actions such that:

1. \(B_s \models S_{\text{tr}}^{\text{tr}}(\mathcal{E}; \mathcal{P}_B'; \Phi_B'; D_B'; \text{Eq}_B')\);

2. \((\sigma_B, \theta') \in \text{Sol}((\mathcal{E}; \Phi_B'; D_B'; \text{Eq}_B'))\);

3. \((\mathcal{E}; \mathcal{P}_B'; \Phi_B') = (\mathcal{E}; \mathcal{P}_B'; \Phi_B'; \sigma_B)\); and

4. \(\text{tr}'_s \theta' = \text{tr}\).

Let \(C'_B = (\mathcal{E}; \Phi_B'; D_B'; \text{Eq}_B')\). Actually, we can assume that \(w'_s = w_s\) (by renaming the second order variables that occur in \(w'_s\)). Moreover, since \(w_s \theta' = w_s \theta\), we have that \(\theta' = \theta\). Lastly, since \(\nu \mathcal{E}. \Phi_A' \sigma_A \sim \nu \mathcal{E}. \Phi_B' \sigma_B\) and \(\Phi_B' = \Phi_B' \sigma_B\), we easily deduce that \(\nu \mathcal{E}. \Phi_A' \sigma_A \sim \nu \mathcal{E}. \Phi_B' \sigma_B\).

### 4.3 Main result and conclusion

In this chapter, we have shown that deciding trace equivalence of processes in the applied \(\pi\) calculus can be reduced to deciding symbolic equivalence of sets of constraint systems. Hence, we extract a decision procedure for trace equivalence.

**Theorem 4.1.** Given an algorithm for deciding symbolic equivalence between sets of constraint systems, we can derive an algorithm for deciding trace equivalence between processes without replication.

**Proof.** The algorithm for deciding trace equivalence follows from Proposition 4.4. Given a fixed sequence of symbolic labels \(\text{tr}_s\), given \(\Sigma_A\) such that \((\text{tr}_s, \Sigma_A) \in \text{trace}_s(A_s)\), for any renaming \(\alpha\) of the second order variables of \(\text{tr}_s\), we have \((\text{tr}_s \alpha, \Sigma_A) \in \text{trace}_s(A_s)\). Hence, when computing the set of constraint systems capturing the possible executions of \(A\), we only consider one sequence of symbolic labels \(\text{tr}_s\) to represent the set \(\{\text{tr}'_s \mid (\text{tr}'_s, \Sigma_A') \in \text{trace}_s(A_s)\}\) and \(\text{tr}'_s\) is equal to \(\text{tr}_s\) through
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renaming of second order variables\}. Of course the same sequence of symbolic labels \( \tau_s \) must be used to represent the set \( \{ \tau'_{s} \mid (\tau'_{s},\Sigma'_{B}) \in \text{trace}_{s}(B_{s}) \} \) and \( \tau'_{s} \) is equal to \( \tau_{s} \) through renaming of second order variables\}. In such a case, there is only a finite set of traces of a symbolic process to consider, and each symbolic trace leads to a finite number of constraint systems.

Thanks to this reduction result, we can now focus on deciding the symbolic equivalence between sets of constraint systems. So far, the previous works in the literature focus on symbolic equivalence between two positive constraint systems [Bau07, TD10, CR12] and not between two sets of constraint systems. More details on these three previous works are given in the introduction of Chapter 6. Using these algorithms, [CD09a] shows that the trace equivalence of simple processes can be decided by reducing the problem of trace equivalence for simple processes to the symbolic equivalence between two positives constraint systems.

Even though the class of protocol that can be expressed as simple process is large, protocols that need non-trivial else branches, private channels or that are not deterministic, such as the private authentication protocol and the e-passport protocols, cannot be expressed as simple processes. This is why, in Part II, we provide a decision procedure for symbolic equivalence of sets of constraint systems with standard cryptographic primitives and inequalities.
As previously mentioned, most of the existing techniques for analysing protocols with respect to privacy-type properties (e.g. [TD10, BAF08]), consider protocols to be executed in isolation. But in reality many applications run in parallel and the underlying protocols may interact in unexpected ways if cryptographic material is shared amongst them. This situation can arise if, for example, a user chooses the same password for two different network services, or a server uses the same key for different protocols. Furthermore, real life protocols are usually complex and composed of several sub-protocols that rely on the same cryptographic material. For example, the e-passport protocol (see Section 3.3) is composed of at least three sub-protocols (BAC, AA and PA) that share private keys.

Unfortunately, even if a protocol is secure for an unbounded number of sessions, there is no guarantee if the protocol is executed in an environment where other protocols sharing some common keys are executed. The interaction with the other protocols may dramatically damage the security of the former protocol. This is a well-known fact that has been already observed for trace-based security properties e.g. [GT00, CC10], and that remains true for privacy-type properties.
An attacker may take advantage of a protocol $Q$ to break anonymity of another protocol $P$ that has been proved secure in isolation. This can happen for instance if the security of $P$ relies on the secrecy of a particular shared key that is revealed by the protocol $Q$.

In order to enable verification of complex real life systems, composition theorems for modular reasoning about security and privacy are therefore desirable. They may allow one to deduce security guarantees for a complex protocol, from the security guarantees of the individual sub-protocols. The goal of this chapter is to study the composition of protocols with respect to privacy-type properties.

As mentioned in the introduction, most of the existing results focus on trace properties and few focus on equivalence properties. However, we highlight a result closely related to ours that is the one of S. Ciobaca and V. Cortier [CC10]. Their result holds for any cryptographic primitives that focus on equivalence properties. However, we highlight a result closely related to ours that is the one of S. Ciobaca and V. Cortier [CC10]. Their result holds for any cryptographic primitives that can be modelled using equational theories, and their main result transforms any attack trace of the combined protocol into an attack trace of one of the individual protocols. This allows various ways of combining protocols such as sequentially or in parallel, possibly with inner replications. Although, the major difference with our result is that they consider trace-based security properties, and more precisely secrecy (encoded as a reachability property), the proof technique we present in this chapter is directly inspired from their work.

More specifically, we show that whenever processes $P$ and $Q$ (resp. $P'$ and $Q'$) satisfy some disjointness properties (e.g. tagged processes, no shared key revealed, . . .), we can derive that $P$ and $Q$ running in parallel under the composition context $C[\_] \equiv C'[\_]$, i.e.

$$C[P \mid Q] \equiv C'[P' \mid Q']$$

from the equivalences $C[P] \equiv C'[P']$ and $C[Q] \equiv C'[Q']$. The composition context under which two processes are composed contains the shared keys possibly under some replications. We illustrate the application of our results on the $c$-passport protocol described in Section 5.4.

### 5.1 Some difficulties

The secure parallel composition of protocols is an easy task if the protocols do not share any secret key which is represented by the following lemma.

**Lemma 5.1.** Let $P, Q, P', Q'$ four processes. $P \approx_1 Q$ and $P' \approx_1 Q'$ imply $P \mid P' \approx_1 Q \mid Q'$.

This lemma comes directly from the fact the trace equivalence is closed under application of a composition context. This holds in many cryptographic calculus and more specifically in the applied pi calculus.

However, as soon as the protocols share some private keys, some difficulties arises. In particular, the security of the parallel composition can be compromised if one of the protocol revealed a shared key.

**Example 5.1.** Consider the equational theory introduced in Example 4.1 and consider the two processes $P_i = \nu r.\text{out}(c, \text{aenc}((r, id), \text{pk}(sk_S)))$ with $i \in \{1, 2\}$. The first component generates a fresh random number $r$, publishes the message $\text{aenc}((r, id), \text{pk}(sk_S))$ containing its identity $id$, by sending it on the public channel $c$. Note that the encryption of a pairing where one of its component is a fresh nonce is a way to model randomized asymmetric encryption.

We have that $\nu sk_S.P_1 \approx_1 \nu sk_S.P_2$. This equivalence may express for instance the anonymity of the identity $id_i$.

Assume now that $P$ is executed in an environment where another protocol $Q = \nu sk_S.\text{out}(c, sk_S)$ is executed as well and $Q$ uses the same asymmetric key $sk_S$ as the protocol $P$. Clearly, the equivalence expressing the anonymity of $P$ does not hold anymore:

$$\nu sk_S.(\nu r.\text{out}(c, \text{aenc}((r, id), \text{pk}(sk_S))) \mid \text{out}(c, sk_S)) \not \approx_1$$

$$\nu sk_S.(\nu r.\text{out}(c, \text{aenc}((r, id), \text{pk}(sk_S))) \mid \text{out}(c, sk_S))$$
5.1. SOME DIFFICULTIES

Indeed, in this example, id₁ and id₂ are both public so can appear in the tests for the static equivalence. Hence a witness for the non-trace equivalence consists of the sequence of actions tr = \text{var}_1.\text{out}(c, ax_1).\text{var}_2.\text{out}(c, ax_2) and the test proj₂(\text{dec}(ax_1, ax_2)) = id₁

As shown by the example above, the equivalence \( P₁ \approx_t P₂ \) holds thanks to the secrecy of \( sk_S \), and thus a protocol \( Q \) that uses this key \( sk_S \) should at least not reveal it. Revealing shared keys would clearly compromise the security of \( P \).

Actually, even if shared keys are not revealed, the interaction of two protocols using common primitives may compromise their security (also true for trace properties such as secrecy).

Example 5.2. Consider the processes \( P_i \) with \( i \in \{1, 2\} \) as defined in Example 5.1 and consider the process \( Q \) defined as follows:

\[
Q \overset{def}{=} \text{in}(c).\text{out}(c, \text{dec}(x, sk_S))
\]

The equivalence expressing the anonymity of \( P \) (for one session) holds. We have that \( \nu k.P₁ \approx_t \nu k.P₂ \) whereas the equivalence expressing the anonymity of \( P \) in presence of \( Q \) does not hold anymore. We have that:

\[
\nu k.S₁ \not\approx_t \nu k.(P₂ | Q)
\]

The sequence of actions tr = \text{var}_1.\text{out}(c, ax_1).\text{var}_2.\text{out}(c, ax_2) and the test ax₂ = id₁ are a witness of the non-equivalence. Intuitively, instead of revealing the secret key \( sk_S \), \( Q \) can be used as an oracle to decrypt a ciphertext that comes from the process \( P \), and thus \( Q \) can be used to reveal the identity hidden in the ciphertext.

5.1.1 Sharing primitives with tagging

In this chapter, we will use the intermediate calculus with its associated semantics. However, given a plain process \( P \), we will sometimes also denote by \( P \) the intermediate process \( (\emptyset; \{P\}; \emptyset) \).

To avoid a ciphertext from a process to be decrypted by another one, we can consider processes that use disjoint primitives. However, this is an unnecessarily restrictive condition. So, we consider protocols that may share some cryptographic primitives provided they are tagged. Tagging is a syntactic transformation that consists in assigning to each protocol an identifier (e.g. the protocol’s name) that should appear in any encrypted message. Many relevant equational theories are not so easy to tag (e.g. exclusive or). So, we only consider a fix common signature with its associated equational theory, denoted \( (F₀, E₀) \), and we explain how to transform any process built on a signature \( F \) (possibly larger that \( F₀ \)) into a tagged process.

The common signature \( F₀ \) is defined as follows:

\[
\{\text{sdec}/2, \text{senc}/2, \text{aenc}/2, \text{pk}/1, \langle \rangle/2, \text{proj}_1/1, \text{proj}_2/1, \text{sign}/2, \text{check}/2, \text{vk}/1, \text{h}/1\}
\]

The common equational theory \( E₀ \) is defined by the following equations \( i \in \{1, 2\} \):

\[
\begin{align*}
\text{sdec}(\text{senc}(x, y), y) &= x \\
\text{aenc}(\text{pk}(y), y) &= \text{dec}(\text{aenc}(x, pk(y)), y) = x \\
\text{proj}_i((x₁, x₂)) &= x₁, \text{check}(\text{sign}(x, \text{vk}(y)), y) &= x
\end{align*}
\]

For our composition results, we will assume that the processes we want to compose are built on \((F_a \cup F₀, E_a \cup E₀)\) and \((F_b \cup F₀, E_b \cup E₀)\), where \((F_a, E_a)\), \((F_b, E_b)\) and \((F₀, E₀)\) are disjoint signatures.

5.1.1.1 Tagging a term

We define the signature \( F_{\tag,c} = \{\text{tag}_c/1, \text{untag}_c/1\} \) where \( \text{tag}_c \) and \( \text{untag}_c \) are two function symbols that we will use for tagging. The role of the \( \text{tag}_c \) function is to tag its argument with the tag \( c \). The role of the \( \text{untag}_c \) function is to remove the tag. To model this interaction between \( \text{tag}_c \) and \( \text{untag}_c \), we consider the equational theory:

\[
E_{\tag,c} = \{\text{untag}_c(\text{tag}_c(x)) = x\}.
\]
Intuitively, tagging a protocol $P_A$, built on $(F_A \cup F_0, E_A \cup E_0)$, with the tag $a$ will result a process built on $(F_A \cup F_{tags}, F_0, E_A \cup E_{tags} \cup E_0)$. We denote by $F_A^+ = F_A \cup F_{tags}$ and $E_A^+ = E_A \cup E_{tags}$ with $c \in \{a, b\}$ and $a, b$ are the two tags that we will use in this chapter.

**Definition 5.1.** Let $u$ be a term built on $F_c \cup F_0$ ($c \in \{a, b\}$). The $c$-tagged version of $u$, denoted $[u]_c$, is defined as follows:

$\begin{align*}
[senc(u, v)]_c & \overset{\text{def}}{=} senc(tag_c([u]_c), [v]_c) \\
[aenc(u, v)]_c & \overset{\text{def}}{=} aenc(tag_c([u]_c), [v]_c) \\
[sign(u, v)]_c & \overset{\text{def}}{=} sign(tag_c([u]_c), [v]_c)
\end{align*}$

$\begin{align*}
[h(u)]_c & \overset{\text{def}}{=} h(tag_c([u]_c)) \\
[f(u_1, \ldots, u_n)]_c & \overset{\text{def}}{=} f([u_1]_c, \ldots, [u_n]_c) \quad \text{otherwise.}
\end{align*}$

Note that we do not tag the pairing function symbol (this is actually useless), and we do not tag the pk and vk function symbols. Actually, tagging pk and vk would greatly help us to establish our results and would also avoid us to introduce some additional assumptions, but this would lead us to consider an unrealistic modeling for asymmetric keys. Some of the difficulties encountered with asymmetric keys will be discussed in Section 5.3.

**Example 5.3.** Consider $u_i = aenc((r, id_i), pk(sk_S))$ with $i \in \{1, 2\}$ and $v = proj_2(adc(x, sk_S))$. We have that $[u_i]_a = aenc(tag_a((r, id_i)), pk(sk_S))$, whereas $[v]_b = proj_2(untag_2(adc(x, sk_S)))$.

**5.1.1.2 Tagging a process**

Before extending the notion of tagging to processes, we have to express the tests that are performed by an agent when he receives a message that is supposed to be tagged. Indeed, the main purpose of tagging $P_A$ and $P_B$ with two different tags is to ensure that the intruder cannot reinject a message obtained from $P_A$ (resp. $P_B$) into the process $P_B$ (resp. $P_A$). Hence to do so, the tagged version of $P_A$ and $P_B$ will check that each message they receive are properly tagged with the tags $a$ and $b$ respectively. This is the purpose of test$_c(u)$ that represents the tests which ensure that every execution and every untagging performed by an agent during the computation of $u$ is successful.

**Definition 5.2.** Let $u$ be a term built on $F_A^+ \cup F_0$ with $c \in \{a, b\}$. We define test$_c(u)$ as follows:

- test$_c(u) \overset{\text{def}}{=} \text{test}._1(u) \land \text{test}._2(u)$ & $\land \text{tag}_c(\text{untag}_c(u)) = u$, if $u = g(u_1, u_2)$ with $g \in \{sdec, adec, check\}$;

- test$_c(u) \overset{\text{def}}{=} \text{test}._1(u) \land u_1 = \langle \text{proj} \rangle(u_1)$ & $\land \text{proj}_2(u_1)$, if $u = \text{proj}_1(u_1)$ with $i \in \{1, 2\}$;

- test$_c(u) \overset{\text{def}}{=} \text{true, if } u \text{ is a name or a variable};$

- Otherwise $u = f(u_1, \ldots, u_n)$ for some $n$, and test$_c(u) \overset{\text{def}}{=} \text{test}._1(u) \land \ldots \land \text{test}._n(u)$.

Note that in the first case, e.g. $u = sdec(u_1, u_2)$, if $u$ is a ground term then we have $\text{tag}_c(\text{untag}_c(u)) = E$ if and only if the decryption succeeds and the plain text is tagged with the tag $c$, i.e. $u_1 = E$ senc(tag$_c(u_3), u_2)$ for some $u_3$.

For any term $u$, test$_c(u)$ is a conjunction of elementary formulas (equalities between term).

Hence, given a ground substitution $\alpha$ such that $\text{feats}(u) \subseteq \text{dom}(\alpha)$, we say that $\alpha$ satisfies test$_c(u)$, denoted $\alpha \vDash \text{test}._c(u)$ if $\alpha$ satisfies all elementary formulas of test$_c(u)$ whereas $\alpha$ satisfies $t_1 = t_2$, denoted $\alpha \vDash t_1 = t_2$, if $t_1 \alpha = t_2 \alpha$.

**Example 5.4.** Again, consider the terms $u_i = aenc((r, id_i), pk(sk_S))$ with $i \in \{1, 2\}$ and $v = \text{proj}_2(adc(x, sk_S))$. We have that:


\[ u_i \]_a = aenc(\text{tag}_a((r, id_i)), \text{pk}(sk_S)) \text{ and } \text{test}_a([u_i]_a) = \text{true}.

\[ [v]_b = \text{proj}_2(\text{untag}_b(\text{adec}(x, sk_S))) \text{ and } \text{test}_b([v]_b) \text{ is the following conjunction:} \]

\[ \text{tag}_b(\text{untag}_b(\text{adec}(x, sk_S))) = \text{adec}(x, sk_S) \land (\text{proj}_1(v'), \text{proj}_2(v')) = v' \]

where \( v' = \text{untag}_b(\text{adec}(x, sk_S)) \).

Let \( \alpha_1 = \{ x \mapsto a \}, \alpha_2 = \{ x \mapsto aenc(\text{tag}_a((n, sk_S))) \} \text{ and } \alpha_3 = \{ x \mapsto aenc(\text{tag}_a((n, n'), sk_S)) \}. \) We have that \( \alpha_1 \not\models \text{test}_b([v]_b) \) and \( \alpha_2 \not\models \text{test}_b([v']_b) \) but \( \alpha_3 \models \text{test}_b([v]_b) \).

We can now explain how to tag an intermediate process. Let \( A = (\mathcal{E}; \mathcal{P}; \Phi) \) be an intermediate process built on \( \mathcal{F}_c \cup \mathcal{F}_0 \) with \( c \in \{ a, b \} \) such that \( \mathcal{P} = \{ P_1, \ldots, P_t \} \) and \( \Phi = \{ ax_1 \triangleright u_1, \ldots, ax_n \triangleright u_n \} \). The \( c \)-tagged version of the process \( A \), denoted \( [A]_c \), is the process \( (\mathcal{E}; [\mathcal{P}]_c; [\Phi]_c) \) where \( [\mathcal{P}]_c = \{ [P_1]_c, \ldots, [P_t]_c \} \) and \( [\Phi]_c = \{ ax_1 \triangleright [u_1]_c, \ldots, ax_n \triangleright [u_n]_c \} \).

For plain processes, the transformation \([P]_c\) is defined as follows:

\[
\begin{align*}
[0]_c & \overset{\text{def}}{=} 0 \\
[\nu k.P]_c & \overset{\text{def}}{=} \nu k.[P]_c \\
[\text{in}(u, x).P]_c & \overset{\text{def}}{=} \text{in}(u, x).[P]_c \\
[\text{out}(u, v).Q]_c & \overset{\text{def}}{=} \begin{cases} 
\text{if } \text{test}_c([v]_c) \text{ then } \text{out}(u, [v]_c).[Q]_c & \text{else } 0 \\
\text{if } u_1 = u_2 \text{ then } Q & \text{else } [Q]_c 
\end{cases} \\
[\text{if } u_1 = u_2 \text{ then } P \text{ else } Q]_c & \overset{\text{def}}{=} \begin{cases} 
\text{if } \text{test}_c([u_1]_c) \land \text{test}_c([u_2]_c) & \text{then } [u_1]_c = [u_2]_c \text{ then } [P]_c \text{ else } [Q]_c \\
\text{else } 0 & 
\end{cases}
\end{align*}
\]

The logical connector \( \land \) that are used in \( \text{test}_c(u) \) are syntactic sugar that can be easily encoded using nested conditionals.

Roughly, instead of simply outputting a term \( v \), a process will first performed some tests to check that the term is correctly tagged, thanks to \( \text{test}_c([v]_c) \), and he will output its \( c \)-tagged version \([v]_c\). For a conditional, the process will first check that the terms \( u_1 \) and \( u_2 \) are correctly tagged before checking that the test is satisfied.

Note that \( \text{test}_c() \) is always applied on a term that is tagged thanks to \([.]_c\). It may seems counter intuitive since one the purpose of \( \text{test}_c(u) \) is to verify that \( u \) is well tagged whereas the purpose of \([u]_c\) is to tag the term \( u \). Indeed, for a ground term \( u \) that do not contain the symbol functions \( \text{sdec}, \text{adec}, \text{proj}_i \) or check, we have that \( \text{test}_c([u]_c) = \text{true} \). However, since we tag an intermediate process, the term on which we apply \([.]_c\) are not necessary ground. Furthermore, the value of their variable may differ in each derivation of the intermediate process. Hence, the tests \( \text{test}_c([u]_c) \) will ensure that for any derivation of the processes, the instantiation of \([u]_c\) is properly tagged.

**Example 5.5.** We consider the processes \( P \) and \( Q \) defined in Example 5.2. Assume that \( P \) and \( Q \) are tagged with respectively the tags \( a \) and \( b \). Hence we have:

\[
[Q]_b = \text{in}(c, x).\text{if } \text{tag}_b(\text{untag}_b(\text{adec}(x, sk_S))) = \text{adec}(x, sk_S) \text{ then } \text{out}(c, \text{untag}_b(\text{adec}(x, sk_S))) \text{ else } 0
\]

Note that \( \text{test}_b(\text{untag}_b(\text{adec}(x, sk_S))) \overset{\text{def}}{=} \text{tag}_b(\text{untag}_b(\text{adec}(x, sk_S))) = \text{adec}(x, sk_S). \)

Consider now the intermediate process \( A = (0, [Q]_b, 0) \) and \( (tr, vE, \Phi) \in \text{trace}_c(A) \) such that \( \text{tr} = \text{in}(c, M).\nu ax_1.\text{out}(c, ax_1) \) for some \( M \). The presence of the conditional in \([Q]_b\) ensure that \( M = ax_1 = \text{aenc}(\text{tag}_a((u), \text{pk}(sk_S))) \) for some \( u \). This is consistent with the goal of \( Q \) which is to reveal any plain text that is encrypted with \( \text{pk}(sk_S) \).

Note that the test only verifies the tags of the part of \( M \) on which the process \([Q]_b\) will apply some function symbols. In this example, even if \( u \) is tagged with the tag \( a \) or not tagged at all, \( M \) will satisfy the test. Intuitively, the intruder may have built \( u \) from scratch or even receive it from the process \([P]_a\) but from the point of view of \( Q \), \( u \) is only some bitstring that is stored as-is.
CHAPTER 5. COMPOSING TRACE EQUIVALENCE

5.1.2 Composition context

We saw in Example 5.1 that parallel composition of processes under name restriction may reveal itself to be problematic. However, for the purpose of this work, i.e., parallel composition of processes for security property such as anonymity and unlikeness, composition under name restriction is not enough.

Example 5.6. Coming back to the e-passport protocol (Section 3.4), the anonymity of the parallel composition of the Active Authentication protocol (AA) and the Passive Authentication protocol (PA) can be expressed with the following equivalence:

\[ \nu_{sk_{DS}}.C[PA | AA, PA_0 | AA_0] \approx_t \nu_{sk_{DS}}.C'[PA | AA] \]

where \( C \) and \( C' \) are contexts defined as follows:

\[ C[\_1, \_2] \overset{\text{def}}{=} ! \nu_{skp}. \nu_{vid}. \nu_{sig}. \nu_{pic}. \ldots ! \nu_{ksenc}. \nu_{ksmac}. \_1 \]
\[ C'_[\_] \overset{\text{def}}{=} ! \nu_{skp_0}. ! \nu_{ksenc}. \nu_{ksmac}. \_ \]

However, if we now look at the protocols AA and PA in isolation, the anonymity of these protocols would be expressed with the two following equivalences:

\[ \nu_{sk_{DS}}.C[AA, AA_0] \approx_t \nu_{sk_{DS}}.C'[AA] \]
\[ \nu_{sk_{DS}}.C[PA, PA_0] \approx_t \nu_{sk_{DS}}.C'[PA] \]

One can note that in the previous example, the parallel composition is done under contexts which are different depending on the side of the equivalence. However, note that each time, the contexts we consider for expressing anonymity are only composed of replication, parallel composition and name restriction.

Furthermore, note that in Example 5.6, the restriction of some shared keys occurs under a replication, e.g., \( k_{senc}, k_{smac} \). Hence, considering composition in a simpler setting where only a bounded number of keys \( \tilde{k} \) are shared (as done in e.g. [CD09b]), would not allow us to establish unlikeness or anonymity in a modular way, but only some results of the form:

\[ \nu_{\tilde{k}}.P_1 \approx_t \nu_{\tilde{k}}.P_2 \Rightarrow \nu_{\tilde{k}}. (P_1 | Q) \approx_t \nu_{\tilde{k}}. (P_2 | Q) \]

assuming that processes \( P_1, P_2, \) and \( Q \) satisfy some additional conditions.

Thus, we introduce the notion of composition context that will help us to describe under which keys the composition has to be done. Note that a composition context may contain several holes, parallel operators, and nested replications.

Definition 5.3. A composition context \( C \) is defined by the following grammar where \( n \) is a name of base type.

\[ C, C_1, C_2 := \_ | \nu n. C \mid ! C \mid C_1 | C_2 \]

We only allow names of base type (typically keys) to be shared between processes through the composition context. In particular, they are not allowed to share a private channel even if each process can use its own private channels to communicate internally. We also suppose w.l.o.g. that names occurring in \( C \) are distinct. A composition context may contain several holes. We can index them to avoid confusion. We write \( C[P_1, \ldots, P_t] \) (or shortly \( C[P] \)) the process obtained by filling the \( i^{th} \) hole with the process \( P_i \) (or the \( i^{th} \) process of the sequence \( P \)). We will also use \( P | Q \) to represent the sequence of processes obtained by putting in parallel the processes of the sequences of same size \( P \) and \( Q \) componentwise, i.e., the sequence \( P_1 | Q_1, \ldots, P_t | Q_t \).
5.2. PRELIMINARIES

In Example 5.1, we saw that revealing a shared key is problematic for composition. Since some shared key may be restricted under a replication, we have to consider renaming and formalise the notion of revealing a shared key. Note that all names that occur in a composition context do not necessary represent shared keys.

Example 5.7. Coming back to Example 5.6 and Figure 3.3 and 3.4, the names skDS, id, sig, pic, dg1, . . . , dg19 are only used in the Passive Authentication protocol and so are not shared keys. On the other hand, the secret key skP, associated to each passport, is used in both Active and Passive Authentication protocols (vk(skP) is stored in dg15). Moreover, the session keys ksen, ksmac and skv are also used in both Active and Passive Authentication protocols and so ksen, ksmac and skv are the only shared keys in the composition contexts vskDS.C and νskDS.C′.

Definition 5.4. Let A be an intermediate process of the form (E; C[P1, . . . , Pℓ]; Φ) where C is a composition context, and let key ∈ {n, pk(n), vk(n) | n ∈ E or n occurs in C}. We say that the intermediate process A reveals the shared key key when:

Either fnames(key) ∈ E, and

• A def (E′; P ′; Φ′) for some (E′; P ′; Φ′); and

• MΦ′ =E key for some M such that fnames(M) ⊆ dom(Φ′) and fnames(M) ∩ E′ = ∅.

Or, we have that fnames(key) occurs in C, the i0th hole is in the scope of vfnames(key), and

• (E ∪ {s}; C[P1, . . . , Pℓ]; Φ) def (E′; P ′; Φ′) with P ′i if i ̸= i0 and P ′i0 def P i0 | in(c,x).if x = key then out(c,s) else 0; and

• MΦ′ =E s for some M such that fnames(M) ⊆ dom(Φ′) and fnames(M) ∩ E′ = ∅.

where s and c are fresh.

Intuitively, a key is revealed if there exists a trace of the extended process where this key can be deduced by the intruder. Hence, in the case where the shared key is in the set of private names E, the definition is straightforward. However, in the case where the shared key appears in the composition context, due to the scope in which the key key is restricted, we say that key is revealed if the intruder is able to deduce the fresh private name s which is possible if and only if the intruder is able to output key on the fresh public channel c.

Example 5.8. Consider the composition context C[ ] = !vskS_. Consider the process P1 described in Example 5.7. The intermediate process (Φ; C[P1]; 0) does not reveal the keys skS, pk(skS) and vk(skS). Indeed, let key ∈ {skS, pk(skS), vk(skS)}, the intermediate process

{(s); C[P1 | in(c,x).if x = key then out(c,s) else 0]; 0}

can not reach a configuration from which s will be derivable by the attacker.

5.2 Preliminaries

As mentioned at the beginning of this chapter, our proof technique is similar to the one of [CC10] and consists of transforming any trace of the combined processes that share secret keys into a trace of a composition of the processes where no secret key is shared. In this section, we will introduce the main notions that will be useful to define and prove such transformation.
5.2.1 Material for composition

As mentioned in Section 5.1, we consider in this chapter several signatures with their associated equational theories. We have \((\mathcal{F}_a, \mathcal{E}_a)\) and \((\mathcal{F}_b, \mathcal{E}_b)\) that are not specified, \((\mathcal{F}_0, \mathcal{E}_0)\) the common signature, and the two signatures that we use for tagging processes: \((\mathcal{F}_{tag_a}, \mathcal{E}_{tag_a})\) and \((\mathcal{F}_{tag_b}, \mathcal{E}_{tag_b})\).

Moreover, we know that all those signatures and equational theory are disjoint two at a time and consistent. Since a message sent over the network can be formed by a combination of all these signatures, we introduce several notions that will help us describing a term. We define \(\mathcal{F}\) and \(\mathcal{E}\) the union of the previous signatures and equational theories, i.e. \(\mathcal{F} = \mathcal{F}_a \cup \mathcal{F}_b \cup \mathcal{F}_0 \cup \mathcal{F}_{tag_a} \cup \mathcal{F}_{tag_b}\) and \(\mathcal{E} = \mathcal{E}_a \cup \mathcal{E}_b \cup \mathcal{E}_0 \cup \mathcal{E}_{tag_a} \cup \mathcal{E}_{tag_b}\).

5.2.1.1 Factors

The term \(N\) is alien to \(M\) if \(\text{root}(N) \in \mathcal{F}_i\), \(\text{root}(M) \in \mathcal{F}_j\) and \(i \neq j\). We now introduce the notion of factors. A similar notion is also used in [CR05].

**Definition 5.5** (Factors). Let \(M \in \mathcal{T}(\mathcal{F}, \mathcal{N} \cup \mathcal{X})\). The factors of \(M\), denoted \(\text{Fct}(M)\), are the maximal syntactic subterms of \(M\) that are alien to \(M\).

The factors will help us determine which parts of a term might have been computed by the processes \(P_A\) and \(P_B\) that we want to compose. Indeed, if the root of a term comes from the signature \(\mathcal{F}_0\) and the root of one of its factors comes from \(\mathcal{F}_j\) then it’s likely that this factor was computed by \(P_B\) and then injected into the process \(P_A\). However, its is not necessary the case since \(P_A\) and \(P_B\) share the signature \(\mathcal{F}_0\).

**Example 5.9.** Assume that \(\mathcal{F}_a\) is the signature made up of the constant symbol 0 and the binary function + and that the associated equation theory \(\mathcal{E}_a\) is the following set of equations:

\[
\begin{align*}
x + (y + z) &= (x + y) + z, \\
x + y &= y + x, \\
x + x &= 0
\end{align*}
\]

Let \(u\) be a term built upon \((\mathcal{F}_a \cup \mathcal{F}_0, \mathcal{E}_a \cup \mathcal{E}_0)\) such that \(u = \text{sdec}(\langle n_1 + n_2, n_3 \rangle; \text{proj}_1(n_1 + n_2)), n_3)\).

The term \(n_1 + n_2, n_3)\) is a syntactic subterm of \(u\) alien to \(u\) since \(\text{root}(n_1 + n_2, n_3) \in \mathcal{F}_+\) and \(\text{root}(u) \in \mathcal{F}_0\). We have that

\[
\text{Fct}(u) = \{n_1 + n_2, n_3), n_1 + n_2, n_3\}
\]

For our composition result, we work with tagged processes, i.e. \([P_A]_a\) and \([P_B]_b\). As described in Section 5.1 theses processes check the tags of a term before sending it over the network. While \(\text{senc}(\text{tag}_a(n), k)\) might have been computed by the process \(P_A\), the term \(\text{senc}(n, k)\) could not have been computed by \(P_A\) since it is not tagged with the tag \(a\) and was most likely computed by the intruder. Hence for terms root which is in the common signature, we introduce a specific notion of factors that takes into account terms.

**Definition 5.6** (Factor for \(\mathcal{F}_0\)). Let \(u\) be a term. We define \(\text{Fct}_{\mathcal{F}_0}(u)\) the factors of a term \(u\) for \(\mathcal{F}_0\) as the maximal syntactic subterms of \(u\) of the form \(f(\text{tag}_a(u_1), u_2)\) with \(f \in \{\text{senc}, \text{aenc}, \text{sign}\}\) and \(i \in \{a, b\}\); or of the form \(h(\text{tag}_a(u_1))\) with \(i \in \{a, b\}\); or whose root symbol is not in \(\mathcal{F}_0\).

**Example 5.10.** Consider the theory \((\mathcal{F}_a, \mathcal{F}_0)\) given in Example 5.9. Let \(u\) be a term built on \((\mathcal{F}_a \cup \mathcal{F}_{tag_a} \cup \mathcal{F}_0), \mathcal{E}_a \cup \mathcal{E}_{tag_a} \cup \mathcal{E}_0)\) such that \(u = \langle \text{senc}(\text{tag}_a(n_1), \langle n_1 + n_2, n_3 \rangle), \text{sign}(n_4, n_5) \rangle\). We have:

- \(\text{Fct}(u) = \{\text{tag}_a(n_1); n_1 + n_2; n_3; n_4; n_5\}\)
- \(\text{Fct}_{\mathcal{F}_a}(u) = \{\text{senc}(\text{tag}_a(n_1), \langle n_1 + n_2, n_3 \rangle); n_4; n_5\}\)
- \(\text{Fct}_{\mathcal{F}_0}(n_1 + n_2) = \{n_1 + n_2\}\)

We can see in this example that since the root of \(u\) is in \(\mathcal{F}_0\), \(\text{Fct}_{\mathcal{F}_0}(u)\) gives more informations than \(\text{Fct}(u)\). Indeed, \(\text{senc}(\text{tag}_a(n_1), \langle n_1 + n_2, n_3 \rangle)\) could have been computed by \([P_A]_a\) whereas \(\text{sign}(n_4, n_5)\) could not have been computed by \([P_A]_a\) or \([P_B]_b\). Hence, only \(n_4\) and \(n_5\) might have been computed by our processes.
Ordered rewriting

Most of the definitions and results in this subsection are borrowed from \cite{CR05} and \cite{CD12} since we use similar techniques. We consider the notion of ordered rewriting defined in \cite{DJ90}, which is a useful tool that has been used (e.g. \cite{BS96}) for proving correctness of combination of unification algorithms. It will allows us to use rewriting systems rather than equational theories which are sometimes difficult to handle in proofs.

Let \( \prec \) be a simplification ordering on ground terms, i.e. \( \prec \) satisfies that for all ground terms \( u, v_1, v_2 \), and for any position \( p \neq \epsilon \) in \( m \), \( v_1 \prec u[v_1]_p \) and \( v_1 \prec v_2 \) implies \( u[v_1]_p \prec u[v_2]_p \). Assume further that \( \prec \) is total, the minimum for \( \prec \) is a name \( n_{\text{min}} \) and the constants in \( \mathcal{F} \) are smaller than any ground term that is neither a constant nor a name. We define \( \mathcal{F}^+ \) to be the set of the function symbols of \( \mathcal{F} \) plus the name \( n_{\text{min}} \), i.e. \( \mathcal{F}^+ = \mathcal{F} \cup \{ n_{\text{min}} \} \). In what follows, we furthermore assume that \( n_{\text{min}} \) is never used under restriction in frames.

Given a possibly infinite set of equations \( \mathcal{O} \), we define the ordered rewriting relation \( \rightarrow_{\mathcal{O}} \) by \( t \rightarrow_{\mathcal{O}} t' \) if and only if there exist an equation \( u_1 = u_2 \in \mathcal{O} \), a position \( p \) in \( M \) and a substitution \( \tau \) such that:

\[
t = t[u_1\tau]_p, \quad t' = t[u_2\tau]_p \quad \text{and} \quad u_2\tau \prec u_1\tau
\]

It has been shown (see \cite{DJ90}) that by applying the unfailing completion procedure to a set of equations \( \mathcal{E} \) we can derive a (possibly infinite) set of equations \( \mathcal{O} \) such that on ground terms:

1. the relations \( =_{\mathcal{O}} \) and \( =_{\mathcal{E}} \) are equal,
2. the rewriting system \( \rightarrow_{\mathcal{O}} \) is convergent.

It was showed (\cite{BS96}) that applying unfailing completion to two disjoints sets of equations, e.g. \( \mathcal{E}_a \cup \mathcal{E}_b \), yields the set of generated equations \( \mathcal{O} \) that is the disjoint union of the two systems \( \mathcal{O}_a \) and \( \mathcal{O}_b \) obtained by applying unfailing completion procedures to \( \mathcal{E}_a \) and to \( \mathcal{E}_b \) respectively. We can easily extend this result to \( \mathcal{E} = \mathcal{E}_a \cup \mathcal{E}_b \cup \mathcal{E}_0 \cup \mathcal{E}_{\text{tag}a} \cup \mathcal{E}_{\text{tag}b} \) since they are all disjoint two at a time.

Thus, applying unfailing completion to \( \mathcal{E} \) yields the set of generated equations \( \mathcal{O} \) that is the disjoint union of \( \mathcal{O}_a, \mathcal{O}_b, \ldots, \mathcal{O}_{\text{tag}b} \) obtained by applying unfailing completion procedures respectively to \( \mathcal{E}_a, \mathcal{E}_b, \ldots, \mathcal{E}_{\text{tag}b} \). In fact, applying the unfailing procedure (see \cite{DJ90}) on \( \mathcal{E}_0 \) (resp. \( \mathcal{E}_{\text{tag}a} \) and \( \mathcal{E}_{\text{tag}b} \)) yields \( \mathcal{O}_0 = \mathcal{E}_0 \) (resp. \( \mathcal{O}_{\text{tag}a} = \mathcal{E}_{\text{tag}a} \) and \( \mathcal{O}_{\text{tag}b} = \mathcal{E}_{\text{tag}b} \)). Typically, it is due to the fact that each equation has a variable as right hand side, which is subterm of the left hand side of the equation. Therefore, the rewriting systems \( \rightarrow_{\mathcal{O}_a}, \rightarrow_{\mathcal{O}_{\text{tag}a}} \) and \( \rightarrow_{\mathcal{O}_{\text{tag}b}} \) are as follows:

\[
\begin{align*}
\rightarrow_{\mathcal{O}_{\text{tag}a}}: \quad & \text{untag}_a(\text{tag}_a(x)) \rightarrow x \\
\rightarrow_{\mathcal{O}_{\text{tag}b}}: \quad & \text{untag}_b(\text{tag}_b(x)) \rightarrow x \\
\rightarrow_{\mathcal{O}_a}: \quad & \text{sdec}(\text{senc}(x, y), y) \rightarrow x \\
& \text{adec}(\text{aenc}(x, \text{pk}(y)), y) \rightarrow x \\
& \text{proj}_1((x, y)) \rightarrow x \\
& \text{proj}_2((x, y)) \rightarrow y \\
& \text{check}(\text{sign}(x, y), \text{vk}(y)) \rightarrow x
\end{align*}
\]

Since the relation \( \rightarrow_{\mathcal{O}} \) is convergent on ground terms, we define \( t \downarrow \) as the unique normal form of the ground term \( t \) for \( \rightarrow_{\mathcal{O}} \).

We can now state two lemmas that we will use in the next sections. Intuitively, the first lemma shows that the rewrite rules, applied during the normalisation of a term with factors in normal form, never modify these factors. The second lemma indicates that the normalisation and the replacement of factors commute, provided that the replacement preserved the equalities between factors.

**Lemma 5.2** (Proved in \cite{CD12}). Let \( t \) be a ground term such that all its factors are in normal form and \( \text{root}(t) \in \mathcal{F}_i \) with \( i \in \{ a, b, \text{tag}_a, \text{tag}_b, 0 \} \). Then

- either \( t \downarrow \in \text{Fct}(t) \cup \{ n_{\text{min}} \} \),
- or \( \text{root}(t \downarrow) \in \mathcal{F}_i \) and \( \text{Fct}(t \downarrow) \subseteq \text{Fct}(t) \cup \{ n_{\text{min}} \} \).
Lemma 5.3. Let \( t \) be a ground term such that \( t = C[u_1, \ldots, u_n] \) where \( C \) is a context built on \( F_i \), \( i \in \{a, b, \text{tag}_a, \text{tag}_b, 0\} \) and \( u_1, \ldots, u_n \) are the factors of \( t \) in normal form. Furthermore, let \( D \) be the context built on \( F_i \) (possibly a hole) such that \( t_\downarrow = D[u_{j_1}, \ldots, u_{j_k}] \) with \( j_1, \ldots, j_k \in \{0, \ldots, n\} \) and \( u_0 = \pi_{\min} \) (the existence is given by Lemma 5.2). For all ground terms \( v_1, \ldots, v_n \) in normal form and alien to \( t \), if
\[
\forall (p, q) \in \{0 \ldots n\}, u_p = u_q \Leftrightarrow v_j = v_q
\]
then \( C[v_1, \ldots, v_n] \downarrow = D[v_{j_1}, \ldots, v_{j_k}] \) with \( v_0 = \pi_{\min} \).

Proof. Thanks to Lemma 19 of [CD12], and the fact that \( u_1, \ldots, u_n \) are factors in normal form, we know that the derivation of \( t \) is due to rewriting rules from \( O \). Hence, we do a proof by induction on the length \( L \) of the derivation
\[
t \rightarrow_O \ t_1 \rightarrow_O \ t_2 \rightarrow_O \ldots \rightarrow_O \ t_n \rightarrow_O t_\downarrow
\]
where each \( t_n \) is minimal among the terms \( N \) such that \( t_k \rightarrow_O \ t \).

Base case \( L = 0 \): In such a case, \( t \) is in normal form and so \( C = D \), \( n = k \) and \( j_\ell = \ell \) for all \( \ell \in \{1, \ldots, n\} \). Let \( v_1, \ldots, v_n \) in normal form and alien to \( t \) such that for all \( (p, q) \in \{0 \ldots n\} \), \( u_p = u_q \) implies \( v_p = v_q \). We show that \( C[v_1, \ldots, v_n] \) is in normal form.

Assume that it is not the case. Let’s denote \( M = C[v_1, \ldots, v_n] \). Thanks to Lemma [CD12], we know that there exists a rule in \( O \) applied on \( M \). Let \( M' \) be the minimal term for \( \prec \) among the terms \( N \) such that \( M \rightarrow_O N \). Let \( \ell = r \in O \) applied on \( M \) at position \( p \) with substitution \( \sigma \) in order to obtain \( M' \).

Since the factors \( v_1, \ldots, v_n \) are in normal form, the position \( p \) is above or incomparable with any position corresponding to a factor of \( M \). Thus, for all \( x \in \text{fears}(\ell) \), there exists a position \( p' \) of \( C \) such that \( x\sigma = C[v_1, \ldots, v_n]_{p'} \). Combined with the fact that \( t \) being in normal form implies that \( t \) and \( t_{\downarrow} \) are not unifiable, we have that there exists two positions \( q, q' \) of \( C \) and a variable \( x \in \text{fears}(\ell) \) such that \( x\sigma = C[v_1, \ldots, v_n]_{q} = C[v_1, \ldots, v_n]_{q'} \) and \( C[u_1, \ldots, u_n]_{q} \neq C[u_1, \ldots, u_n]_{q'} \). Thus there exists \( j, j' \in \{1, \ldots, n\} \) such that \( v_j = v_{j'} \) and \( u_j \neq u_{j'} \) which is in contradiction with our hypothesis.

Inductive step \( L > 0 \): We have \( t \rightarrow_O t_1 \rightarrow_O t_\downarrow \). Let \( \ell = r \in O \) applied on \( t \) at position \( p \) with substitution \( \sigma \) in order to obtain \( t' \). Thanks to Lemma 5.2, we know that \( t' = C[u_{j_1}, \ldots, u_{j_k}] \), with \( j_1, \ldots, j_k \in \{0, \ldots, n\} \) and \( u_0 = \pi_{\min} \). With the same proof as in the base case, we can show that the same rule \( \ell = r \) can be applied on \( C[v_1, \ldots, v_n] \) at position \( p \) with a substitution \( \sigma' \). By minimality of the term \( t_1 \) and monotonicity of \( \prec \), we have that \( \text{fears}(r)\sigma' \subseteq \text{fears}(\ell)\sigma' \cup \{\pi_{\min}\} \) (same for \( \sigma \)). With \( p \) being a position of \( C \) and \( r \) is built upon \( F_i \), we have that \( (C[u_1, \ldots, u_n])_{p}[r\sigma]' = C'[u_{j_1}, \ldots, u_{j_k}] \) implies \( (C[v_1, \ldots, v_n])_{p}[r\sigma]' = C'[v_{j_1}, \ldots, v_{j_k}] \). Thus by application of our inductive hypothesis on \( t_1 \) and \( C'[v_{j_1}, \ldots, v_{j_k}] \), the result holds.

5.2.2 Derived well-tagged processes

We are now focus on the messages that are sent over the network during the execution of the processes. For a term \( u \) that does not contain any tag, we defined in Section 5.1 a way to construct a term that is properly tagged (i.e. \([u]_n\)). Hence, for a term properly tagged, we would never have \( \text{senc}(n, k) \) where \( n \) and \( k \) are both nonces, for example. Instead, we would have \( \text{senc}(\text{tag}(n), k) \).

However, even if we can force the processes to properly tag their term, we do not have any control on what the intruder can build. Typically, if the intruder is able to deduce \( u \) and \( k \), he is allowed to send to a process the term \( \text{senc}(n, k) \). Similarly, while we can restrict our processes to only apply \( v_k \) and \( p_k \) on a nonce, we can not restrict the intruder from using these cryptographic primitive with terms different from a nonce.

Hence, we need to describe what kind of frame and process we obtained in a trace of a tagged process. To do so, we assume from now on that processes and frames are coloured by \( a \) or \( b \). Intuitively, colouring a process by \( a \) means that this process was derived from a process originally tagged by \( a \). The same way, we say that a frame element (\( ax \triangleright u \)) of a frame is coloured by \( a \).
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if u was output by a process derived from a process originally tagged by a. We denote \(\text{col}(ax)\) the colour of the frame element \((ax \triangleright u)\), and \(\text{col}(P)\) the colour of the process \(P\).

**Definition 5.7.** Let \((\mathcal{E}; \Phi; \Phi)\) be an intermediate process. Let’s denote \(\Phi = \{ax_1 \triangleright u_1, \ldots, ax_n \triangleright u_n\}\). We say that \(\nu \mathcal{E}_{\Phi}\) is a derived well-tagged frame if for all \(i \in \{1, \ldots, n\}\), \(u_i\) is a derived well-tagged term up to \(ax_i\), i.e. there exists a term \(v\), a substitution \(\alpha\) and \(c \in \{a, b\}\) such that:

- for all \(vk(t)\), \(pk(t') \in st(v), t, t' \in \mathcal{N}\);
- \(u_i = [v]_c\alpha\); and
- \(\alpha \vdash \text{test}_c([v]_c)\); and
- for all \(x \in \text{dom}(\alpha)\), either \(v\) is not a variable and \(x\alpha\) is a derived well-tagged term up to \(ax_i\); or there exists \(M\) such that \(\text{fvars}(M) \subseteq \{ax_1, \ldots, ax_{i-1}\}\), \(\text{fnames}(M) \cap \mathcal{E} = \emptyset\) and \(M\Phi = x\alpha\).

The terms \([v]_c\) represent the term that was in the original process before instantiation, e.g. \(\text{out}(c, [v]_c)\). On the other hand \(\alpha\) represents the value of the variables defined by the inputs, e.g. \(\text{in}(c, x)\). The third condition is due the fact that in a tagged process, there is always a condition that \(\text{test}_c([v]_c)\) before outputting it. Hence, if \(u_i\) is in the frame, it necessary means that \(\alpha\) satisfies the tests \(\text{test}_c([v]_c)\).

Note that the definition is recursive. Indeed, since \(\alpha\) represents the instantiation of the variables defined by the inputs, given a variable \(x\) of \(\text{dom}(\alpha)\), either it was instantiated by the rule \(\text{In}_x\) and so the intruder can deduce \(x\alpha\); or it was instantiate by an internal communication, i.e. \(\text{Comm}_x\), and so it means that \(x\alpha\) is also well-tagged up to \(ax_i\) (since the term \(x\alpha\) comes from another tagged process).

The condition \(v\) is not a variable allows us to avoid an infinite loop in the definition. Indeed, if this condition did not exist, then any term \(u\) would be well-tagged up to \(ax_i\) (take \(v\) a variable and \(\alpha\) such that \(v\alpha = u\)). In our case, when \(v\) is a variable, it will necessarily means that this variable was instantiate by the rule \(\text{In}_x\) and so that the intruder could deduce it.

**Example 5.11.** Coming back to Example 5.12 we have \(\mathcal{E} = \{sk_a^b, sk_b^a, r'\}\) and the following frame:

\[\Phi(A'_{d}) = \{ax_1 \triangleright \text{aenc}(\text{tag}_a((r', i_1)), pk(sk_b^a)); ax_2 \triangleright \text{aenc}(\text{tag}_a(u), pk(sk_b^a))\}\]

where \(u = \text{aenc}(\text{tag}_a((r', i_1)), pk(sk_b^a))\). This is a well-tagged frame.

Indeed, consider first \(u_1 = \text{aenc}(\text{tag}_a((r', i_1)), pk(sk_b^a))\). Let \(v_1 = \text{aenc}((r', i_1), pk(sk_b^a))\) and \(\alpha_1\) be the identity. We have:

- \(sk_b^a \in \mathcal{N}\) hence the first condition is satisfied
- \(\text{aenc}(\text{tag}_a((r', i_1)), pk(sk_b^a)) = [v_1]_a\alpha_1\)
- \(\text{test}_a([v]_a) = \text{true}\) and \(\alpha_1 \vdash \text{true}\).

The last property is trivially true since \(\text{dom}(\alpha_1) = \emptyset\).

Consider now \(u_2 = \text{aenc}(\text{tag}_a(u), pk(sk_b^a))\). Let \(v_2 = \text{aenc}(x, pk(sk_b^a))\) and \(\alpha_2 = \{x \mapsto u_1\}\). We have:

- \(sk_b^a \in \mathcal{N}\) hence the first condition is satisfies
- \([v_2]_b = \text{aenc}(\text{tag}_a(x), pk(sk_b^a))\) hence \([v_2]_b\alpha_2 = u_2\)
- Once again \(\text{test}_b([v_2]_b) = \text{true}\) and \(\alpha_2 \vdash \text{true}\)

At last, we already show that \(x\alpha_2 = u_1\) is well-tagged up to \(ax_1\) hence it is also well-tagged up to \(ax_2\). Note that the last property is also satisfied by the fact that \(ax_1\Phi(A'_{d}) = x\alpha = u_1\).
Similarly to the notion of a derived well-tagged frame, we introduce the notion of derived well-tagged process.

**Definition 5.8.** Let $P$ a coloured plain process and $\alpha$ be a ground substitution such that $\text{fvars}(P) \subseteq \text{dom}(\alpha)$. We will says that $(P, \alpha)$ is a derived well-tagged process if

- either $P = [Q]_i$;
- or $P = \text{out}(u, [v]_i)_i[Q]_i, \alpha \vdash \text{test}_i([v]_i)$;
- or $P = \text{if} [u]_i = [v]_i \text{ then } [Q_1]_i \text{ else } [Q_2]_i \text{ with } \alpha \vdash \text{test}_i([u]_i) \land \text{test}_i([v]_i)$

where $i = \text{col}(P)$ and $Q, Q_1, Q_2$ are processes built on $F_i \cup F_0$, and $u, v$ are some terms.

For a coloured multi-set of processes $\mathcal{P}$, we say that $(\mathcal{P}, \alpha)$ is an original well-tagged multi-set of processes if for all $P \in \mathcal{P}$, $(P, \alpha)$ is an original well-tagged process.

Intuitively, in a derived well-tagged process $(P, \alpha)$, $P$ represents a subprocess of the original process $P_a$ or $P_b$ (depending on the colour of $P$) and $\alpha$ represents the values of the variables instantiated by the rule $\text{In}_i$. The definition of a derived well-tagged process expresses all the possible states of a plain process obtained from a derivation of $(E_0; \{P_a, P_b\}; \emptyset)$ or $(E_0; \{P_a, P_b\rho^{-1}\}; \emptyset)$.

### 5.3 Going back to the disjoint case

In this section, we will focus on our first composition result. As mentioned in previous sections, we show that the disjoint case (i.e. where the processes do not share any secret) and the shared case (i.e. when the processes share some secrets) are equivalent provided some conditions. More specifically, we will show that given two sequences of plain processes $\mathcal{P}_A$ and $\mathcal{P}_B$, built on $F_a \cup F_0$ and $F_b \cup F_0$ respectively, given a composition context $C$, we have that:

$$C[[\mathcal{P}_A]_a | [\mathcal{P}_B]_b] \approx_t C[[\mathcal{P}_A]_a | C[[\mathcal{P}_B]_b].$$

if $C[[\mathcal{P}_A]_a$ and $C[[\mathcal{P}_B]_b$ do not reveal any shared key in $\{k, pk(k), vk(k) \mid k \text{ occurs in } C\}$. A sketch of proof of right implication of this equivalence is given in Figure 5.1

**Unfolding**

\[ \forall (tr, \nu \varepsilon \Phi) \in \text{trace}_i(C[[\mathcal{P}_A]_a | [\mathcal{P}_B]_b]) \]

\[ \exists (tr, \nu \varepsilon \Phi') \in \text{trace}_i(C[[\mathcal{P}_A]_a | C[[\mathcal{P}_B]_b]) \]

\[ \text{Lemma 5.8} \]

\[ \rho \text{ is a fresh renaming of the shared private name and both } Q_s \text{ and } Q_d \text{ are bounded intermediate processes.} \]

**Figure 5.1:** Sketch of proof of $C[[\mathcal{P}_A]_a | [\mathcal{P}_B]_b] \subseteq_t C[[\mathcal{P}_A]_a | C[[\mathcal{P}_B]_b].$

Intuitively, given a trace of the shared case (i.e. of the processes that share secret), we start by unfolding the replications in the process w.r.t. the trace so that we do not have any more
replication or name restriction. Then, thanks to our soundness lemma, we show that this trace can be transformed into a trace of the disjoint case (i.e. of the processes that do not share secret). We conclude by showing that a trace of a process that has been unfold can be transformed into a trace of this process. The sketch of proof for the left implication of this equivalence is similar although we use a completeness result, instead of a soundness result, in order to transform a trace on the disjoint case into a trace of the shared case.

This section is devoted to the complete proof of this result.

5.3. GOING BACK TO THE DISJOINT CASE

5.3.1 Name replacement

As mentioned in Figure 5.1, we have to transform a trace of the shared case into a trace of the disjoint case, and vice versa. In fact, we will see that the transformation will mainly consist of replacing some instances of the shared names by fresh ones.

Example 5.12. Consider the process $P_1$ in Example 5.1 and the composition context $C = vsk_{S, -}$ and the process $Q = \text{in}(c, x).\text{out}(c, \text{aenc}(x, pk(sk_S)))$. We tag $P_1$ and $Q$ respectively with the tags $a$ and $b$. Hence the intermediate process corresponding to the shared case is the following:

$$A_s = (\emptyset; C[\nu r.\text{out}(c, \text{aenc}(\text{tag}_a((r, id_1)), pk(sk_S))) | \text{in}(c, x).\text{out}(c, \text{aenc}(\text{tag}_a(x), pk(sk_S))); \emptyset)$$

while the disjoint case corresponds to the following intermediate process:

$$A_d = (\emptyset; C[\nu r.\text{out}(c, \text{aenc}(\text{tag}_a((r, id_1)), pk(sk_S))) | C[\text{in}(c, x).\text{out}(c, \text{aenc}(\text{tag}_a(x), pk(sk_S)))]; \emptyset)$$

Now, let $tr$ be the sequence of labels $\text{vax}_1.\text{out}(c, ax_1).\text{in}(c, ax_1).\text{vax}_2.\text{out}(c, ax_2)$. We have that $A_s \xrightarrow{} A'_s$ and $A_d \xrightarrow{} A'_d$ where

$$A'_s = (\{sk^a_S, r'; \emptyset; \{ax_1 \triangleright \text{aenc}(\text{tag}_a((r', id_1)), pk(sk^a_S)); ax_2 \triangleright \text{aenc}(\text{tag}_a(u), pk(sk^a_S))\})$$

$$A'_d = (\{sk^b_S, sk^b_S, r'; \emptyset; \{ax_1 \triangleright \text{aenc}(\text{tag}_a((r', id_1)), pk(sk^b_S)); ax_2 \triangleright \text{aenc}(\text{tag}_a(u), pk(sk^b_S))\})$$

where $u = \text{aenc}(\text{tag}_a((r', id_1), pk(sk^a_S))$. In $A'_d$, $sk^b_S$ corresponds to the renaming of the name $sk_S$ restricted over $P_1$ while $sk^b_S$ corresponds to the renaming of the name $sk_S$ restricted over $Q$ (application of the rule New). Furthermore, if we look at the second message of each frame, we can see that they are equal up to replacement of one instance of $sk^a_S$ by $sk^b_S$. Typically, the key $sk^a_S$ that is used to encrypt with the tag $a$ stays $sk^a_S$ in the disjoint case while the key $sk^a_S$ that is used to encrypt with the tag $b$ is replace by $sk^b_S$.

Even if Example 5.12 use very simple processes, we will see that all of the messages in the processes and frames of two matched traces are equal up to a replacement of instances of "shared keys" with their corresponding "disjoint keys". We introduce a notion that formalise this replacement of names.

Let $\rho$ be a bijective renaming of names of base type such that for all $k \in \text{dom}(\rho)$, $k$ is a "fresh name". Let $\delta_\rho (c \in \{a, b\})$ be functions on terms that is defined as follows:

- $\delta_\rho(u) = u$ when $u$ is a name or a variable;
- $\delta_\rho(k) = k$ when $u = kp$ for some $k \in \text{dom}(\rho)$ and $\text{root}(u) \not\in \mathcal{F}_b \cup \mathcal{F}_{\text{tag}_b} \cup \mathcal{F}_0$; otherwise $\delta_\rho(u) = u$ when $u$ is a name or a variable;
- $\delta_\rho(f(t_1, \ldots, t_k)) = f(\delta_\rho(t_1), \ldots, \delta_\rho(t_k))$ if $f \in \mathcal{F}_d \cup \mathcal{F}_{\text{tag}_d}$ with $d \in \{a, b\}$.
- $\delta_\rho(f(\text{tag}_d(t_1), t_2)) = f(\text{tag}_d(\delta_\rho(1)), \delta_\rho(t_2))$ if $f \in \{\text{aenc}, \text{aenc}, \text{sign}\}$ and $d \in \{a, b\}$
- $\delta_\rho(h(\text{tag}_d(t_1))) = h(\text{tag}_d(\delta_\rho(t_1)))$ if $d \in \{a, b\}$
- $\delta_\rho(f(t_1, \ldots, t_k)) = f(\delta_\rho(t_1), \ldots, \delta_\rho(t_k))$ otherwise
CHAPTER 5. COMPOSING TRACE EQUIVALENCE

Intuitively, \( \text{img}(\rho) \) correspond to the key generated in the shared case (same as the key generated by \( P_A \) in the disjoint case, e.g. \( sk^A_S \), while \( \text{dom}(\rho) \) corresponds to keys generated by \( P_B \) in the disjoint case, e.g. \( sk^B_S \). The purpose of \( \delta^\rho_u \) is to replace the keys used by \( P_B \) in the shared case but created by \( P_A \) (i.e. \( \text{img}(\rho) \)) with the keys generated by \( P_B \) (i.e. \( \text{dom}(\rho) \)). We consider the names of \( \text{dom}(\rho) \) "fresh" in the sense that the names in \( \text{dom}(\rho) \) should never appear in the argument of \( \delta^\rho_u \) and \( \delta^\rho_v \).

Example 5.13. Coming back to Example 5.12, we have \( \rho = \{ sk^B_S \mapsto sk^2_S \} \), \( \delta^\rho_v(ax_1 \Phi(A'_u)) = ax_1 \Phi(A'_u) \) and \( \delta^\rho_v(ax_2 \Phi(A'_u)) = ax_2 \Phi(A'_u) \).

Note that \( \delta^\rho_u \) and \( \delta^\rho_v \) do not behave the same way depending of the message being properly tagged or not.

Example 5.14. Let \( \rho = \{ sk^b_S \mapsto sk^a_S \} \) and consider the following terms:

- \( u_1 = \text{aenc}(n, \text{pk}(sk^a_S)) \) and so \( \delta_u(u_1) = \text{aenc}(n, \text{pk}(sk^b_S)) \) and \( \delta_b(u_1) = \text{aenc}(n, \text{pk}(sk^b_S)) \)
- \( u_2 = \text{aenc}(\text{tag}_a(n), \text{pk}(sk^a_S)) \) and so \( \delta_u(u_2) = \delta_b(u_2) = \text{aenc}(\text{tag}_a(n), \text{pk}(sk^b_S)) \)
- \( u_3 = \text{aenc}(\text{tag}_b(n), \text{pk}(sk^b_S)) \) and so \( \delta_u(u_3) = \delta_b(u_3) = \text{aenc}(\text{tag}_b(n), \text{pk}(sk^b_S)) \)

Note that in both previous examples, the terms we considered are already in normal form. We prove three lemmas that describe some properties of \( \delta^\rho_u \) and \( \delta^\rho_v \) on terms in normal form (proofs in Appendix B.1).

Lemma 5.4. If \( t_1, t_2 \) are terms (that do not use \( \text{dom}(\rho) \)) in normal form then for all \( i \in \{a, b\} \), \( t_1 = t_2 \) is equivalent to \( \delta^\rho_i(t_1) = \delta^\rho_i(t_2) \).

The previous lemma shows that \( \delta^\rho_u \) and \( \delta^\rho_v \) preserve equality between terms. It allows us to prove the following result:

Lemma 5.5. Let \( t_1, t_2 \) two terms (that do not use \( \text{dom}(\rho) \)) in normal form. If \( \delta^\rho_u(t_1) = \delta^\rho_v(t_2) \) then \( t_1 = t_2 \).

While the two previous lemmas mainly focus on the relations between equality and the name replacement. The following lemma indicates that the root and irreductibility of terms is also preserved by \( \delta^\rho_u \) and \( \delta^\rho_v \).

Lemma 5.6. Let \( u \) be a term in normal form that do no use \( \text{dom}(\rho) \). We have that for all \( i \in \{a, b\} \), \( \delta^\rho_i(u) \) is in normal form and \( \text{root}(\delta^\rho_i(u)) = \text{root}(u) \).

5.3.2 Unfolding the processes

The first difficulty is the presence of the replication in the composition context \( C \) and also in the sequences of processes \( P_A \) and \( P_B \). The main idea is to unfold the replication in advance so that replication is not needed anymore. Of course, it is impossible to unfold in advance a process \( P \) so that all traces of \( P \) are included in this unfolded process. However, given a trace \( P \), it is possible to unfold \( P \) so that at least this specific trace is included in the unfolded process. The main idea of unfolding a process \( P \) given a trace of \( P \) is to replace any instance of \( 1Q \) in \( P \) by \( Q \mid \ldots \mid Q \) where the number of parallel composition is higher than the number of application of \( \text{Rep}_n \) in the derivation of the trace. At last, similarly to Chapter 4, we move forward the name restriction so that the unfolded process is an bounded intermediate process (i.e. without replication nor name restriction).

Example 5.15. Consider the processes \( P_1 \) (renamed \( P \)) and \( Q \) in Example 5.12. Furthermore, consider the composition context \( C = \nu sk_S.\_\_\_ \) and consider the intermediate process \( A_n = (\emptyset; C|P \mid Q; \emptyset) \). We have that for all \( n \in \mathbb{N} \), \( \text{tr}_n, \nu E_n, \Phi_n \) is in \( \text{trace}(A_n) \) where:

- \( \text{tr}_n = \nu ax_1.\text{out}(c, ax_1) \ldots \nu ax_n.\text{out}(c, ax_n) \)
5.3. GOING BACK TO THE DISJOINT CASE

- \( \mathcal{E}_n = \{ sk_S, sk'_S, r_1, \ldots, r_n \} \)
- \( \Phi_n = \{ ax_1 \triangleright aenc(\text{tag}_{a}(r_1, id_1), pk(sk_S)); \ldots; ax_n \triangleright aenc(\text{tag}_{a}(r_n, id_1), pk(sk_S)) \} \)

Now consider the intermediate process \( A'_1 = (\emptyset; \{ \nu \text{sk}_S, P_1 | \ldots | P_n \mid Q_1 | \ldots | Q_n \}; \emptyset) \) where for all \( i \in \{1, \ldots, n\} \), \( P_i = P \) and \( Q_i = Q \). The process \( A'_1 \) is an unfolded process of \( A_n \) given the trace \((tr_n, \nu \mathcal{E}_n, \Phi_n)\). Furthermore, we have that \((tr_n, \nu \mathcal{E}_n, \Phi_n) \in \text{trace}(A'_1)\).

We can announce an intuitive result on unfolded process:

**Lemma 5.7.** Let \( n \in \mathbb{N} \). Let \( A \) be an intermediate process and \( A' \) be the unfolded intermediate process where we replace every instance of \( iP \) in \( A \) by \( P_1 | \ldots | P_n \) with \( P_i = P \) for all \( i \in \{1, \ldots, n\} \). We have that

- \( \text{trace}(A') \subseteq \text{trace}(A) \)
- if \((tr, \nu \mathcal{E}, \Phi) \in \text{trace}(A)\) such that the derivation contains less than \( n \) application of \( \text{REPL}_i \) then \((tr, \nu \mathcal{E}, \Phi) \in \text{trace}(A')\)

**Proof (sketch).** Intuitively, given a trace of \( A' \) the idea is to replace each \( \tau \) action corresponding to the application of \( \text{PAR}_i \) on an instance \( P | \ldots | P \), by an application of \( \text{REPL}_i \) on \( iP \).

Similarly, to show that \((tr, \nu \mathcal{E}, \Phi) \in \text{trace}(A')\), we replace each \( \tau \) action corresponding to the application of \( \text{REPL}_i \) on an instance \( iP \), by an application of \( \text{PAR}_i \) on \( P | \ldots | P \). It is possible since we know that there is less than \( n \) application of \( \text{REPL}_i \).

Note that in the previous example, we only focused on the "shared case". But, since we have to link the shared case with the disjoint case, we show that we can unfold the same way the intermediate processes representing the shared and disjoint case. This can be expressed with the following lemma.

**Lemma 5.8.** Let \( C \) be a composition context. Let \( \mathcal{P}_A \) (resp. \( \mathcal{P}_B \)) be a sequence of plain processes built on \( \mathcal{F}_u \cup \mathcal{F}_i \) (resp. \( \mathcal{F}_u \cup \mathcal{F}_i \)).

Let \( D = (\emptyset; C[\mathcal{P}_A]_a \mid C[\mathcal{P}_B]_b; \emptyset) \) and \( S = (\emptyset; C[\mathcal{P}_A]_a \mid C[\mathcal{P}_B]_b; \emptyset) \), we have that for all \((tr, \nu \mathcal{E}, \Phi) \in \text{trace}(D)\) (resp. \( \text{trace}(S)\)), there exists a renaming \( \rho \) and two bounded intermediate processes \( S' = (\mathcal{E}_0; \{ P_a, P_b \}; \emptyset) \) and \( D' = (\mathcal{E}_0; \{ P_a, P_b\rho^{-1} \}; \emptyset) \) such that

- \( \text{dom}(\rho) \cup \text{img}(\rho) \subseteq \mathcal{E}_0 \) and \( \text{dom}(\rho) \) does not appear in \( \{ P_a, P_b \} \)
- for all \( i \in \{a, b\} \), there exists \( P'_i \) built on \( \mathcal{F}_u \cup \mathcal{F}_i \) such that such that \( P_i = [P'_i] \);
- there exists \( \Phi' \) such that \((tr, \nu \mathcal{E}_0, \Phi') \in \text{trace}(D')\) (resp. \( \text{trace}(S')\)) and \( \nu \mathcal{E}_0, \Phi' \sim \nu \mathcal{E}, \Phi \)
- for all \((tr', \nu \mathcal{E}_0, \Phi') \in \text{trace}(S')\) (resp. \( \text{trace}(D')\)), there exists \( \nu \mathcal{E}', \Phi' \) such that \((\nu \mathcal{E}', \Phi') \in \text{trace}(S)\) (resp. \( \text{trace}(D)\)) and \( \nu \mathcal{E}', \Phi' \sim \nu \mathcal{E}_0, \Phi''\)

Note that \( \delta_\nu(P_a) = P_a \) and \( \delta_\nu(P_b) = P_b\rho^{-1} \)

**Proof.** Assume w.l.o.g that \((tr, \nu \mathcal{E}, \Phi) \in \text{trace}(S)\). Hence, we have that \( S \xrightarrow{\tau} (E; P; \Phi) \) for some \( P \).

Thus, there exists a word \( w \) such that \( S \xrightarrow{w} E; P; \Phi \) where \( tr = w \cdot \tau \). Let \( N \) be the number of \( \tau \) action corresponding to the application of the rule \( \text{REPL}_i \).

Let \( C' \) be the composition without replication, \( \mathcal{P}'_A \) and \( \mathcal{P}'_B \) the sequences of plain process without replication such that \( C'[\mathcal{P}'_A]_a \mid [\mathcal{P}'_B]_b \) corresponds to \( C[\mathcal{P}_A]_a \mid [\mathcal{P}_B]_b \) where we replaced every instance \( iP \) by \( P_1 | \ldots | P_N \) for some where \( P_i \) is a renaming of \( P \).

Let \( P_a \) be the plain process \( C'[\mathcal{P}'_A]_a \) where we removed all name restriction and let \( P_b \) be the plain process \( C'[\mathcal{P}'_B]_b \) where we removed all name restriction. At last, let \( \rho \) be a renaming such that \( \text{dom}(\rho) \) are fresh names and \( \text{img}(\rho) = bnames(C') \). At last, let \( \mathcal{E}_0 = bnames(C') \cup bnames(\mathcal{P}'_A) \cup bnames(\mathcal{P}'_B) \cup \text{dom}(\rho) \).

Let \( S'_0 = (\mathcal{E}_0, \{ P_a, P_b \}, \emptyset) \) and \( D'_0 = (\mathcal{E}_0, \{ P_a, P_b\rho^{-1} \}, \emptyset) \). We have that \( S' \) is a bounded intermediate process associated to \((\emptyset, \{ C'[\mathcal{P}'_A]_a \mid [\mathcal{P}'_B]_b \}; \emptyset)\). Furthermore, since \( \text{dom}(\rho) \) is only composed of fresh names, \( P_b\rho^{-1} \) is a renaming of \( C'[\mathcal{P}'_B]_b \) and so \( D' \) is a bounded intermediate process associated to \((\emptyset, \{ C'[\mathcal{P}'_A]_a \mid C'[\mathcal{P}'_B]_b \}; \emptyset)\). We conclude by applying Lemma 5.7. \( \square \)
We first show that a frame 5.3.3.1 Static equivalence

Example 5.16. Coming back to Example 5.16, consider the intermediate process $A_5$ and the trace $(\text{tr}_n, \nu E, \Phi_n) \in \text{trace}(A_5)$. Furthermore, consider the intermediate process $A_4 = (\emptyset; C[P] | C[Q]; \emptyset)$. The process $D'$ and $S'$ obtained thanks to Lemma 5.8 from $A_4$ and $A_5$ are the processes $(\mathcal{E}_0; \{P_a, P_b\}; \emptyset)$ and $(\mathcal{E}_0; \{P_a, P_b \rho^{-1}\}; \emptyset)$ where:

- $\mathcal{E}_0 = \{sk_1, sk_1', r_1, \ldots, r_n\}$
- $\rho = \{sk_1' \mapsto sk_1\}$
- $P_a = [P_1 | \ldots | P_n]_a$ where $P_i = \text{out}(c, \text{aenc}(\text{tag}_a(\langle r_i, id_i \rangle), \text{pk}(sk_i)))$, for all $i = 1 \ldots n$
- $P_b = [Q_1 | \ldots | Q_n]_b$ where $Q_i = \text{in}(c, x). \text{out}(c, \text{aenc}(x, \text{pk}(sk_i')))$

5.3.3 Soundness and completeness

In this subsection, we focus our attention on the transformation of a trace from the "shared case" (resp. "disjoint case") to a trace from the "disjoint case" (resp. "shared case").

We will assume that processes of different colours do not share private channels. We denote by $\delta^\rho(\cdot)$ the function that apply $\delta^\rho_i(\cdot)$ on frame elements or processes coloured by $a$, and that apply $\delta^\rho_i(\cdot)$ on frame elements or processes coloured by $b$. Moreover, given $i \in \{a, b\}$ and $\alpha$ a ground substitution, we denote by $\delta^\rho_i(\alpha)$ the substitution such that $\text{dom}(\alpha) = \text{dom}(\delta^\rho_i(\alpha))$ and for all $x \in \text{dom}(\alpha)$, $\delta^{\rho_i}(\alpha x) = \delta^\rho_i(\alpha x)$.

5.3.3.1 Static equivalence

We first show that a frame $\Phi$ in the shared case and its corresponding frame in the disjoint case, i.e. $\delta^\rho(\Phi)$ are statically equivalent. This result is derived from the following lemma (proof in Appendix B.2):

**Lemma 5.9.** Let $\mathcal{E}$ be a set of names and $\Phi = \{ax_1 \triangleright u_1, \ldots, ax_n \triangleright u_n\}$ such that $\nu E. \Phi$ is a derived well-tagged frame in normal form. Let $\rho$ be a renaming such that $\text{dom}(\rho) \cup \text{img}(\rho) \subseteq \mathcal{E}$ and $\text{dom}(\rho) \cap \text{frames}(\Phi) = \emptyset$. If one of the two following conditions is satisfied:

(a) for all $k \in \text{img}(\rho)$, $\nu E. \Phi \not\vdash k$, $\nu E. \Phi \not\vdash \text{pk}(k)$ and $\nu E. \Phi \not\vdash \text{vk}(k)$

(b) for all $k \in \text{img}(\rho) \cup \text{dom}(\rho)$, $\nu E. \delta^\rho(\Phi) \not\vdash k$, $\nu E. \delta^\rho(\Phi) \not\vdash \text{pk}(k)$ and $\nu E. \delta^\rho(\Phi) \not\vdash \text{vk}(k)$;

then for all $M$ such that feesr$(M) \subseteq \text{dom}(\Phi)$ and fnames$(M) \cap \mathcal{E} = \emptyset$, for all $i \in \{a, b\}$, $\delta^\rho_i(M \downharpoonright \Phi) = M \delta^\rho_i(\Phi) \downharpoonright$.

Intuitively, Lemma 5.9 shows that the knowledge deduced by the intruder is the same (up to renaming $\delta^\rho$) in $\Phi$ and $\delta^\rho(\Phi)$ as long as no shared key, public key and verification key are revealed (represented by $\text{img}(\rho)$ and $\text{dom}(\rho)$). From this lemma, we can derive two corollaries:

**Corollary 5.1.** Let $\mathcal{E}$ be a set of names. Let $\Phi$ such that $\nu E. \Phi$ is a derived well-tagged frame in normal form. Let $\rho$ a renaming such that $\text{dom}(\rho) \cup \text{img}(\rho) \subseteq \mathcal{E}$ and $\text{dom}(\rho) \cap \text{frames}(\Phi) = \emptyset$. The two following properties are equivalent:

- for all $k \in \text{img}(\rho) \cup \text{dom}(\rho)$, $\nu E. \delta^\rho(\Phi) \not\vdash k$, $\nu E. \delta^\rho(\Phi) \not\vdash \text{pk}(k)$, $\nu E. \delta^\rho(\Phi) \not\vdash \text{vk}(k)$

- for all $k \in \text{img}(\rho)$, $\nu E. \Phi \not\vdash k$, $\nu E. \Phi \not\vdash \text{pk}(k)$, $\nu E. \Phi \not\vdash \text{vk}(k)$

**Proof.** Assume first that for all $k \in \text{img}(\rho) \cup \text{dom}(\rho)$, $\nu E. \delta^\rho(\Phi) \not\vdash k$, $\nu E. \delta^\rho(\Phi) \not\vdash \text{pk}(k)$, $\nu E. \delta^\rho(\Phi) \not\vdash \text{vk}(k)$. Assume now that there exists $k \in \text{img}(\rho)$ such that $\nu E. \Phi \vdash k$. Hence there exists $M$ such that feesr$(M) \subseteq \text{dom}(\Phi)$, fnames$(M) \cap \mathcal{E} = \emptyset$ and $M \downharpoonright = k$. But by Lemma 5.9 we deduce that $\delta^\rho_i(M \downharpoonright \Phi) = \delta^\rho_i(M \downharpoonright \Phi)$, and so $M \delta^\rho(\Phi) \downharpoonright = \delta^\rho_i(k)$. Hence $\nu E. \delta^\rho(\Phi) \vdash k$ which is a contradiction with our hypothesis. All the other cases are done in a similar way.

Thanks to this result, we will be able to prove that if the shared keys are not revealed in the disjoint case then they will not be revealed in the shared case.
5.3. GOING BACK TO THE DISJOINT CASE

**Corollary 5.2.** Let $E$ be a set of names. Let $\Phi$ such that $\nu E. \Phi$ is a derived well-tagged frame in normal form and let $E$ be a set of names. Let $\rho$ be a renaming such that $\text{dom}(\rho) \cup \text{img}(\rho) \subseteq E$ and $\text{dom}(\rho) \cap \text{frames}(\Phi) = \emptyset$. If for all $k \in \text{img}(\rho)$, $\nu E. \Phi \not\vdash k$, $\nu E. \Phi \not\vdash \nu k(k)$ and $\nu E. \Phi \not\vdash \nu k(k)$, then we have $\nu E. \Phi \sim \nu E. \Phi$.

**Proof.** Let $M_1, M_2$ two term such that $\text{foars}(M_1, M_2) \subseteq \text{dom}(\Phi)$ and $\text{frames}(M_1, M_2) \cap E = \emptyset$. Thanks to Lemma 5.3.1, we have that $M_1 \Phi_1 = M_2 \Phi_2$ is equivalent to $\delta^o(M_1 \Phi_1) = \delta^o(M_2 \Phi_1)$. But thanks to Lemma 5.3.3 this is equivalent to $M_1 \delta^o(\Phi)_1 = M_2 \delta^o(\Phi)_1$. Thus the result holds.

5.3.3.2 Soundness

We now give our soundness lemma which shows that any trace of the “shared case” can be matched by a similar trace in the “disjoint case”.

**Lemma 5.10 (Soundness).** Let $S = (E_S; P_S; \Phi_S)$, $S' = (E'_S; P'_S; \Phi'_S)$ and $D = (E_D; P_D; \Phi_D)$ be three bounded intermediate processes. Assume that $S \xrightarrow{\ell} S'$, $\Phi_S$ is well-tagged and there exists a derived well-tagged multi-set of processes $(P_0, \alpha')$ and a renaming $\rho$, such that

- $\text{dom}(\rho) \cup \text{img}(\rho) \subseteq E_S$, $\text{dom}(\rho) \cap \text{frames}(P_S, \Phi_S) = \emptyset$; and
- $E_S = E_D$, $\Phi_D^\downarrow = \delta^\rho(\Phi_S^\downarrow)$; and
- $P_S = P_0 \alpha$ and $P_D^\downarrow = \delta^\rho(P_0)\delta^\rho(\alpha^\downarrow)$; and
- for all traces $(\text{tr}, \Phi)$ of $D$, for all $k \in \text{img}(\rho) \cup \text{dom}(\rho)$, $\Phi \not\vdash k$, $\Phi \not\vdash \nu k(k)$ and $\Phi \not\vdash \nu k(k)$.

There exists a bounded intermediate process $D' = (E'_D; P'_D; \Phi'_D)$, a derived well-tagged multi-set of processes $(P'_0, \alpha')$ such that $\Phi'_S$ is well-tagged and:

- $E'_S = E_S = E'_D$ and $\Phi'_D^\downarrow = \delta^\rho(\Phi'_S^\downarrow)$; and
- $P'_S^\downarrow = P'_0 \alpha^\downarrow$ and $P'_D^\downarrow = \delta^\rho(P'_0)\delta^\rho(\alpha^\downarrow)$; and
- $D \xrightarrow{\ell} D'$.

5.3.3.3 Completeness

On the other hand, our completeness lemma shows that any trace of the “disjoint case” can be matched by a similar trace in the “shared case”.

**Lemma 5.11 (Completeness).** Let $S = (E_S; P_S; \Phi_S)$, $D = (E_D; P_D; \Phi_D)$ and $D' = (E'_D; P'_D; \Phi'_D)$ and be three bounded intermediate processes. Assume that $D \xrightarrow{\ell} D'$, $\Phi_S$ is a derived well-tagged frame and there exists a derived well-tagged multi-set of processes $(P'_0, \alpha')$ such that $\Phi'_S$ is a derived well-tagged frame and:

- $\text{dom}(\rho) \cup \text{img}(\rho) \subseteq E_S$, $\text{dom}(\rho) \cap \text{frames}(P_S, \Phi_S) = \emptyset$; and
- $E_S = E_D$, $\Phi_D^\downarrow = \delta^\rho(\Phi_S^\downarrow)$; and
- $P_S = P_0 \alpha$ and $P_D^\downarrow = \delta^\rho(P_0)\delta^\rho(\alpha^\downarrow)$; and
- for all traces $(\text{tr}, \Phi)$ of $D$, for all $k \in \text{img}(\rho) \cup \text{dom}(\rho)$, $\Phi \not\vdash k$, $\Phi \not\vdash \nu k(k)$ and $\Phi \not\vdash \nu k(k)$.

There exists a bounded intermediate process $S' = (E'_S; P'_S; \Phi'_S)$, a derived well tagged multi-set of processes $(P'_0, \alpha')$ such that $\Phi'_S$ is a derived well-tagged frame and:

- $E'_S = E_S = E'_D$ and $\Phi'_D^\downarrow = \delta^\rho(\Phi'_S^\downarrow)$; and
- $P'_S^\downarrow = P'_0 \alpha^\downarrow$ and $P'_D^\downarrow = \delta^\rho(P'_0)\delta^\rho(\alpha^\downarrow)$; and
- $S \xrightarrow{\ell} S'$.

The proofs of Lemmas 5.10 and 5.11 can be found in Appendix B.2. Note that in both lemmas, the invariants are the same. $P_0$ represents subprocesses of the original process and $\alpha$ represents the value of the variables restricted by the inputs.
5.3.4 Main result

We conclude this section by the first main result of this chapter:

**Theorem 5.1.** Let $C$ a composition context. Let $P_A$ and $P_B$ two sequences of plain processes built on $F_A \cup F_0$ and $F_B \cup F_0$ respectively. If $C[[P_A]_a]$ and $C[[P_B]_b]$ do not reveal any shared key in $\{k, pk(k), vk(k) \mid k \text{ occurs in } C\}$ then we have that:

$$C[[P_A]_a] \parallel P_B \parallel \equiv C[[P_A]_a] \parallel C[[P_B]_b].$$

**Proof.** Let’s denote $S = (\emptyset; C[[P_A]_a] \parallel [P_B]_b; \emptyset)$ and $D = (\emptyset; C[[P_A]_a] \parallel [P_B]_b; \emptyset)$. We first show that for all $(tr, \nu E, \Phi) \in \text{trace}(S)$, there exists $\nu E', \Phi'$ such that $(tr, \nu E', \Phi') \in \text{trace}(D)$ and $\nu E \parallel \Phi \equiv \nu E', \Phi'$.

Let $(tr, \nu E, \Phi_0) \in \text{trace}(S)$. Thanks to Lemma 5.8, we know that there exist a renaming $\rho$ and two bounded intermediate processes $S' = (E_0; \{P_a, P_b\}; \emptyset)$ and $D' = (E_0; \{P_a, P_b\}^{-1}; \emptyset)$ such that:

1. $\text{dom}(\rho) \cup \text{img}(\rho) \subseteq E_0$ and $\text{dom}(\rho)$ does not appear in $\{P_a, P_b\}$
2. for all $i \in \{a, b\}$, there exists $P_i'$ built on $F_i \cup F_0$ such that $P_i = [P_i']_i$;
3. there exists $\Phi_0$ such that $(tr, \nu E_0, \Phi_0) \in \text{trace}(S')$ and $\nu E_0 \parallel \Phi_0 \equiv \nu E' \parallel \Phi'$
4. for all $(tr', \nu E', \Phi') \in \text{trace}(D')$, there exists $\nu E', \Phi'$ such that $(tr', \nu E', \Phi') \in \text{trace}(D)$ and $\nu E' \parallel \Phi' \equiv \nu E' \parallel \Phi'$.

$(tr, \nu E, \Phi_0) \in \text{trace}(S')$ implies that there exists a bounded intermediate process $S'' = (E_0; P_S; \Phi_0)$ such that $S' \equiv S''$ where $tr = w \times \tau$. Furthermore, we have $P_a = [P_a']_a$ and $P_b = [P_b']_b$, hence $(\{P_a, P_b\}, id)$ is a derived well-tagged multi-set of process. Moreover, since $P_a$ and $P_b$ are coloured with $a$ and $b$ respectively, and $\delta'_a(P_a) \equiv P_a, \delta'_b(P_b) \equiv P_b^{-1}$, we deduce that $(\{P_a, P_b\})_\perp = \delta'(\{P_a, P_b\})_\perp$. At last, by hypothesis we know that $C[[P_A]_a]$ and $C[[P_B]_b]$ do not reveal any shared key in $\{k, pk(k), vk(k) \mid k \text{ occurs in } C\}$ hence it implies that $C[[P_A]_a] \parallel C[[P_B]_b]$ does not reveal any shared key in $\{k, pk(k), vk(k) \mid k \text{ occurs in } C\}$. Thus, we conclude thanks to Lemma 5.8.

We have shown that $S'$ and $D'$ satisfy the conditions of Lemma 5.10 hence using a simple induction on the size of the derivation $S' \equiv S''$ and thanks to Lemma 5.10 we show that there exists a bounded intermediate process $D'' = (E_0; P_D; \Phi_0')$ such that $D' \equiv D''$; $\Phi_0'$ is a derived well-tagged frame and $\Phi_0 \parallel D'' \equiv \delta'((P_a, P_b))_\perp$. But thanks to Corollaries 5.1 and 5.2, we deduce that $\nu E_0, \Phi_0 \equiv \nu E_0, \Phi_0'$.

Since $(tr, \nu E_0, \Phi_0) \in \text{trace}(D')$, then by Lemma 5.8 we also deduce that there exists $\nu E', \Phi'$ such that $(\nu E', \Phi') \in \text{trace}(D)$ and $\nu E' \equiv \nu E_0, \Phi_0$. But we have $\nu E_0, \Phi_0 \equiv \nu E', \Phi'$ and hence we conclude that $\nu E_0, \Phi_0 \equiv \nu E', \Phi'$. Finally, we prove that for all $(tr, \nu E, \Phi) \in \text{trace}(D)$, there exists $\nu E', \Phi'$ such that $(tr, \nu E', \Phi') \in \text{trace}(S)$ and $\nu E \equiv \nu E', \Phi'$.

The proof is symmetrical to the first case except that we apply Lemma 5.11 instead of Lemma 5.10.

5.3.5 A first composition result

From the previous theorem, we can derive our first composition result.

**Corollary 5.3.** Let $C$ and $C'$ be two composition contexts. Let $P_A, P'_A$ (resp. $P_B, P'_B$) be two sequences of plain processes built on the signature $F_A \cup F_0$ (resp. $F_B \cup F_0$). Assume that $C[[P_A]_a]$ and $C[[P_B]_b]$ (resp. $C'[[[P_A]_a], C'[[[P_B]_b]]$) do not reveal any shared key in $\{k, pk(k), vk(k) \mid k \text{ occurs in } C\}$ (resp. $\{k, pk(k), vk(k) \mid k \text{ occurs in } C'\}$). We have that:

$$C[[P_A]_a] \parallel C[[P_B]_b] \equiv C'[[[P_A]_a] \parallel [P_B]_b]$$

$$C[[P_A]_a] \parallel P_B \equiv C'[[[P_A]_a] \parallel [P_B]_b]$$

$$C[[P_A]_a] \parallel [P_B]_b \equiv C'[[[P_A]_a] \parallel [P_B]_b]$$
5.4. MAIN COMPOSITION RESULT

Proof. This composition result is proved in two main steps.

1. We have the equivalences $C[[P_A]_a] \approx_t C'[[[P_A]_a]$ and $C[[P_B]_b] \approx_t C'[[[P_B]_b]$. Thus, thanks to Lemma 5.3, we can show that:
   
   \[ C[[P_A]_a] | C[[P_B]_b] \approx_t C'[[[P_A]_a] | C'[[[P_B]_b]. \]

2. Then, we apply Theorem 5.1 on both sides of the equivalence, and we obtain the expected result:
   
   \[ C[[P_A]_a] | [P_B]_b \approx_t C'[[[P_A]_a] | [P_B]_b. \]

Note that in the hypothesis of Corollary 5.3, the equivalences $C[[P_A]_a] \approx_t C'[[[P_A]_a]$ and $C[[P_B]_b] \approx_t C'[[[P_B]_b]$ holds for the signatures $(F^+ \cup F^+_b \cup F_0, E^+_b \cup E^+_b \cup E_0)$. In fact, one can show that $C[[P_A]_a] \approx_t C'[[[P_A]_a]$ only have to hold on the signature $(F^+_a \cup F_0, E^+_a \cup E_0)$ which is more natural. Indeed, the process $P_A$ and $P'_A$ are only build on $F^+_a \cup F_0$ and the signatures $(F^+_a \cup F_0, E^+_a \cup E_0)$ and $(F^+_b \cup E^+_b)$ are disjoint. Even if [CD12] only shows a result on static equivalence and not trace equivalence, one can adapt their proof technique to show this result.

The main issue with this composition result is the hypothesis that no shared public or verification key can be deduced by the intruder. This lies in opposition to the purpose of the public and verifications that is to be known by anyone.

However, in some cases, it is not unreasonable to assume that some verification or public keys are not deducible by the intruder. For example, coming back to the e-passport protocol (see Section 3.4), we know that each passport has a private signing key $sk_p$ stored in a tamper resistant memory and the associated verification key $vk(sk_p)$ is stored in the data group $dg_{15}$. However, this data group is never send in clear over the network. Typically, in the Passive Authentication protocol, the data groups are encrypted under the symmetric session key $ksenc$ obtained after execution of the Basic Access Control protocol. Hence, the verification of the e-passport will not be deducible by the intruder, provided of course that the intruder did not already know such verification key.

This could model for example an intruder that try to gain informations on some e-passports without any specific target in mind. Although one can assume that an intruder knows the verification keys of few targeted passports, it seems unrealistic to assume that an intruder knows the verification key of all the passports that has been hanged up so far. In such a case, one could apply our first composition result for the unlinkability of the parallel composition of the tagged protocols $AA$ and $PA$.

Indeed, this security property is given by the following equivalence:

\[ \nu_{sk_{DS}}.C'[[[PA]_a | [AA]_b] \approx_t \nu_{sk_{DS}}.C''[[[PA]_a | [AA]_b] \]

where $C''[\_] \eqdef \nu_{sk_p}.vid. vsig. vpic. \ldots vk_{enc}. vksmac. \ldots$ and $C'[\_] \eqdef \nu_{sk_p}. vid. vsig. vpic. \ldots$ Moreover, as mentioned in Example 5.7, the private signing key $sk_{DS}$ is not a shared key since it is only used in the Passive Authentication protocol and so $vk(sk_{DS})$ is allowed to be deducible by the intruder. Hence, it would remain to verify that the session keys $ksenc$, $ksmac$ and the signing key $sk_{DS}$ are not deducible; and of course that the tagged protocols satisfy the unlinkability property in isolation.

5.4 Main composition result

In the previous section, we presented a first composition result. However, this result does not hold as soon as some shared keys are revealed: such a key can be a symmetric shared key, the private part of an asymmetric key pair, but also the public part of an asymmetric key pair. In this section, we will see that we can relax this condition by allowing shared public or verification keys to be revealed from the beginning.
5.4.1 Some additional difficulties

First, as shown by the example below, we do not want public keys to be revealed (for the first time) during the execution of the protocol.

**Example 5.17.** We consider a slightly different version of the process $P_1$ introduced in Example 5.4.1. Basically, we remove the random $r$ inside the encryption and we consider its well-tagged version. We consider the following processes:

$$[P'_1]_a \equiv \text{out}(c, \text{aenc}(\text{tag}_a(id_1), \text{pk}(sk_S))) \quad i \in \{1, 2\}$$

Consider the composition context $C[\_] = \nu sk_S\_$. Note that, the equivalence $C[[P'_1]_a] \approx_i C[[P'_2]_a]$ still holds in this setting. Assume now that $[P'_1]_a$ is executed in presence of the well-tagged process $Q^{pk} = \text{out}(c, \text{pk}(sk_S))$. Clearly, the equivalence expressing the anonymity of $[P'_1]_a$ does not hold anymore. We have that:

$$C[[P'_1]_a | Q^{pk}] \not\approx_i C[[P'_2]_a | Q^{pk}]$$

Actually, the knowledge of $\text{pk}(sk_S)$ will allow the attacker to distinguish the message emitted by $[P'_1]_a$ from the one emitted by $[P'_2]_a$ by rebuilding the message $\text{aenc}(\text{tag}_a(id_1), \text{pk}(sk_S))$ since $id_1$ is public, and comparing it to the message outputted by $P'_1$ and $P'_2$.

To avoid the problem mentioned above, we will assume that shared keys that are revealed have to be revealed from the very beginning. This hypothesis seems indeed reasonable since the purpose of a public key is in general to be disclosed at the beginning, or eventually never revealed to an outsider.

Note that the previous example is not a counter-example anymore if we analyse the equivalence expressing the anonymity of $[P'_1]_a$ assuming that $\text{pk}(sk_S)$ is known by the attacker from the beginning. The fact that $\text{pk}(sk_S)$ is revealed during the execution of $Q^{pk}$ will not give any additional power to the attacker. However, the resulting equivalence still does not hold but essentially because the equivalence expressing the anonymity of $P^{pk}$ (without the presence of $Q$) does not hold anymore in this setting.

**Example 5.18.** We consider again the process $P_1$ as presented in Example 5.4.1 with an additional output to reveal the public key $\text{pk}(sk_S)$ at the very beginning. Basically, we consider the well-tagged process $P''_i \equiv \text{out}(c, \text{pk}(sk_S)) \cdot [P_1]_a$.

We have that $C[P''_1] \approx_i C[P''_2]$ with $C[\_] = \nu sk_S\_$. Now, the presence of $Q^{pk}$ will not prevent this equivalence to hold. Indeed, we have that:

$$C[P''_1 | Q^{pk}] \approx C[P''_2 | Q^{pk}]$$

This hypothesis that states that shared keys are either known from the beginning or never revealed during the execution of the protocol is reasonable, and seems to be sufficient to establish a composition result. However, this complicates a bit the setting. In particular, as illustrated in Example 5.4.19 there is no hope to obtain a result as the one stated in Theorem 5.4.1 The situation where the processes share some keys is not equivalent in this setting to the situation where the processes do not share any key.

**Example 5.19.** Consider the processes $P''_i$ and $Q^{pk}$ used in Example 5.4.18. We have seen that composition works under the composition context $C = \nu sk_S\_$. However, we have that $(i \in \{1, 2\})$:

$$C[P''_i | Q^{pk}] \not\approx_i C[P''_i] | C[Q^{pk}]$$

Indeed, on the left-hand side, the same public-key will be output twice whereas the process on the right-hand side will emit two different public keys. The attacker will observe such a difference. The strong result stated in Theorem 5.4.1 allowing us to easily make the link between the joint state case and the disjoint case does not hold anymore.
The problems encountered for composing processes that reveal shared keys are due to the fact that we do not want to tag the function symbols pk and vk that are used to model asymmetric keys: such a tagging scheme would lead us to an unrealistic modelling of asymmetric keys.

5.4. MAIN COMPOSITION RESULT

We now consider public keys and verifications keys that can be made public from the beginning through an initial frame $\Phi_0$ that will represent the initial knowledge of the attacker. As illustrated in Subsection 5.4.1, we cannot rely on Theorem 5.1 anymore to establish our composition result. We will still go back to the disjoint case but we have to explain how a trace corresponding to the situation where processes share some keys is transformed and mapped to a trace that models the disjoint case. We cannot simply consider the identity transformation as it was done to establish the previous result. The sets of traces issued from both situations are not the same anymore.

Consider the initial frame $\Phi_0 = \{ax_1 \triangleright f_1(k_1), \ldots, ax_n \triangleright f_n(k_n)\}$ and initial set of private names $K_0$ such that for all $i \in \{1, \ldots, n\}$, $f_i \in \{pk, vk\}$ and $k_i \in K_0$. Consider $K_0'$ the subset of $K_0$ that regroups all shared keys of $K_0$ between $P_A, P_B, P'_A$ and $P'_B$. The result we want to show in this section is similar to Corollary 5.3, i.e.

$(K_0; C[[P_A]]_a; \Phi_0) \approx_t (K_0; C'[[[P'_A]]_a]; \Phi_0)$

$(K_0; C[[P_B]]_b; \Phi_0) \approx_t (K_0; C'[[[P'_B]]_b]; \Phi_0)$

$(K_0; C[[P_A]]_a | [P_B]]_b; \Phi_0) \approx_t (K_0; C'[[[P'_A]]_a | [P'_B]]_b; \Phi_0)$

Of course, as Corollary 5.3 we impose some additional conditions on our processes. The most important one is that $(K_0; C[[P_A]]_a; \Phi_0)$ and $(K_0; C[[P_B]]_b; \Phi_0)$ (resp. $(K_0; C'[[[P'_A]]_a]; \Phi_0)$, and $(K_0; C'[[[P'_B]]_b]; \Phi_0)$) do not reveal any key in $\{k, pk(k), vk(k) | k \in K_0\}$ unless the key occurs explicitly in $\Phi_0$ and do not reveal any shared key in $\{k, pk(k), vk(k) | k \in C\}$ (resp. $C'$).

The first step to prove the result is similar to the proof of Corollary 5.3, i.e. we will rely on the fact that the trace equivalence is closed under disjoint parallel composition. Moreover, we rename the restricted names in order to avoid clashes between the two sets of restricted names (possible since the trace equivalence is closed under renaming of restricted names). Hence if we denote $\rho_0$ a renaming on names such that dom($\rho_0$) are fresh names and img($\rho_0$) = $K_0'$, the “disjoint case” would be represented by the following equivalence:

$(K; C[[P_A]]_a | C[[P_B]]_b; \Phi_0) \approx_t (K; C[[P_A]]_a | C[[P_B]]_b; \Phi_0')$

where $K = K_0 \cup K_0'$ and $\Phi_0' = \Phi_0 \oplus \Phi_0^{-1}$.

Note that in $\Phi_0 \oplus \Phi_0^{-1}$, the parameters of $\Phi_0^{-1}$ should be renamed so that the parameters of $\Phi_0'$ constitute a sequence. However, to facilitate the comprehension, we will denote $\Phi_a = \{ax_1' \triangleright f_1(k_1), \ldots, ax_n' \triangleright f_n(k_n)\}$ and $\Phi_b = \{ax_1'' \triangleright f_1(k_1), \ldots, ax_n'' \triangleright f_n(k_n)\}$ where $\Phi_a$ (resp. $\Phi_b$) represents the initial frame of $C[P_A]$ and $C[P'_A]$ (resp. $C[P_B]$ and $C[P'_B]$). Hence, we have $\Phi_0' = \Phi_a \oplus \Phi_b \rho_0^{-1}$.

The main problem with this equivalence is that given a trace of $(K; C[[P_A]]_a; \Phi_0')$, we have no guarantee that the actions in the trace which are due to the process $C([[P_A]]_a)$ (resp. $C([[P_B]]_b; \rho_0^{-1}$), would be matched with some actions on the process $C[[P_A]]_a$ (resp. $C[[P_B]]_b; \rho_0^{-1}$). To solve this issue, we will rely on the fact that the trace equivalence is also closed under renaming of public names. Indeed, if we denote $\rho_{ch_a}$ a renaming of channel names such that dom($\rho_{ch_a}$) = $\text{fchannels}(P_A, P'_A) \cap \text{Ch}$ and img($\rho_{ch_a}$) are fresh channel names, we have that $(K_0; C[[P_A]]_a; \Phi_a) \approx_t (K_0; C'[[[P'_A]]_a]; \Phi_a)$ implies $(K_0; C[[P_A]]_a; \rho_{ch_a}; \Phi_a) \approx_t (K_0; C'[[[P'_A]]_a]; \rho_{ch_a}; \Phi_a)$.

If we denote $\rho_{ch_b}$ a fresh renaming of public channel names of $P_B$ and $P'_B$, the “disjoint case” will in fact be represented by the following equivalence:

$(K; C[[P_A]]_a; \rho_{ch_a}) | C[[P_B]]_b; \rho_0^{-1} ; \rho_{ch_b}; \Phi_0) \approx_t (K; C[[P_A]]_a; \rho_{ch_a}) | C[[P_B]]_b; \rho_0^{-1} ; \rho_{ch_b}; \Phi_0)$
where $\mathcal{K} = \mathcal{K}_0 \cup \mathcal{K}_0^{-1}$ and $\Phi'_0 = \Phi_a \cup \Phi_b \rho_0^{-1}$. With such equivalence, an action labeled for example $in(c, M)$ with $c \in \text{img}(\rho_{ch_0})$ would automatically be matched by some input in $\overline{T_A}$ or $\overline{T_A}^{-1}$.

From here, the proof of our main result will be similar to Section 5.3. Typically, given a trace $(tr, \Phi)$ of $(\mathcal{K}_0; C[\overline{T_A}]_0 \mid \overline{T_B}; \Phi_0)$, we will start by unfolding the process according the given trace (see Lemma 5.12). Then using a soundness lemma (see Lemma 5.14), we will show that this trace can be matched to a similar trace $(tr', \Phi')$ in the disjoint case, i.e. $(\mathcal{K}; C[\overline{T_A}]_0 \rho_{ch_0} \mid C[\overline{T_B}]_0 \rho_0^{-1} \rho_{ch_0}; \Phi'_0)$. Thanks to the equivalence representing the “disjoint case”, we will find a matching trace $(tr', \Phi'')$ in $(\mathcal{K}; C[\overline{T_A}]_0 \rho_{ch_0} \mid C[\overline{T_B}]_0 \rho_0^{-1} \rho_{ch_0}; \Phi'_0)$. At last, using our completeness lemma (see Lemma 5.15), we will show that we can derive from $(tr', \Phi'')$ a trace $(tr, \Phi''')$ of $(\mathcal{K}; C[\overline{T_A}]_0 \mid \overline{T_B}; \Phi_0)$ such that the frames $\Phi'''$ and $\Phi$ are statically equivalent.

We first state the lemma that unfolds the processes according to a specific trace.

**Lemma 5.12.** Let $C$ be a composition context. Let $\overline{T_A}$ (resp. $\overline{T_B}$) be a sequence of plain processes built on $\mathcal{F}_a \cup \mathcal{F}_0$ (resp. $\mathcal{F}_b \cup \mathcal{F}_0$) such that $\text{fnames}(\overline{T_A}) \cap \text{Ch} \subseteq \text{dom}(\rho_{ch_0})$ and $\text{fnames}(\overline{T_B}) \cap \text{Ch} \subseteq \text{dom}(\rho_{ch_0})$. Furthermore, we assume that $\text{dom}(\rho_0), \text{img}(\rho_{ch_0})$ and $\text{img}(\rho_{ch_0})$ do not occur in $C$, $\overline{T_A}$ and $\overline{T_B}$. At last, we assume that the shared private names between $\overline{T_A}$ and $\overline{T_B}$ are included in $\text{img}(\rho_0)$, i.e. $\mathcal{K}_0 \cap \text{names}(\overline{T_A}) \cap \text{names}(\overline{T_B}) \subseteq \text{img}(\rho_0)$.

Let $D = (\mathcal{K}_0 \cup \mathcal{K}_0^{-1}; C[\overline{T_A}]_0 \rho_{ch_0} \mid C[\overline{T_B}]_0 \rho_0^{-1} \rho_{ch_0}; \Phi_a \cup \Phi_b \rho_0^{-1})$ and $S = (\mathcal{K}_0; C[\overline{T_A}]_0 \mid \overline{T_B}; \Phi_0)$, we have that for all $(tr, v\varepsilon; \Phi) \in \text{trace}(D)$ (resp. $(tr, v\varepsilon; \Phi) \in \text{trace}(S)$), there exists a renaming $\rho$ and two bounded intermediate processes $S' = (\mathcal{E}_0; \{P_a, P_b\}; \Phi_0 \cup \Phi_b)$ and $D' = (\mathcal{E}_0; \{P_a \rho_{ch_0}, P_b \rho_0^{-1} \rho_{ch_0}\}; \Phi_a \cup \Phi_b \rho_0^{-1})$ such that

1. $\rho_{\text{dom}(\rho_0)} = \rho_0$, $\text{dom}(\rho) \cup \text{img}(\rho) \subseteq \mathcal{E}_0$ and $\text{dom}(\rho)$ does not appear in $\{P_a, P_b\}$
2. for all $i \in \{a, b\}$, there exists $P_i'$ built on $\mathcal{F}_i \cup \mathcal{F}_0$ such that $S_i = [P_i']$
3. there exists $\Phi'$ such that $(tr, v\varepsilon_0, \Phi') \in \text{trace}(D')$ (resp. $\text{trace}(S')$) and $v\varepsilon_0, \Phi' \sim v\varepsilon_0, \Phi''$
4. for all $(tr', v\varepsilon_0, \Phi'') \in \text{trace}(S')$ (resp $\text{trace}(D')$), there exists $v\varepsilon', \Phi'$ such that $(v\varepsilon', \Phi') \in \text{trace}(S)$ (resp $\text{trace}(D)$) and $v\varepsilon', \Phi' \sim v\varepsilon_0, \Phi''$

Note that $\delta'_0(P_a) = P_a, \delta'_0(P_b) = P_b \rho_0^{-1}, \delta'_0(\Phi_a) = \Phi_a$ and $\delta'_0(\Phi_b) = \Phi_b \rho_0^{-1}$.

**Proof.** The proof is very similar to the proof of Lemma 5.3. Assume w.l.o.g that $(tr, v\varepsilon; \Phi) \in \text{trace}(S)$. Hence, we have that $S \xrightarrow{w} (\mathcal{E}; \mathcal{P}; \Phi)$ for some $\mathcal{P}$. Thus, there exists a word $w$ such that $S \xrightarrow{w} (\mathcal{E}; \mathcal{P}; \Phi)$ where $tr = w \wedge \tau$. Let $N$ be the number of $\tau$ action corresponding to the application of the rule $\text{Repl}_\tau$.

Let $C'$ be the composition context without replication, $\overline{T_A}$ and $\overline{T_B}$ the sequences of plain process without replication such that $C[\overline{T_A}]_0 \mid \overline{T_B}$ corresponds to $C[\overline{T_A}]_0 \mid \overline{T_B}$ where we replaced every instance $\mathcal{P}B$ by $P_1 \mid \ldots \mid P_N$ for some where $P_i$ is a renaming of $P_i$.

Let $P_i$ be the plain process $C'[\overline{T_A}]_0$ where we removed all name restriction and let $P_i$ be the plain process $C'[\overline{T_B}]_0$ where we removed all name restriction. At last, let $\rho$ be a renaming such that $\rho_{\text{dom}(\rho_0)} = \rho_0$, $\text{dom}(\rho) \cap \text{dom}(\rho_0)$ are fresh names and $\text{img}(\rho_0) = (\text{fnames}(C') \cap \text{fnames}(\overline{T_A}) \cap \text{fnames}(\overline{T_B})) \cup \text{img}(\rho_0)$. At last, let $E_0 = \mathcal{K}_0 \cup \text{bnames}(C') \cup \text{bnames}(\overline{T_A}) \cup \text{bnames}(\overline{T_B}) \cup \text{dom}(\rho)$. We have that $S'$ is a bounded intermediate process associated to $(\mathcal{K}_0; C[\overline{T_A}]_0 \mid \overline{T_B}; \Phi_a \cup \Phi_b \rho_0^{-1})$.

Furthermore, we know that $\text{names}(\Phi_0) \subseteq \mathcal{K}_0$. Hence we have that $\Phi_b \rho_0^{-1} = \Phi_b \rho_0^{-1}$. Moreover, since $\text{dom}(\rho) \cap \text{dom}(\rho_0)$ is composed of fresh names and $\text{dom}(\rho_0)$ do not occur in $C$, $\overline{T_A}$ and $\overline{T_B}$, then $\text{dom}(\rho)$ do not occur in $C'$, $\overline{T_A}$ and $\overline{T_B}$. Hence $P \rho_0^{-1}$ is a renaming of $C'[\overline{T_B}]_0$ and so $(\mathcal{E}_0; \{P_a, P_b \rho_0^{-1}\}; \Phi_a \cup \Phi_b \rho_0^{-1})$ is a bounded intermediate process associated to $(\mathcal{K}_0 \cup \mathcal{K}_0^{-1}; C'[\overline{T_A}]_0 \mid C'[\overline{T_B}]_0), \Phi_a \cup \Phi_b \rho_0^{-1})$. But $P \rho_0^{-1}$ and $P \rho_0$ are both renaming on public channel and $\text{img}(\rho_{ch_0})$, $\text{img}(\rho_{ch_0})$ do not occur in $C'$, $\overline{T_A}$ and $\overline{T_B}$. Hence, we deduce that $D' = (\mathcal{E}_0; \{P_a \rho_{ch_0}, P_b \rho_0^{-1} \rho_{ch_0}\}; \Phi_a \cup \Phi_b \rho_0^{-1})$ is a bounded intermediate process associated to $D$. We conclude by applying Lemma 5.7.
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5.4.3 Static equivalence

We will assume, as in Section 5.3, that processes and frames are coloured by \(a\) or \(b\). Furthermore assume that \(\Phi_a\) (resp. \(\Phi_b\)) is coloured by \(a\) (resp. \(b\)).

In Section 5.3.3.1 we gave a lemma which stated that given a well-tagged frame \(\Phi\), and a recipe \(M\) of the intruder, \(\delta^\rho(M\Phi_i) = M\delta^\rho(\Phi)\Phi_i\) for all \(i \in \{a, b\}\), provided that the frame did not reveal any shared key including the public and verification key. This is not true anymore when some public or verification key are revealed.

**Example 5.20.** Consider the initial frame \(\Phi = \Phi_a \uplus \Phi_b\). We have \(\delta^\rho(\Phi_a \uplus \Phi_b) = \Phi_a \uplus \Phi_b \rho^{-1}\). More specifically, \(ax^2_\Phi = ax^2_\Phi \Phi = f(k)\) for some \(f \in \{pk, vk\}\) and \(k \in \text{img}(\rho)\). While we still have \(\delta^\rho(ax^2_\Phi \Phi) = \delta^\rho(ax^2_\Phi \Phi)\Phi = ax^2_\Phi \delta^\rho(\Phi)\Phi\), we have on the other hand:

- \(\delta^\rho(ax^2_\Phi \Phi) = \delta^\rho(f(k)) = f(k)\rho^{-1}\) and \(ax^2_\Phi \delta^\rho(\Phi)\Phi = f(k)\).
- \(\delta^\rho(ax^2_\Phi \Phi) = \delta^\rho(f(k)) = f(k)\) and \(ax^2_\Phi \delta^\rho(\Phi)\Phi = f(k)\rho^{-1}\).

This counter example given in Example 5.20 is very simple but the main idea is that the application of \(\delta^\rho\) on a frame \(\Phi\) depends on how the frame is coloured. Hence, if a public key or verification key is accessible on a frame element of \(\Phi\), the application of \(\delta^\rho\) and \(\delta^\rho\) on this frame element will not produce the same result since the public key and verification keys are not tagged.

**Example 5.21.** Consider \(E = \{k_1, k_2, k'_1, k'_2\}\) and the renaming \(\rho = \{k'_1 \mapsto k_1, k'_2 \mapsto k_2\}\). Consider the frame \(\Phi = \Phi_a \uplus \Phi_b \uplus \{ax_5 \triangleright (pk(k_1), id_1), ax_6 \triangleright (id_2, pk(k_2))\}\) where \(\Phi_a = \{ax^1_1 \triangleright pk(k_1), ax^2_1 \triangleright pk(k_2)\}\) and \(\Phi_b = \{ax^1_2 \triangleright pk(k_1), ax^2_2 \triangleright pk(k_2)\}\). At last, assume that \(ax_5\) is coloured by \(a\) and \(ax_6\) is coloured by \(b\). Let \(M = \langle ax_5, ax_6 \rangle\). We have that

- \(M\Phi_1 = \langle (pk(k_1), id_1), (id_2, pk(k_2)) \rangle\);
- \(\delta^\rho(M\Phi_1) = M\Phi_1\);
- \(\delta^\rho(M\Phi_1) = \langle (pk(k_1), id_1), (id_2, pk(k_2)) \rangle\);
- \(\delta^\rho(\Phi) = \Phi_a \uplus \Phi_b \rho^{-1} \uplus \{ax_5 \triangleright pk(k_1), id_1, ax_6 \triangleright (id_2, pk(k_2))\}\)

While \(M\delta^\rho(\Phi)\Phi\) is not equal to both \(\delta^\rho(M\Phi_1)\) and \(\delta^\rho(M\Phi_1)\), we can still find new recipes that will link the results.

The idea is to extract from the recipe \(M\) the part that use the public key revealed (i.e. contained in \(\Phi_a\) and \(\Phi_b\)) and use the corresponding recipe of \(\Phi_a\) or \(\Phi_b\) depending on which \(\delta^\rho\) we have to apply. Indeed, note that \(ax_5\Phi_1 = \langle ax^1_1, \text{proj}_2(ax_5) \rangle\Phi_1\). Similarly, we have \(ax_6\Phi_1 = \langle \text{proj}_1(ax_6), ax^2_2 \rangle\Phi_1\).

Consider the recipes \(M_a = \langle ax_5, \langle \text{proj}_1(ax_5), ax^2_2 \rangle \rangle \) and \(M_a = \langle ax^1_1, \text{proj}_2(ax_5) \rangle\)

- \(M_a\delta^\rho(\Phi_1) = \langle (pk(k_1), id_1), (id_2, pk(k_2)) \rangle\)
- \(M_a\delta^\rho(\Phi_1) = \langle (pk(k_1), id_1), (id_2, pk(k_2)) \rangle\)

Following Example 5.21 we are now able to show the following result (Proof in Appendix 5.5.3):

**Lemma 5.13.** Let \(\Phi\) and \(\Phi'\) two frames in normal form such that \(\text{dom}(\Phi) = \text{dom}(\Phi')\). Assume that \(\Phi\) and \(\Phi'\) have the same colors, i.e. for all \((ax \triangleright u) \in \Phi\), for all \((ax' \triangleright u') \in \Phi'\), \(ax = ax'\) implies \(\text{col}(ax \triangleright u) = \text{col}(ax' \triangleright u')\).

Let \(E\) be a set of names and let \(\rho\) a renaming such that \(\text{dom}(\rho) \cup \text{img}(\rho) \subseteq E\) and \(\text{dom}(\rho) \cap \\text{names}(\Phi, \Phi') = \emptyset\). Let’s denote \(\Phi_+ = \Phi_a \uplus \Phi_b \uplus \Phi\) and \(\Phi'_+ = \Phi_a \uplus \Phi_b \uplus \Phi'\).

If the following properties are satisfied:

- \(\nu E.\Phi_+\), \(\nu E.\Phi'_+\) are well-tagged
- \(\nu E.\delta^\rho(\Phi_+) \sim \nu E.\delta^\rho(\Phi'_+)\)
- for all \(u \in \{k, pk(k), vk(k) \mid k \in \text{img}(\rho) \cup \text{dom}(\rho)\}\), \(\nu E.\delta^\rho(\Phi_+) \triangleright u\) or \(\nu E.\delta^\rho(\Phi'_+) \triangleright u\) implies that \(u \in \text{img}(\delta^\rho(\Phi_a \uplus \Phi_b))\)
then for all $M$ such that $\text{fnames}(M) \cap E = \emptyset$ and $\text{fears}(M) \subseteq \text{dom}(\Phi_+)$, there exists $M_a$ and $M_b$ such that $\text{fnames}(M_a, M_b) \cap E = \emptyset$, $\text{fears}(M_a, M_b) \subseteq \text{dom}(\Phi_+)$ and:

1. $\delta_0^a(M\Phi_+\downarrow) = M_a\delta^p(\Phi_+)_\downarrow$ and $\delta_0^a(M\Phi'_+\downarrow) = M_a\delta^p(\Phi'_+)_\downarrow$
2. $\delta_0^b(M\Phi_+\downarrow) = M_b\delta^p(\Phi_+)_\downarrow$ and $\delta_0^b(M\Phi'_+\downarrow) = M_b\delta^p(\Phi'_+)_\downarrow$

Similarly to Lemma 5.10, Lemma 5.13 induces a corollary that will help us prove the static equivalence between traces in the shared case.

**Corollary 5.4.** Let $\Phi$ and $\Phi'$ two frames in normal form such that $\text{dom}(\Phi) = \text{dom}(\Phi')$. Assume that $\Phi$ and $\Phi'$ have the same colors. Let $E$ be a set of names and let $\rho$ a renaming such that $\text{dom}(\rho) \cup \text{img}(\rho) \subseteq E$, $\text{dom}(\rho) \cap \text{fnames}(\Phi, \Phi') = \emptyset$ and $\rho_{\text{dom}(\rho)} = \rho_0$. Let's denote $\Phi_+ = \Phi_a \uplus \Phi_b \uplus \Phi$ and $\Phi'_+ = \Phi_a \uplus \Phi_b \uplus \Phi'$.

If the following properties are satisfied:

- $\nu E. \Phi_+ \, \nu E. \Phi'_+$ are well-tagged,
- $\nu E. \delta^p(\Phi_+) \sim \nu E. \delta^p(\Phi'_+)$,
- for all $u \in \{ k, pk(k_i) \mid k \in \text{img}(\rho) \cup \text{dom}(\rho) \}$, $\nu E. \delta^p(\Phi_+) \vdash u$ or $\nu E. \delta^p(\Phi'_+) \vdash u$ imply that $u \in \text{fnames}(\delta^p(\Phi_a \uplus \Phi_b))$

then $\nu E. \Phi_+ \sim \nu E. \Phi'_+$.

**Proof.** Let $M, N$ such that $\text{fnames}(M, N) \cap E = \emptyset$ and $\text{fears}(M, N) \subseteq \text{dom}(\Phi_+)$. Assume that $M\Phi_+\downarrow = N\Phi_+\downarrow$. Thanks to Lemma 5.4, we know that $M\Phi_+\downarrow = N\Phi_+\downarrow$ is equivalent to $\delta_0^a(M\Phi_+\downarrow) = \delta_0^a(N\Phi_+\downarrow)$. But thanks to Lemma 5.13 we know that there exists two recipe $M_a$ and $N_a$ such that:

- $\delta_0^a(M\Phi_+\downarrow) = M_a\delta^p(\Phi_+)_\downarrow$ and $\delta_0^a(M\Phi'_+\downarrow) = M_a\delta^p(\Phi'_+)_\downarrow$
- $\delta_0^b(N\Phi_+\downarrow) = N_a\delta^p(\Phi_+)_\downarrow$ and $\delta_0^b(N\Phi'_+\downarrow) = N_a\delta^p(\Phi'_+)_\downarrow$

Hence we have $\delta_0^a(M\Phi_+\downarrow) = \delta_0^a(N\Phi_+\downarrow)$ is equivalent to $M_a\delta^p(\Phi_+)_\downarrow = N_a\delta^p(\Phi_+)_\downarrow$. By hypothesis, we know that $\nu E. \delta^p(\Phi_+) \sim \nu E. \delta^p(\Phi'_+)$, hence $M_a\delta^p(\Phi_+)_\downarrow = N_a\delta^p(\Phi_+)_\downarrow$ is equivalent to $M_a\delta^p(\Phi'_+)_\downarrow = N_a\delta^p(\Phi'_+)_\downarrow$. Therefore we deduce that it is also equivalent to $\delta_0^a(M\Phi'_+\downarrow) = \delta_0^a(N\Phi'_+\downarrow)$. At last, once again thanks to Lemma 5.4, we have that $\delta_0^a(M\Phi'_+\downarrow) = \delta_0^a(N\Phi'_+\downarrow)$ is equivalent to $M\Phi'_+\downarrow = N\Phi'_+\downarrow$ and so we conclude that $M\Phi_+\downarrow = N\Phi_+\downarrow$ is equivalent to $M\Phi'_+\downarrow = N\Phi'_+\downarrow$.  

### 5.4.4 Soundness and completeness

For this subsection, we consider $E_0$ a set of private names and $P_a$, $P_b$ two processes without name restriction or replication, and coloured respectively by $a$ and $b$. At last consider $\rho$ a renaming such that:

- $\text{dom}(\rho) \cup \text{img}(\rho) \subseteq E_0$ and $\text{dom}(\rho)$ does not appear in $P_a$, $P_b$, $\Phi_a$ or $\Phi_b$.
- for all $i \in \{ a, b \}$, there exists $P_i'$ built on $F_i \cup F_0$ such that $P_i = [P_i']_{\rho_i}$.
- for all $i \in \{ a, b \}$, $\text{fnames}(P_i) \cap C \subseteq \text{dom}(\rho C_{\rho_i})$ and $\text{img}(\rho C_{\rho_i})$ does not appear in $P_a$ or $P_b$.

We will denote $D = (E_0; \{ P_a \rho_{P_a}; P_b \rho_{P_b}; \Phi_a \uplus \Phi_b \rho_{P_a}^{-1} \})$ and $S = (E_0; \{ P_a, P_b; \Phi_a \uplus \Phi_b \})$. We assume that $P_a$ and $P_b$ do not share any private channel name, i.e. $\text{fnames}(P_a) \cap \text{fnames}(P_b) \cap C \cap E_0 = \emptyset$, and do not use variable of channel type.

For our soundness and completeness, we want to preserve a similar invariant as Lemmas 5.10 and 5.11. Typically, for a derivation $D \rightarrow^* (E_0; P_D; \Phi_D)$, we want to match it in the shared case to a derivation $S \rightarrow^* (E_0; P_S; \Phi_S)$ where $P_D\downarrow = \delta^p(\Phi_S)_\downarrow$, $P_S = P_0\alpha$ and $P_D\downarrow = \delta^p(P_0)\delta^p(\alpha\downarrow)_\downarrow$, for some original well-tagged multi-set of processes $(P_0, \alpha)$. 

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However, contrary to Lemmas 5.10 and 5.11, we can’t use the same sequence of actions \( \sigma \). Typically, it is due to the fact that, as we saw in Subsection 5.3.3, given a process \( M \) and a frame \( \Phi \) that may reveal some verification or public keys, we may have \( \delta^\rho(M\downarrow) \neq \delta^\rho(M\downarrow) \). Hence the main idea is to transform the sequence of labels \( \sigma \) using Lemma 5.13.

Example 5.22. Coming back to Example 5.21, consider the process \( P_a = \text{out}(c, (\langle \text{pk}(k_1), id_1 \rangle)) \) and \( P_b = \text{out}(c, (id_2, \text{pk}(k_2))) \).\( \text{in}(c, x).\text{out}(c, a_{\text{enc}}(\text{tag}(x), \text{pk}(k_1))) \). Furthermore, the consider the set \( E_0 = \{k_1, k_2, k_3\} \), \( \rho = \{k_1 \mapsto k_1, k_2 \mapsto k_2\} \), \( \rho_{\text{ch}} = \{c \mapsto c_a\} \) and \( \rho_{\text{ch}} = \{c \mapsto c_b\} \). At last consider the frames \( \Phi_a = \{ax_3^a \triangleright \text{pk}(k_1), ax_3^b \triangleright \text{pk}(k_2)\} \) and \( \Phi_b = \{ax_3^a \triangleright \text{pk}(k_1), ax_3^b \triangleright \text{pk}(k_2)\} \) coloured respectively with \( a \) and \( b \). We denote \( \Phi_0 = \Phi_a \uplus \Phi_b \).

Let’s denote \( S = (E_0; P_a, P_b) \) and \( D = (E_0; P_a, \rho_{\text{ch}} = \rho_{\text{ch}};\{c \mapsto \rho_{\text{ch}}\}; \Phi_0 \uplus \Phi_b \).

We have:

\[
S \xrightarrow{\nu_{ax_5, \text{out}(c, ax_5)}} (E_0; \{P_b\}; \Phi_0 \uplus \{ax_5 \triangleright (\text{pk}(k_1), id_1)\})
\]

\[
S \xrightarrow{\nu_{ax_6, \text{out}(c, ax_6)}} (E_0; \{P_b\}; \Phi_0 \uplus \{ax_5 \triangleright (\text{pk}(k_1), id_1), ax_6 \triangleright (id_2, \text{pk}(k_2))\})
\]

\[
S \xrightarrow{\text{in}(c, M)} (E_0; \{P_b\}; \Phi_0 \uplus \{ax_5 \triangleright (\text{pk}(k_1), id_1), ax_6 \triangleright (id_2, \text{pk}(k_2))\})
\]

where \( M = \langle ax_3^a, ax_3^b \rangle, u = \text{aenc}(\text{tag}(x), \text{pk}(k_1)) \) and \( P_0' = \text{out}(c, \text{aenc}(\text{tag}(x), \text{pk}(k_1))) \), \( P_0'' = \text{out}(c, u) \) with \( v = \langle (id_2, \text{pk}(k_2)) \rangle \).

In Example 5.21 we showed that \( M_0, \delta^\rho(M) \) is the process coloured by \( b \) which \( M_0 = \langle (ax_3^a, \text{proj}_2(ax_3^a)), ax_6^b \rangle \) and \( \Phi = \Phi_0 \uplus \{ax_5 \triangleright (\text{pk}(k_1), id_1), ax_6 \triangleright (id_2, \text{pk}(k_2))\} \). Since the input corresponding to the label \( \text{in}(c, M) \) corresponds to a process coloured by \( b \), we will replace \( M \) by \( M_0 \) in the sequence of action. Similarly, the output corresponding to \( \nu_{ax_5, \text{out}(c, ax_5)} \) corresponds to a process coloured by \( a \), hence we will replace \( c \) by \( c_{\text{ch}} = c_a \).

Thus:

\[
D \xrightarrow{\nu_{ax_5, \text{out}(c, ax_5)}} (E_0; \delta^\rho_0(P_{\text{ch}}) \cup \{ax_5 \triangleright (\text{pk}(k_1), id_1)\})
\]

\[
D \xrightarrow{\nu_{ax_6, \text{out}(c, ax_6)}} (E_0; \{P_b\}; \Phi_0 \uplus \{ax_5 \triangleright (\text{pk}(k_1), id_1), ax_6 \triangleright (id_2, \text{pk}(k_2))\})
\]

\[
D \xrightarrow{\text{in}(c, M)} (E_0; \{P_b\}; \Phi_0 \uplus \{ax_5 \triangleright (\text{pk}(k_1), id_1), ax_6 \triangleright (id_2, \text{pk}(k_2))\})
\]

where \( u' = \text{aenc}(\text{tag}(x'), \text{pk}(k_1)) \) with \( v' = \langle (\text{pk}(k_1'), \text{proj}_2(\text{pk}(k_1)), id_1), (id_2, \text{pk}(k_2)) \rangle \).

Note that \( \delta^\rho_0(P_{\text{ch}}) \cup \{ax_5 \triangleright (\text{pk}(k_1), id_1), ax_6 \triangleright (id_2, \text{pk}(k_2))\} \) and \( \delta^\rho_0(u') \).

Moreover, note that \( u' = \langle (\text{pk}(k_1'), id_1), (id_2, \text{pk}(k_2)) \rangle \) and \( \delta^\rho_0(u') = u' \).

More generally, if we denote by \( \Phi_S \) and \( \Phi_D \) the last two frames of the derivations, we have \( \delta^\rho(\Phi_S) = \Phi_D \).

We formalise the transformation of sequence of labels (see Example 5.22) in the following lemmas (proofs in Appendix 3.3).

Lemma 5.14 (Soundness). If for all \( (t, \Phi) \in \text{trace}(D) \), for all \( u \in \{\text{vk}(k), \text{pk}(k) \mid k \in \text{img}(\rho) \cup \text{dom}(\rho)\} \), \( \nu E_0, \Phi \vdash u \) implies that \( u \in \text{img}(\Phi_a \uplus \Phi_b) \), then for all \( S \xrightarrow{\sigma} (E_0; P_S; \Phi_S) \) such that \( w \) does not contain any action that corresponds to an internal communication between two processes of different colours, we have that \( \Phi_S \) is well-tagged and there exists \( D \xrightarrow{w'} (E_0; P_D; \Phi_D) \) such that \( \Phi_D \downarrow = \delta^\rho(\Phi_S \downarrow) \).

Furthermore, if \( w = \ell_1, \ldots, \ell_n \) then \( w' = \ell'_1, \ldots, \ell'_n \) such that for all \( k \in \{1, \ldots, n\} \),

- if \( \ell_k = \nu_{ax_m, \text{out}(c, ax_m)} \) is an output coming from a process coloured by \( i \in \{a, b\} \), then \( \ell'_k = \nu_{ax_m, \text{out}(c_{\text{ch}}, ax_m)} \)

- if \( \ell_k = \text{in}(c, M) \) is an input coming from a process coloured by \( i \in \{a, b\} \), then \( \ell'_k = \text{in}(c_{\text{ch}}, M) \) with \( M_0, \Phi_D \downarrow = \delta^\rho(M_0, \Phi_S \downarrow) \).

- if \( \ell_k = \text{out}(c, d) \) is an output coming from a process coloured by \( i \in \{a, b\} \) with \( d \) a channel name, then \( \ell'_k = \text{out}(c_{\text{ch}}, d_{\text{ch}}) \)
• if $\ell_k = \nu_{c, m}.out(c, ch_m)$ is an output coming from a process coloured by $i \in \{a, b\}$ with $ch_m$ a channel name, then $\ell'_k = \nu_{c, m}.out(c_{\rho ch_m}, ch_m)$

• if $\ell_k = \tau$, then $\ell'_k = \tau$.

Note that in Lemma 5.14 we only consider traces that do not have internal communication between two processes of different colours. Indeed, for these internal communications, we will apply a specific transformation (see Example 5.23).

Lemma 5.15 (Completeness). Let $D \xrightarrow{w} (E_0; P_D; \Phi_D)$. Let $\Phi_+$ be a ground well-tagged frame such that $\Phi_+ = \Phi_a \uplus \Phi \uplus \Phi$ for some $\Phi$ and $\Phi_+, \Phi_D$ have the same colours. If the following properties are satisfied:

• $w = \ell_1, \ldots, \ell_n$
• $\nu E_0.\Phi_D \sim \nu E_0.\delta_0(\Phi_+)$
• for all $u \in \{k, \nu(k), \delta(k) \mid k \in \img(\rho) \cup \dom(\rho)\}$, $\nu E_0.\delta_0(\Phi_+) \vdash u$ or $\nu E_0.\Phi_D \vdash u$ implies that $u \in \img(\Phi_a \uplus \Phi b\rho^{-1})$
• for all $k \in \{1, \ldots, n\}$, if $\ell_k = \in(c, M_k)$ with $c \in \img(\rho_{ch_k})$, $i \in \{a, b\}$ then there exists $M'_k$ such that $M_k\delta_0(\Phi_+) \Downarrow = \delta_0(M'_k \Phi_+)$.  

then there exists a label $w' = \ell'_1, \ldots, \ell'_n$ and a well-tagged frame $\Phi_S$ such that $S \xrightarrow{w'} (E; P_S; \Phi_S)$, $\Phi_D \Downarrow = \delta_0(\Phi_S \downarrow)$, and for all $k \in \{1, \ldots, n\}$,

• if $\ell_k = \nu ax.\text{out}(c, ax)$ with $c \in \img(\rho_{ch_k})$, $i \in \{a, b\}$ then $\ell'_k = \nu ax.\text{out}(c_{\rho_{ch_k}}^{-1}, ax)$
• if $\ell_k = \in(c, M_k)$ with $c \in \img(\rho_{ch_k})$, $i \in \{a, b\}$, then $\ell'_k = \in(c_{\rho_{ch_k}}^{-1}, M'_k)$.
• if $\ell_k = \text{out}(c, d)$ with $c \in \img(\rho_{ch_k})$, $i \in \{a, b\}$ and $d$ a channel name, then $\ell'_k = \text{out}(c, d)\rho_{ch_k}^{-1}$
• if $\ell_k = \nu_{c, m}.\text{out}(c, ch_m)$ with $c \in \img(\rho_{ch_k})$, $i \in \{a, b\}$ and $ch_m$ a channel name, then $\ell'_k = \nu_{c, m}.\text{out}(c_{\rho_{ch_k}}^{-1}, ch_m)$
• if $\ell_k = \tau$ then $\ell'_k = \tau$

5.4.5 Dealing with internal communication

As mentioned earlier, Lemma 5.14 focuses on traces of $S$ that do not have internal communication between processes of different colours. More specifically, since in the intermediate process $D$, the processes coloured by $a$ and $b$ do not share any channel name, then an internal communication in a trace of $S$ between processes of different colours could not be matched by an internal communication in a trace of $D$ anymore. However, we know that the processes $P_a$ and $P_b$ do not share private channel name. Hence, if an internal communication occurs between two processes of different colours in a trace of $S$, then it implies that this internal communication was done over a public channel. This will allow us to modify the trace of $S$ in order to remove such internal communication.

Example 5.23. Coming back to Example 5.22, we have:

$$S \xrightarrow{\nu ax.\text{out}(c, ax_5)} (E_0; \{P_a, P'_b\}; \Phi_0 \uplus \{ax_5 \triangleright \langle id_2, \rho(k_2) \rangle\})$$

$$\xrightarrow{\tau} (E_0; \{\text{out}(c, a\text{enc}(tag_{ax}(u), \rho(k_1)))\}; \Phi_0 \uplus \{ax_5 \triangleright \langle id_2, \rho(k_2) \rangle\})$$

where $u = \langle \rho(k_1), id_1 \rangle$. To match this trace to a trace of $D$, we first have to remove the internal communication between $P_a$ and $P'_b$. To do so, we replace the internal communication by the
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sequence of label \( \nu \alpha_5.out(c, ax_6).in(c, ax_6) \):

\[
S \xrightarrow{\nu \alpha_5.out(c, ax_6)} (E_0; \{P_\alpha, P'_\beta\}; \Phi_0 \uplus \{ax_5 \triangleright \langle id_2, pk(k) \rangle\})
\]

\[
S \xrightarrow{\nu \alpha_5.out(c, ax_6)} (E_0; \{P'_{\beta}\}; \Phi_0 \uplus \{ax_5 \triangleright \langle id_2, pk(k) \rangle, ax_6 \triangleright u\})
\]

\[
S \xrightarrow{\nu \alpha_5.out(c, ax_6)} (E_0; \{ out(c, aenc(tag_6(u), pk(k)))\}; \Phi_0 \uplus \{ax_5 \triangleright \langle id_2, pk(k) \rangle, ax_6 \triangleright u\})
\]

Then we can apply the transformation described in Lemma 5.14 to obtain the corresponding trace of \( D \):

\[
D \xrightarrow{\nu \alpha_5.out(c, ax_6)} (E_0; \{P_\alpha, \delta_1(P'_{\beta})\}; \Phi_0 \uplus \{ax_5 \triangleright \langle id_2, pk(k) \rangle\})
\]

\[
D \xrightarrow{\nu \alpha_5.out(c, ax_6)} (E_0; \{\delta_1(P'_{\beta})\}; \Phi_0 \uplus \{ax_5 \triangleright \langle id_2, pk(k) \rangle, ax_6 \triangleright u\})
\]

\[
D \xrightarrow{\nu \alpha_5.out(c, ax_6)} (E_0; \{ out(c_2, aenc(tag_6(v), pk(k)))\}; \Phi_0 \uplus \{ax_5 \triangleright \langle id_2, pk(k) \rangle, ax_6 \triangleright u\})
\]

where \( M = (ax_1, \text{proj}_2(ax_6)) \) and \( v = (pk(k'), \text{proj}_2(u)) \). Note that \( v_\downarrow = (pk(k'), id_1) = \delta_1(u) \).

However, it remains one final issue with the internal communication. As mentioned in the proof technique for our main result consists of taking a trace \((tr, \Phi)\) of \((K_0; C[P_A]|P_B]; \Phi_0)\) (the shared case), matching it with a trace \((tr', \Phi')\) of the disjoint case, i.e. the process \((K'_0; C[P_A]|P_B]; \Phi_0)\). Then, thanks to the equivalence representing the “disjoint case”, we consider the trace \((tr', \Phi')\) in \((K'_0; C[P_A]|P_B]; \Phi_0)\) such that \(\Phi' \sim \Phi\), and at last we apply the completeness lemma in order to come back to a trace \((tr, \Phi')\) of the shared case, i.e. \((K_0; C[P_A]|P_B]; \Phi_0)\).

As we saw in this subsection, the trace internal communication between processes of different colours in \((tr, \Phi)\) are replaced by a sequence of visible actions of the form \(\nu \alpha \cdot out(c, ax).in(c, M)\) in the trace \((tr', \Phi')\). However, when considering the trace \((tr', \Phi')\) obtained thanks to the equivalence representing the disjoint case, it is possible that some \(\tau\)-actions are applied between the actions labeled \(\nu \alpha.out(c, ax)\) and \(in(c, M)\) in the trace \((tr', \Phi')\). But the two actions must be applied in sequence in order to transform back the sequence of actions \(\nu \alpha.out(c, ax).in(c, M)\) into an internal communication in the trace \((tr, \Phi')\). Hence, we show that it is possible to find a derivation of the trace \((tr', \Phi')\) where the two actions \(\nu \alpha.out(c, ax)\) and \(in(c, M)\) are applied consecutively.

**Lemma 5.16.** Let \( D' \) be an intermediate bounded process and \( w \) a sequence of labels such that \( D \xrightarrow{\nu \alpha} D' \). If \( w = w_1 \cdot w_2 \cdot w_3 \) with \( w_2 \in \nu \alpha.out(c_1, ax).\tau^*.in(c_2, M) \), \( c_1 \in \text{img}(\rho_{c_1}) \), \( c_2 \in \text{img}(\rho_{c_2}) \) and \( i \neq j \), then there exist two sequences of labels \( w' \), \( w'' \) such that \( w' = w_1 \cdot w'_2 \cdot w_3 \), \( w'' = \tau^*.\nu \alpha.out(c_1, ax).in(c_2, M).\tau^* \) and \( D \xrightarrow{w'} D' \).

**Proof.** \( D \xrightarrow{w'} D' \) and \( w = w_1 \cdot w_2 \cdot w_3 \) with \( w_2 \in \nu \alpha.out(c_1, ax).\tau^*.in(c_2, M) \) imply that there exist \( D_1, \ldots, D_n \) such that \( D \xrightarrow{w_1} D_1 \xrightarrow{\nu \alpha.out(c_1, ax)} D_2 \xrightarrow{\tau^*} \ldots \xrightarrow{\tau^*} D_n \xrightarrow{\text{in}(c_2, M)} D_0 \). By hypothesis on \( D \), we know that processes of different colors in \( D \) do not share public nor private channels. Thus, a \( \tau \) action, i.e. \( \tau \) action, can only be applied on processes of same colour.

But, applying a \( \tau \) action on a process of colour \( i \) does not modify the processes whose colours are \( j \neq i \).

Let \( S_1 = (E; P_\alpha \uplus P_\beta; \Phi) \) be an intermediate bounded process such that for all \( P \in P_\alpha \) (resp. \( P_\beta \)), \( \text{col}(P) = a \) (resp. \( b \)). Assume that we apply a \( \tau \) action, denoted \( \tau_a \), on \( P_\alpha \), i.e. there exists \( P_a \) such that \( S_1 \xrightarrow{\tau_a} (E; P_a \uplus P_\beta; \Phi) = S_2 \). Assume now that we apply a \( \tau \) action, denoted \( \tau_b \), on \( P_\beta \), i.e. there exists \( P_\beta \) such that \( S_2 \xrightarrow{\tau_b} (E; P_\alpha \uplus P'_\beta; \Phi) = S_3 \). Hence \( S_1 \xrightarrow{\tau_a} S_2 \xrightarrow{\tau_b} S_3 \). But we can see that \( S_1 \xrightarrow{\tau_a} (E; P_\alpha \uplus P'_\beta; \Phi) \xrightarrow{\tau_b} S_3 \). Thus it is possible to swap \( \tau \) actions.

With a similar proof, we can show that if \( S_1 \xrightarrow{\nu \alpha.out(c_1, ax)} S_2 \xrightarrow{\tau_a} S_3 \), with \( \tau_a \) a \( \tau \) action initiated by a process of colour \( b \), then we also have that there exists \( S'_2 \) such that \( S_1 \xrightarrow{\tau_a} S'_2 \xrightarrow{\nu \alpha.out(c_1, ax)} S_3 \). Furthermore, once again with a similar proof, we can show that if \( S_1 \xrightarrow{\tau_a} S_2 \xrightarrow{\text{in}(c_2, M)} S_3 \), with \( \tau_a \) a \( \tau \) action initiated by a process of colour \( a \), then there exists \( S'_2 \) such that \( S_1 \xrightarrow{\tau_a} S'_2 \xrightarrow{\text{in}(c_2, M)} S_3 \).
Therefore, a simple induction on the number of $\tau$ actions in the derivation $D \overset{w_1, w_2}{\rightarrow} D'$ allows us to prove that there exists $D_2, \ldots, D_{n-1}$ and an index $k \in \{1, \ldots, n-2\}$ such that $D_1 \overset{\tau}{\rightarrow} D'_2 \overset{\tau}{\rightarrow} \ldots \overset{\tau}{\rightarrow} D'_k \overset{\nu_{\text{ax}, \text{out}(c_1, ax)}}{\rightarrow} D'_{k+1} \overset{\iota_{\nu(c_2, M)}}{\rightarrow} D'_{k+1} \overset{\tau}{\rightarrow} \ldots \overset{\tau}{\rightarrow} D_n$. Hence the result holds.

\section*{5.4.6 Main composition result}

We can now state the main composition result of this chapter (proof in Appendix B.3).

\begin{theorem}
Let $P_A, P'_A$ (resp. $P_B, P'_B$) be two sequences of plain processes built $F_a \cup F_0$ (resp. $F'_a \cup F'_0$). Let $K_0$ be a finite set of names of base type, and $C$ and $C'$ be two composition contexts. Let $K'_0$ be a subset of $K_0$ such that $K'_0 = \text{names}(P_A, P'_A) \cap \text{names}(P_B, P'_B) \cap K_0$. Let $\Phi_0 = \{ax_1 \triangleright f_1(k_1), \ldots, ax_n \triangleright f_n(k_n)\}$ with $f_i \in \{pk, vk\}$, and $k_i \in K_0$ for any $i \in \{1, \ldots, n\}$. Assume that the processes $(K_0; C|\{P'_A\}_a; \Phi_0)$ and $(K_0; C|\{P'_B\}_b; \Phi_0)$ (resp. $(K_0; C|\{P'_A\}_a; \Phi_0)$, and $(K_0; C|\{P'_B\}_b; \Phi_0)$):

\begin{itemize}
  \item do not reveal any key in $\{k, pk(k), vk(k) | k \in K'_0\}$ unless the key occurs explicitly in $\Phi_0$;
  \item do not reveal any shared key in $C$ (resp. $C'$).
\end{itemize}

Lastly, we assume that plain processes $P_A, P'_A$ and $P_B, P'_B$ do not use variable of channel type. In such a case,

\begin{align*}
(K_0; C|\{P'_A\}_a; \Phi_0) & \equiv_t (K_0; C'|\{P'_A\}_a; \Phi_0) \\
(K_0; C|\{P'_B\}_b; \Phi_0) & \equiv_t (K_0; C'|\{P'_B\}_b; \Phi_0)
\end{align*}

\[ (K_0; C|\{P'_A\}_a | \{P'_B\}_b; \Phi_0) \equiv_t (K_0; C'|\{P'_A\}_a | \{P'_B\}_b; \Phi_0) \]

\end{theorem}

\section*{5.5 Application}

In this section, we present an example of application of Theorem 5.2 using the e-passport protocol. In Section 3.4 we described that the anonymity of the parallel composition of the protocols $AA$ and $PA$ can be expressed with the following equivalence:

\[ \nu_{\text{skDS}}.C[PA | AA, PA_0 | AA_0] \equiv_t \nu_{\text{skDS}}.C'[PA | AA] \]

where $C$ and $C'$ are contexts defined as follows:

\begin{align*}
C|_{\_1, \_2} & \overset{\text{def}}{=} !\nu_{\text{skp}}. \text{vid}. \text{vsig}. \text{vpic}. \ldots \\
& \quad !\nu_{\text{ksenc}}. \text{vksmac}._{\_1} \\
& \quad \text{vskp}0. !\nu_{\text{ksenc}}. \text{vksmac}._{\_2}
\end{align*}

\begin{align*}
C'|_{\_} & \overset{\text{def}}{=} !\nu_{\text{skp}}. \text{vid}. \text{vsig}. \text{vpic}. \ldots !\nu_{\text{ksenc}}. \text{vksmac}._{\_}
\end{align*}

Using the ProVerif tool [BAF08], we tried to prove these two equivalences, but it failed to terminate. The problem comes from the $PA$ protocol. Indeed, while ProVerif fails to prove that $PA$ satisfies anonymity and unlinkability (ProVerif does not terminate), it can perfectly prove that $AA$ satisfies these two properties.

In order to exploit the fact that ProVerif is able to prove anonymity of the $AA$ protocol, we show how we can apply Theorem 5.2 on the e-passport protocol. More specifically, we use Theorem 5.2 to show that the anonymity (resp. unlinkability) of the protocol $PA$ with tags implies the anonymity (resp. unlinkability) of the parallel composition of the protocols $AA$ and $PA$ with tags to the problem of anonymity of $PA$ with tags.
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First of all, note that both protocols PA and AA use the primitive \( \text{mac}/2 \) that can be modelled using our hash function \( h \) and the pairing, i.e., \( \text{mac}(u, k) \) is modelled by \( h(u, k) \). With this modelisation, we have that both protocols PA and AA are built over \( \mathcal{F}_0 \) which means that it is possible to tag these protocols. We will tag PA with \( a \) and AA with \( b \). Note that the protocols PA and AA do not have private channel nor variable of channel type.

Secondly, the key \( \text{sk}_{DS} \) corresponds to the private signing key of a signing authority. Hence, we will assume that the intruder knows the verification key \( \text{vk}(\text{sk}_{DS}) \). Moreover, for the victim’s e-passport, we might consider that the intruder have access to the verification key \( \text{vk}(\text{sk}_{P0}) \). Hence, using intermediate processes, the anonymity of the parallel composition of the protocols AA and PA with tags can be expressed with the following equivalence:

\[
\{\{\text{sk}_{DS}, \text{sk}_{P0}\}; \{C''[\text{PA}]_a | [\text{AA}]_b, [\text{PA}]_0 \} | [\text{AA}]_0 \}; \{ax_1 \triangleright \text{vk}(\text{sk}_{DS}), ax_2 \triangleright \text{vk}(\text{sk}_{P0})\} \equiv_i
\{\{\text{sk}_{DS}, \text{sk}_{P0}\}; \{C''[\text{PA}]_a | [\text{AA}]_b\}; \{ax_1 \triangleright \text{vk}(\text{sk}_{DS}), ax_2 \triangleright \text{vk}(\text{sk}_{P0})\}\]
\]

where \( C'' \) is defined as follows:

\[
C''[a_1, a_2] \overset{\text{def}}{=} !\nu \text{skp}, \text{vid}, \nu \text{sig}, \nu \text{pic}, \ldots
\]

\[
\nu \text{ksenc}, \nu \text{ksmac} - 1
\]

\[
(\text{vk}_{\text{skenc}}, \text{vk}_{\text{ksmac}})_2
\]

Note that both \( C' \) and \( C'' \) are composition context. While ProVerif can not prove this previous equivalence, it can prove that the following equivalence holds:

\[
(K_0; \{C''[\text{AA}]_b, [\text{AA}]_0\}; \Phi_0) \approx_t (K_0; \{C'[\text{AA}]_b\}; \Phi_0)
\]

where \( K_0 = \{\text{sk}_{DS}, \text{sk}_{P0}\} \) and \( \Phi_0 = \{ax_1 \triangleright \text{vk}(\text{sk}_{DS}), ax_2 \triangleright \text{vk}(\text{sk}_{P0})\} \).

It remains to prove that the shared key are not revealed. As already mentioned in Subsection 5.1.2, the only shared keys between the protocols PA and AA are \( \text{sk}_{P0} \) and the several instance of \( \text{ksenc,ksmac} \) and \( \text{skp} \). Hence we have to show that \( (K_0; \{C''[\text{AA}]_b, [\text{AA}]_0\}; \Phi_0), (K_0; \{C'[\text{AA}]_b\}; \Phi_0), (K_0; \{C''[\text{PA}]_b, [\text{PA}]_0\}; \Phi_0) \) and \( (K_0; \{C'[\text{PA}]_b\}; \Phi_0) \) do not reveal the keys \( \text{sk}_{P0} \) and the several instances of \( \text{ksenc, ksmac} \) and \( \text{vk}(\text{skp}) \). Note that according to the hypotheses of Theorem 5.2, we should also check that the processes do not reveal \( \text{vk}(\text{ksmac}), \ldots \text{vk}(\text{skp}) \) and the several instances of \( \text{ksenc, ksmac} \) as symmetric key, and \( \text{skp} \) as signing key, one can note that these checks are not necessary.

According to Definition 5.3, the process \( (K_0; \{C''[\text{PA}]_b, [\text{PA}]_0\}; \Phi_0) \) do not reveal the keys \( \text{sk}_{P0}, \text{ksenc, ksmac, skp} \) and \( \text{vk}(\text{skp}) \) if:

- \( \{\{\text{sk}_{DS}, \text{sk}_{P0}\}; \{C''[\text{PA}]_b, [\text{PA}]_0\}; \Phi_0\} \) preserves the secret of \( \text{sk}_{P0} \); and
- \( \{\{\text{sk}_{DS}, \text{sk}_{P0}, s\}; \{C''[\text{PA}]_b|\text{in}(c, x), \text{if } x = \text{key then } \text{out}(c, s) \text{ else } 0, [\text{PA}]_0\}; \Phi_0\} \) preserves the secrecy of \( s \), with \( \text{key} \in \{\text{ksenc, ksmac, skp, vk}(\text{skp})\} \); and
- \( \{\{\text{sk}_{DS}, \text{sk}_{P0}, s\}; \{C''[\text{PA}]_b, [\text{PA}]_0|\text{in}(c, x), \text{if } x = \text{key then } \text{out}(c, s) \text{ else } 0\}; \Phi_0\} \) preserves the secrecy of \( s \), with \( \text{key} \in \{\text{ksenc, ksmac, skp, vk}(\text{skp})\} \).

Similar conditions exist for the three others processes. Using ProVerif, we are able to prove that all these conditions hold. Hence, thanks to Theorem 5.2, we have that:

\[
(K_0; \{C''[\text{PA}]_b, [\text{PA}]_0\}; \Phi_0) \approx_t (K_0; \{C'[\text{PA}]_b\}; \Phi_0)
\]

implies

\[
(K_0; \{C''[\text{AA}]_b | [\text{PA}]_b, [\text{AA}]_0 | [\text{PA}]_0\}; \Phi_0) \approx_t (K_0; \{C'[\text{AA}]_b | [\text{PA}]_b\}; \Phi_0)
\]
5.6 Conclusion

In this chapter, we investigated composition results for privacy-type properties expressed using trace equivalence. We have shown that secure protocols can be safely composed. We consider arbitrary equational theories and we assume that protocols may share some usual primitives provided they are tagged. Moreover, we have to assume that the shared keys are not revealed and we allow public and verification shared keys to be known by the intruder, provided that they were given at the beginning (using the frame $\Phi_0$). However, in our setting (and in many others) such a sequence has to be finite and thus we are only able to deal with a bounded number of public shared keys.

To relax this hypothesis without modifying our model, we need to abstract the public shared keys. For example, the public shared keys initially given to the intruder could be modelled by a unique private shared key (e.g. $sk_0$) and the successive applications of a new one-way function (e.g. $s/1$). Hence, if $\{pk(sk_1), \ldots, pk(sk_n), \ldots\}$ represented the infinite set of public shared keys initially given to the intruder then this would be modelled by the set

$$\{pk(sk_0), pk(s(sk_0)), pk(s(s(sk_0))), \ldots\}$$

Then, relying on this representation, we could build a server that distributes the shared public keys to the intruder, e.g.

$$S = \nu d. (\text{out}(c, pk(sk_0)). \text{out}(d, sk_0) \parallel \text{in}(d, x). \text{out}(c, pk(s(x))). \text{out}(d, s(x)))$$

where $c$ is a public channel. However, we would probably need to add in the hypotheses of our composition result that any successive application of $s$ on $sk_0$ cannot be deduced by the intruder.

We also showed in this chapter how to apply our composition result on the parallel composition of the Active Authentication and Passive Authentication protocols from the e-passport protocols. However, we had to abstract the symmetric session keys that were generated by the Basic Access Control protocol beforehand. Thus, to include the Basic Access Control protocol, we would have to establish a “sequential” composition result. The term sequential may be misleading since there is no general sequence operator in the applied pi calculus that would compose for example the process $(A \parallel B)$ with the process $(P \parallel Q)$. In fact, in the case of the e-passport protocols, the Active Authentication and Passive Authentication) protocols are plugged inside the Basic Access Control protocol, i.e.

$$BAC_P[P_A \mid AA_P] \parallel BAC_R[P_A \mid AA_R]$$

where $BAC_P[\_], PA_P$ and $AA_P$ (resp. $BAC_R[\_], PA_R$ and $AA_R$) are the processes represented the role of the passport (resp. the reader). Note that the processes of the Basic Access Control protocol are modelled by the means of contexts where the holes represented where the others processes will be plugged. This plugging is crucial to properly model the behaviour of the whole e-passport protocols. Indeed, since the protocols $PA$ and $AA$ should only be executed if the protocol $BAC$ succeeded then they must be plugged in the proper conditional branch of the protocol $BAC$ which model a successful execution.

Such a “sequential" composition result would probably subsume the results presented in this chapter.
Part II

A decision procedure for trace equivalence
Chapter 6

Model

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We are focusing on a decision procedure of trace equivalence of bounded processes that allows a set of standard cryptographic primitives, in particular signatures, pairing, hash function, symmetric and asymmetric encryptions. Moreover, we will consider that the primitives such as decryption, projection, ... may fail. Hence instead of modelling the behaviour of these cryptographic primitives with an equational theory as in Part I, they will be modelled by a set of rewrite rules. Thus, we propose in this chapter a new model adapted to the behaviour of these primitives, and that is still close to the applied pi calculus.

The aim of this chapter is to provide with a number of simplifications and restrictions of the trace equivalence problem, without losing in generality. First, following the footsteps of Chapter 4, we reduce the decidability of trace equivalence to decidability of symbolic equivalence between sets of constraint systems. Then, we simplify the problem of symbolic equivalence by

1. getting rid of free names in the processes and the actions of the intruder; and
2. only considering normalised recipe
3. only considering constructor constraint system, i.e. constraint system which only contains constructor terms.

Chapter 7 will then be dedicated to a decision procedure of symbolic equivalence between sets of constructor constraint systems.

Amongst the existing tools, only SPEC [TD10] relies on constraint systems whereas the tools ProVerif [Bau01] and AKiSs [Cio11] relies on Horn clauses. However, since the aim of [TD10] is a decision procedure for open-bisimulation for bounded processes in the spi-calculus, they reduce this problem to the problem of symbolic equivalence between positive constraint systems. Baudet [Bau05, Bau07] also proves decidability of equivalence between positive constraint systems...
but for a much larger set of primitives that is for subterm convergent theories. In [CR12], a shorter proof of the result by Baudet is given. Although our decision procedure lacks of cryptographic primitives in comparison of [Bau05, Bau07], their procedure along with [CD09a] is restricted the trace equivalence of determinate processes that do not contain (non trivial) conditional branching.

6.1 Syntax and semantics

6.1.1 Syntax

Similarly to the applied pi calculus, we consider an infinite set of names \( N \) and an infinite set of variable \( X \). However, we define \( F_c \) and \( F_d \) the finite sets of constructor function symbols and destructor function symbols respectively. More specifically, we consider:

\[
F_c \supseteq \{ \text{senc/2, aenc/2, pk/1, sign/2, vk/1, } \langle \rangle /2, \text{h/1}\}
\]

\[
F_d = \{ \text{sdec/2, adec/2, check/2, proj\textsubscript{1}/1, proj\textsubscript{2}/1} \}.
\]

We allow \( F_c \) to contain more primitives than the one we specified. It allows the users to consider some constants or primitives such as \( \text{mac} \). The constructor terms, resp. ground constructor terms, are those in \( T(F_c, N \cup X^1) \), resp. in \( T(F_c, N) \).

We model the properties of our cryptographic primitives by the following set of rewrite rules:

\[
s\text{dec}(\text{senc}(x, y), y) \rightarrow x
\]

\[
\text{adec}(\text{aenc}(x, \text{pk}(y)), y) \rightarrow x
\]

\[
\text{check}(\text{sign}(x, y), \text{vk}(y)) \rightarrow x
\]

This term rewriting system is convergent. Note that only the specified primitives intervene in the rewriting system.

A ground term \( u \) is a message if \( v \downarrow \) is a constructor term for all \( v \in \text{st}(u) \). We define the predicate \( \text{Message}(\cdot) \) on terms such that \( \text{Message}(u) \) is true if, and only if, \( u \) is a message. For instance, the terms \( \text{sdec}(a, b) \), \( \text{proj\textsubscript{1}}(\langle a, \text{sdec}(a, b) \rangle) \), and \( \text{proj\textsubscript{1}}(a) \) are not messages. Intuitively, we view terms as modus operandi to compute bitstrings where we use the call-by-value evaluation strategy.

For our processes, since we do not consider replication, we define processes that are similar to the bounded intermediate processes defined in Chapter 4. The grammar of our plain processes is as follows:

\[
P, Q, R ::= 0
\]

\[
P \mid Q
\]

\[
P + Q
\]

\[
\text{if } u_1 = u_2 \text{ then } P \text{ else } Q
\]

\[
in(u, x). P
\]

\[
\text{out}(u, v). P
\]

where \( u_1, u_2, u, v \) are terms, and \( x \) is a variable.

This is almost identical to the definition of plain processes in the applied pi calculus. However, we added the choice operator \( P + Q \). As mentioned in Chapter 3 this could have been modelled using private channels but we added it to enhance the efficiency of our algorithm. Moreover, we confuse channel with message. At last, similarly to the bounded intermediate processes (see Section 4.1.4), there is no name restriction in the plain processes.

As last, we define concrete processes from Definition 4.1 of intermediate processes with this definition of plain processes.

6.1.2 Semantics

The semantics of concrete processes is given in the Figure 6.1. Note also that, since we allow arbitrary terms for channels, we have to check whether the channel is known by the attacker or
not (see rules IN and OUT). Moreover, we check that all terms that have to be evaluated during the execution are messages.

Let $A_\pi$ be the alphabet of actions for the intermediate semantics. For every $w \in A_\pi^*$ the relation $\xrightarrow{\pi}$ on intermediate processes is defined in the usual way. For $s \in (A_\pi \setminus \{\tau\})^*$, the relation $\xrightarrow{\pi}$ on intermediate processes is defined by: $A \xrightarrow{\pi} B$ if, and only if there exists $w \in A_\pi^*$ such that $A \xrightarrow{w} B$ and $s$ is obtained by erasing all occurrences of $\tau$. Note that by definition, intermediate processes are closed.

$\begin{align*}
(\mathcal{E}; \{f(u \leftarrow v) \text{ then } Q_1 \text{ else } Q_2\} \uplus P; \Phi) & \xrightarrow{i} (\mathcal{E}; \{Q_1\} \uplus P; \Phi) \\
& \quad \text{if } u \downarrow = v \downarrow, \text{ Message}(u) \text{ and Message}(v) \\
(\mathcal{E}; \{f(u \leftarrow v) \text{ then } Q_1 \text{ else } Q_2\} \uplus P; \Phi) & \xrightarrow{i} (\mathcal{E}; \{Q_2\} \uplus P; \Phi) \\
& \quad \text{if } u \downarrow \neq v \downarrow \text{ or } \neg \text{Message}(u) \text{ or } \neg \text{Message}(v) \\
(\mathcal{E}; \{\text{out}(u,t), Q_1; \text{in}(v,x), Q_2\} \uplus P; \Phi) & \xrightarrow{i} (\mathcal{E}; \{\{Q_1; Q_2\} \uplus P; \Phi) \\
& \quad \text{if Message}(u), \text{Message}(v), \text{Message}(t) \text{ and } u \downarrow = v \downarrow \\
(\mathcal{E}; \{\text{in}(u,x), Q\} \uplus P; \Phi) & \xrightarrow{i} (\mathcal{E}; \{Q\} \uplus P; \Phi) \\
& \quad \text{in } \text{Message}(u), \text{Message}(v) \subseteq \text{fvars}(M), \text{fnames}(M) \cap \mathcal{E} = \emptyset \\
& \quad \text{Message}(M\Phi), \text{Message}(\Phi) \text{ and Message}(u) \\
(\mathcal{E}; \{\\text{out}(u,t), Q\} \uplus P; \Phi) & \xrightarrow{i} (\mathcal{E}; \{Q\} \uplus P; \Phi) \\
& \quad \text{if } M\Phi = t, \text{fvars}(M,N) \subseteq \text{dom}(\Phi), \text{fnames}(M,N) \cap \mathcal{E} = \emptyset \\
& \quad \text{Message}(M\Phi), \text{Message}(\Phi) \text{ and Message}(\Phi) \\
(\mathcal{E}; \{P_1 | P_2\} \uplus P; \Phi) & \xrightarrow{i} (\mathcal{E}; \{P_1, P_2\} \uplus P; \Phi) \\
(\mathcal{E}; \{P_1 + P_2\} \uplus P; \Phi) & \xrightarrow{i} (\mathcal{E}; \{P_1\} \uplus P; \Phi) \\
(\mathcal{E}; \{P_1 + P_2\} \uplus P; \Phi) & \xrightarrow{i} (\mathcal{E}; \{P_2\} \uplus P; \Phi)
\end{align*}$

where $u$, $v$, $t$ are ground terms, and $x$ is a variable.

Figure 6.1: Concrete semantics

As we will see in Chapter 9, checking whether a term is a message is very similar the check of failure of a term evaluation in ProVerif. In ProVerif, the evaluation of terms is explicit in let $x = D$ in $P$ whereas in our semantics, the evaluation of a term is performed on the fly. Typically, given a plain process $P$, one can transform $P$ into a ProVerif process that has the same behaviour by replacing every out($u,t$) by let $x = \text{addeval}(u)$ in let $y = \text{addeval}(t)$ in out($x,y$), every in($u,x$) by let $y = \text{addeval}(u)$ in in($y,x$), ... .

Similarly to Chapter 4, given a concrete process $(\mathcal{E}_1; P_1; \Phi_1)$, the set of its traces is defined by:

$\text{trace}_c((\mathcal{E}_1; P_1; \Phi_1)) = \{ (\mathcal{E}_2; P_2; \Phi_2) | (\mathcal{E}_1; P_1; \Phi_1) \xrightarrow{c} (\mathcal{E}_2; P_2; \Phi_2) \text{ for some } (\mathcal{E}_2; P_2; \Phi_2) \}$

Note that due to our semantics, we have in fact $\mathcal{E}_1 = \mathcal{E}_2$.

**Example 6.1.** Consider the sequence of actions $\mathcal{E}_1 = v ax_1.\text{out}(c_1, ax_1).\text{in}(c_1, \text{proj}_1((ax_1, \text{sdec}(a,b)))).v ax_2.\text{out}(c_2, ax_2)$. For all concrete process $A$, no trace in $\text{trace}_c(A)$ can have $\mathcal{E}_1$ as sequence of actions. Indeed, for all $\Phi$, $\text{Message}(\text{proj}_1((ax_1, \text{sdec}(a,b))) \Phi) = \text{false}$.

Intuitively, the intruder will never be able to compute $\text{proj}_1((ax_1, \text{sdec}(a,b))) \Phi$ since the computation of $\text{sdec}(a,b)$ will fail and so $(ax_1, \text{sdec}(a,b))$ does not represent a bitstring.

### 6.1.3 Equivalence

We redefine the static equivalence (Definition 3.1) in this context.
We recall the notations used in the symbolic calculus in Chapter 4.2: We consider a new set of private names \( X \) and symbolic process (Definition 4.6) used in Section 4.2. A constraint system (Definition 4.3) is a set of parameters in \( \mathcal{E} \), usually denoted \( \xi \). The set of parameters in \( \mathcal{E} \), or \( \mathcal{E} \), has the form \( \nu \mathcal{E} \Phi \sim \nu \mathcal{E} \Phi' \), when \( \text{dom}(\Phi) = \text{dom}(\Phi') \) and for all terms \( M, N \) such that \( \text{fvars}(M, N) \subseteq \text{dom}(\Phi) \) and \( \text{fnames}(M, N) \cap \mathcal{E} = \emptyset \), we have:

- Message\((M \Phi)\) if and only if Message\((M \Phi')\)
- if Message\((M \Phi)\) and Message\((N \Phi')\) then \( M \Phi \downarrow = N \Phi \downarrow \) if and only \( M \Phi \downarrow = N \Phi' \downarrow \).

The second item of Definition 6.1 corresponds to the usual definition of the static equivalence. However, we add the conditions Message\((M \Phi)\) and Message\((N \Phi')\) otherwise the equality \( M \Phi \downarrow = N \Phi' \downarrow \) would be meaningless. Note that we do not require that Message\((M \Phi')\) or Message\((N \Phi')\) but it is implied by the first item of the static equivalence.

We recall the definition of trace equivalence in Section 3.1 that we adapt to our set of traces \( \rho \mathcal{C} \). Let \( \rho \mathcal{C} \) be concrete processes with the same set of private names \( \mathcal{E} \). A \( \subseteq \) \( B \) if for every \( (s, \nu \mathcal{E} \Phi) \in \text{trace}(A) \), there exists \( (s', \nu \mathcal{E} \Phi') \in \text{trace}(B) \) such that \( s = s' \) and \( \nu \mathcal{E} \Phi \sim \nu \mathcal{E} \Phi' \).

Two closed extended processes \( A \) and \( B \) are trace equivalent, denoted by \( A \cong_t B \), if \( A \subseteq_t B \) and \( B \subseteq_t A \).

Note that we do not have anymore the condition \( \text{fnames}(B) \cap \text{bnames}(s) = \emptyset \). This condition was essential for the applied pi calculus since a action label could be of the form \( \nu c . \text{out}(p, c) \) with \( c \) a channel name. In our case, only the parameters \( ax_i \) can be found in \( s \) hence we necessarily have \( \text{bnames}(s) = \emptyset \).

6.2 Symbolic calculus

In order to decide the trace equivalence between two concrete process, we propose, similarly to Section 4.2 a symbolic calculus and its semantics. We consider the constraint system (Definition 4.3) and symbolic process (Definition 4.6) used in Section 4.2.

6.2.1 Semantics

We recall the notations used in the symbolic calculus in Chapter 4.2. We consider a new set \( X^2 \) of variables called second order variables \( X, Y, . . \) To avoid conflict between the variables in \( X^2 \) and the one we already used to described the protocols and the processes, we denote by \( X^1 \) the latter set variables and call them first order variables. Note that \( X^1, X^2, AX \) are all disjoint subsets of \( X \). We call recipe, usually denoted \( \xi \), the terms in \( \mathcal{T}(F, N \cup X^2 \cup AX) \). We say that a recipe \( \xi \) is closed (or ground) if \( \xi \in \mathcal{T}(F, N \cup AX) \). Given a recipe \( \xi \in \mathcal{T}(F, N \cup X^2 \cup AX) \), we denote \( \text{param}(\xi) \) the set of parameters in \( \xi \), i.e. \( \text{vars}(\xi) \cap AX \).

We adapt the definition of solutions of a constraint system so that it matches with the concrete semantics (see Figure 6.1).

Definition 6.3 (concrete solution). A concrete solution of a constraint system \( \mathcal{C} = (\mathcal{E}; \Phi; D; Eq) \) is a pair of substitutions \((\sigma, \theta)\) such that \( \sigma \) is a mapping from \( \text{vars}^1(\mathcal{C}) \) to \( \mathcal{T}(F, N) \), \( \theta \) is a mapping from \( \text{vars}^2(\mathcal{C}) \) to \( \mathcal{T}(F, N \sim \{ \mathcal{E} \}, AX) \), and:

1. for all \((X, k \vdash x) \in D\), \((X \theta)(\Phi \sigma) = x \sigma\), \( \text{param}(X \theta) \subseteq \{ ax_1, . . . , ax_k \} \) and Message\((x \sigma)\);
2. for all \((s \vdash s') \in Eq\), \( s \sigma \downarrow = s' \sigma \downarrow\), Message\((s \sigma)\) and Message\((s' \sigma)\);
3. for all \((s \neq s') \in Eq\), \( s \sigma \downarrow \neq s' \sigma \downarrow\), or \( \neg \text{Message}(s \sigma) \), or \( \neg \text{Message}(s' \sigma) \).
4. for all \((ax_i \triangleright u_i) \in \Phi\), Message\((u_i \sigma)\)
The substitution $\sigma$ is called the first-order solution of $C$ associated to $\theta$, called second-order solution of $C$. The set of solutions of a constraint system $C$ is denoted $\text{Sol}_1(C)$. A constraint system $C$ is satisfiable if $\text{Sol}_1(C) \neq \emptyset$.

Compared to the usual definition of solution (see Definition 4.4), we added the fact that every term in the constraint system has to be a message as it is specified in the rule $(\text{OUT}_c)$.

**Example 6.2.** Coming back to the Example 4.7, we had $(\sigma, \theta) \in \text{Sol}_1(C_1)$. But $(\sigma, \theta)$ also satisfies all conditions of a concrete solution, hence $(\sigma, \theta) \in \text{Sol}_c(C_1)$.

The rules of Figure 6.2 define the semantics of symbolic processes. Similarly to Section 4.2, this relation transforms a symbolic process into a symbolic process. Once again, thanks to this symbolic semantics, we avoid infinite branching due to the inputs of the environment. We added some rules for the choice operator and we removed the rules that was specific to the outputs of channel names.

$$(E; \{\text{if } u = v \text{ then } P_1 \text{ else } P_2\} \triangleright P; \Phi; D; Eq) \overset{\text{THEN}_c}{\rightarrow} (E; \{P_1\lor P_2; \Phi; D; Eq \cup \{u \overset{?}{=} v\})$$

$$(E; \{u = v \text{ then } P_1 \text{ else } P_2\} \triangleright P; \Phi; D; Eq) \overset{\text{THEN}_c}{\rightarrow} (E; \{P_1\lor P_2; \Phi; D; Eq \cup \{u \overset{?}{=} v\})$$

$$(E; \{\text{out}(u, t).Q_1; \text{in}(v, x).Q_2\} \triangleright P; \Phi; D; Eq) \overset{\text{ELSE}_c}{\rightarrow} (E; \{Q_1; Q_2[x \mapsto t]\} \triangleright P; \Phi; D; Eq \cup \{u \overset{?}{=} v\})$$

$$(E; \{P \mid Q\} \triangleright P; \Phi; D; Eq) \overset{\text{PAR}_c}{\rightarrow} (E; \{P; Q\} \triangleright P; \Phi; D; Eq)$$

$$(E; \{P + Q\} \triangleright P; \Phi; D; Eq) \overset{\text{CHOICE}_{ax-1}}{\rightarrow} (E; \{P\} \triangleright P; \Phi; D; Eq)$$

$$(E; \{P + Q\} \triangleright P; \Phi; D; Eq) \overset{\text{CHOICE}_{ax-1}}{\rightarrow} (E; \{Q\} \triangleright P; \Phi; D; Eq)$$

$$(E; \{\text{in}(u, x).Q\} \triangleright P; \Phi; D; Eq) \overset{\text{IN}_c}{\rightarrow} (E; \{Q[x \mapsto y]\} \triangleright P; \Phi; D \cup \{Y, n \overset{?}{=} y; Z, n \overset{?}{=} z; Eq \cup \{z \overset{?}{=} u\})$$

if $Y, y, Z, z$ are fresh variables, $n = |\Phi|$ (IN$_c$)

$$(E; \{\text{out}(u, t).Q\} \triangleright P; \Phi; D; Eq) \overset{\text{PAR}_c, \text{OUT}_c}{\rightarrow} (E; \{Q\} \triangleright P; \Phi \cup \{ax_{n+1} \triangleright t\}; D \cup \{Z, n \overset{?}{=} z; Eq \cup \{z \overset{?}{=} u\})$$

if $ax_{n+1} \in \mathcal{AX}$ such that $n = |\Phi|$, $Z, z$ are fresh variables (OUT$_c$)

$u, v, t$ are terms and $x$ is a variable.

Figure 6.2: Concrete symbolic semantics

Note that the rules are almost identical to the symbolic semantics used for the applied pi calculus, except for the new/removed rules. Indeed, all the new requirement of the concrete semantics were added in the definition of a concrete solution of a constraint system instead of being added in the symbolic semantics directly. We define the relations $\overset{w}{\rightarrow}_c$ and $\overset{u}{\rightarrow}_c$ as usual.

We denote $\text{trace}_{cs}(A)$ the set of concrete symbolic traces of a concrete process as follow:

$$\text{trace}_{cs}(A) = \{\text{tr}; (E; \Phi; D; Eq)) \mid A \overset{\Sigma_c}{\rightarrow} (E; \Phi; D; Eq)\text{ for some } E, \mathcal{P}, \Phi, D, Eq\}$$

When $\text{tr}$ is fixed, we also write $(\text{tr}, \Sigma) \in \text{trace}_{cs}(A)$ to define the set $\Sigma$ as the set of constraint systems $\{C \mid (\text{tr}, C) \in \text{trace}_{cs}(A)\}$.

### 6.2.2 From trace equivalence to concrete symbolic equivalence

Following the results of Chapter 4, we define the concrete symbolic equivalence between two sets of constraint systems.

Definition 6.4 (concrete symbolic equivalence). Let $\Sigma$ and $\Sigma'$ be two sets of constraint systems that contain constraint systems having the same structure. We say that $\Sigma$ and $\Sigma'$ are in concrete symbolic equivalence, denoted by $\Sigma \approx_c \Sigma'$, if for all $C \in \Sigma$, for all $(\sigma, \theta) \in \text{Sol}_c(\mathcal{C})$, there exists $C' \in \Sigma'$ and a substitution $\sigma'$ such that $(\sigma', \theta) \in \text{Sol}_c(C')$ and $\nu E . F \sigma \sim_c \nu E . F' \sigma'$ (and conversely for all $C' \in \Sigma'$) where $\mathcal{C} = (E; \Phi; D; E_\text{eq})$ and $\mathcal{C}' = (E; \Phi'; D'; E'_\text{eq})$.

The definition of $\approx_c$ is very close to the definition of $\approx_s$ (see Definition 4.8). Typically, only the solutions used in the equivalence and the static equivalence are different between $\Sigma$ and $\Sigma'$.

Example 6.3. Coming back to the Example 4.8, $\Sigma \approx_c \Sigma'$ also holds. Moreover $\{C_1\}$ and $\{C'_1\}$ are not in concrete symbolic equivalence.

We establish the link between trace equivalence and concrete symbolic equivalence:

Theorem 6.1. Let $A$ and $B$ two concrete processes: $A \approx_1 B$ if, and only if, for all sequences of symbolic actions $\mathcal{A}$, for all $(\mathcal{A}, \mathcal{B}) \in \text{trace}_c(A, B)$, $A \approx_1 B$.

Proof (sketch). The proof of this theorem is an adaptation of the proof of Proposition 4.4. It also relies on soundness and completeness results similar to Lemmas 4.2 and 4.3 that focus on concrete solutions instead of solutions of a constraint system and focus on $\rightarrow_s$ instead of $\sim_s$. The proofs of these lemmas are a simple adaptation of the proofs of Lemmas 4.2 and 4.3.

The focus on the rest of this part is to provide an algorithm that decides if two concrete symbolic equivalence between two sets of constraint systems.

6.3 Getting rid of some recipes

Deciding the symbolic equivalence of sets of constraint systems is a difficult problem. One of the main issues is that the set of recipes $\mathcal{T}(\mathcal{F}, \mathcal{AX} \cup \mathcal{N})$ that have to be considered for the static equivalence and also for the solutions of a constraint system is infinite. In this section, we aim at reducing this set of recipes. More specifically, we will first show that $\Sigma \approx_s \Sigma'$ is equivalent to the symbolic equivalence where we do not consider public names for the intruder ($\approx_{s, \mathcal{T}(\mathcal{F}, \mathcal{AX})}$). Then we show that it is equivalent to the symbolic equivalence where we do not consider public names and recipes that are not normalised ($\approx_{s, \mathcal{T}(\mathcal{F}, \mathcal{AX})}$). Lastly, we will show that there exist $\Sigma_1, \Sigma'_1$ sets of constraint systems that only contain constructor terms, called constructor constraint systems, such that $\Sigma \approx_{s, \mathcal{T}(\mathcal{F}, \mathcal{AX})}$ is equivalent to $\Sigma_1 \approx_{s, \mathcal{T}(\mathcal{F}, \mathcal{AX})}$ where $\approx_s$ excludes recipes containing public names or recipe not normalised. Moreover, the predicate $\text{Message}()$ is no longer required.

6.3.1 Getting rid of names

One of the infinite components in $\mathcal{T}(\mathcal{F}, \mathcal{AX} \cup \mathcal{N})$ is the infinite set of names $\mathcal{N}$. We show in this subsection that we do not need to consider the names $\mathcal{N}$ in the intruder’s recipes.

6.3.1.1 Processes without free names

First of all, we have to distinguish two kinds of names: the ones that are already used by the processes and the ones that might be introduced by the intruder in the trace. In a first step, illustrated in the Example 6.4 we avoid free names in the processes by privatising and disclosing them.

Example 6.4. Consider the concrete process $A$ defined as follows:

$$A = \{(sk); \text{out}(c, \text{aenc}(a, pk(sk))); \text{in}(c, x); \text{vnout}(c, \langle x, n \rangle); \emptyset\}.$$  

We can transform $A$ into a process $A'$ that does not contain any free public name by putting the free names $c$ and $a$ inside the private set of names and adding two frame elements with $c$ and $a$:

$$A' = \{(sk, c, a); \text{out}(c, \text{aenc}(a, pk(sk))); \text{in}(c, x); \text{vnout}(c, \langle x, n \rangle); \{ax_1 \triangleright c, ax_2 \triangleright a\}.$$
6.3. GETTING RID OF SOME RECIPES

Consider now the trace \((\text{tr}, \nu \mathcal{E}. \Phi) \in \text{trace}_c(A)\) where \(\mathcal{E} = \{sk\}\), \(\text{tr} = \nu ax_1.\text{out}(c, ax_1).\nu ax_2.\text{out}(c, ax_2)\) and \(\Phi = \{ax_1 \triangleright \text{aenc}(a, pk(sk)), ax_2 \triangleright \langle \text{aenc}(a, pk(sk)), n\}\). There exists a similar trace \((\text{tr}', \nu \mathcal{E}'. \Phi') \in \text{trace}_c(A')\) where:

- \(\mathcal{E}' = \{sk, c, a\}\)
- \(\text{tr}' = \nu ax_1.\text{out}(ax_1, ax_3).\nu ax_2.\text{out}(c, ax_4)\)
- \(\Phi' = \{ax_1 \triangleright c; ax_2 \triangleright a; ax_3 \triangleright \text{aenc}(a, pk(sk)); ax_4 \triangleright \langle \text{aenc}(a, pk(sk)), n\}\)\)

We formalise the transformation presented in Example 6.4 in the following lemma.

**Lemma 6.1.** Let \(A = (\mathcal{E}_A; \mathcal{P}_A; \Phi_A)\) and \(B = (\mathcal{E}_B; \mathcal{P}_B; \Phi_B)\) be two closed concrete processes such that \(\mathcal{E}_A = \mathcal{E}_B\) and \(\text{dom}(\Phi_A) = \text{dom}(\Phi_B)\). Let’s denote \(n = |\Phi_A|\). Assume that \(A\) and \(B\) contains \(m - 1\) free names, i.e. \(\text{fnames}(A) \cup \text{fnames}(B) = \{c_2, \ldots, c_m\}\) and let \(c_1\) be a fresh name in \(\mathcal{N}\). Let \(\Phi_0\) the frame \(\{ax_1 \triangleright c, \ldots, ax_m \triangleright c_m\}\), \(\Phi_A'\) (resp. \(\Phi_B'\)) be the frame obtained from \(\Phi_A\) (resp. \(\Phi_B\)) by replacing every \((ax_k \triangleright u_k) \in \Phi_A\) (resp. \(\Phi_B\)) by \((ax_k+m \triangleright u_k)\). The following property holds:

\[ A \approx_1 B \text{ if, and only if, } (\mathcal{E}_0; \mathcal{P}_A; \Phi_0 \cup \Phi_A') \approx_1 (\mathcal{E}_0; \mathcal{P}_B; \Phi_0 \cup \Phi_B') \]

where \(\mathcal{E}_0 = \text{fnames}(A) \cup \text{fnames}(B) \cup \mathcal{E}\)

**Proof (sketch).** Let’s denote \(A' = (\mathcal{E}_0; \mathcal{P}_A; \Phi_0 \cup \Phi_A')\) and \(B' = (\mathcal{E}_0; \mathcal{P}_B; \Phi_0 \cup \Phi_B')\). The proof consists of applying a simple transformation on the traces of \(A\) and \(B\). Considering \((\text{tr}, \nu \mathcal{E}_A.(\Phi_A \cup \Phi_A')) \in \text{trace}(A)\), we transform \(\text{tr}\) into \(\text{tr}'\) as follows:

- we replace every instance of \(c_i\) in \(\text{tr}\) by \(ax_i\), for all \(i \in \{1, \ldots, m\}\).
- we replace every instance of \(ax_i\) by \(ax_{i+1}\) for all \(i > n\)

Similarly, we transform \(\Phi_A\) into \(\Phi_A'\) by replacing every \((ax_i \triangleright u) \in \Phi_A\) by \((ax_{i+1} \triangleright u)\). Note that both transformations are bijective. One can easily show that \((\text{tr}', \nu \mathcal{E}_0.(\Phi_0 \cup \Phi_A' \cup \Phi_A')) \in \text{trace}(A')\).

At last, one can show that \(\nu \mathcal{E}_A.(\Phi_A \cup \Phi_A') \sim_c \nu \mathcal{E}_B.(\Phi_B \cup \Phi_B')\) if and only if \(\nu \mathcal{E}_0.(\Phi_0 \cup \Phi_A' \cup \Phi_A) \sim_c \nu \mathcal{E}_0.(\Phi_0 \cup \Phi_B' \cup \Phi_B)\) by applying on the recipes the same transformations used for the sequence of labels.

Thanks to Lemma 6.1 we can now assume that there is no public names in our constraint system. Indeed, given a concrete process \(A\) such that \(\text{fnames}(A) = \emptyset\), for all \((\text{tr}, C) \in \text{trace}_c(A)\), \(\text{fnames}(C) = \emptyset\). Moreover Lemma 6.1 also indicates that \(\Phi_0\) contains at least one frame element \((ax_1 \triangleright c_1)\) with \(c_1 \in \mathcal{N}\). Thus, if \(A\) is the concrete process obtained from Lemma 6.1 then there exists \(a \in \mathcal{N}\) such that for all \((\text{tr}, C) \in \text{trace}_c(A)\), \(ax_1 \Phi = a\) where \(C = (\mathcal{E}; \Phi; D; Eq)\).

6.3.1.2 Removing all names in the recipes

In the previous paragraph we showed how avoid free names in the processes. However, as previously mentioned, the intruder might still introduce new public names in the sequence of labels \(\text{tr}\). We show that it is possible to model the public names in \(\mathcal{N}\) by \(h(h(\ldots h(ax_1) \ldots))\). Consider a constraint system \(\mathcal{C} = (\mathcal{E}; \Phi; D; Eq)\) such that \(\text{fnames}(C) = \emptyset\). Following Lemma 6.1 we assume that \(\Phi\) is not empty and \(ax_1 \Phi \in \mathcal{E}\). Since \(\mathcal{N}\) is a countable set, we denote \(\mathcal{N}\setminus \mathcal{E} = \{b_1, \ldots, b_i, \ldots\}\).

Intuitively, we would represent each \(b_i\) by \(h^i(ax_1)\) in the recipe of the intruder where \(h^i(\cdot)\) is \(i\) successive applications of \(h\) on \(ax_1\). However, this model may not work for all solutions of a constraint system.

**Example 6.5.** Consider the constraint system \(\mathcal{C} = (\mathcal{E}; \Phi; D; Eq)\) where:

- \(\mathcal{E} = \{a, c\}\)
• $\Phi = \{ ax_1 \triangleright a, ax_2 \triangleright senc(c, x) \}$

• $D = \{ X, 2 \vdash x; Y, 2 \vdash y \}$

• $Eq = \{ c \notin \text{sdec}(y, h(a)) \}$

Consider $\theta = \{ X \mapsto b_1, Y \mapsto ax_2 \}$ and $\sigma = \{ x \mapsto b_1, y \mapsto \text{senc}(c, b_1) \}$. We have that $(\sigma, \theta) \in \text{Sol}_\nu(C)$. Indeed, we trivially have $\text{Message}(\sigma)$, $\text{Message}(b_1)$ and $\text{Message}(\text{senc}(c, b_1))$. Furthermore, $\neg \text{Message}(\text{sdec}(\text{senc}(c, b_1), h(a)))$ since $\text{sdec}(\text{senc}(c, b_1), h(a))$ is in normal form. Thus $c \notin \text{sdec}(y, h(a))$ is satisfied by $\sigma$.

However, if we replace our replacement of free names introduced by the intruder, we obtain that $\theta' = \{ X \mapsto h(ax_1), Y \mapsto ax_2 \}$ and so $\sigma' = \{ x \mapsto h(a), y \mapsto \text{senc}(c, h(a)) \}$. Unfortunately $(\sigma', \theta') \notin \text{Sol}_\nu(C)$ since $\text{Message}(c)$, $\text{Message}(\text{sdec}(\text{senc}(c, h(a)), h(a)))$ and $c_\downarrow = \text{sdec}(\text{senc}(c, h(a)), h(a))$.

On the other hand, if we consider the replacement $b_k \mapsto h^{2 \times k}(ax_1)$, then we obtain that $\theta'' = \{ X \mapsto h(h(ax_1)), Y \mapsto ax_2 \}$ and so $\sigma'' = \{ x \mapsto h(h(a)), y \mapsto \text{senc}(c, h(h(a))) \}$. In such a case, $(\sigma'', \theta'') \in \text{Sol}_\nu(C)$.

As illustrated in Example 6.5, we cannot fix the replacement of the public names in advance when checking the symbolic equivalence. The replacement will depend on the solutions that we consider. Let $N$ be a positive integer. Let $a \in \mathcal{E}$. We denote $\sigma_{\nu, N, a}$ and $\theta_{\nu, N}$ the replacements defined for all $i \in \mathbb{N}^+$ by $b_i \sigma_{\nu, N, a} = h^{i \times N}(a)$ and $b_i \theta_{\nu, N} = h^{i \times N}(ax_1)$.

We now show that when checking the concrete symbolic equivalence of sets of constraint systems, we only have to consider the recipes of the intruder that do not contain names. Let's denote $\sim_{\tau(F, AX)}$ the concrete static equivalence where we only consider recipe $\xi, \xi' \in (F, AX)$, and let's denote $\approx_{\tau(F, AX)}$ the symbolic equivalence on concrete constraint systems which only consider the solution $(\sigma, \theta)$ with $f\text{names}(\theta) = \emptyset$, and rely on the static equivalence $\sim_{\tau(F, AX)}$. The proof of the following lemma can be found in Appendix C.6.

**Lemma 6.2.** Let $\Sigma$ and $\Sigma'$ two sets of constraint systems that contain constraint systems having the same structure. Assume that $\mathcal{E}$ is the common set of privates names in $\Sigma$ and $\Sigma'$. At last, assume that there exists $a \in \mathcal{E}$ such that for all $C \in \Sigma \cup \Sigma'$, $ax_3 \Phi = a$ with $\Phi$ the frame of $C$.

If $\Sigma \approx_{\tau(F, AX)} \Sigma'$ then for all $C \in \Sigma$, for all $(\sigma, \theta) \in \text{Sol}_\nu(C)$, there exists $N'$ such that for all $N > N'$, there exist $C' \in \Sigma'$ and a substitution $\sigma'$ such that $(\sigma', \theta) \in \text{Sol}_\nu(C')$ and $\nu\mathcal{E}, \Phi \sigma_{\nu, N, a} \sim_{\tau(F, AX)} \nu\mathcal{E}, \Phi' \sigma'_{\nu, N, a}$.

The previous lemma is not sufficient to prove that $\Sigma \approx_{\tau(F, AX)} \Sigma'$ implies $\Sigma \approx_{\tau} \Sigma'$. Indeed, we matched each solution of a constraint system in $\Sigma$ with a solution in a constraint system in $\Sigma'$ but the static equivalence does not correspond to the usual static equivalence $\sim_{\tau}$. Moreover, for two ground frames $\Phi$ and $\Phi'$, we do not necessarily have that $\nu\mathcal{E}, \Phi \sigma_{\nu, N, a} \sim_{\tau(F, AX)} \nu\mathcal{E}, \Phi' \sigma'_{\nu, N, a}$ implies $\nu\mathcal{E}, \Phi \sim_{\tau} \nu\mathcal{E}, \Phi'$.

**Example 6.6.** Let $\mathcal{E} = \{ a, c \}$. Let $\Phi = \{ ax_1 \triangleright a, ax_2 \triangleright senc(c, b_1) \}$ and $\Phi' = \{ ax_1 \triangleright a, ax_2 \triangleright senc(c, h(a)) \}$. Consider $\xi = \text{sdec}(ax_2, b_1)$. $\text{Message}(\xi \Phi)$ holds whereas $\text{Message}(\xi \Phi')$ does not hold. Hence $\Phi \neq \tau_{\nu} \Phi'$.

However, if we assume that $N = 1$, $\Phi \sigma_{\nu, 1, a} = \{ ax_1 \triangleright a, ax_2 \triangleright senc(c, h(a)) \}$ and $\Phi' \sigma_{\nu, 1, a} = \{ ax_1 \triangleright a, ax_2 \triangleright senc(c, h(a)) \}$. Since $\Phi \sigma_{\nu, 1, a} = \Phi' \sigma_{\nu, 1, a}$, we trivially have $\Phi \sigma_{\nu, 1, a} \sim_{\tau(F, AX)} \Phi' \sigma_{\nu, 1, a}$. On the other hand, if we assume that $N = 2$, then $\Phi \sigma_{\nu, 2, a} \neq \tau(F, AX) \Phi' \sigma_{\nu, 2, a}$.

Note that the previous example raises the same issues than Example 6.5. We cannot fix in advance the representation of names even for the static equivalence. However, we show in the next lemma how we obtain the static equivalence $\sim_{\tau}$ from $\sim_{\tau(F, AX)}$. (Proof in Appendix C.6)

**Lemma 6.3.** Let $\mathcal{E}$ be a set of private names. Let $\Phi$ and $\Phi'$ two ground frames with the same domain and $ax_1 \Phi = ax_1 \Phi' \in \mathcal{E}$. If for all $N'$, there exists $N > N'$ such that $\Phi \sigma_{\nu, N, a} \sim_{\tau(F, AX)} \Phi' \sigma_{\nu, N, a}$ then $\Phi \sim_{\tau} \Phi'$. 
Thanks to Lemmas 6.2 and 6.3, we can now show that ≈_s^2 is the same relation than ≈_{\mathcal{T}(F, AX)}.

**Lemma 6.4.** Let Σ and Σ′ two finite sets of constraint systems that contain constraint systems having the same structure. Assume that \(E\) is the common set of private names in Σ and Σ′. At last, assume that there exists a c ∈ \(E\) such that for all C ∈ Σ ∪ Σ′, ax_1 Φ = a with Φ the frame of C.

The following property holds:

\[ Σ \approx_s^2 Σ′ \text{ if, and only if, } Σ \approx_{\mathcal{T}(F, AX)} Σ′ \]

**Proof.** We first prove the right implication of the equivalence (⇒). Let C ∈ Σ and let (σ, θ) ∈ Sol_c(Σ) such that for all X ∈ dom(θ), \(\text{fnames}(Xθ) = \emptyset\). By hypothesis Σ ≈_s^2 Σ′ hence there exist C′ ∈ Σ′ and a substitution σ′ such that (σ′, θ) ∈ Sol_c(C′) and Φσ ≈_c Φσ′. We show that ν\(E.Φσ \sim_{\mathcal{T}(F, AX)} ν\(E.Φσ′\). Let ξ, ξ′ ∈ \(T(F, AX)\) such that param(ξ) ⊆ dom(Φσ) and param(ξ′) ⊆ dom(Φσ′). ξ, ξ′ ∈ \(T(F, AX)\) implies that ξ, ξ′ ∈ \(T(F, AX) ∪ N \setminus E\) and \(\text{fnames}(ξ, ξ′) ∩ E = \emptyset\). Since Φσ ≈_c Φσ′, we can deduce that Message(ξΦσ) is equivalent to Message(ξΦσ′); and if Message(ξΦσ) and Message(ξΦσ′) then Φσ↓ = Φσ′↓ is equivalent to Φσ′↓ = Φσ↓. Thus ν\(E.Φσ \sim_{\mathcal{T}(F, AX)} ν\(E.Φσ′\) and so the result holds.

The other inclusion of the symbolic equivalence ≈_{\mathcal{T}(F, AX)} is proved symmetrically.

We now prove the left implication (⇐). Let C ∈ Σ and let (σ, θ) ∈ Sol_c(Σ). For a constraint system C′, let’s denote Φ(C′) the frame of C′. Thanks to Lemma 6.2, there exists N′ such that for all N > N′, there exist C′ ∈ Σ′ and a substitution σ′ such that (σ′, θ) ∈ Sol_c(C′) and Φ(C)σσ_{E,N,a} ∼_{\mathcal{T}(F, AX)} Φ(C′)σ′σ_{E,N,a}. Hence, (\(N, C′, σ′, θ\)) ∈ Sol_c(C′) and Φ(C)σσ_{E,N,a} ∼_{\mathcal{T}(F, AX)} Φ(C′)σ′σ_{E,N,a} is an infinite set. However, Σ′ is a finite set of constraint systems thus there exists C′ ∈ Σ′ such that the set \(S_2 = \{(N, σ′, θ) ∈ \text{Sol}_c(C′) \text{ and } Φ(C)σσ_{E,N,a} ∼_{\mathcal{T}(F, AX)} Φ(C′)σ′σ_{E,N,a}\}\) is infinite. Furthermore, when C′ and θ are fixed, by definition of a solution of a constraint system, we have that for all σ_1, σ_2, (σ_1, θ) ∈ Sol_c(C′) and (σ_2, θ) ∈ Sol_c(C′) implies σ_1 = σ_2, i.e. the first order solution is fixed by the second order solution. Thus for all (N_1, σ_1), (N_2, σ_2) ∈ S_2, σ_1 = σ_2. It implies that there exists σ′ such that (σ′, θ) ∈ Sol_c(C′) and for all N > N′, there exists N > N′ such that Φ(C)σσ_{E,N,a} ∼_{\mathcal{T}(F, AX)} Φ(C′)σ′σ_{E,N,a}. Hence by Lemma 6.3 we conclude that Φ(C)σ ∼ Φ(C′)σ′.

The other inclusion of the symbolic equivalence ≈_s^2 is proved symmetrically.

### 6.3.2 Normalised recipe

In the previous subsection, we have shown that we do not have to consider public names in the recipes for the intruder, which reduces a lot the search space for the symbolic equivalence of constraint systems. We will see in this subsection that we can also ignore some recipes that always provide redundant informations for the intruder. Typically, assume that ξ_1, ξ_2 are two recipes such that for all ground frame Φ, their applications always produce the same result, i.e. ξ_1Φ↓ = ξ_2Φ↓, then these recipes will not help an intruder to distinguish one frame from another. Thus, we will not consider both recipes but only keep one.

**Example 6.7.** Let ξ_1, ξ_2, ξ_3 be the recipes such that:

1. \(ξ_1 = \text{proj}_1((\xi'_1, \xi''_1))\) for some \(\xi'_1, \xi''_1\);
2. \(ξ_2 = \text{adec}(\text{aecn}(\xi'_2, \xi''_2))\) for some \(\xi'_2, \xi''_2\);
3. \(ξ_3 = \text{check}(\text{secn}(\xi'_3, \xi''_3))\) for some \(\xi'_3, \xi''_3\).

In fact, for all frames Φ, \(ξ_1Φ↓ = ξ'_1Φ↓, ξ_2Φ↓ = ξ'_2Φ↓\) and \(\neg\text{Message}(ξ_3Φ)\). Since this is true for any frame, they do not provide new informations for the intruder that might help him distinguishing two sets of constraint systems. Hence we will only consider ξ'1 and ξ'2 and ignore ξ_1, ξ_2, ξ_3.

Following the Example 6.7 we define a new set of recipes, denoted \(\Pi_n\), and we show that it is complete and sound to only consider this new set of recipes when deciding the symbolic equivalence of sets of constraint systems.
Definition 6.5. We say that $\xi \in \mathcal{T}(\mathcal{F}, \mathcal{AX} \cup \mathcal{A}^2)$ is a normalised recipe if, and only if, for all $f(\xi_1, \ldots, \xi_n) \in \text{st}(\xi)$, $f \in \mathcal{F}_d$ implies that $\text{root}(\xi_1) \not\in \mathcal{F}_c$. We denote $\Pi_n$ the set of normalised recipes.

Even if the recipes in $\Pi_n$ are called normalised recipes, they do not exactly correspond to the normalisation of a recipe by the rewriting system. More specifically $\xi \in \Pi_n$ implies $\downarrow = \xi$ whereas the converse is not true.

Example 6.8. Consider the recipe $\xi = \text{check}(\text{sen}(ax_1, ax_2))$. $\xi$ is a recipe in normal form w.r.t. the rewriting system but $\xi \notin \Pi_n$.

Intuitively, $\mathcal{T}(\mathcal{F}, \mathcal{AX}) \triangleq \Pi_n$ represents all recipes that will either never provide the intruder with any new information or that will never satisfy the predicate $\text{Message}(\cdot)$. The predicate $\text{Message}(\cdot)$ is also easier to verify on the recipes in $\Pi_n$ as stated in the following lemma. (Proof in Appendix C.1).

Lemma 6.5. Let $\Phi$ be a ground frame such that for all $(ax_i \triangleright u_i) \in \Phi$, $\text{Message}(u_i)$. Let $\xi \in \Pi_n$ a ground recipe such that $\text{param}(\xi) \in \text{dom}(\Phi)$. $\xi', \Phi \in \mathcal{T}(\mathcal{F}_c, \mathcal{N})$ if, and only if, $\text{Message}(\xi')$ holds.

The following lemma shows that the intruder do not lose messages of a frame by only considering the recipes in $\Pi_n$. (Proof in Appendix C.1).

Lemma 6.6. Let $\Phi$ be a ground frame such that for all $(ax_i \triangleright u_i) \in \Phi$, $\text{Message}(u_i)$. Let $\xi \in \mathcal{T}(\mathcal{F}, \mathcal{N} \cup \mathcal{AX})$. If $\text{Message}(\xi')$ then there exists a ground recipe $\xi' \in \Pi_n$ such that $\xi\downarrow = \xi'\downarrow$, $\text{Message}(\xi')$ and $\text{param}(\xi') \subseteq \text{param}(\xi)$.

We denote $\sim_{\Pi_n}$ the static equivalence that only consider the recipe in $\Pi_n$. We show in the next lemma that the static equivalence is preserved when considering the recipes in $\Pi_n$. (Proof in Appendix C.1).

Lemma 6.7. Let $\Phi$ and $\Phi'$ be two ground frames such that for all $(ax_i \triangleright u_i) \in \Phi$ (resp. $\Phi'$), $\text{Message}(u_i)$. $\Phi \sim_{\mathcal{T}(\mathcal{F}, \mathcal{AX})} \Phi'$ is equivalent to $\Phi \sim_{\Pi_n} \Phi'$.

Note that in the previous lemma, we omitted the set of private names $\mathcal{E}$. Since we do not consider names in the recipe when checking the static equivalence, this set is not needed anymore thus we may ignore it. We denote $\approx_{\Pi_n}$ the symbolic equivalence of sets of concrete constraint systems where we only consider solutions $(\sigma, \theta)$ where for all $X \in \text{dom}(\theta)$, $X\theta \in \Pi_n$; and that rely on the static equivalence $\sim_{\Pi_n}$.

Lemma 6.8. Let $\Sigma$ and $\Sigma'$ two sets of constraint systems that contain constraint systems with the same structure. The following property holds:

$$\Sigma \approx_{\Pi_n}^{\mathcal{T}(\mathcal{F}, \mathcal{AX})} \Sigma' \text{ if, and only if, } \Sigma \approx_{\Pi_n} \Sigma'$$

Proof. The right implication of this equivalence ($\Rightarrow$) is rather simple. Indeed, for all $C \in \Sigma$, for all $(\sigma, \theta) \in \text{Sol}(C)$, if for all $X \in \text{dom}(\theta)$, $X\theta \in \Pi_n$ then for all $X \in \text{dom}(\theta)$, $X\theta \in \mathcal{T}(\mathcal{F}, \mathcal{AX})$. Hence with $\Sigma \approx_{\Pi_n}^{\mathcal{T}(\mathcal{F}, \mathcal{AX})} \Sigma'$, it implies that there exists $C' \in \Sigma'$ and a substitution $\sigma'$ such that$(\sigma', \theta) \in \text{Sol}(C')$ and $\Phi\sigma \sim_{\mathcal{T}(\mathcal{F}, \mathcal{AX})} \Phi'\sigma'$, where $\Phi$ (resp. $\Phi'$) is the frame of $C$ (resp. $C'$). By definition of a solution of a constraint system, $(\sigma, \theta) \in \text{Sol}(C)$ and $(\sigma', \theta) \in \text{Sol}(C')$ imply that for all $(ax_i \triangleright u_i) \in \Phi\sigma$ (resp. $\Phi'\sigma'$), $\text{Message}(u_i)$. Hence by Lemma 6.7, $\Phi\sigma \sim_{\Pi_n} \Phi'\sigma'$ which allows us to conclude.

We now focus on the left implication of this equivalence ($\Leftarrow$). Let $C = (C; \Phi; D; Eq) \in \Sigma$ and let $(\sigma, \theta) \in \text{Sol}(C)$ such that for all $X \in \text{dom}(\theta)$, $X\theta \in \mathcal{T}(\mathcal{F}, \mathcal{AX})$. We show by induction on $k$ that there exists $(\sigma', \theta')$ such that:

- for all $(X, i \triangleright x) \in D$, if $i \leq k$ then $(X\theta')((\Phi\sigma') = x\sigma'$, $\text{Message}(x\sigma')$, $x\sigma' \downarrow = x\sigma \downarrow$, $X\theta' \in \Pi_n$ and $\text{param}(X\theta') \subseteq \{ax_1, \ldots, ax_k\}$
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- for all \((ax_i > u_i) \in \Phi\), if \(i \leq k\) then \(u_i\sigma \downarrow = u_i\sigma'\downarrow\) and \(Message(u_i\sigma')\).

**Base case** \(k = 0\): This case is trivial since for all \((X, i \mapsto x) \in D\), for all \((ax_j > u_j) \in \Phi\), \(i > 0\) and \(j > 0\).

**Inductive step** \(k > 0\): In such a case, thanks to our induction hypothesis, we know that there exists \((\sigma', \theta')\) satisfying the above properties for \(k - 1\). Hence, we show how to extend \(\sigma'\) and \(\theta'\) for frame elements \((ax_k > u_k) \in \Phi\) and deducible constraint \((X, k \mapsto x) \in D\).

Let \((ax_k > u_k) \in \Phi\). By definition of a constraint system, we know that for all \(x \in \text{vars}^1(u_k)\), there exists \((X, i \mapsto x) \in D\) such that \(i < k\). By induction hypothesis, we know that \(x\sigma'\) is defined, \(Message(x\sigma')\) and \(x\sigma' \downarrow = x\sigma \downarrow\). Thus, we deduce that \(u_k\sigma \downarrow = u_k\sigma' \downarrow = u_k \sigma' \downarrow\). We now prove that \(Message(u_k\sigma')\). We already know by \((\sigma, \theta) \in \text{Sol}_i(C)\) that \(Message(u_k\sigma)\). Moreover, by our induction hypothesis, we also know that for all \(x \in \text{vars}^1(u_k)\), \(Message(x\sigma')\). Therefore \(Message(u_k\sigma')\) is equivalent to for all \(u \in \text{st}(u_k)\), \(u\sigma \downarrow \in \mathcal{T}(\mathcal{F}_c, \mathcal{N})\). But \(Message(u_k\sigma)\) implies that \(u\sigma \downarrow \in \mathcal{T}(\mathcal{F}_c, \mathcal{N})\). At last, since for all \(x \in \text{vars}^1(u) \subseteq \text{vars}^1(u_k)\), \(x\sigma' \downarrow = x\sigma \downarrow\), we deduce that \(u\sigma \downarrow = u\sigma' \downarrow\), and so \(u\sigma \downarrow \in \mathcal{T}(\mathcal{F}_c, \mathcal{N})\). Therefore, \(Message(u_k\sigma')\).

Let \((X, k \mapsto x) \in D\). We have proved that for all \((ax_i > u_i) \in \Phi\), if \(i \leq k\) then \(Message(u_i\sigma')\), \(Message(u_i\sigma)\) and \(u_i\sigma' \downarrow = u_i\sigma \downarrow\). Moreover, \((\sigma, \theta) \in \text{Sol}_i(C)\) implies that \(\text{param}(X\theta) \subseteq \{ax_1, \ldots, ax_i\}\). Hence \((X\theta)\phi \downarrow = (X\theta)(\phi \sigma)\downarrow\) and \(Message((X\theta)(\phi \sigma))\) implies that \(Message((X\theta)(\phi \sigma'))\). Thus by Lemma 6.6, there exists \(\xi \in \Pi\) such that \((X\theta)(\phi \sigma') \downarrow = (\xi (\phi \sigma))\downarrow\). We deduce that \(\text{param}(\xi) \subseteq \text{param}(X\theta)\). We deduce that \(\text{param}(\xi) \subseteq \{ax_1, \ldots, ax_i\}\), \(Message(\xi(\phi \sigma'))\) and \(\xi(\phi \sigma')\downarrow = (X\theta)(\phi \sigma)\downarrow\). By defining \(X\theta' = \xi\) and \(x\sigma' = \xi(\phi \sigma')\), the result holds.

We have shown that there exists \((\sigma', \theta') \in \text{Sol}_i(C)\) such that for all \(X \in \text{dom}(\theta')\), \(X\theta \in \Pi\); and for all \(x \in \text{dom}(\phi')\), \(x\sigma \downarrow = x\sigma' \downarrow\). Thanks to our hypothesis \(\Sigma \approx \Pi\), \(\Sigma'\), we deduce that there exists \(C' = (\xi; \phi'; D'; \phi\eta') \in \Sigma'\) and \(\sigma''\) a substitution such that \((\sigma'', \theta') \in \text{Sol}_i(C')\) and \(\Phi\sigma'' \approx \Pi\). \(\Phi\sigma''\). By Lemma 6.6, we deduce that \(\Phi\sigma' \approx \tau'(\mathcal{F}, \mathcal{A})\). \(\Phi\sigma''\). But for all \(X \in \text{dom}(\theta)\), \(Message((X\theta)(\phi \sigma'))\), \(Message((X\theta')(\phi \sigma'))\) and \(X\theta\phi \sigma' \downarrow = X\theta' \phi \sigma' \downarrow\). Thus by \(\Phi\sigma' \approx \tau'(\mathcal{F}, \mathcal{A})\), \(\Phi\sigma''\), we deduce that \(Message((X\theta)(\phi \sigma'))\) and \(X\theta(\phi \sigma'') \downarrow = X\theta'(\phi \sigma'') \downarrow\). Since \(\Phi\sigma' \downarrow = \phi \sigma' \downarrow\) and for all \(x \in \text{vars}^1(D)\), \(x\sigma \downarrow = x\sigma' \downarrow\), then we deduce that for all \(x \in \text{dom}(\theta)\), \(X\theta(\phi \sigma) \downarrow = X\theta'(\phi \sigma) \downarrow\). Therefore, thanks to \(\Phi\sigma' \approx \tau'(\mathcal{F}, \mathcal{A})\), \(\Phi\sigma''\), we deduce that \(X\theta(\phi \sigma'') \downarrow = X\theta'(\phi \sigma'') \downarrow\). Using the similar reasoning as when we showed that \((\sigma', \theta') \in \text{Sol}_i(C)\), we prove that there exists \(\phi \sigma''\) such that \((\theta, \sigma'') \in \text{Sol}_i(C')\) and for all \(x \in \text{dom}(\phi')\), \(x\sigma' \downarrow = x\sigma'' \downarrow\). At last, since \(\Phi\sigma' \downarrow = \phi \sigma' \downarrow\), \(\phi \sigma'' \downarrow = \phi \sigma'' \downarrow\), \(\Phi\sigma' \approx \tau'(\mathcal{F}, \mathcal{A})\), \(\Phi\sigma''\) and for all \((ax_i > u_i) \in \Phi\) (resp. \(\phi \sigma', \phi \sigma'', \phi \sigma'''\)), \(Message(u_i)\), we conclude that \(\Phi\sigma' \approx \tau'(\mathcal{F}, \mathcal{A})\), \(\Phi\sigma''\). Thus the result holds.

6.3.3 From concrete to constructor constraint systems

The definition of a solution of a concrete constraint system imposes that all first order terms in the constraint systems must be messages, except for terms in the inequations. Hence, when considering a solution \((\sigma, \theta)\) of a concrete constraint system, one could expect the terms in \(\sigma\) to be constructor terms. Moreover, given an equation \(u \equiv v\) in the constraint system, we will see that it is possible to check if this equation is unsatisfiable, or else to transform it into conjunction of equations that contain only constructor terms. Intuitively, by transforming the terms in our constraint systems into constructor terms, checking the predicate \(Message(\cdot)\) on the frame, equation and inequation will be much easier. Furthermore, since we only consider the recipes in \(\Pi\), for the solutions of our constraint systems, checking of the predicate \(Message(\cdot)\) will also become useless thanks to Lemma 6.5.

6.3.3.1 Narrowing

**Example 6.9.** Consider the equation \(sdec(x, a) \equiv y\). Let \(\sigma\) be a substitution on constructor terms such that \(Message(sdec(x, a))\), \(Message(y\sigma)\) and \(sdec(x, a) \downarrow = y\sigma \downarrow\). \(Message(sdec(x, a))\) implies
that $s_{dec}(xσ, a) ⊥ ∈ T(𝐹, N)$. Thus, it is only possible if there exists $u$ such that $xσ ⊥ = senc(u, a)$. Note that in this case, $s_{dec}(xσ, a) ⊥ = u$.

Hence, we want to replace the equation $s_{dec}(x, a) ⊽ = y$ by $E = (x ⊽ = senc(x′, a) ∧ x′ ⊽ = y)$ where $x′$ is a fresh variable. Note that since there is no more destructors in $E$, a substitution $σ$ on constructor terms satisfies $E$ if and only if $xσ′ = senc(x′σ′, a)$ and $x′σ′ = yσ′$. Thus, there is no need to check the predicate $Message(σ)$ or even normalisation, but only the syntactic equality which easier and faster.

In Example 6.9 we illustrate the transformation that we will apply on the equations in our constraint system. Simplifying the inequations of a constraint system requires the introduction of universal quantifiers.

Example 6.10. Coming back to Example 6.9, we saw that $s_{dec}(x, a) ⊽ = y$ can be replaced by the conjunction of equations $x ⊽ = senc(x′, a) ∧ x′ ⊽ = y$. Actually, $x′$ is (implicitly) existentially quantified: the formulas $s_{dec}(x, a) ⊽ = y$ and $∃x′.x′ ⊽ = senc(x′, a) ∧ x′ ⊽ = y$ are equivalent.

Hence if we now consider the inequation $s_{dec}(x, a) ⊽ = y$, one can replace it by the following formula:

$$∀x′.x′ ⊽ ≠ senc(x′, a) ∨ x′ ⊽ ≠ y$$

We introduce the notion of narrowing [JK91] that formalises the transformations applied on equations and inequations illustrated in Examples 6.9 and 6.10.

Definition 6.6 (Narrowing). Let $R$ be our set of rewriting rules. We define the narrowing as a binary relation on $T(F∪N,X)$, denoted $→_R$, such that: for all $s, t ∈ T(F∪N,X)$, $s →_R t$ if, and only if, there exists a non variable position $p$ of $s$ and a renaming of a rewriting rule $ℓ → r ∈ R$ such that $σ = mgu(ℓ, s_p)$ and $t = sσ[rσ]_p$.

In order to simplify the proof of correctness, soundness and termination of the transformation, we will only use the innermost strategy for the narrowing.

Example 6.11. Coming back to Example 6.9 $s_{dec}(x, a) σ →_R x′$ where $σ = \{x → senc(x′, a)\}$.

We extend the narrowing rule to a conjunction of equations between terms such that:

$$s σ ⊽ = v ∧ E σ →_R t σ ⊽ = v′ ∧ E′ σ$$

where $s σ →_R t$, $v′ = vσ$ and $E′ = Eσ$.

From now on, we confuse a substitution $σ = \{x_1 → u_1, \ldots, x_n → u_n\}$ with the associated conjunction of equation $x_1 ⊽ = u_1 ∧ \ldots ∧ x_n ⊽ = u_n$. Moreover, we denote $σ |= c u ⊽ = v$ when $Message(uσ)$, $Message(vσ)$ and $uσ ⊽ = vσ ⊽$. Similarly, we denote $⊩_c u ⊽ ≠ v$ when $¬Message(uσ)$, or $¬Message(vσ)$ or $uσ ⊽ ≠ vσ ⊽$. We extend $⊩_c$ naturally to conjunctions and disjunctions of equations and inequations with quantified variables. The following lemma shows the soundness and completeness of the narrowing rule on conjunction of equations. (Proof in Appendix C.1)

Lemma 6.9. Let $E$ and $E′$ be two conjunctions of equations between terms such that $E σ →_R E′ σ$. For all substitutions $τ$ on ground constructor terms,

- $τ ⊩_c E′ σ$ implies that $στ ⊩_c E$.
- $τ ⊩_c E σ$ implies that there exists $τ′$ such that $τ = (στ′)_{dom(τ)}$ and $τ′ ⊩_c E′ σ$.

We also extend the narrowing rule to formulas of the form $∀x \bigvee_{j=1}^m u_j ⊽ = v_j$ such that:

$$∀x.\bigvee_{j=1}^m u_j ⊽ = v_j σ →_R ∀y.\bigvee_{i=1}^n u_i′ ⊽ ≠ v_i′$$
where \( E = \bigwedge_{j=1}^{m} u_j \overset{?}{=} v_j, \sigma \land E' = \bigwedge_{j=1}^{m} u'_j \overset{?}{=} v'_j, E \rightarrow^\sigma E', \bar{y} = \bar{x} \cup (\text{vars}^1(\sigma) \setminus \text{vars}^1(E)) \).

The soundness and completeness of this narrowing rule is shown in the following lemma. (Proof in Appendix [C.1])

**Lemma 6.10.** Let \( \phi = \forall \bar{x} \forall_{j=1}^{m} u_j \not\overset{?}{=} v_j \) and \( \phi' = \forall \bar{y} \forall_{j=1}^{m} u'_j \not\overset{?}{=} v'_j \) two formulas such that \( \phi \rightarrow^\sigma \phi' \). For all substitutions \( \tau \) of constructor terms, \( \tau \vDash_c \phi \) if and only if \( \tau \vDash_c \phi' \).

### 6.3.3.2 Constructor constraint systems

We will use the narrowing on equations and inequations presented in the previous paragraph to build constraint systems that only contain constructor terms.

**Definition 6.7 (Constructor constraint system).** A constructive constraint system is either \( \bot \) or a tuple \( (\Phi; D; Eq) \) where:

- \( \Phi \) is a sequence of the form \( \{ ax_1 \vdash t_1, \ldots, ax_n \vdash t_n \} \) where \( t_i \) are constructor terms and \( ax_i \) are variables in \( AX \);

- \( D \) is a set of deducibility constraints of the form \( X, i \vdash u, n \leq n, X \in X^2 \) and \( u \) is a constructor term.

- \( Eq \) is a conjunction of formulas of the form \( u \overset{?}{=} v \) or \( \forall \bar{y} \forall_{j=1}^{m} u_j \not\overset{?}{=} v_j \) where \( u, v, u_j, v_j \) are constructor terms.

We also assume that following conditions are satisfied on a constructor constraint system:

1. each variable \( X \in X^2 \) occurs at most once in \( D \)

2. for every \( 1 \leq k \leq n \), for every \( x \in \text{vars}^1(t_k) \), there exists \( (X, i \vdash u) \in D \) such that \( x \in \text{vars}^1(u) \) and \( i < k \).

3. for each free variable \( x \) of \( Eq \), there exists \( (X, i \vdash u) \in D \) such that \( x \in \text{vars}^1(u) \).

Compared to Definition [1.3], a deducibility constraint allows constructor terms as right hand terms, whereas in Definition [1.3] we only allowed variables. Furthermore, \( Eq \) is more general than the conjunction of equations and inequations in Definition [1.3]. Note that we do not have the set of private names \( E \) in the definition of a constructor constraint system. Intuitively, we consider that all names that occur in a constructor constraint system are private and so \( E \) is omitted.

**Example 6.12.** Let \( C \) be the concrete constraint system \( (E; \Phi \cup \{ ax_4 \vdash t \}; D; Eq) \) where

- \( E = \{ sk_a, sk_{a'}, sk_b, n_b, n_a \} \),
- \( \Phi = \{ ax_1 \triangleright pk(sk_a), ax_2 \triangleright pk(sk_{a'}), ax_3 \triangleright pk(sk_b) \} \),
- \( t = \text{aenc}(\text{proj}_1(\text{adec}(y, sk_b)), \{ n_b, pk(sk_b) \}, pk(sk_a)) \),
- \( D = \{ Z_1, 3 \vdash z_1 x; Y, 3 \vdash y; Z_2, 3 \vdash z_2 \}; \) and
- \( Eq = \{ z_1 \overset{?}{=} c; \text{proj}_2(\text{adec}(y, sk_b)) \overset{?}{=} pk(sk_a); z_2 \overset{?}{=} c \} \).

The constructor constraint system \( C' \) associated to \( C \) is the triplet \( (\Phi' \cup \{ ax_5 \triangleright t' \}; D'; Eq') \) where

- \( \Phi' = \{ ax_1 \triangleright c, ax_2 \triangleright pk(sk_a), ax_3 \triangleright pk(sk_{a'}), ax_4 \triangleright pk(sk_b) \} \)
- \( D' = \{ Z_1, 4 \vdash c; Y, 4 \vdash \text{aenc}(\langle y', pk(sk_a) \rangle, pk(sk_b)); Z_2, 4 \vdash c \} \)
- \( t' = \text{aenc}(\langle y', \{ n_b, pk(sk_b) \}, pk(sk_a) \rangle) \)
• $Eq = \top$.

Note that as mentioned in Subsection [6.3.7], we put the free name $c$ in the frame.

We will denote $\sigma \models u =_? v$ when $w \sigma = v \sigma$. Moreover, we denote $\sigma \models u \neq v$ when $w \sigma \neq v \sigma$. We extend $\models$ naturally to conjunctions and disjunctions of (in)equalities with quantified variables.

**Definition 6.8** (solution of a constructor constraint system). A solution of a constructor constraint system $C = (\Phi; D; Eq)$ consists of a mapping $\sigma$ from $vars^1(D)$ to to ground constructor terms and a substitution $\theta$ mapping $vars^2(D)$ to ground recipes such that:

- for every $(x, k \overset{?}{\leftarrow} u) \in D$, we have $X\theta(\Phi_\sigma) \downarrow = x\sigma$ and $\text{param}(X\theta) \subseteq \{ax_1, \ldots, ax_k\}$.
- $\sigma \models Eq$

We denote Sol($C$) the set of solutions of $C$.

**Example 6.13.** Coming back to the Example 6.12, $(\sigma, \theta) \in \text{Sol}(C')$ where:

- $\sigma = \{y' \mapsto h(c)\}$
- $\theta = \{Z_1 \mapsto ax_1, Y \mapsto \text{aenc}(h(ax_1), ax_2), ax_4\}$

We can adapt the definition of static equivalence and symbolic equivalence to constructor frames and constraint systems.

**Definition 6.9** (static equivalence). Two ground constructor frames $\Phi$ and $\Phi'$ are statically equivalent, denoted $\Phi \sim \Phi'$, if and only if $\text{dom}(\Phi) = \text{dom}(\Phi')$ and for all $\xi, \xi' \in \Pi_n$, if $\text{param}(\{\xi, \xi'\}) \subseteq \text{dom}(\Phi)$ then

- $\xi\Phi \downarrow \in T(F_c, N)$ is equivalent to $\xi'\Phi' \downarrow \in T(F_c, N)$
- if $\xi\Phi \downarrow, \xi'\Phi' \downarrow \in T(F_c, N)$, then $\xi\Phi \downarrow = \xi'\Phi' \downarrow$ is equivalent to $\xi\Phi' \downarrow = \xi'\Phi' \downarrow$.

**Definition 6.10** (symbolic equivalence). Two sets $\Sigma$ and $\Sigma'$ of constructor constraint systems having the same structure are symbolically equivalent, denoted $\Sigma \approx_s \Sigma'$, if and only if for all $C \in \Sigma$, for all $(\sigma, \theta) \in \text{Sol}(C)$, there exists $C' \in \Sigma'$ and a substitution $\sigma'$ such that $(\sigma', \theta) \in \text{Sol}(C')$ and $\Phi\sigma \sim \Phi'\sigma'$ (and conversely for any $C' \in \Sigma'$) where $\Phi$ and $\Phi'$ are the respective frames of $C$ and $C'$.

As previously mentioned, we show the relation between symbolic equivalence of sets of constructor constraint system and the symbolic equivalence $\approx_s^{bs}$ of sets of concrete constraint system. (Proof in Appendix C.1)

**Lemma 6.11.** Let $\Sigma_1, \Sigma_1'$ two sets of concrete constraint systems having the same structure. There exist $\Sigma_2, \Sigma_2'$ two sets of constructor constraint systems having the same structure such that:

$$\Sigma_1 \approx_s^{bs} \Sigma_1'$$

if and only if $\Sigma_2 \approx_s \Sigma_2'$

We summarise what we proved along this section in the following theorem.

**Theorem 6.2.** Given a decision procedure for the symbolic equivalence of sets of constructor constraint systems, the problem of trace equivalence between two concrete processes is decidable.

The algorithm proceeds as follows: Given $A$ and $B$ two concrete processes with the same set of names. We first build the two concrete processes $A'$ and $B'$, that do not consider public names, by following Lemma 6.1. Second, we compute the sets $\text{trace}_a(A')$ and $\text{trace}_a(B')$ (possible since $A'$ and $B'$ do not contain replication). Third, we compute the set $S$ of pair of sets of constructor constraint systems such that:
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- if \((\text{tr}, \Sigma) \in \text{trace}_{cs}(A')\), \((\text{tr}', \Sigma') \in \text{trace}_{cs}(B')\) and \(\text{tr} = \text{tr}'\) then \((\Sigma, \Sigma') \in S\);

- if \((\text{tr}, \Sigma) \in \text{trace}_{cs}(A')\) (resp. \(\text{trace}_{cs}(B')\)) and for all \((\text{tr}', \Sigma') \in \text{trace}_{cs}(B')\) (resp. \(\text{trace}_{cs}(A')\)), \(\text{tr} \neq \text{tr}'\) then \((\Sigma, \emptyset) \in S\).

Four, for every \((\Sigma, \Sigma') \in S\), we compute the sets of constructor constraint systems \(\Sigma_1\) and \(\Sigma'_1\) from \(\Sigma\) and \(\Sigma'\) respectively by following the proof of Lemma 6.11. At last we apply the decision procedure for symbolic equivalence of sets of constructor constraint systems on \(\Sigma_1\) and \(\Sigma'_1\).

The soundness and completeness of this algorithm are ensured by Theorem 6.1 and Lemmas 6.1, 6.4, 6.8 and 6.11.

Note that adding \((\Sigma, \emptyset)\) in the set \(S\) does not necessary imply that \(A \not\approx_{\text{c}} B\). Indeed, it is possible that all constraint systems in \(\Sigma\) do not have any solution and in such a case, we would have \(\Sigma \approx_{\text{c}} \emptyset\).

The next chapter is devoted to a decision procedure for symbolic equivalence between two sets of constructor constraint systems.
This chapter is dedicated to the presentation of a decision algorithm for the symbolic equivalence between two sets of constructor constraint systems. The general idea of our decision algorithm is borrowed from earlier work on deducibility constraints: we simplify the constraints until we get a simple form, on which the equivalence problem should be easy. Since we consider pairs of (sets of) constraint systems, the simplification rules should be applied on both (sets of) systems at the same time; when this corresponds to guessing an attacker action, it should be the same rule, which is applied on both (sets of) systems. The second main difference concerns the equivalence checking: we have to keep track of an extended frame, recording some of the deductions of the attacker, and check the static equivalence of all instances, when the constraints are in solved form.

W.r.t. the previous constraint solving algorithms, there are many additional difficulties, which we will point along the chapter. One of the problems is that, when applying the rules in a naive way, the two constraint systems do not necessarily reach a solved form at the same time. So, we may need to apply further rules, even when one of the systems is in solved form, which causes termination issues.

Finally, along the algorithm, we guess for instance whether or not a key is deducible. This introduces negative deducibility constraints, which might be hard to solve. We turn around the difficulty, keeping track of previous choices (e.g., whether a key was deducible or not). This yields matrices of constraint systems: the rows correspond to sets of constraint systems, that share the same structure, but may yield different outputs of the protocol, and different rows correspond to
different guesses of deducibility along the constraint simplification. This complication in the syntax allows some simplifications in the algorithm, since we may take advantage of the bookkeeping of different rows.

Since the correctness, completeness and termination of our algorithm are rather technical, we delayed most of the proofs in the appendices, focusing on the algorithm itself. In the section 7.1 we introduce most of the definitions together with a few examples. The algorithm is explained in the section 7.2. We start with single constraint systems, before extending the rules to pairs of (sets of) constraint systems, and later matrices of constraint systems. Chapter 8 is dedicated to the proof of soundness, completeness and termination of the algorithm.

7.1 Preliminaries

As mentioned earlier, the general idea of our algorithm consists of simplifying the constraint system by applying simplification rules that guess for example an attacker action, or whether a key is deducible or not, . . . During the execution of these guesses, we need to be able to keep track of the results of these guesses. However, the definition of a constructor constraint system (Definition 6.7) is too restrictive to contain all the informations we need. For example, while guessing that a key sk is deducible might be represented by adding a deducible constraint \( X, i \vdash sk \), there is no way to represent, in a constraint system that follows Definition 6.7, that the key sk is not deducible. Therefore, we extend in this section the definitions of constructor constraint systems, frames, . . .

7.1.1 Extended frame

In previous chapters, a frame is used to record the sequence of messages (or terms in a symbolic execution) that have been sent by the participants of the protocol. We extend this notion to record some additional informations on attacker’s deductions. Typically \sdec(X, \xi), i \triangleright u \ records that, using a decryption with the recipe \xi, on top of a recipe \( X \), allows one to get \( u \) (at stage \( i \)). After recording this information in the frame, we may rely on this bookkeeping, and no longer consider a decryption on top of \( X \).

Definition 7.1 (extended frame). An extended frame \( \Phi \) (resp. a closed extended frame) is a sequence \( \{ \xi_1, i_1 \triangleright u_1; \ldots; \xi_n, i_n \triangleright u_n \} \) where:

- \( u_1, \ldots, u_n \) are constructor terms (resp. ground constructor terms),
- \( i_1, \ldots, i_n \) are integers, and
- \( \xi_1, \ldots, \xi_n \) are distinct general recipes (resp. ground recipes).

The domain of the extended frame \( \Phi \) is \( \text{dom}(\Phi) = AX \cap \{ \xi_1, \ldots, \xi_n \} \). It must be equal to \{\( ax_1, \ldots, ax_m \)\} for some \( m \). \( m \) is called the size of \( \Phi \). Moreover, an extended frame \( \Phi \) must satisfy that for all \( (\xi, i \triangleright u) \in \Phi \), if \( \xi = ax_j \) for some \( j \), then \( i = j \).

The indices \( i_1, \ldots, i_n \) represent the stages at which a message is known. An attacker could indeed distinguish two processes, simply because some message can be computed earlier in one of the process than in the other: the stage at which messages are available is a relevant information.

For a constructor frame \( \Phi = \{ ax_1 \triangleright u_1; \ldots; ax_m \triangleright u_m \} \), the stage is represented by the index of the parameter in \( AX \). Hence, the extended frame obtained from \( \Phi \) is the following: \( \{ ax_1, 1 \triangleright u_1; \ldots; ax_m, m \triangleright u_m \} \). Conversely, for an extended frame \( \Phi \) of size \( m \), We denote \( \text{Init}(\Phi) \) the constructor frame \( \{ ax_1 \triangleright u_1; \ldots; ax_m \triangleright u_m \} \) where for all \( i \in \{1, \ldots, m\}, (ax_i, i \triangleright u_i) \in \Phi \).

An extended frame \( \Phi \) of size \( m \) defines a substitution on \( \text{dom}(\Phi) \): if \( \text{dom}(\Phi) = \{ ax_1, \ldots, ax_m \} \) and, for \( i = 1, \ldots, m \), \( ax_i, j_i \triangleright v_i \), then we write again \( \Phi \) the substitution \( \{ ax_1 \mapsto v_1, \ldots, ax_m \mapsto v_m \} \). Note that the substitution \( \Phi \) and \( \text{Init}(\Phi) \) are the same. A closed extended frame \( \Phi \) is consistent if, for every \( (\xi, i \triangleright u) \in \Phi \), \( (\xi \Phi) \downarrow = u \).
Example 7.1. $\Phi = \{ ax_1, 1 \triangleright \text{senc}(a,b); ax_2, 2 \triangleright b; \text{sdec}(ax_1, ax_2), 2 \triangleright a; ax_3, 3 \triangleright a \}$ is a closed extended frame; the intermediate component records the deduction of a using the recipe $\text{sdec}(ax_1, ax_2)$ as early as stage 2. Moreover, $Init(\Phi) = \{ ax_1 \triangleright \text{senc}(a,b); ax_2 \triangleright b; ax_3 \triangleright a \}$.

Given two extended frames $\Phi$ and $\Phi'$, we say that $\Phi$ and $\Phi'$ are statically equivalent, denoted $\Phi \sim \Phi'$, if and only if their associated constructor frames $Init(\Phi)$ and $Init(\Phi')$ are statically equivalent, i.e., $Init(\Phi) \sim Init(\Phi')$.

From now on, we will always work on extended frames, and call them simplify "frame".

7.1.2 Extended constraint systems

As explained in Chapter 6, our constraint systems need not only to represent sets of traces, but also record some information on the attacker’s actions that led to these traces. That is why we also include equations between recipes and a set $\text{NoUse}$ of obsolete elements in the frame; roughly, a component of the frame is obsolete when the attacker used another recipe to get the message, at an earlier stage (as in the example 7.1). Finally, we also consider negated constraints, in order to enable splitting the set of traces into disjoint sets.

Definition 7.2 (extended constraint system). An extended constraint system is either $\bot$ or a tuple $(S_1; S_2; \Phi; D; Eq; Er; ND; \text{NoUse})$ where:

- $S_1$ (resp. $S_2$) is a set of variables in $\mathcal{X}^1$ (resp. $\mathcal{X}^2$);
- $\Phi$ is a frame, whose size is some $n$ and $\text{NoUse}$ is a subset of $\Phi$;
- $D$ is a set of deducible constraints of the form $X, i \vdash u$ with $1 \leq i \leq n$, $X \in \mathcal{X}^2$ and $u$ is a constructor term.
- $Eq$ is a conjunction of formulas of the form $u \equiv v$ or $\forall \bar{y}. \left[ \bigvee_{j=1}^{m} u_j \equiv v_j \right]$ where $u, v, u_j, v_j$ are constructor terms.
- $Er$ is a conjunction of formulas of the form $\zeta \equiv \zeta'$, or $\xi \neq \xi'$ or $\text{root}(\beta) \neq \ell$ where $\zeta, \zeta', \xi, \xi'$ and $\beta$ are recipe in $\Pi_n$, and $\ell$ is a constructor symbol.
- $ND$ is a conjunction of formulas of the form $\forall \bar{x}. [u \equiv v \lor \bigvee_{j} k \not\models w_j]$ where $u, v, w_j$ are constructor terms and $k \in \mathbb{N}$.

We say that an extended constraint system is initial if $\text{NoUse} = \emptyset$, $ND = \top$, $Er = \top$, $S_2 = \text{vars}^2(D)$, $S_1 = \text{vars}^1(D)$, $\text{vars}^1(Eq) \subseteq \text{vars}^1(D)$ and for all $(\xi, i \triangleright u) \in \Phi$, $\xi = ax_i$.

Intuitively, $S_1$ is the set of free variables in $\mathcal{X}^1$; we may have to introduce auxiliary variables, that will be (implicitly) existentially quantified, as well as (explicitly) universally quantified variables. Similarly, $S_2$ is a set of principal recipe variables (in $\mathcal{X}^2$) of the constraint. For readability, we will sometimes omit some of the components of the constraint system, because they are either straightforward from the context or empty.

We also assume the following conditions are satisfied on an extended constraint system:

1. each variable $X \in \text{vars}^2(D)$ occurs at most once in $D$;
2. for every $(\xi, i \triangleright u) \in \Phi$, for every $x \in \text{vars}^1(u)$, there exists $(X, j \triangleright v) \in D$ such that $x \in \text{vars}^1(v)$ and $j < i$;
3. for every $(\xi, i \triangleright u) \in \Phi$, $\text{param}(\xi) \subseteq \{ ax_1, \ldots, ax_i \}$ and for all $X \in \text{vars}^2(\xi)$, there exists $(X, j \triangleright v) \in D$ such that $j \leq i$. 
The second property corresponds to the origination property on first order variable whereas the third property represents the origination property for second order variables. Note that an initial extended constraint systems corresponds in fact to a constructor constraint system where \( S_1 \) and \( S_2 \) represent all the variables in the constraint systems.

The structure of an extended constraint system \( C = (S_1; S_2; \Phi; D; Eq; Er; ND; \text{NoUse}) \) is given by \( S_2, \emptyset, \{ (X, i) | X, i \not\in D \}, \{ (\xi, i) | \xi, i \not\in \Phi \} \) and \( \{ (\xi, i) | \xi, i \not\in \text{NoUse} \} \). Similarly to the structure of constructor constraint system, the structure of an extended constraint system indicates from which symbolic trace the constraint system is coming from but also indicates the guesses on the attacker’s actions.

Example 7.2. Coming back to Example 6.12, the extended constraint system \( C’ \) corresponding to the constructor constraint system \( C \) is the tuple \( (S_1; S_2; \Phi; D; Eq; Er; ND; \text{NoUse}) \) where

- \( \Phi = \{ ax_1, 1 \triangleright c, ax_2, 2 \triangleright pk(sk_a), ax_3, 3 \triangleright pk(sk_a), ax_4, 4 \triangleright pk(sk_b), ax_5, 5 \triangleright t \} \)
- \( D = \{ Z_1, 1 \triangleright c; Y, 4 \triangleright aenc(\langle y’, pk(sk_a) \rangle, pk(sk_b)); Z_2, 1 \triangleright c \} \)
- \( t = aenc(\langle y’, (u_v, pk(sk_b)) \rangle, pk(sk_a)) \)

with \( S_1 = \{ y’ \}, S_2 = \{ Z_1, Y, Z_2 \}, Eq = Er = ND = \top \) and \( \text{NoUse} = \emptyset \).

More examples will be given later.

In order to define what is a solution for such extended constraint systems, we have to give the semantics of the formulas ND, Eq and Er, and also to introduce the notion of path in order to cope with our generalised notion of frame. The formulas ND, Eq, Er are logic formulas built upon elementary formulas using classical connectives. The semantics for the elementary formulas are given below and is extended as expected to general formulas.

Definition 7.3 (solutions of side constraints). Let \( C \) an extended constraint system with \( \Phi \) its associated frame. Let \( \theta \) be a substitution mapping \( \text{vars}^2(C) \) to ground recipes, and \( \sigma \) be a substitution mapping \( \text{vars}^1(C) \) to ground constructor terms.

- \( \sigma \vdash (i \not\triangleright u) \) if and only if \( \xi(\Phi\sigma) \downarrow \neq u\sigma \downarrow \) for any ground recipe \( \xi \in \Pi_n \) with \( \text{param}(\xi) \subseteq \{ax_1, \ldots, ax_5\} \).
- \( \sigma \vdash u \not\triangleright v \) (resp. \( \not\triangleright v \)), if and only if \( u\sigma = v \sigma \) (resp. \( u\sigma \neq v \sigma \)).
- \( \theta \vdash \xi_1 \not\triangleright \xi_2 \) (resp. \( \theta \vdash \xi_1 \not\triangleright \xi_2 \)) if and only if \( \xi_1\theta = \xi_2\theta \) (resp. \( \xi_1\theta \neq \xi_2\theta \)).
- \( \theta \vdash \text{root}(\xi) \neq f \) if and only if \( \text{root}(\xi\theta) \neq f \)

Note that the semantics of the formulas Eq are identical to the ones used for constructor constraint system.

Example 7.3. Let \( \Phi = \{ ax_1, 1 \triangleright \text{senc}(a, x), ax_2, 2 \triangleright b \} \) and \( \sigma = \{ x \mapsto b \} \). Then \( \sigma \not\vdash (1 \not\triangleright a) \) and \( \sigma \not\vdash (2 \not\triangleright a) \).

There are possibly several ways to compute the same message, given a frame. All possibilities ways of computing such a message are the observable identities that are used in the static equivalence. We need only to consider an arbitrary (but fixed) way of computing a message, as early as possible, the other possible computations being captured by the static equivalence. In other words, if we want to check the symbolic trace equivalence, we need only to consider on the one hand the “canonical” recipes that are used by the attacker, and, on the other hand, the static equivalence of the frames. Assuming such a “canonical” recipe that computes a given message simplifies our proofs.
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Now, we can choose our recipe according to its path, which is the sequence of destructors applied on the leftmost arguments. This sequence determines the result, regardless of other arguments. Let us precise this point.

**Definition 7.4** (path). Let $\xi \in \Pi_n$ be such that $\text{root}(\xi) \notin F_r$. The path of $\xi$, denoted $\text{path}(\xi)$, is a word in $F_\alpha \cdot (\mathcal{A}\chi + \chi^2)$ that is recursively defined as follows:

- $\text{path}(ax) = ax$ when $ax \in \mathcal{A}\chi$,
- $\text{path}(X) = X$ when $X \in \chi^2$, and
- $\text{path}(f(\xi_1, \ldots, \xi_n)) = f \cdot \text{path}(\xi_1)$.

**Example 7.4.** Let $\xi = \text{sdec}(\text{sdec}(ax_2, ax_1), \text{sdec}(ax_1, ax_2))$ and $\xi' = \text{sdec}(\text{sdec}(ax_2, \text{proj}_2(ax_1)), ax_4)$. Then $\text{path}(\xi) = \text{path}(\xi') = \text{sdec} \cdot \text{sdec} \cdot ax_2$.

$\text{NoUse}$ is a subset of the frame whose use is forbidden, because we changed the canonical recipe. This happens only in the course of our algorithm when we discover that a message can actually be computed at an earlier stage. The following defines the restrictions on the recipes that we consider.

**Definition 7.5** ($\xi$ conforms to $\Phi$). Let $\Phi$ be a closed frame, $\text{NoUse}$ be a subset of $\Phi$, and $\xi$ be a ground recipe in $\Pi_n$. We say that $\xi$ conforms to the frame $\Phi$ w.r.t. $\text{NoUse}$ if:

- $\forall \xi \in \text{st}(\xi), \forall (\xi', i \triangleright u) \in \Phi, \text{path}(\xi) = \text{path}(\xi') \Rightarrow \xi' = \xi'$.
- $\forall (\xi, i \triangleright u) \in \text{NoUse}$, $\xi \notin \text{st}(\xi)$

**Example 7.5.** Let $\Phi = \{ ax_1, 1 \triangleright (a, b); ax_2, 1 \triangleright \text{senc}(a, b); \text{sdec}(ax_2, \text{proj}_2(ax_1)), 1 \triangleright a; ax_3, 2 \triangleright b; ax_4, 2 \triangleright a; ax_5, 3 \triangleright \text{senc}(c, a) \}$ and $\text{NoUse} = \{ ax_4, 2 \triangleright a \}$.

Implicitly here, we chose a canonical way to compute $a$, that is recorded in the frame: it consists in decrypting the second message with the second component of the first one. There are other ways of computing $a$, for instance using the first projection on the first message or using the fourth message. $\text{NoUse}$ forbids however this last use ($ax_4$ is not a recipe that conforms to $\Phi$ w.r.t. $\text{NoUse}$). This can be generated when an earlier (at stage 1 instead of stage 2) computation of $a$ is detected and recorded in the frame.

Furthermore, the recipe $\xi = \text{sdec}(ax_2, ax_3)$ does not conform to $\Phi$, while the recipe $\text{sdec}(ax_5, \text{proj}_2(ax_1))$ conforms to $\Phi$ w.r.t. $\text{NoUse}$.

Note that given an initial frame $\Phi$, i.e. $\text{Init}(\Phi) = \Phi$ and the set $\text{NoUse} = \emptyset$, every ground recipe in $\Pi_n$ conforms to $\Phi$ w.r.t. $\text{NoUse}$.

**Definition 7.6** (context w.r.t. $\Phi$). Let $\Phi$ be a frame and $\xi$ be a recipe in $\Pi_n$. The context of $\xi$ w.r.t. $\Phi$, denoted $C[\xi]_\Phi$, is a term in $T(F, F_\alpha \cdot \mathcal{A}\chi + \chi^2)$ and is defined recursively as follows:

- $C[\xi]_\Phi = \text{path}(\xi)$ if there exists $(\xi', i \triangleright u) \in \Phi$ such that $\text{path}(\xi) = \text{path}(\xi')$;
- $C[\xi]_\Phi = \xi$ if $\xi \in \chi^2$;
- $C[\xi]_\Phi = f(C[\xi_1]_\Phi, \ldots, C[\xi_n]_\Phi)$ if $\xi = f(\xi_1, \ldots, \xi_n)$.

For sake of clarity, when $\Phi$ is clear from the context, we denote it by $C[\xi]$.

The context of a recipe w.r.t. a frame represents part of the recipe that are not directly defined by the frame.

**Definition 7.7** (direct access mappings). Let $C = (S_1; S_2; \Phi; D; Eq; Er; ND; NoUse)$ be a constraint system. We define the direct access mapping of $C$, denoted $\text{acc}^1(C)$ (resp. $\text{acc}^2(C)$), to be a mapping from $(F_\alpha \cdot \mathcal{A}\chi + \chi^2)$ to constructor terms (resp. recipe in $\Pi_n$) where:

- for all $(X, i \triangleright u) \in D$, we have that $X\text{acc}^1(C) = u$ (resp. $X\text{acc}^2(C) = X$)
We denote by \( \varsigma \) a substitution \( \preceq \)-solution \( X\theta \) \( \Phi \). Moreover, if \( C \) is a constraint of the example 7.2. Consider the constraint of the example 7.5, together with possible solution is \( D = \{X, 1 \vdash \langle x, a \rangle ; Y, 2 \vdash \langle y \rangle \} \). Let \( \xi_1, \xi_2 \) and \( \xi_3 \) three recipes such that \( \xi_1 = \langle X, Y \rangle \), \( \xi_2 = \text{sdec}(ax_1, Y) \) and \( \xi_3 = \text{senc}(X, \text{sdec}(ax_1, ax_2)) \). We have:

- \( C[\xi_1] = \langle X, Y \rangle \) and \( C[\xi_1]\text{acc}^1(C) = \langle \langle x, a \rangle, b \rangle \)
- \( C[\xi_2] = \text{sdec} \cdot ax_1 \) and \( C[\xi_2]\text{acc}^1(C) = a \)
- \( C[\xi_3] = \text{senc}(X, \text{sdec} \cdot ax_1) \) and \( C[\xi_3]\text{acc}^1(C) = \text{senc}(\langle x, a \rangle, a) \)

Note that for all ground recipe \( \xi \) conforms to a ground frame \( \Phi \), \( C[\xi]\text{acc}^2(C) = \xi \). This illustrates the fact that the context of a recipe represents the canonical way to represent a recipe. Moreover, if \( \Phi \) is consistent then \( C[\xi]\text{acc}^1(C) \downarrow = \xi \Phi \).

**Definition 7.8 ((pre-)solution).** A solution of \( C = (S_1; S_2; \Phi; D; \text{Eq}; \text{Er}; \text{ND}; \text{NoUse}) \) consists of a substitution \( \sigma \) mapping \( \text{vars}^1(C) \) to ground constructor terms and a substitution \( \theta \) mapping \( \text{vars}^2(C) \) to ground recipes in \( \Pi_{\text{ND}} \), such that:

1. for every \( X \in \text{vars}^2(C) \), \( X\theta \) conforms to \( \Phi\theta \) w.r.t. \text{NoUse};
2. for every \( (X, i \vdash u) \in D \), \( X\theta(\Phi\sigma) \downarrow = u\sigma \downarrow \) and \( \text{param}(X\theta) \subseteq \{ax_1, \ldots, ax_i\} \);
3. \( \sigma \vdash \text{ND} \land \text{Eq} \) and \( \theta \vdash \text{Er} \).

We denote by \( \text{Sol}(C) \) the set of solutions of \( C \). By convention, \( \text{Sol}(\bot) = \emptyset \). A pair \( (\sigma, \theta) \) of substitutions that only satisfy the two first items is a pre-solution of \( C \).

From the definition of solutions of a constructor constraint system (Definition 6.2), we added the conditions on the conformity of the \( X\theta \) w.r.t. the frame and the satisfiability of \( \text{ND} \) and \( \text{Er} \).

**Example 7.7.** Consider the constraint of the example 7.3 (\( (\sigma, \theta) \in \text{Sol}(C') \)) where:

- \( \sigma = \{y' \mapsto h(c)\} \)
- \( \theta = \{Z_1 \mapsto ax_1, Y \mapsto a\text{enc}((h(ax_1), ax_2), ax_4), Z_2 \mapsto ax_1\} \)

**Example 7.8.** Consider the frame of the example 7.3 together with \( D = \{X, 3 \vdash \text{senc}(x, a)\} \), \( \text{Eq} = x \neq ax \lor x \neq b \land \forall y_1, y_2 (x \neq \langle y_1, y_2 \rangle) \land \forall y_1, y_2, (x \neq \text{senc}(y_1, y_2)) \) and \( \text{ND} = \text{Er} = \bot \). One possible solution is \( \sigma = \{x \mapsto c\}, \theta = \{X \mapsto \text{sdec}(ax_5, \text{sdec}(ax_2, \text{proj}_2(ax_1)))\} \)

From now on, we will only work with extended constraint system. Thus, similarly to frames, we will call constraint system an extended constraint system. Given a constraint system \( C \), we will sometimes denote \( S_2(C), S_1(C), \Phi(C), D(C), \ldots, \text{NoUse}(C) \) the different components of \( C \).

### 7.2 Simplifying a constraint system

As explained in the introduction, our algorithm that decides the equivalence of sets of constraint systems is based on transformations of such systems until a solved form is reached. We start by defining and explaining these rules on a single constraint system and then explain how it is extended to pairs of sets of constraint systems (see Section 7.3.1) and later to pairs of matrices of constraint systems (see Section 7.3.2).

The transformation rules are displayed in Figure 7.1 and Figure 7.2 for a single constraint system.
7.2. SIMPLIFYING A CONSTRAINT SYSTEM

7.2.1 The transformation rules

A simple idea would be to guess the top function symbol of a recipe and replace the recipe variable with the corresponding instance. When the head symbol of a recipe is a constructor and the corresponding term is not a variable, this is nice, since the constraint becomes simpler. This is the purpose of the rule Cons. When the top symbol of a recipe is a destructor, the constraint becomes more complex, introducing new terms, which yields non-termination. Our strategy is different. We do guess the top symbol of a recipe, when it is a constructor (or a parameter \( az_1 \)). Otherwise, we switch from the top position of the recipe to the redex position. Typically, in case of symmetric encryption, if a ciphertext is in the frame, we will guess whether the decryption key is deducible, and at which stage.

In the transformation rules described below, we only write the components of the constraint systems that are modified during an application of an instance of a rule.

\[
\text{Cons}(X, f) : S_2; X, i \vdash \; t; \text{Eq}; \text{Er} \quad \begin{cases}
S'_2; X_1, i \vdash x_1; \ldots; X_n, i \vdash x_n; \\
\Phi; \text{Eq} \land t \equiv f(x_1, \ldots, x_n); \text{Er} \land X \equiv f(X_1, \ldots, X_n); \\
X, i \vdash t; \text{Eq}; \text{Er} \land \text{root}(X) \neq f
\end{cases}
\]

where \( x_1, \ldots, x_n, X_1, \ldots, X_n \) are fresh variables, and
\( S'_2 = S_2 \cup \{X_1, \ldots, X_n\} \) if \( X \in S_2 \) and \( S'_2 = S_2 \) otherwise.

\[
\text{Axiom}(X, \text{path}) : \Phi; X, i \vdash u; \text{Eq}; \text{Er} \quad \begin{cases}
\Phi; \text{Eq} \land u \equiv v; \text{Er} \land X \equiv \xi \\
\Phi; X, i \vdash u; \text{Eq}; \text{Er} \land X \not\equiv \xi
\end{cases}
\]

If \( \Phi \) contains \( \xi, j \triangleright v \) with \( i \geq j \) then path(\( \xi \)) = path(\( \xi, j \triangleright v \)) \( \not\in \text{NoUse} \).

\[
\Phi; f(\xi, X_2, \ldots, X_n), i \triangleright w; \text{Eq} \land v \equiv u_1
\]

\[
\text{Dest}(\xi, l \rightarrow r, i) : \Phi; \text{Eq}; \text{ND} \quad \begin{cases}
X_2, i \vdash u_2; \ldots; X_n, i \vdash u_n; \text{ND} \\
\Phi; \text{Eq}; \text{ND} \land \forall \bar{x} \cdot [v \neq u_1 \lor i \not\triangleright u_2 \lor \ldots \lor i \not\triangleright u_n]
\end{cases}
\]

If \( \Phi \) contains \( \xi, j \triangleright v \) with \( j \leq i \) then (\( \xi, j \triangleright v \) \( \not\in \text{NoUse} \)). We denote by \( \bar{x} \) the set of variables that occur in \( f(u_1, \ldots, u_n) \rightarrow w \), a fresh renaming of \( l \rightarrow r \).

Figure 7.1: Transformation rules for satisfiability

The Cons rule simply guesses whether the top symbol of the recipe is a constructor \( f \). Either it is, and then we can split the constraint, or it is not and we add a inequation on the recipe forbidding it to start with \( f \).

In all the following examples, we apply eagerly some simplifications (such simplifications are formalised and explained in the section 7.2.2), and omit irrelevant parts of the constraint, in order to improve the readability.

Example 7.9. Consider the constraint system \( C'' = (S_1; S_2; \Phi; D; \text{Eq}; \text{Er}; \text{ND}; \text{NoUse}) \) of Example 7.2. Since \( (Y, 4 \equiv \text{aenc}(y', \text{pk}(sk_a)), \text{pk}(sk_b))) \in D \), the rule Cons(\( Y, \text{aenc} \)) can be applied to \( C'' \), guessing whether or not the attacker obtained the message \( \text{aenc}(x, y, \text{pk}(sk_b)) \) applying a public-key encryption on two previously computed messages. This yields the two constraints \( C_1 \) and \( C_2 \) where

\[
C_1 = \begin{cases}
S_2(C_1) : \{Z_1, X_1, X_2, Y, Z_2\} \\
D(C_1) : \{Z_1, 4 \equiv c; X_1, 4 \triangleright x_1; X_2, 4 \equiv x_2; Z_2, 4 \triangleright c\} \\
\text{Eq}(C_1) : \text{aenc}(x_1, x_2) \equiv \text{aenc}(y', \text{pk}(sk_a), \text{pk}(sk_b)) \\
\text{Er}(C_1) : Y \equiv \text{aenc}(X_1, X_2)
\end{cases}
\]
and
\[ C_2 = \begin{cases} 
D(C_2) : \{ Z_1, 4 \vdash c; Y, 4 \vdash \text{aenc}(y', \text{pk}(sk_a)), \text{pk}(sk_b)); Z_2, 4 \vdash c \} \\
\text{Er}(C_2) : \text{root}(Y) \neq \text{aenc} 
\end{cases} \]

The first constraint can be simplified, solving equations and performing replacements, which yields:
\[ C'_1 = \begin{cases} 
S_2(C_1) : \{ Z_1, X_1, X_2, Y, Z_2 \} \\
D(C_1) : \{ Z_1, 4 \vdash c; X_1, 4 \vdash (y', \text{pk}(sk_1)); X_2, 4 \vdash \text{pk}(sk_b); Z_2, 4 \vdash c \} \\
\text{Er}(C_1) : Y \not= \text{aenc}(X_1, X_2) 
\end{cases} \]

The rule \text{Axiom} also guesses whether a trivial recipe (a left member of the frame, typically an axiom \text{ax}_i) can be applied. If so, the constraint can simply be removed. Otherwise, we also add an inequation on recipe forbidding it.

\textbf{Example 7.10.} Continuing with the two constraints (respectively named \(C'_1\) and \(C_2\)), obtained in the previous example, \(C'_1\) yields, by application of \text{Axiom}(X_2, \text{ax}_4) two constraints systems \(C_{11}\) and \(C_{22}\).

\[ C_{11} = \begin{cases} 
D(C_{11}) : \{ Z_1, 4 \vdash c; X_1, 4 \vdash (y', \text{pk}(sk_1)); Z_2, 4 \vdash c \} \\
\text{Eq}(C_{11}) : \text{pk}(sk_1) \equiv \text{pk}(sk_b) \\
\text{Er}(C_{11}) : Y \not= \text{aenc}(X_1, X_2) \wedge X_2 \not= \text{ax}_4 
\end{cases} \]

and
\[ C_{12} = \begin{cases} 
D(C_{12}) : \{ Z_1, 4 \vdash c; X_1, 4 \vdash (y', \text{pk}(sk_1)); X_2, 4 \vdash \text{pk}(sk_1); Z_2, 4 \vdash c \} \\
\text{Er}(C_{12}) : Y \not= \text{aenc}(X_1, X_2) \wedge X_2 \not= \text{ax}_4 
\end{cases} \]

Again, the first constraint can be simplified into the constraint system \(C'_{11}\):

\[ C_{11} = \begin{cases} 
D(C_{11}) : \{ Z_1, 4 \vdash c; X_1, 4 \vdash (y', \text{pk}(sk_1)); Z_2, 4 \vdash c \} \\
\text{Er}(C_{11}) : Y \not= \text{aenc}(X_1, X_2) \wedge X_2 \not= \text{ax}_4 
\end{cases} \]

As already explained, the \text{Dest} rule is more tricky. If \(v\) is term of the frame, that can be unified with a non variable subterm of a left-hand side of a rewrite rule (for instance \(v\) is a ciphertext), we guess whether the rule can be applied to \(v\). This corresponds to the equation \(u_1 \equiv v\), that yields an instance of \(w\), the right member of the rewrite rule, provided that the rest of the left member is also deducible: in case of symmetric encryption, we get a constraint \(X_2, i \vdash Y\).

\textbf{Example 7.11.} Consider the constraint system \(C\), that includes the frame \(\Phi = \{ \text{ax}_1, 1 \vdash \text{senc}(a, b, c), \text{ax}_2, 2 \vdash \text{cax}_3, 3 \vdash \text{senc}(c, a) \}\) and the deducible constraints \(D = \{ X, 3 \vdash b \}\) (the other component being empty). Applying \text{Dest}(\text{ax}_1, \text{sdec}(\text{senc}(x, y)) \rightarrow x, 2)\), we get two constraint systems \(C_1\) and \(C_2\):

\[ C_1 = \begin{cases} 
\Phi(C_1) : \Phi \cup \{ \text{sdec}(\text{ax}_1, X_1), 2 \vdash x \} \\
D(C_1) : \{ X_2, 2 \vdash y; X, 3 \vdash b \} \\
\text{Eq}(C_1) : \text{senc}(x, y) \vdash \text{senc}(a, b, c) 
\end{cases} \]

and

\[ C_2 = \begin{cases} 
D(C_2) : \{ X, 3 \vdash b \} \\
\text{ND}(C_2) : \forall x, y. (\text{senc}(x, y) \not= \text{senc}(a, b, c) \lor 2 \vdash y) 
\end{cases} \]

Basically, we guess here whether the key \(c\) can be deduced at step 2. The second constraint is unsatisfiable, while the first one can be simplified to:

\[ \begin{cases} 
\Phi(C_1) = \Phi \cup \{ \text{sdec}(\text{ax}_1, X_1), 2 \vdash (a, b) \} \\
D(C_1) = \{ X_2, 2 \vdash c; X, 3 \vdash b \} 
\end{cases} \]
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Of course, these rules will not be applied without restriction, otherwise we would roughly enumerate all possible attackers recipes and, though this would be complete, this would certainly not terminate. For instance, we are not going to apply Cons(\(X, f\)) to \(X, i \vdash x\) when \(x\) is a variable (assuming \(x\) does not appear in another constraint), since the very same rule would apply to one of the resulting constraints.

Another set of rules, the equality rules of the figure \(\mathcal{C}\) guess equalities between right-hand sides of deducibility constraints and/or members of the frame. These rules do not correspond to attacker’s actions and they are not necessary if we are only interested in reachability properties. For equivalence properties, it is however necessary to ensure that the observable identities are the same on both systems.

Example 7.12. \(\Phi_1 = \{ ax_1, 1 \triangleright a; ax_2, 1 \triangleright k_1; ax_3, 2 \triangleright senc(x, k); ax_4, 3 \triangleright senc(senc(a, k_1), k)\}\) and \(\Phi_2 = \{ ax_1, 1 \triangleright a; ax_2, 1 \triangleright k_1; ax_3, 2 \triangleright senc(x, k); ax_4, 3 \triangleright senc(b, k)\}\). If \(x = senc(a, k_1)\), then the two frames are not statically equivalent since \(ax_2 = ax_3\) is an equality satisfied on the first frame and not on the second. If \(x \neq senc(a, k_1)\), then the two frames are statically equivalent.

If, for instance, the deducible constraint associated with both frames is \(X, 1 \vdash x\), then the rules of the figure \(\mathcal{C}\) will not help in finding the witness of non-equivalence.

Finally, the last transformation rule of figure \(\mathcal{C}\) guesses the deducible subterms of the frame, which allows to capture a static equivalence algorithm (such as in \textbackslash{AC06} as a particular case).

Example 7.13. Let us come back to the example \(\mathcal{C}\). Applying Eq\-left\-left\((ax_2, ax_3)\) to the constraint system whose frame is \(\Phi_1\), we get two constraint systems:

\[
\begin{align*}
\Phi(C_1) &= \Phi_1 \\
D(C_1) &= \{ X, 1 \vdash x \}
\end{align*}
\]

\[
\begin{align*}
\Phi(C_2) &= \Phi_1 \\
D(C_2) &= \{ X, 1 \vdash x \}
\end{align*}
\]

\[
\begin{align*}
Eq(C_1) &= senc(x, k) \triangleright senc(senc(a, k_1), k) \\
Eq(C_2) &= senc(x, k) \triangleright senc(senc(a, k_1), k)
\end{align*}
\]

And the case \(x = senc(a, k_1)\) is now distinguished from the case \(x \neq senc(a, k_1)\). We will see later how and why this is sufficient.

Example 7.14. Consider the two constraint systems \(\Phi_1 = \{ ax_1, 1 \triangleright a; ax_2, 2 \triangleright bax_3, 3 \triangleright x_1\}\), \(D_1 = \{ X, 1 \vdash x_1, \ Y, 2 \vdash x_1, \ Z, 3 \vdash y_1\}\), \(\Phi_2 = \{ ax_1, 1 \triangleright a; ax_2, 2 \triangleright bax_3, 3 \triangleright x_2\}\), \(D_2 = \{ X, 1 \vdash y_2, \ Y, 2 \vdash y_2, \ Z, 3 \vdash y_2\}\).

There are redundant constraints in each individual system. However, we need \(x_1 = y_1\) and \(x_2 = y_2\) in order to get equivalent systems, since the recipes \(X, Y\) must yield the same value, according to the first system (hence \(x_2 = y_2\)) and the recipes \(Y, Z\) yield the same value, according to the second system (hence \(x_1 = y_1\)). The rule Eq\-right\-right takes care of such situations: we guess whether different recipes yield the same value and record the result of the guess in the constraint.

Example 7.15. Consider the two constraint systems \(\Phi_1 = \{ ax_1, 1 \triangleright pk(sk_a), ax_2, 2 \triangleright aenc(x, pk(sk_a))\}\) and \(D_1 = \{ X, 1 \vdash x\}\) on the one hand and \(\Phi_2 = \{ ax_1, 1 \triangleright pk(sk_a), ax_2, 2 \triangleright aenc(b, pk(sk_a))\}\) and \(D_2 = \{ X, 1 \vdash x\}\) on the other hand.

Intuitively, the rules do not help in simplifying any further one of the two constraints. The only relevant possibility would be to try decrypting \(aenc(x, pk(sk_a))\), but the private key \(sk_a\) is not deducible. Though, the two constraint systems are not equivalent since the attacker can construct \(aenc(x, pk(sk_a))\) (using the recipe \(aenc(X, ax_1)\)) and therefore observe the identity \(aenc(X, ax_1) = ax_2\) on \(\Phi_1\), which is not possible on \(\Phi_2\).

This is the reason of the rule Ded-st, that guesses the subterms of the frame that can be constructed by the attacker. In the above example, the first constraint system would become

\[
\Phi_1, \{ X, 1 \vdash x; X_1, 2 \vdash x; X_2, 2 \vdash pk(sk_a)\}\]
\( \text{Eq-left-left}(\xi_1, \xi_2) : \quad \text{Eq} \quad \begin{array}{c} \iff \text{Eq} \wedge u_1 \equiv u_2 \\
\iff \text{Eq} \wedge u_1 \neq u_2 \end{array} \)

where \( \xi_1, i_1 \triangleright u_1, \xi_2, i_2 \triangleright u_2 \in \Phi \) for some \( \xi_1, \xi_2, i_1, i_2 \)

\( \text{Eq-left-right}(\xi_1, X_2) : \quad \text{Eq, NoUse} \quad \begin{array}{c} \iff \text{Eq} \wedge u_1 \equiv u_2, \text{NoUse} \cup (\xi_1, i_1 \triangleright u_1) \\
\iff \text{Eq} \wedge u_1 \neq u_2, \text{NoUse} \end{array} \)

where \( \xi_1, i_1 \triangleright u_1 \in \Phi \) and \( X_2, i_2 \vdash u_2 \in D \), with \( i_2 < i_1 \) and \( X_2 \in S_2 \) for some \( \xi_1, \xi_2, u_1, u_2 \)

\( \text{Eq-right-right}(X, \xi) : \quad \text{X, } i \vdash u; \text{ Eq; Er} \quad \begin{array}{c} \iff \text{Eq} \wedge u \equiv v; \text{ Er } X \equiv \xi \\
\iff \text{X, } i \vdash u; \text{ Eq} \wedge u \equiv v; \text{ Er} \end{array} \)

where \( \xi \in T(F_c, \text{dom}(\alpha)) \) and \( v = \xi \alpha \) with \( \alpha = \{Y \rightarrow w \mid (Y, j \vdash w) \in D \wedge j \leq i \wedge Y \in S_2\} \)

Moreover, we assume that:

- if \( \text{root}(\xi) = f \) then \( \text{Er} \not\models \text{root}(X) \neq f \)

- if \( \xi = Y \) then for all \( f \in F_c, \text{Er} \models \text{root}(X) \neq f \) is equivalent to \( \text{Er} \models \text{root}(Y) \neq f \).

\( \text{Ded-st}(\xi, f) : \quad \text{Eq; Nd} \quad \begin{array}{c} \iff \Phi; \text{ X, } m \vdash x_1; \ldots; \text{ X, } m \vdash x_n; \text{ Eq} \wedge u \equiv f(x_1, \ldots, x_n); \text{ Nd} \\
\iff \Phi; \text{ Eq} \end{array} \)

\( \text{Nd} \wedge \forall \bar{x} \cdot [u \neq f(x_1, \ldots, x_n) \lor m \not\models x_1 \lor \ldots \lor m \not\models x_n] \)

If \( \Phi \) contains \( \xi, i \triangleright u \) and \( (\xi, i \triangleright u) \not\in \text{NoUse} \). The sequences \( \bar{x} = x_1, \ldots, x_n \), and \( X_1, \ldots, X_n \) are sequences of fresh variables and \( m \) represents the maximal index that occurs in \( C \).

Figure 7.2: Additional transformation rules for static equivalence

\((\text{the other branch is unsatisfiable}), \text{ while on the second constraint we get}\)

\( \Phi_2, \{X, 1 \vdash x; X_1, 2 \vdash b; X_2, 2 \vdash pk(sk_a)\} \)

Eventually, this last constraint will be proven unsatisfiable, witnessing the non-equivalence of the constraint systems.

Now, before explaining how to apply the rules on pairs of sets of constraint systems, we formalise what we used implicitly in our examples: the constraints are normalised after each transformation step. Next, we define a simple strategy called \textit{strong strategy}, which is sufficient for trace properties, but has to be slightly relaxed for equivalence properties, as we will see in the section 7.3.4.

7.2.2 Normalisation

The normalisation consists mainly in simplifying the equations and inequations and performing the replacements when relevant.

The normalisation rules are displayed in the figure 7.3. As usual, substitutions are confused with solved conjunctions of equations. We also switch sometimes the order of the components of
a constraint, in order to ease the display and omit irrelevant parts of the constraint.

If we do not apply repeatedly the same rule in the same way, the rules of the figure 7.3 terminate on any constraint system.

Now, there are situations in which it is clearly not necessary to apply some rules. We say that CONS(⟨X, f⟩) (resp. AXIOM(⟨X, path⟩)) is useless on a constraint C if it is not applicable or its application results in two constraints C₁ and C₂ such that C₁ simplifies to ⊥ using the rules of the figure 7.3 and C₂ simplifies to C using these rules. Similarly, DEST(⟨ξ, l → r, i⟩) is useless on a constraint C if it has been already applied with the same instance:

- either the frame Φ(C) contains f(ξ, ξ₂, …, ξₙ), j ⊳ w and j ≤ i and root(l) = f
- or ND contains ∀x.(v ̸= u₁ ∨ i ⊳ u₂ ∨ • • • ∨ i ⊳ uₙ), (ξ, j ⊳ v) is in Φ and f(u₁, …, uₙ) → w is a renaming of l → r.
- or Φ does not contain any ξ, j ⊳ v with j ≤ i and (ξ, j ⊳ v) ̸∈ NoUse

We further apply two simplification rules, that are displayed in the figure 7.4.

Intuitively, the first rule states that, in order to deduce a message, the attacker has either

\[ x \text{ belongs to a name, or } \text{it has to be deducible and cannot be obtained from the frame.} \]

Indeed, we have assumed that all public names are explicitly disclosed in the frame (see Chapter 6).

Intuitively, the second rule states that, in order to deduce a message, the attacker has either to construct it from deducible messages, or retrieve it from the frame and deducible messages. In other words, any attacker’s ground recipe is built on F_e, F_d and the axⱼ.

**Definition 7.9** (normalization). *If C is a constraint system, we let C ↓ be an irreducible form of C, w.r.t. the rules of the figures 7.3 and 7.4.*

In what follows we will therefore assume that every constraint system is eagerly normalised.

### 7.2.3 A strong strategy

In the previous subsection, we described that sometimes, it is not necessary to applied the rules DEST, AXIOM and CONS, thus we defined the notion of a rule being useless for a constraint system. In fact, in order to ensure termination, we have to define the condition of uselessness for all the rules in Figure 7.2.

**Example 7.16.** Consider the constraint system C composed of the deducible constraint D = {X, 2 ⊳ x} and the frame Φ = {ax₁, 1 ⊳ a; ax₂, 2 ⊳ senc(a, b); ax₃, 3 ⊳ senc(x, b)}. The application of the rule EQ-LEFT-LEFT(ax₂, ax₃) on C yields two constraint system C₁ and C₂ such that:

\[
C₁ = \left\{ \begin{array}{l}
D(C₁) : \{X, 1 \vdash a\} \\
Φ(C₁) : \{ax₁, 1 \vdash a; ax₂, 2 \vdash \text{senc}(a, b); ax₃, 3 \vdash \text{senc}(a, b)\} \\
Eq(C₁) : X = a
\end{array} \right.
\]

and

\[
C₂ = \left\{ \begin{array}{l}
D(C₂) : \{X, 1 \vdash x\} \\
Φ(C₂) : \{ax₁, 1 \vdash a; ax₂, 2 \vdash \text{senc}(a, b); ax₃, 3 \vdash \text{senc}(x, b)\} \\
Eq(C₂) : x \neq a
\end{array} \right.
\]

However, the rule EQ-LEFT-LEFT(ax₂, ax₃), as described in Figure 7.2, can still be applicable on both constraint systems C₁ and C₂. However, the application of EQ-LEFT-LEFT(ax₂, ax₃) on C₁ yields, after normalisation, the constraint systems C₁ and ⊥. Similarly, the application of EQ-LEFT-LEFT(ax₂, ax₃) on C₂ yields, after normalisation the constraint systems ⊥ and C₂. Hence, to ensure the termination, we have to discard this kind of rule application.
\[ \Phi; D; Er; ND; NoUse; Eq \land \bigwedge_{i=1}^{n} u_i \stackrel{\gamma}{=} v_i \implies \Phi \sigma; D \sigma; Er; ND \sigma; NoUse \sigma; Eq \sigma \land \sigma \] (Nuni1)
\[ \text{if } \sigma = \text{mgu}(\bigwedge_{i=1}^{n} u_i \stackrel{\gamma}{=} v_i) \]
\[ \Phi; D; Er; ND; NoUse; Eq \land \bigwedge_{i=1}^{n} u_i \stackrel{\gamma}{=} v_i \implies \bot \] (Nins1)
\[ \text{if } \text{mgu}(\bigwedge_{i=1}^{n} u_i \stackrel{\gamma}{=} v_i) = \bot \]
\[ \Phi; D; Eq; ND; NoUse; Er \land \bigwedge_{i=1}^{n} \zeta_i \stackrel{\gamma}{=} \xi_i \implies \Phi \theta; D; Eq; ND; NoUse \theta; Er \theta \land \theta \] (Nuni2)
\[ \text{if } \theta = \text{mgu}(\bigwedge_{i=1}^{n} \zeta_i \stackrel{\gamma}{=} \xi_i) \]
\[ \Phi; D; Eq; ND; NoUse; Er \land \bigwedge_{i=1}^{n} \zeta_i \stackrel{\gamma}{=} \xi_i \implies \bot \] (Nins2)
\[ \text{if } \text{mgu}(\bigwedge_{i=1}^{n} \zeta_i \stackrel{\gamma}{=} \xi_i) = \bot \]
\[ Eq \land \forall \bar{x}.[\bigvee_{i=1}^{n} u_i \neq v_i] \implies Eq \] if \( \text{mgu}(\bigvee_{i=1}^{n} u_i \neq v_i) = \bot \) (Nneq1)
\[ Eq \land \forall \bar{x}.[Eq' \lor u \neq u'] \implies Eq \land \forall \bar{x}.Eq' \] (Nt1)
\[ Eq \land \forall \bar{x}.[Eq' \lor \bar{x} \neq u] \implies Eq \land \forall \bar{x} \setminus \{x\}.Eq' \sigma \]
\[ \text{if } x \in \bar{x} \setminus \text{vars}(u) \text{ and } \sigma = \{x \rightarrow u\} \] (Nelim1)
\[ Eq \land \forall \bar{x} \forall \bar{x}.Eq' \implies Eq \land \forall \bar{x}.Eq \] where \( x \notin \text{vars}(Eq) \) (Nelim2)
\[ Eq \land \forall \bar{x}.[Eq' \lor f(u_1, \ldots, u_n) \neq f(v_1, \ldots, v_n)] \implies Eq \land \forall \bar{x}.[Eq' \lor \bigvee_{i=1}^{n} u_i \neq v_i] \] (Nspl1)
\[ Eq \land u \neq v \land \forall \bar{x}.[Eq' \lor u \neq v] \implies Eq \land u \neq v \] (Nd)
\[ Er \land \zeta \neq \xi \implies Er \] if \( \text{mgu}(\zeta, \xi) = \bot \) (Nneq2)
\[ Er \land \zeta \neq \zeta \implies \bot \] (Nt2)
\[ Er \land \text{root}(f(\xi_1, \ldots, \xi_n)) \neq f \implies \bot \] (Ntop1)
\[ Er \land \text{root}(f(\xi_1, \ldots, \xi_n)) \neq g \implies Er \] if \( f \neq g \) (Ntop2)

Figure 7.3: Simplification rules for formula on terms

\[ Eq \land \forall \bar{x}.[Eq' \land x \neq a] \implies Eq \] (Nname)
\[ \text{if } a \in \mathcal{N}, (X, i \mapsto x) \in D, \text{Axiom}(X, \text{path}) \text{ is useless for any path and} \]
\[ \text{DEST}(\xi, l \rightarrow r, i) \text{ is useless for any } \xi, l \rightarrow r, \text{ and} \]
\[ \text{for all } (\zeta, j \rightarrow v) \in \Phi, j \leq i \text{ and } v \in \mathcal{X}^1 \text{ implies } (\zeta, j \rightarrow v) \in \text{NoUse} \]

\[ D \land X, i \vdash u \implies \bot \] (Nnosol)
\[ \text{if } \text{root}(u) = f, \text{CONS}(X, f) \text{ is useless, } \text{Axiom}(X, \text{path}) \text{ is useless for any path and} \]
\[ \text{DEST}(\xi, l \rightarrow r, i) \text{ is useless for all } \xi, l \rightarrow r \text{ and} \]
\[ \text{for all } (\zeta, j \rightarrow v) \in \Phi, j \leq i \text{ and } v \in \mathcal{X}^1 \text{ implies } (\zeta, j \rightarrow v) \in \text{NoUse} \]

Figure 7.4: Two additional simplification rules
Let $\mathcal{C} = (S_1; S_2; \Phi; D; Eq; Er; ND; NoUse)$ be a constraint system. We say that the rules $\text{Eq-left-left}(\xi_1, \xi_2)$, $\text{Eq-left-right}(\xi_1, X_2)$ and $\text{Eq-right-right}(X, \xi)$ are useless on the constraint system $\mathcal{C}$ if their application on $\mathcal{C}$ yields, after normalisation, the constraint systems $\mathcal{C}$ and $\bot$. Moreover, we say that the rule $\text{Ded-st}(\xi, f)$ is useless on the constraint system $\mathcal{C}$ if:

- either there exists $X_1, \ldots, X_n \in \text{vars}^2(\mathcal{C})$ such that $\mathcal{C}[f(X_1, \ldots, X_n)\theta]\text{acc}^1(\mathcal{C}) = u$ with $(\xi, j \triangleright u)$ is in $\Phi$, $\theta$ is the most general unifier of the equation in $Er$.
- or $ND$ contains $\forall \bar{x}.(u \neq f(x_1, \ldots, x_n) \lor m \neq x_1 \lor \cdots \lor m \neq x_n)$, $(\xi, j \triangleright u)$ is in $\Phi$, $x_1, \ldots, x_n$ are fresh variables and $m = |\Phi|$.
- or $\Phi$ does not contain any $(\xi, j \triangleright u)$ and $(\xi, j \triangleright u) \notin \text{NoUse}$

Intuitively, the condition of uselessness of the rule $\text{Ded-st}(\xi, f)$ describe the fact that this rule was already applied or does not need to be applied. The complexity of the first condition comes from the fact that while the rule $\text{Ded-st}$ creates new deducible constraints, these same deducible constraints might be instantiated later on by other rules such as $\text{Cons}$ or $\text{Axiom}$.

**Example 7.17.** Consider the constraint system $\mathcal{C}$ in Example 7.16. The application of the rule $\text{Ded-st}(ax_3, \text{senc})$ on $\mathcal{C}$ yields, after normalisation, two constraint systems $\mathcal{C}_1$ and $\mathcal{C}_2$ such that:

$$
\mathcal{C}_1 = \left\{ \begin{array}{l}
D(\mathcal{C}_1) : \{X, 1 \vdash a; X_1, 3 \vdash x; X_2, 3 \vdash b\} \\
\Phi(\mathcal{C}_1) : \{ax_1, 1 \triangleright a; ax_2, 2 \triangleright \text{senc}(a, b); ax_3, 3 \triangleright \text{senc}(x, b)\}
\end{array} \right.
$$

and

$$
\mathcal{C}_2 = \left\{ \begin{array}{l}
D(\mathcal{C}_1) : \{X, 1 \vdash x\} \\
\Phi(\mathcal{C}_1) : \{ax_1, 1 \triangleright a; ax_2, 2 \triangleright \text{senc}(a, b); ax_3, 3 \triangleright \text{senc}(x, b)\}
\end{array} \right.
$$

The rule $\text{Ded-st}(ax_3, \text{senc})$ is useless on $\mathcal{C}_2$ due to the non deducible constraint, and is useless on $\mathcal{C}_1$ since $\mathcal{C}[\text{senc}(X_1, X_2)]\Phi(\mathcal{C}_1)\text{acc}^1(\mathcal{C}_1) = \text{senc}(x, b)$. Now, if we apply the rule $\text{Axiom}(X_1, ax_2)$ on $\mathcal{C}_2$, we obtain two new constraint systems where one of these is the following:

$$
\mathcal{C}_3 = \left\{ \begin{array}{l}
D(\mathcal{C}_3) : \{X, 1 \vdash a; X_2, 3 \vdash b\} \\
\Phi(\mathcal{C}_3) : \{ax_1, 1 \triangleright a; ax_2, 2 \triangleright \text{senc}(a, b); ax_3, 3 \triangleright \text{senc}(\text{senc}(a, b), b)\}
\end{array} \right.
$$

The rule $\text{Ded-st}(ax_3, \text{senc})$ is useless on $\mathcal{C}_3$ since $\mathcal{C}[\text{senc}(X_1, X_2)]\Phi(\mathcal{C}_3)\text{acc}^1(\mathcal{C}_3) = \text{senc}(\text{senc}(a, b), b)$ with $\theta_3 = \{X_1 \mapsto ax_2\}$.

Discarding the useless application of a rule allows us to avoid some of the trivial termination problem (such as infinite application of $\text{Eq-left-left}$). However, some of the rules, even without being useless on a constraint system, may yield some simple termination problems.

**Example 7.18.** Consider the constraint system $\mathcal{C}$ composed of the deducible constraint $D = \{X, 1 \vdash x\}$ and the frame $\Phi = \{ax_1, 1 \triangleright a; ax_2, 2 \triangleright x\}$. The application of the rule $\text{Cons}(X, \text{senc})$ yields the following constraint system $\mathcal{C}_1$:

$$
\mathcal{C}_1 = \left\{ \begin{array}{l}
D(\mathcal{C}_1) : \{X_1, 1 \vdash x_1; X_2, 1 \vdash x_2\} \\
\Phi(\mathcal{C}_1) : \{ax_1, 1 \triangleright a; ax_2, 2 \triangleright \text{senc}(x_1, x_2)\}
\end{array} \right.
$$

$$
\text{Er}(\mathcal{C}_1) : X_1 \equiv ax_2
$$

$$
\text{Eq}(\mathcal{C}_1) : x_1 \equiv \text{senc}(X_1, X_2)
$$
Since we obtained once again a constraint system which a deducible constraint with a variable as right hand term, we can apply the rule Cons once again, thus leads to a termination problem.

Similarly, the application of the rule Dest\((ax_2, \text{adec}(a_{\text{enc}}(x, \text{pk}(y)), y) \rightarrow x, 2)\) yields the following constraint system \(C_2\):

\[
C_2 = \left\{
\begin{array}{l}
D(C_2) : \left\{ X, 1 \vdash x; X_2, 1 \vdash x_2 \right\} \\
\Phi(C_2) : \left\{ ax_1, 1 \triangleright a; ax_2, 2 \triangleright \text{aenc}(x_1, \text{pk}(x_2)); \text{adec}(ax_2, Y_2), 2 \triangleright x_1 \right\} \\
Eq(C_2) : x_? = \text{aenc}(x_1, \text{pk}(x_2))
\end{array}
\right.
\]

Hence the rule Dest can be applied once again on \(\text{adec}(ax_2, Y_2)\) which leads to a termination problem.

Let \(C = (S_1; S_2; \Phi; D; Eq; Er; ND; \text{NoUse})\) be a constraint system. We say that a rule is applicable on \(C\) when all the conditions needed to apply the rule are fulfilled (see Figure 7.1 and 7.2).

To avoid the termination issues illustrated in Example 7.18, we need to consider some additional requirements. We say that a rule can be strongly applied, or is strongly applicable, when it is not useless on \(C\) and when:

- the rule is Cons\((X, f)\) and either the term \(t\) is not a variable, or there exists an atomic statement \((\text{root}(X) \neq g)\) in \(Er\) such that \(g \in F_c\) and \(g \neq f\);
- the rule is Axiom\((X, \text{path})\) and the term \(v\) is not a variable or there exists \(f \in F_c\) such that \((\text{root}(X) \neq f)\) in \(Er\);
- the rule is Dest and the term \(v\) is not a variable;
- the rule is Ded-st and the term \(u\) is not a variable;
- the rule is Eq-left-left (with no additional condition);
- the rule is Eq-left-right and the terms \(u_1, u_2\) are the same variable.
- the rule is Eq-right-right and \(\xi \in \text{vars}^2(D)\) and \(u = v\), i.e. \(u\) and \(v\) are the same variable.

We will see in the next subsection that our strategy will require to weakened at some point the conditions of strong application of some rules, i.e. Cons, Axiom and Eq-right-right.

### 7.3 Simplifying sets of constraint systems

In the previous subsection, we describe how our transformation rules can be used to transform a single constraint system into two constraint systems. However, since we want to decide the symbolic equivalence of sets of constraint systems, we have to describe how to apply our rules on such sets.

#### 7.3.1 From constraint system to vectors

In fact, for our algorithm, it is crucial to order the constraint systems in a set and to preserve this order. Hence instead of working with sets of constraint system, we will work with vectors of constraint systems. We explain here how our rules can be used on a (pair of) vector of constraint systems (more precisely on a row matrix of constraint systems), assuming that the constraint systems of the vector have the same structure.

Actually, the basic idea is to apply the same transformation rule (with the same parameters) on each constraint system of the vector. Note that, the parameters of a transformation rule only depend on the structure of the underlying constraint system. Thanks to this, the simultaneous application of a transformation rule can be defined in a natural way.
7.3. SIMPLIFYING SETS OF CONSTRAINT SYSTEMS

Definition 7.10 (application of a rule on a pair of row matrices). Let \( M = [C_1, \ldots, C_n] \) and \( M' = [C'_1, \ldots, C'_{n'}] \) be two row matrices having \( n \) (resp. \( n' \)) columns and having the same structure. Let Rule(\( \bar{p} \)) be an instance of a transformation rule. The application of Rule(\( \bar{p} \)) on the pair \((M, M')\) yields two pairs of row matrices \((M_1, M'_1)\) and \((M_2, M'_2)\) such that:

- \( M_1 = [C_1, \ldots, C_{i-1}, C_i, C_{i+1}, \ldots, C_n] \) and \( M_2 = [C_{i+1}, \ldots, C_n] \); whereas \( M'_1 = [C'_1, \ldots, C'_{i-1}, C'_i, C'_{i+1}, \ldots, C'_{n'}] \) and \( M'_2 = [C'_{i+1}, \ldots, C'_{n'}] \);
- for all \( i \in \{1 \ldots n\} \), \( C_i \) and \( C'_i \) are the constraint systems obtained by application of Rule(\( \bar{p} \)) on \( C_i \);
- for all \( i \in \{1 \ldots n'\} \), \( C'_1 \) and \( C'_{2,i} \) are the constraint systems obtained by application of Rule(\( \bar{p} \)) on \( C'_i \).

7.3.2 Matrices of constraint systems

The non-deducible constraints introduced by the rules Dest and Ded-st are formally interesting since they allow us to properly divide the solutions of a constraint system. However, note that in Figures 7.1, 7.2 and 7.3 no rule focuses on solving these non-deducible constraints. We illustrate in the next example how we solve them.

Example 7.19. Consider the constraint system \( C \) composed of the deducible constraints \( D = \{ X, 2 \vdash \text{senc}(a, a) \} \), the frame \( \Phi = \{ ax_1, 1 \triangleright a; ax_2, 2 \triangleright \text{senc}(b, a) \} \), \( S_2 = \{ X \} \) and \( S_1 = \{ x \} \). The application of the rule Dest(\( ax_2, \text{sdec}(\text{senc}(x, y), y) \rightarrow x, 2) \) on \( C \) yields two constraint systems \( C_1 \) and \( C_2 \) such that:

\[
C_1 = \begin{cases} 
D(C_1) : \{ X, 2 \vdash \text{senc}(a, a); Y, 2 \vdash a \} \\
\Phi(C_1) : \{ ax_1, 1 \triangleright a; ax_2, 2 \triangleright \text{senc}(b, a); \text{sdec}(ax_2, Y), 2 \triangleright b \}
\end{cases}
\]

and

\[
C_2 = \begin{cases} 
D(C_2) : \{ X, 2 \vdash \text{senc}(a, a) \} \\
\Phi(C_2) : \{ ax_1, 1 \triangleright a; ax_2, 2 \triangleright \text{senc}(b, a) \} \\
\text{ND}(C_2) : \forall x_1, x_2, \text{senc}(x_1, x_2) \neq \text{senc}(b, a) \lor 2 \nvdash a
\end{cases}
\]

To solve the non-deducible constraint in \( C_2 \), we will use the informations we get from the resolution of \( C_1 \). Note that the rule Axiom(\( Y, ax_1 \)) is applicable on \( C_1 \) and yields two constraint systems \( C_3 \) and \( C_4 \) such that

\[
C_3 = \begin{cases} 
D(C_3) : \{ X, 2 \vdash \text{senc}(a, a) \} \\
\Phi(C_3) : \{ ax_1, 1 \triangleright a; ax_2, 2 \triangleright \text{senc}(b, a); \text{sdec}(ax_2, Y), 2 \triangleright b \} \\
\text{Er}(C_3) : Y \nvdash ax_1
\end{cases}
\]

and

\[
C_4 = \begin{cases} 
D(C_4) : \{ X, 2 \vdash \text{senc}(a, a); Y, 2 \vdash a \} \\
\Phi(C_4) : \{ ax_1, 1 \triangleright a; ax_2, 2 \triangleright \text{senc}(b, a); \text{sdec}(ax_2, Y), 2 \triangleright b \} \\
\text{Er}(C_4) : Y \nvdash ax_1
\end{cases}
\]

But on \( C_4 \), the successive applications of Cons(\( Y, f \)) and Axiom(\( Y, \text{path} \)) for any \( f \) and \( \text{path} \) will yields after normalisation the constraint system \( \bot \). Hence, when we compare \( C_3 \) and \( C_2 \), we can see that the non-deducible constraint in \( C_2 \) will never be satisfiable and so \( C_2 \) does not have a solution.

As illustrated in Example 7.19 to solve the non-deducible constraints of a constraint system, we will use the informations we obtain from the application of the rules on other constraint systems. To keep track of these informations, we regroup the vectors of constraint systems into matrices of constraint systems.
Example 7.20. Consider the constraint system $C$ of Example 7.19 and consider the vector of constraint systems $[C, C']$ where $C'$ is some constraint system with the same structure as $C$. By applying $\text{DEST}(ax, 2), \text{sd}(\text{sec}(x, y), y) \rightarrow x, 2)$ on $[C, C']$, instead of obtaining two vectors $[C_1, C'_1]$ and $[C_2, C'_2]$ where $C_1, C_2$ are the constraint system of Example 7.19, we obtain the following matrix of constraint system:

$$\begin{bmatrix} C_1, C'_1 \\ C_2, C'_2 \end{bmatrix}$$

Then when we applied the rule $\text{Axiom}(Y, ax_1)$ on $[C_2, C'_2]$, we obtained the following matrix of constraint systems:

$$\begin{bmatrix} C_3, C'_3 \\ C_4, C'_4 \\ C_2, C'_2 \end{bmatrix}$$

At this point, to check the non-deducible constraint in $C_2$, we only have to check the informations we have on the constraint systems in the same column as $C_2$.

### 7.3.2.1 Symbolic equivalence of matrices of constraint systems

Note that in Example 7.20, the constraint system $C_1, \ldots, C_4$ has the same sets $S_2$, $S_1$ and also contains the same subset of deducible constraints whose second order variable is in $S_2$. This is formalised in the following definition.

**Definition 7.11** (shape). Let $C = (S_1; S_2; \Phi; D; Eq; Er; ND; NoUse)$ be a constraint system. The shape of $C$ is given by $S_2$, and $\{(X, i) \mid X, i \vdash u \in D \and X \in S_2\}$.

Intuitively, the shape of a constraint system only represents the "actions" of the intruder.

We extend the notion of same structure between matrices of constraint systems in the following way. Two matrices $M$ and $M'$ of constraint systems having $n$ (resp. $n'$) lines and $m$ (resp. $m'$) columns have the same structure if:

- all the constraint systems stored in $M$ and $M'$ have the same shape;
- $n = n'$, i.e. $M$ and $M'$ have the same number of lines; and
- for all $i \in \{1 \ldots n\}$, the constraint systems stored in the $i^{\text{th}}$ line of the matrices $M$ and $M'$ have the same structure.

Since our algorithm considers matrices of constraint system, we extend the notion of symbolic equivalence to pairs of matrices of constraint systems.

**Definition 7.12** (symbolic equivalence $\approx_s$). Let $M, M'$ be two matrices of symbolic constraint systems having the same structure. We have that $M \subseteq_s M'$ if for all $1 \leq i \leq n$, for all $1 \leq j \leq m$, for all $(\sigma, \theta) \in \text{Sol}(M_{i,j})$, there exists $1 \leq k \leq m'$ and a substitution $\sigma'$ such that $(\sigma', \theta) \in \text{Sol}(M'_{i,k})$ and $\Phi_{i,j} \sigma \sim \Phi'_{i,k} \sigma'$.

If $M \subseteq_s M'$ and $M' \subseteq_s M$, then we say that $M$ and $M'$ are in symbolic equivalence, denoted by $M \approx_s M'$.

### 7.3.2.2 Application of the rules on matrices of constraint systems

In fact, introducing the matrices of constraint systems serves a greater purpose than just solving the non-deducible constraints. Indeed, deciding the symbolic equivalence of two row matrices contains two main issues:

- matching an existing solution from one matrix to the other;
- and deciding whether the two resulting frames are statically equivalence or not.
The idea behind matrices with several lines is to keep all the guesses on static equivalence into a single matrix. Intuitively, when we guess the form of the solutions, we split the matrix into two matrices. However, when we guess an equality between terms or a property on static equivalence, we gather the informations in the same matrix. This leads us to consider two kinds of application: internal and external. The transformation rules DED-ST, EQ-LEFT-LEFT, EQ-LEFT-RIGHT and DEST will be applied internally whereas CONS(X, f), AXIOM(X, path) and EQ-RIGHT-RIGHT(X, ξ) will be applied externally when \( X \in S_2 \) and internally otherwise (i.e. \( X \notin S_2 \)).

Let \( (M, M') \) be a pair of matrices of constraint systems having the same structure. In particular, \( M \) and \( M' \) have the same number of lines, say \( n \). Let \( M = [V_1, \ldots, V_n] \) and \( M' = [V'_1, \ldots, V'_n] \). Let Rule(\( \tilde{p} \)) be an instance of a transformation rule and \( i \) be an integer representing a line, i.e. \( 1 \leq i \leq n \).

An internal application of Rule(\( \tilde{p} \)) on the \( i^{th} \) line of the pair \( (M, M') \) yields a pair of matrices \( (\tilde{M}, \tilde{M}') \) such that:

\[
\tilde{M} = [V_1, \ldots, V_{i-1}, W_{i,1}, W_{i,2}, V_{i+1}, V_n] \quad [V'_1, \ldots, V'_{i-1}, W'_{i,1}, W'_{i,2}, V'_{i+1}, V'_n] = \tilde{M'}
\]

where \( (W_{i,1}, W_{i,2}) \) and \( (W'_{i,1}, W'_{i,2}) \) are the pair of row matrices obtained by applying Rule(\( \tilde{p} \)) on \( (V_i, V'_i) \). Note that, since the two matrices \( M \) and \( M' \) have the same structure, the two row matrices \( V_i \) and \( V'_i \) have also the same structure and we can rely on Definition 7.10. We say that an instance Rule(\( \tilde{p} \)) of a rule is internally applicable on \( (M, M') \) on line \( i \) if Rule(\( \tilde{p} \)) is applicable on \( (V_i, V'_i) \).

An external application of Rule(\( \tilde{p} \)) on \( (M, M') \) yields two pairs of matrices \( (\tilde{M}_1, \tilde{M}'_1) \) and \( (\tilde{M}_2, \tilde{M}'_2) \) such that:

\[
\tilde{M}_1 = [W_{1,1}, \ldots, W_{n,1}] \quad [W'_{1,1}, \ldots, W'_{n,1}] = \tilde{M}'_1
\]

\[
\tilde{M}_2 = [W_{1,2}, \ldots, W_{n,2}] \quad [W'_{1,2}, \ldots, W'_{n,2}] = \tilde{M}'_2
\]

where \( (W_{1,1}, W'_{1,1}) \) and \( (W_{1,2}, W'_{1,2}) \) are the pair of row matrices obtained by applying Rule(\( \tilde{p} \)) on \( (V_i, V'_i) \) for each \( i \in \{1, \ldots, n\} \).

Remark. Unfortunately, all the constraint systems in \( M \) and \( M' \) do not have necessarily the same structure, but only the same shape. When the external application involved is an instance of a rule CONS, it is easy to see that having the same shape will ensure that the rule can be applied on each row of the matrices. Regarding an external application of the rule AXIOM(X, path), we have to be a little more specific. Since the constraint systems have the same shape and we know that \( X \in S_2 \), we can ensure that \( X \) occurs in each constraint system. However, it could happen that some rows do not contain the required frame element. By convention, in such a pair \( (V_i, V'_i) \) of row matrices, the resulting pairs of row matrices are \( (W_{i,1}, W'_{i,1}) \defeq (\bot, \bot) \) and \( (W_{i,2}, W'_{i,2}) \defeq (V, V') \).

Example 7.21. All the rules applied in Example 7.20 are internal rules.

7.4 Our strategy

In the previous sections, we defined the conditions of application of all the rules described in Figure 7.1 and 7.2. Furthermore, we also introduced the notion of strong application in order to solve some basic termination problem. Nevertheless, this strong application is not sufficient to ensure termination and soundness. Thus, we describe a strategy on the application of the rule.

By applying the rules described in Figure 7.1 and 7.2 we want to transform the constraint systems into solved constraint system, i.e. either \( \bot \) or constraint system such that:

1. For all \( X, i \vdash u \in D, X \in S_2 \) and \( u \) is a variable distinct from the right hand side of any other deducible constraint.
2. $Eq$ does not contain variable that are universally quantified, and for all $u \neq v$ in $Eq$, we have that $u, v$ do not contain any names.

The first phase of our strategy consists of applying rules to satisfy the first property, without taking care of the inequations. Then, the second phase of our strategy will reduce the constraint systems into solved ones. Both phases will be described as a succession of different steps (see below).

The description of the strategy is always local to the pair of matrices of constraint systems we consider. Consider for example an pair of matrices $(M_0, M'_0)$ of initial constraint systems. The strategy starts with the first phase. If a rule of Phase 1 is applicable on $(M_0, M'_0)$, e.g. an internal rule, we apply this rule on $(M_0, M'_0)$ which yields a pair of matrices of constraint systems $(M_1, M'_1)$. Then, if a rule of Phase 1 is applicable on $(M_1, M'_1)$, e.g. an external rule, we apply this rule on $(M_1, M'_1)$ which yields two pair of matrices of constraint systems $(M_{12}, M'_{12})$ and $(M_{22}, M'_{22})$. The strategy continues independently on $(M_{12}, M'_{12})$ and $(M_{22}, M'_{22})$. Typically, if a rule of Phase 1 is applicable on $(M_{12}, M'_{12})$ then we apply this rule on $(M_{12}, M'_{12})$ and so on. In parallel, if no rule of Phase 1 is applicable on $(M_{22}, M'_{22})$ then we go into Phase 2 and check if one of the rules of Phase 2 is applicable on $(M_{22}, M'_{22})$ and so on.

To summarise, the application of our strategy on a pair of matrices of initial constraint systems yields a binary tree (not necessary full) where each node of this tree is a pair of matrices of constraint systems, and two nodes of same height in the binary tree are not necessary in the same phase / step of the strategy.

When describing the phase and strategy, we denote $(M, M')$ the pair of matrices of constraint system on which we wish to apply a rule.

### 7.4.1 First phase of the strategy

Let $C = (S_1; S_2: \Phi; D; Eq; Er; ND; NoUse)$. We associate, to each instance of a rule applied on a constraint system $C$, an integer, namely its *support*, as follows:

- support of $\text{CONS}(X, \ell)$ is $i$ where $X, i \vdash u \in D$
- support of $\text{Dest}(\xi, \ell \rightarrow r, i)$ is $i$
- support of $\text{Axiom}(X, \text{path})$ is $i$ where $X, i \vdash u \in D$
- support of $\text{EQ-LEFT-LEFT}(\xi_1, \xi_2)$ is $i$ when $\xi_1, i_1 \triangleright u_1 \in \Phi$ and $\xi_2, i_2 \triangleright u_2 \in \Phi$
- support of $\text{EQ-LEFT-RIGHT}(\xi_1, X_2)$ is $i_1$ when $\xi_1, i_1 \triangleright u_1 \in \Phi$
- support of $\text{EQ-RIGHT-RIGHT}(X, \xi)$ is $i$ when $X, i \triangleright u \in \text{vars}(D)$
- support of $\text{Ded-st}(X, \xi)$, is $m$ (i.e. the maximal index that occurs in $C$)

The first phase is a cycle of five steps. Each cycle is characterised by one parameter: the support $s$ of the rules we will apply during this cycle. The first cycle will consider rules having support 1, then the second cycle will take care of the rules of support 2, and so on. Figure 7.5 represents the evolution between the different steps. The exact description of each step is given below.

#### 7.4.1.1 Step 1

We apply the rules $\text{Dest}$ and $\text{EQ-LEFT-RIGHT}$, with support equal to $s$, as long as possible with priority on the rule $\text{EQ-LEFT-RIGHT}$. The application of those rules has to be a strong application for at least one constraint system in the line of the pair of matrices on which we apply the rule.
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7.4.1.1 Step (a)

\[ s := 1 \]

7.4.1.2 Step (b)

\[ k := 1 \]

if no rule of Step (b) applicable

7.4.1.3 Step (c)

\[ s := s + 1 \]

7.4.1.4 Step (d)

\[ k := k + 1 \]

if \( k = n \)

7.4.1.5 Step (e)

\[ \text{if } s = m \]

where \( s \) is the parameter corresponding to the support, \( k \) is the parameter corresponding to the index of the column, \( n \) is the number of column in the pair of matrices and \( m \) is the size of the frame of one of the constraint systems in the pair of matrices.

Figure 7.5: Representation of the first phase of the strategy

In order to obtain some necessary properties on the matrices of constraint system, when a rule Dest(\( \tilde{p} \)) or Eq-left-right(\( \tilde{p} \)) is applied on one line of the matrix, we will apply the same rule with similar parameter on each line of the matrix.

More specifically,

- if Dest(\( \xi, \ell \rightarrow r, s \)) is applied on a line of \((M, M')\) where \((\xi, i)\) belongs to the structure of a constraint systems of this line, then for all line \(L'\) of \((M, M')\) where there exists \(\xi'\) such that \((\xi', i)\) belongs to the structure of the constraint systems in \(L'\) and \(\text{path}(\xi') = \text{path}(\xi)\), we apply Dest(\( \xi', \ell \rightarrow r, s \)) on \(L'\).

- if Eq-left-right(\( \xi, X \)) is applied on a line of \((M, M')\) where \((\xi, i)\) belongs to the structure of the constraint systems of this line, then for all line \(L'\) of \((M, M')\) where there exist \(\xi'\) such that \((\xi', i)\) belongs to the structure of the constraint systems in \(L'\) and \(\text{path}(\xi') = \text{path}(\xi)\), we apply Eq-left-right(\( \xi', X \)) on \(L'\).

At the end of this step, the frame of any constraint system in the matrices is fixed for the support \(s\), i.e. there will be no new frame element added on the frame with a support equal to \(s\).

7.4.1.2 Cycle of steps \(b, c, d\) (solving the deducible constraints)

After this first step, the strategy is once again a cycle of three different steps, denoted \(b, c, d\). This time, the parameter of each cycle is the index of the column on which we will apply the rule. Hence at this point, \(s\) is the parameter of the main cycle and \(k\) is the index of the working column. Each of this cycle alternates steps \(b\) and \(c\), and then ends with step \(d\) (see Figure 7.5).

Given a pair of matrices \((M, M')\) such that \(M\) (resp. \(M'\)) has \(n\) columns (resp. \(n'\)), we say that the \(k\text{th}\) column of \((M, M')\) is either the \(k\text{th}\) column of \(M\) if \(k \leq n\); or else the \((k-n)\text{th}\) column of \(M'\) if \(k > n\). If \(n + n' < k\) then the \(k\text{th}\) column of \((M, M')\) is not defined.

7.4.1.3 Step (b)

We apply the internal applications of the rules Eq-right-right, Eq-left-left, Cons and Axiom with support less than \(s\), as long as possible. In case \(s = |\Phi|\) where \(\Phi\) is a frame of one of the constraint system in the pair of matrices, we also apply the internal applications of Ded-St. Moreover, the instance of the rule must be strongly applicable on the constraint system in the \(i\text{th}\) line and \(k\text{th}\) column of the pair of matrices, where \(i\) is the index of the line on which the rule is applied.
7.4.1.4 Step c

For this step, we need to consider the following set: For a constraint system \( C \), we defined \( X^1(C) \) as a subset of \( X^1 \) such that:

\[
X^1(C) = \{ x \in X^1 \mid (Y, j \vdash x) \in D(C), Y \not\in S_2(C) \}
\]

Furthermore, we define a lexical measure on deducible constraints of a constraint system \( C \), denoted \( L^1_C(\cdot, \cdot) \), such that: for all \((X, j \vdash u) \in D(C)\) such that \( \text{vars}(u) \cap X^1(C) \neq \emptyset \) and \( X \in S_2 \):

\[
L^1_C(X, j \vdash u) = (j, \min \{ p \mid u|_p \in X^1(C) \})
\]

If for all constraint system \( C \) in the \( k \)th column of \((M, M')\), \( X^1(C) \) is empty then no rule is applicable for this step. Else, let \( i_0 \) be an index of the line of \((M, M')\), let \( C_0 \) be the constraint system in the \( i_0 \)th line and \( k \)th column of \((M, M')\), and let \((X_0, j_0 \vdash u_0) \in D(C_0)\) such that \( \text{vars}(u_0) \cap X^1(C_0) \neq \emptyset \), \( X \in S_2(C_0) \), and:

\[
L^1_C(X_0, j_0 \vdash u_0) = \min \left\{ L^1_C(Z, \ell \vdash v) \mid i \in \mathbb{N}, (Z, \ell \vdash v) \in D(C), \text{vars}(v) \cap X^1(C) \neq \emptyset, Z \in S_2(C) \right\}
\]

We apply by order of preference:

1. the internal rule EQ-RIGHT-RIGHT\((Y, X_0)\) on the \( i_0 \)th line for any \( Y \) such that \((Y, j \vdash w) \in D(C_0), j \leq s, Y \not\in S_2(C_0) \) and EQ-RIGHT-RIGHT\((Y, X_0)\) is strongly applicable on \( C_0 \);
2. the external rule Cons\((X_0, f)\), for any \( f \in F_e \) such that Cons\((X_0, f)\) is strongly applicable on \( C_0 \);
3. the external rule Axiom\((X_0, \text{path})\), for any \text{path} such that Axiom\((X_0, \text{path})\) is strongly applicable on \( C_0 \)

Intuitively, the choice of \( X_0, j_0 \vdash u_0 \) is done over all the constraint systems in the \( k \)th column such that one of the variables appearing in the internal deducible constraint of \( C_0 \) is the closest to the root of \( u_0 \). This choice is made for the sole purpose that only the application of the external rule Axiom\((X_0, f)\) can instantiate the internal deducible constraints of the constraint systems in the \( k \)th column.

7.4.1.5 Step d

We apply the external application of the rules EQ-RIGHT-RIGHT, Cons and Axiom as long as they are strongly applicable on \( M_{i,k} \) by increasing order on the index of the line \( i \) (if we assume that \( k \) corresponds to an index of the matrix \( M \) in the pair \((M, M')\)).

To be more specific, if an instance \( R_1(\tilde{p}_1) \) is strongly applicable on \( M_{i_1,k}, R_2(\tilde{p}_2) \) is strongly applicable on \( M_{i_2,k} \), and \( i_1 \leq i_2 \) then we apply the rule \( R_1(\tilde{p}_1) \) on \((M, M')\).

7.4.1.6 Step e (solving the non-deducible constraints)

This last step consists of solving the non-deducible constraints in the matrices. This step will not consist of applying some rules but replacing some constraint systems in the matrices by \( \perp \).

Formally, for each constraint system \( C \) in the matrix, if there exists a constraint system \( C' \) in the same column as \( C \), a recipe \( \xi \), such that:

- \((\xi, s \triangleright u) \in \Phi(C')\) for some \( i \) and \( u \); and
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• for all \( (\xi', s \triangleright u) \in \Phi(C) \), \( \text{path}(\xi) \neq \text{path}(\xi') \)

then we replace the constraint system \( C \) in the matrix by \( \bot \). This corresponds to solving the non-deducible constraints introduced by the rule \( \text{Dest} \).

Furthermore, when \( s \) is equal to the size of the frames in \( (M, M') \) then for each constraint system \( C \) in \( (M, M') \), if there exists a constraint system \( C' \) in the same column as \( C \) such that for all \( (\xi, i \triangleright u) \in \Phi(C) \), for all \( (\xi', i' \triangleright u') \in \Phi(C') \), for all \( f \in F_c \),

\[
\text{path}(\xi) = \text{path}(\xi') \quad \text{and} \quad i = i'; \quad \text{and} \quad \text{ND}(C) \models \forall \tilde{x} u \neq f(x_1, \ldots, x_n) \lor s \not\models x_1 \lor \ldots \lor s \not\models x_n \quad \text{where} \quad \tilde{x} = x_1 \ldots x_n \text{ are variables}; \quad \text{and} \quad \\
\text{there exists } X_1, \ldots, X_n \in \text{vars}^2(C') \text{ such that } C[f(X_1, \ldots, X_n)\theta]_{\Phi(C')\text{acc}}^1(C') = u', \quad \theta \text{ is the most general unifier of the equation in } Er(C')
\]

then we replace the constraint system \( C \) in the matrix by \( \bot \). This corresponds to solving the non-deducible constraints introduced by the rule \( \text{Ded-st} \).

Typically, each constraint system that is replaced by \( \bot \) does not have a solution due to the non-deducible constraint.

7.4.2 Second phase of the strategy

As stated at the beginning of this section, this second phase will take care of the inequations. First of all, after the first phase of the strategy, the rules \( \text{Dest} \), \( \text{Eq-left-right} \), \( \text{Eq-left-left} \) and \( \text{Ded-st} \) will never be applicable anymore for any parameters; thus the only rules that will be applied are \( \text{Cons} \), \( \text{Axiom} \) and \( \text{Eq-right-right} \). Furthermore these rules will always be applied as external rules.

The second phase of the strategy is composed of three steps that we denote \( a, b, c \). Figure 7.6 represents the evolution between the different steps.

![Figure 7.6: Representation of the second phase of the strategy](image)

7.4.2.1 Step a (Getting rid of the universal variables)

We apply the rules \( \text{Cons}(\tilde{p}) \) and \( \text{Axiom}(\tilde{p}) \) as long as they satisfy the following conditions on at least one constraint system of the matrices:

- \( \text{Cons}(X, f) \): either \( \text{Cons}(X, f) \) is strongly applicable or there exists an atomic statement \( t \neq w \) in \( Eq \) (actually at this stage \( t \) will be a variable) for which there exists a universal variable \( y \in \text{vars}^1(w) \).

- \( \text{Axiom}(X, \text{path}) \): either \( \text{Axiom}(X, \text{path}) \) is strongly applicable or there exists an atomic statement \( u \neq w \) in \( Eq \) (actually at this stage \( u \) will be a variable) for which there exists a universal variable \( y \in \text{vars}^1(w) \).

We show that at the end of this step, all the universal variables are removed (see Appendix C.4.3.10).
7.4.2.2 The association tables

After Step a, the strategy is once again a cycle of the two last steps, i.e. Steps b and c. Step b consists of matching the inequations on every constraint systems on the matrices using the rules CONS and EQ-RIGHT-RIGHT, while step b instantiates variables using the rule AXIOM. However, for the strategy to terminate, we have to keep track of which inequations were matched using the rule EQ-RIGHT-RIGHT. Hence we introduce the notion of association table for disjunction of first order inequations. Intuitively, for each constraint system $C$ in the matrices, we associate an association table where the index are the disjunctions of inequation between first order terms in $C$ that comes from an application of the rule EQ-RIGHT-RIGHT. At last, the disjunction of inequation will always be associated to a disjunction of inequation between terms in $T(F_c \cup (F_a^d \cdot AX), \mathcal{X}^2)$, i.e. between contexts of recipes.

Normalisation of a disjunction of inequation between contexts of recipe: We define a transformation on formulas of context of recipe, denote $\vdash$, by the following reductions: For all $E$ disjunction of inequations of contexts of recipes, $f \in F_c$, and $\xi_1, \xi_2 \in T(F_c \cup (F_a^d \cdot AX), \mathcal{X}^2)$,

\[
E \lor f(\xi_1, \ldots, \xi_n) \neq f(\zeta_1, \ldots, \zeta_n) \quad \Rightarrow \quad \exists \xi_1 \neq \zeta_1 \lor \ldots \lor \xi_n \neq \zeta_n
\]

Comparing to the normalisation on formulas of first order terms, this normalisation is very simple and slightly reduces formulas. Indeed, we will use these formula only as a way to rebuild formulas on first order term. Hence, we don’t want the formula $g \cdot ax_1 \neq ax_2$ to be reduced to false because even if the path are different, it is possible that the associated term aren’t, i.e. $(g \cdot ax_1)acc^1(C)$ and $ax_2acc^1(C)$.

At last, we define the maximal parameter for a context of a recipe, denoted $\text{param}C^C_{\text{max}}(\beta)$, such that:

\[
\text{param}C^C_{\text{max}}(\beta) = \max\{i \mid (w \cdot ax_i) \in \text{st}(\beta) \text{ with } w \in F_a^d \text{ or } (Y, i \vdash v) \in D \text{ with } Y \in st(\beta)\}
\]

Evolution of an association table: Let $C$ be a constraint system an T its association table. Let $C_1, C_2$ and $T_1, T_2$ their respective association table such that $C_1$ and $C_2$ are the two constraint system produced by the application of a rule on $C$. We show here how $T_1$ and $T_2$ evolved by default: For all $i \in \{1, 2\}$, for all disjunction $D$ of inequations of first order terms, if $T[D]$ exists and there exists $E'$ and $D'$ such that $Eq(C_i) = E' \land D'$ with $D' = \text{Dmgu}(Eq(C_i))$, then we have that $T_i[D] := T[D][X \mapsto C_i[X \theta \Phi(C_i) \mid X \in \text{dom}(\theta)] \downarrow$ where $\theta = \text{mgu}(Eq(C_i))$.

When describing the step b and c of the strategy, the additional operations on the association tables we may apply will always be done after the default transformation described above. At last, the associations table of each constraint systems in the matrices is empty at the end of Step a.

7.4.2.3 Step b (Splitting the inequations)

In this step, we apply as long as we can the rules CONS and EQ-RIGHT-RIGHT, then we go to the step c. However, their application depends on the association table of the constraint systems.

We say that EQ-RIGHT-RIGHT($X, \xi$) is applicable for Step b if there exists a constraint system $C$ in the matrices with its association table $T$ such that EQ-RIGHT-RIGHT($X, \xi$) is not useless on on $C$, $Eq(C) = E'' \land (E'' \lor u \neq v)$ for some $E', E''$ and $u, v$ are the terms described in Figure 7.2 and

- either $T[E'' \lor u \neq v] = \bot$.
- or else $T[E'' \lor u \neq v] = D \lor X \neq \xi$ with $(F_a^d \cdot AX) \land st(D) \neq \emptyset$ for some $D$. 


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After application of Eq-right-right\(X, \xi\), if we guessed that the inequation holds, then we add in each association table \(T'\) of each constraint system \(C'\) of the matrices the following entry: 
\[T[u' \neq v'] := X \lor \xi\] where \(u' = X\text{acc}^{-1}(C')\) and \(v' = \xi\text{acc}^{-1}(C')\).

We say that Cons\((X, f)\) is applicable for Step \(b\) if there exists a constraint system \(C\) in the matrices with its association table \(T\) such that Cons\((X, f)\) is not useless on \(C\), Eq\((C) = E' \land (E'' \lor t \neq u)\) for some \(E', E''\) and \(t\) is the term described in Figure 7.1 (actually \(t\) is a variable at this stage), and

- either Cons\((X, f)\) is strongly applicable on \(C\);
- or \(T[E'' \lor t \neq u] = \bot\) with root\((u) = f\) and either \(st(u) \cap N \neq \emptyset\) or \(\text{ind}_C(t) < \text{ind}_C(u)\)
- or \(T[E'''] = D \lor X \neq \xi\) with root\((\xi) = f\) and either \((F^*_3 \cdot A\lambda) \cap st(\xi) \neq \emptyset\) or \(\text{param}_{C_{\max}}(X) < \text{param}_{C_{\max}}(\xi)\).

7.4.2.4 Step \(c\) (Instantiating the variables)

In this last step, we apply the rule Axiom\((X, \text{path})\) as long as there is at least one constraint system \(C\) in the matrices satisfying the following conditions:

- either Axiom\((X, \text{path})\) is strongly applicable on \(C\);
- or Eq\((C) = E \land (D \lor u \neq a)\) and \(T[D \lor u \neq a] = \bot\) for some \(E, D, a\) in \(N\) and \(u\) is the term described in Figure 7.1.

7.4.2.5 Removal transformation

During Step \(b\) and Step \(c\), for any association table \(T\), if there exists an entry \(T[\bigvee_i u_i \neq v_i] = \bigvee_i \xi_i \neq \xi'_i\) such that \(\xi_i\) or \(\xi'_i\) is in \((F^*_3 \cdot A\lambda)\) for all \(i\), then we remove this entry, i.e. \(T[\bigvee_i u_i \neq v_i] := \bot\).

Example 7.22. Consider the frames \(\Phi_1\) and \(\Phi_2\) of Example 7.12. Moreover consider the matrix \(M = [C; C']\) such that:

\[
M = \left[ \begin{array}{c}
\{X, 1 \vdash x; Y, 3 \vdash y\} \\
\{X, 1 \vdash x'; Y, 3 \vdash y'\}
\end{array} \right]_{\Phi_1} \quad \text{and} \quad \left[ \begin{array}{c}
\{X, 1 \vdash x'; Y, 3 \vdash y'\}
\end{array} \right]_{\Phi_2}
\]

Assume that their respective association tables, denoted \(T\) and \(T'\) are empty. We can apply the rule Eq-right-right\((X, Y)\) since \(T_1[ x \neq y ] = \bot\). Thus, we obtain two matrices of constraint systems \(M_1 = [C_1; C'_1]\) and \(M_2 = [C_2; C'_2]\) such that:

\[
M_1 = \left[ \begin{array}{c}
\bot \\
\{X, 1 \vdash x'; \} \\
y' \vdash x' \land x' \neq b \land
\end{array} \right]_{\Phi_2}
\]

and

\[
M_2 = \left[ \begin{array}{c}
\{X, 1 \vdash x; Y, 3 \vdash y\} \\
\{X, 1 \vdash x'; Y, 3 \vdash y'\}
\end{array} \right]_{\Phi_1} \quad \text{and} \quad \left[ \begin{array}{c}
\{X, 1 \vdash x'\; ; \\
x' \neq y
\end{array} \right]_{\Phi_2}
\]

Moreover, if we denote \( T_1, T_1', T_2, T_2' \) the respective association tables of \( C_1, C_1', C_2, C_2' \), then \( T_1 \) and \( T_1' \) are empty, \( T_2 [ x \neq y ] = X \neq Y \) and \( T_2 [ x' \neq y' ] = X \neq Y \). We now focuses on \( M_2 \). We can apply \( \text{Cons}(X, \text{senc}) \) since \( x \neq \text{senc}(a, k_1) \) is in \( \text{Eq}(C_2) \) and \( T_2 [ x \neq \text{senc}(a, k_1) ] = \bot \). Thus it yields once again two matrices \( M_{21} = [C_{21}; C_{21}] \) and \( M_{22} \) such that:

\[
C_{21} = \begin{cases} 
\Phi_1 & \{ X_1, 1 \vdash x_1; \; X_2, 1 \vdash x_2; \; Y, 3 \vdash y \} \\
& x \Rightarrow \text{senc}(x_1, x_2) \land (x_1 \neq a \lor x_2 \neq k_1) \land \text{senc}(x_1, x_2) \neq y \\
& X \Rightarrow \text{senc}(X_1, X_2)
\end{cases}
\]

and

\[
C_{21}' = \begin{cases} 
\Phi_2 & \{ X, 1 \vdash x_1'; \; X_2, 1 \vdash x_2'; \; Y, 3 \vdash y' \} \\
& x' \Rightarrow \text{senc}(x_1', x_2') \land \text{senc}(x_1', x_2') \neq y' \\
& X \Rightarrow \text{senc}(X_1, X_2)
\end{cases}
\]

If we denote \( T_{21} \) and \( T_{21}' \) their association tables, then \( T_{21} [ \text{senc}(x_1, x_2) \neq y ] = \text{senc}(X_1, X_2) \neq Y \) and \( T_{21}' [ \text{senc}(x_1', x_2') \neq y' ] = \text{senc}(X_1, X_2) \neq Y \). At this point, no rule of Step b is applicable thus we go into Step c and try to apply the rule \( \text{Axiom} \). Note that \( T_{21} [ x_1 \neq a \lor x_2 \neq k_1 ] = \bot \) hence we apply \( \text{Axiom}(X_1, ax_1) \) on \( M_{21} \). It yields once again two matrices \( M_{211} = [C_{211}; C_{211}] \) and \( M_{212} \) such that:

\[
C_{211} = \begin{cases} 
\Phi_1 & \{ X_2, 2 \vdash x_2; \; Y, 3 \vdash y \} \\
& x_1 \Rightarrow a \land x \Rightarrow \text{senc}(a, x_2) \land x_2 \neq k_1 \land \text{senc}(a, x_2) \neq y \\
& X_1 \Rightarrow ax_1 \land X \Rightarrow \text{senc}(ax_1, X_2)
\end{cases}
\]

and

\[
C_{211}' = \begin{cases} 
\Phi_2 & \{ X, 1 \vdash x_1'; \; X_2, 2 \vdash x_2'; \; Y, 3 \vdash y' \} \\
& x_1' \Rightarrow a \land x' = \text{senc}(a, x_2') \land \text{senc}(a, x_2') \neq y' \\
& X_1' \Rightarrow ax_1 \land X \Rightarrow \text{senc}(ax_1, X_2)
\end{cases}
\]

If we denote \( T_{211} \) and \( T_{211}' \) their association tables, then \( T_{211} [ \text{senc}(a, x_2) \neq y ] = \text{senc}(ax_1, X_2) \neq Y \) and \( T_{211}' [ \text{senc}(a, x_2') \neq y' ] = \text{senc}(ax_1, X_2) \neq Y \).

We will show that this strategy always terminates on row matrices of initial constraint systems. Section 6.4 describes the essential steps of the proof of this theorem.

**Theorem 7.1.** Given a pair of row matrices of initial constraint system \((M, M')\), the application of the strategy described in Subsection 7.2 on \((M, M')\) terminates.

### 7.4.3 The final test

In this section and the previous one, we described how to apply the rules on a pair of matrices of initial constraint systems and also a strategy that terminates. Thus the last thing we need to define is the final test such that this test succeeds if, and only if, the pair of matrices of constraint systems are symbolically equivalent.

By applying the rules on an initial pair of row matrices, we obtain a tree where every nodes (including the leaves) is a pair of matrices. Thus the final test focuses on the leaves of this tree.
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Definition 7.13 (test on the leaves). Let $(M, M')$ be a pair of matrices of constraint systems with $n$ lines and $m$ (resp. $m'$) columns. We define a predicate on a pair of matrices of constraint systems, denoted LeafTest, such that \( \text{LeafTest}(M, M') = \text{true} \) if, and only if, for all $i \in \{1 \ldots n\}$,

\[
\exists j \in \{1, \ldots, m\}. M_{i,j} \neq \perp \text{ is equivalent to } \exists j' \in \{1, \ldots, m'\}. M'_{i,j'} \neq \perp
\]

With the predicate defined in Definition 7.13, we can finally give one of the main theorem of this paper:

Theorem 7.2. Let $(M_0, M'_0)$ be an initial pair of row matrices of constraint systems. We have that $M_0 \approx_s M'_0$ if, and only if, all leaves of a tree, whose root is labeled with $(M_0, M'_0)$ and which followed the strategy given in Subsection 7.4, satisfy the predicate LeafTest.

The next chapter is dedicated to the proof of Theorem 7.1 and 7.2.
Chapter 8

Proof of the decision procedure

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Proving Theorems 7.1 and 7.2 is difficult and highly technical. This is for various reasons. First of all, the large number of transformation rules used in the algorithm usually tends to lengthen the proofs. Indeed, in most of the proofs, we have to do a case analysis on the rules. This is even more true for the termination proof since we have to consider the different rules but also the different phases and steps of the strategy. Second of all, the constraint systems are composed of several elements which make them difficult to manipulate in the proofs. But most of all, the technicality of the proofs comes from the fact that the soundness and termination proofs overlap. A good example is the Step $e$ of the first phase of the strategy. Without this step, our algorithm is not sound anymore.

This chapter is dedicated to the proofs of Theorem 7.1 and 7.2. More specifically, we provide in Section 8.1 the different properties that the matrices of constraint systems satisfy during the execution of the algorithm. In Section 8.2 we explain the main steps of the proofs of soundness and completeness of our transformation rules but also of our final test on a pair of matrices of constraint systems (see Section 8.3). At last, in Section 8.4 we provide all the necessary measures to prove termination. However, most of the actual proofs are in Appendix C.
8.1 Invariants

8.1.1 Invariants independent from the strategy

First it is easy to see that applying our transformation rules preserves the fact that matrices share the same structure. This is stated in the following lemma (Proof in Appendix C.2.1).

**Lemma 8.1.** Let \((M, M')\) be a pair of matrices of constraint systems such that \(M\) and \(M'\) have the same structure. Any internal (resp. external) application of a rule in Figure 7.1 and/or Figure 7.2 transforms the pair \((M, M')\) on a pair \((M_1, M'_1)\) (resp. two pairs \((M_1, M'_1)\) and \((M_2, M'_2)\)) of matrices having the same structure.

Initially, we consider two row matrices of initial constraint systems. By applying our rules, the constraint systems we consider become more and more complex. Nevertheless, we will show that the strategy and the rules ensure several invariants on constraint systems that will be used in the proof of completeness, soundness and termination. A constraint system satisfying all the invariants will be called well-formed (see Definition 8.2).

Most of the invariants focus are about structural properties of the frame. Those are usually direct consequences of the application of the rules \textsc{Dest}, \textsc{Axiom} and \textsc{Cons}. For example, we will state that for any frame element \((\xi, i \triangleright u)\), the path of the recipe \(\xi\) is defined and closed. Looking at the rules, this invariant seems almost trivial since the only rule that generates a new frame element is \textsc{Dest} which apply a destructor on a recipe.

Other invariants focus on the formula \(E_r\). One of these invariants illustrates the instantiation of a recipe variable \(X\) given the equations in \(E_r\). Moreover, since some recipes of the frames are not always ground, the invariants of a well-formed constraint system detail by which parameters such recipe can be instantiated. To describe this, we introduce the notion of maximal parameter of a recipe.

**Definition 8.1** (maximal parameter of a recipe). Let \(\mathcal{C} = (S_1; S_2; \Phi; D; E_q; E_r; ND; \text{NoUse})\) be a constraint system and let \(\xi \in \Pi_n\) such that \(\text{vars}(\xi) \subseteq \text{vars}^2(D)\). We define the maximal parameter of \(\xi\) in \(\mathcal{C}\), denoted \(\text{param}_{\max}^C(\xi)\), such that:

\[
\text{param}_{\max}^C(\xi) = \max\{i \mid ax_i \in \text{st}(\xi) \text{ or } (Y, i, \vdash v) \in D \text{ with } Y \in \text{st}(\xi)\}
\]

For all constraint systems \(\mathcal{C}\), we denote by \(\text{mgu}(E_q(\mathcal{C}))\) (resp. \(\text{mgu}(E_r(\mathcal{C}))\)) the most general unifier of all the equations in \(E_q(\mathcal{C})\) (resp. \(E_r(\mathcal{C})\)).

Our invariants are not independent. For example, we state that for any frame element \((\xi, i \triangleright u)\), the path of the recipe \(\xi\) is defined and closed (item 1 Definition 8.2). From this, we can deduce that, given \(\theta\) and \(\theta'\) two substitutions and \(\zeta\) a recipe in \(\Pi_n\), we have that \(\mathcal{C}|_{\zeta[\theta \theta]} = \mathcal{C}|_{\zeta[\theta \theta']}\). This comes from the fact that the path \(\text{path}(\xi)\) of any frame element \((\xi, i \triangleright u)\) in \(\Phi\theta\) is closed and so do not depend on the substitution \(\theta\) or \(\theta'\).

**Definition 8.2** (well-formed). Let \(\mathcal{C} = (S_1; S_2; \Phi; D; E_q; E_r; ND; \text{NoUse})\) be a constraint system. We say that \(\mathcal{C}\) is well-formed if it satisfies the following properties:

Invariants on the frame \(\Phi\): for all \((\xi, i \triangleright u) \in \Phi\),

1. \(\text{path}(\xi)\) exists and is closed. Moreover, for all distinct frame elements \((\xi_1, i_1 \triangleright u_1)\) and \((\xi_2, i_2 \triangleright u_2)\) in \(\Phi\), we have that \(\text{path}(\xi_1) \neq \text{path}(\xi_2)\).
2. if \(\text{path}(\xi) = f \cdot w\) then there exists \((\xi', j \triangleright v) \in \Phi\) such that \(j \leq i\), \(\text{path}(\xi') = w\), \(\xi' \in \text{st}(\xi)\) and \(u \in \text{st}(v)\).
3. \(\text{param}_{\max}^C(\xi) \leq i\)
4. for all \(X \in \text{vars}^2(\xi)\), for all \(x \in \text{vars}^1(X\text{acc}^1(\mathcal{C}))\), there exists \((\zeta, k \triangleright w) \in \Phi\) such that \(k \leq i\) and \(x \in \text{vars}^1(w)\).
5. for all ground substitution \( \lambda \), if for all \( X \in \text{vars}^2(\xi) \), we have that \((X\lambda)\Phi\lambda_\downarrow = v\lambda\) where \((X,j \vdash v) \in D\), then \((\xi\lambda)(\Phi\lambda)\downarrow = u\lambda\).

Other invariants: let \( \theta = \text{mgu}(Er) \)

6. any inequation in \( Er \) are:
   - either of the form \( X \neq \xi \) and there exists \( i \in \mathbb{N} \) and a term \( u \) such that \((\xi,i \triangleright u) \in \Phi\);
   - or of the form \( \text{root}(X) \neq f \) with \( f \in F_c \).

7. for all \( X \in \text{vars}^2(\mathcal{C}) \), \( C[X\theta]_\Phi \in \mathcal{T}(F_c,F_d^* \cdot AX \cup X^2) \) and for all \( \xi \in \text{st}(X\theta) \), \( \text{path}(\xi) \in F_d^* \cdot AX \) implies that there exists \( j \) and \( v \) such that \((\xi,j \triangleright v) \in \Phi\)

8. For all \((\xi,i \triangleright u) \in \text{NoUse}\), there exists \( X \in \text{vars}^2(\mathcal{C}) \) such that \( C[X\theta]_\Phi \cdot \text{acc}^1(\mathcal{C}) = u \) and \( \text{param}^c_{\max}(X\theta) < i \)

9. for all \((\xi,i \triangleright u) \in \Phi\), for all \( \xi' \in \text{st}(\xi) \), \( C[\xi']_\Phi \in \mathcal{T}(F_c,F_d^* \cdot AX \cup X^2) \) and if \( \text{path}(\xi') \in F_d^* \cdot AX \) then there exists \( j \) and \( v \) such that \((\xi',j \triangleright v) \in \Phi\)

10. for all \((X,i \triangleright u) \in D\), \( X \not\in S_d(\mathcal{C}) \) implies that for all \( x \in \text{vars}^1(u) \), there exists \((Z,j \triangleright v) \in D\) such that \( i < j \) and \( x \in \text{vars}^1(v) \).

The next lemma indicates that our transformation rules transform a well-formed constraint system into a pair of constraint systems that are also well-formed (Proof in Appendix C.2.2).

**Lemma 8.2.** Any rule in Figure 7.4 and Figure 7.5 transforms a normalised well-formed constraint system into a pair of constraint systems that are also well-formed after normalisation. For the rule \( \text{Dest} \), we assume that its application is not useless.

### 8.1. Strategy invariants

Typically, they are very useful to prove some general properties on constraint systems. However, they are not sufficient to establish soundness of our rules or even the termination. The strategy we described in Subsection 7.4 has been essentially designed to ensure termination of our algorithm. However, this strategy also allows us to extract some new invariants that will help us to prove soundness.

Among the invariants, some of them are specific to some steps of the strategy, but we first describe the invariants that are satisfied at any step of the strategy.

**Invariant 8.1 (InvGeneral).** Let \( M \) be a matrix of constraint systems. We say that \( M \) satisfies the invariant InvGeneral, if and only if:

1. \( ax_i \in \text{st}(\xi) \).
2. for all \( \xi' \in \Pi_n \) with \( \text{root}(\xi') \not\in F_c \), if \( \text{path}(\xi') = \text{path}(\xi) \) and \( \text{acc}(\Phi\sigma) \downarrow \in \mathcal{T}(F_c,N) \), then \( \text{param}(\xi') \not\subseteq \{ax_1, \ldots, ax_{i-1}\} \).
3. for all \( X \in \text{vars}^2(\mathcal{C}) \), if \( \text{path}(\xi) \in \text{st}(C[X\text{mgu}(Er)]_\Phi) \) then \((\xi,i \triangleright u) \not\in \text{NoUse}\).
4. if \((\xi,i \triangleright u) \not\in \text{NoUse}\) then for all \( \xi' \in \text{st}(\xi) \), if there exists \( j \) and \( v \) such that \((\xi',j \triangleright v) \in \Phi\) then \((\xi',j \triangleright v) \not\in \text{NoUse}\).
5. \( \forall X \in S_d(\mathcal{C}), C[X\theta]_\Phi \circ = C[X\theta]_\Phi \circ \circ \).

For all constraint systems \( \mathcal{C}, \mathcal{C'} \) in a same column of \( M \), if we denote \( \theta = \text{mgu}(Er(\mathcal{C})) \) and \( \theta' = \text{mgu}(Er(\mathcal{C'})) \), then

\[ \forall X \in S_d(\mathcal{C}), C[X\theta]_\Phi \circ = C[X\theta]_\Phi \circ \circ \]
6. \( \forall X \in S_2(C), \forall f \in F_c, \text{Er}(C) \models \text{root}(X) \neq f \) implies that \( \text{Er}(C') \models \text{root}(X) \neq f \)

7. \( \forall X \in S_2(C), \) for all \((\xi, i \triangleright u) \in \Phi(1), \) for all \((\xi', i' \triangleright u') \in \Phi(2), \) if \( \text{path}(\xi) = \text{path}(\xi') \) then \( \text{Er}(C) \models X \neq \xi \) is equivalent to \( \text{Er}(C') \models X \neq \xi'. \)

Typically, Properties 1 and 2 ensures that we use in the frame the minimal recipes w.r.t. the parameters to deduce the key of a cipher or the verification key of a signature. These two properties are given by the application of the rule \( \text{Dest} \) (Step a of Phase 1) and more specifically by the fact that the cycle of steps in Phase 1 is applied by increasing support.

Property 3 and 4 indicates that during Step a, we always prioritised the application of the rule \( \text{Eq}-\text{left-right} \) over \( \text{Dest} \).

The last three properties established similitudes between constraint systems of a same column. We already know that the shape of the constraint systems are the same but the strategy allows us to be even more specific. Indeed, Property 5 indicates that the actions of the attacker are the same in each constraint system of the column (up to the context) but Property 6 and 7 also indicate that the inequalities corresponding the attacker’s actions are the same. These three properties are in fact due to the application on the external rules on the matrices of constraint system. The proof of the following lemma can be found in Appendix 8.3.8.

**Lemma 8.3.** Let \((M, M')\) be a pair of row matrices of initial constraint systems having the same structure. Let \((M_1, M_1')\) be a pair of matrices of constraint systems obtained by following the strategy on \((M, M')\). \((M_1, M_1')\) satisfies InvGeneral.

The next invariants are more specific to the different steps and phase of the strategy. Thus, they depend on a parameter, i.e. the support of the rules.

**Invariant 8.2 (InvVarConstraint(s)).** Let \( C \) be a constraint system. We say that \( C \) satisfies InvVarConstraint(s) if \( C = \bot \) or

1. for all \((X, i \triangleright u) \in D(C), \) if \( i \leq s \) then \( u \in X^1 \) and \( X \in S_2(C); \) and

2. for all \((X, i \triangleright x), (Y, j \triangleright y) \in D(C), \) if \( i \leq s, j \leq s \) and \( X \neq Y \) then \( x \neq y. \)

**Invariant 8.3 (InvVarFrame(s)).** Let \( C = (S_1; S_2; \Phi; D; Eq; Er; ND; \text{NoUse}) \) be a constraint system. We say that \( C \) satisfies InvVarFrame(s) if and only if for all \((\xi, p \triangleright v) \in \Phi, \) \( p \leq s \) implies for all \( X \in \text{vars}^2(\xi), \) there exists \( q < p \) and \( u \in T(F_c, N \cup X^1) \) such that \((X, q \triangleright u) \in D.\)

Intuitively, InvVarConstraint(s) corresponds to the purpose of the first phase of the strategy, i.e. modifying the constraint systems such that all right hand term of deductible constraints are distinct variables. Thus, all constraint systems during Phase 2 will satisfy this invariant.

**Invariant 8.4 (InvNoUse(s)).** Let \( C = (S_1; S_2; \Phi; D; Eq; Er; ND; \text{NoUse}) \) be a constraint system. We say that \( C \) satisfies InvNoUse(s) if and only if for all \((\xi, p \triangleright v) \in \Phi, \) \( p \leq s \) and \( v \in X^1 \) implies \((\xi, p \triangleright v) \in \text{NoUse}.\)

**Invariant 8.5 (InvDest(s)).** Let \( C = (S_1; S_2; \Phi; D; Eq; Er; ND; \text{NoUse}) \) be a constraint system. We say that \( C \) satisfies InvDest(s) if and only if for all \((\xi, p \triangleright v) \in \Phi, \) for all \( f \in F_4, (\xi, p \triangleright v) \notin \text{NoUse} \) and \( p \leq s \) implies:

- either there exists \( p' \in \mathbb{N} \) such that
  - \( s \geq p' \geq p; \) and
  - \((\xi', p' \triangleright v') \in \Phi \) for some \( \xi' \) such that \( \text{path}(\xi') = f \cdot \text{path}(\xi); \) and

- for every \( p \leq k < p', \) for all \( \sigma \models ND \) implies that \( \sigma \models \forall \tilde{x}, v \neq u_1 \lor k \nmid u_2 \lor \ldots \lor k \nmid u_n \) where \( f(u_1, \ldots, u_n) \rightarrow w \) is a fresh rewriting rule with \( \text{vars}^1(u_1, \ldots, u_n, w) = \tilde{x}. \)
8.2. SOUNDNESS AND COMPLETENESS

- or else for every \( p \leq k \leq s \), we have that ND \( \models \forall \bar{x}, v \neq u_1 \lor k \not\models u_2 \lor \ldots \lor k \not\models u_n \) where \( f(u_1, \ldots, u_n) \rightarrow w \) is a fresh rewriting rule with \( \text{vars}^1(u_1, \ldots, u_n, w) = \bar{x} \).

**Invariant 8.6 (InvDedsub).** Let \( C = (S_1; S_2; \Phi; D; E_1; E_2; \text{ND}; \text{NoUse}) \) be a constraint system. Let \( \theta = \text{mgu}(E_2) \) and \( m = |\Phi| \). We say that \( C \) satisfies InvDedsub if and only if, for all \( (\xi, p \triangleright v) \in \Phi \), for all \( f \in F_e \), \( (\xi, p \triangleright v) \not\in \text{NoUse} \) and \( p \leq s \) implies:

- either there exists \( X_1, \ldots, X_n \in \text{vars}^2(C) \) such that for all \( i \in \{1, \ldots, n\} \), \( \param_{\max}(X_i \theta)s \) and

  \[ C[f(X_1, \ldots, X_n)\theta]_{\Phi, \text{acc}^1}(C) = v \]

- or else \( \text{ND} \models \forall \bar{x}, v \neq f(x_1, \ldots, x_n) \lor m \not\models x_1 \lor \ldots \lor m \not\models x_n \) where \( \bar{x} = x_1 \ldots x_n \) are fresh.

Typically, InvDest(s) ensures that no new subterm can be obtained by applying a destructor while InvDedsub ensures that no new subterm can be obtained by applying a constructor. The invariants InvDest(s) and InvNoUse(s) will be satisfied by any constraint system after Step 0 of Phase 1 with support smaller than \( s \).

The next invariant indicates that no rule was applied with support strictly greater than \( s \). Typically, it is satisfied by all constraint systems during Phase 1 with support smaller than \( s \).

**Invariant 8.7 (InvUntouched(s)).** Let \( C = (S_1; S_2; \Phi; D; E_1; E_2; \text{ND}; \text{NoUse}) \) be a constraint system. We say that \( C \) satisfies InvUntouched(s) if and only if

1. for all \( (\xi, k \triangleright u) \in \Phi \), if \( s < k \) then \( \xi = ax_k \); and

2. for all \( (X, k \triangleright u) \in D \), if \( s < k \) then \( X \in S_2 \) and \( X \not\in \text{vars}^2(E_2) \).

Lastly, we define an invariant that impact on several constraint systems in the matrices.

**Invariant 8.8 (InvMatrix(s)).** Let \( M \) be a matrix of constraint systems. We say that \( M \) satisfies InvMatrix(s) if and only if for all \( C, C' \) two constraint systems in the same column of \( M \),

- \( \{\text{path}(\xi), i \mid (\xi, i \triangleright u) \in \Phi(C) \land i \leq s\} = \{\text{path}(\xi), i \mid (\xi, i \triangleright u) \in \Phi(C') \land i \leq s\} \)

- \( \{\text{path}(\xi), i \mid (\xi, i \triangleright u) \in \text{NoUse}(C) \land i \leq s\} = \{\text{path}(\xi), i \mid (\xi, i \triangleright u) \in \text{NoUse}(C') \land i \leq s\} \)

8.2 Soundness and completeness

This section is dedicated to the proofs the soundness and completeness of our transformation rules.

8.2.1 Preliminaries

In our main proof of completeness and soundness, we usually assume an existing solution in a well-formed constraint system and then we transform this solution such that it become a solution of another constraint system. In most cases, the transformation consists of replacing a recipe by another one which deduces the same message. The main issue of this replacement is that the new recipe has to satisfy several properties such that the conformity to the frame, its belonging to \( \Pi_n, \ldots \).

**Example 8.1.** Let a constraint system with a the following frame:

\[ \{ax_1, 1 \triangleright \text{senc}(a, b); ax_2, 2 \triangleright \text{senc}(b, a); ax_3, 3 \triangleright a\} \]

A possible and natural execution of the rules would be to guess that the messages \( \text{senc}(a, b) \) and \( \text{senc}(b, a) \) are reducible and so by application of the rule Dest, we would have a constraint system such that:
Thus one possible solution for this constraint system would be \( \theta \) with \( X\theta = \text{sdec}(ax_2, ax_3) \) and \( Y\theta = ax_3 \). We can see that \( \theta \) belongs to \( \Pi_n \) and also conforms to the frame \( \Phi \).

Since the two recipes \( ax_3 \) and \( \text{sdec}(ax_2, Y) \) both deduce the same message, we could replace any instance of \( ax_3 \) by \( \text{sdec}(ax_1, X) \) and then forbid the use of the recipe \( ax_3 \) (equivalent to adding the frame element \( (ax_3, 3 \triangleright a) \) into the set \text{NoUse}).

Thus to ensure the soundness of this transformation, we need to ensure that we can transform \( \theta \) in \( \theta' \) such that \( \theta' \) is a solution of the constraint system and such that it satisfies the belonging to \( \Pi_n \) and the conformity to the frame. But on this example, the only way to deduce \( a \) (for the constraint \( 3 \triangleright a \)) without using \( ax_3 \) is to use the recipe \( \text{sdec}(ax_1, X) \) and the only way to deduce \( b \) (for the constraint \( 3 \triangleright b \)) is to use \( \text{sdec}(ax_2, Y) \) which produces a loop. Therefore, on this example, the replacement of the recipe \( ax_3 \) by \( \text{sdec}(ax_1, X) \), that deduces the same message, does not lead to a solution.

To formalise this, we introduce the following order.

**Definition 8.3** (relation \(<_\theta>\).) Let \( C = (S_1; S_2; \Phi; D; Eq; Er; ND; \text{NoUse}) \) be a well-formed constraint system, and \( \theta \) be a mapping from \( \text{vars}^2(C) \) to ground recipes such that for all \( (X, i \triangleright u) \in D \), we have that \( \text{param}(X\theta) \subseteq \{ax_1, \ldots, ax_i\} \).

We define a relation on \( \text{vars}^2(D) \), denoted \(<_\theta>\), as the smallest relation that is closed by transitivity and such that: \( X <_\theta Y \) if \( X \in \text{vars}^2(C[Y\theta]\text{acc}^2(C)) \) and \( X \neq Y \).

Intuitively, \( X <_\theta Y \) represents the fact that in the solution \( \theta \), \( X\theta \) is used in \( Y\theta \). Thus, if you replace \( X\theta \) by another recipe, the recipe \( Y\theta \) will also need to be changed accordingly in order to conform to the frame.

**Example 8.2.** Going back to our previous example, we have that \( Y <_\theta X \) since \( C[Y\theta]\text{acc}^2(C)) = \text{sdec}(ax_2, Y) \).

We stated at the beginning of this subsection that the replacement has to preserve the belonging to \( \Pi_n \). But a simple example with the application of the rule EQ-LEFT-RIGHT shows that it is generally not true.

**Example 8.3.** Let \( C \) be a constraint system with the following frame:

\[
\Phi = \{ ax_1, 1 \triangleright a; \ ax_2, 2 \triangleright \text{senc}(a, a); \ ax_3, 3 \triangleright a; \ \text{sdec}(ax_1, X) \triangleright a; \ \text{sdec}(ax_2, Y) \triangleright b \}
\]

and the following set of deducibility constraints:

\[
D = \{ X, 1 \triangleright \text{senc}(a, a); \ Y, 3 \triangleright a \}
\]

One possible solution for this constraint system would be \( \theta \) with \( X\theta = \text{senc}(ax_1, ax_1) \) and \( Y\theta = \text{sdec}(ax_2, ax_3) \). We can see that \( \theta \) belongs to \( \Pi_n \) and also conforms to the frame \( \Phi \). By applying the rule EQ-LEFT-RIGHT on \( (ax_2, 2 \triangleright \text{senc}(a, a)) \) and \( (X, 1 \triangleright \text{senc}(a, a)) \), the frame element \( (ax_2, 2 \triangleright \text{senc}(a, a)) \) will be added in the set \text{NoUse} and thus, we now have to replace each instance of \( ax_2 \) with \( X\theta \). But in such a case, \( Y\theta \) will become the recipe \( \text{sdec}(\text{senc}(ax_1, ax_1), ax_3) \) which does not belong to \( \Pi_n \). Thus, instead of just replacing \( ax_2 \) by \( \text{senc}(ax_1, ax_2) \), we will replace \( Y\theta \) with \( ax_1 \).
8.2. SOUNDNESS AND COMPLETENESS

8.2.2 Core lemmas

Let $\mathcal{C} = (S_1; S_2; \Phi; D; Eq; Er; ND; NoUse)$ be a constraint system. We denote by $\overline{\mathcal{C}}$ the constraint system $(S_1; S_2; \Phi; D; Eq; Er; \Phi; NoUse)$, i.e. the constraint system obtained from $\mathcal{C}$ by removing the non-deducible constraints. This notation is extended as expected to matrices of constraint systems. We first show the soundness of the normalisation of constraint system (Proof in Appendix C.5).

Lemma 8.4. Let $\mathcal{C}$ be a constraint system obtained by following the strategy. $\text{Sol}(\mathcal{C}) = \text{Sol}(\overline{\mathcal{C}})$.

As explained in Section 7.2, our algorithm transforms a pair of matrices of constraint systems into one or two pairs of matrices of constraint systems. The main idea behind the soundness and completeness is to locally prove that our transformation preserves the symbolic equivalence between matrices of constraint systems. Since we have several rules, we will need to prove the local preservation of the symbolic equivalence for each rule.

Lemma 8.5 (completeness). Let $\mathcal{C}$ be a normalised constraint system obtained by following the strategy and $\text{Rule}(_{\overline{\mathcal{C}}})$ be a transformation rule applicable on $\mathcal{C}$. Let $\mathcal{C}_1$ and $\mathcal{C}_2$ be the two resulting constraint systems obtained by applying $\text{Rule}(_{\overline{\mathcal{C}}})$ on $\mathcal{C}$. We denote by $\Phi$, $\Phi_1$ and $\Phi_2$ the respective frames of $\mathcal{C}_1$, $\mathcal{C}_1$ and $\mathcal{C}_2$ and we denote by $\mathcal{S}_i$ the set of free variable of $\mathcal{C}_i$.

For all $i \in \{1, 2\}$, for all $(\sigma_i, \theta_i) \in \text{Sol}(\mathcal{C}_i)$, $(\sigma, \theta) \in \text{Sol}(\mathcal{C})$ and $\text{Init}(\Phi)\sigma = \text{Init}(\Phi_i)\sigma_i$ where $\sigma = \sigma_i|_{\text{vars}_1(\mathcal{C})}$ and $\theta = \theta_i|_{\text{vars}_2(\mathcal{C})}$.

Variation: For all $i \in \{1, 2\}$, for all $(\sigma_i, \theta_i) \in \text{Sol}(\overline{\mathcal{C}_i})$, $(\sigma, \theta) \in \text{Sol}(\overline{\mathcal{C}})$ and $\text{Init}(\Phi)\sigma = \text{Init}(\Phi_i)\sigma_i$ where $\sigma = \sigma_i|_{\text{vars}_1(\overline{\mathcal{C}})}$ and $\theta = \theta_i|_{\text{vars}_2(\overline{\mathcal{C}})}$.

Lemma 8.6 (soundness). Let $\mathcal{C}$ be a normalised constraint system obtained by following the strategy and $\text{Rule}(_{\overline{\mathcal{C}}})$ be a transformation rule applicable on $\mathcal{C}$. Let $\mathcal{C}_1$ and $\mathcal{C}_2$ be the two resulting constraint systems obtained by applying $\text{Rule}(_{\overline{\mathcal{C}}})$ on $\mathcal{C}$. We denote by $\Phi$, $\Phi_1$ and $\Phi_2$ the respective frames of $\mathcal{C}_1$, $\mathcal{C}_1$ and $\mathcal{C}_2$ and we denote by $\mathcal{S}_i$ the set of free variables of $\mathcal{C}_i$.

Let $(\sigma, \theta) \in \text{Sol}(\mathcal{C})$. There exist $\sigma'$, $\theta'$, and $i_0 \in \{1, 2\}$ such that $(\sigma', \theta') \in \text{Sol}(\mathcal{C}_i)$, $\sigma = \sigma'|_{\text{vars}_1(\mathcal{C})}$ and $\theta = \theta'|_{\text{vars}_2(\mathcal{C})}$.

The proofs of Lemma 8.5 and 8.6 can be respectively found in Appendix C.3 and C.4. With the two previous lemmas (Lemma 8.5 and Lemma 8.6), we can see that our rules preserve the set of first-order solution of a constraint system. On the other hand, Lemma 8.6 indicates that it is possible that some second-order solutions are not preserved, for example the solution that use several recipe to deduce the same key. Even if the non-preservation of the whole set of second-order solutions could be surprising at first sight, the idea is to preserve enough second-order solutions to be able to establish symbolic equivalence (Lemma 8.7).

Lemma 8.7. Let $(\mathcal{C}, \mathcal{C}')$ be a pair of normalised constraint systems having the same structure and obtained by following the strategy. We denote by $\Phi$ and $\Phi'$ their associated variables. We denote by $S_1, S_1'$ their associated set of free variables. Let $\text{Rule}(_{\overline{\mathcal{C}'}})$ be a transformation rule applicable on $(\mathcal{C}, \mathcal{C}')$. Let $(\mathcal{C}_1, \mathcal{C}_1')$ and $(\mathcal{C}_2, \mathcal{C}_2')$ the two resulting pairs of constraint systems obtained by applying $\text{Rule}(_{\overline{\mathcal{C}'}})$ on $(\mathcal{C}, \mathcal{C}')$, and we transformation by $\Phi_1$, $\Phi_1'$, $\Phi_2$, and $\Phi_2'$ their respective frame.

Let $\sigma, \theta$ and $\sigma'$ be three substitutions such that $(\sigma, \theta) \in \text{Sol}(\mathcal{C})$, $(\sigma', \theta') \in \text{Sol}(\mathcal{C}')$, and $\Phi \sigma \sim \Phi' \sigma'$. For all substitution $\theta'$,

1. $(\sigma, \theta') \in \text{Sol}(\mathcal{C})$ if, and only, if $(\sigma', \theta') \in \text{Sol}(\mathcal{C}')$.

2. Let $i \in \{1, 2\}$, and $\sigma_i$ be a substitution such that $\sigma_i|_{S_i} = \sigma_i|_{S_1}$ and $\sigma_i, \theta' \in \text{Sol}(\mathcal{C}_i)$. Then, $(\sigma'_i, \theta') \in \text{Sol}(\mathcal{C}_i')$ for some substitution $\sigma'_i$ such that $\sigma_i|_{S_i} = \sigma_i'|_{S_i}$. Moreover, we have that $\text{Init}(\Phi_i)\sigma_i = \text{Init}(\Phi)|\sigma_i$ and $\text{Init}(\Phi'_i)\sigma'_i = \text{Init}(\Phi')|\sigma'_i$.

The proof of Lemma 8.7 can be found in Appendix C.5.
8.2.3 Application to matrices of constraint systems

Using the lemmas 8.5 and 8.6 and 8.7, we now establish completeness and soundness for pairs of linear matrices and for pairs of matrices.

Proposition 8.1. Let $V$, $V'$ be two row matrices of constraint systems obtained by following the strategy. Let Rule($\overline{p}$) be a transformation rule applicable on $(V, V')$. Let $(W_1, W'_1)$ and $(W_2, W'_2)$ be the two resulting pairs of matrices of constraint systems obtained by the application of Rule($\overline{p}$).

$$W_1 \approx_s W'_1 \text{ and } W_2 \approx_s W'_2 \text{ is equivalent to } V \approx_s V'$$

Proof. We prove the two directions of the equivalence separately. We assume w.l.o.g. that $V$ (resp. $V'$) is a row matrix of size $n$ (resp. $n'$). Let $V = [C_1, \ldots, C_n]$ and $V' = [C'_1, \ldots, C'_n]$. We know that $W_1$ and $W_2$ (resp. $W'_1$ and $W'_2$) are row matrices of size $n$ (resp. $n'$). Let $W_i = [C'_1, \ldots, C'_n]$ and $W'_j = [C'_1, \ldots, C'_n]$ for $i = 1, 2$.

Let $1 \leq j \leq n$ and $1 \leq k \leq n'$. We denote by $\Phi_j$ the frame associated to $C_j$ and by $\Phi'_j$ the frame associated to $C'_j$. Let $i \in \{1, 2\}$. Similarly, we denote by $\Phi^i_j$ the frame associated to $C^i_j$ and by $\Phi^i_k$ the frame associated to $C^i_k$.

Right implication: Let $1 \leq j \leq n$ and let $(\sigma, \theta) \in \text{Sol}(C_j)$. By Lemma 8.5, we know that there exists $\theta'$, $i \in \{1, 2\}$ and $\sigma_i$ such that $(\sigma, \theta') \in \text{Sol}(C^i_j)$ and $\sigma_i|_{S(C^i_j)} = \sigma|_{S(C_j)}$. By hypothesis, we have that $W_i \approx_s W^i_j$. Hence, there exist $1 \leq k \leq n'$ and a substitution $\sigma'_i$ such that $(\sigma'_i, \theta') \in \text{Sol}(C^i_k)$ and $\Phi^i_j \sigma_i \sim \Phi^i_k \sigma'_i$. Thanks to Lemma 8.5, we deduce that:

$$(\sigma_i|_{\text{vars}(C_j)}, \theta'|_{\text{vars}(C'_j)}) \in \text{Sol}(C_j) \text{ and } (\sigma'_i|_{\text{vars}(C'_j)}, \theta'|_{\text{vars}(C'_j)}) \in \text{Sol}(C'_k).$$

with $\text{Init}(\Phi'_j) \sigma_i = \text{Init}(\Phi^i_j) \sigma_i|_{\text{vars}(C_j)}$ and $\text{Init}(\Phi'_k) \sigma'_i = \text{Init}(\Phi^i_k) \sigma'_i|_{\text{vars}(C'_j)}$. Note that $\theta'|_{\text{vars}(C'_j)} = \theta'|_{\text{vars}(C'_j)}$ since $C_j$ and $C'_j$ have the same structure. Moreover, by hypothesis, we have that $\sigma = \sigma_i|_{\text{vars}(C_j)}$. Thus, we can apply Lemma 8.5 on $C_j$ and $C'_j$. Since $(\sigma, \theta') \in \text{Sol}(C_j)$, we deduce that $(\sigma', \theta') \in \text{Sol}(C'_j)$ where $\sigma' = \sigma'_i|_{\text{vars}(C'_j)}$. Lastly, since $\Phi'_j \sigma_i \sim \Phi^i_k \sigma'_i$, $\text{Init}(\Phi'_j) \sigma_i = \text{Init}(\Phi^i_k) \sigma_i$ and $\text{Init}(\Phi'_k) \sigma'_i = \text{Init}(\Phi^i_k) \sigma'_i$, we easily deduce that $\Phi'_j \sigma_i \sim \Phi^i_k \sigma'_i$. The other implication can be done in a similar way.

Left implication: Let $1 \leq j \leq n$, $i \in \{1, 2\}$ and let $(\sigma_i, \theta') \in \text{Sol}(C'_j)$. By Lemma 8.5, we know that there exists $\sigma$ and $\theta$ such that $(\sigma, \theta) \in \text{Sol}(C_j)$ with $\sigma = \sigma_i|_{\text{vars}(C_j)}$ and $\theta = \theta'|_{\text{vars}(C'_j)}$. By hypothesis, we have that $V \approx_s V'$. Hence, there exists $1 \leq k \leq n'$ and a substitution $\sigma'$ such that $(\sigma', \theta) \in \text{Sol}(C'_k)$ and $\Phi'_j \sigma_i \sim \Phi^i_k \sigma'_i$. Thus, we can apply Lemma 8.7 (second item) on $C_j$ and $C'_j$. Since $(\sigma, \theta') \in \text{Sol}(C_j)$, we deduce that $(\sigma'_i, \theta) \in \text{Sol}(C'_k)$ for some substitution $\sigma'$ such that $\sigma' = \sigma'_i|_{\text{vars}(C'_j)}$. Moreover, we have that $\text{Init}(\Phi'_k) \sigma_i = \text{Init}(\Phi'_j) \sigma_i$ and $\text{Init}(\Phi'_j) \sigma'_i = \text{Init}(\Phi'_k) \sigma'_i$. Since $\Phi'_j \sigma_i \sim \Phi^i_k \sigma'_i$, we easily deduce that $\Phi'_j \sigma_i \sim \Phi^i_k \sigma'_i$. The other implication can be done in a similar way.

Theorem 8.1 (Soundness and completeness for internal rules). Let $M_1$, $M'_1$ be two matrices of constraint systems obtained by following the strategy. Let Rule($\overline{p}$) be an internal transformation rule applicable on $(M_1, M'_1)$ on the $i$th. Let $(M_2, M'_2)$ be the resulting pair of matrices of constraint systems obtained by the application of Rule($\overline{p}$). We have that:

$$M_2 \approx_s M'_2 \text{ is equivalent to } M_1 \approx_s M'_1$$

Proof. Since $M_1$ and $M'_1$ have the same structure, we know that they have the same number of lines, say $m$. Let $M_1 = [V_1, \ldots, V_m]$ and $M'_1 = [V'_1, \ldots, V'_m]$. Let $(W_1, W'_1)$ and $(W_2, W'_2)$ be the two resulting pairs of row matrices of constraint systems obtained by applying Rule($\overline{p}$) on $(V_1, V'_1)$. Hence $M_2 = [W_1, \ldots, W_{i-1}, W_1, W_2, V_{i+1}, \ldots, V_m]$ and $M'_2 = [W'_1, \ldots, W'_{i-1}, W'_1, W'_2, V'_{i+1}, \ldots, V'_m]$.

By Definition 8.1 of the symbolic equivalence of matrices of constraint systems, $M_1 \approx_s M'_1$ is equivalent to $V_j \approx_s V'_j$ for every $j \in \{1, \ldots, m\}$. Thanks to Proposition 8.1, we easily deduce that $V_j \approx_s V'_j$ is equivalent to $W_1 \approx_s W'_1$ and $W_2 \approx_s W'_2$. This allows us to conclude.
Theorem 8.2 (soundness and completeness for external rules). Let \( M, M' \) be two matrices of well-formed constraint systems that have the same structure. Let RULE(\( \bar{p} \)) be an external transformation rule applicable on \((M, M')\). Let \((M_1, M'_1)\) and \((M_2, M'_2)\) be the two resulting pairs of matrices of constraint systems obtained by the application of RULE(\( \bar{p} \)). We have that:

\[
M_1 \approx_s M'_1 \text{ and } M_2 \approx_s M'_2 \text{ is equivalent to } M \approx_s M'
\]

Proof. Since \( M \) and \( M' \) have the same structure, we know that they have the same number of lines, say \( m \). Let \( M = [V_1, \ldots, V_m] \) and \( M' = [V'_1, \ldots, V'_m] \). When RULE(\( \bar{p} \)) is applicable on \((V_i, V'_i)\), let \((W_{i,1}, W'_{i,1})\) and \((W_{i,2}, W'_{i,2})\) be the two resulting pairs of row matrices of constraint system. Otherwise, let \((W_{i,1}, W'_{i,1}) = (\perp, \perp)\) and \((W_{i,2}, W'_{i,2}) = (V_i, V'_i)\). We have that:

- \( M_1 = [W_{1,1}, \ldots, W_{m,1}] \), \( M'_1 = [W'_{1,1}, \ldots, W'_{m,1}] \), and
- \( M_2 = [W_{1,2}, \ldots, W_{m,2}] \), \( M'_2 = [W'_{1,2}, \ldots, W'_{m,2}] \).

By Definition 7.12 of the symbolic equivalence of matrices of constraint systems, \( M \approx_s M' \) is equivalent to \( V_i \approx_s V'_i \) for every \( i \in \{1, \ldots, m\} \). Relying on Proposition 8.1 when the rule is effectively applied on \((V_i, V'_i)\) (when the rule is not applicable, the result trivially holds), we deduce that for every \( i \), \( V_i \approx_s V'_i \) is equivalent to \( W_{i,1} \approx_s W'_{i,1} \) and \( W_{i,2} \approx_s W'_{i,2} \) which is equivalent to \( M_1 \approx_s M'_1 \) and \( M_2 \approx_s M'_2 \). This allows us to conclude.

8.3 Leaves

In Section 8.2 we proved that all of our rules preserve the symbolic equivalence of matrices of constraint systems. Thus, since our strategy terminates (see Section 8.3.1), we know that for any initial pair of row matrices of constraint systems \((M_0, M'_0)\), we have that \( M_0 \approx_s M'_0 \) if, and only if, all leaves of a tree, whose root is labeled with \((M_0, M'_0)\), are symbolically equivalent. Thus to prove Theorem 8.2 we will have to prove that the predicate LeafTest is equivalent to the symbolic equivalence of a leaf.

The proofs of all the lemmas in this section can be found in Appendix C.6

8.3.1 Shape of the leaves

The purpose of our rules is to transform the constraint systems in the matrices into simpler constraint systems. The idea of simple constraint systems is not new, and was for example use in [CLCZ10] for their reachability algorithm. They introduce the notion of solved constraint system where a constraint system was in solved form if each right hand term of the constraints were a variable. In their algorithm, it was sufficient to prove the existence of at least one solution in a constraint system. But in our case, the right hand term variable condition is not sufficient to prove the symbolic equivalence between matrices. Thus, we introduce a new definition of solved constraint systems.

Definition 8.4 (solved constraint system). Let \( \mathcal{C} = (S_1; S_2; \Phi; D; Eq; Er; ND; NoUse) \) be a well-formed constraint system. We say that \( \mathcal{C} \) is a solved constraint system (or is in solved form) if \( \mathcal{C} \) satisfies InvVarConstraint(\( \infty \)), InvNoUse(\( \infty \)), InvVarFrame(\( \infty \)), InvDest(\( \infty \)), InvDedSub and:

1. \( Eq \) is a formula of the form \( \bigwedge_k u_k \stackrel{7}{=} v_k \bigwedge_i [V_j x_{i,j} \neq w_{i,j}] \) where \( w_{i,j} \in T(F_c, X^1) \), \( x_{i,j} \in X^1 \), \( u_k, v_k \in T(F_c, N \cup X^1) \).

2. for all \( X \in \text{vars}(D) \), for all \( f \in F_c \), for all \( \xi \) recipe of \( \Phi \), \( Er \not\exists X \neq \xi \) and \( Er \not\exists \text{root}(X) \).

We say that a constraint system \( \perp \) is always in solved formed.
CHAPTER 8. PROOF OF THE DECISION PROCEDURE

The definition of a solved constraint relies mainly on the invariant that we used for the termination proof. The last property ensure that no inequations on message contains any name. Thus we will be able to easily match those inequations with inequations on other constraint system. It comes directly from the fact that at the end of the strategy, all inequations in the constraint system have an entry in their association table.

Typically, all those properties correspond to the usual properties needed for deciding the symbolic equivalence:

- existence of a solution
- matching the solutions
- deciding the static equivalence

As we said previously, having the constraint systems in solved form on the leaves will help us deciding the symbolic equivalence. But Definition 8.4 only focuses on one constraint system and does not give any information on the link between constraint systems of the same pair of matrices on a leaf. We already know from Lemma 8.1 that all constraint systems on the matrices have the same shape and furthermore that all constraint systems on the same line have the same structure. But it is not sufficient to show that the predicate $\text{LeafTest}$ is equivalent to the symbolic equivalence. In fact, we need to simplify the matrices the same way we simplified the constraint systems. Thus, we define a notion of solved matrix of constraint systems which will describe all the links between constraint systems in the matrices.

Definition 8.5 (solved matrix of constraint systems). Let $(M, M')$ be a pair of matrices of constraint systems. We say that $(M, M')$ is in solved-form if $(M, M')$ satisfies $\text{InvMatrix}(\infty)$ and $\text{InvGeneral}$, all constraint systems in $(M, M')$ are in solved-form, and $\text{First order term properties on same column :}$

1. $\text{mgu}(\text{Eq}(C))|_{S_1(C) \rho} = \text{mgu}(\text{Eq}(C'))|_{S_1(C')}$, and $\text{D}(C) \rho = \text{D}(C')$;

2. $\{(u, v') | (\xi, i \triangleright u) \in \Phi \land (\xi', i' \triangleright v') \in \Phi' \land \text{path}(\xi) = \text{path}(\xi')\}$ is included in $\{(u, v) | u \in \mathcal{T}(F_{c', N \cup X^1})\}$;

First order term property : for all $C, C'$ constraint system in $(M, M')$, there exists a variable renaming $\rho : X^1 \sim S_1(C) \rightarrow X^1 \sim S_1(C')$ such that:

3. $\text{Eq}(M_{i,j}) \rho$ restricted to inequation and $\text{D}(M_{i,j}) \rho$ are equal to $\text{Eq}(M_{i,j'})$ restricted to inequation and $\text{D}(M_{i,j'})$.

The first properties of Definition 8.5 focus on the messages inside the constraint systems. Intuitively, Property [1] and [2] will help us to prove that all the constraint systems have the same set of first order solutions. To understand why this property holds, we need to come back to the creation of new lines in a matrix of constraint systems, and so to the application of internal rules. In Subsection 7.3.2 we describe the application of internal rules as a way to keep the result of the guesses on static equivalence inside a single matrix. Thus, it is natural that the first order solutions of different constraint systems in a same column are the same.

Property [3] indicates that there exists a matching on the inequations of message for all constraint systems in a same line. The purpose of this property is for us to prove that any substitution satisfying the inequations in one constraint systems will be match by an other first order substitution that satisfies the inequations in an other constraint systems.

Lemma 8.8. Let $(M, M')$ be a pair of matrix obtained at the end strategy. $(M, M')$ is in solved form.
8.3.2 Proving the symbolic equivalence

This last subsection focuses on the proof of that a pair of matrices of constraint system in solved form are symbolically equivalent if, and only if, they satisfy LeafTest.

First of all, it is not trivial to check if a constraint system in solved form has a solution. Intuitively, this is due to the presence of non-deducible constraint in our constraint system, even in solved form. On the other hand, if the non-deducible constraints were to be removed, one can easily show that any solved constraint system would have at least one solution. However, as explain in Section 7.3, Step e of Phase 1 of the strategy were specifically designed to solve the non-deducibility constraints. Indeed, in step e, we only kept the constraint systems whose non-deducible constraints could be satisfied. Hence, on a constraint system on a leaf, we show that any solution that does not consider the non-deducible constraints still satisfies them.

**Lemma 8.9.** Let \((M, M')\) be a pair of matrix obtained at the end strategy. For all constraint system \(C\) in \(M\) or \(M'\), \(\text{Sol}(C) = \text{Sol}(\overline{C})\).

Using this lemma, we can now show that any constraint system on a leaf that is different from \(\bot\) has at least one solution.

**Lemma 8.10.** Let \((M, M')\) be a pair of matrix obtained at the end strategy. Let \(C\) be a constraint system in \(M\) or \(M'\) different from \(\bot\). There exists \((\sigma, \theta)\) \(\in\) \(\text{Sol}(C)\).

In this section, we are interested in the symbolic equivalence of matrices of constraint systems. But in fact, when the matrices are in solved one, we can show that any constraint system in the same line of the matrices are symbolically equivalent.

**Lemma 8.11.** Let \((M, M')\) be a pair of matrix obtained at the end strategy. Let \(C, C'\) be two constraint system in the same line in \((M, M')\) (\(C\) and \(C'\) may be contained in the same matrix). If \(C \neq \bot\) and \(C' \neq \bot\) then \(C \approx_s C'\).

Using the previous lemma, we can finally prove that the pair of matrices on the leaves are symbolically equivalent if and only if they satisfy the final test.

**Theorem 8.3.** Let \((M, M')\) be a pair of matrix obtained at the end strategy. \(M \approx_s M'\) if, and only if, \(\text{LeafTest}(M, M') = \text{true}\).

**Proof.** Assume that \(M\) (resp. \(M'\)) has \(n\) lines and \(m\) (resp. \(m'\)) columns. We prove the two implications separately.

Left implication (\(\Leftarrow\)): Assume that \(\text{LeafTest}(M, M') = \text{true}\). Let \(i \in \{1, \ldots, n\}\) and \(j \in \{1, \ldots, m\}\). Let \((\sigma, \theta) \in \text{Sol}(M_{i,j})\). Since \(M_{i,j}\) contain a solution, we deduce that \(M_{i,j} \neq \bot\). Hence, thanks to \(\text{LeafTest}(M, M') = \text{true}\), there exists \(j' \in \{1, \ldots, m'\}\) such that \(M_{i,j'}' \neq \bot\). By Lemma 8.11 we deduce that \(M_{i,j} = M_{i,j'}'\). Thus, \((\sigma, \theta) \in M_{i,j}\) implies that there exists \(\sigma'\) such that \((\sigma', \theta) \in \text{Sol}(M_{i,j'})'\) and \(\Phi(M_{i,j})\sigma' \sim \Phi(M_{i,j'})\sigma'\). The other side of the equivalence is proved symmetrically. Therefore we deduce that \(M \approx_s M'\).

Right implication (\(\Rightarrow\)): Assume that \(M \approx_s M'\). We have to show that \(\text{LeafTest}(M, M') = \text{true}\). Let \(i \in \{1, \ldots, n\}\) and let \(j \in \{1, \ldots, m\}\). Assume that \(M_{i,j} \neq \bot\). Thanks to Lemma 8.11, we deduce that there exists \((\sigma, \theta) \in \text{Sol}(M_{i,j})\). But \(M \approx_s M'\), thus there exists \(j' \in \{1, \ldots, m'\}\) and \(\sigma'\) such that \((\sigma', \theta) \in \text{Sol}(M_{i,j'})'\) and \(\Phi(M_{i,j})\sigma' \sim \Phi(M_{i,j'})\sigma'\). Since \(M_{i,j'}'\) contain at least a solution, we deduce that \(M_{i,j'}' \neq \bot\). The other side of the equivalence is proved symmetrically. Therefore, we deduce that \(\text{LeafTest}(M, M') = \text{true}\).

8.4 Termination

In this section, we show how we prove that the strategy explained in Subsection 7.4 terminates. The proofs of all the lemmas in this section can be found in Appendix C.7.
8.4.1 Termination of all steps of Phase 1 of the strategy

In this subsection, we describe all the measures that we use to show the termination of each step of phase 1 of the strategy.

8.4.1.1 Termination of Phase 1, Step a

Step a of the strategy only consists of applying the rules DEST and EQ-LEFT-RIGHT. We first define a lexical measure on a constraint system \( C \), denote \( \mu_{1,a}(C) \), as follow: \( \mu_{1,a}(\perp) = (0, \emptyset, 0, 0) \), otherwise \( \mu_{1,a}(C) \) is the following quadruple.

1. \(|\text{vars}^1(D(C))|\)
2. the multiset \( \{ n \mid (\xi, i \triangleright u) \in \Phi(C) \land n = |\{ v \in \text{st}(u) \mid \text{root}(v) \in \{ \text{aenc}, \text{senc}, \}, \text{sign} \}\} \land \text{DEST}(\xi, \ell \rightarrow r, s) \text{ not useless} \} \)
3. \( |\Phi(C)| - |\text{NoUse}(C)| \)
4. \( |\{(X, \xi) \mid (X, i \triangleright u) \in D(C) \land (\xi, j \triangleright v) \in \Phi(C) \land \text{NoUse}(C) \land \text{Eq}(C) \not\models u = v\}| \)

Moreover, we define a measure on pair of matrices of constraint system, denoted \( \mu_{1,a}^m(M, M') \), such that such that \( \mu_{1,a}^m(M, M') = \{ \mu_{1,a}(C) \mid C \in M \lor C \in M' \} \).

Intuitively, the first item represents the number of first order variable in the deducible constraint of \( C \). An application of DEST during step \( a \) always preserves this number while an application of EQ-LEFT-RIGHT may decrease it strictly. The second item of this measure represents the subterms of the frame that may be deducible thanks to the applicable of the rule DEST. Typically when the application of DEST(\( \xi, \ell \rightarrow r, s \)) is useless, then no new subterm \( u \) in (\( \xi, \triangleright u \)) can be deduced thanks to DEST. The third item of the measure represents the number of frame elements that are not considered as useless. Lastly, the fourth item represents the possible parameters for which an application of EQ-LEFT-RIGHT is not useless.

**Lemma 8.12.** Let \((M_0, M'_0)\) be a pair of matrices obtained during Step a of Phase 1 of the strategy. Let \( R(\tilde{p}) \) one of the possible instances of DEST and EQ-LEFT-RIGHT applicable on \((M_0, M'_0)\). If we denote \((M_1, M'_1)\) the pair of matrices of constraint systems obtained by applying \( R(\tilde{p}) \) on \((M_0, M'_0)\), then \( \mu_{1,a}^m(M_1, M'_1) < \mu_{1,a}^m(M_0, M'_0) \).

8.4.1.2 Termination of Phase 1, Step b

As stated in Subsection 7.4 after step \( a \), the strategy alternates between step \( b \) and step \( c \). Thus, we have to show first that both steps terminates independently and then we have to show that the alternation of both steps terminates too. We remind the steps \( b \) and \( c \) have two parameter, i.e. the support of the rules \( s \) and also the current column \( k \) of the matrices.

We define a lexical measure on constraint system. Let \( C = (S_1; S_2; \Phi; D; \text{Eq}; \text{Er}; \text{ND}; \text{NoUse}) \) be a constraint system, we define a lexical measure on \( C \), denoted \( \mu_{1,b}(C) \), which is composed of:

1. The multiset \( \{ (X, f) \mid \text{Er} \not\models \text{root}(X ) \not\models f, (X, i \vdash u) \in D, u \in X^1, f \in F_c \text{ and there exists } g \in F_c \text{ such that } \text{Er} \models \text{root}(X ) \not\models g \} \} \).
2. The number of variables in the deducible constraints, i.e. \(|\text{vars}^1(D)|\).
3. The number of frame elements on which DED-ST is not useless
4. The number of pair of frame elements on which EQ-LEFT-LEFT is not useless
5. The number of function symbols and names in the right term of deducible constraints.
6. The number of \((X, f)\) such that \( \text{root}(X ) \not\models f \) not in \( \text{Er} \), \((X, i \vdash u) \in D \) and \( f \in F_c \).
7. The number of \((X, \xi)\) such that \((X, i \vdash u) \in D, (\xi, j \vdash v) \in \Phi, j \leq i\) and \(X \neq \xi\) is not in \(Er\).

8. The number of deducible constraints, i.e. \(|D|\).

By definition, if \(C = \perp\), we say that \(\mu_{1,b}(C) = (0, 0, 0, 0, 0, 0, 0)\).

**Lemma 8.13.** Let \(C\) be a well-formed constraint system satisfying the invariant \(\text{InvVarFrame}(s)\). Let \(R(\tilde{p})\) be any instance of any rules except Dest and Eq-Left-Right with support inferior to \(s\). Assume that \(R(\tilde{p})\) is strongly applicable on \(C\). Denote \(C_1\) and \(C_2\) the two constraint systems obtained by application of \(R(\tilde{p})\) on \(C\). The following property holds:

\[
\mu_{1,b}(C_1) < \mu_{1,b}(C) \land \mu_{1,b}(C_2) < \mu_{1,b}(C)
\]

We recall that during Step \(b\) with parameter \(s\) and \(k\) where \(k\) is the index of the column of \((M, M')\), an internal rule is applied on the \(i^{th}\) line of the matrices \((M, M')\) only if this rule is strongly applicable on constraint system on the \(i^{th}\) line and \(k^{th}\) column of \((M, M')\). Hence, for a pair of matrices of constraint system, we define a measure from \(\mu_{1,b}()\), denoted \(\mu^k_{1,b}()\), which is the following multiset:

\[
\mu^k_{1,b}(M, M') = \{\{\mu_{1,b}(C) \mid i \in \mathbb{N} \text{ and } C \text{ is on the } i^{th} \text{ line and } k^{th} \text{ column of } (M, M')\}
\]

Hence thanks to Lemma 8.13, we can deduce the following corollary.

**Corollary 8.1.** Let \((M_0, M'_0)\) be a matrix of constraint obtain during Step \(b\) of Phase 1 of the strategy with parameter \(s\) and \(k\). Let \(R(\tilde{p})\) be one of the possible instance of an internal rule of Step \(b\) with parameter \(s\) and \(k\). If we denote \((M_1, M'_1)\) the pair of matrices of constraint systems obtained by applying \(R(\tilde{p})\) on \((M_0, M'_0)\), then \(\mu^k_{1,b}(M_1, M'_1) < \mu^k_{1,b}(M_0, M'_0)\)

### 8.4. TERMINATION

#### 8.4.1.3 Termination of Phase 1, Step \(c\)

As explained in Section 7.3, the purpose of Step \(c\) is to definitely remove the internal deducible constraints in the matrices of constraint systems. Whereas the rules applied in Step \(b\) are internal, the rules applied in step \(c\) are mainly external which lead to more difficulties since an external rule modifies the all matrix. The application condition of a rule during this step of the strategy heavily depend on the subset \(X^1(C)\) which stock the right hand term variable of the deducible constraint whose second order variable are not in \(S_2(C)\). Hence the measure that we use to show the termination of this step also depend on it.

Let \(C = (S_1; S_2; \Phi; D; Eq; Er; ND; NoUse)\) be a constraint system, we define a lexical measure on \(C\), denoted \(\mu_{1,c}(C)\), which is composed by :

1. The multiset \(\{(j, p) \mid (X, i \vdash u) \in D(C), u|_p \in X^1(C), \text{ind}_C(u|_p) = j \text{ and } X \in S_2\}\).
2. The multiset \(\{(X, Y) \mid (X, s \vdash u) \in D(C), (Y, s \vdash v) \in D(C), X, Y \not\in S_2(C) \text{ and } u = v \in X^1\}\).
3. The number of \((X, f)\) such that \(Er \not\vdash \text{root}(X) \neq f, (X, i \vdash u) \in D, X \in S_2, f \in F_c\) and \(\text{vars}(u) \cap X^1(C) \neq \emptyset\).
4. The number of \((X, \xi)\) such that \((X, i \vdash u) \in D, (\xi, j \triangleright v) \in \Phi, j \leq i, Er \not\vdash X \neq \xi, X \in S_2\) and \(\text{vars}(u) \cap X^1(C) \neq \emptyset\).

By definition, if \(C = \perp\), we say that \(\mu_{1,c}(C) = (\emptyset, 0, 0, 0)\).

Furthermore, we define the following measure for matrices of constraint systems: Let \((M, M')\) be a pair of matrices of constraint systems. We define a measure from \(\mu_{1,c}()\), denoted \(\mu^k_{1,c}(M, M')\), which is the following multiset:

\[
\mu^k_{1,c}(M, M') = \{\{\mu_{1,c}(C) \mid i \in \mathbb{N} \text{ and } C \text{ is on the } i^{th} \text{ line and } k^{th} \text{ column of } (M, M')\}\}
Thanks to this measure, we are now able to show that the Step $c$ of Phase 1 of the strategy terminates with parameter $s$ and $k$.

**Lemma 8.14.** Let $(M, M')$ be a pair of matrices of constraint systems obtained during the Step $c$ of Phase 1 of the strategy with parameter $s$ and $k$ respectively for support and column. Let $R(p)$ be the next possible rule applicable according to Step $c$ of the strategy and let $(M_1, M_1')$ and $(M_2, M_2')$ be the two pairs of matrices of constraint systems obtained by application of $R(p)$ on $(M, M')$ (in the case of $R(p)$ being the rule EQ-RIGHT-RIGHT, there is only one pair of constraint system since EQ-RIGHT-RIGHT is applied internally). We have that:

$$
\mu_{1,c}^k(M_1, M_1') < \mu_{1,c}^k(M, M') \land \mu_{1,c}^k(M_2, M_2') < \mu_{1,c}^k(M, M')
$$

### 8.4.1.4 Termination of Phase 1, Cycle of steps $b$ and $c$

We previously showed that the Step $b$ and $c$ terminates. However, since after Step $c$, we apply once again Step $b$ as part of a cycle, it remains to prove that the cycle Step $b + Step c$ terminates. For this purpose, we define a measure on pair of matrices using $\text{ind}_c(\cdot)$. Let $(M, M')$ be a pair of matrices of constraint systems. Assume w.l.o.g. that the parameter $k$ corresponds to a column of $M$. We define a measure, denoted $\mu_{1, b+c}^k(M, M')$, such that:

$$
\mu_{1, b+c}^k(M, M') = \max \left\{ \text{ind}_c(u) \mid i \in \mathbb{N}, X \not\in S_2, (X, j \vdash u) \in D(C) \text{ and } C \text{ is on the } i^{th} \text{ line and } k^{th} \text{ column of } (M, M') \right\}
$$

We will first show that $\mu_{1, b+c}^k(M, M')$ can not increase for any application of rule during step $b$ and $c$. However, the strategy of Step $c$ will allow us to show that between the beginning of Step $c$ and the end of Step $c$, the measure strictly decreases. Indeed, at the beginning of Step $c$, every internal deducible constraints contain only variable as right hand term. Furthermore, we know that these deducible constraints can either be removed thanks to EQ-RIGHT-RIGHT or either be instantiated by the application of AXIOM. But the choice of the rule and its parameters are determined according to the minimal for $L^1(\cdot)$. Hence, in the case of the rule AXIOM, we always instantiate a variable $x$ by a term that can only contains variables appearing strictly at a earlier stage in the constraint system.

**Lemma 8.15.** Let $(M, M')$ be a pair of matrices of constraint systems obtained at the end of the Step $c$ of Phase 1 of the strategy with parameter $s$ and $k$ respectively for support and column. Let $(M_1, M_1')$ be a pair of matrices of constraint systems obtained by application on $(M, M')$ of Steps $b$ and $c$ with the same parameters. $\mu_{1, b+c}^k(M_1, M_1') < \mu_{1, b+c}^k(M, M')$.

### 8.4.1.5 Termination of Phase 1, Step $d$

As explained in Subsection 7.4, after the cycle of steps $b + c$, it remains to simplify the external deducible constraints such that they only have variables as right hand terms. To do so, we apply the external rules EQ-RIGHT-RIGHT, CONS and AXIOM as long as they are strongly applicable on $M_{i,k}$ by increasing order on the index of the line $i$ (if we assume that $k$ corresponds to an index of the matrix $M$ in the pair $(M, M')$).

To prove the termination of this cycle, we will use the measure $\mu_{1, d}(\cdot)$ on constraint system that was used in Step $b$. Thanks to Lemma 8.13, we know that the measure $\mu_{1, d}(\cdot)$ strictly decrease for a rule strongly applicable on a constraint system. Assume that $n$ is the number of line in $M$ and $M'$, we define a lexical measure on $(M, M')$, denoted $\mu_{1,d}(M, M')$, as follows:

1. The number $n - i_0$ where $i_0$ is the maximal index of the line such that for all $i \leq i_0$, $M_{i_0,k} = \bot$ or $M_{i,k}$ satisfies the invariant InvVarConstraint($s$)

2. $\mu_{1,d}(M_{i_0+1,k})$
3. The number of \((X, \text{path})\) such that \((X, i \rightarrow u) \in D(M_{l,k}), (\xi, j \rightarrow v) \in \Phi(M_{l,k}), j \leq i, X \not\in \xi\) is not in \(Er(M_{l,k}), X \in S_2, \text{path}(\xi) = \text{path}, \ell \in \{1, \ldots, n\}\) and there exist \(f \in \mathcal{F}_c\) such that \(\text{root}(X) \not\in f \in Er(M_{l,k})\)

We will assume for this measure that \(M_{n', k} = \perp\) where for all \(n' > n\).

**Lemma 8.16.** Let \((M, M')\) be a pair of matrices of constraint systems obtained during Step \(d\) of Phase 1 of the strategy with parameter \(s\) and \(k\) respectively for support and column. Furthermore, let \(R(p)\) be the next possible rule applicable according to step \(d\) of the strategy and let \((M_1, M'_1)\) and \((M_2, M'_2)\) be the two pairs of matrices of constraint systems obtained by application of \(R(p)\) on \((M, M')\). We have that:

\[
\mu_{k, d}(M_1, M'_1) < \mu_{k, d}(M, M') \land \mu_{k, d}(M_2, M'_2) < \mu_{k, d}(M, M')
\]

### 8.4.1.6 Termination of Phase 1, Step \(c\)

This phase does not need a termination proof since it only consists of modifying the constraint systems in the matrices, i.e. no rules are applied during Step \(c\).

### 8.4.2 Association table

We introduced in Subsection 7.3 the notion of association table. We described how they evolved during Step \(b\) and \(c\) of Phase 2. Hence, we will now show how the association tables are used for the termination proof of the cycles Step \(b + c\) of Phase 2.

First of all, we need to show some properties on association tables that are satisfied for each pair of matrices during Step \(b\) and \(c\).

**Lemma 8.17.** Let \((M, M')\) be a pair of matrices of constraint systems obtained during Step \(b\) or Step \(c\) of Phase 2 of the strategy. For all constraint systems \(C, C'\) in \((M, M')\) and their respective association tables \(T, T'\), for all \(\bigvee_i^n x_i \not\in v_i\), for all \(\bigvee_j^m \beta_j \not\in \beta'_j\), if \(T[\bigvee_i^n x_i \not\in v_i] = T'[\bigvee_j^m \beta_j \not\in \beta'_j]\), then we have that:

\[
\left(\bigvee_j^m \beta_j \mathbf{acc}^1(C) \not\in \beta'_j \mathbf{acc}^1(C)\right) \downarrow = \bigvee_i^n x_i \not\in v_i
\]

Moreover, if \(T[\bigvee_i^n x_i \not\in v_i] = T'[\bigvee_j^m \beta_j \not\in \beta'_j]\) and for all \(k \in \{1, \ldots, m\}\), \(s\beta_j, \beta'_j) \cap (\mathcal{F}_d^t \cdot \mathcal{A}X) = \emptyset\) then there exists \(\bigvee_i^n x_i \not\in v_i\) such that \(T'[\bigvee_i^n x_i \not\in v_i] = \bigvee_j^m \beta_j \not\in \beta'_j\).

We now describe the main property that will never increase during Step \(b\) and \(c\) of Phase 2. In the next paragraphs, we will show that this measure necessary decrease after one cycle Step \(b + c\). For a inequation \(u \not\in v\) in \(Eq(C)\), we define a measure, denoted \(L_C^1(u \not\in v)\) such that \(L_C^1(u \not\in v) = \{\ind_C(u); \ind_C(v)\}\). We extend this measure to disjunction of inequations such that:

\[
L_C^1(\bigvee_i^n u_i \not\in v_i) = \max\{L_C^1(u_i \not\in v_i) \mid i = 1 \ldots n\}
\]

We defined a similar measure for inequation of context of recipe, denoted \(L_C^2()\), such that \(L_C^2(\beta \not\in \beta') = \{\text{param}_C_{\max}(\beta); \text{param}_C_{\max}(\beta')\}\). Furthermore, we also extend this notion to disjunction of inequations such that:

\[
L_C^2(\bigvee_i^n \beta_i \not\in \beta'_i) = \max\{L_C^2(\beta_i \not\in \beta'_i) \mid i = 1 \ldots n\}
\]

The two measures \(L_C^1()\) and \(L_C^2()\) are related as shown in the next lemma.
Lemma 8.18. Let $C$ be a well-formed constraint system satisfying $\text{InvVarConstraint}(\infty)$. Let $\beta, \beta'$ be two contexts of recipes such that $\beta, \beta' \in T(F_c \cup (F_d \cdot AX), AX^2)$. We have that $L^1_k(\beta \text{acc}^1(C) \neq \beta' \text{acc}^1(C)) \leq L^2_k(\beta \neq \beta')$. Furthermore, if $\beta \in (F_d \cdot AX)$ or $\beta' \in (F_d \cdot AX)$, then we have that $L^1_k(\beta \text{acc}^1(C) \neq \beta' \text{acc}^1(C)) < L^2_k(\beta \neq \beta')$.

We define the general measure on matrices, denote $\mu_{\text{gen}}()$, such that: Let $(M, M')$ be a pair of matrices of constraint systems, having the same structure and satisfying $\text{InvVarConstraint}(\infty)$. Let $S$ be the set defined such that

$$S = \{ D \mid T[E] = D \text{ for some association table } T \text{ in } (M, M') \text{ and some } E \}$$

In a pair $(M, M')$, a same formula on context of recipes may appear several times in the association tables of $(M, M')$. The set $S$ represents the set of all these different formulas on contexts of recipes. Let $C_0$ be a constraint system in $(M, M')$ such that $C_0 \neq \bot$. We have:

$$\mu^1_{\text{gen}}(M, M') = \left\{ \begin{array}{l} L^1_k(D) \mid C \text{ is its association table } T \text{ are in } M \text{ or } M' \\ Eq(C) = E \land D, \text{ for some } E \text{ and some disjunction } D \\ T[D] = \bot \end{array} \right\}$$

$$\mu^2_{\text{gen}}(M, M') = \left\{ \begin{array}{l} L^2_{\text{gen}}(D') \mid D' \in S \end{array} \right\}$$

$$\mu_{\text{gen}}(M, M') = \mu^1_{\text{gen}}(M, M') \cup \mu^2_{\text{gen}}(M, M')$$

Intuitively, $\mu^1_{\text{gen}}(M, M')$ represents the measure for the inequation that are not matched by the EQ-RIGHT-RIGHT rule yet. On the other hand, $\mu^2_{\text{gen}}(M, M')$ represents the measure for the inequation that were matched at one point in the strategy by the rule EQ-RIGHT-RIGHT.

Lemma 8.19. Let $(M, M')$ be a pair of matrices of constraint systems obtained during Step b or Step c of Phase 2 of the strategy. Let $R(\tilde{p})$ be one of the following external rules: AXIOM, CONS, EQ-RIGHT-RIGHT. Let $(M_1, M'_1)$ and $(M_2, M'_2)$ be the results of the application of $R(\tilde{p})$ on $(M, M')$. We have that:

$$\mu_{\text{gen}}(M_1, M'_1) \leq \mu_{\text{gen}}(M, M') \text{ and } \mu_{\text{gen}}(M_2, M'_2) \leq \mu_{\text{gen}}(M, M')$$

Furthermore, for $i = 1, 2$, if a removal transformation was applied on the association table of $(M_i, M'_i)$ then $\mu_{\text{gen}}(M_i, M'_i) < \mu_{\text{gen}}(M, M')$.

8.4.3 Termination of all steps of Phase 2 of the strategy

In this subsection, we describe all the measures that we use to show the termination of each step of phase 2 of the strategy.

8.4.3.1 Termination of Phase 2, Step a

This step of the strategy consists of getting rid of the universal variable. Thus, to show that this step terminate, we introduce a measure on the formulas $Eq$ of the constraint systems that checks the positions of all the universal variables in $Eq$. Let $(M, M')$ be a pair of matrices of constraint systems, we define a lexical measure, denoted $\mu_{2,a}(M, M')$, which is composed of:

1. The multiset of the position of any occurrence of universal variables in $Eq(C)$, for any constraint system $C$ in $M$ and $M'$, i.e. \{ $p \mid Eq(C) = E' \land [\forall \tilde{y}. \forall x. E'' \lor u \neq v] \land w_{ip} = x \text{ and } C \text{ in } (M, M')$ \}

2. The number of $(X, f)$ such that root$(X) \neq f$ not in $Er$, $X, i \vdash u \in D(C), f \in F_c$ and $C$ in $(M, M')$.  


3. The number of \((X, \xi)\) such that \(X, i \vdash u \in D, \xi, j \vdash v \in \Phi, j \leq i, X \neq \xi\) is not in \(Er(C)\) and \(C\) in \((M, M')\).

Thanks to this measure we are now able to prove the termination of Step a of Phase 2.

**Lemma 8.20.** Let \((M, M')\) be a pair of matrices of constraint systems obtained during Step a of Phase 2 of the strategy. Let \(R(\tilde{p})\) be one instance of the rule Axiom or Cons such that \(R(\tilde{p})\) is strongly applicable on at least one constraint system in \(M\) or \(M'\). The main difficulty of the termination of this step is the fact that

\[
\begin{align*}
\mu_{2,a}(M_1, M'_1) &< \mu_{2,a}(M, M') \quad \land \quad \mu_{2,a}(M_2, M'_2) < \mu_{2,a}(M, M')
\end{align*}
\]

**8.4.3.2 Termination of Phase 2, Step b**

This step consists of applying the rules Cons and Eq-right-right as long as we can by decreasing support. The main difficulty of the termination of this step is the fact that Cons introduces new variables while Eq-right-right removes variables but also introduces new inequations in each constraint systems.

In order to prove the termination of this step, we have to introduce a new measure on a pair of matrices \((M, M')\), denoted \(\mu_{2,b}(M, M')\), defined such that if \(n\) is the maximal size of the frame in \(M, M'\), then \(\mu_{2,b}(M, M')\) is the tuple composed of:

- \(\mu_{gen}(M, M')\)
- The number of disjunctions \(D\) such that \(Eq(C) = D \land E\) and \(T[D] = \bot\), for some constraint system \(C\) and its associative table \(T\) in \(M\) or \(M'\).
- The number of disjunctions \(D\) such that \(Eq(C) = D \land E\) and \(T[D] = D'\) and \(st(D') \cap (F^*_d \cup A \cup X) \neq \emptyset\), for some constraint system \(C\) and its associative table \(T\) in \(M\) or \(M'\).
- \((\mu_{cons}^0(M, M'), \mu_{var}^0(M, M') \ldots \mu_{cons}^1(M, M'), \mu_{var}^1(M, M'))\)
- The multiset of \((X, \xi)\) such that \(C\) is in \(M\) or \(M'\): \((X, i \vdash x) \in D(C)\), \(Er(C) \not\vDash root(X)\), and there exists \(g \in F_c\) such that \(Er(C) \vDash root(X) \neq g\).

where for all \(i \in \{1, \ldots, n\}\), \(\mu_{var}^i(M, M')\) and \(\mu_{cons}^i(M, M')\) are defined as follows:

\[
\begin{align*}
\mu_{var}^i(M, M') &= |\{x \in \text{vars}^1(C) | C \text{ in } M \text{ or } M', \text{ and } \text{ind}_C(x) = i\}| \\
\mu_{cons}^i(M, M') &= \mu_{cons,1}^i(M, M') \cup \mu_{cons,2}^i(M, M')
\end{align*}
\]

\[
\begin{align*}
\mu_{cons,1}^i(M, M') &= \{ (h_a, h_b) | \begin{array}{l}
\text{C is in M or M'} with T its association table,} \\
\text{Eq(C) = E \land (D \lor \forall v \not\in \forall v) = \bot,} \\
(X, i \vdash x) \in D(C), \text{ root}(v) \in F_c,} \\
Er(C) \not\vDash root(X),} \\
either st(v) \cap N \neq \emptyset \text{ or } i < \text{ind}_C(v),} \\
h_a = \max\{h(p) | v|p \in N\},} \\
h_b = \max\{h(p) | v|p \in A\} i < \text{ind}_C(v|p)\}
\end{array} \}
\end{align*}
\]
Lemma 8.21. Let \((M, M')\) be a pair of matrices of constraint systems obtained during Step b of the second phase. Let \(R(p)\) be an applicable rule and \((M_1, M'_1)\) and \((M_2, M'_2)\) the two pairs of matrices of constraint systems obtained by application of \(R(p)\) on \((M, M')\). We have that:

\[
\mu_{2,b}(M_1, M'_1) < \mu_{2,b}(M, M') \quad \text{and} \quad \mu_{2,b}(M_2, M'_2) < \mu_{2,b}(M, M')
\]

8.4.3.3 Step c: Instantiating the variables

In this paragraph, we show that Step c terminates and we also shows that the general measure, i.e. \(\mu_{\text{gen}}()\), strictly decrease at some point.

The measure used to prove termination of Step c is very simple. Indeed, during Step c, we only apply the rule AXIOM which either decrease the number of deducible constraint or add a disequation on recipe. Let \((M, M')\) be a pair of matrices of constraint systems, let \(C_0\) a constraint system in \(M\) or \(M'\) such that \(C_0 \neq \bot\), we define a lexical measure \(\mu_{2,c}(M, M')\), as follows:

1. The number of deducible constraints, i.e. \(|D(C_0)|\)

2. The number of couple \((X, \xi)\) such that \((X, i \vdash x) \in D(C_0), (\xi, j \triangleright u) \in \Phi(C_0)\) and \(\text{Er}(C_0) \not\models X \neq \xi\).

Thanks to this measure, we can now state the termination lemma.

Lemma 8.22. Let \((M, M')\) be a pair of matrices of constraint systems obtained during Step c of the second phase. Let AXIOM\((p)\) be an applicable rule and \((M_1, M'_1)\) and \((M_2, M'_2)\) the two pairs of matrices of constraint systems obtained by application of AXIOM\((p)\) on \((M, M')\). We have that:

\[
\mu_{2,c}(M_1, M'_1) < \mu_{2,c}(M, M') \quad \text{and} \quad \mu_{2,c}(M_2, M'_2) < \mu_{2,c}(M, M')
\]

It remains to show that the measure \(\mu_{\text{gen}}()\) strictly decrease at some point.

Lemma 8.23. Let \((M, M')\) be a pair of matrices of constraint systems obtained at the end of Step b of the second phase. Assume that there exists \((M_1, M'_1)\) obtained at the end of the next Step b of the second phase such that \((M, M') \rightarrow^*(M_1, M'_1)\). At last, assume that there exists \((M_0, M'_0)\) obtained at the end of step c of the second phase such that \((M_1, M'_1) \rightarrow^*(M_0, M'_0)\). In such a case, \(\mu_{\text{gen}}(M_0, M'_0) < \mu_{\text{gen}}(M, M')\).
8.5 Toward a more powerful attacker

In this section, we explore the possibility of extending the power of the attacker to not only equality test between two messages. Indeed, an attacker may in fact have other ways to compare two messages such as comparing the size of messages. Some encryption scheme also allow one to check if two cyphers were encrypted under the same key, without necessarily know the key or plain text themselves. In this section, we do not pretend to solve the trace equivalence with such attacker but we show a reduction result that simplify such problem.

8.5.1 Semantic with predicate

To model the new capabilities of the attacker, we will consider a predicate \( \mathcal{P} \) of on ground first order terms. For example, in the case of cyphers encrypted with the same key, we would consider that \( \mathcal{P}(u, v) \) is true if and only if \( u = \text{senc}(u', k) \) and \( v = \text{senc}(v', k) \) for some \( u', v', k \). For a substitution \( \sigma \), and two term \( u, v \), we say \( \mathcal{P}(u, v) \) is satisfied, denoted \( \sigma \models \mathcal{P}(u, v) \) if and only if \( \mathcal{P}(u_\sigma, v_\sigma) \) is true.

With this new predicate available for the intruder, we have to redefine the notion of static equivalence, trace equivalence and so on:

**Definition 8.6** (static equivalence w.r.t. \( \mathcal{P} \)). Let \( \mathcal{E} \) a set of private names. Let \( \Phi \) and \( \Phi' \) two frames. We say that \( \nu\mathcal{E}.\Phi \) and \( \nu\mathcal{E}.\Phi' \) are statically equivalent w.r.t. the predicate \( \mathcal{P} \), written \( \nu\mathcal{E}.\Phi \equiv^\mathcal{P} \nu\mathcal{E}.\Phi' \), when \( \text{dom}(\Phi) = \text{dom}(\Phi') \), when \( \nu\mathcal{E}.\Phi \equiv_c \nu\mathcal{E}.\Phi' \), and when for all terms \( M, N \) such that \( \text{fvars}(M, N) \subseteq \text{dom}(\Phi) \) and \( \text{frames}(M, N) \cap \mathcal{E} = \emptyset \), if \( \text{Message}(M\Phi) \) and \( \text{Message}(N\Phi) \), then \( \mathcal{P}(M\Phi, N\Phi_\downarrow) \) is true if and only if \( \mathcal{P}(M\Phi_\downarrow, N\Phi_\downarrow) \) is true.

As expected, the static equivalence w.r.t. \( \mathcal{P} \) implies the static equivalence while the other implication is not true.

**Definition 8.7** (trace equivalence w.r.t. \( \mathcal{P} \)). Let \( A \) and \( B \) be processes with the same set of private names \( \mathcal{E} \). \( A \equiv^\mathcal{P} B \) if for every \( (s, \nu\mathcal{E}.\Phi) \in \text{trace}_\mathcal{P}(A) \), there exists \( (s, \nu\mathcal{E}.\Phi') \in \text{trace}(B) \) such that \( \nu\mathcal{E}.\Phi \equiv^\mathcal{P} \nu\mathcal{E}.\Phi' \).

Two closed processes \( A \) and \( B \) are trace equivalent w.r.t. the predicate \( \mathcal{P} \), denoted by \( A \equiv^\mathcal{P}_\mathcal{P} B \), if \( A \equiv^\mathcal{P}_\mathcal{P} B \) and \( B \equiv^\mathcal{P}_\mathcal{P} A \).

8.5.2 Toward deciding the trace equivalence w.r.t. a predicate

Intuitively, to decide the trace equivalence w.r.t. \( \mathcal{P} \), we would have to go through all the lemma and theorem of this part. Hopefully, some of these lemma either does not depend on the static equivalence or only consider the static equivalence as hypothesis. Since the static equivalence w.r.t. \( \mathcal{P} \) implies the static equivalence, most of the lemma are easily adaptable.

In particular, we first reduce the problem of trace equivalence w.r.t. the predicate \( \mathcal{P} \), to the problem of deciding the symbolic equivalence between set of constructor constraint system. In order to do that, we first have to define again the static equivalence for constructor frame and the symbolic equivalence between set of constraint system.

**Definition 8.8** (static equivalence w.r.t. \( \mathcal{P} \)). Two ground constructor frames \( \Phi \) and \( \Phi' \) are statically equivalent w.r.t. the predicate \( \mathcal{P} \), denoted \( \Phi \equiv^\mathcal{P} \Phi' \), if and only if \( \text{dom}(\Phi) = \text{dom}(\Phi') \), \( \Phi \equiv_c \Phi' \) and for all \( \xi, \xi' \in \Pi_n \), if \( \text{param}((\xi, \xi')) \subseteq \text{dom}(\Phi) \) and \( \xi\Phi_\downarrow, \xi'\Phi_\downarrow \in \mathcal{T}(\mathcal{F}_c, \mathcal{N}) \), then \( \mathcal{P}(\xi\Phi_\downarrow, \xi'\Phi_\downarrow) \) is equivalent to \( \mathcal{P}(\xi'\Phi_\downarrow, \xi\Phi_\downarrow) \).

**Definition 8.9** (symbolic equivalence w.r.t. \( \mathcal{P} \)). Two sets \( \Sigma \) and \( \Sigma' \) of constructor constraint systems having the same structure are symbolically equivalent w.r.t. predicate \( \mathcal{P} \), denoted \( \Sigma \equiv^\mathcal{P} \Sigma' \), if and only if for all \( \xi \in \Sigma \), for all \( (s, \theta) \in \text{Sol}(\xi) \), there exists \( \xi' \in \Sigma' \) and a substitution \( \sigma' \) such that \( (s', \theta) \in \text{Sol}(\xi') \) and \( \Phi\sigma \equiv^\mathcal{P} \Phi'\sigma' \) (and conversely) where \( \Phi \) and \( \Phi' \) are the respective frames of \( \Sigma \) and \( \Sigma' \).
As mentioned, to show that deciding trace equivalence w.r.t. the predicate $P$ can be reduced to the problem of deciding symbolic equivalence w.r.t. the predicate $P$, we follow the same step as for the proof of Theorem 6.2. In particular, we show in Section 6.3.1.2 how it is possible to consider that the attacker does not have access to public name. This is possible thanks to a mobilisation of infinite names. To follow this modelisation, we ask that the predicate we consider satisfy the following property:

**Property 8.1.** Let $E$ be a finite set of names. For all $u, v$ closed constructor terms, there exists $N \in \mathbb{N}$ such that for all $N' > N$, $P(u, v)$ if and only if $P(u\sigma_{E,N,a}, v\sigma_{E,N,a})$.

Intuitively, this property ensures that the terms that model our infinite names cannot be distinguish by the predicate. We can then state the first reduction result:

**Lemma 8.24.** Let $P$ be a predicate on first order term satisfying Property 8.1. Given a decision procedure for the symbolic equivalence w.r.t. $P$ of sets of constructor constraint systems, the problem of trace equivalence w.r.t. $P$ between two concrete processes is decidable.

### 8.5.3 Toward deciding the symbolic equivalence w.r.t. a predicate

As in the previous section, the idea for deciding the symbolic equivalence w.r.t. a predicate is to use our decision procedure. In particular, we can easily show that the soundness and completeness of our algorithm holds for the symbolic equivalence w.r.t. a predicate $P$. Indeed, one can note that the core lemmas 8.4, 8.5, 8.6 and 8.7 still hold. Moreover, one can easily adapt the proof of Proposition 8.1 and Theorems 8.1 and 8.2, by replacing the static equivalence $\sim$ by $\sim^P$ and the symbolic equivalence $\approx_s$ by $\approx^P_s$.

Hence, since the soundness and completeness hold even for the symbolic equivalence w.r.t. a predicate, we reduced the problem to the problem of deciding the symbolic equivalence w.r.t. a predicate on the leaves of our algorithm. Although the properties of such leaves are described in detail in Section 8.3, we simplify in this section the formalism of such leaves and extract our main reduction result.

Consider the definition of a solved constraint system (Definition 8.4). We know thanks to Lemma 8.8 that every constraint system in a leaf satisfies this definition. But item 2 indicates that no deductibility constraint is restricted by an equation on second order solution. Moreover, we know that all constraint system in a line of the matrix have same set $E_r$. Hence, the sets $E_r$s of the constraint systems on the leaves does not have any impact on the decidability of symbolic equivalence w.r.t. $P$ of two sets on a leaf. Similarly, we know that all equation in $Eq$ is automatically satisfied once the variable in $D$ are instantiate. By extending this reasoning to all the invariant satisfied by the constraint system on a leaf, we can define the notion of simplified constraint system and the notion of solution of simplified constraint system

**Definition 8.10.** A simplified constraint system is a triple $(\Phi; D; Eq)$:

- $\Phi$ is a simplified frame $\{\xi_1 \triangleright u_1, \ldots, \xi_n \triangleright u_n\}$ where $u_i$ are constructor terms and $\xi_i$ are recipes.
- $D$ is a set of deducible constraints of the form $X_i \vdash x$ with $i \in \mathbb{N}$, $X \in \mathcal{A}^2$, $x \in \mathcal{A}^1$.
- $Eq$ is a set of inequations of the form $t \neq t'$ where $t, t'$ are constructor terms that do not contain names.

We also assume the following conditions are satisfied on a constraint system:

1. For every $x \in \text{vars}^1(D)$, there exists a unique $X$ such that $(X, i \vdash x) \in D$, and each variable $X$ occurs at most once in $D$.
2. $\text{vars}^1(C) \subseteq \text{vars}^1(D)$
3. for every $1 \leq k \leq n$, for every $x \in \text{vars}^1(t_k)$, if $ax_j \in \text{vars}^2\xi_k$ then there exists $(X, i \vdash x) \in D$ such that $i < j$.

Given a simplified frame $\Phi = \{\xi_1 \triangleright t_1, \ldots, \xi_n \triangleright t_n\}$ and a recipe $\xi$, we say that $\xi$ is build from $\Phi$ if there exists a context $C[\xi_1, \ldots, \xi_m]$ containing only constructor function symbol and $j_1, \ldots, j_m \in \{1, \ldots, n\}$ such that $\xi = C[\xi_{j_1}, \ldots, \xi_{j_m}]$. Moreover, we denote $\xi \Phi$ the term $C[t_{j_1}, \ldots, t_{j_m}]$.

**Definition 8.11 (solution).** A solution of a simplified constraint system $\mathcal{C} = (\Phi; D; \text{Eq})$ is a pair of substitutions $(\sigma, \theta)$ such that $\sigma$ is a mapping from $\text{vars}^1(\mathcal{C})$ to $\mathcal{T}(\mathcal{F}, \mathcal{N})$, $\theta$ is a mapping from $\text{vars}^2(\mathcal{C})$ to $\mathcal{T}(\mathcal{F}, \mathcal{AX})$, and:

1. for all $(X, k \vdash x) \in D$, $X \theta$ is built from $\Phi \theta$, $(X \theta)(\Phi \sigma) = x \sigma$, and $\text{param}(X \theta) \subseteq \{ax_1, \ldots, ax_k\}$;

2. for all $t \neq t'$, $t \sigma \neq t' \sigma$.

The substitution $\sigma$ is called the first-order solution of $\mathcal{C}$ associated to $\theta$, called second-order solution of $\mathcal{C}$. The set of solutions of a constraint system $\mathcal{C}$ is denoted $\text{Sol}(\mathcal{C})$.

Note that in the solution of a constraint system, we only consider the recipe that are built from $\Phi$, i.e., that are built from a constructor context over $\Phi$. In fact in the constraint system on a leave, it is also the case due to the invariant $\text{InvDest}(\infty)$. Similarly, in the definition of simplified constraint system, we only considered distinct variables as right hand term for variables thanks to the invariant $\text{InvVarConstraint}(\infty)$.

**Definition 8.12 (simplified static equivalence).** Let $\Phi$ and $\Phi'$ two closed simplified frames having the same structure. We say that $\Phi$ and $\Phi'$ are in simplified static equivalence if for all $\xi, \xi'$ built from $\Phi$ (thus also built from $\Phi'$), $\xi \Phi = \xi' \Phi'$ if and only if $\xi \Phi' = \xi' \Phi'$. Moreover, we say that $\Phi$ and $\Phi'$ are in simplified static equivalent w.r.t. the predicate $\mathcal{P}$, denoted $\Phi \sim^P \Phi'$ if $\Phi$ and $\Phi'$ are in simplified static equivalence and for all $\xi, \xi'$ built from $\Phi$, $\mathcal{P}(\xi \Phi, \xi' \Phi)$ if and only if $\mathcal{P}(\xi \Phi', \xi' \Phi')$.

**Definition 8.13 (simplified symbolic equivalence).** Let $\Sigma$ and $\Sigma'$ be two sets of simplified constraint systems that contain constraint systems having the same structure. We say that $\Sigma$ and $\Sigma'$ are in simplified symbolic equivalence, denoted by $\Sigma \approx_{\Sigma} \Sigma'$, if for all $\Sigma \in \Sigma$, for all $(\sigma, \theta) \in \text{Sol}(\mathcal{C})$, there exists $\mathcal{C}' \in \Sigma'$ and a substitution $\sigma'$ such that $(\sigma', \theta) \in \text{Sol}(\mathcal{C}')$ and $\Phi \sigma \sim \Phi' \sigma'$ (and conversely) where $\mathcal{C} = (\Phi; D; \text{Eq})$ and $\mathcal{C}' = (\Phi'; D'; \text{Eq}')$.

We say that $\Sigma$ and $\Sigma'$ are in simplified symbolic equivalence w.r.t. the predicate $\mathcal{P}$, denoted by $\Sigma \approx^P_{\Sigma} \Sigma'$, if for all $\Sigma \in \Sigma$, for all $(\sigma, \theta) \in \text{Sol}(\mathcal{C})$, there exists $\mathcal{C}' \in \Sigma'$ and a substitution $\sigma'$ such that $(\sigma', \theta) \in \text{Sol}(\mathcal{C}')$ and $\Phi \sigma \sim^P \Phi' \sigma'$ (and conversely) where $\mathcal{C} = (\Phi; D; \text{Eq})$ and $\mathcal{C}' = (\Phi'; D'; \text{Eq}')$.

With this simpler formalism, we can establish our main reduction result:

**Theorem 8.4.** Consider a predicate $\mathcal{P}$ that satisfies Property 8.1. Given an algorithm for deciding the simplified symbolic equivalence w.r.t. $\mathcal{P}$ between two sets of simplified constraint systems $\Sigma$ and $\Sigma'$ that contain constraint systems having the same structure and such that there exists $a \in \mathcal{N}$ such that for all $(\Phi; D; \text{Eq}) \in \Sigma \cup \Sigma'$, $(ax_1 \triangleright a) \in \Phi$, and for all $\mathcal{C}, \mathcal{C}' \in \Sigma \cup \Sigma'$, $\mathcal{C} \sim_{\Sigma} \mathcal{C}'$, $D = D'$ and $\text{Eq} = \text{Eq}'$ where $\mathcal{C} = (\Phi; D; \text{Eq})$ and $\mathcal{C}' = (\Phi'; D'; \text{Eq}')$, we can derive an algorithm for deciding trace equivalence w.r.t. $\mathcal{P}$ between two bounded processes.
Part III

ProVerif
Chapter 9

Proving more observational equivalences with ProVerif

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ProVerif was first a protocol analyser for trace properties. It implements an algorithm, based on Horn clauses, that accepts protocols written in the applied pi-calculus. The behaviour of the cryptographic primitives is represented by an equational theory and/or rewrite rules. One reason for the success of this tool may come from the fact that ProVerif does not depend on a specific equational theory and allows the user to describe himself the behaviour of his cryptographic primitives.

Since [BAF08], ProVerif can also prove equivalence properties. It focuses on proving equivalences $P \approx Q$ in which $P$ and $Q$ are two variants of the same process obtained by selecting different terms for $P$ and $Q$. Hence, [BAF08] introduced the notion of biprocess and the operator $\text{diff}$ where $P(\text{diff}(M_1, M_2))$ represents the two variants $P(M_1)$ and $P(M_2)$, obtained by giving different interpretations to $\text{diff}([M_1, M_2])$, i.e. either selecting $M_1$ or $M_2$. In [BAF08], the authors also introduce an operational semantics for biprocesses where $P(\text{diff}(M_1, M_2))$ behaves the same way as $P(M_1)$ and $P(M_2)$ if the intruder cannot distinguish $P(M_1)$ from $P(M_2)$. Furthermore, a reduction of $P(\text{diff}(M_1, M_2))$ necessary becomes a biprocess. On the other hand, if an intruder
can distinguish \( P(M_1) \) from \( P(M_2) \), then the operational semantics specifies that \( P(\text{diff}(M_1, M_2)) \) gets stuck. Hence, to prove the equivalence between \( P(M_1) \) and \( P(M_2) \), it is sufficient to prove that \( P(\text{diff}(M_1, M_2)) \) never gets stuck.

However, the notion of equivalence used by ProVerif is stronger than the usual trace equivalence or observational equivalence. As we described earlier, ProVerif requires that the two processes have the same control structure and that all tests yield the same result in both processes. Thus, for a protocol that does not satisfy this condition, ProVerif will fail to prove equivalence, i.e. it will yield a false attack.

**Example 9.1.** Consider for example the two naive protocols:

\[
P : \text{in}(c, x). \text{if } x = \text{pk}(\text{sk}_A) \text{ then out}(c, \{s\}_{\text{pk}(\text{sk}_A)}) \text{ else out}(c, \{N_p\}_{\text{pk}(\text{sk}_A)})
\]

\[
Q : \text{in}(c, x). \text{if } x = \text{pk}(\text{sk}_B) \text{ then out}(c, \{s\}_{\text{pk}(\text{sk}_B)}) \text{ else out}(c, \{N_q\}_{\text{pk}(\text{sk}_B)})
\]

For simplicity, we omitted the name restriction but we assume that all names but \( c \) are private. However, the we assume that the intruder knows the public keys of \( A \) and \( B \), i.e. \( \text{pk}(\text{sk}_A) \) and \( \text{pk}(\text{sk}_B) \) respectively. The protocol \( P \) is simply waiting for the public key of the agent \( A \) (\( \text{pk}(\text{sk}_A) \)) on a channel \( c \), and if he receives it then sends some secret \( s \) encrypted with \( A \)'s public key else a fresh nonce \( N_p \) encrypted with \( A \)'s public key is sent on the channel \( c \). On the other hand, the protocol \( Q \) does similar actions but is waiting for the public key of the agent \( B \) (\( \text{pk}(\text{sk}_B) \)) instead of \( A \). Assuming that the attacker does not have access to the private keys \( \text{sk}_A \) and \( \text{sk}_B \), then the two protocols are equivalent since the attacker cannot differentiate \( \{s\}_{\text{pk}(\text{sk}_A)} \) and \( \{N_q\}_{\text{pk}(\text{sk}_A)} \) (resp. \( \{s\}_{\text{pk}(\text{sk}_B)} \) and \( \{N_q\}_{\text{pk}(\text{sk}_B)} \)).

However, even if those two protocols can be transformed into a biprocess, i.e.

\[
\text{in}(c, x). \text{if } x = \text{diff}[\text{pk}(\text{sk}_A), \text{pk}(\text{sk}_B)] \text{ then out}(c, \text{diff}[\{s\}_{\text{pk}(\text{sk}_A)}, \{s\}_{\text{pk}(\text{sk}_B)}]) \text{ else out}(c, \text{diff}[\{N_p\}_{\text{pk}(\text{sk}_A)}, \{N_q\}_{\text{pk}(\text{sk}_B)}])
\]

ProVerif will yield a false negative due to the conditional. Indeed, if the attacker sends the public key of \( A \), then the left part of the test \( x = \text{diff}[\text{pk}(\text{sk}_A), \text{pk}(\text{sk}_B)] \) will succeed when the right part will fail. Since the test does not behave the same way on the right and left side, the biprocess gets stuck and so ProVerif will be unable to prove the equivalence. More realistic examples illustrating this false attack can be found in several cases studies, e.g. anonymity of the private authentication protocol [AF02] and unlinkability of the Basic Access Control protocol of the e-passport protocols (see Chapter 8).

This chapter address the issue of such false attacks. Our main idea is to extend the behaviour of destructor function symbols, so that we can perform tests directly inside terms. Initially, destructors could only be declared using rewrite rules, such as \( \text{dec}(\text{enc}(x, y), y) \rightarrow x \), which allowed to perform pattern-matching on terms but no inequality test. We have extended ProVerif with inequalities in the definition of destructors. For instance, we can now define a destructor test as follows:

\[
\text{test}(x, x, z, t) \rightarrow z
\]

\[
\text{test}(x, y, z, t) \rightarrow t \quad \text{if } x \neq y
\]

With this definition, a term \( \text{test}(M_1, M_2, M_3, M_4) \) reduces into \( M_2 \) if \( M_1 \) and \( M_2 \) are equal under the equational theory, and into \( M_4 \) if \( M_1 \) and \( M_2 \) are different under the equational theory. This extension allows us, for example, to replace conditional branching in the processes by \( \text{test}(...) \). Coming back to our previous biprocess, we can now write a similar biprocess which has the same control behaviour for both the left and the right side:

\[
\text{in}(c, x).
\]

\[
\text{let } y = \text{test}(x, \text{diff}[\text{pk}(\text{sk}_A), \text{pk}(\text{sk}_B)], \text{diff}[\{s\}_{\text{pk}(\text{sk}_A)}, \{s\}_{\text{pk}(\text{sk}_B)}], \text{diff}[\{N_p\}_{\text{pk}(\text{sk}_A)}, \{N_q\}_{\text{pk}(\text{sk}_B)}])
\]

\[
\text{in out}(c, y)
\]

Since the conditional process is removed, ProVerif will be able to prove the equivalence of such a biprocess. Although the transformation was done on a naive protocol, we show that it also can be done on more realistic examples. Moreover, since such transformations may not be very natural, we provide an implementation that will automatically detect and perform these transformations when possible.
9.1. Model

This section introduces our process calculus, by giving its syntax and its operational semantics. As mentioned above, our work extends the behaviour of destructor symbols our syntax and semantics of terms evaluations change in comparison to the original calculus of ProVerif [BAF08]. However, we did not modify the syntax of processes thus the semantics for processes only differ from the changes led by the modifications in the semantics for term evaluation.

9.1.1 Syntax

Similarly to all our previous works, the messages sent on the network by some agents in a protocol are modelled using an abstract term algebra. We assume an infinite set of names \( \sigma \) and an infinite set of variables \( \mathcal{X} \). We also consider a signature \( \mathcal{F} \) consisting of a finite set of function symbols with their arity.

We saw that the behaviour of cryptographic primitives could be represented by an equational theory (see Part I), or by a rewriting system (see Part II). However, in ProVerif, both representations are used to describe the behaviour of cryptographic primitives. Hence, as in the calculus of ProVerif [BAF08], we distinguish two categories of function symbols: constructors \( f \) and destructors \( g \). Constructors build terms; destructors, defined by rewrite rules, manipulate terms, as detailed below. We denote by \( F_c \) and \( F_d \) the set of constructors and destructors, respectively.

Messages \( M \) are terms built from variables, names, and constructors applied to terms. The tool ProVerif being more focused on a practical syntax and semantics, an equational theory \( E \) can only be described by a finite set of equations \( M = N \), where \( M, N \) are terms without names.

9.1.1.1 Destructors

In [BAF08], the rewrite rules describing the behaviour of destructors follow the usual definition of a rewrite rule, i.e. \( g(M_1, \ldots, M_n) \rightarrow M \) where \( M_1, \ldots, M_n, M \) are terms built on \( T(F_c, \mathcal{X}) \). However, as mentioned in the introduction, we want to introduce tests directly into terms and more specifically into the definition of destructors. Hence, we introduce formulas on messages in order to express these tests. We consider formulas \( \phi \) of the form \( \bigwedge_{i=1}^{n} \forall \bar{x}_i. M_i \not\in E N_i \), where \( \bar{x} \) stand for a sequence of variables \( x_1, \ldots, x_k \) and \( E \) is the equational theory. We denote by \( \top \) and \( \bot \) the true and false formulas, respectively corresponding to an empty conjunction \((n = 0)\) and to \( x \not\in E x \), for instance. Formulas will be used as side conditions for destructors.

Let \( \sigma \) be a substitution mapping variables to ground terms. We define \( \sigma \models \phi \) as follows: \( \sigma \models \bigwedge_{i=1}^{n} \forall \bar{x}_i. M_i \not\in E N_i \) if and only if for \( i = 1, \ldots, n \), for all \( \sigma \) of domain \( \bar{x}_i \), \( M_i \sigma \sigma \not\in E N_i \sigma \sigma \). More generally, we extend \( \models \) to formulas using classic logic connectives with equalities and inequalities. Note that this definition of \( \sigma \) satisfying \( \phi \) is similar to the one given in Part I except that the inequalities and equalities are not syntactic anymore.

In [BAF08] and in Part II destructors are partial functions defined by rewrite rules; when no rewrite rule can be applied, we say that the destructor fails. However, this formalism does not allow destructors to succeed when one of their arguments fails. We shall need this feature in order to include as many tests as possible in terms. Therefore, we extend the definition of destructors by defining may-fail messages, denoted by \( U \), which can be messages \( M \), the special value fail, or a variable \( u \). We separate fail from ordinary messages \( M \) so that the equational theory does not apply to fail. May-fail messages represent the possible arguments and result of a destructor. We differentiate variables for may-fail messages, denoted \( u, v, w \) and variables for messages, denoted \( x, y, z \). A may-fail variable \( u \) can be instantiated by a may-fail term while a message variable \( x \) can only be instantiated by a message, and so cannot be instantiated by fail. The syntax of our terms is summarised in Figure 9.1.

For two ground may-fail messages \( U_1 \) and \( U_2 \), we say that \( U_1 =_E U_2 \) if and only if \( U_1 = U_2 = \text{fail} \) or \( U_1, U_2 \) are both messages, denoted \( M_1, M_2 \), and \( M_1 =_E M_2 \).

**Example 9.2.** Consider the signature \( \mathcal{F} \) and the associated equational theory \( E_{\text{enc}} \) of Example 9.2.

Consider \( U \) and \( V \) defined as follows:

"\[\text{Example 9.2. Consider the signature } \mathcal{F} \text{ and the associated equational theory } E_{\text{enc}} \text{ of Example 9.2. Consider } U \text{ and } V \text{ defined as follows:} \]"
The variables of \( \text{proj} \) necessarily message variables. Variables are subject to renaming. When \( \phi \) is the formula \( \top \), we omit the formula.

**Example 9.3.** Consider a signature \( \mathcal{F} \) and an equational theory \( \mathcal{E} \). A symmetric encryption scheme where the decryption function either properly decrypts a ciphertext using the correct private key, or fails. To model this encryption scheme, we consider, in the signature \( \mathcal{F} \), the constructor \( \text{senc} \) for encryption, the destructor \( \text{sdec} \) for decryption. Decryption can be defined by the rules:

\[
\begin{align*}
\text{sdec}(\text{senc}(x,y), y) & \rightarrow x \quad (\text{decryption succeeds}) \\
\text{sdec}(x,y) & \rightarrow \text{fail} \quad (\forall z. x \not\in \mathcal{E} \text{ senc}(z,y) \quad (\text{decryption fails, because } x \text{ is not a ciphertext under the correct key})
\end{align*}
\]

\[
\begin{align*}
\text{sdec}(\text{fail}, u) & \rightarrow \text{fail}, \text{sdec}(u, \text{fail}) \rightarrow \text{fail} \quad (\text{the arguments failed, the decryption also fails})
\end{align*}
\]

To avoid confusion, we will call **equational presentation**, denoted \( \Sigma \), the signature \( \mathcal{F} \) with its associated equational theory \( \mathcal{E} \) and the sets of rewriting rules that describe the destructors of \( \mathcal{F} \). Hence, we denote \( \text{def}_\Sigma(\mathcal{g}) \) the set of rewrite rule describing \( \mathcal{g} \) in the signature of \( \Sigma \). Moreover, we denote \( U \equiv_\Sigma V \) (resp. \( U \not\equiv_\Sigma V \)) the equality (resp. inequality) modulo the equational theory of \( \Sigma \).

Consider \( U_1, \ldots, U_n \) may-fail messages and consider \( \mathcal{g} \) a destructor of arity \( n \). We say that \( \mathcal{g} \) rewrites \( U_1, \ldots, U_n \) into \( U \), denoted \( \mathcal{g}(U_1, \ldots, U_n) \rightarrow U \), if there exist \( \mathcal{g}(U'_1, \ldots, U'_n) \rightarrow U' \) \( \equiv_\Sigma \phi \) in \( \text{def}_\Sigma(\mathcal{g}) \), and a substitution \( \sigma \) such that \( U'_i \sigma =_\Sigma U_i \) for all \( i = 1, \ldots, n \), \( U' \sigma = U \) and \( \sigma \vdash \phi \).

At last, we ask that given an equational presentation \( \Sigma \), for all destructors \( \mathcal{g} \) of arity \( n \), \( \text{def}_\Sigma(\mathcal{g}) \) satisfies the following properties:

**P1.** For all ground may-fail messages \( U_1, \ldots, U_n \), there exists a may-fail message \( U \) such that \( \mathcal{g}(U_1, \ldots, U_n) \rightarrow U \).

**P2.** For all ground may-fail messages \( U_1, \ldots, U_n \), if \( \mathcal{g}(U_1, \ldots, U_n) \rightarrow V_1 \) and \( \mathcal{g}(U_1, \ldots, U_n) \rightarrow V_2 \) for some \( V_1, V_2 \) then \( V_1 =_\Sigma V_2 \).
Property $[P1]$ expresses that all destructors are total while Property $[P2]$ expresses that all destructors are deterministic (modulo the equational theory). Note that thanks to Property $[P2]$, a destructor cannot reduce to fail and a message at the same time. We provide two algorithms that allow us to automatically verify that a destructor satisfies Properties $[P1]$ and $[P2]$ (See Section 9.3.5).

Example 9.4. We define a destructor that tests equality and returns either true or false, as follows:

\[
\begin{align*}
\text{eq}(x, x) & \rightarrow \text{true} \\
\text{eq}(x, y) & \rightarrow \text{false} \quad | \quad x \neq \Sigma y \\
\text{eq}(	ext{fail}, u) & \rightarrow \text{fail} \\
\text{eq}(u, \text{fail}) & \rightarrow \text{fail}
\end{align*}
\]

This destructor fails when one of its arguments fails. We remark that such a destructor could not be defined in ProVerif without our extension, because one could not test $x \neq \Sigma y$.

9.1.1.2 From usual destructors to our extension

More generally, from a destructor defined, as in [BAF08], by rewrite rules $g(M_1, \ldots, M_n) \rightarrow M$ without side conditions and such that the destructor is considered to fail when no rewrite rule applies, we can build a destructor in our formalism. The algorithm is given in Lemma 9.1 below.

**Lemma 9.1.** Consider an equational presentation $\Sigma$. Let $g$ be a destructor of arity $n$ described by the following set $S$ of rewrite rules:

\[
\{g(M_1^i, \ldots, M_n^i) \rightarrow M^i \mid i = 1, \ldots, m\}
\]

Assume that $g$ is deterministic, i.e. $S$ satisfies Property $[P2]$. The following set $\text{def}_\Sigma(g)$ satisfies Properties $[P1]$ and $[P2]$

\[
\text{def}_\Sigma(g) = S \cup \{g(x_1, \ldots, x_n) \rightarrow \text{fail} \mid \phi\} \\
\cup \{g(u_1, \ldots, u_{k-1}, \text{fail}, u_{k+1}, \ldots, u_n) \rightarrow \text{fail} \mid k = 1, \ldots, n\}
\]

where $\phi = \bigwedge_{i=1}^m \forall y_i.(x_1, \ldots, x_n) \neq \Sigma (M_1^i, \ldots, M_n^i)$ and $y_i$ are the variables of $(M_1^i, \ldots, M_n^i)$, and $x_1, \ldots, x_n$ are message variables.

**Proof.** Let $U_1, \ldots, U_n$ be ground may-fail messages. Consider first the case where there exists $i \in \{1, \ldots, n\}$ such that $U_i = \Sigma \text{ fail}$. Since $x_1, \ldots, x_n$ are message variables and for all $i \in \{1, \ldots, m\}$, for all $j \in \{1, \ldots, n\}$, $M_j^i$ is a message, the only rules that can rewrite $U_1, \ldots, U_n$ are $\{g(u_1, \ldots, u_{k-1}, \text{fail}, u_{k+1}, \ldots, u_n) \rightarrow \text{fail} \mid k = 1, \ldots, n\}$. Moreover, let $\sigma$ be the substitution such that $u_j\sigma = U_j$ for all $j \neq i$. We trivially have that $u_i\sigma = \Sigma U_i$ and by hypothesis $U_i = \Sigma \text{ fail}$. Thus, $g(U_1, \ldots, U_n) \rightarrow \text{fail}$ and there is no message $M$ such that $g(U_1, \ldots, U_n) \rightarrow M$.

Consider now the case where $U_1, \ldots, U_n$ are all messages, that we rename $M_1, \ldots, M_n$. Thus, $M_1, \ldots, M_n$ can only be rewritten by the rules in $S \cup \{g(x_1, \ldots, x_n) \rightarrow \text{fail} \mid \phi\}$. Let $i \in \{1, \ldots, m\}$. By definition, we have that $M_1, \ldots, M_n$ is rewritten by the rule $g(M_1^i, \ldots, M_n^i) \rightarrow M^i$ if, and only if, there exists a substitution $\sigma$ such that $\sigma \vdash \exists y_i.(x_1, \ldots, x_n) = \Sigma (M_1^i, \ldots, M_n^i)$ and $x_j\sigma = M_j$ for $j = 1 \ldots n$ where $y_i = \text{fvars}(M_1^i, \ldots, M_n^i)$. Hence, $M_1, \ldots, M_n$ can be rewritten by one of the rules in $S$ if, and only if, there exists a substitution $\sigma$ such that $\sigma \vdash \neg \phi$. On the other hand, $M_1, \ldots, M_n$ can be rewritten by $g(x_1, \ldots, x_n) \rightarrow \text{fail} \mid \phi$ if, and only if, $\sigma \vdash \phi$. Hence we deduce that $\text{def}_\Sigma(g)$ satisfies Property $[P1]$. Moreover, since $M^i$ is a message for all $i = 1 \ldots m$, and there is no substitution $\sigma$ such that $\sigma \vdash \phi \land \neg \phi$, we deduce that $\text{def}_\Sigma(g)$ satisfies Property $[P2]$.

The users can therefore continue defining destructors as before in ProVerif; the tool automatically completes the definition following Lemma 9.1. The users will also be able to define
destructors using the new formalism, i.e. with side conditions and may-fail messages. However, in this case, it is up to the user to provide a set of rewrite rules that satisfies Properties P1 and P2. Indeed, the algorithms described in Section 9.3.5 only check if a set \( S \) of rewrite rules satisfies both properties but these algorithms do not complete \( S \) if it fails to satisfy the desired properties.

### 9.1.1.3 Term Evaluation

A term evaluation, denoted by \( D \) and defined in Figure 9.2, represents the evaluation of a series of constructors and destructors.

\[
D ::= \text{term evaluations} \quad U \quad \text{may-fail message} \quad \text{eval} h(D_1, \ldots, D_n) \quad \text{function evaluation}
\]

![Figure 9.2: Syntax of term evaluation](image)

\( \text{eval} h(D_1, \ldots, D_n) \) indicates that the function symbol will be evaluated. While all destructor must be preceded by \( \text{eval} \), some constructors might also be preceded by \( \text{eval} \) in a term evaluation. In fact, the reader may ignore the prefix \( \text{eval} \) since \( \text{eval} h \) and \( h \) have the same semantics. However, \( \text{eval} \) becomes useful when we convert equations into rewrite rules (see. Section 9.2.2). Typically, \( \text{eval} \) is used to indicate when a term has been evaluated or not.

In order to avoid distinguishing constructors and destructors in the definition of term evaluation, for \( f \) a constructor of arity \( n \), we let \( \text{def}_f \Sigma (f) = \{ f(x_1, \ldots, x_n) \rightarrow f(x_1, \ldots, x_n) \} \cup \{ f(u_1, \ldots, u_{i-1}, \text{fail}, u_{i+1}, \ldots, u_n) \rightarrow \text{fail} \mid i = 1, \ldots, n \} \). The second part of the union corresponds to the failure cases: the constructor fails if and only if one of its arguments fails. We allow may-fail messages in term evaluations. Since no construct will allow us to bind may-fail variables in processes, only messages \( M \) and \( \text{fail} \) may in fact occur.

### 9.1.1.4 Processes

At last, processes \( P, Q, R \) represent protocols and are defined in Figure 9.3. This syntax corresponds exactly to [BAF08] and is very similar to the syntax of the applied pi calculus. However, note that the condition if \( M = N \) then \( P \) else \( Q \) is not included in our calculus. Indeed, it was replaced by the term evaluation \( \text{let } x = D \text{ in } P \text{ else } Q \) that evaluates the term evaluation \( D \). If \( D \) reduces to a message, it stores the result in \( x \) and executes \( P \). Otherwise, \( D \) reduces to \( \text{fail} \), and \( Q \) is executed. A trailing \( 0 \) can be omitted after an input or an output. An else branch can be omitted when it is else 0.

\[
P, Q, R ::= \text{processes} \quad 0 \quad \text{nil} \quad \text{in}(M, x).P \quad \text{input} \quad \text{out}(M, N).P \quad \text{output} \quad P | Q \quad \text{parallel composition} \quad ! P \quad \text{replication} \quad \nu a.P \quad \text{restriction} \quad \text{let } x = D \text{ in } P \text{ else } Q \quad \text{term evaluation}
\]

![Figure 9.3: Syntax of our processes](image)

Note that even if the condition if \( M = N \) then \( P \) else \( Q \) is not included in our calculus, it can now be defined as \( \text{let } x = \text{equals}(M, N) \text{ in } P \text{ else } Q \), where \( x \) is a fresh variable and \( \text{equals} \) is a binary destructor with the rewrite rules \( \{ \text{equals}(x, x) \rightarrow x, \text{equals}(x, y) \rightarrow \text{fail} \mid x \neq_\Sigma y \} \). The destructor \( \text{equals} \) succeeds if and only if its two arguments are equal messages modulo the equational theory and different from \( \text{fail} \). We always include this destructor in the signature \( F \).
9.1. Model

9.1.2 Semantics

We define in this subsection the semantics for term evaluation and processes.

9.1.2.1 Term evaluation

Given an equational presentation $\Sigma$, given a term evaluation $D$, a term $U$ is the result of an evaluation of $D$, denoted $D \downarrow_{\Sigma} U$, and defined as follows:

$$U \downarrow_{\Sigma} U$$

$$\text{eval } g(D_1, \ldots, D_n) \downarrow_{\Sigma} U \sigma$$

if $g(U_1, \ldots, U_n) \rightarrow U \| \phi \in \text{def}_{\Sigma}(g)$, and $\sigma$ is such that for all $i$, $D_i \downarrow_{\Sigma} V_i, V_i =_{\Sigma} U_i$ and $\sigma \models \phi$

Note that this semantics differs from [BAF08] by the addition of formulas in the destructor definitions and the fact that messages are replaced by may-fail messages.

Thanks to the properties $[P1]$ and $[P2]$ satisfied by the destructors, we establish the following result:

Lemma 9.2. Consider an equational presentation $\Sigma$. For all ground term evaluations $D$,

- there exists a ground may-fail message $U$ such that $D \downarrow_{\Sigma} U$.
- for all ground may-fail messages $U_1, U_2$, if $D \downarrow_{\Sigma} U_1$ and $D \downarrow_{\Sigma} U_2$ then $U_1 =_{\Sigma} U_2$.

Proof. We prove this result by induction on $D$:

Case $D = U$: In such a case, we have that $D \downarrow_{\Sigma} U$ hence the result trivially holds.

Case $D = \text{eval } g(D_1, \ldots, D_n)$: By inductive hypothesis, there exist $U_1, \ldots, U_n$ ground may-fail messages such that $D_i \downarrow_{\Sigma} U_i$ for all $i = 1 \ldots n$. By Property $[P1]$ we know that there exists $g(U_1', \ldots, U_n') \rightarrow U' \| \phi \in \text{def}_{\Sigma}(g)$ and a substitution $\sigma$ such that $U_i' =_{\Sigma} U_i$ for $i = 1 \ldots n$ and $\sigma \models \phi$ hence $D \downarrow_{\Sigma} U' \sigma$. Moreover, since $\text{fears}(U') \subseteq \text{fears}(U_1', \ldots, U_n')$, we deduce that $U' \sigma$ is ground. Thus the first item is satisfied.

Let $V_1, V_2$ two may-fail messages such that $D \downarrow_{\Sigma} V_1$ and $D \downarrow_{\Sigma} V_2$. $D \downarrow_{\Sigma} V_1$ implies that there exist $U_1, \ldots, U_n$ ground may-fail messages such that $D_i \downarrow_{\Sigma} U_i$ for all $i = 1 \ldots n$ and $g(U_1, \ldots, U_n) \rightarrow V_1$. Similarly, $D \downarrow_{\Sigma} V_2$ implies that there exist $W_1, \ldots, W_n$ ground fail-messages such that $D_i \downarrow_{\Sigma} W_i$ for all $i = 1 \ldots n$ and $g(W_1, \ldots, W_n) \rightarrow V_2$. By our inductive hypothesis, we deduce that $W_1 =_{\Sigma} U_1$ for all $i = 1 \ldots n$. Hence, by definition of the reduction of may-fail messages by a destructor, we deduce that $g(U_1, \ldots, U_n) \rightarrow V_2$. But def$_{\Sigma}(g)$ satisfies Property $[P2]$ thus we conclude that $V_1 =_{\Sigma} V_2$. \qed
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In fact, given an equational presentation \( \Sigma' \) defined as in the original ProVerif, \( i.e. \) with partial destructors and no side condition, and given \( \Sigma \) the equational presentation adapted to our semantics thanks to Lemma 9.1, we would have: For all ground term evaluations \( D \), for all messages \( M, D \stackrel{\Sigma}{\rightarrow} M \) if, and only if, \( D \stackrel{\Sigma}{\downarrow} \).

Example 9.6. Consider an equational presentation \( \Sigma \) with the equational theory \( E_{\text{senc}} \) and the destructor \( \text{sdec} \) described in Example 9.3. We have:

- \( \text{eval} \text{sdec}(\text{senc}(n, sk), sk) \stackrel{\Sigma}{\downarrow} n \)
- \( \text{eval} \text{sdec}(\text{senc}(n, sk'), sk) \stackrel{\Sigma}{\downarrow} \text{fail} \)
- \( \text{eval} \text{sdec}(\text{senc}(n, \text{proj}((sk, sk'))), sk) \stackrel{\Sigma}{\downarrow} n \)

9.1.2.2 Processes

Similarly to the applied pi calculus, the semantics for processes in ProVerif is defined by a structural equivalence, denoted \( \equiv \) and some internal reductions. However, both relations slightly differ from the applied pi calculus. The structural equivalence in ProVerif is the smallest equivalence relation on processes that is closed under \( \alpha \)-conversion of bounded names and variables and that includes the following relations:

\[
\begin{align*}
P \mid 0 & \equiv P \\
(P \mid Q) \mid R & \equiv (Q \mid P ) \mid R \\
\nu_a.\nu_b.P & \equiv \nu_b.\nu_a.P \\
\nu_a.(P \mid Q) & \equiv P \mid \nu_a.Q \\
\text{if } a \notin \text{fnames}(P) & \equiv \text{if } a \notin \text{fnames}(P)
\end{align*}
\]

Note that similarly to the applied pi calculus, the structural equivalence is closed by application of evaluation contexts, and basic structural rules such as \( A \mid 0 \equiv A \), associativity and commutativity of \( \mid \), binding-operator-like behaviour of \( \nu \). However, this structural equivalence does not substitute equal terms modulo the equational theory and do not model the replication. Both properties are in fact modelled as internal reduction rules for processes (see below). In [BAP08], they indicate that this weakening of the structural equivalence was designed to simplify the proofs.

Figure 9.4 describes the internal reductions for processes (\( \rightarrow^\Sigma \)). This semantics is different from [BAP08] by the semantics of the rule (Red Fun 2) which previously corresponded to the case where the evaluation term \( D \) could not be reduced.

\[
\begin{align*}
\text{out}(N, M).Q & \mid \text{in}(N', x).P \rightarrow^\Sigma Q \mid P\{^M/x\} & \text{(Red I/O)} \\
\text{if } N \stackrel{\Sigma}{=} N' & \rightarrow^\Sigma M & \text{(Red Fun 1)} \\
\text{let } x = D \text{ in } P \text{ else } Q & \rightarrow^\Sigma P\{^M/x\} & \text{(Red Fun 2)} \\
\text{if } D \stackrel{\Sigma}{\downarrow} M & \rightarrow^\Sigma Q & \text{(Red Repl)} \\
\text{let } x = D \text{ in } P \text{ else } Q & \rightarrow^\Sigma Q \\
\text{if } D \stackrel{\Sigma}{\downarrow} \text{fail} & \equiv P & \text{(Red Par)} \\
!P & \rightarrow^\Sigma P \mid !P & \text{(Red Par)} \\
P & \rightarrow^\Sigma Q & \rightarrow^\Sigma Q \mid R & \text{(Red Fun 2)} \\
P & \rightarrow^\Sigma Q & \rightarrow^\Sigma \nu_a.P & \rightarrow^\Sigma \nu_a.Q & \text{(Red Res)} \\
P \equiv P, P & \rightarrow^\Sigma Q, Q \equiv Q' & \Rightarrow P' \rightarrow^\Sigma Q' & \text{(Red \equiv)} \end{align*}
\]

Figure 9.4: Semantics for processes

Both relations \( \equiv \) and \( \rightarrow^\Sigma \) are defined only on closed processes. Furthermore, we denote \( \rightarrow^\Sigma_* \) the reflexive and transitive closure of \( \rightarrow^\Sigma \). At last, we denote \( \rightarrow^\Sigma_{\equiv} \) for its union with \( \equiv \). When \( \Sigma \) is clear from the context, we abbreviate \( \rightarrow^\Sigma \) and \( \downarrow^\Sigma \) to \( \rightarrow \) and \( \downarrow \), respectively.
Example 9.7. Coming back to Example 9.5, consider the process $P \overset{\text{def}}{=} \text{out}(c,n)\text{in}(c,z) | \nu sk_k.\nu sk_b.\Sigma(B(sk_b,sk_k)$ and the equational presentation $\Sigma$ with the equational theory $E_{\text{aenc}}$ of Example 2.2. A possible reduction of $P$ would be the following:

\[ P \rightarrow_{\Sigma} \nu sk_a.\nu sk_b.\nu n_b.(\text{out}(c,n)\text{in}(c,z) | \text{in}(c,y).B') \] (Red $\equiv$)

\[ \rightarrow_{\Sigma} \nu sk_a.\nu sk_b.\nu n_b.\{\text{in}(c,z) | B'\{n/y\}\} \] (Red $1/O$ and Res)

\[ \rightarrow_{\Sigma} \nu sk_a.\nu sk_b.\nu n_b.\{\text{in}(c,z) | B''\{n/y\}\} \] (Red Fun 1 and Res)

\[ \rightarrow_{\Sigma} \nu sk_a.\nu sk_b.\nu n_b.\{\text{in}(c,z) | B'''\{n/y\}\} \] (Red Fun 1 and Res)

\[ \rightarrow_{\Sigma} \nu sk_a.\nu sk_b.\nu n_b.(\text{out}(c,\text{aenc}(n_b,\text{pk}(sk_b)))\} \] (Red Fun 2 and Res)

\[ \rightarrow_{\Sigma} \nu sk_a.\nu sk_b.\nu n_b.(0 \mid 0) \] (Red $1/O$ and Res)

where $u = \text{adec}(n,sk_b), v = \text{proj}_1(\text{adec}(n,sk_b))$ and $B', B''$ and $B'''$ are defined as follows:

\[ B' \overset{\text{def}}{=} \text{let } x = \text{adec}(y,sk_b) \text{ in } B' \text{ else } \text{out}(c,\text{aenc}(n_b,\text{pk}(sk_b))) \]

\[ B'' \overset{\text{def}}{=} \text{let } xn_a = \text{proj}_1(x) \text{ in } B'' \text{ else } \text{out}(c,\text{aenc}(n_b,\text{pk}(sk_b))) \]

\[ B''' \overset{\text{def}}{=} \text{let } z = \text{equals} (\text{proj}_2(x),\text{pk}(sk_a)) \text{ in } \]

\[ \text{out}(c,\text{aenc}((\text{proj}_1(x),n_b,\text{pk}(sk_b))),\text{pk}(sk_a)) \]

\[ \text{else out}(c,\text{aenc}(n_b,\text{pk}(sk_b))) \]

However, if we now consider $\Sigma'$ as the equational presentation where $\text{adec}$ is a destructor and $\text{def}_{\Sigma'}(\text{adec})$ is described by the following rules:

- $\text{adec}(\text{aenc}(x,\text{pk}(y)),y) \rightarrow x$ (decryption succeeds)
- $\text{adec}(x,y) \rightarrow \text{fail} || \forall x. x \neq \text{aenc}(x,\text{pk}(y))$ (decryption fails, because $x$ is not a ciphertext under the correct public key)
- $\text{adec}(\text{fail},u) \rightarrow \text{fail}, \text{adec}(u,\text{fail}) \rightarrow \text{fail}$ (the arguments failed, the decryption also fails)

then a possible reduction of $P$ (we omit the eval $\text{adec}$) would be the following:

\[ P \rightarrow_{\Sigma} \nu sk_a.\nu sk_b.\nu n_b.(\text{out}(c,n)\text{in}(c,z) | \text{in}(c,y).B') \] (Red $\equiv$)

\[ \rightarrow_{\Sigma} \nu sk_a.\nu sk_b.\nu n_b.\{\text{in}(c,z) | B'\{n/y\}\} \] (Red $1/O$ and Res)

\[ \rightarrow_{\Sigma} \nu sk_a.\nu sk_b.\nu n_b.\{\text{in}(c,z) | \text{out}(c,\text{aenc}(n_b,\text{pk}(sk_b)))\} \] (Red Fun 2 and Res)

\[ \rightarrow_{\Sigma} \nu sk_a.\nu sk_b.\nu n_b.(0 \mid 0) \] (Red $1/O$ and Res)

Note that while in the first case, we have $\text{adec}(n,sk_b) \downarrow_{\Sigma} \text{adec}(n,sk_b)$ since $\text{adec}$ is a constructor in $\Sigma$, we have in the second case $\text{adec}(n,sk_b) \downarrow_{\Sigma} \text{fail}$ due to the definition of $\text{def}_{\Sigma'}(\text{adec})$. Hence the application of the internal reduction rule (Red Fun 2). In the first case, the application of the internal reduction rule (Ref Fun 2) is due to the destructor $\text{equals}$ and more specifically to the fact that $\text{equals}(\text{proj}_2(\text{adec}(n,sk_b)),\text{pk}(sk_a)) \downarrow_{\Sigma} \text{fail}$.

9.2 Using biprocesses to prove observational equivalence

One of the purposes of ProVerif is to prove the observational equivalence between processes. In Chapter 3, we provide a definition for such equivalence (see Definition 3.5) in the applied pi calculus. While the syntax and semantic of ProVerif are different from the applied pi calculus, the definition of observational equivalence for ProVerif is almost identical to Definition 3.5.

Definition 9.1. Given an equational presentation $\Sigma$, the process $P$, built on $\Sigma$, emits on $M$ ($P \Downarrow M$) if and only if $P \rightarrow_{\Sigma} C[\text{out}(M',N).R]$ for some evaluation context $C$ that does not bind $\text{fnames}(M)$ and $M \Rightarrow_{\Sigma} M'$.

The observational equivalence, denoted $\approx$ is the largest symmetric relation $R$ between closed processes with the same domain such that $P R Q$ implies:
and 9.3, with additional cases so that they contain. The grammar for the calculus is a simple extension of the grammar of Figures 9.1, 9.2.

To solve this problem, [BAF08] introduces a calculus that represents pairs of processes, called biprocesses.

There are usually an infinite number of candidates for this mapping. However, we consider a process algebra with replication, hence item of Definition 9.1. Indeed, this condition indicates that each reduction of a process has to be by replacing all occurrences of diff

To prove this equivalence using ProVerif, we first have to transform this equivalence into a biprocess. This is easily done since only the private keys sk_a and sk_a’ change between the two processes. Hence, we define the biprocess $P_0$ as follows:

$$\nu sk_a.\nu sk_a’.\nu sk_b.\text{out}(c, pk(sk_a)).\text{out}(c, pk(sk_a’)).\text{System}(sk_a, sk_b) \approx \nu sk_a.\nu sk_a’.\nu sk_b.\text{out}(c, pk(sk_a)).\text{out}(c, pk(sk_a’)).\text{System}(\text{diff}[sk_a, sk_a’], sk_b)$$

We already know that this equivalence holds for the trace equivalence, but in fact it also holds for the observational equivalence. To prove this equivalence using ProVerif, we first have to transform this equivalence into a biprocess. This is easily done since only the private keys $sk_a$ and $sk_a’$ change between the two processes. Hence, we define the biprocess $P_0$ as follows:

$$\nu sk_a.\nu sk_a’.\nu sk_b.\text{out}(c, pk(sk_a)).\text{out}(c, pk(sk_a’)).\text{System}(\text{diff}[sk_a, sk_a’], sk_b)$$

Note that $\text{fst}(P_0)$ and $\text{snd}(P_0)$ correspond to the two protocols of the equivalence.
9.2. USING BIPROCESSES TO PROVE OBSERVATIONAL EQUIVALENCE

The semantics for biprocesses is defined as in Figure 9.4 with generalized rules (Red I/O), (Red Fun 1), and (Red Fun 2) given in Figure 9.5. Once again, the difference with [BAF08] is that, in rule (Red Fun 1), we require that \( \text{fst}(D) \) and \( \text{snd}(D) \) reduce to a message and, in rule (Red Fun 2), \( \text{fst}(D) \) and \( \text{snd}(D) \) both reduce to fail. In contrast, in [BAF08], in rule (Red Fun 1), \( \text{fst}(D) \) and \( \text{snd}(D) \) reduced to any message and, in rule (Red Fun 2), \( \text{fst}(D) \) and \( \text{snd}(D) \) failed to reduce.

The semantics of biprocesses is such that a biprocess reduces if and only if both sides of the biprocess reduce in the same way: a communication succeeds on both sides; a term evaluation succeeds on both sides or fails on both sides. When the two sides of the biprocess reduce in different ways, the biprocess blocks. The following lemma shows that, when both sides of a biprocess always reduce in the same way, then that biprocess satisfies observational equivalence. Its proof can be found in Appendix D.1.

**Lemma 9.3.** Let \( P_0 \) be a closed biprocess. Suppose that, for all plain evaluation contexts \( C \), all evaluation contexts \( C' \), and all reductions \( C[P_0] \rightarrow^* P \),

1. if \( P \equiv C'[\text{out}(N, M), Q \mid \text{in}(N', x), R] \), then \( \text{fst}(N) =_\Sigma \text{fst}(N') \) if, and only if, \( \text{snd}(N) =_\Sigma \text{snd}(N') \) and
   \[ \text{snd}(D) \]
2. if \( P \equiv C'[\text{let } x = D \text{ in } Q \text{ else } R] \), then \( \text{fst}(D) \downarrow_\Sigma \text{fail} \) if, and only if, \( \text{snd}(D) \downarrow_\Sigma \text{fail} \).

Then \( P_0 \) satisfies observational equivalence.

Intuitively, the semantics for biprocesses forces that each reduction of a process has to be matched by the same reduction in the second process. Hence, verifying the second item of Definition D.1 becomes less problematic since we reduce to one the number of possible candidates.

9.2.2 FROM EQUATIONAL THEORIES TO REWRITE RULES

Equational theories are very useful when it comes to theoretical results. However, for a practical algorithm, it is easier to work with rewrite rules rather than with equational theories. Hence in [BAF08], the equational theory is transformed into a set of rewrite rules. Typically, for an equational presentation \( \Sigma \) with its associated equational theory, a new equational presentation \( \Sigma' \) with the same function symbols and the empty equational theory is generated. Moreover, \( \Sigma' \) models \( \Sigma \). In this section, we adapt the definitions used in [BAF08] to our formalism.

9.2.2.1 Generation of \( \Sigma' \)

For an equational presentation \( \Sigma' \) (with the empty equational theory), we define evaluation on open terms as a relation \( D \Downarrow \Sigma' \ (U, \sigma, \phi) \), where \( \sigma \) collects instantiations of \( D \) obtained by unification and \( \phi \) collects the side conditions of destructor applications:

\[
\begin{align*}
U & \Downarrow \Sigma' \ (U, \emptyset, \top) \\
\text{eval } h(D_1, \ldots, D_n) & \Downarrow \Sigma' \ (V\sigma_u, \sigma'\sigma_u, \phi'\sigma_u \land \phi\sigma_u) \\
\text{if } (D_1, \ldots, D_n) & \Downarrow \Sigma' \ ((U_1, \ldots, U_n), \sigma', \phi'), \\
\text{h}(V_1, \ldots, V_n) & \rightarrow V \mid \phi \in \text{def}_\Sigma(h) \text{ and} \\
\sigma_u & \text{is a most general unifier of } (U_1, V_1), \ldots, (U_n, V_n) \\
(D_1, \ldots, D_n) & \Downarrow \Sigma' \ ((U_1\sigma_u, \ldots, U_{n-1}\sigma_u, U_n), \sigma\sigma_u, \phi\sigma_u \land \phi_u) \\
\text{if } (D_1, \ldots, D_{n-1}) & \Downarrow \Sigma' \ ((U_1, \ldots, U_{n-1}), \sigma, \phi) \text{ and } D_n\sigma \Downarrow \ (U_n, \sigma_u, \phi_u).
\end{align*}
\]

The most general unifier of may-fail messages is computed similarly to the most general unifier of messages, even though specific cases hold due to may-fail variables and message variables: there is no unifier of \( M \) and fail, for any message \( M \) (including variables \( x \), because these variables can be instantiated only by messages); the most general unifier of \( u \) and \( U \) is \( \{ u \rightarrow U \} \); the most general unifier of fail and fail is the identity; finally, the most general unifier of \( M \) and \( M' \) is computed as usual.
Example 9.9. Consider $\Sigma'$ the equational presentation with the empty equational theory and containing the destructor $\texttt{sdec}$ defined in Example 9.3. Let $D$ and $D'$ be two term evaluations such that $D' = \text{eval sdec}(x, sk)$ and $D = \text{eval sdec}(D', sk')$. We have:

1. $D' \downarrow_{\Sigma'} (y, \{x \mapsto senc(y, sk)\}, \top)$
2. $D' \downarrow_{\Sigma'} (\text{fail}, \emptyset, \forall y.x \notin \Sigma \text{senc}(y, sk))$
3. $D \downarrow_{\Sigma'} (z, \{x \mapsto \text{senc}(%senc(z, sk'), sk)\}, \top)$
4. $D \downarrow_{\Sigma'} (\text{fail}, \{x \mapsto \text{senc}(y, sk)\}, \forall z.y \notin \Sigma \text{senc}(z, sk'))$
5. $D \downarrow_{\Sigma'} (\text{fail}, \emptyset, \forall y.x \notin \Sigma \text{senc}(y, sk))$

Note that the evaluations 3 and 4 of $D$ are obtained from the evaluation 1 of $D'$. On the other hand, the evaluation 5 of $D$ is obtained by the evaluation 2 of $D'$.

We let $\text{addeval}(U_1, \ldots, U_n)$ be the tuple of term evaluations obtained by adding eval before each function symbol of $U_1, \ldots, U_n$. Using these definitions, we recall the definition of an equational presentation $\Sigma'$ with an empty equational theory modelling another equational presentation $\Sigma$ with equations:

We consider an auxiliary rewriting system on terms, $S$, that defines partial normal forms. The rules of $S$ do not contain names and do not have a single variable on the left-hand side. We say that a term is irreducible by $S$ and, for all subterms $M_1$ and $M_2$ of terms of $\mathcal{M}$, if $M_1 =_{\Sigma} M_2$ then $M_1 = M_2$. Typically, while a term might have several partial normal forms, any equal (sub)terms in $\mathcal{M}$ modulo the equational theory are in the same normal form in $\text{nf}_{S, \Sigma}(\mathcal{M})$. We extend the definition of $\text{nf}_{S, \Sigma}(\cdot)$ to sets of processes: $\text{nf}_{S, \Sigma}(P)$ if and only if the set of terms that appear in processes in $P$ is in normal form.

Definition 9.3. Let $\Sigma$ and $\Sigma'$ be two equational presentations on the same function symbols. We say that $\Sigma'$ models $\Sigma$ if and only if

1. The equational theory of $\Sigma'$ is syntactic equality: $M =_{\Sigma'} N$ if and only if $M = N$.
2. The constructors of $\Sigma'$ are the constructors of $\Sigma$: their definition $\text{def}_{\Sigma'}(f)$ contains the rule $f(x_1, \ldots, x_n) \rightarrow f(x_1, \ldots, x_n)$, the rewrite rules corresponding to possible failure, i.e. for all $i \in \{1, \ldots, n\}$, $f(u_1, \ldots, u_{i-1}, \text{fail}, u_{i+1}, \ldots, u_n) \rightarrow \text{fail}$, and perhaps other rules such that there exists a rewriting system $S$ on terms that satisfies the following properties:

   S1. If $M \rightarrow N$ is in $S$, then $M =_{\Sigma} N$.
   S2. If $\text{nf}_{S, \Sigma}(M)$, then for any term $M$ there exists $M'$ such that $M' =_{\Sigma} M$ and $\text{nf}_{S, \Sigma}(M \cup \{M'\})$.
   S3. If $f(N_1, \ldots, N_n) \rightarrow N \mid \phi$ is in $\text{def}_{\Sigma'}(f)$, then $f(N_1, \ldots, N_n) =_{\Sigma} N$ and $\phi = \top$.
   S4. If $f(M_1, \ldots, M_n) =_{\Sigma} M$ and $\text{nf}_{S, \Sigma}(\{M_1, \ldots, M_n, M\})$, then there exist $\sigma$ and $f$ such that $M = N\sigma$ and $M_i = N_i\sigma$ for all $i \in \{1, \ldots, n\}$.

3. The destructors of $\Sigma'$ are the destructors of $\Sigma$, with a rule $g(U_1, \ldots, U_n) \rightarrow U' \mid \phi \land \phi'$ in $\text{def}_{\Sigma'}(g)$ for each $g(U_1, \ldots, U_n) \rightarrow U \mid \phi$ in $\text{def}_{\Sigma}(g)$ and each $\text{addeval}(U_1, \ldots, U_n, U) \downarrow_{\Sigma'} (\{U_1', \ldots, U_n', U'\}, \sigma, \phi')$.

Stress that, in Item 3, since $U_1, \ldots, U_n$ do not contain any destructor and the side conditions of constructors are always $\top$, $\phi'$ is necessarily $\top$. The main difference between this definition and the definition of $\text{nf}_{S, \Sigma}$ is in Condition 3, since our destructors can now have a formula as side condition. The constructors of $\Sigma'$ can be computed by the algorithms given in [Baf08], and Item 3 shows how to compute the destructors of $\Sigma'$.

Note that, in $\Sigma'$, the side conditions of destructors still rely on the equational theory of $\Sigma$. Moreover, even if the semantics of the function symbols of $\Sigma'$ are all defined by rewrite rules, we still consider the constructors of $\Sigma$ as the constructors in $\Sigma'$. 

CHAPTER 9. PROVING MORE OBSERVATIONAL EQUIVALENCES WITH PROVERIF
9.3. CLAUSE GENERATION

Example 9.10. Consider the equational presentation \( \Sigma \) that has the constructors \( \text{senc} \) and \( \text{sdec} \) with the equations

\[
\text{sdec}(\text{senc}(x, y), y) = x \quad \text{senc}(\text{sdec}(x, y), y) = x
\]

In \( \Sigma' \), we adopt the rewrite rules:

\[
\begin{align*}
\text{sdec}(x, y) & \rightarrow \text{sdec}(x, y) & \text{senc}(x, y) & \rightarrow \text{senc}(x, y) \\
\text{sdec}(\text{senc}(x, y), y) & \rightarrow x & \text{senc}(\text{sdec}(x, y), y) & \rightarrow x \\
\text{sdec}(\text{fail}, u) & \rightarrow \text{fail} & \text{senc}(\text{fail}, u) & \rightarrow \text{fail} \\
\text{sdec}(u, \text{fail}) & \rightarrow \text{fail} & \text{senc}(u, \text{fail}) & \rightarrow \text{fail}
\end{align*}
\]

We have that \( \Sigma' \) models \( \Sigma \) for the rewriting system \( S \) with rules \( \text{sdec}(\text{senc}(x, y), y) \rightarrow x \) and \( \text{senc}(\text{sdec}(x, y), y) \rightarrow x \), and a single normal form for every term.

9.2.2.2 Observation equivalence w.r.t. \( \Sigma' \)

From this point on, we assume that \( \Sigma' \) models \( \Sigma \). We say that a biprocess \( P_0 \) is unevaluated when every term in \( P_0 \) is either a message variable or \( \text{diff}[a, a] \) for some name \( a \). Hence, every function symbol in \( P_0 \) must be in a term evaluation and prefixed by \( \text{eval} \). Moreover, we extend equality modulo the equational theory in \( \Sigma \) from terms to biprocesses and term evaluations: \( P =_{\Sigma} P' \) if, and only if, \( P' \) can be obtained from \( P \) by replacing some of its subterms \( M \) (not containing \( \text{diff} \) or \( \text{eval} \)) with subterms equal modulo \( \Sigma \). We define \( D =_{\Sigma} D' \) similarly. We can give two results that show the correspondence between \( \Sigma \) and \( \Sigma' \) in the derivation of biprocesses. The proofs of these results are adapted from [BAF08] Lemmas 1.2.

Lemma 9.4. Let \( P_0 \) be a closed, unevaluated biprocess. If \( P_0 \rightarrow^*_\Sigma P'_0, P'_0 =_{\Sigma} P', \) and \( \text{nf}_{S, \Sigma}(\{P'\}) \), then \( P_0 \rightarrow^*_\Sigma' P' \). Conversely, if \( P_0 \rightarrow^*_\Sigma' P' \) then there exists \( P'_0 \) such that \( P'_0 =_{\Sigma} P' \) and \( P_0 \rightarrow^*_\Sigma P'_0 \).

This lemma gives an operational correspondence between \( \rightarrow^*_\Sigma \) and \( \rightarrow^*_\Sigma' \). Using Lemma 9.4 we obtain:

Lemma 9.5. A closed biprocess \( P_0 \) satisfies the conditions of Lemma 9.3 if and only if, for all plain evaluation contexts \( C \), all evaluation contexts \( C' \), and all reductions unevaluated \( C[P_0] \rightarrow^*_\Sigma P \), we have

1. if \( P \equiv C'[\text{out}(N, M), Q | \text{in}(N', x), R] \) and \( \text{fst}(N) = \text{fst}(N') \), then \( \text{snd}(N) =_{\Sigma} \text{snd}(N') \),

2. if \( P \equiv C'[\text{let } x = D \text{ in } Q \text{ else } R] \) and \( \text{fst}(D) \downarrow_{\Sigma} M_1 \) for some \( M_1 \), then \( \text{snd}(D) \downarrow_{\Sigma} M_2 \) for some \( M_2 \),

as well as the symmetric properties where we swap \( \text{fst} \) and \( \text{snd} \).

In [BAF08], a special transition \( P \rightarrow^*_\Sigma' P' \) was defined as \( P \rightarrow^*_\Sigma P' \) except that signature \( \Sigma' \) was used for reduction rules (Red I/O) and (Red Fun 1)—signature \( \Sigma \) was still used for (Red Fun 2). In our case, we always use the signature \( \Sigma' \). The difference is due to the fact that the reference to \( \Sigma \) is now included in the side conditions of the definition of destructors in \( \Sigma' \).

9.3 Clause generation

In [BAF08], observational equivalence is verified by translating the considered biprocess into a set of Horn clauses, and using a resolution algorithm on these clauses. In this section, we show how we adapt the generation of the clauses to our new formalism.
9.3.1 Patterns and facts

In the clauses, the messages are represented by patterns, with the following grammar:

\[ p ::= \]
\[ x, y, z, i \]
\[ f(p_1, \ldots, p_n) \]
\[ a[p_1, \ldots, p_n] \]

patterns

variable

constructor application

name

\[ mp ::= \]
\[ p \]
\[ u, v \]
\[ \text{fail} \]

may-fail patterns

patterns

may-fail variable

failure

The patterns \( p \) are the same as in [BAF08]. The variable \( i \) represents a session identifier for each replication of a process. A pattern \( a[p_1, \ldots, p_n] \) is assigned to each name of a process \( P \). The arguments \( p_1, \ldots, p_n \) allow one to model that a fresh name \( a \) is created at execution of \( !a \). For example, in the process \(!m(c', x).va.P\), each name created by \( v a \) is represented by \( a[i, x] \) where \( i \) is the session identifier for the replication and \( x \) is the message received as input in \( \text{in}(c', x) \). Hence, the name \( a \) is represented as a function of \( i \) and \( x \). In two different sessions, \( (i, x) \) takes two different values, so the two created instances of \( a (a[i, x]) \) are different.

Since our formalism introduced may-fail messages to describe possible failure of a destructor, we also define may-fail patterns to represent the failure in clauses. Similarly to messages and may-fail messages, a may-fail variable \( u \) can be instantiated by a pattern or fail, whereas a variable \( x \) cannot be instantiated by fail.

Clauses are built from the following predicates:

\[ F ::= \]
\[ \text{att}'(mp, mp') \]
\[ \text{msg}'(p_1, p_2, p'_1, p'_2) \]
\[ \text{input}'(p, p') \]
\[ \text{formula}(\forall q. \neg \phi) \]
\[ \text{bad} \]

attacker knowledge

output message \( p_2 \) on \( p_1 \) (resp. \( p'_2 \) on \( p'_1 \))

input \( p \) (resp. \( p' \))

formula

bad

Once again, the facts are similar to the ones defined in [BAF08]. Intuitively, \( \text{att}'(mp, mp') \) means that the attacker may obtain \( up \) in \( \text{fst}(P) \) and \( up' \) in \( \text{snd}(P) \) by the same operations; the fact \( \text{msg}'(p_1, p_2, p'_1, p'_2) \) means that message \( p_2 \) may be output on channel \( p_1 \) by the process \( \text{fst}(P) \) while \( p'_2 \) may be output on channel \( p'_1 \) by the process \( \text{snd}(P) \) after the same reductions; \( \text{input}'(p, p') \) means that an input is possible on channel \( p \) in \( \text{fst}(P) \) and on channel \( p' \) in \( \text{snd}(P) \). Note that both facts \( \text{msg}' \) and \( \text{input}' \) contain only patterns and not may-fail patterns. Hence channels and terms sent are necessarily messages and so cannot be fail.

The fact formula(\( \phi \)) means that \( \phi \) has to be satisfied. In [BAF08], a fact nounif \((p, p')\) was used instead: nounif \((p, p')\) is equivalent to formula \((\forall \phi. p \neq p')\) where \( \phi \) are symbols in \( p \) and \( p' \) that belong to a special set of “general variables”. Hence, our formulas can also be encoded as conjunctions of nounif facts. We prefer using formulas, because their meaning is clearer from just reading the formula.

At last, \( \text{bad} \) serves in detecting violations of observational equivalence: when \( \text{bad} \) is not derivable, we have observational equivalence.

9.3.2 Clauses for the attacker

The following clauses represent the capabilities of the attacker:

\[ \text{For each } a \in \text{fnames}(P_0), \text{att}'(a[], a[]) \] (Rinit)

\[ \text{For some } b \text{ that does not occur in } P_0, \text{att}'(b[x], b[x]) \] (Rn)
9.3. CLAUSE GENERATION

\[ \text{att'}(\text{fail}, \text{fail}) \] (Rfail)

For each function \( h \), for each pair of rewrite rules

\[ h(U_1, \ldots, U_n) \rightarrow U \parallel \phi \] and \( h(U'_1, \ldots, U'_n) \rightarrow U' \parallel \phi' \)

in defV(h) (after renaming of variables),

\[ \text{att'}(U_1, U'_1) \land \ldots \land \text{att'}(U_n, U'_n) \land \text{formula}(\phi \land \phi') \rightarrow \text{att'}(U, U') \] (Rf)

\[ \text{msg}^i(x, y, x', y') \land \text{att'}(x, x') \rightarrow \text{att'}(y, y') \] (Ri)

\[ \text{input}'(x, x') \land \text{msg}'(x, y, x', y') \rightarrow \text{bad} \] (Rcom)

\[ \text{att'}(x, \text{fail}) \rightarrow \text{bad} \] (Rfailure)

plus symmetric clauses (Rcom') and (Rfailure') obtained from (Rcom) and (Rfailure) by swapping the first and second arguments of att' and input', and the first and third arguments of msg'.

The previous clauses are directly inspired from the ones in [BAF08] and correspond to the same semantics adapted to our formalism. Clauses (Rcom) and (Rcom') detect when a communication can occur in one variant of the biprocess and not in the other which yields the non-equivalence due to Condition 1 of Lemma 9.5.

Clause (Rfail) indicates that the attacker knows fail. Clauses (Ri) apply a constructor or a destructor on the attacker's knowledge, given the definition of the destructor in defV(h). Since our destructors may return fail, these clauses and clauses (Rfailure), (Rfailure') detect when a destructor succeeds in one variant of the biprocess and not in the other. In [BAF08], since the destructors were partial, the checking of success or failure of a destructor was written directly into clauses which correspond to the composition of our clauses (Rfailure) and (Ri) (respectively, (Rfailure') and (Ri)).

Stress that, in clause (Rfailure), \( x \) is a message variable and so \( x \) cannot be instantiated by fail. Similarly, in (Rcom), (Rs) and (Ri) \( x, x', y, y' \) are message variables and so they cannot be instantiated by fail.

9.3.3 Clauses for the protocol

The translation \([P]sH\) of a biprocess \( P \) is a set of clauses, where \( \rho \) is an environment that associates a pair of patterns with each name and variable, \( s \) is a sequence of patterns, and \( H \) is a sequence of facts. The empty sequence is written \( \emptyset \); the concatenation of a pattern \( p \) to the sequence \( s \) is written \( s, p \); the concatenation of a fact \( F \) to the sequence \( H \) is written \( H \parallel F \).

Intuitively, \( H \) represents the hypothesis of the clauses, \( \rho \) represents the names and variables that are already associated with a pattern, and \( s \) represents the current values of session identifiers and inputs.

When \( \rho \) associates a pair of patterns with each name and variable, and \( f \) is a constructor, we extend \( \rho \) as a substitution by \( \rho(f(M_1 \ldots, M_n)) = (f(p_1 \ldots, p_n), f(p'_1 \ldots, p'_n)) \) where \( \rho(M_i) = (p_i, p'_i) \) for all \( i \in \{1, \ldots, n\} \). We denote by \( \rho(M)_1 \) and \( \rho(M)_2 \) the components of the pair \( \rho(M) \).

We let \( \rho(\text{diff}[M, M']) = (\rho(M)_1, \rho(M)_2) \).

We define \([P]sH\) as follows:

\[ [0]sH = \emptyset \]
\[ [! P]sH = [P]sH \]
\[ [P | Q]sH = [P]sH \cup [Q]sH \]
\[ [\nu a.P]sH = [P](\rho(a \mapsto (a[s], a[s])))sH \]
\[ [\text{in}(M, x). P]sH = \]
\[ [P](\rho(x \mapsto (x', x'')))((s, x', x'')(H \parallel \text{msg}'(\rho(M)_1, x', \rho(M)_2, x''))) \]
\[ \cup (H \rightarrow \text{input}'(\rho(M)_1, \rho(M)_2)) \]

where \( x' \) and \( x'' \) are fresh variables.
[let $x = D$ in $P$ else $Q]]psH = $ \[ P \] psH \cup \{H \rightarrow msg'(\rho(M)_1, \rho(N)_1, \rho(M)_2, \rho(N)_2)\}$

$$\{\begin{array}{l}
\begin{align*}
& \cup \{[P][((\rho\sigma)(x \mapsto (p, p')))((\sigma, p, p')(H\sigma \land formula(\phi))) \mid (\rho(D)_1, \rho(D)_2) \downarrow' ((p, p'), (\sigma, \phi))
\end{align*}
\end{array}$$

Comparing with the clauses described in [BAF08], we can recognise the same kind of generated clauses: The process $P$ is translated when both $\rho(D)_1$ and $\rho(D)_2$ succeed; the process $Q$ is translated when both fail; and at last clauses deriving bad are generated when one of $\rho(D)_1$, $\rho(D)_2$ succeeds and the other fails. Since may-fail variables do not occur in $D$, we can show by induction on the computation of $\downarrow'$ that, when $(\rho(D)_1, \rho(D)_2) \downarrow' ((mp_1, mp_2), (\sigma, \phi))$, $mp_1$ and $mp_2$ are either fail or a pattern, but cannot be an may-fail variable, so our definition of $[let x = D$ in $P$ else $Q]]psH$ handles all cases.

However, one of the differences occurs for the translation of $[let x = D$ in $P$ else $Q]]psH$. It is once again due to the fact that in our formalism, in case of failure, term evaluations reduce into fail, whereas in [BAF08], they did not reduce at all. For example, the clauses representing the cases where a term evaluation of $D$ fails on the left side and succeeds on the right side was generated by considering a formula representing the negation of all possible terms reduced by the term evaluation on the left side. In our semantics, this formula is generated thanks to $(\rho(D)_1, \rho(D)_2) \downarrow' ((fail, fail), (\sigma, \phi))$.

A more meaningful difference is the presence of only one sequence of patterns $s$. Indeed, in [BAF08], the translation of a process was written $\llbracket P \rrbracket ps's'H$ where $s$ and $s'$ were sequences of patterns. Typically, $s$ was reserved for the part of the clauses translating $fst(P)$ whereas $s'$ was reserved for the part of the clauses translating $snd(P)$. For instance, in [BAF08], we have:

$$\llbracket[v a. P]ps's'H = \llbracket P \rrbracket \rho[a \mapsto (a[s], a[s'])]ss'H$$

$$\llbracket(M, x). P]ps's'H = \llbracket P \rrbracket \rho[x \mapsto (x', x'')]ss'H$$

As a result, in [BAF08], the arguments of the name $a$ in the first component were only the arguments coming from $fst(P)$ and the arguments of $a$ in the second component were the arguments coming from $snd(P)$. In this paper, the arguments of $a$ are the same in both components, and include the arguments coming from both $fst(P)$ and $snd(P)$. The difference is subtle, but Example 9.11 below gives an example of a biprocess that satisfies equivalence, and such that the clauses generated in [BAF08] yield a false attack which is avoided by our new clauses.

**Example 9.11.** Consider the signature $\Sigma = \{mac\}$ consisting of a MAC of arity 2 with the empty equational theory and the following biprocess:

$$P = vd!vk!vk'. out(d, diff[k, k']) | v!in(d, x). va. out(c, mac(a, x))$$

In this biprocess, the keys $k$ and $k'$ are generated and sent over a private channel $d$. After receiving these keys on $d$, they are used to mac a fresh nonce $a$ which is send on a public channel $c$. The main difference between $fst(P)$ and $snd(P)$ is that in $fst(P)$, an instance of the key $k$ can be sent several times on $d$ whereas in $snd(P)$, an instance of the key $k'$ is sent only once. However, since the instances of keys $k$ and $k'$ are never revealed to the attacker and the nonces $a$ are freshly generated for each MAC sent on the public channel $c$, the biprocess $P$ satisfies equivalence.

According to [BAF08], the translation of $P$ will generate the following clauses:
9.3. CLAUSE GENERATION

1. \(\text{msg}'(d[j], k[i], d[j], k'[i, j])\),

2. \(\text{input}'(d[j], d[j])\), and

3. \(\text{msg}'(d[j], x', d[j], x'') \Rightarrow \text{msg}'(c[j], \text{mac}(a[l, x'], x'), c[j], \text{mac}(a[l, x''], x''))\)

where \(i, j, \ell\) correspond to the session identifiers of replications.

But using two instances of \(j\), denoted \(j_1\) and \(j_2\), we obtain from Clause 1 the following facts \(\text{msg}'(d[j], k[i], d[j], k'[i, j_1])\) and \(\text{msg}'(d[j], k[i], d[j], k'[i, j_2])\). Hence, using Clause 3, we derive

- \(\text{msg}'(c[j], \text{mac}(a[l, k[i]], k[i]), c[j], \text{mac}(a[l, k'[i, j_1]], k'[i, j_1]))\); and
- \(\text{msg}'(c[j], \text{mac}(a[l, k[i]], k[i]), c[j], \text{mac}(a[l, k'[i, j_2]], k'[i, j_2]))\).

Thus, we obtain two facts \(\text{msg}'\) where the second arguments are equal whereas the fourth arguments are different (since \(j_1 \neq j_2\)). Using the Clause \(\text{R}\) and the clause corresponding to the test of failure of destructor equals, \(\text{bad}\) will be derivable.

This false attack is due to the fact that \(a[l, k[i]]\) and \(a[l, k'[i, j]]\) do not have the same level of freshness that is, the same arguments. This is why, to ensure that a name generated have the same level of freshness in \(\text{fst}(P)\) and \(\text{snd}(P)\), both \(x\) and \(x'\) are put as argument of \(a\) in \(\text{fst}(P)\) and \(\text{snd}(P)\). For instance, with our formalism, instead of Clause 3, we obtain from \(P\) the clause:

\(\text{msg}'(d[j], x', d[j], x'') \Rightarrow \text{msg}'(c[j], \text{mac}(a[l, x', x''], x'), c[j], \text{mac}(a[l, x', x''])\))

By applying this clause on \(\text{msg}'(d[j], k[i], d[j], k'[i, j_1])\) and \(\text{msg}'(d[j], k[i], d[j], k'[i, j_2])\), we obtain:

- \(\text{msg}'(c[j], \text{mac}(a[l, k[i]], k'[i, j_1]), c[j], \text{mac}(a[l, k[i]], k'[i, j_1]))\); and
- \(\text{msg}'(c[j], \text{mac}(a[l, k[i]], k'[i, j_2]), c[j], \text{mac}(a[l, k[i]], k'[i, j_2]))\).

In such a case, \(\text{mac}(a[l, k[i]], k'[i, j_1], k[i]) \neq \text{mac}(a[l, k[i]], k'[i, j_2], k[i])\) and so the previous false attack is avoided.

This example is a toy example but this kind of false attack can be found when checking the unlinkability of the e-passport protocol (see Section 3.3).

9.3.4 Proving equivalences

Let \(\rho_0 = \{a \mapsto (a[], a[]) \mid a \in \text{fnames}(P_0)\}\). We define the set of clauses that corresponds to biprocess \(P_0\) as:

\(\mathcal{R}_{P_0} = [\text{unevaluated}(P_0)]\rho_0\emptyset \cup \{\text{Rinit}, \text{Rn}, \ldots, \text{Rfailurc}, \text{Rfailurc}^c\}\)

The following theorem enables us to prove equivalences from these clauses.

Theorem 9.1. If \(\text{bad}\) is not a logical consequence of \(\mathcal{R}_{P_0}\), then \(P_0\) satisfies observational equivalence.

This theorem shows the soundness of the translation. The proof of this theorem is adapted from the proof of Theorem 3 of [BAF08]. Furthermore, since we use almost the same patterns and facts as in [BAF08], we also use the algorithm proposed in [BAF08] to automatically check if \(\text{bad}\) is a logical consequence of \(\mathcal{R}_{P_0}\), with the only change that we use the unification algorithm for may-fail patterns.
9.3.5 Proving Properties $P_1$ and $P_2$

In this section, we propose two algorithms that respectively verify Properties $P_1$ and $P_2$ of the destructors of $\Sigma$. We already know that all deterministic destructors obtained from Lemma $9.1$ satisfy both properties. However, since our extension allows a user to define his own destructor with side conditions, it is important to ensure that such destructors satisfy the desired properties.

Consider an equational presentation $\Sigma$ and assume that $\Sigma'$ models $\Sigma$. Consider the fact $\text{att}(mp)$ where $mp$ is a may-fail pattern. In order to verify that the destructors of $\Sigma$ satisfy Properties $P_1$ and $P_2$, we generate a new set of clauses defined as follows:

For some $a$, $\text{att}(a[x])$ (Rname)

$\text{att}(\text{fail})$ (Rfail)

For each constructor $f$ or arity $n$

$\text{att}(x_1) \land \ldots \land \text{att}(x_n) \rightarrow \text{att}(f(x_1, \ldots, x_n))$ (Recons)

For each destructor $g$, for each pair of rewrite rules

$g(U_1, \ldots, U_n) \rightarrow U \parallel \phi$ and $g(U'_1, \ldots, U'_n) \rightarrow U' \parallel \phi'$

in $\text{def}_{\Sigma'}(g)$ (after renaming of variables), $\sigma$ is the most general unifier of $\{(U, x), (U', x)\}$ and $x$ fresh,

$\text{att}(U_1) \land \ldots \land \text{att}(U_n) \land \text{att}(\text{fail}) \land \text{att}(\phi \land \phi' \land x \sigma \neq \Sigma y \sigma) \rightarrow \text{bad}$ (Rdeter)

For each destructor $g$, for each pair of rewrite rules

$g(U_1, \ldots, U_n) \rightarrow U \parallel \phi$ and $g(U'_1, \ldots, U'_n) \rightarrow U' \parallel \phi'$

in $\text{def}_{\Sigma'}(g)$ (after renaming of variables), $\sigma$ is the most general unifier of $\{(U, x), (U', \text{fail})\}$ and $x$ fresh,

$\text{att}(U_1) \land \ldots \land \text{att}(U_n) \land \text{att}(\text{fail}) \land \text{att}(\phi \land \phi' \rightarrow \text{bad})$ (Rdeter2)

For each destructor $g$, for each $i \subseteq \{1, \ldots, n\}$

$\forall i \in I, U_i = x_i,$ and $\forall i \notin I, U_i = \text{fail}$

$x_1, \ldots, x_n$ fresh variables

$\text{att}(x_1) \land \ldots \land \text{att}(x_n) \land \text{fails}(U_1, \ldots, U_n) \rightarrow \text{bad}$ (Rtotal)

where $\text{fails}(U_1, \ldots, U_n) = \bigwedge_{\sigma_u} g(V_1, \ldots, V_n) \rightarrow V' \parallel \phi$ in $\text{def}_{\Sigma'}(g)$

$\text{formula}(\forall \bar{z}. [\bigvee_{i \in I} x_i \neq \Sigma V_i \sigma_u \lor \phi \sigma_u])$

where $\bar{z}$ are the variables of $V_1 \sigma_u, \ldots, V_n \sigma_u$.

Intuitively, the purpose of the clauses (Recons) and (Rname) is to generate constructor terms. Clauses (Rdeter) and (Rdeter2) check that the destructors satisfy Property $P_2$. Clauses (Rtotal) check that the destructors satisfy Property $P_1$.

Note that in Clauses (Rtotal), the formulas $\phi$ included in the predicate formula$(\phi)$ are more complex than the usual conjunction of inequalities. In [BAC08], the solving algorithm applies several simplifications on predicates $\text{formula}(\phi)$ that preserve the solutions of $\phi$. However, only the formulas $\bigwedge_i \forall \bar{z}_i, p_i \not\equiv_{\Sigma} p'_i$, for some $\bar{z}_i$, $p_i$, $p'_i$, are handled in this algorithm. Hence, we added some simplifications (see Appendix D.1.3) on first order logic such that our extension of ProVerif can now handle predicates $\text{formula}(\phi)$ with a formula $\phi$ of the form $\bigwedge_i \forall \bar{z}_i. [M_i \not\equiv_{\Sigma} N_i \lor \bigvee_{j} \exists y_j, L_j \equiv_{\Sigma} O_i]$.

The algorithms that check Properties $P_1$ and $P_2$ follow the next two lemmas (proofs in Appendix D.1.2):

**Lemma 9.6.** We consider $R_{\Sigma'} = \{ \text{Rname}, \text{Rfail}, \text{Recons}, \text{Rtotal} \}$, $\text{bad}$ is not a logical consequence of $R_{\Sigma'}$ if, and only if, for all $g$ destructors of $\Sigma$, $g$ satisfies Property $P_2$. 
9.4. AUTOMATIC MODIFICATION OF THE PROTOCOL

Lemma 9.7. We consider \( R_{\Sigma_{P_2}} = \{ \{ \text{Rname}, \text{Rfail}, \text{Rcons}, \text{Rdeter}, \text{Rdeter2} \} \} \). bad is not a logical consequence of \( R_{\Sigma_{P_2}} \) if, and only if, for all g destructors of \( \Sigma \), g satisfies Property \( P_2 \).

Note that we do not provide guarantees on the termination of the two algorithms but we rely on the algorithm of \([\text{BAFOS}]\) to check if bad is derivable or not.

9.4 Automatic modification of the protocol

In this section, we first present the false attack that we want to avoid and then propose an algorithm to automatically generate, from a biprocess \( P \), equivalent biprocesses on which ProVerif will avoid this kind of false attack.

9.4.1 Targeted false attack

We present a false attack on the anonymity of the private authentication protocol due to structural conditional branching, but similar false attack exists on the unlinkability of the Basic Access Control protocol.

Example 9.12. Coming back to the private authentication protocol (see Example 9.8), we obtained a biprocess \( P_0 \) on which we would ask ProVerif to check the equivalence. Unfortunately, ProVerif is unable to prove the equivalence of \( P_0 \) and yields a false attack. Indeed, consider the evaluation context \( C \) defined as follows:

\[
C \overset{\text{def}}{=} \nu n_i . \text{in}(c, x_{sh_a}) . \text{in}(c, x_{sh_b}) . \text{out}(c, \text{aenc}((n_i, x_{sh_a}), x_{sh_b}))
\]

The process \( C[P_0] \) can be derived as follows:

\[
C[P_0] \rightarrow \Sigma^{\nu n_i . \text{in}(c, x_{sh_a}) . \text{in}(c, x_{sh_b}) . \text{out}(c, \text{aenc}((n_i, x_{sh_a}), x_{sh_b}))}
\]

\[
\rightarrow \Sigma^{\nu n_i . \text{in}(c, x_{sh_a}) . \text{in}(c, x_{sh_b}) . \text{out}(c, \text{aenc}((n_i, x_{sh_a}), x_{sh_b}))}
\]

However from this point, the biprocess gets stuck, i.e. no internal reduction rule is applicable. More specifically, neither the internal rule (Red Fun 1) nor (Red Fun 2) is applicable. Indeed, if we denote \( D = \text{equals}(|\text{proj}_2((n_i, x_{sk_a})), \text{pk}(|\text{diff}[x_{sk_a}, x_{sk_b}]|)) \), we have that \( \text{snd}(D) \downarrow \Sigma \text{fail} \) and \( \text{fst}(D) \downarrow \Sigma \text{pk}(x_{sk_a}) \), which contradicts the item 2 of Lemma 9.3. So ProVerif cannot prove the equivalence.

On the other hand, even though a different branch of the let is taken, the process outputs the message \( \text{aenc}((n_b, x_{sk_b}), \text{pk}(x_{sk_a})) \) in the first variant (in branch of the let) and the message \( \text{aenc}(n_b, \text{pk}(sk_b)) \) in the second variant (else branch of the let). Intuitively, these two messages are indistinguishable, so in fact the attacker will not be able to determine which branch of the let is taken, and observational equivalence still holds.

As shown in the previous example, ProVerif may return a false attack against the observational equivalence, when a different branch of let is taken, but these branches are in fact indistinguishable. In this section, we will show how to use destructors with side conditions in order to avoid such false attacks. Moreover, we will propose an algorithm to automatically transform a biprocess into biprocesses that will avoid such false attacks when such a transformation is possible.

The key idea is to transform term evaluations such as let \( x = D \) in \( \text{out}(c, M_1) \) else \( \text{out}(c, M_2) \) into a computation that always succeeds let \( x = D' \) in \( \text{let} \ m = D'' \text{in} \text{out}(c, m) \). The term evaluation \( D' \) will correspond to the value of the evaluation of \( D \) when the latter succeeds and a new constant when \( D \) fails. Thus we ensure that \( D' \) never fails. Moreover, the term evaluation \( D'' \) computes either \( M_1 \) or \( M_2 \) depending on the value of \( D' \), i.e. depending on whether \( D \) succeeds or not. The omitted else 0 branches are never taken. Since the same branch is always taken, the false attack disappears. To do that, we introduce three new destructors \( \text{glet}, \text{gletin}, \text{notfail} \) and a constant \( c_o \),
which rely on the side conditions that we have added to destructors. These new destructors are defined as follows:

\[
\begin{align*}
def_{\Sigma}(\text{glet}) &= glet(x) \rightarrow x \\
def_{\Sigma}(\text{gletin}) &= gletin(x, u, v) \rightarrow u \mid x \neq \Sigma \ c_o \\
def_{\Sigma}(<\text{notfail}) &= \text{notfail}(x) \rightarrow \text{fail} \\
gletin(fail) &\rightarrow c_o \\
gletin(c_o, u, v) &\rightarrow v \\
gletin(fail, u, v) &\rightarrow \text{fail}
\end{align*}
\]

One can easily check that \(\text{def}_{\Sigma}(\text{glet}), \text{def}_{\Sigma}(\text{gletin})\) and \(\text{def}_{\Sigma}(<\text{notfail})\) satisfy Properties [\[11\]] and [\[12\]]. Intuitively, the destructor \(\text{glet}\) evaluates its argument and returns either the result of this evaluation when it did not fail or else returns the new constant \(c_o\) instead of the failure constant \(\text{fail}\). The destructor \(\text{gletin}\) will get the result of \(\text{glet}\) as first argument and return its third argument if \(\text{glet}\) returned \(c_o\) and its second argument otherwise. Importantly, \(\text{glet}\) never fails: it returns \(c_o\) instead of \(\text{fail}\). Hence, let \(x = D\) in \(\text{out}(c, M_1)\) else \(\text{out}(c, M_2)\) can be transformed into let \(x = \text{eval} \ glet(D)\) in \(m = \text{eval} \ gletin(x, M_1, M_2)\) in \(\text{out}(c, m)\): if \(D\) succeeds, \(x\) has the same value as before, and \(x \neq c_o\), so \(\text{gletin}(x, M_1, M_2)\) returns \(M_1\); if \(D\) fails, \(x = c_o\) and \(\text{gletin}(x, M_1, M_2)\) returns \(M_2\). The destructor \(<\text{notfail}>\) inverses the status of a term evaluation: it fails if and only if its argument does not fail. These destructors will be used in the next section.

**Example 9.13.** Coming back to Example [\[7.1\]], the false attack occurs due to the following term evaluation:

\[
\begin{align*}
\text{let } x &= \text{equals}(\text{proj}_2(x), \text{pk}(\text{diff}[\Sigma, \text{sk_a}])) \text{ in} \\
\text{out}(c, \text{aenc}(\langle n_i, \langle n_b, \text{pk}(\text{sk_b}) \rangle, \text{pk}(\text{diff}[\text{sk_a}, \text{sk_a}]) \rangle)) \\
\text{else } \text{out}(c, \text{aenc}(\langle n_b, \text{pk}(\text{sk_b}) \rangle))
\end{align*}
\]

We transform this term evaluation as explained above:

\[
\begin{align*}
\text{let } x &= \text{gletin}(\text{glet}(\text{equals}(\text{proj}_2(x), \text{pk}(\text{diff}[\Sigma, \text{sk_a}]))), M, M') \text{ in } \text{out}(c, x)
\end{align*}
\]

where \(M = \text{aenc}(\langle n_i, \langle n_b, \text{pk}(\text{sk_b}) \rangle \rangle, \text{pk}(\text{diff}[\text{sk_a}, \text{sk_a}]) \rangle)\) and \(M' = \text{aenc}(\langle n_b, \text{pk}(\text{sk_b}) \rangle)\). Note that with \(x = \langle n_i, \text{pk}(\text{sk_b}) \rangle\) (see Example [\[7.1\]], if \(D\) is the term evaluation \(D = \text{gletin}(\text{glet}(\text{equals}(\text{proj}_2(x), \text{pk}(\text{diff}[\Sigma, \text{sk_a}]))), M, M')\), we obtain that:

- \(\text{fst}(D) \downarrow \text{aenc}(\langle n_i, \langle n_b, \text{pk}(\text{sk_b}) \rangle \rangle, \text{pk}(\text{sk_a}))\)
- \(\text{snd}(D) \downarrow \text{aenc}(\langle n_b, \text{pk}(\text{sk_b}) \rangle)\)

which corresponds to what \(\text{fst}(P_0)\) and \(\text{snd}(P_0)\) respectively output. Thanks to this, if we denote by \(P'_0\) our new biprocess, we obtain that \(\text{fst}(P_0) \approx \text{fst}(P'_0)\) and \(\text{snd}(P_0) \approx \text{snd}(P'_0)\). Furthermore, \textsc{ProVerif} will be able to prove that the biprocess \(P'_0\) satisfies equivalence, i.e. \(\text{fst}(P'_0) \approx \text{snd}(P'_0)\) and so \(\text{fst}(P_0) \approx \text{snd}(P_0)\).

The transformation proposed in the previous example can be generalised to term evaluations that perform other actions than just a single output. However, it is possible only if the success branch and the failure branch of the term evaluation both input and output the same number of terms. For example, the biprocess \(P = \text{let } x = D \text{ in } \text{out}(c, M_0) \text{ out}(c, M') \text{ else } \text{out}(c, N)\) cannot be modified into one without else branch even with our new destructors. On the other hand, the success or failure of \(D\) can really be observed by adversary, by tracking the number of outputs on channel \(c\), so the failure of the proof of equivalence corresponds to a real attack in this case.

### 9.4.2 Merging and simplifying biprocesses

To automatically detect and apply this transformation, we define two functions, denoted \textit{merge} and \textit{simpl}. The function \textit{simpl} takes one biprocess as argument and applies the transformation when possible. The function \textit{merge} takes two biprocesses as arguments and detects if those two biprocesses can be merged into one biprocess. Furthermore, if the merging is possible, it returns the merged biprocess. This merged biprocess is expressed using a new operator \textit{diff}, similar to \textit{diff}, in such a way that \(\text{diff}[D, D']\) is a term evaluation. Furthermore, we introduce the functions \(\text{fst}'\)
and $\text{snd}'$: $\text{fst}'(P)$ replaces each $\text{diff}'[D, D']$ with $D$ in $P$; similarly, $\text{snd}'(P)$ replaces each $\text{diff}'[D, D']$ with $D'$ in $P$.

Figures 9.6 and 9.7 define the functions $\text{merge}$ and $\text{simpl}$. The function $\text{merge}$ is partial whereas $\text{simpl}$ is total. Both functions are non-deterministic; the implementation may try all possibilities.

In the current implementation of PROVERIF, we apply the rules $\text{Mlet1}$ and $\text{Mlet2}$ only if the rules $\text{Mlet3}$ and $\text{Mlet4}$ are not applicable. Moreover, we never merge 0 with a process different from 0. This last restriction is crucial to reduce the number of biprocesses returned by the functions $\text{merge}$ and $\text{simpl}$. Typically, we avoid 0 and let $x = M$ in $P$ else 0 to be merged by the rule $\text{Mlet4}$.

Case $\text{Mlet1}$ detects that both biprocesses output a message while case $\text{Mlet2}$ detects that both biprocesses input a message. We introduce a $let$ for the channels and messages so that they can later be replaced by a term evaluation. Case $\text{Mpar}$ uses the commutativity and associativity of parallel composition to increase the chances of success of $\text{merge}$. Cases $\text{Mres}$ and $\text{Mres'}$ use $Q \approx \nu a.Q$ when $a \notin \text{frames}(Q)$ to allow merging processes even when a restriction occurs only on one side. Case $\text{Mrepl2}$ is the basic merging of replicated processes, while Case $\text{Mrepl1}$ allows merging $!!P$ with $!!P'$ (case $n = 0$) because $P \approx !!P$, and furthermore allows restrictions between the two replications, using $Q \approx \nu a.Q$.

Case $\text{Mlet1}$ merges two processes that both contain term evaluations, by merging their success branches together and their failure branches together. On the other hand, Case $\text{Mlet2}$, $\text{Mlet3}$ also merge two processes that contain term evaluations, by merging the success branches with the other failure branches.

Cases $\text{Mlet3}$, $\text{Mlet3'}$, $\text{Mlet4}$, $\text{Mlet4'}$ allow merging a term evaluation with another process $P'$, by merging $P'$ with either the success branch or the failure branch of the term evaluation. (The evaluation of $c_a$ always succeeds since it is a message.) This merging is useful when $\text{PROVERIF}$ can prove that the resulting process satisfies equivalence, hence when both sides of the obtained $let$ succeed simultaneously. Therefore, rule $\text{Mlet3}$ is helpful when the term evaluation $P$ always succeeds, and rule $\text{Mlet4}$ when $D$ always fails. When no such case applies, merging fails.

The function $\text{simpl}$ proceeds by induction on the process. The only interesting case is $\text{Smerge}$, which performs the transformation of term evaluations outlined above, when we can merge the success and failure branches. $Q' = \text{eval gletin}(x, D_1, D_2)/\text{diff}[D_1, D_2]$ means that we replace in $Q'$ every instance of $\text{diff}'[D_1, D_2]$ for some $D_1, D_2$, with eval $\text{gletin}(x, D_1, D_2)$.

Lemmas 9.8 and 9.9 below show that the functions $\text{merge}$ and $\text{simpl}$ preserve observational equivalence. In these two lemmas, we consider processes $P$ and $P'$ that are not necessarily closed. We say that a context $C$ is closing for $P$ when $C[P]$ is closed. Moreover, given two biprocesses $P$ and $Q$, we say that $P \approx Q$ if, and only if, $\text{fst}(P) \approx \text{fst}(Q)$ and $\text{snd}(P) \approx \text{snd}(Q)$. All results of this section are proved in Appendix D.2.

**Lemma 9.8.** Let $P$ and $P'$ be two biprocesses. If $\text{merge}(P, P') = Q$, then:

- for all contexts $C$ closing for $P$, $C[P] \approx C[\text{fst}'(Q)]$;
- for all contexts $C$ closing for $P'$, $C[P'] \approx C[\text{snd}'(Q)]$.

**Lemma 9.9.** Let $P$ be a biprocess. For all contexts $C$ closing for $P$, $C[P] \approx C[\text{simpl}(P)]$.

**Corollary 9.1.** Let $P$ be a closed biprocess. If $\text{simpl}(P)$ satisfies observational equivalence then $\text{fst}(P) \approx \text{snd}(P)$.

**Proof.** $\text{simpl}(P)$ satisfies observational equivalence implies $\text{fst}(\text{simpl}(P)) \approx \text{snd}(\text{simpl}(P))$. Since $P$ is closed, we can apply Lemma 9.9 with the empty context, so $\text{simpl}(P) \approx P$. Hence by definition of the observation equivalence on biprocesses, we obtain that $\text{fst}(\text{simpl}(P)) \approx \text{fst}(P)$ and $\text{snd}(P) \approx \text{snd}(\text{simpl}(P))$. We conclude that $\text{fst}(P) \approx \text{snd}(P)$. □

From Corollary 9.1 we can extract our new algorithm. Given a biprocess $P$ as input, we first apply the function $\text{simpl}$ on $P$. Since the function $\text{simpl}$ is total but non-deterministic, we may have several biprocesses as result for $\text{simpl}(P)$. If $\text{PROVERIF}$ is able to prove equivalence on at least one of them, then we conclude that $\text{fst}(P) \approx \text{snd}(P)$. 

\[
\begin{align*}
merge(0, 0) & \overset{\text{def}}{=} 0 \\
merge(out(M, N).P, out(M', N').P') & \overset{\text{def}}{=} \\
& \text{let } x = \text{diff}'[M, M'] \text{ in let } x' = \text{diff}'[N, N'] \text{ in out}(x, x').merge(P, P') \\
& \text{where } x \text{ and } x' \text{ are fresh variables} \\
merge(in(M, x).P, in(M', x').P') & \overset{\text{def}}{=} \\
& \text{let } y = \text{diff}'[M, M'] \text{ in in}(y, y').merge(P[y/x], P'[y'/x']) \\
& \text{where } y \text{ and } y' \text{ are fresh variables} \\
merge(P_1 \{ P_n, P_1', \ldots, P_n' \} & \overset{\text{def}}{=} Q_1 \{ Q_n, \ldots, Q_n' \} \\
& \text{if } (i_1, \ldots, i_n) \text{ is a permutation of } (1, \ldots, n) \\
& \text{and for all } k \in \{1, \ldots, n\}, Q_k = merge(P_k, P_k') \\
merge(va.P, Q) & \overset{\text{def}}{=} va.merge(P, Q) \\
& \text{after renaming } a \text{ such that } a \notin \text{frames}(Q) \\
merge(!va_1 \ldots va_n.P, !P') & \overset{\text{def}}{=} !va_1 \ldots va_n.merge(!P, !P') \\
& \text{after renaming } a_1, \ldots, a_n \text{ such that } a_1, \ldots, a_n \notin \text{frames}(P') \\
merge(!P, !P') & \overset{\text{def}}{=} !merge(P, P') \\
& \text{if there is no } P \text{ such that } P = !P_1 \text{ and no } P' \text{ such that } P' = !P'_1 \\
merge(\text{let } x = D \text{ in } P_1 \text{ else } P_2, \text{let } x' = D' \text{ in } P_1' \text{ else } P_2') & \overset{\text{def}}{=} \\
& \text{let } y = \text{diff}'[D, D'] \text{ in } Q_1 \text{ else } Q_2 \text{ if } y \text{ is a fresh variable,} \\
& Q_1 = merge(P_1[y/x], P_1'[y'/x']), \text{ and } Q_2 = merge(P_2, P_2') \\
merge(\text{let } x = D \text{ in } P_1 \text{ else } P_2, \text{let } x' = D' \text{ in } P_1' \text{ else } P_2') & \overset{\text{def}}{=} \\
& \text{let } y = \text{diff}'[D, \text{notfail}(D')] \text{ in } Q_1 \text{ else } Q_2 \text{ if } y \text{ is a fresh variable,} \\
& x' \notin \text{fvars}(P_1'), Q_1 = merge(P_1[y/x], P_2), \text{ and } Q_2 = merge(P_2, P_1') \\
merge(\text{let } x = D \text{ in } P_1 \text{ else } P_2, P') & \overset{\text{def}}{=} \text{let } y = \text{diff}'[D, \epsilon_\circ] \text{ in } Q \text{ else } P_2 \\
& \text{if } y \text{ is a fresh variable and } Q = merge(P_1[y/x], P') \\
merge(\text{let } x = D \text{ in } P_1 \text{ else } P_2, P') & \overset{\text{def}}{=} \\
& \text{let } y = \text{diff}'[D, \text{fail}] \text{ in } P_1[y/x] \text{ else } Q \\
& \text{if } y \text{ is a fresh variable and } Q = merge(P_2, P') \\
\end{align*}
\]

plus symmetric cases \(\text{Mres}', \text{Mrepl1}', \text{Mlet1}', \text{Mlet2}', \text{Mlet3}', \text{Mlet4}')\) obtained from \(\text{Mres}, \text{Mrepl1}, \text{Mlet1}, \text{Mlet2}, \text{Mlet3}, \text{and Mlet4})\) by swapping the first and second arguments of \(\text{merge}\) and \(\text{diff}'\).

Figure 9.6: Definition of the function \(\text{merge}\)


\begin{verbatim}
\text{simpl}(0) \text{ def} 0  \quad \text{(Snil)}
\text{simpl}(\text{out}(M,N).P) \text{ def} \text{out}(M,N).\text{simpl}(P)  \quad \text{(Sout)}
\text{simpl}(\text{in}(M,x).P) \text{ def} \text{in}(M,x).\text{simpl}(P)  \quad \text{(Sin)}
\text{simpl}(P \mid Q) \text{ def} \text{simpl}(P) \mid \text{simpl}(Q)  \quad \text{(Smid)}
\text{simpl}(\text{va}.P) \text{ def} \text{va}.\text{simpl}(P)  \quad \text{(Sres)}
\text{simpl}(\text{!}P) \text{ def} \text{!}\text{simpl}(P)  \quad \text{(Srepl)}
\end{verbatim}

\textbf{Corollary 9.2.} Let \( P \) and \( P' \) be two closed processes. Let \( Q = \text{merge}(\text{simpl}(P), \text{simpl}(P')) \). If the biprocess \( Q' = Q\{\text{def}[D,D']/\text{dhr}[D,D']\} \) satisfies observational equivalence, then we have \( P \approx P' \).

\textbf{Proof.} According to Figures 9.6 and 9.7, if \( P \) and \( P' \) do not contain any \text{diff} then so do \text{simpl}(P), \text{simpl}(P') and \text{merge}(P,P'). Hence, \( Q \) does not contain any \text{diff}. Hence, the biprocess \( Q' = Q\{\text{def}[D,D']/\text{dhr}[D,D']\} \) satisfies \( \text{fst}(Q') = \text{fst}'(Q) \) and \( \text{snd}(Q') = \text{snd}'(Q) \). Since \( Q' \) satisfies observational equivalence, we have that \( \text{fst}(Q') \approx \text{snd}(Q') \) thus \( \text{fst}'(Q) \approx \text{snd}'(Q) \). Since \( P \) and \( P' \) are closed processes, by Lemma 9.8 we have \( P \approx \text{simpl}(P) \) and \( P' \approx \text{simpl}(P') \). Furthermore, by Lemma 9.8 we deduce that \( \text{simpl}(P) \approx \text{fst}'(Q) \) and \( \text{simpl}(P') \approx \text{snd}'(Q) \). We conclude that \( P \approx P' \).

Currently, ProVerif can only take a biprocess as input. But thanks to Corollary 9.2, we will be able to loosen this condition. Indeed, consider \( P \) and \( P' \) two processes (without \text{diff}). If we manage to merge them into the biprocess \( Q' \) as in Corollary 9.2 and to prove that \( Q' \) satisfies equivalence by ProVerif, then we obtain that \( P \approx P' \).

\section{Applications}

Currently, we implemented our extension in a development version of ProVerif for typed processes. However, some features still need to be adapted to the new formalism before the next stable release, such as the front-end for untyped processes. In any case, we present in this subsection the application of our extension on the private authentication protocol and the e-passport protocol (see Section 3-5).

\subsection{Successful case study: the private authentication protocol}

The simplification of processes described in this section was implemented in such a way that the transformation stays hidden from the users. However, since the function \text{simpl} may return several biprocesses, we do not automatically test the equivalence of all the biprocesses given by the function \text{simpl}. Furthermore, proving the equivalence requires a lot of times on some biprocesses and might even not terminate. Hence allowing the user to choose whether or not ProVerif has to prove equivalence on the biprocesses returned by the function \text{simpl} seemed more user-friendly.
By default, ProVerif first tries to prove the equivalence that was provided in the input file without modifying it. Figure 9.8 is a possible input file for the private authentication protocol. In case of non-equivalence, it will compute the function simpl on the input biprocess and propose to prove the equivalence on the simplified biprocesses. In the case of the private authentication protocol, ProVerif first states the non-equivalence due to a false attack (see Example 9.12), but then succeeds to prove the observational equivalence on the only biprocess obtained by application of the function simpl. Note that ProVerif also proposes to display the biprocesses obtained by application of simpl but they are usually difficult to parse due to the variable renaming and the extensive use of the destructors glet and gletin.

9.5.2 Limitations: the Basic Access Control protocol

We consider here the unlinkability of the BAC protocol. As mentioned in Section 9.4, this security property can be expressed by the following equivalence:

$$!\nu ke. \nu km. !BAC(ke, km) \approx !\nu ke. \nu km. BAC(ke, km)$$

In contrast to the equivalence given in Section 9.3 we explicitly denote the keys whom BAC depends on and we rely on the observational equivalence and not the trace equivalence. Moreover,
BAC(ke, km) is in fact the parallel composition of two processes, one for the passport and one for the reader, each of them depending on the keys ke and km.

Note that the two parts of this equivalence cannot be directly transformed into a biprocess due to the second replication on the left part of the process. However, we can modify slightly the two parts of the equivalence so that they can define a biprocess. Indeed, the following equivalence holds:

\[
!\nu ke. \nu km. BAC(ke, km) \approx !\nu ke'. \nu km'. !\nu ke. \nu km. BAC(ke, km)
\]

Intuitively, this non-trivial equivalence holds due to the fact that the keys ke, km are not used in BAC(ke, km) and that \( !! P \approx P \). Similarly, we have that:

\[
!\nu ke. \nu km. !BAC(ke, km) \approx !\nu ke. \nu km. !\nu ke'. \nu km'. BAC(ke, km)
\]

Hence, after renaming of the keys ke, km, ke', km', the unlinkability of the BAC protocol can be expressed by the following equivalence:

\[
!\nu ke. \nu km. !\nu ke'. \nu km'. BAC(ke, km) \approx !\nu ke. \nu km. !\nu ke'. \nu km'. BAC(ke', km')
\]

which is represented by the biprocess \( !\nu ke. \nu km. !\nu ke'. \nu km'. BAC(ke, km) \approx !\nu ke. \nu km. !\nu ke'. \nu km'. BAC(ke', km') \). Figure 9.9 is a possible input file for the unlinkability of the BAC protocol.

Thanks to our extension, the false attack described in Example 9.11 is now avoided. Moreover, after application of the function simp1, PROVerif also avoids a false attack similar to the false attack on the anonymity of the private authentication protocol (due to the test \( \text{mac}(m_1, km) = m_m \) in the process representing the passport). Hence, in both case studies, PROVerif avoids the false attacks that are due to conditional branching. Unfortunately, even with our extension, PROVerif is still not able to prove unlinkability of the BAC protocol and returns a false attack. This false attack, described below, is caused by the fact that PROVerif necessarily matches an interleaving of actions of one part of a biprocess with exactly the same interleaving of actions of the other part of this biprocess (see semantics of biprocesses).

We denote \( P(ke, km) \) the process representing the passport and \( R(ke, km) \) the one representing the reader. The intruder proceeds as follows: He starts by engaging the communication with two sessions of the same passport on the one hand, and so necessarily one session of two different passports on the other hand. Hence, it is similar to a biprocess where the left and right parts are represented as follows:

- **Left**: \( P(ke_1, km_1) \ | R(ke_1, km_1) \ | P(ke_1, km_1) \ | R(ke_1, km_1) \)
- **Right**: \( P(ke_1, km_1) \ | R(ke_1, km_1) \ | P(ke_2, km_2) \ | R(ke_2, km_2) \)

In the right part of the biprocess, the intruder receives the nonce \( n_1 \) that \( P(ke_1, km_1) \) output and sends it to the reader \( R(ke_2, km_2) \). Similarly, he sends the nonce \( n_2 \) that \( P(ke_2, km_2) \) output and sends it to the reader \( R(ke_1, km_1) \). Hence, the readers \( R(ke_1, km_1) \) and \( R(ke_2, km_2) \) will output respectively the messages \( (m_1, \text{mac}(m_1, km_1)) \) and \( (m_2, \text{mac}(m_2, km_2)) \) where \( m_1 = \text{sdec}(\langle n_1, \langle n_2, kr_1 \rangle \rangle, ke_1) \) and \( m_2 = \text{sdec}(\langle n_2, \langle n_1, kr_2 \rangle \rangle, ke_2) \). Note that since the intruder swaps the nonces \( n_1, n_2 \) that was intended to the readers, they are also swapped in \( m_1, m_2 \).

Then, the intruder swaps again the messages \( (m_1, \text{mac}(m_1, km_1)) \) and \( (m_2, \text{mac}(m_2, km_2)) \) and sends them to \( P(ke_2, km_2) \) and \( P(ke_1, km_1) \) respectively. Since \( P(ke_1, km_1) \) receives \( m_2 \) which is encrypted with \( ke_2 \), the decryption \( \text{sdem}(m_2, ke_1) \) will fail and so \( P(ke_1, km_1) \) will output the error \( \text{error}_{6A80} \). Similarly, \( P(ke_2, km_2) \) will also output the error \( \text{error}_{6A80} \).

On the other hand, in the left part of the biprocess, since the intruder communicates with two sessions of the same passport, there is only one set of keys \( (ke_1, km_1) \) and so both decryptions will succeed. Moreover, since the intruder swaps the messages twice, both passports will be able to check that the nonce \( n_1 \) encrypted in the message they received corresponds to the nonce they previously sent. Hence, both passports will output a message of the form \( \text{senc}(m', \text{mac}(m', km_1)) \). Since \( \text{error}_{6A80} \) is public, the intruder is able to distinguish \( \text{error}_{6A80} \) from \( \text{senc}(m', \text{mac}(m', km_1)) \) and so PROVerif returns that the equivalence does not hold.
(* ePassport Protocol Taken from Arapinis, Ryan, CSF'10 *)

fun enc(bitstring, bitstring): bitstring.
fun mac(bitstring, bitstring): bitstring.
fun dec(bitstring, bitstring): bitstring.

(* Symmetric decryption *)
equation for all x: bitstring, y: bitstring; dec(enc(x,y),y) = x.

(* addition of one *)
free c: channel.
free get_challenge: bitstring.
free error_6A80: bitstring.

let reader(ke:bitstring, km:bitstring) =
  out(c, get_challenge);
in(c, nt: bitstring);
new nr: bitstring;
new kr: bitstring;
let m:bitstring = enc((nr,nt,kr),ke) in
out(c, (m,mac(m,km)));
in(c, y: bitstring).

let passport(ke:bitstring, km:bitstring) =
in(c, x: bitstring);
if x = get_challenge then
  new nt: bitstring;
  out(c, nt);
in(c, y: bitstring);
  let (m_e:bitstring, m_m: bitstring) = y in
  if mac(m_e,km) = m_m then
    new nr:bitstring;
    let (nr:bitstring, nt':bitstring, kr:bitstring) = dec(m_e,ke) in
    if nt = nt' then
      new kt: bitstring;
      out(c, (enc((nt, nr, kr), ke), mac(enc((nt, nr, kr), ke), km)))
    else
      out(c, error_6A80)
  else
    out(c, error_6A80)
else
  out(c, error_6A80).

process
  !new ke1:bitstring; new km1:bitstring;
  !new ke2:bitstring; new km2:bitstring;
  reader(choice[ke1,ke2], choice[km1,km2])
  | passport(choice[ke1,ke2], choice[km1,km2])

Figure 9.9: Input file for the unlinkability of the BAC protocol
Intuitively, this false attack is due to the fact that the swaps done in the right part of the biprocess have to be executed in the left part of the biprocess with the two sessions of the same passport. However, when considering the observational equivalence, the actions of the right part of the equivalence could have been matched in the left part of the equivalence by considering a session of a third passport and reader (available thanks to the replication) and then swapping the messages between the first and third passport.
CHAPTER 9. PROVING MORE OBSERVATIONAL EQUIVALENCES WITH PROVERIF
Chapter 10

Conclusion and perspectives

This thesis reports our contributions to the automatic verification of cryptographic protocols. In particular, we focused our attention to privacy-type security properties that play an important role in many modern applications. Some further developments have already been proposed at the end of chapters. We recall the important ones and propose further perspectives.

Algorithms for deciding trace equivalence

In Part II we designed a new decision procedure for the trace equivalence between bounded processes with possible non-trivial else branches and non-deterministic choices. This procedure is sound, complete and terminates but only accepts a fixed set of cryptographic primitives whose behaviour is expressed by a rewriting system.

The cryptographic primitives are idealised which is sometimes not accurate enough. For example, we do not model the length of messages. However, depending on the padding scheme, encryption scheme may disclose the length of the plaintext and therefore allow to distinguish two ciphers. Hence we would like to add new predicates, e.g. a predicate that compares the lengths of terms, in our decision procedure. In fact, such a research track would allow us to use our procedure along with [CC08] for proving computational indistinguishability for a certain class of protocols. Since these predicates would only intervene in the static equivalence, we would like to use the properties of the constraint systems that we obtain at the end of our current procedure, in order to facilitate the development of a decision procedure for trace equivalence with these predicates.

We cannot currently handle some very interesting cryptographic protocols, such as e-voting protocols, that rely on different cryptographic primitives that the ones we fixed. Hence a natural direction of work would be to allow more cryptographic primitives. In particular, we are interested in the cryptographic primitives with algebraic properties such as exclusive-or or the blind signature. However, compared to adding predicates for the static equivalence, adding these cryptographic primitives will most certainly be a huge challenge, especially if we want to ensure the termination of our procedure.

Tool optimisations

Although the procedure described in Part II terminates, an early implementation showed that the computation of all interleavings of actions results in a significant increase of the execution time of the procedure, even for few sessions of small protocols such as the Basic Access Control protocol. We would like to optimise the algorithm such that the execution time remains reasonable, at least for few sessions of any standard protocol. There are two possible directions.

We could apply a partial order reduction on the symbolic traces of the processes [CJM09]. This area seems very promising since the experiments show that there are many interleavings that yield the same state. This is not straightforward, however, when considering equivalence
properties, since we have to match traces from a process to the other process. The reductions
have to match on both processes.

An implementation of our algorithm on a parallel machine should be possible. Indeed, the two
matrices resulting from an application of a constraint solving rule can be processed independently.
Ideally, it should be possible to combine these two optimisations. However, this seems only possible
with small enough reductions that do not break the parallelism. Nevertheless, both optimisations
would still be implemented since they are both worthy depending on the user’s hardware.

**Proving more equivalences with ProVerif**

In Part III, we proposed an extension of the tool ProVerif that proves more observational
equivalences. In particular, we were able to automatically prove the anonymity property on the
private authentication protocol for an unbounded number of sessions. However, as mentioned in
Chapter 9, we are still unable to prove the unlinkability property for the Basic Access Control
protocol even though we managed to avoid some previously existing false attacks. This a conse-
quence of the matching by ProVerif of traces with the same scheduling in the two variants of
the biprocesses. On the one hand, this is probably one of the most frequent cause of false attacks
yield by ProVerif, and on the other hand, this is also one of the main reason why ProVerif is
very efficient in practice for proving equivalence. To prove even more observational (or trace)
equivalence with ProVerif, some approaches could be investigated.

This first approach would consist of applying some small transformations on the processes
beforehand that are sound for observational (or trace) equivalence. However, our first tries on the
BAC protocol seem to show that while such small transformations might exist, they would be very
specific to the processes and therefore very hard to automate.

A second direction consists of relaxing a bit the matching of traces e.g. by modifying the
replication identifiers on the left and right parts of biprocesses. Even if we manage to propose a
transformation that is still sound for the observational equivalence, we also would have to preserve
the termination “in practice” of ProVerif.

Although ProVerif and our decision procedure for trace equivalence are very different,
it would be interesting to study the possible interactions between them. For example, when
ProVerif yields a false attack, a possible idea would be to check the possible matched traces
for the false attack in a our decision procedure and then inject the result in ProVerif so that it
could prove the security properties by relying our the result of the procedure.

**Composition results**

In Chapter 5, we have shown that protocols can be securely composed w.r.t. privacy-type proper-
ties if they are tagged and do not reveal any shared secret. Moreover, we allow a finite number of
public or verification keys associated to shared secret keys to be known by the intruder, provided
that they were known at the beginning of the protocol. We also showed in this chapter how to
apply our composition result to the parallel composition of the Active Authentication and Passive
Authentication protocols from the e-passport protocols. However, we had to abstract the symmet-
ric session keys that were generated by the Basic Access Control protocol beforehand. Thus, a
possible extension of this work will consist of generalising our composition result in order to allow
the sequential composition of processes.

In [ADK08], the authors characterise a class of protocols for which secrecy is decidable for
an unbounded number of sessions. Typically, they showed how to transform a protocol that is
secure for one session, in a protocol that is secure for an unbounded number of sessions. This
transformation also relies on tagging of terms but the tags are not constant and are generated
by the sessions. Thus, a possible direction of research is to extend their result to privacy-type
properties.

All these possible extensions of our work heavily rely on tagged processes. However, most of
existing real protocols are not tagged and tagging a process increases the payloads of messages
that are sent over the network. Hence following the idea of [KTIJ], we would like to define an ideal
property that, if shown on each process individually, would ensure the secure composition of these processes. One of the difficulty of this approach would probably be to find the correct balance between the generality of such an ideal property and the difficulty of automatically verifying it.
Bibliography


Appendices
Appendix A

From the applied pi calculus to symbolics semantics

A.1 Proofs on relating equivalence

**Proposition 3.1.** Let A and B be two closed extended process with dom(A) = dom(B), and $C[\_\_] = \nu \eta . (D \mid \_)$ be an evaluation context closing for A. If $C[A] \Rightarrow A''$ for some process $A''$, then there exist a closed extended process $A'$, an evaluation context $C' = \nu \eta . (D' \mid \_)$ closing for $A'$, and a trace $\tau \in (A \setminus \{\tau\})^*$ such that $A'' \equiv C'[A']$, $A \triangleright B$, and for all closed extended process $B'$,

$$B \Downarrow B' \text{ and } \Phi(B') \sim \Phi(A') \text{ imply that } C[B] \Rightarrow C'[B'].$$

**Proof.** Let A and B be two closed extended processes with dom(A) = dom(B) and C be an evaluation context closing for A. Let $A''$ be such that $C[A] \Rightarrow A''$. We prove the result by induction on the length $\ell$ of the derivation.

**Base case $\ell = 0$:** In such a case, we have that $A'' \equiv C[A]$. Let $A' = A$, $C' = C$ and $\tau = \epsilon$, we have that $A'' \equiv C'[A']$, and $A \triangleright A'$. Let $B'$ be a closed extended process such that $B \Rightarrow B'$ and $\Phi(B') \sim \Phi(A')$ for some $B'$. Clearly, we have that $C[B] \Rightarrow C'[B']$ since $C' = C$ and $B \Rightarrow B'$.

**Inductive case $\ell > 0$:** In such a case, we have that there exists a closed extended process $A_1$ such that $C[A] \Rightarrow A_1$ with a derivation whose length is smaller than $\ell$, and $A_1 \Rightarrow A''$. Thus, we can apply our induction hypothesis allowing us to conclude that there exist an extended process $A_1'$, an evaluation context $C_1[\_\_] = \nu \eta_1 . (D_1' \mid \_)$ closing for $A_1'$, and a trace $\tau_1 \in (A \setminus \{\tau\})^*$ such that $A_1 \equiv C_1'[A_1']$, $A \Downarrow A_1'$, and for all closed extended processes $B_1'$, we have that:

$$B \Downarrow B_1' \text{ and } \Phi(B_1') \sim \Phi(A_1') \text{ implies that } C[B] \Rightarrow C_1'[B_1'].$$

Since $A_1 \equiv C_1'[A_1']$ and $A_1 \Rightarrow A''$, we have that $C_1'[A_1'] \Rightarrow A''$ (internal reduction is closed under structural equivalence). We do a case analysis on the rule involved in this reduction.

**Case of an internal reduction in $A_1'$, i.e. there exists $A'$ such that $A_1' \Rightarrow A'$ and $A'' \equiv C_1'[A']$.** In such a case, we have that $C_1'[A_1'] \Rightarrow C_1'[A']$. Let $C' = C_1''$ and $\tau = \tau_1$. We have that $A'' \equiv C_1'[A'] = C'[A']$ and $A \Downarrow A_1' \Rightarrow A'$, i.e. $A \Downarrow A'$. Lastly, let $B'$ be a closed extended process such that $B \Downarrow B'$ and $\Phi(B') \sim \Phi(A')$. We have that $B \Downarrow B'$ and $\Phi(B') \sim \Phi(A')$, and thus relying on our induction hypothesis, we conclude that $C[B] \Rightarrow C_1'[B'] = C'[B']$. This allows us to conclude.

**Case of an internal reduction in $C_1'$, i.e. there exists $D'_2$ such that $\nu \eta_1 . (D'_1 \mid B) \Rightarrow \nu \eta_1 . (D'_2 \mid B)$ for any process $B$ such that $\Phi(B) \sim \Phi(A_1')$, and $A'' \equiv \nu \eta_1 . (D'_2 \mid A_1')$.** In such a case, we have
that $C_i'[A_i'] \overset{\ll}{\rightarrow} \nu n_i.(D_2 \mid A_i')$. Let $A' = A_i'$, $C'[\_] = \nu n_i.(D_2 \mid \_)$ and $\text{tr} = \text{tr}_1$. We have that 

$A'' \equiv \nu n_i.(D_2 \mid A_i') = C'[A']$ and $A \overset{\ll}{\rightarrow} A'$. Lastly, let $B'$ be a closed extended process such that $B \overset{\ll}{\rightarrow} B'$ and $\Phi(B') \sim \Phi(A')$. We have that $B \overset{\ll}{\rightarrow} B'$ and $\Phi(B') \sim \Phi(A_i') \equiv \Phi(A')$, and thus relying on our induction hypothesis, we have that $C[B] \overset{\ll}{\rightarrow} C'[B']$. But by our hypothesis on the internal reduction, $\Phi(B') \sim \Phi(A_i')$ implies that $C_i'[B'] \overset{\ll}{\rightarrow} \nu n_i.(D_2 \mid B') = C'[B']$ and so $C[B] \overset{\ll}{\rightarrow} C'[B']$. This allows us to conclude.

Case of a rule (COMM) between $C_i'$(output) and $A_i'$(input), i.e. $D_i' \equiv \nu \tilde{n}.(\text{out}(c,M).P D)$. Since $A_2 \equiv A_2 = \nu \tilde{r}.(\text{in}(c,z).Q A_2)$ for some $c$, $M$, $P$, $D$, $A_2$, $\tilde{r}$, $z$, $Q$, and $A_2$ such that $z$ is a fresh variable, $\text{fvars}(M) \subseteq \text{dom}(A_2)$, $\tilde{r} \cap \text{fnames}(M) \cup \text{fvars}(M) = \emptyset$, and $\tilde{n} \cap \text{fnames}(A_2) \cup \text{fvars}(A_2) = \emptyset$. We assume in addition that names and variables in $\tilde{n}$ do not occur in $\text{fnames}(B)$, $\text{fvars}(B)$, and $\text{tr}$. In such a case, we have that

$$C_i'[A_i'] \equiv \nu n_i.[\nu \tilde{n}.(\text{out}(c,M).P D) A_i']$$

$$\overset{\ll}{\rightarrow} \nu n_i.[\nu \tilde{n}.(\text{out}(c,M).P D | A_2)]$$

and $A'' \equiv \nu n_i.\tilde{n}.[P D | \nu \tilde{r}.(Q\{M/z\} A_2)]$. Let $A' = \nu \tilde{r}.(Q\{M/z\} A_2)$, $C'[\_] = \nu n_i.\tilde{n}.(P D | \_)$, and $\text{tr} = \text{tr}_1 \cdot \tilde{r}.(c,M)$. We have that $A'' \equiv C'[A']$. By induction hypothesis, we have that $A \overset{\ll}{\rightarrow} A'$ and $A_i' \overset{\text{tr}(c,M)}{\rightarrow} A'$. This allows us to conclude that $A \overset{\ll}{\rightarrow} A'$. Note that $A'$ is a closed extended process ($\text{fnames}(M) \subseteq \text{dom}(A_2) = \text{dom}(A_i')$).

Lastly, let $B'$ be a closed extended processes such that $B \overset{\ll}{\rightarrow} B'$ and $\Phi(B') \sim \Phi(A')$. We have that there exists $B_i'$ such that $B \overset{\ll}{\rightarrow} B_i' \overset{\text{tr}(c,M)}{\rightarrow} B'$. Moreover, we can assume w.l.o.g. that $\tilde{n}$ do not occur in $\text{fnames}(B_i')$ and $\text{fvars}(B_i')$ since $\tilde{n}$ do not occur in $\text{fnames}(B)$, $\text{fvars}(B)$ and $\text{tr}_1$. Since $B' \sim \Phi(A')$, we have also that $\Phi(B_i') \sim \Phi(A_i')$. Thus, we can apply our induction hypothesis on $B_i'$. This allows us to deduce that $C[B] \overset{\ll}{\rightarrow} C_i'[B_i']$. In order to conclude, it remains to show that $C_i'[B_i'] \overset{\ll}{\rightarrow} C'[B']$.

We have seen that $B_i' \overset{\text{tr}(c,M)}{\rightarrow} B'$. Hence, we know that there exists $\tilde{n}, P_2, B_2$ such that $B_i' \equiv \nu \tilde{n}.(\text{in}(c,z).P_2 B_2)$, $B' \equiv \nu \tilde{n}.(P_2\{M/z\} B_2)$, and $\tilde{n} \cap \text{fnames}(M) \cup \text{fvars}(M) = \emptyset$. Moreover, we have already seen that $\tilde{n} \cap (\text{fnames}(B_i') \cup \text{fvars}(B_i')) = \emptyset$. Hence, we have that:

$$C_i'[B_i'] \equiv \nu n_i.[\nu \tilde{n}.(\text{out}(c,M).P D) B_i']$$

$$\equiv \nu n_i.[\nu \tilde{n}.(\text{out}(c,M).P D | B_i')]$$

and $A_i' \equiv A_i = \nu \tilde{r}.(\text{out}(c,M).Q A_2)$ for some $c$, $M$, $P$, $D$, $A_2$, $\tilde{r}$, $z$, and $A_2$ such that $z$ is a fresh variable, $\text{fvars}(M) = \emptyset$, $\tilde{r} \cap \text{fnames}(A_2) = \emptyset$, $\tilde{r} \cap \text{fnames}(\text{in}(c,z).P) \cup \text{fnames}(\text{in}(c,z).P) = \emptyset$. We assume in addition that names and variables in $\tilde{n}$ do not occur in $\text{fnames}(B)$, $\text{fvars}(B)$, and $\text{tr}$. In such a case, we have that

$$C_i'[A_i'] \equiv \nu n_i.[\nu \tilde{n}.(\text{in}(c,z).P D) A_i']$$

$$\equiv \nu n_i.[\nu \tilde{n}.(\text{in}(c,z).P D | A_2)]$$

and $A'' \equiv \nu n_i.\tilde{n}.[P\{M/z\} Q A_2 | D]$.

To determine $C_i'$, $A'$ and $\text{tr}$, we distinguish several cases depending on the term $M$:
• \( M \) is a name of channel type and \( M \not\in \tilde{\tau} \). In such a case, we have that \( A'' \equiv \nu\tilde{n}.\nu\tilde{n}.(\nu \tilde{\tau}.(Q \mid A_2) \mid D \mid \nu \tilde{\tau}.(Q \mid A_2)) \). Thus, let \( C''[\_\_] = \nu\tilde{n}.\nu\tilde{n}.(\nu \tilde{\tau}.(Q \mid A_2) \mid D \mid \_\_), A' = \nu \tilde{\tau}.(Q \mid A_2) \) and \( \text{tr} = \text{tr}_1 \cdot \text{out}(c, M) \). Clearly, we have that \( A'' \equiv C'[A'] \) and \( A'_1 \xrightarrow{\text{out}(c,M)} A' \).

Lastly, let \( B' \) be a closed process such that \( B \xrightarrow{B'} B' \) and \( \Phi(B') \sim \Phi(A') \). We have that there exists \( B'_1 \) such that \( B \xrightarrow{B'_1} B' \). Moreover, we can assume w.l.o.g. that \( \tilde{n} \) do not occur in \( \text{fnames}(B'_1), \text{fears}(B'_1) \), and \( \text{tr}_1 \). We have also that \( \Phi(A'_1) \sim \Phi(B'_1) \). Thus, we can apply our inductive hypothesis on \( B'_1 \) which means that \( C[B] \xrightarrow{\tau} C'_1[B'_1] \). In order to conclude, it remains to show that \( C'_1[B'_1] \sim C'[B'] \).

We have seen that \( B'_1 \xrightarrow{\text{out}(c,M)} B' \). Hence, we know that there exists \( \tilde{m}, Q_2, B_2 \) such that \( B'_1 \equiv \nu \tilde{m}.(\text{out}(c, M) \mid Q_2 \mid B_2) \), \( B' \equiv \nu \tilde{m}.(Q_2 \mid B_2) \), \( M \not\in \tilde{m} \) and \( \tilde{m} \cap (\text{fears}(D_1) \cup \text{fnames}(D_1)) = 0 \). Therefore, we have that:

\[
\begin{align*}
C'_1[B'_1] & \equiv \nu \tilde{m}.\nu \tilde{m}.(\text{in}(c, z).P \mid D) \mid B'_1) \\
& \equiv \nu \tilde{m}.\nu \tilde{m}.\nu \tilde{m}.(\text{in}(c, z).P \mid D) \mid B'_1) \\
& \equiv \nu \tilde{m}.\nu \tilde{m}.(\text{in}(c, z).P \mid D \mid \text{out}(c, M) \mid Q_2 \mid B_2)] \\
& \xrightarrow{\tau} \nu \tilde{m}.\nu \tilde{m}.(\nu \tilde{\tau}.(Q \mid A_2) \mid D \mid \nu \tilde{\tau}.(Q \mid A_2) \\
& \equiv C'[B']
\end{align*}
\]

• \( M \) is a name of channel type that occurs in \( \tilde{\tau} \). Let \( \tilde{\tau}' \) be a sequence such that \( \tilde{\tau} = \tilde{\tau}' \cup M \). In such a case, we have that \( A'' \equiv \nu \tilde{n}.\nu \tilde{n}.\nu \tilde{\nu}.(\nu \tilde{\tau}'.(Q_{M/M} \mid A_2^M \mid M)) \mid D \mid \nu \tilde{\tau}'.(Q_{M/M} \mid A_2^M \mid M) \) where \( M' \) is a fresh name of channel type. Let \( C''[\_\_\_] = \nu \tilde{n}.\nu \tilde{n}.\nu \tilde{\nu}.(\nu \tilde{\tau}'.(Q_{M/M} \mid A_2^M \mid M)) \mid D \mid \_\_, A' = \nu \tilde{\tau}'.(Q_{M/M} \mid A_2^M \mid M) \) and \( \text{tr} = \text{tr}_1 \cdot \nu \tilde{\nu}.(\text{out}(c, M')) \). Clearly, we have that \( A'_1 \equiv \nu \tilde{\nu}.\nu \tilde{\nu}.\nu \tilde{\nu}.(\text{out}(c, M) \mid Q_2 \mid A_2') \xrightarrow{\nu \tilde{\nu}.(\text{out}(c,M')) \nu \tilde{\nu}.(Q \mid A_2) \\
\equiv \nu \tilde{\nu}.\nu \tilde{\nu}.\nu \tilde{\nu}.(\text{out}(c, M) \mid Q_2 \mid A_2 \sim C'[A']
\]

Lastly, let \( B' \) be a closed process such that \( B \xrightarrow{B'} B' \) and \( \Phi(B') \sim \Phi(A') \). We have that there exists \( B'_1 \) such that \( B \xrightarrow{B'_1} B' \). Moreover, we can assume w.l.o.g. that \( \tilde{n} \) do not occur in \( \text{fnames}(B'_1), \text{fears}(B'_1) \), and \( \text{tr}_1 \). We also have that \( \Phi(A'_1) \sim \Phi(B'_1) \). Thus, we can apply our inductive hypothesis on \( B'_1 \) which means that \( C[B] \xrightarrow{\tau} C'_1[B'_1] \). In order to conclude, it remains to show that \( C'_1[B'_1] \sim C'[B'] \).

We have seen that \( B'_1 \xrightarrow{\text{out}(c,M)} B' \). Hence, we know that there exists \( \tilde{m}, Q_2, B_2 \) such that \( B'_1 \equiv \nu \tilde{m}.(\text{out}(c, M) \mid Q_2 \mid B_2) \), \( B' \equiv \nu \tilde{m}.(Q_2 \mid B_2) \), \( M \not\in \tilde{m} \) and \( \tilde{m} \cap (\text{fears}(D'_1) \cup \text{fnames}(D'_1)) = 0 \). Therefore, we have that \( \text{where } M'' \) is a fresh channel:

\[
C'_1[B'_1] \equiv \nu \tilde{m}.\nu \tilde{m}.(\text{in}(c, z).P \mid D) \mid B'_1) \\
\equiv \nu \tilde{m}.\nu \tilde{m}.\nu \tilde{m}.(\text{in}(c, z).P \mid D) \mid B'_1) \\
\equiv \nu \tilde{m}.\nu \tilde{m}.(\text{in}(c, z).P \mid D \mid \text{out}(c, M') \mid Q_2 \mid B_2) \\
\xrightarrow{\tau} \nu \tilde{m}.\nu \tilde{m}.(\text{in}(c, z).P \mid D \mid \text{in}(c, z).P \mid D \mid \text{out}(c, M') \mid Q_2 \mid B_2) \\
\equiv \nu \tilde{m}.\nu \tilde{m}.(\nu \tilde{\tau}.(Q \mid A_2) \mid D \mid \nu \tilde{\tau}.(Q \mid A_2) \\
\equiv \nu \tilde{m}.\nu \tilde{m}.(\nu \tilde{\tau}.(Q \mid A_2) \mid D \mid \nu \tilde{\tau}.(Q \mid A_2) \\
\equiv \nu \tilde{m}.\nu \tilde{m}.(\nu \tilde{\tau}.(Q \mid A_2) \mid D \mid \nu \tilde{\tau}.(Q \mid A_2) \\
\equiv C'[B']
\]

• \( M \) is a term of base type. In such a case, we have that \( A'' \equiv \nu \tilde{n}.\nu \tilde{n}.\nu \tilde{v}.(\text{in}(c, z).P \mid D \mid \nu \tilde{\tau}.(Q \mid A_2 \mid \{M/M\}) \). Let \( C''[\_\_] = \nu \tilde{n}.\nu \tilde{n}.\nu \tilde{v}.(\text{in}(c, z).P \mid D \mid \_\_, A' = \nu \tilde{\tau}.(Q \mid A_2 \mid \{M/M\}) \) and \( \text{tr} = \text{tr}_1 \cdot \nu \tilde{\tau}.\nu \tilde{v}.(c, z) \). Clearly, we have that \( A'_1 \equiv \nu \tilde{\tau}.(\text{out}(c, M) \mid Q_2 \mid A_2) \equiv \nu \tilde{\tau}.(Q \mid A_2) \equiv \nu \tilde{\tau}.(Q \mid A_2) \equiv \nu \tilde{\tau}.(Q \mid A_2) \equiv C'[A'] \).

Lastly, let \( B' \) be a closed process such that \( B \xrightarrow{B'} B' \) and \( \Phi(B') \sim \Phi(A') \). We have that there exists \( B'_1 \) such that \( B \xrightarrow{B'_1} B' \). Moreover, we can assume w.l.o.g. that \( \tilde{n} \) do not occur in \( \text{fnames}(B'_1), \text{fears}(B'_1) \), and \( \text{tr}_1 \). We also have that \( \Phi(A'_1) \sim \Phi(B'_1) \). Thus, we can apply our inductive hypothesis on \( B'_1 \) which means that \( C[B] \xrightarrow{\tau} C'_1[B'_1] \). In order to conclude, it remains to show that \( C'_1[B'_1] \sim C'[B'] \).
Let $B'_1 \xrightarrow{\nu x \cdot \text{in}(c,z)} B'$. Hence, we know that there exists $\hat{m}, Q_2, B_2$ such that $B'_1 \equiv \nu \hat{m} \cdot (\text{out}(c,M),Q_2 \mid B_2)$. $B' \equiv \nu \hat{m} \cdot (Q_2 \mid B_2 \mid \{M/z\})$ and $\hat{m} \cap (\text{vars}(D'_1) \cup \text{fnames}(D'_1)) = \emptyset$. Therefore, we have that:

$$C'_1[B'_1] \equiv \nu \hat{m}_1 \cdot [\nu \hat{m} \cdot (\text{in}(c,z) \cdot P \mid D) \mid B'_1]$$

$$\rightarrow \nu \hat{m}_1 \cdot \nu \hat{m} \cdot [\text{in}(c,z) \cdot P \mid D \mid \nu \hat{m} \cdot (\text{out}(c,M),Q_2 \mid B_2)]$$

$$\equiv C'[B']$$

\[\square\]

### A.2 Proofs on symbolic semantics

In this appendix, we provide the complete proof of Proposition 4.2 and 4.3.

**Proposition 4.2** (soundness). Let $(E_1; P_1; \Phi_1; D_1; Eq_1)$, and $(E_2; P_2; \Phi_2; D_2; Eq_2)$ be two symbolic processes such that

1. $(\sigma_1, \theta_1) \in \text{Sol}(\{E_1; P_1; \Phi_1; D_1; Eq_1\})$.
2. $(\sigma_2, \theta_2) \in \text{Sol}(\{E_2; P_2; \Phi_2; D_2; Eq_2\})$.

Let $\theta_1 = \theta_2|_{\text{vars}^2(D_1)}$ and $\sigma_1 = \sigma_2|_{\text{vars}^1(D_1)}$. We have that:

1. $(\sigma_1, \theta_1) \in \text{Sol}(\{E_1; P_1; \Phi_1; D_1; Eq_1\})$, and
2. $(\sigma_2, \theta_2) \in \text{Sol}(\{E_2; P_2; \Phi_2; D_2; Eq_2\})$.

**Proof.** The proof consists of a case analysis on the rule involved in the reduction step of:

$$(E_1; P_1; \Phi_1; D_1; Eq_1) \xrightarrow{\alpha} (E_2; P_2; \Phi_2; D_2; Eq_2)$$

**Case THEN:** In such a case there exist $u, v, Q_1$, and $Q_2$ such that $D_2 = D_1$, $Eq_2 = Eq_1 \cup \{u \equiv v\}$, $P_1 = \{u = v \rightarrow Q_1 \} \cup P$, $P_2 = \{Q_1 \} \cup P$, $E_1 = E_2$, $\Phi_1 = \Phi_2$, and $\alpha_s = \tau$.

1. Since $\text{vars}^2(D_1) = \text{vars}^2(D_2)$ and $\text{vars}^1(D_1) = \text{vars}^1(D_2)$, we have $\theta_1 = \theta_2$ and $\sigma_1 = \sigma_2$. Furthermore, $(\sigma_2, \theta_2) \in \text{Sol}(\{E_2; P_2; \Phi_2; Eq_2\})$ and $\Phi_1 = \Phi_2$ implies that $(\sigma_2, \theta_2)$ satisfies the constraints of $D_2 = D_1$ and the (in)equalities of $Eq_2 = Eq_1 \cup \{u \equiv v\}$, and so satisfies $Eq_1$. At last, with $E_1 = E_2$, we conclude that $(\sigma_1, \theta_1) \in \text{Sol}(\{E_1; P_1; D_1; Eq_1\})$.

2. Since $(\sigma_2, \theta_2) \in \text{Sol}(\{E_2; P_2; D_2; Eq_2 \})$, we have that $u \sigma_2 = u \sigma_2$. With $\sigma_1 = \sigma_2$, we deduce that $u \sigma_1 = u \sigma_1$ and so:

$$(E_1; \{u \sigma_1 = u \sigma_1 \text{ then } Q_1 \} \sigma_1 \sigma_2 \mid Q_2 \mid P_1) \xrightarrow{\tau_s} (E_1; \{Q_1 \} \sigma_1 \sigma_2 \mid P_1 \sigma_1)$$

i.e. $(E_1; P_1; \Phi_1; D_1; Eq_1) \xrightarrow{\alpha} (E_2; P_2; \Phi_2; D_2; Eq_2)$.

The case of the rule ELSE can be done in a similar way.

**Case COMM:** In such a case, there exist $p, q, u, x, Q_1, Q_2$, and $P$ such that $D_2 = D_1$, $Eq_2 = Eq_1 \cup \{p \equiv q\}$, $\Phi_2 = \Phi_1$, $E_2 = E_1$, $P_1 = \{\text{out}(p, u), Q_1; \text{in}(q, x), Q_2\} \cup P$, $P_2 = \{Q_1; Q_2 \mid \{x \rightarrow u\} \}$, and $\alpha_s = \tau$.

1. Since $\text{vars}^2(D_1) = \text{vars}^2(D_2)$ and $\text{vars}^1(D_1) = \text{vars}^1(D_2)$, we have $\theta_1 = \theta_2$ and $\sigma_1 = \sigma_2$. Furthermore, $(\sigma_2, \theta_2) \in \text{Sol}(\{E_2; P_2; Eq_2\})$, and $\Phi_1 = \Phi_2$ implies that $(\sigma_2, \theta_2)$ satisfies the constraints of $D_2 = D_1$ and the (in)equalities of $Eq_2 = Eq_1 \cup \{p \equiv q\}$, and so satisfies $Eq_1$. At last, with $E_1 = E_2$, we conclude that $(\sigma_1, \theta_1) \in \text{Sol}(\{E_1; P_1; D_1; Eq_1\})$. 


2. Since \((\sigma_2, \theta_2) \in \text{Sol}((E_2; \Phi_2; D_2; Eq_1 \cup \{ p \equiv q \}))\), we have that \(p \sigma_2 = q \sigma_2\). With \(\sigma_1 = \sigma_2\), we deduce that \(p \sigma_1 = q \sigma_1\). But \(p\) and \(q\) are of channel type, then so does \(p \sigma_1\) and \(q \sigma_1\) which means that \(p \sigma_1 = q \sigma_1\). Hence, we have that:

\[
(E_1; \{ \text{out}(p \sigma_1, u \sigma_1), Q_1 \sigma_1; \text{in}(p \sigma_1, x).Q_2 \sigma_1 \} \not\subseteq P \sigma_1; \Phi_1 \sigma_1) \not\xrightarrow{\alpha_1} (E_1; \{ Q_1 \sigma_1; Q_2 \sigma_1 \{ x \mapsto u \sigma_1 \}\} \not\subseteq P \sigma_1; \Phi_1 \sigma_1).
\]

Since \(\sigma_1 = \sigma_2\), \(\Phi_1 = \Phi_2\) and \(Q_2 \sigma_2 \{ x \mapsto u \sigma_2 \} = (Q_2 \{ x \mapsto u \}) \sigma_2\), we can deduce that:

\[
(E_1; \{ p \sigma_1 \mid Q_1 \sigma_1 \} \not\subseteq P \sigma_1; \Phi_1 \sigma_1) \not\xrightarrow{\alpha_2} (E_1; \{ p \sigma_1 \mid Q_1 \sigma_1 \} \not\subseteq P \sigma_1; \Phi_1 \sigma_1)
\]

Since \(\sigma_1 = \sigma_2\), we can deduce that:

\[
(E_1; \{ p \sigma_1 \mid Q_1 \sigma_1 \} \not\subseteq P \sigma_1; \Phi_1 \sigma_1) \not\xrightarrow{\alpha_2} (E_2; \{ p \sigma_2 \mid Q_2 \sigma_2 \} \not\subseteq P \sigma_2; \Phi_2 \sigma_2).
\]

Case \(\text{PAR}_s\): In such a case, there exist \(P, Q, \) and \(\mathcal{P}\) such that \(D_2 = D_1, Eq_2 = Eq_1, \Phi_2 = \Phi_1, E_2 = E_1, \mathcal{P}_1 = \{ P \mid Q \} \not\subseteq \mathcal{P}, \mathcal{P}_2 = \{ P \mid Q \} \not\subseteq \mathcal{P},\) and \(\alpha_s = \tau\).

1. Since \(\text{vars}^2(D_1) = \text{vars}^2(D_2)\) and \(\text{vars}^1(D_1) = \text{vars}^1(D_2)\), we have \(\theta_1 = \theta_2\) and \(\sigma_1 = \sigma_2\). Furthermore, we have that \((E_1; \Phi_1; D_1; Eq_1) = (E_2; \Phi_2; D_2; Eq_2)\) hence we trivially have that \((\sigma_1, \theta_1) \in \text{Sol}((E_1; \Phi_1; D_1; Eq_1))\).

2. We have that:

\[
(E_1; \{ p \sigma_1 \mid Q_1 \sigma_1 \} \not\subseteq P \sigma_1; \Phi_1 \sigma_1) \not\xrightarrow{\alpha_2} (E_1; \{ p \sigma_1 \mid Q_1 \sigma_1 \} \not\subseteq P \sigma_1; \Phi_1 \sigma_1)
\]

Since \(\sigma_1 = \sigma_2\), we can deduce that:

\[
(E_1; \{ p \sigma_1 \mid Q_1 \sigma_1 \} \not\subseteq P \sigma_1; \Phi_1 \sigma_1) \not\xrightarrow{\alpha_2} (E_2; \{ p \sigma_2 \mid Q_2 \sigma_2 \} \not\subseteq P \sigma_2; \Phi_2 \sigma_2).
\]

Case \(\text{IN}_{\sigma}\): In such a case, there exist \(p, x, Q, \mathcal{P}\) and fresh variables \(y, z\) and \(Y, Z\) and such that \(\alpha_s = \text{in}(Z, Y), \mathcal{P}_1 = \text{in}(p, x, Q) \not\subseteq \mathcal{P}, \mathcal{P}_2 = \{ Q \{ x \mapsto y \} \} \not\subseteq \mathcal{P}, D_2 = D_1 \cup \{ Y, n \vdash y; Z, n \vdash z \}, Eq_2 = Eq_1 \cup \{ z \equiv p \}, E_2 = E_1 \) and \(\Phi_1 = \Phi_2\) where \(n \mid \Phi_1\).

1. We have that \(\text{vars}^2(D_1) = \text{vars}^2(D_2) \setminus \{ Y ; Z \}, \text{vars}^1(D_1) = \text{vars}^1(D_2) \setminus \{ y ; z \}\) implies that \(\Phi_1 \sigma_1 = \Phi_2 \sigma_2\). Since \((\sigma_2, \theta_2) \in \text{Sol}((E_2; \Phi_2; D_2; Eq_2))\) and \(D_1 \subseteq D_2\), we have that for all \((X, i \vdash x) \in D_1, (X \theta_2)(\Phi_2 \sigma_2) = x \sigma_2\). With \(\Phi_1 \sigma_1 = \Phi_2 \sigma_2\), we deduce that \((X \theta_2)(\Phi_1 \sigma_1) = x \sigma_1\). Furthermore, we know that \(\sigma_2\) satisfies the (in)equalities of \(Eq_2 = Eq_1 \cup \{ z \equiv p \}\) and so satisfies also the (in)equalities of \(Eq_1\). Since \((E; \Phi_1; D_1; Eq_1)\) being a constraint system also implies \(\text{vars}^1(Eq_1) \subseteq \text{vars}^1(D_1)\), we deduce that \(\sigma_1\) satisfies the (in)equalities of \(Eq_1\) and so we conclude that \((\sigma_1, \theta_1) \in \text{Sol}((E_1; \Phi_1; D_1; Eq_1))\).

2. Let \(M = Y \theta_2\) and \(u = y \sigma_2\). Thanks to \((\sigma_2, \theta_2) \in \text{Sol}((E_2; \Phi_2; D_2; Eq_2))\) and \(E_2 = E_1\), we have that \(\text{fnames}(M) \cap \mathcal{E}_1 = \emptyset\). We have also that \(u = y \sigma_2 = M(\Phi_2 \sigma_2)\). We already know that \(\Phi_1 \sigma_1 = \Phi_2 \sigma_2\), thus we have that \(u = M(\Phi_2 \sigma_2) = M(\Phi_1 \sigma_1)\). Furthermore, by definition of a solution, we have that \(\text{fnames}(M) \not\subseteq \text{dom}(\Phi_1)\). Lastly, since \((\sigma_2, \theta_2) \in \text{Sol}((E_2; \Phi_2; D_2; Eq_2))\), we have that \((Z \theta_2)(\Phi_2 \sigma_2) = z \sigma_2, z \sigma_2 = p \sigma_2\) and \(Z \theta_2 \in T(\mathcal{N} \setminus \{ E_2 \}, \text{dom}(\Phi_2))\). But \(p\) is a term of type channel, thus so does \(p \sigma_2\). Since all the function symbol operate on and return term of base type and since all terms in \(\Phi_2\) are base type, we can deduce that \((Z \theta_2) \not\subseteq \text{dom}(\Phi_2)\) and \(\text{vars}^2(D_1) = \text{vars}^2(D_2) \setminus \{ y ; z \}\) where \(y, z\) are fresh variables, then \(p\) is either a name or a variable in \(\text{vars}^1(D_1)\) and we have that \(p \sigma_2 = p \sigma_1\). Hence, we have that:

\[
(E_1; \{ \text{in}(p \sigma_1, x).Q_1 \sigma_1; \text{in}(p \sigma_1, x).Q_2 \sigma_1 \} \not\subseteq P \sigma_1; \Phi_1 \sigma_1) \not\xrightarrow{\alpha_2} (E_1; \{ Q_1 \sigma_1 \{ x \mapsto u \} \} \not\subseteq P \sigma_1; \Phi_1 \sigma_1),
\]

i.e. \((E_1; \mathcal{P}_1 \sigma_1; \Phi_1 \sigma_1) \not\xrightarrow{\alpha_2} (E_2; \{ Q \{ x \mapsto y \} \} \sigma_2 \not\subseteq P \sigma_2; \Phi_2 \sigma_2)\) since \(E_2 = E_1, \Phi_2 \sigma_2 = \Phi_1 \sigma_1\) and \(\sigma_2 = \sigma_1 \cup \{ y \mapsto u ; z \mapsto p \sigma_1 \}\). Hence, we have that \((E_1; \mathcal{P}_1 \sigma_1; \Phi_1 \sigma_1) \not\xrightarrow{\alpha_2} (E_2; \mathcal{P}_2 \sigma_2; \Phi_2 \sigma_2)\).
Case Out-T. In such a case, there exist \( p, u, Q, \mathcal{P} \), fresh variables \( Z, z \) and \( ax_{n+1} \in \mathcal{A}\mathcal{X} \) such that \( n = |\Phi_1|, \alpha_x = \nu_{ax_{n+1}, out}(Z, ax_n), \mathcal{P}_1 = \{ \{ out(p, u), Q \} \} \), \( \mathcal{P}_2 = \{ Q \} \), \( \mathcal{D}_2 = D_1 \cup \{ Z, n \vdash z \} \), \( \mathcal{E}_q_2 = \mathcal{E}_q_1 \cup \{ z \vdash p \} \), \( \mathcal{E}_2 = \mathcal{E}_1 \), and \( \Phi_2 = \Phi_1 \cup \{ ax_n \vdash u \} \).

1. We know that \( Z \) and \( z \) are fresh variables. Hence we have that \( \text{vars}^2(D_1) = \text{vars}^2(D_2) \setminus \{ Z \} \), \( \text{vars}^1(D_1) = \text{vars}^1(D_2) \setminus \{ z \} \) and \( z \notin \text{vars}^1(\Phi_1) \). Thus thanks to \( \sigma_1 = \sigma_2 |_{\text{vars}^1(D_1)} \), we deduce that \( \Phi_1|_{\sigma_1} = \Phi_1|_{\sigma_2} \).

Furthermore, we know that \((\mathcal{E}_1; \Phi_1; D_1; \mathcal{E}_q_1)\) is a constraint system. Hence, with \( D_2 = D_1 \cup \{ Z, n \vdash z \} \) and \( (\sigma_2, \theta_2) \in \text{Sol}(\mathcal{E}_2; \Phi_2; D_2; \mathcal{E}_q_2) \), we have that for all \( (X, i \vdash x) \in D_1, i \leq n \) and \( \text{param}(X\theta_2) \subseteq \{ ax_1, \ldots, ax_n \} \). Thus thanks to \( \mathcal{E}_1 = \mathcal{E}_2 \) and \( \theta_1 = \sigma_2 |_{\text{vars}^2(D_2)} \), we deduce that for all \( (X, i \vdash x) \in D_1, x\sigma_1 = x\sigma_2 = X\theta_2(\Phi_2\sigma_2) = X\theta_1(\Phi_1\sigma_1) \) and \( X\theta_1 \in \mathcal{T}(\mathcal{F}, \mathcal{N} \setminus \{ \} , \mathcal{A}\mathcal{X}) \).

At last, \( z \) being fresh also implies that \( z \notin \text{vars}^1(\mathcal{E}_q_1) \). Hence, for all \( (s \vdash s') \in \mathcal{E}_q_1 \) (resp. \( s \neq s' \)), we have that \( \sigma_{s_1} = \sigma_{s_1} \) and \( \sigma_{s_1} = \sigma_{s_2} \). Since \( (\sigma_2, \theta_2) \in \text{Sol}(\mathcal{E}_2; \Phi_2; D_2; \mathcal{E}_q_2) \), we deduce that \( \sigma_{s_2} \subseteq \mathcal{E}_q_1 \sigma_{s_2} \) which implies \( \sigma_{s_1} \subseteq \mathcal{E}_q_1 \sigma_{s_1} \). We can conclude that \( \sigma_{s_1} = \sigma_{s_2} \).

2. Since \((\sigma_2, \theta_2) \in \text{Sol}(\mathcal{E}_2; \Phi_2; D_2; \mathcal{E}_q_2) \), we have that \( Z\theta_2(\Phi_2\sigma_2) = z\sigma_2, z\sigma_2 \equiv \mathcal{E}_q_2 \) and \( Z\theta_2(\Phi_2\sigma_2) \in \mathcal{T}(\mathcal{F}, \mathcal{N} \setminus \{ \mathcal{E}_2 \} \cup \{ \} , \mathcal{A}\mathcal{X}) \). Since all the function symbol operate on and return term of base type and since all terms of \( \Phi_2 \) are base type, we can deduce that \( Z\theta_2 \in \mathcal{N} \setminus \{ \mathcal{E}_2 \} \) and so \( Z\theta_2 \equiv \mathcal{E}_q_2 \) and \( \mathcal{E}_q_2 \subseteq \mathcal{E}_q_1 \). Furthermore, since \( \sigma_1 = \sigma_2 |_{\text{vars}^1(D_1)} \) and \( \text{vars}^1(D_1) = \text{vars}^1(D_2) \setminus \{ z \} \) where \( z \) is a fresh variable, we have that \( p \) is either a name or a variable in \( \text{vars}^1(D_1) \) and we have that \( \rho_{s_1} = \rho_{s_2} \).

We have that:

\[
(\mathcal{E}_1; \{ out(p\sigma_1, u\sigma_1), Q\sigma_1 \} ) \cup \mathcal{P}\sigma_1; \Phi_1|_{\sigma_1} \xrightarrow{\nu_{ax_{n+1}, out(Z\theta_2, ax_n)}} (\mathcal{E}_2; \{ Q\sigma_1 \} \cup \mathcal{P}\sigma_1; \Phi_1|_{\sigma_1} \cup \{ ax_{n+1} \vdash u\sigma_1 \}),
\]

i.e. \((\mathcal{E}_1; \mathcal{P}\sigma_1; \Phi_1|_{\sigma_1}) \xrightarrow{\nu_{ax_{n+1}, out(Z\theta_2, ax_n)}} (\mathcal{E}_2; \mathcal{P}\sigma_2; \Phi_2|_{\sigma_2}) \) since \( \sigma_2 = \sigma_1 \cup \{ z \rightarrow p \} \).

Case Out-Ch. In such a case, there exist \( p, c, Q, \mathcal{P} \), fresh variables \( Z, Y, z, y \) and \( \mathcal{P}_1 = \{ out(p, c), Q \} \), \( \mathcal{P}_2 = \{ Q \} \), \( \mathcal{E}_q_2 = \mathcal{E}_q_1 \cup \{ z \vdash p \} \), and \( \mathcal{E}_2 = \mathcal{E}_1 \) with \( n = |\Phi_1| \).

1. We have that \( \text{vars}^2(D_1) = \text{vars}^2(D_2) \setminus \{ Z, Y \} \), \( \text{vars}^1(D_1) = \text{vars}^1(D_2) \setminus \{ z, y \} \) and \( \Phi_1 = \Phi_2 \). But \((\mathcal{E}_1; \Phi_1; D_1; \mathcal{E}_q_1)\) is a constraint system hence \( \text{vars}^1(\Phi_1) \subseteq \text{vars}^1(D_1) \) which implies that \( \Phi_1|_{\sigma_1} = \Phi_2|_{\sigma_2} \). Since \( (\sigma_2, \theta_2) \in \text{Sol}(\mathcal{E}_2; \Phi_2; D_2; \mathcal{E}_q_2) \) and \( D_1 \subseteq D_2 \), we have that for all \( (X, i \vdash x) \in D_1, (X\theta_2(\Phi_2\sigma_2) = x\sigma_2 \). With \( \Phi_1|_{\sigma_1} = \Phi_2|_{\sigma_2} \), we deduce that \( (X\theta_1(\Phi_1|_{\sigma_1}) = x\sigma_1 \). Furthermore, we know that \( \sigma_2 \) satisfies the (in)equalities of \( \mathcal{E}_q_2 = \mathcal{E}_q_1 \cup \{ z \vdash p \} \) and so satisfies also the (in)equalities of \( \mathcal{E}_1 \). Since \((\mathcal{E}_1; \Phi_1; D_1; \mathcal{E}_q_1)\) being a constraint system also implies \( \text{vars}^1(\mathcal{E}_q_1) \subseteq \text{vars}^1(D_1) \), we deduce that \( \sigma_1 \) satisfies the (in)equalities of \( \mathcal{E}_q_1 \) and so we conclude that \( \sigma_1 = \sigma_2 \in \text{Sol}(\mathcal{E}_1; \Phi_1; D_1; \mathcal{E}_q_1) \).

2. Since \((\sigma_2, \theta_2) \in \text{Sol}(\mathcal{E}_2; \Phi_2; D_2; \mathcal{E}_q_2) \), we have that \( (Y\theta_2(\Phi_2\sigma_2) = y\sigma_2, y\sigma_2 = c\sigma_2 \) and \( (Y\theta_2) \in \mathcal{T}(\mathcal{F}, \mathcal{N} \setminus \{ \mathcal{E}_2 \} \cup \mathcal{D}(\Phi_2)) \). Since all the function symbol operate on and return terms of base type and since all terms of \( \Phi_2 \) are base type, we can deduce that \( (Y\theta_2) \in \mathcal{N} \setminus \{ \mathcal{E}_2 \} \) and \( \mathcal{D}(\Phi_2) = c\sigma_2 \) with \( \sigma_2 \subseteq \mathcal{E}_2 \). Furthermore, since \( \sigma_1 = \sigma_2 |_{\text{vars}^1(D_1)} \) and \( \text{vars}^1(D_1) = \text{vars}^1(D_2) \setminus \{ z, y \} \) where \( z, y \) are fresh variables, we have that \( c \) is either a name or a variable in \( \text{vars}^1(D_1) \) and we have that \( \sigma_2 = \sigma_1 \).
Lastly, \((\sigma_2, \theta_2) \in \text{Sol}((\mathcal{E}_2; \Phi_2; D_2; Eq_2))\) also implies that \((Z\theta_2)(\Phi_2\sigma_2) = z\sigma_2\) and \(z\sigma_2 \models \tau\).

We apply the same reasoning we used with \(Y\theta_1\) to prove that \(Z\theta_2 = p\sigma_1\) with \(p\sigma_1 \notin \mathcal{E}_1\).

Hence, we have that:

\[
(\mathcal{E}_1; \{\text{out}(p\sigma_1, c).Q\sigma_1\} \uplus \mathcal{P}\sigma_1; \Phi_1\sigma_1) \xrightarrow{\text{out}(Z\theta_2,Y\theta_2)} (\mathcal{E}_1; \{Q\sigma_1\} \uplus \mathcal{P}\sigma_1; \Phi_1\sigma_1).
\]

Hence, we have that \((\mathcal{E}_1; \mathcal{P}_1\sigma_1; \Phi_1\sigma_1) \xrightarrow{\alpha_0\theta_2, i} (\mathcal{E}_2; \mathcal{P}_2\sigma_2; \Phi_2\sigma_2)\).

**Case** open-ch_1. In such a case, there exist \(p, c, Q, \mathcal{P}\) and fresh variables \(Z, z\) such that \(p \notin \mathcal{E}_1\), \(c \in \mathcal{E}_1\), \(\mathcal{P}_1 = \{\text{out}(p, c).Q\} \uplus \mathcal{P}\), \(\mathcal{P}_2 = \{\{Q\} \uplus \mathcal{P}\}\{c \rightarrow ch\}\), \(\mathcal{E}_2 = \mathcal{E}_1\), \(\Phi_2 = \Phi_1\), \(D_2 = D_1 \cup \{Z, n \uplus z\}\), \(Eq_2 = Eq_1 \cup \{z \doteq p\}\), and \(\alpha_0 = \nu ch_m, \text{out}(Z, ch_m)\) with \(n = |\Phi_1|\).

1. We have that \(\text{vars}^2(D_1) = \text{vars}^2(D_2) \setminus \{Z\}\), \(\text{vars}^1(D_1) = \text{vars}^1(D_2) \setminus \{z\}\) and \(\Phi_1 = \Phi_2\). But \((\mathcal{E}; \Phi_1; D_1; Eq_1)\) is a constraint system hence \(\text{vars}^1(\Phi_1) \subseteq \text{vars}^1(D_1)\) which implies that \(\Phi_1\sigma_1 = \Phi_2\sigma_2\). Since \((\sigma_2, \theta_2) \in \text{Sol}((\mathcal{E}_2; \Phi_2; D_2; Eq_2))\) and \(D_1 \subseteq D_2\), we have that for all \((X, i \vdash x) \in D_1\), \((X\theta_2)(\Phi_2\sigma_2) = x\sigma_2\). With \(\Phi_1\sigma_1 = \Phi_2\sigma_2\), we deduce that \((X\theta_1)(\Phi_1\sigma_1) = x\sigma_1\). Furthermore, we know that \(\sigma_2\) satisfies the (in)equalities of \(Eq_2 = Eq_1 \cup \{z \doteq p\}\) and so satisfies also the (in)equalities of \(Eq_1\). Since \((\mathcal{E}; \Phi_1; D_1; Eq_1)\) being a constraint system also implies \(\text{vars}^1(Eq_1) \subseteq \text{vars}^1(D_1)\), we deduce that \(\sigma_1\) satisfies the (in)equalities of \(Eq_1\) and so we conclude that \((\sigma_1, \theta_1) \in \text{Sol}((\mathcal{E}_1; \Phi_1; D_1; Eq_1))\).

2. Since \((\sigma_2, \theta_2) \in \text{Sol}((\mathcal{E}_2; \Phi_2; D_2; Eq_2))\), we have that \((Z\theta_2)(\Phi_2\sigma_2) = z\sigma_2\), \(z\sigma_2 = p\sigma_2\) and \((Z\theta_2) \in T(\mathcal{N} \setminus \{\mathcal{E}_2\}, \text{dom}(\Phi_2))\). Since all the function symbols operate on and return terms of base type and since all terms of \(\Phi_2\) are base type, we can deduce that \((Z\theta_2) \in \mathcal{N} \setminus \{\mathcal{E}_2\}\) and so \(Z\theta_2 = p\sigma_2\) with \(p\sigma_2 \notin \mathcal{E}_1\) (\(\mathcal{E}_1 = \mathcal{E}_2\)). Furthermore, since \(\sigma_1 = \sigma_2\), \(\text{vars}^1(D_1) = \text{vars}^1(D_2) \setminus \{z\}\) where \(z\) is a fresh variable, then \(p\) is either a name or a variable and we have that \(p\sigma_2 = p\sigma_1\). Hence, we have that:

\[
(\mathcal{E}_1; \{\text{out}(p\sigma_1, c).Q\sigma_1\} \uplus \mathcal{P}\sigma_1; \Phi_1\sigma_1) \xrightarrow{\nu ch_m, \text{out}(Z\theta_2, ch_m)} (\mathcal{E}_1; \{Q\sigma_1\} \uplus \mathcal{P}\sigma_1; \{c \rightarrow ch_m\}; \Phi_1\sigma_1).
\]

Since \(ch_m\) is fresh name, we have that \(((Q\sigma_1) \uplus \mathcal{P}\sigma_1; \{c \rightarrow ch_m\}) = (\{Q\} \uplus \mathcal{P}\sigma_1; \{c \rightarrow ch_m\})\).

Hence, we have that \((\mathcal{E}_1; \mathcal{P}_1\sigma_1; \Phi_1\sigma_1) \xrightarrow{\alpha_0, \theta_2, i} (\mathcal{E}_2; \mathcal{P}_2\sigma_2; \Phi_2\sigma_2)\). \(\square\)

**Proposition 4.3** (completeness). Let \((\mathcal{E}_1; \mathcal{P}_1; \Phi_1; D_1; Eq_1)\) be a symbolic process. Let \((\sigma_1, \theta_1) \in \text{Sol}((\mathcal{E}_1; \Phi_1; D_1; Eq_1))\). Let \((\mathcal{E}; \mathcal{P}; \Phi)\) be an intermediate process such that \((\mathcal{E}_1; \mathcal{P}_1\sigma_1; \Phi_1\sigma_1) \xrightarrow{\alpha_1} (\mathcal{E}_1; \mathcal{P}_1; \Phi_1)\). There exist a symbolic process \((\mathcal{E}_2; \mathcal{P}_2; \Phi_2; D_2; Eq_2)\), a pair of substitutions \((\sigma_2, \theta_2)\), and a symbolic action \(\alpha_2\) such that:

1. \((\mathcal{E}_1; \mathcal{P}_1; \Phi_1; D_1; Eq_1) \xrightarrow{\alpha_1} (\mathcal{E}; \mathcal{P}_1; \Phi_1)\);
2. \((\sigma_2, \theta_2) \in \text{Sol}((\mathcal{E}_2; \Phi_2; D_2; Eq_2))\);
3. \((\mathcal{E}; \mathcal{P}; \Phi) = (\mathcal{E}_2; \mathcal{P}_2\sigma_2; \Phi_2\sigma_2)\); and
4. \(\alpha_2\theta_2 = \alpha\).

**Proof.** The proof consists of a case analysis on the rule involved in the reduction step of:

\[
(\mathcal{E}_1; \mathcal{P}_1\sigma_1; \Phi_1\sigma_1) \xrightarrow{\alpha_1} (\mathcal{E}; \mathcal{P}; \Phi).
\]

**Case** THEN.; In such a case we have that \(\mathcal{E} = \mathcal{E}_1\) and there exist \(u', v', Q'_1, Q'_2\), and \(P'\) such that \(u' = u', \mathcal{P}_1\sigma_1 = \{u' \rightarrow v' \mid Q'_1, \text{else } Q'_2\} \uplus \mathcal{P}'\), \(P = \{Q'_1\} \uplus \mathcal{P}'\), \(\Phi = \Phi_1\sigma_1\), and \(\alpha = \tau\). Hence we deduce that that there exist \(u, v, Q_1, Q_2\), and \(P_0\) such that \(P_1 = \{u \rightarrow v \mid \text{then } Q_1, \text{else } Q_2\} \uplus P_0\), and thus we have that \(u\sigma_1 = u, v\sigma_1 = v', Q_1\sigma_1 = Q'_1, Q_2\sigma_1 = Q'_2,\) and \(P_0\sigma_1 = P'\). Let \(\mathcal{E}_2 = \mathcal{E}_1\), \(\mathcal{P}_2 = Q_1 \uplus P_0, \Phi_2 = \Phi_1, D_2 = D_1, Eq_2 = Eq_1 \cup \{u \doteq v\}, \alpha_2 = \tau, \theta_2 = \theta_1\) and \(\sigma_2 = \sigma_1\). We have that:
1. \((E_1; P_1; \Phi_1; D_1; Eq_1) \xrightarrow{s} (E_2; P_2; \Phi_2; D_2; Eq_2)\). Indeed, we have that

\[(E_1; \{\text{if } u = v \text{ then } Q_1 \text{ else } Q_2\} \triangleright P_0; \Phi_1; D_1; E_1) \xrightarrow{s} (E_2; \{Q_1\} \triangleright P_0; \Phi_1; D_1; E_1 \cup \{u \triangleright v\})\].

2. We have that \(\text{vars}^s(D_2) = \text{vars}^s(D_1), E_2 = E_1, D_2 = D_1 \text{ and } \Phi_2 = \Phi_1\). To check that \((\sigma_2, \theta_2)\)
is a solution, it remains to show that \(\sigma_2\) satisfies the (in)equalities in \(E_2 = E_1 \cup \{u \triangleright v\}\). But, we have that \(u' \equiv E v'\) and \(s\omega_1 \equiv E s\omega_2\). With \(\sigma_1 = \sigma_2\), we deduce that \(u \omega_2 = E v \omega_2\) and so \((\sigma_2, \theta_2) \in \text{Sol}((E_2; P_2; D_2; E_2))\).

3. We have that

\[(E_2; P_2\sigma_2; \Phi_2\sigma_2) = \begin{align*}
(E_2; \{Q_1\} \triangleright P_0; \Phi_1; D_1; E_1) &\xrightarrow{s} (E; \{Q_1^s\} \triangleright P_0; P; \Phi) \\
(E; \{Q_1^s\} \triangleright P_0; P; \Phi) &\xrightarrow{s} (E; \{Q_1\} \triangleright P_0; \Phi_2; D_2; E_2) \\
\end{align*}\]

4. We have that \(\alpha_s \theta_2 = \alpha_s = \alpha\).

The case of the rule ELSE can be done in a similar way.

**Case COMM:** In such a case we have that \(E = E_1\) and there exist \(p', u', x, Q'_1, Q'_2,\) and \(P'\) such that \(P_1, \sigma_1 = \{\text{out}(p', u'), Q'_1, \text{in}(q, x), Q'_2\} \triangleright P', P = \{Q_1'; Q_2'; x \triangleright u'\} \triangleright P', \Phi = \Phi_1,\) and \(\alpha = \tau\). Hence we deduce that that there exist \(u, p, q, Q_1, Q_2\) and \(P_0\) such that \(P_1 = \{\text{out}(p, u), Q_1; \text{in}(q, x), Q_2\} \triangleright P_0,\) and thus we have that \(u \sigma_1 = u', q \sigma_1 = p \sigma_1 = p', Q_1 \sigma_1 = Q'_1, Q_2 \sigma_1 = Q'_2,\) and \(P_0 \sigma_1 = P'\). Let \(E_2 = E_1, P_2 = \{Q_1; Q_2; x \triangleright u\} \triangleright P_0, \Phi_2 = \Phi_1, D_2 = D_1, E_2 = E_1 \cup \{p \triangleright q\}\).

1. \((E_1; P_1; \Phi_1; D_1; E_1) \xrightarrow{s} (E_2; P_2; \Phi_2; D_2; E_2)\). Indeed, we have that

\[(E_1; \{\text{out}(p, u), Q_1; \text{in}(q, x), Q_2\} \triangleright P_0; \Phi_1; D_1; E_1) \xrightarrow{s} (E_1; \{Q_1; Q_2; x \triangleright u\} \triangleright P_0; \Phi_1; D_1; E_1 \cup \{p \triangleright q\})\].

2. We have that \(E_2 = E_1 = E_1, D_2 = D_1, E_2 = E_1 \cup \{p \triangleright q\}\) and \(\Phi_2 = \Phi_1\). To check that \((\sigma_2, \theta_2)\) is a solution, it remains to show that \(\sigma_2\) satisfies the (in)equalities in \(E_2 = E_1 \cup \{p \triangleright q\}\). But we know that \(p \sigma_2 = q \sigma_2\) hence \(p \sigma_2 = E q \sigma_2\) and so \((\sigma_2, \theta_2) \in \text{Sol}((E_2; P_2; D_2; E_2))\).

3. Since \(x\) is fresh and \(x \not\in \text{dom}(\sigma_1)\), we have \(Q_2; x \triangleright u\) is a solution, it remains to show that \(\sigma_2\) satisfies the (in)equalities in \(E_2 = E_1 \cup \{p \triangleright q\}\). But we know that \(p \sigma_2 = q \sigma_2\) hence \(p \sigma_2 = E q \sigma_2\) and so \((\sigma_2, \theta_2) \in \text{Sol}((E_2; P_2; D_2; E_2))\).

4. We have that \(\alpha_s \theta_2 = \alpha_s = \alpha\).

**Case IN:** In such a case we have that \(E = E_1, \Phi = \Phi_1,\) and there exist \(p', x, Q', P', M\) and \(u\) such that \(p' \not\in E_1, P_1, \sigma_1 = \{\text{in}(p', x), Q'\} \triangleright P', P = \{Q' \triangleright u\} \triangleright P', M \Phi_1 \sigma_1 = u,\) \(\text{vars}(M) \subseteq \text{dom}(\Phi_1 \sigma_1),\) and \(\alpha = \text{in}(p', M)\). Hence, we deduce that that there exist \(p, Q, P_0\) such that \(P_1 = \{\text{in}(p, x), Q\} \triangleright P_0,\) and \(\text{for} = p, Q_1 = Q'\) and \(P_0 \sigma_1 = P'\).

Let \(Y\) and \(Z\) be two free order variables and \(y, z\) be two free order variables. Let \(E_2 = E_1, P_2 = \{Q \triangleright y\} \triangleright P_0, \Phi_2 = \Phi_1, D_2 = D_1 \cup \{Y, n \triangleright y; Z, n \triangleright z\}; E_2 = E_1 \cup \{z \triangleright p\}\) and \(\alpha_s = \text{in}(Z, Y)\) with \(n = \Phi_1 \sigma_1\). Let \(\theta_2\) be the substitution such that \(\theta_2 = \theta_1 \cup \{Y \triangleright M; Z \triangleright p'\}\) and let \(\sigma_2\) be the substitution such that \(\sigma_2 = \sigma_1 \cup \{y \triangleright u; z \triangleright p'\}\). We have that:

1. \((E_1; P_1; \Phi_1; D_1; E_1) \xrightarrow{s} (E_2; P_2; \Phi_2; D_2; E_2)\). Indeed, we have that

\[(E_1; \{\text{in}(p, x), Q\} \triangleright P_0; \Phi_1; D_1; E_1) \xrightarrow{s} (E_1; \{Q \triangleright y\} \triangleright P_0; \Phi_1; D_1 \cup \{Y, n \triangleright y; Z, n \triangleright z\}; E_1 \cup \{z \triangleright p\})\].
2. Thanks to $\text{fnames}(\theta_1) \cap \mathcal{E}_1 = \emptyset$, $\text{fnames}(M) \cap \mathcal{E}_1 = \emptyset$ and $p' \not\in \mathcal{E}_1$, we have $\text{dom}(\theta_2) = \text{vars}^2(D_2)$ and $\text{fnames}(\theta_2) \cap \mathcal{E}_2 = \emptyset$. Hence we have that $Z\theta_2, Y\theta_2 \in \mathcal{T}(N \setminus \mathcal{E}_2, AX)$. Furthermore, since $\{\Phi_1, \sigma_2\} \subseteq \text{vars}(M) \subseteq \text{dom}(\Phi_1)$ and $p'$ is a channel name we deduce that $\text{param}(Z\theta_2) \subseteq \{ax_1, \ldots, ax_n\}$ and $\text{param}(Y\theta_2) \subseteq \{ax_1, \ldots, ax_n\}$.

Now, it remains to show that $\sigma_2$ satisfies the constraints in $D_2$ and the (in)equalities in $E_{q_2}$.

Since $\sigma_2 = \sigma_1 \cup \{y \rightarrow u: z \rightarrow p'\}$ where $y, z$ are fresh variables, it implies that $\Phi_2(\sigma_2) = \Phi_1, \sigma_1, p\sigma_2 = p\sigma_1$ which allows us to conclude since $(Y\theta_2)(\Phi_2(\sigma_2)) = M(\Phi_1, \sigma_1) = u = y\sigma_2, (Z\theta_2)(\Phi_2(\sigma_2)) = p'(\Phi_2(\sigma_2)) = p' = z\sigma_2 = p\sigma_2$ and $z\sigma_2 = p\sigma_2$ implies $z\sigma_2 =_{E} p\sigma_2$.

3. We have that
\begin{align*}
(\mathcal{E}_2, p_2, \Phi_2, \sigma_2) &= (\mathcal{E}_1, \{(Q \{x \rightarrow y\})\sigma_2 \vdash P_0, \Phi_1, \sigma_1\}) \\
&= (\mathcal{E}_1, \{(Q \{x \rightarrow u\})\sigma_2 \vdash P_0, \Phi_1, \sigma_1\}) \\
&= (\mathcal{E}_1, \{(Q' \{x \rightarrow u\}) \vdash P', \Phi\}) \\
&= (\mathcal{E}, P, \Phi).
\end{align*}

4. We have that $\alpha, \theta_2 = In(Z, Y)\theta_2 = In(p', M) = \alpha$.

**Case Out-T:** In such a case we have that $E = \mathcal{E}_1$ and there exist $p', u', Q'$, and $P'$ such that $p' \not\in \mathcal{E}_1$, $P_1, \sigma_1 = \{\text{out}(p', u'), Q'\} \vdash P'$, $\Phi = \Phi_1, \sigma_1 \cup \{ax_{n+1} \triangleright u'\}$ where $n = |\Phi_1, \sigma_1|$, $P = \{Q'\} \vdash P'$, and $\alpha = \nu ax_{n+1} \text{out}(p', ax_{n+1})$. Since $P_1, \sigma_1 = \{\text{out}(p', u'), Q'\} \vdash P'$, we deduce that there exist $u, p, Q$ and $P_0$ such that $P_1 = \{\text{out}(p, u), Q\} \vdash P_0$, with $u_1 = u$, $p_1 = p$, $Q_1 = Q'$, and $P_0, \sigma_1 = P'$.

Let $Z$ be a second order variable and $z$ be a fresh first order variable. Let $E_2 = \mathcal{E}_1$, $P_2 = Q \cup P_0$, $\Phi_2 = \Phi_1 \cup \{ax_{n+1} \triangleright u\}$, $D_2 = D_1 \cup \{Z, n \vdash z, \mathcal{E}_2\}$. $E_{q_2} = E_{q_1} \cup \{z \vdash p\}$. $\alpha_s = \nu ax_{n+1} \text{out}(Z, ax_{n+1}), \theta_2 = \theta_1 \cup \{Z \rightarrow p'\}$ and $\sigma_2 = \sigma_1 \cup \{z \rightarrow p'\}$. We have that:

1. $(\mathcal{E}_1; P; \Phi; D; E_{q_1}) \xrightarrow{\alpha_s} (\mathcal{E}_2; P_2; \Phi_2; D_2; E_{q_2})$. Indeed, we have that
\begin{align*}
(\mathcal{E}_1; \{(Q \{x \rightarrow y\})\} \vdash P_0, \Phi_1, \theta_1 \cup \{ax_{n+1} \triangleright u\}) \quad &\xrightarrow{\nu ax_{n+1} \text{out}(Z, ax_{n+1})} \quad (\mathcal{E}_1; \{(Q \vdash P); \Phi_1 \cup \{ax_{n+1} \triangleright u\}) \quad &\vdash D_1 \cup \{Z, n \vdash z\}; E_{q_1} \cup \{z \vdash p\}).
\end{align*}

2. We have $\text{dom}(\theta_2) = \text{vars}^2(D_2)$ and $\text{fnames}(\theta_2) \cap \mathcal{E}_2 = \emptyset$ since $\text{fnames}(\theta_1) \cap \mathcal{E}_1 = \emptyset$ and $p' \not\in \mathcal{E}_1$. Furthermore, for all $(X, i \vdash x) \in D_1$, we have that $i \leq n, X\theta_2 = X\theta_1, x_\sigma_1 = x_\sigma_2$ and $\Phi_2(\sigma_1) = \Phi_1, \sigma_2$ thus we deduce that $\text{param}(X\theta_2) \subseteq \{ax_1, \ldots, ax_n\}$ and $\text{param}(X\theta_1)(\Phi_1, \sigma_1) = \text{param}(X\theta_2) \subseteq \{ax_1, \ldots, ax_n\}$ implies $(X\theta_2)(\Phi_2(\sigma_2)) = \text{param}(X\theta_1)(\Phi_1, \sigma_1) = \text{param}(X\theta_2) \subseteq \{ax_1, \ldots, ax_n\}$. Moreover, we know have that $Z\theta_2 = p' = z\sigma_2$ thus we deduce that $(Z\theta_2)(\Phi_2(\sigma_2)) = z\sigma_2$. At last, we know that $p_1 = p'$ hence $p\sigma_2 = p' = \sigma_2$, thus we deduce that $\sigma_2 =_{E} z\sigma_2$. We can conclude that $(\sigma_2, \theta_2) \in \text{Sol}((\mathcal{E}_2; \Phi_2; D_2; E_{q_2}))$.

3. We have that
\begin{align*}
(\mathcal{E}_2, P_2, \Phi_2, \sigma_2) &= (\mathcal{E}_1, \{Q\sigma_1 \vdash P_0, \Phi_1, \sigma_1 \cup \{ax_{n+1} \triangleright u\}\}) \\
&= (\mathcal{E}, \{Q' \vdash P'; \Phi_1 \cup \{ax_{n+1} \triangleright u\}\}) \\
&= (\mathcal{E}; P, \Phi).
\end{align*}

4. We have that $\alpha, \theta_2 = \nu ax_{n+1} \text{out}(Z, ax_{n+1})\theta_2 = \nu ax_{n+1} \text{out}(p', ax_{n+1}) = \alpha$.

**Case Out-CH.** In such a case we have that $E = \mathcal{E}_1$, $\Phi = \Phi_1, \sigma_1$ and there exist $p', c', Q'$, and $P'$ such that $P_1 = \{\text{out}(p', c'), Q'\} \vdash P'$, $P = \{Q'\} \vdash P', p', c' \not\in \mathcal{E}_1$, and $\alpha = \text{out}(p', c')$. Hence, we deduce that there exist $p, c, Q$ and $P_0$ such that $P_1 = \{\text{out}(p, c), Q\} \vdash P_0$ with $c_\sigma_1 = c', p_\sigma_1 = p', P_0, \sigma_1 = P'$ and $Q_\sigma_1 = Q'$.

Let $Z$ and $Y$ be second order variables and $z, y$ be fresh first order variables. Let $E_2 = \mathcal{E}_1, P_2 = Q \cup P_0, \Phi_2 = \Phi_1, D_2 = D_1 \cup \{Z, n \vdash z, Y, n \vdash y\}$. $E_{q_2} = E_{q_1} \cup \{z \vdash p, y \vdash c\}$. $\alpha_s = \text{out}(Z, Y)$, $\theta_2 = \theta_1 \cup \{Z \rightarrow p', Y \rightarrow c'\}$ and $\sigma_2 = \{z \rightarrow p', y \rightarrow c'\}$ with $n = |\Phi_1|$. We have that:
1. \((\mathcal{E}_1; \mathcal{P}_1; \Phi_1; D_1; E_{q_1}) \xrightarrow{\alpha \sigma_2} (\mathcal{E}_2; \mathcal{P}_2; \Phi_2; D_2; E_{q_2})\). Indeed, we have that
\[
(\mathcal{E}_1; \{\text{out}(p, c), Q\} \uplus \mathcal{P}_0; \Phi_1; D_1; E_{q_1}) \xrightarrow{\text{out}(Z, Y)} (\mathcal{E}_2; \{Q\} \uplus \mathcal{P}_0; \Phi_1; D_1 \cup \{Z, n \vdash z; Y \vdash y\}; E_{q_1} \cup \{z \equiv p; y \equiv c\}).
\]

2. First of all, we have \(\text{dom}(\theta_2) = \text{vars}^2(D_2)\). Second, we know that \(p'\) and \(c'\) are both channel names such that \(p', c' \notin \mathcal{E}_2 (\mathcal{E}_1 = \mathcal{E}_2)\). Thus, it implies that \(Z\theta_2, Y\theta_2 \in \mathcal{T}(\mathcal{N} \setminus \mathcal{E}_2, \mathcal{A}\mathcal{X})\). Furthermore, we trivially have that \(\text{param}(Z\theta_2) = \text{param}(Y\theta_2) = \emptyset \subseteq \{ax_1, \ldots, ax_n\}\).

Now, it remains to show that \(\sigma_2\) satisfies the constraints in \(D_2\) and the (in)equalities in \(E_{q_2}\). Since \(\sigma_2 = \{z \mapsto p'; y \mapsto c'\}\) with \(z, y\) fresh variables, it implies that \(\Phi_2\sigma_2 = \Phi_1\sigma_1, p\sigma_2 = p\sigma_1\) and \(c\sigma_2 = c\sigma_1\) which allows us to conclude since
- \((Y\theta_2)(\Phi_2\sigma_2) = c'(\Phi_2\sigma_2) = c' = y\sigma_2;\)
- \((Z\theta_2)(\Phi_2\sigma_2) = p'(\Phi_2\sigma_2) = p' = z\sigma_2;\)
- \(y\sigma_2 \equiv E \sigma_2\) and \(z\sigma_2 \equiv E \sigma_2\) since \(c' = c\sigma_1 = c\sigma_2\) and \(p' = p\sigma_1 = p\sigma_2\).

3. We have that
\[
(\mathcal{E}_2; \mathcal{P}_2\sigma_2; \Phi_2\sigma_2) = (\mathcal{E}_1; \{Q\sigma_1 \uplus \mathcal{P}_0\sigma_1; \Phi_1\sigma_1\})
= (\mathcal{E}; \mathcal{P}; \Phi).
\]

4. We have that \(\alpha \theta_2 = \text{out}(Z, Y)\theta_2 = \text{out}(p', c') = \alpha\).

Case Open-Ch₁: In such a case we have that \(\mathcal{E} = \mathcal{E}_1, \Phi = \Phi_1\sigma_1\) and there exist \(p', c, Q', P'\) and a fresh channel name \(ch_b\) such that \(\mathcal{P}_1\sigma_1 = \{\text{out}(p', c), Q'\} \uplus P', P = \{Q' \uplus P'; \{c \mapsto ch_b\}\},\)
\(p' \notin \mathcal{E}_1, c \in \mathcal{E}_1,\) and \(\alpha = \nu ch_m, \text{out}(p, ch_m)\). Hence, we deduce that there exist \(p, Q\) and \(P_0\) such that \(\mathcal{P}_1 = \{\text{out}(p, c), Q\} \uplus P_0\) with \(\sigma_1 = p', P_0\sigma_1 = P'\) and \(Q\sigma_1 = Q'\).

Let \(Z\) be a second order variable and \(z\) be a fresh first order variable. Let \(\mathcal{E}_2 = \mathcal{E}_1, \mathcal{P}_2 = \{\{Q\} \uplus P_0\} \{c \mapsto ch_m\}, \Phi_2 = \Phi_1, D_2 = D_1 \cup \{Z, n \vdash z\}, E_{q_2} = E_{q_1} \cup \{z \equiv p\}, \alpha_s = \nu ch_m, \text{out}(Z, ch_m),\)
\(\theta_2 = \theta_1 \cup \{Z \mapsto p', \sigma_2 = \sigma_1 \cup \{z \mapsto p'\}\} \text{ with } n = \{\Phi_1\sigma_1\} \). We have that:

1. \((\mathcal{E}_1; \mathcal{P}_1; \Phi_1; D_1; E_{q_1}) \xrightarrow{\alpha \sigma_2} (\mathcal{E}_2; \mathcal{P}_2; \Phi_2; D_2; E_{q_2})\). Indeed, we have that
\[
(\mathcal{E}_1; \{\text{out}(p, c), Q\} \uplus \mathcal{P}_0; \Phi_1; D_1; E_{q_1}) \xrightarrow{\nu ch_m, \text{out}(Z, ch_m)} (\mathcal{E}_2; \{\{Q\} \uplus P_0\} \{c \mapsto ch_m\}; \Phi_1; D_1 \cup \{Z, n \vdash z\}; E_{q_1} \cup \{z \equiv p\}).
\]

2. First of all, we have \(\text{dom}(\theta_2) = \text{vars}^2(D_2)\). Second, we know that \(p'\) is a channel name such that \(p' \notin \mathcal{E}_2 (\mathcal{E}_1 = \mathcal{E}_2)\). Thus, it implies that \(Z\theta_2 \in \mathcal{T}(\mathcal{N} \setminus \mathcal{E}_2, \mathcal{A}\mathcal{X})\). Furthermore, we trivially have that \(\text{param}(Z\theta_2) = \emptyset \subseteq \{ax_1, \ldots, ax_n\}\).

Now, it remains to show that \(\sigma_2\) satisfies the constraints in \(D_2\) and the (in)equalities in \(E_{q_2}\). Since \(\sigma_2 = \{z \mapsto p'\}\) with \(z\) fresh variables, it implies that \(\Phi_2\sigma_2 = \Phi_1\sigma_1, p\sigma_2 = p\sigma_1\) and \(c\sigma_2 = c\sigma_1\) which allows us to conclude since \((Z\theta_2)(\Phi_2\sigma_2) = p'(\Phi_2\sigma_2) = p' = z\sigma_2\) and \(p' = p\sigma_1 = p\sigma_2\) implies \(z\sigma_2 \equiv E \sigma_2\).

3. We have that
\[
(\mathcal{E}_2; \mathcal{P}_2\sigma_2; \Phi_2\sigma_2) = (\mathcal{E}_1; \{\{Q\} \uplus P_0\} \{c \mapsto ch_m\}; \Phi_1\sigma_1) \equiv (\mathcal{E}; \mathcal{P}; \Phi).
\]

4. We have that \(\alpha \theta_2 = \nu ch_m, \text{out}(Z, ch_m)\theta_2 = \nu ch_m, \text{out}(p', ch_m) = \alpha\).
Case \textsc{Par}_{1}: In such a case we have that $E = E_1$ and there exist $P', Q'$, and $\mathcal{P}'$ such that $\mathcal{P}_1\sigma_1 = \{P' | Q'\} \uplus \mathcal{P}'$, $P = \{P'; Q'\} \uplus \mathcal{P}'$, $\Phi = \Phi_1\sigma_1$, and $\alpha = \tau$. Hence we deduce that that there exist $P, Q$, and $\mathcal{P}_0$ such that $\mathcal{P}_1 = \{P | Q\} \uplus \mathcal{P}_0$, and thus we have that $Q\sigma_1 = Q'$, $P\sigma_1 = P'$, and $\mathcal{P}_0\sigma_1 = \mathcal{P}'$. Let $E_2 = E_1$, $P_2 = \{P; Q\} \uplus \mathcal{P}_0$, $\Phi_2 = \Phi_1$, $D_2 = D_1$, $E_{q2} = E_{q1}$, $\alpha_s = \tau$, $\theta_2 = \theta_1$ and $\sigma_2 = \sigma_1$. We have that:

1. $(E_1; P_1; \Phi_1; D_1; E_{q1}) \overset{\alpha_s}{\rightarrow} (E_2; P_2; \Phi_2; D_2; E_{q2})$. Indeed, we have that $(E_1; \{P | Q\} \uplus \mathcal{P}_0; \Phi_1; D_1; E_{q1}) \overset{\alpha_s}{\rightarrow} (E_1; \{P; Q\} \uplus \mathcal{P}_0; \Phi_1; D_1; E_{q1})$.

2. We have that $(E_2; \Phi_2; D_2; E_{q2}) = (E_1; \Phi_1; D_1; E_{q1})$, $\theta_2 = \theta_1$ and $\sigma_2 = \sigma_1$ and we trivially have that $(\sigma_2, \theta_2) \in \text{Sol}((E_2; \Phi_2; D_2; E_{q2}))$.

3. We have that

$$
(E_2; \mathcal{P}_2\sigma_2; \Phi_2\sigma_2) = (E_1; \{P\sigma_2; Q\sigma_2\} \uplus \mathcal{P}_0\sigma_2; \Phi_2\sigma_2) = (E_1; \{P\sigma_1; Q\sigma_1\} \uplus \mathcal{P}_0\sigma_1; \Phi_1\sigma_1) = (\mathcal{E}; \mathcal{P}; \Phi).
$$

4. We have that $\alpha \theta_2 = \alpha_s = \alpha$. \qed
Appendix B

Composition of trace equivalence

B.1 Preliminaries

**Lemma 5.4.** If $t_1, t_2$ are terms (that do not use dom($\rho$)) in normal form then for all $i \in \{a, b\}$, $t_1 = t_2$ is equivalent to $\delta^\rho_i(t_1) = \delta^\rho_i(t_2)$.

**Proof.** The right implication of the lemma is trivial thus, we focus on the left implication: for all $i \in \{a, b\}, \delta^\rho_i(t_1) = \delta^\rho_i(t_2)$ implies $t_1 = t_2$. We prove this result by induction on max($|t_1|, |t_2|$).

**Base case** max($|t_1|, |t_2|$) = 1: In such a case, we have that $t_1, t_2 \in X \cup \mathcal{N}$. By definition of $\delta^\rho_i$, we know that $\delta^\rho_i(t_1) = t_1$ and $\delta^\rho_i(t_2) = t_2$. Thus, we can conclude that $\delta^\rho_i(t_1) = \delta^\rho_i(t_2)$ implies $t_1 = t_2$.

For the case $i = b$, we do a case analysis on whether $\delta^\rho_i(t_1) = \delta^\rho_i(t_2) = k$ for some $k \in \text{dom}(\rho)$ or not.

*Case $\delta^\rho_i(t_1) = k \in \text{dom}(\rho)$:* By hypothesis, we know that $t_2$ and $t_1$ do not use dom($\rho$). Therefore, by definition of $\delta^\rho_i$, we can deduce that, $t_2 \downarrow = kp$ and $t_1 \downarrow = kp$. Since $t_1$ and $t_2$ are in normal form, we can conclude that $t_1 = t_2 = kp$.

*Case $\delta^\rho_i(t_1) \neq k$ for every $k \in \text{dom}(\rho)$:* By definition of $\delta^\rho_i$, we have that $\delta^\rho_i(t_1) = t_1$ and $\delta^\rho_i(t_2) = t_2$, and thus $t_1 = t_2$.

**Inductive step** max($|t_1|, |t_2|$) > 1: Assume w.l.o.g. that $|t_1| > 1$. Thus, there exists a function symbol $f$ and terms $u_1, \ldots, u_n$ such that $t_1 = f(u_1, \ldots, u_n)$. Since $t_1$ is in normal form, we can deduce that $t_1 \downarrow \neq kp$, for every $k \in \text{dom}(\rho)$. We do a case analysis on $t_1$:

*Case $f \in \mathcal{F}_d \cup \mathcal{F}_{tag}$ and $d \in \{a, b\}$:* In such a case, we have that $\delta^\rho_d(t_1) = f(\delta^\rho_d(u_1), \ldots, \delta^\rho_d(u_n))$.

But $\delta^\rho_d(t_2) = \delta^\rho_d(t_1)$ and by definition of $\delta^\rho_d$ we know that it implies that there exists $v_1, \ldots, v_n$ such that $t_2 = f(v_1, \ldots, v_n)$ and $\delta^\rho_d(t_2) = f(\delta^\rho_d(v_1), \ldots, \delta^\rho_d(v_n))$. Thus we have that $\delta^\rho_d(v_j) = \delta^\rho_d(u_j)$ for all $j \in \{1, \ldots, n\}$. Furthermore, since $t_1$ and $t_2$ are in normal form, we also know that $u_j$ and $v_j$ are in normal form, for every $j$. But, max($|t_1|, |t_2|$) = max($|u_j|, |v_j|$), for any $j$, thus by our inductive hypothesis, we can deduce that $u_j = v_j$, for all $j$ and so $t_1 = f(u_1, \ldots, u_n) = f(v_1, \ldots, v_n) = t_2$.

*Case $t_1 = f(\tag_d(w_1), w_2)$ and $d \in \{\text{senc, aenc, sign}\}$:* In this case, we know that $\delta^\rho_d(t_1) = f(\tag_d(\delta^\rho_d(w_1)), \delta^\rho_d(w_2))$. But we know that $\delta^\rho_d(t_2) = \delta^\rho_d(t_1) = f(\tag_d(\delta^\rho_d(w_1)), \delta^\rho_d(w_2))$. Thus thanks to $t_2$ being in normal form and by definition of $\delta^\rho_d$ it implies that there exists $v_1$ and $v_2$ such that $t_2 = f(\tag_d(v_1), v_2)$ and so $\delta^\rho_d(t_2) = f(\tag_d(\delta^\rho_d(v_1)), \delta^\rho_d(v_2))$. Thus, we have that $\delta^\rho_d(v_1) = \delta^\rho_d(u_1)$ and $\delta^\rho_d(v_2) = \delta^\rho_d(w_2)$. Moreover, $t_1$ and $t_2$ being in normal form and not using dom($\rho$), so are $u_j$ and $v_j$ for $j \in \{1, 2\}$, so we can apply our inductive hypothesis and conclude that $v_1 = u_1$ and $v_2 = u_2$ and so $t_1 = t_2$.

*Case $t_1 = h(\tag_d(w_1))$ and $d \in \{a, b\}$:* This case is analogous to the previous one and can be handled in a similar way.

*Else case:* Otherwise, we have that $f \in \mathcal{F}_0$ but the root symbol of $v_1$ is not tag_a or tag_b. By definition of $\delta^\rho_d$, we can deduce that $\delta^\rho_d(t_1) = f(\delta^\rho_d(u_1), \ldots, \delta^\rho_d(u_n))$. Since $\delta^\rho_d(t_1) = \delta^\rho_d(t_2)$, we can deduce that the top symbol of $t_2$ is also $f$ and so there exists $v_1, \ldots, v_n$ such that $t_2 = f(v_1, \ldots, v_n)$. In the previous cases, we showed that if $f \in \{\text{senc, aenc, sign, h}\}$ and the top symbol of $v_1$ is tag_a or
tag_\alpha, then \delta^\alpha_0(t_1) = \delta^\alpha_0(t_2) implies that the top symbol of u_1 is also tag_\alpha or tag_\beta. Thus, thanks to our hypothesis, we can deduce that either f \not\in \{\text{send}, \text{aenc}, \text{sign}, \text{h}\} or the top symbol of u_1 is different from tag_\alpha and tag_\beta. Hence by definition of \delta^\alpha_0, we can deduce that \delta^\alpha_0(t_2) = f(\delta^\alpha_0(v_1), \ldots, \delta^\alpha_0(v_n)) and so \delta^\alpha_0(v_j) = \delta^\alpha_0(u_j) for all j \in \{1, \ldots, n\}. Moreover, t_1 and t_2 being in normal form and not using names in \text{dom}(\rho), implies that so are u_j and v_j for all j \in \{1, \ldots, n\}. We can thus invoke our inductive hypothesis and conclude that u_j = v_j for all j \in \{1, \ldots, n\} and so t_1 = t_2.

\[\square\]

**Lemma 5.5.** Let t_1, t_2 two terms (that do not use \text{dom}(\rho)) in normal form. If \delta^\rho_0(t_1) = \delta^\rho_0(t_2) then t_1 = t_2.

**Proof.** We prove the result by induction on |\delta^\rho_0(t_1)|.

Base case |\delta^\rho_0(t_1)| = 1: In such a case, we have that \delta^\rho_0(t_1) \in \mathcal{N} \cup \mathcal{X}. Assume first that \delta^\rho_0(t_1) \in \mathcal{X} and so \delta^\rho_0(t_2) \in \mathcal{X} by definition of \delta^\rho_0 and \delta^\rho_0. We can deduce that \delta^\rho_0(t_1) = t_1 and \delta^\rho_0(t_2) = t_2. Thus we conclude that t_1 = t_2. Assume now that \delta^\rho_0(t_1) \in \mathcal{N}. We need to distinguish two cases:

Case \delta^\rho_0(t_1) \in \text{dom}(\rho): By definition of \delta^\rho_0, \delta^\rho_0(t_1) \in \mathcal{N} implies that \delta^\rho_0(t_1) = t_1. But we assumed that t_1, t_2 do not use \text{dom}(\rho). Thus this case is impossible.

Case \delta^\rho_0(t_1) \not\in \text{dom}(\rho): Once again by definition of \delta^\rho_0, we have \delta^\rho_0(t_1) = t_1. Furthermore, since t_2 do not use \text{dom}(\rho) and \delta^\rho_0(t_2) \not\in \text{dom}(\rho), we also have that \delta^\rho_0(t_2) = t_2 by definition of \delta^\rho_0. Thus we conclude that t_1 = t_2.

Inductive step |\delta^\rho_0(t_1)| > 1: In such a case, we have that \delta^\rho_0(t_1) = f(u_1, \ldots, u_n) = \delta^\rho_0(t_2). Assume that f \in \mathcal{F}_{\rho} \cup \mathcal{F}_{\text{tag}_{\rho}}, with d \in \{a, b\}. By definition of \delta^\rho_0 and \delta^\rho_0, we can deduce that root(t_1) = f = root(t_2). Furthermore, if we assume that t_1 = f(v_1, \ldots, v_n) and t_2 = f(w_1, \ldots, w_n), we would have \delta^\rho_0(v_j) = \delta^\rho_0(w_j) for all j \in \{1, \ldots, n\}. By Lemma 5.3 we deduce that v_j = w_j for all j \in \{1, \ldots, n\}. Hence, we conclude that t_1 = t_2. Assume now that f \in \mathcal{F}_0. According to the definition of \delta^\rho_0 and \delta^\rho_0, there exists v_1, \ldots, v_n and w_1, \ldots, w_n such that t_1 = f(v_1, \ldots, v_n), t_2 = f(w_1, \ldots, w_n) and \delta^\rho_0(v_j) = \delta^\rho_0(w_j), for some k, \ell \in \{a, b\}. Moreover, t_1 and t_2 being in normal form and not using names in \text{dom}(\rho) imply that so are v_j and w_j for all j \in \{1, \ldots, n\}. Now, either k = \ell and so by Lemma 5.3 we have that v_j = w_j, else k \neq \ell but then by our inductive hypothesis, we also have v_j = w_j. Hence we conclude that t_1 = t_2.

\[\square\]

**Lemma 5.6.** Let u be a term in normal form that do no use \text{dom}(\rho). We have that for all i \in \{a, b\}, \delta^\rho_i(u) is in normal form and root(\delta^\rho_i(u)) = root(u).

**Proof.** We prove this result by induction on |u|.

Base case |u| = 1: In such a case, u \in \mathcal{X} \cup \mathcal{N}. If u \in \mathcal{X}, then for all i \in \{a, b\}, \delta^\rho_i(u) = u. Since u is in normal form then the result holds. If u \in \mathcal{N}, by definition, we also have that \delta^\rho_i(u) \in \mathcal{N} and so \delta^\rho_i(u) is in normal form with the same root as u, namely \perp.

Inductive |u| > 1: In this case, we have that u = C[u_1, \ldots, u_n] with u_1, \ldots, u_n factors of u. Assume first that C is built upon \mathcal{F}_0 \cup \mathcal{F}_{\text{tag}_0}, for some j \in \{a, b\}. Since u is in normal form, then for all position p of C, we have that u_{i\perp} \notin \text{img}(\rho) and so for all k \in \{a, b\}, \delta^\rho_i(u) = C[\delta^\rho_i(u_1), \ldots, \delta^\rho_i(u_n)]. By inductive hypothesis on u_1, \ldots, u_n, we have that \delta^\rho_i(u_1), \ldots, \delta^\rho_i(u_n) are in normal form and root(\delta^\rho_i(u_1), \ldots, \delta^\rho_i(u_n)) = root(u_1), \ldots, root(\delta^\rho_i(u_n)) = root(u_n), thus \delta^\rho_i(u_1), \ldots, \delta^\rho_i(u_n) are factors of \delta^\rho_i(u). Thus, since u is in normal form, by Lemmas 5.2 and 5.3, we have that \delta^\rho_i(u_{\perp}) = C[\delta^\rho_i(u_1), \ldots, \delta^\rho_i(u_n)] = \delta^\rho_i(u). Furthermore, we also have that root(\delta^\rho_i(u)) = root(u). Assume now that C is built upon \mathcal{F}_0. Thus, assume that u = f(v_1, \ldots, v_m). By definition of \delta^\rho_i and \delta^\rho_i, there exists j \in \{a, b\} such that \delta^\rho_i(u) = f(\delta^\rho_i(v_1), \ldots, \delta^\rho_i(v_m)). We do a case analysis on f:

Case f \in \{\text{send}, \text{aenc}, \text{pk}, \text{sign}, \text{vk}, \text{h}, \langle \rho \rangle\}: In this case, by the rewriting system \mathcal{O}_0, we have that \delta^\rho_i(v_j) = f(\delta^\rho_i(v_1), \ldots, \delta^\rho_i(v_{m_j})). Since by inductive hypothesis, \delta^\rho_i(v_k) is in normal form, for all k \in \{1, \ldots, m\}, we can deduce that \delta^\rho_i(u) is also in normal form and root(\delta^\rho_i(u)) = f = root(u).

Case f = \text{sdec}: Then by definition of \delta^\rho_i and \delta^\rho_i, we have that \delta^\rho_i(u) = \text{sdec}(\delta^\rho_i(v_1), \delta^\rho_i(v_2)), with j \in \{a, b\}. By inductive hypothesis, we have that \delta^\rho_i(v_1) and \delta^\rho_i(v_2) are both in normal form and have the same root as v_1 and v_2 respectively.

Assume first that \text{sdec} can not be reduced, i.e. \delta^\rho_i(u) = \text{sdec}(\delta^\rho_i(v_1), \delta^\rho_i(v_2)) and so \delta^\rho_i(u) = \text{sdec}(\delta^\rho_i(v_1), \delta^\rho_i(v_2)). Thus the result holds. Otherwise, if \text{sdec} can be reduced, it implies that there
exists $w_1, w_2$ such that $\delta^j_w(v_1) = \text{senc}(w_1, w_2)$ and $\delta^j_w(v_2) = w_2$. But by definition of $\delta^j_w$, there must exist $k \in \{a, b\}$, and $w'_1, w'_2$ such that $\delta^j_w(v_1) = \text{senc}(\delta^k_r(w'_1), \delta^k_r(w'_2))$, $v_1 = \text{senc}(w'_1, w'_2)$, $w_1 = \delta^k_r(w'_1)$ and $w_2 = \delta^k_r(w'_2)$. Thus, we have that $\delta^j_w(v_2) = \delta^k_r(w'_2)$. Thanks to Lemmas 5.4 and 5.5, we can conclude that $v_2 = w'_2$ and so $u = \text{sdec}(\text{senc}(w'_1, w'_2), w'_2)$. But in such a case, we would have that $u$ is not in normal form which contradicts our hypothesis.

Case $f = \text{check}$: Then by definition of $\delta^j_w$ and $\delta^j_u$, we have that $\delta^j_w(u) = \text{check}(\delta^j_w(v_1), \delta^j_w(v_2))$, with $j \in \{a, b\}$. By inductive hypothesis, we have that $\delta^j_w(v_1)$ and $\delta^j_w(v_2)$ are both in normal form and have the same root as $v_1$ and $v_2$ respectively.

Assume first that check cannot be reduced: this case is analogous to the sdec one and can be handled similarly. Otherwise, if check can be reduced, it implies that there exist $w_1, w_2$ such that $\delta^j_w(v_1) = \text{sign}(w_1, w_2)$ and $\delta^j_w(v_2) = \text{vk}(w_2)$. But by definition of $\delta^j_w$, there must exist $k \in \{a, b\}$, and $w'_1, w'_2$ such that $\delta^j_w(v_1) = \text{sign}(\delta^k_r(w'_1), \delta^k_r(w'_2))$, $v_1 = \text{sign}(w'_1, w'_2)$, $w_1 = \delta^k_r(w'_1)$ and $w_2 = \delta^k_r(w'_2)$. Thus, we have that $\delta^j_w(v_2) = \text{vk}(\delta^k_r(w'_2)) = \delta^k_r(\text{vk}(w'_2))$. Thanks to Lemmas 5.4 and 5.5, we can conclude that $v_2 = \text{vk}(w'_2)$ and so $u = \text{check}(\text{sign}(w'_1, w'_2), \text{vk}(w'_2))$. But in such a case, we would have that $u$ is not in normal form which contradicts our hypothesis.

Case $f = \text{adec}$: Then by definition of $\delta^j_w$ and $\delta^j_u$, we have that $\delta^j_w(u) = \text{adec}(\delta^j_w(v_1), \delta^j_w(v_2))$, with $j \in \{a, b\}$. By inductive hypothesis, we have that $\delta^j_w(v_1)$ and $\delta^j_w(v_2)$ are both in normal form and have the same root as $v_1$ and $v_2$ respectively.

Assume first that adec cannot be reduced: this case is analogous to the sdec one and can be handled similarly. Otherwise, if adec can be reduced, it implies that there exist $w_1, w_2$ such that $\delta^j_w(v_1) = \text{aenc}(w_1, \text{pk}(w_2))$ and $\delta^j_w(v_2) = w_2$. But by definition of $\delta^j_w$, there must exist $k \in \{a, b\}$, and $w'_1, w'_2$ such that $\delta^j_w(v_1) = \text{aenc}(\delta^k_r(w'_1), \text{pk}(\delta^k_r(w'_2)))$, $v_1 = \text{aenc}(w'_1, \text{pk}(w'_2))$, $w_1 = \delta^k_r(w'_1)$ and $w_2 = \delta^k_r(w'_2)$. Thus, we have that $\delta^j_w(v_2) = \delta^k_r(w'_2)$. Thanks to Lemmas 5.4 and 5.5, we can conclude that $v_2 = w'_2$ and so $u = \text{adec}(\text{aenc}(w'_1, \text{pk}(w'_2)), w'_2)$. But in such a case, we would have that $u$ is not in normal form which contradicts our hypothesis.

Lemma B.1. Let $\rho$ be a renaming of name of base type. Let $u$ be a term, $C$ a context (possibly a hole) built over $F_0$ and $v_1, \ldots, v_m$ terms such that $u = C[v_1, \ldots, v_m]$, $\{v_1, \ldots, v_m\} = \text{Fct}_{F_0}(u)$ and $\text{dom}(\rho)$ do not occur in $u$. If for all $i \in \{1, \ldots, m\}$, $v_i \neq \text{kp}$ for any $k \in \text{dom}(\rho)$, then we have that $\delta^j(u) = \delta^j_u(u)$.

Proof. We prove this lemma by induction on the syntactic size of $|C|$.

**Base case** $|C| = 0$ : In this case, $C$ is a hole which means that either $\text{root}(u) \notin F_0$, or $u$ is of the form $f(\text{tag}(u_1), u_2)$ with $f \in \{\text{senc}, \text{aenc}, \text{sign}\}$ and $i \in \{a, b\}$, or $u$ is of the form $h(\text{tag}(u_1))$ with $i \in \{a, b\}$. Remember that $u_i \neq \text{kp}$ for any $k \in \text{dom}(\rho)$. We do a case analysis on $u$ :

- **Case $u \in F_0$**: In such a case, since we assume that $u \neq \text{kp}$ for any $k \in \text{dom}(\rho)$, then by definition of $\delta^j_w$ and $\delta^j_u$, we have that $\delta^j_w(u) = \delta^j_u(u)$.
- **Case $u = f(u_1, \ldots, u_n)$ with $f \notin F_0$**: $f \notin F_0$ implies that $f \in F_d \cup F_{\text{tag}_d}$ with $d \in \{a, b\}$. Thus, by definition of $\delta^j_w$ and $\delta^j_u$, we have that $\delta^j_w(u) = f(\delta^j_w(u_1), \ldots, \delta^j_w(u_n)) = \delta^j_u(u)$.
- **Case $u = f(\text{tag}(u_1), u_2)$ with $d \in \{a, b\}$ and $f \in \{\text{senc}, \text{aenc}, \text{sign}\}$**: In that case, we have by definition of $\delta^j_w$ and $\delta^j_u$ that $\delta^j_w(u) = f(\text{tag}(\delta^j_w(u_1)), \delta^j_w(u_2)) = \delta^j_u(u)$.
- **Case $u = h(\text{tag}(u_1))$ with $d \in \{a, b\}$**: This case is analogous to the previous one and can be handled in a similar way.

**Inductive step** $|C| > 1$ : In this case, we know that $u = f(u_1, \ldots, u_n)$ with $f \in F_0$. But $|C| > 1$ also implies that for all $i \in \{1, \ldots, n\}$, there exists a sub context $C_i$ (possibly a hole) of $C$ such that $u_i = C_i[v'_1, \ldots, v'_m]$ and $\{v'_1, \ldots, v'_m\} = \text{Fct}_{F_0}(u_i)$. Note that $C_i$ is a sub context of $C$, then thanks to our hypothesis, we have that for all $j \in \{1, \ldots, m\}$, $v'_j \neq \text{kp}$ for any $k \in \text{dom}(\rho)$. Thus we can apply our inductive hypothesis and deduce that $\delta^j_w(u_i) = \delta^j_u(u_i)$. Since $C \neq \text{tag}_d$ and $f \in F_0$, it must be the case that $\text{root}(u_1) \neq \text{tag}_d$ for any $k \in \{a, b\}$, thus by definition of $\delta^j_w$ and $\delta^j_u$, since $\text{root}(u) \notin F_0$, we have that $\delta^j_w(u) = f(\delta^j_w(u_1), \ldots, \delta^j_w(u_n))$ and $\delta^j_u(u) = f(\delta^j_u(u_1), \ldots, \delta^j_u(u_n))$. Thanks to the previously established equalities $\delta^j_w(u_i) = \delta^j_u(u_i)$ for all $i \in \{1, \ldots, n\}$, we can conclude that $\delta^j_w(u) = \delta^j_u(u)$.
Lemma B.2. Let $i \in \{a,b\}$. Let $u \in \mathcal{T}(\mathcal{F}_i \cup \mathcal{F}_o, \mathcal{N} \cup \mathcal{X})$. Let $\alpha$ be a ground substitution such that $\text{fvars}(u) \subseteq \text{dom}(\alpha)$ and for all $x \in \text{dom}(\alpha)$, $\alpha x$ is in normal form. Let $\rho$ a renaming of names of base type such that $\text{dom}(\rho)$ do not occur in $u$ or $\alpha$. We have that:

- $\delta^i_{\nu}(\tau[u],\alpha) = \delta^i_{\nu}(\tau[\alpha],\delta^i_{\nu}(\alpha))$; and

Proof. We prove the two results separately. First of all, we show by induction on $|u|$ that

$$\delta^i_{\nu}(\tau[u],\alpha) = \delta^i_{\nu}(\tau[\alpha],\delta^i_{\nu}(\alpha))$$

Base case $|u| = 1$: In this case, $u \in \mathcal{N} \cup \mathcal{X}$. If $u \in \mathcal{N}$ then we have that $[u] = u$ and so $[u] \alpha = u$ and $\delta^i_{\nu}(u) \in \mathcal{N}$. Thus, we have that $\delta^i_{\nu}(\tau[u],\alpha) = \delta^i_{\nu}(u) \delta^i_{\nu}(\alpha) = \delta^i_{\nu}(\tau[u],\delta^i_{\nu}(\alpha))$. Else if $u \in \mathcal{X}$, then we also have that $[u] = u$ and $\delta^i_{\nu}(u) = u$. Thus, $\delta^i_{\nu}(u) \delta^i_{\nu}(\alpha) = u \delta^i_{\nu}(\alpha)$. Since $u \in \mathcal{X}$ and $\text{fvars}(u) \subseteq \text{dom}(\alpha)$, we have that $u \delta^i_{\nu}(\alpha) = \delta^i_{\nu}(\alpha u) = u \delta^i_{\nu}(\alpha) = \delta^i_{\nu}(u) \delta^i_{\nu}(\alpha) = \delta^i_{\nu}(\tau[u],\delta^i_{\nu}(\alpha))$.

Inductive step $|u| > 1$: In this case, $u = f(u_1, \ldots, u_n)$. We do a case analysis on $f$.

Case $f \in \mathcal{F}_i$: In such a case, we have that $[u] = f([u_1], \ldots, [u_n])$. But by definition of $\delta^i_{\nu}$, we have that $\delta^i_{\nu}(\tau[u],\alpha) = f(\delta^i_{\nu}(\tau[u_1],\alpha), \ldots, \delta^i_{\nu}(\tau[u_n],\alpha))$ and $\delta^i_{\nu}(\tau[u],\delta^i_{\nu}(\alpha)) = f(\delta^i_{\nu}(\tau[u_1],\delta^i_{\nu}(\alpha)), \ldots, \delta^i_{\nu}(\tau[u_n],\delta^i_{\nu}(\alpha)))$. By our inductive hypothesis, we can deduce that for all $k \in \{1, \ldots, n\}$, we have that $\delta^i_{\nu}(\tau[u_k],\alpha) = \delta^i_{\nu}(\tau[u_k],\delta^i_{\nu}(\alpha))$. Thus, $\delta^i_{\nu}(\tau[u],\alpha) = f(\delta^i_{\nu}(\tau[u_1],\alpha), \ldots, \delta^i_{\nu}(\tau[u_n],\alpha)) \delta^i_{\nu}(\alpha) = \delta^i_{\nu}(\tau[u],\delta^i_{\nu}(\alpha))$.

Case $f \in \{\text{anc}, \text{sign}, \text{senb}\}$: In this case $n = 2$, and by definition of $[u]$, we have that $[u] = f(\text{tag}_i([u_1]), [u_2])$. Thus, we have that $\delta^i_{\nu}(\tau[u],\alpha) = f(\delta^i_{\nu}(\tau[u_1],\alpha), \delta^i_{\nu}(\tau[u_2],\alpha))$ and $\delta^i_{\nu}(\tau[u],\delta^i_{\nu}(\alpha)) = f(\delta^i_{\nu}(\tau[u_1],\delta^i_{\nu}(\alpha)), \delta^i_{\nu}(\tau[u_2],\delta^i_{\nu}(\alpha)))$. But by our inductive hypothesis, we can deduce that $\delta^i_{\nu}(\tau[k],\alpha) = \delta^i_{\nu}(\tau[k],\delta^i_{\nu}(\alpha))$, for all $k \in \{1, 2\}$. Thus, $\delta^i_{\nu}(\tau[u],\alpha) = f(\delta^i_{\nu}(\tau[u_1],\delta^i_{\nu}(\alpha)), \delta^i_{\nu}(\tau[u_2],\delta^i_{\nu}(\alpha)))$ and so we conclude that $\delta^i_{\nu}(\tau[u],\alpha) = \delta^i_{\nu}(\tau[u],\delta^i_{\nu}(\alpha))$.

Case $f = \text{h}$: This case is analogous to the previous one and can be handled in a similar way.

Now we prove the second property, i.e. if $\alpha \equiv \text{test}_i([u_1])$, then $\delta^i_{\nu}(\tau[u_1],\alpha) = \delta^i_{\nu}(\tau[u_1],\alpha_\downarrow)$. Once again, we prove the results by induction on $|u|:

Base case $|u| = 1$: In this case, $u \in \mathcal{N} \cup \mathcal{X}$. In both cases, we have that $[u] = u$ and $\text{test}_i(u) = \text{true}$. If $u \in \mathcal{N}$, we know that $\delta^i_{\nu}(u) \in \mathcal{N}$ and so $\delta^i_{\nu}(u) \downarrow = \delta^i_{\nu}(u)$. But we also have that $u \alpha \downarrow = u \alpha = u$. Thus, we conclude that $\delta^i_{\nu}(u \alpha) \downarrow = \delta^i_{\nu}(u) \downarrow = \delta^i_{\nu}(u \alpha \downarrow)$. Else, if $u \in \mathcal{X}$, by hypothesis on $\alpha$, we deduce that $u \alpha \downarrow = u \alpha$. Furthermore, by Lemma 5.6 we also know that $\delta^i_{\nu}(u \alpha \downarrow) \downarrow = \delta^i_{\nu}(u \alpha \downarrow)$. Thus, we conclude that $\delta^i_{\nu}(u \alpha \downarrow) \downarrow = \delta^i_{\nu}(u \alpha \downarrow)$.

Inductive step $|u| > 1$: In this case, we have $u = f(u_1, \ldots, u_n)$. We do a case analysis on $f$.

Case $f \in \mathcal{F}_i$: In such a case, we have that $[u] = f([u_1], \ldots, [u_n])$. Hence, we deduce that $\delta^i_{\nu}(\tau[u_1],\alpha) = f(\delta^i_{\nu}(\tau[u_1],\alpha), \ldots, \delta^i_{\nu}(\tau[u_n],\alpha))$ and so $\delta^i_{\nu}(\tau[u_1],\alpha \downarrow) \downarrow = \delta^i_{\nu}(\tau[u_1],\alpha \downarrow) \downarrow = \delta^i_{\nu}(\tau[u_1],\alpha \downarrow) \downarrow = \delta^i_{\nu}(\tau[u_1],\alpha \downarrow) \downarrow = \delta^i_{\nu}(\tau[u_1],\alpha \downarrow) \downarrow = \delta^i_{\nu}(\tau[u_1],\alpha \downarrow) \downarrow = \delta^i_{\nu}(\tau[u_1],\alpha \downarrow) \downarrow$.

Let’s denote $t = f([u_1],\alpha \downarrow, \ldots, [u_n],\alpha \downarrow)$. We can assume that there exists a context $C$ built on $\mathcal{F}_i$ such that $t = C_{t_1, \ldots, t_m}$ with $C(t) = \{t_1, \ldots, t_m\}$ and $t_1, \ldots, t_m$ are in normal form. Thus, by Lemma 5.2 there exists a context $D$ (possibly a hole) such that $t \downarrow = D[t_{j_1}, \ldots, t_{j_k}]$.
with \( j_1, \ldots, j_k \in \{0, \ldots, m\} \) and \( t_0 = n_{\text{min}} \). But since \( t_1, \ldots, t_m \) are all in normal form and thanks to Lemma 5.3, we know that for all \( k \in \{0, \ldots, m\} \), \( \delta_i^k(t_k) \) is also in normal form and its root is not in \( F_i \). Moreover, we can apply Lemma 5.3 such that \( C[\delta_i^k(t_1), \ldots, \delta_i^k(t_k)] = D[\delta_i^k(t_1), \ldots, \delta_i^k(t_k)] \). But since \( C \) and \( D \) are both built upon \( F_i \), we have that \( C[\delta_i^k(t_1), \ldots, \delta_i^k(t_k)] = \delta_i^k(C[t_1, \ldots, t_k]) \), and \( D[\delta_i^k(t_1), \ldots, \delta_i^k(t_k)] = \delta_i^k(D[t_1, \ldots, t_k]) \). Hence, we can deduce that \( \delta_i^k(t) \downarrow = \delta_i^k(t) \downarrow \). But we already know that \( t_\downarrow = [u_i]_\alpha \downarrow \) and \( \delta_i^k(t) \downarrow = \delta_i^k([u_i]_\alpha) \downarrow \). Thus, we can conclude that \( \delta_i^k([u_i]_\alpha) \downarrow = \delta_i^k([u_i]_\alpha) \downarrow \).

Case \( f \in \{ \text{senc, aenc, sign} \} \): In such a case, we have that \([u_i]_{\downarrow} = f(\text{tag}_{\downarrow}([u_i]_{\downarrow}), [u_2]_{\downarrow}) \) and \( \text{test}_{\downarrow}([u_i]_{\downarrow}) = \text{test}_{\downarrow}([u_i]_{\downarrow}) \wedge \text{test}_{\downarrow}([u_2]_{\downarrow}) \). By definition of the rewriting system \( O_\downarrow \), we have that \([u_i]_{\downarrow} = f(\text{tag}_{\downarrow}([u_i]_{\downarrow}, [u_2]_{\downarrow}) \). Moreover, \( \delta_i^k([u_i]_{\downarrow}) = f(\text{tag}_{\downarrow}([u_2]_{\downarrow}), [u_2]_{\downarrow}) \) and so we have \( \delta_i^k([u_2]_{\downarrow}, [u_2]_{\downarrow}) \). By our inductive hypothesis on \( u_1 \) and \( u_2 \), we have that \( \delta_i^k([u_2]_{\downarrow}, [u_2]_{\downarrow}) = \delta_i^k([u_2]_{\downarrow}, [u_2]_{\downarrow}) \), for \( k \in \{1, 2\} \). Hence, we can deduce that \( \delta_i^k([u_i]_{\downarrow}) = f(\text{tag}_{\downarrow}([u_i]_{\downarrow}), [u_2]_{\downarrow}) \downarrow \downarrow \). Thus, \( \delta_i^k([u_i]_{\downarrow}) = \delta_i^k([u_i]_{\downarrow}) \downarrow \downarrow \).

Case \( f = h \): This case is analogous to the previous one and can be handled in a similar way.

Case \( f \in \{ \text{pk, vk, } () \} \): In this case, we have that \([u_i]_{\downarrow} = f([u_i], [u_i], [u_i]_{\downarrow}) \) with \( n \in \{1, 2\} \), and \( \text{test}_{\downarrow}([u_i]_{\downarrow}) = \text{test}_{\downarrow}([u_i]_{\downarrow}) \). By definition of \( O_\downarrow \), we have that \([u_i]_{\downarrow} = f([u_1], [u_1], [u_2], [u_2]) \). Thus, this case is similar to the senc case and can be handled similarly.

Case \( f \in \{ \text{sdec, adec, check} \} \): In such a case, we have that \([u_i]_{\downarrow} = \text{untag}_{\downarrow}([u_1]_{\downarrow}), [u_2]_{\downarrow}) \) and \( \text{test}_{\downarrow}([u_i]_{\downarrow}) = \text{test}_{\downarrow}([u_i]_{\downarrow}) \wedge \text{test}_{\downarrow}([u_2]_{\downarrow}) \). By hypothesis, we know that \( \alpha \vdash \text{test}_{\downarrow}([u_i]_{\downarrow}) \), thus \( \text{tag}_{\downarrow}([u_1]_{\downarrow}), [u_2]_{\downarrow})_{\downarrow} = f([u_1], [u_2])_{\downarrow} \). Hence, we deduce that the root function symbol \( f \) can be reduced and the root symbol of the plain text is \( \text{tag}_{\downarrow}([u_i]_{\downarrow}) \), i.e. there exists \( v_1, v_2 \) such that

- \( f = \text{sdec} \) then \([u_i]_{\downarrow} = \text{senc}_{\downarrow}([v_1]_{\downarrow}), [v_2]_{\downarrow}) ), \([u_2]_{\downarrow} = v_2 \) and \([u_i]_{\downarrow} = v_1 \). It implies that \( \delta_i^k([u_i]_{\downarrow}) = \text{senc}_{\downarrow}([v_1]_{\downarrow}), [v_2]_{\downarrow}) ) \downarrow \downarrow \) and so we can deduce that \( \delta_i^k([u_2]_{\downarrow}) = \delta_i^k([v_1]_{\downarrow}) \downarrow \downarrow \).

- \( f = \text{adev} : [u_i]_{\downarrow} = \text{aenc}_{\downarrow}([v_1]_{\downarrow}), [v_2]_{\downarrow}) ), \([u_2]_{\downarrow} = v_2 \) and \([u_i]_{\downarrow} = v_1 \). It implies that \( \delta_i^k([u_2]_{\downarrow}) = \text{aenc}_{\downarrow}([v_1]_{\downarrow}), [v_2]_{\downarrow}) ) \downarrow \downarrow \) and so we can deduce that \( \delta_i^k([u_2]_{\downarrow}) = \delta_i^k([v_1]_{\downarrow}) \downarrow \downarrow \).

- \( f = \text{check} : [u_i]_{\downarrow} = \text{sign}_{\downarrow}([v_1]_{\downarrow}), [v_2]_{\downarrow}) ), \([v_2]_{\downarrow} = v_2 \) and \([u_i]_{\downarrow} = v_1 \). It implies that \( \delta_i^k([u_2]_{\downarrow}) = \text{sign}_{\downarrow}([v_1]_{\downarrow}), [v_2]_{\downarrow}) ) \downarrow \downarrow \) and so we can deduce that \( \delta_i^k([u_2]_{\downarrow}) = \delta_i^k([v_1]_{\downarrow}) \downarrow \downarrow \).

In all cases, the following equality holds: \( \text{untag}_{\downarrow}(f([u_1]_{\downarrow}), [u_2]_{\downarrow})_{\downarrow} = \delta_i^k([u_1]_{\downarrow})_{\downarrow} \). But by inductive hypothesis, we know that \( \delta_i^k([u_2]_{\downarrow})_{\downarrow} = \delta_i^k([u_2]_{\downarrow})_{\downarrow} \), for \( k \in \{1, 2\} \). Thus, we also have that \( \delta_i^k([u_2]_{\downarrow})_{\downarrow} = \text{untag}_{\downarrow}(f([u_1]_{\downarrow}), [u_2]_{\downarrow})_{\downarrow} = \text{untag}_{\downarrow}(f([u_1]_{\downarrow}), [u_2]_{\downarrow})_{\downarrow} \). Thus, we can conclude that \( \delta_i^k([u_2]_{\downarrow})_{\downarrow} = \delta_i^k([u_1]_{\downarrow})_{\downarrow} \).
Proof. Thanks to Lemma 5.3, \([u_i]_\alpha \downarrow = [v_j]_\alpha \downarrow\) is equivalent to \(\delta_\alpha^\delta([u_i]_\alpha \downarrow) = \delta_\alpha^\delta([v_j]_\alpha \downarrow)\). But thanks to Lemma 13.2, we have that \(\delta_\alpha^\delta([u_i]_\alpha \downarrow) = \delta_\alpha^\delta([u_i],\alpha \downarrow) = \delta_\alpha^\delta([u_i],\delta_\alpha^\delta(\alpha \downarrow)\). Thus, the result holds.

Lemma B.3. Let \(i \in \{a, b\}\). Let \(u, v \in T(F_i \cup F_0, \mathcal{N} \cup \mathcal{X})\). Let \(\alpha\) be a ground substitution such that \(\text{fvars}(u) \subseteq \text{dom}(\alpha)\) and for all \(x \in \text{dom}(\alpha), x\alpha\) is in normal form. Let \(\rho\) a renaming of names of base type such that \(\text{dom}(\rho)\) do not occur in \(u, v\) or \(\alpha\). We have that:

\[
\alpha \models \text{test}_i([u_i]) \text{ is equivalent to } \delta_\alpha^\delta(\alpha \vdash \text{test}_i([u_i]))
\]

Proof. We prove this result by induction on \(|u|\):

Base case \(|u| = 1\): In this case, we have that \(u \in \mathcal{N} \cup \mathcal{X}\), and thus \([u_i], \delta_\alpha^\delta([u_i]) \in \mathcal{N} \cup \mathcal{X}\). But then by definition, \(\text{test}_i([u_i]) = \text{true}\) and \(\text{test}_i(\delta_\alpha^\delta([u_i])) = \text{true}\). Thus the result trivially holds.

Inductive step \(|u| > 1\): Then, we have that \(u = f(u_1, \ldots, u_n)\). We do a case analysis on \(f\):

Case \(f \in \{\text{f} \downarrow\}:\) In this case, we have that \([u_i] = f([u_1], \ldots, [u_n])\) and \(\delta_\alpha^\delta([u_i]) = f(\delta_\alpha^\delta([u_1]), \ldots, \delta_\alpha^\delta([u_n])).\) Thus, we deduce that \(\text{test}_i([u_i]) = \Lambda_{i=1}^n \text{test}_i([u_i])\) and \(\text{test}_i(\delta_\alpha^\delta([u_i])) = \Lambda_{i=1}^n \text{test}_i(\delta_\alpha^\delta([u_i])).\) By inductive hypothesis on \(u_1, \ldots, u_n\), the result holds.

Case \(f \in \{\text{s}, \text{a}, \text{c}\}:\) In this case, we have that \([u_i] = \text{untag}_i(f([u_1], [u_2]))\) and \(\delta_\alpha^\delta([u_i]) = \text{untag}_i(\delta_\alpha^\delta(f([u_1], [u_2]))).\) Thus, we deduce that:

\[
\text{test}_i([u_i]) = \text{test}_i([u_1]) \land \text{test}_i([u_2]) \land \text{tag}_i(\text{untag}_i(f([u_1], [u_2]))) = f([u_1], [u_2])
\]

\[
\text{test}_i(\delta_\alpha^\delta([u_i])) = \text{test}_i(\delta_\alpha^\delta([u_1])) \land \text{test}_i(\delta_\alpha^\delta([u_2])) \land \text{tag}_i(\text{untag}_i(f(\delta_\alpha^\delta([u_1]), \delta_\alpha^\delta([u_2])))) = f(\delta_\alpha^\delta([u_1]), \delta_\alpha^\delta([u_2]))
\]

Whether we assume that \(\alpha \vdash \text{test}_i([u_i])\) or \(\alpha \vdash \text{test}_i(\delta_\alpha^\delta([u_i]))\), we have by inductive hypothesis that \(\alpha \vdash \text{test}_i([u_k])\) for \(k \in \{1, 2\}\). Thus by Lemma 13.2 it implies that \(\delta_\alpha^\delta([u_k], \alpha \downarrow) = \delta_\alpha^\delta([u_k], \delta_\alpha^\delta(\alpha \downarrow), \alpha \downarrow)\), for \(k \in \{1, 2\}\). We do a case analysis on \(f\):

\[
f = \text{sd}: \alpha \vdash \text{tag}_i(\text{untag}_i(f([u_1], [u_2]))) = f([u_1], [u_2])\) is equivalent to there exists \(v_1, v_2\) such that \([u_1]_\alpha \downarrow = \text{tag}_i(\text{untag}_i(f([u_1], [u_2]))) = [v_1]_\alpha \downarrow\) and \([u_2]_\alpha \downarrow = v_2;\) But by Lemma 5.3, it is equivalent to \(\delta_\alpha^\delta([u_k], \alpha \downarrow) = \text{tag}_i(\text{untag}_i(f([u_1], [u_2]))) = f([u_1], [u_2])\) and \(\delta_\alpha^\delta([u_k], \alpha \downarrow) = \delta_\alpha^\delta(\text{untag}_i(f([u_1], [u_2])))\). Thus, it is equivalent to \(\delta_\alpha^\delta([u_1], \alpha \downarrow) = \text{untag}_i(f([u_1], [u_2]))\) and \(\delta_\alpha^\delta([u_2], \alpha \downarrow) = \delta_\alpha^\delta(\text{untag}_i(f([u_1], [u_2])))\). Hence it is equivalent to \(\delta_\alpha^\delta(\alpha \downarrow) = \text{untag}_i(f([u_1], [u_2]))\) and \(\delta_\alpha^\delta([u_k], \alpha \downarrow) = \delta_\alpha^\delta(\text{untag}_i(f([u_1], [u_2])))\). Thus, we deduce that:

\[
\text{test}_i([u_i]) = \text{test}_i([u_1]) \land \text{test}_i([u_2]) \land \text{untag}_i(f([u_1], [u_2])) = f([u_1], [u_2])
\]

\[
\text{test}_i(\delta_\alpha^\delta([u_i])) = \text{test}_i(\delta_\alpha^\delta([u_1])) \land \text{test}_i(\delta_\alpha^\delta([u_2])) \land \text{untag}_i(f(\delta_\alpha^\delta([u_1]), \delta_\alpha^\delta([u_2]))) = f(\delta_\alpha^\delta([u_1]), \delta_\alpha^\delta([u_2]))
\]

Whether we assume that \(\alpha \vdash \text{test}_i([u_i])\) or \(\alpha \vdash \text{test}_i(\delta_\alpha^\delta([u_i]))\), we have by inductive hypothesis that \(\alpha \vdash \text{test}_i([u_1])\). Thus by Lemma 13.2 it implies that \(\delta_\alpha^\delta([u_1], \alpha \downarrow) = \delta_\alpha^\delta([u_1], \delta_\alpha^\delta(\alpha \downarrow))\).

But \(\alpha \vdash \text{proj}_i([u_1]), \text{proj}_2([u_1]) = [u_1],\) is equivalent to there exists \(v_1, v_2\) such that \([u_1]_\alpha \downarrow = \langle v_1, v_2 \rangle,\) which is equivalent to \(\delta_\alpha^\delta([u_1], \alpha \downarrow) = \delta_\alpha^\delta([v_1], \alpha \downarrow)\) thanks to Lemma 5.3. We showed that it is equivalent to \(\delta_\alpha^\delta([u_1]) \delta_\alpha^\delta(\alpha \downarrow) = \delta_\alpha^\delta([v_1], \alpha \downarrow),\) which allows us to conclude that \(\alpha \vdash \text{proj}_i([u_1]), \text{proj}_2([u_1]) = [u_1],\) is equivalent \(\delta_\alpha^\delta(\alpha \downarrow) \vdash \text{proj}_i([u_1]), \text{proj}_2([u_1])) = \delta_\alpha^\delta([u_1]).\)
B.1. PRELIMINARIES

We are now focus on the message that will be send the network during the execution of the processes. For a term $u$ that does not contain any tag, we defined in Section 5.1 a way to construct a term that is properly tagged (i.e. $[u_i]$). Hence, for a term properly tagged, we would never have $\text{senc}(n, k)$ where $n$ and $k$ are both nonces, for example. Instead, we would have $\text{senc}(\text{tag}_u(n), k)$. However, even if we can force the processes to properly tag their term, we do not have any control on what the intruder can build. Typically, if the intruder is able to deduce $n$ and $k$, he is allowed to send to a process the term $\text{senc}(n, k)$. Similarly, while we can restrict our processes to only apply $\text{vk}$ and $\text{pk}$ on a nonce, we can not restrict the intruder from using those cryptographic primitive with terms different from a nonce.

Thus, we define the notion of flawed tagged subterm of a term.

Definition B.1. Let $u$ be a ground term in normal form. We define the flawed tagged subterm of $u$, denoted Flawed$(u)$, is the set of subterms $v$ in $st(u)$ such that either:

- $v = f(u_1, u_2)$ with $f \in \{\text{senc}, \text{aenc}, \text{sign}\}$ and $\text{root}(u_1) \notin \{\text{tag}_u, \text{tag}_b\}$ for some $u_1, u_2$; or
- $v = f(u)$ with $f \in \{\text{pk}, \text{vk}\}$ and $u \notin \mathcal{N}$ for some $u$; or
- $v = f(u_1, \ldots, u_n)$ with $f \in \{\text{sdec}, \text{aenc}, \text{check}, \text{proj}_1, \text{proj}_2\}$ for some $u_1, \ldots, u_n$.

Note that all subterm with a destructor is considered as flawed. Indeed, we saw in Section 5.1 that a process $P_A$ tagged with the tag $a$ may output the instantiation of $[a_i]$, only if it satisfies the the instantiation of the conditional $\text{test}_{[a_i]}(\alpha)$. But as already mentioned in Subsection 5.1.1.2, $\text{test}_{[a_i]}(\alpha)$ verifies that the computation done by $P_A$ on $[a_i]$ succeed properly, i.e. the destructors from $\text{sdec}, \text{aenc}, \text{check}, \text{proj}_1, \text{proj}_2, \text{untag}_u, \text{untag}_v$ are reduced before sending the instantiation of $[a_i]$ over the network. But once again, we cannot restrict the intruder from misusing those cryptographic primitives. Thus, he is allowed to send $\text{sdec}(n, k)$ to a process. Hence, to sum up, Flawed$(u)$ represents all the subterm of $u$ that the intruder is sure to have computed (he may have computed more that Flawed$(u)$).

Example B.1. Consider the term $u = \langle\text{tag}_u(\text{proj}_1(\text{sdec}(n, k), k), \text{aenc}(a, \text{pk}(\langle k, k' \rangle)))\rangle$. We have that $u$ is in normal form and

\[
\text{Flawed}(u) = \{\text{proj}_1(\text{sdec}(n, k)); \text{sdec}(n, k); \text{aenc}(a, \text{pk}(\langle k, k' \rangle)); \text{proj}(\langle k, k' \rangle)\}
\]

We formalise the property that any flawed subterm has to be computed by the intruder with the following result:

Lemma B.4. Let $i \in \{a, b\}$. Let $u \in \mathcal{T}(\mathcal{F}_i \cup \mathcal{F}_o, \mathcal{N} \cup \mathcal{X})$ such that for all $v \in st(u)$, $\text{root}(v) = f$ with $f \in \{\text{pk, vk}\}$ implies that there exists $v' \in \mathcal{N}$ such that $v = f(v')$. Let $\alpha$ be a ground substitution such that $\text{fvars}(u) \subseteq \text{dom}(\alpha)$ and for all $x \in \text{dom}(\alpha)$, $x\alpha$ is in normal form. We have that if $\alpha \models \text{test}_{[u_i]}(\alpha)$ then for all $t \in \text{Flawed}([u_i], \alpha\downarrow)$, there exists $x \in \text{fvars}([u_i])$ such that $t \in \text{Flawed}(x\alpha)$.

Proof. We prove the result by induction on $|u|$.

Base case $|u| = 1$: In this case, we have that $u \in \mathcal{X} \cup \mathcal{N}$ and so $[u_i] = u$. If $u \in \mathcal{N}$, then $u \alpha \in \mathcal{N}$ and $[u_i] \alpha \downarrow \in \mathcal{N}$, which means that Flawed$(u_i, \alpha\downarrow) = 0$. Thus the results holds. Else $u \in \mathcal{X}$ and so $[u_i] = u \in \text{dom}(\alpha)$ which means that the result trivially holds.

Inductive step $|u| > 1$: Then, $u = f(u_1, \ldots, u_n)$. We do a case analysis on $f$.

Case $f \in \mathcal{F}_i$: In this case, $[u_i] = f([u_1], \ldots, [u_n])$ and $[u_i] \alpha \downarrow = f([u_1] \alpha \downarrow, \ldots, [u_n] \alpha \downarrow)$. By definition, we know that for all $t \in \text{Flawed}([u_i] \alpha \downarrow)$, $\text{root}(t) \notin \mathcal{F}_o \cup \mathcal{F}_b$. Thus, thanks to Lemma B.2, we can deduce that for all $t \in \text{Flawed}([u_i] \alpha \downarrow)$, there exists $k \in \{1, \ldots, n\}$ such that $t \in \text{Flawed}([u_k], \alpha \downarrow)$. By hypothesis, $\alpha \models \text{test}_{[u_k]}(\alpha)$ and so $\alpha \models \text{test}_{[u_k]}(\alpha)$. Thus, by inductive hypothesis, we know that there exists $x \in \text{fvars}([u_k])$ such that $t \in st(x\alpha)$. But $x \in \text{fvars}([u_k])$ implies $x \in \text{fvars}([u_i])$, thus the result holds.

Case $f \in \{\text{senc}, \text{aenc}, \text{sign}\}$: In this case, $[u_i] = f([u_1], [u_2])$. Furthermore, $[u_i] \alpha \downarrow = f([\text{tag}_u([u_1], [u_2]) \alpha \downarrow]$, $[u_i] \alpha \downarrow$. At last, $\alpha \models \text{test}_{[u_i]}(\alpha)$ implies that $\alpha \models \text{test}_{[u_k]}(\alpha)$, for all $k = 1, 2$. But,
by definition, Flawed([u]_1, α↓) = Flawed([u]_1, α↓) ∪ Flawed([u]_2, α↓) and so by our inductive hypothesis on u_1 and u_2, the result holds.

Case f = h: This case is analogous to the previous one and can be handled in a similar way.

Case f = h: In this case, [u]_1 = f([u]_1, [u]_2). Furthermore, [u]_2, α↓ = f([u]_1, α↓, [u]_2, α↓).

At last, α ⊨ test,([u]_i) implies that α ⊨ test,([u]_i), for all k = 1, 2. But, by definition, Flawed([u]_1, α↓) = Flawed([u]_1, α↓) ∪ Flawed([u]_2, α↓) and so by our inductive hypothesis on u_1 and u_2, the result holds.

Case f = {vk, pk}: In this case, we know by hypothesis that u = f(v) with v ∈ N. Thus [u]_1 = u and Flawed(u) = ∅. Thus the result trivially holds.

Case f ∈ {sdec, adec, check}: In this case, we have that [u]_i = untag, f([u]_1, [u]_2) and test,([u]_i) = test,([u]_1, α↓) ∧ test,([u]_2, α↓) ∧ tag, untag,([u]_i) = [u]_i. But by hypothesis, we know that α ⊨ test,([u]_i) and more specifically tag, untag,([u]_i)α↓ = [u]_1α↓. It implies that there exists v_1, v_2 such that [u]_1α↓ = g(tag, (v_1), v_2) and [u]_2α↓ = v_1, with g ∈ {senc, aenc, sign}. Thus, for all t ∈ Flawed([u]_1, α↓), t ∈ Flawed([u]_1, α↓). Since α ⊨ test,([u]_i), the result holds by inductive hypothesis.

Case f = proj, j ∈ {1, 2}: In this case, we have that [u]_i = f([u]_i, α↓) and test,([u]_i) = test,([u]_1, j) ∧ test,([u]_2, j) = [u]_i. Hence, α ⊨ test,([u]_i) implies that there exist v_1, v_2 such that [u]_1α↓ = v_1, v_2) and [u]_2α↓ = v_1, Thus, for all t ∈ Flawed([u]_1, α↓), t ∈ Flawed([u]_1, α↓). Since α ⊨ test,([u]_i) by hypothesis, our inductive hypothesis allows us to conclude.

**Corollary B.2.** Let i ∈ {a, b}. Let u ∈ T(F, ∪ F_0, N ∪ X) such that for all v ∈ st(u), root(v) = f with f ∈ {pk, vk} implies that there exists v' ∈ N such that v = f(v'). Let α be a ground substitution such that fears(u) ⊆ dom(α) and for all x ∈ dom(α), xα is in normal form. Let ρ a renaming of names of base type such that dom(ρ) do not occur in u or α. We have that if δα^ρ(u) = test, δα^ρ([u]_1), there exists x ∈ fears(δα^ρ([u]_1)) such that t ∈ Flawed(xδα^ρ([u]_1)).

**Proof (sketch).** This result is a corollary of Lemma [B.4]. Actually, this can be proved in a similar way since the transformation δα^ρ does not change the structure of the term.

We use the previous Lemmas to prove some properties on well-tagged frames. Let (E; P; Φ) be a closed intermediate process such that Φ = {ax_1 ⊢ u_1, ..., ax_n ⊢ u_n}. We define a lexicographic measure on terms M, denoted M(M), where fears(M) ⊆ dom(Φ) and fnames(M) ∩ E = ∅ such that M(M) = (max{i | ax_i ∈ fars(M)}, |M|).

**Lemma B.5.** Let (E; P; Φ) be a closed intermediate process such that νE.Φ is well-tagged. Let’s denote Φ = {ax_1 ⊢ u_1; ..., ax_n ⊢ u_n}. We have that for all i ∈ {1, ..., n}, for all t ∈ Flawed(u_i↓), there exists M such that fears(M) ⊆ {ax_1, ..., ax_{i-1}}, fames(M) ∩ E = ∅ and t ∈ Flawed(M)↓.

**Proof.** We prove this result for any ground term u well-tagged up to ax_i, i ∈ {1, ..., n}. By definition, u being well-tagged up to ax_i, i ∈ {1, ..., n} implies that there exists a term v, a substitution α and c ∈ {a, b} such that:

- for all vk(t), pk(t') ∈ st(v), t, t' ∈ N
- u = [v]_c, α; and
- α ⊨ test,([v]_c); and
- for all x ∈ dom(α), either v is not a variable and xα is well-tagged up to ax_i; or there exists M such that fears(M) ⊆ {ax_1, ..., ax_{i-1}}, fames(M) ∩ E = ∅ and MΦ = xα.

The proof is done by induction on |u|.

**Base case |u| = 1:** In this case, u ∈ N which implies u↓ = u, and thus by definition Flawed(u↓) = ∅. Hence the result trivially holds.

**Inductive step |u| > 1:** Let t ∈ Flawed(u↓). Since for all vk(t), pk(t') ∈ st(v), t, t' ∈ N, and u = [v]_c, α and α ⊨ test,([v]_c), we can apply Lemma [B.3] to v and α↓. Thus, we have that there
exists $x \in \text{fvargs}(\alpha')$ such that $t \in \text{Flawed}(\alpha x)$. But since $u$ is well-tagged up to $\alpha x$, we know that either (a) there exists $M$ such that $\text{fvargs}(M) \subseteq \{x\alpha_1, \ldots, x\alpha_{m-1}\}$, $\text{fnames}(M) \cap \mathcal{E} = \emptyset$ and $M\Phi = \alpha x$. Hence $t \in \text{Flawed}(\alpha x) = \text{Flawed}(M\Phi)$ and so the result holds in such a case.

Or, (b) $v$ is not a variable and thus neither is $[v]_\alpha$. Moreover, $\alpha x$ is well-tagged up to $\alpha x$. Now because $v$ is not a variable and $x \in \text{fvargs}([v]_\alpha)$, we have that $|\alpha x| < |[v]_\alpha| = |u|$, we conclude by applying our inductive hypothesis. 

\begin{lemma}
\textbf{Lemma B.6.} Let $(\mathcal{E}, \mathcal{P}, \Phi)$ be a closed intermediate process such that $\nu\mathcal{E}\Phi$ is well-tagged. We have that for all $M$ such that $\text{fnames}(M) \cap \mathcal{E} = \emptyset$ and $\text{fvargs}(M) \subseteq \text{dom}(\Phi)$, for all $f(t_1, \ldots, t_n) \in \text{Flawed}(M\Phi)$, there exists $M_1, \ldots, M_n$ such that $\text{fvargs}(M_i) \subseteq \text{dom}(\Phi)$, $\text{fnames}(M_i) \cap \mathcal{E} = \emptyset$, $M_i\Phi = t_i$, and $M(M_i) < M(M_i') < M(M)$, for all $i \in \{1, \ldots, n\}$.
\end{lemma}

\textbf{Proof.} We prove this result by induction on $M(M)$.

\textbf{Base case $M(M) = (0, 0)$:} A term with $|M| = 0$ is impossible so the result trivially holds.

\textbf{Inductive step $M(M) = (i, 1)$:} In this case, either we have that $M \in \mathcal{N}$ or $M = \alpha x$. If $M \in \mathcal{N}$, then we have $M\Phi = M \in \mathcal{N}$ and $\text{Flawed}(M\Phi) = \emptyset$. Thus the result holds. If $M = \alpha x$, then by Lemma \ref{lem:tagcheck}, for all $f(t_1, \ldots, t_m) \in \text{Flawed}(\alpha x)$, there exists $M'$ such that $\text{fvargs}(M') \subseteq \{\alpha_1, \ldots, \alpha_{m-1}\}$, $\text{fnames}(M') \cap \mathcal{E} = \emptyset$ and $f(t_1, \ldots, t_m) \in \text{Flawed}(M\Phi)$. But $M(M') < M(M)$, thus by our inductive hypothesis, we can deduce that there exists $M_1, \ldots, M_m$ such that $\text{fvargs}(M_i) \subseteq \Phi$, $\text{fnames}(M_i) \cap \mathcal{E} = \emptyset$, $M_i\Phi = t_i$ and $M(M_i) < M(M_i') < M(M)$, for all $i \in \{1, \ldots, m\}$. Hence the result holds.

\textbf{Case $f = \ell$:} In this case, $M\Phi = f(M_1\Phi, \ldots, M_n\Phi)$. Furthermore by definition, we have $\text{Flawed}(M\Phi) = \text{Flawed}(M_1\Phi) \cup \text{Flawed}(M_2\Phi)$. Since $M(M_1) < M(M)$, $M(M_2) < M(M)$ and $t \in \text{Flawed}(M_1\Phi) \cup \text{Flawed}(M_2\Phi)$, we conclude by applying our inductive hypothesis on $M_1$ (or $M_2$).

\textbf{Case $f \in \{pk, vk\}$:} In this case, $M\Phi = f(M_1\Phi)$. If $M_1\Phi \in \mathcal{N}$, then we have that $\text{Flawed}(M\Phi) = \emptyset$, else $\text{Flawed}(M\Phi) = \{M_1\Phi\} \cup \text{Flawed}(M_1\Phi)$. If $t = M_1\Phi$, then we have $t_1 = M_1\Phi$. Since $M(M_1) < M(M)$, then the result holds; else we conclude by applying our inductive hypothesis on $M_1$.

\textbf{Case $f \in \{\text{senc}, \text{aenc}, \text{sign}\}$:} In such a case, $M\Phi = f(M_1\Phi, M_2\Phi)$. We need to distinguish if $\text{root}(M_1\Phi) \in \{\text{tag}_{\text{aenc}}, \text{tag}_{\text{senc}}\}$ or not.

If $\text{root}(M_1\Phi) \in \{\text{tag}_{\text{aenc}}, \text{tag}_{\text{senc}}\}$, then there exists $\ell \in \{a, b\}$ and $u_1$ such that $M_1\Phi = \text{tag}_{\ell}(u_1)$. Thus, as before, we define that $\text{Flawed}(M\Phi) = \text{Flawed}(\text{tag}_{\ell}(u_1) \cup \text{Flawed}(M_2\Phi))$. Thus, $t \in \text{Flawed}(M\Phi)$ implies that $t \in \text{Flawed}(M_1\Phi)$ or $t \in \text{Flawed}(M_2\Phi)$. Since $M(M_1) < M(M)$ and $M(M_2) < M(M)$, we conclude by applying our inductive hypothesis on $M_1$ or $M_2$.

Else $\text{root}(M_1\Phi) \notin \{\text{tag}_{\text{aenc}}, \text{tag}_{\text{senc}}\}$. In such a case, we have that $\text{Flawed}(M\Phi) = \text{Flawed}(M_1\Phi) \cup \text{Flawed}(M_2\Phi)$. If $t = M_1\Phi$, we have that $t_1 = M_1\Phi, t_2 = M_2\Phi$ and $M(M_1) < M(M)$, $M(M_2) < M(M)$. Thus the result holds. If $t \in \text{Flawed}(M_1\Phi) \cup \text{Flawed}(M_2\Phi)$, we conclude by applying our inductive hypothesis on $M_1$ or $M_2$.

\textbf{Case $f = h$:} This case is analogous to the previous one and can be handled similarly.

\textbf{Case $f \in \{\text{sdex}, \text{aex}, \text{check}\}$:} For all those functions, we have to distinguish two cases: Either $f$ is reduced in $M\Phi$, or not.
If $f$ is not reduced, then we have that $M \Phi \downarrow = f(M \downarrow_1, M \downarrow_2)$. By definition we have that

$\text{Flawed}(M \Phi \downarrow) = \{M \Phi \downarrow\} \cup \text{Flawed}(M_1 \Phi \downarrow) \cup \text{Flawed}(M_2 \Phi \downarrow)$. Thus if $t = M \Phi \downarrow$, we have that

$t_1 = M_1 \Phi \downarrow, t_2 = M_2 \Phi \downarrow$ and $M(M_1) < M(M), M(M_2) < M(M)$. Therefore the result holds.

Else if $t \in \text{Flawed}(M_1 \Phi \downarrow)$ or $t \in \text{Flawed}(M_2 \Phi \downarrow)$, since $M(M_1) < M(M), M(M_2) < M(M)$, we can conclude by applying our inductive hypothesis on $M_1$ or $M_2$.

If $f$ is reduced, then we have that $M_1 \Phi \downarrow = f'(u_1, u_2)$ with $M \Phi \downarrow = u_1$ and $f' \in \{\text{senc, aenc, sign}\}$. By inductive hypothesis on $M_1$, we have $M \Phi \downarrow = u_1$ and $M \Phi \downarrow(1) = u_1 \Phi \downarrow$. If $\text{root}(u_1) = \text{tag}_\ell$, with $\ell \in \{a, b\}$ then we have that there exists $u_1'$ such that $u_1' = \text{tag}_\ell(u_1')$. Thus if $\text{root}(u_1) \neq \text{tag}_\ell$, for all $\ell \in \{a, b\}$, then we have that $\text{Flawed}(M_1 \Phi \downarrow) = \{M_1 \Phi \downarrow\} \cup \text{Flawed}(u_1) \cup \text{Flawed}(u_2)$. Thus we have that $\text{Flawed}(M \Phi \downarrow) \subseteq \text{Flawed}(M_1 \Phi \downarrow)$. Since in both cases, we have that $\text{Flawed}(M \Phi \downarrow) \subseteq \text{Flawed}(M_1 \Phi \downarrow)$ and $M(M_1) < M(M)$, we can conclude by applying our inductive hypothesis on $M_1$.

Case $f = \text{proj}_j, j \in \{1, 2\}$: One again, we have to distinguish two cases: Either $f$ is reduced in $M \Phi \downarrow$, or not. If $f$ is not reduced, then we have that $M \Phi \downarrow = f(M_2 \Phi \downarrow)$. By definition we have that $\text{Flawed}(M \Phi \downarrow) = \{M \Phi \downarrow\} \cup \text{Flawed}(M_2 \Phi \downarrow)$. Thus if $t = M \Phi \downarrow$, we have that $t_1 = M_1 \Phi \downarrow$ and $M(M_1) < M(M)$. Therefore the result holds.

Lemma B.7. Let $u$ be a ground term in normal form. We have that there exists a context $C$ (possibly a hole) built on $\{\langle \rangle\}$, and $u_1, \ldots, u_m$ such that $u = C[u_1, \ldots, u_m]$, and for all $i \in \{1, \ldots, m\}$,

- either $u_i \in \text{Flawed}(u)$;
- or $u_i \in \text{Fct}_{\text{Fct}}(u)$ and $\delta^\alpha(u_i) = \delta^\beta(u_i)$;
- or $u_i = f(n)$ for some $f \in \{\text{pk, vk}\}$ and $n \in N$;
- or $u_i \in N$.

Proof. Let $u$ a ground term in normal form and let $\{v_1, \ldots, v_n\} = \text{Fct}_{\text{Fct}}(u)$. Thus there exists a context $D$ (possibly a hole) built on $\text{Fct}$ such that $u = D[v_1, \ldots, v_n]$. We prove the result by induction on $|D|$.

Base case $|D| = 0$: We show that the result holds with $C = _\_$. $|D| = 0$ implies that $\text{Fct}_{\text{Fct}}(u) = u$. Assume first that $u \notin \text{img}(\rho)$. Hence by Lemma B.1, we have $\delta^\alpha(u) = \delta^\beta(u)$ and so the result holds. Assume now that $u \notin \text{img}(\rho)$. In such a case, since $u$ is in normal form, we have $u \in N$ which allow us to conclude.

Inductive step $|D| > 0$: We choose $f \in \text{Fct}$, and $v_1, \ldots, v_k$ such that $u = f(u_1, \ldots, u_k)$. We do a case analysis on $f$.

Case $f = \langle \rangle$: In such a case, there exists $D_1, D_2$ context (possibly holes) built on $\text{Fct}$ such that $D = \langle D_1, D_2 \rangle$, $u_1 = D_1[v_1', \ldots, v_n']$, with $\{v_1', \ldots, v_n'\} = \text{Fct}_{\text{Fct}}(u_1)$ and $|D_i| < |D|$, for all $i \in \{1, 2\}$. By inductive hypothesis on $u_1$ and $u_2$, we have that there exists $C_1$ and $C_2$ context built on $\{\langle \rangle\}$ such that $u_1 = C_1[u_1', \ldots, u_m']$, $u_2 = C_2[u_1', \ldots, u_m']$, and for all $i, j$,

- either $u_j' \in \text{Flawed}(u_i)$, but we have that $\text{Flawed}(u) = \text{Flawed}(u_1) \cup \text{Flawed}(u_2)$ so $u_j' \in \text{Flawed}(u)$;
- or $u_j' \in \text{Fct}_{\text{Fct}}(u_i)$ and $\delta^\alpha(u_j') = \delta^\beta(u_j')$, but we have that $\text{Fct}_{\text{Fct}}(u) = \text{Fct}_{\text{Fct}}(u_1) \cup \text{Fct}_{\text{Fct}}(u_2)$ thus $u_j' \in \text{Fct}_{\text{Fct}}(u)$;
- or $u_j' = f(n)$ for some $f \in \{\text{pk, vk}\}$ and $n \in N$,
B.2. Proof for the first result

In this section, we will focus on the lemmas needed for the proof of Theorem 5.1. Typically, the first section of the Appendix is useful for the proofs of both main results. Thus, this section is independent of section B.3.

Lemma 5.9. Let \( E \) be a set of names and \( \Phi = \{ ax_1 \triangleright u_1, \ldots, ax_n \triangleright u_n \} \) such that \( \nu E \Phi \) is a derived well-tagged frame in normal form. Let \( \rho \) be a renaming such that \( \text{dom}(\rho) \cup \text{img}(\rho) \subseteq E \) and \( \text{dom}(\rho) \cap \text{fnames}(\Phi) = \emptyset \). If one of the two following conditions is satisfied:

(a) for all \( k \in \text{img}(\rho) \), \( \nu E \Phi \not\triangleright k \), \( \nu E \Phi \not\triangleright pk(k) \) and \( \nu E \Phi \not\triangleright \nu k(k) \)

(b) for all \( k \in \text{img}(\rho) \cup \text{dom}(\rho) \), \( \nu E \delta^\rho(\Phi) \not\triangleright k \), \( \nu E \delta^\rho(\Phi) \not\triangleright pk(k) \) and \( \nu E \delta^\rho(\Phi) \not\triangleright \nu k(k) \);

then for all \( M \) such that \( \text{fears}(M) \subseteq \text{dom}(\Phi) \) and \( \text{fnames}(M) \cap E = \emptyset \), for all \( i \in \{a, b\} \), \( \delta^\rho_i(M\Phi) = M\delta^\rho_i(M\Phi) \).

Proof. We prove this result by induction on \( \text{M}(M) \):

Base case \( \text{M}(M) = (0, 0) \): There exists no term \( M \) such that \( |M| = 0 \), thus the result holds.

Inductive step \( \text{M}(M) > (0, 0) \): We first prove there exists \( i \in \{a, b\} \) such that \( \delta^\rho_i(M\Phi) = M\delta^\rho_i(M\Phi) \) and then we show that \( \delta^\rho_i(M\Phi) = \delta^\rho_i(M\Phi) \).

Assume first that \( |M| = 1 \), i.e. either \( M \in N \) or there exists \( j \in \{1, \ldots, n\} \) such that \( M = ax_j \).

Let us first suppose \( M \in N \). In that case, \( M\beta_j = M \) for any substitution \( \beta \). Now, because by hypotheses \( \text{dom}(\rho) \cup \text{img}(\rho) \subseteq E \), and \( \text{fnames}(M) \cap E = \emptyset \), we necessarily have \( M\downarrow = kp \) for any \( k \in \text{dom}(\rho) \). Thus, by definition \( \delta^\rho_j(M\Phi) = \delta^\rho_j(M) = M\delta^\rho_j(M) \) for any \( d \in \{a, b\} \).

Let’s now assume that there exists \( j \in \{1, \ldots, n\} \) such that \( M = ax_j \), and suppose that \( \text{col}(ax_j) = i \in \{a, b\} \). According to the definition of \( \delta^\rho_i(\Phi) \), we have that \( ax_j\delta^\rho_i(\Phi) = \delta^\rho_i(ax_j\Phi) \). Since \( u_j \) is in normal form, then by Lemma 5.6 we know that \( \delta^\rho_i(ax_j \Phi) \) is also in normal form.

Thus, we have that \( \delta^\rho_i(M\Phi) = M\delta^\rho_i(M\Phi) \).

Otherwise, if \( |M| > 1 \), then there exists \( f \) and \( M_1, \ldots, M_n \) such that \( M = f(M_1, \ldots, M_n) \). We do a case analysis on \( f \):

Case \( f \in F_T \cup F_{\text{tag}}, \ell \in \{a, b\} \): In this case, let \( t = f(M_1\Phi, \ldots, M_n\Phi) \). Since \( f \in F_T \), then there exists a context \( C \) built upon \( F_T \) such that \( t = C[u_1, \ldots, u_m] \) and \( u_1, \ldots, u_m \) are factor of \( t \) in normal form. By Lemma 5.2 we know that there exists a context \( D \) (possibly a hole) over \( F_T \) such that \( \ell \downarrow = D[u_{i_1}, \ldots, u_{i_k}] \) with \( i_1, \ldots, i_k \in \{0, \ldots, m\} \) and \( u_0 = \text{min} \). But thanks to Lemma 5.3 we also that \( C[\delta^\rho_i(u_1), \ldots, \delta^\rho_i(u_m)]\downarrow = D[\delta^\rho_i(u_{i_1}), \ldots, \delta^\rho_i(u_{i_k})] \) and \( D[\delta^\rho_i(t)] \downarrow = D[\delta^\rho_i(u_1), \ldots, \delta^\rho_i(u_m)], \delta^\rho_i(t) ] \) and \( \ell \downarrow = M\Phi \) which means that \( \delta^\rho_i(M\Phi) = \delta^\rho_i(t) \).

At last \( \delta^\rho_i(t) \downarrow = \delta^\rho_i(f(M_1\Phi, \ldots, M_n\Phi))_\downarrow = f(\delta^\rho_i(M_1\Phi), \ldots, \delta^\rho_i(M_n\Phi))_\downarrow \). Since we have that \( \text{M}(M_1) < \text{M}(M), \ldots, \text{M}(M_n) < \text{M}(M) \), we can apply our inductive hypothesis on \( M_1, \ldots, M_n \) and so \( \delta^\rho_i(t) \downarrow = f(M_1\delta^\rho_i\Phi, \ldots, M_n\delta^\rho_i(M\Phi))_\downarrow = f(M_1, \ldots, M_n)\delta^\rho_i(M\Phi)_\downarrow \). Thus we can conclude that \( \delta^\rho_i(M\Phi) = \delta^\rho_i(t) \downarrow = M\delta^\rho_i(M\Phi) \).
Case $f \in \{\text{senc, aenc, sign, }\emptyset, \text{pk, vk, h}\}$: In such a case, $M\Phi \downarrow = f(M_1\Phi_1, \ldots, M_n\Phi_n)$. By applying our inductive hypothesis on $M_1, \ldots, M_n$, we have $\delta^\rho_k(M\Phi_\downarrow) = \delta^\rho_k(M_k\Phi_k\downarrow)$, for all $k \in \{1, \ldots, n\}$. Thus we have that $\delta^\rho_j(M\Phi_\downarrow) = f(\delta^\rho_j(M_1\Phi_1\downarrow), \ldots, \delta^\rho_j(M_n\Phi_n\downarrow))$ with $j \in \{a, b\}$, for all $i \in \{a, b\}$. Thus by applying again our inductive hypothesis on $M_1, \ldots, M_n$, we have that $\delta^\rho_i(M\Phi_\downarrow) = f(M_1\delta^\rho_i(\Phi_1\downarrow), \ldots, M_n\delta^\rho_i(\Phi_n\downarrow)) = M\delta^\rho_i(\Phi_\downarrow)$.

Case $f \in \{\text{sdec, adec, check}\}$: If we first assume that the root symbol $f$ is not reduced in $M\Phi_\downarrow$ then the proof is similar to the previous case. Thus, we focus on the case where the root occurrence of $f$ is reduced. In this case, there exists $v_1, v_2$ such that

- $M_1\Phi_\downarrow = \text{senc}(v_1, v_2)$, $M_2\Phi_\downarrow = v_2$ and $M\Phi_\downarrow = v_1$. According to the definition of $\delta^\rho_a$ and $\delta^\rho_b$, we know that there exists $i \in \{a, b\}$ such that $\delta^\rho_i(\text{senc}(v_1, v_2)) = \text{senc}(\delta^\rho_i(v_1), \delta^\rho_i(v_2))$. For such $i$, we have that $\text{sdec}(\delta^\rho_i(M_1\Phi_\downarrow), \delta^\rho_i(M_2\Phi_\downarrow)) = \delta^\rho_i(M\Phi_\downarrow)$. But by applying our inductive hypothesis on $M_1$ and $M_2$, we obtain $\delta^\rho_i(M\Phi_\downarrow) = \text{sdec}(M_1\delta^\rho_i(\Phi_1\downarrow), M_2\delta^\rho_i(\Phi_2\downarrow)) = M\delta^\rho_i(\Phi_\downarrow)$.

- $M_1\Phi_\downarrow = \text{aenc}(v_1, pk(v_2))$, $M_2\Phi_\downarrow = v_2$ and $M\Phi_\downarrow = v_1$: According to the definition of $\delta^\rho_a$ and $\delta^\rho_b$, there exists $i \in \{a, b\}$ such that $\delta^\rho_i(\text{aenc}(v_1, pk(v_2))) = \text{aenc}(\delta^\rho_i(v_1), pk(\delta^\rho_i(v_2)))$. For such $i$, we have that $\text{adec}(\delta^\rho_i(M_1\Phi_\downarrow), \delta^\rho_i(M_2\Phi_\downarrow)) = \delta^\rho_i(M\Phi_\downarrow)$. But by applying our inductive hypothesis on $M_1$ and $M_2$, we obtain $\delta^\rho_i(M\Phi_\downarrow) = \text{adec}(M_1\delta^\rho_i(\Phi_1\downarrow), M_2\delta^\rho_i(\Phi_2\downarrow)) = M\delta^\rho_i(\Phi_\downarrow)$.

- $M_1\Phi_\downarrow = \text{sign}(v_1, v_2)$, $M_2\Phi_\downarrow = \text{vk}(v_2)$ and $M\Phi_\downarrow = v_1$: According to the definition of $\delta^\rho_a$ and $\delta^\rho_b$, there exists $i \in \{a, b\}$ such that $\delta^\rho_i(\text{sign}(v_1, v_2)) = \text{sign}(\delta^\rho_i(v_1), \delta^\rho_i(v_2))$. For such $i$, we have that $\text{sdec}(\delta^\rho_i(M_1\Phi_\downarrow), \delta^\rho_i(M_2\Phi_\downarrow)) = \delta^\rho_i(M\Phi_\downarrow)$. But by applying our inductive hypothesis on $M_1$ and $M_2$, we obtain $\delta^\rho_i(M\Phi_\downarrow) = \text{sdec}(M_1\delta^\rho_i(\Phi_1\downarrow), M_2\delta^\rho_i(\Phi_2\downarrow)) = M\delta^\rho_i(\Phi_\downarrow)$.

Case $f \in \text{proj}_j$, $j = 1, 2$: Similarly to the previous case, we only focus on the case where $f$ is reduced in $M\Phi_\downarrow$. In such a case, there exists $u_1, u_2$ such that $M_1\Phi_\downarrow = \langle u_1, u_2 \rangle$ and $M\Phi_\downarrow = u_j$. Thus for all $i \in \{1, 2\}$, we have that $\delta^\rho_i(M\Phi_\downarrow) = \delta^\rho_i(u_j)$ and $\delta^\rho_i(M_1\Phi_\downarrow) = \langle \delta^\rho_i(u_1), \text{delta}^\rho_i(u_2) \rangle$. Hence we deduce that $f(\delta^\rho_i(M_1\Phi_\downarrow)) = \delta^\rho_i(u_j)$ and $f(\delta^\rho_i(M\Phi_\downarrow)) = \delta^\rho_i(u_j)$. By inductive hypothesis on $M_1$, there exist $i_0$ such that $\delta^\rho_i(M_1\Phi_\downarrow) = M_1\delta^\rho_i(\Phi_1\downarrow)$. Therefore, we deduce that $\delta^\rho_i(M\Phi_\downarrow) = f(M_1\delta^\rho_i(\Phi_1\downarrow)) = M\delta^\rho_i(\Phi_\downarrow)$.

It remains to prove that $\delta^\rho_i(M\Phi_\downarrow) = \delta^\rho_i(M\Phi_\downarrow)$, for all $i \in \{1, 2\}$. We proved that there exists $i_0 \in \{a, b\}$ such that $\delta^\rho_i(M\Phi_\downarrow) = M\delta^\rho_i(\Phi_\downarrow)$. But by Lemma 13.7, we know that there exists a context $C$ built over $\{\emptyset\}$, and $v_1, \ldots, v_m$ terms such that $M\Phi_\downarrow = C[v_1, \ldots, v_m]$ and for all $i \in \{1, \ldots, m\}$:

- either $v_i \in \text{Flawed}(M\Phi_\downarrow)$
- or $v_i \in \text{Fct}_{\text{pk}}(M\Phi_\downarrow)$ and $\delta^\rho_i(v_i) = \delta^\rho_i(v_i)$.
- or $v_i = f(n)$ for some $f \in \{\text{pk, vk}\}$ and $n \in \mathcal{N}$;
- or $v_i \in \mathcal{N}$.

First of all, note that $C$ being built upon $\{\emptyset\}$ means that $v_i$ is deducible in $\Phi$, for all $i \in \{1, \ldots, m\}$. Furthermore, we also have that $\delta^\rho_i(M\Phi_\downarrow) = C[\delta^\rho_i(v_1), \ldots, \delta^\rho_i(v_m)]$. But we previously proved that $\delta^\rho_i(M\Phi_\downarrow) = M\delta^\rho_i(\Phi_\downarrow)$, for all $i \in \{1, \ldots, m\}$.

Case $v_1 \in \text{Flawed}(M\Phi_\downarrow)$: There exists $w_1, \ldots, w_\ell$ terms and a function symbol $f$ such that $v_1 = f(w_1, \ldots, w_\ell)$. By Lemma 13.6, there exists $N_1, \ldots, N_\ell$ such that for all $k \in \{1, \ldots, \ell\}$, $M(N_k) < M(M)$ and $N_k \Phi_\downarrow = w_k$. Hence, by applying inductive hypothesis on $N_1, \ldots, N_\ell$, we obtain that $\delta^\rho_i(N_k\Phi_\downarrow) = \delta^\rho_i(N_k\Phi_\downarrow)$, for all $k \in \{1, \ldots, \ell\}$. Thus, thanks to $v_1$ being in normal form, we can conclude that $\delta^\rho_i(v_1) = \delta^\rho_i(v_1)$.

Case $v_1 \in \text{Fct}_{\text{pk}}(M\Phi_\downarrow)$: we also have $\delta^\rho_i(v_1) = \delta^\rho_i(v_1)$.

Case $v_1 = f(n)$ for some $f \in \{\text{pk, vk}\}$ and $n \in \mathcal{N}$. By hypothesis, we know that either $\Phi \not\vdash f(k)$, for all $k \in \text{img}(\rho)$; or $\delta^\rho_i(\Phi) \not\vdash f(k)$, for all $k \in \text{img}(\rho) \cup \text{dom}(\rho)$. Since we showed that $v_i$ is deducible from $\Phi$ and $\delta^\rho_i(v_i)$ is deducible from $\delta^\rho_i(\Phi)$, both hypotheses imply that $n \not\in \text{img}(\rho)$ and so $\delta^\rho_i(v_i) = \delta^\rho_i(v_i)$.
Case $v_i \in N$: By hypothesis we know that either $\Phi \not\vdash k$, for all $k \in \text{img}(\rho)$; or $\delta^\rho(\Phi) \not\vdash k$, for all $k \in \text{img}(\rho) \cup \text{dom}(\rho)$. Since we showed that $v_i$ is deducible from $\Phi$ and $\delta^\rho_v(v_i)$ is deducible from $\delta^\rho(\Phi)$, both hypotheses imply that $v_i \notin \text{img}(\rho)$ and so $\delta^\rho_v(v_i) = \delta^\rho_v(v_i)$. \hfill \Box

**Lemma 5.10** (Soundness). Let $S = (E_S; P_S; \Phi_S)$, $S' = (E'_S; P'_S; \Phi'_S)$ and $D = (E_D; P_D; \Phi_D)$ be three bounded intermediate processes. Assume that $S \xrightarrow{\delta} S'$, $\Phi_S$ is well-tagged and there exists a derived well-tagged multi-set of processes $(P_0, \alpha)$ and a renaming $\rho$, such that

- $\text{dom}(\rho) \cup \text{img}(\rho) \subseteq E_S$, $\text{dom}(\rho) \cap \text{fnames}(P_S; \Phi_S) = \emptyset$; and
- $E_S = E_D$, $P_D \downarrow = \delta^\rho(P_S \downarrow)$; and
- $P_S = P_0 \circ \rho$ and $P_D \downarrow = \delta^\rho(P_0) \delta^\rho(\alpha) \downarrow$; and
- for all traces $(tr, \Phi)$ of $D$, for all $k \in \text{img}(\rho) \cup \text{dom}(\rho)$, $\Phi \not\vdash k$, $\Phi \not\vdash \rho k(k)$ and $\Phi \not\vdash \rho k(k)$.

There exists a bounded intermediate process $D' = (E'_D; P'_D; \Phi'_D)$, a derived well tagged multi-set of processes $(P'_0, \alpha')$ such that $\Phi'_S$ is well-tagged and:

- $E'_S = E_S = E_D$ and $P_D \downarrow = \delta^\rho(P'_S \downarrow)$; and
- $P'_S = P'_0 \circ \rho$ and $P'_D \downarrow = \delta^\rho(P'_0) \delta^\rho(\alpha') \downarrow$; and
- $D \xrightarrow{\delta} D'$.

**Proof.** We show this result by case-by-case analysis on the rule:

**Case of the rule THEN:** In this case, there exists $\phi$ formula and $Q_1$, $Q_2$ plain processes and $Q$ a multi-set of processes such that $P_S = \{ \phi \text{ then } Q_1 \text{ else } Q_2 \} \uplus Q$, $P'_S = \{ Q_1 \} \uplus Q$, $E_S = E'_S$ and $\Phi_S = \Phi'_S$ with $i = \text{col}(Q_1) = \text{col}(Q_2)$ and $\phi$ is a conjunction of equation. Furthermore, we have that for all equation $u = v$ if $\phi$, $u = v$.

Since $P_S = P_0 \circ \rho$, then there exists $Q_0^0$, $Q_0^2$ plain processes and $Q^0$ a multi-set of processes such that $Q_1^0 = Q_1$, $Q_2^0 = Q_2$ and $Q^0 = Q$. Furthermore, either (a) there exists $u$ such that $\phi$ is the formula $\text{test}([u_1], \alpha)$, or (b) there exists $u_1, u_2$ such that $\phi$ is the formula $[u_1], \alpha = [u_2], \alpha$ and $\alpha \equiv \text{test}([u_1], \alpha) \land \text{test}([u_2], \alpha)$.

But we also have $P_D = \delta^\rho(P_0) \delta^\rho(\alpha) \downarrow$, which means that there exists $\phi'$ formula and $Q'_1$, $Q'_2$ plain processes and $P'$ a multi-set of processes such that $P_D = \{ \phi' \text{ then } Q'_1 \text{ else } Q'_2 \} \uplus Q'$ with $Q'_1 \downarrow = \delta^\rho([u_1], \alpha_\downarrow) \downarrow$, $Q'_2 \downarrow = \delta^\rho([u_2], \alpha_\downarrow) \downarrow$, $Q' = \delta^\rho([u_1], \alpha_\downarrow) \downarrow$ and $P_D \downarrow = \delta^\rho(P'_S \downarrow)$. Furthermore, in case (a) $\phi' \downarrow$ is the formula $\text{test}([u_1], \alpha) \land \text{test}([u_2], \alpha)$; and in case (b) $\phi'$ is the formula $[u_1], \alpha = [u_2], \alpha$ where $u_1 = \delta^\rho([u_1], \alpha) \downarrow$ and $u_2 = \delta^\rho([u_2], \alpha) \downarrow$.

In case (a), since for all equation in $u = v$ if $\phi$, $u = v$, then $u_1 = v_1$. Thus it is equivalent to $(\alpha_\downarrow \equiv \text{test}([u_1], \alpha))$. By Lemma [3.3], we know that this is equivalent to $\alpha_\downarrow \equiv \text{test}([u_1], \alpha))$. Thus we have that for all equation $u = v$ of $\text{test}([u_1], \alpha_\downarrow) = \delta^\rho([u_1], \alpha_\downarrow)$. Since $\phi' \downarrow$ is the formula $\text{test}([u_1], \alpha) \land \text{test}([u_2], \alpha)$, we can conclude that for all equation $u = v$ of $\phi'$, $u_1 = v_1$ and so $u = v$.

In case (b), we know that $\alpha_\downarrow \equiv \text{test}([u_1], \alpha) \land \text{test}([u_2], \alpha)$ and $[u_1], \alpha = [u_2], \alpha$. Thus by Corollary [5.1] we can deduce that $\delta^\rho_v([u_1], \alpha_\downarrow) = \delta^\rho_v([u_2], \alpha_\downarrow)$ which means that $u_1 = v \downarrow$ and so $u = v$.

In case of the rule COMM: In this case, there exists $p, u, x$ terms, $Q_1$, $Q_2$ processes, and $Q$ multi-set of processes such that $P_S = \{ \text{out}(p, u).Q_1; \text{in}(x).Q_2 \} \uplus Q$, $P'_S = \{ Q_1; Q_2 \} \uplus Q$, $E_S = E'_S$ and $\Phi_S = \Phi'_S$. Assume that $\text{col}([\text{out}(p, u).Q_1]) = i$ and $\text{col}([\text{in}(p, x).Q_2]) = j$. We distinguish two cases:
Case $p \in E_i$: Because processes of different color do not share private channel, it is necessary the case that $i = j$.

Since $P_S = P_0\alpha$, then there exists $Q_0^1$, $Q_0^2$ processes, $Q^0$ multi-set of processes, $v$ term such that $Q_0^1\alpha = Q_1$, $Q_0^2\alpha = Q_2$, $Q^0\alpha = Q$ and $u = [v].\alpha$. Furthermore, since $(P_0, \alpha)$ is an original well tagged process, we have that $\alpha \models test([v], i)$.

But we also have that $P_D\downarrow = \delta^p(P_0)\delta^u(\alpha)\downarrow$, which means that there exists $p', p'', u', u''$ terms, $Q_1', Q_2'$ processes, and $Q'$ multi-set of processes such that $P_D = \{\text{out}(p', u'), Q_i'; \text{in}(p'', v), Q_i\} \cup Q'$, $E_D = E_S$ with $Q_1'\downarrow = \delta^p(Q_1')\delta^u(\alpha)\downarrow$, $Q_2'\downarrow = \delta^p(Q_2')\delta^u(\alpha)\downarrow$, $Q_i'\downarrow = \delta^p(Q_i')\delta^u(\alpha)\downarrow$, $\Phi_D\downarrow = \delta^p(\Phi_S\downarrow)$, $p'' = \delta^p(p')$ and $u'' = \delta^u([v], i)\delta^u(\alpha)\downarrow$.

Therefore, we have that $(E_D; P_D; \Phi_D) \xrightarrow{\delta^p} (E_D; \{Q_1'; Q_2'; \{x \mapsto u'\}\} \cup P'; \Phi_D)$.

Let’s denote $\alpha' = \alpha \cup \{x \mapsto u\}$ with $\text{col}(x) = i$. Since $Q_2 = Q_2^0\alpha$, we have that $Q_2\{x \mapsto u\} = Q_2^0\alpha'$. Furthermore, $Q_2\{x \mapsto u'\} \downarrow = (Q_2\downarrow)(x \mapsto (u'))\downarrow$. But thanks to Lemma 13.2 and $(\alpha') \models test([v], i)$, we have $\delta^p([v], i)\delta^u(\alpha)\downarrow = \delta^u([v], i)\alpha\downarrow = \delta^u(\alpha)\downarrow$. Thus, we deduce that $Q_2\{x \mapsto u'\} = \delta^p(Q_2')\delta^u(\alpha)\downarrow$, $Q_2\{x \mapsto u\} = \delta^p(Q_2')\delta^u(\alpha)\downarrow$.

Let $P'_{0'} = \{Q_1'; Q_2'; Q_0^0\} \cup Q^0$. Since $x$ doesn’t appears in $Q_0^0$ and $Q^0$, we conclude that $P'_{0'} = P_S'$ and $\delta^p(P'_{0'})\delta^u(\alpha)\downarrow = P_D\downarrow$. Hence the result holds.

Case $p \notin E_i$: Since $P_S = P_0\alpha$, then there exists $Q_0^1$, $Q_0^2$ processes, $Q^0$ multi-set of processes, $v$ term such that $Q_0^1\alpha = Q_1$, $Q_0^2\alpha = Q_2$, $Q^0\alpha = Q$ and $u = [v].\alpha$. Furthermore, since $(P_0, \alpha)$ is an original well tagged process, we have that $\alpha \models test([v], i)$.

But we also have that $P_D\downarrow = \delta^p(P_0)\delta^u(\alpha)\downarrow$, which means that there exists $p', p'', u', u''$ terms, $Q_1$, $Q_2$ processes, and $Q'$ multi-set of processes such that $P_D = \{\text{out}(p', u'), Q_i'; \text{in}(p'', v), Q_i\} \cup Q'$, $E_D = E_S$ with $Q_1\downarrow = \delta^p(Q_1')\delta^u(\alpha)\downarrow$, $Q_2\downarrow = \delta^p(Q_2')\delta^u(\alpha)\downarrow$, $p'' = \delta^p(p')$ and $\Phi_D\downarrow = \delta^p(\Phi_S\downarrow)$.

$p'$ and $p$ are both channel type term and we assumed that all the names in $\text{im}(\Phi_D) \cup \text{dom}(\Phi_D)$ are names of base type. Thus we have that $p' \notin E_D$.
Hence the result holds.

Case of the rule \textsc{Out-T}: In this case, there exists \(u, p\) terms, \(Q_1\) a process, and \(Q\) a multi-set of processes such that \(P_S = \{\text{out}(p, u), Q_1\} \cup Q\), \(P'_S = \{Q_1\} \cup Q\). \(S_c, E_c, S_f\) are \(\Phi_S\) and \(\Phi'_S = \Phi_S \cup \{ax_n \triangleright u\}\). Furthermore, have that \(\ell = \nu x_n. \text{out}(p, ax_n), p \notin S_c, ax_n\) is a parameter such that \(n-1 = |\Phi_S|\). Assume that \(\text{col}(\text{out}(p, u), Q_1) = i \in \{a, b\}\).

Since \(P_S = P_0\alpha\), then there exists \(Q_0\) a process, \(Q\) a multi-set of processes and \(v\) a term such that \(Q_0\alpha = Q_1, Q'\alpha = Q\) and \(u = [v]\alpha\) where \(i = \text{col}(\text{out}(p, u), Q_1)\). Furthermore, since \(\text{col}(\nu x_n. \text{out}(p, ax_n))\) is an original \text{well tagged} process, we have that \(\alpha \equiv \text{test}([v], i)\). Hence we deduce that \(\Phi'_S\) is well-formed.

But we also have that \(P_D = \{\text{in}(p, u'), Q_1\} \cup Q'\), \(E_D = E = E'_c\) and \(S_f = S_f\), which means that \(\alpha' \equiv \text{test}([v], i)\). Hence we deduce that \(\Phi'_S\) is well-formed.

Thanks to Lemma 5.11 and \((\Omega, \Lambda) \equiv \text{test}([v], i)\), we have that \(\delta'(\Omega, \Lambda) = \delta'(\Omega, \Lambda)_\downarrow = \delta'(\Omega, \Lambda)_\downarrow\). But \(\delta'(\Omega, \Lambda) = \delta'(\Omega, \Lambda)_\downarrow\), which means that \(\delta'(\Omega, \Lambda)_\downarrow\). Since \(\text{col}(ax_n) = i\), we can deduce that \(\Phi'_D = \text{test}(\Phi'_S)\). We conclude with \(P_0 = \{Q_0\} \cup Q'\) and \(\alpha' = \alpha\). We also conclude that \(\Phi'_D = \text{test}(\Phi'_S)\) which means that \(\Phi'_S = \Phi'_S\). Hence the result holds.

\begin{lemma}[Completeness] \label{lem:completeness}
Let \(S = (E_S; P_S; \Phi_S), \Phi \equiv \langle D, D' \rangle; \Phi'_S\) and \(D' = (E_S; D; \Phi'_S)\) be three bounded intermediate processes. Assume that \(D \xrightarrow{\rho} D'\), \(\Phi'\) is a derived \text{well tagged} frame and there exists a derived \text{well tagged} multi-set of processes \((P_0, \alpha)\) and a renaming \(\rho\), such that
\begin{itemize}
  \item \(\text{dom}(\rho) \cup \text{img}(\rho) \subseteq \mathcal{S}_c, \text{dom}(\rho) \cap \text{fnames}(P_S, \Phi_S) = \emptyset;\) and
  \item \(\Phi = \mathcal{E}_c = \Phi_D \downarrow = \delta'(\Phi_S)\;\).
\end{itemize}
\end{lemma}

\begin{proof}
\end{proof}
Lemma B.2 shows that those two properties are equivalent. The same goes for Corollary B.1.

In this section, we will focus on the proof of Theorem 5.2. We will assume, as in Section B.2, that processes and frames are colored by \( P \) or \( D \), respectively.

B.3 Proof of second result

In this section, we will focus on the proof of Theorem 5.2. We will assume, as in Section B.2, that processes and frames are colored by \( P \) or \( D \), respectively.

Lemma 5.13. Let \( \Phi \) and \( \Phi' \) two frames in normal form such that \( \text{dom}(\Phi) = \text{dom}(\Phi') \). Assume that \( \Phi \) and \( \Phi' \) have the same colors, i.e. for all \( (ax \triangleright u) \in \Phi \), for all \( (ax' \triangleright u') \in \Phi' \), \( ax = ax' \) implies \( \text{col}(ax \triangleright u) = \text{col}(ax' \triangleright u') \).

Let \( E \) be a set of names and let \( \rho \) a renaming such that \( \text{dom}(\rho) \cup \text{img}(\rho) \subseteq E \) and \( \text{dom}(\rho) \cap \text{fnames}(\Phi, \Phi') = \emptyset \). Let’s denote \( \Phi_+ = \Phi_a \cup \Phi_b \cup \Phi \) and \( \Phi'_+ = \Phi_a \cup \Phi_b \cup \Phi' \).

If the following properties are satisfied:

- \( \nu E, \Phi_+, \nu E, \Phi'_+ \) are well-tagged
- \( \nu E, \delta^\rho(\Phi_+) \sim \nu E, \delta^\rho(\Phi'_+) \)
- for all \( u \in \{ k, pk(k), wk(k) \mid k \in \text{img}(\rho) \cup \text{dom}(\rho) \} \), \( \nu E, \delta^\rho(\Phi_+) \vdash u \) or \( \nu E, \delta^\rho(\Phi'_+) \vdash u \) implies that \( u \in \text{img}(\rho) \cup \text{dom}(\rho) \)

then for all \( M \) such that \( \text{fnames}(M) \cap E = \emptyset \) and \( \text{fears}(M) \subseteq \text{dom}(\Phi_+) \), there exists \( M_a \) and \( M_b \) such that \( \text{fnames}(M_a, M_b) \cap E = \emptyset \), \( \text{fears}(M_a, M_b) \subseteq \text{dom}(\Phi_+) \) and:

1. \( \delta^\rho_M(\Phi_a \downarrow) = M_a \delta^\rho(\Phi_+) \downarrow \) and \( \delta^\rho_M(\Phi_b \downarrow) = M_b \delta^\rho(\Phi_+) \downarrow \)
2. \( \delta^\rho_M(\Phi'_a \downarrow) = M_a \delta^\rho(\Phi'_+) \downarrow \) and \( \delta^\rho_M(\Phi'_b \downarrow) = M_b \delta^\rho(\Phi'_+) \downarrow \)

Proof. We prove this lemma by induction on \( \mathcal{M}(M) \).

Base case \( \mathcal{M}(M) = (0, 0) \): There exists no term \( M \) such that \( |M| = 0 \), thus the result holds.

Inductive step \( \mathcal{M}(M) > (0, 0) \): The first step of the proof will be to show that there exists \( c \in \{a, b\} \), a terms \( M_c \) such that \( \text{fnames}(M_c) \cap E = \emptyset \), \( \text{fears}(M_c) \subseteq \text{dom}(\Phi_+) \), \( \delta^\rho_M(\Phi_+ \downarrow) = M_a \delta^\rho(\Phi_+) \downarrow \) and \( \delta^\rho_M(\Phi'_+ \downarrow) = M_b \delta^\rho(\Phi'_+) \downarrow \). Then the second step will consist in showing that there exists another term \( M_d \), with \( d \in \{a, b\} \) and \( c \neq d \) that verifies the wanted properties.

First step: Assume first that \( |M| = 1 \). In such a case, we have that either \( M \in \mathcal{N} \) or there exists \( ax \in \text{dom}(\Phi_+) \) such that \( M = ax \).
If \( M \in \mathcal{N} \), then by hypothesis, we know that \( M \notin \mathcal{E} \). Since \( \text{dom}(\rho) \cup \text{img}(\rho) \subseteq \mathcal{E} \), we can deduce that \( \delta_0^\rho(\Phi) = M \), for all \( i \in \{a, b\} \). Furthermore, \( M \in \mathcal{N} \) also implies that \( M \Phi_\downarrow = M \), \( M \Phi_\downarrow \downarrow = M \), and \( M \delta_0^\rho(\Phi) = M \), and \( M \delta_0^\rho(\Phi) = M \). Thus, the result holds.

Else \( ax \in \text{dom}(\Phi_\downarrow) \). Since we know there exists \( u, u' \) such that \( (ax \triangleright u) \in \Phi_\downarrow \) and \( (ax \triangleright u') \in \Phi_\downarrow' \). Furthermore, we assumed that \( \Phi \) and \( \Phi' \) have the same colors, so do \( \Phi_\downarrow \) and \( \Phi_\downarrow' \). Hence we have that \( \text{col}(ax \triangleright u) = \text{col}(ax \triangleright u') \). Let’s denote \( i = \text{col}(ax \triangleright u) \). By definition of \( \delta_1^\rho(\Phi) \) and \( \delta_1^\rho(\Phi') \), we have that \( ax \delta_1^\rho(\Phi) = \delta_1^a(ax \Phi_\downarrow) \) and \( a \delta_1^\rho(\Phi') = \delta_1^a(ax \Phi_\downarrow') \). Note that we assumed that \( \Phi \) and \( \Phi' \) are both in normal form, thus so are \( \Phi_\downarrow \) and \( \Phi_\downarrow' \). Hence, we can conclude that \( M \delta_1^\rho(\Phi_\downarrow) = \delta_1^a(M \Phi_\downarrow) \) and \( M \delta_1^\rho(\Phi_\downarrow') = \delta_1^a(M \Phi_\downarrow') \).

Assume now that \( |M| > 1 \). It implies that there exists \( M_1, \ldots, M_n \) in \( \mathcal{N} \) such that \( f = (M_1, \ldots, M_n) \). We do a case analysis on \( f \).

Case \( f \in \mathcal{F}_i \cup \mathcal{F}_\tag, i \in \{a, b\} \): In such a case, let \( t = f(M_1 \Phi_\downarrow, \ldots, M_n \Phi_\downarrow) \) and \( t' = f(M_1 \Phi_\downarrow', \ldots, M_n \Phi_\downarrow') \). Since \( f \in \mathcal{F}_i \cup \mathcal{F}_\tag \), we have that \( \delta_i^\rho(t) = \delta_i^\rho(M_1 \Phi_\downarrow, \ldots, M_n \Phi_\downarrow) \) and \( \delta_i^\rho(t') = \delta_i^\rho(M_1 \Phi_\downarrow', \ldots, M_n \Phi_\downarrow') \). But we have that \( \mathcal{M}(M_j) < \mathcal{M}(M_1), \ldots, \mathcal{M}(M_n) < \mathcal{M}(M) \). Thus we can apply or inductive hypothesis on \( M_1, \ldots, M_n \) and so there exists \( M_1', \ldots, M_n' \) such that for all \( k \in \{1, \ldots, n\}, \mathcal{M}(M_k') \leq \mathcal{M}(M_k) \). Furthermore, we assumed that \( f \) and \( g \) are both in normal form, thus so are \( \Phi_\downarrow \) and \( \Phi_\downarrow' \). Hence, we can conclude that \( M \delta_i^\rho(\Phi_\downarrow) = \delta_i^\rho(M \Phi_\downarrow) \) and \( M \delta_i^\rho(\Phi_\downarrow') = \delta_i^\rho(M \Phi_\downarrow') \).

On the other hand, \( t = f(M_1 \Phi_\downarrow, \ldots, M_n \Phi_\downarrow) \) implies that there exists \( C \) context built on \( \mathcal{F}_i \cup \mathcal{F}_\tag \) and \( u_1, \ldots, u_m \) terms in normal form such that \( t = C[u_1, \ldots, u_m] \) with \( u_1, \ldots, u_m \) factors of \( t \). Thanks to Lemma 5.2 there exists a context \( D \) (possibly a hole) built on \( \mathcal{F}_i \cup \mathcal{F}_\tag \) such that \( t = D[u_1, \ldots, u_m] \) with \( u_1, \ldots, u_m \in \mathcal{M}(M) \). By using Lemmas 5.3 and 5.6 we can deduce that \( \mathcal{M}(M_1 \Phi_\downarrow, \ldots, M_n \Phi_\downarrow) \). Since \( C \) and \( D \) are both built upon \( \mathcal{F}_i \cup \mathcal{F}_\tag \), we can conclude that \( \delta_i^\rho(C[u_1, \ldots, u_m]) = \delta_i^\rho(D[u_1, \ldots, u_m]) \) and \( \delta_i^\rho(C[u_1, \ldots, u_m]) \).

Similarly, we have that \( t' = f(M_1 \Phi_\downarrow', \ldots, M_n \Phi_\downarrow') \) implies that \( \delta_i^\rho(t') = \delta_i^\rho(t') \). Since we proved that \( \delta_i^\rho(t') = f(M_1, \ldots, M_n) \delta_i^\rho(\Phi_\downarrow) \) and \( t = M \Phi_\downarrow \), we can deduce that \( \delta_i^\rho(\Phi_\downarrow) = f(M_1, \ldots, M_n) \delta_i^\rho(\Phi_\downarrow) \). Similarly, we have that \( f(M_1, \ldots, M_n) \delta_i^\rho(\Phi_\downarrow) = \delta_i^\rho(\Phi_\downarrow) \). Hence, the result holds with \( M_i = f(M_1, \ldots, M_n) \).

Case \( f \in \{ \text{sen}, \text{aen}, \text{sign}, \} \): By definition of \( \mathcal{F}_0 \), we know that \( M \Phi_\downarrow = f(M_1 \Phi_\downarrow, M_2 \Phi_\downarrow) \) and \( M \Phi_\downarrow = f(M_1 \Phi_\downarrow, M_2 \Phi_\downarrow) \). Thanks to Lemma 5.6 we can deduce that for all \( i \in \{a, b\} \), \( \mathcal{M}(M_1 \Phi_\downarrow) = \mathcal{M}(M_2 \Phi_\downarrow) \). Thus by our inductive hypothesis, there exists \( M_1' \) such that \( \delta_0^\rho(M_1 \Phi_\downarrow) = \delta_0^\rho(M_1 \Phi_\downarrow) \). And \( \delta_0^\rho(M_1 \Phi_\downarrow) = \delta_0^\rho(M_1 \Phi_\downarrow) \). Hence for all \( j \in \{a, b\} \), \( \mathcal{M}(M_1 \Phi_\downarrow) = \mathcal{M}(M_2 \Phi_\downarrow) \).

This equivalence and the definition of \( \delta_i^\rho \) and \( \delta_i^\rho \) allow us to deduce that for all \( i \in \{a, b\} \), there exists \( j \in \{a, b\} \) such that \( \delta_i^\rho(M_1 \Phi_\downarrow) = \delta_i^\rho(M_1 \Phi_\downarrow) \) and \( \delta_i^\rho(M_1 \Phi_\downarrow) = \delta_i^\rho(M_1 \Phi_\downarrow) \). By our inductive hypothesis on \( M_1 \) and \( M_2 \), we deduce that there exists \( M_1' \) and \( M_2' \) such that \( \delta_0^\rho(M_1 \Phi_\downarrow) = \delta_0^\rho(M_1 \Phi_\downarrow) \) and \( \delta_0^\rho(M_1 \Phi_\downarrow) = \delta_0^\rho(M_1 \Phi_\downarrow) \). Let’s first focus on \( M_1 \). We need to distinguish several cases:

(a) If the root occurrence of \( \text{sen} \) cannot be reduced, then \( \Phi_\downarrow = \text{sen}(M_1 \Phi_\downarrow, M_2 \Phi_\downarrow) \). Thus for all \( i \in \{a, b\} \), \( \delta_i^\rho(M_1 \Phi_\downarrow) = \text{sen}(\delta_i^\rho(M_1 \Phi_\downarrow), \delta_i^\rho(M_2 \Phi_\downarrow)) = \text{sen}(M_1 \delta_i^\rho(\Phi_\downarrow), M_2 \delta_i^\rho(\Phi_\downarrow)) \).
Thanks to Lemma 5.6, we know that \( \delta'_1(\Phi_+ \downarrow) \) is in normal form which means that 
\[
\delta'_1(\Phi_+ \downarrow) = f(M_1' \downarrow, M_2') \delta'(\Phi_+ \downarrow).
\]

(b) If the root occurrence of sdec can be reduced and 
root(\( \Phi_+ \downarrow \)) = tag\(_j\), for some \( j \in \{a, b\} \) 
then there exists \( u_1, u_2 \) such that 
\( M_1 \downarrow = \text{senc}(\text{tag}_j(u_1), u_2) \) and 
\( M_2 \downarrow = u_2 \). Hence we have that 
\[
\text{sdec}(\delta'_1(M_1 \downarrow), \delta'_1(\Phi_+ \downarrow)) \downarrow = \delta'_j(\text{tag}_j(u_1)) = \delta'_j(\Phi_+ \downarrow) \downarrow.
\]
On the other hand, we also have 
\[
\text{sdec}(\Phi_+, \Phi_+ \downarrow) = \text{sdec}(M_1' \downarrow, M_2') \delta'(\Phi_+ \downarrow) \downarrow.
\]
Hence, we have that 
\[
\delta'_j(\Phi_+ \downarrow) = \text{sdec}(M_1' \downarrow, M_2') \delta'(\Phi_+ \downarrow) \downarrow.
\]
(c) Else, the root occurrence of sdec can be reduced and 
for all \( j \in \{a, b\} \), root(\( \Phi_+ \downarrow \)) ≠ tag\(_j\). 
In such a case, there exist \( u_1, u_2 \) such that 
\( M_1 \downarrow = \text{senc}(u_1, u_2) \) and 
\( M_2 \downarrow = u_2 \). Moreover, for all \( i \in \{a, b\} \), 
\( \delta'_i(M_1 \downarrow) = \text{senc}(\delta'_1(u_1), \delta'_2(u_2)) \) and 
\( \delta'_2(M_2 \downarrow) = \delta'_2(\Phi_+ \downarrow) \). Hence, we have that 
\[
\text{sdec}(\delta'_i(M_1 \downarrow), \delta'_2(M_2 \downarrow)) \downarrow = \text{sdec}(M_1', M_2') \delta'(\Phi_+ \downarrow) \downarrow.
\]
At last, since 
\[
\text{sdec}(\delta'_1(M_1 \downarrow), \delta'_2(M_2 \downarrow)) \downarrow = \text{sdec}(M_1', M_2') \delta'(\Phi_+ \downarrow) \downarrow,
\]
we have that \( \text{sdec}(M_1, M_2') \delta'(\Phi_+ \downarrow) \downarrow = \delta'_j(\Phi_+ \downarrow) \downarrow \).

We could do the same case analysis for \( \Phi_+ \downarrow \) and we would obtain similar results. Since 
in two cases (a) and (c), the result holds for all \( i \in \{a, b\} \), it only remains to show that for all \( j \in \{a, b\} \), 
the root occurrence of sdec is reduced in \( \Phi_+ \downarrow \) and 
root(\( \Phi_+ \downarrow \)) = tag\(_j\), if and only if, 
the root occurrence of sdec is reduced in \( \Phi_+ \downarrow \) and 
root(\( \Phi_+ \downarrow \)) = tag\(_j\). 
We already showed that the root occurrence of sdec is reduced in \( \Phi_+ \downarrow \) and 
root(\( \Phi_+ \downarrow \)) = tag\(_j\) 
implies that 
\( \delta'_j(\Phi_+ \downarrow) = \text{sdec}(M_1', M_2') \delta'(\Phi_+ \downarrow) \downarrow \).
Thus we have 
\( \text{sdec}(M_1', M_2') \delta'(\Phi_+ \downarrow) \downarrow = \text{tag}_j(\text{untag}_j(\text{sdec}(M_1', M_2'))) \downarrow \).
But by hypothesis, \( \nu E \delta'(\Phi_+ \downarrow) \sim \nu E \delta'(\Phi_+ \downarrow) \).
Hence we have 
\( \text{untag}_j(\text{sdec}(M_1', M_2')) \delta'(\Phi_+ \downarrow) \downarrow = \text{sdec}(\text{tag}_j(v_1), v_2) \downarrow = v_2 \).
Thus for all \( i \in \{a, b\} \), 
\( M_1 \downarrow = \text{senc}(\text{tag}_i(v_1), v_2) \) and 
\( M_2 \downarrow = \text{senc}(\text{tag}_i(v_1), v_2) \).
Hence, for all \( i \in \{a, b\} \), 
\( \delta'_i(\text{tag}_i(v_1), v_2) \) 
and we deduce that there exists \( v'_1 \) and \( v'_2 \) such that 
\( M_2 \downarrow = \text{tag}_i(v'_1), v'_2 \) 
\( v_2 \downarrow = v'_2 \) 
and 
\( v_1 \downarrow = v'_1 \).
We can conclude that the root occurrence of sdec is reduced in \( \Phi_+ \downarrow \) and 
root(\( \Phi_+ \downarrow \)) = tag\(_j\).

The other implication is symmetrical to this one. Hence our result holds.

Case \( f \in \{\text{sdec}, \text{check}\} \): This case is similar to the case \( f = \text{sdec} \).

Case \( f \in \text{proj}_k \), \( k \in \{1, 2\} \): In such a case, we have \( M = f(M_1) \).
Thus we can apply our inductive hypothesis on \( M_1 \) which means that for all \( i \in \{a, b\} \), 
there exists \( M_1' \downarrow = \delta'_i(M_1 \downarrow) \) and 
\( M_1' \downarrow \downarrow = \delta'_i(M_1' \downarrow) \).
Let’s first focus on \( \Phi_+ \downarrow \).

(a) If the root occurrence of \( f \) cannot be reduced, then 
\( \Phi_+ \downarrow = f(M_1' \downarrow) \).
Thus for all \( i \in \{a, b\} \), 
\( \delta'_i(\Phi_+ \downarrow) = f(\delta'_i(M_1 \downarrow)) \).
Thanks to Lemma 5.6 we know that 
\( \delta'_i(\Phi_+ \downarrow) \downarrow = \delta'_i(\Phi_+ \downarrow) \downarrow \).

(b) Else, the root occurrence of \( f \) can be reduced. In such a case there exists \( u_1, u_2 \) such that 
\( M_1 \downarrow = (u_1, u_2) \).
Hence for all \( i \in \{a, b\} \), we have 
\( \delta'_i(M_1 \downarrow) = \delta'_i(u_1), \delta'_i(u_2) \) 
and 
\( f(\delta'_i(u_1), \delta'_i(u_2)) \).
Thus, we conclude that 
\( f(\delta'_i(u_1), \delta'_i(u_2)) \).

We could do the same case analysis for \( \Phi_+ \downarrow \) and we would obtain similar results. Since 
the result holds in both cases, we can conclude.

Second step: Thanks to the first step, we showed that there exists a \( c \in \{a, b\} \), and a term \( M_c \) such that 
frames(\( M_c \)) \cap E = \emptyset, \ fears(\( M_c \)) \subseteq \text{dom}(\Phi_+) \).
Thus we can apply our inductive hypothesis on \( M_1 \) which means that 
\( \phi_1(\Phi_+ \downarrow) \downarrow = \delta'_i(\Phi_+ \downarrow) \downarrow \).
Let \( d \in \{a, b\} \) such that \( d \neq c \).

By Lemma 5.7 we know that there exists two contexts \( C, C' \) (possibly holes) built on \( \{\} \), 
and \( u_1, \ldots, u_m, v_1, \ldots, v_n \) such that 
\( M_1 \downarrow = C[u_1, \ldots, u_m] \) and 
\( M_1' \downarrow = C'[v_1, \ldots, v_n] \).
Hence, we have that 
\( \delta'_i(\Phi_+ \downarrow) = C[\delta'_1(u_1), \ldots, \delta'_i(u_m)] \) and 
\( \delta'_i(\Phi_+ \downarrow) = C'[\delta'_1(v_1), \ldots, \delta'_i(v_n)] \).
Our hypothesis implies 
\( M_1' \downarrow = \delta'_i(\Phi_+ \downarrow) \downarrow \).
But \( \nu E \delta'(\Phi_+ \downarrow) \sim \nu E \delta'(\Phi_+ \downarrow) \).
Therefore, since \( C \) and \( C' \) are both built upon \( \{\} \), we deduce that 
\( C = C' \) and \( n = m \).
Note that it also implies that there exists \( D_1, \ldots, D_n \) contexts built on 
\( \text{proj}_1, \text{proj}_2 \) such that for all \( k \in \{1, \ldots, n\} \), 
\( D_k(M_1 \downarrow) \delta'(\Phi_+ \downarrow) \downarrow = \delta'_c(u_k) \) and 
\( D_k(M_1 \downarrow) \delta'(\Phi_+ \downarrow) \downarrow = \delta'_c(v_k) \).

Lemma 5.7 also tells us that for all \( k \in \{1, \ldots, n\} \),

- either \( u_k \in \text{Flawed}(\Phi_+ \downarrow) \);
• or \( u_k \in \text{Fct}_{\rho_z}(M \Phi_\downarrow) \) and \( \delta_\rho'(u_k) = \delta_\rho'(u_k) 
olonger
• or \( u_k = f(n) \) for some \( f \in \{pk, vk\} \) and \( n \in N \),
• or \( u_k \in N \).

Thus, we build \( M_d \) such that \( M_d = C[N_1, \ldots, N_n] \) where, for all \( k \in \{1, \ldots, n\} \),

(a) if \( \delta_\rho'(u_k) = \delta_\rho'(u_k) \) then \( N_k = D_k(M_c) \)

(b) else if \( u_k \in \text{Flawed}(M \Phi_\downarrow) \), then by Lemma \[\text{B.3}\] there exists \( f \) and \( M_1, \ldots, M_t \) such that

for all \( i \in \{1, \ldots, \ell\} \), \( M(M_i) \prec M(M) \) and \( u_k = f(M_1 \Phi_\downarrow, \ldots, M_t \Phi_\downarrow) \). But by our inductive hypothesis on \( M_1, \ldots, M_t \), we have that there exists \( M_1', \ldots, M_t' \) such that for all \( i \in \{1, \ldots, \ell\} \),

\[ M_i' \delta_\rho'(\Phi_\downarrow) \downarrow = \delta_\rho'(M_i \Phi_\downarrow) \downarrow \]

and \( M_i' \delta_\rho'(\Phi_\downarrow') \downarrow = \delta_\rho'(M_i \Phi_\downarrow') \downarrow \). Therefore:

\[ f(M_1 \Phi_\downarrow, \ldots, M_t \Phi_\downarrow) + f(M_1 \Phi_\downarrow', \ldots, M_t \Phi_\downarrow') \downarrow = \delta_\rho'(f(M_1 \Phi_\downarrow, \ldots, M_t \Phi_\downarrow')) \downarrow \]

We define \( N_k = f(M_1', \ldots, M_t') \). We know that \( N_k \delta_\rho'(\Phi_\downarrow) \downarrow = \delta_\rho'(u_k) \), thus it remains to show that

\( N_k \delta_\rho'(\Phi_\downarrow') \downarrow = \delta_\rho'(v_k) \). Our inductive hypothesis on \( M_1, \ldots, M_t \) allows us to show that there exists \( M_1', \ldots, M_t' \) such that

\( f(M_1, \ldots, M_t) \delta_\rho'(\Phi_\downarrow) \downarrow = \delta_\rho'(u_k) \). But \( \delta_\rho'(u_k) = D_k(M_c) \delta_\rho'(\Phi_\downarrow) \downarrow \).

Since \( \delta_\rho'(\Phi_\downarrow) \sim \delta_\rho'(\Phi_\downarrow') \), we deduce that \( D_k(M_c) \delta_\rho'(\Phi_\downarrow') \downarrow = f(M_1', \ldots, M_t') \delta_\rho'(\Phi_\downarrow') \downarrow \).

Hence we have that \( \delta_\rho'(u_k) = \delta_\rho'(f(M_1', \ldots, M_t') \Phi_\downarrow) \downarrow \). By applying Lemma \[\text{B.3}\] we obtain that

\( f(M_1', \ldots, M_t') \Phi_\downarrow = v_k \) and so \( N_k \delta_\rho'(\Phi_\downarrow') \downarrow = \delta_\rho'(v_k) \).

(c) else if \( u_k \in f(n) \) for some \( f \in \{pk, vk\} \) and \( n \in N \), then \( D_k(M_c) \delta_\rho'(\Phi_\downarrow) \downarrow = f(\delta_\rho'(n)) \), i.e. \( f(\delta_\rho'(n)) \) is deductible. If \( n \notin \text{img}(\rho) \) then \( \delta_\rho'(u_k) = \delta_\rho'(u_k) \) and so it is the same as case (a). Else by hypothesis on \( \delta_\rho'(\Phi_\downarrow) \), we have that \( n \in \text{img}(\rho) \) implies that \( f(\delta_\rho'(n)) \in \text{img}(\rho(\Phi_\downarrow \cup \Phi_\downarrow')) \).

By construction of \( \Phi_a \) and \( \Phi_b \), we know that there exist \( (ax_1 \downarrow \Phi(\delta_\rho'(n)), ax_2 \downarrow \Phi(\delta_\rho'(n))) \) in \( \delta_\rho'(\Phi_\downarrow \cup \Phi_\downarrow') \) with \( \text{col}(ax_1 \downarrow \Phi) = d \) and \( \text{col}(ax_2 \downarrow \Phi) = c \) and some \( \ell \in N \).

We define \( N_k = ax_1 \downarrow \Phi \). It remains to show that \( ax_1 \downarrow \Phi(\delta_\rho'(n)) \downarrow = \delta_\rho'(v_k) \). But we have \( ax_2 \downarrow \Phi(\delta_\rho'(n)) \downarrow = D_k(M_c) \delta_\rho'(\Phi_\downarrow) \downarrow \).

Thanks to our hypothesis \( \delta_\rho'(\Phi_\downarrow) \sim \delta_\rho'(\Phi_\downarrow') \), we deduce that \( ax_2 \downarrow \Phi(\delta_\rho'(n)) \downarrow = D_k(M_c) \delta_\rho'(\Phi_\downarrow) \downarrow \).

By definition of \( \Phi_a' \), we have that \( ax_2 \downarrow \Phi(\delta_\rho'(n)) \downarrow = f(\delta_\rho'(n)) \) which means that \( \delta_\rho'(v_k) = D_k(M_c) \delta_\rho'(\Phi_\downarrow) \downarrow = \delta_\rho'(f(n)) \). By applying Lemma \[\text{B.3}\] we obtain that \( v_k = f(n) \). At last, by definition of \( \Phi_a' \), we have that \( ax_2 \downarrow \Phi(\delta_\rho'(n)) \downarrow = \delta_\rho'(f(n)) = \delta_\rho'(v_k) \).

(d) Else \( u_k \in N \). But by hypothesis on \( \delta_\rho'(\Phi_\downarrow) \), we know that \( n \in \text{img}(\rho) \) implies \( \delta_\rho'(n) \) is not deductible from \( \delta_\rho'(\Phi_\downarrow) \). Thus \( u_k \notin \text{img}(\rho) \) and so \( \delta_\rho'(u_k) = \delta_\rho'(u_k) \), which leads to \( N_k = D_k(M_c) \), i.e. same as case (a).

We showed that for such \( M_d = C[N_1, \ldots, N_n] \), we have that \( M_d \delta_\rho'(\Phi_\downarrow) \downarrow = \delta_\rho'(C[u_1, \ldots, u_n]) \) and \( M_d \delta_\rho'(\Phi_\downarrow') \downarrow = \delta_\rho'(C[v_1, \ldots, v_n]) \), which leads to \( M_d \delta_\rho'(\Phi_\downarrow) \downarrow = \delta_\rho'(M \Phi_\downarrow) \downarrow \) and \( M_d \delta_\rho'(\Phi_\downarrow') \downarrow = \delta_\rho'(M \Phi_\downarrow') \downarrow \).

For the next two lemmas, i.e. soundness and completeness, we consider \( E_0 \) a set of private names and \( P_a, P_b \) two processes without name restriction or replication, and coloured respectively by \( a \) and \( b \). At last consider \( \rho \) a renaming such that:

• \( \text{dom}(\rho) \cup \text{img}(\rho) \subseteq E_0 \) and \( \text{dom}(\rho) \) do not appear in \( P_a, P_b, \Phi_a \) or \( \Phi_b \).

• for all \( i \in \{a, b\} \), there exists \( P_i \) built on \( F_i \cup F_0 \) such that \( P_i = [P_i'] \).

• for all \( i \in \{a, b\} \), \( \text{frames}(P_i) \cap Ch \subseteq \text{dom}(\rho C_{\text{hl}}) \) and \( \text{img}(\rho C_{\text{hl}}) \) does not appear in \( P_a \) or \( P_b \).

We will denote \( D = (E_0; \{P_a \rho C_{\text{hl}}, P_b \rho^{-1} C_{\text{hl}}\}; \Phi_a \cup \Phi_b \rho^{-1}) \) and \( S = (E_0; \{P_a, P_b\}; \Phi_a \cup \Phi_b) \). We assume that \( P_a \) and \( P_b \) do not share any private channel name, i.e. \( \text{frames}(P_a) \cap \text{frames}(P_b) \cap \text{Ch} \cap E_0 = \emptyset \), and \( \rho \) does not appear of \( \text{Ch} \) type.

**Lemma 5.14** (Soundness). If for all \( \tau, \Phi \in \text{trace}(D) \), for all \( u \in \{vk(k) \mid k \in \text{img}(\rho) \cup \text{dom}(\rho)\} \), \( \nu E_0, \Phi \vdash u \) implies that \( u \in \text{img}(\Phi_a \cup \Phi_b \rho^{-1}) \), then for all \( S \overset{\omega}{\twoheadrightarrow} (E_0; \tau, \Phi) \) such that \( \Phi_\downarrow = \delta_\rho'(\Phi_\downarrow) \).

Furthermore, if \( w = \ell_1, \ldots, \ell_n \) then \( w' = \ell_1', \ldots, \ell_n' \) such that for all \( k \in \{1, \ldots, n\} \),
• if $\ell_k = \nu x_m.\text{out}(c.\text{ax}_m)$ is an output coming from a process coloured by $i \in \{a, b\}$, then $\ell'_k = \nu x_m.\text{out}(c\Phi_{ch_i}.\text{ax}_m)$

• if $\ell_k = \text{in}(c.\mathcal{M})$ is an input coming from a process coloured by $i \in \{a, b\}$, then $\ell'_k = \text{in}(c\Phi_{ch_i}.\mathcal{M}_i)$ with $M_i\Phi_{D \downarrow} = \delta'_i(M\Phi_{S \downarrow})$.

• if $\ell_k = \text{out}(d.\mathcal{D})$ is an output coming from a process coloured by $i \in \{a, b\}$ with $d$ a channel name, then $\ell'_k = \text{out}(d\Phi_{ch_i}.d\Phi_{ch_i})$

• if $\ell_k = \nu v\text{ch}_m.\text{out}(c.\text{ch}_m)$ is an output coming from a process coloured by $i \in \{a, b\}$ with $\text{ch}_m$ a channel name, then $\ell'_k = \nu v\text{ch}_m.\text{out}(c\Phi_{ch_i}.\text{ch}_m)$

• if $\ell_k = \tau$, then $\ell'_k = \tau$.

Proof. We have that $S \xrightarrow{w} (E_0; P''_S; \Phi''_S)$. We will show by induction on $|w|$ the properties stated in the lemma but also that there exists $(P_a, \alpha_a)$ and $(P_b, \alpha_b)$ two original well-tagged multi-sets of processes such that $\text{col}(P_a) = a$, $\text{col}(P_b) = b$, $P'_S = P_a\alpha_a \uplus P_b\alpha_b$ and $P''_D = P''_D \uplus P''_D$ with for all $i \in \{a, b\}$, $P''_D \uplus \delta'_i(P)\rho_{ch_i}\delta'_i(\alpha_i)$.

Base case $|w| = 0$: In this case, we need to verify that $S$ and $D$ satisfy the wanted properties. By hypothesis on $S$ and $D$, we have that $S = (E_0; P''_S; \Phi''_S)$ and $D = (E_0; P''_S; \Phi''_S)$ such that $P''_S = \{P''_a\}, \Phi''_S = \Phi''_a \uplus \Phi''_b$, $P''_D = \{\delta''_a(P''_a)\rho_{ch_a}\delta''_a(\alpha_a), \delta''_b(P''_b)\rho_{ch_b}\delta''_b(\alpha_b)\}$ and $\Phi''_S = \delta''(\Phi''_S)$.

Thus by definition of an original well-tagged multi-set of processes, we define $P_a = \{P''_a\}$, $\alpha_a = id$, $P_b = \{P''_b\}$, $\alpha_b = id$. Hence, we have $\delta''_a(\alpha_a) = id$ and so $P''_D \uplus \delta''(P')\rho_{ch_i}\delta''(\alpha_i)$, for all $i \in \{a, b\}$.

Furthermore, we know by hypothesis that for all $(w \triangleright u) \in \Phi_A \uplus \Phi_D$, $u = f(n)$ for some $f \in \{pk, vk\}$ and $n \in N$. Hence we have that $|u| = u$ and $\text{test}_i(u) = true$ for all $i \in \{a, b\}$, which implies that $\Phi_S$ is well-tagged and in normal form.

At last, $\delta''(\Phi_A) = \Phi_A$ and $\delta''(\Phi_B) = \Phi_B\rho_0^{-1}$, hence we have that $\Phi''(\Phi_{S \downarrow}) = \Phi_{D \downarrow}$.

Inductive case $|w| > 0$: In this case, we have that $w = w_1.f$ and so $S \xrightarrow{w_1} (E_0; P''_S; \Phi''_S) \xrightarrow{f} (E_0; P''_S; \Phi''_S)$ with no internal communication between two processes of different colors. Hence, by inductive hypothesis on $w_1$, we have that there exists $D \xrightarrow{w_1} (E_0; P''_D; \Phi''_D)$, $(P''_a, \alpha''_a)$ and $(P''_b, \alpha''_b)$ two original well-tagged multi-sets of processes such that:

- $\Phi''_D \downarrow = \delta''(\Phi''_S)$
- $\Phi''_S$ is well-tagged
- $P''_D = P''_a\alpha''_a \uplus P''_b\alpha''_b$ and $P''_D = P''_D \uplus P''_D$ with for all $i \in \{a, b\}$, $P''_D \uplus \delta'_i(P)\rho_{ch_i}\delta'_i(\alpha_i)$
- for all $k \in \{1, \ldots, |w| - 1\}$, $\ell_k$ satisfies the desired properties.

We proceed by case analysis on the rule applied for the transition $(E_0; P''_S; \Phi''_S) \xrightarrow{f} (E_0; P''_S; \Phi''_S)$.

Since by hypothesis, we know that there is no internal communication between two processes of different colors, and $P''_S = P''_a\alpha''_a \uplus P''_b\alpha''_b$ we can assume that a rule is applied on $P'_i\alpha''_i$, with $i \in \{a, b\}$. Let $j \in \{a, b\}$ such that $i \neq j$.

Case of the rule THEN: In this case, by definition of $P'_i\alpha''_i$, there exists $\phi$ and $Q_1, Q_2$ processes and $Q'_i \subseteq P'_i$ such that $P''_S = \{if \phi then [Q_1]_i\alpha''_i \ else [Q_2]_i\alpha''_i \ uplus Q'_i\alpha''_i \ uplus P'_{i'}\alpha''_{i'}\}$, $P''_D = \{[Q_1]_i\alpha''_i \ uplus Q'_i\alpha''_i \ uplus P'_{i'}\alpha''_{i'}\}$, $\Phi''_S = \Phi''_S$ and $\phi$ is a conjunction of equations ($u = v$). By definition, we have that $([Q_1]_i\alpha''_i \ uplus [Q_2]_i\alpha''_i)$ are both original well-tagged processes.

Furthermore, we have that for all equation ($u = v$) in $\phi$, $u = v$; and either (a) there exists $u$ such that $\phi$ is the formula $\text{test}_i([u_1],\alpha''_i)$, or (b) there exists $u_1, u_2$ such that $\phi$ is the formula $[u_1],\alpha''_i = [u_2],\alpha''_i$ and $\phi = \text{test}_i([u_1],\alpha''_i) \land \text{test}_i([u_2],\alpha''_i)$.

But we also have $P''_D \uplus \delta''(P')\rho_{ch_i}\delta''(\alpha_i)$, which means that there exists $\phi'$ and $Q'_1, Q'_2$ processes and $Q_D \subseteq P'_D$, such that $P''_D = \{if \phi' then [Q'_1] \ else [Q'_2] \ uplus Q_D \ uplus P''_D$ with $Q''_D = \{[Q'_1] \ uplus [Q'_2] \ uplus Q_D \ uplus P''_D$. We will show by induction on $|w|$ and by the property of $\delta''(P)\rho_{ch_i}\delta''(\alpha_i)$ that $P''_D \uplus \delta''(P')\rho_{ch_i}\delta''(\alpha_i)$.
δ′_i(\{Q_1\}_\rho \delta_i(\alpha'_i)). Q'_2 \downarrow = δ′_i(\{Q_2\}_\rho \delta_i(\alpha'_i)). Furthermore, in case (a) ϕ^\downarrow is the formula test(δ′_i(\{u\}_\rho))δ_i(\alpha'_i)↓; and in case (b) ϕ is the formula (u′ = v′) where u′_↓ = δ′_i(\{u\}_\rho)δ_i(\alpha'_i)↓ and v′_↓ = δ′(\{u\}_\rho)δ_i(\alpha'_i)↓.

In case (a), for all equation (u′ = v′) ∈ φ, u′_↓ = v′_↓ which is equivalent to u′_↓ = v′_↓. Thus it is equivalent to (α'_i) ⊨ test(\{u\}_\rho). But by Lemma B.3 we know that this is equivalent to δ′_i(α'_i) ⊨ test(δ′(\{u\}_\rho)). Thus we have that for all equation (u′ = v′) of test(δ′(\{u\}_\rho)), u′_↓ = v′_↓ = δ′_i(\alpha'_i)↓. Since ϕ_↓ is the formula test(δ′(\{u\}_\rho))δ′_i(\alpha'_i)↓, we can conclude that for all equation (u′ = v′) of ϕ, u_↓ = v_↓ and so u′_↓ = v′_↓.

In case (b), we know that α_i ⊨ test(\{u\}_\rho) and \{u\}_\rho, α'_i_↓ = \{u\}_\rho, α'_i_↓. Thus by Corollary B.3, we can deduce that δ′_i(\{u\}_\rho)δ_i(\alpha'_i)↓ = δ′_i(\{u\}_\rho)δ_i(\alpha'_i)↓ which means that u_↓ = v_↓ and so u′_↓ = v′_↓.

ϕ being satisfied in both cases allows us to deduce that (E_0; P′_2, Φ'_2) \overset{\to}{\Rightarrow} (E_0; \{Q'_1\} \uplus Q'_2 \uplus \rho \Phi'_2).

Thus, we have Φ'_2 = Φ'_2, but Φ'_2 = Φ'_2, hence we have that Φ'_2 is well-tagged and Φ'_2 = δ′_i(Φ'_2). Furthermore, let ℓ′ = ℓ = τ and P_i = \{Q_1\}_\rho \uplus \{Q'_1\} \uplus \{Q_2\}_\rho \uplus \rho \Phi'_2. By definition of [Q_1], we have that (P_i, α_i) and (P_j, α_j) are both original well-tagged multisets of processes.

We already showed that P_*= P_α \uplus P_α and thanks to Q'_1 \downarrow = δ′_i(\{Q_1\}_\rho \rho \delta_i(\alpha'_i)↓), we can deduce that P_{D↓} = δ′(\{P_1\}_\rho \delta_i(\alpha'_i)↓ \uplus \rho \Phi'_2)\delta_i(\alpha'_i)↓ which means that the result holds.

Case of the rule ELSE: This case similar to the rule THEN.

Case of the rule COMM: In this case, by definition of (P'_1, α'_1), there exists u, x, p, t, processes and Q'_1, Q'_2 processes that P'_2 = \{out(p, [u], α'_1); [Q_1], α_i; in(p, x), [Q_2], α_i \uplus \rho \Phi'_2, P'_1 \uplus \rho \Phi'_2, P'_2 = \{\{Q_1\}_\rho \{Q_2\}_\rho \{x \mapsto [u], α_i\} \uplus \rho \Phi'_2 \uplus \rho \Phi'_2, Φ'_2 = Φ'_2 and α_i \uplus test(\{u\}_\rho).

First of all, we trivially have that Φ'_2 is well-tagged.

Furthermore, we have P′_2 \downarrow = \delta′_i(\{P'_1\}_\rho \rho \delta_i(\alpha'_i)↓), which means that there exists p, u, t, processes such that P′_2 = \{out(p, u, \lambda \rho \Phi'_2, P'_1 \uplus \rho \Phi'_2, P′_2, P'_1 \uplus \rho \Phi'_2, P'_2 = \{\{Q_1\}_\rho \{Q_2\}_\rho \{x \mapsto u\} \uplus \rho \Phi'_2 \uplus \rho \Phi'_2, Φ'_2 = Φ'_2 and α_i \uplus test(\{u\}_\rho).

Let Φ'_2 = Φ'_2. Since Φ'_2 = Φ'_2, then by hypothesis, we have that Φ'_2 = δ′_i(Φ'_2). Let’s denote α_i = α'_i \{x \mapsto [u], α_i\}. We already know that α_i \uplus test(\{u\}_\rho). Thus thanks to Lemma B.3 and (α'_i) ⊨ test(\{u\}_\rho), we deduce that u_↓ = v_↓ = δ′(\{u\}_\rho)δ′(\alpha'_i)↓. This implies that δ′(\alpha'_i)↓ = δ′(\alpha'_i)↓ \{x \mapsto u\}↓. But Q'_2 \{x \mapsto u\}↓ = (Q'_2↓) \{x \mapsto u\}↓, hence Q'_2 \{x \mapsto u\}↓ = \delta′_i(\{Q_2\}_\rho \delta_i(\alpha'_i)↓).

Moreover, since x \notin \text{fvars}(\{Q_1\}_\rho \uplus \text{fvars}(\{Q'_2\}_\rho)), we can deduce that (\{Q_1\}_\rho \delta_i(\alpha'_i), \{Q'_{2} \delta_i(\alpha'_i)↓\}) \uplus \rho \Phi'_2 = (\{Q_1\}_\rho \delta_i(\alpha'_i)↓) \uplus \rho \Phi'_2 = (\{Q'_2 \delta_i(\alpha'_i)↓\}) \uplus \rho \Phi'_2 = (\{Q_1\}_\rho \delta_i(\alpha'_i)↓) \uplus \rho \Phi'_2. Thus, we have that (\{\{Q_1\}, \{Q_2\}_\rho \uplus \rho \Phi'_2, \alpha_i) is an original well-tagged multi-set of processes. Hence the result holds.

Case of the rule IN: In this case, by definition of (P'_1, α'_1), there exists x, p, M, t, processes, Q'_1 \uplus \rho \Phi'_2 = \rho, \text{fvars}(M) \subseteq \text{dom}(\rho \Phi'_2) and \text{fnames}(M) \cap E_0 = \emptyset such that P'_2 = \{in(p, x), [Q_1], α_i \uplus \rho \Phi'_2, P'_1 \uplus \rho \Phi'_2, P'_2 = \{[Q_1], \alpha_i \{x \mapsto u\}\} \uplus \rho \Phi'_2 \uplus \rho \Phi'_2, Φ'_2 = Φ'_2 and α_i \uplus test(\{u\}_\rho).

We trivially have that Φ'_2 is well-tagged.

Furthermore, we have P′_2 \downarrow = \delta′_i(\{P'_1\}_\rho \rho \delta_i(\alpha'_i)↓), which means that there exists p, u, t, processes such that P′_2 = \{in(p, x), \lambda \rho \Phi'_2, P'_1 \uplus \rho \Phi'_2, P′_2, P'_1 \uplus \rho \Phi'_2, P'_2 = \{[Q_1], \alpha_i \{x \mapsto u\}\} \uplus \rho \Phi'_2 \uplus \rho \Phi'_2, Φ'_2 = Φ'_2 and α_i \uplus test(\{u\}_\rho).

By hypothesis, we assumed that for all v \in \{k, v(k), pk(k) | k \in \text{img}(\rho) \uplus \text{dom}(\rho)\}, v \in \text{img}(\Phi'_3), where \Phi'_3 = \delta′_i(\rho \Phi'_2)↓. Thus, thanks to Lemma B.13, we have that there exists a term \text{fvars}(M) \subseteq \text{dom}(\rho \Phi'_2), \text{fnames}(M) \cap E_0 = \emptyset and M, \rho \Phi'_2 = \delta′_i(M \Phi'_2↓). Thus, with \ell′ = \text{in}(pp \rho \Phi'_2, M_i), we can deduce that (E_0; P'_2; P'_2) \overset{\to}{\Rightarrow} (E_0; \{Q'_1 \{x \mapsto u\}\} \uplus \rho \Phi'_2 \uplus \rho \Phi'_2) where u′_↓ = M_i \Phi'_2↓.
But $M\Phi_q^\downarrow = u_\downarrow$ and $M_i\Phi_q^\downarrow = u_i^\downarrow$. Thus, we have that $\delta^\rho(u_\downarrow) = u'\downarrow$. Since $Q'\downarrow = \delta^\rho([Q_1];_\rho\rho_n,\delta^\rho(\alpha_i)_\downarrow)$, we deduce that $Q'\downarrow(x \mapsto u'\downarrow) = \delta^\rho([Q_1];_\rho\rho_n,\delta^\rho(\alpha_i)_\downarrow(x \mapsto \delta^\rho(u_\downarrow))$.

Let $\alpha_i = \alpha_i'(x \mapsto u')$, we have that $\delta^\rho(x \mapsto \alpha_i') = \delta^\rho(\alpha_i')_\downarrow = \delta^\rho(Q'_\downarrow)\downarrow$ and $Q'\downarrow(x \mapsto u') = \delta^\rho([Q_1];_\rho\rho_n,\delta^\rho(\alpha_i)_\downarrow)$ and $Q'\downarrow(x \mapsto u') = \delta^\rho([Q_1];_\rho\rho_n,\delta^\rho(\alpha_i)_\downarrow)$, Moreover, since $x \notin \text{feats}(Q'_\downarrow)$, we can deduce that $Q'_\downarrow = \delta^\rho([Q_1];_\rho\rho_n,\delta^\rho(\alpha_i)_\downarrow)$ and $Q'\downarrow = \delta^\rho(\alpha_i')_\downarrow$. Thus, we have that $([Q_1];_\rho\rho_n,\alpha_i)$ is an original well-tagged multi-set of processes. Hence the result holds.

Case of the rule $\text{Out-T}$: In such a case, by definition of $(P'_i,\alpha'_i)$, there exists $u,p$ terms and $Q_1$ process such that $Q'_i \subseteq P'_i$ such that $P'_i = \{\text{out}(p,u),[Q_1];_\rho\rho_n,\alpha'_i\} \sqcup P'_i$, $P'_i = \{[Q_1];_\rho\rho_n,\alpha'_i\} \sqcup Q'_i \sqcup P'_i$, $P'_i = \{[Q_1];_\rho\rho_n,\alpha'_i\} \sqcup Q'_i \sqcup P'_i$, $\Phi'_i = \Phi'_i \sqcup \{\alpha'_i\}$ and $\alpha'^i \models \text{test}(\{u\}_i)$. Furthermore, we have that $\ell = \nu\alpha'_i$., out($p,\alpha'_i$).

Moreover, we have $P'_i \downarrow = \delta^\rho(P'_i)\rho\rho_n,\delta^\rho(\alpha'_i)_\downarrow$, which means that there exists $p',u'$ terms and $Q'_i$ process such that $P'_i = \{\text{out}(p',u'),Q'_i\} \sqcup P'_i \sqcup P'_i$, with $\delta^\rho(\alpha'_i)_\downarrow = \delta^\rho([Q_1];_\rho\rho_n,\alpha'_i)_\downarrow$, $p' = p'\downarrow = \delta^\rho(p)\rho\rho_n, \rho\rho_n,\rho\rho_n,\rho\rho_n,\rho\rho_n,\rho\rho_n$, and $u'\downarrow = \delta^\rho([u\downarrow])\rho\rho_n,\alpha'_i)_\downarrow$. Hence for $\ell'_i = \nu\alpha'_{i},\text{out}(p,p,\alpha'_i)$, we have that $(E_0; P'_i; \Phi'_i) \xrightarrow{\ell'_i} (E_0; Q'_i \sqcup P'_i; \Phi'_i)$.

We first need to show that $\Phi'_i$ is well-tagged. Since $\Phi'_i$ is well-tagged, we only need to focus on the new term $[u\downarrow]\alpha'_i$. Let $x \in \text{dom}(\alpha'_i)$, we know that $x$ was initially a variable from $S$. Thus, $x$ was introduced by an input $\text{in}(x,c)$ for some $c$ and so there exists a transition $\ell_x$ in $w_1$ such that this transition reduces $\text{in}(c,x)$. If $\ell_x = \text{in}(c,M)$ (i.e., the rule In), then we trivially have that the result holds with $M$; else $\ell_x = \tau$ (i.e., the rule Comm). But in the case $\ell_x = \tau$, we know that the output comes from a process colored by $i$ and so there exists $v$ such that $\alpha'_i = [v]\alpha'_i$. Thus with a simple induction on the size of $w_1$, we can show that $\Phi'_i$ is well-tagged.

Since all variables in $[u\downarrow]$ are colored by $i$, then thanks to Lemma 2 and $\alpha'^i \models \text{test}((u\downarrow)_i)$, $\delta^\rho([u\downarrow])\rho\rho_n,\alpha'_i)_\downarrow = \delta^\rho([u\downarrow])\rho\rho_n,\alpha'_i)_\downarrow = \delta^\rho(u\downarrow)_\downarrow$. But $u'\downarrow = \delta^\rho([u\downarrow])\rho\rho_n,\alpha'_i)_\downarrow$, which means that $u'\downarrow = \delta^\rho(u\downarrow)_\downarrow$. Since $\text{coll}(w_1) = i$, we can conclude that $\Phi'_i \downarrow = \delta^\rho(\Phi'_i)$, hence the result holds.

At last, let $\alpha_i = \alpha'_i$, we have that $([Q_1];_\rho\rho_n,\alpha_i)$ is an original well-tagged multi-set of processes. Hence our result holds.

Case of the rule $\text{Out-Ch}$: Obvious since $\text{dom}(\rho)$ and $\text{img}(\rho)$ only contain names of base type and so if $\ell = \text{out}(c,d)$, since $c$ and $d$ are public then $\ell' = \text{out}(c\rho\rho_n, d\rho\rho_n)$.

Case of the rule $\text{Open-Ch}$: Obvious since $\text{dom}(\rho)$ and $\text{img}(\rho)$ only contain names of base type and so if $\ell = \text{vchout}(c, ch)$, since $c$ is public and $\text{dom}(\rho\rho_n)$ is only composed of public channels, then $\ell' = \text{vchout}(c\rho\rho_n, ch\rho\rho_n)$.

Case of the rule $\text{Par}$: Obvious

Lemma 5.15 (Completeness). Let $D \xrightarrow{w} (E_0; P_D; \Phi_D)$. Let $\Phi_+$ be a ground well-tagged frame such that $\Phi_+ = \Phi_+ \sqcup \Phi_\rho \sqcup \Phi$ for some $\Phi$, and $\Phi_+, \Phi_D$ have the same colours. If the following properties are satisfied:

- $w = \ell_1, \ldots, \ell_n$
- $\nu\epsilon_0, \epsilon_0, \Phi_D \sim \nu\epsilon_0, \delta^\rho(\Phi_+)$
- for all $u \in \{k, v(k), p(k) \mid k \in \text{img}(\rho) \cup \text{dom}(\rho)\}$, $\nu\epsilon_0, \delta^\rho(\Phi_+) \vdash u$ or $\nu\epsilon_0, \Phi_D \vdash u$ implies that $u \in \text{img}(\Phi_+ \sqcup \Phi_\rho \rho^{-1})$
- for all $k \in \{1, \ldots, n\}$, if $\ell_k = \text{in}(c, M_k)$ with $c \in \text{img}(\rho\rho_n)$, $i \in \{a, b\}$ then there exists $M_k$ such that $M_k \delta^\rho(\Phi_+)_\downarrow = \delta^\rho(M_k \Phi_+)_\downarrow$.

then there exists a label $w' = \ell'_1, \ldots, \ell'_n$ and a well-tagged frame $\Phi_S$ such that $S \xrightarrow{w'} (E; P_S; \Phi_S)$, $\Phi_D \downarrow = \delta^\rho(\Phi_S)_\downarrow$, and for all $k \in \{1, \ldots, n\}$,

- if $\ell_k = \nu\alpha_{i},\text{out}(c, ax)$ with $c \in \text{img}(\rho\rho_n)$, $i \in \{a, b\}$ then $\ell'_k = \nu\alpha_{i},\text{out}(c\rho\rho_n, ax)$
- if $\ell_k = \text{in}(c, M_k)$ with $c \in \text{img}(\rho\rho_n)$, $i \in \{a, b\}$, then $\ell'_k = \text{in}(c\rho\rho_n, M_k)$.

\qed
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- if \( \ell_k = \text{out}(c, d) \) with \( c \in \text{img}(\rho_{ch_i}) \), \( i \in \{a, b\} \) and \( d \) a channel name, then \( \ell_k' = \text{out}(c, d)\rho_{ch_i}^{-1} \)
- if \( \ell_k = \nu ch_{m}.\text{out}(c, ch_{m}) \) with \( c \in \text{img}(\rho_{ch_i}) \), \( i \in \{a, b\} \) and \( ch_{m} \) a channel name, then \( \ell_k' = \nu ch_{m}.\text{out}(c\rho_{ch_i}^{-1}, ch_{m}) \)
- if \( \ell_k = \tau \) then \( \ell_k' = \tau \)

Proof. The proof of this Lemma is very similar to the proof of Lemma \ref{lem:second_result}. Indeed, in the proof of Lemma \ref{lem:second_result} we used Lemma \ref{lem:third_result} to show that \( \alpha = \text{test}_i([u_i]) \) implies that \( \delta''(\alpha) = \text{test}_i([\delta'(u_i)]) \). But Lemma \ref{lem:second_result} shows that those two properties are equivalent. The same goes for Corollary \ref{cor:second_result}

The only difference is that in the case of the rule IN, Lemma \ref{lem:second_result} cannot be called. Intuitively, Lemma \ref{lem:second_result} allows us to show that for all recipes applied on \( \Phi_S \), we can create an equivalent recipe for \( \Phi_D \); but not the other way around. On the other hand, the new hypothesis is added in this lemma (the last one) which is the corresponding result of Lemma \ref{lem:second_result}.

Indeed we have \( \nu \mathcal{E}_0, \delta'(\Phi_+), \Phi''_S \) well tagged and \( \Phi''_D \downarrow = \delta'(\Phi''_S) \). Thus we have that \( \nu \mathcal{E}_0, \delta'(\Phi_+), \Phi''_S \) well tagged. But with our inductive step, we would have \( \Phi''_D = \Phi'_D, \Phi''_S \) well tagged and \( \Phi'_{D} \downarrow = \delta'(\Phi''_S) \). Let \( M_k \) be the recipe from an input. By hypothesis, we have that \( M_k \delta'(\Phi_+), \Phi''_S \) well tagged. But by Lemma \ref{lem:second_result} there exists \( M \) such that \( M \delta'(\Phi_+), \Phi''_S \) well tagged. But \( M \delta'(\Phi_+), \Phi''_S \) well tagged implies \( M_k \delta'(\Phi_+), \Phi''_S \) well tagged, which allows us to conclude that \( M_k \delta'(\Phi''_S) \downarrow = M_k \Phi''_D \downarrow = \delta'(\Phi''_S) \).

We conclude this appendix with the proof of Theorem \ref{thm:second_result}.

**Theorem 5.2.** Let \( P_A, P_A' \) (resp. \( P_B, P_B' \)) be two sequences of plain processes built \( F_a \cup F_0 \) (resp. \( F_b \cup F_0 \)). Let \( K_0 \) be a finite set of names of base type, and \( C \) and \( C' \) be two composition contexts. Let \( K_0' \) be a subset of \( K_0 \) such that \( K_0' = \text{names}(P_A, P_A') \cap \text{names}(P_B, P_B') \). Let \( \Phi_0 = \{ ax_i \triangleright f_i(k_1), \ldots , ax_n \triangleright f_i(k_n) \} \) with \( f_i \in \{ pk, vk \} \) and \( k_i \in K_0 \) for any \( i \in \{1, \ldots , n\} \). Assume that the processes \((K_0; C[[P_A]_a]; \Phi_0)\) and \((K_0; C[[P_B]_b]; \Phi_0)\) (resp. \((K_0; C[[P_A']_a]; \Phi_0)\), and \((K_0; C[[P_B']_b]; \Phi_0)\)).

- do not reveal any key in \( \{k; pk(k), vk(k) \mid k \in K_0'\} \) unless the key occurs explicitly in \( \Phi_0 \); and
- do not reveal any shared key in \( C \) (resp. \( C' \)).

Lastly, we assume that plain processes \( P_A \), \( P_A' \) and \( P_B \), \( P_B' \) do not use variable of channel type. In such a case,

\[
(K_0; C[[P_A]_a]; \Phi_0) \approx_t (K_0; C'[[[P_A']_a]; \Phi_0) \\
(K_0; C[[P_B]_b]; \Phi_0) \approx_t (K_0; C'[[[P_B']_b]; \Phi_0)
\]

\[
(K_0; C[[P_A]_a \mid [P_B]_b]; \Phi_0) \approx_t (K_0; C'[[[P_A']_a \mid [P_B']_b]; \Phi_0)
\]

Proof. Before we start the proof, we rename \( \Phi_0 \) into \( \Phi_0' \). We colour \( \Phi_0' \) by \( a \). If we assume that \( \Phi_a = \{ ax_i \triangleright u_1, \ldots , ax_n \triangleright u_n \} \), we build the frame \( \Phi_b \), colored by \( b \) such that \( \Phi_b = \{ ax_i \triangleright u_1, \ldots , ax_n \triangleright u_n \} \). At last, let \( \rho_0 \) be the bijective renaming such that \( \text{img}(\rho_0) = K_0' \) and \( \text{dom}(\rho_0) \) are composed of fresh names.

Let \( ch_a \) and \( ch_b \) be two sets of fresh channel type names. Furthermore, let \( \rho_{ch_a} \) be a bijective renaming from the public channel of \( (K_0; C[[P_A]_a]; \Phi_0) \) and \( (K_0; C[[P_A']_a]; \Phi_0) \) to \( ch_a \). We define \( \rho_{ch_b} \) in the same way.

We know by hypothesis that \((K_0; C[[P_A]_a]; \Phi_0) \approx_t (K_0; C'[[[P_A']_a]; \Phi_0)\) and \((K_0; C[[P_B]_b]; \Phi_0) \approx_t (K_0; C'[[[P_B']_b]; \Phi_0)\). But the trace equivalence is stable under renaming. Thus, we have:

\[
(K_0; C[[P_A]_a \rho_{ch_a}]; \Phi_0) \approx_t (K_0; C'[[[P_A']_a \rho_{ch_a}]; \Phi_0) \\
(K_0 \rho_0^{-1}; C[[P_B]_b \rho_{ch_b} \rho_0^{-1}]; \Phi_0 \rho_0^{-1}) \approx_t (K_0 \rho_0^{-1}; C'[[[P_B']_b \rho_{ch_b} \rho_0^{-1}]; \Phi_0 \rho_0^{-1})
\]

But \( \text{img}(\rho_0) = K_0' \) and \( K_0' \) represents the sets of shared named of \( K_0 \) between \( P_A, P_A' \) and \( P_B, P_B' \). Hence, since \( \text{dom}(\Phi_a) \cap \text{dom}(\Phi_b) = \emptyset \), we can compose the two equivalences such
that if we denote \( D = (\mathcal{K}_0 \cup \mathcal{K}_0 \rho_0^{-1}; C[[\mathcal{P}_2]_a] \rho\mathcal{C}_h\mathcal{K}_a] \cup C[[\mathcal{P}_2]_b] \rho\mathcal{C}_h\mathcal{K}_b] ; \Phi_a \vdash \Phi_b \rho_0^{-1}) \) and \( D' = (\mathcal{K}_0 \cup \mathcal{K}_0 \rho_0^{-1}; C'[[\mathcal{P}_2]_a] \rho\mathcal{C}_h\mathcal{K}_a] \cup C'[[\mathcal{P}_2]_b] \rho\mathcal{C}_h\mathcal{K}_b] ; \Phi_a \vdash \Phi_b \rho_0^{-1}) \), we have that \( D \approx D' \).

Let’s denote now \( S = (\mathcal{K}_0; C[[\mathcal{P}_2]_a] | [\mathcal{P}_2]_b] ; \Phi_a \vdash \Phi_b) \) and \( S' = (\mathcal{K}_0; C'[[\mathcal{P}_2]_a] | [\mathcal{P}_2]_b] ; \Phi_a \vdash \Phi_b) \).

We will show that \( S \approx S' \). Indeed, since \( \Phi_a = \Phi_a \) and \( \Phi_b \) have exactly the same terms, then \( S \approx S' \) is equivalent to \((\mathcal{K}_0; C[[\mathcal{P}_2]_a] | [\mathcal{P}_2]_b] ; \Phi_a \vdash \Phi_b) \approx (\mathcal{K}_0; C'[[\mathcal{P}_2]_a] | [\mathcal{P}_2]_b] ; \Phi_a \vdash \Phi_b) \).

To avoid confusion, for a sequence of actions \( w \) including the \( \tau \) actions, we will denote \( \vec{w} \) the sequence of actions \( w \) where we removed the \( \tau \) actions.

Let \( (tr, \nu \mathcal{E}, \Phi) \in \text{trace}(S) \), by Lemma 5.14 there exists a renaming \( r \) and two bounded intermediate processes \( S_1 = (E_1; \{P_a, P_b\}; \Phi_a \vdash \Phi_b) \) and \( D_1 = (E_1; \{P_a \rho \mathcal{C}_h \mathcal{K}_a, P_b \rho^{-1} \mathcal{C}_h \mathcal{K}_a\}; \Phi_a \vdash \Phi_b \rho^{-1}) \) such that

1. \( \rho | \text{dom}(\rho) = \rho_0, \text{dom}(\rho) \cup \text{img}(\rho) \subseteq E_1 \) and \( \text{dom}(\rho) \) does not appear in \( \{P_a, P_b\} \)
2. for all \( i \in \{a, b\} \), there exists \( P_i \) built on \( E_1 \cup F_0 \) such that such that \( P_i = [P_i]_1 \)
3. there exists \( \Phi_1 \) such that \((tr, \nu \mathcal{E}_1, \Phi_1) \in \text{trace}(S_1) \) and \( \nu \mathcal{E}_1, \Phi_1 \sim \nu \mathcal{E} \Phi \)
4. for all \((tr', \nu \mathcal{E}_1, \Phi') \in \text{trace}(D_1) \), there exists \( \nu \mathcal{E}', \Phi'' \) such that \((tr', \nu \mathcal{E}', \Phi'') \in \text{trace}(D) \) and \( \nu \mathcal{E}_1, \Phi' \sim \nu \mathcal{E}', \Phi'' \)

We colour \( P_a \) and \( P_b \) by \( a \) and \( b \) respectively.

In order to apply Lemma 5.14 we need to get rid of the possible internal communications between two processes of different colours in \((tr, \nu \mathcal{E}_1, \Phi_1) \). Since \((tr, \nu \mathcal{E}_1, \Phi_1) \in \text{trace}(S_1) \), we have that \( S_1 \models (E_1; P_i; \Phi_1) \), for some \( P_i \). Thus, there exists \( w_S \) such that \( \vec{w} = tr \) and \( S_1 \xrightarrow{w_S} (E_1; P_i; \Phi_1) \).

We show by induction on \(#\{\tau \in w_S\}\) that there exists \( w_S' \) such that \( S_1 \xrightarrow{w_S'} (E_1; P_i; \Phi_1 \oplus \Phi_a) \), for some \( \Phi_a \) and \( w_S' \) does not contain any \( \tau \) action corresponding to an internal communications between two processes of different colours:

**Base case** \(#\{\tau \in w_S\} = 0\): The result trivially holds since there is no \( \tau \) action.

**Inductive step** \(#\{\tau \in w_S\} > 0\): Assume that there is an internal communication between two processes of different colours (if not the result holds trivially). Thus there exists \( w_1, w_2 \) such that \( w_S = w_1, \tau w_2 \) and \( S_1 \xrightarrow{w_1} (E_1; P_1; \Phi_2) \xrightarrow{\tau} (E_1; P_2; \Phi_2) \xrightarrow{w_2} (E_1; P_3; \Phi_1) \). Since \( \tau \) is an internal communication, then \( P_1 = \{\text{in}(c, x) P_1; \text{out}(c, u), P_2\} \cup Q \) and \( P_2 = \{P_1; x \mapsto u\}; P_2 \cup Q \), for some \( P_1, P_2, Q, c, x, u \). But by hypothesis, we know that processes of different colours do not share private channels. Thus \( c \) is a public channel. Hence, we have that \((E_1; P_1; \Phi_2) \xrightarrow{\nu \text{ax.out}(c, ax) P} \) where \( P' = (E_1; \{\text{in}(c, x) P_1, P_2\} \cup Q; \Phi_2 \cup \{ax \mapsto u\}) \). Once again, since \( c \) is a public channel, we now have that \( P' \xrightarrow{\text{in}(c, ax)} (E_1; P_2; \Phi_2 \cup \{ax \mapsto u\}) \). A simple induction on the rest of the trace allows us to show that \((E_1; P_2; \Phi_2 \cup \{ax \mapsto u\}) \xrightarrow{w_2} (E_1; P_3; \Phi_1 \cup \{ax \mapsto u\}) \). Since we removed the \( \tau \) action without adding new ones, we can apply our inductive hypothesis on \( w_1, \nu \text{ax.out}(c, ax) \text{in}(c, ax) w_2 \) in order to conclude.

We showed that \( S_1 \xrightarrow{w_S} (E_1; P_i; \Phi_1 \oplus \Phi_a) \), for some \( \Phi_a \) and \( w_S' \) does not contain any \( \tau \) action corresponding to an internal communication between two processes of different colours. Let’s denote \( \Phi_S = \Phi_1 \cup \Phi_a \), we have that \((w_S', \nu \mathcal{E}_i, \Phi_S) \in \text{trace}(S_1) \). Thanks to Lemma 5.14 we can deduce that \( \Phi_S \) is well-tagged and there exists \( D_1 \xrightarrow{w_D} (E_1; P_D; \Phi_D) \) such that \( \Phi_D \downarrow = \delta^\text{e}(\Phi_S \downarrow) \). Furthermore, if \( w_S' = \ell_1, \ldots, \ell_n \) then \( w_D' = \ell_1', \ldots, \ell_n' \) such that for all \( k \in \{1, \ldots, n\} \),

- if \( \ell_k = \nu \text{ax.out}(c, ax) \) is an output coming from a process coloured by \( i \in \{a, b\} \), then \( \ell_k' = \nu \text{ax.out}(cP_i, ax) \)
- if \( \ell_k = \text{in}(c, M) \) is an input coming from a process coloured by \( i \in \{a, b\} \), then \( \ell_k' = \text{in}(cP_i, M_i) \) with \( M_i \Phi_D \downarrow = \delta^\text{e}(M \Phi_S \downarrow) \)
- if \( \ell_k = \text{out}(c, d) \) is an output coming from a process coloured by \( i \in \{a, b\} \) with \( d \) a channel name, then \( \ell_k' = \text{out}(cP_i, dP_i) \)
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- if \( \ell_k = \nu \text{ch}_m \cdot \text{out}(c, \text{ch}_m) \) is an output coming from a process coloured by \( i \in \{a, b\} \) with \( \text{ch}_m \) a channel name, then \( \ell'_k = \nu \text{ch}_m \cdot \text{out}(c\rho_{\text{ch}_i}, \text{ch}_m) \)

- if \( \ell_k = \tau \), then \( \ell'_k = \tau \).

Hence we have that \( (w_{D'}^\sim, \nu \mathcal{E}_1, \Phi_D) \in \text{trace}(D_1) \). Thus, thanks to the property \([4]\) established earlier with Lemma \([5.12]\), there exists \( \nu \mathcal{E}'_1, \Phi'_D \) such that \( (\nu \mathcal{E}'_1, \Phi'_D) \in \text{trace}(D) \) and \( \nu \mathcal{E}'_1 \cdot \Phi'_D \sim \nu \mathcal{E}_1 \cdot \Phi_D \). Furthermore, we showed that \( D \cong D'_\ell \), hence we deduce that there exists \( \nu \mathcal{E}'_1 \cdot \Phi'_D \) such that \( (w_{D'}^\sim, \nu \mathcal{E}'_1, \Phi'_D) \in \text{trace}(D') \) and \( \nu \mathcal{E}'_1 \cdot \Phi'_D \sim \nu \mathcal{E}'_1 \cdot \Phi'_D \).

Once again by Lemma \([5.12]\), there exists a renaming \( \rho' \) and two bounded intermediate processes \( S'_1 = (E'_1; \{P'_a, P'_b\}; \Phi_a \oplus \Phi_b) \) and \( D'_1 = (E'_1; \{P'_a \rho_{\text{ch}_a}, P'_b \rho_{\text{ch}_b}; \Phi_a \oplus \Phi_b \rho^{-1}\}) \) such that

1. \( \rho'_{\text{dom}(\rho)} = \rho_0, \text{dom}(\rho') \cup \text{img}(\rho') \subseteq \mathcal{C}_i \) and \( \text{dom}(\rho') \) does not appear in \( \{P'_a, P'_b\} \)
2. for all \( i \in \{a, b\} \), there exists \( P'_i \) built on \( F_i \cup F_0 \) such that \( P'_i = [P'_i]_i \)
3. there exists \( \Phi'_D \) such that \( (w_{D'}^\sim, \nu \mathcal{E}'_1, \Phi'_D) \in \text{trace}(D'_1) \) and \( \nu \mathcal{E}'_1 \cdot \Phi'_D \sim \nu \mathcal{E}'_1 \cdot \Phi'_D \)
4. for all \( \text{tr}'(i, \nu \mathcal{E}'_1, \Phi'_D) \in \text{trace}(S'_1) \), there exists \( \nu \mathcal{E}_i \cdot \Phi'' \) such that \( \text{tr}'(i, \nu \mathcal{E}_i \cdot \Phi'' \in \text{trace}(S) \) and \( \nu \mathcal{E}_i \cdot \Phi'' \sim \nu \mathcal{E}_i \cdot \Phi'' \)

Since our processes are bounded intermediate process, we can assume that \( \mathcal{E}_1 = \mathcal{E}'_1 \) and \( \rho = \rho' \) (if not we can apply some renaming on private name in \( \mathcal{E}_1 \) or \( \mathcal{E}'_1 \) in order to make them equal). Thus, \( (w_{D'}^\sim, \nu \mathcal{E}_1, \Phi'_D) \in \text{trace}(D'_1) \).

Let's summarise what we have proved so far. We had \( \text{tr}(i, \nu \mathcal{E}, \Phi) \in \text{trace}(S) \), then obtain a trace \( (\text{tr}(i, \nu \mathcal{E}, \Phi) \in \text{trace}(S_1)) \) such that \( \nu \mathcal{E} \cdot \Phi \sim \nu \mathcal{E}_1 \cdot \Phi_1 \). We modified this into \( (w_{D_S}^\sim, \Phi_1 \oplus \Phi_+) \) where visible actions \( \nu \text{ax} \cdot \text{out}(c, \text{ax}).\text{in}(c, \text{ax}) \) replaced some \( \tau \) actions. Then Lemma \([5.12]\) allowed us to build the trace \( (w_{D_S}^\sim, \nu \mathcal{E}_1, \Phi_D) \) in \( \text{trace}(D_1) \) which only modify the terms in the trace but not the actions themselves. At last, we obtain, thanks to our hypothesis, that there exists \( \Phi'_D \) such that \( (w_{D'}^\sim, \nu \mathcal{E}_1, \Phi'_D) \in \text{trace}(D'_1) \) such that \( \nu \mathcal{E}_1 \cdot \Phi_D \sim \nu \mathcal{E}_1 \cdot \Phi'_D \).

\( (w_{D'}^\sim, \nu \mathcal{E}_1, \Phi'_D) \in \text{trace}(D'_1) \) implies that there exists \( w_{D'}^\sim \) such that \( w_{D'}^\sim \in \text{trace}(E_1; \mathcal{P}'_1; \Phi'_D) \). It is possible that there exists \( \ell \in \tau^* \) such that \( \nu \text{ax} \cdot \text{out}(c_i, \text{ax}).\text{in}(c_j, \text{ax}) \in w_{D'}^\sim \) where \( c_i \in \text{img}(\rho_{\text{ch}_a}), c_j \in \text{img}(\rho_{\text{ch}_b}) \) and \( i \neq j \). But, thanks to Lemma \([5.18]\), we can assume that this case does not occur and so there is no \( \tau \) action between \( \nu \text{ax} \cdot \text{out}(c_i, \text{ax}) \) and \( \text{in}(c_j, \text{ax}) \), for any \( \text{ax} \in \text{dom}(\Phi'_D) \).

Since \( \nu \mathcal{E}_1 \cdot \Phi_D \sim \nu \mathcal{E}_1 \cdot \Phi'_D \), \( \Phi_S \) is a well-tagged frame and \( \Phi_D \downarrow = \delta^\rho(\Phi_S \downarrow) \), we can apply Lemma \([5.15]\) on \( D_1 = \nu \Phi_D \to \nu \Phi_D \) which allow us to deduce that there exists a well-tagged frame \( \Phi'_S \) such that \( S_1 \overset{w_{D'}^\sim}{\longrightarrow} (E_0; \mathcal{P}'_S; \Phi'_S) \), \( \Phi'_D \downarrow = \delta^\rho(\Phi'_S \downarrow) \), and if \( w_{D'}^\sim = \ell_1 \ldots \ell_n \) then \( w_{S'}^\sim = \ell'_1 \ldots \ell'_n \) and for all \( k \in \{1, \ldots, n\} \),

- if \( \ell_k = \nu \text{ax} \cdot \text{out}(c, \text{ax}) \) with \( c \in \text{ch}_i, i \in \{a, b\} \) then \( \ell'_k = \nu \text{ax} \cdot \text{out}(c\rho_{\text{ch}_i}^{-1}, \text{ax}) \)
- if \( \ell_k = \text{in}(c, M_k) \) with \( c \in \text{ch}_i, i \in \{a, b\} \), then \( \ell'_k = \text{in}(c\rho_{\text{ch}_i}^{-1}, M_k) \).
- if \( \ell_k = \text{out}(c, d) \) with \( c \in \text{ch}_i, i \in \{a, b\} \) and \( d \) a channel name, then \( \ell'_k = \text{out}(c\rho_{\text{ch}_i}^{-1}, d\rho_{\text{ch}_i}^{-1}) \)
- if \( \ell_k = \tau \) then \( \ell'_k = \tau \)

where the couples \( (M_k, M'_k) \) were generated by the application of Lemma \([5.14]\) earlier on the trace \( w_{S'}^\sim \). Note that it is possible because the channels (public and private) of processes with different colours are disjoints in \( D_1 \) and \( D'_1 \). For example, if we have \( \text{in}(c, M) \in w_{D'}^\sim \) and \( c \in \text{ch}_a \), then we know for sure that the input was done by a process coloured by \( a \) in \( D_1 \) and in \( D_1 \).
Hence, by construction of $w^+_S$ and $w'^+_S$, we have in fact that $w^+_S = w'^+_S$ and so $(\overline{w^+_S}, \nu E_1, \Phi'_S) \in \text{trace}(S'_1)$. Thanks to Corollary 5.4 we can also deduce that $\nu E_1, \Phi_S \sim \nu E_1, \Phi'_S$.

But $\Phi_S = \Phi_1 \oplus \Phi_+$ and since $\text{dom}(\Phi_S) = \text{dom}(\Phi'_S)$, there exists $\Phi'_1$ and $\Phi'_+$ such that $\text{dom}(\Phi'_1) = \text{dom}(\Phi_1)$ and $\text{dom}(\Phi'_+) = \text{dom}(\Phi'_+)$ and $\Phi'_S = \Phi'_1 \oplus \Phi'_+$. Since the transformation between $w^+_D$ and $w'^+_S$ only modifies the terms of the sequence of actions and not the actions themselves, and since we assume that there is no $\tau$ action between $\nu ax.\text{out}(c_a, ax)$ and $\text{in}(c_b, ax)$ in $w'^+_S$, for any $ax \in \text{dom}(\Phi'_+)$, a simple induction on $|\text{dom}(\Phi'_+)|$ allows us to show that $(\overline{w^+_S}, \nu E_1, \Phi'_1) \in \text{trace}(S'_1)$ and so $(\nu \text{tr}, \nu E_1, \Phi'_1) \in \text{trace}(S'_1)$. Moreover, since we have that $\nu E_1, \Phi_1 \sim \nu E_1, \Phi'_1$, we can deduce that $\nu E_1, \Phi_1 \sim \nu E_1, \Phi'_1$. At last, thanks to the property 4 obtained by application of Lemma 5.12 we deduce that there exists $\nu E', \Phi'$ such that $(\nu E', \Phi') \in \text{trace}(S)$ and $\nu E', \Phi' \sim \nu E_1, \Phi'_1$. Since we have $\nu E', \Phi \sim \nu E_1, \Phi_1$, we conclude that $(\nu \text{tr}, \nu E', \Phi') \in \text{trace}(S)$ and $\nu E', \Phi \sim \nu E', \Phi'$. Hence the result holds. \qed
Appendix C

Decision procedure of trace equivalence

C.1 Getting rid of some recipes

C.1.1 Getting rid of public names in the recipes

Let $N$ be a positive integer. Let $a \in \mathcal{E}$. We denote $\sigma_{\mathcal{E},N,a}$ and $\theta_{\mathcal{E},N}$ the substitution defined such that for all $i \in \mathbb{N}^+$, $b_i \sigma_{\mathcal{E},N,a} = h_i \times N(a)$ and $b_i \theta_{\mathcal{E},N} = h_i \times N(\alpha x_1)$. At last, we denote $\text{len}_\theta(u) = \max \{k \mid h^k(u') \in \text{st}(u) \text{ for some } u'\}$. Intuitively, $\text{len}_\theta(u)$ represents the longest successive application of $h$ in $u$.

**Lemma C.1.** Let $\mathcal{E}$ be a finite set on names and $a \in \mathcal{E}$. Let $N \in \mathbb{N}^+$. For all $u, v \in T(F,N)$, if $u \sigma_{\mathcal{E},N,a} = v \sigma_{\mathcal{E},N,a}$, $\text{len}_\theta(u) < N$ and $\text{len}_\theta(v) < N$ then $u = v$.

*Proof.* We prove the result by induction on $|u \sigma_{\mathcal{E},N,a}|$.

**Base case** $|u \sigma_{\mathcal{E},N,a}| = 1$: In such a case, $u \sigma_{\mathcal{E},N,a} \in \mathcal{N}$. Since $N > 0$, we deduce that $\text{fnames}(u) \cap (\mathcal{N} \setminus \mathcal{E}) = \emptyset$. Hence $u \in \mathcal{E}$ and so $u \sigma_{\mathcal{E},N,a}$. Similarly, we have that $v \sigma_{\mathcal{E},N,a} = v$ and so $u = v$.

**Inductive step** $|u \sigma_{\mathcal{E},N,a}| > 1$: Otherwise we have $u \sigma_{\mathcal{E},N,a} = f(u_1, \ldots, u_n)$. We do a case analysis on $f$:

- **Case** $f = h$: In such a case, there exists $k \in \mathbb{N}^+$ such that $u \sigma_{\mathcal{E},N,a} = h^k(u_1)$ and $\text{root}(u_1) \neq h$ for some $u_1$. If $u_1 \neq a$ then by definition of $\sigma_{\mathcal{E},N,a}$, we deduce that there exists $u_1'$ such that $u_1' \sigma_{\mathcal{E},N,a} = u_1$ and $u = h^k(u_1')$. Similarly, we have that there exists $v \sigma_{\mathcal{E},N,a} = u_1$ and $v = h^k(v_1')$. By inductive hypothesis, we deduce that $u_1' = v_1'$ and so $u = h^k(u_1') = h^k(v_1') = v$.

Assume now that $u_1 = a$. In such a case, there exists $i \in \mathbb{N}^+$ and $j \leq k$ such that $u = h^j(b_i)$ and $k = j + i \times N$. Similarly, there exists $i' \in \mathbb{N}^+$ and $j' \leq k$ such that $v = h^j'(b_i')$ and $k = j' + i' \times N$. By hypothesis, we know that $\text{len}_\theta(u) < N$ and $\text{len}_\theta(v) < N$ hence $j < N$ and $j' < N$. Thus $j + i \times N = j' + i' \times N$ implies that $i = i'$ and $j = j'$. We conclude that $u = v$.

- **Case** $f \neq h$: By definition of $\sigma_{\mathcal{E},N,a}$, there exists $u_1', \ldots, u_n', v_1', \ldots, v_n'$ such that $u = f(u_1', \ldots, u_n')$, $v = f(v_1', \ldots, v_n')$ and so for all $i \in \{1, \ldots, n\}$, $u_i \sigma_{\mathcal{E},N,a} = u_i = v_i \sigma_{\mathcal{E},N,a}$. By our inductive hypothesis on $u_i', v_i'$, we conclude that $u_i' = v_i'$ for all $i \in \{1, \ldots, n\}$ and so $u = v$. \qed

In Lemma C.1, the conditions on the number of occurrence of $h$ in $u$ and $v$ is crucial. Indeed, if we consider $N = 1$ and the terms $u = \text{senc}(h(a), b_1)$, $v = \text{senc}(b_1, b_1)$ then we obtain $u \sigma_{\mathcal{E},N,a} = v \sigma_{\mathcal{E},N,a} = \text{senc}(h(a), h(a))$. This is an issue when it comes to check if a message or not. Intuitively, our representation of public names should not change the validity of a term. However, if we
consider the term \( t = \text{sdec}(u, h(a)) \) then \( \text{Message}(t) \) does not hold while \( \text{Message}(\tau_{E,N,a}) \) holds. Using the conditions on the number of occurrence of \( h \) in terms, we will see in the next lemma that such example can be avoided.

**Lemma C.2.** Let \( E \) be a finite set of names and \( a \in E \). Let \( N \in \mathbb{N}^+ \). For all \( u \in \mathcal{T}(F,N) \), if \( \text{len}_h(u) < N \) then:

- \( \text{Message}(u) \) if, and only if, \( \text{Message}(u_{σ,E,N,a}) \); and
- \((uσ_{E,N,a})↓ = (u↓)σ_{E,N,a}\)

**Proof.** We prove both results at the same time by induction on \(|u|\):

**Base case** \(|u| = 1\): In such a case, we have that \( u \in E \) then \( uσ_{E,N,a} = u \) and so the results trivially holds. Else there exists \( i \in \mathbb{N}^+ \) such that \( u = b_i \). Thus \( uσ_{E,N,a} = h_1^{×N}(a) \). But \( h \in \mathcal{F}_c \) hence \((uσ_{E,N,a})↓ = uσ_{E,N,a} = (u↓)σ_{E,N,a}\). Moreover, \( \text{Message}(b_i) \) and \( \text{Message}(h_1^{×N}(a)) \) both hold. Thus the result holds.

**Inductive step** \(|u| > 1\): Otherwise \( u = f(u_1, \ldots, u_n) \) with \( f \in \mathcal{F} \). We first prove that \((uσ_{E,N,a})↓ = (u↓)σ_{E,N,a}\) by case analysis on \( f \).

- **Case 1**, \( f \in \mathcal{F}_c \): In such a case, we have that \((uσ_{E,N,a})↓ = f(u_1σ_{E,N,a}↓, \ldots, u_nσ_{E,N,a}↓)\).
  
  By inductive hypothesis on \( u_1, \ldots, u_n \), we deduce that \((uσ_{E,N,a})↓ = f((u_1↓)σ_{E,N,a}, \ldots, (u_n↓)σ_{E,N,a})\) and so \((uσ_{E,N,a})↓ = f(u_1, \ldots, u_n)↓)σ_{E,N,a}\).

- **Case 2**, \( f \in \mathcal{F}_d \): In such a case, \( u↓ = f(u_1↓, \ldots, u_n↓)↓\). Moreover, \( uσ_{E,N,a}↓ = f(u_1σ_{E,N,a}↓, \ldots, u_nσ_{E,N,a}↓)↓\).
  
  By inductive hypothesis on \( u_1, \ldots, u_n \), we deduce that \( uσ_{E,N,a}↓ = f(u_1σ_{E,N,a}, \ldots, u_nσ_{E,N,a})↓\).

  Consider \( f(v_1, \ldots, v_n) \rightarrow v \) a fresh instance of the rewrite rule of \( f \). \( f \) is reduced in \( u↓ \) equivalent to \((u_1↓, \ldots, u_n↓)↓\) is unifiable with \((v_1, \ldots, v_n)\). Similarly, \( f \) is reduced in \( uσ_{E,N,a}↓ \) equivalent to \((u_1↓σ_{E,N,a}, \ldots, u_n↓σ_{E,N,a})↓\) is unifiable with \((v_1, \ldots, v_n)\). We prove by case analysis on the rewrite rule involve that \( f \) is reduced in \( u↓ \) equivalent to \( f \) is reduce in \( uσ_{E,N,a}↓ \):

  - \( f = \text{sdec} \): In such a case, we have that \( u = \text{sdec}(u_1, u_2) \).
    
    Hence \( f \) is reduced in \( u↓ \) equivalent to \( u_1↓ = \text{senc}(v_1, v_2) \) and \( u_2↓ = v_2 \) for some \( v_1, v_2 \). Moreover, \( f \) is reduced in \( uσ_{E,N,a}↓ \) equivalent to \( u_1↓σ_{E,N,a} = \text{senc}(v_1′, v_2′) \) and \( u_2↓σ_{E,N,a} = v_2′ \) for some \( v_1′, v_2′ \).
    
    First of all, \( u_1↓ = \text{senc}(v_1, v_2) \) and \( u_2↓ = v_2 \) implies that \( u_1↓ = \text{senc}(v_1σ_{E,N,a}, v_2σ_{E,N,a}) \) and \( u_2σ_{E,N,a} = v_2σ_{E,N,a} \). Hence \( f \) is reduced in \( u↓ \) implies \( f \) is reduced in \( uσ_{E,N,a}↓ \).
    
    Secondly, by definition of \( σ_{E,N,a} \), \( u_1↓σ_{E,N,a} = \text{senc}(v_1′, v_2′) \) implies that there exists \( v_1′, v_2′ \) such that \( u_1↓ = \text{senc}(v_1′, v_2′) \) and \( v_1′σ_{E,N,a} = v_1′ \) and \( v_2′σ_{E,N,a} = v_2′ = u_2↓σ_{E,N,a} \). By Lemma [C.1] we obtain that \( v_1′ = u_2↓ \) and so \( u_1↓ = \text{senc}(v_1′, u_2↓) \). Hence \( f \) is reduced in \( uσ_{E,N,a}↓ \) implies that \( f \) is reduced in \( u↓ \).

- \( f \in \{\text{adec, proj}_1, \text{proj}_2\} \): Similar to the case \( f = \text{sdec} \).

We have shown that \( f \) is reduced in \( u↓ \) equivalent to \( f \) is reduce in \( uσ_{E,N,a}↓ \). Since all rewrite rules are subterm convergent, we deduce that \((uσ_{E,N,a})↓ = (u↓)σ_{E,N,a}\).

At last, \( \text{Message}(u) \) is equivalent to \( \text{Message}(u_i) \) for all \( i \in \{1, \ldots, n\} \) and \( u_i \in \mathcal{T}(F_c,N) \). By inductive hypothesis, we know that \( \text{Message}(u_i) \) if and only if \( \text{Message}(u_iσ_{E,N,a}) \). Furthermore, we have shown that \((uσ_{E,N,a})↓ = (u↓)σ_{E,N,a} \) and we know that for all \( i \in \mathbb{N}^+ \), \( b_iσ_{E,N,a} \in \mathcal{T}(F_c,N) \). We can deduce that \( u↓ \in \mathcal{T}(F_c,N) \) is equivalent to \((u↓)σ_{E,N,a} \in \mathcal{T}(F_c,N) \) which is equivalent to \((uσ_{E,N,a})↓ \in \mathcal{T}(F_c,N) \). Hence we conclude that \( \text{Message}(u) \) if and only if \( \text{Message}(uσ_{E,N,a}) \).

**Corollary C.1.** Let \( E \) be a finite set of names. Let \( N \in \mathbb{N}^+ \). Let \( Φ \) be a ground frame such that \( ax_1Φ → a ∈ E \). For all \( ξ ∈ \mathcal{T}(F,AΩ∪N) \), if \( \text{param}(ξ) ⊆ \text{dom}(Φ) \) and \( \text{len}_a(ξΦ) < N \) then:

- \( \text{Message}(ξΦ) \) if and only if \( \text{Message}(ξσ_{E,N}(Φσ_{E,N,a})) \)
• \((\xi \Phi)_{\Sigma, N, a} = (\xi \Phi, N)(\Phi_{\Sigma, N, a})\)

Proof. By definition of \(\sigma_{E, N, a}\) and \(\theta_{E, N}\), we have that for all \(i \in \mathbb{N}^+\), \(b_{i, \sigma_{E, N, a}} = b_{i, \theta_{E, N, a}} = (b_{i, \theta_{E, N}})(\Phi_{\Sigma, N, a})\). More over, for all \(ax_k \in \text{dom}(\Phi)\), \(ax_k \Phi_{\Sigma, N, a} = (ax_k \Phi_{\Sigma, N})(\Phi_{\Sigma, N, a})\). Hence we have \((\xi \Phi)_{\Sigma, N, a} = (\xi \Phi, N)(\Phi_{\Sigma, N, a})\). We conclude by applying Lemma C.2 to \(\xi \Phi\).

\[\\]

\textbf{Lemma 6.2.} Let \(\Sigma\) and \(\Sigma'\) two sets of constraint systems that contain constraint systems having the same structure. Assume that \(\mathcal{E}\) is the common set of privates names in \(\Sigma\) and \(\Sigma'\). At last, assume that there exist \(a \in \mathcal{E}\) such that for all \(C \in \Sigma \cup \Sigma'\), \(ax_1 \Phi = a\) with \(\Phi\) the frame of \(C\).

If \(\Sigma \approx_{\mathcal{T}(F, A^X, \Phi)} \Sigma'\) then for all \(C \in \Sigma\), for all \((\sigma, \theta) \in \text{Sol}_k(C)\), there exists \(N'\) such that for all \(N > N'\), there exist \(\mathcal{C}' \in \Sigma'\) and a substitution \(\sigma'\) such that \((\sigma', \theta) \in \text{Sol}_k(C')\) and \(\nu \mathcal{E}, \Phi, \sigma_{E, N, a} \sim_{\mathcal{T}(F, A^X, \Phi')} \nu \mathcal{E}, \Phi' \sigma'_{E, N, a}\).

Proof. Let \(C = (\mathcal{E}; \Phi; D; E_0) \in \Sigma\) and let \((\sigma, \theta) \in \text{Sol}_k(C)\). Let \(N'\) be the integer equal to the number of occurrence of the function symbol \(h\) in \(\Sigma, \Sigma'\) and \(\theta\). Let \(N > N'\). Before proving the result, we show the following proposition:

Proposition: For all \(\mathcal{E}, \Phi' ; D'; E_0' \in \Sigma \cup \Sigma'\), for all substitution \(\sigma'\), if for all \((X, k \vdash x) \in D'\), \((X \theta)(\Phi' \sigma')\) and \(\text{param}(X \theta) \subseteq \{ax_1, \ldots, ax_k\}\), then

- for all \((X, k \vdash x) \in D'\), \(\text{len}(x \sigma) \leq N_k(C')\)
- for all \((ax_k \triangleright u_k) \in \Phi\), \(\text{len}(u_k \sigma') \leq N_{k-1}(C') + M_k(C')\)

where \(M_k(C')\) is the number of occurrence of \(\{u_j \mid (ax_j \triangleright u_j) \in \Phi' \land j \leq k\}\) and \(N_k(C')\) is the number of occurrence in \(\{Y \theta \mid (Y, j \vdash y) \in D' \land j \leq k\}\) plus \(M_k(C')\). We assume that \(M_0 = N_0 = 0\). We prove these both results at the same time by induction on \(k\).

Base case \(k = 1\): In such a case, by hypothesis on \(\Phi'\) we know that \(ax_1 \Phi' = a\). Hence \(\text{len}(ax_1 \sigma) = 0 = M_1\). Let \((X, 1 \vdash x) \in D'\). Since \(\text{param}(X \theta) \subseteq \{ax_1\}\), \((X \theta)(\Phi' \sigma') = x \sigma'\) and \(ax_1 \Phi' = a\), we deduce that \(\text{len}(x \sigma) = \text{len}(X \theta)\). Thus we deduce that \(\text{len}(X \theta) \leq N_1\) and so \(\text{len}(x \sigma) \leq N_1\).

Inductive step \(k > 1\): Let \((ax_k \triangleright u_k) \in \Phi'\). Let \(h^i(u) \in \text{st}(u_k \sigma)\) for some \(j\) and \(u\). Either (a) there exists \(w' \in \text{st}(u_k)\) and \(j'\) such that \(u' = h^j(x)\) and \(x \sigma = h^{-j'}(u)\) with \(x \in \text{vars}^i(u_k)\); or (b) there exists \(x \in \text{vars}^i(u_k)\) such that \(h^j(u) \in \text{st}(x \sigma')\).

In case (a), by definition of \(M_k(C')\), we have \(j' = M_k(C')\) and so \(j' + N_{k-1}(C') \leq M_k(C') + N_{k-1}(C')\). Moreover, by definition of a constraint system, we know that for all \(x \in \text{vars}^i(u_k)\), there exists \((X, i \vdash x) \in D'\) such that \(i < k\). By inductive hypothesis on \(x\), we deduce that \(\text{len}(x \sigma) \leq N_i(C')\). Since \(N_i(C') \leq N_{k-1}(C')\), we deduce that \(N_{k-1}(C') + M_k(C') \geq j' + N_{k-1}(C') \geq j' + N_{k-1}(C') \geq j' + \text{len}(x \sigma) \geq j' + j - j' = j\). Hence, it implies that \(N_{k-1}(C') + M_k(C') \geq j\).

In case (b), once again by inductive hypothesis on \(x\), we deduce that \(\text{len}(x \sigma) \leq N_i(C')\). Since \(N_i(C') \leq N_{k-1}(C')\) and \(j \leq \text{len}(x \sigma)\), then \(j \leq N_{k-1}(C') + M_k(C')\).

Since we have showed that for all \(h^i(u) \in \text{st}(u_k \sigma)\), \(j \leq N_{k-1}(C') + M_k(C')\), we conclude that \(\text{len}(u_k \sigma) \leq M_k(C') + N_{k-1}(C')\).

Let \((X, k \vdash x) \in D'\), by hypothesis on \(\theta\) and \(\sigma'\), we have that \((X \theta)(\Phi' \sigma') = x \sigma'\) and \(\text{param}(X \theta) \subseteq \{ax_1, \ldots, ax_k\}\). Let \(h^i(u) \in \text{st}(x \sigma')\) for some \(j\) and \(u\). Either (a) there exists \(\xi \in \text{st}(X \theta)\) and \(j'\) such that \(u' = h^j(ax_i)\), \(ax_i \Phi' = h^{-j'}(u)\) for some \(i < k\); or (b) there exists \(ax_i \in \text{dom}(\Phi')\) such that \(h^j(u) \in \text{st}(ax_i \Phi' \sigma')\); or (c) \(h^j(u) \in \text{st}(X \theta)\).

In case (a), we have proved that \(\text{len}(ax_i \Phi' \sigma') \leq M_k(C')\) and by definition of \(N_k(C')\), we deduce that \(N_k(C') \geq j' + M_k(C')\) and so \(N_k(C') \geq j' + \text{len}(ax_i \Phi' \sigma')\). Since \(\text{len}(ax_i \Phi' \sigma') = j - j'\), we conclude that \(N_k(C') \geq j\). In case (b), thanks to \(\text{len}(ax_i \Phi' \sigma') \leq M_k(C')\), we directly conclude that \(j \leq N_k(C')\). In case (c), the definition of \(N_k(C')\) implies that \(j \leq N_k(C')\).

Since we have showed that for all \(h^i(u) \in \text{st}(x \sigma')\), \(j \leq N_k(C')\), we conclude that \(\text{len}(x \sigma') \leq N_k(C')\).
Main result: Let $\theta' = \theta E_N$ and $\sigma' = \sigma E_{N,a}$. We show that $(\sigma', \theta') \in \text{Sol}_r(C)$:

- Let $(X, k \vdash x) \in D$. $(\sigma, \theta) \in \text{Sol}_r(C)$ implies that $(X \theta)(\Phi \sigma) = x \sigma$, param $(X \theta) \subseteq \{ax_1, \ldots, ax_k\}$ and $\text{Message}(x \sigma)$. Moreover, by our proposition, $(\sigma, \theta) \in \text{Sol}_r(C)$ also implies that $\text{len}_\theta(x \sigma) \leq N_k(\Phi) < N$. By Corollary C.1, $\text{Message}(x \sigma)$ implies that $\text{Message}((X \theta E_N)(\Phi \sigma E_{N,a}))$. Hence, we deduce that $(X \theta')(\Phi \sigma') = x \sigma E_{N,a} = x \sigma'$ and $\text{Message}(x \sigma')$. At last, since $\text{param}(b_i \theta E_N) = \{ax_1\}$ for all $i \in N^+$, we conclude that $\text{param}(X \theta') \subseteq \{ax_1, \ldots, ax_k\}$.

- Let $(s \nmid s')$ or $(s \nmid s')$ in $E_q$. Thanks to our proposition, we know that for all $x \in \text{vars}^1(s, s')$, $\text{len}_\theta(x \sigma) \leq N_k$ with $k = |\Phi|$. But $N$ is strictly bigger that $N_k$ plus the number of occurrence of $h$ in $s$ and $s'$. Hence, we deduce that $\text{len}_\theta(s \sigma) < N$ and $\text{len}_\theta(s' \sigma) < N$. By Lemma C.2 we deduce that $\text{Message}(s \sigma)$ is equivalent to $\text{Message}(s \sigma E_{N,a})$ and $\text{Message}(s' \sigma)$ is equivalent to $\text{Message}(s' \sigma E_{N,a})$. Hence by Corollary C.1, we deduce that $s \sigma \vdash s \sigma'$ and $s' \sigma \vdash s' \sigma'$. Therefore we can deduce that $s \sigma \vdash s \sigma'$. Hence by Lemma C.2, we deduce that $\text{Message}(s \sigma)$ and $\text{Message}(s' \sigma)$ is equivalent to $s \sigma \vdash s' \sigma'$. 

Message$(s \sigma'')$ and Message$(s' \sigma')$. Thus, if $(s \nmid s')$ (resp. $(s \nmid s')$) is in $E_q$ then $(\sigma, \theta) \in \text{Sol}_r(C)$ implies that $s \sigma \vdash s' \sigma'$, Message$(s \sigma')$ and Message$(s' \sigma')$ (resp. $s' \sigma' \nmid s' \sigma'$, or $\neg \text{Message}(s \sigma')$ or $\neg \text{Message}(s' \sigma')$).

- Let $(ax_i \nmid u_i) \in \Phi$. By our proposition, we know that $\text{len}_\theta(u_i \sigma) < N$ hence thanks to Lemma C.3, $(\sigma, \theta) \in \text{Sol}_r(C)$ implies that $\text{Message}(u_i \sigma E_{N,a})$ and so $\text{Message}(u_i \sigma')$.

It conclude the proof that $(\sigma', \theta') \in \text{Sol}_r(C)$.

By hypothesis, $\Sigma \models_{(F,A \vee)} \sum'$ hence there exists a constraint system $C' = (\varepsilon; \Phi'; D'; E_q')$ and a substitution $\sigma''$ such that $(\sigma'', \theta') \in \text{Sol}_r(C)$ and $\nu E \Phi' \sim_{(F,A \vee)} \nu E \Phi' \sigma''$. We now show that there exists $\sigma'''$ such that $\sigma'' = \sigma''' \sigma E_{N,a}$ and $(\sigma''', \theta') \in \text{Sol}_r(C)$.

We define $\sigma'''$ such that $\text{dom}(\sigma''') = \text{dom}(\sigma'')$ and for all $(X, k \vdash x) \in D'$, $x \sigma''' = (X \theta)(\Phi \sigma'')$. Such substitution exists thanks to the origination property of the constraint system $C'$. We prove by induction on $k$ that for all $(X, k \vdash x) \in D'$, $x \sigma''' E_{N,a} = x \sigma'''$, Message$(x \sigma''')$; and for all $(ax_i \nmid u_i) \in \Phi'$, Message$(u_i \sigma'''')$.

Base case $k = 0$: This case is impossible.

Base case $k > 0$: Let $(ax_k \nmid u_k) \in \Phi'$. By the origination property of a constraint system, we know that for all $y \in \text{vars}^1(u_k)$, there exists $(Y, i \vdash y) \in D'$ such that $i < k$. Hence by our inductive hypothesis, we deduce that for all $y \in \text{vars}^1(u_k)$, $\nu y \sigma''' E_{N,a} = y \sigma'''$. Hence we deduce that $u_k \sigma''' E_{N,a} = u_k \sigma'''$. Thanks to our proposition, we know that $\text{len}_\theta(u_k \sigma''') N$. Moreover, we have $(\sigma''', \theta') \in \text{Sol}_r(C')$ which implies $\text{Message}(u_k \sigma''')$. Hence by Lemma C.2 we deduce that $\text{Message}(u_k \sigma'''')$.

Let $(X, k \vdash x) \in D'$. Let $(ax_i \nmid u_i) \in \Phi'$ such that $ax_i \in X \theta'$ and so $i < k$. By our inductive hypothesis on the variable of $u_i$, we deduce that $u_i \sigma''' E_{N,a} = u_i \sigma'''$. Hence $(X \theta')(\Phi \sigma'') = (X \theta')(\Phi \sigma'') = (X \theta')(\Phi \sigma'')$. Since $(\sigma', \theta') \in \text{Sol}_r(C)$, then $x \sigma''' = (X \theta')(\Phi \sigma'') = (X \theta)(\Phi \sigma'' \sigma E_{N,a})$. Moreover $(\sigma', \theta') \in \text{Sol}_r(C')$ implies Message$(x \sigma''')$. But, thanks to our proposition, we know that $\text{len}_\theta(x \sigma'''') \leq N_k(C') < N$ therefore by Lemma C.2 we deduce that $\text{Message}(x \sigma''')$ implies Message$(x \sigma''')$ which implies Message$(x \sigma''')$.

It remains to show that for all $(s \nmid s') \in \Phi'$, $s \sigma''' \vdash s' \sigma'''$, Message$(s \sigma''')$ and Message$(s' \sigma''')$. We know by $(\sigma'', \theta') \in \text{Sol}_r(C')$ that $s \sigma''' \vdash s' \sigma'''$, Message$(s \sigma''')$ and Message$(s' \sigma''')$. Since $\text{len}_\theta(s \sigma''') N$, $\text{len}_\theta(s' \sigma''') N$ and $\sigma''' \sigma E_{N,a}$, we can apply Lemma C.2 which allows us to conclude.

For all $(s \nmid s') \in \Phi'$, we similarly prove that $s \sigma''' \vdash s' \sigma'''$, or $\neg \text{Message}(s \sigma''')$ or $\neg \text{Message}(s' \sigma''')$. Thus we conclude that $(\sigma'', \theta') \in \text{Sol}_r(C')$. 


We have proved that there exists $C' \in \Sigma'$ and a substitution $\sigma''$ such that $(\sigma'',\theta) \in \text{Sol}_c(C')$ and $\nu E. \Phi \sigma_{E,N,a} \sim_{T(F,A,X)} \nu E. \Phi' \sigma'' \sigma_{E,N,a}$. Hence the result holds.

**Lemma 6.3.** Let $E$ be a set of private names. Let $\Phi$ and $\Phi'$ two ground frames with the same domain and $ax_1 = ax_1 \Phi' \in E$. If for all $N'$, there exists $N > N'$ such that $\Phi \sigma_{E,N,a} \sim_{T(F,A,X)} \Phi' \sigma_{E,N,a}$ then $\Phi \sim_c \Phi'$.

**Proof.** Let $\xi, \xi' \in T(F,A,X \cup N \setminus E)$ such that $\text{param}(\xi) \subseteq \text{dom}(\Phi)$, $\text{param}(\xi') \subseteq \text{dom}(\Phi')$ and $\text{fnames}(\xi, \xi') \cap E = \emptyset$. Let $N'$ the number of occurrence of $h$ in $\xi$, $\xi'$, $\Phi$ and $\Phi'$. By hypothesis the exists $N > N'$ such that $\Phi \sigma_{E,N,a} \sim_{T(F,A,X)} \Phi' \sigma_{E,N,a}$. Since $N > N'$, we have that $\text{len}_n(\xi') < N$, $\text{len}_n(\Phi') < N$ and $\text{len}_n(\xi') < N$.

- Thanks to Corollary C.1 and $\text{len}_n(\xi') < N$, $\text{Message}(\Phi')$ is equivalent to $\text{Message}((\xi \theta_{E,N})(\Phi \sigma_{E,N,a}))$. But $\xi \theta_{E,N} \in T(F,A,X)$ and $\text{param}(\xi \theta_{E,N}) \subseteq \text{dom}(\Phi) = \text{dom}(\Phi \sigma_{E,N,a})$. Hence we deduce that $\Phi \sigma_{E,N,a} \sim_{T(F,A,X)} \Phi' \sigma_{E,N,a}$ implies that $\text{Message}((\xi \theta_{E,N})(\Phi \sigma_{E,N,a}))$ is equivalent to $\text{Message}((\xi \theta_{E,N})(\Phi' \sigma_{E,N,a}))$.

Once again by Corollary C.1 and $\text{len}_n(\xi') < N$, we deduce that $\text{Message}((\xi \theta_{E,N})(\Phi' \sigma_{E,N,a}))$ is equivalent to $\text{Message}(\xi \Phi')$. Thus $\text{Message}(\Phi')$ is equivalent to $\text{Message}(\xi \Phi')$.

- Assume that $\xi \Phi' = \xi \Phi'$. $\text{Message}(\Phi')$ and $\text{Message}(\xi \Phi')$. Corollary C.1, $\text{len}_n(\xi') < N$ and $\text{len}_n(\xi') < N$ imply that $(\xi \theta_{E,N})(\Phi \sigma_{E,N,a}) \downarrow = (\xi \Phi')(\Phi \sigma_{E,N,a})$ and $(\xi \theta_{E,N})(\Phi \sigma_{E,N,a}) \downarrow = (\xi \Phi')(\Phi \sigma_{E,N,a})$. Hence from $\xi \Phi' = \xi \Phi'$, we deduce that $(\xi \theta_{E,N})(\Phi \sigma_{E,N,a}) \downarrow = (\xi \theta_{E,N})(\Phi' \sigma_{E,N,a}) \downarrow$. But $(\xi \theta_{E,N}), (\xi \theta_{E,N}) \in T(F,A,X)$. Moreover, thanks to by Corollary C.1, we also have $\text{Message}((\xi \theta_{E,N})(\Phi \sigma_{E,N,a}))$ and $\text{Message}((\xi \theta_{E,N})(\Phi' \sigma_{E,N,a}))$. Thus we deduce that $\Phi \sigma_{E,N,a} \sim_{T(F,A,X)} \Phi' \sigma_{E,N,a}$ implies that $(\xi \theta_{E,N})(\Phi' \sigma_{E,N,a}) \downarrow = (\xi \theta_{E,N})(\Phi' \sigma_{E,N,a}) \downarrow$. Once again by Corollary C.1, $\text{len}_n(\xi') < N$ and $\text{len}_n(\xi') < N$, $(\xi \theta_{E,N})(\Phi' \sigma_{E,N,a}) \downarrow = (\xi \Phi')(\Phi' \sigma_{E,N,a}) \downarrow$ implies that $(\xi \Phi')(\Phi' \sigma_{E,N,a}) \downarrow$. Thus thanks to Lemma C.1, we deduce that $\xi \Phi' \downarrow = \xi \Phi' \downarrow$. The proof of the other side of the static equivalence can be done symmetrically.

We can conclude that $\Phi \sim_c \Phi'$.

**C.1.2 Normalised recipe**

For a recipe $\xi$ and a frame $\Phi$, we say that $\text{root}(\xi)$ is not reduced if $\text{f}(\xi_1, \ldots, \xi_n) \Phi \downarrow = \text{f}(\xi_1 \Phi, \ldots, \xi_n \Phi)$ and $\text{root}(\xi) \in F_d$ with $\xi = \text{f}(\xi_1, \ldots, \xi_n)$ for some $\xi_1, \ldots, \xi_n$. We establish three properties on the recipes in $\Pi_n$:

**Lemma C.3.** Let $\Phi$ be a ground frame such that for all $(ax_i \triangleright u_i) \in \Phi$, $\text{Message}(u_i)$. Let $\xi$ be a recipe such that $\text{param}(\xi) \subseteq \text{dom}(\Phi)$, $\xi \Phi \downarrow \not\in T(F_c,N)$. If for every $\xi' \in s(\xi)$,

$$\xi' = \text{f}(\xi_1, \ldots, \xi_n, \ldots, \beta_m), f \in F_d \text{ and } g \in F_c \text{ implies } f \text{ is not reduced},$$

then, either $\text{root}(\xi) \in F_c$ or $\text{root}(\xi)$ is not reduced.

**Proof.** We prove this result by induction on the size of $\xi$.

*Base case:* $|\xi| = 1$. In such a case, $\xi \in \text{dom}(\Phi)$ and so $\xi \Phi \downarrow \in T(F_c,N)$ by hypothesis on the frame. Hence the result trivially holds.

*Induction step:* $|\xi| > 1$. If $\text{root}(\xi) \in F_c$ or $\text{root}(\xi)$ is not reduced then the property trivially holds. Else we have that $\xi = \text{f}(\xi_1, \ldots, \xi_m)$ with $f \in F_d$ and $f$ is reduced. We show that this case is impossible.

$f$ is reduced implies that there is a rewrite rule $\text{f}(u_1, \ldots, u_n) \rightarrow u$ such that $\text{f}(u_1, \ldots, u_n)$ and $\text{f}(\xi_1 \Phi, \ldots, \xi_n \Phi)$ are unifiable. Since $\xi \Phi \not\in T(F_c,N)$ and $\xi \Phi \downarrow \in s(\xi_1 \Phi \downarrow)$ (since $u \in s(\xi_1)$), we have that $\xi_1 \Phi \downarrow \not\in T(F_c,N)$. By applying our induction hypothesis on $\xi_1$, we deduce that either $\text{root}(\xi_1) \in F_c$ or $\text{root}(\xi_1)$ is not reduced.
• If root(ξ₁) ∈ F_c then by hypothesis on the subterms of ξ, we deduce that f is not reduced which is in contradiction with the hypothesis.

• If root(ξ₁) is not reduced, then root(ξ₁Φ↓) ∈ F_d. This contradicts the fact that f(u₁, . . . , uₙ) and f(ξ₁Φ↓, . . . , ξₙΦ↓) are unifiable since we have that root(u₁) ∈ F_c.

This allows us to conclude that either root(ξ) ∈ F_c or root(ξ) is not reduced.

The following corollary is a direct consequence of Lemma C.3 since by definition of ξ ∈ Πₙ, there is no ξ′ ∈ st(ξ) of form f(ξ₁, . . . , ξₙ) with f ∈ F_d and root(ξ₁) ∈ F_c.

Corollary C.2. Let Φ be a ground frame such that for all (ax_i ▷ u_i) ∈ Φ, Message(u_i). Let ξ ∈ Πₙ such that param(ξ) ⊆ dom(Φ) and Φ↓ ∈ T(F_c, N). We have that either root(ξ) ∈ F_c or root(ξ) is not reduced.

Lemma 6.5. Let Φ be a ground frame such that for all (ax_i ▷ u_i) ∈ Φ, Message(u_i). Let ξ ∈ Πₙ a ground recipe such that param(ξ) ⊆ dom(Φ). Φ↓ ∈ T(F_c, N) if, and only if, Message(ξΦ) holds.

Proof. We prove this result by induction on the size of ξ.

Base case: |ξ| = 1. In such a case, ξ ∈ dom(Φ) thus there exists (ax_i ▷ u_i) ∈ Φ such ax_i = ξ and Φ↓ = u↓. But Message(u_i) holds thus by definition, u↓ ∈ T(F_c, N). Hence, the result holds.

Induction case: |ξ| > 1. In such a case, we have that ξ = f(ξ₁, . . . , ξₙ) with f ∈ F_c ∪ F_d. Assume first that f ∈ F_c. In such a case, ξΦ↓ ∈ T(F_c, N) for every i ∈ {1, . . . , n}. Hence, we can apply our induction hypothesis on each ξ_i. This allows us to conclude.

Assume now that f ∈ F_d. By hypothesis, we have that ξΦ↓ ∈ T(F_c, N) and so f is reduced by the rewriting system. Let f(u₁, . . . , uₙ) → u be the rewrite rule involved in f(ξ₁Φ↓, . . . , ξₙΦ↓) → Φ↓. We distinguish two cases:

• Case 1: ξ₁Φ↓ ∈ T(F_c, N). Since vars({u₂, . . . , uₙ}) ⊆ vars(u₁), we deduce that for every i ∈ {1, . . . , n}, ξ_iΦ↓ ∈ T(F_c, N). Hence, we easily conclude by applying our induction hypothesis.

• Case 2: ξ₁Φ↓ ∉ T(F_c, N). Thanks to Corollary C.2, we deduce that either root(ξ₁) ∈ F_c or root(ξ₁) is not reduced. Since ξ ∈ Πₙ, we have that root(ξ₁) ∉ F_c, hence root(ξ₁) is not reduced. It implies that root(ξ₁Φ↓) ∈ F_d. By definition of a rewriting rule, we know that root(u₁) ∈ F_c. This contradicts the fact that f(u₁, . . . , uₙ) and f(ξ₁Φ↓, . . . , ξₙΦ↓) are unifiable. Hence, this case is impossible.

Lemma C.4. Let Φ be a ground frame such that for all (ax_i ▷ u_i) ∈ Φ, Message(u_i). Let ξ be a recipe such that param(ξ) ⊆ dom(Φ) and ξ ∉ Πₙ. If for all f(ξ₁, . . . , ξₙ) ∈ st(ξ), f ∈ F_d and root(ξ₁) ∈ F_c imply f is not reduced, then Φ↓ ∉ T(F_c, N).

Proof. We prove this result by induction on the size of ξ.

Base case: |ξ| = 1. In such a case, we have that ξ ∈ dom(Φ), and thus ξ ∈ Πₙ. Hence, there is nothing to prove.

Induction step: |ξ| > 1. In such a case, we have that ξ = f(ξ₁, . . . , ξₙ) with f ∈ F_c ∪ F_d. We distinguish several cases:

• Case 1, f ∈ F_c: In such a case, we have that ξ_i ∉ Πₙ for some i ∈ {1, . . . , n}. Assume w.l.o.g. that ξ₁ ∉ Πₙ. Hence, by applying our induction hypothesis on ξ₁, we deduce that ξ₁Φ↓ ∉ T(F_c, N). Since ξΦ↓ = f(ξ₁Φ↓, . . . , ξₙΦ↓), we have that Φ↓ ∉ T(F_c, N). The same reasoning holds when i ∈ {2, . . . , n}.

• Case 2, f is not reduced: In such a case, we have that root(ξΦ↓) ∈ F_d. Hence, we have that Φ↓ ∉ T(F_c, N). This allows us to conclude.
C.1. GETTING RID OF SOME RECIPES

- Case 3, \( f \in \mathcal{F}_d \) and \( f \) is reduced. In such a case, by hypothesis, we have that \( \text{root}(\xi_1) \not\in \mathcal{F}_c \).
  Let \( f(u_1, \ldots, u_n) \rightarrow u \) be the rewrite rule involved in \( f(\xi_1, \ldots, \xi_n) \rightarrow \xi_1 \).
  Since \( \xi \not\in \Pi_n \), we have that \( \xi_i \not\in \Pi_n \) for some \( i \in \{1, \ldots, n\} \).
  We distinguish two cases:

1. If \( \xi_1 \not\in \Pi_n \), then by applying our induction hypothesis on \( \xi_1 \), we have that \( \xi_1 \not\in \mathcal{T}(\mathcal{F}_c, \mathcal{N}) \).
2. Otherwise, if \( \xi_i \not\in \Pi_n \) for some \( i \in \{2, \ldots, n\} \), then by applying our induction hypothesis on \( \xi_i \), we have that \( \xi_i \not\in \mathcal{T}(\mathcal{F}_c, \mathcal{N}) \), and thus \( \xi_1 \not\in \mathcal{T}(\mathcal{F}_c, \mathcal{N}) \) since vars \((u_i)\) \( \subseteq \) vars \((u_1)\) and \( u_1, u_i \) are constructor terms.

Hence, in both cases, we have that \( \xi_1 \) is reduced. Thanks to Lemma C.3 we know that either \( \text{root}(\xi_1) \in \mathcal{F}_d \) or \( \text{root}(\xi_1) \) is not reduced. We have already shown that \( \text{root}(\xi_1) \not\in \mathcal{F}_c \), thus we have that \( \text{root}(\xi_1) \) is not reduced, and thus \( \text{root}(\xi_1) \) is reduced. This contradicts the fact that \( \text{root}(\xi_1) \in \mathcal{F}_d \) and \( \text{root}(\xi_1) \) is reduced. Thus, this case is impossible.

\[ \square \]

**Lemma 6.6.** Let \( \Phi \) be a ground frame such that for all \( (ax_i \triangleright u_i) \in \Phi \), \( \text{Message}(u_i) \). Let \( \xi \in \mathcal{T}(\mathcal{F}_c, \mathcal{N} \cup AX) \). If \( \text{Message}(\Phi) \) then there exists a ground recipe \( \xi' \in \Pi_n \) such that \( \xi \rightarrow \xi' \), \( \text{Message}(\xi') \) and \( \text{param}(\xi') \subseteq \text{param}(\xi) \)

**Proof.** We prove this result by induction on the number of subterm \( \xi' \) of \( \xi \) such that \( \xi' \) is of the form \( g(\xi_1, \ldots, \xi_n) \), \( g \in \mathcal{F}_d \) and \( \text{root}(\xi_1) \in \mathcal{F}_d \). We denote this number \( N(\xi) \)

**Base case** \( N(\xi) = 0 \): In such a case, we have that \( \xi \in \Pi_n \) and so the result holds.

**Inductive step** \( N(\xi) > 0 \): Let \( p \in \mathcal{P}(\xi) \) such that \( \xi_p = g(\xi_1, \ldots, \xi_n) \), \( g \in \mathcal{F}_d \) and \( \text{root}(\xi_1) \in \mathcal{F}_d \).
By hypothesis, we have \( \text{Message}(\Phi) \) hence it implies that \( g(\xi_1, \ldots, \xi_n) \rightarrow \xi_1 \) is reduced. Since \( \text{root}(\xi_1) \in \mathcal{F}_d \), we have \( \xi_1 = f(\alpha_1, \ldots, \alpha_m) \) for some \( f \in \mathcal{F}_c \) and some receive \( \alpha_1, \ldots, \alpha_m \).
However, according to the rewriting system, \( g \) is reduced implies that \( p(\xi_1) = f(\alpha_1, \ldots, \alpha_m) \).

Let \( \xi' = \xi_p \). We deduce that \( \xi' \rightarrow \xi_1 \). Moreover, \( \alpha \in \text{st}(\xi) \) and \( \text{Message}(\xi') \) implies that \( \text{Message}(\xi') \) and \( \text{param}(\xi') \subseteq \text{param}(\xi) \).
At last, since \( N(\xi') < N(\xi) \) then by inductive hypothesis on \( \xi' \), there exists \( \xi'' \in \Pi_n \) such that \( \xi'' \rightarrow \xi_1 \), \( \text{root}(\xi'') \in \mathcal{F}_c \), \( \text{Message}(\xi'') \) and \( \text{param}(\xi'') \subseteq \text{param}(\xi') \subseteq \text{param}(\xi) \).

\[ \square \]

**Lemma C.5.** Let \( \Phi, \Phi' \) be ground frames of some domain and such that for all \( (ax_i \triangleright u_i) \in \Phi \) (resp. \( \Phi' \)), \( \text{Message}(u_i) \). Assume that \( \Phi \sim \Phi' \). Let \( \xi_1, \xi_2, \xi_3 \in \mathcal{T}(\mathcal{F}_c, \mathcal{A}X) \) such that \( \text{param}((\xi_1, \xi_2, \xi_3)) \subseteq \text{dom}(\Phi) \) and for all \( f(\alpha_1, \ldots, \alpha_n) \in \text{st}(\xi_1) \) (\( i = 1, 2, 3 \)), \( \text{root}(\alpha_1) \in \mathcal{F}_c \) implies \( f \) is not reduced by \( \Phi \). The following properties hold:

1. \( \text{Message}(\xi_3 \Phi) \) implies \( \text{Message}(\xi_3 \Phi') \); and
2. if \( \text{Message}(\xi_1 \Phi), \text{Message}(\xi_2 \Phi) \), \( \xi_1 \Phi' = \xi_2 \Phi' \), then \( \xi_1 \Phi' = \xi_2 \Phi' \).

**Proof.** Assume that \( \text{Message}(\xi_3 \Phi) \) thus \( \xi_3 \Phi' \in \mathcal{T}(\mathcal{F}_c, \mathcal{N}) \). In such a case, thanks to Lemma C.4, we have that \( \xi_3 \in \Pi_n \). Since \( \Phi \sim \Phi' \), we easily conclude that \( \text{Message}(\xi_3 \Phi') \).

Now, assume that \( \text{Message}(\xi_1 \Phi), \text{Message}(\xi_2 \Phi) \) and \( \xi_1 \Phi' = \xi_2 \Phi' \). First, if \( \xi_1 \) and \( \xi_2 \) are in \( \Pi_n \), then the result trivially holds. Otherwise, we prove that \( \xi_1 \Phi' = \xi_2 \Phi' \) by induction on \( \max((|\xi_1|, |\xi_2|)) \).

**Base case** \( \max((|\xi_1|, |\xi_2|)) = 1 \): In such a case, we have that \( \xi_1, \xi_2 \in \text{dom}(\Phi) \) and so \( \xi_1, \xi_2 \in \Pi_n \). We already proved that the result holds.

**Induction step** \( \max((|\xi_1|, |\xi_2|)) > 1 \): We assume w.l.o.g. that \( \xi_1 \not\in \Pi_n \). In such a case, thanks to Lemma C.4, we have that \( \xi_1 \Phi' \not\in \mathcal{T}(\mathcal{F}_c, \mathcal{N}) \) and since \( \xi_1 \Phi' \not\in \mathcal{T}(\mathcal{F}_c, \mathcal{N}) \) thanks to Lemma C.3 we have that:

- either \( \text{root}(\xi_1) \) is not reduced or \( \text{root}(\xi_1) \in \mathcal{F}_c \); and
- either \( \text{root}(\xi_2) \) is not reduced or \( \text{root}(\xi_2) \in \mathcal{F}_c \).
Hence, we deduce that $\xi_1 = f_1(\alpha_1, \ldots, \alpha_m)$ and $\xi_2 = f_2(\beta_1, \ldots, \beta_k)$ for some $f_1, \alpha_1, \ldots, \alpha_m$ and $f_2, \beta_1, \ldots, \beta_k$. Moreover, we also deduce that

$$\xi_1 \Phi \downarrow = f_1(\alpha_1 \Phi \downarrow, \ldots, \alpha_m \Phi \downarrow) \text{ and } \xi_2 \Phi \downarrow = f_2(\beta_1 \Phi \downarrow, \ldots, \beta_k \Phi \downarrow).$$

Since $\xi_1 \Phi \downarrow = \xi_2 \Phi \downarrow$, it implies that $f_1 = f_2$, $k = m$ and $\alpha_i \Phi \downarrow = \beta_i \Phi \downarrow$ for every $i \in \{1, \ldots, m\}$. Moreover, $\text{Message}(\xi_1 \Phi)$ implies $\text{Message}(\alpha \Phi)$ and $\text{Message}(\xi_2 \Phi)$ implies $\text{Message}(\beta \Phi)$ for all $i \in \{1, \ldots, m\}$. By applying our induction hypothesis on $\alpha_i, \beta_i$, we have that $\alpha_i \Phi' \downarrow = \beta_i \Phi' \downarrow$ for every $i \in \{1, \ldots, m\}$. This allows us to deduce that $f_1(\alpha_1 \Phi' \downarrow, \ldots, \alpha_m \Phi' \downarrow) = f_2(\beta_1 \Phi' \downarrow, \ldots, \beta_k \Phi' \downarrow)$, and thus $\xi_1 \Phi' \downarrow = \xi_2 \Phi' \downarrow$.

**Lemma 6.7.** Let $\Phi$ and $\Phi'$ be two ground frames such that for all $(ax_i \triangleright u_i) \in \Phi$ (resp. $\Phi'$), $\text{Message}(u_i)$. $\Phi \sim_{T(F, AX)} \Phi'$ is equivalent to $\Phi \sim_{\Pi_n} \Phi'$.----------

**Proof.** The right implication (⇒) is an easy case. Indeed, for all $\xi, \xi' \in \Pi_n$, by definition of $\Pi_n$, we have $\xi, \xi' \in T(F, AX)$. Hence, since $\Phi \sim_{T(F, AX)} \Phi'$, $\text{Message}(\xi \Phi)$ is equivalent to $\text{Message}(\xi' \Phi')$. Furthermore, if $\text{Message}(\xi \Phi)$ and $\text{Message}(\xi' \Phi')$ then $\xi \Phi \downarrow = \xi' \Phi' \downarrow$ is equivalent to $\xi \Phi \downarrow = \xi' \Phi' \downarrow$. Hence $\Phi \sim_{\Pi_n} \Phi'$.

We now prove the left implication (⇐) of the equivalence. Let $\xi_1, \xi_2 \in T(F, AX)$ such that $\text{param}(\xi_1, \xi_2) \subseteq \text{dom}(\phi)$. We show that

- $\text{Message}(\xi_1 \Phi)$ implies $\text{Message}(\xi_1 \Phi')$; and
- if $\text{Message}(\xi_1 \Phi)$ and $\text{Message}(\xi_2 \Phi)$ then $\xi_1 \Phi \downarrow = \xi_2 \Phi \downarrow$ implies $\xi_1 \Phi' \downarrow = \xi_2 \Phi' \downarrow$.

Let $n_1$ (resp. $n_2$) be the number of subterms of the form $f(\alpha_1, \ldots, \alpha_n) \in \text{st}(\xi_1)$ (resp. $\text{st}(\xi_2)$) such that $f \in F_d$, $\text{root}(\alpha_1) \in F_c$ and $f$ is reduced by $\Phi$. Let $n = \max(n_1, n_2)$ and $m = |\xi_1| + |\xi_2|$. We prove this result by induction on $(n, m)$ with the lexicographic ordering. We assume that $\text{Message}(\xi_1 \Phi)$ and $\text{Message}(\xi_2 \Phi)$.

**Base case:** $n = 0$. In such a case, for all $f(\alpha_1, \ldots, \alpha_n) \in \text{st}([\xi_1, \xi_2])$, $\text{root}(\alpha_1) \in F_c$ and $f \in F_d$ imply $f$ is not reduced. Hence, we apply Lemma [6.5] and so the result holds.

**Induction step:** $n > 0$. There exists w.l.o.g $p \in \mathcal{P}os(\xi_1)$ such that $\xi_1|_p = \xi$ where $\xi = f(\alpha_1, \ldots, \alpha_n)$, $f \in F_d$, $\text{root}(\alpha_1) \in F_c$ and $f$ is reduced by $\Phi$. Thus, there exists a rewriting rule that can be applied on the position $p$ of $\xi_1$. We consider the different rewriting rules in turn:

- $f = \text{proj}_1$ with $\xi = \text{proj}_1(\alpha_1, \alpha_2)$. Moreover $\text{Message}(\xi_1 \Phi)$ implies $\text{Message}(\alpha_2 \Phi)$ and $\text{Message}(\beta_2 \Phi)$;
- $f = \text{proj}_2$ with $\xi = \text{proj}_2(\beta_1, \beta_2)$. Moreover $\text{Message}(\xi_1 \Phi)$ implies $\text{Message}(\alpha_2 \Phi)$ and $\text{Message}(\beta_2 \Phi)$;
- $f = \text{check}$ with $\xi = \text{check}(\text{sign}(\beta_1, \beta_2), \alpha_2)$ and $\alpha_2 \Phi \downarrow = \emptyset \Phi \downarrow$. Moreover $\text{Message}(\xi_1 \Phi)$ implies $\text{Message}(\alpha_2 \Phi)$ and $\text{Message}(\beta_2 \Phi)$;
- $f = \text{check}$ with $\xi = \text{check}(\text{sign}(\beta_1, \beta_2), \alpha_2)$ and $\alpha_2 \Phi \downarrow = \emptyset \Phi \downarrow$. Moreover $\text{Message}(\xi_1 \Phi)$ implies $\text{Message}(\alpha_2 \Phi)$ and $\text{Message}(\beta_2 \Phi)$;
- $f = \text{proj}_1$ with $\xi = \text{proj}_1(\alpha_1, \alpha_2)$. Moreover $\text{Message}(\xi_1 \Phi)$ implies $\text{Message}(\beta_1 \Phi)$;
- $f = \text{proj}_2$ with $\xi = \text{proj}_2(\beta_1, \beta_2)$. Moreover $\text{Message}(\xi_1 \Phi)$ implies $\text{Message}(\beta_1 \Phi)$.

In the first three cases, we can apply our induction hypothesis in order to deduce that:

- $f = \text{proj}_1 \downarrow \Phi = \beta_2 \Phi' \downarrow$; or
- $f = \text{proj}_2 \downarrow \Phi = \beta_2 \Phi' \downarrow$; or
- $f = \text{check} \downarrow \alpha_2 \Phi' \downarrow = (\emptyset \Phi) \downarrow$. or
- $f = \text{check} \downarrow \alpha_2 \Phi' \downarrow = (\emptyset \Phi) \downarrow$. or
Hence, we can deduce that \( \xi \Phi' \downarrow = \beta_1 \Phi' \downarrow \). Note that this result trivially holds when \( f \in \{\text{proj}_1, \text{proj}_2\} \). Hence, we have that:

\[
\xi_1 \Phi \downarrow = (\xi_1[\beta_1]_p) \Phi \downarrow \text{ and } \xi_1[\Phi'] \downarrow = (\xi_1[\beta_1]_p) \Phi' \downarrow
\]

Moreover, since \( \xi \Phi' \downarrow = \beta_1 \Phi' \downarrow \), Message(\( \xi_1 \Phi \)) and Message(\( \beta_1 \Phi \)), we have that Message(\( \xi_1[\beta_1]_p \Phi \)).

We apply now our induction hypothesis on \( \xi_1[\beta_1]_p \) and \( \xi_2 \). Note that even if the first measure does not decrease, we necessarily have that \( [\xi_1[\beta_1]] < [\xi_1] \). This allows us to obtain that Message(\( \xi_1[\beta_1]_p \Phi' \)). Moreover, if \( \xi_1 \Phi \downarrow = \xi_2 \Phi' \downarrow \), then we have that \( \xi_1[\beta_1]_p \Phi \downarrow = \xi_2 \Phi' \downarrow \) and so by our induction hypothesis, we deduce that \( \xi_1[\beta_1]_p \Phi' \downarrow = \xi_2 \Phi' \downarrow \), and thus \( \xi_1 \Phi \downarrow = \xi_2 \Phi' \downarrow \). The other side of the static equivalence is proved symmetrically. This allows us to conclude.

\[ \square \]

### C.1.3 Constructor constraint system

**Lemma C.6.** Let \( s \in \mathcal{T}(\mathcal{F} \cup \mathcal{N}, \mathcal{X}^1) \). Assume that \( s' \in st(s) \) such that root(\( s' \)) \( \in \mathcal{F}_d \) and all strict subterms of \( s' \) is constructive. If for all fresh rewriting rule \( \ell \rightarrow r \), \( \ell \) is not unifiable with \( s' \), then for all mapping \( \tau \) from \( \vars^1(s) \) to ground constructor terms, \( \neg \text{Message}(st) \).

**Proof.** Let \( \tau \) a mapping from \( \vars^1(s) \) to ground constructor terms. Assume that Message(st). By definition of Message(), we can deduce that \( s' \tau \downarrow \in \mathcal{T}(\mathcal{F}_c, \mathcal{N}) \). But root(\( s' \)) \( \in \mathcal{F}_d \), thus \( s' \tau \) has to be reduced. Let's assume that \( s' = f(u_1, \ldots, u_n) \). We know that all strict subterms of \( s' \) only contain constructor; but \( \tau \) is a mapping to ground constructor terms. Therefore, we have \( u_i \tau \downarrow = u_i \tau, \) for \( i = 1 \ldots n \), which means that \( s' \tau \) is reducible implies that \( s' \) is unifiable with a fresh rewriting rule. It implies a contradiction with our hypothesis and so \( \neg \text{Message}(st) \).

**Lemma C.7.** Let \( s, t \in \mathcal{T}(\mathcal{F} \cup \mathcal{N}, \mathcal{X}^1) \) such that \( s \xrightarrow{\sigma} t \). For all mapping \( \tau \) (resp. \( \tau' \)) from a set of variable including \( \vars^1(s) \) (resp. \( \vars^1(t) \)) to ground constructor terms, we have:

- **Message\((st)\)** implies that there exists \( \tau' \) such that \( \tau = (\sigma \tau')\downarrow_{\dom(\tau)} \), Message\((t\tau')\) and \( s\tau \downarrow = t\tau' \downarrow \).

- **Message\((t\tau')\)** implies that there exists \( \tau \) such that \( \tau = \sigma \tau', \) Message\((st)\), and \( s\tau \downarrow = t\tau' \downarrow \).

**Proof.** Let \( s, t \in \mathcal{T}(\mathcal{F} \cup \mathcal{N}, \mathcal{X}^1) \) such that \( s \xrightarrow{\sigma} t \). Let \( \tau \) (resp. \( \tau' \)) a mapping from \( \vars(s) \) (resp. \( \vars(t) \)) to ground constructor terms. We prove the two result separately:

- If **Message\((st)\)**: By hypothesis, we know that \( s \xrightarrow{\sigma} t \) and so there exists a fresh rewriting rule \( \ell \rightarrow r \) and a position \( p \) non variable of \( s \) such that:

  \[
  \sigma = \text{mgu}(\ell, s_p) \quad \text{and} \quad t = s \sigma[p]_p
  \]

  By definition of a rewriting rule, we deduce that \( s \sigma \downarrow = t \sigma \downarrow = s_p \sigma \downarrow \). Thus, it implies that \( t \downarrow = s \sigma[p]_p \downarrow = s \sigma \downarrow \).

  But by Lemma C.6, we know that Message(st) implies that there exists a fresh rewriting rule \( \ell' \rightarrow r' \) such that \( \ell' \) and \( s_p \tau \) are unifiable. Since we consider rewriting rule such that a destructor can be reduced by only one rewriting rule, we deduce that \( \ell \rightarrow r \) is the same rule as \( \ell' \rightarrow r' \) and so \( \ell \) and \( s_p \tau \) are unifiable. Since \( s_p \tau \) is closed, there exists \( \tau'' \) such that \( \dom(\tau'') = \vars^1(\ell) \) and \( \ell'' = s_p \tau \). \( \ell \) being fresh also implies that \( \dom(\tau'') \cap \dom(\tau) = \emptyset \) and so \( t \tau'' = s_p \tau \tau' \). But \( \sigma = \text{mgu}(\ell, s_p) \), which means that there exists a mapping \( \tau'' \) such that \( \tau'' \sigma = \sigma \tau' \). Hence \( \tau = (\sigma \tau'')\downarrow_{\dom(\tau)} \).

  But, we already know that \( t \downarrow = s \sigma \downarrow \), thus \( t \tau'' \downarrow = s \sigma \tau'' \downarrow = s \tau \downarrow \).

  At last, we check that Message\((t\tau')\). Let \( t' \in st(t \tau') \). If \( t' \in st(r \sigma \tau') \), then \( t' \in \mathcal{T}(\mathcal{F}_c, \mathcal{N}) \) since we know that \( \sigma \) and \( \tau' \) are both mapping to ground constructor terms and \( r \) is also a constructor term. If \( t' \notin st(r \sigma \tau') \) then a simple induction on the position \( p' \) of \( t' \) on \( t \) allows us to conclude that \( t' \downarrow = s_{p'} \sigma \tau' \downarrow \) and so \( \ell' \downarrow = s_{p'} \tau \downarrow \). But Message(st) implies \( s_{p'} \tau \downarrow \in \mathcal{T}(\mathcal{F}_c, \mathcal{N}) \) so \( s_{p'} \tau \downarrow \in \mathcal{T}(\mathcal{F}_c, \mathcal{N}) \).
As proved in the previous point, \( s \rightarrow_R t \) implies that \( t_\downarrow = s_\downarrow \). Thus \( t_\tau \downarrow = s_\tau \downarrow \) with \( \tau = \sigma \tau' \).

Let \( s' \in st(\sigma \tau) \), if \( s' \in st(\tau) \), then either \( s' \) is a strict subterm of \( \ell \tau \) or \( s' = \ell \tau \). In the first case, we know by the innermost strategy that all strict subterm are constructive terms which means that \( \text{Message}(s') \); in the second case, we know that \( \ell \tau \downarrow = r \tau \downarrow \). Since \( \text{Message}(\tau') \) and \( \tau = \sigma \tau' \), we can conclude that \( \ell \tau \downarrow \in \mathcal{T}(F_c, \mathcal{N}) \).

At last, if \( s' \not\in st(\tau) \), then a simple induction on the position \( p' \) of \( s' \) on \( s \) allows us to conclude that \( s_\downarrow = t_{p'} \tau \downarrow \) and so \( \text{Message}(s') \).

\[ \blacksquare \]

**Lemma 6.9.** Let \( E \) and \( E' \) be two conjunctions of equations between terms such that \( E \rightarrow_R E' \).

For all substitutions \( \tau \) on ground constructor terms,

- \( \tau \models_c E' \) implies that \( \sigma \tau \models_c E \)
- \( \tau \models_c E \) implies that there exists \( \tau' \) such that \( \tau = (\sigma \tau')|_{\text{dom}(\tau)} \) and \( \tau' \models_c E' \)

**Proof.** This Lemma is almost a direct implication of Lemma 6.7. Let \( E = \wedge_{i=1}^{n} u_i = v_i \) be a conjunction of equations between terms. Let \( \tau \) be a mapping from \( \text{vars}^{1}(E) \) to ground constructor terms, we have \( \tau \models E \) iff :

\[ \forall i \in \{1 \ldots n\}, u_i \downarrow = v_i \downarrow \land \text{Message}(u_i \tau) \land \text{Message}(v_i \tau) \]

Assume now that \( E \rightarrow_R E' \) and \( j \in \{1 \ldots n\} \) such that \( u_j \rightarrow_R t \).

- Assume that there exists a mapping \( \tau \) from \( \text{vars}^{1}(E) \) to ground constructor terms such that \( \tau \models_c E' \). It implies that \( \text{Message}(u_j \tau) \) and so by Lemma 6.7, we know that there exists a mapping \( \tau' \) from \( \text{vars}(E') \) to ground constructor terms such that \( \tau = (\sigma \tau')|_{\text{dom}(\tau)} \) and \( \tau' \models_c E' \).

- Assume that there exists a mapping \( \tau' \) from \( \text{vars}^{1}(E') \) to ground constructor terms such that \( \tau' \models_c E' \). It implies that \( \text{Message}(\tau') \) and so by Lemma 6.7, we have that \( \tau = \sigma \tau' \), \( \tau \downarrow = u_j \downarrow \) and \( \text{Message}(u_j \tau) \). But \( \tau \models E' \) also implies that \( \tau \downarrow = v_j \downarrow \) and \( \text{Message}(v_j \tau) \). At last, we know that \( (u_i, \sigma) \tau \downarrow = (v_i, \sigma) \tau \downarrow \), \( \text{Message}(u_i \tau) \) and \( \text{Message}(v_i \tau) \), for \( i = 1 \ldots n \) which means that \( \text{Message}((u_i, \sigma) \tau) \) and \( \text{Message}((v_i, \sigma) \tau) \). In the case of \( i = j \), we know that \( \text{Message}(\tau) \) by Lemma 6.7. We can conclude that \( \tau \models E \).

\[ \blacksquare \]

**Lemma 6.10.** Let \( \phi = \forall x \exists y \bigwedge_{i=1}^{m} u_i \neq v_i \) and \( \phi' = \forall y \exists x \bigwedge_{i=1}^{n} u_i \neq v_i \) two formulas such that \( \phi \rightarrow_R \phi' \). For all substitutions \( \tau \) of constructor terms, \( \tau \models_c \phi \) if and only if \( \tau \models_c \phi' \).

**Proof.** Assume first that \( \tau \not\models_c \phi \).

There exists a substitution \( \tau' \) on constructor terms such that \( \text{dom}(\tau') = y \) and \( \tau' \not\models \bigwedge_{i=1}^{n} u_i \neq v_i \). This implies that \( \tau' \models \sigma \land \text{E} \). By hypothesis, we have \( E \rightarrow_R E' \), hence \( \text{dom}(\sigma) \cap \text{fvars}(E') = \emptyset \). Thus \( \tau' \models_{\sigma} E' \) implies that there exists \( \tau'' \) such that \( \tau'' = \sigma \tau'' \) and \( \tau'' \models_c E' \). Hence by lemma 6.9 we deduce that \( \tau'' \models E \) and so \( \tau'' \not\models \bigwedge_{i=1}^{n} u_i \neq v_i \).

Since \( \sigma \tau'' = \tau'' \), \( \text{dom}(\tau') = \text{fvars}(\phi) \) and \( x \subseteq \text{dom}(\tau') \), we conclude that \( \tau \not\models_c \phi \).

Assume now that \( \tau \not\models_c \phi \).

There exists a substitution \( \tau' \) on ground constructor terms such that \( \text{dom}(\tau') = \tilde{x} \) and \( \tau' \not\models \bigwedge_{i=1}^{n} u_i \neq v_i \). This implies that \( \tau' \models E \). By hypothesis, we have \( E \rightarrow_R E' \), hence thanks to Lemma 6.9 we deduce that there exists \( \tau'' \) such that \( \tau'' = (\sigma \tau'')|_{\text{dom}(\tau') \cap \text{fvars}(\phi)} \) and \( \tau'' \models E' \). Hence, \( \sigma \tau'' \models_{\sigma} \text{E} \). Since \( \text{dom}(\tau) = \text{fvars}(\phi) \) and \( \sigma \tau'' = \sigma \tau'' \) | dom(\tau'), we deduce that there exists \( \tau'' = (\sigma \tau'')|_{y} \) such that \( \tau'' \models \bigwedge_{i=1}^{n} u_i \neq v_i \).

Hence we conclude that \( \tau \not\models_c \phi \).

\[ \blacksquare \]
Lemma 6.11. Let $\Sigma_1, \Sigma'_1$ two sets of concrete constraint systems having the same structure. There exist $\Sigma_2, \Sigma'_2$ two sets of constructor constraint systems having the same structure such that:

$$\Sigma_1 \approx^D_1 \Sigma'_1 \text{ if and only if } \Sigma_2 \approx_s \Sigma'_2$$

Proof. We first show how we obtain a constructor constraint system from a concrete constraint system. Then we will show that the solutions are preserved and finally we will prove the wanted equivalence.

Building the constructor constraint systems: Let $C = (E; \Phi; D; Eq)$ be a concrete constraint system where $\Phi = \{ax_1 \triangleright t_1, \ldots, ax_n \triangleright t_n\}$. Let $y_1, \ldots, y_n$ fresh variables. Assume that $Eq = E_c \wedge D$

where $D = \bigwedge_{j=1}^m u_j \neq v_j$ and $E_c$ is a conjunction of equations. We associate a constructor constraint system $C'$ or $\bot$ to $C$ as follows:

Let $E_0 = E_c \wedge \bigwedge_{i=1}^n y_i \not\equiv t_i$. Assume that $E_0 \not\rightarrow R E_1 \not\rightarrow R \ldots \not\rightarrow_R E_\ell$ and for all $E'$, for all $\sigma'$, $E_1 \not\rightarrow_{R'} E'$. $E_c$ exists since the narrowing strictly decrease the number of destructor symbols. If $E_\ell$ contains a function symbol then we associate $\bot$ to $C$.

Else, since applying a narrowing on a conjunction of equation does not change the number of conjunction, and for all $i \in \{1, \ldots, n\}$, $y_i$ are fresh variables, we deduce that $E_\ell = E_c' \wedge \bigwedge_{i=1}^n y_i \not\equiv t_i'$ for some $E_c', t_1', \ldots, t_n'$. Hence, we associate $C' = (\Phi'; D'; Eq')$ to $C$ where

1. $\alpha = \sigma_1 \ldots \sigma_\ell$
2. $D' = D\alpha$
3. $\Phi' = \{ax_1 \triangleright t_1', \ldots, ax_n \triangleright t_n'\}$
4. $Eq' = E_c' \wedge \bigwedge_{k \in I} \phi_k$

and $I \subseteq \{1 \ldots m\}$ satisfies:

- for all $k \in I$, $u_k\alpha \neq v_k\alpha \not\rightarrow_R \ldots \not\rightarrow_R \phi_k$, $\phi_k$ does not contain destructor symbols.
- for all $k \notin I$, for all $\phi$, $u_k\alpha \neq v_k\alpha \not\rightarrow_R \ldots \not\rightarrow_R \phi$ implies $\phi$ contain at least a destructor symbol.

By construction, $C'$ is a constructor constraint system. However, it remains to prove the following properties:

- for every $1 \leq k \leq n$, for every $z \in vars^1(t_k\alpha)$, there exists $(X, i \vdash x\alpha) \in D'$ such that $z \in vars^1(x\alpha)$ and $i < k$.
- for every the free variables $z$ of $Eq'$, there exists $(X, i \vdash x\alpha) \in D'$ such that $z \in vars^1(x\alpha)$.

Our rewriting system is subterm hence for all $s \not\rightarrow_R t$, for all $x \in vars^1(t)$, either $x \in vars^1(s)$ and $x \not\in \text{dom}(\sigma)$; or else there exists $y \in vars^1(s)$ such that $x \in vars^1(y\sigma)$. Thus, by extension to conjunction of equations, we have for all $\bigwedge_{k=1}^m u_k \neq v_k \not\rightarrow_R \bigwedge_{k=1}^m u'_k \neq v'_k$, for all $k \in \{1, \ldots, m\}$, for all $x \in vars^1(u'_k)$ (resp. $vars^1(v'_k)$), either $x \in vars^1(u_k)$ (resp. $vars^1(v_k)$) and $x \not\in \text{dom}(\sigma)$; or else there exists $y \in vars^1(u'_k)$ (resp. $vars^1(v'_k)$) such that $x \in vars^1(y\sigma)$.

By applying a simple induction on $\ell$, we can deduce that for all $i \in \{1, \ldots, n\}$, for all $x \in vars^1(t_i)$, either (a) $x \in vars^1(t_i)$ and $x \not\in \text{dom}(\sigma)$; or else (b) there exists $y \in vars^1(t_i)$ such that $x \in vars^1(y\alpha_1 \ldots \alpha_s)$. In case (a), by the origination property of concrete constraint systems, we deduce that there exists $(X, j \vdash x) \in D$ such that $j < i$. Since $x\alpha = x$, we deduce that $(X, j \vdash x) \in D'$ and so the result holds. In case (b), by the origination property of concrete constraint
systems, we deduced that there exists \((X, j \vdash y) \in D\) such that \(j < i\) and so \((X, j \vdash y \sigma) \in D'\). Since \(x \in \text{vars}^1(y \sigma)\), the results holds. The proof is similar for the variables in \(E'\).

At last, consider two formulas \(\phi\) and \(\phi'\) such that \(\phi \rightarrow_{R} \phi'\). By definition, we know that there exists \(E, E', \sigma, x, y\) such that: \(\phi = \forall \bar{x}. \neg E, \phi' = \forall \bar{x}. \neg (\sigma \land E')\), \(E \rightarrow_{R} E'\) and \(y = \text{vars}^1(\sigma) \land \neg E\).

We show that \(\text{fvars}(\phi') \subseteq \text{fvars}(\phi)\). Let \(z \in \text{fvars}(\phi')\) and \(z \notin x\) and either \(a)\) \(z \in \text{vars}^1(\sigma)\) or \(b)\) \(z \in \text{vars}^1(E')\). In case \(a)\), since \(y = \text{vars}^1(\sigma) \land \neg E\), we deduce that \(z \in \text{vars}^1(E)\). Moreover, with \(z \notin x\), we deduce that \(z \in \text{fvars}(\phi)\). In case \(b)\), we already proved that either \(z \in \text{vars}^1(E)\) or else there exists \(y \in \text{vars}^1(E)\) such that \(x \in \text{vars}^1(y \sigma)\). We do the same reasoning as in case \(a)\) and we conclude that \(z \in \text{fvars}(\phi)\).

For all \(k \in I\), by applying a simple induction on \(u_k \alpha \neq v_k \alpha \rightarrow_{R} \ldots \rightarrow_{R} \phi_k\), we deduced that \(\text{fvars}(\phi_k) \subseteq \text{vars}^1(u_k \alpha, v_k \alpha)\). Thus by applying the same reasoning as for the variables of \(t_i\), we can conclude that \(\text{fvars}(\phi_k) \subseteq \text{vars}^1(D')\).

Preserving the solution: We say that \(\text{Sol}(\bot) = \emptyset\). Let’s denote \(\text{Sol}^\text{II}_C(\bot) = \{(\sigma, \theta) \in \text{Sol}_C(\bot) \mid \forall X \in \text{dom}(\theta), X \theta \in \Pi_n\}\). We show the two following properties:

1. For all \((\sigma, \theta) \in \text{Sol}^\text{II}_C(\bot)\), there exists \(\sigma'\) such that \((\sigma', \theta) \in \text{Sol}(\bot)\) and \(\Phi \sigma \downarrow = \Phi' \sigma'\);

2. For all \((\sigma, \theta) \in \text{Sol}(\bot)\), there exists \(\sigma'\) such that \((\sigma, \theta) \in \text{Sol}^\text{II}_C(\bot)\) and \(\Phi \sigma \downarrow = \Phi' \sigma'\).

where \(\Phi'\) is the frame of \(C'\).

First property: Let \((\sigma, \theta) \in \text{Sol}^\text{II}_C(\bot)\). By definition, for all \(i \in \{1, \ldots, n\}\), \(\text{Message}(t_i \sigma)\). Let’s denote \(\tau = \{y_1 \mapsto t_1 \sigma; \ldots; y_n \mapsto t_n \sigma\} \cup \sigma\). We have that \(\tau \models_C \bigwedge_{i=1}^{n} y_i \triangleright t_i\). Moreover, \((\sigma, \theta) \in \text{Sol}^\text{II}_C(\bot)\) also implies that \(\sigma \models_C \text{Eq}\) hence \(\tau \models_C \text{Eq}^0\). At last, since \((\sigma, \theta) \in \text{Sol}^\text{II}_C(\bot)\) implies that for all \((X, i \vdash x) \in D\), \(\text{Message}(x \sigma)\), we deduced that \((\tau_\downarrow) \models_C \text{Eq}_0\) and \((\tau_\downarrow)\) is a mapping from \(\text{vars}^1(\text{Eq}_0)\) to ground constructor terms. Thanks to Lemma 6.9 we deduced with a simple induction on \(\ell\) that there exists \(\tau^r\) such that \(\tau^r = (\sigma_1 \ldots \sigma_\ell \tau^r)\) \(\text{dom}(\tau)\) and \(\tau^r \models_C \text{Eq}_\ell\). Thanks to Lemma C.6 we deduced that \(\text{Eq}_\ell\) does not contain a destructor and so \(C' \neq \bot\).

Let \(\sigma'\) be the substitution \(\tau^r\) restricted to the domain \(\text{dom}(\tau^r) \setminus \{y_1, \ldots, y_n\}\). We verify that \((\sigma', \theta) \in \text{Sol}(\bot)\). \(\tau_\downarrow \models_C \text{Eq}_0\) and \(\tau^r \models_C \text{Eq}_\ell\) and that \(\tau^r = \sigma_1 \ldots \sigma_\ell \tau^r\). Hence we deduce that \(\Phi \tau_\downarrow = \Phi' \tau^r\). Since the variables \(y_1, \ldots, y_n\) are not in \(\Phi\) nor \(\Phi'\), \(\Phi \sigma \downarrow = \Phi' \sigma'\). Furthermore, we know that for all \((X, i \vdash x) \in D\), \(\text{Message}(x \sigma)\). But \(x \sigma \downarrow = x \sigma_1 \ldots x \sigma_\ell \sigma = x \sigma^r = x \sigma \sigma^r\). Hence, we have that \(\text{Message}(\Phi' \sigma')\) is a mapping from \(\text{vars}^1(\text{Eq}_0)\) to ground constructor terms. Moreover, we know that \(\tau^r \models_C \text{Eq}_\ell\) and \(\text{Eq}_\ell\) contains constructor terms. Thus \(\tau^r \models_C \text{Eq}_\ell\). Since \(y \notin \text{vars}^1(\text{Eq}_\ell)\), we deduced that \(\sigma^r \models_C \text{Eq}_\ell\).

At last, let \(k \in I\). Since \(\tau \models_C u_k \neq v_k\) and for all \(x \in \text{dom}(\tau)\), \(\text{Message}(x \tau)\), we deduced that \(\tau_\downarrow \models_C u_k \neq v_k\) which implies that \(\sigma \sigma^r \models_C u_k \neq v_k\) and so \(\sigma \models_C u_k \alpha \neq v_k \alpha\). Thanks to Lemma 6.10 we deduced that \(\sigma \models_C \phi_k\). Since \(\phi_k\) only contains constructor terms, we deduce that \(\sigma \models_C \phi_k\). This concludes the proof of \((\sigma', \theta) \in \text{Sol}(\bot)\).

Second property: Let \((\sigma', \theta) \in \text{Sol}(\bot)\). By definition, we have that \(\sigma'\) is a mapping to ground constructor terms. Let denote \(\tau' = \{y_1 \mapsto t'_1 \sigma'; \ldots; y_n \mapsto t'_n \sigma'\} \cup \sigma'\). Hence \(\tau' \models_C \bigwedge_{i=1}^{n} y_i \triangleright t'_i \sigma'\). Moreover, \((\sigma', \theta) \in \text{Sol}(\bot)\) implies that \(\tau' \models_C \text{Eq}_\ell \bigwedge_{k \in I} \phi_k\). Thus, we deduced that \(\tau' \models_C \text{Eq}_\ell \bigwedge_{k \in I} \phi_k\).

Since all terms in \(\text{Eq}_\ell\) are constructor term, \(\tau' \models_C \text{Eq}_\ell \bigwedge_{k \in I} \phi_k\).

By Lemma 6.10 \(\tau' \models_C \bigwedge_{k \in I} \phi_k\) implies that \(\tau' \models_C \bigwedge_{k \in I} u_k \alpha \neq v_k \alpha\). Let \(k \notin I\), we know that for all \(\phi, u_k \alpha \neq v_k \alpha\) implies \(\phi\) contains a destructor. Assume that no narrowing can be apply on \(\phi\) (\(\phi\) exists since the narrowing strictly reduces the number of destructors). Let \(w \neq w' \in \phi\) such that \(w\) contains a destructor. By Lemma C.6 we deduced that for all mapping to ground constructor terms, and more specifically \(\tau', \neg \text{Message}(w \tau')\). Hence, we deduced that \(\tau' \models_C \bigwedge_{k=1}^{n} u_k \alpha \neq v_k \alpha\) and so \(\alpha \tau' \models_C D\).
C.1. GETTING RID OF SOME RECIPES

Thanks to Lemma [6.3] $\tau' \models_c E_0$, it implies that $\sigma_1 \ldots \sigma_r \models_c E_0$ and so $\alpha \tau' \models_c E_0$. Hence, $\alpha \tau' \models_c E_c$ and for all $i \in \{1, \ldots, n\}$, $\text{Message}(t_i \alpha \tau' \downarrow)$. Moreover, since $y_1, \ldots, y_n$ are not variable of $\alpha$, we deduce for all $i \in \{1, \ldots, n\}$, $t_i \alpha \tau' \downarrow = y_i \alpha \tau' \downarrow = y_i \tau' \downarrow = t_i' \tau'$.

Let $\sigma$ be the substitution such that for all $(X, i \vdash x) \in D$, $(X \theta)(\Phi \sigma) = x \sigma$. We prove by induction on $i$ that $\text{Message}(x \sigma)$, $x \sigma_1 \downarrow = x \sigma r \downarrow$ and $\text{Message}(t_i \sigma)$.

The base case $i = 0$ is trivial since there is no deducible constraint with $i = 0$.

Inductive step $i > 0$: $(\alpha', \theta) \in \text{Sol}(C')$ implies that $\text{param}(X \theta) \subseteq \{ax_1, \ldots, ax_i\}$. But thanks to the origination property of a constraint system, we know that for all $j \leq i$, for all $y \in \text{vars}^{-1}(t_j)$, there exists $(Y, k \vdash y) \in D$ such that $k < j \leq i$. Hence by our inductive hypothesis, $y \sigma_1 \downarrow = y \sigma r \downarrow$ and $\text{Message}(y \sigma)$. We already proved that $\text{Message}(t_j \alpha \tau' \downarrow)$ and $t_j \alpha \tau' \downarrow = t_j' \tau'$ thus $\text{Message}(t_j \sigma)$ and $t_j \sigma_1 \downarrow = t_j' \tau'$. Therefore $x \sigma_1 \downarrow = (X \theta)(\Phi \sigma) \downarrow = (X \theta)(\Phi' \sigma) \downarrow = x \sigma r \downarrow$. At last, since $X \theta \in \Pi_n$ and $x \sigma \downarrow = x \sigma r \downarrow \in T(F_c, N)$ then by Lemma 6.5 we deduce that $\text{Message}(x \sigma)$.

At last, since for all $x \in \text{dom}(\sigma)$, $x \sigma_1 \downarrow = x \sigma r \downarrow$ and $\text{Message}(x \sigma)$ then $x \sigma r \downarrow \models E_c$ implies $\sigma \models E_\Pi$ and $\alpha \tau' \models_c D$ implies $\sigma \models_D$. This conclude the proof of $(\sigma, \theta) \in \text{Sol}(\Pi_n(C'))$.

The main result: Let $\Sigma_1, \Sigma_2'$ two sets of concrete constraint systems having the same structure. We build $\Sigma_2, \Sigma_2' \Pi_n$ the two sets of constructor constraint system associated to $\Sigma_1, \Sigma_1'$ respectively.

- Assume that $\Sigma_2 \approx_{s_2} \Sigma_2'$: Let $C_1 \in \Sigma_1$, let $(\sigma_1, \theta) \in \text{Sol}(\Pi_n(C_1))$. We have shown that there exists $C_2 \in \Sigma_2$ and a substitution $\sigma_2$ such that $(\sigma_2, \theta) \in \text{Sol}(C_2)$ and $\Phi_1 \sigma_1 \downarrow = \Phi_2 \sigma_2$, where $\Phi_1$ and $\Phi_2$ are the respective frames of $C_1$ and $C_2$. Thus by our hypothesis, we deduce that there exists $C_2' \in \Sigma_2'$ and a substitution $\sigma_2'$ such that $(\sigma_2', \theta) \in \text{Sol}(C_2')$ and $\Phi_2 \sigma_2 \sim \Phi_2 \sigma_2'$, where $\Phi_2'$ is the frame of $C_2'$.

  We have shown that there exists $C_1' \in \Sigma_1'$ and a substitution $\sigma_1'$ such that $(\sigma_1', \theta) \in \text{Sol}(\Pi_n(C_1'))$ such that $\Phi_1' \sigma_1' \downarrow = \Phi_2' \sigma_2'$, where $\Phi_1'$ is the frame of $C_1'$.

  It remains to show that $\Phi_1 \sigma_1 \sim_{\Pi_n} \Phi_1' \sigma_1'$. First of all, $(\sigma_1, \theta) \in \text{Sol}(\Pi_n(C_1))$ and $(\sigma_1', \theta) \in \text{Sol}(\Pi_n(C_1'))$ implies that for all $(ax_i \triangleright u) \in \Phi_1 \sigma_1$ (resp. $\Phi_1' \sigma_1'$), $\text{Message}(u)$. Let $\xi, \xi' \in \Pi_n$ such that $\text{param}(\xi, \xi') \subseteq \text{dom}(\Phi_1 \sigma_1)$. Thanks to Lemma 6.5 $\text{Message}(\Phi_1 \sigma_1)$ is equivalent to $\xi \Phi_1 \sigma_1 \downarrow \in T(F_r, N)$. But we proved $\Phi_1 \sigma_1 \downarrow \sim \Phi_1' \sigma_1' \downarrow$ thus $\Phi_1 \sigma_1 \downarrow \sim \Phi_1' \sigma_1' \downarrow$. Moreover, we also proved that $\text{Message}(\xi \Phi_1 \sigma_1)$ is equivalent to $\text{Message}(\xi \Phi_1' \sigma_1')$. Assume now that $\text{Message}(\xi \Phi_1 \sigma_1)$ and $\text{Message}(\xi \Phi_1' \sigma_1')$. It implies that $\Phi_1 \sigma_1 \downarrow \sim \Phi_1' \sigma_1' \downarrow \sim \Phi_2 \sigma_2 \downarrow$ (resp. $\Phi_2' \sigma_2' \downarrow$), we deduce that $\Phi_1 \sigma_1 \downarrow \sim \Phi_1' \sigma_1' \downarrow$. Therefore, we deduce that $\Phi_1 \sigma_1 \sim_{\Pi_n} \Phi_1' \sigma_1'$. This conclude the proof of $\Sigma_1 \approx_{s_2} \Sigma_1'$.

- Assume that $\Sigma_1 \approx_{s_1} \Sigma_1'$: Let $C_2 \in \Sigma_2$, let $(\sigma_2, \theta) \in \text{Sol}(C_2)$. We have shown that there exists $C_1 \in \Sigma_1$ and a substitution $\sigma_1$ such that $(\sigma_1, \theta) \in \text{Sol}(\Pi_n(C_1))$ and $\Phi_1 \sigma_1 \downarrow = \Phi_2 \sigma_2$, where $\Phi_1$ and $\Phi_2$ are the respective frames of $C_1$ and $C_2$. Thus by our hypothesis, we deduce that there exists $C_1' \in \Sigma_1'$ and a substitution $\sigma_1'$ such that $(\sigma_1', \theta) \in \text{Sol}(C_1')$ and $\Phi_1 \sigma_1 \sim_{\Pi_n} \Phi_1' \sigma_1'$, where $\Phi_1'$ is the frame of $C_1'$.

  We have shown that there exists $C_2' \in \Sigma_2'$ and a substitution $\sigma_2'$ such that $(\sigma_2', \theta) \in \text{Sol}(C_2')$ such that $\Phi_1' \sigma_1' \sim_{\Pi_n} \Phi_2' \sigma_2'$, where $\Phi_2'$ is the frame of $C_2'$.

  It remains to show that $\Phi_2 \sigma_2 \sim \Phi_2' \sigma_2'$. First of all, $(\sigma_1, \theta) \in \text{Sol}(\Pi_n(C_1))$ and $(\sigma_1', \theta) \in \text{Sol}(\Pi_n(C_1'))$ implies that for all $(ax_i \triangleright u) \in \Phi_2 \sigma_2$ (resp. $\Phi_2' \sigma_2'$), $\text{Message}(u)$. Let $\xi, \xi' \in \Pi_n$ such that $\text{param}(\xi, \xi') \subseteq \text{dom}(\Phi_2 \sigma_2)$. Thanks to Lemma 6.5 $\text{Message}(\Phi_2 \sigma_2)$ is equivalent to $\xi \Phi_2 \sigma_2 \downarrow \in T(F_r, N)$. Since $\Phi_2 \sigma_2 \downarrow = \Phi_2' \sigma_2'$, we deduce that $\text{Message}(\xi \Phi_2 \sigma_2)$ is equivalent to $\text{Message}(\xi \Phi_2' \sigma_2')$. Similarly, $\text{Message}(\xi \Phi_2 \sigma_2)$ is equivalent to $\text{Message}(\xi \Phi_2' \sigma_2')$. Assume know that $\text{Message}(\xi \Phi_2 \sigma_2) \in T(F_r, N)$ and $\xi \Phi_2' \sigma_2' \in T(F_r, N)$. We already proved that is was equivalent to $\text{Message}(\xi \Phi_1 \sigma_1)$ and $\text{Message}(\xi \Phi_1' \sigma_1')$. Moreover, we also proved that $\Phi_2 \sigma_2 \downarrow = \Phi_1 \sigma_1 \downarrow$ and $\Phi_2' \sigma_2' \downarrow = \Phi_1' \sigma_1' \downarrow$. Hence, thanks to $\Phi_1 \sigma_1 \sim_{\Pi_n} \Phi_1' \sigma_1'$, we deduce that...
while we refer to the different elements of a constraint system. 

Rule on the rule

Case Rule

Axiom i.e. application of

Thus if Eq-left-left definition of 248

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C.2 General invariants

C.2.1 Structure invariant

Lemma 8.1. Let (M, M') be a pair of matrices of constraint systems such that M and M' have the same structure. Any internal (resp. external) application of a rule in Figure [7A] and/or Figure [7C] transforms the pair (M, M') on a pair (M1, M1') (resp. two pairs (M1, M1') and (M2, M2')) of matrices having the same structure.

Proof. Let C and C' be two constraint systems. Recall that the transformations rules Dest, Eq-left-left, Eq-left-right and Ded-st are applied internally whereas the rules Cons(X, f), Axiom(X, path) and Eq-right-right(X, ξ) are applied externally when X ∈ S2 and internally otherwise (i.e. X /∈ S2).

Let Rule(̃p) be a rule and let C1, C2 (resp. C1', C2') be the two constraint systems obtained by application of R on C (resp. C'). We assume that the application of Rule(̃p) is done simultaneously on C and C' (i.e. the possible fresh second order variables created are the same in both applications). We show that :

1. if C and C' have the same structure (resp. shape) then C1, C1' and C2, C2' have the same structure (resp. shape);

2. if Rule(̃p) is applied internally on C, then C, C1 and C2 have the same shape.

With these properties, the result directly holds. We prove these properties by case analysis on the rule Rule(̃p). To simplify the notation, we will use the notation S1(C), S2(C), Φ(C),... while we refer to the different elements of a constraint system C.

Case Rule(̃p) = Cons(X, f): We assume that the application of R(̃p) was done simultaneously, thus if ar(f) = u, we denote by X1, ..., Xn the fresh second order variables used in C1 and C1'.

Assume first that C and C' have the same structure. Thus we have that S2(C) = S2(C'). By definition of Cons(X, f), we have that S2(C) = S2(C2) and S2(C') = S2(C2') which means that S2(C2) = S2(C2'). Furthermore, if X ∈ S2(C) = S2(C') then S2(C1) = S2(C2) ∪ {X1, ..., Xn} = S2(C2') ∪ {X1, ..., Xn} = S2(C1'). Otherwise, we have that S2(C1) = S2(C) = S2(C2') = S2(C1').

We also have that Er(C) = Er(C'). But by definition of Cons(X, f), Er(C1) = Er(C) ∧ X ⊨ f(X1, ..., Xn) and Er(C1') = Er(C') ∧ X ⊨ f(X1, ..., Xn). Thus we have that Er(C1') = Er(C1).

Similarly, we have that Er(C2) = Er(C2').

Since the frame is not modified by the rule Cons(X, f), then we have {{ξ, i} | ξ, i ⊨ Φ(C)} = {{ξ, i} | ξ, i ⊨ Φ(C1)} implies that {{ξ, i} | ξ, i ⊨ Φ(C1')} = {{ξ, i} | ξ, i ⊨ Φ(C1')}. The same holds for C2 and C2'.

At last, we have D(C1) = D(C) ∪ {X1, i ⊨ x1, ..., Xn, i ⊨ xn} and D(C1') = D(C') ∪ {X1, i ⊨ x1', ..., Xn, i ⊨ x'n} where x1, ..., xn, x1', ..., x'n are fresh variables. Thus, {{X, i} | X, i ⊨ u ∈ D(C)} = {{X, i} | X, i ⊨ u ∈ D(C')} implies that {{X, i} | X, i ⊨ u ∈ D(C1)} = {{X, i} | X, i ⊨ u ∈ D(C1')} The case for C2 and C2' is trivial since D(C2) = D(C) and D(C2') = D(C').

We can conclude that if C and C' have the same structure then C1 and C1' (resp. C2 and C2') also have the same structure. Similarly, we show that if C and C' have the same shape then C1 and C1' (resp. C2 and C2') also have the same shape.
At last, if Cons$(X,f)$ is applied internally (i.e. $X \notin S_2(C)$), then we have that $S_2(C) = S_2(C_1) = S_2(C_2)$. Furthermore since $X_1,\ldots,X_n$ are fresh then $X_1,\ldots,X_n \notin S_2(C)$ and so $C,C_1$ and $C_2$ have the same shape.

Case Rule $\hat{\rho}$ = Axiom$(X,$path$)$: The rule Axiom$(X,$path$)$ does not modify $S_2$ and either it does not modify $D$, in the case of $C_2$ and $C_2'$, or it removes this constraint in the case of $C_1$, and $C_1'$. Thus, we easily have that if $C$ and $C'$ have the same shape, then $C_1$ and $C_1'$ (resp. $C_2$ and $C_2'$) also have the same shape. Furthermore, in the case of an internal application of Axiom$(X,$path$)$, we have that $X \notin S_2(C)$. If $(X,i \vdash u) \in D(C)$, then we have that $(X,i) \notin \{(Y,j) | (Y,j \vdash v) \in D(C) \land Y \in S_2(C)\}$. Thus we can also deduce that $C,C_1$ and $C_2$ have the same shape when the rule Axiom$(X,$path$)$ is applied internally.

At last, assume that $C$ and $C'$ have the same structure. Thus, we have that $\{(\xi,i) | \xi,i \triangleright u \in \Phi(C)\} = \{(\xi,i) | \xi,i \triangleright u \in \Phi(C')\}$. But if there exists $(\xi,i \triangleright u) \in \Phi(C)$ with path$(\xi) =$ path then it implies that there exists $u'$ such that $(\xi,i \triangleright u') \in \Phi(C')$. With this, we can deduce that Er$(C_1) = Er(C) \land X \nvdash \xi$ and Er$(C_1') = Er(C') \land X \nvdash \xi$. Since Er$(C) = Er(C')$, we can conclude that Er$(C_1) = Er(C_1')$ and so $C_1$ and $C_1'$ have the same structure. A similar reasoning allows us to conclude that $C_2$ and $C_2'$ have the same structure.

Case Rule $\hat{\rho}$ = Dest$(\xi,\ell \rightarrow r,i)$: The application of this rule on $C$ (resp $C'$) only adds a new non deducibility constraint on $C_2$ (resp $C_2'$). Thus, we trivially have that $C,C_2$ have the same shape; and $C,C'$ have the same structure (resp. shape) implies that $C_2,C_2'$ have the same structure (resp. shape).

We consider now the constraint systems $C_1$ and $C_1'$. Since Dest$(\xi,\ell \rightarrow r,i)$ is applied simultaneously on $C$ and $C'$, then there exist $X_2,\ldots,X_n$ fresh second order variables such that $D(C_1) = D(C) \cup \{X_2,i \vdash u_2; \ldots; X_n,i \vdash u_n\}$ and $D(C_1') = D(C') \cup \{X_2,i \vdash u_2'; \ldots; X_n,i \vdash u_n'\}$ where $f(u_1,\ldots,u_n) \rightarrow w$ and $f(u_1',\ldots,u_n') \rightarrow w'$ are fresh renaming of $\ell \rightarrow r$. Thus we can deduce that $\{(X,i) | X,i \vdash u \in D(C_1)\} = \{(X,i) | X,i \vdash u \in D(C')\}$ implies that $\{(X,i) | X,i \vdash u \in D(C_1)\} = \{(X,i) | X,i \vdash u \in D(C_1')\}$.

Furthermore, we also have that $\Phi(C_1) = \Phi(C) \cup \{f(\xi,X_2,\ldots,X_n),i \triangleright w\}$ and $\Phi(C_1') = \Phi(C') \cup \{f(\xi,X_2,\ldots,X_n),i \triangleright w'\}$. Thus, we deduce that $\{(\xi,i) | \xi,i \triangleright u \in \Phi(C)\} = \{(\xi,i) | \xi,i \triangleright u \in \Phi(C')\}$ implies that $\{(\xi,i) | \xi,i \triangleright u \in \Phi(C_1)\} = \{(\xi,i) | \xi,i \triangleright u \in \Phi(C_1')\}$.

Since $S_2(C) = S_2(C_1)$ and $S_2(C') = S_2(C_1')$ by definition of Dest, we can conclude that if $C,C'$ have the same structure then $C_1,C_1'$ also have the same structure.

At last, the facts that $S_2(C) = S_2(C_1)$ and $X_2,\ldots,X_n$ are fresh variables (i.e. $X_2,\ldots,X_n \notin S_2(C)$) also imply that $\{(X,i) | X,i \vdash u \in D(C) \land X \in S_2(C)\} = \{(X,i) | X,i \vdash u \in D(C_1) \land X \in S_2(C_1)\}$. Thus, we can conclude that $C,C_1$ have the same shape.

Case Rule $\hat{\rho}$ = Eq-left-left$(\xi_1,\xi_2)$: This rule only modifies $Eq(C)$ and $Eq(C')$ thus the result trivially holds.

Case Rule $\hat{\rho}$ = Eq-left-right$(\xi_1,X_2)$: The application of this rule modifies $Eq(C)$, $Eq(C')$ and adds an frame element on NoUse$(C)$ and NoUse$(C')$. Hence, it is easy to see that the rule does not modify the shape of the constrain systems. Assume now that $C$ and $C'$ have the same structure. It implies that $\{(\xi,i) | (\xi,i \triangleright u) \in \Phi(C)\} = \{(\xi,i) | (\xi,i \triangleright u) \in \Phi(C')\}$ and $\{(\xi,i) | (\xi,i \triangleright u) \in \Phi(C)\} = \{(\xi,i) | (\xi,i \triangleright u) \in \Phi(C')\}$. Hence, we have that there exists $u,u'$ such that $(\xi_1,i \triangleright u) \in \Phi(C)$ and $(\xi_1,i \triangleright u') \in \Phi(C')$. Thus, by definition of the rule, we have that NoUse$(C_1) = NoUse(C) \cup \{\xi_1,i \triangleright u\}$ and NoUse$(C_1') = NoUse(C') \cup \{\xi_1,i \triangleright u'\}$. It implies that $\{(\xi,i) | (\xi,i \triangleright u) \in \Phi(C_1)\} = \{(\xi,i) | (\xi,i \triangleright u) \in \Phi(C_1')\}$ and so $C_1,C_1'$ have the same structure.

Since only $Eq(C_2)$, $Eq(C_2')$ are modified from $Eq(C)$, $Eq(C')$, we easily deduce that $C_2,C_2'$ have the same structure.

Case Rule $\hat{\rho}$ = Eq-right-right$(X,\xi)$: By the application of this rule on $C$ and $C'$, we have
that \( \text{Er}(C_1) = \text{Er}(C) \land X \nvdash \xi \) and \( \text{Er}(C'_1) = \text{Er}(C') \land X \nvdash \xi \). Furthermore, the constraint \( X, i \vdash u \in D(C) \) (resp. \( X, i \vdash u' \in D(C') \)) is removed in \( D(C_1) \) (resp. \( D(C_2) \)). Thus, we can easily see that if \( C, C' \) have the same structure (resp. shape) then \( C_1, C'_1 \) and \( C_2, C'_2 \) also have the same structure (resp. shape).

In the case were \( \text{EQ}-\text{RIGHT}-\text{RIGHT}(X, \xi) \) is applied internally, we have that \( X \notin S_2(C) \) which means that \( (X, i) \notin \{(Y, j) \mid Y, j \vdash v \in D(C) \land Y \in S_2(C)\} \). Thus, we have that \( \{(Y, j) \mid Y, j \vdash v \in D(C) \land Y \in S_2(C)\} \). This allows us to conclude that \( C \) and \( C_1 \) have the same shape when \( \text{EQ}-\text{RIGHT}-\text{RIGHT}(X, \xi) \) is applied internally. The result trivially holds for \( C_2 \) and \( C'_2 \).

Case Rule \( \text{Rule}(p = \text{Ded-st}(\xi, f)) \): The application of this rule on \( C \) (resp \( C' \)) only adds a new non deducibility constraint on \( C_2 \) (resp. \( C'_2 \)). Thus, we trivially have that \( C, C' \) have the same shape; and \( C, C' \) have the same structure (resp. shape) implies that \( C_2, C'_2 \) have the same structure (resp. shape).

We consider now the constraint systems \( C_1 \) and \( C'_1 \). Since \( \text{Ded-st}(\xi, f) \) is applied simultaneously on \( C \) and \( C' \), then \( X_1, \ldots, X_n \) fresh second order variables such that \( D(C_1) = D(C) \cup \{X_1, i \vdash x_1; \ldots; X_n, i \vdash x_n\} \) and \( D(C'_1) = D(C') \cup \{X_1, i \vdash x_1; \ldots; X_n, i \vdash x_n\} \) where \( x_1, \ldots, x_n \) are fresh variables. Thus we can deduce that \( \{(X, i) \mid X, i \vdash u \in D(C)\} = \{(X, i) \mid X, i \vdash u \in D(C')\} \) implies that \( \{(X, i) \mid X, i \vdash u \in D(C_1)\} = \{(X, i) \mid X, i \vdash u \in D(C'_1)\} \).

Since \( S_2(C) = S_2(C_1) \) and \( S_2(C') = S_2(C'_1) \) by definition of \( \text{Ded-st} \), we can conclude that if \( C, C' \) have the same structure then \( C_1, C'_1 \) also have the same structure.

At last, the facts that \( S_2(C) = S_2(C_1) \) and \( X_2, \ldots, X_n \) fresh variables (i.e. \( X_2, \ldots, X_n \notin S_2(C) \)) also imply that \( \{(X, i) \mid X, i \vdash u \in D(C) \land X \in S_2(C)\} = \{(X, i) \mid X, i \vdash u \in D(C_1) \land X \in S_2(C_1)\} \). Thus, we can conclude that \( C, C_1 \) have the same shape.

\[\Box\]

**C.2.2 Well-formed invariant**

**Lemma C.8.** Let \( \xi, \zeta \in \Pi_n \) and let \( X \in X^2 \). Let \( \theta \) and \( \Theta \) be two substitutions such that \( \theta = \{X \mapsto \zeta\} \) and \( \Theta = \{X \mapsto \text{path}(\zeta)\} \). The following property holds:

\[\text{path}(\theta) = \text{path}(\zeta) \Theta\]

**Proof.** We prove this result by induction on \( |\text{path}(\xi)|\):

**Base case** \( |\text{path}(\xi)| = 1 \): In such a case, either \( \xi \in A X \) or \( \xi \in X^2 \). If \( \xi \in A X \), then \( \xi \theta = \xi \), \( \text{path}(\xi) = \xi \) and \( \Theta = \xi \). Thus, we have \( \text{path}(\xi) \theta = \text{path}(\xi) \Theta \). Otherwise \( \xi \in X^2 \) and \( \text{path}(\xi) = \xi \).

We distinguish two cases: \( \xi = X \) or \( \xi \neq X \). If \( \xi = X \) then \( \text{path}(X \theta) = \text{path}(\xi) = X \Theta = \text{path}(X) \Theta \).

Else, we have that \( \xi \theta = \xi \), \( \text{path}(\xi) = \xi \) and so \( \text{path}(\xi) \Theta = \text{path}(\xi) \). Thus we conclude \( \text{path}(\xi \theta) = \text{path}(\xi) \Theta \).

**Inductive step** \( |\text{path}(\xi)| > 1 \): Otherwise, there exist \( \xi_1, \ldots, \xi_n \in \Pi_n \) and \( f \in F \) such that \( \xi = f(\xi_1, \ldots, \xi_n) \) and \( \text{path}(\xi) = f \cdot \text{path}(\xi_1) \). Thus \( \xi \theta = f(\xi_1 \theta, \ldots, \xi_n \theta) \) and so \( \text{path}(\xi \theta) = f \cdot \text{path}(\xi \theta) \).

Using our induction hypothesis on \( \text{path}(\xi_1) \), we have that \( \text{path}(\xi_1 \theta) = \text{path}(\xi_1) \Theta \) which allows us to conclude that \( \text{path}(\xi \theta) = f \cdot \text{path}(\xi_1) \Theta = \text{path}(\xi) \Theta \).

\[\Box\]

**Lemma C.9.** Let \( C \) be a well formed constraint system and \( \Phi \) its associated frame. Let \( \xi \in \Pi_n \) such that \( C[\xi]_\Phi \in \mathcal{T}(F_c, F_d^*, AX \cup X^2) \). Let \( \theta, \Theta \) be two substitutions such that \( \theta = \{X \mapsto \zeta\}, \Theta = \{X \mapsto C[\zeta]_\Phi\} \) and \( C[\zeta]_\Phi \in \mathcal{T}(F_c, F_d^*, AX \cup X^2) \). The following property holds:

\[C[\xi]_\Phi = C[\zeta]_\Phi \Theta\]
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Proof. We prove this result by induction on $|C[\xi]|$:

**Base case** $|C[\xi]| = 1$: In such a case, either $C[\xi] \in (F_d^* \cdot AX)$ or $\xi \in X^2$. If $\xi \in X^2 \setminus \{X\}$, then $\theta = \xi$ and so $C[\xi] = C[\xi \theta]$. Thus the result holds. On the other hand, if $\xi = X$, then $\theta = \xi$ and $C[\xi] = X$ and so $C[\xi \theta] = X \theta$.

Assume now that $C[\xi] \in (F_d^* \cdot AX)$. In such a case, there exists $(\zeta, i \triangleright u) \in \Phi$ such that path$(\zeta) = \text{path}(\xi)$. But since path$(\xi) \in (F_d^* \cdot AX)$, we also have that path$(\xi) = \text{path}(\theta)$, which means that $C[\xi \theta] = C[\xi] \Phi$.

**Inductive step** $|C[\xi]| > 1$: By hypothesis, we know that $C[\xi] \in T_1(F_c, F_d^* \cdot AX \cup X^2)$, thus, we have that root$(C[\xi]) \in F_c$ and so root$(\xi) \in F_c$. Assume that $\xi = f(\xi_1, \ldots, \xi_n)$. By definition of a context, we have: $C[\xi] = f(C[\xi_1], \ldots, C[\xi_n])$. Thus we can apply our inductive hypothesis on $\xi_i$ for $i \in \{1 \ldots n\}$. This allows us to deduce that $C[\xi_i \theta] = C[\xi_i] \Phi$. Hence, we have that

$$C[\xi \theta] = C[f(\xi_1, \ldots, \xi_n) \theta] = C[f(C[\xi_1 \theta], \ldots, C[\xi_n \theta])] = C[f(C[\xi_1], \ldots, C[\xi_n]) \Phi] = C[f(\xi_1, \ldots, \xi_n) \phi \Phi] = C[\xi \Phi].$$

This allows us to conclude.

**Lemma 8.2.** Any rule in Figure 7.7 and Figure 7.8 transforms a normalised well-formed constraint system into a pair of constraint systems that are also well-formed after normalisation. For the rule DEST, we assume that its application is not useless.

Proof. Let $C = (S_1; S_2; \Phi; D; Eq; Er; ND; NoUse)$ be a normalised well-formed constraint system and let Rule$(\vec{\rho})$ be a rule. Let $C_1$ and $C_2$ be the two constraint systems obtained by application of Rule$(\vec{\rho})$ on $C$. In the case where the normalisation of $C_1$ and $C_2$ is $\perp$, the result trivially holds thus we will assume that $C_1 \perp \neq \perp$ and $C_2 \perp \neq \perp$. We show the result by base analysis on the rule Rule$(\vec{\rho})$.

Case Rule$(\vec{\rho}) = \text{Cons}(X, f)$: The rule Cons only adds the inequation root$(X) \neq f$ on $Er(C_2)$. Thus, we have that $C_2 \perp = C_2$ and $C_2$ trivially satisfies all the properties of Definition S2 except for the property 6. But $Er(C_2) = Er(C) \wedge \text{root}(X) \neq f$. Since $C$ is a well-formed constraint system, then $Er(C)$ satisfies Property 6. Furthermore, since $f \in F_c$, then root$(X) \neq f$ also satisfies Property 6. We can conclude that $C_2$ is a well-formed constraint system.

On the other hand, we have that $Er(C_1) = Er(C) \wedge X \not\preceq f(X_1, \ldots, X_n)$, $D(C_1) = D(C) \setminus \{X, i \vdash l\} \cup \{X_1, i \vdash l; \ldots; X_n, i \vdash l\}$, $Eq(C_1) = Eq(C) \wedge t \not\preceq f(x_1, \ldots, x_n)$ and $\Phi(C) = \Phi(C_1)$. Let $\sigma = 
mu(t \preceq f(x_1, \ldots, x_n))$ and $\theta = 
mu(X \not\preceq f(X_1, \ldots, X_n))$. By hypothesis, we know that $C$ is normalised which means that $X \not\in \text{dom}(\muu(\text{Er}(C)))$ and $\forall x^1(t) \cap \text{dom}(\muu(\text{Eq}(C))) = \emptyset$. Since $X_1, \ldots, X_n, x_1, \ldots, x_n$ are fresh variables, we can deduce $\muu(\text{Er}(C_1)) = \muu(\text{Er}(C)) \theta$ and $\muu(\text{Eq}(C_1)) = \muu(\text{Eq}(C)) \sigma$.

Furthermore, $C$ normalised also implies that $\Phi(C) \muu(\text{Er}(C)) \muu(\text{Eq}(C)) = \Phi(C)$ and also that $D(C) \muu(\text{Eq}(C)) = D(C)$. Thus, we can deduce that $\Phi(C_1 \perp) = \Phi(C) \theta \sigma$ and $D(C_1 \perp) = D(C_1) \sigma$. We now prove the different properties one by one.

Let $(\xi, j \triangleright u) \in \Phi(C_1 \perp)$. Since $\Phi(C_1 \perp) = \Phi(C) \theta \sigma$, we know that there exists $(\xi', j \triangleright u') \in \Phi(C)$ such that $\xi = \xi' \theta$ and $u = u' \sigma$.

1. this property is direct from Lemma C.8 and $C$ being a well-formed constraint system.

2. this property is direct from Lemma C.8 and $C$ being a well-formed constraint system.

3. We know that $\xi = \xi' \theta$ where $\theta = \muu(X \not\preceq f(X_1, \ldots, X_n))$. But $\text{param}^C_{\text{max}}(X) = i = \text{param}^C_{\text{max}}(X_j)$, we deduce that $\text{param}^C_{\text{max}}(\xi) = \text{param}^C_{\text{max}}(\xi')$. Since $C$ is well-formed, we have $\text{param}^C_{\text{max}}(\xi) \leq j$ and so $\text{param}^C_{\text{max}}(\xi') \leq j$. 

4. Let \( Y \in \text{vars}^2(\xi) \) and \( y \in \text{vars}^4(Y' \text{acc}^1(C_1 \downarrow)) \). If \( Y \subseteq \{ X_1, \ldots, X_n \} \) then there exists \( z \) such that \( y \in \text{vars}^4(z') \) and \( z \in \text{vars}^4(t) \). Thus \( z \in \text{vars}^4(X' \text{acc}^1(C)) \). But \( \xi = \varepsilon \theta \) thus it implies that \( X \in \text{vars}^2(\xi') \). Since \( C \) is well formed, we deduce that there exists \((c, k \triangleright w) \in \Phi(C)\) such that \( z \in \text{vars}^4(w) \) and \( k \leq j \). We already showed that \( \Phi(C_1 \downarrow) = \Phi(C) \theta \sigma \) hence \( y \in \text{vars}^4(w) \) with \((\varepsilon \theta, k \triangleright w) \in \Phi(C_1 \downarrow)\). The result holds.

If \( Y \notin \{ X_1, \ldots, X_n \} \), then \( Y \in \text{vars}^2(\xi') \) and \( Y \neq X \). Hence \( Y \in \text{vars}^2(D(C)) \). Since \( D(C_1 \downarrow) = D(C_1) \sigma \theta \Phi(C_1 \downarrow) = \Phi(C) \theta \sigma \) and \( C \) is well-formed, we deduce the result.

5. Let \( \lambda \) be a ground substitution such that for all \( Y \in \text{vars}^2(\xi) \), \((Y \lambda) \Phi(C_1 \downarrow) \lambda \triangleright v \lambda \) where \( (Y, k \triangleright v) \in D(C_1 \downarrow) \). Let \( \lambda' \) be a substitution such that \( \lambda' = \theta \sigma \lambda \). We show that for all \( Z \in \text{vars}^2(\xi') \), \((Z \lambda') \Phi(C) \lambda \triangleright w \lambda' \) where \((Z, k \triangleright w) \in D(C) \). Let \( Z \in \text{vars}^2(\xi') \).

- Either \( Z = X \): In this case, we have that \( Z \lambda' = X \theta \sigma \lambda = f(X_1, \ldots, X_n) \lambda \).
- Or \( Z \in \text{vars}^2(\xi') \): In such a case, we have that \( Z \theta \sigma = Z \) and so \( Z \lambda' = Z \lambda \).

Furthermore, we know that \( \Phi(C_1 \downarrow) = \Phi(C) \theta \sigma \) and so \( \Phi(C_1 \downarrow) = \Phi(C) \lambda' \).

Thus, we have that \((Z \lambda') \Phi(C) \lambda \triangleright (Z \lambda') \Phi(C_1 \downarrow) \lambda' \).

By hypothesis, we know that \( C \) is a well-formed constraint system and so we deduce that \((\xi' \lambda') \Phi(C) \lambda \triangleright u \lambda' \). But \( \xi' \lambda' = \xi, u \lambda' = u \lambda \) and \( \Phi(C) \lambda' = \Phi(C_1 \downarrow) \lambda \) since we deduce that \((\xi \lambda) \Phi(C_1 \downarrow) \lambda = u \lambda \).

6. Let \((\zeta_1, \zeta_2) \in \text{Er}(C_1 \downarrow)\). By the normalisation, we know that there exists \((\zeta_1, \zeta_2) \in \text{Er}(C_1)\) such that \(\xi = \zeta_2 \) and \(\zeta_2 \equiv \zeta\). Moreover, by the rule \text{Cons}, the sets of inequations of \(\text{Er}(C)\) and \(\text{Er}(C_1)\) are the same thus \((\zeta_1, \zeta_2) \in \text{Er}(C)\). Since \(C\) is well-formed, we deduce that \((\zeta_1, \zeta_2) \in \text{X}^2\) and there exists \(k \in \mathbb{N}\) and a term \(u\) such that \((\zeta_1, k \triangleright u) \in \Phi(C)\).

Since \(\Phi(C_1 \downarrow) = \Phi(C) \theta \sigma\), we deduce that \((\zeta_2, k \triangleright u \sigma) \in \Phi(C_1 \downarrow)\).

But \(\text{path}(\zeta_2)\) exists thanks to \(C\) being well-formed (Property \text{I}) thus \(\text{root}((\zeta_2)) \notin \mathcal{F}_c\). Since \(f \in \mathcal{F}_c\) and \(\zeta_1 = \zeta \theta\), we deduce that \(\zeta_1 \neq X\) otherwise the inequation would have disappeared by the normalisation rule (Nneg2). Thus \(\zeta_1 \in \text{X}^2\) and so the result holds.

Let \(\text{root}(\zeta) \neq g \in \text{Er}(C_1 \downarrow)\). Thanks to the normalisation, we know that \(\zeta \in \text{X}^2\) otherwise the inequation would have disappeared by the normalisation rules (Ntop2). Hence the result holds.

7. Let \( Y \in \text{vars}^2(C_1 \downarrow) \). If \( Y \subseteq \{ X_1, \ldots, X_n \} \), then since \( \theta = \{ X \mapsto f(X_1, \ldots, X_n) \} \) and \( Y \) is fresh, we have that \( \text{Y} \text{mgu}(\text{Er}(C_1 \downarrow)) = Y \) and so we deduce that \( \text{C} [ \text{Y} \text{mgu}(\text{Er}(C_1 \downarrow))] \Phi(C_1 \downarrow) = Y \in \mathcal{T}(\mathcal{F}_c, \mathcal{F}_d : \text{AX} \cup \text{X}^2) \). Otherwise, we have that \( Y \in \text{vars}^2(C) \). Note that \( C \) is well-formed, we deduce that \( \text{C} [ \text{Y} \text{mgu}(\text{Er}(C))] \Phi(C) \in \mathcal{T}(\mathcal{F}_c, \mathcal{F}_d : \text{AX} \cup \text{X}^2) \). But the path of any recipe in \( \Phi(C) \) is closed which means that any context with \( \text{C} [ \text{Y} \text{mgu}(\text{Er}(C))] \Phi(C) \) are the same. More specifically, we have \( \text{C} [ \text{Y} \text{mgu}(\text{Er}(C))] \Phi(C) = \text{C} [ \text{Y} \text{mgu}(\text{Er}(C))] \Phi(C_1 \downarrow) \). Note that \( \text{mgu}(\text{Er}(C_1 \downarrow)) = \text{mgu}(\text{Er}(C)) \theta \). Thus by Lemma \text{C.9} we have that \( \text{C} [ \text{Y} \text{mgu}(\text{Er}(C_1 \downarrow))] \Phi(C_1 \downarrow) = \text{C} [ \text{Y} \text{mgu}(\text{Er}(C))] \Phi(C) \in \mathcal{T}(\mathcal{F}_c, \mathcal{F}_d : \text{AX} \cup \text{X}^2) \).
Let \( \zeta \in st(Y \text{mgu}(Er(C_1))) \) such that \( \text{path}(\zeta) \in F^2 \cdot AX \). Since \( \theta = \{ X \mapsto f(X_1, \ldots, X_n) \} \) with \( f \in F_2 \) and \( \text{mgu}(Er(C_1)) = \text{mgu}(Er(C)) \theta \), then there exists \( \zeta' \in st(Y \text{mgu}(Er(C))) \) such that \( \zeta = \zeta' \theta \). Since \( C \) is well-formed, then there exists \( k \) and \( u \) such that \( (\zeta', k \triangleright u) \in \Phi(C) \). But \( \Phi(C_1) = \Phi(C) \theta \sigma \). Hence \( (\zeta, k \triangleright u \sigma) \in \Phi(C_1) \). Hence the result holds.

8. Assume that \((\xi, j \triangleright u) \in \text{NoUse}(C_1)\). Since \( \text{NoUse}(C_1) = \text{NoUse}(C) \theta \sigma \), we have that \((\xi', j \triangleright u') \in \text{NoUse}(C)\). Since \( C \) is a well-formed constraint system, we deduce that there exists \( Y \in \text{vars}^2(C) \) such that \( C[Y \text{mgu}(Er(C))_{\theta \sigma}] \cap \text{acc}^1(C) = u' \) and \( \text{param}^{\text{max}}_\ell(Y \text{mgu}(Er(C))) < j \). We have seen that \( C[Y \text{mgu}(Er(C_1))]_{\Phi(C_1)} = C[Y \text{mgu}(Er(C))]_{\Phi(C) \theta \sigma} \) when proving the previous item. Furthermore, we know that \( D(C_1) = D(C_1) \sigma \) and \( D(C_1) = D(C) \setminus \{ X, i \vdash t \} \cup \{ X_1, i \vdash x_1; \ldots; X_n, i \vdash x_n \} \). Thus, we deduce that \( \text{acc}^1(C) \sigma = \theta \text{acc}^1(C_1) \). This allows us to conclude that \( C[Y \text{mgu}(Er(C_1))]_{\Phi(C_1)} \text{acc}^1(C_1) = C[Y \text{mgu}(Er(C))]_{\Phi(C) \theta \sigma} \text{acc}^1(C_1) = u' \sigma = u \).

At last, we already have that \( Y \text{mgu}(Er(C_1)) = Y \text{mgu}(Er(C)) \theta \). Thus, since \( \text{param}^{\text{max}}_\ell(X) = \text{param}^{\text{max}}_\ell(f(X_1, \ldots, X_n)) = i \), then \( \text{param}^{\text{max}}_\ell(Y \text{mgu}(Er(C))) < j \) implies that \( \text{param}^{\text{max}}_\ell(Y \text{mgu}(Er(C_1))) < j \).

9. Similar to Property 7

10. Let \( (Z, k \triangleright u) \in D(C_1) \). Assume that \( Z \notin S_2(C_1) \) and let \( x \in \text{vars}^1(u) \). If \( X \in S_2(C) \) then it implies that there exists \( (Z, k \triangleright u') \in D(C) \) such that \( u = u' \sigma \). There exists a variable \( z \) such that \( x \in \text{vars}^1(z \sigma) \) and \( z \in \text{vars}^1(u') \). Since \( C \) is well-formed, we deduce that there exists \( (Y, p \triangleright u') \in D(C) \) such that \( z \in \text{vars}^1(w') \) and \( p < k \). Thus \( x \in \text{vars}^1(u') \). If \( Y \neq X \) then we deduce that \( (Y, p \triangleright w' \sigma) \in D(C_1) \) and so the result holds. If \( Y = X \), then \( t = w' \) and \( p = i \). Since \( \sigma = \text{mgu}(t \vdash f(x_1, \ldots, x_n)) \), we deduce that there exists \( \ell \in \{ 1, \ldots, n \} \) such that \( x \in \text{vars}^1(x_{\ell} \sigma) \). (But \( X_{\ell}, i \vdash x_{\ell} \) \( \in D(C_1) \) with \( k < i \) and so the result holds.

Assume now that \( X \notin S_2(C) \). If \( Z \notin \{ X_1, \ldots, X_n \} \) then the proof is similar to the case where \( X \in S_2(C) \) and so the result holds. If \( X \in \{ X_1, \ldots, X_n \} \) then there exists \( \ell \in \{ 1, \ldots, n \} \) such that \( x \in \text{vars}^1(x_{\ell} \sigma) \). Since \( \sigma = \text{mgu}(t \vdash f(x_1, \ldots, x_n)) \), we deduce that \( x \in \text{vars}^1(x_{\ell} \sigma) \). Hence, there exists \( z \) such that \( x \in \text{vars}^1(z \sigma) \) and \( z \in \text{vars}^1(t) \). Once again, thanks to \( C \) being-well formed, there exists \( (Y, p \triangleright w') \in D(C) \) such that \( p < k \) and \( z \in \text{vars}^1(w') \) and so \( x \in \text{vars}^1(w' \sigma) \). But \( (Y, p \triangleright w' \sigma) \in D(C_1) \) thus the result holds.

Case Rule \((\tilde{p}) = \text{Axiom}(X, \text{path})\): By definition of Axiom, we have \( X, i \vdash u \in D(C) \) and \( \xi, j \triangleright v \) in \( \Phi(C) \) such that \( i \geq j \), \( \text{path}(\xi) = \text{path} \) and \( (\xi, j \triangleright v) \notin \text{NoUse}(C) \). The rule Axiom only adds the inequation \( X \neq \xi \) on \( Er(C_2) \). Thus, we have that \( C_2 = \xi = \xi \) and \( C_2 \) trivially satisfies all the properties of Definition 5.24 except for the property 6. But \( Er(C_2) = Er(C) \land X \neq \xi \). Since \( C \) is a well-formed constraint system, then \( Er(C) \) satisfies Property 6. Furthermore, \( X \neq \xi \) also satisfies Property 6 by definition. We can conclude that \( C_2 \) is a well-formed constraint system.

On the other hand, we have that \( Er(C_1) = Er(C) \land X \neq \xi \), \( D(C_1) = D(C) \setminus \{ X, i \vdash u \} \), \( Eq(C_1) = Eq(C) \land u \neq v \) and \( \Phi(C) = \Phi(C_1) \). Let \( \sigma = \text{mgu}(u \neq v) \) and \( \theta = \text{mgu}(X \neq \xi) \). By hypothesis, \( C \) is a normalized constraint system which means that \( \{ X \cup \text{vars}^2(\xi) \rangle \cap \text{dom}(\text{mgu}(Er(C))) = \emptyset \) and \( \text{vars}^1(u, v) \cap \text{dom}(\text{mgu}(Eq(C))) = \emptyset \). Thus, we can deduce \( \text{mgu}(Er(C_1)) = \text{mgu}(Er(C)) \theta \) and \( \text{mgu}(Eq(C_1)) = \text{mgu}(Eq(C)) \sigma \). Since \( C \) is normalized, we have that \( \Phi(C)\text{mgu}(Er(C))\text{mgu}(Eq(C)) = \Phi(C) \) and \( D(C)\text{mgu}(Eq(C)) = D(C) \). Thus, we can deduce that \( \Phi(C_1) = \Phi(C) \theta \sigma \) and \( D(C_1) = D(C)\sigma \setminus \{ X, i \vdash u \sigma \} \). We now prove the different properties one by one.
Let \( (\zeta, k \triangleright w) \in \Phi(C) \). Since \( \Phi(C) = \Phi(C) \theta \sigma \), we know that there exists \( (\zeta', k \triangleright w') \in \Phi(C) \) such that \( \zeta = \zeta' \theta \) and \( w = w' \sigma \).

1. this property is direct from Lemma \( C.8 \) and \( C \) being a well-formed constraint system.

2. this property is direct from Lemma \( C.8 \) and \( C \) being a well-formed constraint system.

3. We know that \( \zeta = \zeta' \theta \) where \( \theta = \{ X \mapsto \xi \} \). But \( C \) is a well-formed constraint system hence we deduce that \( \text{param}^C_{\text{max}}(\zeta) \leq j \). Since \( \text{param}^C_{\text{max}}(\lambda) = i \geq j \geq \text{param}^C_{\text{max}}(\zeta) \), we deduce that \( \text{param}^C_{\text{max}}(\zeta) \leq \text{param}^C_{\text{max}}(\zeta') \). Hence the result holds.

4. Let \( Y \in \text{vars}^2(\zeta) \) and \( y \in \text{vars}^1(Y_{\text{acc}}(C)) \). \( Y \in \text{vars}^2(D(C)) \) which means that \( Y \in \text{vars}^2(D(C)) \). Since \( D(C) = D(C) \sigma, \Phi(C) = \Phi(C) \theta \sigma \) and \( C \) is well-formed, we deduce the result.

5. Let \( \lambda \) be a substitution such that for all \( Y \in \text{vars}^2(\zeta), (Y\lambda)\Phi(C)\lambda = r\lambda \) where \( (Y, \ell \triangleright r) \in D(C) \). Let \( \lambda' \) the substitution such that \( \lambda' = \theta \sigma \lambda \). We show that for all \( Y \in \text{vars}^2(\zeta), (Y\lambda')\Phi(C)\lambda' = r\lambda' \) where \( (Y, \ell \triangleright r) \in D(C) \). Let \( Y \in \text{vars}^2(\zeta') \). Since \( \zeta = \zeta' \theta \), we have to distinguish two cases:

   - Either \( Y = X \): In this case, we have that \( \xi \in st(\zeta) \). Thus, by hypothesis, we have that for all \( Z \in \text{vars}^2(\zeta), (Z\lambda)\Phi(C)\lambda = t\lambda \), where \( (Z, m \triangleright t) \in D(C) \). But \( (Z, m \triangleright t) \in D(C) \) implies that there exist \( t' \) such that \( (Z, m \triangleright t') \in D(C) \) and \( t = t' \sigma \). Since \( \Phi(C) = \Phi(C) \theta \sigma \), we can deduce that \( (Z\lambda)\Phi(C)\lambda = t' \sigma \lambda = t' \lambda \). At last, \( \theta = \{ X \mapsto \xi \} \) implies that \( Z\lambda = Z \lambda' = Z \lambda \). Thus we have that \( (Z\lambda')\Phi(C)\lambda' = t\lambda' \). Since \( C \) is a well-formed constraint system, we can deduce that \( (\lambda\lambda')\Phi(C)\lambda' = w\lambda' \). Since \( X\theta = \xi \) and \( \lambda' = \theta \sigma \lambda \), we have that \( \lambda' = X\lambda' \). With \( w\sigma = \sigma \), we can conclude that \( (X\lambda')\Phi(C)\lambda' = w\lambda' \).

   - Or \( Y \in \text{vars}^2(\zeta) \): In this case, we have that \( Y\theta \sigma = Y \) and so \( Y\lambda' = Y \lambda \). Furthermore, we know that \( \Phi(C) = \Phi(C) \theta \sigma \) and so \( \Phi(C)\lambda = \Phi(C)\lambda' \). Thus, we have that \( (Y\lambda')\Phi(C)\lambda' = (Y\lambda)\Phi(C)\lambda \). By hypothesis, there exists \( Y, \ell \triangleright r \in D(C) \) such that \( (Y\lambda)\Phi(C)\lambda = r \lambda \). However, we have that \( D(C) = D(C) \sigma \{ X, \ell \triangleright w \sigma \} \) and \( Y \neq X \). Thus there exists \( Y, \ell \triangleright r' \in D(C) \) such that \( r = r' \sigma \) and so \( r = r' \lambda' \). We can conclude that \( (Y\lambda')\Phi(C)\lambda' = r' \lambda' \) with \( Y, \ell \triangleright r' \in D(C) \).

   By hypothesis, we know that \( C \) is well-formed and so \( (\zeta'\lambda')(\Phi(C)\lambda') = w\lambda' \). We have that \( \zeta' \lambda' = \zeta \lambda, w \lambda' = w \lambda \) and \( \Phi(C)\lambda' = \Phi(C)\lambda \). Thus we conclude that \( (\zeta\lambda)(\Phi(C)\lambda) = w \lambda \).

6. Let \( (\zeta_1, k \triangleright w) \in \text{Er}(C) \). By the normalisation, we know that there exists \( (\zeta_1', k \triangleright w) \in \text{Er}(C) \) such that \( \zeta_1' = \zeta_1 \) and \( \zeta_1' \theta = \zeta_2 \). Moreover, by the rule AXIOM, the sets of inequations of \( \text{Er}(C) \) and \( \text{Er}(C) \) are the same thus \( (\zeta_1' \neq \zeta_2) \in \text{Er}(C) \). Since \( C \) is well-formed, we deduce that \( \zeta_1' \in X^2 \) and there exists \( k \in \mathbb{N} \) and a term \( u \) such that \( (\zeta_2, k \triangleright u) \in \Phi(C) \). Since \( (\zeta_1 \lambda = \zeta_2 \lambda) \Phi(C) \sigma \), we deduce that \( (\zeta_2, k \triangleright w \sigma) \in \Phi(C) \). But thanks to \( C \) being well-formed (Property 1), path(\( \zeta_2 \)) and path(\( \xi \)) exists, are closed and if path(\( \zeta_2 \)) = path(\( \xi' \)) then \( \zeta_2 = \zeta' \). But \( \xi = \xi' \), \( \zeta_2 = \zeta_2 \theta \), path(\( \zeta_2 \)) = path(\( \zeta_2 \)) and path(\( \xi \)) = path(\( \xi' \)). Thus we deduce that \( \zeta_2 = \xi \) implies that \( \zeta_1 \neq \xi \) otherwise \( C \downarrow = \bot \) by the normalisation rule (Nt2).

   Moreover, by definition of the path of recipe, path(\( \xi \)) \( \neq \) path(\( \zeta_2 \)) implies \( \xi \neq \zeta_2 \). Thus we deduce that \( \zeta_1 \neq \xi \) otherwise the inequation would have disappeared by the normalisation rule (Nt2). Thus \( \zeta_1 \in X^2 \) and so the result holds.
7. Let $Y \in \text{vars}^2(C_\downarrow)$. We have \( \mgu(\text{Er}(C_\downarrow)) = \mgu(\text{Er}(C))\theta \) with \( \theta = \{X \mapsto \xi\} \). Furthermore, we know that \( \text{path}(\xi) \in F_{\text{d}}. A\chi \) since \( C \) is well-formed. Let \( \Theta = \{X \mapsto \text{path}(\xi)\} \). By Lemma \([C9]\) we have that \( C[Y \mgu(\text{Er}(C_\downarrow))]_{\phi(\Theta)} = C[Y \mgu(\text{Er}(C))]_{\phi(\Theta)} \). However, we have that \( C[Y \mgu(\text{Er}(C))]_{\phi(\Theta)} = C[Y \mgu(\text{Er}(C))]_{\phi(\Theta)} \) and since \( C \) is well-formed, we also have that \( C[Y \mgu(\text{Er}(C))]_{\phi(\Theta)} \in \mathcal{T}(F_{\text{d}}, F_{\text{d}}. A\chi \cup A^2) \). Since \( \text{path}(\xi) \in F_{\text{d}}. A\chi \), we conclude that \( C[Y \mgu(\text{Er}(C_\downarrow))]_{\phi(\Theta)} \in \mathcal{T}(F_{\text{d}}, F_{\text{d}}. A\chi \cup A^2) \).

Let \( \zeta \in \text{st}(Y \mgu(\text{Er}(C_\downarrow))) \) such that \( \text{path}(\zeta) \in F_{\text{d}}. A\chi \). Since \( \theta = \{X \mapsto \xi\} \) and \( \mgu(\text{Er}(C)) = \mgu(\text{Er}(C))\theta \), then (a) either \( \zeta \in \text{st}(\xi) \) with \( (\xi, i \mapsto v) \in \Phi(C) \) and \( (\xi, i \mapsto v) \in \Phi(C_\downarrow) \) or (b) there exists \( \zeta' \in \text{st}(Y \mgu(\text{Er}(C))) \) such that \( \zeta = \zeta'\theta \). In both cases, since \( C \) is well-formed (Property \([7]\)), then there exists \( k \) and \( u \) such that \( (\zeta', k \mapsto u) \in \Phi(C) \).

But \( \Phi(C_\downarrow) = \Phi(C)\theta \). Hence \( (\zeta, k \mapsto u) \in \Phi(C_\downarrow) \). Hence the result holds.

8. Assume that \( (\zeta, k \mapsto u) \in \text{NoUse}(C_\downarrow) \). Since \( \text{NoUse}(C_\downarrow) = \text{NoUse}(C)\theta \sigma \), we have that \( (\zeta', k \mapsto u') \in \text{NoUse}(C) \). Since \( C \) is well-formed, we deduce that there exists \( Y \in \text{vars}^2(C) \) such that \( C[Y \mgu(\text{Er}(C))]_{\phi(\Theta)} \acc^1(C) = u' \) and \( \text{param}_{\text{max}}^C(Y \mgu(\text{Er}(C))) \leq k \). We have seen that \( C[Y \mgu(\text{Er}(C))]_{\phi(\Theta)} = C[Y \mgu(\text{Er}(C))]_{\phi(\Theta)} \) when proving the previous point. We have that \( \text{path}(\xi) \acc^1(C)\sigma = u' = u = \sigma = \text{Xacc}^1(C)\sigma \). Thus, we deduce that \( \Theta\acc^1(C)\sigma = \acc^1(C)\sigma \). Furthermore, we know that \( D(C_\downarrow) = D(C)\sigma \{X, i \mapsto w'\} \) and \( \Phi(C_\downarrow) = \Phi(C)\theta \sigma \) which means that \( \acc^1(C)\sigma = \Theta\acc^1(C) \). This allows us to conclude that \( u = u'\sigma = C[Y \mgu(\text{Er}(C))]_{\phi(\Theta)} \acc^1(C)\sigma = C[Y \mgu(\text{Er}(C))]_{\phi(\Theta)} \acc^1(C) \).

Lastly, since \( C \) is a well-formed constraint system, we know that for all \( Z \in \text{vars}^2(C) \), \( \text{param}_{\text{max}}^C(Z) \leq j \leq i = \text{param}_{\text{max}}^C(X) \). Since \( Y \mgu(\text{Er}(C)) = Y \mgu(\text{Er}(C))\theta \), then \( \text{param}_{\text{max}}^C(Y \mgu(\text{Er}(C))) \leq k \) implies that \( \text{param}_{\text{max}}^C(Y \mgu(\text{Er}(C)) \leq k \).

9. Similar to Property \([7]\).

10. Let \( (Z, k \mapsto t) \in D(C_\downarrow) \). Assume that \( Z \not\in S_2(C_1) \) and let \( x \in \text{vars}^1(u) \). It implies that there exists \( (Z, k \mapsto t') \in D(C) \) such that \( t = t'\sigma \). Hence, there exists a variable \( z \) such that \( x \in \text{vars}^1(z\sigma) \) and \( z \in \text{vars}^1(t') \). Since \( C \) is well-formed, we deduce that there exists \( (Y, p \mapsto w') \in D(C) \) such that \( z \in \text{vars}^1(w') \) and \( p < k \). Thus \( x \in \text{vars}^1(w'\sigma) \). If \( Y \neq X \) then we deduce that \( (Y, p \mapsto w' \sigma) \in D(C_\downarrow) \) and so the result holds. If \( Y = X \), then \( u = w' \) and \( p = i \). Since \( \sigma = \mgu(u \sigma) \), we deduce that \( x \in \text{vars}^1(w\sigma) \sigma \). But \( (\xi, j \mapsto v) \in \Phi(C_\downarrow) \) with \( j \leq i \). Thus by the origination property of a constraint system, there exists \( (Y_2, p_2 \mapsto w_2) \in D(C_\downarrow) \) such that \( p_2 < j \) and \( x \in \text{vars}^1(w_2) \). Since \( p_2 < j \leq i < k \) then the result holds.

Case Rule \( \text{Rule}(\xi, \ell \mapsto r, i) \): By definition of \( \text{Dest} \), we have that \( (\xi, j \mapsto v) \in \Phi(C) \) such that \( j < i \), \( (\xi, j \mapsto v) \not\in \text{NoUse}(C) \), \( X_1, \ldots, X_n \) fresh variables and \( f(u_1, \ldots, u_n) \to w \) a fresh renaming of \( \ell \mapsto r \). The rule \( \text{Dest} \) adds only a non-deductibility constraint in \( C_2 \). Hence, we have that \( C_2 = C_3 = C_3 \) and since \( C \) is well-formed, we easily deduce that \( C_2 \) is also well-formed.

On the other hand, we have that \( D(C) = D(C)\setminus\{X_2, i \mapsto w_2; \ldots; X_n, i \mapsto u_n\} \), \( \text{Eq}(C_1) = \text{Eq}(C) \setminus u_1 \leadsto v \) and \( \Phi(C_1) = \Phi(C) \cup \{f(\xi, X_2, \ldots, X_n, i \mapsto w\sigma)\} \). By hypothesis, we know that \( C \) is normalised which means that \( \text{vars}^1(w) \cap \text{dom}(\text{mgu}(\text{Eq}(C))) = \emptyset \). Let \( \sigma = \text{mgu}(u_1 \leadsto v) \). Since \( f(u_1, \ldots, u_n) \to w \) is a fresh renaming of \( \ell \mapsto r \) and for all \( k \in \{1, \ldots, k\} \), \( \text{vars}^1(u_k) \subseteq \text{vars}^1(u_1) \), we can deduce \( \text{mgu}(\text{Eq}(C_1)) = \text{mgu}(\text{Eq}(C))\sigma \). Furthermore, \( C \) normalised also implies that \( \Phi(C)\text{mgu}(\text{Eq}(C)) = \Phi(C) \) and \( D(C)\text{mgu}(\text{Eq}(C)) = D(C) \). Thus, we can deduce that \( \Phi(C_\downarrow) = \Phi(C)\sigma \cup \{f(\xi, X_2, \ldots, X_n) \mapsto w\sigma\} \) and \( D(C_\downarrow) = D(C)\sigma \cup \{X_2, i \mapsto w_2\sigma; \ldots; X_n, i \mapsto u_n\sigma\} \). We now prove the different properties one by one.
APPENDIX C. DECISION PROCEDURE OF TRACE EQUIVALENCE

Let \((\zeta, k \triangleright u) \in \Phi(C_{\downarrow})\). Since \(\Phi(C_{\downarrow}) = \Phi(C) \sigma \cup \{f(\xi, X_2, \ldots, X_n) \triangleright u\sigma\}\), we know that either there exists \(u'\) such that \((\zeta, k \triangleright u') \in \Phi(C)\) with \(u'\sigma = u\), or \((\zeta, k \triangleright u) = (f(\xi, X_2, \ldots, X_n), i \triangleright u\sigma)\).

1. If \((\zeta, k \triangleright u) = (f(\xi, X_2, \ldots, X_n), i \triangleright u\sigma)\), we have that \(\text{path}(\zeta) = f \cdot \text{path}(\xi)\). Since \(C\) is well-formed, we have that \(\text{path}(\xi)\) exists and is closed. Thus \(\text{path}(\zeta)\) exists and is closed.

Furthermore, since the rule \(\text{DEST}\) is never applied if its application is useless, then we deduce that the frame \(\Phi(C)\) does not contain \(f(\xi, \zeta_2, \ldots, \zeta_m), j \triangleright u'\) and \(j \leq i\) and \(\text{root}(f) = f\). Thus, with \(C\) being well formed hence satisfies Property II we can conclude that for all distinct frame elements \((\xi_1, i_1 \triangleright u_1)\) and \((\zeta_2, i_2 \triangleright u_2)\) in \(\Phi(C_{\downarrow})\), \(\text{path}(\xi_1) \neq \text{path}(\zeta_2)\).

2. If \((\zeta, k \triangleright u) = (f(\xi, X_2, \ldots, X_n), i \triangleright u\sigma)\), since we know that \((\xi, j \triangleright u\sigma) \in \Phi(C_{\downarrow})\), the result trivially holds. Otherwise, we have that \((\zeta, k \triangleright u') \in \Phi(C)\) and since \(C\) is well-formed, we easily conclude.

3. If \((\zeta, k \triangleright u) = f(\xi, X_2, \ldots, X_n)\) then \(\text{param}_{\max}^C(\zeta) = \max(\text{param}_{\max}^C(\xi), i)\). But \(\text{param}_{\max}^C(\xi) = \text{param}_{\max}^C(\xi)\) thus since \(C\) is well-formed, we deduce that \(\text{param}_{\max}^C(\xi) \leq j\). Since \(j \leq i\) by definition, we conclude that \(\text{param}_{\max}^C(\zeta) = i\) thus the result holds.

4. Let \(Y \in \text{vars}^2(\zeta)\) and \(y \in \text{vars}^1(\text{Yacc}^1(C_{\downarrow}))\). If \(Y \in \{X_2, \ldots, X_n\}\) then \(y \in \text{vars}^1(u\sigma)\).

Indeed, our rewrite rule satisfies \(\text{vars}^1(u_2, \ldots, u_n) \subseteq \text{vars}^1(u_1)\) thus with \(\sigma = \text{mgu}(u_1, v)\) and \(y \in \text{vars}^1(u_2, \ldots, u_n\sigma)\) the result holds.

If \(Y \notin \{X_2, \ldots, X_n\}\) then \(Y \in \text{vars}^2(\text{D}(C))\) and so there exists \(z\) such that \(y \in \text{vars}^1(z\sigma)\) and \(z' \in \text{vars}^1(\text{Yacc}^1(C))\). Since \(C\) is well-formed, we deduce that there exists \((\beta, m \triangleright t) \in \Phi(C)\) such that \(m \leq k\) and \(z \in \text{vars}^1(t)\). But \((\beta, m \triangleright t) \in \Phi(C_{\downarrow})\) hence \(y \in \text{vars}^1(t\sigma)\). Thus the result holds.

5. Let \(\lambda\) be a substitution such that for all \(Y \in \text{vars}^2(\zeta)\), we have that \((Y\lambda)\Phi(C_{\downarrow})\lambda_{\downarrow} = r\lambda\) where \((Y, k \triangleright r) \in \text{D}(C_{\downarrow})\). Let \(X' = \lambda X\). Actually, \(Y \in \text{vars}^2(\zeta)\) and \((\zeta, k \triangleright u') \in \Phi(C)\) implies that there exists \(r'\) such that \((Y, k \triangleright r') \in \text{D}(C)\) and \(r'\sigma = r\). Since \(Y\sigma \lambda = Y\lambda\) and \(\Phi(C_{\downarrow}) = \Phi(C)\sigma \cup \{f(\xi, X_2, \ldots, X_n) \triangleright u\sigma\}\), we can deduce that \((Y\lambda')(\Phi(C)\lambda'_{\downarrow} = r'\lambda'\). Since \(C\) is well-formed, we have that \((\zeta)(\Phi(C)\lambda)_{\downarrow} = u\lambda'\). Since \(\zeta\sigma \lambda = \lambda\) and \(u\lambda' = u\lambda\), we can deduce that \((\lambda)\Phi(C_{\downarrow})\lambda_{\downarrow} = \lambda\).

6. \(\text{Er}(C_{\downarrow}) = \text{Er}(C)\) thus the result trivially holds.

7. Let \(X \in \text{vars}^2(C_{\downarrow})\). We have that \(\text{Er}(C_{\downarrow}) = \text{Er}(C)\). Let \(\theta = \text{mgu}(\text{Er}(C))\). We show that \(C[X\theta]_{\Phi(C_{\downarrow})} \in \mathcal{T}(F_c, F_d', \mathcal{AX} \cup \mathcal{X}^2)\). If \(X \in \{X_2, \ldots, X_n\}\), then the result trivially holds.

Otherwise, we have that \(X \in \text{vars}^2(C)\). Since \(C\) is a well-formed constraint system, we know that \(C[X\theta]_{\Phi(C)} \in \mathcal{T}(F_c, F_d', \mathcal{AX} \cup \mathcal{X}^2)\). Thus for all \(\zeta \in st(C[X\theta]_{\Phi(C)})\), \(\text{root}(\zeta) \notin \mathcal{F}_d\). Since \(\Phi(C_{\downarrow}) = \Phi(C)\sigma \cup \{f(\xi, X_2, \ldots, X_n) \triangleright u\sigma\}\) and \(f \in \mathcal{F}_d\), we conclude that \(C[X\theta]_{\Phi(C_{\downarrow})} \in \mathcal{T}(F_c, F_d', \mathcal{AX} \cup \mathcal{X}^2)\).

Let \(\beta \in \text{st}(X\text{mgu}(\text{Er}(C_{\downarrow})))\) and \(\text{path}(\beta) \in F_d' \cdot \mathcal{AX}\). Since \(\text{mgu}(\text{Er}(C_{\downarrow})) = \text{mgu}(\text{Er}(C))\), then \(\beta \in \text{st}(X\text{mgu}(\text{Er}(C)))\). Thanks to \(C\) being well-formed, we deduce that there exists \(k, u\) such that \((\beta, k \triangleright u) \in \Phi(C)\) and so \((\beta, k \triangleright u\sigma) \in \Phi(C_{\downarrow})\). Hence the result holds.

8. Assume that \((\zeta, k \triangleright u) \in \text{NoUse}(C_{\downarrow})\). Since \(\text{NoUse}(C) = \text{NoUse}(C)\sigma\), we know that there exists \(u'\) such that \((\xi, k \triangleright u') \in \Phi(C)\) and \(u'\sigma = u\). Since \(C\) is a well-formed constraint system, we know that there exists \(X \in \text{vars}^2(C)\) such that \(C[X\theta]_{\Phi(C)} \text{acc}^1(C) = u'\) and \(\text{param}_{\max}^C(X\text{mgu}(\text{Er}(C))) < k\). Since \(\text{mgu}(\text{Er}(C)) = \text{mgu}(\text{Er}(C_{\downarrow}))\) and \(D(C)\sigma \subseteq D(C_{\downarrow})\), we deduce that \(\text{param}_{\max}^C(X\text{mgu}(\text{Er}(C_{\downarrow}))) = \text{param}_{\max}^C(X\text{mgu}(\text{Er}(C))) < k\).

In the previous point, we have shown that \(C[X\theta]_{\Phi(C_{\downarrow})} = C[X\theta]_{\Phi(C)}\). Furthermore, we have \(\text{acc}^1(C_{\downarrow}) = \text{acc}^1(C)\sigma \cup \{f \cdot \text{path}(\xi) \rightarrow w\sigma; X_2 \rightarrow u_2\sigma; \ldots; X_n \rightarrow u_n\sigma\}\). Actually, \(C[X\theta]_{\Phi(C_{\downarrow})} = C[X\theta]_{\Phi(C)}\) implies that \(f \cdot \text{path}(\xi) \notin \text{st}(C[X\theta]_{\Phi(C)})\). Hence, we have that \(C[X\theta]_{\Phi(C_{\downarrow})}\text{acc}^1(C_{\downarrow}) = C[X\theta]_{\Phi(C)}\text{acc}^1(C)\sigma = u'\sigma = u\).
9. Similar to Property ✓

10. Let \((Z, k \vdash u) \in D(C, \downarrow)\). Assume that \(Z \not\in S_2(C_1)\) and let \(x \in \mathit{vars}^1(u)\). If \(Z \not\in \{X_2, \ldots, X_n\}\) then there exists \((Z, k \vdash u') \in D(C)\) such that \(u = u' \sigma\). There exists a variable \(z\) such that \(x \in \mathit{vars}^1(z \sigma)\) and \(z \in \mathit{vars}^1(u')\). Since \(C\) is well-formed, we deduce that there exists \((Y, p \vdash t') \in D(C)\) such that \(z \in \mathit{vars}^1(t')\) and \(k < p\). Thus \(x \in \mathit{vars}^1(t' \sigma)\). But \((Y, p \vdash t' \sigma) \in D(C, \downarrow)\) hence the result holds.

If \(Z \in \{X_2, \ldots, X_n\}\) then there exists \(\ell \in \{2, \ldots, n\}\) such that \(x \in \mathit{vars}^1(x_\ell \sigma)\). Since 
\[
\sigma = \mathit{mgu}(u_1 \vdash u_2), \quad f(u_1, \ldots, u_n) \rightarrow w
\]
is a renaming of \(\ell \rightarrow r\) and \(\mathit{vars}^1(u_\ell) \subseteq \mathit{vars}^1(u_1)\), we deduce that \(x \in \mathit{vars}^1(v \sigma)\). By the origination property of a constraint system, \((\xi, j \gg v \sigma) \in \Phi(C, \downarrow)\) and \(x \in \mathit{vars}^1(v \sigma)\) implies that there exists \((Y, p \vdash t) \in D(C, \downarrow)\) such that \(p < j\) and \(x \in \mathit{vars}^1(t)\). But \(j \leq p < i = k\) and so the result holds.

**Case Rule** \(\bar{\rho} = \mathit{EQ-LEFT-LEFT}(\xi_1, \xi_2)\): The rule \(\mathit{EQ-LEFT-LEFT}\) only adds the inequality \(u_1 \neq u_2\) in \(C_2\). Since \(C\) is well-formed, we easily deduce that \(C_{\downarrow}\) is also well-formed.

On the other hand, we have that \(\Phi(C_1) = \Phi(C), \quad D(C_1) = D(C), \quad \mathit{NoUse}(C_1) = \mathit{NoUse}(C), \quad \mathit{Eq}(C) = \mathit{Eq}(C_1)\) and \(\mathit{Eq}(C_1) = \mathit{Eq}(C)\land \mathit{vars}^1(u_1, u_2) \cap \mathit{dom}(\mathit{mgu}(\mathit{Eq}(C))) = \emptyset\). Let \(\sigma = \mathit{mgu}(u_1 \vdash u_2)\). We have that \(\Phi(C_1) = \Phi(C)\sigma, \quad D(C_1) = D(C)\sigma\) and \(\mathit{NoUse}(C_1) = \mathit{NoUse}(C)\sigma\). We have also that \(\mathit{acc}^1(C_{\downarrow}) = \mathit{acc}^1(C)\sigma\). Thus, we easily deduce that \(C_{\downarrow}\) is a well-formed constraint system.

**Case Rule** \(\bar{\rho} = \mathit{EQ-LEFT-RIGHT}(\xi_1, X_2)\): This case is similar to the rule \(\mathit{EQ-LEFT-LEFT}\). Let 
\[
\sigma = \mathit{mgu}(u_1 \vdash u_2).
\]
We have that \(\Phi(C_1) = \Phi(C)\sigma, \quad D(C_1) = D(C)\sigma\) and \(\mathit{acc}^1(C_{\downarrow}) = \mathit{acc}^1(C)\sigma\). On the other hand, we have that \(\mathit{NoUse}(C_1) = \mathit{NoUse}(C)\sigma \cup \{\xi_1, \xi_1 \gg u_1 \sigma\}\). Thus \(C_{\downarrow}\) easily satisfies all the properties of Definition \(\text{S.2}\) except the property \(\text{S}\). We know that \(u_1 \sigma = u_2 \sigma\) and \(X_2, i_2 \vdash u_2 \sigma \in D(C_{\downarrow})\). Furthermore, since \(C\) is normalised, we have that \(X_2 \mathit{mgu}(\mathit{Eq}(C)) = X_2 \mathit{mgu}(\mathit{Eq}(C_{\downarrow}))\) and so \(C[X_2 \mathit{mgu}(\mathit{Eq}(C_{\downarrow}))]_{\Phi(C_{\downarrow})} = X_2\). Lastly, since \(X_2 \mathit{acc}^1(C_1) = u_2 \sigma\), we deduce that \(C[X_2 \mathit{mgu}(\mathit{Eq}(C_{\downarrow}))]_{\Phi(C_{\downarrow})} \mathit{acc}^1(C_{\downarrow}) = u_1 \sigma\). Moreover, by definition of the rule \(\mathit{EQ-LEFT-RIGHT}\), \(i_1 > i_2\) hence we deduce that \(\mathit{param}_{\max}^1(X_2) < i_1\).

For any frame element other than \((\xi_1, i_1 > u_1 \sigma)\) the result holds since \(C\) is well-formed, \(\Phi(C_{\downarrow}) = \Phi(C)\sigma, \quad D(C_{\downarrow}) = D(C)\sigma\) and \(\mathit{acc}^1(C_{\downarrow}) = \mathit{acc}^1(C)\sigma\).

**Case Rule** \(\bar{\rho} = \mathit{EQ-RIGHT-RIGHT}(X, \xi)\): By definition of the rule \(\mathit{EQ-RIGHT-RIGHT}\), we have that 
\[
X, i \vdash u \in D(C), \quad \xi \in \mathcal{T}(C, \mathit{vars}^2(D(C))), \quad \text{and} \quad \mathit{acc}^1(C) = v.\] The rule \(\mathit{EQ-RIGHT-RIGHT}\) only adds the inequality \(u \neq v\) in \(\mathit{Eq}(C_2)\). Thus, we have that \(C_{\downarrow} = C_2\). Since \(C\) is well-formed, we also have that \(C_{\downarrow}\) is a well-formed constraint system.

On the other hand, we have that 
\[
\mathit{Eq}(C_1) = \mathit{Eq}(C) \land X \vdash \xi, \quad D(C_1) = D(C) \setminus \{X, i \vdash u\}, \quad \mathit{Eq}(C_1) = \mathit{Eq}(C) \land u \vdash v \quad \text{and} \quad \Phi(C_{\downarrow}) = \Phi(C_1)\].
By hypothesis, \(C\) is normalised which means that \(\{X\} \cup \mathit{vars}^2(\xi) \cap \mathit{dom}(\mathit{mgu}(\mathit{Eq}(C))) = \emptyset\) and \(\mathit{vars}^1(u, v) \cap \mathit{dom}(\mathit{mgu}(\mathit{Eq}(C))) = \emptyset\). Let \(\sigma = \mathit{mgu}(u \vdash v)\) and \(\delta = \mathit{mgu}(X \vdash \xi)\). We deduce that \(\mathit{mgu}(\mathit{Eq}(C_1)) = \mathit{mgu}(\mathit{Eq}(C))\theta\) and \(\mathit{mgu}(\mathit{Eq}(C_1)) = \mathit{mgu}(\mathit{Eq}(C))\sigma\). Furthermore, since \(C\) is normalised, we have that \(\Phi(C)\mathit{mgu}(\mathit{Eq}(C))\mathit{mgu}(\mathit{Eq}(C)) = \Phi(C)\) and \(D(C)\mathit{mgu}(\mathit{Eq}(C)) = D(C)\). Thus, we can deduce that \(\Phi(C_{\downarrow}) = \Phi(C)\theta\sigma\) and \(D(C_{\downarrow}) = D(C)\sigma\setminus\{X, i \vdash u \sigma\}\). We now prove the different properties one by one.

Let \((\zeta, k \gg w) \in \Phi(C_{\downarrow})\). Since \(\Phi(C_{\downarrow}) = \Phi(C)\theta\sigma\), we know that there exists \((\zeta' \gg w' \in \Phi(C))\) such that \(\zeta = \zeta' \theta\) and \(w = w' \sigma\).

1. this property is direct from Lemma \(\text{S.8}\) and \(C\) being a well-formed constraint system.
2. This property is direct from Lemma C.3 and C being a well-formed constraint system.

3. We know that \( \zeta = \zeta' \theta \) where \( \theta = \text{mgu}(X \downarrow \zeta) \). By definition of the rule Eq-right-right, \( \text{param}_\text{max}^C(\zeta) \leq \text{param}_\text{max}^C(X) = i \). Since C is a well-formed constraint system hence we deduce that \( \text{param}_\text{max}^C(\zeta') \leq \text{param}_\text{max}^C(\zeta') \leq j \). Hence the result holds.

4. Let \( Y \in \text{vars}^2(\zeta) \) and \( y \in \text{vars}^1(Y \text{acc}^1(C_1)) \). \( Y \in \text{vars}^2(D(C_1)) \) implies that \( Y \in \text{vars}^2(D(C)) \). Since \( D(C) \sigma \subseteq D(C_1) \), we deduce that there exists \( z \in \text{vars}^1(Y \text{acc}^1(C)) \) such that \( y = \text{vars}^1(z \sigma) \). Since C is well-formed, we deduce that there exists \( (\beta, j \vdash v) \in \Phi(C) \) such that \( j \leq k \) and \( z \in \text{vars}^1(v) \). Hence \( (\beta \theta, j \vdash v \sigma) \in \Phi(C_1) \) and \( y \in \text{vars}^1(v \sigma) \). Thus the result holds.

5. Let \( \lambda \) be a substitution such that for all \( Y \in \text{vars}^2(\zeta) \), \( (Y \lambda) \Phi(C_1) \downarrow \lambda = r \lambda \) where \( (Y, \ell \vdash r) \in D(C_1) \). Let \( \lambda' \) the substitution such that \( \lambda' = \theta \sigma \lambda \). We show that for all \( Y \in \text{vars}^2(\zeta') \), \( (Y \lambda') \Phi(C) \downarrow \lambda = r \lambda' \) where \( (Y, \ell \vdash r) \in D(C) \). Let \( Y \in \text{vars}^2(\zeta) \). Since \( \zeta = \zeta' \theta \), we have to distinguish two cases:

- **Either** \( Y = X \): In this case, we have that \( \xi \in st(\zeta) \). Thus, by hypothesis, we have that for all \( Z \in \text{vars}^2(\zeta) \), \( (Z \lambda) \Phi(C_1) \downarrow \lambda = t \lambda \), where \( (Z, m \vdash t) \in D(C_1) \). But \( (Z, m \vdash t) \in D(C_1) \) implies that there exist \( t' \) such that \( (Z, m \vdash t') \in D(C) \) and \( t = t' \sigma \). Since \( \Phi(C_1) = \Phi(C) \lambda \sigma \), we deduce that \( (Z \lambda) \Phi(C) \downarrow \lambda = t' \sigma \lambda = t' \lambda' \). Moreover, \( \theta = \{ X \rightarrow \xi \} \) implies that \( Z \beta = Z \) and so \( Z \lambda = Z \lambda' \). Thus we have that \( (Z \lambda) \Phi(C) \downarrow \lambda' = \lambda' = \text{acc}^1(C) \lambda' \). Since \( \xi \in T(F_c, \text{vars}^2(D(C))) \), we deduce that \( (\lambda' \sigma \theta) \Phi(C_1) \downarrow \lambda' = v \lambda' \). With \( v \sigma = v \sigma \), we can conclude that \( (\lambda' \Phi(C_1)) \downarrow = w \lambda' \).

- **Or** \( Y \in \text{vars}^2(\zeta) \): In such a case, we have that \( Y \theta \sigma = Y \) and so \( Y \lambda' = Y \lambda \). Furthermore, we know that \( \Phi(C_1) = \Phi(C) \theta \sigma \) and so \( \Phi(C_1) \lambda = \Phi(C) \lambda' \). Thus, we have that \( (Y \lambda') \Phi(C) \downarrow = (Y \lambda) \Phi(C_1) \downarrow \lambda \). By hypothesis, there exists \( Y, \ell \vdash r \in D(C_1) \) such that \( (Y \lambda) \Phi(C_1) \downarrow \lambda = r \lambda \). Since \( D(C_1) = D(C) \sigma \{ X, i \vdash u \} \) and \( Y \neq X \), there exists \( Y, \ell \vdash r' \in D(C) \) such that \( r = r' \sigma \) and so \( r = r' \lambda' \). We can conclude that \( (Y \lambda') \Phi(C) \downarrow = r \lambda' \) with \( Y, \ell \vdash r' \in D(C) \).

By hypothesis, we know that C well-formed. Hence, we have that \( (\lambda' \lambda') \Phi(C) \downarrow = w \lambda' \). Since \( \lambda' = \lambda \), \( w \lambda' = w \lambda \) and \( \Phi(C) \lambda' = \Phi(C_1) \lambda \), we conclude that \( (\lambda) \Phi(C_1) \downarrow = w \lambda \).

6. We know that \( \xi \in T(F_c, \mathcal{A} \lambda \mu) \) hence this case is similar to the proof of Property 6 for the rule CONS.

7. Let \( Y \in \text{vars}^2(C_1) \). We have \( \text{mgu}(Er(C_1)) = \text{mgu}(Er(C)) \theta \) with \( \theta = \{ X \rightarrow \xi \} \). Furthermore, we know that \( \xi \in T(F_c, \text{vars}^2(D(C))) \) and so \( C[\xi] \Phi(C_1) = \xi \in T(F_c, \mathcal{A} \lambda \mu) \). By Lemma C.3 we have that \( C[\text{Ymgu}(Er(C_1))] \Phi(C_1) = C[\text{Ymgu}(Er(C))] \Phi(C_1) \). We have that \( C[\text{Ymgu}(Er(C_1))] \Phi(C_1) = C[\text{Ymgu}(Er(C))] \Phi(C_1) \) for \( C \) well-formed. Since we have that \( \xi \in T(F_c, \text{vars}^2(D(C))) \), we conclude that \( C[\text{Ymgu}(Er(C_1))] \Phi(C_1) = T(F_c, F_d \mu) \). Let \( \zeta \in st(\text{Ymgu}(Er(C_1))) \) such that \( \text{path}(\zeta) \in F_d \mu \). We know that \( \text{mgu}(Er(C_1)) = \text{mgu}(Er(C)) \theta \). But \( \theta = \text{mgu}(X \rightarrow \xi) \) with \( \xi \in T(F_c, \mathcal{A} \lambda \mu) \). Hence \( \text{path}(\zeta) \in F_d \mu \). Thus \( \text{path}(\zeta) \in F_d \mu \) and \( \text{mgu}(Er(C_1)) \) such that \( \zeta = \zeta' \theta \). Since C is well-formed, we deduce that there exists \( k, w \) such that \( (\zeta', k \vdash w) \in \Phi(C) \). Thus \( (\zeta' \theta, k \vdash w \sigma) \in \Phi(C_1) \) and so the result holds.

8. Assume that \( (\xi, k \vdash w) \in \text{NoUse}(C_1) \). Since \( \text{NoUse}(C_1) = \text{NoUse}(C) \theta \sigma \), we have that \( (\xi, k \vdash w') \in \text{NoUse}(C) \). Since C is well-formed, we deduce that there exists \( Y \in \text{vars}^2(C) \)
such that $C[Y_{\text{mgu}}(Er(C))]_{\Phi(C)}\text{acc}^1(C) = w'$ and $\text{param}_{\text{max}}^C(Y_{\text{mgu}}(Er(C))) < k$. As shown in the previous point, we have that $C[Y_{\text{mgu}}(Er(C))]_{\Phi(C)}\text{acc}^1(C) = C[Y_{\text{mgu}}(Er(C))]_{\Phi(C)}\theta$. Furthermore, we have $\xi\text{acc}^1(C)\sigma = w\sigma = u\sigma = X\text{acc}^1(C)\sigma$. Thus, we deduce that $\theta\text{acc}^1(C)\sigma = \text{acc}^1(C)\sigma$. Moreover, we know that $D(C_{\downarrow}) = D(C)\sigma\{X, i \vdash u\sigma\}$ and $\Phi(C_{\downarrow}) = \Phi(C)\theta$ which means that $\text{acc}^1(C)\sigma = \theta\text{acc}^1(C_{\downarrow})$. We can conclude that $C[Y_{\text{mgu}}(Er(C))]_{\Phi(C)}\text{acc}^1(C_{\downarrow}) = C[Y_{\text{mgu}}(Er(C))]_{\Phi(C)}\text{acc}^1(C)\sigma = w'\sigma = w$. Lastly, for all $Z \in \text{vars}^2(\xi)$, $\text{param}_{\text{max}}^z(Z) \leq i = \text{param}_{\text{max}}^z(X)$. Since $Y_{\text{mgu}}(Er(C_{\downarrow})) = Y_{\text{mgu}}(Er(C))\theta$, we conclude that $\text{param}_{\text{max}}^z(Y_{\text{mgu}}(Er(C))) < k$ implies that $\text{param}_{\text{max}}^z(Y_{\text{mgu}}(Er(C_{\downarrow}))) < k$.

9. Similar to Property 8

10. Let $(Z, k \vdash t) \in D(C_{\downarrow})$. Assume that $Z \notin S_2(C_1)$ and let $x \in \text{vars}^1(u)$. It implies that there exists $(Z, k \vdash t') \in D(C)$ such that $t = t'\sigma$. Hence, there exists a variable $z$ such that $x \in \text{vars}^1(z\sigma)$ and $z \in \text{vars}^1(t')$. Since $C$ is well-formed, we deduce that there exists $(Y, p \vdash w') \in D(C)$ such that $z \in \text{vars}(w')$ and $p < k$. Thus $x \in \text{vars}^1(w'\sigma)$. If $Y \neq X$ then we deduce that $(Y, p \vdash w'\sigma) \in D(C_{\downarrow})$ and so the result holds. If $Y = X$, then $u = w'$ and $p = i$. Since $\sigma = \text{mgu}(u \vdash v)$, we deduce that $x \in \text{vars}^1(v\sigma)$. Moreover, by construction of $v$, it implies that there exists $(Y', p' \vdash u') \in D(C_{\downarrow})$ such that $Y' \in \text{vars}^2(\xi)$, $p' \leq i$ and $x \in \text{vars}^1(u')$. Since $p' \leq i < k$, we deduce that $p' < k$ and so the result holds.

Case Rule $(\tilde{p}) = \text{DED-st}(\xi, f)$: The rule $\text{DED-st}$ only adds a non-deducibility constraint in $C_2$. Thus, we have that $C_{\downarrow} \subseteq C_2$ and since $C$ is a well-formed constraint system, we easily deduce that $C_2$ is also well-formed.

On the other hand, we have that $\Phi(C_1) = \Phi(C)$, $D(C_1) = D(C) \cup \{X_1, m \vdash x_1; \ldots; X_n, m \vdash x_n\}$, $\text{NoUse}(C_1) = \text{NoUse}(C)$, $\text{Er}(C) = \text{Er}(C_1)$ and $\text{Eq}(C_1) = \text{Eq}(C) \land u \vDash f(x_1, \ldots, x_n)$ where $x_1, \ldots, x_n$ are fresh variables. Since $C$ is well-formed, we have $\text{vars}^1(u) \cap \text{dom}(\text{mgu}(\text{Eq}(C))) = \emptyset$. Let $\sigma = \text{mgu}(u \vdash f(x_1, \ldots, x_n))$. We have that $\Phi(C_{\downarrow}) = \Phi(C)\sigma$, $D(C_{\downarrow}) = D(C)\sigma \cup \{X_1, m \vdash x_1\sigma; \ldots; X_n, m \vdash x_n\sigma\}$ and $\text{NoUse}(C_{\downarrow}) = \text{NoUse}(C)\sigma$. Since the variables $X_1, \ldots, X_n$ do not appear in the frame, the facts that $C$ is well-formed and $\sigma = \text{mgu}(u \vdash f(x_1, \ldots, x_n))$ implies that $C_{\downarrow}$ is also a well-formed constraint system. \hfill \square

**Lemma C.10.** Let $C$ be a well-formed constraint system. We have for all $(Y, p \vdash u) \in D$, for all $x \in \text{vars}^1(u)$, there exists $(X, q \vdash v) \in D$ such that $x \in \text{vars}^1(v)$, $q \leq p$ and $X \in S_2$.

**Proof.** Let $C$ be a well-formed constraint system and $C_1$, $C_2$ the two constraint systems obtained by application of the rule on $C$.

For any rule, only disequations and non-deducibility constraint are added on $C_2$. Thus, we trivially have that $D(C) = D(C_2)$, $\Phi(C) = \Phi(C_2)$ and $S_2(C) = S_2(C_2)$. Therefore, we can conclude that $C_2$ satisfies the property.

We focus now $C_1$. First of all, we prove that the application of a substitution preserves the property. Let $\sigma$ be a substitution such that $\text{dom}(\sigma) \cap \text{img}(\sigma) = \emptyset$. Let $(Y, p \vdash u\sigma) \in D(C)$, let $x \in \text{vars}^1(u\sigma)$.

- if $x \in \text{vars}^1(u)$, then by hypothesis, there exists $(X, q \vdash v) \in D(C)$ such that $x \in \text{vars}^1(v)$, $q \leq p$ and $X \in S_2(C)$. But $\text{dom}(\sigma) \cap \text{img}(\sigma) = \emptyset$, which means that $x \in \text{vars}^1(v\sigma)$.
- Since $S_2(C) = S_2(C\sigma)$, the result holds.
• if $x \not\in \mathit{vars}^1(u)$, it means that $x \in \mathit{img}(\sigma)$ and that there exists $y \in \mathit{vars}^1(u)$ such that $x \in \mathit{vars}^1(y\sigma)$. Thus by hypothesis, we have that there exists $(X, q \vdash v) \in D(\mathcal{C})$ such that $y \in \mathit{vars}^1(v)$, $q \leq p$ and $X \in S_2(\mathcal{C})$. Therefore, we have $x \in \mathit{vars}^1(u\sigma)$ which prove the result.

We prove the result by case analysis on the rule applied on a constraint system:

**Rule CONS:** The substitution $\sigma = \mathit{mgu}(t \overset{\gamma}{\sim} f(x_1, \ldots, x_n))$ was applied on $\mathcal{C}$, with $x_1, \ldots, x_n$ fresh variables. Hence we know that $\mathcal{C}\sigma$ satisfies the property. Let first assume that the rule CONS was applied on $(X, i \vdash t)$ such that $X \not\in S_2(\mathcal{C})$. In such a case, we have that $S_2(\mathcal{C}) = S_2(\mathcal{C}_1)$. On $\mathcal{C}_1$, the deducible constraints $(X_k, i \vdash x_i\sigma)$ are added, for all $j \in \{1, \ldots, n\}$. Since $\sigma = \mathit{mgu}(t \overset{\gamma}{\sim} f(x_1, \ldots, x_n))$, we know that $\mathit{vars}^1(x_1\sigma, \ldots, x_n\sigma) = \mathit{vars}^1(t\sigma)$. Thus for all $x \in \mathit{vars}^1(x_k\sigma)$, there exists $(Y, q \vdash v\sigma) \in D(\mathcal{C})$ such that $x \in \mathit{vars}^1(v)$, $q \leq i$ and $Y \in S_2(\mathcal{C}\sigma) = S_2(\mathcal{C}_1)$, which proves the result.

If we assume now that $X \in S_2(\mathcal{C})$, by application of the rule, we have $S_2(\mathcal{C}_1) = S_2(\mathcal{C}) \cup \{X_1, \ldots, X_n\}$. Thus for all $(Y, p \vdash u\sigma) \in D(\mathcal{C}_1)$, for all $x \in u\sigma$, we know by hypothesis that there exists $(Z, q \vdash v\sigma) \in D(\mathcal{C})$ such that $x \in \mathit{vars}^1(v\sigma)$, $q \leq p$ and $Z \in S_2(\mathcal{C}\sigma)$. If $Z \neq X$ then the result holds, else we know that $\sigma = \mathit{mgu}(t \overset{\gamma}{\sim} f(x_1, \ldots, x_n))$ and so $\mathit{vars}^1(x_1\sigma, \ldots, x_n\sigma) = \mathit{vars}^1(t\sigma)$. Therefore, there exists $k \in \{1 \ldots n\}$ such that $x \in \mathit{vars}^1(x_k\sigma)$, which also proves the result.

**Rule AXIOM($\mathcal{X}, \mathit{path}$):** Assume that the rule is applied on $(X, i \vdash u) \in D$ and $(\xi, j \vdash v) \in \Phi$ with $\mathit{path}(\xi) = \mathit{path}$. The substitution $\sigma = \mathit{mgu}(u \overset{\gamma}{\sim} v)$ was applied on $\mathcal{C}$ thus we know that $\mathcal{C}\sigma$ satisfies the property. Furthermore, the deducible constraint $X, i \vdash u$ was removed from $D(\mathcal{C})$ in $\mathcal{C}_1$. If $X \not\in S_2(\mathcal{C}_1)$ then the result trivially holds. Else, let $(Y, p \vdash u\sigma) \in D(\mathcal{C}_1)$ such that $Y \not\in S_2(\mathcal{C}_1)$. By hypothesis, we know that for all $x \in \mathit{vars}^1(u\sigma)$, there exists $(Z, q \vdash v\sigma) \in D(\mathcal{C}\sigma)$ such that $x \in \mathit{vars}^1(v\sigma)$, $q \leq p$. If $Z \neq X$ then the result holds, else $x \in \mathit{vars}^1(u\sigma)$ implies that $x \in \mathit{vars}^1(v\sigma)$ since $\sigma = \mathit{mgu}(u \overset{\gamma}{\sim} v)$. But the rule tells us that $j \leq i$ and so $j \leq p$. Furthermore, by Definition of a constraint system, we know that there exists $(Z', k \vdash u') \in D(\mathcal{C}_1)$ such that $x \in \mathit{vars}^1(u')$ and $k < j$. But $(Z', k \vdash u') \in D(\mathcal{C}\sigma)$ and so by hypothesis, there exists $(Y', k' \vdash v') \in D(\mathcal{C}\sigma)$ such that $x \in \mathit{vars}^1(v')$, $k' \leq k$ and $Y' \in S_2(\mathcal{C}\sigma)$. Since $k' \leq k < i$ then we have $Y' \neq X$ which implies that $(Y', k' \vdash v') \in D(\mathcal{C}_1)$ and $Y' \in S_2(\mathcal{C}_1)$. Hence the result holds.

**Rule DEST($\xi, \ell \rightarrow r, i$):** Assume that the rule is applied on $(\xi, j \vdash v) \in \Phi(\mathcal{C})$ with $f(u_1, \ldots, u_n) \rightarrow w$ a fresh variant of $\ell \rightarrow r$. The substitution $\sigma = \mathit{mgu}(v \overset{\gamma}{\sim} u_i)$ was applied on $\mathcal{C}$ thus we know that $\mathcal{C}\sigma$ satisfies the property. Furthermore, only deducible constraints $(X_i, j \vdash u_i\sigma)$ were added on $\mathcal{C}_1$ such that $X_i \not\in S_2(\mathcal{C}_1)$, for all $i \in \{2, \ldots, n\}$. Since by definition of our rewriting rules, $\mathit{vars}^1(u_2, \ldots, u_n) \subseteq \mathit{vars}^1(u_1)$, we have for all $i \in \{2 \ldots n\}$, for all $x \in \mathit{vars}^1(u_i\sigma)$, $x \in \mathit{vars}^1(u\sigma)$. Thus by Definition of a constraint system, we have that there exists $(Z, k \vdash t) \in D(\mathcal{C}_1)$ such that $x \in \mathit{vars}^1(t)$, $k < j$ and $k < i$. But $k < i$ implies that $(Z, k \vdash t) \in D(\mathcal{C}\sigma)$. Hence there exists $(Z', k' \vdash t') \in D(\mathcal{C}\sigma)$ such that $Z' \in S_2(\mathcal{C}\sigma)$, $k' \leq k'$ and $x \in \mathit{vars}^1(\mathcal{C}\sigma)$. But, it implies that $(Z, k' \vdash t') \in D(\mathcal{C}_1)$ and $Z' \in S_2(\mathcal{C}_1)$. Hence the result holds.

**Rule EQ-LEFT-LEFT, EQ-LEFT-RIGHT and EQ-RIGHT-RIGHT:** For those rules, $D(\mathcal{C}\sigma) = D(\mathcal{C}_1)$ and $S_2(\mathcal{C}\sigma) = S_2(\mathcal{C}_1)$ hence the result trivially holds.
C.3. PROOF OF COMPLETENESS

Rule Ded-st($\xi, f$): Assume that the rule is applied on ($\xi, i \triangleright u$). The substitution $\sigma = \text{mgu}(u \vdash f(x_1, \ldots, x_n))$ was applied on $C$ with $x_1, \ldots, x_n$ fresh variables. Thus we know that $C\sigma$ satisfies the property. Furthermore, only deducible constraints $(X, m \vdash x_i\sigma)$ were added on $C_1$ such that $X_i \notin S_2(C_1)$, for all $i \in \{1, \ldots, n\}$. Since $\sigma = \text{mgu}(u \vdash f(x_1, \ldots, x_n))$, we have for all $i \in \{1, \ldots, n\}$, for all $x \in \text{vars}^1(x_i\sigma)$, $x \in \text{vars}^1(u\sigma)$. Thus by definition of a constraint system, we have that there exists $(X, k \vdash t) \in D(C_1)$ with $x \in \text{vars}^1(t)$, $t < i$ and so $t < m$. But $t < m$ implies that $(X, k \vdash t) \in D(C\sigma)$ which means that there exists $(X', k' \vdash t') \in D(C\sigma)$ with $x \in \text{vars}^1(t)$, $X' \in S_2(C\sigma)$ and $k' \leq k$ and so $k' < m$. It implies that $(X', k', \vdash t') \in D(C_1)$ and $X' \in S_2(C_1)$. Hence the result holds.

\[\square\]

C.3 Proof of completeness

Lemma 8.5 (completeness). Let $C$ be a normalised constraint system obtained by applying the strategy and Rule($\bar{p}$) be a transformation rule applicable on $C$. Let $C_1$ and $C_2$ be the two resulting constraint systems obtained by applying Rule($\bar{p}$) on $C$. We denote by $\Phi_1$ and $\Phi_2$ the respective frames of $C, C_1$ and $C_2$ and we denote by $S_1$ the set of free variable of $C$.

For all $i \in \{1, 2\}$, for all $(\sigma_i, \theta_i) \in \text{Sol}(C_i)$, $(\sigma, \theta) \in \text{Sol}(C)$ and $\text{Init}(\Phi)\sigma = \text{Init}(\Phi_i)\sigma_i$ where $\sigma = \sigma_i|_{\text{vars}^1(C)}$ and $\theta = \theta_i|_{\text{vars}^2(C)}$.

\begin{itemize}
  \item \textbf{Variation:} For all $i \in \{1, 2\}$, for all $(\sigma_i, \theta_i) \in \text{Sol}(C_i)$, $(\sigma, \theta) \in \text{Sol}(C)$ and $\text{Init}(\Phi)\sigma = \text{Init}(\Phi_i)\sigma_i$ where $\sigma = \sigma_i|_{\text{vars}^1(C)}$ and $\theta = \theta_i|_{\text{vars}^2(C)}$.
\end{itemize}

\textbf{Proof.} We prove this lemma by case analysis on the transformation rule that is used to transform $C$ on $C_1, C_2$. In each situation where some conditions are added on the resulting constraint system (without modifying the conditions that are already present in $C$), the result trivially holds. This remark allows one to conclude for the rules Eq-left-left, Eq-left-right, Ded-st, Dest, and the case $i = 2$ for the rules Cons, Axiom and Eq-right-right. Therefore, it remains to prove the result for the remaining cases, i.e. rule Cons when $i = 1$, rule Axiom when $i = 1$ and rule Eq-right-right when $i = 1$.

Let $C = (S_1; S_2; \Phi; D; Er; ND; NoUse)$. We consider the remaining cases using the notation introduced in Figure 7.1.

Rule Cons($X, f$), $i = 1$: Assume that $X, k \vdash t \in D(C)$ and so $D(C_1) = \{X, k \vdash x_1; \ldots; X_n, k \vdash x_n\} \cup D(C) \smallsetminus \{X, k \vdash t\}$. $Eq(C_1) = Eq(C) \land x \vdash f(x_1, \ldots, x_n)$ and $Er(C_1) = Er(C) \land X \vdash f(x_1, \ldots, x_n)$. Let $(\sigma_1, \theta_1) \in \text{Sol}(C_1)$. By definition of a solution of a constraint system, we know that:

1. $(X_j\theta_1)(\Phi(C)\sigma_1) \downarrow = x_j\sigma_1\downarrow$ and $\text{param}(X_j\theta_1) \subseteq \{ax_1, \ldots, ax_n\}$ for any $j \in \{1, \ldots, n\}$;
2. $\sigma_1 \models Eq(C) \land x \vdash f(x_1, \ldots, x_n) \land ND(C)$ and so $\sigma_1 \downarrow = f(x_1\sigma_1, \ldots, x_n\sigma_1)\downarrow$;
3. $\theta_1 \models Er(C) \land X \vdash f(X_1, \ldots, X_n)$ and so $X\theta_1 = f(X_1\theta_1, \ldots, X_n\theta_1)$.

Hence, we have that:

\[(X\theta_1)(\Phi(C)\sigma_1) \downarrow = f(X_1\theta_1, \ldots, X_n\theta_1)(\Phi(C)\sigma_1)\downarrow = f((X_1\theta_1)(\Phi(C)\sigma_1)\downarrow, \ldots, (X_n\theta_1)(\Phi(C)\sigma_1)\downarrow)\downarrow = f(x_1\sigma_1\downarrow, \ldots, x_n\sigma_1\downarrow)\downarrow = f(x_1\sigma_1, \ldots, x_n\sigma_1)\downarrow = \sigma_1 \downarrow.\]

Moreover, thanks to $\text{param}(X_j\theta_1) \subseteq \{ax_1, \ldots, ax_n\}$ for any $j \in \{1, \ldots, n\}$, we have that $\text{param}(X\theta_1) \subseteq \{ax_1, \ldots, ax_n\}$. This allows us to conclude that $(\sigma_1|_{\text{vars}^1(C)}, \theta_1|_{\text{vars}^2(C)}) \in \text{Sol}(C)$. 

\[\square\]
Rule Axiom($X$, path), $i = 1$. Assume that $(X, k \xrightarrow{\gamma} u) \in D(C)$ and $(\xi, j \vdash v) \in \Phi(C)$ with $j \leq k$ and path($\xi$) = path. Thus, we have $Er(C_1) = Er(C) \land X \xrightarrow{\gamma} \xi$, $Eq(C_1) = Eq(C) \land u \xrightarrow{\gamma} v$, $D(C_1) = D(C) \setminus \{(X, k \xrightarrow{\gamma} u)\}$ and $\Phi(C_1) = \Phi(C)$.

Let $(\sigma_1, \theta_1) \in \text{Sol}(C_1)$. By definition of a solution of a constraint system, we know that:

1. $\sigma_1 \models Eq(C) \land u \xrightarrow{\gamma} v \land ND(C)$, and so $u\sigma_1 = v\sigma_1$.
2. $\theta_1 \models Er(C) \land X \xrightarrow{\gamma} \xi$, and so $X\theta_1 = \xi\theta_1$.

Hence, we have that $(X\theta_1)(\Phi\sigma_1) \downarrow = (\xi\theta_1)(\Phi\sigma_1) \downarrow$. Moreover, since $C$ is well-formed (Definition 8.2, item 5), there exists $q \leq j$ and $w$ such that $(Y, q \xrightarrow{\gamma} w) \in D(C)$. Since $X$ an $\xi$ are unifiable, we also deduce that $X \not\in \text{vars}(X)$.

Hence, $(Y, q \xrightarrow{\gamma} w) \in D(C_1)$. Thanks to $(\sigma_1, \theta_1) \in \text{Sol}(C_1)$, $Y\theta_1\Phi(C_1)\sigma_1 = w\sigma_1$. Hence, thanks to $C$ being well-formed (Definition 8.2, item 5) and $\Phi(C_1) = \Phi(C)$, we deduce that $\xi\theta_1(\Phi\sigma_1)\sigma_1 = w\sigma_1$.

At last, since $\text{param}_{\text{max}}(\Phi(\sigma_1)) \leq j$ and for all $Y \in \text{vars}(\xi)$, $(\sigma_1, \theta_1) \in \text{Sol}(C_1)$ also indicates that $\text{param}(Y\theta_1) \subseteq \{ax_1, \ldots, ax_j\}$ and so $\text{param}(\xi\theta_1) \subseteq \{ax_1, \ldots, ax_j\}$. This allows us to conclude that $(\sigma_1|_{\text{vars}(\xi)}, \theta_1|_{\text{vars}(\xi)}) \in \text{Sol}(C)$.

Rule $\text{Eq-right-right}(X, \xi), i = 1$. Assume that $(X, k \xrightarrow{\gamma} u) \in D(C)$ and $\xi \in T(F_c, \text{dom}(\alpha))$ with $\alpha = \{Y \rightarrow w \mid (Y, j \xrightarrow{\gamma} w) \in D(C) \land j \leq i \land Y \in S_2\}$. Thus, we have $Er(C_1) = Er(C) \land X \xrightarrow{\gamma} \xi$, $Eq(C_1) = Eq(C) \land u \xrightarrow{\gamma} v$, $D(C_1) = D(C) \setminus \{(X, k \xrightarrow{\gamma} u)\}$ and $\Phi(C_1) = \Phi(C)$.

Let $(\sigma_1, \theta_1) \in \text{Sol}(C_1)$. By definition of a solution of a constraint system, we know that:

1. $\sigma_1 \models Eq \land u \xrightarrow{\gamma} v \land ND$, and so $u\sigma_1 = v\sigma_1$.
2. $\theta_1 \models Er \land X \xrightarrow{\gamma} \xi$, and so $X\theta_1 = \xi\theta_1$.

Hence, we have that $(X\theta_1)(\Phi\sigma_1) \downarrow = (\xi\theta_1)(\Phi\sigma_1) \downarrow$. Moreover, according to Figure 7.2, we have that $\xi \in T(F_c, \text{dom}(\alpha))$ and $v = \xi\alpha$.

Since $(\sigma_1, \theta_1) \in \text{Sol}(C_1)$, we have that for all $(Y, j \xrightarrow{\gamma} w) \in D(C_1)$, $(Y\theta_1)\Phi(\sigma_1)\sigma_1 = w\sigma_1$. Since $\xi \in T(F_c, X^2)$, we can deduce that $(\xi\theta_1)(\Phi\sigma_1)\sigma_1 \downarrow = w\sigma_1$. This allows us to deduce that $(X\theta_1)(\Phi\sigma_1)\sigma_1 \downarrow = v\sigma_1$ and so $(X\theta_1)(\Phi\sigma_1)\sigma_1 \downarrow = w\sigma_1$. Furthermore, we also know that for all $(Y, j \xrightarrow{\gamma} w) \in D$, if $Y \in \text{vars}(\xi)$, then $j \leq i$ which means that $\text{param}(Y\theta_1) \subseteq \{ax_1, \ldots, ax_i\}$. Thus we have:

$$\text{param}(X\theta_1) = \text{param}(\xi\theta_1) \subseteq \{ax_1, \ldots, ax_i\}.$$ 

This allows us to conclude that $(\sigma_1|_{\text{vars}(\xi)}, \theta_1|_{\text{vars}(\xi)}) \in \text{Sol}(C)$.

C.4 Strategy Invariants

C.4.1 Preliminaries

We write $C \rightarrow^* C'$ when $C'$ is obtained from $C$ by applying a sequence of transformation rules.

Lemma C.11. Let $C$ and $C'$ be two normalised well-formed constraint systems such that $C \rightarrow^* C'$. Let $\theta = \text{mgu}(Er(C))$, $\theta' = \text{mgu}(Er(C'))$ and $\sigma' = \text{mgu}(Eq(C'))$. The following property holds: for all $X \in \text{vars}(C)$, $C[X\theta]_{\Phi,\text{acc}}(C')\sigma' = C[X\theta']_{\Phi,\text{acc}}(C')$ and $\text{param}_{\text{max}}^{C'}(X\theta') \leq \text{param}_{\text{max}}(X\theta)$.


C.4. STRATEGY INVARIANTS

Proof. We prove this result by induction on the length $N$ of the derivation $C \rightarrow \ast C'$.

Base case $N = 0$: In such a case, $C = C'$. Thus, we have that $\theta = \theta'$ and $\text{acc}^1(C) = \text{acc}^1(C')$. Therefore, we have for all $X \in \text{vars}^2(C)$, $\text{acc}^1(C)\sigma' = \text{acc}^1(C')\sigma'$. Since $C$ is normalised, we have that $\text{dom}(\sigma') \cap \text{img}(\text{acc}^1(C')) = \emptyset$, which means that $\text{acc}^1(C')\sigma' = \text{acc}^1(C')$. Furthermore, since $\theta = \theta'$ and $C = C'$, we trivially have that $\text{param}_{\text{max}}^C(X\theta) \leq \text{param}_{\text{max}}^C(X\theta)$. Hence the result holds.

Inductive case $N > 0$: In such a case, we have that $C \rightarrow \ast C'' \rightarrow C'$ for some normalised constraint system $C''$. By Lemma C.22 we know that $C''$ is also well-formed. Let $\theta'' = \text{mgu}(Er(C''))$ and $\sigma'' = \text{mgu}(\text{Eq}(C''))$. By inductive hypothesis, we know that for all $X \in \text{vars}^2(C)$, $\text{acc}^1(C)\sigma'' = \text{acc}^1(C')\sigma''$. Since $\theta'$ is normalised, it means that $\text{acc}^1(C')\sigma'' = \text{acc}^1(C')$. Moreover, since $\theta = \theta'$ and $C = C'$, we conclude that $\text{param}_{\text{max}}^C(X\theta') \leq \text{param}_{\text{max}}^C(X\theta)$ and so the result holds.

Case $C'' = C_2$ for any rule: According to Figure 7.1 and Figure 7.2 for any rule, only inequations or non deducibility constraint are added in $C_2$, or some frame elements are marked as NoUse. Hence, we have that $\theta'' = \theta'$, $\sigma'' = \sigma'$, $\Phi'' = \Phi'$ and $D'' = D'$. Thus, $\text{acc}^1(C')\sigma'' = \text{acc}^1(C')\sigma''$ implies $\text{acc}^1(C')\sigma'' = \text{acc}^1(C')$. Moreover, we also deduce $\text{param}_{\text{max}}^C(Y\theta) = \text{param}_{\text{max}}^C(Y\theta')$. Since $\text{param}_{\text{max}}^C(Y\theta') \leq \text{param}_{\text{max}}^C(Y\theta)$ and so the result holds.

We now consider the case where $C'' = C_1$, and we consider each rule in turn:

Rule CONS($X, f$): Let $Y \in \text{vars}^2(C)$. The rule described in Figure 7.1 tells us that:

- $Eq' = Eq'' \land t \not\models f(x_1, \ldots, x_n)$.
- $Er' = Er'' \land X \not\models f(X_1, \ldots, X_n)$.
- $(X, i \vdash t) \in D(C'')$.

Since $C''$ is normalised, it means that $\text{vars}(t) \cap \text{dom}(\sigma'') = \emptyset$. Furthermore, $x_1, \ldots, x_n$ are fresh variables, and so $\{x_1, \ldots, x_n\} \cap \text{dom}(\sigma'') = \emptyset$. Thus, $\text{mgu}(Eq'' \land t \not\models f(x_1, \ldots, x_n)) = \sigma'' \text{mgu}(t \not\models f(x_1, \ldots, x_n))$. Let $\Sigma = \text{mgu}(t \not\models f(x_1, \ldots, x_n))$ (it exists otherwise the normalised constraint system $C'$ would be $\perp$), we have $\sigma' = \sigma''\Sigma$. Since $X_1, \ldots, X_n$ are also fresh variables, thus if we denote $\theta = \text{mgu}(X \not\models f(X_1, \ldots, X_n))$, then $\theta = \theta''\Theta$.

According to Figure 7.1 $(X, i \vdash t) \in D(C'')$ implies $(X, k \vdash x_k\Sigma) \in D(C')$ for all $k \in \{1, \ldots, n\}$. Hence, we have that $\text{param}_{\text{max}}^C(X, i \vdash t) = \text{param}_{\text{max}}^C(X, \vdash t)$. Since only $X, i \vdash t$ was removed from $D(C'')$, we deduce that $\text{param}_{\text{max}}^C(Y\theta''\Theta) = \text{param}_{\text{max}}^C(Y\theta)$. Hence $\text{param}_{\text{max}}^C(Y\theta') \leq \text{param}_{\text{max}}^C(Y\theta)$.

From the first equality, we deduce that $\text{acc}^1(C')\sigma' = \text{acc}^1(C')\sigma''\Sigma$. Therefore by inductive hypothesis, we have $\text{acc}^1(C')\sigma'' = \text{acc}^1(C')\sigma''\Sigma$. But since no frame element was added on $\Phi'$, thus we have $\text{acc}^1(C')\sigma''\Sigma = \text{acc}^1(C')\sigma''\Sigma$. Furthermore, since $C''$ is well-formed, we know that $\text{acc}^1(C')\sigma'' = (\text{acc}^1(C')\sigma''\Sigma)(\Phi') \in \text{acc}^1(C')\sigma''(\Phi') \in T(\text{acc}^1(C'), \text{acc}^1(C'))$ and so $\text{acc}^1(C')\sigma''\Sigma = \text{acc}^1(C')\sigma''\Sigma$. By Lemma C.9 that $\text{acc}^1(C')\sigma'' = \text{acc}^1(C')\sigma''\Sigma$.

At last, since the constraint with the variable $X$ was removed in $D'$ and since we consider $C'$ normalised, we have:

- for all $Z \in \text{vars}^2(D'') \setminus \{X\}$, $Z\text{acc}^1(C') = Z\text{acc}^1(C') = Z\text{acc}^1(C'')\Sigma$.
- for all $i \in \{1, \ldots, n\}$, $X_i\text{acc}^1(C') = x_i\Sigma$ and so $X\text{acc}^1(C''\Sigma) = t\Sigma = f(x_1, \ldots, x_n)\Sigma = X\text{acc}^1(C')$.
Thus, we deduce that $\text{acc}(C')\Sigma = \Theta \text{acc}(C')$, which implies, thanks to $C[Y\theta']\Theta = C[Y\theta']\varphi\Theta$, that $C[Y\theta']\varphi\text{acc}(C') = C[Y\theta']\varphi\text{acc}(C')$ and so $C[Y\theta']\varphi\text{acc}(C')\sigma' = C[Y\theta']\varphi\text{acc}(C')$.

Rule Axiom($X,\text{path}$): Let $Y \in \text{vars}^2(C)$. The rule described in Figure [73] tells us that:

- $Eq' = Eq' \land u \equiv v$.
- $Er' = Er' \land X \equiv \xi$.
- $(X,i \vdash u) \in D(C')$, $(\xi,j \triangleright v) \in \Phi(C')$ and $\text{path}(\xi) = \text{path}$.

Since $C'$ is normalised, it means that $(\text{vars}(u) \cup \text{vars}(v)) \cap \text{dom}(\sigma'') = \emptyset$ which means that $\text{mgu}(Eq' \land u \equiv v) = \sigma''\text{mgu}(u \equiv v)$. Let $\Sigma = \text{mgu}(u \equiv v)$; we have $\sigma' = \sigma''\Sigma$. For the same reason, if we denoted $\Theta = \text{mgu}(X \equiv \xi)$, we have $\theta' = \theta''\Theta$. No element has been added into the frame $C'$ (from $C''$), which means that $C[Y\theta']\varphi' = C[Y\theta']\varphi'' = C[Y\theta']\varphi'$. By Lemma [C.9] and since $C'$ is well-formed, we deduce that $C[Y\theta']\varphi' = C[Y\theta']\varphi'' \{X \rightarrow C[Y\theta']\varphi''\}$.

Thanks to $C$ being well-formed (Definition [8.2] item 3), we deduce that $\text{param}_{\text{max}}(\xi) \leq j$. Moreover, since $\Theta = \text{mgu}(X \equiv \xi)$, we deduce that $X \not\in \text{vars}^2(\xi)$ and so $(\xi,j \triangleright v) \in \Phi(C')$.

The deductible constraint $(X,i \vdash u)$ being the only one removed from $D(C')$, we deduce that $\text{param}_{\text{max}}(\xi) = \text{param}_{\text{max}}(\xi)$. Hence $\text{param}_{\text{max}}(X) = i \geq j \geq \text{param}_{\text{max}}(\xi)$. Therefore we deduce that $\text{param}_{\text{max}}(Y\theta') = \text{param}_{\text{max}}(Y\theta'\Theta) = \text{param}_{\text{max}}(Y\theta'')$. Thus we deduce that $\text{param}_{\text{max}}(Y\theta') = \text{param}_{\text{max}}(Y\theta'\Theta) = \text{param}_{\text{max}}(Y\theta'')$.

At last, since the constraint with the variable $X$ was removed in $D'$ and $C'$ normalised, we have:

- for all $Z \in \text{vars}(D') \setminus \{X\}, Z\{X \rightarrow C[\xi]\varphi\} \text{acc}(C') = Z\text{acc}(C') = Z\text{acc}(C''\Sigma)$
- $X\text{acc}(C'')\Sigma = u\Sigma = v\Sigma = X\{X \rightarrow C[\xi]\varphi\}\text{acc}(C')$

Thus, we deduce that $\text{acc}(C'')\Sigma = \{X \rightarrow C[\xi]\varphi\}\text{acc}(C')$. Hence, thanks to our inductive hypothesis (applied on $C''$ and $Y$), we have that $C[Y\theta']\varphi\text{acc}(C')\sigma'' = C[Y\theta']\varphi\text{acc}(C')$, and we deduce that $C[Y\theta']\varphi\text{acc}(C')\sigma' = C[Y\theta']\varphi\text{acc}(C')\sigma''\Sigma = C[Y\theta']\varphi\text{acc}(C'')\Sigma = C[Y\theta']\varphi\text{acc}(C')\{X \rightarrow C[\xi]\varphi\}\text{acc}(C') = C[Y\theta']\varphi\text{acc}(C') = C[Y\theta']\varphi\text{acc}(C')$.

Rule Dest($\xi, \ell \rightarrow r, i$): Let $Y \in \text{vars}^2(C)$. The rule described in Figure [73] tells us that:

- $Eq' = Eq' \land u \equiv u_1$.
- $Er' = Er' \land \text{so} \theta' = \theta''$.

Since $C'$ is normalised, it means that $\text{vars}(u) \cap \text{dom}(\sigma'') = \emptyset$. Furthermore, we know that all variable in $u_1$ are fresh variables, which means that $\text{mgu}(Eq' \land u \equiv u_1) = \sigma''\text{mgu}(u \equiv u_1)$. Let $\Sigma = \text{mgu}(u \equiv u_1)$. We have that $\sigma' = \sigma''\Sigma$.

Since $\theta' = \theta''$ and no deductable constraint is removed from $D(C'')$ to $D(C')$, we trivially have that $\text{param}_{\text{max}}(Y\theta'\Theta) = \text{param}_{\text{max}}(Y\theta')$ and so $\text{param}_{\text{max}}(Y\theta') \leq \text{param}_{\text{max}}(Y\theta)$.

The frame element $(f\{X_1, \ldots, X_n\}, i \vdash v)$ with $f \in \mathcal{F}_2$ was added in $\Phi'$, but since $C''$ is well-formed, we know that $C[Y\theta']\varphi\varphi' \in \mathcal{T}(\mathcal{F}_1 \cup \mathcal{F}_2 \cup \mathcal{A}) \cap X^2$, thus we deduce that $C[Y\theta']\varphi\varphi' = C[Y\theta']\varphi\varphi'$. At last, since only constraints with fresh variable $X_k$ were added in $D'$ and since $C'$ is normalised, we have that $\text{acc}(C')\{\text{dom}(\text{acc}(C'))\} = \text{acc}(C'')\Sigma$. With this last property, we can use the inductive hypothesis (on $C''$ and $Y$). We obtain that $C[Y\theta']\varphi\text{acc}(C'')\sigma'' = C[Y\theta']\varphi\text{acc}(C'')$, and so $C[Y\theta']\varphi\text{acc}(C'')\sigma' = C[Y\theta']\varphi\text{acc}(C'')\sigma''\Sigma = C[Y\theta']\varphi\text{acc}(C'')\Sigma = C[Y\theta']\varphi\text{acc}(C'')\Sigma = C[Y\theta']\varphi\text{acc}(C'')\Sigma$.

Since $C[Y\theta']\varphi\varphi' = C[Y\theta']\varphi'$, then for all $Z \in \text{vars}^2(C[Y\theta']\varphi'), Z \in \text{dom}(\text{acc}(C''))$. Moreover, it also implies that for all path $\in \text{st}(C[Y\theta']\varphi')$, path $\in \text{dom}(\text{acc}(C''))$. Hence, we deduce that $C[Y\theta']\varphi\text{acc}(C')\{\text{dom}(\text{acc}(C'))\} = C[Y\theta']\varphi\text{acc}(C')$ and so $C[Y\theta']\varphi\text{acc}(C')\sigma' = C[Y\theta']\varphi\text{acc}(C')$. 


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Rules Eq-left-right and Eq-left-left: Let $Y \in \text{vars}^2(\mathcal{C})$. The rule described in Figure C.1 tells us that $Eq' = Eq'' \land u_1 \not\preceq u_2$ and $Er' = Er''$, hence $\theta'' = \theta'$. Since $C''$ is normalised, we have that $(\text{vars}(u_1) \cup \text{vars}(u_2)) \cap \text{dom}(\sigma'') = \emptyset$ which means that $\text{mgu}(Eq'' \land u_1 \not\preceq u_2) = \sigma'' \text{mgu}(u_1 \not\preceq u_2)$. Let $\Sigma = \text{mgu}(u_1 \not\preceq u_2)$. We have that $\sigma' = \sigma'' \Sigma$.

Neither the frame nor the constraints changed between $C''$ and $C'$, which means that $C|\mathcal{Y}'|_{\Phi'} = C|Y \theta'|_{\Phi_{\mathcal{F}}}$. Since $C'$ is normalised, we also have $\text{acc}^1(C') = \text{acc}^1(C'')\Sigma$. By the inductive hypothesis (applied on $C''$ and $Y$), we have that $C|\mathcal{Y}'|_{\Phi_{\mathcal{F}}} \text{acc}^1(C)\sigma' = C|\mathcal{Y}'|_{\Phi_{\mathcal{F}}} \text{acc}^1(C'')\Sigma$ and so $C|\mathcal{Y}'|_{\Phi_{\mathcal{F}}} \text{acc}^1(C)\sigma' = C|\mathcal{Y}'|_{\Phi_{\mathcal{F}}} \text{acc}^1(C'')\Sigma = C|\mathcal{Y}'|_{\Phi_{\mathcal{F}}} \text{acc}^1(C')$.

Furthermore, since $\theta' = \theta''$ and no deducible constraint is removed from $D(C'')$ to $D(C')$, we trivially have that $\text{param}^C_{\text{max}}(Y\theta'') = \text{param}^C_{\text{max}}(Y\theta')$ and so $\text{param}^C_{\text{max}}(Y\theta') \leq \text{param}^C_{\text{max}}(Y\theta)$.

Rule Eq-right-right($X, \xi$): Let $Y \in \text{vars}^2(\mathcal{C})$. The rule described in Figure C.1 tells us that:

- $Eq' = Eq'' \land u \not\preceq v$.
- $Er' = Er'' \land X \preceq \xi$.
- $(X, i \vdash u) \in D(C'')$

where $\xi \in \mathcal{T}(\mathcal{F}, \text{dom}(\alpha))$ and $v = \xi \alpha$ with $\alpha = \{Y \rightarrow u \mid (Y, j \vdash u) \in D(C'') \land j \leq i \land Y \in S_2\}$. But $\text{acc}^1(C'')|_{\text{dom}(\alpha)} = \alpha$. Hence, we have that $v = \xi \text{acc}^1(C'')$.

Since $C''$ is normalised, it means that $(\text{vars}(u) \cup \text{vars}(v)) \cap \text{dom}(\sigma'') = \emptyset$ which means that $\text{mgu}(Eq'' \land u \not\preceq v) = \sigma'' \text{mgu}(u \not\preceq v)$. Let $\Sigma = \text{mgu}(u \not\preceq v)$. We have that $\sigma' = \sigma'' \Sigma$. For the same reason, we have that $\theta' = \theta'' \Theta$ where $\Theta = \{X \rightarrow \xi\}$. No element has been added into the frame $C'$ (w.r.t. $C''$). Hence, we have that $C|\mathcal{Y}'|_{\Phi_{\mathcal{F}}} = C|\mathcal{Y}'|_{\Phi_{\mathcal{F}}} = C|\mathcal{Y}'|_{\Phi_{\mathcal{F}}} \Theta \Phi_{\mathcal{F}}$. By Lemma C.9, $C''$ well formed and $\xi \in \mathcal{T}(\mathcal{F}, X^2)$, we deduce that $C|\mathcal{Y}'|_{\Phi_{\mathcal{F}}} \text{acc}^1(C')$. Since for all $Z \in \text{vars}^2(\xi)$, $\text{param}^C_{\text{max}}(Z) \leq i = \text{param}^C_{\text{max}}(X)$ and $\Theta = \{X \rightarrow \xi\}$, we deduce that $\text{param}^C_{\text{max}}(X \Theta) \leq \text{param}^C_{\text{max}}(X)$. Therefore $\text{param}^C_{\text{max}}(Y\theta') \leq \text{param}^C_{\text{max}}(Y\theta'')$. Thus we deduce that $\text{param}^C_{\text{max}}(Y\theta') \leq \text{param}^C_{\text{max}}(Y\theta'') \leq \text{param}^C_{\text{max}}(Y\theta)$.

At last, since the constraint with the variable $X$ was removed in $D'$ and $C'$ normalised, we have:

- for all $Z \in \text{vars}(D'') \setminus \{X\}$, $Z \text{acc}^1(C') = Z \text{acc}^1(C') = Z \text{acc}^1(C'')\Sigma$
- $X \text{acc}^1(C'') = u\Sigma = v\Sigma = X \Theta \text{acc}^1(C'')\Sigma = X \Theta \text{acc}^1(C')$

Thus, we deduce that $\text{acc}^1(C'')\Sigma = \Theta \text{acc}^1(C')$. Hence, thanks to our inductive hypothesis (applied on $C'$ and $Y$), we have that $C|\mathcal{Y}'|_{\Phi_{\mathcal{F}}} \text{acc}^1(C')\sigma'' = C|\mathcal{Y}'|_{\Phi_{\mathcal{F}}} \text{acc}^1(C'')\Sigma$. From this, we deduce that $C|\mathcal{Y}'|_{\Phi_{\mathcal{F}}} \text{acc}^1(C)\sigma' = C|\mathcal{Y}'|_{\Phi_{\mathcal{F}}} \text{acc}^1(C'')\Sigma = C|\mathcal{Y}'|_{\Phi_{\mathcal{F}}} \Theta \text{acc}^1(C') = C|\mathcal{Y}'|_{\Phi_{\mathcal{F}}} \text{acc}^1(C')$. Hence we conclude that $C|\mathcal{Y}'|_{\Phi_{\mathcal{F}}} \text{acc}^1(C)\sigma' = C|\mathcal{Y}'|_{\Phi_{\mathcal{F}}} \text{acc}^1(C')$.

Rule DED-ST: Let $Y \in \text{vars}^2(\mathcal{C})$. The rule described in Figure C.1 tells us that:

- $Eq' = Eq'' \land u \not\preceq f(x_1, \ldots, x_n)$.
- $Er' = Er''$ and so $\theta' = \theta''$.

Since $C''$ is normalised, this means that $\text{vars}(u) \cap \text{dom}(\sigma'') = \emptyset$. Furthermore, we know that the variables $x_i$ are fresh variables, which means that $\text{mgu}(Eq'' \land u \not\preceq f(x_1, \ldots, x_n)) = \sigma'' \text{mgu}(u \not\preceq f(x_1, \ldots, x_n))$. Let $\Sigma = \text{mgu}(u \not\preceq f(x_1, \ldots, x_n))$. We have that $\sigma' = \sigma'' \Sigma$.

Since $\theta' = \theta''$ and no deducible constraint is removed from $D(C'')$ to $D(C')$, we trivially have that $\text{param}^C_{\text{max}}(Y\theta'') = \text{param}^C_{\text{max}}(Y\theta')$ and so $\text{param}^C_{\text{max}}(Y\theta') \leq \text{param}^C_{\text{max}}(Y\theta)$.

No element has been added into the frame $C'$ (w.r.t. $C''$). Hence, we have that $C|\mathcal{Y}'|_{\Phi_{\mathcal{F}}} = C|\mathcal{Y}'|_{\Phi_{\mathcal{F}}} = C|\mathcal{Y}'|_{\Phi_{\mathcal{F}}}.}$
At last, since only constants with fresh variable \( X_i \) were added in \( D' \) and since \( C' \) normalised, we have that \( \text{acc}^1(C')_{|\text{dom}((\text{acc}(C')))} = \text{acc}^1(C'')_{|\Sigma} \). With this last property, we can use the inductive hypothesis (applied on \( C'' \) and \( Y' \)). We obtain that \( C[Y\theta]\phi \text{acc}^1(C)\sigma' = C[Y\theta]^{|\phi} \phi \text{acc}^1(C'') \), and so \( C[Y\theta]\phi \text{acc}^1(C)\sigma'' = C[Y\theta]^{|\phi} \phi \text{acc}^1(C') \). Thus, if \( \sigma = \text{mgu}(C'' \cap \Sigma) \), we can conclude that \( u = \text{mu}(C') \).

**Proof.** According to the rules described in Figure 7.1 and 7.2 and the fact that \( u \) and \( \sigma \) have the same support of the rule is \( \Phi \) and \( \Phi' \), hence, we deduce that \( C[Y\theta]^{|\phi} \phi \text{acc}^1(C') \). Moreover, since \( \sigma = \text{mgu}(C'') \), we can conclude that \( u = \text{mu}(C') \).

**Lemma C.12.** Let \( C \) and \( C' \) be two normalised well-formed constraint systems such that \( C \to^* C' \). Let \( \sigma = \text{mgu}(\text{Eq}(C')) \), and \( (\xi, i \triangleright u) \in \Phi \). There exist \( (\xi', i \triangleright u') \in \Phi' \) such that \( \text{path}(\xi) = \text{path}(\xi') \) and \( u' = u \sigma \).

**Proof.** According to the rules described in Figure 7.1 and 7.2 and the fact that \( C \) is well-formed, the path \( \text{path}(\xi) \) of a frame element \( (\xi, i \triangleright u) \) is never modified. The only operation that affects this frame element is the normalisation of a constraint system, i.e., the most general unifier of \( \Phi \) is applied on \( \Phi \) (idem for \( E\rho \)). Thus, if \( \sigma = \text{mgu}(\text{Eq}(C')) \), we can conclude that \( u = u \sigma \).

**Lemma C.13.** Let \( C \) be a normalised well-formed constraint system. Let \( C_1 \) and \( C_2 \) be two normalised well-formed constraint systems such that \( C \to^* C_1 \) and \( C \to^* C_2 \). Let \( \rho \) be a variable renaming from \( X^1 \) to \( X^2 \). Let \( ax \in A X \) such that \( \{ ax, i \triangleright u \} \in \Phi_1 \) and \( \{ ax, i \triangleright u \} \in \Phi_2 \). Let \( w \in F_d \). \( (\xi_1, i_1 \triangleright v_1) \in \Phi_1 \) and \( (\xi_2, i_2 \triangleright v_2) \in \Phi_2 \) such that \( \text{path}(\xi_1) = \text{path}(\xi_2) = w \cdot ax \). We have:

\[
\text{if } u_1 \rho = u_2 \text{ then } v_1 \rho = v_2
\]

**Proof.** We prove the result by induction on \(|w|\):

**Base case** \(|w| = 0\): In such a case, then \( \xi_1 = \xi_2 = ax \). Thus by Property 1 of a well-formed constraint system, we know that \( u_1 = v_1 \) and \( u_2 = v_2 \) and so the result trivially holds.

**Inductive step** \(|w| > 0\): Assume that \( w = f \cdot u' \) and \( u_1 \rho = u_2 \). By Property 2 of a well-formed constraint system, we know that there exists \( (\xi'_1, i'_1 \triangleright v'_1) \in \Phi_1 \) and \( (\xi'_2, i'_2 \triangleright v'_2) \in \Phi_2 \) such that \( \text{path}(\xi'_1) = \text{path}(\xi'_2) = w' \cdot ax \). Thus by our inductive hypothesis, we know that \( v'_1 \rho = v'_2 \). Furthermore, by definition of the rule Dest (the only rule that can add an element into the frame), we know that there exists a position \( p \) (actually for our rewriting rules \( p = 1 \)) such that \( v_1 = v'_1|_p \) and \( v_2 = v'_2|_p \). Hence, we have that \( v_1 \rho = (v'_1|_p) = (v'_1)\rho = (v'_2|_p) = v_2 \).

**C.4.2 Preservation of the strategy invariants by the rules**

**Lemma C.14.** Let \( C \) be a well formed constraint system satisfying InvVarConstraint\((s)\). Let \( R(\bar{p}) \) be an occurrence of the rule Cons, or Axiom or Eq-RIGHT-RIGHT with support \( s' \leq s \). Let \( C_1, C_2 \) be the two constraint systems obtained by applying \( R(\bar{p}) \) on \( C \). We have that for all \( i \in \{1, 2\} \), \( C_i \) satisfies the invariant InvVarConstraint\((s)\).

**Proof.** According to the definitions of the three rules, \( C_2 \) only differs from \( C \) by an addition of an inequality on recipes. Thus, we trivially deduce that \( C_2 \) satisfies InvVarConstraint\((s)\). We prove the result for \( C_1 \) by case analysis on the rule applied:

**Rule Cons\((X, f)\):** Since the support of the rule is \( s' \), then there exists \( (X, s' \triangleright u) \in D(C) \). Moreover, \( C \) satisfies InvVarConstraint\((s)\) hence, we deduce \( u \in X^1 \). But \( D(C_1) = D(C) \cap \{ X, s' \triangleright u \} \cup \{ X_1, s' \triangleright x_1; \ldots; x_n, s' \triangleright x_n \sigma \} \) where \( \sigma = \text{mgu}(u \triangleright f(x_1, \ldots, x_n)) \) and \( x_1, \ldots, x_n \) are fresh variables. Since \( s' \leq s \) then \( C \) satisfies InvVarConstraint\((s)\) also implies that \( X \in S_2 \). Thus, by definition of the rule Cons, \( X_1, \ldots, X_n \in S_2 \).

Moreover, since \( u \in X^1 \), we deduce that \( \sigma = \{ u \mapsto f(x_1, \ldots, x_n) \} \). Hence for all \( i \in \{1, \ldots, n\} \), \( x_i \sigma = x_i \). Moreover, since \( C \) satisfies InvVarConstraint\((s)\), we deduce that for all \( (Y, j \triangleright y) \in D \)
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such that $Y \neq 1$, $y = Y$. Thus, thanks to $x_1, \ldots, x_n$ and $X_1, \ldots, X_n$ being fresh, the result holds.

Rule Axiom($X, \text{path}$): Since the support of the rule is $s'$, then there exists $(X, s' \overset{?}{\rightarrow} u) \in D(C)$ and $(\xi, j \overset{?}{\rightarrow} v) \in \Phi(C)$ with $j \leq s'$. Moreover, $C$ satisfies InvVarConstraint($s$) hence, we deduce $u \in \mathcal{X}$.

But $D(C_1) = D(C) \setminus \{X, s' \overset{?}{\rightarrow} w\}$ where $s = \mu (u \overset{?}{=} v)$. Thus the first property is trivially satisfied.

Moreover, $u \in \mathcal{X}$ implies that either (a) $s \sigma = \{u \mapsto v\}$ or (b) $v \in \mathcal{X}$ and $\sigma = \{v \mapsto u\}$. In case (a), since $C$ satisfies InvVarConstraint($s$), we deduce that for all $(Z, k \overset{?}{\rightarrow} z) \in D(C)$ and $k \leq s$, if $Z \neq X$ then $(Z, k \overset{?}{\rightarrow} z) \in D(C_1)$ hence the result holds. In case (b), $v \in \mathcal{X}$ implies, by the origination property, that there exists $(Y, k \overset{?}{\rightarrow} (v')) \in D(C)$ such that $k < j$ and $v \in \text{vars}(v')$. But $C$ satisfies InvVarConstraint($s$) thus $v = v'$. Hence for all $(Z, \ell_1 \overset{?}{\rightarrow} z_1) \in D(C_1)$, if $\ell_1 \leq s$ then either $Z_1 \neq Y$ and so $(Z_1, \ell_1 \overset{?}{\rightarrow} z_1) \in D(C)$, or $Z_1 = (Y$ and $v' = u)$. By relying on $C$ satisfying InvVarConstraint($s$), the result holds.

Rule Eq-right-right($X, \xi$): Proof similar to the rule Axiom.

Lemma C.15. Let $C$ be a well formed constraint system satisfying InvUntouched($s$). Let $R(\bar{p})$ be an occurrence of a rule with support $s' \leq s$. Let $C_1, C_2$ be the two constraint systems obtained by applying $R(\bar{p})$ on $C$. We have that for all $i \in \{1, 2\}$, $\hat{C}_i$ satisfies the invariant InvUntouched($s$).

Proof. The rule Dest is the only one that add frame element. But the support of the rule being $s'$, Dest can only introduce frame element of the form $(\xi, s' \overset{?}{\rightarrow} w)$. Thus since $s' \leq s$, we deduce deduce that for all $(\xi, k \overset{?}{\rightarrow} u) \in \Phi(C_1)$ (resp. $\Phi(C_2)$), if $s < k$ then $\xi = ax_k$.

Similarly, the only rules that add elements in $\text{Er}(C)$ are CONS, AXIOM and Eq-right-right.

In case of CONS and Eq-right-right, the result trivially holds by definition of the rules and the fact that $s' \leq s$. In case of application of the rule Axiom($X, \text{path}$), by definition, we know that there exists $(X, s' \overset{?}{\rightarrow} u) \in D(C)$ and $(\xi, k \overset{?}{\rightarrow} v) \in \Phi(C)$ with $k \leq s'$. But since $C$ is well formed (Definition 8.2 item 3), we know that param$_{\text{max}}^C(\xi) \leq k$ which implies that for all $Y \in \text{vars}(\xi)$, $(Y, \ell \overset{?}{\rightarrow} w) \in D(C)$ implies that $\ell \leq k$. Hence any new (in)equations in $\text{Er}$ only contain variables $Y$ such that param$_{\text{max}}^C(\xi) \leq s' \leq s$. Hence the result holds.

Lemma C.16. Let $C$ be a well formed constraint system satisfying InvNoUse($s$) (resp. InvDest($s$), InvVarFrame($s$) and InvDesub($s$)). Let $R(\bar{p})$ be an occurrence of a rule different from Dest, or the rule Dest with support $s' > s$. Let $C_1, C_2$ be the two constraint systems obtained by applying $R(\bar{p})$ on $C$. We have that for all $i \in \{1, 2\}$, $\hat{C}_i$ satisfies the invariant InvNoUse($s$) (resp. InvDest($s$), InvVarFrame($s$) and InvDesub($s$)).

Proof. We prove the different invariant by case analysis on the rule applied.

Rule CONS($X, f$): The rule CONS only adds the inequation $\text{root}(X) \neq f$ on $\text{Er}(C_2)$. Thus, $\hat{C}_2$ trivially satisfies all the wanted invariants.

On the other hand, we have that $\Phi(C_1) = \Phi(C) \cup \sigma$, NoUse($C_1$) = NoUse($C$) $\cup \sigma$, ND($C_1$) = ND($C$) $\cup \sigma$ and $D(C_1) = D(C) \setminus \{X, i \overset{?}{\rightarrow} x_1; \ldots; X_n, i \overset{?}{\rightarrow} x_n\}$ where $\sigma = \mu (t \overset{?}{=} f(x_1, \ldots, x_n))$ and $\theta = \mu (X \overline{=} f(X_1, \ldots, X_n))$. We now prove the different invariants one by one.

Let $(\xi, p \overset{?}{\rightarrow} v) \in \Phi(C_1)$ such that $p \leq s$. Since $\Phi(C_1) = \Phi(C) \cup \sigma$, there exists $\xi'$ and $v'$ such that $(\xi', p \overset{?}{\rightarrow} v') \in \Phi(C)$, $\xi' = \xi$ and $v' \sigma = v$:

- InvNoUse($s$): Assume that $v \in \mathcal{X}$. In such a case, $v' \sigma = v$ implies $v' \in \mathcal{X}$. But $C$ satisfies InvNoUse($s$) hence $(\xi', p \overset{?}{\rightarrow} z) \in \text{NoUse}(C)$. With NoUse($C_1$) = NoUse($C$) $\cup \sigma$, we deduce that $(\xi, p \overset{?}{\rightarrow} v) \in \text{NoUse}(C_1)$ thus the result holds.
• InvVarFrame(s): Let \( Y \in \text{vars}^2(\xi) \). In such a case, \( \xi'\theta = \xi \) implies that there exists \( Y' \in \text{vars}^2(\xi') \) such that \( Y \in \text{vars}^2(Y'\theta) \). But \( C \) satisfies InvVarFrame(s) implies that there exists \( q < p \) and \( u \in T(\mathcal{F}_c, \mathcal{N} \cup \mathcal{X}^1) \) such that \( (Y', q \vdash u) \in D(C) \). If \( Y' \neq X \) then \( Y' = Y \) and so \( (Y, q \vdash u\sigma) \in D(C) \) then the result holds. If \( Y' = X \) then \( Y \in \{X_1, \ldots, X_n\} \) and \( s' = q \).

But for all \( k \in \{1, \ldots, n\} \), we have \( (X_k, s' \vdash x_k\sigma) \in D(C_1) \). With \( s' = q < p \) then the result holds.

• InvDest(s): The result is direct from the definition of the invariants.

• InvDedsub: Assume that \( |\Phi(C)| = m \). Since \( C \) satisfies the invariant, then for all \( g \in \mathcal{F}_c \), \((\xi', p, \sigma) \in \text{EqUse}(C)\) implies that either (a) there exists \( Y_1, \ldots, Y_k \in \text{vars}^2(C) \) such that for all \( i \in \{1, \ldots, k\} \), \( \text{param}^C_{\max}(Y_i \text{mgu}(\text{Er}(C))) \leq s \) and \( C[\text{g}(Y_1, \ldots, Y_m) \text{mgu}(\text{Er}(C))] \sigma = v' \), or else (b) \( ND(C) \equiv \forall \exists. v. \sigma \neq g(x_1, \ldots, x_n) \lor m \not\vdash x_1 \lor \ldots \lor m \not\vdash x_k \) where \( x_1, \ldots, x_k \) are fresh variables.

In case (a), since \( \text{mgu}(\text{Er}(C_1)) = \text{mgu}(\text{Er}(C))\theta \) and \( f(X_1, \ldots, X_n) = C[f(X_1, \ldots, X_n)] \in T(\mathcal{F}_c, \mathcal{N}^2) \) then thanks to Lemma C.17 we deduce that \( C[\text{g}(Y_1, \ldots, Y_m) \text{mgu}(\text{Er}(C))] \sigma = \text{Zacc}^C(C) \sigma = Z\theta\text{acc}^C(C) \). Hence the result holds.

In case (b), since \( ND(C_1) = ND(C)\sigma \) then \( ND(C_1) \equiv \forall \exists. v \not\equiv g(x_1, \ldots, x_n) \lor m \not\vdash x_1 \lor \ldots \lor m \not\vdash x_k \). Hence the result holds.

Rule Dest(\( \xi, \ell \rightarrow r, s' \)) and \( s' > s \): Since the rule only adds a frame element \((\xi, s' \rightarrow w)\) for some \( \xi, w \) and applies a substitution on first order term, then the result holds by relying on \( C \) verifying each invariant respectively.

The proofs of all the others rules are similar to the rule Cons. Note that for the rule Ded-St(\( \xi, f \)), if \( C \) satisfies the invariant InvDedsub, then it implies that the application of the rule Ded-St(\( \xi, f \)) was in fact useless hence according to the strategy, such application could not have happen. Hence the result holds.

Lemma C.17. Let \( M \) be a well-formed matrix of constraint systems satisfying InvMatrix(s). Let \( R(p) \) be an occurrence of a rule different from Dest and Eq-Left-Right, or Dest with support \( s' > s \), or Eq-Left-Right with support \( s' > s \). Let \( M_1, M_2 \) be the two matrix of constraint systems obtained by applying \( R(p) \) on \( M \) (if \( R(p) \) is an internal rule, only \( M_1 \) exists). We have that for all \( i \in \{1, 2\} \), \( M_i \) satisfies the invariant InvMatrix(s).

Proof. Note that the invariant InvMatrix(s) mainly focus on the path of the frames. But thanks to \( M \) being well-formed we have that for all \( C \in T(\mathcal{F}_c, \mathcal{N}) \), \( C \) is well-formed. Hence by Definition S.22 item i, we know that all path of the frame element are closed. Hence relying on Lemma C.18 we trivially deduce that the result holds for the rule Cons, EqSum, Eq-Right, Eq-Left, Eq-Left-Right and Ded-St. Hence it remains to prove that the result holds for Eq-Left-Right with support \( s' > s \) and Dest with support \( s' > s \). But in both cases, the only possible modifications on the frames or the sets NoUse only occurs on frame elements with support strictly bigger than \( s \). Hence the result holds.

Lemma C.18. Let \( C \) be a well formed constraint system. Let \( s \in \mathbb{N} \), if \( C \) satisfies InvDedsubs (resp. InvVarFrame(s), InvNoUse(s), InvDest(s) and InvVarConstraint(s)) then for all \( s' \leq s \), \( C \) satisfies InvDedsubs\( s' \) (resp. InvVarFrame\( s' \), InvNoUse\( s' \), InvDest\( s' \) and InvVarConstraint\( s' \)).

If \( C \) satisfies InvUntouched\( s \) then for all \( s' \geq s \), \( C \) satisfies InvUntouched\( s' \).

Proof. Direct from the definition of the invariants.
Lemma C.19. Let $M$ be a well formed constraint system satisfying InvGeneral. Let $R(p)$ be an occurrence of a rule different from Dest and Eq-Left-Right. Let $M_1, M_2$ be the two matrices of constraint systems obtained by applying $R(p)$ on $M$ (if $R(p)$ is an internal rule, only $M_1$ exists). We have that for all $i \in \{1, 2\}$, $M_i$ satisfies the invariant InvGeneral.

Let $R(p)$ be a occurrence of the rule Dest or Eq-Left-Right. Let $M'$ be the matrix of constraint systems obtained by applying $R(p)$ on $M$. We have that $M'$ satisfies Properties 5, 6 and 7 of the invariant InvGeneral.

C.4.3 Invariants specific to different steps and phases of the strategy

In this subsection, we will show several invariants that are specific to each phase and step of the strategy. In fact, the invariants are interconnected. Intuitively, we have to define an invariant for each step and also an invariant for the link between each step, i.e. we have to show that the invariant of the end of a step corresponds to the invariant at the beginning of the next step.

Let $(M_0, M'_0)$ be a pair of matrices of constraint systems. We say that a pair of matrices of constraint systems $(M_1, M'_1)$ is obtained from $(M_0, M'_0)$ by applying Step $i$ of Phase $j$ of the strategy with parameters $s$ (and $k$), for some $i \in \{a, b, c, d, e\}$, $j \in \{1, 2\}$ if $(M_0, M'_0) \rightarrow^*(M_1, M'_1)$ and the rules applied follow exactly the description of Step $i$ of Phase $j$ with parameters $s$ (and $k$) given in Section 7.3.

Moreover, we will say that $(M_1, M'_1)$ is obtained from $(M_0, M'_0)$ at the end of Step $i$ of Phase $j$ of the strategy with parameters $s$ (and $k$) if $(M_0, M'_0) \rightarrow^*(M_i, M'_i)$, the rules applied follow exactly the description of Step $i$ of Phase $j$ with parameters $s$ (and $k$) given in Section 7.3 and no rule following the description of Step $i$ of Phase $j$ with parameters $s$ (and $k$) is applicable on $(M_1, M'_1)$.

C.4.3.1 Invariants of Phase 1

Property C.1. We say that a pair of matrices of constraint systems $(M, M')$ satisfy PP1($s$) if $M$ and $M'$ have the same structure, satisfy InvMatrix($s$) and InvGeneral, and for all constraint system $C$ in $M$ or $M'$, $C$ satisfies the invariants InvVarConstraint($s$), InvVarFrame($s$), InvDest($s$), InvNoUse($s$) and InvUntouched($s$).

Moreover, if $\Phi$ is a frame of a constraint system in $M$ or $M'$ and $s = [\Phi]$ then $(M, M')$ satisfies also InvDedsub.

Lemma C.20. Let $(M, M')$ be a pair of row matrices of initial constraint systems having the same structure. $(M, M')$ satisfies PP1($0$).

Proof. We start by proving that $M$ and $M'$ satisfy InvGeneral (Definition 8.1). First of all, Items 5 and 7 trivially hold since $M$ and $M'$ are row matrices, i.e. there is only one constraint system in each column of $M$ and $M'$. Furthermore, by definition of an initial constraint system, we know that for all $C$ different from $\perp$, for all $(\xi, i \vdash u) \in \Phi(C)$, $\xi = ax_i$. Hence Item 5 is trivially true. More over, for all $\xi' \in \Pi_0$ with $\text{root}(\xi') \notin F_c$, if $\text{path}(\xi') = \text{path}(\xi\theta)$ then $\text{path}(\xi\theta) = \text{path}(ax_i\theta) = \text{path}(ax_i)$. Hence, $\text{path}(\xi') = ax_i$ implies $ax_i = \xi'$ and so Item 7 holds. Since $\xi = ax_i$, then Item 4 also holds. At last, $C$ is an initial constraint system also implies NoUse($C$) = $\emptyset$. Hence Item 6 holds.

The invariants InvMatrix($s$), InvVarConstraint($0$), InvVarFrame($0$), InvDest($0$), InvNoUse($0$) are trivially satisfied since their no deducible constraint $(X, i \vdash u)$ or frame element $(\xi, i \vdash u)$ such that $i \leq 0$.

It remains to prove that $(M, M')$ satisfies the invariant InvUntouched($0$). We already know that for all constraint system $C$ in $M$ or $M'$. If $C$ is different from $\perp$ then for all $(\xi, i \vdash u) \in \Phi(C)$, $\xi = ax_i$. Furthermore we know that $Er(C) = \top$. At last, by definition of an initial constraint system $\text{vars}^2(D(C)) \subseteq S_2(C)$. Hence $C$ satisfies the invariant InvUntouched($0$).
C.4.3.2 Invariants of Phase 1, Step a

Property C.2. We say that a pair of matrices of constraint systems \((M, M')\) satisfy PP1Sa(s) if \(M\) and \(M'\) have the same structure, satisfy InvMatrix(s−1) and InvGeneral, and for all constraint system \(C\) in \(M\) or \(M'\), if \(C \not\perp\) then

- \(C\) invariants InvDest(s−1), InvVarFrame(s−1), InvNoUse(s−1), InvUntouched(s); and

- for all \((\xi, s \triangleright u) \in \Phi(C)\) with \(u \in \mathcal{X}^1\), there exists \(X \in S_2(C)\) and \(\ell < s\) such that \((X, \ell \triangleright u) \in D(C); and

- for all \((\xi, s \triangleright u) \in \Phi(C)\), either \(\xi \in \mathcal{AX}\) or there exists \(X_2, \ldots, X_n \in \mathcal{X}^2 \triangleleft S_2(C)\), \(f \in \mathcal{F}_d\) and \((\xi', p \triangleright v) \in \Phi(C)\) such that \(\xi = f(\xi', X_2, \ldots, X_n)\) and \(p \leq s\); and

- for all \((X, i \triangleright u) \in D(C)\), for all \(f \in \mathcal{F}_e\), for all \((\xi, j \triangleright v) \in \Phi(C)\), \(\text{Er} (C) \not\subseteq X \not\subseteq \xi\) and \(\text{Er} (C) \not\subseteq \text{root}(X) \not\subseteq f; and

- for all \((X, i \triangleright u) \in D(C)\), \(X \in S_2(C)\) implies \(i = s\) and there exists a unique frame element \((g(\xi_1, \ldots, \xi_n), j \triangleright v) \in \Phi(C)\) and \(k \in \{2, \ldots, n\}\) such that \(j = s\) and \(\xi_k = X\).

Lemma C.21. Let \((M, M')\) be a pair of matrices of constraint systems satisfies PP1(s−1). For all pair of matrices of constraint systems \((M_1, M'_1)\) obtained during Step a of the first phase on \((M, M')\) with support \(s\), \((M_1, M'_1)\) satisfies PP1Sa(s).

Proof. Let \((M_1, M'_1)\) be a pair of matrices of constraint systems obtained during Step a of the first phase on \((M, M')\). We show by induction on the size \(N\) of the branch of \((M_1, M'_1)\) that \((M_1, M'_1)\) satisfies the wanted properties. plus a new one : for all \(C\) in \((M_1, M'_1)\),

6. for all \(x \in \text{vars}\{u \mid \{X, i \triangleright u \wedge i < s\}\}\), if for all \((X, i \triangleright u) \in D(C)\) such that \(X \in S_2(C), i < s\) implies \(x \neq u\), then for all \(u \in \{v \mid (\xi, i \triangleright v) \in \Phi(C)\) or \((X, i \triangleright v) \in D(C)\}\), for all position \(p\), if \(u|_p = x\) then there exists \(p'\) such that \(p = p' \cdot 1\) and \(u|_{p'} = \text{pk}(x)\).

This property stated that when a variable is never a right hand term of a deductible constraint, then this variable is always used under the constructor pk.

Base case \(N = 0\): In such a case we have that \((M_1, M'_1) = (M, M')\). Hence, we trivially have that \((M_1, M'_1)\) satisfies InvMatrix(s−1) and InvGeneral. Furthermore, we also have that for all \(C\) in \(M_1\) and \(M'_1\), \(C\) satisfies the invariant InvVarFrame(s−1) and InvNoUse(s−1). Furthermore, thanks to Lemma C.13, we also have that \(C\) satisfies InvUntouched(s). We know prove the other properties:

6. We know that \(C\) satisfies InvVarConstraint(s−1) hence for all \(x \in \text{vars}\{u \mid \{X, i \triangleright u \wedge i < s\}\}\), there exists \((X, i \triangleright u) \in D(C)\) such that \(x = u\) and \(X \in S_2(C)\). Hence the property holds.

3. for all \((\xi, s \triangleright x) \in \Phi(C)\), thanks to the property of origination of a constraint system, we know that there exists \((X, \ell \triangleright u) \in D(C)\) such that \(\ell < s\) and \(x \in \text{vars}\{u\}\). But \(C\) satisfies InvVarConstraint(s−1) which means that \(u \in \mathcal{X}^1\) and so \(x = u\).

4. Since \(C\) satisfies InvUntouched(s−1), we know that for all \((\xi, s \triangleright u) \in \Phi(C)\), \(\xi = ax \in \mathcal{AX}\).

5. Since \(C\) satisfies InvUntouched(s−1), we know that for all \((X, k \triangleright u) \in D(C)\), if \(k \geq s\) then \(X \not\in \text{vars}\{\text{Er}(C)\}\). Hence for all \(f \in \mathcal{F}_e\), for all recipe \(\xi\) on a frame element of \(\Phi(C)\), we have that \(\text{Er}(C) \not\subseteq X\) and \(\text{Er}(C) \not\subseteq \text{root}(X)\).
C.4. STRATEGY INVARIANTS

Inductive step \( N > 0 \): In such a case, there exists a couple of matrices of constraint systems \((M_2, M'_2)\) such that \((M_2, M'_2)\) is the father of \((M_1, M'_1)\). By our inductive hypothesis, we know that \((M_2, M'_2)\) satisfies the properties stated by the lemma. For all \( C \) in \((M_1, M'_1)\), there exists a constraint system \( C' \) in \((M_2, M'_2)\) such that \( C' \rightarrow C \).

1. We know that \( M_2 \) and \( M'_2 \) satisfy \( \text{InvMatrix}(s - 1) \), \( M_2 \rightarrow M_1 \), \( M'_2 \rightarrow M_1 \). Since the rule applied are of support \( s \), then thanks to Lemma [C.17] we have that \( M_1 \) and \( M'_1 \) satisfy \( \text{InvMatrix}(s - 1) \).

Thanks to Lemma [C.19] we already know that Property 3 of \( \text{InvGeneral} \) is satisfied. Thus, it remains to prove the others properties. Let \((\sigma, \theta) \in \text{Sol}(C)\) and let \((\xi, i > u) \in \Phi(C)\). Thanks to Lemma [C.5] we know that there exists \((\sigma', \theta') \in \text{Sol}(C')\) such that \( \theta' = \theta|_{\text{vars}(C')} \) and \( \sigma' = \sigma|_{\text{vars}(C')} \).

We do a case analysis on the rule applied

- Case \( \text{Eq-Leftright} \): In such a case, we have that \( Er(C') = Er(C) \) and if \( \Sigma = \text{mgu}(Eq(C)) \), we have that \( \Phi(C) = \Phi(C')\Sigma \) and \( D(C) = D(C')\Sigma \). Hence we have \( \theta = \theta' \). Thus since, by hypothesis, \( C' \) satisfies the Property 1 of \( \text{InvGeneral} \), we have \( \text{param}(\xi'\theta') \subseteq \{ax_1, \ldots, ax_i\} \) and so \( \text{param}(\xi\theta) \subseteq \{ax_1, \ldots, ax_i\} \).

Let \( \xi' \in \Pi_n \) with root \( (\xi') \notin \mathcal{F}_n \), path \( \xi' \) = path(\( \xi\theta \)) and \( \xi' = \Phi(C)\sigma\Sigma \) \( \subseteq \mathcal{F}_n \). Since \( \theta = \theta' \), we have that \( \text{path}(\xi') = \text{path}(\xi') \). Furthermore, \( \sigma' = \sigma|_{\text{vars}(C')} \) implies that \( \xi' = \Phi(C')\sigma'\Sigma \) \( \subseteq \mathcal{F}_n \). Hence by hypothesis, since \( C \) satisfies Property 2 of \( \text{InvGeneral} \), we have that \( \text{param}(\xi'\theta) \subseteq \{ax_1, a_{x_i, \ldots, a_{x_j}}\} \).

- Case \( \text{Dest} \) when the guess is negative: The proof is similar to the case \( \text{Eq-Leftright} \).

- Case \( \text{Dest} \): Otherwise, we have that \( Er(C') = Er(C) \) and if \( \Sigma = \text{mgu}(Eq(C)) \), we have that \( \Phi(C) = \Phi(C')\Sigma \) and \( D(C) = D(C')\Sigma \) \( \subseteq \mathcal{F}_n \). Hence, \( j < s \) and \( \sigma' \notin \text{ND}(C') \) implies that there exists no recipe \( (\xi_2, \ldots, \xi_n) \in \Pi_n \) such that \( \text{param}(\xi_2, \ldots, \xi_n) \subseteq \{ax_1, \ldots, ax_s\} \) such that \( g(\xi_2, \ldots, \xi_n|\Phi(C')\sigma') \notin \mathcal{F}_n \). But we know that \( g(\xi'\theta, \xi_2, \ldots, \xi_n|\Phi(C')\sigma') \notin \mathcal{F}_n \). Hence by hypothesis on \( C' \), we can conclude that there exists \( k \in \{2, \ldots, n\} \) such that \( ax_s \in st(x_k) \) and so \( ax_s \in st(\xi') \). Thus, \( C \) satisfies Properties 1 and 2 of \( \text{InvGeneral} \).

It remains to prove Property 3 and 4 of the invariant \( \text{InvGeneral} \). Let \( X \in \text{vars}(C) \) such that \( \text{path}(\xi) \in \text{st}(C[X \text{mgu}(Er(C))]_{\phi}) \). We already know that the rule \( \text{Eq-Leftright} \) and \( \text{Dest} \) do not modify \( Er \). Furthermore, all new second order variables introduced by the \( \text{Dest} \) are not instantiated during Step a. Hence if \( C'' \) is the constraint system in \( M \) or \( M' \) such that \( C'' \rightarrow^* C \), then we have that \( \text{path}(\xi) \in \text{st}(C[X \text{mgu}(Er(C))]_{\phi}) \) implies that \( X \in \text{vars}(C'') \) and \( \text{path}(\xi) \in \text{st}(C[X \text{mgu}(Er(C''))]_{\phi}) \). Furthermore, since \( C'' \) satisfies \( \text{InvUntouched}(s - 1) \), we can deduce that \( i < s \). Hence, by hypothesis on \( C'' \), we have that \( (\xi, i > u) \notin \text{NoUse}(C'') \) where \( u'\text{mgu}(Eq(C'')) = u \). At last, since during Step a with support \( s \), \( \text{Eq-Leftright} \) only add frame element of the form \( (\xi', s > v) \) and \( i < s \), we can conclude that \( (\xi, i > u) \notin \text{NoUse}(C) \). Hence \( C \) satisfies Property 3 of \( \text{InvGeneral} \).

Assume now that \((\xi, i > u) \notin \text{NoUse}(C)\) and let \( \xi' \in \text{st}(\xi) \) such that \( (\xi', j > v) \in \Phi(C) \cap \text{NoUse}(C) \). Since \( \text{Eq-Leftright} \) only add frame element of the form \( (\xi, s > w) \) and \( C' \) satisfies Property 4 of \( \text{InvGeneral} \), we can deduce that \( i = j = s \). Thus, the only way this case occurs is if \( \text{Dest} \) was applied on a frame element which belong to \( \text{NoUse} \) or if
APPENDIX C. DECISION PROCEDURE OF TRACE EQUIVALENCE

EQ-LEFT-RIGHT was applied on $(\xi', j \triangleright v)$ after that DEST was applied on it. But this case is impossible since it would imply that $v \in X^1$ and we now by definition of DEST that $u$ is a strict subterm of $v$. Hence we have that $(\xi', j \triangleright v) \not\in \text{NoUse}(C)$ and so $C$ satisfies Property 4 of InvGeneral.

2. Since $C'$ in $(M_2, M'_2)$, $C'$ satisfies InvVarFrame$(s - 1)$, InvNoUse$(s - 1)$ and InvUntouched$(s)$. Thanks to Lemmas C.15 and C.16, we can deduce that $C$ satisfies InvVarFrame$(s - 1)$, InvNoUse$(s - 1)$ and InvUntouched$(s)$.

6. Let $x \in \text{vars}$ of $(\xi, \xi' \triangleright u \land i < s)$ such that for all $(X, i \triangleright u) \in D(C)$ such that $i < s$ and $X \in S_2(C')$, $x \neq u$. We know that $C' \rightarrow C$ hence we do a case analysis on the rule applied DEST or EQ-LEFT-RIGHT:

Case EQ-LEFT-RIGHT$(X, \xi)$: We focus on the son which modifies the terms in the constraint systems, i.e. when the equality guess is true. Since the rule EQ-LEFT-RIGHT$(X, \xi)$ is applicable then there exists $i, u_0, v_0$ such that $(X, i \triangleright u_0) \in D(C')$, $X \in S_2(C')$ and $(\xi, s \triangleright v_0) \in \Phi(C')$. Let $\sigma = \text{mgu}(u, v)$. We know that $\Phi(C) = \Phi(C')\sigma$ and $D(C) = D(C')\sigma$.

But $x \in \text{vars}((\{u \mid X, i \triangleright u \in D(C') \land i < s\})$, thus it implies that $x \notin \text{dom}(\sigma)$ and so $x' \in \text{vars}((\{u \mid X, i \triangleright u \in D(C') \land i < s\})$. Furthermore, it also implies that for all $(X, i \triangleright u) \in D(C')$ such that $i < s$ and $X \in S_2(C')$, $x \neq u$. Indeed, if there exists $(X, i \triangleright x) \in D(C')$ then $(X, i \triangleright x) \in D(C)$ which is a contradiction with our hypothesis.

Let $t \in \{v \mid (\xi, i \triangleright v) \in \Phi(C)\lor (\xi, i \triangleright v) \in D(C)\}$, thus there exists $t' \in \{v \mid (\xi, i \triangleright v) \in \Phi(C')\lor (X, i \triangleright v) \in D(C')\}$ such that $t'\sigma = t$. Let $p$ a position such that $t|_p = x$.

If $x \notin \text{img}(\sigma)$, then we can deduce that $t'|_p = x$. Hence, by our inductive hypothesis, we have that there exists $p'$ such that $p = p' \cdot 1$ and $t'|_{p'} = \text{pk}(x)$ and so $t'\sigma|_{p'} = \text{pk}(x)$.

If $x \notin \text{img}(\sigma)$, then $x = u_0$ or $x = v_0$. But by our inductive hypothesis we have that for all $p$, if $u_0|_{p'} = x$ then there exists $p'$ such that $p = p' \cdot 1$ and $u_0|_{p'} \notin \text{pk}(x)$.

Hence by definition of the mgu, for all $y \in \text{dom}(\sigma)$, $x \in \text{vars}(y\sigma)$ implies that either (a) $x = y\sigma$ or (b) there for all $p$, $y\sigma|_p = x$ and then there exists $p'$ such that $p = p' \cdot 1$.

Case (a): In such a case, we have that for all $(X, i \triangleright u) \in D(C')$ such that $i < s$ and $X \in S_2(C')$, $y \neq u$. Indeed, if there exists $(X, i \triangleright y) \in D(C')$ then $(X, i \triangleright x) \in D(C)$ which is a contradiction with our hypothesis. Hence, $t|_p = x$ implies that $t'|_p = y$ or $t'|_p = x$. If $t'|_p = x$ then the result holds similarly to the case $x \notin \text{img}(\sigma)$. If $t'|_p = y$, then we know our inductive hypothesis that $t'|_{p'} = \text{pk}(y)$ with $p = p' \cdot 1$ and so $t'\sigma|_{p'} = \text{pk}(x)$. Hence the result holds.

Case (b): Otherwise, $t|_p = x$ implies that $t'|_p = x$ or there exists $p'$, $p''$ such that $p = p' \cdot p''$ and $t'|_{p'} = y$ and $y\sigma|_{p''} = x$. But by hypothesis on $y$, there exists $p''$ such that $p'' = p'' \cdot 1$ and $y\sigma|_{p''} = \text{pk}(x)$, hence we have that $t'\sigma|_{p''} = \text{pk}(x)$. Hence the result holds.

Case DEST$(\xi, \ell \rightarrow r, s)$: Once again, we focus on the son which may instantiate the terms in the constraint system, i.e. when the guess is positive. Since DEST$(\xi, \ell \rightarrow r, s)$ is applicable then there exists $i \leq s, u_0$ such that $(\xi, i \triangleright u_0) \in \Phi(C')$. First of all, we deduce $u_0 \notin X^1$. Indeed, if $u_0 \in X^1$, then since $C'$ satisfies the properties the lemma, we have that either $(\xi, i \triangleright u_0) \in \text{NoUse}(C')$ if $i < s$, or else there exists $(X, j \triangleright u_0) \in D(C')$. Thus we would have that the rule EQ-LEFT-RIGHT$(X, \xi)$ would be applicable which contradict the strategy that imposes that the rule EQ-LEFT-RIGHT are prioritised over the rule DEST.

By definition of the rule DEST, we know that $\Phi(C')\sigma \cup \{\xi', s \triangleright w\sigma\} = \Phi(c)$ and $\{(X, i \triangleright u) \in D(C') \mid X \in S_2\} = \{(X, i \triangleright u) \in D(C) \mid X \in S_2\}$ where $\sigma = \text{mgu}(u_0, v_1)$ and
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Proof. The proof of this Lemma follows the application of the rule Eq-left-right and Dest do not modify Er(C'). Hence, we only have to look at the new frame element that are added on the frame. But by definition of Dest, the application of Dest(ξ, ℓ → r, s) implies the addition of a new element (g(ξ, X2, ..., Xn), s ▷ w) where g ∈ Fd, X2, ..., Xn are fresh, and there exists i, u such that (ξ, i ▷ u) ∈ Φ(C). Hence the result holds.

5. Once again, the rule Eq-left-right and Dest no not modify Er(C') hence Er(C') = Er(C). Hence, C' satisfies Property C.2 implies that C satisfies Property C.2.

Lemma C.22. Let (M1, M1') be a pair of matrices of constraint system satisfying PP1(s – 1).

Let (M2, M2') be a pair of matrices of constraint systems obtained from (M1, M1') by applying Step a of Phase 1 of the strategy with parameter s. Moreover we assume that (M2, M2') is obtained after a sequence of application of Dest or Eq-left-right. For all constraint system C, C' in (M2, M2'),

1. for all (ξ, s ▷ u) ∈ NoUse(C), there exists X ∈ S2(C) such that for all C'' in M or M', if there exists (ξ', s ▷ u') ∈ NoUse(C'') such that path(ξ') = path(ξ) then C|Xmgu(Err(C''))|Φ(C'') acc1(C'') = u'. Else, by denoting v' = C|Xmgu(Err(C''))|Φ(C'')acc1(C''), we have that Eq(C'') ▷ v' ≠ u'.

2. for all (ξ, i ▷ u) ∈ Φ(C) \ NoUse(C), for all (ξ', i' ▷ u') ∈ Φ(C') \ NoUse(C'), if path(ξ) = path(ξ') then Dest(ξ, ℓ → r, s) is applicable on C is equivalent to Dest(ξ', ℓ → r, s) is applicable on C'.

Proof. The proof of this Lemma follows the application of the rule Dest and Eq-left-right in sequence.

Property C.3. We say that a pair of matrices of constraint systems (M, M') satisfy PP1SaE(s) if M and M' have the same structure, satisfy InvMatrix(s – 1) and InvGeneral, and for all constraint system C in M or M', if C ▷⊥ then C satisfies the invariants InvVarFrame(s – 1), InvDest(s), InvNoUse(s) and InvUntouched(s). Moreover, for all (X, i ▷ u) ∈ D(C),

- X /∈ S2(C) implies that i = s.

- for all f ∈ Fc, for all ξ ∈ Πa, Er(C) /∀ X /≠ ξ and Er(C) /∀ root(X) /≠ f.

Lemma C.23. Let (M, M') be a pair of matrices of constraint systems satisfying PP1(s – 1). For all pair of matrices of constraint systems (M1, M1') obtained from (M, M') at the end of Step a of Phase 1 of the strategy with parameter s, (M1, M1') satisfies PP1SaE(s).
Proof. We know that all constraint system in M and M’ satisfies InvVarConstraint(s − 1). Hence, 
for all C ∈ M (resp. M’), for all (X, i 7→ u) ∈ D(C), if i ≤ s − 1 implies that X ∈ S2(C). Moreover, 
C satisfies InvUntouched(s − 1) which implies that if i > s − 1, X ∈ S2(C). Thus we deduce that 
X ∈ S2(C). But during the step a of Phase 1, only the rule Dest add new deducible constraint. 
Furthermore, Dest is applied with support s. Hence, Dest can only add deducible constraint of 
the form Y, s ⊢ v. Thus for all C, for all (X, i 7→ u) ∈ D(C), if X ̸∈ S2(C) then i = s. 

Since (M, M’) satisfies PP1(s − 1), we already know that already know that M and M’ satisfy 
the invariant InvMatrix(s − 1). Furthermore, Lemma [C.24] also indicates that for all constraint 
system C in M or M’, C satisfies the invariant InvGeneral, InvVarFrame(s − 1), InvDest(s − 1), 
InvNoUse(s − 1) and InvUntouched(s). Hence it remains to prove that C satisfies InvDest(s) and 
InvNoUse(s).

At the end of Step a, we know that the rules Dest and Eq-Left-Right are not applicable on 
a constraint system in M or M’ for any parameter with support inferior or equal to s.

Invariant InvNoUse(s): Let (ξ, p 7→ v) ∈ Φ(C). If p < s then, thanks to InvNoUse(s − 1), the result holds. 
Else assume that p = s and v ∈ X^k. But, thanks to Lemma [C.24] we have that there exists 
(X, i 7→ u) ∈ D(C) such that u = v and i < s. Thus, since Eq-Left-Right is not applicable on C, 
we have that either (ξ, p 7→ v) ∈ NoUse(C) or Eq(C) ⊢ u 7→ v. But u = v implies Eq(C) ⊢ u 7→ u 
which implies that C_ξ = ⊥ by normalisation, which is a contradiction with a fact that Φ(C). Thus 
we have that (ξ, p 7→ v) ∈ NoUse(C) and so C satisfies InvNoUse(s).

Invariant InvDest(s): Let (ξ, p 7→ v) ∈ Φ(C), f ∈ F_d and (ξ, p 7→ v) ̸∈ NoUse(C) and p ≤ s. We do 
a case analysis on p:

• Case p = s: In such a case, we only have to show that either (ξ’, s 7→ v’) ∈ Φ(C) for some 
ξ’ such that path(ξ’) = f · path(ξ); or else ND ⊢ ∀x, v ̸̸= u_1 ∨ s ̸̸= u_2 ∨ · · · ∨ s ̸̸= u_n where 
f(u_1, . . . , u_n) → w is a fresh rewriting rule with vars^1(u_1, . . . , u_n, w) = x.

But we know that Dest is not applicable on C for any parameter with support s. Hence 
Dest(ξ, f(u_1, . . . , u_n) → w, s) is not applicable. But since ξ, f(u_1, . . . , u_n) → w and s are 
valid parameter for C, it implies that Dest(ξ, f(u_1, . . . , u_n) → w, s) was already applied and 
so the definition of the rule Dest in Figure 7.1 allows us to conclude.

• Case p < s: We know that C satisfies InvDest(s − 1). Hence, we have to show that if for 
every p ≤ k ≤ s − 1, ND ⊢ ∀x, v ̸̸= u_1 ∨ s ̸̸= u_2 ∨ · · · ∨ s ̸̸= u_n where f(u_1, . . . , u_n) → w 
is a fresh rewriting rule with vars^1(u_1, . . . , u_n, w) = x, then either (ξ’, s 7→ v’) ∈ Φ(C) for 
some ξ’ such that path(ξ’) = f · path(ξ); or else ND ⊢ ∀x, v ̸̸= u_1 ∨ s ̸̸= u_2 ∨ · · · ∨ s ̸̸= u_n.

But once again, we know that Dest is not applicable on C for any parameter with support 
s. Hence Dest(ξ, f(u_1, . . . , u_n) → w, s) is not applicable. But since ξ, f(u_1, . . . , u_n) → w 
and s are valid parameter for C, it implies that Dest(ξ, f(u_1, . . . , u_n) → w, s) was already 
noticed and so the definition of the rule Dest in Figure 7.1 allows us to conclude. □

C.4.3.3 Invariants of Phase 1, Step b

Given a pair of matrices (M, M’) such that M (resp. M’) has n columns (resp. n’), we say that 
the kth column of (M, M’) is either the kth column of M if k ≤ n; or else the (k − n)th column 
of M’ if k > n. If n + n’ < k then the kth column of (M, M’) is not defined.

Moreover, will assume from now on that m is the size of a frame of a constraint system in M 
or M’.

Property C.4. We say that a pair of matrices of constraint systems (M, M’) satisfy PP1SB(s, k) 
if (M, M’) satisfies PP1SA(s) and for all i ≤ k, for all constraint system C in the ith column of 
(M_1, M_1’), C also satisfies InvVarConstraint(s) and InvVarFrame(s) (and InvDedsub when s = m)
Lemma C.24. Let \((M, M')\) be a pair of matrices of constraint systems satisfying PP1SaE(s). \((M, M')\) satisfies PP1Sb(s, 0).

Proof. Trivial since \((M, M')\) does not have a 0th column. \(\square\)

Property C.5. We say that a pair of matrices of constraint systems \((M, M')\) satisfy PP1SbE(s, k) if \(M\) and \(M'\) have the same structure, satisfy InvMatrix(s-1) and InvGeneral, and for all constraint system \(C\) in \(M\) or \(M'\), if \(C\) \(\neq \bot\), then \(C\) satisfies the invariants InvVarFrame(s-1), InvDest(s), InvNoUse(s) and InvUntouched(s). Moreover, for all constraint system \(C\) in the \(k^{th}\) column of \((M_1, M'_1)\), for all \((X, i \vdash u) \in D(C)\),

- \(X \not\in S_2(C)\) implies \(u \in \mathcal{X}^1\) and \(i = s\).
- for all \(f \in F_c\), for all \(\xi \in \Pi_n\), \(Er(C) \not\models X \not\models \xi\) and \(Er(C) \not\models \text{root}(X) \not\models f\).
- if \(s = m\) then \(C\) satisfies InvDedsub.

At last, for all \(i \leq k\), for all constraint system \(C\) in the \(i^{th}\) column of \((M_1, M'_1)\), \(C\) also satisfies InvVarConstraint(s) and InvVarFrame(s) (and InvDedsub when \(s = m\)).

Lemma C.25. Let \((M, M')\) be a pair of matrices of constraint systems satisfying PP1Sb(s, k).
For all pair of matrices of constraint systems \((M_1, M'_1)\) obtained at the end of Step \(b\) of the first phase with support \(s\) and column \(k\) on \((M, M')\), \((M_1, M'_1)\) satisfies PP1SbE(s, k).

Proof. During Step \(b\) of the first phase, the rule Dest and EQ-LEFT-RIGHT are not applied. Furthermore, the rules applied can only be applied with support inferior or equal to \(s\). Hence, thanks to Lemmas \([6.19, 6.15, 6.16] and C.17\) we can deduce that \(M_1\) and \(M'_1\) satisfy InvMatrix(s-1), and for all \(C\) in \(M_1\) or \(M'_1\), \(C\) satisfies InvGeneral, InvVarFrame(s-1), InvNoUse(s), InvDest(s), InvDedsub (when \(s = \#(\Phi(C))\)) and InvUntouched(s).

At the end of Step \(b\), we cannot apply the rule Ded-st. Hence for all \((\xi, p \geq v) \in \Phi(C)\), we know that Ded-st(\(\xi, f\)) is useless for any \(f \in F_c\). However, the definition of Ded-st(\(\xi, f\)) being useless for all \(\xi\) and path implies the invariant InvDedsub. Thus we deduce that \(C\) satisfies the invariant InvDedsub.

Let \((X, i \vdash u) \in D(C)\). Since \((M_1, M'_1)\) is obtained at the end of step \(b\), we know that Cons(X, f) is not strongly applicable on \(C\), for all \(f \in F_c\). Hence it implies that \(u \notin \mathcal{X}^1\) and either:

(a) for all \(f \in F_c\), \(Er(C) \models \text{root}(X) \not\models f\) or
(b) for all \(f \in F_c\), \(Er(C) \not\models \text{root}(X) \not\models f\).

In case (a), since Axiom(\(X, \xi\)) is not strongly applicable on \(C\), for all \(\xi\), we deduce that for all \((\xi, j \geq v) \in \Phi(C)\), if \(j \leq i\) then \(Er(C) \not\models X \not\models \xi\). But \(C\) satisfies InvNoUse(s), InvDest(s), i.e. the rule Dest(\(\xi, \ell \rightarrow r, s\)) is useless for all \(\xi\) and \(\ell \rightarrow r\). Thus, by Definition 7.9 of the normalisation, we would have that \(C\) \(\vdash \bot\) which is a contradiction with the fact that \(D(C) \not\models \emptyset\). Hence this case is impossible.

In Case (b), the rule Axiom can only be applied during Step \(b\) if the strong application conditions of the rule are satisfied. But since \(u \notin \mathcal{X}^1\) and for all \(f \in F_c\), \(Er(C) \not\models \text{root}(X) \not\models f\), we deduce that the rule Axiom(X, path) was never applied during step \(b\) for any path. Hence, we deduce that for all \(\xi\), \(Er \not\models X \not\models \xi\). Hence the result holds.

At last, we know that the only rule that add deducible constraints during step \(b\) are Cons and Ded-st. But Ded-st is only applied when \(i = s\) and it create deducible constraint of the form \(X, s \vdash u\). On the other hand, thanks to Lemma \([6.23]\) we know that for all \(C\) in \(M\) or \(M'\), for all \((X, i \vdash u) \in D(C)\), if \(X \not\in S_2\) then \(i = s\). But, according to Figure \([7.4]\) by applying Cons(\(Y, f\)) for some \(f \in F_c\) and \(Y, i \vdash v\), if \(Y \in S_2\) (resp. \(\not\in S_2\)) then the rule Cons creates new deducible constraint systems of the form \((Z, i \vdash w)\) where \(Z\) is in \(S_2\) (resp. not in \(S_2\)). Since the only for all
\(C\) in \(M\) or \(M'\), for all \((X, i \rightarrow u) \in D(C)\), if \(X \not\in S_2\) then \(i = s\), we deduce that the index of any new deducible constraints created by \(\text{CONS}\) whose second order variables are not in \(S_2\) is necessary \(s\). Thus the result holds.

### C.4.3.4 Invariants of Phase 1, Step \(c\)

**Property C.6.** We say that a pair of matrices of constraint systems \((M, M')\) satisfy \(\text{PP1ScE}(s, k)\) if \(M\) and \(M'\) have the same structure, satisfy \(\text{InvMatrix}(s - 1)\) and \(\text{InvGeneral}\), and for all constraint system \(C\) in \(M\) or \(M'\), if \(C \not\perp\) then \(C\) satisfies the invariants \(\text{InvVarFrame}(s - 1)\), \(\text{InvDest}(s)\), \(\text{InvNoUse}(s)\) and \(\text{InvUntouched}(s)\). Moreover, for all constraint system \(C\) in the \(k\)th column of \((M, M'_1)\), for all \((X, i \rightarrow u) \in D(C)\),

- \(X \not\in S_2(C)\) implies \(u \not\in \mathcal{X}^1\).
- for all \(f \in F_c\), for all \(\xi \in \Pi_n\), \(\text{Er} \not\vdash \text{root}(X) \not\in f\) and \(\text{Er} \not\vdash X \not\in \xi\).
- if \(s = m\) then \(C\) satisfies \(\text{InvDedsub}\).

At last, for all \(i \leq k\), for all constraint system \(C\) in the \(i\)th column of \((M, M'_1)\), \(C\) also satisfies \(\text{InvVarConstraint}(s)\), \(\text{InvVarFrame}(s)\) (and \(\text{InvDedsub}\) when \(s = m\)).

**Lemma C.26.** Let \((M, M')\) be a pair of matrices of constraint systems satisfying \(\text{PP1SbE}(s, k)\).
For all pair of matrices of constraint systems \((M_1, M'_1)\) obtained at the end of Step \(c\) of the first phase with support \(s\) and column \(k\) on \((M, M')\), \((M_1, M'_1)\) satisfies \(\text{PP1ScE}(s, k)\).

**Proof.** Let \((M_0, M'_0)\) be the pair of matrices of constraint systems, ancestor of \((M, M')\), obtained at the end of step \(b\). Thanks to Lemma \(\text{C.25}\) we know that \((M_0, M'_0)\) satisfies \(\text{InvMatrix}(s - 1)\).
Furthermore, we know that for all constraint system \(C\) in the \(k\)th column of \((M_0, M'_0)\), \(C\) satisfies \(\text{InvGeneral}\), \(\text{InvVarFrame}(s - 1)\), \(\text{InvNoUse}(s)\), \(\text{InvDest}(s)\) and \(\text{InvUntouched}(s)\). Hence thanks to Lemmas \(\text{C.19, C.15, C.10 and C.17}\) we deduce, by a simple induction on the size of the branch between \((M_0, M'_0)\) and \((M, M')\), that \((M, M')\) satisfies \(\text{InvMatrix}(s - 1)\) and for all constraint system \(C\) in the \(k\)th column of \((M, M')\), \(C\) satisfies \(\text{InvGeneral}\), \(\text{InvVarFrame}(s - 1)\), \(\text{InvNoUse}(s)\), \(\text{InvDest}(s)\) and \(\text{InvUntouched}(s)\).

It remains to prove that for all \(i \in \{1, \ldots, n\}\), for all \((X, j \rightarrow v) \in D(M, k)\), if \(X \not\in S_2(C)\) then \(u \not\in \mathcal{X}^1\). Let’s denote \(C = M_{i,k}\). Let \((X, j \rightarrow u) \in D(C)\) such that \(X \not\in S_2(C)\) and \(u \in \mathcal{X}^1\). Thus we have that \(X'(C) \not\perp\). Thanks to \(C\) being well-formed (Definition \(\text{5.2, item \text{C.10}}\) and Lemma \(\text{C.10}\)) we know that there exists \((Y, \ell \rightarrow v) \in D(C)\) such that \(Y \in S_2(C), \ell < j\) and \(u \in \text{vars}^1(v)\).

Assume first that \(v \in \mathcal{A}^1\) and so \(u = v\). Thanks to Lemma \(\text{C.25}\) and the fact that the rules applied in step \(c\) do not add second order inequation in \(\text{Er}\) with a variable not in \(S_2\), we deduce that for all \(f \in F_c\), \(\text{Er}(C) \not\vdash \text{root}(X) \not\in f\). But if there exists \(f \in F_c\) such that \(\text{Er}(C) \vdash \text{root}(Y) \not\in f\), then it would implies that either a rule \(\text{AXIOM}\) or \(\text{CONS}\) would be applicable on \((Y, \ell \rightarrow v); \) or else \(C = \perp\) by normalisation. Hence, we have that for all \(f \in F_c\), \(\text{Er}(C) \not\vdash \text{root}(Y) \not\in f\). Therefore we have that \(\text{Eq-right-right}(X, Y)\) is applicable which contradicts the fact that \((M, M')\) was obtained at the end of step \(c\).

Similarly, if \(v \not\in \mathcal{A}^1\), it implies that either \(C = \perp\) by normalisation or that a rule \(\text{AXIOM}\) or \(\text{CONS}\) would be applicable on \((Y, \ell \rightarrow v); \) which contradicts our hypothesis.

Thus we deduce that for all \(i \in \{1, \ldots, n\}\), for all \((X, j \rightarrow u) \in D(M_i, k)\), if \(X \not\in S_2\) then \(u \not\in \mathcal{X}^1\).
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C.4.3.5 Invariants of Phase 1, end of cycle Step b - c

Property C.7. We say that a pair of matrices of constraint systems \((M, M')\) satisfy \textsc{PP1SbcE}(s, k) if \(M\) and \(M'\) have the same structure, satisfy \textsc{InvMatrix}(s - 1) and \textsc{InvGeneral}, and for all constraint system \(C\) in \(M\) or \(M'\), if \(C \notin \perp\) then \(C\) satisfies the invariants \textsc{InvVarFrame}(s - 1), \textsc{InvDest}(s), \textsc{InvNoUse}(s) and \textsc{InvUntouched}(s). Moreover, for all constraint system \(C\) in the \(k\)th column of \((M_1, M'_1)\), for all \((X, i \vdash u) \in D(C)\),

- \(X \in S_2(C)\)
- for all \(f \in \mathcal{F}_c\), for all \(\xi \in \Pi_u\), \(Er \not\in \text{root}(X) \neq f\) and \(Er \not\in X \neq \xi\)
- if \(s = m\) then \(C\) satisfies \textsc{InvDedsub}.

At last, for all \(i \leq k\), for all constraint system \(C\) in the \(i\)th column of \((M_1, M'_1)\), \(C\) also satisfies \textsc{InvVarConstraint}(s) and \textsc{InvVarFrame}(s) (and \textsc{InvDedsub} when \(i = s\)).

Lemma C.27. Let \((M, M')\) be a pair of matrices of constraint systems satisfying \textsc{PP1Sb}(s, k).

For all pair of matrices of constraint systems \((M_1, M'_1)\) obtained at the end of the cycle of steps \(b + c\) of the first phase with support \(s\) and column \(k\) on \((M, M')\), \((M_1, M'_1)\) satisfies \textsc{PP1SbcE}(s, k).

Proof. \((M, M')\) being obtained at the end of cycle of steps \(b + c\) of Phase 1 implies that \((M, M')\) is also obtained at the end of step \(c\). Hence thanks to Lemma C.26 we know that \((M, M')\) satisfies \textsc{InvMatrix}(s - 1) and for all constraint system \(C\) in the \(k\)th of \((M, M')\), we have that \(C\) satisfies the invariants \textsc{InvGeneral}, \textsc{InvVarFrame}(s - 1), \textsc{InvNoUse}(s), \textsc{InvDest}(s) and \textsc{InvUntouched}(s). Hence it remains to prove that for all \((X, i \vdash u) \in D(C)\), \(X \in S_2(C)\).

Assume that there exists \((X, i \vdash u) \in D(C)\) such that \(X \not\in S_2(C)\). Thus, thanks to Lemma C.26 we have that \(u \not\in X^1\). But thanks to Lemma C.24 we know that if no rule of step \(b\) is applicable than it would imply that \(u \in X^1\) which is a contradiction. Hence a rule of step \(b\) is applicable on \((M, M')\) which contradicts the fact that \((M, M')\) is obtained at the end of the cycle step \(b + c\). Hence we have that \(X \in S_2(C)\). \(\square\)

C.4.3.6 Invariant of Phase 1, Step d

Lemma C.28. Let \((M, M')\) be a pair of matrices of constraint systems satisfying \textsc{PP1SbcE}(s, k).

For all pair of matrices of constraint systems \((M_1, M'_1)\) obtained at the end of the Step \(d\) of the first phase with support \(s\) and column \(k\) on \((M, M')\), \((M_1, M'_1)\) satisfies \textsc{PP1Sb}(s, k, 1).

Proof. Let \((M_1, M'_1)\) be the pair of matrices of constraint systems, ancestor of \((M, M')\), obtained at the end of the cycle \(b + c\). Thanks to Lemma C.26 we already know that \((M_1, M'_1)\) satisfy \textsc{InvMatrix}(s - 1) and \textsc{InvGeneral}. Furthermore, for all constraint system \(C\) in the \(k\)th column on \((M_1, M'_1)\), we have that \(C\) satisfies the invariants \textsc{InvVarFrame}(s - 1), \textsc{InvNoUse}(s), \textsc{InvDest}(s) and \textsc{InvUntouched}(s). But thanks to Lemmas C.16, C.17, C.16, C.13 and C.14 we have that \((M, M')\) satisfies \textsc{InvMatrix}(s - 1) and \textsc{InvGeneral}. Furthermore, for all constraint system \(C\) in the \(k\)th column on \((M, M')\), we have that \(C\) satisfies the invariants \textsc{InvVarFrame}(s - 1), \textsc{InvNoUse}(s), \textsc{InvDest}(s) and \textsc{InvUntouched}(s).

Using a similar proof as in Lemma C.26 we also show that \(C\) satisfies \textsc{InvVarConstraint}(s) and for all \((X, i \vdash x) \in D(C)\), for all \((\xi, j \vdash u) \in \Phi(C)\), for all \(f \in \mathcal{F}_c\), \(Er \not\in \text{root}(X) \neq f\) and \(Er \not\in X \neq \xi\).

Hence it remains to prove that \(C\) satisfies the invariant \textsc{InvVarFrame}(s). Let \((\xi, s \vdash v) \in \Phi(C)\) and \(Z \in \text{vars}^2(\xi)\). Thanks to \(C\) being well formed, we know that there exists \(j \leq s\) and a term \(u\) such that \((Z, j \vdash u) \in D(C)\). Furthermore, for all \(x \in \text{vars}^1(u)\), there exists \((\zeta, k \vdash w) \in \Phi\) such that \(k \leq s\) and \(x \in \text{vars}^1(w)\). But since \(C\) satisfies \textsc{InvVarConstraint}(s), we know that \(u \in X^1\) and...
so $x = u$. But by the property of origination of a constraint system, we deduce that there exists $(X, q \vdash t) \in D$ with $q < k \leq s$ and $u \in \mathit{vars}^1(t)$. Once again since $C$ satisfies $\mathit{InvVarConstraint}(s)$, we deduce that $t = u$. Moreover, the invariant $\mathit{InvVarConstraint}(s)$ stipulates that all right hand term of the deducible constraints with index inferior to $s$ are distinct. Hence, we deduce that $(X, q \vdash t)$ and $(Z, j \vdash u)$ are the same constraint and so $q = j$. But we proved that $q < k$ and $k \leq s$ which means that $j < s$ and so the result holds.

\[ \square \]

\section*{C.4.3.7 Invariant of Phase 1, Step $e$}

**Lemma C.29.** Let $(M, M')$ be a pair of matrices of constraint systems obtained by following the strategy. Assume that $M$ and $M'$ satisfy the invariant $\mathit{InvGeneral}$. Let $C$ and $C'$ be two constraint systems occurring in the same column of $M$. Assume that $C$ and $C'$ satisfy the invariants $\mathit{InvVarConstraint}(s)$ and $\mathit{InvUntouched}(s)$ for some $s$. We have that there exists a variable renaming $\rho : X^1 \setminus S_1(C) \rightarrow X^1 \setminus S_1(C')$ such that:

1. $\mathit{mgu}(\mathit{Eq}(C))|_{S_1(C)}\rho = \mathit{mgu}(\mathit{Eq}(C'))|_{S_1(C')}$, and $D(C)\rho = D(C')$;

2. $\{ (u, u') \mid (\xi, i \triangleright u) \in \Phi \land (\xi', i' \triangleright u') \in \Phi' \land \mathit{path}(\xi) = \mathit{path}(\xi') \} \subseteq \{ (u, u) \mid u \in T(F, N \cup \mathcal{X}^1) \}$.

**Proof.** First, we define the renaming $\rho$, and then we show that the two properties are satisfied.

**Definition of the renaming $\rho$.** By Lemma S.1, we know that the matrices $M$ and $M'$ have the same structure, and so the systems $C$ and $C'$ have the same shape. Hence, we have:

- $S_2(C) = S_2(C')$, and

- $\{ (X, i) \mid X, i \triangleright u \in D(C) \text{ and } X \in S_2(C) \} = \{ (X, i) \mid X, i \triangleright u \in D(C') \text{ and } X \in S_2(C') \}$.

Since the system $C$ satisfies the invariants $\mathit{InvVarConstraint}(s)$ and $\mathit{InvUntouched}(s)$, we have that $X \in S_2(C)$ for each $(X, i \triangleright u) \in D(C)$, and similarly, we have that $X \in S_2(C')$ for each $(X, i \triangleright u) \in D(C')$. This allows us to conclude that $\{ (X, i) \mid X, i \triangleright u \in D(C) \} = \{ (X, i) \mid X, i \triangleright u \in D(C') \}$.

Actually, the invariant $\mathit{InvVarConstraint}(s)$ also tells us that:

- for all $(X, i \triangleright u) \in D(C)$ such that $i \leq s$, we have that $u$ is a variable (distinct of the ones introduced by the other constraints); and

- for all $(X, i \triangleright u) \in D(C')$ such that $i \leq s$, we have that $u$ is a variable (distinct of the ones introduced by the other constraints).

Hence, this allows us to define a renaming $\rho$ such that $\mathit{dom}(\rho) = \{ x \mid (X, i \triangleright x) \in D(C) \land i \leq s \}$, and $\rho(x) = X\mathit{acc}^1(C')$ where $(X, i \triangleright x) \in D(C)$.

**Property 1.** With such renaming, we trivially have that $D(C)\rho = D(C')$ but only for the deducibility constraints $(X, i \triangleright u)$ with $i \leq s$. Hence, we still have to prove this result for $i > s$. Since the systems $C$ and $C'$ occur on the same column of the matrix $M$, there exists an initial constraint system $C_0$ that is an ancestor of $C$ and $C'$. Moreover, we know that $C$ and $C'$ satisfy the invariant $\mathit{InvUntouched}(s)$. Hence, we deduce that:

- for all $(X, i \triangleright u) \in D(C)$ such that $i > s$, we have that $X \in \mathit{vars}^2(D(C_0))$; and

- for all $(X, i \triangleright u') \in D(C')$ such that $i > s$, we have that $X \in \mathit{vars}^2(D(C_0))$. 

\[ \blacksquare \]
C.4. STRATEGY INVARIANTS

Let \( \sigma = \text{mgu}(E_q(C)) \) and \( \sigma' = \text{mgu}(E_q(C')) \). Since \( C \) and \( C' \) are normalised, for \( i > s \), we deduce that \( (X, i \vdash u) \in D(C) \), \( (X, i \vdash u') \in D(C') \), and \( (X, i \vdash u_0) \in D(C_0) \) imply that \( u = u_0\sigma' \) and \( u' = u_0\sigma' \). Let \( S_1 = S_1(C) = S_1(C') = S_1(C_0) \). Hence, to conclude the proof of \( D(C)\rho = D(C') \), it remains to show that \( \sigma_{|S_1}\rho = \sigma'_{|S_1} \).

By definition of an initial constraint system, we know that for all \( x \in S_1 \), there exists \( (X, k \vdash u) \in D(C_0) \) such that \( x \in \text{vars}^1(u) \) and \( x \in S_2(C_0) \). Since \( C \) and \( C' \) satisfy the invariant \( \text{InvUntouched}(s) \), we have that no rule was applied with support strictly superior to \( s \), and we deduce that for all \( (Y, j \vdash v) \in D(C_0) \), for all \( y \in \text{vars}^1(v) \), \( \text{ind}_0(y) > s \), we have that \( y \not\in \text{dom}(\sigma') \).

Hence, we only focus on variable \( x \in S_1 \) such that there exists \( (X, k \vdash u) \in D(C_0) \), \( x \in \text{vars}^1(u) \) and \( k \leq s \). We prove by induction on \( k \leq s \) that \( X\text{acc}^1(C_0)\sigma\rho = X\text{acc}^1(C_0)\sigma'\rho \).

**Base case** \( k = 0 \). There is no constraint \( X, k \vdash u \) with \( k = 0 \). Hence, the result trivially holds.

**Inductive step** \( k > 0 \). Let \( (X, k \vdash u) \in D(C_0) \). By Lemma C.11 we know that:

\[
\begin{align*}
\{ \Sigma & = \text{mgu}(E_q(C)) \text{ and } \Theta' = \text{mgu}(E_q(C')). \\
\text{where } \Theta = \text{mgu}(E_q(C)) \text{ and } \Theta' = \text{mgu}(E_q(C')). \end{align*}
\]

However, \( X \in S_2(C_0) \) implies that \( X \in S_2(C) = S_2(C') \) and so thanks to \( M \) satisfying the invariant \( \text{InvGeneral} \) (item 5), we deduce that \( C[X\Theta]\rho = C[X\Theta']\rho \). Furthermore, for all \( i \leq k \), for all \( w \cdot ax_i \in st(C[X\Theta]\rho) \), we know that there exists \( u_0 \) such that \( (ax_i, i \vdash u_0) \in \Phi(C_0) \). Thus by Lemma C.12 \( (ax_i, i \vdash u_0\sigma) \in \Phi \) and \( (ax_i, i \vdash u_0\sigma') \in \Phi' \). By definition of a constraint system, for all \( y \in \text{vars}^1(u_0) \), there exists \( (Y, \ell \vdash v) \in D(C_0) \) such that \( \ell < k \) and \( y \in \text{vars}^1(v) \). By our inductive hypothesis, we know that \( y\sigma = y\sigma' \) which implies that \( y\rho = y\rho' \) and so we can deduce that \( u_0\rho = u_0\rho' \).

But thanks to the definition of a context, for all \( w, w \cdot ax_i \in st(C[X\Theta]\rho) \), implies that there exists \( (\xi, \ell \vdash v) \in \Phi \) and \( (\xi', \ell' \vdash v') \in \Phi' \) such that \( \text{path}(\xi) = \text{path}(\xi') = w \cdot ax_i \).

Since \( ax_i\text{acc}^1(C_0)\rho = u_0\sigma\rho = u_0\sigma' = ax_i\text{acc}^1(C') \), then thanks to Lemma C.13 we can deduce that \( v\rho = v' \) and so \( (w \cdot ax_i)\text{acc}^1(C_0)\rho = (w \cdot ax_i)\text{acc}^1(C') \).

At last, since \( \text{param}_{\max}(X\Theta)k \in \text{param}_{\max}(X\Theta')k \), then for all \( (w \cdot ax_i) \in st(C[X\Theta]\rho) \), we have \( i \leq k \). The same holds for \( (w \cdot ax_i) \in st(C[X\Theta']\rho) \). Hence, since we proved that for all \( w, \) for all \( i \leq k, (w \cdot ax_i)\text{acc}^1(C_0)\rho = (w \cdot ax_i)\text{acc}^1(C') \), since \( C[X\Theta]\rho = C[X\Theta']\rho \), and since for all \( X, i \vdash x \in D(C) \), for all \( X, i \vdash x \in D(C') \), \( i \leq s \) implies \( x\rho = x' \), then we can deduce that \( X\text{acc}^1(C_0)\rho = X\text{acc}^1(C') \). Thus we conclude that \( X\text{acc}^1(C_0)\sigma\rho = u\sigma\rho = u\sigma' = X\text{acc}^1(C'0)\sigma' \).

**Property 2.** Let \( (\xi, i \vdash u) \in \Phi \) and \( (\xi', i' \vdash u') \in \Phi' \) such that \( \text{path}(\xi) = \text{path}(\xi') = w \cdot ax_k \).

Since the constraint systems \( C \) and \( C' \) are well-formed, there exist \( (ax_k, k \vdash v) \in \Phi \) and \( (ax_k, k \vdash v') \in \Phi' \). Thanks to Lemma C.12 we know that there exists \( v_0 \) such that \( (ax_k, k \vdash v_0) \in \Phi_0 \) with \( v_0\sigma = v \) and \( v_0\sigma' = v' \). Since \( \sigma_{|S_1}\rho = \sigma'_{|S_1} \), we deduce that \( v_0\rho = v_0\rho' \) and so \( v = v' \).

**Lemma C.30.** Let \( (M, M') \) be a pair of matrices of constraint systems satisfying PP1(s). For all pairs of matrices of constraint systems \( (M_1, M'_1) \) obtained by applying all the steps of Phase 1 of the strategy with support \( s \), \( (M_1, M'_1) \) satisfies PP1(s + 1).

**Proof.** The step \( e \) of the strategy consists of transforming some of the constraint systems into \( \bot \). Moreover, the step \( e \) is applied only once step \( d \) was applied on all columns of \( (M, M') \).

Thus, thanks to Lemma C.28, we can already deduce that \( M \) and \( M' \) satisfies \( \text{InvGeneral} \) and for all constraint system \( C \) in \( (M, M') \), \( C \) satisfies the invariants \( \text{InvVarConstraint}(s), \text{InvVarFrame}(s), \text{InvNoUse}(s), \text{InvDest}(s), \text{InvUntouched}(s) \) and for all \( (X, i \vdash x) \in D(C) \), for all \( (\xi, j \vdash u) \in \Phi(C) \), for all \( f \in F_c \), \( Er \not\models \text{root}(X) \not\subseteq f \) and \( Er \not\models X \not\subseteq \xi \).
Similarly, we have that \((M, M')\) satisfies the invariant \(\text{InvGeneral}\) and \(\text{InvMatrix}(s - 1)\). Thus it remains to prove that \((M, M')\) satisfies the invariant \(\text{InvMatrix}(s)\). But by the definition of the transformation in step \(c\), we can deduce that for all \(C\), for all \(C'\) in the same column of \((M, M')\), we have \(\{\text{path}(\xi), i \mid (\xi, i \triangleright u) \in \Phi(C) \land i \leq s\} = \{\text{path}(\xi), i \mid (\xi, i \triangleright u) \in \Phi(C') \land i \leq s\}\).

At last, let \((M_1, M_1')\) be the matrices ancestors of \((M, M')\) obtained at the end of Step \(a\) of phase 1 with support \(s\). Let \(C\) be a constraint system in \((M, M')\) such that \((\xi, s \triangleright u) \in \text{NoUse}(C)\). Let \(C'\) be a constraint system in \((M, M')\) in the column on \(C\). We proved that there exists \((\xi', s \triangleright u') \in \Phi(C')\) such that \(\text{path}(\xi') = \text{path}(\xi)\). Assume that \((\xi', s \triangleright u') \not\in \Phi(C')\). Since the frame is not modify during step \(b - c - d\), other than applying substitution, we can deduce that there exists \(C_1, C_1'\) in \((M_1, M_1')\), \(\xi_1, \xi_1' \in H_u, u_1, u_1' \in T(F_c, N_uX^1)\) such that \(C_1 \rightarrow^* C, C_1' \rightarrow^* C', (\xi_1, s \triangleright u_1) \in \Phi(C_1) \land \text{NoUse}(C_1), (\xi_1', s \triangleright u_1') \in \Phi(C_1') \land \text{NoUse}(C_1')\) and \(\text{path}(\xi_1) = \text{path}(\xi_1')\).

Thanks to Lemma C.22, there exists \(X_2(C_1)\) such that \(C[X \text{mgu}(E_2(C_1))]_{\phi(C_1)} \text{acc}^1(C_1) = u_1\) and either (a) \((\xi_1', s \triangleright u_1') \not\in \text{NoUse}(C_1')\) and \(C[X \text{mgu}(E_2(C_1))]_{\phi(C_1')} \text{acc}^1(C_1') = u_1'\). Or else, (b) by denoting \(v_1' = C[X \text{mgu}(E_2(C_1))]_{\phi(C_1')} \text{acc}^1(C_1')\), we have that \(E_2(C_1) \vDash v_1' \neq u_1'\). We show that case (b) can not happen.

Let’s denote \(\sigma = \text{mgu}(E_2(C))\), \(\sigma' = \text{mgu}(E_2(C'))\), \(\theta = \text{mgu}(E_2(C))\) and \(\theta' = \text{mgu}(E_2(C'))\).

Thanks to Lemma C.11 we deduce that \(v_1' \sigma' = C[X \theta']_{\phi(C')} \text{acc}^1(C')\) and \(u_1 \sigma = C[X \theta]_{\phi(C)} \text{acc}^1(C)\). However, since \(X \in S_2(C_1)\) and \((M, M')\) have the same structure, we deduce that \(X \in S_2(C)\) and \(X \in S_2(C')\). But \((M, M')\) satisfies the invariant \(\text{InvGeneral}\), hence thanks to Property 5 of invariant \(\text{InvGeneral}\), we have that \(C[X \theta]_{\phi(C)} = C[X \theta]_{\phi(C')}\).

On the other hand, since \(C\) and \(C'\) satisfies \(\text{InvVarConstraint}(s)\) and \(\text{InvUntouched}(s)\), then by Lemma C.29, we have that there exists a variable renaming \(\rho : X^1 \rightarrow S_1(C) \rightarrow X^1 \rightarrow S_1(C')\) such that:

1. \(\text{mgu}(E_2(C))|_{S_1(C)} \rho = \text{mgu}(E_2(C'))|_{S_1(C')},\) and \(D(C) \rho = D(C');\)
2. \(\{(u, u') \mid (\xi, i \triangleright u) \in \Phi \land (\xi', i' \triangleright u') \in \Phi' \land \text{path}(\xi) = \text{path}(\xi')\} \) is included in \(\{(u, u) \mid u \in T(F_c, N_uX^1)\}\).

Thus we have that \(\text{acc}^1(C) \rho = \text{acc}^1(C')\) and so \(v_1' \sigma' = C[X \theta']_{\phi(C')} \text{acc}^1(C') = C[X \theta]_{\phi(C)} \text{acc}^1(C)\).

Hence we have that \(v_1' \sigma' = u_1' \sigma'\). However, we assume that \(E_2(C') \vDash v_1' \neq u_1'\) which implies that \(E_2(C') \vDash v_1' \sigma' \neq u_1' \sigma'\). But \(v_1' \sigma' = u_1' \sigma'\) and by the normalisation, we would have that \(C' = \bot\) which is a contradiction with our hypothesis. Hence, we proved that only case (a) can happen which implies that \((\xi, s \triangleright u) \not\in \text{NoUse}(C)\) implies \((\xi', s \triangleright u') \not\in \text{NoUse}(C')\). It allows us to conclude that \(\{\text{path}(\xi), i \mid (\xi, i \triangleright u) \not\in \text{NoUse}(C) \land i \leq s\} = \{\text{path}(\xi), i \mid (\xi, i \triangleright u) \not\in \text{NoUse}(C) \land i \leq s\}\).

\[
\]
C.4. Strategy Invariants

- if \((M_2, M'_2)\) is obtained at the end of the cycle of steps \(b + c\) with support \(s\) and column \(k\) then \((M_2, M'_2)\) satisfies PP1SbcE\((s, k)\);
- if \((M_2, M'_2)\) is obtained at the end of Step \(d\) with support \(s\) then \((M_2, M'_2)\) satisfies PP1Sb\((s, k + 1)\).

Proof. Simple induction on the parameter \(s\) and \(k\) that rely on all the previous lemmas of this subsection.

Lemma 8.3. Let \((M, M')\) be a pair of row matrices of initial constraint systems having the same structure. Let \((M_1, M'_1)\) be a pair of matrices of constraint systems obtained by following the strategy on \((M, M')\). \((M_1, M'_1)\) satisfies InvGeneral.

Proof. We rely on Lemma C.31 to prove that if \((M_1, M'_1)\) is obtained from Step \(a\) with support \(s\), \(s \in \mathbb{N}\), then \((M_1, M'_1)\) satisfies PP1Sa\((s)\) and so InvGeneral. For any other step and phase, we rely on Lemma C.19 to conclude.

C.4.3.9 Invariant of Phase 2, Step a

Lemma C.32. Let \((M, M')\) be a pair of matrices of constraint systems obtained at the end of Step \(a\) of the second phase of the strategy. We have that for all constraint system \(C\) in \((M, M')\), \(\text{vars}^1(Eq(C))\) do not contain universal variable.

Proof. Thanks to the normalisation, we know that for all constraint system \(C\) in \(M\), the disjunctions of inequations in \(Eq(C)\) are of the form \(\forall \vec{y}. \bigvee_i x_i \neq u_i\) where \(\vec{y}\) is a set of universal variable and \(x_i\) are not universal for any \(i\). Furthermore, thanks to the normalisation and more specifically by rule (Nelim1), \(x_i \notin \vec{y}\), for all \(i\) and by rule (Nelim2), for all \(y \in \vec{y}\), there exists \(i\) such that \(y \in \text{vars}^1(u_i)\). Thus, \(x_i \neq u_i\) and \(y \in \text{vars}^1(u_i) \cap \vec{y}\). Since \(x_i\) is not a universal variable, there exists \((X, \vec{y}) \vdash x_i \in D(C)\). But we assumed that the rules CONS and AXIOM are no longer applicable. Thus, we deduce that for all \(f \in F_c\), \(Er(C) \equiv \text{root}(X) \neq f\) and for all \((\xi, k \vdash u) \in \Phi(C)\), \(Er(C) \equiv X \neq \xi\). Moreover, we know that \(C\) satisfies the invariant InvDest\((\infty)\) hence by the definition of the normalisation, we should have \(C = \bot\) which is a contradiction with our hypothesis on \(C\). Hence \(\text{vars}^1(u_i) \cap \vec{y} = \emptyset\) for all \(x_i \neq u_i\). Hence by rule (Nelim2) of the normalisation, we deduce that \(Eq(C)\) do not contain universal variable.

C.4.3.10 Invariant of Phase 2, Step b

Lemma C.33. Let \((M, M')\) be a pair of matrices of constraint systems at the end of Step \(b\). For all constraint system \(C\) and its association table in \(M\) or \(M'\), we have that:

- for all disjunction \(\bigvee_i u_i \neq v_i\), if \(Eq(C) = E \land \bigvee_i u_i \neq v_i\) and \(T[\bigvee_i u_i \neq v_i] = \bot\), then for all \(i\), \(u_i \neq v_i\) satisfies one of the following properties:
  1. \(u_i \in X^i\) and \(v_i \in N\).
  2. \(u_i, v_i \in X^i\), \(Er(C) \not\equiv \text{root}(X) \neq f\) and \(Er(C) \equiv \text{root}(Y) \neq g\), for all \(f, g \in F_c\) where \((X, p \vdash u_i), (Y, q \vdash v_i) \in D(C)\).
  3. \(u_i \in X^i\), \(\text{root}(v_i) \in F_c\) and for all \(f \in F_c\), \(Er(C) \equiv \text{root}(X) \neq f\), where \((X, p \vdash u_i) \in D(C)\).
- for all disjunction \(D\), if \(Eq(C) = E \land D\) and \(T[D] = \bigvee_i \xi_i \neq \xi'_i\), then either for all \(i\), \(st(\xi_i, \xi'_i) \cap (F_d^*: A.X) = \emptyset\) or else for all \(i\), \(\xi_i \neq \xi'_i\) satisfies one of the following properties:
1. $\xi_i \in (F^*_d \cdot AX)$

2. $\xi_i, \xi'_i \in X^2$, for all $f \in F_c$, $Er(C) \equiv \text{root}(\xi_i) \not\equiv f$ and $Er(C) \not\equiv \text{root}(\xi'_i) \not\equiv f$.

3. $\xi_i \in X^2$, $\text{root}(\xi'_i) \in F_c$ and for all $f \in F_c$, $Er(C) \equiv \text{root}(\xi_i) \not\equiv f$.

**Proof.** By definition of Step b oh Phase 2 of the strategy, for all constraint system $C$ and its association table $T$, $\text{Cons}(X, f)$ and EQ-RIGHT-RIGHT($X, \xi)$ is not applicable for all $f \in F_c$ and all $\xi$.

Consider a disjunction $\bigvee^n_i u_i \not\equiv v_i$ such that $Eq(C) = E \land \bigvee^n_i u_i \not\equiv v_i$ and $T[\bigvee^n_i u_i \not\equiv v_i] = \bot$. Let $i \in \{1, \ldots, n\}$. We do a case analysis on $u_i$ and $v_i$.

- $u_i \in X^1$ and $v_i \in \mathcal{N}$ (or the reverse): The results holds trivially.
- $u_i \not\in X^1$ and $v_i \in \mathcal{N}$ (or the reverse): We know that $C$ is normalised. Hence such inequality is necessary reduced either by the rules (Nneq1) or (Nt1). Hence this case is impossible.
- $u_i, v_i \in X^1$: In such a case, there exists $(X, k \vdash u_i) \in D(C)$ and $(Y, \ell \vdash v_i) \in D(C)$. Assume w.l.o.g. that $\ell \leq k$. Since EQ-RIGHT-RIGHT is not applicable for step b, we deduce that the conditions of application of the rule EQ-RIGHT-RIGHT($X, Y$) in Figure 7.2 are not satisfied. Hence we deduce that there exists $f \in F_c$ such that $Er \equiv \text{root}(X) \not\equiv f$ and $Er \not\equiv \text{root}(Y) \not\equiv f$ (or the reverse). Assume w.l.o.g. that $Er \equiv \text{root}(X) \not\equiv f$ and $Er \not\equiv \text{root}(Y) \not\equiv f$.

Since $\text{Cons}(X, g)$ is not applicable for Step b, for all $g \in F_c$, $Er \equiv \text{root}(X) \not\equiv f$ implies that $Er \equiv \text{root}(X) \not\equiv g$ for all $g \in F_c$. Similarly, $Er \not\equiv \text{root}(Y) \not\equiv f$ implies that $Er \not\equiv \text{root}(Y) \not\equiv g$ for all $g \in F_c$ (otherwise $\text{Cons}(Y, g)$ would be applicable). Hence we deduce that for all $f, g \in F_c$, $Er(C) \not\equiv \text{root}(X) \not\equiv f$ and $Er(C) \equiv \text{root}(Y) \not\equiv g$. Thus the result holds.

- Otherwise, $u_i \in X^1$ and $\text{root}(v_i) = f \in F_c$ (or the reverse): $u_i \in X^1$ implies that there exist $(X, k \vdash u_i) \in D(C)$. Since $\text{Cons}(X, g)$ is not applicable for Step b, for all $g \in F_c$, we deduce that $\text{st}(v_i) \cap \mathcal{N} = \emptyset$, $\text{ind}_C(v_i) \leq k$ and either for all $g \in F_c$, $Er \equiv \text{root}(X) \not\equiv g$; or for all $g \in F_c$, $Er \not\equiv \text{root}(X) \not\equiv g$.

$\text{st}(v_i) \cap \mathcal{N} = \emptyset$ implies that there exists $\xi \in T(F_c, X^2)$ such that $\xi \text{acc}^1(C) = v_i$. But EQ-RIGHT-RIGHT($X, \xi$) is not applicable for Step b. Hence, we deduce that $\text{ind}_C(v_i) \leq k$ implies that $Er \equiv \text{root}(X) \not\equiv \text{root}(\xi)$ where $\text{root}(\xi) \in F_c$. Hence using what we proved thanks to $\text{Cons}$ not being applicable, we deduce that for all $g \in F_c$, $Er \equiv \text{root}(X) \not\equiv g$. Hence the result holds.

Consider now a disjunction $D$ such that $Eq(C) = E \land D$ for some $E$, $T[D] = \bigvee^n_i \xi_i \not\equiv \xi'_i$ and there exists $j \in \{1, \ldots, n\}$ such that $\text{st}(\xi_j, \xi'_j) \cap (F^*_d \cdot AX) \not= \emptyset$. Let $i \in \{1, \ldots, n\}$, we do a case analysis on $\xi_i$ and $\xi'_i$:

- $\xi_i \in (F^*_d \cdot AX)$ or $\xi'_i \in (F^*_d \cdot AX)$: The result trivially holds.

- $\xi_i, \xi'_i \in X^2$: In such a case, since EQ-RIGHT-RIGHT($\xi_i, \xi'_i$) is not applicable for Step b, we deduce that there exists $f \in F_c$ such that $Er \equiv \text{root}(\xi_i) \not\equiv f$ and $Er \not\equiv \text{root}(\xi'_i) \not\equiv f$ (or the reverse). Assume w.l.o.g. that $Er \equiv \text{root}(\xi_i) \not\equiv f$ and $Er \not\equiv \text{root}(\xi'_i) \not\equiv f$.

Since $\text{Cons}(\xi_i, g)$ and $\text{Cons}(\xi'_i, g)$ are not applicable for Step b for all $g \in F_c$, $Er \equiv \text{root}(\xi_i) \not\equiv f$ implies that $Er \not\equiv \text{root}(\xi_i) \not\equiv g$, for all $g \in F_c$. Moreover, $Er \not\equiv \text{root}(\xi'_i) \not\equiv f$ implies that $Er \not\equiv \text{root}(\xi'_i) \not\equiv g$ for all $g \in F_c$. Hence the result holds.
\[ \xi \in \mathcal{A}^2, \text{ root}(\xi') = f \in \mathcal{F}_c \] (or the reverse): Since \( \text{Cons}(\xi, f) \) is not applicable for Step \( b \), we deduce that either (a) \( \text{Er} \vdash \text{root}(\xi) \not\models f \) or (b) \( \text{st}(\xi) \cap (\mathcal{F}_d \cdot \mathcal{A}) = \emptyset \) and \( \text{paramC}_{\text{max}}(C) \geq \text{paramC}_{\text{max}}'(C) \). In case (a), since \( \text{Cons}(\xi, g) \) not applicable for Step \( b \) for all \( g \in \mathcal{F}_c \), then \( \text{Er} \vdash \text{root}(\xi) \not\models f \) implies for all \( g \in \mathcal{F}_c \), \( \text{Er} \vdash \text{root}(\xi) \not\models g \). Hence the result holds. In case (b), since \( \text{st}(\xi, \xi') \cap (\mathcal{F}_d \cdot \mathcal{A}) \not\models \emptyset \), \( \text{st}(\xi) \cap (\mathcal{F}_d \cdot \mathcal{A}) = \emptyset \), \( \text{paramC}_{\text{max}}(C) \geq \text{paramC}_{\text{max}}'(C) \) and \( \text{Eq-right-right}(\xi, \xi') \) not applicable for Step \( b \), then we deduce that \( \text{Er}(\xi) \not\models \text{root}(\xi) \not\models f \).

But thanks to \( \text{Cons}(\xi, g) \) not applicable for Step \( b \), we conclude that \( \text{Er}(\xi) \not\models \text{root}(\xi) \not\models g \) for all \( g \in \mathcal{F}_c \). Hence the result holds.

\[ \Box \]

### C.5 Proof of soundness

In this section, we will focus on the proof of soundness. However, unlike the proof of completeness, this proof depends heavily on the strategy that has been described in Section 4.4 and on the invariants described in Section 4.4. Hence, the proof will depend on the strategy.

#### C.5.1 Preliminaries

**Lemma C.34.** Let \( \Phi \) be a closed frame and \( \xi, \xi' \) be two ground recipes in \( \Pi_n \) with \( \text{root}(\xi), \text{root}(\xi') \not\in \mathcal{F}_c \) and such that \( \text{path}(\xi) = \text{path}(\xi') \). If \( \xi \Phi \downarrow, \xi' \Phi \downarrow \in \mathcal{T}(\mathcal{F}_c, \mathcal{N}) \), then we have that \( \xi \Phi \downarrow = \xi' \Phi \downarrow \).

**Proof.** We prove this result by induction of the length \( n \) of \( \text{path}(\xi) \):

*Base case \( n = 1 \)*: In such a case, we have that \( \text{path}(\xi) = \text{path}(\xi') \in \mathcal{A} \). Hence, we have that \( \xi = \xi' \), and so \( \xi \Phi \downarrow = \xi' \Phi \downarrow \).

*Inductive step \( n > 1 \)*: Since \( \text{path}(\xi) = \text{path}(\xi') \), we know that there exists \( f \in \mathcal{F}_d \) and there exist \( \xi_1, \ldots, \xi_n, \xi'_1, \ldots, \xi'_n \in \Pi_n \) such that \( \xi = f(\xi_1, \ldots, \xi_n) \) and \( \xi' = f(\xi'_1, \ldots, \xi'_n) \). By Lemma 5.5, for all \( \xi \in \text{st}(\xi) \cup \text{st}(\xi') \), we have that \( \xi \Phi \downarrow \in \mathcal{T}(\mathcal{F}_c, \mathcal{N}) \). Hence, for all \( i = 1, \ldots, n \), for all \( \xi \in \text{st}(\xi_i) \cup \text{st}(\xi'_i) \), we have that \( \xi \Phi \downarrow \in \mathcal{T}(\mathcal{F}_c, \mathcal{N}) \). By definition of path, we have that \( \text{path}(\xi_i) = \text{path}(\xi'_i) \) (since \( \text{path}(\xi) = \text{path}(\xi') \)).

Applying our induction hypothesis on \( (\xi_1, \xi'_1) \), we obtain that \( \xi_1 \Phi \downarrow = \xi'_1 \Phi \downarrow \). We have that \( \xi \Phi \downarrow, \xi' \Phi \downarrow \in \mathcal{T}(\mathcal{F}_c, \mathcal{N}) \). Hence, we have that

\[
\begin{align*}
f(\xi_1 \Phi \downarrow, \ldots, \xi_n \Phi \downarrow) &\rightarrow \xi \Phi \downarrow \quad \text{and} \quad f(\xi'_1 \Phi \downarrow, \ldots, \xi'_n \Phi \downarrow) \rightarrow \xi' \Phi \downarrow
\end{align*}
\]

using the rewriting rule associated to \( f \). This rule is of the form \( f(u_1, \ldots, u_n) \rightarrow u \) with \( u \in \text{st}(u_1) \). Since \( \xi_1 \Phi \downarrow = \xi'_1 \Phi \downarrow \), we easily conclude that \( \xi \Phi \downarrow = \xi' \Phi \downarrow \).

**Lemma C.35.** Let \( \mathcal{C} = (S_1; S_2; \Phi; D; E; \text{Er}; \text{ND}; \text{NoUse}) \) be a well-formed constraint system obtained by following the strategy and \( (\sigma, \theta) \in \text{Sol}(\mathcal{C}) \). Let \( \xi \in \Pi_n \) be a ground recipe conforms to \( \Phi \theta \) w.r.t. \( \text{NoUse} \). For all \( \xi' \in \text{st}(\xi) \), \( \xi' \) conforms to \( \Phi \theta \) w.r.t. \( \text{NoUse} \).

**Proof.** We prove the result by induction on \( |\xi| \).

**Base case \( |\xi| = 1 \):** In such a case, \( \xi \in \mathcal{A} \). Hence for all \( \xi' \in \text{st}(\xi) \), \( \xi' = \xi \) and so the result trivially holds.

**Inductive step \( |\xi| > 1 \):** Otherwise, \( \xi = f(\xi_1, \ldots, \xi_n) \). We do a case analysis on \( \mathcal{C}[\xi]_{\Phi} \):

- Case \( |\mathcal{C}[\xi]_{\Phi}| > 1 \): In such a case, we have that \( \mathcal{C}[\xi]_{\Phi} = f(\mathcal{C}[\xi_1]_{\Phi}, \ldots, \mathcal{C}[\xi_n]_{\Phi}) \). Moreover, \( \xi \) conforms to \( \Phi \theta \) w.r.t. \( \text{NoUse} \) implies that for all \( i \in \{1, \ldots, n\} \), \( \xi_i \) conforms to \( \Phi \theta \) w.r.t. \( \text{NoUse} \). Hence by inductive hypothesis on \( \xi_i \), for all \( i \in \{1, \ldots, n\} \), the result holds.
obtained by following the strategy and

Let \( \xi \in I \) be a well-formed constraint system such that for all \( i \in \{1, \ldots, n\} \), \( \xi_i \in I \) and \( \xi \in I \). Thanks to \( C \) being well-formed, (Definition \( \xi \)) we deduce that \( \text{path}(\xi) \) is closed. Hence there exists \( \xi_1, \ldots, \xi_n \) such that \( \xi = f(\xi_1, \ldots, \xi_n) \) and \( \xi \in I \) for all \( i \in \{1, \ldots, n\} \).

But thanks to \( C \) being well-formed (Definition \( \xi \)), we deduce that for all \( \xi' \in \text{st}(\xi) \), \( C[\xi'] \in \tau (F_c, F^+_d \cdot AX \cup X^2) \) and if \( \text{path}(\xi') \in F^+_d \cdot AX \) then there exists \( j \) and \( v \) such that \( (\xi', j \cdot v) \in \Phi \). Hence for all \( i \in \{1, \ldots, n\} \), \( \xi_i \in I \) such that \( \xi_i \in I \). We deduce that for all \( i \in \{1, \ldots, n\} \), \( \xi_i \in I \) for some \( j', v' \) then \( (\xi_i, j' \cdot v') \in \Phi \).

Since \( (\xi, i \cdot v) \in I \) and relying on Lemma \( \xi \) (item 1), we deduce that for all \( \xi'' \in \text{st}(\xi_i) \), if \( \text{path}(\xi'') \in F^+_d \cdot AX \) then there exists \( j \) and \( v \) such that \( (\xi'', j \cdot v) \in \Phi \) and \( (\xi', j \cdot v) \in I \). At last, since \( (\sigma, \theta) \in \text{Sol}(C) \) implies that for all \( X \in \text{vars}^2(C), X \theta \) conforms to \( \Phi \) w.r.t. \( \text{NoUse} \) and for all \( \xi'' \in \text{st}(\xi_i) \), \( \xi_i \in I \) for \( i \in \{1, \ldots, n\} \), \( \xi_i \in I \).

We conclude by applying our inductive hypothesis on \( \xi_i \), for all \( i \in \{1, \ldots, n\} \).

Lemma C.36. Let \( C = (S_1; S_2; \Phi; D; Eq; Er; ND; NoUse) \) be a well-formed constraint system obtained by following the strategy and \( (\sigma, \theta) \in \text{Sol}(C) \). Let \( \xi \) be a ground recipe in \( \Pi_n \) such that \( \xi \in I \). We prove that there exists \( \xi' \) a recipe in \( \Pi_n \) such that:

- \( \xi' \) conforms with \( \Phi \) w.r.t. \( \text{NoUse} \);
- \( \xi(\Phi \sigma) \downarrow = \xi'(\Phi \sigma) \downarrow \) and
- \( \text{param}^c_{\text{max}}(\xi') \leq \text{param}^c_{\text{max}}(\xi) \).

Proof. We prove this lemma by induction on \( |\xi| \).

Base case \( |\xi| = 0 \): In such a case, the result trivially holds.

Inductive step \( |\xi| > 0 \): We do a case analysis on \( C[\xi] \):

- Case 1: \( C[\xi] \in \tau (F^+_d \cdot AX) \). By definition of \( C[\xi] \), we know that there exists \( \xi, i \cdot v \in I \) such that \( \text{path}(\xi) = \text{path}(\xi_i) \) and \( \sigma(\Phi \sigma) \downarrow = \sigma(\Phi \sigma) \downarrow \). Since \( \xi(\Phi \sigma) \downarrow \), we deduce that \( \xi_i(\Phi \sigma) \downarrow = \xi(\Phi \sigma) \downarrow \). Moreover, relying on Lemma \( \xi \), we can deduce that \( \xi(\Phi \sigma) \downarrow = \xi'(\Phi \sigma) \downarrow \).

Case 1. a: \( (\xi, i \cdot v) \in I \). Let \( \Theta = \text{ngu}(Er) \). In such a case, since \( C \) is a well-formed constraint system (Definition \( \xi \)), we know that there exists \( X \in \text{vars}^2(C) \) such that \( C[X \Theta] \text{acc}^1(C) = u \) and \( \text{param}^c_{\text{max}}(X \Theta) < i \). Since we proved that \( i \leq \text{param}^c_{\text{max}}(\xi) \), we can deduce that \( \text{param}^c_{\text{max}}(X \Theta) < \text{param}^c_{\text{max}}(\xi) \).

But since \( \sigma(\Phi \sigma) \downarrow \), we know that \( \sigma = Er \) and \( \Phi \sigma \downarrow \). This allows us to conclude for \( \xi' = \Theta \).

Case 1. b: \( (\xi, i \cdot v) \in I \). In such a case, let \( \xi' = \xi \). Since \( C \) is a well formed constraint system (Definition \( \xi \)), we know that \( \text{param}^c_{\text{max}}(\xi) \leq i \). Since \( \sigma(\Phi \sigma) \downarrow \), we deduce that \( \text{param}^c_{\text{max}}(\xi) \leq \text{param}^c_{\text{max}}(\xi) \).

At last, since we assumed that \( (\xi, i \cdot v) \in I \), we deduce that \( \xi' = \xi \).

Case 2: root(\( C[\xi] \)) \( \in F_c \). By definition of \( C[\xi] \), there exists \( i_1, \ldots, i_n \in I \) such that \( \xi = f(i_1, \ldots, i_n) \) and \( i \in F_c \). But for any \( i = 1 \ldots n \), we have \( \text{param}^c_{\text{max}}(i_n) \leq \text{param}^c_{\text{max}}(i) \) and \( |\xi| < |\xi| \). Thus, by our inductive hypothesis, we can deduce that there exists \( i_1', \ldots, i_n' \in I \) such that for all \( i = 1 \ldots n \),
We conclude that such position

$\xi \in \text{Proof.}$

Let $\xi = f(\xi_1, \ldots, \xi_n)$. Since $f \in F_c$, we can deduce that:

- $f(\xi_1, \ldots, \xi_n)$ conforms with $\Phi \sigma$ w.r.t. $\text{NoUse}\theta$;
- $\xi(\Phi \sigma) \downarrow = \xi'(\Phi \sigma) \downarrow$;
- $\text{param}(\xi) \subseteq \{ax_1, \ldots, ax_j\}$ implies $\text{param}(\xi') \subseteq \{ax_1, \ldots, ax_j\}$, for any $j$.

Let $\xi = f(\xi_1, \ldots, \xi_n)$. Since $f \in F_c$, we can deduce that:

- $f(\xi_1, \ldots, \xi_n)$ conforms with $\Phi \theta$ w.r.t. $\text{NoUse}\theta$;
- $\xi(\Phi \sigma) \downarrow = f(\xi_1, \ldots, \xi_n)\Phi \sigma \downarrow = f(\xi', \ldots, \xi_n)\Phi \sigma \downarrow = \xi'(\Phi \sigma) \downarrow$;
- $\text{param}_{\text{max}}^C(\xi') = \max \{\text{param}_{\text{max}}^C(\xi_i) | i \in \{1, \ldots, n\}\}$ and so $\text{param}_{\text{max}}^C(\xi') \leq \text{param}_{\text{max}}^C(\xi)$.

- $\text{root}(C[\xi_\Phi]) \in F_d$. By definition of $C[\xi_\Phi]$, there exists $\xi_1, \ldots, \xi_n \in \Pi_n$ such that $\xi = g(\xi_1, \ldots, \xi_n)$ and $g \in F_d$. As in Case 2, we can apply our inductive hypothesis on each $\xi_i$. Thus, we will also have that there exists $\xi'_1, \ldots, \xi'_n$ such that:

- $\xi'_i$ conforms with $\Phi \theta$ w.r.t. $\text{NoUse}\theta$;
- $\xi_i(\Phi \sigma) \downarrow = \xi'_i(\Phi \sigma) \downarrow$;
- $\text{param}_{\text{max}}^C(\xi_i) \leq \text{param}_{\text{max}}^C(\xi'_i)$.

Let $\xi' = g(\xi'_1, \ldots, \xi'_n)$. In order to conclude, we have to show that $\xi' = g(\xi'_1, \ldots, \xi'_n)$ conforms with $\Phi \theta$ w.r.t. $\text{NoUse}\theta$. We do a case analysis:

Case 3.a: if $\text{root}(\xi_1') \in F_c$, then we have that $g(\xi_1', \ldots, \xi_n') \notin \Pi_n$. But we know that $g(\xi_1', \ldots, \xi_n')\Phi \sigma \downarrow \in T(F_c, N)$ which means that $g$ is reduced by a rewriting rule $\ell \rightarrow r$. But all the rewriting rules we consider are defined such that $g$ is reduced then it implies there exists a subterm $\zeta$ of $\xi$ such that $\zeta(\Phi \sigma) = g(\xi_1', \ldots, \xi_n')\Phi \sigma \downarrow = g(\xi_1, \ldots, \xi_n)\Phi \sigma \downarrow$. Since $\xi_1'$ conforms with $\Phi \theta$ w.r.t. $\text{NoUse}\theta$, then so does $\xi'$, which allows us to conclude.

Case 3.b: Otherwise, we deduce that $\xi' \notin \Pi_n$. Moreover, if there exists $(\zeta, i \succ u) \in \Phi$ such that $\text{path}(\zeta) = g:\text{path}(\zeta_i)$, then we apply the same reasoning as Case 1. Else it implies that $C[\xi_\Phi] = g(C[\xi'_1], \ldots, C[\xi'_n])$ and since $\xi'_i, i = 1 \ldots n$ are all conform to $\Phi \theta$ w.r.t. $\text{NoUse}\theta$, we conclude that $\xi'$ conforms to $\Phi \theta$ w.r.t. $\text{NoUse}\theta$.

Lemma C.37. Let $C = (S_1; S_2; \Phi; D; E_1; E_2; \text{ND}; \text{NoUse})$ be a well-formed constraint system obtained by following the strategy and $(\sigma, \theta) \in \text{Sol}(C)$. Let $s \in \mathbb{N}$. Assume that $\text{Dest}(\zeta, \ell \rightarrow r, s)$ is useless $C$ for any $\zeta, \ell \rightarrow r$. For all ground recipe $\xi \in \Pi_n$, if $\xi$ conforms to $\Phi \theta$ w.r.t. $\text{NoUse}\theta$, $\xi(\Phi \sigma) \downarrow \in T(F_c, N)$ and $\text{param}(\xi) \subseteq \{ax_1, \ldots, ax_s\}$ then $C[\xi_\Phi] \in T(F_c, F_d^* \cdot A)$.

Proof. Let $p$ the position of the smallest subterm of $C[\xi_\Phi]$ such that $\text{root}(C[\xi_\Phi]) \in F_d$. Hence, we deduce that $\xi_p = g(\xi_1, \ldots, \xi_n)$ and $g \in F_d$. Moreover, since $\xi$ conforms to $\Phi \theta$ w.r.t. $\text{NoUse}\theta$, $\xi \in \Pi_n$ and by the minimality of $C[\xi_\Phi]$, we deduce that there exists $(\zeta, i \succ u) \in \Phi$ such that $\xi_1 = \emptyset$ and $(\zeta, i \succ u) \notin \text{NoUse}$. Since $C$ is well-formed, we know that $\text{param}_{\text{max}}^C(\zeta) \leq i$. Furthermore, since $(\sigma, \theta) \in \text{Sol}(C)$, and so $\text{param}_{\text{max}}^C(\theta) \leq i$. Moreover, since $C$ is obtained by following the strategy then thanks to Lemma C.33, $C$ satisfies InvGeneral. Thus we deduce that $ax_i \in \text{st}(\zeta)$ and so $\text{param}_{\text{max}}^C(\theta) = i$. But $\zeta \in \text{st}(\xi)$ and $\text{param}(\zeta) \subseteq \{ax_1, \ldots, ax_s\}$ hence $i \leq s$.

Thus thanks Dest$(\zeta, \ell \rightarrow r, s)$ being useless on $C$ with $\ell \rightarrow r$ the rewrite rule associated to $g$, we deduce that:

- either there exists $(\zeta', p' \succ v') \in \Phi$ for some $\zeta'$ such that $\text{path}(\zeta') = g:\text{path}(\zeta)$ and some $p'$ such that $p' \leq s$. But $\text{path}(\zeta_p) = g:\text{path}(\zeta_1) = g:\text{path}(\zeta)$. Thanks to $C$ being well-formed (Definition S.24 item 1), we know that $\text{path}(\zeta)$ is closed hence $\text{path}(\zeta_p) = \text{path}(\zeta')$. This is a contradiction with the fact that $\text{root}(C[\xi_\Phi]) \in F_d$.

- else $\text{ND} \equiv \forall \bar{x}. u \neq u_1 \land \ldots \land \neq u_n$ where $g(u_1, \ldots, u_n) \rightarrow w$ is a renaming of $\ell \rightarrow r$. But $(\sigma, \theta) \in \text{Sol}(C)$ implies $\sigma \equiv \text{ND}$. Moreover, $\xi \in \Pi_n$ and $\xi(\Phi \sigma) \downarrow$ implies, thanks to Lemma C.35 that $\xi_p = g(\xi_1, \ldots, \xi_n)(\Phi \sigma) \downarrow$. Hence along with the hypothesis $\text{param}(\xi) \subseteq \{ax_1, \ldots, ax_s\}$, this is a contradiction with $\sigma \equiv \text{ND}$.

We conclude that such position $p$ does not exist and so $C[\xi_\Phi] \in T(F_c, F_d^* \cdot A)$. □
C.5.2 Order relation on second order variables

In this subsection, we state some properties regarding the relation $<_\theta$ described in Definition 8.33.

**Lemma C.38.** Let $C = (S_1; S_2; \Phi; D; Eq; Er; ND; NoUse)$ be a well-formed constraint system. Let $(\sigma, \theta)$ be a pre-solution of $C$. Let $X, Y \in \text{vars}^2(D)$ such that $X <_\theta Y$. We have that $X \theta$ is a strict subterm of $Y \theta$.

**Proof.** $X <_\theta Y$ implies that there exist $X_1, \ldots, X_n \in \text{vars}^2(D)$ such that $X <_\theta X_1 <_\theta \ldots <_\theta X_n <_\theta Y$, and if we rename $X, Y$ into $X_0, X_{n+1}$ then we have that for all $i \in \{0, \ldots, n\}$, $X_i \in \text{vars}^2(C[X_{i+1}] \text{acc}^2(C))$ and $X_i \neq X_{i+1}$.

Since $(\sigma, \theta)$ is a pre-solution of $C$, we know that for all $X \in \text{vars}^2(C)$, $X \theta$ conforms to the $\Phi \theta$ w.r.t. $\text{NoUse}$. Moreover, for all $i \in \{0, \ldots, n\}$, $X_i \in \text{vars}^2(C[X_{i+1}] \cap \text{acc}^2(C))$ implies that there exists $(\xi, k > u) \in \Phi$ such that $X_i \in \text{vars}^2(\xi)$ and $\text{path}(\xi) \in \text{st}(C[X_{i+1}] \Phi)$. Thanks to $C$ being well-formed, we know that $\text{path}(\xi) \in \text{path} \cdot A\text{Y}$ and exists hence $X_i$ is a strict subterm of $\xi$ which implies that $X \theta$ is a strict subterm of $\theta$. But $X_{i+1} \theta$ is conform to $\Phi \theta$ w.r.t. $\text{NoUse}$, and thus we have that $\theta \theta$ is a strict subterm of $X_{i+1} \theta$.

A simple induction on $n$ allows us to conclude that $X_0 \theta$ is a strict subterm of $X_{n+1} \theta$ and so $X \theta$ is a strict subterm of $Y \theta$.

**Lemma C.39.** Let $C = (S_1; S_2; \Phi; D; Eq; Er; ND; NoUse)$ be a well-formed constraint system. Let $(\sigma, \theta)$ be a pre-solution of $C$. We have that $<_\theta$ is a strict partial order.

**Proof.** Since $(\sigma, \theta)$ is a pre-solution of $C$, we have that for all $X \in \text{vars}^2(D)$, $X \theta$ conforms to $\Phi \theta$ w.r.t. $\text{NoUse}$. By definition, $<_\theta$ is a strict partial order if, and only if:

- $\neg(X <_\theta X)$ (irreflexivity)
- if $X <_\theta Y$ then $\neg(Y <_\theta X)$ (asymmetry)
- if $X <_\theta Y$ and $Y <_\theta Z$ then $X <_\theta Z$ (transitivity)

By Definition 8.33, we already know that $<_\theta$ is closed by transitivity. Assume first that $X <_\theta X$. Thanks to Lemma C.38, we know that $X \theta$ is a strict subterm of $X \theta$ which is impossible. For the same reason, $X <_\theta Y$ and $Y <_\theta X$ would imply that $X \theta$ is a strict subterm of $X \theta$, hence the contradiction.

**Lemma C.40.** Let $C = (S_1; S_2; \Phi; D; Eq; Er; ND; NoUse)$ be a well-formed constraint system obtained by following the strategy. Let $(\sigma, \theta) \in \text{Sol}(C)$. Let $X, Y \in \text{vars}^2(D)$, we have that $X <_\theta Y$ implies that $\text{param}^c_{\text{max}}(X) \leq \text{param}^c_{\text{max}}(Y)$.

**Proof.** Thanks to Lemma 8.33 item 11, we know that for all $(\xi, i > u) \in \Phi$, $ax_i \in \text{st}(\xi \theta)$. Furthermore, since $C$ is well formed (Definition 8.22 item 3), we deduce that $\text{param}_{\text{max}}^c(\xi) \leq i$. Moreover, $(\sigma, \theta) \in \text{Sol}(C)$ implies that for all $Y \in \text{vars}^2(\xi)$, $\text{param}^c_{\text{max}}(Y \theta) \leq \text{param}^c_{\text{max}}(Y)$. Thus with $ax_i \in \text{st}(\xi \theta)$, we deduce that $\text{param}^c_{\text{max}}(\xi \theta) = i$.

We have that $X <_\theta Y$ and thus there exist $X_1, \ldots, X_n \in \text{vars}^2(D)$ such that $X <_\theta X_1 <_\theta \ldots <_\theta X_n <_\theta Y$ and if we rename $X, Y$ into $X_0, X_{n+1}$ then for all $i \in \{0, \ldots, n\}$, $X_i \in \text{vars}^2(C[X_{i+1}] \text{acc}^2(C))$ and $X_i \neq X_{i+1}$.

Let $i \in \{0, \ldots, n+1\}$. We know that there exist $u_i$ and $k_i$ such that $(X_i, k_i \vdash u_i) \in D$. Since $(\sigma, \theta) \in \text{Sol}(C)$, we have that $\text{param}(X_i \theta) \subseteq \{ax_1, \ldots, ax_{k_i}\}$.

But $X_i \in \text{vars}^2(C[X_{i+1}] \text{acc}^2(C))$ implies that there exists $(\xi, j > u) \in \Phi$ such that $\text{path}(\xi) \in \text{st}(C[X_{i+1}])$ and $X_i \in \text{vars}^2(\xi)$. Furthermore, since $X_{i+1} \theta$ conforms with $\Phi \theta$ w.r.t. $\text{NoUse}$, we can deduce that $\xi \in \text{st}(\xi \theta)$. We have seen that $ax_j \in \text{st}(\xi \theta)$, we can deduce that $j \leq k_{i+1}$. At last, since $X_i \theta \in \text{st}(\xi \theta)$, $\text{param}(X_i \theta) \subseteq \{ax_1, \ldots, ax_{k_i}\}$ and $\text{param}(\xi \theta) \subseteq \{ax_1, \ldots, ax_j\}$, we can deduce that $k_i \leq j$ which implies $k_i \leq k_{i+1}$ and so $\text{param}^c_{\text{max}}(X_i) \leq \text{param}^c_{\text{max}}(X_{i+1})$. Altogether, this allows us to conclude that $\text{param}^c_{\text{max}}(X_0) \leq \ldots \leq \text{param}^c_{\text{max}}(X_{n+1})$ and so $\text{param}^c_{\text{max}}(X) \leq \text{param}^c_{\text{max}}(Y)$. 


Lemma C.41. Let $\mathcal{C} = (S_1; S_2; \Phi; D; Eq; Er; ND; NoUse)$ be a well-formed constraint system obtained by following the strategy. Let $(\sigma, \theta) \in \text{Sol}(\mathcal{C})$. Let $\xi$ be a ground recipe in $\Pi_n$ and $(X, i \vdash u) \in D$ such that:

- $\xi$ conforms to $\Phi$ w.r.t. $\text{NoUse}\theta$ and $\text{param}(\xi) \subseteq \{ax_1, \ldots, ax_i\}$.
- there exists a position $p$, such that $\xi' = X\theta[p], \xi' \Phi \sigma_\downarrow = \xi \Phi \sigma_\downarrow$, and $C_0 = C_1[C_2]_p$ where $C_0 = C[X\theta[p]], C_1 = C[X\theta]$ and $C_2 = C[\xi]$.
- for all $Y \in \text{vars}^2(C[\xi \text{acc}^2(C)])$, $\neg(X <_\theta Y)$.

Then there exists $\theta'$ such that $(\sigma, \theta')$ is a pre-solution of $\mathcal{C}$ with $\theta' \models \text{mgu}(Er)$, $X\theta' = X\theta[p]$ and for all $Y \in \text{vars}^2(D) \setminus \{X\}$, $C[Y\theta][\Phi\text{acc}^2(C)] = C[Y\theta'][\Phi\text{acc}^2(C)]$.

Proof. Since we assume that $\mathcal{C}$ is well-formed (Definition 8.2 item 2), the path of any recipe of a frame element of $\Phi$ is closed hence for all $\xi$, for all $\theta$, $C[\xi]_{\Phi\theta} = C[\xi]_{\Phi\theta'}$. Hence we omit the substitution in the context. Let $\theta'$ be a substitution defined as follows:

- for all $Y \in \text{vars}^2(D)$ such that $\neg(X <_\theta Y)$, $Y\theta' \overset{\text{def}}{=} Y\theta$
- $X\theta' \overset{\text{def}}{=} X\theta[p]$
- Otherwise, $Y\theta' \overset{\text{def}}{=} C[Y\theta][\Phi\text{acc}^2(C)]\theta'$, where $Y \in \text{vars}^2(D)$
- for all $Y \in \text{vars}^2(C) \setminus \text{vars}^2(D)$, $Y\theta' = Y\text{mgu}(Er)\theta'$

First, we need to justify that the substitution $\theta'$ is well-defined. By Lemma [C.39] we know that the relation $<_\theta$ is a strict partial order. Let $Y \in \text{vars}^2(D)$ such that $X <_\theta Y$ and so $Y\theta' = C[Y\theta][\Phi\text{acc}^2(C)]\theta'$. But for all $Z \in \text{vars}^2(C[Y\theta][\Phi\text{acc}^2(C)])$, we have $Z <_\theta Y$. Since the relation $<_\theta$ is a strict partial order on $\text{vars}^2(D)$, we conclude that $Y\theta'$ is well-defined. At last, for all $Y \in \text{vars}^2(C) \setminus \text{vars}^2(D)$, for all $X \in \text{vars}^2(Y\text{mgu}(Er))$, $X \in \text{vars}^2(D)$. Since $\theta'$ is well defined on any variables in $\text{vars}^2(D)$, we conclude that $\theta'$ is well-defined on all variable of $\mathcal{C}$.

Now, it remains to prove the three expected properties.

Property 1. $X\theta' = X\theta[p]$. By definition of $\theta'$, we know that $X\theta' = X\theta[p]$, hence the result trivially holds.

Property 2. $\theta' \equiv \text{mgu}(Er)$: By definition, for all $Y \in \text{vars}^2(C) \setminus \text{vars}^2(D)$, $Y\theta' = Y\text{mgu}(Er)\theta'$. Hence, we trivially deduce that $\theta' \equiv \text{mgu}(Er)$.

Property 3. for all $Y \in \text{vars}^2(D) \setminus \{X\}$, $C[Y\theta][\Phi\theta] = C[Y\theta'][\Phi\theta']$: For any variable $Y \in \text{vars}^2(D)$ such that $\neg(X <_\theta Y)$, we have that $Y\theta' = Y\theta$ which means that $C[Y\theta][\Phi\theta] = C[Y\theta'][\Phi\theta']$. Moreover, for all $Y \in \text{vars}^2(C) \setminus \{X\}$, if $X <_\theta Y$ then $Y\theta' = C[Y\theta][\Phi\text{acc}^2(C)]\theta'$. But since $Y\theta'$ is a ground recipe, then $\text{st}(C[Y\theta][\Phi\text{acc}^2(C)]) \cap \text{dom}(\text{acc}^2(C)) \subseteq (F_{\Phi\cdot AX})$ and for all $w \in \text{dom}(\text{acc}^2(C)) \cap (F_{\Phi\cdot AX})$, we have $C[w\text{acc}^2(C)]\Phi = C[w\text{acc}^2(C)]\Phi \ (= w)$. Therefore, we have that $C[Y\theta'][\Phi\theta'] = C[Y\theta'][\Phi\theta']$.

Property 4. $(\sigma, \theta')$ is a pre-solution of $\mathcal{C}$, i.e.

- for every $Y \in \text{vars}^2(C)$, we have that $Y\theta'$ conforms to the frame $\Phi\theta'$ w.r.t. $\text{NoUse}\theta$, and
- for every $(Y, j \vdash v)$ in $D$, we have that $(Y\theta')(\Phi\sigma)\downarrow = v\downarrow$ and $\text{param}(Y\theta') \subseteq \{ax_1, \ldots, ax_j\}$.

Thanks to $\mathcal{C}$ being well-formed (Definition 8.2 item 7), we know that for all $Y \in \text{vars}^2(C)$, $C[Y\text{mgu}(Er)] \in \mathcal{T}(F_{\Phi\cdot AX} \cup X^2)$ and for all $\zeta \in \text{st}(Y\text{mgu}(Er))$, $\text{path}(\zeta) \in F_{\Phi\cdot AX}$ implies that there exists $j$ and $v$ such that $\langle \zeta, j \triangleright v \rangle \in \Phi$. Since $\theta \equiv Er$, we deduce that $C[Y\theta] = C[Y\text{mgu}(Er)] \mid X \mapsto C[\Phi\theta] \mid Z \in \text{vars}^2(C[Y\text{mgu}(Er)] \}$. But by definition, for all $Y \in \text{vars}^2(C) \setminus \text{vars}^2(D)$, $Y\theta' = \text{mgu}(Er)\theta'$. Hence, along with $\mathcal{C}$ satisfying InvGeneral (Definition 8.1 item 3)
thanks to Lemma 8.3, we deduce that Y’ conforms to Φ’ w.r.t. NoUseθ. Thus it remains to prove that for all Y ∈ vars²(C), Y’ conforms to Φ’ w.r.t. NoUseθ. Let Y, j ⊢ v be a deducibility constraint in D. We prove the results by induction on <θ.

Base case 1: \( \neg(X <_\theta Y) \). In such a case, we have that Y’ = Yθ. Thus, we have (Y’θ)Φσ↓ = (Yθ)Φσ↓ and param(Y’θ) = param(Yθ) ⊆ \{ ax_1, \ldots, ax_j \}. Furthermore, by definition of <θ, we have that for all Z ∈ vars²(C[Yθ]Φacc²(C)), Z <θ Y and so \( \neg(X <_\theta Z) \). Thus, Zθ = Zθ’. With Y’ = Yθ and Yθ conforms with Φθ w.r.t. NoUseθ, we can deduce that Y’ also conforms with Φθ w.r.t. NoUseθ.

Base case 2: Y = X. In such a case, we have that Xθ = Xθ[ξ]p. By hypothesis, we know that ξ(Φσ)↓ = Xθ[ξ]pΦσ↓. Thus, we have that Xθ[ξ]pΦσ↓ = Xθ[ξ]pΦσ↓. Furthermore, we also know that param(ξ) ⊆ \{ ax_1, \ldots, ax_1 \} and param(Xθ) ⊆ \{ ax_1, \ldots, ax_1 \}. Thus we can conclude that param(Xθ[ξ]p) ⊆ \{ ax_1, \ldots, ax_1 \}.

By hypothesis, we know that for all Z ∈ vars²(C[ξ]Φacc²(C)), \( \neg(X <_\theta Z) \) which means that Zθ’ = Zθ and so ξ conforms with Φθ w.r.t. NoUseθ. By definition of <θ, we have that for all Z ∈ vars²(C[Xθ]Φacc²(C)), Z <θ X which means that Zθ’ = Zθ and so Xθ conforms with Φθ w.r.t. NoUseθ. Therefore, since by hypothesis we have that C[Xθθ] = C[Xθθ[C[ξ]p]]p, we can conclude that Xθ’ = Xθ[ξ]p conforms with Φθ w.r.t. NoUseθ.

Inductive case X <θ Y: In such a case, Y’θ = C[Yθ]Φacc²(C)θ. We know by definition of <θ that if Z ∈ vars²(C[Yθ]Φacc²(C)) then Z <θ Y. Hence by Lemma C.40, param^C max(Z) ≤ param^C max(Y) which implies that there exists a constraint (Z, ℓ, r) ∈ D with ℓ ≤ j. Therefore, thanks to our induction hypothesis, we deduce that \( (Y’θ)(ωσ)_↓ = rσ_↓ \) and param(Zθ’) ⊆ \{ ax_1, \ldots, ax_ℓ \}.

Let w ∈ st(C[Yθθ])/(F^Aθ).AX. Hence there exists (ξ, ℓ, r) ∈ Φ such that ξ = wacc²(C)θ’. We already show that for all Z ∈ vars²(ξ) with (Z, ℓ, r) ∈ D, Zθ(Φσ)↓ = rσ↓ and param(Zθ) ⊆ \{ ax_1, \ldots, ax_ℓ \}. Hence, thanks to C being well-formed (Definition S.2 item 3), we deduce that ξ(Φσ)↓ = r↓ = ξ(Φσ)↓. Moreover, once again thanks to C being well-formed (Definition S.2 item 3), param(ξ(θ)θ) ⊆ \{ ax_1, \ldots, ax_ℓ \} and so param(wacc²(C)θ’) ⊆ \{ ax_1, \ldots, ax_ℓ \}. At last, since (σ, θ) ∈ Sol(C) and thanks to C satisfying InvGeneral (item 1), we deduce that ax_ℓ ∈ st(ξ(θ)) which implies that ax_ℓ ∈ st(Yθ) and so ℓ ≤ j. Hence, we can conclude that Y’(Φσ)↓ = Yθ(Φσ)↓ = νσ↓ and param(Yθ) ⊆ \{ ax_1, \ldots, ax_ℓ \}.

Lastly, by definition of θ’, we have that Y’θ = C[Yθθ]acc²(C)θ’ thus, since Yθ conforms with Φθ w.r.t. NoUseθ, we deduce that Y’θ conforms with the frame Φ’ w.r.t. NoUseθ’.

C.5.3 Preliminaries for soundness of Phase 1 Step a

In this subsection, we are only looking to prove Lemma 8.6 when the strategy is on the first phase of the first step. Hence, according to Subsection 7.4 the only rules that can be applied during this phase are Dest and Eq-left-right. In such a case, thanks to Lemma C.31 the constraint systems or matrices of constraint system we will consider in this subsection all satisfy the invariants PPI1Sa(s) for some s depending on the parameter of the rules Dest and Eq-left-right.

Let T be a set of terms, and u be a term, we denote by nbocc(u, T) the number of occurrences of u in T.

Lemma C.42. Let M be a matrix of constraint systems obtained during phase 1.a with support s by following the strategy. Let C be a constraint system in M with Φ its associated frame, and (σ, θ) ∈ Sol(C). Moreover, let (ξ, s ⊢ u) ∈ Φ and let ζ ∈ Π_n such that:

- param(ζ) ⊆ \{ ax_1, \ldots, ax_{s-1} \},
- ζ(Φσ)↓ = uσ,
C.5. PROOF OF SOUNDNESS

- for all $Y \in \text{vars}^2(\mathcal{C})$, $\xi \notin \text{st}(Y \text{mgu}(Er))$, and

- for all $g \in \mathcal{F}_d$, for all $(\xi', i \succ v) \in \Phi$, $\text{path}(\xi') \neq g \cdot \text{path}(\xi)$.

Either $\text{nbe}_\mathcal{C}(\xi, \{X \theta \mid X \in \text{vars}^2(\mathcal{C})\}) = 0$ or else there exists $\theta'$ such that $(\sigma, \theta') \in \text{Sol}(\mathcal{C})$ and:

$$\text{nbe}_\mathcal{C}(\xi, \{X \theta' \mid X \in \text{vars}^2(\mathcal{C})\}) < \text{nbe}_\mathcal{C}(\xi', \{X \theta' \mid X \in \text{vars}^2(\mathcal{C})\}).$$

Proof. Let $C = (S_1; S_2; \Phi; D; Eq; Er; ND; \text{NoUse})$, $(\sigma, \theta) \in \text{Sol}(\mathcal{C})$, and consider $(X, k \vdash v) \in D$ such that $k \geq s$ and $C[\xi] \in \text{st}(C[X \theta])$. We first show that if such $(X, k \vdash v)$ does not exists, then $\text{nbe}_\mathcal{C}(\xi, \{X \theta \mid X \in \text{vars}^2(\mathcal{C})\}) = 0$. By hypothesis, we know that for all $g \in \mathcal{F}_d$, for all $(\xi', i \succ v) \in \Phi$, $\text{path}(\xi') \neq g \cdot \text{path}(\xi)$. Moreover, since $C$ satisfies $\text{PPISa}(s)$, we know that for all $(\beta, s \succ v) \in \Phi(\mathcal{C})$, either $\beta \in \mathcal{A} \times$ or there exists $X_1, \ldots, X_n \in \mathcal{X}^2$, $f \in \mathcal{F}_d$ and $(\beta', p \succ v) \in \Phi(\mathcal{C})$ such that $\beta = f(\beta', X_2, \ldots, X_n)$ and $p \leq s$. Hence we deduce that for all $(\beta, s \succ v) \in \Phi(\mathcal{C})$, if $\xi \in \text{st}(\beta)$ then $\xi = \beta$. Furthermore, since for all $Y \in \text{vars}^2(\mathcal{C})$, $\xi \not\in \text{st}(Y \text{mgu}(Er))$, then for all $Y \in \text{vars}^2(\mathcal{C})$, $\xi \not\in \text{st}(Y \theta)$ implies that there exists $Z \in \text{vars}^2(D)$ such that $\xi \not\in \text{st}(Z \theta)$. We select $X \in \text{vars}^2(D)$ such that $X \theta$ is the smallest recipe that contain $\xi \theta$. If $X \theta$ does not exists then $\text{nbe}_\mathcal{C}(\xi, \{X \theta \mid X \in \text{vars}^2(\mathcal{C})\}) = 0$ else since $X \theta$ conforms with $\Phi \theta$ w.r.t. $\text{NoUse}_\mathcal{C}$ and for all $(\beta, s \succ v) \in \Phi(\mathcal{C})$, if $\xi \in \text{st}(\beta)$ then $\xi = \beta$, we conclude that $C[\xi] \in \text{st}(C[X \theta])$.

Property 1. We first show for all $\xi \in \Pi_n$, for all position $p$ in $X \theta$, if $\xi \Phi \sigma_\downarrow = (X \theta)[p] \Phi \sigma_\downarrow$, then there exists $\zeta \in \text{st}(\zeta)$ and a position $p'$ such that $p'$ is a prefix of $p$ and $X \theta[\zeta][p \Phi \sigma_\downarrow] = X[\zeta][p'] \Phi \sigma_\downarrow$ and $X \theta[\zeta][p'] \Phi \sigma_\downarrow \in \Pi_n$. We prove this result by induction on the length $|p|$ of $p$.

Base case $|p| = 0$. In such a case we have that $p = \epsilon$. Let $\zeta' = \zeta$ and $p' = p$. We have that $X \theta[\zeta'][p'] \Phi \sigma_\downarrow = \zeta' = \zeta$. Since by hypothesis, we have that $\zeta \in \Pi_n$, the result trivially holds.

Inductive step $|p| > 0$. In such a case, we have that $p = p_1 \cdot r$ for some $r \in \mathbb{N}$ and some $p_1$ such that $|p_1| < |p|$. Assume that $X \theta[p_1] = f(\xi_1, \ldots, \xi_n)$. We have to distinguish two cases:

1. $r = 1$, $f \in \mathcal{F}_d$ and $\text{root}(\xi) \in \mathcal{F}_c$. We know that $X \theta[\Phi \sigma_\downarrow] \in \mathcal{T}(\mathcal{F}_c, \mathcal{N})$ and $X \theta \in \Pi_n$. Thus, by Lemma 6.22, we can deduce that $f(\xi_1, \ldots, \xi_n) \Phi \sigma_\downarrow \in \mathcal{T}(\mathcal{F}_c, \mathcal{N})$, and thus $f$ has been reduced. By hypothesis, we also know that $\xi \Phi \sigma_\downarrow = \xi \Phi \sigma_\downarrow$. If we denote $\xi = (\xi_1, \ldots, \xi_n)$, then by definition of our rewrite rule, we have that $\xi \Phi \sigma_\downarrow = f(\xi_1, \ldots, \xi_n) \Phi \sigma_\downarrow$. Since $\xi \in \Pi_n$, we have also that $\xi \in \Pi_n$. Furthermore, we have $\xi \Phi \sigma_\downarrow = X \theta[p_1] \Phi \sigma_\downarrow$. Thanks to our induction hypothesis, we deduce that there exist $\zeta \in \text{st}(\zeta)$ and $p'$ a prefix of $p_1$ such $X \theta[\zeta][p_1] \Phi \sigma_\downarrow = X \theta[\zeta][p_1] \Phi \sigma_\downarrow$ and $X \theta[\zeta][p_1] \Phi \sigma_\downarrow \in \Pi_n$. Let $\zeta' = \zeta$ and $p' = p$. This allows us to conclude.

2. Otherwise: By definition of $\Pi_n$, we have that $X \theta[\zeta][p] \in \Pi_n$, and thus the result holds with $\zeta' = \zeta$ and $p' = p$.

Property 2. We show that for all $\xi \in \Pi_n$ such that $\text{param}(\zeta) \subseteq \{ax_1, \ldots, ax_k\}$, for all $(\sigma, \theta) \in \text{Sol}(\mathcal{C})$, for all position $p \in \text{Pos}(C[X \theta])$, if $\xi \Phi \sigma_\downarrow = (X \theta)[p] \Phi \sigma_\downarrow$, $\zeta$ conforms to $\Phi \theta$ w.r.t. $\text{NoUse}_\mathcal{C}$, for all $Y \in \text{vars}^2(C[\zeta][\text{acc}^2(\mathcal{C})])$, $\neg (X < \theta Y)$ and $\text{nbe}_\mathcal{C}(C[\xi], C[X \theta][p]) < \text{nbe}_\mathcal{C}(C[\xi], C[X \theta])$ then there exists $\theta'$ such that $(\sigma, \theta') \in \text{Sol}(\mathcal{C})$ and $\text{nbe}_\mathcal{C}(C[\xi], C[Y \theta'] | Y \in \text{vars}^2(\mathcal{C})) < \text{nbe}_\mathcal{C}(C[\xi], C[Y \theta] | Y \in \text{vars}^2(\mathcal{C}))$.

We prove this property by induction on the length $|p|$ of $p$.

Base case $|p| = 0$. In such a case, we can apply Lemma C.41. Indeed, $\zeta$ conforms to $\Phi \theta$ w.r.t. $\text{NoUse}_\mathcal{C}$ and $\text{param}(\zeta) \subseteq \{ax_1, \ldots, ax_k\}$. Furthermore we have $\zeta \Phi \sigma_\downarrow = X \theta[\Phi \sigma_\downarrow]$ and for all $Y \in \text{vars}^2(C[\zeta][\text{acc}^2(\mathcal{C})])$, $\neg (X < \theta Y)$. Hence, we deduce that there exists $\theta'$ such that $(\sigma, \theta')$ is a pre-solution of $C$ with $X \theta' = \zeta$ and for all $Y \in \text{vars}^2(D) \setminus \{X\}$, we have that $C[Y \theta] = C[Y \theta']$. $\theta' \not\equiv \text{mgu}(Er)$, By hypothesis, we know that $\text{nbe}_\mathcal{C}(C[\xi], C[Y \theta]) < \text{nbe}_\mathcal{C}(C[\xi], C[X \theta])$ and since $C[Y \theta] = C[Y \theta']$, for all $Y \in \text{vars}^2(D) \setminus \{X\}$, we can deduce that

$$\text{nbe}_\mathcal{C}(C[\xi], C[Y \theta'] | Y \in \text{vars}^2(D)) < \text{nbe}_\mathcal{C}(C[\xi], C[Y \theta] | Y \in \text{vars}^2(D)).$$
Moreover, by hypothesis on ξ, we know that for all Y ∈ vars^2(C), ξ ∉ st(Y mgu(Er)). Hence, since θ ⊨ mgu(Er) and θ' ⊨ mgu(Er), we deduce that:

\[ nb_{acc}(C[\xi], \{C[Yθ'] | Y \in vars^2(C)\}) < nb_{acc}(C[\xi], \{C[Yθ] | Y \in vars^2(C)\}) \]

Furthermore, (σ, θ) ∈ Sol(C) implies σ ⊨ Eq ∧ ND. At last, C satisfies PP1Sa(s) (item C.22) thus along with θ' ⊨ mgu(Er), we deduce that θ' ⊨ Er and so the result holds. Hence the result holds.

**Inductive step |p| > 0.** In such a case, we have that p = p' · r with r ∈ N and |p'| < |p|. Assume that Xθ|p'| = f(ξ₁, ..., ξₙ). Since ζ(Φσ)↓ = Xθ|p|(Φσ)↓, we have that (Xθ|p'|)[ζ|p](Φσ)↓ = Xθ|p|(Φσ)↓. By definition of (σ, θ) ∈ Sol(C), we know that f(ξ₁, ..., ξₙ) conforms to Φθ. Now, we distinguish several cases:

**Case (a):** f ∈ F_c. In such a case, let ζ' = (Xθ|p'|)[ζ]. Hence we have that Xθ[ζ'|p]' = Xθ[ζ]'p which implies that Xθ[ζ'|p]'(Φσ)↓ = Xθ(Φσ)↓ and Xθ[ζ'|p]' ∈ Π_n.

Moreover, since f ∈ F_c, we have that C[ζ'] = f(C[ζ₁], ..., C[ζₙ−1], C[ζ], C[ζₙ+1], ..., C[ζₙ]). But by hypothesis, ζ and Xθ|p'| are conforms to Φθ w.r.t. NoUse. Hence, ξ₁, ..., ξₙ also conform to Φθ w.r.t. NoUse which implies that ζ' conforms to Φθ w.r.t. NoUse.

Furthermore, we know that Xθ conforms to Φθ w.r.t. NoUse and p ∈ Pos(C[Xθ]) hence C[ζ₁], ..., C[ζₙ] ∈ st(C[Xθ]). Moreover, by definition of <θ, we have for all i ∈ {1, ..., n}, for all Y ∈ vars^2(C[ζₐ acc^2(C)]), Y <θ X. But by Lemma C.30 <θ = a is a strict partial order which means that Y <θ X implies ¬(X <θ Y). Since by hypothesis, we have that for all Y ∈ vars^2(C[ζ acc^2(C)]), ¬(X <θ Y), then we can deduce that for all Y ∈ vars^2(C[ζ acc^2(C)]), ¬(X <θ Y).

At last, Xθ[ζ'|p]' = Xθ[ζ]p and #C[ζ] ∈ st(C[Xθ[ζ]p]) < #C[ζ] ∈ st(C[Xθ]) trivially implies that #C[ζ] ∈ st(C[Xθ[ζ]p']) < #C[ζ] ∈ st(C[Xθ]) trivially implies that #C[ζ] ∈ st(C[Xθ[ζ]p']) < #C[ζ] ∈ st(C[Xθ])

Hence we conclude by applying our inductive hypothesis on θ, ζ' and p'.

**Case (b):** f ∈ F_d, r ≠ 1. This case is similar to Case (a). Indeed, let ζ' = (Xθ|p'|)[ζ]. We have p ∈ Pos(C[Xθ]). Hence C[Xθ|p'|] = f(C[ζ₁], ..., C[ζₙ]) and ζ' = f(C[ζ₁], ..., C[ζₙ]). Thus we can apply the same reasoning as Case (a).

**Case (c):** f ∈ F_d, r = 1 and |C[Xθ|p'|[ζ]|r] = 1. In such a case, we know that C[Xθ|p'|[ζ]|r] = f(C[ζ₁], ..., C[ζₙ]) since |C[Xθ|p'|[ζ]| r] = 1. Thus, similarly to Case (a), we can apply our inductive hypothesis.

**Case (d):** f ∈ F_d, r = 1 and |C[Xθ|p'|[ζ]|r] = 1. In such a case, we have that there exists (γ, ℓ > u) ∈ ζ such that path(γ) = f · path(ζ). Since ζ conforms to Φθ w.r.t. NoUse, we can denote γθ = f(γ, γ₂θ, ..., γ_nθ). Since C is well-formed and (σ, θ) ∈ Sol(C), we also know that γθ(Φσ)↓ = wσ and Xθ(Φσ)↓ ∈ Τ(F_c, N). Thus by Lemma C.3 we can deduce that Xθ|p|(Φσ)↓ ∈ Τ(F_c, N). Therefore, since we have seen that ζ = ζ₁ Φσ↓, we can deduce that for all i ∈ {2, ..., n}, ζ(Φσ)↓ = γ_i Φσ↓. We now distinguish three cases:

- **ℓ < s:** In such a case, let ζ' = γθ. Since (X, k ⊨ v) ∈ D(M_i,j), k ≥ s > ℓ and C is well-formed, we know that for all Y ∈ vars^2(γ), param_max²(Y) = k = param_max²(X). Hence by Lemma C.40 ¬(X <θ Y).

At last, we know that nb_{acc}(C[ζ], C[Xθ|p'|]) < nb_{acc}(C[ζ], C[Xθ]) hence we deduce that C[ζ] ∈ st(C[Xθ|p'|]). Thus along with |C[ζ']| = 1, C[ζ'] ≠ C[ζ] (since s ≠ ℓ), we can deduce that #C[ζ] ∈ st(C[Xθ[ζ']]) < #C[ζ] ∈ st(C[Xθ]) hence we can apply our inductive hypothesis on ζ', θ and p'.

- **ℓ > s:** Such a case is impossible. Indeed, by Property PP1Sa(s), ℓ > s implies that γ ∈ AX which is in contradiction with path(γ) = f · path(ζ).

- **ℓ = s:** Thanks to C satisfying Property PP1Sa(s), we know that γ₂, ..., γ_n ∈ AX^2. We prove our result now by induction on N = # {γ_i | X <θ γ_i, i ∈ {2, ..., n}}.
Proof of the lemma. Relying on Property 1 and Property 2, we are now able to conclude.

We have \( \zeta \in \Pi_n \), \( \text{param}(\zeta) \subseteq \{ax_1, \ldots, ax_{s-1}\} \), \( \xi \Phi \sigma \downarrow = us \sigma \) where \( \xi, s \uparrow u \in \Phi \) and \( X \theta_p = \theta \) where \( p \in \text{Pos}(C[X \theta]) \). But since \( C \) is well formed and \((\sigma, \theta) \in \text{Sol}(C)\), we know that \( \xi \theta(\Phi \sigma) \downarrow = us \sigma = \zeta(\Phi \sigma) \).

Hence by the first property, we can deduce that there exists \( \zeta' \in st(\zeta) \), a position \( p' \) prefix of \( p \) such that \( X \theta[\zeta_p(\Phi \sigma) \downarrow] = X \theta[\zeta'_p(\Phi \sigma) \downarrow] \) and \( X \theta[\zeta'_p] \in \Pi_n \). But we already know that \( X \theta[\zeta'_p(\Phi \sigma) \downarrow] = X \theta[\Phi \sigma] \downarrow \) is \( X \theta[\zeta'_p] \in \Pi_n \). Furthermore \( \zeta' \in st(\zeta) \), \( \zeta' \) conforms to \( \Phi \theta \) w.r.t. \( \text{NoUse} \) thus we have that \( \zeta' \) also conforms to \( \Phi \theta \) w.r.t. \( \text{NoUse} \). At last, \( \text{param}(\zeta) \subseteq \{ax_1, \ldots, ax_{s-1}\} \) and \( \zeta' \in st(\zeta) \) implies that \( \text{param}(\zeta') \subseteq \{ax_1, \ldots, ax_{s-1}\} \).

Let \( Y \in \text{vars}^2(C[\zeta'] \text{acc}^2(C)) \) and assume that \( X <_\theta Y \). Thanks to Lemma \( \text{C.40} \), it implies that \( \text{param}_{\text{max}}(X) \leq \text{param}_{\text{max}}(Y) \) and so \( s \leq k \leq \text{param}_{\text{max}}(Y) \). Furthermore \( Y \in \text{vars}^2(C[\zeta'] \text{acc}^2(C)) \) also implies that there exists \( \gamma, i \uparrow u \in \Phi \) such that \( \gamma \theta \in st(\zeta') \) and \( Y \in \text{vars}^2(\gamma) \). But thanks to \( C \) satisfying InvGeneral, \( ax_i \in st(\gamma) \). Thus with \( \text{param}(\zeta') \subseteq \{ax_1, \ldots, ax_{s-1}\} \), we deduce that \( i \leq s - 1 \). On the other hand, \( Y \in \text{vars}^2(\gamma) \) implies that \( \text{param}_{\text{max}}(Y) \leq i \). Hence we deduce that \( s \leq \text{param}_{\text{max}}(Y) \) which contradicts. Therefore, for all \( Y \in \text{vars}^2(C[\zeta'] \text{acc}^2(C)) \), \( \neg(X <_\theta Y) \).
At last, since \( \text{param}(\zeta') \subseteq \{ax_1, \ldots, ax_{s-1}\} \) and \( ax_s \in st(\xi\theta) \) by the invariant \text{InvGeneral}, we can deduce \( \xi\theta \notin st(\zeta') \), and thus \( C[\xi] \notin st[C[\zeta']] \). Furthermore, by hypothesis, for all \( (\xi', i \triangleright v) \in \Phi \), for all \( g \in \mathcal{F}_d \), we have that \( \text{path}(\xi') \neq g \cdot \text{path}(\xi) \). Since \( \xi\theta = \chi_{\theta_i} \) and \( p' \) is a prefix of \( p \), then \( C[\xi\phi] = (C[N\phi])**{p_i} \), and we can conclude that \( \text{nb}(C[\xi], \{C[X\phi]\}) < \text{nb}(C[\xi], \{C[X\phi]\}) \).

We can now apply the second property which means that there exists \( \theta' \) such that \( (\sigma, \theta') \in \text{Sol}(C) \) and

\[
\text{nb}(C[\xi], \{C[Y\theta'] \mid Y \in \text{vars}^2(C)\}) < \text{nb}(C[\xi], \{C[Y\theta] \mid Y \in \text{vars}^2(C)\})
\]

Once again, since for all \( (\xi', i \triangleright v) \in \Phi \), for all \( g \in \mathcal{F}_d \), we have that \( \text{path}(\xi') \neq g \cdot \text{path}(\xi) \) and for all \( Y \in \text{vars}^2(C), Y\theta' \) conforms to \( \Phi\theta' \) w.r.t. NoUse, then we can deduce that:

\[
\text{nb}(\xi', \{Y\theta' \mid Y \in \text{vars}^2(C)\}) < \text{nb}(\xi', \{Y\theta \mid Y \in \text{vars}^2(C)\}).
\]

\( \square \)

### C.5.4 Soundness

The purpose of this section is to prove the soundness of step 6 of Phase 1 of the strategy, the soundness of the normalisation and the following lemma.

**Lemma 8.6** (soundness). Let \( C \) be a normalised constraint system obtained by following the strategy and \( \text{Rule}(p) \) be a transformation rule applicable on \( C \). Let \( C_1 \) and \( C_2 \) be the two resulting constraint systems obtained by applying \( \text{Rule}(p) \) on \( C \). We denote by \( \Phi, \Phi_1 \) and \( \Phi_2 \) the respective frames of \( C, C_1 \) and \( C_2 \) and we denote by \( S_1 \) the set of free variables of \( C \).

Let \( (\sigma, \theta) \in \text{Sol}(C) \). There exist \( \sigma', \theta' \), and \( i_0 \in \{1, 2\} \) such that \( (\sigma', \theta') \in \text{Sol}(C_{i_0}), \sigma = \sigma'|_{\text{vars}^1(C)} \) and \( \text{init}(\Phi)\sigma = \text{init}(\Phi_{i_0})\sigma' \).

We distinguish two cases:

- An application of a rule during Phase 1, Step a. Note that in such a case, only the rules \( \text{Dest} \) and \( \text{Eq-LEFT-RIGHT} \) are applicable.

- An application of a rule during 1.b, 1.c, 1.d or phase 2. Note that in such a case, only the rules \( \text{Cons}, \text{Axiom}, \text{Eq-LEFT-LEFT}, \text{Eq-RIGHT-RIGHT} \) and \( \text{Ded-ST} \) are applicable.

**An application during phase 1.a.** In such a phase, only the rules \( \text{Dest} \) and \( \text{Eq-LEFT-RIGHT} \) are applicable. Assume that we are on the cycle with parameter for support equal to \( s \). We prove the result by case analysis on the rules.

**Rule \( \text{Dest}(\xi, l \rightarrow r, s) \):** Let \( g(u_1, \ldots, u_s) \rightarrow u \) be a fresh variant of \( l \rightarrow r \) and \( \bar{x} \) be the variables that occur in this variant. Note that \( g \in \mathcal{F}_d \). Let \( (\sigma, \theta) \in \text{Sol}(C) \). We distinguish two cases.

**Case 1:** there exist ground recipes \( \xi_2, \ldots, \xi_n \in \Pi_a \) such that \( g(\xi\theta, \xi_2, \ldots, \xi_n)\Phi\sigma \downarrow \in \mathcal{T}(\mathcal{F}_c, \lambda) \) and \( \text{param}((\xi_2, \ldots, \xi_n)) \subseteq \{ax_1, \ldots, ax_s\} \). To be more specific, since the rule \( \text{Dest}(\xi, l \rightarrow r, s) \) is applicable and the constraint system was obtained by following the strategy, we deduce that \( ax_s \in \text{param}((\xi_2, \ldots, \xi_n)) \) (else \( \sigma \) would not satisfy ND).

First, w.l.o.g., we can assume that for any strict subterm \( \xi_k \) of \( \xi_k \) with \( k \in \{2, \ldots, n\} \), we have that \( \xi_k(\Phi\sigma) \neq \xi_k(\Phi\sigma) \) (otherwise, we can simply choose \( \xi_k \) instead of \( \xi_k \)). Moreover, by Lemma (C.36) we can also assume that \( \xi_2, \ldots, \xi_n \) conform to the frame \( \Phi\theta \). Let \( \tau = \text{mgu}((\xi\theta|_{\Phi\sigma} \downarrow = u_1, \xi_2|_{\Phi\sigma} \downarrow = u_2, \ldots, \xi_n|_{\Phi\sigma} \downarrow = u_n)), and \sigma_1 = \sigma \cup \tau \).

Our goal is to build a substitution \( \theta' \) such that for all \( X \in \text{vars}^2(C_1), X\theta' \) conforms to the frame \( \Phi_1\theta' \) (where \( \Phi_1 \) is the frame associated to \( C_1 \)). In particular, we have to ensure that there is a unique “key” that is used to decrypt \( \xi' \). Actually, we show how to build \( \theta' \) in order to ensure that \( X\theta' \) conforms to \( \Phi_1\theta' \) for every \( X \in \{Y \mid Y, j \not\vdash \tau \in C_1\} \), we conclude for the remaining variables.

Let \( S = \{Y \mid Y, j \not\vdash \tau \} \subseteq C \) and \( g(\xi\theta, \xi_2, \ldots, \xi_n) \in st(\Phi\theta) \) for some \( \xi_2, \ldots, \xi_n \). Notice that for all \( Y \in S, s \leq \text{param}_c^\lambda(Y) \) else \( \sigma \) would not satisfy ND. We distinguish two cases:

**Case a:** \( S = \emptyset \). Let \( \theta' \) be a substitution defined as follows:
\begin{itemize}
  \item $X, \theta' = \xi_i$ for $i = 2 \ldots n$, and
  \item $X\theta = X\theta$ otherwise.
\end{itemize}

In such a case, it is relatively easy to conclude that $(\sigma_1, \theta') \in \text{Sol}(C_1)$. In particular, we have that $X\theta'$ conforms to $\Phi_1, \theta'$ for all variable $X$. First $\Phi_1 = \Phi \cup \{g(\xi, X_2, \ldots, X_n), i > w\}$. For every variable $X \not\in \{X_2, \ldots, X_n\}$, we have $X\theta' = X\theta$, which means that $\Phi \theta' = \Phi \theta$. Since $S = \emptyset$, we easily conclude that $Y\theta'$ conforms to $\Phi_1, \theta'$ for all variables in \{Y | Y,j \in r \in D(C_1)\} \setminus \{X_2, \ldots, X_n\}.

Furthermore, since $\xi_i$ conforms to $\Phi_1$ and by the choice of $\xi_i$, we deduce that $\xi_i$ conforms to $\Phi_1, \theta'$. At last, also by the choice of $\xi_i$, we also deduce that $(X, \theta') \Phi_1 \sigma_1 = \omega_i \sigma_1$ which allows us to conclude.

\textbf{Case b:} $S \not\in \emptyset$. Otherwise, we chose $Y_0$ a minimal variable w.r.t. the relation $<_\theta$ and the maximal parameter. Such minimal exists since by Lemma C.39, the relation $<_\theta$ is a strict partial order.

We have that $g(\xi, \zeta_2, \ldots, \zeta_n) \in st(Y_0 \theta)$ for some recipe $\zeta_2, \ldots, \zeta_n$.

If $\text{param}(\zeta_2, \ldots, \zeta_n) \not\subseteq \{ax_1, \ldots, ax_s\}$ then for each $i \in \{2, \ldots, n\}$, we denote by $\xi_i = \xi_i$, else for each $i \in \{2, \ldots, n\}$, we denote by $\xi_i$ a minimal (for the size) subterm of $\zeta_i$ such that

\[ \zeta_i(\Phi \sigma) \upharpoonright = \xi_i(\Phi \sigma) \downharpoonright. \]

Note that in both cases, for all $i \in \{2, \ldots, n\}$, $\zeta_i(\Phi \sigma) \downharpoonright = \xi_i(\Phi \sigma) \downharpoonright$. Indeed, we know that $g(\xi, \zeta_2, \ldots, \zeta_n) \in st(Y \theta)$, $g(\xi, \zeta_2, \ldots, \zeta_n) \in \Pi_n$ and $Y \theta(\Phi \sigma) \downharpoonright \in T(F_{c.n})$. Hence by Lemma 6.5, $g(\xi, \zeta_2, \ldots, \zeta_n) \in st(Y \theta)$, $g(\xi, \zeta_2, \ldots, \zeta_n) \in T(F_{c.n})$.

Hence since $\text{path}(g(\xi, \zeta_2, \ldots, \zeta_n)) = \text{path}(g(\xi, \zeta_2, \ldots, \zeta_n))$, then by Lemma C.39, $\zeta_i(\Phi \sigma) \downharpoonright = \xi_i(\Phi \sigma) \downharpoonright$, for all $i \in \{2, \ldots, n\}$.

We rely on Lemma C.39 to build a substitution $\theta'$ that will be conformed to the frame $\Phi_1, \theta'$. To achieve this, the idea is to replace any occurrence of $g(\xi, \ldots)$ that occur in $Y \theta$ with $Y \in S$ by $g(\xi, \zeta_2, \ldots, \zeta_n)$. We prove our result by induction on:

\[ m = \text{nb}_{\text{ooc}}(g(\xi, \zeta_2, \ldots, \zeta_n), \{Y \theta | Y \in S\}) - \text{nb}_{\text{ooc}}(g(\xi, \zeta_2, \ldots, \zeta_n), \{Y \theta | Y \in S\}) \]

where $\_\_\_$ is used to represent any value.

\textbf{Base case $m = 0$:} Let $\theta'$ be the substitution defined as follows:

\begin{itemize}
  \item $X, \theta' = \xi_i$ for $i = 2 \ldots n$, and
  \item $X\theta' = X\theta$ otherwise.
\end{itemize}

We conclude as in the previous case ($S = \emptyset$).

\textbf{Inductive case $m > 0$:} Let $Y \in S$ such that there exists $p \in P\text{os}(C[Y \theta])$ such that $\text{path}(Y \theta_p) = g \cdot \text{path}(\xi)$ and $Y \theta_p \neq g(\xi, \zeta_2, \ldots, \zeta_n)$. We first show that such $Y$ and $p$ exists. We know that there is no frame element in $\Phi$ whose recipe has a path equal to $g \cdot \text{path}(\xi)$. Furthermore, thanks to $C$ being well-formed (Definition 6.2, item 6), we deduce that no subterm of a frame of a recipe of a frame element in $\Phi$ has a path equal to $g \cdot \text{path}(\xi)$. Hence, we choose $Y$ minimal w.r.t. $<_\theta$ such that $g(\xi, \gamma_2, \ldots, \gamma_n) \in st(Y \theta)$ for some $\gamma_2, \ldots, \gamma_n$ and $g(\xi, \gamma_2, \ldots, \gamma_n) = g(\xi, \zeta_2, \ldots, \zeta_n)$. We can conclude that there exists $p \in P\text{os}(C[Y \theta])$ such that $\text{path}(Y \theta_p) = g \cdot \text{path}(\xi)$ and $Y \theta_p \neq g(\xi, \zeta_2, \ldots, \zeta_n)$ (otherwise $Y \theta$ would not be minimal w.r.t. $<_\theta$).

Let $\xi_0 = \zeta_0(\Phi \sigma)$. By definition of each $\xi_0$, $i \in \{1, \ldots, n\}$, we know that $\text{param}(\xi_0) \subseteq \{ax_1, \ldots, ax_s\}$. Moreover, $(\sigma, \theta) \in \text{Sol}(C)$ implies $\text{param}(Y \theta_0) \subseteq \{ax_1, \ldots, ax_s\}$ hence $\xi_0$ subterm of $Y_0 \theta$ implies that $\text{param}(\xi_0) \subseteq \{ax_1, \ldots, ax_s\}$.

Since $Y \theta_p$ conforms with $\Phi \theta$ and $\text{path}(Y \theta_p) = g \cdot \text{path}(\xi)$, there exists $\xi_2, \ldots, \xi_n$ such that $Y \theta_p = g(\xi, \zeta_2, \ldots, \zeta_n)$. Furthermore, $\xi$ is a recipe of a frame element in $\Phi$, and there is no frame element in $\Phi$ having $g \cdot \text{path}(\xi)$ as a path. Hence, we have that $C[Y \theta_p, \theta]' = g(\text{path}(\xi), C[\zeta_2]_{\xi \theta}, \ldots, C[\zeta_n]_{\xi \theta})$ and $C[\xi_0]_{\xi \theta} = g(\text{path}(\xi), C[\xi_0]_{\xi \theta})$. Thus, we
deduce that $C[Yθ][c], Yθ[|C[0]][p] = C[Yθ[|C[0]][p]$. We have that $(σ, θ) ∈ Sol(C)$, thus $(Yθ)(Φσ)_↓ ∈ T(Fc,N)$ and $(Yθ)(Φσ)_↓ ∈ T(Fc,N)$. Thanks to Lemma 5.5, $(Yθ)_0(Φσ)_↓ ∈ T(Fc,N)$ and $(C[0])_0(Φσ)_↓ ∈ T(Fc,N)$. Since $path(Yθ)_p = path(0)$, by Lemma C.34, we conclude that $(Yθ)_p(Φσ)_↓ = ζ(Φσ)_↓$.

- Lastly, by definition of $C[0]$, either (a) $ζ^0 = ζ$, for $i ∈ {2, . . . , n}$ and $ζ^0$ are subterms of $Yθ$; or (b) $param(g(ζθ_2, . . . , ζ_n)) = \{ax_1, . . . , ax_k\}$ and $ζ^0 = ζ_i$, for $i ∈ {2, . . . , n}$.

In case (a), since $Yθ, Yθ ∈ S$ and $Yθ$ is a minimal variable, $\equiv$ then we deduce that for all $Z ∈ varC[0]$ we have that $Yθ ∈ varC[0]$ and all $Z ∈ varC[0] \setminus \{Yθ\}$, we have that $C[Zθ] = C[Zθ[Φσ]$. Hence, we have that the measure $m$ strictly decreases. Furthermore, since $(σ, θ) ∈ Sol(C)$ and using the fact that $(σ, θ′)$ is a pre-solution of $C$, it only remains to prove that $θ′ ≡ Er$ in order to conclude that $(σ, θ′) ∈ Sol(C)$. Actually, we know that $θ′ ≡ mgu(ρσ)$ and thanks to $C$ satisfying PP1Sa (item 3), we have trivially have that $θ′ ≡ Er$ and so $(σ, θ′) ∈ Sol(C)$. Then, we conclude by relying on our induction hypothesis.

**Case 2:** for all ground recipes $ξ_2, . . . , ξ_n$ in $Π_2$, either $param(\{ξ_2, . . . , ξ_n\})$ or we have that $g(ξθ_2, . . . , ξ_n)Φσ_↓ \notin T(Fc,N)$. Since $g ∈ F_d, g(ξθ_2, . . . , ξ_n)Φσ_↓ ∈ T(Fc,N)$ means that there exists a substitution $τ$ which maps variable in $x$ to ground constructor terms such that $g(u_1τ, . . . , u_nτ) = g(ξθ(Φσ)_↓, ξ_2(Φσ)_↓, . . . , ξ_n(Φσ)_↓).$ This means that $u_1τ = ξθ(Φσ)_↓, u_2τ = ξ_2(Φσ)_↓, . . . , u_nτ = ξ_n(Φσ)_↓$. Moreover, since $(σ, θ) ∈ Sol(C)$, we have that $(ξθ(Φσ)_↓ = θσ$. Therefore, we have that:

$$σ |= \forall x \cdot [v ≠ u_1 \land s ↑ v_2 \land \ldots \land s ↑ u_n].$$

This allows us to conclude that $(σ, θ) ∈ Sol(C)$.

**Rule EQ-LEFT-SIDE:** By hypothesis we know that there exists $u, v$ and $k$ such that $(X, k \uparrow u) ∈ D(C)$, $(ξ, s \triangleright v) ∈ Finder(C)$ and $k < s$. Furthermore, according to the strategy, we know that the rule EQ-LEFT-SIDE is prioritised over the rule DEST, and that the rule EQ-LEFT-SIDE is strongly applicable on at least on constraint system on the row of the matrix of constraint system. Assume that $C′$ is such constraint system. By hypothesis, $C′$ is normalised. It would imply that there exists $x ∈ X^1$ such that $(X, k \uparrow x) ∈ D(C′)$ and $(ξ, s \triangleright x) ∈ Finder(C′)$. Assume now that there exists $(ξ′, t \triangleright w) ∈ Finder(C′)$ and $g ∈ F_d$ such that $path(ξ′) = g \cdot path(ξ)$, hence it means that an instance of the rule DEST was previously applied on $(ξ, s \triangleright x)$. But according to the definition of our rewrite rules and since $C′$ is normalised, it would imply that $x$ is instantiated by a term different from a variable and so $x \notin X^1$ which is a contradiction. Hence, for all $(ξ′, t \triangleright w) ∈ Finder(C′)$, for all $g ∈ F_d, path(ξ′) \neq g \cdot path(ξ)$. But by Lemma S.1 and since $C$ and $C′$ are on the same row of $M$, we can deduce that $C′$ and $C$ have the same structure and so for all $(ξ′, t \triangleright w) ∈ Finder(C′)$, for all $g ∈ F_d, path(ξ′) \neq g \cdot path(ξ)$.

Let $(σ, θ) ∈ Sol(C).$ We distinguish two cases:
1. \( u\sigma \downarrow = v\sigma \downarrow \). In such a case, we need to transform \( \theta \) such that the frame element \((\xi, s \triangleright v)\) will not be used anymore. Let denote \( Nb(\theta) = \text{n}b_{\text{recl}}(\xi, \{Y \theta \mid Y \in \text{vars}^2(C)\}) \). We show that there exists \( \theta' \) such that \((\sigma, \theta') \in \text{Sol}(C_1)\). We prove this result by induction on \( Nb(\theta) \).

**Base case** \( Nb(\theta) = 0 \): We know that \( C_1 \) is \( C \) where \( \text{NoUse}(C_1) = \text{NoUse}(C) \cup (\xi, s \triangleright v) \) and \( \text{Eq}(C_1) = \text{Eq}(C) \wedge u \models \sigma \models v \). By hypothesis, we already know that \( u\sigma \downarrow = v\sigma \downarrow \), hence \( \sigma \models \text{Eq}(C_1) \). Hence it remains to prove that for all \( Y \in \text{vars}^2(C) \), \( Y \theta \) conforms to \( \Phi \theta \) w.r.t. \( \text{NoUse}(C_1) \). But we already know thanks to \((\sigma, \theta) \in \text{Sol}(C)\) that \( Y \theta \) conforms to \( \Phi \theta \) w.r.t. \( \text{NoUse}(C) \). And since \( Nb(\theta) = 0 \), we can conclude that \( Y \theta \) conforms to \( \Phi \theta \) w.r.t. \( \text{NoUse}(C_1) \) and so \((\sigma, \theta) \in \text{Sol}(C_1)\).

**Inductive step** \( Nb(\theta) > 0 \): Since \((\sigma, \theta) \in \text{Sol}(C)\) and \( u\sigma \downarrow = v\sigma \downarrow \), we have that \( X\theta(\Phi\sigma) \downarrow = \xi \theta(\Phi\sigma) \downarrow \) and \( \text{param}(X\theta) \subseteq \{ax_1, \ldots, ax_k\} \) with \( k < s \). Moreover, we proved that for all \((\xi', \ell \triangleright w) \in \Phi(C)\), for all \( g \in F_{\delta}, \text{path}(\xi') \nsubseteq g \cdot \text{path}(\xi) \). At last, since the rule DEST and \text{EQ-LEFT-RIGHT} does not add equations in \( \text{Er} \) and Step \( a \) is the first step applied during Phase 1 with parameter \( s \), we deduce that \( \xi \notin \text{st}(\text{mg}(\text{Er})) \). Hence by Lemma [Lemma 1.12], we can deduce that there exists \( \theta' \) such that \((\sigma, \theta') \in \text{Sol}(C)\) and \( Nb(\theta') < Nb(\theta) \). Since \((\sigma, \theta') \in \text{Sol}(C)\) and \( u\sigma \downarrow = v\sigma \downarrow \), we have still have that \( X\theta'(\Phi\sigma) \downarrow = \xi \theta'(\Phi\sigma) \downarrow \). Hence, by our inductive hypothesis on \( \theta' \), we can deduce that there exists \( \theta'' \) such that \((\sigma, \theta'') \in \text{Sol}(C_1)\).

2. \( u\sigma \downarrow \neq v\sigma \downarrow \). In such a case, it is easy to see that \((\sigma, \theta) \in \text{Sol}(C_2)\). }

**An application during phase 1.b, 1.c, 1.d or 2.** Rule \text{CONS}(X, f) : Let \((\sigma, \theta) \in \text{Sol}(C)\). We distinguish two cases:

1. \( \text{root}(X \theta) = f \). In such a case, there exists \( \xi_1, \ldots, \xi_n \in \Pi_n \) such that \( X \theta = f(\xi_1, \ldots, \xi_n) \).

Since \((\sigma, \theta) \in \text{Sol}(C)\) and \( f \in F_{\epsilon} \), we deduce that \( \text{param}(X \theta) \subseteq \{ax_1, \ldots, ax_i\} \), and

\[
(X \theta)(\Phi\sigma) \downarrow = f(\xi_1(\Phi\sigma) \downarrow, \ldots, \xi_n(\Phi\sigma) \downarrow) = f(t_1, \ldots, t_n) = \tau \sigma \downarrow
\]

for some terms \( t_1, \ldots, t_n \).

Let \( \theta' = \theta \cup \{X_1 \mapsto \xi_1, \ldots, X_n \mapsto \xi_n\} \) and \( \theta'' = \sigma \cup \{x_1 \mapsto t_1, \ldots, x_n \mapsto t_n\} \). Since \( \Phi(C_1) = \Phi(C) \), we trivially have that \( \Phi\sigma = \Phi \sigma' \) and thus for every \( i \in \{1, \ldots, n\} \), we have that \( (X \theta')(\Phi\sigma) \downarrow = t_i \downarrow \) and \( \text{param}(X \theta') \subseteq \text{param}(X \theta) \subseteq \{ax_1, \ldots, ax_i\} \).

Furthermore, \( t \sigma' = f(t_1, \ldots, t_n) \) and \( x_i \sigma' = t_i \), for all \( i \in \{1, \ldots, n\} \) implies that \( t \sigma' \downarrow = f(x_1, \ldots, x_n) \sigma' \downarrow \).

At last, by definition of \( \theta' \), we also have that \( X \theta' = f(X_1, \ldots, X_n) \theta' \). This allows us to conclude that \((\sigma, \theta'') \in \text{Sol}(C_1)\).

2. \( \text{root}(X \theta) \neq f \). In such a case, we have that \( \theta \models \text{Er} \wedge \text{root}(X) \neq f \) and so we can conclude that \((\sigma, \theta) \in \text{Sol}(C_2)\).

**Rule Axiom(X, path).** Let \((\sigma, \theta) \in \text{Sol}(C)\). We distinguish two cases:

1. \( \text{path}(X \theta) = \text{path} \). In such a case, by definition of \((\sigma, \theta) \in \text{Sol}(C)\), we have that \( X \theta \) conforms to \( \Phi \theta \) w.r.t. \( \text{NoUse} \), and thus \( X \theta = \theta \). We have also that \( (X \theta)(\Phi\sigma) \downarrow = u\sigma \downarrow \). Lastly, since \( C \) is well-formed, we know that \((\xi \theta)(\Phi\sigma) \downarrow = v\sigma \downarrow \). Altogether, this allows us to deduce that \( u\sigma \downarrow = v\sigma \downarrow \). We conclude that \((\sigma, \theta) \in \text{Sol}(C_1)\).

2. \( \text{path}(X \theta) \neq \text{path} \). Since \( \text{path}(\xi \theta) = \text{path} \) and \( \text{path}(X \theta) \neq \text{path} \) implies that \( X \theta \neq \xi \). Thus, \( \theta \models \text{Er} \wedge X \neq \xi \). We can conclude that \((\sigma, \theta) \in \text{Sol}(C_2)\).

**Rule EQ-LEFT-RIGHT(\(\xi_1, \xi_2\)).** Let \((\sigma, \theta) \in \text{Sol}(C)\). We distinguish two cases:

1. \( u_1 \sigma \downarrow = u_2 \sigma \downarrow \). In such a case, it is easy to see that \((\sigma, \theta) \in \text{Sol}(C_1)\).

2. \( u_1 \sigma \downarrow \neq u_2 \sigma \downarrow \). In such a case, it is easy to see that \((\sigma, \theta) \in \text{Sol}(C_2)\).
Thus, in both cases, we easily conclude.

Rule Eq-right-right (X, ξ). Let (σ, θ) ∈ Sol(C). We distinguish two cases:

1. uσ↓ = uσ↓′. In such a case, since (σ, θ) ∈ Sol(C), then for all Y ∈ vars^2(ξ), we have that Yθ conforms to the frame Φθ w.r.t. NoUse. But the conditions of the rule Eq-right-right tell us that ξ ∈ T(F, vars^2(α)) where α = {Y → w | (Y, j ⊨ w) ∈ D(C) ∧ j ≤ i ∧ Y ∈ S_α(C)} which means that C[ξθ]_φθ = ξY → C[Yθ]_φθ | Y ∈ vars^2(ξ)). Thus, we deduce that ξθ conforms to Φθ too.

Moreover, the conditions of the rule Eq-right-right also tell us that v = ξα. By (σ, θ) ∈ Sol(C), we deduce that for all Y ∈ vars^2(ξ), (Yθφσ↓ = (Yα)σ↓. Once again, since ξ ∈ T(F, dom(α)), we have that (ξθ)φσ↓ = uσ = uσ = (Xθ)φσ↓.

We want to conclude the result by applying Lemma [C.41] But in order to do that, we need to prove that for all Y ∈ vars^2(C[ξθ]_φacc^2(C)), ¬(X <θ Y). We prove this property by case analysis on ξ:

Case ξ ∈ vars^2(D): In such a case, we denote ξ by Z and so there exists (Z, j ⊨ v) ∈ D. For all Y ∈ vars^2(C[ξθ]_φacc^2(C)), we have that Y <θ Z by definition of <θ. Hence, if ¬(X <θ Z) then for all Y ∈ vars^2(C[ξθ]_φacc^2(C)), ¬(X <θ Y). We apply Lemma [C.41] on the deducibility constraint X, i ⊨ u with the recipe Zθ; otherwise we have X <θ Z and so since <θ is a strict partial order by Lemma [C.39] we deduce that ¬(Z <θ X). Thus, we apply Lemma [C.41] on the deducibility constraint Z, j ⊨ v with the recipe Xθ. Therefore, in both cases, we know that there exists θ′ such that (σ, θ′) is a pre-solution of C with Xθ′ = Zθ′, θ′ ⊨ mgu(Er) and for all Y ∈ vars^2(D)\{X, Z}, we have C[Yθ]_φθ′ = C[Yθ]_φθ′. At last, by the condition of Eq-right-right, we know that root(X) ≠ f ∈ Er if equivalent to root(Z) ≠ f ∈ Er, thus (relying on the form of the inequations in Er) we can deduce that θ′ ⊨ Er and so (σ, θ′) ∈ Sol(C_1).

Case ξ ∉ vars^2(D): As explained in the strategy (Section 7.4), the rule Eq-right-right with such parameter is only applied when the strategy is on the second phase. But, in such a case, since C satisfies the invariant InvVarFrame(∞), we have that (⋆):

for all (ξ, k ⊨ u) ∈ Φ, for all Z ∈ vars^2(ξ), there exists j < k and z ∈ X^1 such that (Z, j ⊨ z) ∈ D.

Moreover, we proved that C[ξθ]_φθ = ξY → C[Yθ]_φθ | Y ∈ vars^2(ξ)), hence for all Y ∈ vars^2(C[ξθ]_φacc^2(C)), there exists Z ∈ vars^2(ξ) such that Y ∈ vars^2(C[Zθ]_φacc^2(C)). It implies that there exists (ξ, k ⊨ u) ∈ Φ such that Y ∈ vars^2(ξ) and ξ ∈ st(Zθ). Since C also satisfies InvGeneral, we know that aRX ∈ st(ξθ) and so we have that k ≤ param^C_{max}(Z).

But thanks to (⋆), we have that param^C_{max}(Y) < k, which implies that param^C_{max}(Y) < param^C_{max}(Z). But by definition of ξ, we have that Z ∈ vars^2(ξ), and thus we have that param^C_{max}(Z) ≤ param^C_{max}(X), hence we conclude, thanks to Lemma [C.39] that ¬(X <θ Y).

Thus we apply Lemma [C.41] on the deducibility constraint X, i ⊨ u with the recipe ξθ. Therefore, there exists θ′ such that (σ, θ′) is a pre-solution of C with Xθ′ = ξθ and for all Y ∈ vars^2(C)\{X}, we have C[Yθ]_φθ′ = C[Yθ]_φθ′. At last, by the condition of Eq-right-right, we know that root(ξθ) = f implies root(X) ≠ f ∈ Er, thus we can deduce that θ′ ⊨ Er and so (σ, θ′) ∈ Sol(C_1).

2. uσ↓ ≠ uσ↓′. In such a case, it is easy to see that (σ, θ) ∈ Sol(C_2).
Rule Ded-st(\(\xi, f\)). Let (\(\sigma, \theta\)) \(\in\) Sol(C). We distinguish two cases:

1. There exist ground recipes \(\xi_1, \ldots, \xi_n\) in \(\Pi_n\) such that \(f(\xi_1, \ldots, \xi_n)(\Phi \sigma)\downarrow = u\sigma\downarrow\). In such a case, we can assume w.l.o.g. (see Lemma C.36) that \(f(\xi_1, \ldots, \xi_n)\) conforms to \(\Phi \sigma\) w.r.t. NoUse, and thus \(\xi_1, \ldots, \xi_n\) conform also to the frame \(\Phi \theta\) w.r.t. NoUse. For every \(j \in \{1, \ldots, n\}\), let \(t_j = \xi_j(\Phi \sigma)\downarrow\). Let \(\theta' = \theta \cup \{X_1 \mapsto \xi_1, \ldots, X_n \mapsto \xi_n\}\), and \(\sigma' = \sigma \cup \{x_1 \mapsto t_1, \ldots, x_n \mapsto t_n\}\). Clearly, we have that \(X\theta'\) conforms to \(\Phi \theta'\) for every \(X \in \text{vars}(C_1)\). Since \(f\) is a constructor symbol, \(f(\xi_1, \ldots, \xi_n)(\Phi \sigma)\downarrow = u\sigma\downarrow\) implies \(\theta' \vdash u = f(x_1, \ldots, x_n)\). Moreover, since \(m\) is the maximal index that occurs in \(C\), we have that \(\text{param}(X\theta') \subseteq \{ax_1, \ldots, ax_m\}\) and thus \((\sigma, \theta) \in\) Sol(C_1).

2. Otherwise, for all ground recipes \(\xi_1, \ldots, \xi_n\) in \(\Pi_n\), we necessarily have that \(f(\xi_1, \ldots, \xi_n)(\Phi \sigma) \not\downarrow = u\sigma\downarrow\). Since \(f\) is a constructor symbol, we have that

\[
f(\xi_1, \ldots, \xi_n)\Phi \sigma \not\downarrow = f(\xi_1\Phi \sigma \downarrow, \ldots, \xi_n\Phi \sigma \downarrow).
\]

We can distinguish two cases: either root(\(u\sigma\)) \(\not\in\) \(f\) or else there exists \(i \in \{1 \ldots n\}\), terms \(t_1, \ldots, t_n\) such that \(u\sigma = f(t_1, \ldots, t_n)\) and \(\xi_i\Phi \sigma \not\downarrow = t_i\downarrow\) for any ground recipe \(\xi_i\). Therefore, we have that:

\[
\sigma \vdash \forall \bar{x}. \left[ u \neq f(x_1, \ldots, x_n) \lor m \not\models x_1 \lor \ldots \lor m \not\models x_n \right].
\]

This allows us to conclude that \((\sigma, \theta) \in\) Sol(C_2).

Lemma 8.4. Let \(C\) be a constraint system obtained by following the strategy. Sol(C) = Sol(C\downarrow).

Proof. The rules for normalisation presented in Figure 7.3 corresponds to classic transformation on formula of first order logic. Once can easily prove that all the rules in Figure 7.3 preserves the Axiom. Moreover, But AX(\(X, \text{path}\)) is useless for any path, and Dest(\(\xi, \ell \rightarrow r, i\)) is useless for any \(\xi, \ell \rightarrow r\).

Let (\(\sigma, \theta\)) \(\in\) Sol(C). We show that \(x\sigma \neq a\). Thanks to Lemma C.37, \(C[\text{X}\theta]_{\phi} \in \mathcal{T}(\mathcal{F}_c, \mathcal{F}_d \cdot \mathcal{AX})\). Moreover, But AX(\(X, \text{path}\)) is useless for any path. Hence either AX(\(X, \text{path}\)) is not applicable or its application results in two constraint systems \(C_1\) and \(C_2\) such that \(C_1\) simplifies to \(\bot\) using the rules in Figure 7.3 and \(C_2\) simplifies into \(C\). But if there exists \((\xi, j \rightarrow v) \in \Phi\) such that path(\(\xi\)), \(j \leq i\) and \((\xi, j \rightarrow u) \not\in\) NoUse then the application of \(C_1\) add the equation \(x \not\models \xi\) in \(E_r\), and the equation \(x \not\models \xi\) in \(E_q\). Hence \(C_1\) simplifies into \(\bot\) implies that \(X\theta \neq \xi\) or \(x\sigma \neq \psi\sigma\). However, thanks to \(C\) being well-formed (Definition S.2) item 5 and \((\sigma, \theta) \in\) Sol(C), we deduce that \(X\theta(\Phi \sigma)\downarrow = x\sigma\) and \(\xi\theta(\Phi \sigma)\downarrow = \psi\sigma\). Hence \(x\sigma \neq \psi\sigma\) implies \(X\theta \neq \xi\).

Hence AX(\(X, \text{path}\)) is useless for any path implies that for all \((\xi, j \rightarrow v) \in \Phi(C)\), if \(j \leq i\) and \((\xi, j \rightarrow v) \not\in\) NoUse then \(X\theta \neq \xi\). But we know that \(C\) satisfies InvGeneral thus for all \((\xi, j \rightarrow v) \in \Phi(C)\), \(ax_j \in \text{st}(\xi\theta)\). Thus, paramX(\(\Phi \sigma\)) \(\subseteq\) \(\{ax_1, \ldots, ax_i\}\) and \(X\theta\) conforms to \(\Phi \sigma\) w.r.t. NoUse. Hence AX(\(X, \text{path}\)) is useless for any path and \(\text{param}(X\theta) \subseteq \{ax_1, \ldots, ax_m\}\) and \(X\theta\) conforms to \(\Phi \sigma\) w.r.t. NoUse. Since we already proved that in this case, \(X\theta \neq \xi\), then we deduce that \(C[\text{X}\theta]_{\phi} \in \mathcal{T}(\mathcal{F}_c, \mathcal{F}_d \cdot \mathcal{AX})\) and \(|C[\text{X}\theta]_{\phi}| > 1\). Along with \(X\theta(\Phi \sigma)\downarrow = x\sigma\), it implies that \(|x\sigma| > 1\) and so \(x\sigma \neq a\).

Rule (Nnosol): In such a case, we have \((X, i \not\models u) \in D\), Cons(\(X, f\)) is useless for any \(f \in \mathcal{F}_c\), AX(\(X, \text{path}\)) is useless for any path and Dest(\(\xi, \ell \rightarrow r, i\)) is useless for all \(\xi, \ell \rightarrow r\).

Let (\(\sigma, \theta\)) \(\in\) Sol(C). In the case of rule (Nname), we showed that \(C[\text{X}\theta]_{\phi} \in \mathcal{T}(\mathcal{F}_c, \mathcal{F}_d \cdot \mathcal{AX})\) and \(|C[\text{X}\theta]_{\phi}| > 1\). But Cons(\(X, f\)) is useless for any \(f \in \mathcal{F}_c\). Hence either Cons(\(X, f\)) is not applicable or its application results in two constraint systems \(C_1\) and \(C_2\) such that \(C_1\) simplifies to \(\bot\) using the rules in Figure 7.3 and \(C_2\) simplifies into \(C\).
Let $f \in F_c$. Since $(X, i \vdash \tau) \in D$, then $\text{Cons}(X, f)$ is applicable. According to Figure 4, its application adds an equation $X \overset{\tau}{=} f(x_1, \ldots, x_n)$ in $Er$ and $u \overset{\tau}{=} f(x_1, \ldots, x_n)$ where $X_1, \ldots, X_n$ and $x_1, \ldots, x_n$ are fresh variables. Since $X_1, \ldots, X_n, x_1, \ldots, x_n$ are fresh, $C_1$ simplifying to $\perp$ implies that $\text{root}(X \theta) \neq f$ or $\text{root}(u \theta) \neq f$. But $(\sigma, \theta) \in \text{Sol}(C)$ implies that $(X \theta)(\Phi \sigma)_1 = u \theta$. Moreover, along with $C_i[X \theta]_\phi \in T(F_c, F_d^2 \cdot AX)$ and $|C_i[X \theta]_\phi| > 1$, $C_1$ simplifying to $\perp$ implies that $\text{root}(u \theta) = \text{root}(X \theta)$. Hence we deduce that $\text{root}(X \theta) \neq f$. Hence, we proved that for all $f \in F_c$, $\text{root}(X \theta) \neq f$ which is a contradiction with $C_i[X \theta]_\phi \in T(F_c, F_d^2 \cdot AX)$ and $|C_i[X \theta]_\phi| > 1$. Hence $(\sigma, \theta) \notin \text{Sol}(C)$ and so $\text{Sol}(C) = \emptyset = \text{Sol}(\perp)$.

**Lemma C.43.** Let $(M, M')$ be a pair of matrices of constraint systems. Let $k$ with the number of column in $M$ and $M'$. Assume that $(M, M')$ is obtained at the end of Step $d$ of Phase 1 of the strategy with parameter $s$ for the support and $k$ for the index of the column. Let $C$ be a constraint system in $M$ or $M'$. If $C$ is replaced by $\perp$ when applying Step $e$ of Phase 1 of the strategy, then we have that $\text{Sol}(C) = \emptyset$.

**Proof.** Let $C$ be a constraint system in $M$ or $M'$ such that $C$ is replaced by $\perp$ when applying Step $e$ of Phase 1 of the strategy. By definition, we know that there is two conditions that trigger the replacement of $C$ by $\perp$. We prove that if one of the two conditions is satisfied then $\text{Sol}(C) = \emptyset$.

**Condition 1:** By definition, we know that there exists a constraint system $C'$ in the same column as $C$, a recipe $\xi$, such that:

- $(\xi, i \geq u) \in \Phi(C')$ for some $i \leq s$ and $u$
- for all $(\xi', j \geq v) \in \Phi(C)$, path($\xi$) $\neq$ path($\xi'$)

Let $w \cdot ax = \text{path}(\xi)$. We prove by induction on $|w|$ that there exists a suffix of $w$, $(\xi, j \geq u) \in \Phi(C)$, $(\xi', j' \geq u') \in \Phi(C')$ such that:

- path($\xi$) = path($\xi'$) = $w' \cdot ax$, $j \leq s$ and $j' \leq s$.
- there exists $(\xi'', j'' \geq u'') \in \Phi(C)$ such that path($\xi''$) = $g \cdot$ path($\xi$) for some $g \in F_d$.
- for all $(\xi'', j'' \geq u'') \in \Phi(C)$, path($\xi''$) $\neq$ path($\xi''$).

**Base case $|w| = 0$:** In such a case, we have that $\xi = ax$. But $C$ and $C'$ are both originated from the same initial constraint system, thus we know that there exists $u, u'$ such that $(ax, s \geq u) \in \Phi(C)$ and $(ax, s \geq u') \in \Phi(C')$. Hence there is a contradiction with our hypothesis on $\xi$.

**Inductive step $|w| > 0$:** Otherwise, there exists $w'$ and $g \in F_d$ such that $w = g \cdot w' \cdot ax$. But $C'$ is a well-formed constraint system, hence by Property 2 of a well formed constraint system, $(\xi, i \geq u) \in \Phi(C')$ implies that there exists $(\xi', j' \geq v') \in \Phi(C')$ such that path($\xi'$) = $w' \cdot ax$ and $i \leq j'$.

Hence if there exists $(\xi, j \geq u) \in \Phi(C)$ such that path($\xi$) = path($\xi'$) then the result holds with $(\xi'', j'' \geq u'') = (\xi, i \geq u)$. Else, since $|w''| < |w|$, we can apply our inductive hypothesis on $(\xi'', j'' \geq v'')$ and so the result also holds.

**Main proof for Condition 1:** Thanks to Lemma C.31, we know that $(M, M')$ satisfies PP15b($s, k + 1$). Since $k$ corresponds to the number of column in $M$ and $M'$, we deduce that all constraint systems in $M$ or $M'$ satisfies InvVarConstraint($s$), InvUntouched($s$) and InvDest($s$).

Let $(\sigma, \theta) \in \text{Sol}(C)$. Thanks to $C$ satisfying InvDest($s$), $(\xi, j \geq u) \in \Phi(C)$ and for all $(\xi'', j'' \geq u'') \in \Phi(C)$, path($\xi''$) $\neq$ $g \cdot$ path($\xi$), we deduce that $\sigma \not= ND(C)$ implies that there is no recipe $\xi_2, \ldots, \xi_n \in \Pi_{\ell}$ such that $g(\xi, \xi_2, \ldots, \xi_n)(\Phi(\sigma) \sigma)_1 \in T(F_c, N)$ and $\text{param}^c_{\max}(\xi_i) \leq s$ for all $i \in \{2, \ldots, n\}$.

But $(\xi'', j'' \geq u'') \in \Phi(C')$ with $\text{path}(\xi'') = g \cdot$ path($\xi$). Hence there exists $\xi_2, \ldots, \xi_n$ such that $\xi'' = g(\xi', \xi_2, \ldots, \xi_n)$. We will show that $\xi'(\Phi(\sigma) \sigma)_1 = \xi'(\Phi(\sigma) \sigma)_1$ and $\xi''(\Phi(\sigma) \sigma)_1$ is in $T(F_c, N)$ with $\text{param}^c_{\max}(\xi_i) \leq s$, for all $i \in \{2, \ldots, n\}$. Hence it will contradict the fact that $\sigma \not= ND(C)$ and so it will implies that $\text{Sol}(C) = \emptyset$. 
C.5. PROOF OF SOUNDNESS

We know that $C$ and $C'$ satisfy $\text{InvVarConstraint}(s)$ and $\text{InvUntouched}(s)$. Moreover, thanks to Lemma 205, we also know that there exists a variable renaming $\rho : X^1 \cup S_1(C) \to X^1 \cup S_1(C')$ such that:

1. $\text{mgu}(\text{Eq}(C))|_{S_1(C)}\rho = \text{mgu}(\text{Eq}(C'))|_{S_1(C')}$, and $D(C)\rho = D(C')$;

2. $\{(u, u') \mid (\xi, i \triangleright u) \in \Phi \land (\xi', i' \triangleright u') \in \Phi' \land \text{path}(\xi) = \text{path}(\xi')\}$ is included in $\{(u, u) \mid u \in T(\mathcal{F}_\ell, N \cup X^1)\}$;

$$(\sigma, \theta) \in \text{Sol}(C)$$ implies that for all $X, k \vdash t \in D(C)$, we have $(X\theta)(\Phi(C)\sigma)\downarrow = t\sigma$. Moreover, we know that for all $(ax, \ell \triangleright v) \in \Phi(C)$, $(ax, \ell' \triangleright v') \in \Phi(C')$, $v\rho = v'$ which means that $(X\theta)(\Phi(C)\sigma)\downarrow = t\sigma$ implies $(X\theta)(\Phi(C')\rho^{-1}\sigma)\downarrow = t'\rho^{-1}\sigma$ with $(X, k \vdash t') \in D(C')$ and $t\rho = t'$.

But, for all $X \in \text{vars}(\xi')$, by Property 3 of a well formed constraint system, we know that $\text{param}_{\max}^{\xi_1}(\xi')$ and so there exists $(X, k \vdash t') \in D(C')$ such that $k \leq j'$. Thus $(X\theta)(\Phi(C')\rho^{-1}\sigma)\downarrow = t'\rho^{-1}\sigma$. $C$ being well-formed (item 2) allows us to deduce that $(\xi'\theta)(\Phi(C')\rho^{-1}\sigma)\downarrow = u'\rho^{-1}\sigma \in T(\mathcal{F}_\ell, N)$. Hence, we have that $(\xi'\theta)(\Phi(C)\sigma)\downarrow = u\sigma \downarrow = (\xi'\theta)(\Phi(C)\sigma)\downarrow$.

Similarly, we have that $$(\xi'\theta)(\Phi(C)\sigma)\downarrow = u'\rho^{-1}\sigma \downarrow \in T(\mathcal{F}_\ell, N).$$ It remains to show that for all $i \in \{2, \ldots, n\}$, $\text{param}(\xi, \theta) \subseteq \{ax_{i-1}, \ldots, ax_i\}$. Since $C'$ satisfies the invariant $\text{InvUntouched}(s)$, for all $C'$ we have that $j'' \leq s$. But $C'$ is well-formed (item 3) hence we deduce that $\text{param}_{\max}^{\xi_1}(\xi') = j''$. Since $C$ and $C'$ have the same shape and satisfy $\text{InvVarConstraint}(s)$, we deduce that $\text{param}_{\max}^{\xi_1}(\xi') = \text{param}_{\max}^{\xi_1}(\xi')$. But for all $X \in \text{vars}(\xi')$, $(\sigma, \theta) \in \text{Sol}(C)$ implies $\text{param}_{\max}(X\theta) \leq \text{param}_{\max}(X)$. Hence, along with $\text{param}_{\max}(\xi') = j''$, it implies that $\text{param}_{\max}(\xi'\theta) \leq j'' \leq s$. Since for all $i \in \{2, \ldots, n\}$, $\xi_i \in st(\xi''')$, we can deduce that $\text{param}_{\max}(\xi_i, \theta) \leq s$.

**Condition 2:** By hypothesis, there exists a constraint system $C'$ in the column of $C$, $(\xi', i' \triangleright u') \in \Phi(C')$, $f \in \mathcal{F}_\ell$ such that

- $\text{path}(\xi) = \text{path}(\xi')$, $i \leq s$ and $i' \leq s$
- $\text{ND}(C) = \forall x. u \neq f(x_1, \ldots, x_n) \lor s \not\models x_1 \lor \ldots \lor s \not\models x_n$ where $x = x_1 \ldots x_n$ are variables.
- there exists $X_1, \ldots, X_n \in \text{vars}(C')$ such that $C[f(x_1, \ldots, x_n)]_{\Phi(C')\theta}^{\text{acc}(C')} = u' \land$ and such that $\text{param}_{\max}^{\xi_1}(f(x_1, \ldots, x_n), \Theta)s$ where $\Theta = \text{mgu}(\text{Er}(C')).$

We prove in Condition 1 that $(\sigma, \theta) \in \text{Sol}(C)$ implies that for all $(X, k \vdash t') \in D(C')$, $X\theta(\Phi(C')\rho^{-1}\sigma)\downarrow = X\theta(\Phi(C')\rho^{-1}\sigma)\downarrow = t'\rho^{-1}\sigma$. Hence, for all $(\xi, i' \triangleright v') \in \Phi(C')$, Property 3 of a well formed constraint systems for $C'$ implies that $(\xi'\theta)(\Phi(C')\rho^{-1}\sigma)\downarrow = u'\rho^{-1}\sigma$ with $\text{param}_{\max}^{\xi_1}(\xi'\theta)$.

Let $\Theta = \text{mgu}(\text{Er}(C'))$ and $\Theta' = \text{mgu}(\text{Er}(C'))$. By hypothesis, we know that $X_1, \ldots, X_n \in \text{vars}(C')$, hence thanks to Property 7 of a well formed constraint system, we have that for all $i \in \{1, \ldots, n\}$, $C[X_i, \Theta']_{\Phi(C')} \subseteq (T(\mathcal{F}_\ell, \mathcal{F}_\ell \cdot AX \cup AX^2)$ and for all $\xi \in \text{st}(X\Theta')$, $\text{path}(\xi)$ exists implies that there exists $j$ and $v$ such that $(\xi, j \triangleright v) \in \Phi(C')$. Hence, $C[f(x_1, \ldots, x_n)]_{\Phi(C')\theta}^{\text{acc}(C')} = u' \land$ implies that $(f(x_1, \ldots, x_n)\Theta'(\Phi(C')\rho^{-1}\sigma)\downarrow = u'\rho^{-1}\sigma$. Since $f(x_1, \ldots, x_n)\Theta'(\Phi(C')\rho^{-1}\sigma)\downarrow = f(x_1, \ldots, x_n)\Theta'(\Phi(C)\sigma)\downarrow$ and $u\rho = u'$ we can deduce that $f(x_1, \ldots, x_n)\Theta'(\Phi(C)\sigma)\downarrow = u\sigma$.

Moreover, we know that $\text{param}_{\max}^{\xi_1}(f(x_1, \ldots, x_n)\Theta') \leq s$ which implies that for all $Y \in \text{vars}(f(x_1, \ldots, x_n)\Theta')$, $\text{param}_{\max}^{\xi_1}(Y) \leq s$. But $C$ and $C'$ have the same shape and both satisfy the invariant $\text{InvVarConstraint}(s)$. Hence $\text{param}_{\max}^{\xi_1}(Y) = \text{param}_{\max}^{\xi_1}(Y)$.

Since $(\sigma, \theta) \in \text{Sol}(C)$, we have that $\text{param}_{\max}(Y) \leq s$ implies $\text{param}_{\max}(Y) \leq s$. We conclude that $\text{param}_{\max}^{\xi_1}(f(x_1, \ldots, x_n)\Theta') \leq s$.

Hence, we proved that there exist $\xi_1, \ldots, \xi_n \in \Pi_n$ such that $\text{param}_{\max}^{\xi_1}(\xi_i) \leq s$ for all $i \in \{1, \ldots, n\}$, and $f(\xi_1, \ldots, \xi_n)(\Phi(C)\sigma)\downarrow = u\sigma$. But $\text{ND}(C) \models \forall x. u \neq f(x_1, \ldots, x_n) \lor s \not\models x_1 \lor \ldots \lor s \not\models x_n$ where $x = x_1 \ldots x_n$ are variables. Moreover, $(\sigma, \theta) \in \text{Sol}(C)$ implies that $\sigma \not\models \text{ND}(C)$ which is a contradiction with the fact that $f(\xi_1, \ldots, \xi_n)(\Phi(C)\sigma)\downarrow = u\sigma$. Hence, $\text{Sol}(C) = \emptyset$. 

□
C.5.5 Link between solutions

Lemma 8.7. Let \( (C, C') \) be a pair of normalised constraint systems having the same structure and obtained by following the strategy. We denote by \( \Phi \) and \( \Phi' \) their associated frame. We denote by \( S_1, S_1' \) their associated set of free variables. Let \( \text{RULE}(p) \) be a transformation rule applicable on \( (C, C') \). Let \( (C_1, C_1') \) and \( (C_2, C_2') \) the two resulting pairs of constraint systems obtained by applying \( \text{RULE}(p) \) on \( (C, C') \), and we denote by \( \Phi_1, \Phi_1', \Phi_2, \) and \( \Phi_2' \) their associated frame.

Let \( \sigma, \theta \) and \( \sigma' \) be three substitutions such that \( (\sigma, \theta) \in \text{Sol}(C) \), \( (\sigma', \theta) \in \text{Sol}(C') \), and \( \Phi \sigma \sim \Phi' \sigma' \).

For all substitution \( \theta' \),

1. \( (\sigma, \theta') \in \text{Sol}(C) \) if, and only if, \( (\sigma', \theta') \in \text{Sol}(C') \).

2. Let \( i \in \{1, 2\} \), and \( \sigma_i \) be a substitution such that \( \sigma_i|_{S_1} = \sigma_i|_{S_1} \) and \( (\sigma_i, \theta') \in \text{Sol}(C_i) \). Then, \( (\sigma_i', \theta') \in \text{Sol}(C'_i) \) for some substitution \( \sigma_i' \) such that \( \sigma_i'|_{S_i'} = \sigma_i'|_{S_i'} \). Moreover, we have that \( \text{Init}(\Phi) \sigma_i = \text{Init}(\Phi') \sigma_i' \) and \( \text{Init}(\Phi') \sigma'_i = \text{Init}(\Phi') \sigma_i' \).

Proof. Let \( \sigma, \theta \) and \( \sigma' \) be three substitutions such that \( (\sigma, \theta) \in \text{Sol}(C) \), \( (\sigma', \theta) \in \text{Sol}(C') \), and \( \Phi \sigma \sim \Phi' \sigma' \). Let \( \theta' \) be another substitution. We prove the two properties separately. The variation can be proved in a similar way.

1. We assume that \( (\sigma, \theta') \in \text{Sol}(C) \), and we show that \( (\sigma', \theta') \in \text{Sol}(C') \). The other implication can be done in a similar way. Let \( C = (S_1; S_2; \Phi; D; Eq; Er; ND; \text{NoUse}) \) and \( C' = (S_1'; S_2'; \Phi'; D'; Eq'; Er'; ND'; \text{NoUse}) \). First, since \( (\sigma', \theta') \in \text{Sol}(C') \), we have that \( \sigma' \models ND' \land Eq' \). Second, since \( C \) and \( C' \) have the same structure, we have that \( Er = Er', \) and so \( \theta' \models Er' \). Moreover, for any \( X, i \vdash u' \in D' \), we have that \( \text{param}(X \theta') \subseteq \{ax_1, \ldots, ax_1\} \) and for any ground recipe \( \xi \in \Pi_a \), \( \xi \) conforms to \( \Phi \theta' \) w.r.t. \( \text{NoUse} \theta' \) if, and only if, \( \xi \) conforms to \( \Phi' \theta' \) w.r.t. \( \text{NoUse} \theta' \).

In order to conclude, it remains to show that \( \text{Init}(\Phi') \sigma_i \downarrow = u' \sigma_i' \downarrow \) for any \( X, i \vdash u \in D' \).

Since \( (\sigma, \theta) \in \text{Sol}(C) \) and \( (\sigma', \theta') \in \text{Sol}(C) \), we have \( \text{Init}(\Phi') \sigma_i \downarrow = \text{Init}(\Phi' \theta') \sigma_i' \downarrow \) for each constraint \( X, i \vdash u \in D' \).

Moreover, \( \Phi \sigma \sim \Phi' \sigma' \), we have that \( \text{Init}(\Phi') \sigma_i \downarrow = \text{Init}(\Phi' \sigma' \downarrow) \) for each constraint \( X, i \vdash u' \in D' \) (by relying also on the fact that \( C \) and \( C' \) have the same structure). Moreover, since \( (\sigma, \theta') \in \text{Sol}(C') \), we have that \( \text{Init}(\Phi') \sigma_i \downarrow = u' \sigma_i' \downarrow \) for each constraint \( X, i \vdash u' \in D' \).

2. Let \( i \in \{1, 2\} \) and \( \sigma_i \) be a substitution such that \( \sigma = \sigma_i|_{\text{vars}(C)} \) and \( \sigma_i, \theta' \in \text{Sol}(C_i) \).

First, by inspection of the rules, it is easy to see that \( \text{Init}(\Phi_i) \sigma_i = \text{Init}(\Phi) \sigma \) and \( \text{Init}(\Phi_i') \sigma_i' = \text{Init}(\Phi') \sigma_i' \). Since \( C_i \) and \( C_i' \) have the same structure, we have that \( Er(C_i) = Er(C'_i) \), and so \( \theta' \models Er(C'_i) \). Moreover, for any \( X, j \vdash u \in D(C'_i) \), we have that \( \text{param}(X \theta') \subseteq \{ax_1, \ldots, ax_1\} \) and for any ground recipe \( \xi \in \Pi_a \), \( \xi \) conforms to \( \Phi_i \theta' \) w.r.t. \( \text{NoUse} \theta' \) if, and only if, \( \xi \) conforms to \( \Phi'_i \theta' \) w.r.t. \( \text{NoUse} \theta' \).

In order to conclude, it remains to show that there exists a substitution \( \sigma'_i \) such that \( (\sigma'_i, \theta') \in \text{Sol}(C'_i) \), i.e., such that \( \text{Init}(\Phi_i) \sigma_i \downarrow = u' \sigma_i' \downarrow \) for any \( X, j \vdash u' \in D'_i \) and \( \sigma'_i \models ND'_i \lor Eq'_i \).

Thanks to Lemma 8.5, we have that \( (\sigma, \theta'|_{\text{vars}(C)}) \in \text{Sol}(C) \). Thanks to Item 1, we know that \( (\sigma'_i, \theta'|_{\text{vars}(C)}) \in \text{Sol}(C'_i) \). Then, we prove the results by case analysis on the rule \( \text{RULE}(p) \) (we rely on the notation of Figures 8.1 and 8.2, focusing on the additional constraints that have been added in \( C'_i \)).
C.5. PROOF OF SOUNDNESS

We already know that \( C \) implies that \( \sigma' \vdash ND' \land Eq' \) which means that \( \sigma' \vdash ND' \land Eq' \land t' = f(x'_1, \ldots, x'_n) \) and so \( \sigma' \vdash ND' \land Eq' \). At last, since we already know that \( X \theta' = f(x_1 \theta', \ldots, x_n \theta') \) and \( (X \theta')^\Psi \sigma'_j = t' \sigma' = f(x'_1 \sigma'_j, \ldots, x'_j \sigma'_j) \), we can deduce that \( (X \theta')(\Psi \sigma'_j) \downarrow \equiv x'_j \sigma'_j \) for \( j = \{1, \ldots, n\} \).

Rule CONS, \( i = 2 \): We have that \( (\sigma', \theta') \in \text{Sol}(C') \), thus it remains to prove that \( \theta' \vdash \text{root}(X) \neq f \). We know that \( \theta' \vdash \text{root}(X) \neq f \).

Rule Axiom, \( i = 1 \): We already know that \( \theta' \vdash Er_1' \) thus \( \theta' \vdash X \equiv \xi \). Thus it remains to prove that \( \sigma' \vdash u' \equiv v' \). We know that \( (\sigma', \theta') \in \text{Sol}(C') \), and thus we have that \( X \theta'(\Psi \sigma') \downarrow = u' \sigma' \) and \( (\Phi \theta'(\Psi \sigma')) \downarrow = v' \sigma' \). Moreover, thanks to Item 1, we have that \( (\sigma, \theta') \in \text{Sol}(C) \). This implies that \( X \theta'(\Phi \sigma') \downarrow = u' \sigma' \) and \( (\Phi \theta'(\Phi \sigma')) \downarrow = v' \sigma' \). But, we know that \( \Phi \sigma \sim \Phi \sigma' \) and we have that \( \sigma \vdash u' \equiv v' \). Thus, we can deduce that \( \theta'(\Psi \sigma') \downarrow = X \theta'(\Phi \sigma') \downarrow \) and so \( \sigma' \vdash u' \equiv v' \).

Rule Axiom, \( i = 2 \): We already shown that \( \theta' \models Er_1' \) and so \( \theta' \models X \neq \xi \). We have nothing else to prove.

Rule Dest, \( i = 1 \): Since \( (\sigma, \theta') \in \text{Sol}(C_1) \), we can deduce that \( f(\xi, x_1, \ldots, x_n) \theta'(\Phi \sigma) \downarrow = u' \sigma' \) in \( T(\mathcal{F}_c, N) \). Moreover, we know that \( \Phi \sigma \sim \Phi \sigma' \) for \( f(\xi, x_1, \ldots, x_n) \theta'(\Phi \sigma) \downarrow = T(\mathcal{F}_c, N) \) which means that \( \Psi \theta'(\Phi \sigma') \downarrow \) can be reduced by the destructor \( f \). Thus, \( f(u'_1, \ldots, u'_n) \rightarrow w' \) being a fresh renaming of \( \ell \rightarrow r \), we can extend \( \sigma' \) into \( \sigma'' \) such that \( u'_i \sigma'' = v' \sigma' \). Moreover, for each rewriting rule, we have that \( \text{vars}^1(u'_i) \subseteq \text{vars}^1(u_i) \) for \( j = 2 \ldots n \), thus \( f(\xi, x_1, \ldots, x_n) \theta'(\Phi \sigma') \downarrow = T(\mathcal{F}_c, N) \) implies that \( X \theta'(\Phi \sigma') \downarrow = u'_j \sigma'' \) for \( j = 2 \ldots n \).

Rule Dest, \( i = 2 \): The non deducibility constraint added in \( C_2 \) corresponds to the fact that for all \( (\xi_1, \ldots, \xi_n) \in \Pi_2 \) with parameter included in \( \{ax_1, \ldots, ax_1\} \), we have \( \xi \Phi \sigma' \downarrow \neq \xi \Phi \sigma' \downarrow \) \( \in T(\mathcal{F}_c, N) \). But, by hypothesis, we know that \( (\sigma_2, \theta') \in \text{Sol}(C_2) \) and \( \sigma = \sigma_2 \downarrow \text{vars}^1(C_2) = \sigma_2 \). Thus, \( \sigma_2 \vdash ND_2 \) and so for all recipes \( (\xi_1, \ldots, \xi_n) \in \Pi_2 \) with parameter included in \( \{ax_1, \ldots, ax_1\} \), we have \( \xi_1 \Phi \sigma \downarrow \neq \xi \Phi \sigma \downarrow \land f(\xi_1, \ldots, \xi_n) \Phi \sigma \downarrow \notin T(\mathcal{F}_c, N) \). Lastly, since we have that \( \Phi \sigma \sim \Phi \sigma' \), the result holds.

Rule Eq-LEFT-LEFT: We add an equation \( u_1 \equiv u_2 \) (resp. a disequation \( u_1 \neq u_2 \)). Moreover, we have that \( u_1 \sigma = \xi \theta'(\Phi \sigma) \downarrow \), \( u_2 \sigma = \xi \theta'(\Phi \sigma) \downarrow \). Thanks to Item 1, we know that \( (\sigma', \theta') \in \text{Sol}(C') \) which means that \( u' \sigma' = \xi \theta'(\Phi \sigma') \downarrow \), for \( j = 1, 2 \). Since \( \Phi \sigma \sim \Phi \sigma' \), we have that \( u_1 \sigma = u_2 \sigma \) (resp. \( u_1 \sigma \neq u_2 \sigma \)) and this allows us to conclude.

The case of the rule Eq-LEFT-RIGHT can be done in a similar way.

Rule Eq-RIGHT-RIGHT: We know that \( (\sigma, \theta') \in \text{Sol}(C') \), and thus we have that \( X \theta'(\Phi \sigma') \downarrow = u' \sigma' \) and for all \( Y \in \text{vars}^2(\xi) \text{ and } Y \theta'(\Phi \sigma') \downarrow = w' \sigma' \) where \( (Y, k \equiv w') \in D(C') \). Hence, by construction of \( v' \), we deduce that \( \xi \theta'(\Phi \sigma') \downarrow = v' \sigma' \). Moreover, thanks to Item 1, we have that \( (\sigma, \theta') \in \text{Sol}(C) \). Similarly, this implies that \( X \theta'(\Phi \sigma) \downarrow = u \sigma \) and \( \xi \theta'(\Phi \sigma) \downarrow = u \sigma \). We do a case analysis on \( i \).

Case \( i = 1 \): In such a case, \( \theta' \vdash Er_1' \) and so \( \theta' \models X \equiv \xi \). Thus it remains to prove that \( \sigma' \vdash u' \equiv v' \). But, we know that \( \Phi \sigma \sim \Phi \sigma' \) and we have that \( \sigma \vdash u \equiv v \). Thus, we can deduce that \( \theta'(\Phi \sigma') \downarrow = X \theta'(\Phi \sigma') \downarrow \) and so \( \sigma' \vdash u' \equiv v' \).

Case \( i = 2 \): In such a case, we only have to prove that \( u' \sigma' \neq v' \sigma' \). We know that \( u \sigma \neq v \sigma \) which implies that \( X \theta'(\Phi \sigma) \downarrow \neq \xi \theta'(\Phi \sigma) \downarrow \). But we have \( \Phi \sigma \sim \Phi \sigma' \) hence \( X \theta'(\Phi \sigma) \downarrow \neq \xi \theta'(\Phi \sigma) \downarrow \). Thus, we can deduce that \( X \theta'(\Phi \sigma') \downarrow \neq \xi \theta'(\Phi \sigma') \downarrow \) and so \( u' \sigma' \neq v' \sigma' \). This allows us to conclude.
C.6 Link between equivalence symbolic and the final test

C.6.1 Preliminaries

Lemma C.44. Let $M$ be matrix of constraint systems obtained by following the strategy. Let $C$ and $C'$ be two constraint systems from the same column in $M$. Let $(\sigma, \theta) \in \text{Sol}(C)$ and $(\sigma', \theta') \in \text{Sol}(C')$ such that $\sigma|_{S_i(C)} = \sigma'|_{S_i(C')}$.

We have that:

1. $\text{Init}(\Phi(C))\sigma = \text{Init}(\Phi(C'))\sigma'$;

2. for all $(\xi, i \dashv u) \in \Phi(C)$, for all $(\xi', i' \dashv u') \in \Phi(C')$, if $\text{path}(\xi) = \text{path}(\xi')$ then $u\sigma = u'\sigma'$;

3. for all $X \in S_2(C) = S_2(C')$, if $(X, i \dashv u) \in D(C)$ and $(X, i' \dashv u') \in D(C')$, then $u\sigma = u'\sigma'$.

Proof. Since $C$ and $C'$ are both from the same column of $M$, we deduce that they have at least one common ancestor. Let $C_0$ be the constraint system on the row matrix of initial constraint system such that $C_0 \rightarrow C$ and $C_0 \rightarrow C'$.

Property 1: Let $u, u' \in T(F_r, N \cup X^1)$ such that $(ax_i, i \dashv u) \in \Phi(C)$ and $(ax_i, i \dashv u') \in \Phi(C')$, for some $i$. Furthermore let $u_0 \in T(F_r, N \cup X^1)$ such that $(ax_i, i \dashv u_0) \in \Phi(C_0)$.

Since $C_0 \rightarrow C$ and $C_0 \rightarrow C'$, we obtain from Lemma C.42 that $u = u_0\Sigma$ and $u' = u_0\Sigma'$ where $\Sigma = \text{mgu}(Eq)$ and $\Sigma' = \text{mgu}(Eq')$. But $(\sigma, \theta) \in \text{Sol}(C)$ implies that $\sigma \models Eq$ and so there exists $\sigma_0$ such that $\sigma = \Sigma\sigma_0$. Similarly, there exists $\sigma'_0$ such that $\sigma' = \Sigma'\sigma'_0$. Moreover, $u_0$ is a term in the initial constraint system $C_0$, hence $\vars\{u_0\} \subseteq S_1(C_0) = S_1(C) = S_1(C')$ which also implies that $u_0\sigma|_{S_2(C)} = u_0\sigma$ and $u_0\sigma|_{S_2(C')} = u_0\sigma'$. At last, by applying the hypothesis $\sigma|_{S_2(C)} = \sigma'|_{S_2(C')}$, which leads to $u\sigma = u\sigma'$.

Property 2: Let $(\xi, i \dashv u) \in \Phi(C)$ and $(\xi', i' \dashv u') \in \Phi(C')$. We know that $C$ and $C'$ are well-formed constraint systems. Thanks to Property 1 of a well-formed constraint system and the fact that $(\sigma, \theta) \in \text{Sol}(C)$ and $(\sigma', \theta') \in \text{Sol}(C')$, we deduce that $\xi\theta(\Phi(C))\sigma|_{\vars}(\xi')\theta'(\Phi(C'))\sigma'$. We have seen that $\text{Init}(\Phi(C))\sigma = \text{Init}(\Phi(C'))\sigma'$. We know that $u\sigma, u'\sigma' \in T(F_r, N)$. Hence we can apply Lemma C.42 which leads to $\xi\theta(\Phi(C))\sigma|_{\vars}(\xi')\theta'(\Phi(C'))\sigma'$.

Property 3: Since $X \in S_2(C) = S_2(C')$ and $C_0 \rightarrow C$, $C_0 \rightarrow C'$, then there exists $Y \in S_2(C_0)$ such that $X \in \vars^2[C[Y\Theta]_{|\Phi(C)}]$ where $\Theta = \text{mgu}(Er(C))$. Let $\Theta' = \text{mgu}(Er(C'))$, $\Sigma = \text{mgu}(Eq(C))$ and $\Sigma' = \text{mgu}(Eq'(C'))$. By applying Lemma C.11 on $Y$, we have that $Y\text{acc}_1^1(C_0)\sigma = C[Y\Theta]_{|\Phi(C)}\text{acc}_1^1(C)$.

But $(\sigma, \theta) \in \text{Sol}(C)$ implies that $\sigma \models Eq(C)$ and so there exists $\sigma_0$ such that $\sigma = \Sigma\sigma_0$. Since $\Sigma = \text{mgu}(Eq(C))$ and $\Sigma' = \text{mgu}(Eq'(C'))$, we have that $Y\text{acc}_1^1(C_0)\sigma' = C[Y\Theta]_{|\Phi(C)}\text{acc}_1^1(C')\sigma'$.

Our inductive hypothesis tells us that $\sigma|_{S_1(C)} = \sigma'|_{S_1(C)}$, which implies that $\text{acc}_1^1(C_0)\sigma = \text{acc}_1^1(C_0)\sigma'$.

Furthermore, $M$ satisfies InvGeneral, hence for all $Z \in S_2(C) = S_2(C')$, $C[Z\Theta]_{|\Phi(C)} = C[Z\Theta']_{|\Phi(C')}$. Since $Y \in S_2(C_0)$ then $Y \in S_2(C)$ and so we deduce that $C[Y\Theta]_{|\Phi(C)} = C[Y\Theta']_{|\Phi(C')}$. Hence, we deduce that $C[Y\Theta]_{|\Phi(C)}\text{acc}_1^1(C)\sigma = C[Y\Theta']_{|\Phi(C')}\text{acc}_1^1(C')\sigma'$. Since $X \in \vars^2[C[Y\Theta]_{|\Phi(C)}]$, we can conclude that $X\text{acc}_1^1(C)\sigma = X\text{acc}_1^1(C')\sigma'$ and so $u\sigma = u'\sigma'$.
C.6. LINK BETWEEN EQUIVALENCE SYMBOLIC AND THE FINAL TEST

C.6.2 Step e of the strategy

Lemma C.45. Let $M, M_1$ be a matrix of constraint system obtained respectively at the beginning and end of step a of phase 1 with support $s$ such that $M \rightarrow M_1$. Let $C_1$ be a constraint system in $M_1$. Assume that $C$ the constraint system in $M$ ancestor of $C_1$ satisfies $\text{Sol}(C) = \text{Sol}(C_1)$. Let $(\sigma, \theta) \in \text{Sol}(C_1)$. If $(\sigma, \theta) \not\in \text{Sol}(C_1)$ then there exists a constraint system $C'_1$ in the same column of $C_1$ such that:

1. $C \rightarrow^* C'_1$;
2. $\{ (\xi, i) \mid i < s \land (\xi, i \triangleright u) \in \Phi(C_1) \} = \{ (\xi, i) \mid i < s \land (\xi, i \triangleright u) \in \Phi(C'_1) \}$;
3. $\{ \text{path}(\xi) \mid (\xi, s \triangleright u) \in \Phi(C_1) \} \subseteq \{ \text{path}(\xi) \mid (\xi, s \triangleright u) \in \Phi(C'_1) \}$;
4. $\{ \text{path}(\xi) \mid (\xi, s \triangleright u) \in \text{NoUse}(C_1) \} = \{ \text{path}(\xi) \mid (\xi, s \triangleright u) \in \text{NoUse}(C'_1) \} \cap \{ \text{path}(\xi) \mid (\xi, s \triangleright u) \in \Phi(C'_1) \}$;
5. there exists $(\sigma', \theta') \in \text{Sol}(C'_1)$ such that $\sigma'_{|S_1(C)} = \sigma''_{|S_1(C)}$.

Proof. We prove this result by induction on the size $N$ of the branch $C \rightarrow C_1$. According to the strategy, every application of the rule Dest or Eq-left-right implies the application of the same rule with the same parameters on each line of the matrix. Hence, for the induction, we assume that the sequence of applications of a rule Dest or Eq-left-right on each line is applied simultaneously.

Base case $N = 0$: In such a case, $C = C_1$, hence $\text{Sol}(C_1) = \text{Sol}(C'_1)$. By choosing $C'_1 = C_1 = C$, properties $\text{I}$ and $\text{II}$ trivially holds. Furthermore, since $\text{NoUse}(C'_1) \subseteq \Phi(C'_1)$, property $\text{II}$ holds. At last, by hypothesis we have $(\sigma, \theta) \in \text{Sol}(C'_1)$ which implies that $(\sigma, \theta) \in \text{Sol}(C_1)$. With $C_1 = C'_1$, we conclude that $(\sigma, \theta) \in \text{Sol}(C'_1)$. Hence property $\text{II}$ holds.

Inductive step $N > 0$: Let $R(\tilde{p})$ be the last rule applied. Let $M_2$ be the matrix such that $M_2 \rightarrow M_1$ (note that the rule applied is necessary an internal rule) and let $C_2$ be the constraint system in $M_2$ such that $C_2 \rightarrow C_1$. Thanks to Lemma $\text{C.5}$ $(\sigma, \theta) \in \text{Sol}(C'_1)$ implies that $(\sigma', \theta') \in \text{Sol}(C_2)$ with $\sigma'_{|S_1} = \sigma_{|S_1}$ and $\theta'_{|\text{parse}^2 C_2} = \theta'$.

Hence by induction hypothesis, we know that there exists a constraint system $C'_2$ in the same column of $C_2$ such that:

1. $C \rightarrow^* C'_2$;
2. $\{ (\xi, i) \mid i < s \land (\xi, i \triangleright u) \in \Phi(C_2) \} = \{ (\xi, i) \mid i < s \land (\xi, i \triangleright u) \in \Phi(C'_2) \}$;
3. $\{ \text{path}(\xi) \mid (\xi, s \triangleright u) \in \Phi(C_2) \} \subseteq \{ \text{path}(\xi) \mid (\xi, s \triangleright u) \in \Phi(C'_2) \}$;
4. $\{ \text{path}(\xi) \mid (\xi, s \triangleright u) \in \text{NoUse}(C_2) \} = \{ \text{path}(\xi) \mid (\xi, s \triangleright u) \in \text{NoUse}(C'_2) \} \cap \{ \text{path}(\xi) \mid (\xi, s \triangleright u) \in \Phi(C'_2) \}$;
5. there exists $(\sigma'', \theta'') \in \text{Sol}(C'_2)$ such that $\sigma''_{|S_1} = \sigma'_{|S_1}$.

Thanks to the description of the strategy (see Section 7.4), we know that applying the rule Dest or Eq-left-right is always follows by the application of the same instance of the rule on each line of the matrix. However, when the parameters of the instance of the rule are not compatible with the constraint systems on a line of the matrix, this line stay untouched. Hence, we do a case analysis on the rule applied and on whether the parameters were compatible or not. Note that Property $\text{II}$ of the inductive hypothesis on $C_2$ and $C'_2$ implies that if the parameters of the rule are compatible for $C_2$, then they also are compatible for $C'_2$.

- $R(\tilde{p}) = \text{Eq-left-right}(X_0, \xi_0)$ where $X_0, \xi_0$ are not compatible parameters for $C'_2$: In such a case, it implies that there is no frame element in $\Phi(C'_2)$ with $\text{path}(\xi_0)$ as path. Hence, $C'_2$ remains unchanged and so $C_2$ is a constraint system in $M_1$. However, we know that for all $(\xi, s \triangleright u) \in \Phi(C_2)$, there exists $(\xi', s \triangleright u') \in \Phi(C'_2)$ such that $\text{path}(\xi) = \text{path}(\xi')$, thus we can deduce that $X_0, \xi_0$ are also not compatible parameters for $C_2$ which means that $C_1$ is in fact $C_2$. Hence, by denoting $C'_1 = C'_2$, the result holds.
We already proved that \(\xi_0, \ell \mapsto r, s\) are not compatible for \(C_2'\). Similarly to the previous case, it implies that there is no frame element in \(\Phi(C_2')\) with path(\(\xi_0\)) as path. Hence \(C_2 = C_1\) and by denoting \(C_1' = C_2'\), the result holds.

\[R(\tilde{p}) = \text{EQ-LEFT-RIGHT}(X_0, \xi_0)\] where \(X_0, \xi_0\) are compatible parameters for \(C_2'\) but not for \(C_2\): In such a case, there exists a frame element \((\xi, s \triangleright u) \in \Phi(C_2')\) such that \(\text{path}(\xi_0) = \text{path}(\xi)\). Furthermore, there is not such frame element in \(C_2\). Since the rule is applied on \(C_2'\) and \((\sigma''', \theta''') \in \text{Sol}(C_1')\), then by Lemma S.6 we can deduce that there exists a constraint system \(C_1'\) in \(M_1\) such that:

- \(C_2' \mapsto C_1'\) which implies \(C \mapsto^* C_1'\) hence property [4] holds.
- there exist \((\sigma''', \theta''') \in \text{Sol}(C_1')\) such that \(\sigma''_{S_1(C)} = \sigma'''_{S_1(C)}\) hence property [5] holds.

Hence it remains to proves Properties [2] [3] and [4]. But the rule EQ-LEFT-RIGHT does not add new frame elements in the frame, thus properties [2] and [3] are trivially satisfied. At last, by the rule EQ-LEFT-RIGHT, we may have:

\[\text{NoUse}(C_1') = \text{NoUse}(C_2') \cup \{ (\xi, s \triangleright u) \}\]

But, by hypothesis \(X_0, \xi_0\) are not compatible parameters for \(C_2\) then it means that there is no frame element \((\xi, s \triangleright u) \in \Phi(C_2)\) such that \(\text{path}(\xi) = \text{path}(\xi_0) = \text{path}(\xi)\). Hence, we have that:

\[
\{\text{path}(\xi) \mid (\xi, s \triangleright u) \in \text{NoUse}(C_1')\} \cap \{\text{path}(\xi) \mid (\xi, s \triangleright u) \in \Phi(C_2)\} = \{\text{path}(\xi) \mid (\xi, s \triangleright u) \in \text{NoUse}(C_2')\} \cap \{\text{path}(\xi) \mid (\xi, s \triangleright u) \in \Phi(C_2)\}
\]

Therefore, property [4] holds.

\[R(\tilde{p}) = \text{EQ-LEFT-RIGHT}(X_0, \xi_0)\] where \(X_0, \xi_0\) are compatible parameters for both \(C_2\) and \(C_2'\): Thanks to Lemma S.11 we can deduce that there exists a constraint system \(C_1\) in \(M_1\) such that:

\[
\text{NoUse}(C_1') = \text{NoUse}(C_2') \cup \{ (\xi, s \triangleright u) \}
\]

Let \(u, u' \in T(F_c, N' \cup X')\) such that \((X_0, i \vdash u) \in D(C_1)\) and \((X_0, i \vdash u') \in D(C_1')\). Furthermore, let \((\xi, s \triangleright v) \in \Phi(C_1)\) and \((\xi', s \triangleright v') \in \Phi(C_1')\) such that \(\text{path}(\xi) = \text{path}(\xi_0)\). We already proved that \((\sigma, \theta) \in \text{Sol}(C_1), (\sigma''', \theta''') \in \text{Sol}(C_1')\) and \(\sigma_{S_1(C)} = \sigma'''_{S_1(C)}\). Thus, by Lemma C.4 we can deduce that \(u \equiv u'' \equiv v\) and \((\xi', s \triangleright u') \in \text{NoUse}(C_1')\) is equivalent to \(\sigma'' \vdash u' \equiv v'\). Hence we conclude that

\[(\xi, s \triangleright v) \in \text{NoUse}(C_1)\]

C.6. LINK BETWEEN EQUIVALENCE SYMBOLIC AND THE FINAL TEST

- \( R(\tilde{p}) = \text{DEST}(\xi_0, \ell \rightarrow r, s) \) where \( \xi_0, \ell \rightarrow r, s \) are compatible parameters for \( C_1' \) and \( C_2 \).

Thanks to Lemma C.45 we can deduce that there exists a constraint system \( C_1' \) in \( M_1 \) such that:

- \( C_2' \Rightarrow C_1' \) which implies \( C \Rightarrow^* C_1' \) hence property 1 holds.

- there exist \( (\sigma''', \theta''') \in \text{Sol}(C_1') \) such that \( \sigma'|_{S_1(C)} = \sigma''|_{S_1(C)} \) hence property 2 holds.

Let \( g \in F_d \) be the destructor symbol of \( \ell \rightarrow r \). This instance of the rule DEST may only add a frame element \( (\xi, s \triangleright w) \) where \( \text{path}(\xi) = g \cdot \text{path}(\xi_0) \). Hence Property 2 holds.

Let \( (\xi, j \triangleright u) \in \Phi(C_1) \) and \( (\xi', j' \triangleright u') \in \Phi(C_1') \) such that \( \text{path}(\xi) = \text{path}(\xi') = \text{path}(\xi_0) \).

First of all, thanks to Property 2 of our inductive hypothesis, we deduce that \( j = j' \).

Assume now that there exists \( \xi, s \triangleright w \in \Phi(C_1) \) such that \( \text{path}(\xi) = g \cdot \text{path}(\xi_0) \). We show that there necessarily exists \( \xi, s \triangleright w' \in \Phi(C_1') \) such that \( \text{path}(\xi') = g \cdot \text{path}(\xi_0) \).

Since \( \text{path}(\xi) = g \cdot \text{path}(\xi_0) \) then there exists \( X_2, \ldots, X_n \in \mathcal{X}^2 \) such that \( \xi = g(\xi, X_2, \ldots, X_n) \).

Furthermore, thanks to \( (\sigma, \theta) \in \text{Sol}(\mathcal{C}) \), to the definition of a solution of a constraint system and to Property 3 of a well-formed constraint system, we deduce that \( \theta(\Phi(C_1)\sigma) \downarrow = w \sigma \).

But \( (\sigma''', \theta''') \in \text{Sol}(C_1') \) and \( \sigma'|_{S_1(C)} = \sigma''|_{S_1(C)} \). Thus, by Lemma C.44 we can deduce that \( \text{Init}(\Phi(C_1)\sigma) = \text{Init}(\Phi(C_1')\sigma''') \) which implies that \( \theta(\Phi(C_1)\sigma) \downarrow = \theta(\Phi(C_1')\sigma''') \downarrow \in \mathcal{T}(F_e,N) \). Furthermore, Lemma C.44 also implies that \( w \sigma = u' \sigma''' \). Hence we have that \( \xi, s \triangleright u' \in \Phi(C_1) \sigma''') \). Thus, \( g(\xi, \xi', X, \theta) \in \Phi(C_1') \sigma''') \downarrow \in \mathcal{T}(F_e,N) \).

With \( \sigma''' = ND(C_1') \) thanks to \( (\sigma''', \theta''') \in \text{Sol}(C_1') \), the description of the rule DEST allows us to conclude that there exists \( \xi, s \triangleright w' \in \Phi(C_1') \) such that \( \text{path}(\xi') = \text{path}(\xi) \).

Hence Property 4 holds.

Since the rule DEST does not add a frame element in NoUse, we conclude that Property 4 holds.

Lemma C.46. Let \( M, M_1 \) be a matrix of constraint system obtained respectively at the beginning and end of step \( a \) of support \( s \) such that \( M \Rightarrow M_1 \). Let \( C_1 \) be a constraint system in \( M_1 \). Assume that \( C \) the constraint system in \( M \) ancestor of \( C_1 \) satisfies \( \text{Sol}(C) = \text{Sol}(\mathcal{C}) \).

Let \( (\sigma, \theta) \in \text{Sol}(\mathcal{C}_1) \). Assume that

1. for all \( X \in D(C_1), \) for all position \( p \) of \( C|X|_\Phi(C_1) \), if \( \text{root}((C|X|_\Phi(C_1)) \in F_d, \) then there is no ground recipe \( \xi \in \Pi_n \) such that \( \xi(\Phi(C_1)\sigma) \downarrow = X\theta|_p(\Phi(C_1)\sigma) \downarrow \) and \( \text{param}_\max(\xi') < \text{param}_\max(\xi)|_p \); and

2. for all \( \xi, \xi' \in st(X|_p \ | \ X \in D(C_1)) \), \( \text{path}(\xi) = \text{path}(\xi') \) implies \( \xi = \xi' \).

There exists a constraint system \( C_1' \) in the same column of \( C_1 \) and there exists \( (\sigma', \theta') \in \text{Sol}(C_1') \) such that \( \sigma'|_{S_1(C)} = \sigma'_{|S_1(C)} \) and for all \( X \in S_2(C_1), \ X \theta = X\theta' \).

Proof. Our hypothesis on \( M, M_1 \) and \( C_1 \) allows us to apply Lemma C.45. Hence we have that there exists a constraint system \( C_1' \) in the same column as \( C_1 \) such that:

1. \( C \Rightarrow C_1' \);

2. \( \{ (\xi, i) \ | \ i \neq s \land (\xi, i \triangleright u) \in \Phi(C_1) \} = \{ (\xi, i) \ | \ i < s \land (\xi, i \triangleright u) \in \Phi(C_1') \} \};

3. \( \{ \text{path}(\xi) \ | \ (\xi, s \triangleright u) \in \Phi(C_1) \} \subseteq \{ \text{path}(\xi) \ | \ (\xi, s \triangleright u) \in \Phi(C_1') \} \};

4. \( \{ \text{path}(\xi) \ | \ (\xi, s \triangleright u) \in \text{NoUse}(C_1) \} = \{ \text{path}(\xi) \ | \ (\xi, s \triangleright u) \in \text{NoUse}(C_1') \} \cap \{ \text{path}(\xi) \ | \ (\xi, s \triangleright u) \in \Phi(C_1) \} \};

5. there exists \( (\sigma', \theta') \in \text{Sol}(C_1') \) such that \( \sigma'|_{S_1(C)} = \sigma'_{|S_1(C)} \).
However, Property 5 is not sufficient for our result. Hence we will build a new substitution $\theta''$ that satisfies the properties stated in the Lemma.

Since $C_1$ and $C'_1$ have the same shape, we have that $S_2(C_1) = S_2(C'_1)$. Furthermore, since during Step 1 of phase 1 with support $s$, the only added deducible constraint are of the following form:

Although $s \not\vdash u$, for some $X$ and $u$ where $X \not\in S_2(C_1)$.

We now show that there exists a second order variable renaming $\rho$ such that:

- $\{ (X, i \vdash u) \in D(C_1) \} \subseteq \{ (X, i \vdash u) \in D(C'_1) \}$
- $\{ (\xi, i \vdash u) \in \Phi(C_1) \} \subseteq \{ (\xi, i \vdash u) \in \Phi(C'_1) \}$

First of all, since $C_1$ and $C'_1$ have the same shape, we deduce that $S_2(C_1) = S_2(C'_1)$ and $\{ (X, i \vdash u) \in D(C_1) \} \subseteq \{ (X, i \vdash u) \in D(C'_1) \}$. Hence, we define $\rho$ on $S_2(C)$ is the identity. Let $(X, i \vdash u) \in D(C_1)$ such that $X \not\in S_2(C_1)$. Since $M_1$ satisfies $PP_{1Sa}(s)$, we deduce that there exists a unique frame element $(g(\xi_1, \ldots, \xi_n), j \vdash v) \in C_1(C_1)$ and $k \in \{2, \ldots, n\}$ such that $j = s$ and $\xi_k = X$. We can already proved that $\{ \text{path}(\xi, \xi, i \vdash u) \in \Phi(C_1) \} \subseteq \{ \text{path}(\xi, \xi, i \vdash u) \in \Phi(C'_1) \}$. Hence along with Property 5 of the invariant $PP_{1Sa}(s)$ on $C'_1$, we deduce that there exists $(g(\xi'_1, X_{j+1}, \ldots, X_n), s \vdash v) \in C'_1$ and $\text{path}(\xi'_1) = \text{path}(\xi)$. Thus, we define $\rho$ on $X$ such that $X\rho = X_1'$. Moreover, since $X_1' \not\in S_2(C_2)$, we deduce that there exists $u'_k$ such that $(X'_1, s \vdash u'_k) \in D(C'_1)$. Hence we can conclude that $\{ (X, i \vdash u) \in D(C_1) \} \subseteq \{ (X, i \vdash u) \in D(C'_1) \}$.

We already know that $\{ (\xi, i) \in S_2(C_1) \} \subseteq \{ (\xi, i) \in S_2(C'_1) \}$. Hence, for all $(\xi, i \vdash u) \in \Phi(C_1)$, for all $X \in \text{vars}(\xi)$, $\text{param}_{\max}(C'_1)(\xi, u) \leq i$ (thanks to $C_1$ being well-formed. But $C_1$ satisfies $\text{Inv\nontouched}(s)$. Hence if $i \neq s$ and $X \in \text{vars}(\xi)$, then $i < s$ and so $X \in S_2(C)$. Thus, if $i \neq s$ then $\xi = \rho = \xi$. Let $(\xi, s \vdash u) \in \Phi(C_1)$. Since $C_1$ is well-formed (item 3), $\text{param}_{\max}(C_1)(\xi)$ exists and so for all $Z \in \text{vars}(\xi)$, there exists $(Z, j \vdash u) \in D(C_1)$. Thus by construction of $\rho$, we deduce that there exists $u'_k$ such that $(Z, s \vdash u'_k) \in \Phi(C'_1)$ and so $\{ (\xi, s \vdash u) \in \Phi(C_1) \} \subseteq \{ (\xi, i \vdash u) \in \Phi(C'_1) \}$.

Hence, for all $X \in \text{vars}(\xi)$, $\text{Inv\nontouched}(s)$, we deduce that the variables that are not in $\text{img}(\rho)$.

First of all, for all $Y \in \text{vars}(\xi)$, for all position $p$, if $\text{root}(C_1[Y \theta|_{\Phi(C_1)}]_p) = g \in F_2$ then $\text{path}(Y|D) \in F^\_1 \cdot \text{AX}$. But since $(\sigma, \theta) \in \text{Sol}(C_1)$, then $Y|D \cdot \text{path} \in T(F_2, N)$. Moreover, we know that $(\sigma', \theta') \in \text{Sol}(C'_1)$ with $\sigma|S_1 = \sigma'|S_1$. By Lemma 4.44 we know that $\text{Init}(C_1)\sigma = \text{Init}(C'_1)\sigma'$ and so $Y|D \cdot \text{path} \in T(F_2, N)$.

Furthermore, the matrix $M_1$ is obtained at the end of step 1 of phase 1 of the strategy, then $C'_1$ satisfies the invariant $\text{Inv\dest}(s)$. Thus, with $\sigma' \not= \text{ND}(C'_1)$, we can deduce that either (a) there exists a frame element $(\xi, s \vdash u) \in \Phi(C'_1)$ such that $\text{path}(\xi) = \text{path}(Y|D)$ or else (b) there exists a frame element $(\xi', i \vdash u) \in \Phi(C'_1)$ such that $\text{path}(\xi')$ is a suffix of $\text{path}(Y|D)$ and $(\xi', i \vdash u) \in \text{NoUse}(C'_1)$.

Case (b): Since $(\sigma, \theta) \in \text{Sol}(C_1)$, we deduce that $Y \theta$ conforms to $\Phi(C_1)$ w.r.t. $\text{NoUse}(C_1)$. Hence, we deduce that there is no frame element on $\Phi(C_1)$ which element have path$(\xi')$ as path. Hence, thanks to property 3 of the well-formed constraint system, we can also deduce that there exists position $p'$ of $C_1[Y \theta|_{\Phi(C_1)}]$ such that $C_1[Y \theta|_{\Phi(C_1)}]_p = \text{path}(\xi')$ and $i = s$. But by Property 3 of a well-formed constraint system, $(\xi', s \vdash v) \in \text{NoUse}(C'_1)$ implies that there exists $Z \in \text{vars}(\xi)$ such that $C[Z_{\text{mgu}}(\text{Er}(C'_1))]_{\Phi(C'_1)} \text{acc}(C'_1) = v$ and $\text{param}_{\max}(Z_{\text{mgu}}(\text{Er}(C'_1))) < s$.

Since we proved that $\text{Init}(C_1)\sigma = \text{Init}(C'_1)\sigma'$, then $Z(\theta|\Phi(C_1)\sigma) = Z(\theta|\Phi(C'_1)\sigma)$. Hence we have that $Y|D = Z(\theta|\Phi(C'_1)\sigma)$, where $\text{param}_{\max}(Z(\theta)) < s$ which is a contradiction on the hypothesis on $\theta$. Thus we can deduce that this case is impossible.

Case (a): Let’s denote $Y|D = g(\xi_1, \ldots, \xi_n)$. Thanks to $M_1$ satisfying invariant $PP_{1Sa}(s)$, we know that there exists $X_2, \ldots, X_n \in \text{vars}(\xi)$ such that $\xi = g(\xi_1, X_2, \ldots, X_n)$ for some $\xi_1$. Some useful results from Property 8 of the well-formed constraint system include: $\text{Card}(\Phi(C_1)) = \text{Card}(\Phi(C'_1))$. Hence for all $\xi \in \Phi(C_1)$, $\xi \not\in \text{vars}(\xi)$, we can already proved that $\{ \text{path}(\xi, \xi, i \vdash u) \in \Phi(C_1) \} \subseteq \{ \text{path}(\xi, \xi, i \vdash u) \in \Phi(C'_1) \}$.
Furthermore, we know, by definition of $\theta$, that all recipe in $\theta$ with the same path is equal to $Y\theta|_p$.

Hence for all $i \in \{2, \ldots, n\}$, we define $X_i^{\theta''} = \zeta_i$.

Let $M$ be the set of all the others variables in $D(C_i')$ not already defined at this stage. For all $X \in M$, we define $X^{\theta''} = C[X\theta']_{\Phi(C_i')}\text{acc}^2(C_i')^{\theta''}$ which exists by following the order $<_{\theta'}$ on $M$.

Typically, the variables in $M$ represents the variables that could not be instantiate thanks to $\theta$. Thus, since $(\sigma', \theta') \in \text{Sol}(C_i')$, we used $\theta'$ to defined those variables. The expression $C[X\theta']_{\Phi(C_i')}\text{acc}^2(C_i')^{\theta''}$ represents the fact that the context of $X\theta'$ and $X^\theta''$ are the same.

Finally, for all $X \in \text{vars}^2(C_i') \setminus \text{vars}^2(D(C_i'))$, we define $X^{\theta''} = X\text{mgu}(Er(C_i'))^{\theta''}$

To verify that $(\sigma', \theta') \in \text{Sol}(C_i')$, it remains to prove that $\theta'' \models \text{Er}(C_i')$. The others propriety are indeed satisfied by construction of $\theta''$. Thanks to $M_i$ satisfying invariant PP1Sa(s) item C.2, we know that the variable in $D(C_i')$ do not appear in any inequation in $\text{Er}(C_i')$. Furthermore, since by definition of $\theta''$, $\theta''$ satisfies $\text{mgu}(\text{Er}(C_i'))$, we can deduce that $\theta'' \models \text{Er}(C_i')$.

\medskip

Lemma C.47. Let $M$ be a matrix of constraint system obtained at the end of step $e$ of phase 1 of the strategy with $s$ as support. Let $C$ be a constraint system in $M$. Let $(\sigma, \theta) \in \text{Sol}(\overline{C})$. We have that there exists $\theta''$ such that $(\sigma, \theta'') \in \text{Sol}(\overline{C})$

1. for all $X \in D(C)$, for all position $p$ of $C[X\theta']_{\Phi(C)}$, if $\text{root}(C[X\theta']_{\Phi(C)}, \in F_d$, then there is no ground recipe $\xi \in \Pi_n$ such that $\xi(\Phi(C)\sigma)_L = X\theta'_p(\Phi(C)\sigma)_L \in T(F_c, N)$ and $\text{param}_{\text{max}}(\xi) < \text{param}_{\text{max}}(X^{\theta''}_p)$; and

2. for all $\xi, \xi' \in st(X\theta | X \in D(C))$, path($\xi$) = path($\xi'$) implies $\xi = \xi'$.

Proof. We begin by proving the first property of the result: We show that there exists $\theta''$ such that $(\sigma, \theta'') \in \text{Sol}(\overline{C})$ and for all $X \in D(C)$, for all position $p$ of $C[X\theta']_{\Phi(C)}$, if $\text{root}(C[X\theta']_{\Phi(C)}, \in F_d$, then there is no ground recipe $\xi \in \Pi_n$ such that $\xi(\Phi(C)\sigma)_L = X\theta'_p(\Phi(C)\sigma)_L \in T(F_c, N)$ and $\text{param}_{\text{max}}(\xi) < \text{param}_{\text{max}}(X^{\theta''}_p)$.

We prove this property by induction on the number of positions $p$ which do not satisfy the property. Let’s denote this number $m(\theta)$.

Base case $m(\theta) = 0$: In such a case, the result trivially holds.

Inductive step $m(\theta) > 0$: Otherwise, let $X \in \text{vars}^2(D(C))$, a position $p$ and a ground recipe $\xi \in \Pi_n$ such that $\text{root}(C[X\theta']_{\Phi(C)}, \in F_d$, $\xi(\Phi(C)\sigma)_L = X\theta'_p(\Phi(C)\sigma)_L \in T(F_c, N)$ and $\text{param}_{\text{max}}(\xi) < \text{param}_{\text{max}}(X^{\theta''}_p)$.

First of all, thanks to Lemma C.46, we know that there exists $\xi' \in \Pi_n$ such that $\xi'$ conforms to $\Phi(C)$ w.r.t. NoUse($C)$, $\xi(\Phi(C)\sigma)_L = \xi'(\Phi(C)\sigma)_L$ and $\text{param}_{\text{max}}(\xi') \leq \text{param}_{\text{max}}(\xi)$.

Secondly, thanks to Property 1 shown in Lemma C.42, we know that there exists a position $p'$ and $\xi'' \in st(\xi')$, such that $p'$ is a prefix of $p$ and $X\theta'[\xi'_p(\Phi(C)\sigma)_L = X\theta''[\xi''_p(\Phi(C)\sigma)_L \in T(F_c, N)$.

We want to apply Lemma C.45 for the replacement. We know that $C$ satisfies the invariants InvVarFrame(s) and InvUntouched(s). Thus for all $(\zeta, i \succ u) \in \Phi(C)$, for all $Z \in \text{vars}^2(C)$, $\text{param}_{\text{max}}(Z) < i$. But, for all $Z \in \text{vars}^2(C[X\theta']_{\Phi(C)}, \Phi(C))$, either $Z \in \text{vars}^2(C[X\theta']_{\Phi(C)}$ else $Z \in \text{vars}^2(C[\xi''_p|\Phi(C)]$. Since $\xi'' \in st(\xi')$ and $\text{param}_{\text{max}}(\xi') \leq \text{param}_{\text{max}}(X^{\theta''}_p)$, we can deduce, thanks to Lemma C.48 that $\neg(X < Z)$. Hence we can apply Lemma C.41 which gives us that there exists $\theta''$ such that $(\sigma, \theta'')$ is a pre-solution of $C$ with $X\theta'' = X\theta'[\xi''_p, \theta'' \models \text{mgu}(\text{Er}(C))$ and for all $Y \in \text{vars}^2(D(C) \setminus \{X\})$, $C[Y\theta']_{\Phi(C)} = C[Y\theta']_{\Phi(C)}$.

However, we know that $M$ is obtained at the end of step $e$ of Phase 1 with support $s$. Hence thanks to Lemma C.47, $M$ satisfies PP1Sa(s), and so $C$ satisfies: for all $(X, i \succ x) \in D(C)$, for all $(\xi, j \succ u) \in \Phi(C)$, for all $f \in F_c$, $\text{Er} \not\models \text{root}(X) \neq f$ and $\text{Er} \not\models X \neq \xi$, Hence, we can deduce that $\theta'' \models \text{Er}(C)$ and $(\sigma, \theta'') \in \text{Sol}(\overline{C})$.

At last, since we replace a subterm of $X\theta$ by a recipe of strictly smaller maximal parameter and for all $Y \in \text{vars}^2(D(C) \setminus \{X\})$, $C[Y\theta']_{\Phi(C)} = C[Y\theta']_{\Phi(C)}$, we can deduce that $m(\theta''') < m(\theta)$. Hence we conclude by applying our inductive hypothesis.

We now show the second property of the result. First of all, we know that for all $X \in D(C)$, $X\theta''$ conforms to $\Phi(C)\theta$ w.r.t. NoUse($C)$, Hence, if there exists $X, Y \in D(C), \xi \in st(X\theta)$ and
\[\xi' \in \text{st}(Y \theta)\] such that \(\text{path}(\xi) = \text{path}(\xi')\) and \(\xi \neq \xi'\), it implies that \(\text{root}((\xi)) \in F \varnothing\) and there is no frame element \((\xi, i > u) \in \Phi(C)\) such that \(\text{path}(\xi) = \text{path}(\xi)\) (otherwise it would contradict the conformity of \(X \theta\) to \(\Phi(C)\) w.r.t. \(\text{NoUse}(\theta)\). Hence it implies that there exists \(p\) (resp. \(p')\) position of \(C[X \theta]_{\Phi(C)}\) (resp. \(C[Y \theta]_{\Phi(C)}\)) such that \(X \theta[p] = \xi\) (resp. \(Y \theta[p'] = \xi'\)).

Hence, we do our proof by induction on the number of position that do not satisfies the wanted property: Let \(M(\theta)\) be the set defined such that \(M(\theta) = \{\text{path} | X, Y \in \text{vars}^2(D(C))\) and \(\xi, \xi' \in \text{st}(X \theta, Y \theta)\) and \(\text{path}(\xi) = \text{path}(\xi')\) and \(\xi \neq \xi'\).

**Base case** \(M(\theta) = \emptyset\): In such a case, the result trivially holds.

**Inductive step** \(M(\theta) \neq \emptyset\): Let \(w\) be a minimal path in term of size in \(M(\theta)\). Let \(X_0\) be a minimal variable in term of \(<_\theta\) of all variables \(X\) where there exists a position \(p\) of \(C[X \theta]_{\Phi(C)}\) such that \(\text{path}(X \theta[p]) = w\).

Hence we know that there exists \(p_0\) position of \(C[X_0 \theta]_{\Phi(C)}\) such that \(\text{path}(X_0 \theta[p_0]) = w\). We will replace any recipe that have \(w\) as path by \(X_0 \theta[p_0]\) that we denote \(\xi_0\). Hence, we do a new induction on:

\[m(\theta) = \sum_{\text{path}(\xi) = w} \text{nb} \text{occ}(\xi, \{Y \theta | Y \in D(C)\}) - \text{nb} \text{occ}(\xi_0, \{Y \theta | Y \in D(C)\})\]

**Base case** \(m = 0\): In such a case, it implies that any subterm whose path is equal to \(w\), is in fact \(\xi_0\). Hence it contradicts the fact that \(w \in M\).

**Inductive case** \(m > 0\): Otherwise, we have that there exists \(Y \in \text{vars}^2(D(C))\) and \(p\) position of \(C[Y \theta]_{\Phi(C)}\) such that \(\text{path}(Y \theta[p]) = w\) but \(Y \theta[p] \neq X \theta[p]\). We want to apply Lemma C.41 hence we have to verify the application conditions of the lemma. Let \(\xi = X \theta[p]\).

- Since \(\xi\) is a subterm of \(X \theta\) and \((\sigma, \theta) \in \text{Sol}(\text{C})\), we have that \(\xi\) conforms to \(\Phi(C)\) w.r.t. \(\text{NoUse}(C)\). Furthermore, thanks to the first property we shown in this lemma, we know that \(\text{path}(\xi) = \text{path}(Y \theta[p])\) implies \(\text{param}_{\text{max}}(\xi) = \text{param}_{\text{max}}(Y \theta[p])\). Hence since \(Y \theta[p] \in \text{st}(Y \theta)\) and \((\sigma, \theta) \in \text{Sol}(\text{C})\), we deduce that \(\text{param}_{\text{max}}(\xi) \leq \text{param}_{\text{max}}(Y)\).

- Since \(\text{path}(\xi) = \text{path}(Y \theta[p])\), \(\Phi(C)\sigma)\downarrow \in T(F_c, N)\) and \(Y \theta[p](\Phi(C)\sigma)\downarrow \in T(F_c, N)\), then by Lemma C.31 we have that \(\xi(\Phi(C)\sigma)\downarrow = Y \theta[p](\Phi(C)\sigma)\downarrow\). Furthermore \(\text{path}(\xi) = \text{path}(Y \theta[p])\) also implies \(C[Y \theta[p]]_{\Phi(C)} = C[Y \theta[p]]_{\Phi(C)}\).

- \(X_0\) was chosen as minimal under \(<_\theta\), hence for all \(Z \in \text{vars}^2(C[\xi]_{\Phi(C)}\text{acc}^2(C))\), if we had \(Y <_\theta Z\) then it would imply that \(Y <_\theta X_0\) since we have that \(Z <_\theta X_0\). This is a contradiction, hence we have that \(\neg(Y <_\theta Z)\).

Thus by Lemma C.41, we have that there exists \(\theta'\) such that \((\sigma, \theta')\) is a pre-solution of \(C\) with \(Y \theta' = Y \theta[\xi]\), \(\theta' = \text{mg}(E \theta(C))\) and for all \(Z \in \text{vars}^2 D \setminus \{Y\}\), we have that \(C[Z \theta']_{\Phi(C)} = C[Z \theta]_{\Phi(C)}\).

But with \((\sigma, \theta) \in \text{Sol}(\text{C})\), we trivially have that \(\sigma = \text{Eq}(C)\). Moreover, since \(\text{C}\) is a constraint system obtained from \(\text{step}\) \(\varepsilon\), we have shown that for all \(Z \in \text{vars}^2(D(C))\), for all \(f \in F_c\), there is no inequation in \(E \theta(C)\) of the form \(Z \neq \xi \) or \(\text{root}(Z) \neq f\) where \(\xi\) is a recipe of \(\Phi(C)\). Hence we have that \(\theta' \equiv E \theta(C)\) and so \((\sigma, \theta') \in \text{Sol}(\text{C})\).

By construction, we have that \(m(\theta') < m(\theta)\). Furthermore, the construction of \(\theta'\), i.e. \(Y \theta' = Y \theta[\xi]\) and for all \(Z \in \text{vars}^2 D \setminus \{Y\}\), \(C[Z \theta']_{\Phi(C)} = C[Z \theta]_{\Phi(C)}\), imply that \(X_0\) is also a minimal variable in term of \(<_\theta'\) from all variables \(X \in \text{vars}^2(D(C))\) where there exists a position \(p\) of \(C[X \theta]_{\Phi(C)}\) such that \(\text{path}(X \theta[p]) = w\). Hence we can apply our inductive hypothesis on \(\theta'\) which conclude the result.

**Definition C.1.** We define a constructor layer equivalence relation between ground recipe of \(\Pi_n\), denoted \(R_{F_c}\), as follows: Let \(\xi, \xi' \in \Pi_n\) two ground recipes, \(\xi R_{F_c} \xi'\) if:

- \(\text{path}(\xi)\), \(\text{path}(\xi')\) exist and \(\text{path}(\xi) = \text{path}(\xi')\); or
\[ \xi = f(\xi_1, \ldots, \xi_n), \xi' = g(\xi'_1, \ldots, \xi'_n) \text{ for some } g, f \in \mathcal{F}_c, \text{ and for all } i \in \{1, \ldots, n\}, \xi_i \mathcal{R}_{\mathcal{F}_c} \xi'_i. \]

**Lemma C.48.** Let \( \Phi \) a ground frame. Let \( \xi \) and \( \xi' \) two ground recipes. \( C[\xi]_\Phi = C[\xi']_\Phi \) implies \( \xi \mathcal{R}_{\mathcal{F}_c} \xi' \).

**Proof.** We prove the result by induction on \( |C[\xi]_\Phi| \) but we will also prove in the same time that if \( C[\xi]_\Phi = C[\xi']_\Phi \), and path(\( \xi \)) = path(\( \xi' \)) exist then path(\( \xi' \)) = path(\( \xi \)).

**Base case** \( |C[\xi]_\Phi| = 1 \): In such a case, there exists \( (\xi, i \triangleright u) \in \Phi \) such that path(\( \xi \)) = path(\( \xi' \)). Since \( C[\xi']_\Phi = C[\xi]_\Phi \), we deduce that path(\( \xi' \)) = path(\( \xi \)) and so \( \xi \mathcal{R}_{\mathcal{F}_c} \xi' \).

**Inductive step** \( |C[\xi]_\Phi| > 1 \): By definition of a context, it implies that \( \xi = f(\xi_1, \ldots, \xi_n) \) and \( C[\xi]_\Phi = f(C[\xi_1]_\Phi, \ldots, C[\xi_n]_\Phi) \). Similarly, \( \xi' = g(\xi'_1, \ldots, \xi'_n) \) and \( C[\xi']_\Phi = g(C[\xi'_1]_\Phi, \ldots, C[\xi'_n]_\Phi) \). Since \( C[\xi]_\Phi = C[\xi']_\Phi \), we deduce that \( g = f \) and for all \( i \in \{1, \ldots, n\}, \), \( C[\xi_i]_\Phi = C[\xi'_i]_\Phi \). If \( f \in \mathcal{F}_c \) then by induction on \( \xi_i \) and \( \xi'_i \), we deduce that for all \( i \in \{1, \ldots, n\}, \xi_i \mathcal{R}_{\mathcal{F}_c} \xi'_i \). Along with \( f = g \), we conclude that \( \xi \mathcal{R}_{\mathcal{F}_c} \xi' \).

Else we have \( f = g \in \mathcal{F}_d \). But \( \xi \) and \( \xi' \) are recipe in \( \Pi_{\mathcal{F}} \). Hence it implies that root(\( \xi \)) \( \not\in \mathcal{F}_c \) and root(\( \xi' \)) \( \not\in \mathcal{F}_d \). Hence path(\( \xi \)) and path(\( \xi' \)) exists and path(\( \xi \)) = path(\( \xi' \)).

But by inductive hypothesis on \( \xi_1, \xi'_1 \), we deduce that path(\( \xi_1 \)) = path(\( \xi'_1 \)). Hence we conclude that path(\( \xi \)) = path(\( \xi' \)) and so \( \xi \mathcal{R}_{\mathcal{F}_c} \xi' \).

**Lemma C.49.** Let \( M \) be a matrix of constraint system obtained during step b to d of phase 1 of the strategy. Let \( M' \) be the father of \( M \). Let \( \mathcal{C}_1 \) a constraint system in \( M \) and \( \mathcal{C}_2 \) be its father in \( M' \). Let \( \mathcal{C}_2' \) be a constraint system in the column of \( \mathcal{C}_1 \) in \( M' \). Let \((\sigma_1', \theta'_1) \in \text{Sol}(\mathcal{C}_1') \), \((\sigma_2', \theta'_2) \in \text{Sol}(\mathcal{C}_2') \) and \((\sigma_1, \theta_1) \in \text{Sol}(\mathcal{C}_1) \). If

1. \( \sigma_1|_{\text{vars}^*(\mathcal{C}_1')} = \sigma_1', \theta_1|_{\text{vars}^*(\mathcal{C}_1')} = \theta'_1 \)
2. \( \sigma_2'|_{S_1(\mathcal{C}_1')} = \sigma_2'|_{S_1(\mathcal{C}_2')} \)
3. for all \( X \in S_2(\mathcal{C}_1'), X \theta_1 \mathcal{R}_{\mathcal{F}_c} X \theta_2 \)
4. for all \( X, Y \in S_2(\mathcal{C}_2'), \) for all \( p \in \text{Pos}(C[X \theta_2|_{\Phi(\mathcal{C}_2')}], \) for all \( p \in \text{Pos}(C[Y \theta_2|_{\Phi(\mathcal{C}_2')}], \) if path(\( X \theta_2|_{\Phi(\mathcal{C}_1)} \)) = path(\( X \theta_2|_{\Phi(\mathcal{C}_1)} \)) then \( X \theta_2|_{\Phi(\mathcal{C}_1)} = X \theta_2|_{\Phi(\mathcal{C}_1)} \).

then we have that there is a constraint system \( \mathcal{C}_2 \) in the column of \( \mathcal{C}_1 \) in \( M \) and \((\sigma_2, \theta_2) \in \text{Sol}(\mathcal{C}_2) \) such that

1. \( \mathcal{C}_2 \rightarrow \mathcal{C}_2 \)
2. \( \sigma_2|_{\text{vars}^*(\mathcal{C}_2')} = \sigma_2', \theta_2|_{\text{vars}^*(\mathcal{C}_2')} = \theta'_2 \)
3. for all \( X \in S_2(\mathcal{C}_1), X \theta_1 \mathcal{R}_{\mathcal{F}_c} X \theta_2 \)
4. for all \( X, Y \in S_2(\mathcal{C}_2), \) for all \( p \in \text{Pos}(C[X \theta_2|_{\Phi(\mathcal{C}_1)}], \) for all \( p \in \text{Pos}(C[Y \theta_2|_{\Phi(\mathcal{C}_1)}], \) if path(\( X \theta_2|_{\Phi(\mathcal{C}_1)} \)) = path(\( X \theta_2|_{\Phi(\mathcal{C}_1)} \)) then \( X \theta_2|_{\Phi(\mathcal{C}_1)} = X \theta_2|_{\Phi(\mathcal{C}_1)} \).

**Proof.** Since \( M' \) is the father of \( M \), we do a case analysis on the rule applied on \( M' \).

**Case of internal rule not applied on \( \mathcal{C}_2' \):** In such a case, it implies that \( \mathcal{C}_2' \) is also a constraint system in the column of \( \mathcal{C}_1 \) in the matrix \( M \). Hence, by denoting \( \mathcal{C}_2 = \mathcal{C}_2' \), and \((\sigma_2, \theta_2) = (\sigma_2', \theta_2') \), we trivially have that the two first wanted properties. Hence, it remains to show that \( X \theta_1 = X \theta_2 \) for all \( X \in S_2(\mathcal{C}_1) \). But since \( \mathcal{C}_2 \) is in \( M \), we know that \( \mathcal{C}_2 \) and \( \mathcal{C}_1 \) have the same structure and so \( S_2(\mathcal{C}_1) = S_2(\mathcal{C}_2) \). Similarly, we have \( S_2(\mathcal{C}_1') = S_2(\mathcal{C}_2') \). At last, the rule applied is an internal rule hence we have \( S_2(\mathcal{C}_1) = S_2(\mathcal{C}_1') \). Thus, \( \theta_1|_{\text{vars}^*(\mathcal{C}_1')} = \theta'_1 \) implies that for all \( X \in S_2(\mathcal{C}_1)' \), \( X \theta_1 = X \theta'_1 \). Hence with \( X \theta'_1 \mathcal{R}_{\mathcal{F}_c} X \theta_2' \) and \( \theta_2 = \theta'_2 \), then we deduce that \( X \theta_1 \mathcal{R}_{\mathcal{F}_c} X \theta_2 \).

Moreover, \( \theta_2 = \theta'_2 \) and hypothesis \( \mathcal{H} \) implies property \( \mathcal{H} \).
Case of internal rule applied on \(C'_2\): In such a case, it implies that \(C_1 = C'_1\) and so \((\sigma_1, \theta_1) = (\sigma'_1, \theta'_1)\). Let \(C_3\) and \(C_4\) be the two constraint system obtained by application of \(R(\tilde{p})\) on \(C'_2\). By the definition of an internal rule, we know that both \(C_3\) and \(C_4\) are in the column of \(C_1\) in the matrix \(M\).

Thanks to Lemma 3.10, \((\sigma_2, \theta'_2) \in \text{Sol}(C'_2)\) implies that there exists \(i \in \{3, 4\}\) and \((\sigma, \theta) \in \text{Sol}(C_i)\) such that \(\sigma_i|\{C_i\} = \sigma'_2|\{C'_2\}\).

Furthermore, the only possible rule applicable in this case are Axiom, Cons, Eq-left-left, Eq-right-right and Ded-st. Since the strategy dictates that Eq-right-right can only be applied internally when \(\xi\) is a variable with \(\text{param}_{\text{max}}(\xi) < s\) then, by following the proof of Lemma 3.10, we deduce for all \(X \in S_2(C'_2)\), \(C[X\theta]|\{C_i\} = C[X\theta'_2]|\{C'_i\}\). But thanks to Lemma 3.10, we deduce that \(X \theta \R_{\mathcal{F}} X \theta'_2\).

Let \(p, p'\) positions of \(C[X\theta]|\{C_i\}, C[Y\theta]|\{C_i\}\) respectively where \(X, Y \in S_2(C)\). Assume that \(\text{path}(X\theta|_p) = \text{path}(Y\theta|_{p'})\). But \(C[X\theta]|\{C_i\} = C[X\theta'_2]|\{C'_i\}\) and \(C[Y\theta]|\{C_i\} = C[Y\theta'_2]|\{C'_i\}\). Hence \(\text{path}(X\theta|_p) = \text{path}(Y\theta|_{p'})\) implies that \(\text{path}(X\theta'_2|_p) = \text{path}(Y\theta'_2|_{p'})\). By hypothesis, we deduce that \(X \theta'_2|_p = Y \theta'_2|_{p'}\). Hence, thanks to \(C[X\theta]|\{C_i\} = C[X\theta'_2]|\{C'_i\}\), \(C[Y\theta]|\{C_i\} = C[Y\theta'_2]|\{C'_i\}\) we deduce that \(C[X\theta]|_p|\{C_i\} = C[Y\theta]|_{p'}|\{C'_i\}\). Since \(X \theta, Y \theta'\) conforms to \(\Phi(C_i)\) w.r.t. NoUse, we deduce that \(X \theta|_p = Y \theta|_{p'}\).

Moreover, since \(X \theta\) (resp. \(X \theta'_2\)) conforms with \(\Phi(C'_1)\) (resp. \(\Phi(C'_2)\)) and \(C[X\theta]|\{C_i\} = C[X\theta'_2]|\{C'_i\}\) since \(S_2(C'_1) = S_2(C_2)\) and by hypothesis, \(X \theta'_1 \R_{\mathcal{F}} X \theta'_2\), we have that \(X \theta_1 \R_{\mathcal{F}} X \theta'_1\), \(X \theta' \R_{\mathcal{F}} X \theta'_2\), \(X \theta_1 \R_{\mathcal{F}} X \theta'_1\). Hence, the result holds by denoting \(C_2 = C_i\) and \((\sigma_2, \theta_2) = (\sigma, \theta)\).

Case of external rule: In such a case, the rule \(R(\tilde{p})\) is applied on both \(C'_1\) and \(C'_2\). The only possible external rules are Cons, Axiom and Eq-right-right. By definition of an external application of the rule, we also know that if \(C\) is the right (resp. left) son of \(C_i\) then there exists a constraint system \(C'\) in \(M\) such that \(S'\) is the right (resp. left) son of \(C'_1\). We do a case analysis on the rule applied.

- Rule Cons\((X, f)\), left son: In such a case, \(E \text{r}(C_1) = E \text{r}(C'_1)\) and \(X \nleq f(X_1, \ldots, X_n)\), \(E \text{r}(C_2) = E \text{r}(C'_2)\) and \(X \nleq f(X_1, \ldots, X_n)\), \(E \text{q}(C_1) = E \text{q}(C'_1)\) and \(X \text{acc}(C_1) = f(x_1, \ldots, x_n)\), \(E \text{q}(C_2) = E \text{q}(C'_2)\) and \(X \text{acc}(C_2) = f(y_1, \ldots, y_n)\) where \(X_i, x_i, y_i\) are fresh variables for all \(i \in \{1, \ldots, n\}\) in \(S_2(C'_1) = S_2(C_2)\). Moreover, \(X \in S_2(C'_1) = S_2(C_2)\).

By hypothesis, we know that \((\sigma_1, \theta_1) \in \text{Sol}(\overline{C_1})\), \(\theta_1|_{\text{var}^2(C'_1)}\) and \((\sigma'_2, \theta'_2) \in \text{Sol}(\overline{C'_2})\). Hence \(\theta_1 \nleq E \text{r}(C_1)\) implies that \(\text{root}(X \theta'_1) = f \in \mathcal{F}_c\). But \(X \theta'_1 \R_{\mathcal{F}} X \theta'_2\) thus we deduce that \(\text{root}(X \theta'_2) = f\). We define \(\theta_2 = \theta'_2 \cup \{X_1 \nleq X \theta'_1|_{\mathcal{F}_c}, \ldots, X_n \nleq X \theta'_1|_{\mathcal{F}_c}\}\). We show that for all \(i \in \{1, \ldots, n\}\), \(X_1 \theta_2 \R_{\mathcal{F}} X \theta_2\) \(\text{root}(X \theta'_2) = \text{root}(X \theta'_1) \equiv f \in \mathcal{F}_c\) and \(X \theta'_1 \R_{\mathcal{F}} X \theta'_2\) implies by definition of \(\mathcal{F}_c\) that \(X_1 \theta' = f(\xi_1, \ldots, \xi_n)\) and \(X_1 \theta_2 = f(\xi_1, \ldots, \gamma_n)\) for some \(\xi_1, \ldots, \gamma_n, \xi_1, \ldots, \gamma_n\) and for all \(i \in \{1, \ldots, n\}\), \(X_i \theta_2 = \xi_i\) and \(X_2 \theta_2 = \gamma_i\), the result holds.

Moreover, since for all \(i \in \{1, \ldots, n\}\), \(C[x_i]|\{C'_2\}\) is a subterm of \(C[X\theta'_2]|\{C'_2\}\), then hypothesis 8 implies property 4.

It remains to build \(\sigma_2\). Since \((\sigma'_2, \theta'_2) \in \text{Sol}(C'_2)\), we know that \(X \theta'_2(\Phi(C'_2)\sigma'_2) = f(u_1, \ldots, u_n)\) where for all \(i \in \{1, \ldots, n\}\), \(\xi_i(\Phi(C'_2)\sigma'_2) = u_i\). Since \(y_1, \ldots, y_n\) are fresh variables, we define \(\sigma_2 = \sigma'_2 \cup \{y_1 \nleq u_1, \ldots, y_n \nleq u_n\}\). Hence \(\text{root}(X \theta'_2) = f(y_1, \ldots, y_n)\). Hence we conclude that \((\sigma_2, \theta_2) \in \text{Sol}(\overline{C'_2})\).

- Rule Cons\((X, f)\), right son: In such a case, \(E \text{r}(C_1) = E \text{r}(C'_1)\) and \(\text{root}(X) \nleq f\) and \(E \text{r}(C_2) = E \text{r}(C'_2)\) and \(\text{root}(X) \nleq f\). By hypothesis, we know that \((\sigma_1, \theta_1) \in \text{Sol}(\overline{C_1})\), \(\theta_1|_{\text{var}^2(C'_1)}\) and \((\sigma'_2, \theta'_2) \in \text{Sol}(\overline{C'_2})\). Hence \(\theta_1 \nleq E \text{r}(C_1)\) implies that \(\text{root}(X \theta'_1) \nleq f \in \mathcal{F}_c\). But \(X \theta'_1 \R_{\mathcal{F}} X \theta'_2\) thus we deduce that \(\text{root}(X \theta'_2) \nleq f\). Hence the result holds with \((\sigma_2, \theta_2) = (\sigma'_2, \theta'_2)\). Moreover, hypothesis 4 trivially implies property 4.

- Rule Axiom\((X, \text{path})\), left son: \(E \text{r}(C_1) = E \text{r}(C'_1)\) and \(X \nleq \xi_1\), \(E \text{r}(C_2) = E \text{r}(C'_2)\) and \(X \nleq \xi_2\). \(E \text{q}(C_1) = E \text{q}(C'_1)\) and \(X \text{acc}(C'_1) = \text{path}(\xi_1) \text{acc}(C'_1)\) and \(E \text{q}(C_2) = E \text{q}(C'_2)\) and \(X \text{acc}(C'_2) = \text{path}(\xi_2) \text{acc}(C'_2)\) where \(\text{path}(\xi_1) = \text{path}(\xi_2)\).
By hypothesis, we know that \((\sigma_1, \theta_1) \in \text{Sol}(C_1)\), \(\theta_1|_{\text{vars}(C_1)}\) and \((\sigma_2, \theta_2) \in \text{Sol}(C_2)\). Hence \(\theta_1 \models \text{Er}(C_1)\) implies \(X \theta_1 |_{\text{vars}(C_1)} = \xi_1|_{\text{vars}(C_1)}\). But \(X \theta_1 \cdot \mathcal{R}_F \cdot X \theta_2\) hence since \(\text{path}(X \theta_1 |_{\text{vars}(C_1)})\) exists, we deduce that \(\text{path}(X \theta_2 |_{\text{vars}(C_1)}\) exists and \(\text{path}(X \theta_2 |_{\text{vars}(C_1)})\) exists. Moreover, \((\sigma_2, \theta_2) \in \text{Sol}(C_2)\) also implies that \(X \theta_2 |_{\text{vars}(C_1)}\) is \(\Phi(C_2)|\theta_2\) w.r.t. \text{NoUse}(\sigma_2)\). Hence since \(\xi_2\) is a recipe of a frame element of \(\Phi(C_2)\) such that \(\text{path}(\xi_2) = \text{path}(\xi_1) = \text{path}(X \theta_2 |_{\text{vars}(C_1)})\), we conclude that \(X \theta_2 |_{\text{vars}(C_1)} = \xi_2 |_{\text{vars}(C_1)}\). Hence \((\sigma_2, \theta_2) \models \text{Er}(C_2)\). Moreover, hypothesis \([4]\) trivially implies property \([4]\).

Since \((\sigma_1, \theta_1) \in \text{Sol}(C_1)\), \((\sigma_2, \theta_2) \in \text{Sol}(C_2)\) and \(\sigma_1|_{\text{vars}(C_1)} = \sigma_2|_{\text{vars}(C_1)}\) then by Lemma \([C.44]\) we have that \(\text{Xacc}\left(C_1\right) \sigma_2 \models \text{Xacc}\left(C_1\right) \sigma_1\) and \(\text{path}(\xi_1) \text{acc}\left(C_1\right) \sigma_1 = \text{path}(\xi_2) \text{acc}\left(C_2\right) \sigma_2\). Hence, \(\sigma_1\) satisfies \(\text{Xacc}\left(C_1\right) \models \text{Xacc}\left(C_1\right)\) implies \(\sigma_2 \models \text{Xacc}\left(C_2\right) \models \text{path}(\xi_2) \text{acc}\left(C_2\right) \sigma_2\). Hence \((\sigma_2, \theta_2) \in \text{Sol}(C_2)\).

- **Rule Axiom(X,path), right son**: \(\text{Er}(C_1) = \text{Er}(C_1) \wedge X \neq \xi_1, \text{Er}(C_2) = \text{Er}(C_2) \wedge X \neq \xi_2\). By hypothesis, we know that \((\sigma_1, \theta_1) \in \text{Sol}(C_1)\), \((\sigma_2, \theta_2) \in \text{Sol}(C_2)\) and \(\theta_1 \models \text{Er}(C_1)\) implies \(X \theta_1 \neq \xi_1|_{\text{vars}(C_1)}\). Since \(X \theta_1|_{\text{vars}(C_1)}\) is \(\Phi(C_1)|\theta_1\) w.r.t. \text{NoUse}(\sigma_1)\), it also implies that \(\text{path}(X \theta_1|_{\text{vars}(C_1)}) \neq \text{path}(\xi_1)\). But \(X \theta_1 \cdot \mathcal{R}_F \cdot X \theta_2\) hence \(\text{path}(X \theta_1|_{\text{vars}(C_1)}) = \text{path}(X \theta_2|_{\text{vars}(C_1)})\) and so \(\text{path}(X \theta_2|_{\text{vars}(C_1)}) \neq \text{path}(\xi_2)\). Thus, we deduce that \(X \theta_2 \neq \xi_2|_{\text{vars}(C_1)}\) and so the result holds with \((\sigma_2, \theta_2) = (\sigma_2, \theta_2)\).

- **Rule Eq-right(X,ξ), left son**: \(\text{Er}(C_1) = \text{Er}(C_1) \wedge X \neq \xi_1, \text{Er}(C_2) = \text{Er}(C_2) \wedge X \neq \xi_2\). By hypothesis, we know that \((\sigma_1, \theta_1) \in \text{Sol}(C_1)\), \((\sigma_2, \theta_2) \in \text{Sol}(C_2)\) and \(\theta_1 \models \text{Er}(C_1)\) implies \(X \theta_1 = Y \theta_1\). But \(X \theta_1 \cdot \mathcal{R}_F \cdot X \theta_2\) and \(Y \theta_1 \cdot \mathcal{R}_F \cdot Y \theta_2\). Hence, we deduce that \(X \theta_2 \cdot \mathcal{R}_F \cdot Y \theta_2\). Moreover, thanks to hypothesis \([4]\) \(X \theta_2 \cdot \mathcal{R}_F \cdot Y \theta_2\) implies that \(X \theta_2 = Y \theta_2\) and so \((\sigma_2, \theta_2) = (\sigma_2, \theta_2)\).

- **Rule Eq-right-right(X,ξ), right son**: \(\text{Er}(C_1) = \text{Er}(C_1) \wedge X \neq \xi_1, \text{Er}(C_2) = \text{Er}(C_2) \wedge X \neq \xi_2\). Since \((\sigma_1, \theta_1) \in \text{Sol}(C_1)\), \((\sigma_2, \theta_2) \in \text{Sol}(C_2)\) and \(\sigma_1|_{\text{vars}(C_1)} = \sigma_2|_{\text{vars}(C_1)}\) then by Lemma \([C.44]\) we have that \(\text{Xacc}\left(C_1\right) \sigma_2 = \text{Xacc}\left(C_1\right) \sigma_1\) and \(\text{Yacc}\left(C_1\right) \sigma_1 = \text{Yacc}\left(C_2\right) \sigma_2\). Hence, \(\sigma_1\) satisfies \(\text{Xacc}\left(C_1\right) \models \text{Yacc}\left(C_1\right)\) implies \(\sigma_2 \models \text{Xacc}\left(C_2\right) \models \text{Yacc}\left(C_2\right)\). Hence \((\sigma_2, \theta_2) \in \text{Sol}(C_2)\).

Thus the result holds with \((\sigma_2, \theta_2) = (\sigma_2, \theta_2)\).}

**Lemma C.50.** Let \(M\) be a matrix of constraint system obtained by at step \(c\) of phase 1 of the strategy with any support. Let \(C\) be a constraint system in \(M\). We have that \(\text{Sol}(C) = \text{Sol}(\bar{C})\)

**Proof.** We prove this result by induction of the support \(s\) of the step \(c\). For the purpose of the induction, we assume that step \(c\) of phase 1 with support \(0\) corresponds to the root.

**Base case \(s = 0\):** In such a case, we know that \(M\) is a row matrix of initial constraint system. Hence, we trivially have that \(\text{Sol}(C) = \text{Sol}(\bar{C})\) and so the result holds.

**Inductive step \(s > 0\):** Let \((\sigma, \theta) \in \text{Sol}(\bar{C})\). Thanks to Lemma \([C.47]\) we know that there exists \(\theta'\) such that \((\sigma, \theta') \in \text{Sol}(\bar{C})\) and

1. for all \(X \in D(C)\), for all position \(p\) of \(C[X \theta']|F(C)\), if \(\text{root}(C[X \theta']|F(C)) \in F_d\), then there is no recipe \(\xi \in \Pi_s\) such that \(\xi(\Phi(C)|\sigma) = X \theta' |_{\text{vars}(C)}\) and \(\text{param}_{max}(\xi) < \text{param}_{max}(X \theta'|p)\); and
2. for all $\xi, \xi' \in st(X\theta') \mid X \in D(C')$, path($\xi$) = path($\xi'$) implies $\xi = \xi'$.

Since $s > 0$, we also know that there exists a matrix $M_1$ ancestor of $M$ such that $M_1$ is obtained at the end of step $a$ of the first phase with support $s$. Hence, there exists a constraint system $C_1$ ancestor of $C$ such that $C_1$ is in $M_1$.

By a simple induction on the number of rule applied between $M_1$ and $M$, we prove, thanks to Lemma 8.5, that there exists $(\sigma, \theta_1) \in \text{Sol}(C_1)$ such that $\sigma_{\text{vars}(C_1)} = \sigma_1$ and $\theta_{\text{vars}(C_1)} = \theta_1$.

Let $X \in D(C_1)$ and $p$ a position of $C[X\theta]_{\Phi(C_1)}$ such that $\text{root}(C[X\theta]_{\Phi(C_1)}) = \phi_d$. We show that there exists $Y \in D(C)$ and $p'$ a position of $C[Y\theta]_{\Phi(C)}$ such that $\text{root}(C[Y\theta]_{\Phi(C)}) = \phi_d$.

The rule $\text{Dest}$ was never applied to obtained $M$ from $M_1$, thus $\theta_{\text{vars}(C_2)} = \theta_1$ implies that $\text{root}(C[X\theta]_{\Phi(C_1)}) = \phi_d$. We deduce that $C[X\theta]_{\Phi(C_1)} = C[Y\theta]_{\Phi(C)}$ implies $C[Y\theta]_{\Phi(C)} = \phi_d$ and $\text{root}(C[Y\theta]_{\Phi(C)}) = \phi_d$.

Thus there exists a renaming of $\sigma', \theta'$ such that $\phi_d = \phi_d$.

Moreover, let $M_2$ be the matrix ancestor of $M_1$ obtained from step $e$ with support $s - 1$. Thanks to our inductive hypothesis, we know that for all constraint system $C_0$ in $M_2$, we have $\text{Sol}(C_0) = \text{Sol}(C_0)$.

Hence, we can apply Lemma 8.5 to $C_0$ and $(\sigma, \theta_1)$ which implies that there exists a constraint system $C_2$ in the same column of $C_1$ and there exists $(\sigma_2, \theta_2) \in \text{Sol}(C_2)$ such that $\sigma_{\text{vars}(C_1)} = \sigma_{\text{vars}(C_2)}$ and for all $X \in S_2(C_1), X\theta_1 = X\theta_2$. $X\theta_1 = X\theta_2$ trivially implies that $X\theta_1 \supseteq X\theta_2$. Moreover, since $X\theta_1 = X\theta_2$ and for all $\xi, \xi' \in st(X\theta_1) \mid X \in D(C_1)$, $\text{path}(\xi) = \text{path}(\xi')$ implies $\xi = \xi'$, we deduce that for all $X, Y \in S_2(C_2)$, for all $p \in \text{Pos}(C[X\theta_1]_{\Phi(C_2)})$, for all $p \in \text{Pos}(C[Y\theta_1]_{\Phi(C_2)})$, if $\text{path}(X\theta_1[p]) = \text{path}(X\theta_2[p])$ then $X\theta_1[p] = X\theta_2[p]$.

Once again with a simple induction on the number of rule applied between $M_1$ and $M$, we use Lemma 8.5 to prove that there exists a constraint system $C'$ in the column of $C$ and $(\sigma', \theta') \in \text{Sol}(C')$ such that $\sigma''_{\text{vars}(C')} = \sigma_{\text{vars}(C)}$ and for all $X \in S_2(C), X\theta = X\theta$.

But thanks to Lemma 8.5, we know that the matrix $M$ satisfies the invariant $\text{invMatrix}(i,s)$.

Thus there exists a renaming $\rho$ of first order variable such that:

- $\{x\rho \mid (X, i \vdash x) \in D(C) \land i \leq s\} = \{x \mid (X, i \vdash x) \in D(C') \land i \leq s\}$
- $\{u\rho \mid (\xi, i \models u) \in \Phi(C) \land i \leq s\} = \{u \mid (\xi, i \models u) \in \Phi(C') \land i \leq s\}$
- $(\text{ND}(C))\rho = \text{ND}(C')$

Moreover, $(\sigma, \theta) \in \text{Sol}(C), (\sigma', \theta') \in \text{Sol}(C')$ and $\sigma_{\text{vars}(C')} = \sigma''_{\text{vars}(C)}$. Hence by Lemma 8.5, we can deduce that for all $(X, i \vdash x) \in D(C')$, with $i \leq s$, we have that $(X, i \vdash x) \in D(C')$ and $x\sigma'' = x\sigma\rho$. Thus with $\text{ND}(C)\rho = \text{ND}(C')$ and $(\sigma', \theta') \in \text{Sol}(C')$, we have that $\sigma'' \equiv \text{ND}(C')$ which implies $\sigma \equiv \text{ND}(C)\rho$. Since for all $x \in \text{vars}(\text{ND}(C))$, $\text{ind}_{C}(x) \leq s$, we conclude that $\rho\sigma \equiv \text{ND}(C)\rho$ which implies that $\sigma \equiv \text{ND}(C)$ and so $(\sigma, \theta) \in \text{Sol}(C)$.

**Lemma 8.9.** Let $(M, M')$ be a pair of matrix obtained at the end strategy. For all constraint system $C$ in $M$ or $M'$, $\text{Sol}(C) = \text{Sol}(C)$.

**Proof.** Let $(\sigma, \theta) \in \text{Sol}(C)$. Let $C'$ be the constraint system ancestor of $C$ that $C'$ is on the matrix obtained from the last step $e$ of phase 1. With a simple induction on the number of rule applied from $C'$ to $C$, we use Lemma 8.5 to show that there exists $(\sigma', \theta') \in \text{Sol}(C')$ with $\sigma_{\text{vars}(C')} = \sigma'$. But by Lemma 8.5, we know that $(\sigma', \theta') \in \text{Sol}(C')$. Furthermore, the rules applied on phase 2 of the strategy do not add new non-deducible constraint system hence we can deduce that $\sigma' \equiv \text{ND}(C')$ and $\sigma_{\text{vars}(C')} = \sigma'$ implies that $\sigma \equiv \text{ND}(C)$ and so $(\sigma, \theta) \in \text{Sol}(C)$. 

C.6. LINK BETWEEN EQUIVALENCE SYMBOLIC AND THE FINAL TEST

C.6.3 Proof of symbolic equivalence on a leaf

Lemma C.51. Let $C$ a well formed constraint system in a pair of matrices of constraint systems obtained by application of the strategy on initial pair of matrices of constraint systems. Let $\sigma, \sigma'$ two substitution such that $\sigma \vdash Eq$ and $\sigma' \vdash Eq$. If $\sigma[S_i] = \sigma'[S_i]$, then $\sigma = \sigma'$.

Proof. The proof of this Lemma is direct from the definition of the rules. Indeed, $S_i$ correspond to the first order variable in the initial pair of matrices of constraint systems. Furthermore, even if a rule may create fresh first order variable, they are always related to existing variables by an equation on first order terms.

Lemma 8.8. Let $(M, M')$ be a pair of matrix obtained at the end strategy. $(M, M')$ is in solved form.

Proof. Since $(M, M')$ is obtained at the end of the strategy then there exists $(M_0', M_0')$, $(M_1', M_1')$ and $(M_2, M_2')$ such that

$$(M_0, M_0') \rightarrow^\ast (M_1', M_1') \rightarrow^\ast (M_2, M_2') \rightarrow^\ast (M, M')$$

and $(M_0, M_0')$ is the pair of row matrices of initial constraint system, $(M_1', M_1')$ is obtained at the end of Phase 1 of the strategy and $(M_2, M_2')$ is obtained at the end of Step a of Phase 2 of the strategy.

Thanks to Lemma C.31, we know that $(M_1', M_1')$ satisfies PP1E. Hence for all constraint system in $M_1$ or $M_1'$, $C$ satisfies InvDedsub, InvVarFrame($\infty$), InvDest($\infty$), InvNoUse($\infty$), InvUntouched($\infty$) and InvVarConstraint($\infty$). The rule applied on Phase 2 are only CONS, EQ-RIGHT-RIGHT and AXIOM. Hence thanks to Lemma C.16 we deduce that any constraint system in $(M, M')$ satisfies InvNoUse($\infty$), InvDest($\infty$), InvVarFrame($\infty$) and InvDedsub. Moreover by Lemma C.15 we deduce that any constraint system in $(M, M')$ satisfies InvUntouched($\infty$). At last, by Lemma C.14 we deduce that any constraint system in $(M, M')$ also satisfies InvVarConstraint($\infty$).

Since $(M_1, M_1')$ satisfies PP1E, we deduce that $(M, M')$ satisfies InvMatrix($\infty$) and InvGeneral. Hence thanks to Lemma C.17 and C.19 we deduce that $(M, M')$ also satisfies InvMatrix($\infty$) and InvGeneral.

Let $C \neq \bot$ in $M$ or $M'$. $(M, M')$ being obtained at the end of the strategy implies that the rule CONS and AXIOM are not applicable on any constraint system in $M, M'$. Hence we deduce that either property 2 holds or there exists $X \in D(C)$ such that AXIOM$(X, \text{path})$ and CONS$(X, f)$ are useless for all path, $f$. But we know that $C$ satisfies InvDest($\infty$). Hence $\text{Dest}(\xi, \ell \rightarrow r, s)$ is useless for any $\xi, \ell \rightarrow r, s$. This case is impossible since $C$ is normalised and we assumed that $C \neq \bot$. Hence $C \neq \bot$ implies that property 2 holds on $C$.

We show the properties 1 and 2 of solved pair of matrices on $(M, M')$. If we assumed that $C$ and $C'$ was in the same column. We know that $(M, M')$ satisfies the invariant InvGeneral and $C, C'$ both satisfy InvVarConstraint($\infty$) and InvUntouched($\infty$). Hence by Lemma C.29 we deduce that the properties 1, 2 hold.

It remains to show property 1 of solved constraint system and property 3 of solved pair of matrices. Thanks to Lemma C.32 we know that $(M_2, M_2')$ does not contain universal variables. But the rule CONS, AXIOM and EQ-RIGHT-RIGHT do not add new universal variable. Hence $(M, M')$ does not contain universal variables. $(M, M')$ being at the end of the strategy implies that the rule AXIOM, CONS and EQ-RIGHT-RIGHT are no longer applicable. Consider $C$ a constraint system in $(M, M')$ and $T$ its association table. We show that all disjunction of inequation are in the association table $T$.

Let $\bigvee_i u_i \neq v_i$ such that $E_1(C) = E \land \bigvee_i u_i \neq v_i$ for some $E$, and $T[\bigvee_i u_i \neq v_i] = \bot$. Thanks to Lemma C.33 we know that for all $i, u_i \neq v_i$ satisfies one of the following properties:

1. $u_i \in X^x$ and $v_i \in N$: In such a case, there exists $(X, k \vdash u_i) \in D$. But AXIOM$(X, \text{path})$ is useless for any path. Since $C$ satisfies InvDest($\infty$), $\text{Dest}(\xi, \ell \rightarrow r, s)$ is useless for any
2. $u_i, v_i \in X^1$, $Er(C) \not\vdash \text{root}(X) \neq f$ and $Er(C) \models \text{root}(Y) \neq g$, for all $f, g \in F_c$, where $(X, p \models u_1), (Y, q \models v_1) \in D(C)$: In such a case, for all $g \in F_c$, $Er(C) \models \text{root}(Y) \neq g$ implies that $\text{CONS}(Y, g)$ is useless. But $\text{AXIOM}(Y, \text{path})$ is not applicable and $Er(C) \models \text{root}(Y) \neq g$ implies that $\text{AXIOM}(Y, \text{path})$ is useless for all path. Since $C$ satisfies $\text{invDest}(\infty)$, $\text{Dest}(\xi, \ell \rightarrow r, s)$ is useless for any $\xi, \ell \rightarrow r, s$. But in such a case, the normalisation rule (Nnosol) is applicable which is a contradiction with the fact that $C$ is normalised. Hence this case is impossible.

3. $u_i \in X^1$, $\text{root}(v_i) \in F_c$ and for all $f \in F_c$, $Er(C) \models \text{root}(X) \neq f$, where $(X, p \models u_i) \in D(C)$:

Since for all $f \in F_c$, $Er(C) \models \text{root}(X) \neq f$, then similarly to the previous case, we prove that this case is impossible.

Since all cases are impossible, we can deduce that $T[\bigvee_i u_i \neq v_i] \models \bot$. Hence let $\bigvee_i \xi_i \neq \xi_j$ such that $T[\bigvee_i u_i \neq v_i] = \bigvee_i \xi_i \neq \xi_j$. Once again thanks to Lemma C.33, we know that either for all $i$, $st(\xi_i, \xi_j) \cap (F^*_d \cdot AX) = \emptyset$ or else for all $i$, $\xi_i \neq \xi'_i$ satisfies one of the following properties:

1. $\xi_i \in (F^*_d \cdot AX)$

2. $\xi_i, \xi'_i \in X^2$, for all $f \in F_c$, $Er(C) \models \text{root}(\xi_i) \neq f$ and $Er(C) \not\vdash \text{root}(\xi'_i) \neq f$

3. $\xi_i \in X^2$, $\text{root}(\xi'_i) \in F_c$ and for all $f \in F_c$, $Er(C) \models \text{root}(\xi_i) \neq f$

We already prove that if for all $f \in F_c$, $Er(C) \models \text{root}(X) \neq f$ for some $X \in \text{vars}^2(D)$ then thanks to $\text{AXIOM}(X, \text{path})$ not being applicable and $C$ satisfying $\text{invDest}(\infty)$, the normalisation rule (Nnosol) is applicable which is a contradiction with the fact that $C$ is normalised. Hence, we deduce that either (a) for all $i$, $st(\xi_i, \xi'_i) \cap (F^*_d \cdot AX) = \emptyset$ or else (b) for all $i$, $st(\xi_i, \xi'_i) \cap (F^*_d \cdot AX) \neq \emptyset$. In case (b), we describe in Subsection 7.4 the entry $\bigvee_i u_i \neq v_i$ should be removed, i.e. $T[\bigvee_i u_i \neq v_i] = \bot$ which is a contradiction with or hypothesis. Hence, we deduce that only case (a) is possible.

To sum up, we proved that for all $\bigvee_i u_i \neq v_i$, for all $E$, $Er(C) = E \land \bigvee_i u_i \neq v_i$ implies that there exists $\bigvee_j \xi_j \neq \xi_j$ such that $T[\bigvee_i u_i \neq v_i] = \bigvee_j \xi_j \neq \xi_j$ and for all $j$, $st(\xi_j, \xi'_j) \cap (F^*_d \cdot AX) = \emptyset$. But thanks to Lemma 8.17, we deduce that $\left( \bigvee_j \beta \cdot \text{acc}^1(C) \neq \beta' \cdot \text{acc}^1(C) \right) \downarrow = \bigvee_i u_i \neq v_i$. Since for all $j$, $st(\xi_j, \xi'_j) \cap (F^*_d \cdot AX) = \emptyset$, we deduce that for all $i$, $st(u_i, v_i) \cap N = \emptyset$. Hence property 1 of solved constraint system is satisfied.

Furthermore, Lemma 8.17 also indicates that there exists $\bigvee_i u'_i \neq v'_i$ such that $T[\bigvee_i u'_i \neq v'_i] = \bigvee_j \xi_j \neq \xi_j$ and so $\left( \bigvee_j \beta \cdot \text{acc}^1(C') \neq \beta' \cdot \text{acc}^1(C') \right) \downarrow = \bigvee_i u'_i \neq v'_i$.

Since $C$ and $C'$ both satisfy $\text{invVarConstraint}(\infty)$, we deduce that for all $(X, i \vdash u) \in D(C)$, $X \in S_2(C)$ and $u \in X^1$. Moreover, the variables as right hand term of deducible constraints are all distinct. Since $C$ and $C'$ have the same shape, then $(X, i \vdash x) \in D(C)$ implies that there exists $x' \in X^1$ such that $(X, i \vdash x') \in D(C')$. Hence we can define $\rho$ such that for all $x \rho = x'$. Therefore, we have $\text{acc}^1(C) \rho = \text{acc}^1(C')$ and for all $j$, $st(\xi_j, \xi'_j) \cap (F^*_d \cdot AX) = \emptyset$. Hence, we deduce that $\bigvee_i u_i \rho \neq v_i \rho = \bigvee_i u'_i \rho \neq v'_i \rho$. Thus, we can conclude that $Eq(C) \rho$ restricted to inequation is equal to $Eq(C') \rho$ restricted to inequation, and so the result holds. □
Lemma 8.10. Let \((M, M')\) be a pair of matrix obtained at the end strategy. Let \(C\) be a constraint system in \(M\) or \(M'\) different from \(\perp\). There exists \((\sigma, \theta) \in \text{Sol}(C)\).

Proof. Assume that \(C \neq \perp\). Thanks to Lemma [S.3] we know that \((M, M')\) is in solved form. Hence we deduce that \(C\) satisfies InvVarConstraint(\(\infty\)) and all right hand terms of deducible constraints are distinct variable. Therefore, for each deducible constraint \((X, i \vdash x) \in D(C)\), we can define \(\theta\) on \(\text{vars}^2(D)\) such that \(X\theta \in T(\mathcal{F}_c, \{ax_1\})\) for all \(X \in \text{vars}^2(D)\).

We show that for all \(u, (ax_1, 1 \triangleright u) \notin \text{NoUse}(C)\). \((M, M')\) is in solved form implies that \(C\) is well-formed. Hence, if \((ax_1, 1 \triangleright u) \notin \text{NoUse}(C)\) then by Definition [S.2] item [S] there exists \(X \in \text{vars}^2(C)\) such that \(\text{param}_{\text{max}}(X\text{mgu}(Er(C))) < 1\) which is impossible. Hence \((ax_1, 1 \triangleright u) \notin \text{NoUse}(C)\) and so for all \(\xi \in T(\mathcal{F}_c, \{ax_1\})\), for all \(\theta, \xi\) conforms to \(\Phi\theta\) w.r.t. \(\text{NoUse}\theta\).

Since the set \(T(\mathcal{F}_c, \{ax_1\})\) is infinite, we have an infinite set of pair of substitutions \((\sigma, \theta)\) where for all \((X, i \vdash x) \in D, X\theta(\Phi\sigma)\downarrow = x\sigma, \text{param}(X\theta) = \{ax_1\} \subseteq \{ax_1, \ldots, ax_1\}\) and \(X\theta\) conforms to \(\Phi\theta\) w.r.t. \(\text{NoUse}\theta\). We extend each of \((\sigma, \theta)\) by \((\sigma', \theta')\) such that \(\theta'|_{\text{vars}^2(D)} = \theta, \sigma'|_{\text{vars}^2(D)} = \sigma\), for all \(X \in \text{vars}^2(C)\setminus\text{vars}^2(D), X\theta' = X\text{mgu}(Er\theta)\); and for all \(x \in \text{vars}^1(C)\setminus\text{vars}^1(C), x\sigma' = x\text{mgu}(Eq\theta)\). Hence obtain an infinite set of pre-solution \((\sigma, \theta)\) of \(C\) such that \(\sigma \ni \text{mgu}(Er)\) and \(\theta \ni \text{mgu}(Er)\). Moreover, we also know that for all \((X, i \vdash x) \in D(C),\) for all \(f \in \mathcal{F}_c,\) \(Er \not\triangleright \text{root}(X) \neq f\). At last, we also know that \(Er \not\triangleright X \neq ax_1\). Hence, we deduce that \(\theta \ni Er\).

It remains to prove that there exists a pre-solution in this infinite set that satisfies the inequalities in \(Eq(C)\). Since each variable in the inequations are a variable of \(\text{vars}^1(D)\) and the set of possible value for each of these variable is infinite, then Thanks to [C194], we deduce that there exists at least one \((\sigma_0, \theta_0)\) of pre-solution such that \(\sigma_0 \ni Eq(C)\) and so \((\sigma_0, \theta_0) \in \text{Sol}(C)\). Therefore, thanks to Lemma [S.3] we deduce that \((\sigma_0, \theta_0) \in \text{Sol}(C)\) and so the result holds.

Definition C.2. Let \(C = (S_1, S_2, \Phi, D, Eq, Er, ND)\) be a well formed solved constraint system. Let \(\sigma\) be a substitution mapping \(\text{vars}^1(C)\) to ground messages. We define a new semantics on logic formula built upon elementary formulas using classical connectives. The semantics for the elementary formulas are given below and is extended as expected to general formulas. We have: for all \(i \in \mathbb{N}\), for all \(u, v \in T(\mathcal{F}_c, \mathcal{N} \cup X^1)\),

- \(\sigma \ni_{\leq i} u \ni v\) if \(\sigma \ni u \ni v\)
- \(\sigma \ni_{\leq i} u \ni v\) if \(\sigma \ni u \ni v\) or there exists \(x \in \text{vars}^1(u) \cup \text{vars}^1(v)\) such that \(\text{ind}_C(x) > i\)

Lemma C.52. Let \(C\) be a well formed solved constraint system on a leaf. Let \(n \in \mathbb{N}\). Let \((\sigma, \theta)\) such that:

- \(\sigma \ni_{\leq n} Eq(C)\)
- for all \((X, i \vdash u) \in D(C), X\theta(\Phi(C)\sigma)\downarrow = u\sigma\) and \(\text{param}_{\text{max}}(X\theta) \leq i\)
- for all \((X, i \vdash u) \in D(C), C[\text{th}_{\Phi(C)}] \in T(\mathcal{F}_c \cup (\mathcal{F}_d \cup AX))\) and for \((\xi, j \triangleright v) \in \Phi(C)\), if \(\text{path}(\xi) \in sL(C[\text{th}_{\Phi(C)}])\) then \(j \leq i\)
- for all \(X \in D(C), X\theta\) conforms to \(\Phi(C)\theta\) w.r.t. \(\text{NoUse}(C)\theta\)

There exists \((\sigma', \theta') \in \text{Sol}(C)\) such that \(\sigma_{x[\text{ind}_C(x) \leq n]} = \sigma'_{x[\text{ind}_C(x) \leq n]}\)

Proof. Since \(C\) is in solved form, we know that it satisfies the invariants \(\text{InvVarConstraint}(\infty)\).

Hence, we have that for all \((X, i \vdash u) \in D(C), u\) is a variable. Furthermore, all right hand variables of the deductible constraints are distinct. Thus, for all \((X, i \vdash x) \in D(C), \text{ind}_C(x) = i\).
Let $\sigma_0 = \sigma_{x[\text{ind}(x)] \leq n}$. Let $D_0 = \{(X, i \vdash x) \in D(C) \mid i > n\}$, $\Phi_0 = \text{Init}(\Phi)\sigma_0$ and $E_{\Phi_0} = Eq(C)\sigma_0$. $D_0$, $\Phi_0$ and $E_{\Phi_0}$ represent a simplified version of $C$ where we fixed the value of the variable in $\text{dom}(\sigma_0)$.

Let $(ax_1, t \triangleright u) \in \Phi_0$. Thanks to the origination property of a constraint system, we know that $\text{vars}^1(u) = \emptyset$. Furthermore, since $C$ is a well formed constraint system, we also have that $(ax_1, t \triangleright u) \not\in \text{NoUse}(C)$. Hence for all $\xi \in \mathcal{T}(F_c \cup \{ax_1\})$, for all substitution $\lambda$, we have $\xi(\Phi_0\lambda) \downarrow \in \mathcal{T}(F_c, N)$. Thus for all $(X, i \vdash x) \in D_0$, $x$ can be instantiate by any recipe $\xi \in \mathcal{T}(F_c \cup \{ax_1\})$. But the set $\mathcal{T}(F_c \cup \{ax_1\})$ is an infinite set and for all $x \in \text{vars}^1(E_{\Phi_0})$, $x \in \text{vars}^1(D_0)$. Therefore, thanks to [CDF94], we deduce that there exists a substitution $(\sigma_1, \theta_1)$ such that $\text{dom}(\theta_1) = \text{vars}^2(D_0)$, $\text{dom}(\sigma_1) = \text{vars}^1(D_0)$ and:

- for all $(X, i \vdash x) \in D_0$, $X\theta_1 \in \mathcal{T}(F_c \cup \{ax_1\})$ and $x\sigma_1 = X\theta_1(\Phi_0\sigma_1)\downarrow$
- $\sigma_1$ satisfies the inequations of $E_{\Phi_0}$.

We define $\theta'$ such that:

- for all $X \in \text{vars}^2(D(C)) \setminus \text{vars}^2(D_0)$, $X\theta' = X\theta$
- for all $X \in \text{vars}^2(D_0)$, $X\theta' = X\theta_1$
- for all $X \in \text{vars}^2(C) \setminus \text{vars}^2(D(C))$, $X\theta' = X\text{mgu}(E_{\Phi_0})\theta'$.

Furthermore, we define $\sigma'$ such that:

- $\sigma'|_{x[\text{ind}(x)] \leq n} = \sigma_0 = \sigma_{x[\text{ind}(x)] \leq n}$
- $\sigma'|_{x[\text{ind}(x)] > n} = \sigma_1$
- for all $X \in \text{vars}^1(C) \setminus \text{vars}^1(D(C))$, $x\sigma' = x\text{mgu}(Eq(C))\sigma'$.

We verify that $(\sigma', \theta') \in \text{Sol}(C)$: For all $(X, i \vdash x) \in D(C)$, if $i \leq n$ then $X\theta' = X\theta$. But $\text{param}^C_{\text{max}}(X\theta) \leq i$ and $\sigma'|_{x[\text{ind}(x)] \leq n} = \sigma_0 = \sigma_{x[\text{ind}(x)] \leq n}$. Thus we have that $X\theta'(\Phi(C)\sigma')\downarrow = X\theta(\Phi(C)\sigma)\downarrow = x\sigma = x\sigma'$.

Furthermore, since for all $(\xi, j \triangleright v) \in \Phi(C)$, for all $Y \in \text{vars}^2(\xi)$, $\text{param}^C_{\text{max}}(Y) < j$, thanks to $C$ being in solved form and so satisfying the invariant $\text{InvVarFrame}(\infty)$. But for all $(X, i \vdash x) \in D(C)$, for all $(\xi, j \triangleright v) \in \Phi(C)$, $\text{path}(\xi) \in \text{st}(C, X\theta_{\phi(C)})$ implies $j \leq i$ and so for all $Y \in \text{vars}^2(C \setminus \text{vars}^1(C)), \text{param}^C_{\text{max}}(Y) < \text{param}^C_{\text{max}}(X)$. Hence we deduce with a simple induction on $i$ that for all $(X, i \vdash x) \in D(C)$, if $i \leq n$ then $X\theta$ conforms to $\Phi(C)\theta$ w.r.t. $\text{NoUse}(C)\theta$ implies that $X\theta'$ conforms to $\Phi(C)\theta'$ w.r.t. $\text{NoUse}(C)\theta'$.

Moreover, for all $(X, i \vdash x) \in D(C)$, if $i > n$ then $X\theta' \in \mathcal{T}(F_c \cup \{ax_1\})$ and so $X\theta'$ trivially conforms to $\Phi(C)\theta'$ w.r.t. $\text{NoUse}(C)\theta'$.

We already know that $\sigma_1$ satisfies the inequations of $E_{\Phi_0}$ where $E_{\Phi_0} = Eq(C)\sigma_0$. Hence by definition of $\sigma'$, we have that $\sigma' \vdash Eq(C)$.

At last, we know that for all $X \in \text{vars}^2(C) \setminus \text{vars}^2(D(C))$, $X\theta' = X\text{mgu}(Er(C))\theta'$. Furthermore, since $C$ is in solved form, we have that for all $X \in \text{vars}^2(D(C))$, for all $f \in F_c$, for all $\xi$ recipe of $\Phi(C)$, $\text{Er(C)} \not\vdash X \not\vdash \xi$ and $\text{Er(C)} \not\vdash \text{root}(X) \not\vdash f$. Hence, we conclude that $\theta' \vdash \text{Er(C)}$.

To sum up, we have proved that $(\sigma', \theta') \in \text{Sol}(C)$. But since $C$ is a constraint system on a leaf, then by Lemma 8.3, we know that $\text{Sol}(C) = \text{Sol}(C)$. Hence we conclude that $(\sigma', \theta') \in \text{Sol}(C)$.\qed

**Lemma 8.11.** Let $(M, M')$ be a pair of matrix obtained at the end strategy. Let $C, C'$ be two constraint system in the same line in $(M, M')$ ($C$ and $C'$ may be contained in the same matrix). If $\mathcal{C} \not\perp$ and $\mathcal{C}' \not\perp$ then $\mathcal{C} \simeq \mathcal{C}'$. 


Proof. We show one side of the equivalence, the other side being done symmetrically. Let \((σ, θ) ∈ Sol(C)\). Thanks to Lemma 8.8, we know that \((M, M')\) are in solved form. We will show that there exists \(σ'\) such that:

1. \((σ', θ)\) is a pre-solution of \(C'\) with \(σ' ⊢ mgu(Eq(C'))\) and \(θ ⊨ Er(C')\);
2. \(σ' ⊢ Eq(C')\) and for all \(ξ, ξ' ∈ Π_n\), if \(C[ξ|φ(C), C[ξ'|φ(C)] ∈ T(F_c ∪ (F_d • AX))\) then
   - \(ξ(Φ(σ)) ↓ = ξ'(Φ(σ')) ↓\) is equivalent to \(ξ(Φ(C)σ') ↓ = ξ'(Φ(C)σ') ↓\)
   - \(ξ(Φ(σ)) ↓ ∈ T(F_c, N)\) is equivalent to \(ξ(Φ(C)σ') ↓ ∈ T(F_c, N)\)
3. \(Φ(C)σ \sim Φ(C)σ'\) and \((σ', θ) ∈ Sol(C')\)

**Property 1:** Since \((M, M')\) are in solved form then \(C\) and \(C'\) also have the same structure. Hence, we deduce that \(Er(C) = Er(C')\). But \((σ, θ) ∈ Sol(C)\), thus \(θ ⊨ Er(C)\) and so \(θ ⊨ Er(C')\). Moreover, since \(C'\) is normalised, then \(mgu(Eq(C'))\) exists and \(vars(Φ') \cup vars(D') = \text{img}(mgu(Eq'))\). Thus, we will first define \(σ'\) on the variables contain in \(Φ'\) and \(D'\); and then for any variable \(y \in vars(C')\) we will have \(yσ' = y \text{mgu}(Eq')σ'\).

We define \(σ'\) recursively on the index of minimal constraint of a variable \(x\):

**Base case** \(\text{ind}_C(x) = 0\) : By definition of a constraint system, for all \((X, k ⊨ u) ∈ D(C)\), \(k > 0\) which means that for all \(x ∈ vars(D')\), \(\text{ind}_C(x) > 0\). Thus, the result trivially holds.

**Inductive step** \(\text{ind}_C(x) > 0\) : Let \((X, k ⊨ u) ∈ D(C)\) such that \(k = \text{ind}_C(x)\). Since \(C\) and \(C'\) have same structure, we deduce that there exists \((X, k ⊨ y) \in D(C)\) and \(\text{param}(Xθ) ⊆ \{ax_1, ..., ax_k\}\). \(C\) being in solved form indicates that \(C\) satisfies \(\text{InvDest}(∞)\). Hence thanks to Lemma 3.37, we have that \(C[Xθ]φ(C) ∈ T(F_c ∪ (F_d • AX))\), which also means that \(C[Xθ]φ(C) ∈ T(F_c ∪ (F_d • AX))\).

\(σ, θ) ∈ Sol(C)\) implies that \(θ\) conforms to \(Φ(C)θ\) w.r.t \(\text{NoUse}(C)θ\). Once again, due to the same structure between \(C\) and \(C'\), we have \(\{ξ, i | ξ, i > u \in \text{NoUse}(C)\} = \{ξ, i | ξ, i > w \in \text{NoUse}(C')\}\). Thus, \(θ\) conforms to \(Φ(C)θ\) w.r.t \(\text{NoUse}(C')θ\) implies that \(θ\) conforms to \(Φ(C')θ\) w.r.t \(\text{NoUse}(C')θ\).

Let \(ξ ∈ st((i)Xθ)\) such that \(C[ξ|φ(C) ∈ (F_d • AX)\). By definition of a context we know that there exists \((ξ, ξ ⊨ v) ∈ Φ(C)\) such that \(path(ξ) = path(ξ)\). Furthermore, since \(θ\) conforms to \(Φ(C')θ\) w.r.t \(\text{NoUse}(C')θ\), we have that \(ξ = θ\). Since \(C\) is in solved form, \(C\) satisfies \(\text{InvFrame}(∞)\) and so for all \(Y ∈ varsξ\), \(Y, q ⊨ y \in D(C')\) such that \(q < p\). But we also know that the right hand term of the deducible constraints are distinct variables. Hence, we have that \(\text{ind}_C(y) = q < p\). Moreover \((σ, θ) ∈ Sol(C)\) implies, thanks to \((M, M')\) satisfying \(\text{InvGenera}\), that \(\text{param}(ξ) ⊆ \{ax_1, ..., ax_p\}\) and so \(p ≤ k\). Thus, we can deduce that \(\text{ind}_C(y) < k\). By applying our inductive hypothesis on \(y\), we know that \((Yθ)(Φ(C)σ') ↓ = yσ'\). By Property \(\text{Inductive of a well formed constraint system, we can now deduce \((θ)(Φ(C)σ') ↓ = ξ(Φ(C)σ') ↓ = ξ(Φ(C)σ') ↓ ∈ T(F_c, N)\). Furthermore, we proved that \(C[Xθ]φ(C) ∈ T(F_c ∪ (F_d • AX))\) which allows us to conclude that \((Xθ)(Φ(C)σ') ↓ ∈ T(F_c, N)\) and so we define \(xσ'\) such that : \(xσ' = (Xθ)(Φ(C)σ') ↓ ∈ T(F_c, N)\).

**Property 2:** We first prove that for all \(n ∈ \mathbb{N}\), \(σ' ⊢_{≤ n} Eq(C')\) implies that for all \(ξ, ξ' ∈ Π_n\), if \(C[ξ|φ(C'), C[ξ'|φ(C') ∈ T(F_c ∪ (F_d • AX))\), \(ξ\) and \(ξ'\) conforms to \(Φ(C)θ\), and for all \(x \in vars(C[ξ|φ(C'), C[ξ'|φ(C') acc(1)]\) \(vars(C[ξ|φ(C'), C[ξ'|φ(C') acc(1)]\), \(\text{ind}_C(x) ≤ n\), then

- \(ξ(Φ(σ)) ↓ ∈ T(F_c, N)\) implies \(ξ(Φ(C)σ) ↓ ∈ T(F_c, N)\)
- \(ξ(Φ(σ)) ↓ = ξ(Φ(C)σ) ↓ \) \(∈ T(F_c, N)\)\)

We prove this result by induction on \((ξ(Φ(σ)) ↓, \text{param}_{\text{max}}(ξ) + \text{param}_{\text{max}}(ξ'))\):

**Base case** \((ξ(Φ(σ)) ↓, param_{\text{max}}(ξ) + param_{\text{max}}(ξ')) = (0, 0)\) : Such a case is impossible thus the result holds.

**Inductive step** \((ξ(Φ(σ)) ↓, param_{\text{max}}(ξ) + param_{\text{max}}(ξ')) > (0, 0)\) : We prove the result by case analysis on the two recipes \(ξ\) and \(ξ'\):
Thus, since \( C \) is a well-formed constraint system, we can also conclude that

\[
\xi_k(\Phi(C)) \subseteq \xi_k(\Phi(C)') \subseteq \xi_k(\Phi(C))
\]

for all \( k \in \{1, \ldots, n\} \).

Let’s denote \( \Theta = \text{mgu}(\xi_k(\Phi(C))) \). We have \( \Theta = \Theta' \).

Since \( C \) is well-formed then by the property [5] of a well-formed constraint system, we deduce that \( (\xi \theta)(\Phi(C)) \subseteq u_1 \sigma \in \mathcal{T}(F_c, N) \) and so \( (\xi(\Phi(C)) \sigma) \subseteq \mathcal{T}(F_c, N) \). Secondly, by the property [5] we also know that there exists \( X \in \text{vars}(C) \) such that

\[
\mathcal{C}[X \theta'](\Phi(C)) \subseteq \mathcal{T}(F_c, F_c' \cup AX \cup A^2)
\]

and

\[
\mathcal{C}[X \theta'](\Phi(C)) \subset \text{acc}(C) 
\]

and \( \text{param}_{\max}(X \theta) < p \) where \( \theta' = \text{mgu}(\mathcal{E}(C')) \).

Furthermore, by hypothesis, we assumed that for all \( (z, q \rightarrow z) \in D(C') \), \( \mathcal{C}[Z \theta](\Phi(C)) \in \mathcal{T}(F_c, F_c' \cup AX) \), thus we have that \( \mathcal{C}[X \theta](\Phi(C)) \subseteq \mathcal{T}(F_c, F_c' \cup AX) \). At last, by Property [5] of a well-formed constraint system, we can also conclude that \( (X \theta)(\Phi(C)) \sigma' \subseteq u_1 \sigma' \).

Furthermore, the equation \( \mathcal{C}[X \theta](\Phi(C)) \subset \text{acc}(C) \) is due to the application of the rule \text{EQ-LEFT-RIGHT}, implies that \( \mathcal{C}[X \theta](\Phi(C)) \subset \text{acc}(C) = u_1 \). Hence, with the same reasoning, we deduce that \( (X \theta)(\Phi(C)) \sigma \subseteq u_1 \sigma \). But \( \text{param}_{\max}(X \theta) < p \) therefore we can apply our inductive hypothesis on \( X \theta, \xi' \) which means that \( \xi' \Phi(C) \sigma \subseteq (X \theta)(\Phi(C)) \sigma \subseteq u_1 \sigma \subseteq (\xi(\Phi(C)) \sigma) \).

Since \( C, C' \) are well-formed then by the property [5] of a well-formed constraint system, we deduce that \( (\Phi(C)) \subseteq u_1 \sigma, (\xi(\Phi(C)) \sigma) \subseteq u_2 \sigma, (\Phi(C)) \sigma' \subseteq u_1 \sigma' \). But \( (M, M') \) is a leaf then the rule \text{EQ-LEFT-LEFT}(\xi, \xi') is already applied on \( (M, M') \). Thus,

- either we have \( Eq(C) \equiv u_1 \equiv u_2 \) and \( Eq(C') \equiv u_1' \equiv u_2' \). By the normalisation of a constraint system, we deduce that \( u_1 = u_2 \) and \( u_1' = u_2' \). Thus, we trivially have that \( \xi(\Phi(C)) \sigma \subseteq (\xi(\Phi(C))) \).

- or \( Eq(C) \equiv u_1 \not\equiv u_2 \) and \( Eq(C') \equiv u_1' \not\equiv u_2' \). \( \xi(\Phi(C)) \sigma \subseteq (\xi(\Phi(C))) \) implies that \( \sigma' \not\equiv u_1' \not\equiv u_2' \). But we know that for all \( x \in \text{vars}(u_1') \cup \text{vars}(u_2') \), \( \text{ind}(x) \leq n \), thus we have \( \sigma' \not\equiv u_1' \not\equiv u_2' \) implies that \( \sigma' \not\equiv \leq n \ Eq(C') \), which is in contradiction with our hypothesis.
C.6. LINK BETWEEN EQUIVALENCE SYMBOLIC AND THE FINAL TEST

- \( \mathbb{C}[\xi, \Phi(C')] \in \mathcal{F}_d \cdot \mathcal{A}X \) and \( \text{root}(\xi') \in \mathcal{F}_c \) : By Lemma \( \text{[C52]} \) we know that there exists \((\sigma'', \theta') \in \text{Sol}(C')\) such that \( \sigma'_{\vert \text{ind}_c(x) \leq n} = \sigma''_{\vert \text{ind}_c(x) \leq n} \). Since \( \mathbb{C}[\xi, \Phi(C')] \in \mathcal{F}_d \cdot \mathcal{A}X \), then there exists \((\xi, p \geq u) \in \Phi(C)\) and \((\xi, p \geq u') \in \Phi(C')\) such that \( \theta' = \xi \). Furthermore, since \( C, C' \) are well-formed then by the property \( \text{[B]} \) of a well-formed constraint system, we deduce that \( \xi(\Phi(C)|\sigma) \downarrow = u\sigma \) and \( \xi(\Phi(C')|\sigma') \downarrow = u'\sigma' \). Since \((\sigma'', \theta') \in \text{Sol}(C')\), we also have that \( \theta'(\Phi(C')|\sigma') \downarrow = u'\sigma'' \).

By hypothesis, we know that for all \( x \in \vars(\mathbb{C}[\xi, \Phi(C')]\cdot \Phi(C')) \), \( \text{ind}_c(x) \leq n \). Furthermore since \( \sigma'_{\vert \text{ind}_c(x) \leq n} = \sigma''_{\vert \text{ind}_c(x) \leq n} \), we can deduce that \( u'\sigma' = u'\sigma'' \). Thus we have \( \xi(\Phi(C')|\sigma'' \downarrow = \xi(\Phi(C')|\sigma') \downarrow \).

Similarly, we have that for all \( x \in \vars(\mathbb{C}[\xi, \Phi(C')]\cdot \Phi(C')) \), \( \text{ind}_c(x) \leq n \). Since \( \mathbb{C}[\xi, \Phi(C')] \in \mathcal{T}(\mathcal{F}_c \cup \mathcal{F}_d \cdot \mathcal{A}X) \), we can deduce that \( \xi(\Phi(C')|\sigma') \downarrow = \xi(\Phi(C')|\sigma'') \downarrow \) where \( \sigma'' = \xi(\Phi(C')|\sigma') \downarrow \).

Thus, \( \xi(\Phi(C')|\sigma') \downarrow = \xi(\Phi(C')|\sigma'') \downarrow \) implies that \( \theta'(\Phi(C')|\sigma'') \downarrow = \theta'(\Phi(C')|\sigma') \downarrow \). But \( (\sigma'', \theta') \in \text{Sol}(C') \) implies \( \sigma'' \models \text{ND}(C') \). Furthermore, since \( \text{C} \) satisfies \text{InvDedubc} and since \( \text{root}(\xi') \in \mathcal{F}_c \), we can deduce that there exists \( X_1, \ldots, X_n \in \vars(\mathbb{C}') \) such that \( \mathbb{C}[\{X_1, \ldots, X_n\}|\theta'(\Phi(C')|\sigma') \downarrow = u' \), where \( \theta' = \text{mgu}(\text{Eq}(C')) \). Furthermore, since \( X_1, \ldots, X_n \) was obtained by the application of the rule \text{DED-ST} on the frame element \((\xi, p \geq u)\), we also have that \( \mathbb{C}[\{X_1, \ldots, X_n\}|\theta(\Phi(C)|\sigma) \downarrow = u, \theta = \text{mgu}(\text{Eq}(C)) \).

But thanks to \( C \) being well formed, we know that for all \( i \in \{1, \ldots, n\}, \mathbb{C}[X_i|\theta'|\Phi(C')] \in \mathcal{T}(\mathcal{F}_c \cup \mathcal{F}_d \cdot \mathcal{A}X) \). Hence we can deduce from Property \( \text{[B]} \) of a well-formed constraint system that \( f(X_1, \ldots, X_n)|\theta'(\Phi(C')|\sigma') \downarrow = u' \). Similarly, we also have that \( f(X_1, \ldots, X_n)|\theta(\Phi(C)|\sigma) \downarrow = u \).

At last, \( \text{root}(\xi') \in \mathcal{F}_c \) implies that there exists \( X_1, \ldots, X_n \) such that \( \xi' = f(\xi_1, \ldots, \xi_n) \). Hence, by applying our inductive hypothesis on \((X_i, \theta, \xi_i)\) since \( X_i|\theta(\Phi(C)|\sigma') \downarrow < \xi(\Phi(C')|\sigma') \downarrow \), for \( i = 1 \ldots n \). Hence we deduce that \( f(X_1, \ldots, X_n)|\theta(\Phi(C)|\sigma) \downarrow = \xi(\Phi(C)|\sigma) \downarrow \). Since we already proved that \( f(X_1, \ldots, X_n)|\theta'(\Phi(C)|\sigma') \downarrow = u = \xi(\Phi(C)|\sigma) \downarrow \), we conclude that \( \xi(\Phi(C)|\sigma) \downarrow = \xi(\Phi(C)|\sigma) \downarrow \).

We continue the proof of Property \( \text{[B]} \) by proving that for all \( n \in \mathbb{N}, \sigma' \models_{\leq n} \text{Eq}(C') \). We prove this result by induction on \( n \):

**Base case** \( n = 0 \): In such a case, we know that for all \( u \not\models v \) in \( \text{Eq}(C') \), for all \( x \in \vars(\mathbb{C}|\text{ind}_c(x) > 0) \). Moreover, we know that \( u, v \in \mathcal{T}(\mathcal{F}_c, \mathcal{X}^t) \) thanks to \( C' \) being in solved form. Thus we can conclude that \( \sigma' \models_{\leq 0} \text{Eq}(C') \).

**Inductive step** \( n > 0 \): Let \( u \not\models v \) in \( \text{Eq}(C') \) such that for all \( x \in \vars(\mathbb{C}|\text{ind}_c(x) \leq n, \text{ind}_c(x) \leq n \). But since \( C \) is in solved form, we know that there is no name inside \( u \) and \( v \). Thus, we can define two recipes \( \xi, \xi' \) such that \( \xi = u\lambda, \xi' = v\lambda \) where \( \lambda \) is the substitution \( \{x \rightarrow X|X, p \models x \in \text{D}(C')\} \) and \( \xi(\Phi(C')|\sigma') \downarrow = u\sigma' \), \( \xi'(\Phi(C')|\sigma') \downarrow = v\sigma' \). We know for all \((X, p \models x) \in \text{D}(C'), \mathbb{C}[X|\theta|\Phi(C')] \in \mathcal{T}(\mathcal{F}_c \cup \mathcal{F}_d \cdot \mathcal{A}X) \) that \( \mathbb{C}[X|\theta|\Phi(C')] \in \mathcal{T}(\mathcal{F}_c \cup \mathcal{F}_d \cdot \mathcal{A}X) \) and \( \xi(\Phi(C')|\sigma') \downarrow = u\sigma' \), \( \xi'(\Phi(C')|\sigma') \downarrow = v\sigma' \). We know that for all \((X, p \models x) \in \text{D}(C'), \mathbb{C}[X|\theta|\Phi(C')] \in \mathcal{T}(\mathcal{F}_c \cup \mathcal{F}_d \cdot \mathcal{A}X) \) and \( \xi(\Phi(C')|\sigma') \downarrow = u\sigma' \), \( \xi'(\Phi(C')|\sigma') \downarrow = v\sigma' \). We know that for all \((X, p \models x) \in \text{D}(C'), \mathbb{C}[X|\theta|\Phi(C')] \in \mathcal{T}(\mathcal{F}_c \cup \mathcal{F}_d \cdot \mathcal{A}X) \) and \( \xi(\Phi(C')|\sigma') \downarrow = u\sigma' \), \( \xi'(\Phi(C')|\sigma') \downarrow = v\sigma' \). We know that for all \((X, p \models x) \in \text{D}(C'), \mathbb{C}[X|\theta|\Phi(C')] \in \mathcal{T}(\mathcal{F}_c \cup \mathcal{F}_d \cdot \mathcal{A}X) \) and \( \xi(\Phi(C')|\sigma') \downarrow = u\sigma' \), \( \xi'(\Phi(C')|\sigma') \downarrow = v\sigma' \).

Assume now that \( u\sigma' \equiv v\sigma' \). By our inductive hypothesis, we know that \( \sigma' \models_{\leq n} \text{Eq}(C') \) and from the first result we showed in Property \( \text{[B]} \) in \( \mathbb{C}[\sigma', \Phi(C')] \), we can deduce that \( \xi(\Phi(C')|\sigma') \downarrow = \xi'(\Phi(C')|\sigma') \downarrow \) implies that \( \xi(\Phi(C)|\sigma) \downarrow = \xi'(\Phi(C)|\sigma) \downarrow \). But thanks to \( \{M, M'\} \) being in solved form, we know that that there exists a renaming \( \rho \) such that \( u\rho \not\models v\rho \) in \( \text{Eq}(C) \), \( \xi(\Phi(C)|\sigma) \downarrow = u\sigma \rho \) and \( \xi'(\Phi(C)|\sigma) \downarrow = v\rho\sigma \). Hence, it implies that \( \sigma \not\models v \cdot \text{Eq}(C) \) which is incoherent with \( (\sigma, \theta) \in \text{Sol}(C) \). Our assumption is contradictory and so \( u\sigma' \not\equiv v\sigma' \). Hence the result holds.
By combining the first and second result of Property 2, we prove that \( \sigma' \models E q(C') \) and for all \( \xi, \xi' \in \Pi_n \), if \( C[\xi]_{\Phi(C)}, C[\xi']_{\Phi(C)} \in T(F_c \cup (F_d \cdot AX)) \) and \( \xi, \xi' \) conforms to \( \Phi(C') \theta \) then

- \( \xi(\Phi(C')\sigma') \downarrow = \xi'(\Phi(C')\sigma_\downarrow \downarrow \) implies \( \xi(\Phi(C)\sigma_\downarrow \downarrow ) \downarrow = \xi'(\Phi(C)\sigma_\downarrow \downarrow ) \downarrow \)

- \( \xi(\Phi(C')\sigma') \downarrow \in T(F_c, N) \) implies \( \xi(\Phi(C)\sigma_\downarrow \downarrow ) \downarrow \in T(F_c, N) \)

By hypothesis, we know that \( (\sigma, \theta) \in SoI(C) \) and so \( \sigma = E q(C) \). Thus, we can use the same reasoning as for the first result to prove that: for all \( \xi, \xi' \in \Pi_n \), if \( C[\xi]_{\Phi(C)}, C[\xi']_{\Phi(C)} \in T(F_c \cup (F_d \cdot AX)) \) and \( \xi, \xi' \) conforms to \( \Phi(C) \theta \) then

- \( \xi(\Phi(C)\sigma_\downarrow \downarrow ) \downarrow = \xi'(\Phi(C)\sigma_\downarrow \downarrow ) \downarrow \), and \( \xi(\Phi(C')\sigma') \downarrow = \xi'(\Phi(C')\sigma') \downarrow \)

Thus, we conclude the proof of Property 2.

**Property 3:** We have to show that \( \Phi(C) \alpha \sim \Phi(C') \alpha' \) and \( (\alpha', \theta) \in SoI(C') \). From Property 2, we proved the static equivalence for any recipe \( \xi, \xi' \in \Pi_n \) such that in \( C[\xi]_{\Phi(C)}, C[\xi']_{\Phi(C)} \in T(F_c \cup (F_d \cdot AX)) \) and \( \xi, \xi' \) conforms to the frame \( \Phi(C) \theta \) (and so \( \Phi(C') \theta \)).

Thanks to Property 2, we deduce that \( \alpha' \equiv E q(C') \). Hence we have that \( (\alpha', \theta) \in SoI(C) \). But, thanks to Lemma [8.9] we know that \( SoI(C') = SoI(C) \). Hence, we have that \( (\alpha', \theta) \in SoI(C) \). Thus, by Lemma [C.31], we can deduce that for all \( \xi \in \Pi_n \), \( C[\xi]_{\Phi(C') \sigma_\downarrow } \downarrow \in T(F_c, N) \) and \( \xi, \xi' \) conforms to \( \Phi(C') \theta \) w.r.t. \( \text{NoUse}(C') \theta \) implies that \( C[\xi]_{\Phi(C') \sigma_\downarrow } \downarrow \in T(F_c \cup (F_d \cdot AX)) \).

Let \( \xi, \xi' \in \Pi_n \). Let \( M(\xi, \xi') \) be the multiset of recipe \( \zeta \) such that \( \zeta \in st(\xi) \cup st(\xi') \) and \( \xi \) doesn’t conform to the frame \( \Phi(C') \theta \) w.r.t. \( \text{NoUse}(C') \theta \). We prove our result by induction on the natural order on multiset.

**Base case \( M = \emptyset \):** In such a case, we can deduce that \( \xi \) and \( \xi' \) conforms to the frame \( \Phi(C') \theta \) w.r.t. \( \text{NoUse}(C') \theta \). Thus, thanks to Lemma [C.31] \( C[\xi]_{\Phi(C')} \in T(F_c \cup (F_d \cdot AX)) \) and \( C[\xi']_{\Phi(C')} \in T(F_c \cup (F_d \cdot AX)) \). Thus we deduce by applying Property 2.

**Inductive case \( M \neq \emptyset \):** Let \( \zeta \in st(\xi) \cup st(\xi') \) the smallest recipe such that \( \zeta \) doesn’t conform to the frame \( \Phi(C) \theta \). In such a case, we can deduce that \( C[\zeta]_{\Phi(C)} \in (F_d \cdot AX) \) (if not, we would have \( \zeta = f(\zeta_1, \ldots, \zeta_n) \) and there exists \( i \in \{1, \ldots, n\} \) such that \( \zeta_i \) doesn’t conforms to the frame \( \Phi(C) \) which contradict \( \zeta \) being the smallest). Since \( C[\zeta]_{\Phi(C)} \) is a subterm of \( F_d \cdot AX \), then there exists \( \beta \in (\beta, i \succ u) \in \Phi(C) \) and \( (\beta, i \succ u') \in \Phi(C') \) such that \( \text{path}(\beta) = \text{path}(\zeta) \). We do a case analysis on \( (\beta, i \succ u) \):

**Case \( (\beta, i \succ u) \notin \text{NoUse}(C) \):** In such a case, since \( \zeta \) does not conforms with \( \Phi(C) \theta \) w.r.t. \( \text{NoUse}(\theta) \), we deduce that \( \zeta \neq \beta \theta \). Hence \( \zeta = f(\zeta_1, \ldots, \zeta_n) \) for some \( f \in F_d \). Moreover, by minimality of \( \zeta \), for all \( i \in \{1, \ldots, n\} \), we know that \( \zeta_i \) conforms to \( \Phi(C) \theta \). Furthermore, \( \text{path}(\beta) = \text{path}(\zeta) \) implies that \( \beta = f(\beta_1, \ldots, \beta_n) \) and \( \text{path}(\beta_1) = \text{path}(\zeta_1) \). Thus, \( \zeta_1 \) conforms to \( \Phi(C) \theta \). Furthermore, we know that \( \Phi(C) \sigma_\downarrow \in T(F_c, N) \) and \( (\beta \theta) \Phi(C) \sigma_\downarrow \in T(F_c, N) \), then by Lemma [C.32], we deduce that \( C[\phi(\beta) \Phi(C) \sigma_\downarrow ] \in T(F_c, N) \). But all of \( \beta_1 \theta \) and \( \zeta_1 \) conform to \( \Phi(C) \theta \), which means by Property 2 that \( C[\phi(\beta) \Phi(C') \sigma_\downarrow ] \in T(F_c, N) \), for all \( k = 1, \ldots, n \). At last, from the rewriting rule we consider and from \( \zeta_1 = \beta_1 \theta \), we can deduce that \( (\beta_1 \theta) \Phi(C) \sigma_\downarrow = \phi(\beta_1) \Phi(C) \sigma_\downarrow \). But all of \( \beta_1 \theta \) and \( \zeta_1 \) conform to \( \Phi(C) \theta \), which means by Property 2 that \( (\beta_1 \theta) \Phi(C') \sigma_\downarrow ' = \phi(\beta_1) \Phi(C') \sigma_\downarrow ' \), for all \( k = 1, \ldots, n \) and so \( \Phi(C') \sigma_\downarrow ' = (\beta \theta) \Phi(C') \sigma_\downarrow ' \).

At last, since \( \zeta \) is a subterm of \( \xi \) or \( \xi' \) (w.l.o.g., subterm of \( \xi \)), there exists a position \( p \) such that \( \zeta = \xi_p \). But \( M(\xi_\theta, \xi' \theta) \) is strictly smaller than \( M(\xi, \xi') \) since \( \xi \) doesn’t conforms to \( \Phi(C) \theta \) and \( \beta \theta \) does. Thus we can apply our inductive hypothesis on \( (\xi_\theta, \xi' \theta) \) and so:

- \( \xi(\beta_\theta)_p \Phi(C) \sigma_\downarrow \in T(F_c, N) \) is equivalent to \( \xi(\beta_\theta)_p \Phi(C') \sigma_\downarrow ' \in T(F_c, N) \)
- \( \xi(\beta_\theta)_p \Phi(C) \sigma_\downarrow \in T(F_c, N) \) then \( \xi(\beta_\theta)_p \Phi(C) \sigma_\downarrow = \xi(\Phi(C) \sigma_\downarrow = \xi(\Phi(C') \sigma_\downarrow ' = \xi(\Phi(C') \sigma_\downarrow ' \). Hence we deduce that:
C.7. PROOFS OF TERMINATION

C.7.1 Proofs of termination of each step of Phase 1 of the strategy

In the following section, we will denote \( \pi_i(\cdot) \) the function that project the \( i \)-th of a tuple.
C.7.1.1 Termination of Step $a$ of Phase 1

Lemma 8.12. Let $(M_0, M'_0)$ be a pair of matrices obtained during Step $a$ of Phase 1 of the strategy. Let $R(p)$ one of the possible instances of $\text{DEST}$ and $\text{EQ-LEFT-RIGHT}$ applicable on $(M_0, M'_0)$. If we denote $(M_1, M'_1)$ the pair of matrices of constraint systems obtained by applying $R(p)$ on $(M_0, M'_0)$, then $\mu_1^p(M_1, M'_1) < \mu_1^p(M_0, M'_0)$.

Proof. Let $C$ be a constraint system in $M_0$ or $M'_0$. Let $C_1$ and $C_2$ be the two constraint systems obtained by application of an instance of $\text{DEST}$ or $\text{EQ-LEFT-RIGHT}$. We show that:

$$\mu_1(a)(C_1) < \mu_1(a)(C) \quad \text{and} \quad \mu_1(a)(C_2) < \mu_1(a)(C)$$

We do a case analysis on the rule applied:

Case $\text{EQ-LEFT-RIGHT}(X, \xi)$: The definition of $\text{EQ-LEFT-RIGHT}$ implies that there exists $(X, i \triangleright u) \in D(C)$ and $(\xi, s \triangleright v) \in \Phi(C)$ with $i < s$. Furthermore, we have that $D(C_1) = D(C)\sigma$ and $\Phi(C_1) = \Phi(C_1)\sigma$ where $\sigma = \text{mgu}(u, v)$. But thanks to the property of origination of a constraint system, we know that $\text{vars}^1(v) \subseteq \text{vars}^1(D(C))$.

Assume first that $\sigma$ is different from the identity. In such a case, since $C_1$ is normalised, we have that $\text{dom}(\sigma) \cap \text{vars}^1(D(C_1)) = \emptyset$ and so $|\text{vars}^1(D(C_1))| < |\text{vars}^1(D(C))|$. Hence we have that $\mu_1(a)(C_1) < \mu_1(a)(C)$.

Assume now that $\sigma$ is the identity. In such a case, we have that $\pi_1(\mu_1(a)(C_1)) = \pi_1(\mu_1(a)(C))$ and $\pi_2(\mu_1(a)(C_1)) = \pi_2(\mu_1(a)(C))$. Moreover, the definition of the rule $\text{EQ-LEFT-RIGHT}$ indicated that $(\xi, s \triangleright v) \notin \text{NoUse}(C_1)$ while $(\xi, s \triangleright v) \notin \text{NoUse}(C)$. Hence we have that $|\Phi(C_1)| = |\text{NoUse}(C_1)| < |\Phi(C)| = |\text{NoUse}(C)|$ and so $\mu_1(a)(C_1) < \mu_1(a)(C)$.

For the constraint system $C_2$, since no substitution is applied on $C$, then $\pi_1(\mu_1(a)(C_2)) = \pi_1(\mu_1(a)(C_2))$ and $\pi_2(\mu_1(a)(C_2)) = \pi_2(\mu_1(a)(C_2))$. Furthermore, we have that $\text{NoUse}(C) = \text{NoUse}(C_2)$ hence $\pi_2(\mu_1(a)(C_2)) = \pi_2(\mu_1(a)(C_2))$. On the other hand, we have $Eq(C_2) = Eq(C) \wedge u \neq v$. Hence we deduce that $\pi_2(\mu_1(a)(C_2)) < \pi_2(\mu_1(a)(C))$ and so $\mu_1(a)(C_2) < \mu_1(a)(C)$.

Case $\text{DEST}(\xi, \ell \rightarrow r, s)$: By definition there exists $i, u$ such that $(\xi, i \triangleright u) \in \Phi(C)$. First of all, we deduce $u \notin X'$. Indeed, thanks to Lemma [C.31] we know that $(M_0, M'_0)$ satisfies Property PP1Sa($\sigma$). Hence if $u \notin X'$, then either (a) $(\xi, i \triangleright u) \notin \text{NoUse}(C')$ if $i < s$, or else (b) there exists $(X, j \triangleright u) \in D(C)$. Case (a) is impossible since the rule $\text{DEST}(\xi, \ell \rightarrow r, s)$ would not be applicable, and case (b) is also impossible since it would imply that the rule $\text{EQ-LEFT-RIGHT}(X, \xi)$ is applicable which contradict the strategy that imposes that the rule $\text{EQ-LEFT-RIGHT}$ are prioritised over the rule $\text{DEST}$.

According to Figure 7.1, $\Phi(C)\sigma \cup \{\xi', i \triangleright u\} = \Phi(C_1)$ and $D(C)\sigma \cup \{X_2, s \triangleright u_2; \ldots; X_n, d \triangleright u_n\} = D(C_1)$ where $f(u_1, \ldots, u_n) \rightarrow w$ is a fresh renaming of the rewrite rule $\ell \rightarrow r$ and $\sigma = \text{mgu}(u_1 \equiv u)$. But according to the definition of our rewrite rules, $u \notin X'$ implies that either $\sigma|_{\text{vars}^1(u)}$ is the identity or $\sigma|_{\text{vars}^1(u)} = \{x \mapsto pk(z)\}$ where $x \in \text{vars}^1(u)$ and $z \in \text{vars}^1(u)$. Therefore, along with the fact that $\text{vars}^1(u_2, \ldots, u_n) \subseteq \text{vars}^1(u_1)$, we deduce that $|\text{vars}^1(D(C_1))| = |\text{vars}^1(D(C))|$. Furthermore, $w$ is a strict subterm of $u_1$ hence $w\sigma$ is a strict subterm of $w\sigma$. For simplicity, let’s denote $F' = \{\text{aenc, senc, }(), \text{sign}\}$. For all $(\zeta, p \triangleright v) \in \Phi(C)$, since $\sigma|_{\text{vars}^1(D)}$ is either identity or $\sigma|_{\text{vars}^1(D)} = \{x \mapsto pk(y)\}$, then have that $|\{t \in st(w)\} \rightarrow root(t) \in F'| = |\{t \in st(v)\} \rightarrow root(t) \in F'|$. Furthermore, $\sigma$ being a strict subterm of $w\sigma$ implies that $|\{t \in st(w\sigma)\} \rightarrow root(t) \in F'|$, denoted $n_1$, is strictly inferior to $|\{t \in st(w)\} \rightarrow root(t) \in F'|$, denoted $n_2$. At last, $\text{DEST}(\xi, \ell \rightarrow r, s)$ is useless on $C_1$ hence there exists a multiset $S$ such that $\pi_2(\mu_1(a)(C_1)) = S \cup \{n_2\}$ and $\pi_2(\mu_1(a)(C_1)) = S \cup \{n_1, n_1, n_1, n_1, n_1\}$ (there are five rewriting rules available). Thus, $n_1 < n_2$ implies that $\pi_2(\mu_1(a)(C_1)) < \pi_2(\mu_1(a)(C))$ and so $\mu_1(a)(C_1) < \mu_1(a)(C)$.

For the case of the constraint system $C_2$, since $\text{DEST}(\xi, \ell \rightarrow r, s)$ is useless on $C_2$ and since only non-deducible constraint are added, we trivially have that $|\text{vars}^1(D(C_2))| = |\text{vars}^1(D(C))|$ and $\pi_2(\mu_1(a)(C_2)) < \pi_2(\mu_1(a)(C))$. Hence we have $\mu_1(a)(C_2) < \mu_1(a)(C)$.
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We finish the proof by showing that \( \mu^{\mu}_{\pi}(M_1, M'_1) < \mu^{\mu}_{\pi}(M_0, M'_0) \). Each application of Dest or Eq-LFRT are internal rule. Assume that \( M_0 = [R_1, \ldots, R_n] \) and \( M'_0 = [R'_1, \ldots, R'_n] \) where \( R_i, R'_i \) are row matrices. Assume w.l.o.g. that the rule is applied on the first line. By definition of the application of an internal rule, we have \( M_1 = [W_1, W_2, R_2, \ldots, R_n] \) and \( M'_1 = [W'_1, W'_2, R'_2, \ldots, R'_n] \) where \( W_1, W_2 \) (resp. \( W'_1, W'_2 \)) are the two row matrices obtained from \( R_1 \) (resp. \( R'_1 \)).

Let \( C \) be constraint system in \( R_1 \) (resp. \( R'_1 \)). Let \( C_1 \) and \( C_2 \) be the two sons of \( C \) by application of the rule. We know that \( C_1 \in W_1 \) (resp. \( C_1 \in W'_1 \)) and \( C_2 \in W_2 \) (resp. \( C_2 \in W'_2 \)). But since we proved that \( \mu_{1,\pi}(C_1) < \mu_{1,\pi}(C) \) and \( \mu_{1,\pi}(C_2) < \mu_{1,\pi}(C) \), we deduce that \( \mu^{\mu}_{\pi}(M_1, M'_1) < \mu^{\mu}_{\pi}(M_0, M'_0) \).

\[ \square \]

C.7.1.2 Termination of Step b of Phase 1

Lemma 8.13. Let \( C \) be a well-formed constraint system satisfying the invariant InvVarFrame(s). Let \( R(\bar{p}) \) be any instance of any rules except Dest and Eq-LFRT with support inferior to s. Assume that \( R(\bar{p}) \) is strongly applicable on \( C \). Denote \( C_1 \) and \( C_2 \) the two constraint systems obtained by application of \( R(\bar{p}) \) on \( C \). The following property holds:

\[ \mu_{1,b}(C_1) < \mu_{1,b}(C) \quad \text{and} \quad \mu_{1,b}(C_2) < \mu_{1,b}(C) \]

Proof. We prove the this lemma by case analysis on the rule \( R(\bar{p}) \). We will assume that \( C_1 \) (resp. \( C_2 \)) always corresponds to the son where the guess is positive (resp. negative).

Rule Cons(X,f): We assumed that the rule is strongly applicable on \( C \), hence there exists \( i, t \) such that \( (X, i \vdash t) \in D(C) \) and \( t \not\in X^1 \) or \( t \in X^1 \) and there exists \( g \in F_c \) such that \( \text{root}(X) \not\equiv g \) is in \( E(C) \).

We first focus on \( C_1 \). We know that \( C_1 \) is normalised. Hence, the rule Cons adds in \( D(C) \) the deducible constraints \( (X_k, i \vdash x_k \sigma) \) where \( X_k, x_k \) are fresh, for \( k = 1, \ldots, n \), and \( \sigma = \text{mgu}(t, f(x_1, \ldots, x_n)) \).

But since \( X_k \) are fresh and \( E(C_1) = E(C) \land X \equiv f(x_1, \ldots, x_n) \), we deduce that \( (X_k, g) \not\in \pi_1(\mu_{1,b}(C_1)) \), for all \( g, k = 1, \ldots, n \). Furthermore, since for all \( (Y, j \vdash v) \in D(C) \) other than \( (X, i \vdash t) \), \( (Y, j \vdash v \sigma) \in D(C_1) \), then \( (Y, g) \in \pi_1(\mu_{1,b}(C_1)) \) implies \( (Y, g) \in \pi_1(\mu_{1,b}(C_1)) \). Hence we deduce that \( \pi_1(\mu_{1,b}(C_1)) \leq \pi_1(\mu_{1,b}(C_1)) \).

If \( t \in X^1 \) then we have at least \( (X, f) \in \pi_1(\mu_{1,b}(C_1)) \). But since \( X \not\in \text{vars}^2(D(C_1)) \), we deduce that \( \pi_1(\mu_{1,b}(C_1)) < \pi_1(\mu_{1,b}(C)) \). Thus, we conclude that \( \mu_{1,b}(C_1) < \mu_{1,b}(C) \).

Else \( t \not\in X^1 \). If \( \text{root}(t) \not\equiv f \), we have that \( C_1 \models \bot \) hence the result trivially holds. Else \( \text{root}(t) \equiv f \) and so it implies that \( \text{root}(t) = f \) and \( \text{dom}(\sigma) = \{x_1, \ldots, x_n\} \). Hence \( x_k \sigma \) is a strict subterm of \( t \), for \( k = 1, \ldots, n \). Hence we have that \( \text{vars}^1(D(C_1)) = \text{vars}^1(D(C)) \) and so \( \pi_2(\mu_{1,b}(C_1)) = \pi_2(\mu_{1,b}(C)) \).

\( t \not\in X^1 \) also implies that \( \Phi(C_1) = \Phi(C) \) and \( ND(C_1) = ND(C) \). Hence, since the applications conditions of Ded-ST and Eq-LFRT depend only on these two elements, we deduce that \( \pi_4(\mu_{1,b}(C_1)) = \pi_4(\mu_{1,b}(C)) \) and \( \pi_5(\mu_{1,b}(C_1)) = \pi_5(\mu_{1,b}(C)) \). At last, since \( \text{dom}(\sigma) = \{x_1, \ldots, x_n\} \) and \( x_k \sigma \) are strict subterms of \( t \), we can deduce that \( \pi_5(\mu_{1,b}(C_1)) < \pi_5(\mu_{1,b}(C)) \). Thus, we conclude that \( \mu_{1,b}(C_1) < \mu_{1,b}(C) \).

We now focus on \( C_2 \). In such a case, the only difference between \( C_2 \) and \( C \) is that \( E(C_2) = E(C) \land \text{root}(X) \not\equiv f \). Hence we trivially have that \( \pi_k(\mu_{1,b}(C_2)) = \pi_k(\mu_{1,b}(C)) \), for \( k = 2 \ldots 5 \). On the other hand, if \( t \in X^1 \) then we have \( \pi_1(\mu_{1,b}(C_2)) < \pi_1(\mu_{1,b}(C)) \) else we have that \( \pi_1(\mu_{1,b}(C_2)) = \pi_1(\mu_{1,b}(C)) \) and \( \pi_6(\mu_{1,b}(C_2)) < \pi_6(\mu_{1,b}(C)) \). Hence, in both cases, we can conclude that \( \mu_{1,b}(C_2) < \mu_{1,b}(C) \).

Rule Axiom(X,\xi): We assumed that the rule is strongly applicable on \( C \), hence there exists \( (X, i \vdash u) \in D(C), (\xi, j \triangleright v) \in \Phi(C) \) such that \( j \leq i \) and either \( u \not\in X^1 \) or \( t \in X^1 \) and there exists \( g \in F_c \) such that \( \text{root}(X) \not\equiv g \).
We first focus on $C_1$. We know that $C_1$ is normalised. Hence, we have that $D(C_1) = D(C)\sigma \setminus \{X, i \vdash u\sigma\}$ where $\sigma = \text{mgu}(u, v)$. Furthermore, we have $Er(C_1) = Er(C) \land X \models \xi$. Thus, we have that $\pi_1(\mu_{1,b}(C_1)) \leq \pi_1(\mu_{1,b}(C))$. We do a case analysis on $u$ and $v$:

Case $u \in X^1$: In such a case we have that there exist $f$ such that $(X, f) \in \pi_1(\mu_{1,b}(C))$. Since $D(C_1) = D(C)\sigma \setminus \{X, i \vdash u\sigma\}$, we can deduce that $\pi_1(\mu_{1,b}(C_1)) < \pi_1(\mu_{1,b}(C))$. Thus we conclude that $\mu_{1,b}(C_1) < \mu_{1,b}(C)$.

Case $u \notin X^1$ and $\sigma$ is the identity: $\sigma$ being the identity implies that $u = v$ and so thanks to the originisation property of constraint system, we have that $|\text{vars}^1(D(C_1))| = |\text{vars}^1(D(C))|$. Furthermore since $\Phi(C_1) = \Phi(C)$, we trivially have that $\pi_4(\mu_{1,b}(C_1)) = \pi_4(\mu_{1,b}(C))$ and $\pi_3(\mu_{1,b}(C_1)) = \pi_3(\mu_{1,b}(C))$. At last, $u \notin X^1$ implies that $u$ is either a name or $\text{root}(u) \in F_c$. Thus $D(C_1) = D(C) \setminus \{X, i \vdash u\}$ implies that $\pi_5(\mu_{1,b}(C_1)) < \pi_5(\mu_{1,b}(C))$. Thus we conclude that $\mu_{1,b}(C_1) < \mu_{1,b}(C)$.

Case $u \notin X^1$ and $\sigma$ is not the identity: By the property of originisation of a constraint system, we know that $\text{vars}^1(v) \subseteq \text{vars}^1(D(C))$. Hence we have that $|\text{vars}^1(D(C_1))| < |\text{vars}^1(D(C))|$. We proved that $D(C_1) \subseteq D(C)\sigma$, therefore we can deduce that $\pi_2(\mu_{1,b}(C_1)) < \pi_2(\mu_{1,b}(C))$. Thus we conclude that $\mu_{1,b}(C_1) < \mu_{1,b}(C)$.

We now focus on $C_2$. In such a case, the only difference between $C_2$ and $C$ is that $Er(C_2) = Er(C) \land X \models \xi$. Hence we trivially have that $\pi_k(\mu_{1,b}(C_2)) = \pi_k(\mu_{1,b}(C))$, for $k = 1 \ldots 6$. Moreover, $Er(C_2) = Er(C) \land X \models \xi$ also implies that $\pi_7(\mu_{1,b}(C_2)) < \pi_7(\mu_{1,b}(C))$. Thus we conclude that $\mu_{1,b}(C_2) < \mu_{1,b}(C)$.

**Rule Eq-left-left($\xi_1, \xi_2$):** We assumed that the rule is applicable on $C$ (for Phase 1), hence there exists $(\xi_1, i \vdash u_1) \in \Phi(C)$, $(\xi_2, u_2 \triangleright u_2) \in \Phi(C)$.

We first focus on $C_1$. We know that $C_1$ is normalised. Hence, we have that $D(C_1) = D(C)\sigma$ where $\sigma = \text{mgu}(u_1, u_2)$. Thus, we have that $\pi_1(\mu_{1,b}(C_1)) \leq \pi_1(\mu_{1,b}(C))$.

By the originisation property of a constraint system, we know that $\text{vars}^1(u_1, u_2) \subseteq \text{vars}^1(D(C))$. Hence we deduce that $\text{vars}^1(D(C_1)) \subseteq \text{vars}^1(D(C))$. But if $\sigma$ is not the identity then we have that $|\text{vars}^1(D(C_1))| < |\text{vars}^1(D(C))|$. Thus we deduce that $\mu_{1,b}(C_1) < \mu_{1,b}(C)$.

Else if $\sigma$ is the identity, then we have that $\text{vars}^1(D(C_1)) = \text{vars}^1(D(C))$ and so $\pi_2(\mu_{1,b}(C_1)) \leq \pi_2(\mu_{1,b}(C))$. Furthermore, $\sigma$ being the identity also implies that $\Phi(C_1) = \Phi(C)$. Thus we deduce that $\pi_3(\mu_{1,b}(C_1)) = \pi_3(\mu_{1,b}(C))$. At last, we are focused on the case of the application of the rule Eq-left-left, therefore we trivially have that $\pi_6(\mu_{1,b}(C_1)) < \pi_6(\mu_{1,b}(C))$. Thus we conclude that $\mu_{1,b}(C_1) < \mu_{1,b}(C)$.

**Rule Eq-right-right($X, Y$):** We assumed that the rule is strongly applicable on $C$ hence there exists $(X, i \vdash u) \in D(C)$ and $(Y, j \vdash v) \in D(C)$ such that $u = v \in X^1$. In such a case, we first have that $C_2 = \perp$ since $Er(C_2) \models u \models v$ yields $\perp$ by normalisation. Thus we deduce that $\mu_{1,b}(C_2) < \mu_{1,b}(C)$.

We know focus on $C_1$. We have that $D(C_1) = D(C) \setminus \{Xi \vdash u\}$. Hence we deduce that $\pi_5(\mu_{1,b}(C_1)) \leq \pi_5(\mu_{1,b}(C))$, for $k = 1, 6, 7$ and that $\pi_5(\mu_{1,b}(C_1)) < \pi_5(\mu_{1,b}(C))$. Furthermore, since $\Phi(C_1) = \Phi(C)$, we deduce that $\pi_6(\mu_{1,b}(C_1)) = \pi_6(\mu_{1,b}(C))$, for $k = 2, 3, 4, 5$. Thus we conclude that $\mu_{1,b}(C_1) < \mu_{1,b}(C)$.

**Rule Ded-st($\xi, f, i$):** We assumed that the rule is applicable on $C$ hence there exists $(\xi, i \vdash u) \in \Phi(C)$ such that $(\xi, i \vdash u) \notin \text{NoUse}(C)$. We know that $C$ satisfies the invariant InvVarFrame($\xi$) hence we can deduce that $u \notin X^1$.

We first focus on $C_1$: If $\text{root}(u) \neq f$ then we have that $C_1 = \perp$ since $C_1$ is normalised (otherwise, we would have $Eq(C_1) = Eq(C) \land u \models f(x_1, \ldots, x_n)$ which is reduced into $\perp$ by the normalisation rule (Nims1)). Thus we deduce that $\mu_{1,b}(C_1) < \mu_{1,b}(C)$. 


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Elie root(u) = f. In such a case, we have Er(C1) = Er(C), Φ(C1) = Φ(C) and D(C1) = D(C) ∪ \{X_k, i → x_kσ\}_{k=1...n} such that x_kσ is a strict subterm of u and X_k are fresh, for k = 1...n and σ = mgu(u = f(x_1,...,x_n)). X_k being fresh implies that there do not exist g ∈ F_c such that Er(C1) ⊨ root(X) \neq g. Hence we deduce that π_1(μ_{1, b}(C_1)) = π_1(μ_{1, b}(C)). Furthermore, thanks to the origination property of a constraint system, we know that vars^1(u) ⊆ vars^1(D(C)), thus thanks to x_kσ being strict subterm of u, we deduce that π_2(μ_{1, b}(C_1)) ≤ π_2(μ_{1, b}(C)). At last, we are focused on the case of the application of the rule Ded-st, therefore we trivially have that π_3(μ_{1, b}(C)) ≤ π_3(μ_{1, b}(C)). Thus we conclude that μ_{1, b}(C_1) < μ_{1, b}(C).

We now focus on C_2: In such a case, we have that Er(C_2) = Er(C), Φ(C_2) = Φ(C) and D(C_2) = D(C). Hence we trivially have that π_k(μ_{1, b}(C_2)) ≤ π_k(μ_{1, b}(C)), for k = 1, 2. At last, we are focused on the case of the application of the rule Ded-st, therefore we trivially have that π_3(μ_{1, b}(C_2)) < π_3(μ_{1, b}(C)) and so we conclude that μ_{1, b}(C_2) < μ_{1, b}(C).

C.7.1.3 Termination of Step c of Phase 1

Lemma C.53. Let (M, M') be a pair of matrices of constraint systems obtained during the Step c of Phase 1 of the the strategy with parameters s and k. Assume w.l.o.g. that the k^{th} column of (M, M') is the k^{th} column of M. Assume that the rule Cons(X_0, f) can be applied externally on (M, M') such that (X_0, j_0 \rightarrow u_0) \in D(M_{i_0, k}), i_0 \in \{1,...,n\} and

\[ L^1_{M_{i_0, k}}(X_0, j_0 \rightarrow u_0) = \min \left\{ L^1_{M_{i, k}}(Z, \ell \rightarrow v) \mid i \in \{1,...,n\}, (Z, \ell \rightarrow v) \in D(M_{i, k}), \right. \]
\[ \left. \text{vars}(v) \cap \text{X}(M_{i, k}) \neq \emptyset, Z \in S_2 \right\} \]

For all term u, for all i \in \{1,...,n\}, if (X_0, j_0 \rightarrow u) \in D(M_{i, k}) and u \in X^1 then u \not\in X^1(M_{i, k}).

Proof. For simplicity, we will denote C = M_{i_0, k} and C' = M_{i, k}. We know that (X_0, j_0 \rightarrow u_0) \in D(C) and (X_0, j_0 \rightarrow u) \in D(C') such that u \in X^1(C').

In such a case, we have that L^1_{C'}(X_0, j_0 \rightarrow u) = (j_0, ε). But we know that (X_0, j_0 \rightarrow u_0) \in D(C) and by the minimality of L^1_{C'}(X_0, j_0 \rightarrow u_0), we deduce that L^1_{C'}(X_0, j_0 \rightarrow u_0) ≤ (j_0, ε). Hence we deduce that u_0 \in X^1(C) also implies that there exists (Y, j \rightarrow u_0) \in D(C) such that Y \not\in S_2. Moreover, the minimality of L^1_{C'}(X_0, j_0 \rightarrow u_0) also implies that there no deducible constraint \((Y', j' \rightarrow v') \in D(C)\) such that u_0 \in vars^1(v) and j' < j_0. Hence, thanks to C being well-formed (Definition S.2 item S.24) we deduce that j_0 < j. Consider the pair of matrices of constraint system \((M_{1}, M'_{1})\) ancestor of \((M, M')\) such that \((M_{1}, M'_{1})\) is obtained at the end of Step b with parameters s and k. Thanks to Lemma C.31 we know that \((M_{1}, M'_{1})\) satisfies PP1SbE(s, k). Let C_1 be the constraint system in M_1 ancestor of C. Since no internal rule are applied other than EQ-RIGHT-RIGHT during step c, we deduce that \((Y', j' \rightarrow v') \in D(C_1)\) for some v' and so thanks to Property PP1SbE(s, k), we deduce that for all f \in F_c, Er(C_1) \not\models root(Y) \neq f. Once again thanks to the fact that no internal rule are applied other than EQ-RIGHT-RIGHT during step c, we can easily show that for all f \in F_c, Er(C) \not\models root(Y) \neq f.

Furthermore, Property PP1SbE(s, k) indicates that for all X \in vars^2(D(C_1)), for all f \in F_c, Er(C_1) \not\models root(X) \neq f. Hence, if if there exists f \in F_c such that Er(C) \not\models root(X_0) \neq f, it would implies that there exists C'' such that C_1 \rightarrow^+ C'' \rightarrow^+ C, C'' is obtained during step c, \((X_0, j_0 \rightarrow u_0) \in D(C'')\), \((Y, j \rightarrow u_0) \in D(C'')\) and for all f \in F_c, Er(C) \not\models root(X_0) \neq f. But in such a case, the rule EQ-RIGHT-RIGHT should have been applied according to the strategy and
so we would have that \((Y, j \vdash x_0) \notin D(C)\) which is a contradiction. Hence we conclude that 
\(u \notin X^1(C)\).

**Lemma 8.14.** Let \((M, M')\) be a pair of matrices of constraint systems obtained during the Step \(c\) of 
Phase 1 of the strategy with parameter \(s\) and \(k\) respectively for support and column. Let \(R(\tilde{p})\) be 
the next possible rule applicable according to step \(c\) of the strategy and let \((M_1, M'_1)\) and \((M_2, M'_2)\) 
be the two pairs of matrices of constraint systems obtained by application of \(R(\tilde{p})\) on \((M, M')\) (in 
the case of \(R(\tilde{p})\) being the rule \(\text{Eq-right-right}\), there is only one pair of constraint system since 
\(\text{Eq-right-right}\) is applied internally). We have that:

\[
\mu^k_{\mu,c}(M_1, M'_1) < \mu^k_{\mu,c}(M, M') \quad \land \quad \mu^k_{\mu,c}(M_2, M'_2) < \mu^k_{\mu,c}(M, M')
\]

**Proof.** We prove the result by case analysis on the rule \(R(\tilde{p})\):

**Rule Eq-right-right** \((X, Y)\): Since this rule is applied internally, there exists \(C\) in the \(k\)th 
column of \((M, M')\) such that \(\text{Eq-right-right}(X, Y)\) is strongly applicable on \(C\). Furthermore, we deduce 
that \(X \notin S_2(C)\) and \(Y \notin S_2(C)\). Assume that \((X, i \vdash x) \in D(C)\) and \((Y, j \vdash x) \in D(C)\). According 
to the strong application condition of Eq-right-right \((X, Y)\) in case of internal rule for phase 1, we have that 
\(j < i\).

By normalisation, we have that \(C_2 = \bot\) and so we trivially have that \(\mu_{\mu,c}(C_2) < \mu_{\mu,c}(C)\).

We focus on \(C_1\): Since \(Y \notin S_2(C)\) and \(x \notin X^1\), we can deduce that \(L^1_{\mu}(Y, j \vdash x) = (j, 0)\). But 
\(D(C_1) = D(C) \setminus \{X, i \vdash x\}\).

If there is no \((Z, \ell \vdash x) \in D(C)\) such that \(Z \neq X\) and \(Z \notin S_2(C)\), we have that \(x \notin X^1(C_1)\). 
Hence, we can deduce that \(L^1_{\mu}(Y, j \vdash x)\) is not defined and so \(\pi_1(\mu_{\mu,c}(C_1)) < \pi_1(\mu_{\mu,c}(C))\). Thus 
we deduce that \(\mu_{\mu,c}(C_1) < \mu_{\mu,c}(C)\)

Else there exists \((Z, \ell \vdash x) \in D(C)\) such that \(Z \neq X\) and \(Z \notin S_2(C)\). Thus \(X^1(C_1) = X^1(C)\).

Thus, with \(D(C_1) = D(C) \setminus \{X, i \vdash x\}\), we deduce that \(\pi_1(\mu_{\mu,c}(C_1)) = \pi_1(\mu_{\mu,c}(C))\). Furthermore, 
we \((X, Z) \in \pi_2(\mu_{\mu,c}(C))\) while \((X, Z) \notin \pi_2(\mu_{\mu,c}(C_1))\). Hence we easily deduce that \(\pi_2(\mu_{\mu,c}(C_1)) < \pi_2(\mu_{\mu,c}(C))\) and 
so that \(\mu_{\mu,c}(C_1) < \mu_{\mu,c}(C)\).

Since we proved that \(\mu_{\mu,c}(C_1) < \mu_{\mu,c}(C)\) and \(\mu_{\mu,c}(C_2) < \mu_{\mu,c}(C)\) and since the rule is applied 
internally, we deduce that \(\mu^k_{\mu,c}(M_1, M'_1) < \mu^k_{\mu,c}(M, M')\).

**Rule Cons** \((X, f)\): The rule is applied externally. Hence we will show that for all constraint system 
\(C\) in the \(k\)th column, we have that \(\mu_{\mu,c}(C_1) \leq \mu_{\mu,c}(C)\) and \(\mu_{\mu,c}(C_2) \leq \mu_{\mu,c}(C)\) where \(C_1\) and \(C_2\) 
are the constraint system obtained by applying the rule on \(C\). Furthermore, by the definition of 
the strategy, we know that there exists \(C_0\) such that \(L^1_{c_0}(X, i_0 \vdash u_0)\) is minimal. Thus we will show that 
in the case of \(C_0\), \(\mu_{\mu,c}(C_1) < \mu_{\mu,c}(C_0)\) and \(\mu_{\mu,c}(C_2) < \mu_{\mu,c}(C_0)\), where \(C_1\) and \(C_2\) are 
the constraint system obtained by applying the rule on \(C_0\). 

We first focus on \(C_1\): Thanks to Lemma \(\ref{Lemma5.53}\) we know that for all \(C\) in the \(k\)th column, for all 
\(i \in \mathbb{N}\), for all term \(u\), \((X, i_0 \vdash u) \in D(C)\) and \(u \notin X^1\) implies \(u \notin X^1(C)\).

**Case** \(u \in X^1\): By normalisation, \(D(C_1) = (D(C) \{X, i_0 \vdash u\}) \sigma \cup \{X_j, i_0 \vdash x_j\}_{j=1...n}\) where 
\(\sigma = \{u \rightarrow (x_1, \ldots, x_n)\}\) and \(x_j\) are fresh variables and \(u \notin X^1(C)\). Hence we deduce that for all 
\((Y, j \vdash v) \in D(C_1)\) for all \(p\), if \(v\_p \in X^1(C)\) then \(v\_p \in X^1(C)\) and \((Y, j \vdash v) \in D(C)\). Thus 
we deduce that \(v\_p \in X^1(C)\) and so \(\pi_1(\mu_{\mu,c}(C_1)) = \pi_1(\mu_{\mu,c}(C))\). Since \(x_j \in S_2(C_1)\), for \(j = 1 \ldots n\), 
we deduce that \(\pi_2(\mu_{\mu,c}(C_1)) = \pi_2(\mu_{\mu,c}(C))\). At last, \(x_j \notin X^1(C)\), for \(j = 1 \ldots n\) also implies that 
\(\pi_i(\mu_{\mu,c}(C_1)) = \pi_i(\mu_{\mu,c}(C))\), for \(i = 3, 4\) and so we deduce that \(\mu_{\mu,c}(C_1) = \mu_{\mu,c}(C)\).

**Case** \(u \notin X^1\) and \(\text{vars}^+(u) \cap X^1(C) = \emptyset\): In such a case, we have that \(D(C_1) = (D(C) \setminus 
\{X, i_0 \vdash u\}) \cup \{X_j, i_0 \vdash x_j\}_{j=1...n}\) where \(x_j\sigma\) is a strict subterm of \(u\), for \(j = 1 \ldots n\) and
\[ \sigma = \operatorname{mgu}(u \vdash f(x_1, \ldots, x_n)). \] Thus, \( \operatorname{vars}^1(u) \cap X^1(C) = \emptyset \) implies that \( \operatorname{vars}^1(x_j \sigma) \cap X^1(C) = \emptyset \) for \( j = 1 \ldots n \). Therefore, we have that \( \mathcal{L}^1_{C_1}(X_j, i_0 \vdash x_j \sigma) \) does not exist, for \( j = 1 \ldots n \) which implies that \( \pi_j(\mu_{1,c}(C_1)) = \pi_j(\mu_{1,c}(C)) \) for \( j = 1, 3, 4 \). At last, since \( \mathcal{L}^1_{C_1}(X_j, i_0 \vdash x_j \sigma) \) does not exist, for \( j = 1 \ldots n \), we deduce that \( \pi_2(\mu_{1,c}(C_1)) = \pi_2(\mu_{1,c}(C)) \) and so we conclude that \( \mu_{1,c}(C_1) = \mu_{1,c}(C) \).

**Case** \( u \notin X^1 \) and \( \operatorname{vars}^1(u) \cap X^1(C) \neq \emptyset \): In such a case, we still have that \( D(C_1) = (D(C) \setminus \{ X, i_0 \vdash u \}) \cup \{ X_j, i_0 \vdash x_j \sigma \}_{j=1\ldots n} \) where \( \sigma = \operatorname{mgu}(u, f(x_1, \ldots, x_n)) \). Since \( u \notin X^1 \), we can deduce that for all \( j \in \{ 1, \ldots, n \} \), for all \( p \), if \( x_j \sigma \vdash \in X^1(C_1) \) then \( u|_p = x_j \sigma \vdash \in X^1(C) \). With the fact that \( \text{ind}_C(x) = \text{ind}_C(x) \) for all \( x \in \operatorname{vars}^1(D(C)) \), we can deduce that \( \text{ind}_C(\{x_j \sigma \vdash \}, p) < \text{ind}_C(\{x_j \sigma \vdash \}, j \vdash \) for all \( j \in \{1, \ldots, n\} \). Thus we can deduce that \( \pi_1(\mu_{1,c}(C_1)) < \pi_1(\mu_{1,c}(C)) \) and so \( \mu_{1,c}(C_1) < \mu_{1,c}(C) \).

Note that by the application condition on the rule \( \operatorname{Cons}(X,f) \) for step \( c \), we can deduce that \( u_0 \notin X^1 \) and \( \operatorname{vars}^1(u_0) \cap X^1(C_0) \neq \emptyset \). Thus we have \( \mu_{1,c}(C_1) < \mu_{1,c}(C_0) \).

We now focus on \( C_2 \): In such a case we have that \( D(C_2) = D(C) \). Hence we trivially have that \( \pi_i(\mu_{1,c}(C_2)) = \pi_i(\mu_{1,c}(C)) \), for \( i = 1, 2 \). On the other hand, since \( \operatorname{Er}(C_2) = \operatorname{Er}(C) \cup \text{root}(X) \) \( \emptyset \), we have that \( \pi_3(\mu_{1,c}(C_2)) \leq \pi_3(\mu_{1,c}(C)) \) which allows us to conclude that \( \mu_{1,c}(C_2) \leq \mu_{1,c}(C) \).

Note that by the application condition on the rule \( \operatorname{Cons}(X,f) \) for step \( c \), we can deduce that \( u_0 \notin X^1 \) and \( \operatorname{vars}^1(u_0) \cap X^1(C_0) \neq \emptyset \). Thus we have \( \pi_3(\mu_{1,c}(C_2)) < \pi_3(\mu_{1,c}(C_0)) \) which allows us to conclude that \( \mu_{1,c}(C_2) < \mu_{1,c}(C_0) \).

**Rule Axiom** \( \{X, \pi \vdash \} \): The rule is applied externally. Hence, similarly to the case of the rule \( \operatorname{Cons} \), we will show that for all constraint system \( C \) in the \( k \)th column, we have that \( \mu_{1,c}(C_1) \leq \mu_{1,c}(C) \) and \( \mu_{1,c}(C_1) \leq \mu_{1,c}(C) \) where \( C_1 \) and \( C_2 \) are the constraint system obtained by applying the rule on \( C \). Furthermore, we will show that in the case of \( C_0 \), \( \mu_{1,c}(C_1) < \mu_{1,c}(C_0) \) and \( \mu_{1,c}(C_2) < \mu_{1,c}(C_0) \), where \( C_1 \) and \( C_2 \) are the constraint system obtained by applying the rule on \( C_0 \).

By definition of the rule, we know that there exists \( (?X, i \vdash u) \in D(C) \) and \( (?X, i \vdash \in \Phi(C) \) such that \( j \leq i \).

We first focus on \( C_1 \): By definition of the rule, we have that \( D(C_1) = D(C) \vdash \{X, i \vdash u \} \) where \( \sigma = \operatorname{mgu}(u, \pi) \). Furthermore, we have that \( \Phi(C_1) = \Phi(C) \).

Let \( x \in \operatorname{vars}^1(v \pi) \). By the property of origination of a constraint system, we deduce that \( \text{ind}_C(x) < i \). Let \( (Y, \ell \vdash t \in D(C) \text{ such that } x \in \operatorname{vars}^1(t) \text{ and } \text{ind}_C(x) = \ell \). By the minimality of \( \mathcal{L}^1_{C_1}(X, i \vdash \sigma) \), we deduce that \( x \notin X^1(C) \).

Let \( x \in X^1(C) \cap \operatorname{vars}^1(u) \). If \( x \in \text{img}(\sigma) \) then we have that \( x \in \operatorname{vars}^1(v \pi) \). But by the property of origination of a constraint system, we deduce that there exists \( Y, \ell \vdash t \in D(C) \) such that \( \ell < j \leq i \) and \( x \in \operatorname{vars}^1(t) \). Moreover, \( x \in X^1(C) \) implies that for all \( (Z, m \vdash w) \in D(C) \), \( x \in \operatorname{vars}^1(w) \) implies that \( \mathcal{L}^1_{C_1}(X, i \vdash \sigma) \). But by minimality of \( \mathcal{L}^1_{C_1}(X, i \vdash \sigma) \), we deduce that \( i \leq m \). Hence, we deduce that \( \text{ind}_C(x) = i \). Since we already show that \( \text{ind}_C(x) = i \), we deduce that \( \text{ind}_C(x) < \in \).

Let \( (Y, \ell \vdash t \sigma \in \Phi(C), \text{ let } p \text{ a position such that } t \sigma \vdash \in X^1(C) \). We distinguish two cases:

- **Case 1**, \( t \sigma \vdash \not \in X^1(C) \): In such a case, it implies that \( t \sigma \vdash \in X^1(C) \). Furthermore, we deduce that \( \text{ind}_C(t \sigma) = \text{ind}_C(t \sigma) \). Hence we have that \( \{ (\text{ind}_C(t \sigma), p \pi) \mid (Z, \ell \vdash t \sigma \vdash \} \in \{ (\text{ind}_C(t \sigma), p \pi) \mid (Z, \ell \vdash t \sigma \vdash \} \in D(C) \land t \sigma \vdash = t \sigma \} \} \).

- **Case 2**, \( \sigma \vdash \in \Phi(C) \): We have shown that in such a case, \( \text{ind}_C(t \sigma) < \text{ind}_C(t \sigma) \). Since \( t \sigma \vdash \in \operatorname{vars}^1(u) \), we deduce that \( \{ (\text{ind}_C(t \sigma), p \pi) \mid (Z, \ell \vdash t \sigma \vdash = t \sigma \} \in D(C) \land t \sigma \vdash = t \sigma \} \} < \{ (\text{ind}_C(t \sigma), p \pi) \mid (Z, \ell \vdash t \sigma \vdash = t \sigma \} \in D(C) \land t \sigma \vdash = t \sigma \} \} \).
Hence we deduce that \( \pi_1(\mu_{1,c}(C_1)) \leq \pi_1(\mu_{1,c}(C)) \) and if \( \text{vars}^1(u) \cap X^1(C) \neq \emptyset \) then \( \pi_1(\mu_{1,c}(C_1)) < \pi_1(\mu_{1,c}(C)) \).

At last, since \( D(C_1) = D(C) \sigma \setminus \{X_i \mid i \leq w\} \) and \( \text{Er}(C_1) = \text{Er}(C) \setminus X \), we deduce that \( \pi_1(\mu_{1,c}(C_1)) \leq \pi_1(\mu_{1,c}(C)) \) for \( i = 2, 3, 4 \). Thus we conclude that \( \mu_{1,c}(C_1) \leq \mu_{1,c}(C) \).

Note that \( \text{vars}^1(u_0) \cap X^1(C_0) \neq \emptyset \). Hence we have that \( \pi_1(\mu_{1,c}(C_1)) < \pi_1(\mu_{1,c}(C_0)) \) and so \( \mu_{1,c}(C_1) < \mu_{1,c}(C_0) \).

We now focus on \( C_2 \). In such a case, we have that \( D(C_2) = D(C) \) and \( \text{Er}(C_2) = \text{Er}(C) \setminus X \). Hence we trivially have that \( \pi_1(\mu_{1,c}(C_2)) = \pi_1(\mu_{1,c}(C)) \) for \( i = 1, 2, 3, 4 \). Furthermore, we also have that \( \pi_4(\mu_{1,c}(C_2)) = \pi_4(\mu_{1,c}(C)) \) if \( \text{vars}^1(u) \cap X^1(C) = \emptyset \), else \( \pi_4(\mu_{1,c}(C_2)) < \pi_4(\mu_{1,c}(C)) \).

We conclude that \( \mu_{1,c}(C_2) \leq \mu_{1,c}(C) \) and since \( \text{vars}^1(u_0) \cap X^1(C_0) \neq \emptyset \), we also conclude that \( \mu_{1,c}(C_2) < \mu_{1,c}(C_0) \).

\[ \square \]

C.7.1.4 Termination of the cycle of steps \( b \) and \( c \) of Phase 1

**Lemma C.54.** Let \( C \) be a well-formed constraint system. Let \( \text{R}(\overline{p}) \) be an instance of one of the following rule: CONS, AXIOM or EQ-RIGHT-RIGHT. Let \( C_1, C_2 \) be the two constraint systems obtained by application of \( \text{R}(\overline{p}) \) on \( C \). For all \( i \in \{1, 2\}, \) for all \( u \in T(F_i, N \cup X^1) \), if \( \text{vars}^1(u) \subseteq \text{vars}^1(D(C)) \) then \( \text{ind}_{C_i}(u) \geq \text{ind}_{C}(u) \) where \( \sigma = \text{mgu}(\text{Eq}(C)) \).

**Proof.** We do a case analysis on the rule applied: First of all, according to the definition of the rule in Figure 7.1 and 7.2 we have that \( \text{mgu}(\text{Eq}(C_2)) = \text{mgu}(\text{Eq}(C)) \) and \( D(C_2) = D(C) \) for all the rules considered. Hence we have that \( u_2 = u \) and \( \text{ind}_{C_2}(u) = \text{ind}_{C}(u) \). Thus the result holds.

**Rule CONS(X, f):** Let \( (X, i \vdash \text{t}) \in D(C) \). According to Figure 7.1 we have that \( D(C_1) = (D(C) \sigma \setminus \{X, i \vdash \text{t} \}) \cup \{X_k, i \vdash \text{x}_k \} \), where \( X_k \) are fresh variables for \( k = 1 \ldots n \) and \( \sigma = \text{mgu}(t, f(x_1, \ldots, x_n)) \).

If \( t \not\in X^1 \) then it implies that \( \text{dom}(\sigma) = \{x_1, \ldots, x_n\} \), \( D(C) \sigma = D(C) \) and \( \text{vars}^1(D(C)) = \text{vars}^1(D(C_1)) \). Hence we deduce that \( u_\sigma = u \) and \( \text{ind}_{C_1}(u \sigma) = \text{ind}_{C}(u \sigma) \) and so \( \text{ind}_{C_1}(u) = \text{ind}_{C}(u) \).

Else \( t \in X^1 \). In such a case, \( \sigma_1 = \{t \mapsto f(x_1, \ldots, x_n)\} \). For all \( x \in \text{vars}^1(D(C_1)) \setminus \{x_1, \ldots, x_n\} \), \( \text{ind}_{C_1}(x) = \text{ind}_{C}(x) \). Assume now that \( \text{ind}_{C}(t) < j \) thus there exists \( (Y, j \vdash \text{v}) \in D(C) \) such that \( t \in \text{vars}^1(v) \) and \( \text{ind}_{C}(t) = j \). But it implies that \( (Y, j \vdash \text{v}) \in D(C_1) \). On the other hand, if \( \text{ind}_{C}(t) = i \) we know that \( \{X_k, i \vdash \text{x}_k \} \) \( k = 1 \ldots n \). \( D(C_1) \). Hence we deduce that for all \( k = 1, \ldots, n \), \( \text{ind}_{C_1}(x_k) = \text{ind}_{C}(\text{t}) \).

Since \( \text{ind}_{C}(u) = \max\{\text{ind}_{C}(x) \mid x \in \text{vars}^1(u)\} \), we deduce that \( \text{ind}_{C}(u) = \text{ind}_{C}(u \sigma_1) \). Thus the result holds.

**Rule AXIOM(X, path):** Let \( (X, i \vdash \text{t}) \in D(C) \) and \( (\xi, j \succ \text{v}) \in \Phi(C) \) such that \( \text{path}(\xi) = \text{path} \).

According to Figure 7.1 we have that \( D(C_1) = (D(C) \sigma \setminus \{X, i \vdash \text{t} \}) \) then \( \sigma = \text{mgu}(t, v) \).

For all \( x \not\in \text{vars}^1(t, v) \), we have that \( x \sigma = x \) and since \( D(C_1) = (D(C) \sigma \setminus \{X, i \vdash \text{t} \}) \), we can deduce that \( \text{ind}_{C_1}(x) = \text{ind}_{C}(x) \).

Let \( x \in \text{dom}(\sigma) \). We show that for all \( y \in \text{vars}^1(x \sigma) \), \( \text{ind}_{C_1}(y) \leq \text{ind}_{C}(x) \). If \( \text{ind}_{C}(x) = \ell \) then it implies that there exists \( (Y, \ell \vdash w) \in D(C) \) such that \( x \in \text{vars}^1(w) \). If \( X \neq Y \) then we have that \( (Y, \ell \vdash w \sigma) \in D(C_1) \) and since \( y \in \text{vars}^1(w \sigma) \), we can deduce that \( \text{ind}_{C_1}(y) \leq \text{ind}_{C}(x) \). Else if \( X = Y \) then it implies that \( x \in \text{vars}^1(t) \). But \( \Phi(C_1) = \Phi(C) \) which implies that \( (\xi, j \succ \text{v}) \in \Phi(C) \).

Thus, by the origination property of a constraint system, we can deduce that \( y \in \text{vars}^1(w \sigma) \) implies that there exists \( (Z, p \vdash w') \in D(C_1) \) such that \( p < j \) and \( y \in \text{vars}^1(w') \). Hence we deduce that \( \text{ind}_{C}(y) \leq p < j \leq \text{ind}_{C}(x) \). Hence the result holds.
Let $x \in \text{vars}^1(\text{img}(\sigma))$. If $\text{ind}_C(x) < i$ then since $D(C_i) = (D(C) \sigma \setminus \{X, i \vdash t \sigma\})$, we deduce that $\text{ind}_{C_i}(x) \leq \text{ind}_C(x)$. Else $\text{ind}_{C_i}(x) = i$. But since $x \in \text{vars}^1(\sigma)$, the by the properties of origination, we deduce that $\text{ind}_{C_i}(x) < \text{ind}_C(x)$.

We proved that for all $x \in \text{vars}^1(u)$, we have that $\text{ind}_{C_i}(x) \leq \text{ind}_C(x)$. Thus we conclude that $\text{ind}_C(u) \leq \text{ind}_C(u)$.

**Rule Eq-right-right-right** $(X, Y)$: Let $(X, i_1 \vdash v_1) \in D(C)$ and $(Y, i_2 \vdash v_2) \in D(C)$ such that $i_1 \geq i_2$.

According to Figure 7.22 we have that $D(C_1) = (D(C) \sigma \setminus \{X, i_1 \vdash v_1 \sigma\})$ were $\sigma = \text{mgu}(v_1, v_2)$.

For all $x \notin \text{vars}^1(v_1, v_2)$, we have that $x \sigma = x$ thus we can deduce that $\text{ind}_{C_i}(x) = \text{ind}_C(x)$.

Let $x \in \text{dom}(\sigma)$. Let $y \in \text{vars}^1(\sigma)$. If $\text{ind}_C(x) = \ell$ then it implies that there exists $(Z, \ell \vdash w) \in D(C)$ such that $x \in \text{vars}^1(w)$. If $X \neq Z$ then we have that $(Z, \ell \vdash w \sigma) \in D(C)$ and since $y \in \text{vars}^1(\sigma w)$, we can deduce that $\text{ind}_{C_i}(y) \leq \text{ind}_C(x)$. Else if $X = Z$ then it implies that $x \in \text{vars}^1(v_i)$. But $(Y, i_2 \vdash v_2) \in D(C_1)$ and $y \in \text{vars}^1(v_2)$. Hence we have that $\text{ind}_{C_i}(y) \leq i_2 \leq i_1 = \text{ind}_C(x)$.

Let $x \in \text{vars}^1(\text{img}(\sigma))$. If $\text{ind}_C(x) < i_1$ then since $D(C_1) = (D(C) \sigma \setminus \{X, i_1 \vdash v_1 \sigma\})$, we deduce that $\text{ind}_{C_1}(x) \leq \text{ind}_C(x)$. Else $\text{ind}_{C_1}(x) = i_1$. But since $x \in \text{vars}^1(v_2) \sigma$ and $(Y, i_2 \vdash v_2 \sigma) \in D(C_1)$, we deduce that $\text{ind}_{C_1}(x) \leq i_2 \leq i_1 = \text{ind}_C(x)$.

We proved that for all $x \in \text{vars}^1(u)$, we have that $\text{ind}_{C_i}(x) \leq \text{ind}_C(x)$. Thus we conclude that $\text{ind}_C(u) \leq \text{ind}_C(u)$.

**Lemma 8.15.** Let $(M, M')$ be a pair of matrices of constraint systems obtained at the end of the Step $c$ of Phase 1 of the strategy with parameter $s$ and $k$ respectively for support and column. Let $(M_1, M'_1)$ be a pair of matrices of constraint systems obtained by application on $(M, M')$ of Steps $b$ and $c$ with the same parameters. $\mu_{1,b+c}^k(M_1, M'_1) < \mu_{1,b+c}^k(M, M')$.

**Proof.** Since $(M, M')$ and $(M_1, M'_1)$ are both obtained at two consecutive end of step $c$ of phase 1, there exists $(M_2, M'_2)$ such that $(M, M') \rightarrow^*(M_2, M'_2) \rightarrow^*(M_1, M'_1)$ and $(M_2, M'_2)$ is obtained at the end of Step $b$ of Phase 1. The proof of this result is divided in two parts. We first show that $\mu_{1,b+c}^k(M_2, M'_2) \leq \mu_{1,b+c}^k(M, M')$. Secondly we show that $\mu_{1,b+c}^k(M_1, M'_1) < \mu_{1,b+c}^k(M_2, M'_2)$.

**First part**, $\mu_{1,b+c}^k(M_2, M'_2) \leq \mu_{1,b+c}^k(M, M')$: All the rules applied during Step $b$ are internal rules. Furthermore, we know that $M, M'$ was obtained at the end of step $c$ which means that we already apply at leaf one Step $b$ before obtaining $(M, M')$. Hence, the rules Ded-st and Eq-left-left are useless on $(M, M')$ for the support $s$ and the column $k$. Thus the only rules that are applied between $(M, M')$ and $(M_2, M'_2)$ are CONS, Eq-right-right-right and Axiom.

Consider two pair of matrices $(M_2, M'_2)$ and $(M_4, M'_4)$ such that $(M_2, M'_2) \rightarrow^*(M_4, M'_4) \rightarrow^*(M_2, M'_2)$ and assume that $R(\tilde{p})$ is the rule applied on $(M_4, M'_4)$. Let $C$ be a constraint system in the $k$th column of $(M_4, M'_4)$. If the rule $R(\tilde{p})$ was not applied on $C$ then $C$ is in the $k$th column on $(M_3, M'_3)$. If the rule $R(\tilde{p})$ was applied on $C$ then there exists $C_1$ and $C_2$ such that $C_1$ and $C_2$ both in the $k$th column of $(M_3, M'_3)$ and they are the two constraint systems obtained by applying $R(\tilde{p})$ on $C$.

According to Figure 7.23 and 7.22 and the normalisation rules 7.23, for all $i \in \{1, 2\}$, for all $(X, i \vdash u) \in D(C)$, there exists $(Y, i \vdash v) \in D(C)$ and $v' \in st(v)$ such that $v' \text{mgu}(\text{Eq}(C_i)) = u$. But thanks to Lemma 8.15, $\text{ind}_C(v' \text{mgu}(\text{Eq}(C_i))) \leq \text{ind}_C(v')$ and so $\text{ind}_C(u) \leq \text{ind}_C(v')$. Since $v' \in st(v)$, we deduce that $\text{ind}_C(u) \leq \text{ind}_C(v)$. This allows us to deduce that $\text{max}(\text{ind}_C(u) | X \notin S_2(C), (X, j \vdash u) \in D(C_i)) \leq \text{max}(\text{ind}_C(u) | X \notin S_2(C), (X, j \vdash u) \in D(C))$. Hence we deduce that $\mu_{1,b+c}^k(M_3, M'_3) \leq \mu_{1,b+c}^k(M_4, M'_4)$. With a simple induction, we can conclude that $\mu_{1,b+c}^k(M_2, M'_2) \leq \mu_{1,b+c}^k(M, M')$.

**Second part**, $\mu_{1,b+c}^k(M_1, M'_1) < \mu_{1,b+c}^k(M_2, M'_2)$: Let $C_1$ be a constraint system in the $k$th column of $(M_1, M'_1)$. Let $C_2$ be the constraint system ancestor of $C_1$ such that $C_2$ is in $(M_2, M'_2)$. 

C.7. PROOFS OF TERMINATION
Thanks to Lemma [C.31], we know that \((M_1, M'_1)\) satisfies PP1ScE\((s, k)\), and \((M_2, M'_2)\) satisfies PP1SbE\((s, k)\). Thus we deduce that for all \((X, i \vdash u) \in D(C_1)\), if \(X \not\in S_2(C_1)\), then \(u \not\in X^d\) and \(i = s\). Furthermore, we deduce that for all \((X, i \vdash u) \in D(C_2)\), if \(X \not\in S_2(C_2)\), then \(u \in X^d\) and \(i = s\). But the rules applied during step \(c\) either remove internal deducible constraint by Eq-right-right or instantiate them by Axiom or Cons. Thus, for all \((X, s \vdash t_1) \in D(C_1)\), if \(X \not\in S_2(C_1)\), then there exists \(t_2\) such that \((X, s \vdash t_2) \in D(C_2)\).

Let \(C_3\) be a constraint system such that \(C_2 \rightarrow C_3 \rightarrow C_1\). Let \((X, s \vdash t_3) \in D(C_3)\). Thanks to Lemma [C.35], we know that \(\text{ind}_{C_1}(t_1) \leq \text{ind}_{C_1}(t_2) \leq \text{ind}_{C_1}(t_3)\). We will show that there exists \(C_4\) such that \(C_2 \rightarrow C_3 \rightarrow C_4 \rightarrow C_1\). Those two constraints systems exist since we know that \(t_1 \neq t_2\). Let \(R()\) be the rule applied on \(C_3\) to obtained \(C_4\). Since \(t_2 \neq t_3\), we deduce that \(t_3 \in X^d\) and so \(t_3 \in X^d(C_3)\). Thanks to Lemma [C.53] and \(t_3 \in X^d(C_3)\), we deduce that \(R()\) is not an instance of Cons. Furthermore, since Eq-right-right is applied internally we also deduce that \(R()\) is not an instance of Eq-right-right. Hence we conclude that \(R()\) is an instance of Axiom.

Assume that \(R(\tilde{p}) = \text{Axiom}(X_0, \text{path})\). By definition, of the rule, there exists \((X_0, i_0 \vdash u_0) \in D(C_3)\) and \((\xi, j_0 \triangleright v_0) \in \Phi(C_3)\) such that \(j_0 \leq i_0\). Furthermore, we have \(D(C_4) = D(C_3) \sigma \setminus \{X_0, i_0 \vdash u_0\\}, t = v \sigma\) and \(\Phi(C_4) = \Phi(C_3) \sigma\) where \(\sigma = \text{mgu}(u_0, v_0)\). Since by hypothesis \((X, s \vdash t_4) \in D(C_4)\) and \(t_4 \neq t_3\), we have that \(t_3 \in \text{dom}(\sigma)\) and \(t_3 \in \text{vars}^1(u_0, v_0)\). But the rule Axiom is applied on the deducible constraint minimal for \(L^1()\). Hence we deduce that \(t_3 \in \text{vars}^1(u_0, v_0)\) and \(\text{ind}_{C_4}(t_3) = i_0\). But for all \(x \in \text{vars}^1(t_3 \sigma)\), we have that \(x \in \text{vars}^1(v_0 \sigma)\) and \(\Phi(C_4) = \Phi(C_3) \sigma\). Thus, by the property of origination of a constraint system, we know that there exists \((Y, p \vdash w) \in D(C_4)\) such that \(x \in \text{vars}^1(w)\) and \(p < j_0 \leq i_0\). Thus, we have that \(\text{ind}_{C_1}(x) < i_0\) and so for all \(x \in \text{vars}^1(t_3 \sigma)\), \(\text{ind}_{C_4}(x) < \text{ind}_{C_1}(t_3)\). Since \(t_3 \sigma = t_4\), we conclude that \(\text{ind}_{C_4}(t_4) < \text{ind}_{C_1}(t_3)\).

We have shown that for all \((X, s \vdash u) \in D(C_1)\), if \(X \not\in S_2(C_1)\) there exists \(v\) such that \((X, s \vdash v) \in D(C_2)\) and \(\text{ind}_{C_1}(u) < \text{ind}_{C_2}(v)\). Thus we can conclude that \(\mu_{1,k+b+c}(M_1, M'_1) < \mu_{1,k+b+c}(M_2, M'_2)\).

C.7.1.5 Termination of Step \(d\) of Phase 1

Lemma 8.16. Let \((M, M')\) be a pair of matrices of constraint systems obtained during Step \(d\) of Phase 1 of the strategy with parameter \(s\) and \(k\) respectively for support and column. Furthermore, let \(R(\tilde{p})\) be the next possible rule applicable according to step \(d\) of the strategy and let \((M_1, M'_1)\) and \((M_2, M'_2)\) be the two pairs of matrices of constraint systems obtained by application of \(R(\tilde{p})\) on \((M, M')\). We have that:

\[
\mu_{1,d}(M_1, M'_1) < \mu_{1,d}(M, M') \quad \wedge \quad \mu_{1,d}(M_2, M'_2) < \mu_{1,d}(M, M')
\]

Proof. Assume w.l.o.g. that the \(k^{th}\) column of \((M, M')\) is the \(k^{th}\) column of \(M\). We know that the only rules that can be applied in Step \(d\) are Cons, Eq-right-right and Axiom. Furthermore, the external application of those rules implies that \(M_{i,k} \rightarrow M_{1,i,k}\) and \(M_{i,k} \rightarrow M_{2,i,k}\) for all \(i \in \{1, \ldots, n\}\). But thanks to Lemma [C.14] we know that if \(M_{i,k}\) satisfies InvVarConstraint\((s)\) then \(M_{1,i,k}\) and \(M_{2,i,k}\) also satisfy InvVarConstraint\((s)\) or are equal to \(\perp\). Thus, we deduce that \(\pi_1(\mu_{1,d}(M_{1,i,k}, M'_1)) \leq \pi_1(\mu_{1,d}(M, M'))\) and \(\pi_1(\mu_{1,d}(M_{2,i,k}, M'_2)) \leq \pi_1(\mu_{1,d}(M, M'))\).

Let \(i_0\) be the index of the line such that for all \(i \leq i_0, M_{i_0,k} = \perp\) or \(M_{i,k}\) satisfies the invariant InvVarConstraint\((s)\). Let \(R(\tilde{p})\) be an instance of a rule that is strongly applicable on \(M_{i_0,k}\). We do
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a case analysis on $j_0$.

Case $j_0 \leq i_0 + 1$ and $R(\bar{p})$ strongly applicable on $M_{i_0 + 1,k}$: In such a case, by applying Lemma S.13 we obtained that $\mu_{1,b}(M_{i_0 + 1,k}) < \mu_{1,b}(M_{i_0 + 1,k})$ and $\mu_{1,b}(M_{i_0 + 1,k})$. It implies that $\pi_2(\mu_{1,d}^k(M_1, M_1')) < \pi_2(\mu_{1,d}^k(M, M'))$. Hence the result holds.

Case $j_0 \leq i_0 + 1$ and $R(\bar{p})$ not strongly applicable on $M_{i_0 + 1,k}$: Since $R(\bar{p})$ is strongly applicable on $M_{j_0,k}$ then we have that $M_{j_0,k} \neq \bot$ and $j_0 \neq i_0 + 1$. Hence by definition of $i_0$, we deduce that $M_{j_0,k}$ satisfies the invariant InvVarConstraint(s). Hence $R(\bar{p})$ strongly applicable on $M_{j_0,k}$ implies that:

- $R(\bar{p}) = CONS(X,f)$ with $(X, i \vdash x) \in D(M_{j_0,k})$, $x \in X^1$ and there exists $g \in F_c$ such that $\text{Er}(M_{j_0,k}) \vDash root(X) \neq g$. But thanks to Lemma S.3 $(M, M')$ satisfies InvGeneral and more specifically Property 9 of the invariant InvGeneral which means that $\text{Er}(M_{i_0 + 1,k}) \vDash root(X) \neq g$. Thus, we deduce that $R(\bar{p})$ is also strongly applicable on $M_{i_0 + 1,k}$ which is a contradiction with our hypothesis.

- $R(\bar{p}) = \text{AXIOM}(X, \text{path})$ with $(X, i \vdash x) \in D(M_{j_0,k})$, $x \in X^1$ and there exists $g \in F_c$ such that $\text{Er}(M_{j_0,k}) \vDash root(X) \neq g$. Once again, thanks to Property 9 of the invariant InvGeneral, we deduce that $\text{Er}(M_{i_0 + 1,k}) \vDash root(X) \neq g$. However $R(\bar{p})$ is not strongly applicable on $M_{i_0 + 1,k}$ which means that if there exists a frame element $(\xi, i \vdash u) \in \Phi(M_{i_0 + 1,k})$ such that $\text{path}(\xi) = \text{path}$ then $\text{Er}(M_{i_0 + 1,k}) \vDash X \neq \xi$. But thanks to Property 9 and the fact that \text{AXIOM}(X, \text{path}) is strongly applicable on $M_{j_0,k}$, we deduce that there is no frame element $(\xi, i \vdash u) \in \Phi(M_{i_0 + 1,k})$ such that $\text{path}(\xi) = \text{path}$. Thus, we have that $M_{i_0 + 1,k} = \bot$ and $M_{i_0 + 1,k} = M_{i_0 + 1,k}$.

Therefore, we deduce that $\pi_1(\mu_{1,1}^k(M_1, M_1')) < \pi_1(\mu_{1,1}^k(M, M'))$ and $\pi_2(\mu_{1,1}^k(M_2, M_2')) = \pi_2(\mu_{1,1}^k(M, M'))$. Furthermore, we have that $\text{Er}(M_{j_0,k}) = \text{Er}(M_{j_0,k}) \land X \neq \xi$ where $\text{path}(\xi) = \text{path}$ and $(\xi, i \vdash u) \in \Phi(M_{i_0,k})$. Hence we deduce that $\pi_3(\mu_{1,1}^k(M_2, M_2')) < \pi_3(\mu_{1,1}^k(M, M'))$. Thus we conclude that $\mu_{1,1}^k(M_1, M_1') < \mu_{1,1}^k(M, M')$ and $\mu_{1,1}^k(M_2, M_2') < \mu_{1,1}^k(M, M')$.

Case $j_0 > i_0 + 1$: In such a case, it implies that no instance of the rule CONS, AXIOM and EQ-RIGHT-RIGHT can be strongly applied on $M_{i_0 + 1,k}$ with support inferior of equal to $s$. Thus, we can first deduce that for all $(X, i \vdash u) \in D(M_{i_0 + 1,k})$, if $i \leq s$ then $u \in X^1$ and for all $f \in F_c$, $\text{Er}(M_{i_0 + 1,k}) \not\vDash root(X) \neq f$. Indeed, assume that $u \not\in X^1$.

- if there exists $(\xi, j \vdash v) \in \Phi(M_{i_0 + 1,k})$ such that $j \leq i$ and $\text{Er}(M_{i_0 + 1,k}) \not\vDash X \neq \xi$, then AXIOM$(X, \text{path}(\xi))$ would be strongly applicable on $M_{i_0,k}$ which contradicts our hypothesis.

- if there exists $f \in F_c$ such that $\text{Er}(M_{i_0 + 1,k}) \not\vDash root(X) \neq f$, then CONS$(X,f)$ would be strongly applicable on $M_{i_0 + 1,k}$ which contradicts our hypothesis.

- Else we would have that for all $(\xi, j \vdash v) \in \Phi(M_{i_0 + 1,k})$, $j \leq i$ implies $\text{Er}(M_{i_0 + 1,k}) \vDash X \neq \xi$ and for all $f \in F_c$, $\text{Er}(M_{i_0 + 1,k}) \vDash root(X) \neq f$. But in such a case, the normalisation of the constraint system would implies that $M_{i_0 + 1,k} = \bot$ with contradicts the definition of $i_0$. 
We now prove that in fact the case $j_0 > i_0 + 1$ is impossible. Assume that $(X, i \vdash x)$ and $(Y, j \vdash y)$ in $D(M_{i_0+1,k})$ such that $x = y$. In such a case, since we proved that for all $f \in F_c$, $Er(M_{i_0+1,k}) \not\models \text{root}(X) \neq f$ and $Er(M_{i_0+1,k}) \not\models \text{root}(Y) \neq f$, we can deduce that the rule $\text{EQ-RIGHT-RIGHT}(X,Y)$ is strongly applicable on $M_{i_0+1,k}$ which is a contradiction on our hypothesis. Hence we can deduce that $M_{i_0+1,k}$ satisfies the invariant $\text{InvVarConstraint}(s)$ which is also a contradiction on the definition of $i_0$. Hence the case $j_0 > i_0 + 1$ is impossible.

\[\square\]

C.7.2 Proofs of results on association tables

Lemma C.55. Let $C$ be a well-formed constraint system. Let $E$ be a disjunction of disequation on first order constructive term. Let $D$ be a disjunction of disequation on context of recipe. We have that:

\[L_C^1(E) = L_C^1(\leq E) \quad \text{and} \quad L_C^2(D) = L_C^2(D \leq)\]

\[\text{Proof.} \quad \text{Direct from the definition of normalisation} \downarrow \text{and} \downarrow.\]

Lemma C.56. Let $E$ be a disjunction of first order constructive term and let $\sigma$ a substitution on constructive term. Let $D$ be a disjunction of term in $T(F_c, F_d^* \cdot AX) \cup X^2$ and let $\theta$ be a substitution from $X^2$ to $T(F_c, (F_d^* \cdot AX) \cup X^2)$. We have that:

\[E \sigma \downarrow = (E \downarrow) \sigma \downarrow \quad \text{and} \quad D \theta \downarrow = (D \downarrow) \theta \downarrow\]

Let $C$ be a constraint system such that for all $\beta \in \text{st}(D) \cap ((F_d^* \cdot AX) \cup X^2)$, $\beta \in \text{dom}(\text{acc}^1(C))$. We have that $(D \downarrow) \text{acc}^1(C) = \text{acc}^1(C) \downarrow$.

\[\text{Proof.} \quad \text{Direct from the definition of normalisation} \downarrow \text{and} \downarrow.\]

Lemma 8.17. Let $(M, M')$ be a pair of matrices of constraint systems obtained during Step b or Step c of Phase 2 of the strategy. For all constraint systems $C, C'$ in $(M, M')$ and their respective association tables $T, T'$, for all $\forall_i^n x_i \neq v_i$, for all $\forall_j^m \beta_j \neq \beta'_j$, $T | \forall_i^n x_i \neq v_i | \forall_j^m \beta_j \neq \beta'_j | T'$, if $T | \forall_i^n x_i \neq v_i | \equiv \forall_j^m \beta_j \neq \beta'_j | T'$, then we have that:

\[\left(\bigvee_j^m \beta_j \text{acc}^1(C) \neq \beta'_j \text{acc}^1(C)\right) \downarrow = \bigvee_i^n x_i \neq v_i\]

Moreover, if $T | \forall_i^n x_i \neq v_i | \equiv \forall_j^m \beta_j \neq \beta'_j |$ and for all $k \in \{1, \ldots, m\}$, $\text{st}(\beta_j, \beta'_j) \cap (F_d^* \cdot AX) = \emptyset$ then there exists $\forall_i^n x'_i \neq v'_i$ such that $T | \forall_i^n x'_i \neq v'_i | \equiv \forall_j^m \beta_j \neq \beta'_j |$.

\[\text{Proof.} \quad \text{Let} (M_0, M'_0) \text{ be the pair of matrices of constraint system, ancestor of} (M, M'), \text{obtained at the end of Step a of the second phase of the strategy. As mentioned in Section 12.2 there is three different kind of transformations on the association tables. The first one, called default transformation, is applied on each application of any rule. The second one consist of added new entry on the association table after the application of the rule CONS. The last one consisting of removing some entry is applied when the association tables meet some conditions. Hence we will prove the result by case analysis on the three transformations and by induction on the size $N$ of the branch between $(M_0, M'_0)$ and $(M, M')$.}\]

Base case $N = 0$: In such a case, we have $(M_1, M'_1) = (M_0, M'_0)$. But according to the strategy, the association table of any constraint system, in $(M_0, M'_0)$ are empty. Hence the result trivially holds.

Inductive step $N > 0$: Since $N > 0$, we know that there exists $(M_1, M'_1)$ a pair of matrices of constraint systems such that $(M_1, M'_1) \rightarrow (M, M')$. Let $C$ be two constraint system in $(M, M')$ and let $T$ its respective association table. Let $R(\bar{p})$ be the rule applied on $(M_1, M'_1)$ to obtain
\( (M, M') \). Furthermore, let \( C_1 \) be the constraint system in \( (M_1, M'_1) \) such that \( C_1 \rightarrow C \) and let \( T_1 \) its association table. We do a case analysis on the transformation from \( T_1 \) to \( T \).

Let \( E \) be a disjunction of inequation on first order term and let \( D \) be a disjunction of inequation on context of recipe such that \( T[E] = D \). For simplicity purpose, we will denote \(\sigma = \text{mgu}(E\theta(C))\), \(\theta = \{X \mapsto C[X\theta]_{\phi(C)} \mid X \in \text{vars}^2(C)\}\).

- Default transformation: By definition of the default transformation, we know that there exists a disjunction on first order term such that \( E = E_1\sigma \downarrow \) and \( T[E] = T_1[E_1]\Theta_1 \). Let's denote \( T_1[E_1] = D_1 = \bigvee_i \beta_i \neq \beta'_i \).

  By inductive hypothesis on \( (M_1, M'_1) \), we know that \( D_1\sigma \downarrow = E_1 \) which implies that \( D_1\sigma \downarrow = E_1\sigma \downarrow = E \). Hence, thanks to Lemma C.56, we deduce that \( D_1\sigma \downarrow = E \). But thanks to Lemma C.57, we know that for all \( i \), for all \( X \in \text{vars}^2(\beta_i) \), \( X\sigma \downarrow = C[X\theta]_{\phi(C)}X\theta \downarrow = X\Theta \downarrow \).

  Hence, since for all \( i, \beta, \beta' \in T(F, (F_d^*\cdot AX) \cup X^2) \), we deduce that \( \beta\sigma \downarrow = \beta\Theta \downarrow \). Similarly, we have that \( \beta'\sigma \downarrow = \beta'\Theta \downarrow \).

  Hence we deduce that \( D_1\sigma \downarrow = \beta_1\Theta \downarrow \). But again thanks to Lemma C.56, we prove that \( D_1\Theta \downarrow = (D_1\Theta \downarrow)\sigma \downarrow = D\sigma \downarrow \). Thus we conclude that \( D\sigma \downarrow = D \).

- Rule \( \text{Eq-right-right}(X, \xi) \): In the case of the rule \( \text{Eq-right-right} \) when the inequation holds, the strategy indicates that we add on \( T \) the following entry: \( T[x \neq v] := X \neq \xi \) where \( x = X\sigma \downarrow \) and \( v = \xi\sigma \downarrow \). Hence we deduce that \( X \neq \xi \). But \( v \in T(F, X^1) \) which means that \( x \neq v \).

- Removing entry: The last transformation consists of removing some entry from the association table. Hence the result trivially holds.

Lemma 8.18. Let \( C \) be a well-formed constraint system satisfying \( \text{InvVarConstraint}(\infty) \). Let \( \beta, \beta' \) be two contexts of recipes such that \( \beta, \beta' \in T(F, (F_d^*\cdot AX) \cup X^2) \). We have that \( L_2^C(\beta\sigma \downarrow \neq \beta\sigma \downarrow) \leq L_2^C(\beta \neq \beta') \). Furthermore, if \( \beta \in (F_d^*\cdot AX) \) or \( \beta' \in (F_d^*\cdot AX) \), then we have that \( L_2^C(\beta\sigma \downarrow \neq \beta\sigma \downarrow) < L_2^C(\beta \neq \beta') \).

Proof. We know that \( L_2^C(\beta \neq \beta') = \{\text{param}_{\text{max}}^C(\beta); \text{param}_{\text{max}}^C(\beta')\} \). But we know that \( \beta, \beta' \in T(F, (F_d^*\cdot AX) \cup X^2) \) means that \( \text{param}_{\text{max}}^C(\beta) = \max\{\text{param}_{\text{max}}^C(\zeta) \mid \zeta \in \text{st}(\beta) \cap \{(F_d^* \cdot AX) \cup X^2\}\} \). Similarly, we have that \( \text{ind}_{\text{c}}(\beta\sigma \downarrow) = \max\{\text{ind}_{\text{c}}(u) \mid u \in \text{st}(\beta) \cap \{(F_d^* \cdot AX) \cup X^2\}\} \).

Hence, to prove the result, it suffices to show that for all \( (\xi, i \triangleright u) \in \Phi(\xi), \text{ind}_{\text{c}}(u) \leq \text{param}_{\text{max}}^C(\text{path}(\xi)) \); and for all \( (X, i \triangleright x) \in D(\xi), \text{ind}_{\text{c}}(x) \leq \text{param}_{\text{max}}^C(\text{path}(X)) \).

- Case \( (X, i \triangleright x) \in D(\xi) \): We know that \( C \) satisfies the invariant \( \text{InvVarConstraint}(\infty) \). Hence, \( (X, i \triangleright x) \) is the only deducible constraint system that contain \( x \) which means that \( \text{ind}_{\text{c}}(x) = i \). Furthermore, by definition of \( \text{param}_{\text{max}}^C(X) \), we have that \( \text{param}_{\text{max}}^C(X) = i \) and so the result holds.

- Case \( (\xi, i \triangleright u) \in \Phi(\xi) \): We know that \( \text{path}(\xi) \in F_d^* \cdot AX \) hence there exists \( ax_k \) such that \( \xi = w \cdot ax_k \). Hence by definition, we have that \( \text{param}_{\text{max}}^C(\text{path}(\xi)) = k \). Let \( v \) such that \( ax_k, k \triangleright v \in \Phi(\xi) \). Once again thanks to the fact that \( C \) is well-formed, we can deduce that \( v \in \text{st}(v) \). But thanks to the origination property of constraint system and the invariant \( \text{InvVarConstraint}(\infty) \), we have that for all \( x \in \text{vars}^2(v) \), there exists \( (X, \ell \triangleright x) \in D(\xi) \) such that \( \ell < k \). Hence, we can deduce that \( \text{ind}_{\text{c}}(v) \leq \text{ind}_{\text{c}}(v) < k = \text{param}_{\text{max}}^C(\text{path}(\xi)) \). Hence the result holds.

\qed
Lemma 8.19. Let \((M, M')\) be a pair of matrices of constraint systems obtained during Step b or Step c of Phase 2 of the strategy. Let \(R(\hat{p})\) be one of the following external rules: AXIOM, CONS, EQ-RIGHT-RIGHT. Let \((M_1, M'_1)\) and \((M_2, M'_2)\) be the results of the application of \(R(\hat{p})\) on \((M, M')\). We have that:

\[
\mu_{gen}(M_1, M'_1) \leq \mu_{gen}(M, M') \quad \text{and} \quad \mu_{gen}(M_2, M'_2) \leq \mu_{gen}(M, M')
\]

Furthermore, for \(i = 1, 2\), if a removal transformation was applied on the association table of \((M_i, M'_i)\) then \(\mu_{gen}(M_i, M'_i) < \mu_{gen}(M, M')\).

Proof. The removal transformation is independent of the rule applied on the pair of matrices. Hence, we will first prove the result without considering the removal transformation (i.e. only default transformation for the rule CONS and AXIOM; and the default and addition transformations for the rule EQ-RIGHT-RIGHT). Then we will show the result when a removal transformation is applied. We do a case analysis on the rule applied on \((M, M')\):

Case Rule CONS(X; f): Let \(C\) be a constraint system in \((M, M')\) different from \(\bot\) and let \(C_1, C_2\) the two constraint systems obtained by applying the rule CONS(X; f) on \(C\). Hence we have that \(C_1\) and \(C_2\) are respectively in \((M_1, M'_1)\) and \((M_2, M'_2)\). We can first notice that the only difference between \(C_2\) and \(C\) is that \(Er(C_2) = Er(C) \land \text{root}(X) \neq f\). Hence, we can deduce that \(Eq(C_2) = Eq(C)\) and so the association tables of \(C\) and \(C_2\) are the same. Thus, we conclude that \(\mu_{gen}(M_2, M'_2) = \mu_{gen}(M, M')\).

We now focus on \((M_1, M'_1)\): Since \(C\) satisfies InvVarConstraint(\(\infty\)), we know that there exist \(x \in A^1\) such that \((X, i \vdash x) \in D(C)\). Furthermore, by definition of the rule, we know that \(Eq(C_1) = Eq(C) \land X \vdash f(x_1, \ldots, x_n)\) and \(Eq(C_1) = Eq(C) \land x \vdash f(x_1, \ldots, x_n)\) where \(X_k, x_k\) are fresh variable and \(\text{ind}_C(x_k) = \text{param}_{\text{max}}(X_k) = i\), for all \(k = 1, \ldots, n\).

Hence, thanks to the normalisation, we deduce that for all disjunction \(D_1\) of disjunction of first order term, if there exists \(E_1\) such that \(Eq(C_1) = E_1 \land D_1\) then there exists \(D\) such that \(Eq(C) = E \land D\) and \(D\sigma \downarrow = D_1\) where \(\sigma = \{x \mapsto f(x_1, \ldots, x_n)\}\). But \(\text{ind}_C(x) = \text{ind}_C(x_k)\), for all \(k = 1, \ldots, n\). Hence we deduce that \(L^1_C(D) = L^1_C(D\sigma)\). But, thanks to Lemma \([7.55]\) we have that \(L^1_C(D\sigma) = L^1_C(D\sigma)\) and so \(L^1_C(D) = L^1_C(D_1)\).

Since we only consider the default transformation on the association table from now, we also have that \(T_1[D_1] = \bot\) implies \(T[D] = \bot\). Hence, we proved that for all \(D_1\) such that \(Eq(C_1) = E_1 \land D_1\) and \(T_1[D_1] = \bot\), there exists \(D\) such that \(Eq(C) = E \land D\) and \(T[D] = \bot\) and \(L^1_C(D) = L^1_C(D_1)\). Thus we deduce that \(\mu_{gen}(M_1, M'_1) \leq \mu_{gen}(M, M')\).

Furthermore, by definition of the default transformation on the association tables, we have that if \(T_1[D_1] = \bot\) then we know that \(T[D]\) also exists and \(T[D] = \bot\) where \(\Theta = \{X \mapsto f(x_1, \ldots, x_n)\}\). But once again, we know that \(\text{param}_{\text{max}}(X) = \text{param}_{\text{max}}(X_k)\), for all \(k = 1, \ldots, n\). Hence we deduce that \(L^1_C(T[D]) = L^1_C(T[D\Theta])\). Thanks to Lemma \([7.55]\) we have that \(L^1_C(T[D\Theta]) = L^1_C(T[D\Theta])\) and so \(L^1_C(T[D_1]) = L^1_C(T[D])\). Thus we deduce that \(\mu_{gen}(M_1, M'_1) \leq \mu_{gen}(M, M')\). Since we proved that \(\mu_{gen}(M_1, M'_1) \leq \mu_{gen}(M, M')\), we can conclude that \(\mu_{gen}(M_1, M'_1) \leq \mu_{gen}(M, M')\).

Case Rule AXIOM(X; path): Let \(C\) be a constraint system in \((M, M')\) different from \(\bot\) and let \(C_1, C_2\) the two constraint systems obtained by applying the rule AXIOM(X; path) on \(C\). Hence we have that \(C_1\) and \(C_2\) are respectively in \((M_1, M'_1)\) and \((M_2, M'_2)\). We can first notice that either \(C_1 = \bot\) and \(C_2 = C\) or else the only difference between \(C_2\) and \(C\) is that \(Er(C_2) = Er(C) \land \text{root}(X) \neq \xi\) for some \(\xi\) such that \(\text{path}(\xi) = \text{path}\). Hence, we can deduce that \(Eq(C_2) = Eq(C)\) and so the association tables of \(C\) and \(C_2\) are the same. Thus, we conclude that \(\mu_{gen}(M_2, M'_2) = \mu_{gen}(M, M')\).

We now focus on \((M_1, M'_1)\): Since \(C\) satisfies InvVarConstraint(\(\infty\)), we know that there exist \(x \in A^1\) such that \((X, i \vdash x) \in D(C)\). Furthermore, by definition of the rule, we know that there exists \((\xi, j \vdash v) \in \Phi(C)\) such that \(\text{path}(\xi) = \text{path}, j \leq i, Er(C_1) = Er(C) \land X \vdash \xi\) and \(Eq(C_1) = Eq(C) \land x \vdash v\).
Hence, thanks to the normalisation, we deduce that for all disjunction $D_1$ of disjunction of first order term, if there exists $E_1$ such that $Eq(C_1) = E_1 \land D_1$ then there exists $D$ and $E$ such that $Eq(C) = E \land D$ and $D \sigma \downarrow = D_1$ where $\sigma = \{ x \mapsto v \}$. But thanks to InvVarConstraint($\infty$) and the property of origination of a constraint system, we know that for all $y \in \operatorname{vars}^2(v)$, there exists $(Y, \ell \vdash y) \in D(C)$ with $\ell < j$. Hence we have that $\text{ind}_C(v) < \text{ind}_C(x)$ which implies that $L^1_{\text{acc}}(D \sigma) \leq L^1_{\text{acc}}(D)$. But, thanks to Lemma C.55, we have that $L^1_{\text{acc}}(D \sigma) = L^1_{\text{acc}}(D \sigma \downarrow)$ and so $L^1_{\text{acc}}(D_1) \leq L^1_{\text{acc}}(D)$.  

Since we only consider the default transformation on the association table from now, we also have that $T_1[D_1] = \perp$ implies $T[D] = \perp$. Hence, we proved that for all $D_1$ such that $Eq(C_1) = E_1 \land D_1$ and $T_1[D_1] = \perp$, there exists $D$ such that $Eq(C) = E \land D, T[D] = \perp$ and $L^1_{\text{acc}}(D_1) \leq L^1_{\text{acc}}(D)$. Thus we deduce that $\mu^\perp\text{gen}(M_1, M'_1) \leq \mu^\perp\text{gen}(M, M')$.  

Furthermore, by definition of the default transformation on the association tables, we have that if $T_1[D_1]$ exists then we know that $T[D]$ also exists and $T_1[D_1] = T[D] \Theta_1$ where $\Theta = \{ X \mapsto C(\xi_\phi(C)) \}$. But we know $C(\xi_\phi(C)) = C(\xi_\phi(C)) = \text{path} \in F_{\text{ax}} \cdot A \chi$. Assume that $\text{path} = w \cdot a z_k$. Since $C$ is a well-formed constraint system and thanks to Property [1] of a well-formed constraint system, we know that $k \leq j$. Hence we deduce that $\text{param}_{\text{max}}^C(\xi, \phi(C)) = k \leq j$. But since $(X, i \vdash x) \in D(C)$, we have that $\text{param}_{\text{max}}^C(X) = i$ with $j \leq i$. Thus we have that $\text{param}_{\text{gen}}^C(X \Theta) \leq \text{param}_{\text{gen}}^C(X)$ which implies that $L^2_{\text{acc}}(T[D] \Theta) \leq L^2_{\text{acc}}(T[D])$. Thanks to Lemma C.56, we have that $L^2_{\text{acc}}(T[D] \Theta) = L^2_{\text{acc}}(T[D] \Theta_1)$ and so $L^2_{\text{acc}}(T[D_1]) \leq L^2_{\text{acc}}(T[D])$. Thus we deduce that $\mu^\parallel\text{gen}(M_1, M'_1) \leq \mu^\parallel\text{gen}(M, M')$. Since we proved that $\mu^\perp\text{gen}(M_1, M'_1) \leq \mu^\perp\text{gen}(M, M')$, we can conclude that $\mu^\perp\text{gen}(M_1, M'_1) \leq \mu^\perp\text{gen}(M, M')$.  

Case Rule Eq-right-right($X, \xi$): We first focus on $(M_2, M'_2)$: Let $C$ be a constraint system in $(M, M')$ different from $\perp$ and $T$ its association table. Let $C_2$ the constraint system in $(M_2, M'_2)$ with $T_2$ its association table such that $C \rightarrow C_2$ by the rule Eq-right-right($X, \xi$). According to Figure 7.2 and since $C$ satisfies the invariant InvVarConstraint($\infty$), we have that $(X, i \vdash x) \in D(C)$ with $x \in X^1$. Furthermore, for all $Y \in \operatorname{vars}^2(\xi)$, there exists $(Y, j \vdash y) \in D(C)$ with $y \in X^1$, $j \leq i$ and $\text{ind}_C(y) = j$. At last, we have $Eq(C_2) = (Eq(C) \land x \neq y) \downarrow$ where $x = \xi \text{acc}^1(\{ \xi \})$. Note that if there exists $E'$ and $E''$ such that $Eq(C) = E' \land (E'' \lor x \neq y)$ then we have that $Eq(C_2) = E' \downarrow \land x \neq y$. Furthermore, by definition of the addition transformation, we have that $T_2[x \neq y] = X \neq \xi$, i.e. $(X \neq \xi) \notin S(M_2, M'_2)$. Since we proved those properties for any constraint system $C$ in $(M, M')$, we can deduce that:  

• Case (a): If there exists $C$ in $(M, M')$ and $T$ its association table, $E', E''$ such that $Eq(C) = E' \land (E'' \lor x \neq y)$ and $T[E'' \lor x \neq y] = \perp$ where $x = X \text{acc}^1(C)$ and $v = \xi \text{acc}^1(C)$ then the number of occurrence of $L^1_{\text{acc}}(E'' \lor x \neq y)$ strictly decrease between $\mu^\parallel\text{gen}(M, M')$ and $\mu^\parallel\text{gen}(M_2, M'_2)$. Thus we have $\mu^\parallel\text{gen}(M_2, M'_2) < \mu^\parallel\text{gen}(M, M')$;  

• Case (a’): else $\mu^\parallel\text{gen}(M_2, M'_2) = \mu^\parallel\text{gen}(M, M')$  

Assume now that there exists $E', E''$, $D$ such that $Eq(C) = E' \land (E'' \lor x \neq y)$ and $T[E'' \lor x \neq y] = D \lor X \neq \xi$ with $x = X \text{acc}^1(C)$ and $v = \xi \text{acc}^1(C)$. We already have shown that $Eq(C_2) = E' \downarrow \land x \neq y$. Hence by definition of the default transformation, we deduce that $T_2[E'' \lor x \neq y] = \perp$. Since we prove this property for any constraint system $C$ in $(M, M')$, we can deduce that:  

• Case (b): if there exists $D$ such that $(D \lor X \neq \xi) \notin S(M, M')$ then $(D \lor X \neq \xi) \notin S(M_2, M'_2)$ and $(X \neq \xi) \notin S(M_2, M'_2)$. But for all $D$, $L^2_{\text{acc}}(X \neq \xi) \leq L^2_{\text{acc}}(D \lor X \neq \xi)$. Thus, we have that $\mu^\parallel\text{gen}(M_2, M'_2) \leq \mu^\parallel\text{gen}(M, M')$.  

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Proof: Case (b): else S(M2, M‘2) = S(M, M‘) ∪ \{X ̸= ξ\} and so ρ2_gen(M2, M‘2) = ρ2_gen(M, M‘) ∪ \{|L_1^c(X ̸= ξ)\}.

If (M, M‘) satisfies Case (b) then we proved that ρ2_gen(M2, M‘2) ≤ ρ2_gen(M, M‘) and in both cases (a) or (a’) we proved that ρ1_gen(M2, M‘2) ≤ ρ1_gen(M, M‘). Hence we conclude that ρ_gen(M2, M‘2) ≤ ρ_gen(M, M‘).

It remains to show that when (M, M‘) satisfies Case (b’) then the result holds. Case (b’) is satisfied when then there is no D such that (D ∨ X ̸= ξ) ∈ S(M, M‘). It implies that for all constraint system C in (M, M‘) and T its association table, for all E, T[E ∨ x ̸= v] = ⊥ with x = Xacc1(C) and v = ξacc1(C). But according to the application condition of the rule EQ-RIGHT-RIGHT for Step b of the strategy, it implies that there exists C in (M, M‘), T its association table, E’, E‘‘ formulas such that E(C) = E ∨ (E‘ ∨ x ̸= v) and T[E‘ ∨ x ̸= v] = ⊥ with x = Xacc1(C) and v = ξacc1(C). Thus (M, M‘) satisfies Case (a). In such a case, we already shown that the number of occurrence of L_1^c(E‘ ∨ x ̸= v) strictly decrease between ρ1_gen(M, M‘) and ρ1_gen(M2, M‘2). But L_1^c(x ̸= v) ≤ L_1^c(E‘ ∨ x ̸= v) and since all constraint system in (M, M‘) satisfy InvVarConstraint(∞) and ξ ∈ T(F_c, vars2(C)), we also have that L_1^c(X ̸= ξ) = L_1^c(x ̸= v) ≤ L_1^c(E‘ ∨ x ̸= v). Hence we have that ρ1_gen(M2, M‘2)∪\{|L_1^c(X ̸= ξ)\}) ≤ ρ1_gen(M, M‘).

Thus, ρ_gen(M2, M‘2) ≤ ρ_gen(M, M‘).

We now focus on (M1, M‘1): Let C be a constraint system in (M, M‘) different from ⊥ and T its association table. Let C1 the constraint system in (M1, M‘1) with T1 its association table such that C → C1 by the rule EQ-RIGHT-RIGHT(X, ξ). According to Figure[7a] and since C satisfies the invariant InvVarConstraint(∞), we have that (X, i ◄ x) ∈ D(C) with x ∈ X1. Furthermore, for all Y ∈ vars2(ξ), there exists (Y, j ◄ y) ∈ D(C) with y ∈ X1, j ≤ i and ind(C)(y) = j. At last, we have

Eq(C1) = Eq(C) ∧ x = y and D(C1) = D(C) \{X, i ◄ x\} where v = ξacc1((i)(C)).

Hence, thanks to the normalisation, we deduce that for all disjunction D1 of disjunction of first order term, if there exists E1 such that Eq(C1) = E1 ∧ D1 then there exists D and E such that Eq(C) = E ∨ D and Dσ↓ = D1 where σ = (x → v). But we proved that for all Y ∈ vars2(ξ), there exists (Y, j ◄ y) ∈ D(C) with y ∈ X1, j ≤ i and ind(C)(y) = j. Hence with ξ ∈ T(F_c, X2), we deduce that ind(C)(v) ≤ ind(C)(x). Since X /∈ vars2(ξ) and D(C1) = D(C) \{X, i ◄ x\}, we also have that ind(C1)(v) = ind(C)(v) which implies that L_1^c(Dσ↓) ≤ L_1^c(D). But, thanks to Lemma[65], we have that L_1^c(Dσ↓) = L_1^c(Dσ↓) and so L_1^c(Dσ↓) ≤ L_1^c(D).

Since only the default transformation on the association table is applied for (M1, M‘1), we also have that T1[D1] = ⊥ implies T[D] = ⊥. Hence, we proved that for all D1 such that Eq(C1) = E1 ∧ D1 and T1[D1] = ⊥, there exists D such that Eq(C) = E ∨ D, T[D] = ⊥ and L_1^c(D) ≤ L_1^c(D). Thus we deduce that μ_gen(M1, M‘1) ≤ μ_gen(M, M‘).

Furthermore, by definition of the default transformation on the association table, we have that if T1[D1] exists then we know that T[D] also exists and T1[D1] = T[D]θ1 where θ1 = {X ↦ C[ξ]φ(C)}. But ξ ∈ T(F_c, X2) implies that C[ξ]φ(C) = ξ. Moreover, according to Figure[7b] for all

Y ∈ vars2(ξ), param(Cmax1, Y) ≤ param(Cmax1, X). Since D[C1] = D(C) \{X, i ◄ x\} and X /∈ vars2(ξ), we deduce that param(Cmax1, Y) = param(Cmax1, Y) and so param(Cmax1, ξ) ≤ param(Cmax1, X). Thus we have L_2^c(T[D]θ1) ≤ L_2^c(T[D]). Thanks to Lemma[65], we have that L_2^c(T[D]θ1) = L_2^c(T[D]θ1) and so L_2^c(T[D]θ1) ≤ L_2^c(T[D]). Hence we deduce that μ_gen(M1, M‘1) ≤ μ_gen(M, M‘).

Application of the removal transformations: To simplify the proof, for a pair of matrices (M, M‘),
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we denote \((M, \bar{M}')\) the pair of matrices obtained after applying all the removal transformation. Similarly, for an association table \(T\) in \((M, M')\), we denote \(\bar{T}\) the association table corresponding of \(T\) in \((\bar{M}, \bar{M}')\).

Let \(C\) be constraint system in \((M, M')\) and its association table \(T\) such that \(T[D] = \bigvee_j \beta_j \neq \beta_j'\) with \(\beta_j \in (\mathcal{F}_a \cdot AX)\), for all \(j\) and for some \(D\). In such a case, we have \((\bigvee_j \beta_j \neq \beta_j') \in \mathcal{S}(M, M')\) which means that there exists a multiset \(\mathcal{M}_2\) such that \(\mu_{\text{gen}}(M, M') = \mathcal{M}_2 \cup \{L^2_2(\bigvee_j \beta_j \neq \beta_j')\}\). However according to the definition of the removal transformation, the entry is in fact removed, i.e. \(\bar{T}[D] = \bot\).

Since the removal transformation is applied on all association tables in \((M, M')\), we can deduce that \((\bigvee_j \beta_j \neq \beta_j') \notin S(\bar{M}, \bar{M}')\) and so \(\mu_{\text{gen}}(\bar{M}, \bar{M}') = \mathcal{M}_2\). On the other hand, if we denote \(\mathcal{M}_1\) the multiset such that \(\mathcal{M}_1 = \{L^2_1(D) \mid T[D] = (\bigvee_j \beta_j \neq \beta_j')\}\), for some \(D\) and some \(C\) in \((\bar{M}, \bar{M}')\) with \(T\) its association table, we also have that \(\mu_{\text{gen}}(\bar{M}, \bar{M}') = \mu_{\text{gen}}(\bar{M}, \bar{M}') \cup \mathcal{M}_1\).

But thanks to Lemma \([S.17]\), we know that for all \(C\) in \((M, M')\) and \(T\) its association table, for all \(D\), if \(T[D] = (\bigvee_j \beta_j \neq \beta_j')\) then \((\bigvee_j \beta_j \neq \beta_j')acc^1(C) \notin D\). Hence thanks to Lemma \([C.35]\), we deduce that \(L^2_2(D) = L^2_2(\bigvee_j \beta_jacc^1(C) \neq \beta_j'acc^1(C))\). At last, thanks to Lemma \([S.18]\) and \(\beta_j \in (\mathcal{F}_a \cdot AX)\) for all \(j\), we deduce that \(L^2_2(D) < L^2_2(\bigvee_j \beta_j \neq \beta_j')\). Thus, it allows us to conclude that \(\mathcal{M}_2 < \{L^2_2(\bigvee_j \beta_j \neq \beta_j')\}\) and so \(\mu_{\text{gen}}(\bar{M}, \bar{M}') < \mu_{\text{gen}}(M, M')\). \(\square\)

C.7.3 Proofs of termination of each step of Phase 2 of the strategy

C.7.3.1 Termination of Step \(a\) of Phase 2

Lemma 8.20. Let \((M, M')\) be a pair of matrices of constraint systems obtained during Step \(a\) of Phase 2 of the strategy. Let \(R(p)\) be one instance of the rule AXIOM or CONS such that \(R(p)\) is strongly applicable on at least one constraint system in \(M\) or \(M'\). At last, let \((M_1, M'_1)\) and \((M_2, M'_2)\) be the two pairs of matrices of constraint systems obtained by application of \(R(p)\) on \((M, M')\). We have that:

\[
\mu_{2,a}(M_1, M'_1) < \mu_{2,a}(M, M') \quad \land \quad \mu_{2,a}(M_2, M'_2) < \mu_{2,a}(M, M')
\]

Proof. Thanks to the normalisation, we know that for all constraint system \(C\) in \(M\), the disjunctions of inequations in \(Eq(C)\) are of the form \(\forall \bar{y}. \forall_i x_i \neq u_i\) where \(\bar{y}\) is a set of universal variable and \(x_i\) are not universal for any \(i\). Assume that \((X, i \vdash x) \in D(C)\) and a rule is applied on this deducible constraint, i.e. CONS(X, f) or AXIOM(X, path). Let’s denote \(C_1\) and \(C_2\) the two constraint systems obtained by applying the rule on \(C\), i.e. \(C_1\) is in \((M_1, M'_1)\) and \(C_2\) is in \((M_2, M'_2)\).

We first focus on \((M_1, M'_1)\): In the case of rule CONS, since \(C\) satisfies InvVarConstraint(\(\infty\)), we deduce that \(x\) will be instantiatiated in \(C_1\) by \(f(x_1, \ldots, x_n)\) where \(x_k\) are not universal, for all \(k \in \{1, \ldots, n\}\). In the case of rule AXIOM, since \(C\) satisfies the invariant InvNoUse(\(\infty\)), we know that \((\xi, j \triangleright u) \in \Phi(C)\) with path(\(\xi\)) = path(\(\xi\)) implies that \(u \notin X^1\) (otherwise we would have \((\xi, j \triangleright u) \in \text{NoUse}(C)\) and so the rule AXIOM(X, path) would not be applicable).

Hence we have shown that \(x\) is necessary instantiated by a term different from a variable. We denote \(\sigma\) the substitution that instantiates \(x\). Let’s now look at the possible atomic statement that contains \(x\):

1. Case \(Eq(C) = E' \land [\forall \bar{y}. z \cdot E'' \lor x \neq v]\) and \(z \in \text{vars}^1(v)\): In such a case, we have that \(Eq(C_1) = E'\sigma \downarrow \land [\forall \bar{y}. z \cdot E''\sigma \lor x\sigma \neq v\sigma]\). By hypothesis, we know that \(Eq(C)\) is normalised. Hence we have that \(v \neq z\) which means that \(\text{root}(v) \in \mathcal{F}_c\). Let’s denote \(v = g(v_1, \ldots, v_n)\).
Since \( x \in \text{vars}^1(v) \), there exists \( k \) and a position \( p \) such that \( z \in \text{vars}^1(v_k) \) and \( v_k|_p = z \). This implies that \((k \cdot p) \in \pi_1(\mu_2.a(M, M'))\). Furthermore, we proved that \( x\sigma \not\in \mathcal{X}^1 \), thus we can denote \( x\sigma = f(u_1, \ldots, u_m) \).

If \( g = f \) then \( u = n \) and we have that \( (x\sigma \not\in \mathcal{X}^1) \land u_1 \lor v_1 \lor \ldots \lor v_n \). Hence in such a case, we deduce that the same occurrence of \( z \) have the position \( p \in \pi_1(\mu_2.a(M, M')) \).

Else \( g \neq f \). In such a case, we deduce that \( E' \land [\forall y. z. E' \land \sigma \not\in \mathcal{X}^1] \implies E' \land \sigma \). Thus, this specific occurrence of \( z \) in \( \text{Eq}(\mathcal{C}) \) is no longer in \( \text{Eq}(\mathcal{C}_1) \).

2. Case \( \text{Eq}(\mathcal{C}) = E' \land [\forall y. z. E'' \land z' \neq v], z' \neq x \) and \( z \in \text{vars}^1(v) \): We already proved that \( x\sigma \) do not contain an universal variable and \( x \neq x' \) which implies that \( x' \neq v\sigma \). Hence if \( p \) is a position such that \( v\sigma|_p = z \) then we also have that \( v|_p = z \) which means that \( p \in \pi_1(\mu_2.a(M, M')) \) and \( p \in \pi_1(\mu_2.a(M, M')) \).

We have shown that the position of an occurrence of an universal variable either stay the same or decrease. More specifically, we have shown that in Case 1, the position necessary decrease or the occurrence is no longer in \( \text{Eq}(\mathcal{C}_1) \). Since Case 1 corresponds to the application condition of the rule Axiom and Cons, we deduce that \( \mu_2.a(M, M'_1) < \mu_2.a(M, M') \).

We now focus on \( (M_2, M'_2) \): By definition of the rule Axiom and Cons, we know that the only difference between \( \mathcal{C} \) and \( \mathcal{C}_2 \) is the second order formula \( \text{Er} \), i.e. \( \text{Er}(\mathcal{C}_2) = \text{Er}(\mathcal{C}) \land \text{root}(X) \). In the case of the rule Cons(\( X,f \)); and \( \text{Er}(\mathcal{C}_2) = \text{Er}(\mathcal{C}) \land X \neq \xi \) in the case of the rule Axiom(\( X, \text{path} \)) with \( \text{path}(\xi) = \text{path} \) and \( (\xi, \eta) \in \Phi(\mathcal{C}) \). Hence we trivially have that \( \pi_k(\mu_2.a(M_2, M'_2)) = \pi_k(\mu_2.a(M, M')) \) with \( k = 1, 2 \) and \( \pi_3(\mu_2.a(M_2, M'_2)) < \pi_3(\mu_2.a(M, M')) \) in the case of the rule Axiom; whereas we have \( \pi_1(\mu_2.a(M_2, M'_2)) = \pi_1(\mu_2.a(M, M')) \) and \( \pi_2(\mu_2.a(M_2, M'_2)) < \pi_2(\mu_2.a(M, M')) \) in the case of the rule Cons. We conclude that \( \mu_2.a(M_2, M'_2) < \mu_2.a(M, M') \). \( \square \)

### C.7.3.2 Termination of Step b of Phase 2

**Definition C.3.** Let \( \mathcal{C} \) be a well-formed constraint system satisfying InvVarConstraint(\( \infty \)). We say that \( H \land (x \neq v) \) exists if \( \text{root}(v) \in \mathcal{F}_c \) and either \( st(v) \land \mathcal{N} \neq \emptyset \) or \( \text{ind}(x) < \text{ind}(v) \). Moreover, when \( H \land (x \neq v) \) exists, \( H_1(x \neq v) = (h_a, h_b) \) where \( h_a = \max\{||p|| v|_p \in \mathcal{N}\} \) and \( h_b = \max\{||v|_p \in \mathcal{X}^1 \land \text{ind}(x) < \text{ind}(v|_p)\} \).

We define similarly \( H_2 \) for context of recipes:

**Definition C.4.** Let \( \mathcal{C} \) be a well-formed constraint system satisfying InvVarConstraint(\( \infty \)). We say that \( H \land (X \neq \beta) \) exists if \( \text{root}(\beta) \in \mathcal{F}_c \) and either \( st(\beta) \land (F^v \cdot \mathcal{X}) \neq \emptyset \) or \( \text{param}_{\text{max}}(\mathcal{X}) < \text{param}_{\text{max}}(\beta) \).

Moreover, when \( H \land (X \neq \beta) \) exists, \( H_1(X \neq \beta) = (h_a, h_b) \) where \( h_a = \max\{||p|| \beta|_p \in (F^v \cdot \mathcal{X})\} \) and \( h_b = \max\{||\beta|_p \in \mathcal{X}^2 \land \text{param}_{\text{max}}(\mathcal{X}) < \text{param}_{\text{max}}(\beta|_p)\} \).

**Lemma C.57.** Let \( \mathcal{C} \) be a well-formed constraint system satisfying InvVarConstraint(\( \infty \)). Let \( y \neq u \) be an inequation on term. Let \( \sigma = \{x \mapsto v\} \) such that \( x \not\in \text{vars}^1(v) \), \( \text{ind}(v) \leq \text{ind}(x) \) and \( st(v) \land \mathcal{N} = \emptyset \). If \( \text{mgu}(y\sigma \neq u\sigma) \) exists then \( \forall_k z_k \neq t_k \) such that \( (y \neq u)\sigma \downarrow = \forall_k y_k \neq t_k \). Moreover,

- if \( \text{ind}(x) < \text{ind}(y) \) then...
Thus the result holds. 

- \((y \neq u) \sigma \downarrow = (y \neq u \sigma)\); and

- \(H^1(y \neq u \sigma)\) exists implies \(H^1(y \neq u)\) exists and \(H^1(y \neq u \sigma) = H^1(y \neq u)\);

- **else if** \(\text{ind}_C(x) = \text{ind}_C(y)\) **then** for all \(k\),
  - if \(\text{ind}_C(y_k) > \text{ind}_C(y)\) then \(H^1(y_k \neq t_k)\) **does not exist**.
  - if \(\text{ind}_C(y_k) = \text{ind}_C(y)\) and \(H^1(y_k \neq t_k)\) exists then \(H^1(y \neq t_k)\) exists. Moreover, if \(x = y\) and \(v \notin \mathcal{X}^1\) then \(H^1(y_k \neq t_k) < H^1(y \neq u)\) **else** \(H^1(y_k \neq t_k) = H^1(y \neq u)\) and \((y \neq u) \sigma \downarrow = (y \sigma \neq u \sigma)\).

**Proof.** Since \(\text{mgu}(y \sigma \neq u \sigma)\) exists, we deduce that either \(x \not\in st(y, u)\) or \(x \in st(u)\) or else \(x = y\).

In the first two cases, we deduce that \((y \sigma \neq u \sigma) \downarrow = (y \neq u \sigma)\). Moreover, since \(\text{ind}_C(v) \subseteq \text{ind}_C(x)\) and \(st(v) \cap \mathcal{N} = \emptyset\), we also deduce that if \(H^1(y \neq u \sigma)\) exists then so does \(H^1(y \neq u)\) and \(H^1(y \neq u \sigma)\).

Assume now that \(x = y\) and \(u = v\). In such a case, by the normalisation rule (Nt1), we deduce that \(n = 0\) and so the result trivially holds.

At last, assume that \(x = y\) and \(u \neq v\). In such a case, since \(\text{mgu}(y \sigma \neq u \sigma)\) exists, then the only normalisation rule that can be applied are (N1) and (Nsplit). Hence, thanks to \(st(v) \cap \mathcal{N} = \emptyset\), we deduce that there exists \(\bigvee_k y_k \neq t_k\) such that \((y \neq u) \sigma \downarrow = \bigvee_k y_k \neq t_k\) and for all \(k \in \{1, \ldots, n\}\):

1. either \(y_k \in st(v)\) and \(t_k \in st(u)\);
2. or \(y_k \in st(u)\) and \(t_k \in st(v)\).

Let \(k \in \{1 \ldots n\}\). Assume first that \(\text{ind}_C(y_k) > \text{ind}_C(y)\). Since \(x = y\) and \(\text{ind}_C(v) \subseteq \text{ind}_C(x)\), we deduce that \(y_k \not\in st(v)\) and so \(y_k \in st(u)\) and \(t_k \in st(v)\). But \(t_k \in st(v)\) and \(\text{ind}_C(y_k) > \text{ind}_C(v)\) implies \(\text{ind}_C(t_k) < \text{ind}_C(y_k)\). Moreover, by hypothesis, \(st(v) \cap \mathcal{N} = \emptyset\) hence \(st(t_k) \cap \mathcal{N} = \emptyset\) and thus we deduce that \(H^1(y_k \neq t_k)\) does not exist. Hence the result holds.

Assume now that \(\text{ind}_C(y_k) = \text{ind}_C(y)\) and \(H^1(y_k \neq t_k)\) exists. Thus, we deduce that \(\text{root}(t_k) \in \mathcal{F}_c\) and either \(st(t_k) \cap \mathcal{N} \neq \emptyset\) or \(\text{ind}_u(\vartheta) (\text{ind}_k(\vartheta))\). But we know that \(\text{ind}_C(v) \subseteq \text{ind}_C(x) = \text{ind}_C(y) = \text{ind}_C(y_k)\) and \(st(v) \cap \mathcal{N} = \emptyset\) hence in both cases, we deduce that \(y_k \in st(v)\) and \(t_k \in st(u)\). Furthermore, \(t_k \in st(v)\) and \(\text{root}(t_k) \in \mathcal{F}_c\) implies that \(\text{root}(u) \in \mathcal{F}_c\). At last, \(t_k \in st(u)\), \(\text{ind}_C(y_k) = \text{ind}_C(y)\) and either \(st(t_k) \cap \mathcal{N} \neq \emptyset\) or \(\text{ind}_u(\vartheta) (\text{ind}_k(\vartheta))\) imply that either \(st(u) \cap \mathcal{N} \neq \emptyset\) or \(\text{ind}_u(\vartheta) (\text{ind}_k(\vartheta))\). Hence \(H^1(y \neq u)\) exists.

It remains to check the value of \(H^1(y \neq u)\). If \(v \in \mathcal{X}^1\) then \(t_k = u\) and so we deduce that \(H^1(y \neq u) = H^1(y \neq u)\). Else \(v \not\in \mathcal{X}^1\) implies that \(\text{root}(v) = \text{root}(u) \in \mathcal{F}_c\). In such a case, there is at least one application of the normalisation rule (Nsplit) and so the length of the position of each name or each variable in \(u\) strictly decrease. Hence we deduce that \(H^1(y_k \neq t_k) < H^1(y \neq u)\). Thus the result holds. 

**Lemma C.58.** Let \(C\) be a well-formed constraint system satisfying \(\text{InvVarConstraint}(\infty)\). Let \(Y \neq \beta\) be a inequation on context of recipe. Let \(\theta = \{X \mapsto \xi\}\) such that \(X \not\in \text{vars}^*({\xi})\), \(\text{param}^X_{\text{max}}(\xi) \leq \text{param}^X_{\text{max}}(C)\) and \(st(\xi) \cap (\mathcal{F}_d \cdot \mathcal{AX}) = \emptyset\). If \(\text{mgu}(Y \theta \neq \beta \theta)\) exists then \(\bigvee_k Y_k \neq \zeta_k\) such that \((Y \neq \beta) \theta \downarrow = \bigvee_k Y_k \neq \zeta_k\). Moreover,
Appendix C. Decision Procedure of Trace Equivalence

Let \( \text{root} \) be a constraint rule Cons and \( k \) be the second phase. Let Lemma 8.21. Thanks to Lemma 8.19, we know that \( \mu \) is the constraint system such that \( \mu \) and \( \mu' \) be the constraint system obtained by application of \( \mu \) and \( \mu' \) on \( \mu \). Hence we will assume from now on that no removal transformation is applied. We do a case analysis on the rule applied and the pairs of matrices we consider:

Case rule Cons(X, f) and \( (M_2, M_2') \): Let \( \mathcal{C} \) be a constraint system in \( (M, M') \) different from \( \perp \) and \( T \) its association table. Let \( \mathcal{C}_2 \) be the constraint system in \( (M_2, M_2') \) and \( T_2 \) its association table such that \( \mathcal{C} \rightarrow \mathcal{C}_2 \). According to Figure 7.41 and the strategy, there exists \( (X, i \vdash x) \in D(\mathcal{C}) \) and \( \mathcal{E}(\mathcal{C}) \not\models \text{root}(X) \neq f \). Furthermore, the only difference between \( \mathcal{C}_2 \) and \( \mathcal{C} \) is that \( \mathcal{E}(\mathcal{C}_2) = \mathcal{E}(\mathcal{C}) \land \text{root}(X) \neq f \).

Hence the default transformation on association table does not modify \( T \) which means that \( T = T_2 \) and so \( \pi(x_{2, k}(M_2, M_2')) = \pi(x_{2, k}(M, M')) \), for \( k = 2, 3 \). Furthermore, we also have that for all \( k \in \{1, \ldots, n\} \setminus \{i\} \), \( x_{\text{var}}(M_2, M_2') = x_{\text{var}}(M, M') \), \( x_{\text{cons}}(M_2, M_2') = x_{\text{cons}}(M, M') \) and \( x_{\text{cons}}(M_2, M_2') = x_{\text{cons}}(M, M') \). Moreover, for all \( g \in \mathcal{F}_c \), \( \mathcal{E}(\mathcal{C}_2) \models \text{root}(X) \neq g \) implies that \( \mathcal{E}(\mathcal{C}) \not\models \text{root}(X) \neq g \). Thus we deduce that \( x_{\text{cons}}(M_2, M_2') = x_{\text{cons}}(M, M') \) and so \( \pi(x_{2, k}(M_2, M_2')) \leq \pi(x_{2, k}(M, M')) \). At last, since \( \mathcal{E}(\mathcal{C}) \not\models \text{root}(X) \neq f \) and \( \mathcal{E}(\mathcal{C}_2) \models \text{root}(X) \neq f \), we deduce that \( \pi(x_{2, k}(M_2, M_2')) \leq \pi(x_{2, k}(M, M')) \) and so we have \( x_{2, k}(M_2, M_2') \leq x_{2, k}(M, M') \).

Case rule Cons(X, f) and \( (M_1, M_1') \): Let \( \mathcal{C} \) be a constraint system in \( (M, M') \) different from \( \perp \) and \( T \) its association table. Let \( \mathcal{C}_1 \) be the constraint system in \( (M_1, M_1') \) and \( T_1 \) its association table such that \( \mathcal{C} \rightarrow \mathcal{C}_1 \). According to Figure 7.41 and the strategy, there exists \( (X, i \vdash x) \in D(\mathcal{C}) \) and \( \mathcal{E}(\mathcal{C}) \not\models \text{root}(X) \neq f \). Furthermore, we have that \( \mathcal{E}(\mathcal{C}_1) = \mathcal{E}(\mathcal{C}) \land X \models f(x_1, \ldots, x_m), \mathcal{E}(\mathcal{C}_1) = \mathcal{E}(\mathcal{C}) \land X \models (x_1, \ldots, x_m) \downarrow \) and \( D(\mathcal{C}_1) = D(\mathcal{C}) \land \{X, i \vdash x\} \cup \{X_k, i \vdash x_k\}_{k=1..m} \) where \( X_1, x_1, \ldots, x_m, x_m \) are fresh variables.
Thanks to the normalisation, we deduce that for all disjunction $D_1$ of first order terms, if there exists $E_1$ such that $Eq(C_1) = E_1 \land D_1$ then there exists $D$ and $E$ such that $Eq(C) = E \land D$ and $D \vdash D_1$ where $\sigma = \{x \mapsto f(x_1, \ldots, x_m)\}$. But we assumed that only the default transformation on association table is applied and so we have $T_1[D_1] = \bot$ is equivalent to $T[D] = \bot$. Thus we deduce that $\pi_2(\mu_{2,1}(M_1, M_1')) \leq \pi_2(\mu_{2,1}(M, M'))$. Moreover, since $T_1[D_1] = T[D\{X \mapsto f(x_1, \ldots, x_m)\}]$, then and $st(T_1[D_1]) \cap (F_{d} \cdot A\chi) \neq \emptyset$ is equivalent to $st(T[D]) \cap (F_{d} \cdot A\chi) \neq \emptyset$. Hence we deduce that $\pi_3(\mu_{2,1}(M_1, M_1')) \leq \pi_3(\mu_{2,1}(M, M'))$.

We first show that for all $j > i$, $\mu_{\text{cons},1}^j(M, M')$. Let $D_1$ be a disjunction on first order terms. Let $y_1 \in \mathcal{X}_1$ and $u_1$ a term such that $Eq(C_1) = E_1 \land (D_1 \land y_1 \not\in u_1)$, $T_1[D_1 \land y_1 \not\in u_1] = \bot$, $j = \text{ind}_{C_1}(y_1)$, $i$ and $H^1(y_1 \not\in u_1)$ exists. Since we only consider the default transformation on association table, we deduce that there exists $D$ and $E$ such that $Eq(C) = E \land D$ and $D \vdash D_1 \land y_1 \not\in u_1$. Let $C$ and $C_1$ satisfy $\text{InvVarConstraint}(\bot)$. Thus, thanks to Lemma $\text{C.57}$ and since $\text{ind}_{C}(x) < \text{ind}_{C_1}(y_1) \not\in u_1$, we deduce that there exists $D'$, $y$, $u$ such that $D' \equiv D \lor (y \not\in u)$, $(y \not\in u) \sigma_{\downarrow} = (y \not\in u) \sigma_{\uparrow} = (y_1 \not\in u_1)$ and $H^1(y \not\in u) = H^1(y_1 \not\in u_1)$. At last, $C$ being normalised and satisfying $\text{InvVarConstraint}(\bot)$ also implies that there exists $(Y, j \vdash y_1) \in D(C)$ and so $(Y, j \vdash y) \in D(C)$. Thus $\text{Er}(C_1) \equiv \text{root}(Y) \not\equiv \text{root}(u_1)$ implies that $\text{Er}(C_1) \equiv \text{root}(Y) \not\equiv \text{root}(u)$. We conclude that $H^1(y_1 \not\in u_1) \in \mu_{\text{cons},1}^j(M_1, M_1')$ implies that $H^1(y \not\in u) \in \mu_{\text{cons},1}^j(M, M')$ and so $\mu_{\text{cons},1}^j(M_1, M_1') \subseteq \mu_{\text{cons},1}^j(M, M')$.

Using a similar proof and relying on Lemma $\text{C.58}$, we can show that $\mu_{\text{cons},2}^j(M_1, M_1') \subseteq \mu_{\text{cons},2}^j(M, M')$ and so $\mu_{\text{cons},1}^j(M_1, M_1') \subseteq \mu_{\text{cons},1}^j(M, M')$.

We now show that $\mu_{\text{cons},1}^j(M_1, M_1') < \mu_{\text{cons},1}^j(M, M')$. Let $D_1$ be a disjunction on first order terms. Let $y_1 \in \mathcal{X}_1$ and $u_1$ a term such that $Eq(C_1) = E_1 \land (D_1 \land y_1 \not\in u_1)$, $T_1[D_1 \land y_1 \not\in u_1] = \bot$, $j = \text{ind}_{C_1}(y_1) = i$ and $H^1(y_1 \not\in u_1)$ exists. Since we only consider the default transformation on association table, we deduce that there exists $D$ and $E$ such that $Eq(C) = E \land D$ and $D \vdash D_1 \land y_1 \not\in u_1$. Let $C$ and $C_1$ satisfy $\text{InvVarConstraint}(\bot)$. Thus, thanks to Lemma $\text{C.57}$ and since $\text{ind}_{C}(x) = \text{ind}_{C_1}(y_1) \not\in u_1$, we deduce that there exists $D'$, $y$, $u$ such that $D' \equiv D \lor (y \not\in u)$ and $H^1(y \not\in u) \sigma_{\downarrow} = H^1(y \not\in u) \sigma_{\uparrow} = H^1(y_1 \not\in u_1)$ and $H^1(y \not\in u) \not\equiv H^1(y_1 \not\in u_1)$. Moreover, since $\sigma = \{x \mapsto f(x_1, \ldots, x_n)\}$, we deduce that $H^1(y \not\equiv u)$ exists and if $x = y$ then $H^1(y_1 \not\equiv u_1) < H^1(y \not\equiv u)$ else $H^1(y_1 \not\equiv u_1) = H^1(y \not\equiv u)$, $y_1 = y_1$ and $u_\sigma = u_1$.

Thus, we deduce that $\mu_{\text{cons},1}^j(M_1, M_1') \leq \mu_{\text{cons},1}^j(M, M')$ and if there exists one inequation in $C$ of the form $x \not\equiv y$ where $H^1(x \not\equiv y)$ exists then $\mu_{\text{cons},1}^j(M_1, M_1') < \mu_{\text{cons},1}^j(M, M')$.

Similarly, relying on Lemma $\text{C.58}$, we can show that $\mu_{\text{cons},2}^j(M_1, M_1') \leq \mu_{\text{cons},2}^j(M, M')$ and if there exists one inequation in $T$ of the form $X \not\equiv \beta$ where $H^2(X \not\equiv \beta)$ exists then $\mu_{\text{cons},2}^j(M_1, M_1') < \mu_{\text{cons},2}^j(M, M')$.

But according to the application condition for $\text{Cons}(X, f)$, there exists at least one constraint system $C$ in $(M, M')$ and $T$ its association table that satisfy one of these two conditions. Hence, we deduce that $\mu_{\text{cons},1}^j(M_1, M_1') < \mu_{\text{cons},1}^j(M, M')$.

At last, since we trivially have that $\mu_{\text{var}}^j(M_1, M_1') = \mu_{\text{var}}^j(M, M')$ for all $j > i$, we conclude that $\mu_{2,1}(M_1, M_1') < \mu_{2,1}(M, M')$.

Case rule $\text{Eq-right-right}(X, \xi)$ and $(M_2, M_2')$: Let $C$ be a constraint system in $(M, M')$ different from $\bot$ and $T$ its association table. Let $C_2$ be the constraint system in $(M_2, M_2')$ and $T_2$ its
association table such that $C \rightarrow C_2$. According to Figure 7, there exists $(X, i \vdash x) \in D(C)$. Furthermore, the only difference between $C_2$ and $C$ is that $Eq(C_2) = (Eq(C) \wedge \text{Xacc}^1(C) \neq \text{xiacc}^1(C)) \downarrow$. Moreover, $T_2[\text{Xacc}^1(C) \neq \text{xiacc}^1(C)] = X \neq \xi$. But we know that $\xi \in T(F_c, \lambda^2) \text{ thus st}(X \neq \xi) \cap (F_d^b \cdot AX) = \emptyset$. Hence we deduce that $\pi_k(\mu_{2,b}(M_2, M'_2)) < \pi_k(\mu_{2,b}(M, M'))$, for $k = 1, 2$.

But according to the application condition for Eq-right-right-right($X, \xi$), there exists at least one constraint system $C$ in $(M, M')$ and $T$ its association table such that $Eq(C) = E' \wedge (E'' \vee \text{Xacc}^1(C) \neq \text{xiacc}^1(C))$ and

- either (a) $T[E'' \vee \text{Xacc}^1(C) \neq \text{xiacc}^1(C)] = \bot$
- or else (b) $T[E'' \vee \text{Xacc}^1(C) \neq \text{xiacc}^1(C)] = D \vee X \neq \xi$ with $(F_d^b \cdot AX) \cap \text{st}(D) \neq \emptyset$.

But $Eq(C_1) = (Eq(C) \wedge \text{Xacc}^1(C) \neq \text{xiacc}^1(C)) \downarrow$ and so by the normalisation rule (Nd), we have $Eq(C_1) = E' \wedge \text{Xacc}^1(C) \neq \text{xiacc}^1(C)$. Hence in Case (a), we deduce that $\pi_2(\mu_{2,b}(M_2, M'_2)) < \pi_2(\mu_{2,b}(M, M'))$ whereas in Case (b), $\pi_2(\mu_{2,b}(M_2, M'_2)) < \pi_3(\mu_{2,b}(M, M'))$. Thus in both cases, we deduce that $\mu_{2,b}(M_2, M'_2) < \mu_{2,b}(M, M')$.

Case rule Eq-right-right-right($X, \xi$) and $(M_1, M'_1)$: Let $C$ be a constraint system in $(M, M')$ different from $\bot$ and $T$ its association table. Let $C_1$ be the constraint system in $(M_1, M'_1)$ and $T_1$ its association table such that $C \rightarrow C_1$. According to the definition of the rule and since $C$ satisfies InvVarConstraint($\infty$), there exists $(X, i \vdash x) \in D(C)$ such that $\text{param}C_{\text{max}}(\xi) \leq i$, $\text{xiacc}^1(C) \in T(F_c, X^2)$ and $\text{ind}_C(\text{xiacc}^1(C)) \leq i$. Moreover, $Eq(C_1) = Eq(C) \sigma \downarrow \wedge x \not\in \text{xiacc}^1(C)$ and $\text{Er}(C_1) = Eq(C) \theta_1 \wedge X \not\in \xi$ where $\sigma = \{ x \mapsto \text{xiacc}^1(C) \}$ and $\theta = \{ X \mapsto \xi \}$.

Thanks to the normalisation, we deduce that for all disjunction $D_1$ of first order term, if there exists $E_1$ such that $Eq(C_1) = E_1 \wedge D_1$ then there exists $D$ and $E$ such that $Eq(C) = E \wedge D$ and $D \sigma \downarrow = D_1$. But we assumed that only the default transformation on association table is applied and so we have $T_1[D_1] = \bot$ is equivalent to $T(D_1) = \bot$. Thus we deduce that $\pi_2(\mu_{2,b}(M_1, M'_1)) \leq \pi_2(\mu_{2,b}(M, M'))$. Moreover, since $T_1[D_1] = T(D)\{X \mapsto \xi\} \downarrow$ and $\text{st}(\xi) \cap (F_d^b \cdot AX) = \emptyset$, then $\text{st}(T[D_1]) \cap (F_d^b \cdot AX) = \emptyset$ is equivalent to $\text{st}(T[D]) \cap (F_d^b \cdot AX) = \emptyset$. Hence we deduce that $\pi_3(\mu_{2,b}(M_1, M'_1)) \leq \pi_3(\mu_{2,b}(M, M'))$.

Once again, we can rely on Lemmas 3.2.4 and 3.1.6. Hence using a similar proof to the one for the rule Cons, we deduce that $\mu_{i\text{cons}}(M_1, M'_1) \leq \mu'_{i\text{cons}}(M, M')$ for all $j \geq i$. Since the deducible constraint $(X, i \vdash x)$ is removed in $D(C_1)$, we can also deduce that $\mu_{i\text{var}}(M_1, M'_1) < \mu'_{i\text{var}}(M, M')$ and so $\mu_{2,b}(M_1, M'_1) < \mu_{2,b}(M, M')$.

C.7.3.3 Termination of Step c of Phase 2

Lemma 8.22. Let $(M, M')$ be a pair of matrices of constraint systems obtained during Step c of the second phase. Let Axiom($\bar{p}$) be an applicable rule and $(M_1, M'_1)$ and $(M_2, M'_2)$ the two pairs of matrices of constraint systems obtained by application of Axiom($\bar{p}$) on $(M, M')$. We have that:

$$\mu_{2,c}(M_1, M'_1) < \mu_{2,c}(M, M') \quad \text{and} \quad \mu_{2,c}(M_2, M'_2) < \mu_{2,c}(M, M')$$

Proof. Direct from the definition of the rule Axiom.

C.7.3.4 Termination of the cycle of steps b and c of Phase 2

Lemma 8.23. Let $(M, M')$ be a pair of matrices of constraint systems obtained at the end of Step b of the second phase. Assume that there exists $(M_1, M'_1)$ obtained at the end of the next Step b of such that $(M, M') \rightarrow^* (M_1, M'_1)$. At last, assume that there exists $(M_0, M'_0)$
obtained at the end of step c of the second phase such that \((M_1, M'_1) \rightarrow^* (M_0, M'_0)\). In such a case, 
\(\mu_{\text{gen}}(M_0, M'_0) < \mu_{\text{gen}}(M, M')\).

**Proof.** Since \((M, M') \rightarrow^* (M_1, M'_1)\) and both are obtained at the end of Step b, we deduce that there exists \((M_2, M'_2)\) obtained at the end of Step c such that 
\((M, M') \rightarrow^* (M_2, M'_2) \rightarrow^* (M_1, M'_1)\). First of all, thanks to Lemma 8.13, if a removal transformation was applied on the association table, we directly deduce that 
\(\mu_{\text{gen}}(M_0, M'_0) < \mu_{\text{gen}}(M, M')\). Hence for the rest of this proof, we will assume that no removal transformation is applied.

Consider \(C\) (resp \(C_1, C_2\)) a constraint system in \((M, M')\) (resp. \((M_1, M'_1)\), \((M_2, M'_2)\)) and \(T\) (resp. \(T_1, T_2\)) its association table. Assume that \(C \rightarrow^* C_2 \rightarrow^* C_1\).

Let \(\forall \ i, u_i \neq v_i\) such that \(\text{Eq}(C) = E \land \forall \ i, u_i \neq v_i\) for some \(E\), and \(T[\forall \ i, u_i \neq v_i] = \bot\). Thanks to Lemma C.33 we know that for all \(i\), \(u_i \neq v_i\) satisfies one of the following properties:

1. \(u_i \in \mathcal{X}^1\) and \(v_i \in \mathcal{N}\)
2. \(u_i, v_i \in \mathcal{X}^1\), \(\text{Err}(\mathcal{C}) \models \text{root}(X_i) \neq f\) and \(\text{Err}(\mathcal{C}) \not\models \text{root}(Y_i) \neq g\), for all \(f, g \in \mathcal{F}_c\), where 
   \((X_i, p \vdash u_i), (Y_i, q \vdash v_i) \in \mathcal{D}(C)\):
3. \(u_i \in \mathcal{X}^1\), \(\text{root}(v_i) \in \mathcal{F}_c\) and for all \(f \in \mathcal{F}_c\), \(\text{Err}(\mathcal{C}) \models \text{root}(X) \neq f\), where \((X_i, p \vdash u_i) \in \mathcal{D}(C)\)

We can assume that \(C_1\) and \(C_2\) are different from \(\bot\) otherwise the result trivially holds. However, since in case 1 \(v_i \in \mathcal{N}\) and in cases 2,3 we have for all \(f \in \mathcal{F}_c\), \(\text{Err}(\mathcal{C}) \models \text{root}(X_i) \neq f\), we deduce that the rules Axiom(\(X_i\), path) are applied during step c, for all \(i\). Hence, since we assume that \(C_1 \neq \bot\), we deduce that either \((\forall \ i, u_i \neq v_i)\text{mgu}(\text{Eq}(C))\) is true or else each \(u_i \in \text{dom}(\text{Eq}(\text{mgu}(C)))\) for all \(i\), i.e. each \(u_i\) are instantiate by the rule axiom.

However, by applying Axiom(\(X_i\), path), we know that there exists a frame element \((\xi, j \triangleright t)\) such that \(j \leq i\) and \(\text{path}(\xi) = \text{path}\). Moreover, by the origination property of a constraint system, we know that \(\text{ind}(t) < j \leq i\). Hence thanks to Lemma C.54 and since each \(u_i\) are instantiated by a term \(t_i\) such that \(\text{ind}(t_i) < \text{ind}(u_i)\), we deduce that \(L_{\mathcal{C}}(\forall \ i, u_i \neq v_i) < L_{\mathcal{C}}((\forall \ i, u_i \neq v_i)\text{mgu}(\text{Eq}(C)))\). Hence we conclude that 
\(\mu_{\text{gen}}(M_2, M'_2) < \mu_{\text{gen}}(M, M')\) and so 
\(\mu_{\text{gen}}(M_0, M'_0) < \mu_{\text{gen}}(M, M')\).

Let \(\forall \ j, \xi_j \neq \xi_j\) such that 
\(T[\forall \ i, u_i \neq v_i] = \forall \ j, \xi_j \neq \xi'_j\). Once again thanks to Lemma C.33 we know that either for all \(i\), \(st(\xi_i, \xi'_i) \cap (\mathcal{F}_d^* \cdot \mathcal{A}\mathcal{X}) = \emptyset\) or else for all \(i\), \(\xi_i \neq \xi'_i\) satisfies one of the following properties:

1. \(\xi_i \in (\mathcal{F}_d^* \cdot \mathcal{A}\mathcal{X})\)
2. \(\xi_i, \xi'_i \in \mathcal{X}^2\), for all \(f \in \mathcal{F}_c\), \(\text{Err}(\mathcal{C}) \models \text{root}(\xi_i) \neq f\) and \(\text{Err}(\mathcal{C}) \not\models \text{root}(\xi'_i) \neq f\)
3. \(\xi_i \in \mathcal{X}^2\), \(\text{root}(\xi'_i) \in \mathcal{F}_c\) and for all \(f \in \mathcal{F}_c\), \(\text{Err}(\mathcal{C}) \models \text{root}(\xi_i) \neq f\)

Assume first that there exists \(i\) such that \(st(\xi_i, \xi'_i) \cap (\mathcal{F}_d^* \cdot \mathcal{A}\mathcal{X}) \neq \emptyset\). Since in cases 2 and 3 we have \(\xi_i \in \mathcal{X}^2\) and for all \(f \in \mathcal{F}_c\), \(\text{Err}(\mathcal{C}) \models \text{root}(\xi_i) \neq f\), we deduce that the rules Axiom(\(\xi_i\), path) are applied during step c, for all \(i\) and all path. But we consider that \(C_2 \neq \bot\). Hence thanks to the normalisation rule (Nunosol), we deduce that each \(\xi_i\) that satisfied cases 2 and 3 are instantiated in \(C_2\) by the rule Axiom(\(\xi_i\), path). But in such a case, we would have that 
\(T_2[\forall \ i, u_i \neq v_i] = \forall \ j, \xi_j \neq \xi'_j\) where for all \(j\), \(\xi_j \in (\mathcal{F}_d^* \cdot \mathcal{A}\mathcal{X})\). Hence the removal transformation would have been applied which is in contradiction with our hypothesis. Hence we deduce that for all \(i\), \(st(\xi_i, \xi'_i) \cap (\mathcal{F}_d^* \cdot \mathcal{A}\mathcal{X}) = \emptyset\).
Thus, can assume from now on that for all constraint system $C$ in $M$ or $M'$, for all $\forall u_i \neq v_i$ in $Eq(C)$, there exists $D$ such that $T[\forall u_i \neq v_i] = D$ and $st(D) \cap (T^* \cdot AX) = \emptyset$. (We already covered all the other cases). Since we assumed that $(M, M') \rightarrow^\ast (M_2, M'_2)$, it implies that some instances of the rules Axiom was applied between $(M, M')$ and $(M_2, M'_2)$ (otherwise, we would have that the strategy would have stop at $(M, M')$).

But the according to the application conditions of the rule Axiom, it implies that there exists $C$ in $(M, M')$ and $f \in F_c$ such that $(X, i \vdash x) \in D(C)$ and $Er(C) \models \text{root}(X) \neq f$. Since we assumed that $(M_2, M'_2) \rightarrow^\ast (M_1, M'_1)$, we can deduce that there exists a disjunction $E \vee x \neq u$ such that $T[E \vee x \neq u] = D \vee X \neq \beta$ (otherwise no rule Cons and Eq-right-right would be applicable on $(M_2, M'_2)$). But by application of the rule Axiom(X,path), then we deduce that $st(T_2[(E \vee x \neq u) \mu \text{gu}(Eq(C_2)) \mu \text{gu}][F_0^* \cdot AX]) \neq \emptyset$. Since the rules Cons and Eq-right-right only instantiate the association tables by context of recipes in $T(F_c, X^2)$, we deduce that $st(T_1[(E \vee x \neq u) \mu \text{gu}(Eq(C_1)) \mu \text{gu}][F_0^* \cdot AX]) \neq \emptyset$. Since $(M_0, M'_0)$ is obtained at the end of Step e and $(M_1, M'_1) \rightarrow^\ast (M_0, M'_0)$, by using a similar proof as previously, we prove that $\mu_{gen}(M_0, M'_0) < \mu_{gen}(M_1, M'_1)$ and so $\mu_{gen}(M_0, M'_0) < \mu_{gen}(M, M')$. \hfill \square
Appendix D

ProVerif

D.1 Equivalence proofs

We say that a biprocess $P$ is uniform when $\text{fst}(P) \rightarrow Q_1$ implies that $P \rightarrow Q$ for some biprocess $Q$ with $\text{fst}(Q) \equiv Q_1$, and symmetrically for $\text{snd}(P) \rightarrow Q_2$. For the proof of Lemma 9.3, we rely on [BAF08, Theorem 1].

Lemma 9.3. Let $P_0$ be a closed biprocess. Suppose that, for all plain evaluation contexts $C$, all evaluation contexts $C'$, and all reductions $C[P_0] \rightarrow^* P$,

1. if $P \equiv C'[\text{out}(N,M),Q \mid \text{in}(N',x),R]$, then $\text{fst}(N) =_{\Sigma} \text{fst}(N')$ if, and only if, $\text{snd}(N) =_{\Sigma} \text{snd}(N')$; and

2. if $P \equiv C'[\text{let } x = D \text{ in } Q \text{ else } R]$, then $\text{fst}(D) \downarrow_{\Sigma} \text{fail}$ if, and only if, $\text{snd}(D) \downarrow_{\Sigma} \text{fail}.

Then $P_0$ satisfies observational equivalence.

Proof. We show that $P$ is uniform, then we conclude by [BAF08, Theorem 1]. Let us show that, if $\text{fst}(P) \rightarrow P'_1$ then there exists a biprocess $P'$ such that $P \rightarrow P'$ and $\text{fst}(P') \equiv P'_1$. The case for $\text{snd}(P) \rightarrow P'_2$ is symmetric.

By induction on the derivation of $\text{fst}(P) \rightarrow P'_1$, we first show that there exist $C$, $Q$, and $Q'_1$ such that $P \equiv C'[Q]$, $P'_1 \equiv \text{fst}(C)[Q]'$, and $\text{fst}(Q) \rightarrow Q'_1$ using one of the four process rules (Red 1/O), (Red Fun 1), (Red Fun 2), or (Red Repl): every step in this derivation trivially commutes with $\text{fst}$, except for structural steps that involve a parallel composition and a restriction, in case $a \in \text{fnames}(P)$ but $a \notin \text{fnames}(\text{fst}(P))$. In that case, we use a preliminary renaming from $a$ to some fresh $a' \notin \text{fnames}(P)$.

For each of these four rules, relying on a hypothesis of Corollary 9.2, we find $Q'$ such that $\text{fst}(Q') = Q'_1$ and $Q \rightarrow Q'$ using the corresponding biprocess rule:

(1) (Red 1/O): We have $Q = \text{out}(N,M),R \mid \text{in}(N',x),R'$ with $\vdash \text{fst}(N) =_{\Sigma} \text{fst}(N')$ and $Q'_1 = \text{fst}(R) | \text{fst}(R')[\text{fst}(M)/x]$. For $Q' = R | R'[M/x]$, we have $\text{fst}(Q') = Q'_1$ and, by hypothesis 1, $\text{snd}(N) =_{\Sigma} \text{snd}(N')$, hence $Q \rightarrow Q'$.

(2) (Red Fun 1): We have $Q = \text{let } x = D \text{ in } R \text{ else } R'$ with $\text{fst}(D) \downarrow_{\Sigma} M_1$ and $Q'_1 = \text{fst}(R)[M_1/x]$. By hypothesis 2 and Lemma 9.2, $\text{snd}(D) \downarrow_{\Sigma} M_2$ for some $M_2$. We take $Q' = R[\text{diff}[M_1,M_2]/x]$, so that $\text{fst}(Q') = Q'_1$ and $Q \rightarrow Q'$.

(3) (Red Fun 2): We have $Q = \text{let } x = D \text{ in } R \text{ else } R'$ with $\text{fst}(D) \downarrow_{\Sigma} \text{fail}$ and $Q'_1 = \text{fst}(R')$. By hypothesis 2, $\text{snd}(D) \downarrow_{\Sigma} \text{fail}$. We obtain $Q \rightarrow Q'$ for $Q' = R'$.

(4) (Red Repl): We have $Q = !R$ and $Q'_1 = \text{fst}(R) \mid !\text{fst}(R)$. We take $Q' = R \mid !R$, so that $\text{fst}(Q') = Q'_1$ and $Q \rightarrow Q'$.

To conclude, we take the biprocess $P' = C'[Q']$ and the reduction $P \rightarrow P'$. \qed
**D.1.1 Lemmas for modelling the equational theory**

The following lemma shows the soundness of $D' \downarrow^\Sigma \Sigma (M', \sigma', \phi')$ with respect to $D \downarrow^\Sigma M$. We say that a term evaluation is plain if it does not contain $\text{diff}$. Similarly, we define a plain message and plain may-fail message.

**Lemma D.1.** Let $\sigma$ be a closed substitution.

Let $D$ be a plain term evaluation. If $D \downarrow^\Sigma U$, then there exist $U', \sigma_1, \phi$, and $\sigma_1'$ such that

$D \downarrow^\Sigma (U', \sigma_1, \phi)$, $U = U'\sigma_1'$, $\sigma = \sigma_1\sigma_1'$ except on fresh variables introduced in the computation of $D \downarrow^\Sigma (U', \sigma_1, \phi)$, and $\sigma_1' \vDash \phi$.

Let $D_1, \ldots, D_n$ be plain term evaluations. If for all $i \in \{1, \ldots, n\}$, $D_i \downarrow^\Sigma M_i$, then there exist $U'_1, \ldots, U'_n$, $\sigma_1$, $\phi$ and $\sigma_1'$ such that $(D_1, \ldots, D_n) \downarrow^\Sigma (\{U'_1, \ldots, U'_n\}, \sigma_1, \phi)$, $U_i = U'_i\sigma_1'$ for all $i \in \{1, \ldots, n\}$, $\sigma = \sigma_1\sigma_1'$ except on fresh variables introduced in the computation of $(D_1, \ldots, D_n) \downarrow^\Sigma (\{U'_1, \ldots, U'_n\}, \sigma_1, \phi)$, and $\sigma_1' \vDash \phi$.

**Proof.** The proof is by mutual induction following the definition of $\downarrow^\Sigma$.

- Case $D = U'$: Take $\sigma_1 = \emptyset$, $\sigma_1' = \sigma$ and $\phi = \top$. Since $U = U'\sigma$ and $\sigma_1' \vDash \top$, we have the result.

- Case $D = \text{eval } h(D_1, \ldots, D_n)$: Since eval $h(D_1, \ldots, D_n) \downarrow^\Sigma U$, there exist $\text{eval } h(V_1, \ldots, V_n) \rightarrow V || \phi'$ in $\text{def}\Sigma (h)$ and $\sigma_m$ such that $D_i \downarrow^\Sigma V_i\sigma_m$, $U = V\sigma_m$ and $\sigma_m \vDash \phi'$.

By induction hypothesis, there exist $U'_i$, $\phi''_i$, $\sigma_1$, and $\sigma_1'$ such that $V_i\sigma_m = U'_i\sigma_1'$ for all $i \in \{1, \ldots, n\}$, $(D_1, \ldots, D_n) \downarrow^\Sigma (\{U'_1, \ldots, U'_n\}, \sigma_1, \phi''_n)$. $\sigma = \sigma_1\sigma_1'$ except on fresh variables introduced in the computation of $(D_1, \ldots, D_n) \downarrow^\Sigma (\{U'_1, \ldots, U'_n\}, \sigma_1, \phi'')$, and $\sigma_1' \vDash \phi'$.

Let $\sigma_u$ be the most general unifier of $U'_i$ and $V_i$ for $i \in \{1, \ldots, n\}$. (The substitution $\sigma_u$ exists since $V_i\sigma_m = U'_i\sigma_1'$.) Then eval $h(D_1, \ldots, D_n) \downarrow^\Sigma (V\sigma_u, \sigma_1\sigma_u, \phi''_n \land \phi\sigma_u)$. The substitution that maps variables of $V_i, V$ as $\sigma_m$ and other variables as $\sigma_1$ is a unifier of $U'_i$ and $V_i$, so there exists $\sigma''_u$ such that $\sigma_m = \sigma_u\sigma''_u$ on variables of $V_i, V$, and $\sigma_1' = \sigma_u\sigma''_u$ on other variables. With $\sigma_u \vDash \phi'$ and $\sigma_1' \vDash \phi'$, it also implies that $\sigma''_u \vDash \phi''_n \land \phi\sigma_u$.

Then $V\sigma_u\sigma''_u = V\sigma_m = U$ and $\sigma_1\sigma_u\sigma''_u = \sigma_1\sigma_1'$ except on fresh variables introduced in the computation of $(D_1, \ldots, D_n) \downarrow^\Sigma (\{U'_1, \ldots, U'_n\}, \sigma_1, \phi''_n)$ and variables of $V_i, V$, that is, fresh variables introduced in the computation of $D \downarrow^\Sigma (V\sigma_u, \sigma_1\sigma_u, \phi''_n \land \phi\sigma_u)$.

- Case $(D_1, \ldots, D_n)$: We have, for all $i \in \{1, \ldots, n\}$, $D_i \downarrow^\Sigma U_i$.

By induction hypothesis, there exist $U'_i$, $\phi$, $\sigma_1$, and $\sigma_1'$ such that $U_i = U'_i\sigma_1'$ for all $i \in \{1, \ldots, n-1\}$, $(D_1, \ldots, D_{n-1}) \downarrow^\Sigma (\{U'_1, \ldots, U'_{n-1}\}, \sigma_1, \phi)$. $\sigma = \sigma_1\sigma_1'$ except on fresh variables introduced in the computation of $(D_1, \ldots, D_{n-1}) \downarrow^\Sigma (\{U'_1, \ldots, U'_{n-1}\}, \sigma_1, \phi)$, and $\sigma_1' \vDash \phi$.

Then $D_n\sigma_1 = D_n\sigma_1\sigma_1'$, so $(D_1, \ldots, D_n) \downarrow^\Sigma U_n$. So by induction hypothesis, there exist $U'_n$, $\phi_2$, $\sigma_2$, and $\sigma_2'$ such that $D_n\sigma_1 \downarrow^\Sigma (U'_n, \sigma_2, \phi_2')$, $U_n = M'_n\sigma_2$, $\sigma'_2 = \sigma_2\sigma_2'$ except on fresh variables introduced in the computation of $D_n\sigma_1 \downarrow^\Sigma (U'_n, \sigma_2, \phi_2')$, and $\sigma_2' \vDash \phi_2'$. With $\sigma_1' \vDash \phi$, we deduce that $\sigma_2\sigma_2' \vDash \phi$, and so $\sigma'_2 \vDash \phi_2$.

Hence $(D_1, \ldots, D_n) \downarrow^\Sigma (\{U'_1\sigma_2, \ldots, U'_{n-1}\sigma_2, U'_n\}, \sigma_2\sigma_2', \phi_2 \land \phi')$, $\sigma'_2 \vDash \phi_2$, $U_i = U'_i\sigma_1' = (U'_i\sigma_2)\sigma'_2$ for all $i \in \{1, \ldots, n-1\}$, $U_n = U'_n\sigma_2'$, and $\sigma = \sigma_1\sigma_2' = \sigma_1\sigma_2\sigma_2'$ except on fresh variables introduced in the computation of $(D_1, \ldots, D_n) \downarrow^\Sigma (\{U'_1\sigma_2, \ldots, U'_{n-1}\sigma_2, U'_n\}, \sigma_2, \phi_2 \land \phi')$.

For the following lemmas, $w$ represents a variable that is either a message variable or a may-fail message variable.

**Lemma D.2.** Let $U'$ a plain ground may-fail message, $\sigma$ a closed substitution and $U$ a plain may-fail message. Assume that $U' = \Sigma U\sigma$. We have:

- if $U' = \text{fail}$ then $\text{addeval}(U)\sigma \downarrow^\Sigma U'$

- if $U'$ is a message and $\text{nf}_\Sigma(\{U'\} \cup \{w\sigma \mid w \in \text{fvars}(U)\})$ then $\text{addeval}(U)\sigma \downarrow^\Sigma U'$.
D.1. EQUIVALENCE PROOFS

Proof. Assume first that \( U' = \text{fail} \). In such a case, \( U \) can be either a may-fail variable or fail. In both cases, \( \text{addeval}(U) = U \) and so \( \text{addeval}(U)\sigma = U\sigma \). Moreover, \( U' = \text{fail} \) and \( U' =_\Sigma U\sigma \) imply that \( U' = U\sigma \) and so \( \text{addeval}(U)\sigma =_\Sigma U' \).

Assume now that \( U' \) is a message. The proof is by induction on \( U \).

- Case \( U = \text{fail} \): Impossible
- Case \( U = w \): We have \( w\sigma =_\Sigma U\sigma =_\Sigma U' \). Since \( \text{nf}_S\Sigma(\{w\sigma, U'\}) \), \( w\sigma = U' \). Moreover, \( \text{addeval}(U)\sigma = w\sigma\downarrow_\Sigma U' \).
- Case \( U = a \): Since \( U' =_\Sigma U\sigma \) and \( \text{nf}_S\Sigma(\{U'\}) \), we have \( U' = a \) by [BAF08] Lemma 4, so \( \text{addeval}(U)\sigma = a\downarrow_\Sigma U' \).
- Case \( U = f(M_1, \ldots, M_n) \): We have \( U' =_\Sigma M' =_\Sigma f(M_1, \ldots, M_n ) \) and \( \text{nf}_S\Sigma(\{U'\}) \) \( U \) is the term obtained by removing any destructor, and \( V \) and \( U \) are the sets of messages of \( U_1, \ldots, U_n, U \). If \( h(V_1, \ldots, V_n) \rightarrow V \) \( \downarrow_\Sigma \phi \) is in \( \text{def}_S(h) \), \( U_i =_\Sigma V_i\sigma \) for all \( i \in \{1, \ldots, n\} \). \( U =_\Sigma V\sigma \), \( \sigma \vdash \phi \), and \( \text{nf}_S\Sigma(U) \), then there exist \( h(V_1', \ldots, V_n') \rightarrow V' \) \( \downarrow_\Sigma \phi' \) in \( \text{def}_S(h) \) and \( \sigma' \) such that \( U_i = V_i\sigma' \) for all \( i \in \{1, \ldots, n\} \), \( U = V'\sigma' \) and \( \sigma' \vdash \phi' \).

Proof. Case 1: \( h \) is a constructor in \( \Sigma \). We do a case analysis on \( U \):

- \( U \) is a message: In such a case, by definition of a destructor \( U_1, \ldots, U_n \) are also messages and \( V = h(V_1, \ldots, V_n) \). Hence we have \( U =_\Sigma h(V_1, \ldots, V_n)\sigma =_\Sigma h(U_1, \ldots, U_n) \). The result follows from Property [S4]
- \( U = \text{fail} \): Otherwise, there exists \( i \in \{1, \ldots, n\} \) such that \( U_i = \text{fail} \). We know that \( h(u_1, \ldots, u_{i-1}, \text{fail}, u_{i+1}, \ldots, u_n) \rightarrow \text{fail} \) is in \( \text{def}_S(h) \). Hence, the result holds with \( \sigma' \) such that \( u_i\sigma' = U_j \), for all \( j \neq i \).

Case 2: \( h \) is a destructor in \( \Sigma \). By Property [S2] there exists \( \sigma_0 \) such that \( u\sigma_0 = u\sigma \) for all \( u \in \text{fvars}(V_1, \ldots, V_n, V) \) and \( \text{nf}_S\Sigma(U) \cup \{u\sigma_0 \mid u \in \text{fvars}(V_1, \ldots, V_n, V) \) and \( u\sigma_0 \) is a message\}. So \( U =_\Sigma V\sigma_0 \), \( U_i =_\Sigma V_i\sigma_0 \) for all \( i \in \{1, \ldots, n\} \) and \( \sigma_0 \vdash \phi \). By Lemma [D.2] \( \text{addeval}(V)\sigma_0 =_\Sigma U \) and \( \text{addeval}(V_i)\sigma_0 =_\Sigma U_i \) for all \( i \in \{1, \ldots, n\} \). By Lemma [D.1] there exist \( V'_1, \ldots, V'_n, V', \sigma, \phi \) and \( \sigma' \) such that \( \text{addeval}(V_1, \ldots, V_n, V) \downarrow_\Sigma ((V'_1, \ldots, V'_n, V'), \sigma_1, \phi') \), \( V_i\sigma' = U_i \) for all \( i \in \{1, \ldots, n\} \). Then \( h(V'_1, \ldots, V'_n) \rightarrow V' \) \( \downarrow_\Sigma \phi' \) is in \( \text{def}_S(h) \). \( V'_i\sigma' = U_i \) for all \( i \in \{1, \ldots, n\} \) and \( V'\sigma' = U \). Moreover, we know that \( \sigma_0 \vdash \phi \) hence \( \sigma' \vdash \phi \sigma_1 \) and so \( \sigma' \vdash \phi \sigma_1 \). Thus the result holds.

We define the function removeeval such that \( \text{removeeval}(D) = M \) where \( D \) is a term evaluation that contains no destructor, and \( M \) is the term obtained by removing any eval before the function symbols of \( D \).

Lemma D.4. Assume that \( D \) is a plain term evaluation that contains no destructor. If \( D \downarrow_\Sigma (U, \sigma, \phi) \) then \( \phi = \top \) and \( \text{removeeval}(D)\sigma =_\Sigma U \).

Assume that \( D_1, \ldots, D_n \) are plain term evaluations that contain no destructor. If we have \( (D_1, \ldots, D_n) \downarrow_\Sigma ((U_1, \ldots, U_n), \sigma, \phi) \) then \( \phi = \top \) and \( \text{removeeval}(D_i)\sigma =_\Sigma U_i \) for all \( i \in \{1, \ldots, n\} \).

Proof. The proof is by mutual induction following the definition of \( \downarrow_\Sigma \).
• Case $D = U$: We have $g = \emptyset$ and $\phi = \top$, so $U \sigma = \Sigma U$.

• Case $D = \text{eval} f(D_1, \ldots, D_n)$: We have eval($f(D_1, \ldots, D_n)$) $\downarrow^\prime (V \sigma_u, \phi \sigma_u)$ where $(D_1, \ldots, D_n)$ $\downarrow^\prime ((U_1, \ldots, U_n), \phi', \phi)$, $f$ is a constructor in $\Sigma$, $f(V_1, \ldots, V_n) \rightarrow V \parallel \phi'$ in $\text{def}_\Sigma^\prime (f)$ (with new variables), and $\sigma_u$ is the most general unifier of $(U_1, \ldots, (U_n, V_n))$. By definition of $\text{def}_\Sigma^\prime (f)$, we know that either $V = \text{fail}$ or $V$ is a message; and $\phi' = \top$.

Assume first that $V$ is a message. In such a case, $V_1, \ldots, V_n$ are messages too and by Property $\Sigma^\prime$, $f(V_1, \ldots, V_n) = \Sigma V$. By induction hypothesis, removeeval($D_i$)$\sigma' = \Sigma U_i$ for all $i = 1 \ldots n$ and $\phi' = \top$. Moreover we have $U_i \sigma_u = \Sigma V_i \sigma_u$. Hence we obtain removeeval(eval($f(D_1, \ldots, D_n)$)$\sigma' = \Sigma f(\Sigma U_1 \sigma_u, \ldots, \Sigma U_n \sigma_u)$ $\rightarrow \Sigma f(V_1 \sigma_u, \ldots, \Sigma V_n \sigma_u) = \Sigma V \sigma_u$.

• Case $(D_1, \ldots, D_n)$: We have $(D_1, \ldots, D_n)$ $\downarrow^\prime ((U_1, \ldots, U_n, \Sigma \sigma, \Sigma \phi), \phi'$ and $(D_1, \ldots, D_n)$ $\downarrow^\prime ((U_1, \ldots, U_n, \phi', \phi))$. Then by induction hypothesis, $\phi = \top$, $\phi = \top$, removeeval($D_i$)$\sigma = U_i$ for $i = 1 \ldots, n - 1$ and removeeval($D_i$)$\sigma' = \Sigma U_n$. Hence, removeeval($D_i$)$\Sigma \sigma' = \Sigma U_i \phi'$ for $i = 1 \ldots, n - 1$ and removeeval($D_i$)$\Sigma \sigma'$ $= U_n$.

The following lemma shows a completeness property: we do not lose precision by translating computation in $\Sigma$ into computations in $\Sigma'$. The proof of Lemma $\Sigma^\prime$ relies on Lemma $\Sigma\Sigma\Sigma$ for destructor applications.

Lemma D.5. If $h(U_1, \ldots, U_n) \rightarrow U \parallel \phi$ in $\text{def}_\Sigma (h)$ then there exists $h(U_1, \ldots, U_n) \rightarrow U' \parallel \phi'$ in $\text{def}_\Sigma^\prime (h)$ and $\sigma$ such that $U_i = \Sigma U'_i \sigma$ for all $i = 1 \ldots, n$, $U = \Sigma U' \sigma$ and for all $\sigma'$, $\sigma' = \phi'$ implies $\sigma' = \phi'$.

Proof. Case 1: $h$ is a constructor in $\Sigma$. According to the definition of $\text{def}_\Sigma (h)$, $\phi = \top$ and either $U = \text{fail}$ or $U$ is a message.

• $U = \text{fail}$: By definition of $\text{def}_\Sigma (h)$, we have $U_i = U'_i$, for all $i = 1 \ldots, n$, $U = U'$ and $\phi' = \top$.

• $U$ is a message: In such a case, $U_1, \ldots, U_n$ are all messages and by Property $\Sigma^\prime$ we have $h(U_1, \ldots, U_n) = \Sigma U$. Let $\sigma$ be defined by $x_i \sigma = U_i$ for all $i = 1 \ldots, n$, $U'_i = x_i$ for all $i = 1 \ldots, n$, $U' = h(x_1, \ldots, x_n)$ and $\phi' = \top$. We have $h(U_1, \ldots, U_n) \rightarrow U' \parallel \phi'$ in $\text{def}_\Sigma (h)$ because $h(x_1, \ldots, x_n) \rightarrow h(U_1, \ldots, U_n) \parallel \top$ is in $\text{def}_\Sigma (h)$. We also have $U_i = \Sigma U'_i \sigma$ for all $i = 1 \ldots, n$, $U = \Sigma h(U_1, \ldots, U_n) = \Sigma U' \sigma$, and for all $\sigma'$, $\sigma' = \top$.

Case 2: $h$ is a destructor in $\Sigma$. Then there exists $h(U_1, \ldots, U_n) \rightarrow U' \parallel \phi'$ in $\text{def}_\Sigma (h)$, such that addremoveeval($U'_1, \ldots, U'_n, U'$) $\downarrow^\prime ((U_1, \ldots, U_n, U), \sigma, \phi''')$ and $\phi = \phi' \sigma' \parallel \phi''$. By definition of the destructors of $\Sigma$, we know that $U'_1, \ldots, U'_n, U'$ do not contain any destructor. Hence by Lemma D.4, $U = \Sigma U' \sigma$, for all $i = 1 \ldots, n$, $U_i = \Sigma U'_i \sigma$ and $\phi'' = \top$. Hence, for all $\sigma'$, $\sigma' = \phi'$ implies $\sigma' = \phi'$ which implies $\sigma = \phi'$.

D.1.2 Proof of Lemmas 9.6 and 9.7

Lemma 9.7 is a consequence of the following lemma.

Lemma D.6. Let $g$ a destructor of $\Sigma$. $\text{def}_\Sigma (g)$ does not satisfy Property $\Sigma^\prime$ if and only if there exist $U_1, \ldots, U_n$ ground may-fail messages, two pair of rewrite rules $g(V_1, \ldots, V_n) \rightarrow V \parallel \phi$ and $g(V'_1, \ldots, V'_n) \rightarrow V' \parallel \phi'$ in $\text{def}_\Sigma (g)$, two substitution $\sigma, \sigma'$ such that:

• $U_i = V_i \sigma = V'_i \sigma'$ for all $i = 1 \ldots, n$

• $V \sigma = \text{fail}$ and $V' \sigma'$ is a message;

• $\sigma = \phi$ and $\sigma' = \phi'$
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Proof. We start by proving the right implication of the result. def$\Sigma$(g) does not satisfy Property$^2$ implies that there exists $U_1, \ldots, U_n$ ground may-fail messages such that $g(U_1, \ldots, U_n) \rightarrow \text{fail}$ and $g(U_1', \ldots, U_n') \rightarrow M$ for some message $M$. Hence there exists $g(V_1, \ldots, V_n) \rightarrow V || \phi$ and $g(V_1', \ldots, V_n') \rightarrow V' || \phi'$ in def$\Sigma$(g) and two substitutions $\sigma, \sigma'$ such that:

- $U_i = \Sigma V_i \sigma = \Sigma V_i' \sigma'$ for all $i \in \{1, \ldots, n\}$
- $V \sigma = \text{fail}$ and $V' \sigma' = M$;
- $\sigma \vdash \phi$ and $\sigma' \not\vdash \phi'$

Thanks to Property$^2$ there exists $U'_1, \ldots, U'_n, M'$ such that $U'_i = \Sigma U_i$ for all $i \in \{1, \ldots, n\}$, $M' = \Sigma M$ and if we denote $U$ is the set of messages of $U'_1, \ldots, U'_n, M'$, then $\text{nf}_\Sigma(U)$.

By application of Lemma D.5 on the two rewrite rules, $(U'_1, \ldots, U'_n, M')$ and $(U'_1, \ldots, U'_n, \text{fail})$, we have that there exist $g(V'_1, \ldots, V'_n) \rightarrow V^1 || \phi_1$ and $g(V'_1, \ldots, V'_n) \rightarrow V'^1 || \phi'_1$ in def$\Sigma$(g), two substitutions $\sigma_1, \sigma'_1$ such that:

- $U'_i = V'_i \sigma_1 = V'_i' \sigma'_1$ for all $i \in \{1, \ldots, n\}$
- $V'_i = \text{fail}$ and $V' \sigma_1 = M'$;
- $\sigma_1 \vdash \phi_1$ and $\sigma'_1 \not\vdash \phi'_1$

Hence the result holds.

We now prove the left implication of the result. We have $U_1, \ldots, U_n$ ground may-fail messages, $g(V_1, \ldots, V_n) \rightarrow V || \phi$ and $g(V'_1, \ldots, V'_n) \rightarrow V' || \phi'$ in def$\Sigma$(g) and two substitutions $\sigma, \sigma'$ such that: two substitution $\sigma, \sigma'$ such that:

- $U_i = V_i \sigma = V_i' \sigma'$ for all $i \in \{1, \ldots, n\}$
- $V \sigma = \text{fail}$ and $V' \sigma'$ is a message;
- $\sigma \vdash \phi$ and $\sigma' \not\vdash \phi'$

By Lemma D.5, we deduce that there exist $g(V'_1, \ldots, V'_n) \rightarrow V^1 || \phi_1$ and $g(V'_1, \ldots, V'_n) \rightarrow V'^1 || \phi'_1$ in def$\Sigma$(g), and two substitution $\sigma_1, \sigma'_1$ such that:

- $V'_i = V^1 \sigma_1$ and $V'_i = V'^1 \sigma'_1$ for all $i \in \{1, \ldots, n\}$. Thus we deduce that $U_i = \Sigma V'_i \sigma_1 = \Sigma V'_i' \sigma'_1$
- $V = V^1 \sigma_1$ and $V' = V'^1 \sigma'_1$. Thus we deduce fail = $V^1 \sigma_1$ and $V'^1 \sigma'_1$ is a message.
- for all $\sigma_0, \sigma_0 \vdash \phi$ implies $\sigma_1 \sigma_0 \vdash \phi_1$; and $\sigma_0 \not\vdash \phi'$ implies $\sigma'_1 \sigma_0 \not\vdash \phi'_1$. Thus we deduce $\sigma_1 \sigma_0 \vdash \phi_1$ and $\sigma'_1 \sigma_0 \not\vdash \phi'_1$.

We can deduce that $g(U_1, \ldots, U_n) \rightarrow \text{fail}$ and $g(U_1, \ldots, U_n) \rightarrow V'^1 \sigma'_1$ where $V'^1 \sigma'_1$ is a message and so we conclude that def$\Sigma$(g) do no satisfy Property$^2$.

Lemma D.7 is a consequence of the following lemma.

Lemma D.7. Let $g$ a destructor of $\Sigma$ or arity $n$. Let $x_1, \ldots, x_n$ fresh message variables. def$\Sigma$(g) does not satisfy Property$^2$ if and only if there exists $(U_1, \ldots, U_n)$, a set $\mathcal{I}$ and a closed substitution $\sigma$ such that:

- $U_i = \text{fail}$, for all $i \notin \mathcal{I}$; and $U_i = x_i$, for all $i \in \mathcal{I}$
- for all $g(V_1, \ldots, V_n) \rightarrow V || \phi$ in def$\Sigma$(g), if $\sigma_u$ is the most general unifier of $(V_1, \ldots, V_n)$ and $(U_1, \ldots, U_n)$ then $\sigma \vdash \forall z_i. [ V_i \sigma \neq \Sigma V_i \sigma_u \vee \neg \phi \sigma_u ]$ where $z$ are the variables of $V_1 \sigma_u, \ldots, V_n \sigma_u$. 

Proof. Assume first that \( \text{def}_2(g) \) does not satisfy Property [P2]. In such a case, there exists \( U'_1, \ldots, U'_n \) ground may-fail messages such that for all \( g(V_1, \ldots, V_n) \rightarrow V \ || \phi \) in \( \text{def}_2(g) \), if there exists a substitution \( \sigma' \) such that \( V_i \sigma' =_S U'_i \) for \( i = 1 \ldots n \) then \( \sigma' \not\models \phi \).

But since \( U'_i \) is ground for all \( i \in \{1, \ldots, n\} \) then either \( U'_i = \text{fail} \) or \( U'_i \) is a message. Let \( I \) be the subset of \( \{1, \ldots, n\} \) such that for all \( i \in I \), \( U'_i = \text{fail} \) and for all \( i \not\in I \), \( U'_i \) is a message. From \( I \) we define \( U'_1, \ldots, U'_n \) as expected. At last, we define \( \sigma = \{ x_i \rightarrow U'_i \mid i \in I \} \).

Let \( g(V_1, \ldots, V_n) \rightarrow V \ || \phi \) in \( \text{def}_2(g) \) such that \( \sigma_u \) is the most general unifier of \( (V_1, \ldots, V_n) \) and \( (U_1, \ldots, U_n) \). Thus \( V_i \sigma_u = U_i \sigma_u \) for all \( i \in \{1, \ldots, n\} \). Assume that there exists \( \sigma'' \) such that \( U'_i =_S V_i \sigma_u \sigma'' \) for all \( i \in \{1, \ldots, n\} \). Hence by hypothesis we have that \( \sigma_u \sigma'' \not\models \phi \) and so \( \sigma'' \not\models \phi \sigma_u \). Thus we conclude that \( \sigma \models \exists \tilde{z} \{ \forall i \in I x_i \not\in \Sigma \ V_i \sigma_u \lor \neg \phi \sigma_u \} \) where \( \tilde{z} \) are the variables of \( V_1 \sigma_u, \ldots, V_n \sigma_u \).

The proof of the left implication is similar. \( \square \)

### D.1.3 Simplifications of the formulas

These simplifications are adapted from those for testunif (from [Bla04]).

- **Conjunction**: \( \text{conjunction} \) transforms clauses of the form \( H \land \text{formula}(\phi_1 \land \phi_2) \rightarrow C \) as follows:
  \[
  H \land \text{formula}(\phi_1) \land \text{formula}(\phi_2) \rightarrow C
  \]

- **Unification of disequations**: \( \text{unifydiseq} \) transforms clauses of the form \( H \land \text{formula}(\forall \exists. [\bigvee_{i=1}^n p_i \neq l_i \lor \bigvee_{j=1}^m \exists y_j.q_j = q'_j]) \rightarrow C \) as follows. It tries to unify \((p_1, \ldots, p_n)\) and \((p'_1, \ldots, p'_m)\) modulo the equational theory. If this unification fails, then the clause becomes \( H \rightarrow C \). Otherwise, \( \text{unifydiseq} \) replaces the clause with
  \[
  H \land \bigwedge_{k=1}^\ell \text{formula}(\forall \exists. \bigvee_{i=1}^n x_i \neq x_i^k \land \bigvee_{j=1}^m \exists y_j.q_j \sigma_k = q'_j \sigma_k) \rightarrow C
  \]
  where \( \sigma_k = \{ x_i^k \mapsto x_i \sigma_k; \ldots; x_i^{k+\ell} \mapsto x_i \sigma_k \} \), for all \( k = 1 \ldots \ell \) are the most general unifiers of \((p_1, \ldots, p_n)\) and \((p'_1, \ldots, p'_m)\) modulo the equational theory and \( x_1^i, \ldots, x_i^{k+\ell} \) are variables of \((p_1, \ldots, p_n)\) and \((p'_1, \ldots, p'_m)\). In this unification, we assume that the variables of in the domain of \( \sigma_k \) do not occur in its image. This way, we don’t have trivial equation \( x = x \).

- **Remove universal variable**: \( \text{elimuniversal} \) transforms clauses of the form \( H \land \text{formula}(\forall \exists. y. \phi) \rightarrow C \), where \( y \) is not a variable of \( \phi \), as \( H \land \text{formula}(\forall \exists. \phi) \rightarrow C \). \( \text{elimuniversal} \) also transforms clauses of the form \( H \land \text{formula}(\forall \exists. y. [y \neq \phi \lor \phi]) \rightarrow C \) as \( H \land \text{formula}(\forall \exists. \phi ([y \neq \phi \lor \phi])) \). A symmetric rule exists for clauses of the form \( H \land \text{formula}(\forall \exists. y. [y \neq \phi \lor \phi]) \rightarrow C \). This simplification is always applied after \( \text{unifydiseq} \).

- **Unification of equation**: \( \text{unifyeq} \) transforms clauses of the form
  \[
  H \land \text{formula}(\forall \exists. \phi \lor \exists y. p = p') \rightarrow C
  \]
  as follows. It tries to unify \( p \) and \( p' \) modulo the equational theory. If this unification fails, then the clause becomes \( H \land \text{formula}(\forall \exists. \phi) \rightarrow C \). Otherwise, \( \text{unifyeq} \) replaces the clause with
  \[
  H \land \text{formula}(\forall \exists. \phi \lor \exists y. (x_1, \ldots, x_n) = (x_1 \sigma_1, \ldots, x_n \sigma_1)) \rightarrow C
  \]
  where \( \sigma_i = \{ x_i^1 \mapsto x_i \sigma_i; \ldots; x_i^k \mapsto x_i \sigma_i \} \), for all \( i = 1 \ldots n \) are the most general unifiers of \( p_1 \) and \( p_2 \) modulo the equational theory and \( x_1^i, \ldots, x_i^k \) are variables of \( p_1 \) and \( p_2 \).

- **Remove existential variables**: \( \text{elimexistential} \) transforms clauses of the form \( H \land \text{formula}(\forall \exists. \phi \lor \exists y. \{x_i\} \rightarrow C \) as follows: if \( I \) is the set of index \( i \) such that \( x_i \in \tilde{y} \), then
  \[
  H \land \text{formula}(\forall \exists. \phi \lor \exists \tilde{y}. \{x_i\}_{i \in I} \rightarrow C
  \]
  \[
  (x_{k_1}, \ldots, x_{k_m}) = (p_{k_1}, \ldots, p_{k_m}) \) \rightarrow C
  \]

These simplifications have been adapted from those for testunif (from [Bla04]).
where \( k_1, \ldots, k_n \) are index between 1 and \( n \) that are not in \( I \). A symmetric rule exists for formulas of the form \( H \land \text{formula}(\forall z. (\phi \lor \exists y. (p_1, \ldots, p_n) = (x_1, \ldots, x_n))) \rightarrow C \)

- Failed universal variables: \( \text{unifailed} \) transforms any clauses of the form \( H \land \text{formula}(\forall z. \bigvee_{j=1}^n \exists y_j. (x_1^j, \ldots, x_n^j) = (q_1^j, \ldots, q_n^j)) \rightarrow C \) as follows: if \( I \) is the set of indexes \( j \) such that any variables of \( (x_1^j, \ldots, x_n^j, q_1^j, \ldots, q_n^j) \) is not in \( z \), then

\[
H \land \text{formula}(\bigvee_{j \in I} \exists y_j. (x_1^j, \ldots, x_n^j) = (q_1^j, \ldots, q_n^j)) \rightarrow C
\]

- Development: \( \text{develop} \) transforms clauses of the form \( H \land \text{formula}(\phi_1 \lor \phi_2) \rightarrow C \) into two new clauses: \( H \land \text{formula}(\phi_1) \rightarrow C \) and \( H \land \text{formula}(\phi_2) \rightarrow C \).

- Application of substitution: \( \text{applysubs} \) transforms clauses of the form \( H \land \text{formula}(\exists y. (x_1, \ldots, x_n) = (q_1, \ldots, q_n)) \rightarrow C \) into \( H \sigma \rightarrow C \sigma \), where \( \sigma \) is the substitution \( \{x_1 \mapsto p_1, \ldots, x_n \mapsto p_n\} \).

- Detection of failed formula: \( \text{elimformula} \) removes clauses that contain the hypothesis \( \text{formula}(\bot) \).

### D.2 Proof of the Automatic Modification

This appendix provides the proofs of the results announced in Section 9.4.

#### D.2.1 Preliminary Lemmas

**Lemma D.8.** Let \( P, Q \) be processes. Suppose that, for all substitutions \( \sigma \) closing for \( P \) and \( Q \), \( P \sigma \approx Q \sigma \). Then, for all contexts \( C \) closing for \( P \) and \( Q \), \( C[P] \approx C[Q] \).

**Proof.** This lemma is fairly standard in process calculi. For example, [AG99, Appendix C.3] shows a similar result for the spi calculus. We give a proof for our calculus.

We rely on Definition 9.1 and use a relation \( \mathcal{R} \) defined by \( P_0 \mathcal{R} P'_0 \) if and only if

\[
P_0 \approx C'[P_1, \ldots, P_n] \text{ and } P'_0 \approx C'[P'_1, \ldots, P'_n]
\]

for some context \( C' \) such that no hole of \( C' \) is in evaluation position and for \( i = 1, \ldots, n \), for all substitutions \( \sigma \) closing for \( P_i \) and \( P'_i \), \( P_i \sigma \approx P'_i \sigma \).

We have that, for contexts \( C \) closing for \( P \) and \( Q \), \( C[P] \mathcal{R} C[Q] \). Indeed, if the hole of \( C \) is not in evaluation position, \( C[P] \approx C[Q] \), and for all substitutions \( \sigma \) closing for \( P \) and \( Q \), \( \sigma P \approx \sigma Q \). If the hole of \( C \) is in evaluation position, \( P \) and \( Q \) are closed, so \( P \approx Q \) by hypothesis, hence \( C[P] \approx C[Q] \), so letting \( P_0 = C[P] \) and \( P'_0 = C = C[Q] \) (\( C' \) is a context with no hole), we have \( P_0 \approx C', P'_0 \approx C', \) hence \( C[P] \mathcal{R} C[Q] \).

We show that \( \mathcal{R} \) satisfies the three conditions of Definition 9.1. Moreover \( \mathcal{R} \) is symmetric, so we can then conclude that \( \mathcal{R} \subseteq \approx \), which implies the desired equivalence.

**Condition 3 of Definition 9.1** Suppose \( P_0 \mathcal{R} P'_0 \), and let \( C \) be an evaluation context. \( P_0 \mathcal{R} P'_0 \) implies that there exists a context \( C' \), some processes \( P_1, \ldots, P_n, P'_1, \ldots, P'_n \) such that \( P_0 \approx C'[P_1, \ldots, P_n] \) and \( P'_0 \approx C'[P'_1, \ldots, P'_n] \). Hence, we have \( C[P_0] \approx C'[C'[P_1, \ldots, P_n]] \) and \( C[P'_0] \approx C'[C'[P'_1, \ldots, P'_n]] \) by Condition 3 of Definition 9.1. Since no hole of \( C' \) is in evaluation position, then no hole of \( C'[C'] \) is also in evaluation position. Hence, we deduce that \( C[P_0] \mathcal{R} C[P'_0] \).

**Condition 2 of Definition 9.1** We first show that, if \( C'[P_1, \ldots, P_n] \equiv Q_0 \) where \( C' \) is any context such that no hole of \( C'[C'] \) is in evaluation position, then \( C''[P'_1, \ldots, P'_n] \equiv C''[P'_1, \ldots, P'_n] \) and \( Q_0 = C''[P'_1, \ldots, P'_n] \) for some context \( C'' \) such that no hole of \( C'' \) is in evaluation position. The proof is done by induction on the derivation of \( C'[P_1, \ldots, P_n] \equiv Q_0 \).
Suppose that $P \rightarrow Q_0$ where $C'$ is any context such that no hole of $C'$ is in evaluation position, and for $i = 1, \ldots, n$, for all substitutions $\sigma$ closing for $P_i$ and $P'_i$, $P_i \equiv \sigma P'_i$, then $C'[P'_1, \ldots, P'_n] \rightarrow Q'_0 \equiv C'[Q'_1, \ldots, Q'_n]$ and $Q_0 \equiv C''[Q_1, \ldots, Q_n]$ for some context $C''$ and processes $Q_0, Q_1, \ldots, Q_n$ such that no hole of $C''$ is in evaluation position and for $i = 1, \ldots, n'$, for all substitutions $\sigma$ closing for $Q_i$ and $Q'_i$, $\sigma Q_i \approx \sigma Q'_i$. The proof is done by induction on the derivation of $C'[P_1, \ldots, P_n] \rightarrow Q_0$.

- Case (Red I/O): We have $C''[P_1, \ldots, P_n] = \text{out}(N, M).Q \mid \text{in}(N', x).P \rightarrow Q_0 = Q \mid P^{M/\sigma}$ with $N = \Sigma N'$. Since no hole of $C''$ is in evaluation position, we have $Q = C_1[P_i \in S]$ and $P = C_2[P(i \notin S)]$ for some contexts $C_1, C_2$ and some subset $S$ of $\{1, \ldots, n\}$, and $C''[P'_1, \ldots, P'_n] = \text{out}(N, M).C_1[P'_i \in S] \mid \text{in}(N', x).C_2[P'_i \notin S] \rightarrow C_1[P'_i \in S] \mid C_2[P'_i \notin S]$ for some context $C''$. We let $Q_1$ and $Q_i'$ be the processes $P_i$ and $P'_i$ for $i \in S$ and $P_i$ and $P'_i$ for $i \notin S$, such that the corresponding hole of $C_1$ or $C_2$ is not in evaluation position. We have for all substitutions $\sigma$ closing for $Q_i$ and $Q'_i$, $\sigma Q_i \approx \sigma Q'_i$, since that property is preserved by instantiation. We let $C'' = C_1[P_i \in S, \text{in evaluation position}] \mid C_2^{M/\sigma}[P'_i \in S]$ where only the holes not in evaluation position remain. We let $Q_0'' = C_1[P_i \in S] \mid C_2[P'_i \notin S]$ for some $Q''_0$. We have $Q_0 = C''[Q_1, \ldots, Q_n]$ and $C''[P_1, \ldots, P_n] \rightarrow Q_0'' \equiv C''[Q'_1, \ldots, Q'_n]$.

- Case (Red Fun 1): As in the case (Red I/O), the holes in the in branch are instantiated. The holes in the else branch disappear. The holes that become in evaluation position are handled as in (Red I/O).

- Case (Red Fun 2): The holes in the in branch disappear. The holes that become in evaluation position are handled as in (Red I/O).

- Case (Red Repl): The holes are duplicated.

- Cases (Red Par) and (Red Res): these cases follow immediately from the induction hypothesis.

- Case (Red Ξ): we use the property shown above for Ξ and the induction hypothesis.

Suppose that $P_0 \rightarrow Q_0$ and $P_0 \equiv P'_0$. We have $P_0 \approx C''[P_1, \ldots, P_n]$ and $P'_0 \approx C[P'_1, \ldots, P'_n]$ for some context $C'$ and processes $P_1, \ldots, P_n, P'_1, \ldots, P'_n$ such that no hole of $C'$ is in evaluation position and for $i = 1, \ldots, n$, for all substitutions $\sigma$ closing for $P_i$ and $P'_i$, $P_i \equiv \sigma P'_i$. By Condition 2 of Definition 9.1, $C'[P_1, \ldots, P_n] \rightarrow Q_0'$ and $Q_0 \approx Q'_0$ for some $Q_0'$. By the property above, $C''[P'_1, \ldots, P'_n] \approx C''[Q'_1, \ldots, Q'_n]$ and $Q_0'' = C''[Q_1, \ldots, Q_n]$ for some context $C''$ and processes $Q_1, \ldots, Q_n$, such that no hole of $C''$ is in evaluation position and for $i = 1, \ldots, n'$, for all substitutions $\sigma$ closing for $Q_i$ and $Q'_i$, $\sigma Q_i \approx \sigma Q'_i$. By Condition 2 of Definition 9.1, again, $P_0 \rightarrow Q_0''$ and $C''[Q'_1, \ldots, Q'_n] \approx Q_0''$ for some $Q'_0$. Hence $Q_0 \approx C''[Q_1, \ldots, Q_n]$ and $Q_0'' \approx C''[Q'_1, \ldots, Q'_n]$, so $Q_0 \equiv Q_0''$.

Condition 1 of Definition 9.1: Let $P \downarrow M$ if and only if $P = C[\text{out}(M', N), R]$ for some evaluation context $C$ that does not bind fnames($M$) and $M = \Sigma M'$. We first notice that, if $C'[P_1, \ldots, P_n] \downarrow M$ where no hole of $C'$ is in evaluation position, then $C'[P'_1, \ldots, P'_n] \downarrow M$, since the difference between $C'[P_1, \ldots, P_n]$ and $C'[P'_1, \ldots, P'_n]$ is only non-evaluation positions.

Suppose that $P_0 \downarrow M$ and $P_0 \equiv P'_0$. We have $P_0 \approx C''[P_1, \ldots, P_n]$ and $P'_0 \approx C''[P'_1, \ldots, P'_n]$ for some context $C''$ and processes $P_1, \ldots, P_n, P'_1, \ldots, P'_n$ such that no hole of $C''$ is in evaluation position and for $i = 1, \ldots, n$, for all substitutions $\sigma$ closing for $P_i$ and $P'_i$, $P_i \equiv \sigma P'_i$. By Condition 1 of Definition 9.1, $C'[P_1, \ldots, P_n] \downarrow M$, that is, $C'[P_1, \ldots, P_n] \rightarrow M$. By the properties proved regarding Condition 2, $C'[P'_1, \ldots, P'_n] \approx C''[Q'_1, \ldots, Q'_n]$ and $C''[Q_1, \ldots, Q_n] \downarrow M$ for some context $C''$ and processes $Q_1, \ldots, Q_n$, such that no hole of $C''$ is in evaluation position. Hence $C''[Q'_1, \ldots, Q'_n] \downarrow M$, so by Conditions 1 and 2 of Definition 9.1, $C'[P'_1, \ldots, P'_n] \downarrow M$. Since $C'[P'_1, \ldots, P'_n] \approx P_0$, we conclude that $P_0 \downarrow M$. □
Lemma D.9. Let $P, Q, R$ be processes. Let $a$ be a name, $x$ a variable, $M$ a term, and $D$ a term evaluation. We have that:

1. If $a \notin \mathsf{names}(P)$, then for all contexts $C$ closing for $P$, $C[P] \simeq C[\nu a.P]$.
2. For all contexts $C$ closing for $! P$, $C[! P] \simeq C[!! P]$.
3. For all contexts $C$ closing for $P^{M/x}$, $C[P^{M/x}] \simeq C[\mathsf{let} \ x = M \ in \ P \ else \ Q]$.
4. For all contexts $C$ closing for $P$, $C[P] \simeq C[\mathsf{let} \ x = \mathsf{fail} \ in \ Q \ else \ P]$.
5. For all contexts $C$ closing for $P_0 = \mathsf{let} \ x = D \ in \ \mathsf{fst}'(P) \ else \ \mathsf{snd}'(P)$, $C[P_0] \simeq C[\mathsf{let} \ x = \mathsf{eval glet}(D) \ in \ P^{\mathsf{eval glet}(x,D_1,D_2)/\mathsf{diff}[D_1,D_2]} \ else \ 0]$.
6. For all contexts $C$ closing for $(P | Q) | R$, $C[(P | Q) | R] \simeq C[P | (Q | R)]$.
7. If $x \notin \mathsf{fvars}(P) \cup \mathsf{fvars}(Q)$ then for all contexts $C$ closing for $let \ x = D \ in \ P \ else \ Q$, $C[\mathsf{let} \ x = D \ in \ P \ else \ Q] \simeq C[\mathsf{let} \ x = \mathsf{notfail}(D) \ in \ Q \ else \ P]$.

Proof. We first prove this result for processes that do not contain $\mathsf{diff}$. By applying the obtained result twice, once for the component $\mathsf{fst}$ and once for the component $\mathsf{snd}$, we obtain the same equivalence for processes that may contain $\mathsf{diff}$. By Lemma D.8 it is enough to show:

1. If $a \notin \mathsf{names}(P)$, then $P \simeq \nu a.P$.
2. $! P \simeq !! P$.
3. $P^{M/x} \simeq \mathsf{let} \ x = M \ in \ P \ else \ Q$.
4. $P \simeq \mathsf{let} \ x = \mathsf{fail} \ in \ Q \ else \ P$.
5. $\mathsf{let} \ x = D \ in \ \mathsf{fst}'(P) \ else \ \mathsf{snd}'(P) \simeq \mathsf{let} \ x = \mathsf{eval glet}(D) \ in \ P^{\mathsf{eval glet}(x,D_1,D_2)/\mathsf{diff}[D_1,D_2]} \ else \ 0$.
6. $P | Q \simeq Q | P$ and $(P | Q) | R \simeq P | (Q | R)$.
7. $\mathsf{let} \ x = D \ in \ P \ else \ Q \simeq \mathsf{let} \ x = \mathsf{equals}(D, \mathsf{fail}) \ in \ Q \ else \ P$

where $P$, $Q$, $R$ are closed processes, $M$ and $D$ are ground terms and term evaluation, except for $P$ in Item 3 in which $\mathsf{fvars}(P) \subseteq \{x\}$, for $Q$ in Item 4 in which $\mathsf{fvars}(Q) \subseteq \{x\}$, and for $P$ in Item 5 in which $\mathsf{fvars}((\mathsf{fst}'(P))) \subseteq \{x\}$ and $\mathsf{fvars}((\mathsf{snd}'(P))) = \emptyset$. Item 6 is obvious since $\equiv \simeq \approx$. Note that in Item 7, since $P$ and $Q$ are closed, $x \notin \mathsf{fvars}(P) \cup \mathsf{fvars}(Q)$. Let us prove the other cases by relying on Definition 9.1.

For Items 3 and 4, we use a relation $\mathcal{R}$ defined by $P_0 R P'_0$ if and only if

$$P_0 = C[P_1] \ and \ P'_0 = C[P'_1]$$

or

$$P_0 = C[P'_1] \ and \ P'_0 = C[P_1]$$

or

$$P_0 = P'_0$$

for some evaluation context $C$ and processes $P_1, P'_1$ such that $P_1 R_1 P'_1$ where

- in Item 3, $R_1$ is defined by $P^{M/x} R_1 \mathsf{let} \ x = M \ in \ P \ else \ Q$ for all $P, Q, x, M$;
- in Item 4, $R_1$ is defined by $P R_1 \mathsf{let} \ x = \mathsf{fail} \ in \ Q \ else \ P$ for all $P, Q, x$.

We show that $\mathcal{R}$ satisfies the three conditions of Definition 9.1. Moreover $\mathcal{R}$ is symmetric, so we can then conclude that $\mathcal{R} \subseteq \simeq$, which implies the desired equivalences.
\( \mathcal{R} \) obviously satisfies Condition 3 of Definition [6.1].

To show Condition 2 of Definition [6.1], we show that, if \( P_0 \rightarrow Q_0 \) and \( P_0 \mathcal{R} P_0' \), then there exists \( Q_0' \) such that \( Q_0 \mathcal{R} Q_0' \) and \( P_0' \rightarrow \ast Q_0' \).

If \( P_0 = C[P_1], P_0' = C[P'_1], \) and \( P_1 \mathcal{R}_1 P'_1 \), then we first reduce \( P'_1 \) into \( P_1 \), transforming let \( x = M \) in \( P \) else \( Q \) into \( P[M/x] \) (Item 3) and let \( x = \text{fail} \) in \( Q \) else \( P \) into \( P \) (Item 4). In this case, we have \( P_0' = C[P'_1] \rightarrow C[P_1] = P_0 \rightarrow Q_0 \). Taking \( Q_0' = Q_0 \), we have \( Q_0 \mathcal{R} Q_0' \) and \( P_0' \rightarrow \ast Q_0' \).

If \( P_0 = C[P'_1], P_0' = C[P_1], \) and \( P_1 \mathcal{R}_1 P'_1 \), we show the following.

1. If \( C[P'_1] \equiv P' \), then \( P' = C'[P'_1] \) and \( C[P_1] \equiv C'[P_1] \) for some evaluation context \( C' \), by induction on the derivation of \( C[P'_1] \equiv P' \).

2. If \( C[P'_1] \rightarrow P' \), then either \( P' = C'[P'_1] \) and \( C[P_1] \equiv C'[P_1] \), or \( P' = C'[P'_1] \) and \( C[P_1] \rightarrow C'[P_1] \), for some evaluation context \( C' \). The proof proceeds by induction of the derivation of \( C[P'_1] \rightarrow P' \):

   Case (Red I/O) is impossible.

   Case (Red Fun 1) can be applied only in Item 3. In this case, \( C[P'_1] = P'_1 \rightarrow P_1 \) and we take \( C' = [] \).

   Case (Red Fun 2) can be applied only in Item 4. In this case, \( C[P'_1] = P'_1 \rightarrow P_1 \) and we take \( C' = [] \).

   In case (Red Par), we have \( C[P'_1] = P \rightarrow R \rightarrow Q \rightarrow P' \) with \( P \rightarrow Q \). First case: \( R = C''[P'_1], C = P \rightarrow C'' \). Then \( P' = Q \rightarrow C''[P'_1] \). Let \( C' = Q \rightarrow C'' \). Then \( P' = C'[P'_1] \), and \( C[P_1] = P \rightarrow C''[P_1] \rightarrow Q \rightarrow C''[P'_1] \). Second case: \( C = C'' \rightarrow R \). Then \( C''[P'_1] \rightarrow Q \). By induction hypothesis, either \( Q = C''[P'_1] \) and \( C''[P_1] \equiv C''[P'_1] \), or \( Q = C''[P'_1] \) and \( C''[P_1] \rightarrow C''[P'_1] \), for some evaluation context \( C' \). Let \( C' = C'' \rightarrow R \). Either \( P' = Q \rightarrow R = C''[P'_1] \rightarrow R = C''[P'_1] \), or \( P' = Q \rightarrow R = C''[P'_1] \) and \( C[P_1] = C''[P_1] \rightarrow R = C''[P'_1] \rightarrow R = C''[P'_1] \).

   Case (Red Res) follows by induction hypothesis, similarly to the second case of (Red Par).

   Case (Red \( \equiv \)) follows using the property above for \( \equiv \) and the induction hypothesis.

We have \( C[P'_1] = P_0 \rightarrow Q_0 \), so either \( Q_0 = C'[P'_1] \) and \( C[P_1] \equiv C'[P_1] \), or \( Q_0 = C'[P'_1] \) and \( C[P_1] \rightarrow C'[P_1] \), for some evaluation context \( C' \). We let \( Q_0' = C'[P_1] \). In the first case, we have \( Q_0 = Q_0' \) so \( Q_0 \mathcal{R} Q_0' \) and \( P_0 = C[P_1] \rightarrow C'[P_1] = Q_0' \). In the second case, we have \( Q_0 = C'[P_1] \) and \( Q_0' = C'[P_1] \) so \( Q_0 \mathcal{R} Q_0' \) and \( P_0' = C[P_1] \rightarrow C'[P_1] = Q_0' \).

If \( P_0 = P_0' \), let \( Q_0' = Q_0 \). We have \( Q_0 \mathcal{R} Q_0' \) and \( P_0' = P_0 \rightarrow Q_0 = Q_0' \).

To show Condition 1, using Condition 2, it is enough to show that, if \( P_0 \mathcal{R} P_0' \) and \( P_0 \equiv C'[\text{out}(M', N), R] \) for some evaluation context \( C' \) that does not bind \( \text{fnames}(M) \) and \( M' \equiv \Sigma M' \), then \( P_0' \downarrow M \).

If \( P_0 = C[P_1], P_0' = C[P_1], \) and \( P_1 \mathcal{R}_1 P'_1 \), we have \( P_0' = C[P'_1] \rightarrow C[P_1] = P_0 \) hence \( P_0' \downarrow M \).

If \( P_0 = C[P'_1], P_0' = C[P_1], \) and \( P_1 \mathcal{R}_1 P'_1 \), we have \( P_0 \equiv C'[\text{out}(M', N), R] \). By Property 1 shown above for \( \equiv, C'[\text{out}(M', N), R] = C'[P'_1] \) and \( C[P_1] \equiv C'[P_1] \) for some \( C' \). Hence there is an evaluation context \( C'' \) that does not bind \( \text{fnames}(M) \) such that \( C'[\text{out}(M', N), R] = C''[P'_1] \rightarrow C''[P_1, \text{out}(M', N), R] \), thus \( P_0' \equiv C''[P_1, \text{out}(M', N), R] \) and so \( P_0' \downarrow M \).

If \( P_0 = P_0' \), the result is obvious.

For Item 5, we define the relation \( \mathcal{R} \) by \( P_0 \mathcal{R} P_0' \) if and only if

\[
P_0 = C[\text{let } x = D \text{ in } \text{fst}'(P) \text{ else } \text{snd}'(P)] \text{ and } \]

\[
P_0' = C[\text{let } x = \text{eval glet}(D) \text{ in } P[\text{eval glet}(x, D_1, D_2) / \text{diff}(D_1, D_2) \text{ else } 0] \]

for some evaluation context \( C \), variable \( x \), term evaluation \( D \), and process \( P \).
or

\[ P_0 = \text{fst}'(P)\{M/\_\} \text{ and } P'_0 = P'\{\text{eval getin}(M, D_1, D_2)/\text{diff}(D_1, D_2)\} \text{ for some } P \text{ and } M \]

or

\[ P_0 = \text{snd}'(P) \text{ and } P'_0 = P'\{\text{eval getin}(c, D_1, D_2)/\text{diff}(D_1, D_2)\} \text{ for some } P \]

or the symmetric obtained by swapping \( P_0 \) and \( P'_0 \). We show let \( x = D \) in \( \text{fst}'(P) \) else \( \text{snd}'(P) \) \( \approx \) let \( x = \text{eval getin}(D) \) in \( P'\{\text{eval getin}(x, D_1, D_2)/\text{diff}(D_1, D_2)\} \) else \( 0 \), by proving that \( \mathcal{R} \) satisfies the three conditions of Definition 9.1, similarly to the proof we have done for Items 3 and 4.

For Item 1, we define the relation \( \mathcal{R} \) by \( P_0 \mathcal{R} P'_0 \) if and only if \( \nu a.P_0 \equiv P'_0 \) and \( \nu a.P'_0 \equiv P_0 \) for some \( a \notin \text{names}(P_0) \) or \( a \notin \text{names}(P'_0) \) respectively. We show \( P \approx \nu a.P \), by proving that \( \mathcal{R} \) satisfies the three conditions of Definition 9.1.

For Item 2, we define the relation \( \mathcal{R} \) by \( P_0 \mathcal{R} P'_0 \) if and only if

\[ P_0 \equiv C[\text{fst}(P)] \text{ and } P'_0 \equiv C[\text{fst}(P)] \]

or

\[ P_0 \equiv C[\text{snd}(P)] \text{ and } P'_0 \equiv C[\text{snd}(P)] \]

for some evaluation context \( C \) and process \( P \). We show \( !P \approx !P \), by proving that \( \mathcal{R} \) satisfies the three conditions of Definition 9.1.

The proof follows a strategy similar to the proof of Items 3 and 4. For Items 1 and 2, some details are however more complex, because the structural equivalence may modify \( \nu a.P \) and \( !P \) or \( |P| \). For instance, to show Condition 2 of Definition 9.1 for Item 1, we need to show that, if \( P_0 \rightarrow Q_0 \) and \( P_0 \equiv \nu a.P'_0 \), then there exists \( Q'_0 \) such that \( Q_0 \equiv \nu a.Q'_0 \) and \( P'_0 \rightarrow Q'_0 \). Such a result is fairly standard in process calculi and can be proved by showing a series of lemmas decomposing reduction of \( \nu a.P \) and \( P \) | \( Q \), using a labeled semantics.

For Item 7, we define the relation \( \mathcal{R} \) by \( P_0 \mathcal{R} P'_0 \) if and only if

\[ P_0 = C[\text{let } x = D \text{ in } P \text{ else } Q] \text{ and } P'_0 = C[\text{let } x = \text{notfail}(D) \text{ in } Q \text{ else } P] \]

for some evaluation context \( C \), variable \( x \), term evaluation \( D \), and processes \( P, Q \) such that \( x \notin \text{fears}(P) \cup \text{fears}(Q) \)

or

\[ P_0 = P'_0 \]

or the symmetric obtained by swapping \( P_0 \) and \( P'_0 \). We show let \( x = D \) in \( P \) else \( Q \approx \text{let } x = \text{notfail}(D) \text{ in } Q \text{ else } P \), by proving that \( \mathcal{R} \) satisfies the three conditions of Definition 9.1, similarly to the proof we have done for Items 3 and 4. It relies on the fact that if \( D \downarrow \Sigma M \) then \( \text{notfail}(D) \downarrow \Sigma \text{fail} \), and if \( D \downarrow \Sigma \text{fail} \) then \( \text{notfail}(D) \downarrow \Sigma C_0 \) which is a message.

\[ \square \]

D.2.2 Proofs for the merge function

Lemma 9.8. Let \( P \) and \( P' \) be two biprocesses. If \( \text{merge}(P, P') = Q \), then:

- For all contexts \( C \) closing for \( P \), \( C[P] \approx C[\text{fst}(Q)] \);
- For all contexts \( C \) closing for \( P' \), \( C[P'] \approx C[\text{snd}(Q)] \).

Proof. Let \( P_0, P'_0 \) be two biprocesses. We prove the result by induction on \( P_0 \) and \( P'_0 \). We do a case analysis on the rules of Figure 9.3.

Case [Mnil]: Trivial.

Case [Mout]: We have \( P_0 = \text{out}(M, N).P \) and \( P'_0 = \text{out}(M', N').P' \). Let \( C \) be a context closing for \( P_0 \). We show that \( C[P_0] \approx C[\text{fst}(\text{merge}(P_0, P'_0))] \), that is, \( C[\text{out}(M, N).P] \approx C[\text{let } x = M \text{ in } \text{let } x' = \text{out}(M', N').P' \text{ in } P] \).

\[ \square \]
Let $C_1 = C[\text{let } x = M \text{ in } x'] = N$ in $\text{out}(x, x')$. By induction hypothesis on $\text{merge}(P, P')$, $C_1[|P|] \approx C_1[\text{fst}'(\text{merge}(P, P'))]$ so we just have to show that $C[\text{out}(M, N, P)] \approx C[\text{let } x = M \text{ in } x'] \approx N$ in $\text{out}(x, x').P$. This follows by two applications of Lemma [D.9], Item 3.

By symmetry, for all contexts $C$ closing for $P_0'$, $C[P_0'] \approx C[\text{snd}'(\text{merge}(P_0, P_0'))]$.

**Case [Min]:** This case is similar to the case [Mout].

**Case [Mpar]:** We have $P_0 = P_1 | \ldots | P_n$ and $P_0' = P_1' \ldots P_n'$ Furthermore, there exists a permutation $(i_k)_{k=1..n}$ of $(1, \ldots, n)$ such that $\text{merge}(P_0, P_0') = Q_1 \ldots Q_n$, with $Q_k = \text{merge}(P_k, P_k')$, for $k = 1..n$. Let $C$ be a context closing for $P_0$. Let $C_k = C[\text{fst}'(Q_1) \ldots \text{fst}'(Q_{k-1}) | \text{fst}'(Q_k)]$.

Since $C$ is closing for $P_0$, we that $C_k$ is closing for $P_k$. By induction hypothesis on $Q_k$, we deduce that $C_k[P_k] \approx C_k[\text{fst}'(Q_k)]$. Moreover, $C_k[\text{fst}'(Q_k)] = C_{k+1}[P_{k+1}]$.

Hence, with a simple induction on $n$, we deduce that $C[P_0] \approx C[\text{fst}'(\text{merge}(P_0, P_0'))]$.

Using a similar proof and Lemma [D.9], Item 6 to permute the elements of the parallel composition, we obtain that $C[P_0'] \approx C[\text{snd}'(\text{merge}(P_0, P_0'))]$, for all contexts $C$ closing for $P_0'$.

**Case [Mres]:** We have $P_0 = va.P$ and $a \notin \text{fnames}(P_0')$. Let $C$ be a context closing for $va.P$.

By induction hypothesis on $\text{merge}(P, P_0)$, $C[va.P] \approx C_1[va.\text{fst}'(\text{merge}(P, P_0))]$. Hence, $C[P_0] \approx C[\text{fst}'(\text{merge}(P_0, P_0'))]$.

Let $C$ be a context closing for $P_0$. Since $a \notin \text{fnames}(P_0)$, by Lemma [D.9], Item 1, $C[P_0] \approx C[va.P_0]$. By induction hypothesis on $\text{merge}(P, P_0)$, we have $C[va.P_0] \approx C[va.\text{snd}'(\text{merge}(P, P_0))]$. Hence we obtain the desired result: $C[P_0'] \approx C[\text{snd}'(\text{merge}(P_0, P_0'))]$.

**Case [Mprel]:** We have $P_0 = !va_1 \ldots va_n.P$ and $P_0' = !P'$. Thanks to our induction hypothesis on $\text{merge}(|P|, P_0')$, we have that, for all contexts $C$ closing for $P_0$, $C[P_0] \approx C[\text{fst}'(\text{merge}(P_0, P_0'))]$.

Let $C$ be a context closing for $P_0$. We have $C[P_0] = C[!]P' \approx C[!]P'$ by Lemma [D.9], Item 2, so $C[P_0'] \approx C[va_1 \ldots va_n.!]P'$ by $n$ applications of Lemma [D.9], Item 1. Let $C = C[va_1 \ldots va_n.]$. By induction hypothesis on $\text{merge}(|P|, P_0)$, $C[!]P' \approx C[\text{snd}'(\text{merge}(|P|, P_0'))]$, so $C[P_0'] \approx C[va_1 \ldots va_n.\text{snd}'(\text{merge}(|P|, P_0'))] = C[\text{snd}'(\text{merge}(P_0, P_0'))]$.

**Case [Mlet]:** This case follows immediately by induction hypothesis.

**Case [Mlet1]:** In this case, we have $P_0 = \text{let } x = D \text{ in } P_1$ else $P_2$ and $P_0' = \text{let } x' = D' \text{ in } P_1'$ else $P_2'$. Let $C$ be a context closing for $P_0$. Since $y$ is a fresh variable, we have that $C[P_0] \approx C[\text{let } x = D \text{ in } P_1{y/x}]$ else $P_2$.

By induction hypothesis on both $Q_1 = \text{merge}(P_1{y/x}, P_1'$) and $Q_2 = \text{merge}(P_2, P_2')$, we obtain that $C[\text{let } y = D \text{ in } P_1{y/x}]$ else $P_2$ $\approx C[\text{let } y = D \text{ in } \text{fst}'(Q_1)]$ else $P_2$.

$\approx C[\text{let } y = D \text{ in } \text{fst}'(Q_1)]$ else $\text{fst}'(Q_2)$. Since $\text{fst}'(\text{diff}'[D, D']) = D$, we obtain that $C[P_0] \approx C[\text{fst}'(\text{merge}(P_0, P_0'))]$.

By symmetry, we obtain that, for all contexts $C$ closing for $P_0$, $C[P_0] \approx C[\text{snd}'(\text{merge}(P_0, P_0'))]$.

**Case [Mlet2]:** We have $P_0 = \text{let } x = D \text{ in } P_1$ else $P_2$ and $P_0' = \text{let } x' = D' \text{ in } P_1'$ else $P_2'$. Let $C$ be a context closing for $P_0$. Since $y$ is a fresh variable, we have that $C[P_0] \approx C[\text{let } y = D \text{ in } P_1{y/x}]$ else $P_2$.

By induction hypothesis on both $Q_1 = \text{merge}(P_1{y/x}, P_1')$ and $Q_2 = \text{merge}(P_2, P_2')$, we obtain that $C[\text{let } y = D \text{ in } P_1{y/x}]$ else $P_2$ $\approx C[\text{let } y = D \text{ in } \text{fst}'(Q_1)]$ else $P_2$.

$\approx C[\text{let } y = D \text{ in } \text{fst}'(Q_1)]$ else $\text{fst}'(Q_2)$. Since $\text{fft}'(\text{diff}'[D, \text{notafi}'(D')]) = D$, we obtain that $C[P_0] \approx C[\text{fst}'(\text{merge}(P_0, P_0'))]$.

Consider $C$ a context closing for $P_0$. Thanks to Lemma [D.9], Item 7, we have that $C[P_0] \approx C[\text{let } x' = \text{notafi}'(D') \text{ in } P_2' \text{ else } P_1']$.

By induction hypothesis on both $Q_1 = \text{merge}(P_1{y/x}, P_1')$ and $Q_2 = \text{merge}(P_2, P_2')$, we obtain that $C[\text{let } x' = \text{notafi}'(D') \text{ in } P_2' \text{ else } P_1'] \approx C[\text{let } x' = \text{notafi}'(D') \text{ in } \text{snd}'(Q_1)]$ else $P_1'$. Since $\text{snd}'(\text{diff}'[D, \text{notafi}'(D')]) = \text{notafi}'(D')$, we obtain that $C[P_0] \approx C[\text{snd}'(\text{merge}(P_0, P_0'))]$.

**Case [Mlet3]:** We have $P_0 = \text{let } x = D \text{ in } P_1$ else $P_2$. Let $C$ be a closing context for $P_0$. Since $\approx$ is closed under renaming and $y$ is a fresh variable, we have that $C[P_0] \approx C[\text{let } y = D \text{ in } P_1{y/x}]$ else $P_2$.

By induction hypothesis on $Q = \text{merge}(P_1{y/x}, P_0)$ with the context $C[\text{let } y = D \text{ in } \text{fst}'(Q_1)]$ else $P_2$, we obtain that $C[P_0] \approx C[\text{let } y = D \text{ in } \text{fst}'(Q_1)]$ else $P_2$. Since
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Let $C$ be a context for closing $D$. Since $y$ is a fresh variable and not a variable of $P_0$, by Lemma 17.9. Item 3, $C[P_0] = C[\text{merge}(P_0, P_0)]$. By induction hypothesis on $Q = \text{merge}(P_{\text{let}}x, P_0)$ with the context $C[\text{let } y = c_0 \text{ in } P_0]$ else $P_2$), we obtain that $C[\text{let } y = c_0 \text{ in } P_0] = C[\text{let } y = c_0 \text{ in } P_0]$ else $P_2) = C[\text{merge}(P_0, P_0)]$.

Case (Mlet4): We have $P_0 = \text{let } x = D \text{ in } P_1 \text{ else } P_2$. Let $C$ be a context for closing $P_0$. Since $\approx$ is closed under renaming and $y$ is a fresh variable, we have that $C[P_0] = C[\text{let } y = D \text{ in } P_1]$ else $P_2)$. By induction hypothesis on $Q = \text{merge}(P_{\text{let}}x, P_0)$ with the context $C[\text{let } y = D \text{ in } P_1]$ else $P_2) = [\text{let } y = c_0 \text{ in } P_0]$ else $P_2)$, we obtain that $C[\text{let } y = c_0 \text{ in } P_0] = C[\text{let } y = c_0 \text{ in } P_0] \approx C[\text{merge}(P_0, P_0)]$.

Case (Sin): Let $C$ be a context for closing $P_0$. Thanks to Lemma 17.9. Item 4, we deduce that $C[P_0] = C[\text{merge}(P_0, P_0)]$.

D.2.3 Proofs for the simpl Function

Lemma 9.9. Let $P$ be a biprocess. For all contexts $C$ closing for $P$, $C[P] = C[\text{simpl}(P)]$.

Proof. Let $P_0$ be a biprocess. We prove by induction on $P_0$ that, for all contexts $C$ closing for $P_0$, $C[P_0] = C[\text{simpl}(P_0)]$. We do a case analysis on the rules of Figure 9.7.

Case (Sin) Trivial.

Case (Sout): We have $P_0 = \text{out}(M, N).P$ and $\text{simpl}(P_0) = \text{out}(M, N).\text{simpl}(P)$. Let $C$ be a context for closing $P_0$. Let $C = C[\text{out}(M, N)]$. We have that $C[P_0] = C[P_1] \approx C[\text{simpl}(P)]$.

Cases (Sin), (Sres) and (Srepl) Proof similar to case (Sout).

Case (Smerge): We have $P_0 = \text{let } x = D \text{ in } P \text{ else } P'$. Let $Q' = \text{merge}(\text{simpl}(P), \text{simpl}(P'))$ and $Q = Q'[\text{eval glet}(D, D_1, D_2) / D]$. Thanks to Lemma 17.3. Item 5, we deduce that $C[\text{let } x = D \text{ in } \text{simpl}(Q') \text{ else } \text{snd}(Q')] = C[\text{let } x = \text{eval glet}(D) \text{ in } Q \text{ else } 0]$.

Furthermore, by induction hypothesis on $P$ and Lemma 17.3. Item 5, with the context $C[\text{let } x = D \text{ in } \text{simpl}(Q') \text{ else } \text{snd}(Q')]$, we obtain $C[\text{let } x = D \text{ in } \text{simpl}(Q') \text{ else } \text{snd}(Q')] \approx C[\text{let } x = D \text{ in } \text{simpl}(Q') \text{ else } \text{snd}(Q')] = C[\text{let } x = D \text{ in } \text{simpl}(Q') \text{ else } \text{snd}(Q')]$.

By combining the two equivalences, we conclude that $C[P_0] = C[\text{let } x = D \text{ in } \text{simpl}(Q') \text{ else } \text{snd}(Q')]$.