

Projet VALMEM
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Analyse de SPSMALL avec IMITATOR 2

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Outline

1 IMITATOR II

- Principle
- Features
- Implementation

2 Analysis of the SPSMALL Memory

3 Future Works

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Inputs and Outputs



The General Idea of Our Method

Start with $K_0 = \text{True}$

REPEAT

- 1 Compute the set S of reachable parametric states under K_0
- 2 Refine K_0 by removing a π_0 -incompatible state from S
 - ▶ Select a π_0 -incompatible state (q, C) within S (i.e., $\pi_0 \not\models C$)
 - ▶ Select a π_0 -incompatible inequality J within C (i.e., $\pi_0 \not\models J$)
 - ▶ Add $\neg J$ to K_0

UNTIL no more π_0 -incompatible state in S

The Algorithm

Algorithm 1: *InverseMethod*(\mathcal{A}, π_0)

input : A PTA \mathcal{A} of initial state s_0

input : Reference point π_0 of the parameters

output: Constraint K_0 on the parameters

1 $i \leftarrow 0$; $K_0 \leftarrow \text{True}$; $S \leftarrow \{s_0\}$

2 **while** *True* **do**

3 **while** *there are π_0 -incompatible states in S* **do**

4 Select a π_0 -incompatible state (q, C) of S (i.e., s.t. $\pi_0 \not\models C$);

5 Select a π_0 -incompatible J in C (i.e., s.t. $\pi \not\models J$);

6 $K_0 \leftarrow K_0 \wedge \neg J$;

7 $S \leftarrow \bigcup_{j=0}^i \text{Post}_{\mathcal{A}(K_0)}^j(\{s_0\})$;

8 **if** $\text{Post}_{\mathcal{A}(K_0)}(S) = \emptyset$ **then return** $K_0 \leftarrow \bigcap_{(q,C) \in S} (\exists X : C)$

9 $i \leftarrow i + 1$;

10 $S \leftarrow S \cup \text{Post}_{\mathcal{A}(K_0)}(S)$; // $S = \bigcup_{j=0}^i \text{Post}_{\mathcal{A}(K_0)}^j(\{s_0\})$

Features

- Improved Features

- ▶ Optimization of the *InverseMethod* algorithm
 - ★ Do not start from the beginning at each iteration, but simply update the reachable states
 - ★ Increase speed
- ▶ Dynamic computation of the reachable states
 - ★ Allow to treat more automata in parallel
 - ★ Increase speed

- New Features

- ▶ Computation of the *traces* in both instantiated and parametric analysis
- ▶ Implementation of a *cartography algorithm* (work in progress)

Implementation

- New standalone tool
 - ▶ About 8000 lines of code
 - ▶ No call to HYTECH
 - ▶ Use of a standard [library for polyhedra](#) (Apron)
- Language: [OCaml](#)
 - ▶ Safety
 - ▶ Various facilities to build compilers
 - ▶ Interface with external libraries (Apron, PPL)

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Abstract Model

- Model considered in the *Blueberry* project
 - ▶ Model built manually
 - ▶ File `spsmall_blueb_lsv`
- Abstraction of the memory for the write operation
 - ▶ 10 automata, 10 clocks, 26 parameters, 450 lines of code
- Constraint generated by IMITATOR II in 1 second (31 states, 30 transitions)
 - ▶ To be compared with 1 hour and 20 minutes using IMITATOR
- After projection onto T_{setup}^D and T_{setup}^{Wen} :

$$\begin{array}{l}
 110 \geq T_{setup}^D \\
 \wedge T_{setup}^{Wen} + 61 > T_{setup}^D \\
 \wedge 54 > T_{setup}^{Wen} \\
 \wedge T_{setup}^{Wen} > 46 \\
 \wedge T_{setup}^D > 99
 \end{array}$$

Generated Model

- **Generated model**
 - ▶ File `lsv`
 - ▶ Automatically generated by LIP6
 - ▶ 28 automata, 28 clocks, 62 parameters, 32 discrete variables, 1500 lines of code
- File successfully parsed and treated by IMITATOR II
- **Inverse method fails** after about 20 iterations (out of memory)
 - ▶ Too many states?
 - ▶ Bad representation of the constraints?

Full SPSMALL 1*2

- Full SPSMALL memory 1*2
 - ▶ File `sp_1x2_md_no`
 - ▶ Automatically generated by LIP6
 - ▶ 101 automata, 101 clocks, 200 parameters, 130 discrete variables, more than 6000 lines of code
- File successfully parsed by IMITATOR II
- Conversion to the abstract structure fails
 - ▶ Most probably a bad representation of the constraints (matrices)
 - ▶ Solution: use [polyhedra](#) instead of matrices

Future Works

- Improve the generated constraint
 - ▶ Use an extension of IMITATOR II allowing to get a maximal constraint
- Improve IMITATOR II
 - ▶ More efficient representation of the polyhedra (PPL?)
- In the VALMEM project
 - ▶ Analyze bigger parts of the SPSMALL memory
 - ▶ Fully automated analysis from the transistor level to the constraint K_0