# Reducing Equational Theories for the Decision of Static Equivalence* 

Steve Kremer ${ }^{1}$, Antoine Mercier ${ }^{1}$, and Ralf Treinen ${ }^{2}$<br>${ }^{1}$ LSV, ENS Cachan, CNRS, INRIA, France<br>${ }^{2}$ PPS, Université Paris Diderot, CNRS, France


#### Abstract

Static equivalence is a well established notion of indistinguishability of sequences of terms which is useful in the symbolic analysis of cryptographic protocols. Static equivalence modulo equational theories allows a more accurate representation of cryptographic primitives by modelling properties of operators by equational axioms. We develop a method that allows in some cases to simplify the task of deciding static equivalence in a multi-sorted setting, by removing a symbol from the term signature and reducing the problem to several simpler equational theories. We illustrate our technique at hand of bilinear pairings.


## 1 Introduction

Many formal models for analyzing cryptographic protocols have been developed over the last thirty years. Among them we find logical or symbolic models, based on the seminal ideas of Dolev and Yao [11], which represent cryptographic primitives in an abstract way. This is justified by the so-called perfect cryptography assumption which states that the intruder has no means to break the cryptographic primitives themselves, and that he can hence break security only by exploiting logical flaws in the protocol.

In symbolic models, messages of the protocol are represented by terms in an abstract algebra. The motivation this abstraction was the simplification and even automation of the analysis and the proof of security protocols. Since the assumption of perfect cryptography is not always realistic, some properties of cryptographic primitives (a survey can be found in [10]) have been taken into account in logical models by the means of equational theories on the terms.

In this paper we concentrate on static equivalence, a standard notion of indistinguishability of sequences of terms originating from the applied pi calculus [3]. Intuitively static equivalence asks whether or not an attacker can distinguish between two sequences of messages, later called frames, by exhibiting a relation which holds on one sequence but not on the other. Static equivalence provides an elegant means to express security properties on pieces of data, for instance those observed by a passive attacker during the run of a protocol. In the context of active attackers, static equivalence has also been used to characterize process equivalences [3] and off-line guessing attacks [9, 5]. There now exist exact [2],

[^0]and approximate [1] algorithms to decide static equivalence for a large family of equational theories.

Our ultimate goal is to develop combination methods for deciding static equivalence, that is to develop means to algorithmically reduce a static equivalence problem modulo some equational theory to some other static equivalence problems modulo simpler equational theories.

Contribution of this paper. We exhibit criteria on equational theories allowing simplifications for the decision of static equivalence. The kind of simplification we describe is the removal of a particular symbol which we call a valve. More precisely, given a sorted signature, and two sorts $r$ and $s$, a valve from $r$ to $s$ is a symbol expecting arguments of sort $r$ and producing a term of another sort $s$. Moreover, it is the only function symbol which allows to build terms of sort $s$ out of terms of sort $r$. Signatures of this kind occur when representing cryptographic primitives using elements of two distinct algebraic structures and a mapping function from one structure to the other. A concrete example occurs in the bilinear pairing operation $[7,12,14]$. We will use this operation as a running example throughout the paper.

We show that under some conditions a valve can be removed from the terms in the frames on which we want to decide the static equivalence, and from the equational theory. Hence our purpose is dual. First we show that deciding static equivalence of a pair of frames involving a given valve can be reduced to the decision of the static equivalence of pairs of frames without this symbol. Second, we show that deciding static equivalence on a pair of frames, not involving a given valve $f$, in the presence of an equational theory involving $f$, can be done in the presence of two other, generally simpler equational theories without $f$. Obviously this cannot be done in general and the first step of this work consists in identifying sufficient conditions on equational theories for which this kind of reduction is possible. The result is illustrated by reducing the decision of static equivalence for an equational theory modelling bilinear pairings between two groups to the decision of static equivalence on groups, yielding a new decidability result.

A completely different combination problem for deciding static equivalence was studied in [4], namely the combination of disjoint equational theories. On the one hand we do not require the two simpler signatures obtained by the reduction to be disjoint, on the other hand we are working in a well-sorted setting.

Structure of the paper. In Section 2 we introduce our formal model. Section 3 presents the running example used throughout the paper. In Section 4 we introduce the concepts of valve and reducibility. Section 5 is dedicated to the presentation of our reduction results. We give a first syntactic criterion for the applicability of our reduction results in Section 6, and conclude in Section 7. Exhaustive versions of some of the proofs are given in [15].

## 2 Model

### 2.1 Sorted term algebras

A sorted signature $(\mathcal{S}, \mathcal{F})$ is defined by a set of sorts $\mathcal{S}=\left\{s, s_{1}, s_{2}, \ldots\right\}$ and a set of function symbols $\mathcal{F}=\left\{f, f_{1}, f_{2}, \ldots\right\}$ with arities of the form $\operatorname{arity}(f)=$ $s_{1} \times \cdots \times s_{k} \rightarrow s$ where $k \geq 0$. If $k=0$ the symbol is called a constant and its arity is simply written $s$. We fix an $\mathcal{S}$-indexed family of sorted names $\mathcal{N}=\left(\mathcal{N}_{s}\right)_{s \in \mathcal{S}}$ where $\mathcal{N}_{s}=\left\{n_{s 1}, n_{s 2}, \ldots\right\}$ and an infinite ordered set of sorted variables $\mathcal{X}$.

The set of terms of sort $s$ is defined inductively by :
$\mathrm{t}::=\quad$ term of sort $s$
$\mid \quad$ variable $x$ of sort $s$
| name $n$ of sort $s$
| $f\left(t_{1}, \ldots, t_{k}\right)$ application of symbol $f \in \mathcal{F}$
where each $t_{i}$ is a term of sort $s_{i}$ and $\operatorname{arity}(f)=s_{1} \times \cdots \times s_{k} \rightarrow s$. The set of terms $T(\mathcal{F}, \mathcal{N}, \mathcal{X})$ is the union of the sets of terms of sort $s$ for every $s \in \mathcal{S}$. We denote by $\operatorname{sort}(t)$ the sort of term $t$. We write $\operatorname{var}(t)$ and names $(t)$ for the set of variables and names occurring in $t$, respectively. A term $t$ is ground iff $\operatorname{var}(t)=\emptyset$. The set of ground terms is denoted by $T(\mathcal{F}, \mathcal{N})$.

We extend the notion of arity to terms as follows. If $t$ is a ground term of sort $s$ then $\operatorname{arity}(t)=s$, otherwise $\operatorname{arity}(t)=s_{1} \times \cdots \times s_{n} \rightarrow s$ if the ordered sequence $x_{1}, \ldots, x_{n}$ of variables of $t$ are of sort $s_{1}, \ldots, s_{n}$ respectively.

We write $|t|$ for the size of $t$, i.e. the number of symbols of $t$.
A context $C$ is a term with distinguished variables sometimes called holes. It can be formalized as a lambda-term of the form $\lambda x_{1} \ldots . \lambda x_{n} . t_{C}$ where the $x_{i}$ may appear or not in $t_{C}$. For the sake of simplicity, in most cases we simply write $C\left[x_{1}, \ldots, x_{n}\right]$ instead of $\lambda x_{1} \ldots . \lambda x_{n} . t_{C}$ as well as $C\left[t_{1}, \ldots, t_{n}\right]$ instead of $\left(\ldots\left(\lambda x_{1} \ldots . \lambda x_{n} . t_{C}\right) t_{1} \ldots\right) t_{n}$. Hence $C\left[t_{1}, \ldots, t_{n}\right]$ is simply the result of replacing each $x_{i}$ by $t_{i}$. A context is public if it does not involve any name.

The positions $\operatorname{Pos}(t)$ of a term $t$ are defined as usual by $\operatorname{Pos}(u)=\{\Lambda\}$ when $u \in \mathcal{N} \cup \mathcal{X}$ and $\operatorname{Pos}\left(f\left(t_{1}, \ldots, t_{n}\right)\right)=\{\Lambda\} \cup\left\{i \cdot \pi \mid 1 \leq i \leq n, \pi \in \operatorname{Pos}\left(t_{i}\right)\right\}$ otherwise. The subterm of $t$ at position $p$ is written $\left.t\right|_{p}$, and the replacement in $t$ at position $p$ by $u$ is written $t[u]_{p}$.

A substitution $\sigma$ written $\sigma=\left\{x_{1} \mapsto t_{1}, \ldots, x_{n} \mapsto t_{n}\right\}$ with domain $\operatorname{dom}(\sigma)=$ $\left\{x_{1}, \ldots, x_{n}\right\}$ is a mapping from $\left\{x_{1}, \ldots, x_{n}\right\} \subseteq \mathcal{X}$ to $T(\mathcal{F}, \mathcal{N}, \mathcal{X})$. We only consider well sorted substitutions in which $x_{i}$ and $t_{i}$ have the same sort. A substitution $\sigma$ is ground if all $t_{i}$ are ground. The application of a substitution $\sigma$ to a term $t$ is written $t \sigma$.

### 2.2 Equational theories and rewriting systems

An equation is an equality $t=u$ where $t$ and $u$ are two terms of the same sort. An equational theory $E$ is a finite set of equations. We denote by $={ }_{E}$ the smallest congruence relation on $T(\mathcal{F}, \mathcal{N}, \mathcal{X})$ such that $t \sigma=_{E} u \sigma$ for any $t=u \in E$ and for any substitution $\sigma$. We say that a symbol $f$ is free in $E$ if $f$ does not occur in $E$.

A term rewriting system $\mathcal{R}$ is a finite set of rewrite rules $l \rightarrow r$ where $l \in$ $T(\mathcal{F}, \mathcal{N}, \mathcal{X})$ and $r \in T(\mathcal{F}, \mathcal{N}, \operatorname{var}(l))$. A term $u \in T(\mathcal{F}, \mathcal{N}, \mathcal{X})$ rewrites to $v$ by $\mathcal{R}$, denoted $u \rightarrow_{\mathcal{R}} v$ if there is a rewrite rule $l \rightarrow r \in \mathcal{R}$, a position $p$ and a substitution $\sigma$ such that $\left.u\right|_{p}=l \sigma$ and $v=u[r \sigma]_{p}$. We write $\rightarrow^{*}$ for the transitive and reflexive closure of $\rightarrow$. Given a set of equations $E, u$ rewrites modulo $E$ by $\mathcal{R}$ to $v$, denoted $u \rightarrow_{\mathcal{R} / E} v$, if $u=_{E} t[l \sigma]_{p}$ and $t[r \sigma]_{p}=_{E} v$ for some context $t$, position $p$ in $t$, rule $l \rightarrow r$ in $\mathcal{R}$, and substitution $\sigma$. $\mathcal{R}$ is $E$-terminating if there are no infinite chains $t_{1} \rightarrow_{\mathcal{R} / E} t_{2} \rightarrow_{\mathcal{R} / E} \ldots \mathcal{R}$ is $E$-confluent iff whenever $t \rightarrow_{\mathcal{R} / E} u$ and $t \rightarrow_{\mathcal{R} / E} v$, there exist $u^{\prime}, v^{\prime}$ such that $u \rightarrow_{\mathcal{R} / E}^{*} u^{\prime}, v \rightarrow_{\mathcal{R} / E}^{*} v^{\prime}$, and $u^{\prime}={ }_{E} v^{\prime}$. $\mathcal{R}$ is $E$-convergent if it is $E$-terminating and $E$-confluent. A term $t$ is in normal form with respect to $(\mathcal{R} / E)$ if there is no term $s$ such that $t \rightarrow_{\mathcal{R} / E} s$. If $t \rightarrow_{\mathcal{R} / E}^{*} s$ and $s$ is in normal form, we say that $s$ is a normal form of $t$. When this normal form is unique (up to $E$ ) we write $s=t \downarrow_{\mathcal{R} / E}$.

### 2.3 Substitutions and frames

A frame is an expression $\phi=\nu \tilde{n}_{\phi} \cdot \sigma_{\phi}$ where $\tilde{n}_{\phi}$ is a set of bound names, and $\sigma_{\phi}$ is a substitution. $|\phi|$ is the size of $\phi$, i.e. the number of elements in $\operatorname{dom}\left(\sigma_{\phi}\right)$. $\sigma_{\phi}$ is called the underlying substitution of $\phi$. We extend the notation dom to frames by $\operatorname{dom}(\nu \tilde{n} . \sigma)=\operatorname{dom}(\sigma)$. We write $\phi={ }_{\alpha} \psi$ when the frames $\phi$ and $\psi$ are equal up to alpha-conversion of bound names. For two frames $\phi=\nu \tilde{n}_{\phi} \cdot \sigma_{\phi}$ and $\psi=\nu \tilde{n}_{\psi} \cdot \sigma_{\psi}$ with $\operatorname{dom}(\phi) \cap \operatorname{dom}(\psi)=\emptyset$ and $\tilde{n}_{\phi} \cap \tilde{n}_{\psi}=\emptyset$ we write $\phi \psi$ for the disjoint composition of $\phi$ and $\psi$ defined as $\phi \psi=\nu\left(\tilde{n}_{\phi} \cup \tilde{n}_{\psi}\right) \cdot \sigma_{\phi} \sigma_{\psi}$. Note that $\tilde{n}_{\phi} \cap \tilde{n}_{\psi}=\emptyset$ is always possible by alpha-conversion of the bound names of $\phi$ and $\psi$. The sort of a frame $\phi$ is the set $S=\{\operatorname{sort}(x) \mid x \in \operatorname{dom}(\phi)\}$, and we say that $\phi$ is $S$-sorted.

For simplicity, we only consider frames $\phi=\nu \tilde{n}\left\{x_{1} \mapsto t_{1}, \ldots, x_{n} \mapsto t_{n}\right\}$ that restrict every name in use, that is, for which $\tilde{n}=$ names $\left(t_{1}, \ldots, t_{n}\right)$. A name $a$ may still be disclosed explicitly by adding a mapping $x_{a} \mapsto a$ to the frame.

### 2.4 Static equivalence

Definition 1 (equality in a frame [2]). We say that two terms $M$ and $N$ are equal in a frame $\phi$ for the equational theory $E$, and write $\left(M={ }_{E} N\right) \phi$, if and only if $\phi={ }_{\alpha} \nu \tilde{n} . \sigma, M \sigma={ }_{E} N \sigma$, and $\{\tilde{n}\} \cap(\operatorname{names}(M) \cup \operatorname{names}(N))=\emptyset$.

Definition 2 (static equivalence [2]). Two frames $\phi$ and $\psi$ are statically equivalent for the equational theory $E$, written $\phi \approx_{E} \psi$, iff $\operatorname{dom}(\phi)=\operatorname{dom}(\psi)$, and for all terms $M$ and $N$, we have $\left(M={ }_{E} N\right) \phi$ if and only if $\left(M={ }_{E} N\right) \psi$.

For two frames $\phi$ and $\psi$, two terms $M, N$ such that $\left(M={ }_{E} N\right) \phi$ and $(M \neq E$ $N) \psi$ are called distinguishers of $\phi$ and $\psi$.

## 3 Running example

We will illustrate our specific definitions and lemmas by a running example involving two distinct algebraic groups $\mathbb{G}_{1}$ and $\mathbb{G}_{2}$ and a pairing operation $e$
mapping two elements of $\mathbb{G}_{1}$ to an element of $\mathbb{G}_{2}$. A concrete cryptographic definition can be found in [7]. In general, a pairing operation maps elements of an additive group to elements of a multiplicative group in the following way.

$$
\begin{aligned}
e: \quad \mathbb{G}_{1} \times \mathbb{G}_{1} & \rightarrow \mathbb{G}_{2} \\
e\left(a g_{1}, b g_{2}\right) & =e\left(g_{1}, g_{2}\right)^{a b}
\end{aligned}
$$

In some protocols, e.g. [12], one has in fact $g_{1}=g_{2}$. We use this assumption in order to simplify our notations. Moreover, we use a multiplicative notation to represent elements of $\mathbb{G}_{1}$, e.g. we write $\exp _{1}(x)$ for both $x g_{1}$ and $x g_{2}$.

Let $\mathcal{S}_{\mathrm{BP}}$ be the set of sorts $\left\{R, G_{1}, G_{2}\right\}, R$ is the sort of the exponents of a chosen generator of the $\mathbb{G}_{i}$, and $G_{1}$ (resp. $G_{2}$ ) are the sorts of the elements of the groups $\mathbb{G}_{1}$ (resp. $\mathbb{G}_{2}$ ). Let $\mathcal{F}_{\mathrm{BP}}$ be the following set of symbols:

$$
\begin{array}{rlrl}
+, \cdot & : R \times R \rightarrow R & & \text { add, mult } \\
- & : R \rightarrow R & & \text { inverse } \\
0_{R}, 1_{R} & : R & & \text { constants } \\
\exp _{i} & : R \rightarrow G_{i} & i \in\{1,2\} & \\
*_{i} & : G_{i} \times G_{i} \rightarrow G_{i} & i \in\{1,2\} & \\
e & \text { mult in } \mathbb{G}_{i} \\
e & G_{1} \times G_{1} \rightarrow G_{2} & & \text { pairing }
\end{array}
$$

We will write $*$ instead of $*_{i}$, the sort of $*$ being always clear from the context. As a convenient shortcut we sometimes write $t^{i}$ for $\underbrace{t * \ldots * t}_{i \times}$. The properties of these function symbols are defined by the following equational theory $E_{\mathrm{BP}}$.

$$
\begin{array}{rlrl}
x+y & =y+x & 0_{R}+x & =x \\
(x+y)+z & =x+(y+z) & x+(-x) & =0_{R} \\
x \cdot y & =y \cdot x & x \cdot(y+z) & =(x \cdot y)+(x \cdot z) \\
(x \cdot y) \cdot z & =x \cdot(y \cdot z) & 1_{R} \cdot x & =x \\
& & & \\
\exp _{i}(x) *_{i} \exp _{i}(y)=\exp _{i}(x+y) & i \in\{1,2\} \\
e\left(\exp _{1}(x), \exp _{1}(y)\right)=\exp _{2}(x \cdot y) &
\end{array}
$$

This signature and this equational theory represent operations realized in protocols where the exchanged messages are elements of the groups $\mathbb{G}_{i}$. The symbol $e$ represents a pairing operation.

Example 1. Bilinear pairing is a central primitive of the Joux protocol [12], a three participant variation of the Diffie-Hellman protocol. It implicitly relies on the decisional Bilinear Diffie-Hellman Assumption (BDH) which can be formally modelled using static equivalence as follows:

$$
\begin{gathered}
\nu a, b, c, r \cdot\left\{x_{1} \mapsto \exp _{1}(a), x_{2} \mapsto \exp _{1}(b), x_{3} \mapsto \exp _{1}(c), y_{1} \mapsto \exp _{2}(a \cdot b \cdot c)\right\} \\
\approx_{E_{\mathrm{BP}}} \\
\nu a, b, c, r \cdot\left\{x_{1} \mapsto \exp _{1}(a), x_{2} \mapsto \exp _{1}(b), x_{3} \mapsto \exp _{1}(c), y_{1} \mapsto \exp _{2}(r)\right\}
\end{gathered}
$$

## 4 Valves and reducibility

The main result of our paper concerns signatures involving a special function symbol which we call a valve. Intuitively, as it is suggested by the name "valve", a valve $f$ is a symbol such that applying $f$ on terms of sort $r$, we obtain a term $t$ of sort $s$ and such that $t$ cannot be a subterm of a term of sort $r$.

We borrow here some useful notions from graph theory.
Definition 3 (Signature graph). Let $(\mathcal{S}, \mathcal{F})$ be a sorted signature. The graph $\mathcal{G}(\mathcal{S}, \mathcal{F})$ is the directed labelled graph $(V, E)$ where $V=\mathcal{S}, E \subseteq V \times V \times \mathcal{F}$ and $(r, s, f) \in E$ iff $\operatorname{sort}(f)=s_{1} \times \cdots \times s_{n} \rightarrow s$ and $s_{i}=r$ for some $i$.

We recall that a path in a graph is a sequence of edges such that for two consecutive edges $(r, s, f)$ and $\left(r^{\prime}, s^{\prime}, f^{\prime}\right)$ we have $s=r^{\prime}$.
Definition 4 (valve). A symbol $f$ of arity $\cdots \times r \times \cdots \rightarrow s$ is a valve from $r$ to $s$ iff every path from $r$ to $s$ in $\mathcal{G}(\mathcal{S}, \mathcal{F})$ contains $(r, s, f)$ and there is no path from $s$ to $r$.
Example 2 (continued). Let us consider the sorted signature $\left(\mathcal{S}_{\mathrm{BP}}, \mathcal{F}_{\mathrm{BP}}\right)$ introduced in our running example in Section 3. $\mathcal{G}\left(\mathcal{S}_{\mathrm{BP}}, \mathcal{F}_{\mathrm{BP}}\right)$ is given in Figure 1.


Fig. 1. $\mathcal{G}\left(\mathcal{S}_{\mathrm{BP}}, \mathcal{F}_{\mathrm{BP}}\right)$

In the signature of Figure $1, e$ is a valve from $G_{1}$ to $G_{2}$ as $\left(G_{1}, G_{2}, e\right)$ lies on every path from $G_{1}$ and $G_{2}$, and since no path leads from $G_{2}$ to $G_{1}$. We also have that $\exp _{1}$ is a valve from $R$ to $G_{1}$. However, exp $p_{2}$ is not a valve from $R$ to $G_{2}$ as the sequence $\left(R, G_{1}, \exp _{1}\right),\left(G_{1}, G_{2}, e\right)$ is a path from $R$ to $G_{2}$.

We are now able to present the central notion of reducibility.
Definition 5 (reducible). Let $r$ and $s$ be two sorts and $f$ a valve from $r$ to $s$. An equational theory $E$ is reducible for $f$ iff for every $n \geq 0$ there exist $m$ public contexts $T_{1}\left[x_{1}, \ldots, x_{n}\right], \ldots, T_{m}\left[x_{1}, \ldots, x_{n}\right]$ of arity $r \times \cdots \times r \rightarrow s$ such that for all public contexts $C_{1}\left[x_{1}, \ldots, x_{n}\right], \ldots, C_{k}\left[x_{1}, \ldots, x_{n}\right]$ of arity $r \times \cdots \times r \rightarrow r$ there exists a public context $D\left[y_{1}, \ldots, y_{m}\right]$ of arity $s \times \cdots \times s \rightarrow s$ such that for any ground terms $t_{1}, \ldots, t_{n}$ of sort $r$

$$
f\left(C_{1}, \ldots, C_{k}\right)\left[t_{1}, \ldots, t_{n}\right]={ }_{E} D\left[T_{1}, \ldots, T_{m}\right]\left[t_{1}, \ldots, t_{n}\right]
$$

Intuitively, reducibility for a valve $f$ means that given a cardinality $n$ of sets of ground terms of sort $r$, we can construct in a uniform way a set of terms such that any sequence of operations performed before applying $f$, there will be a way to reproduce these operations on the terms obtained with the context $T_{i}$. The uniformity lies in the fact that the contexts $T_{i}$ depend only on the number $n$ but not on the contexts $C_{i}$. We illustrate this notion by showing the reducibility for $e$ of the theory of our running example $E_{\mathrm{BP}}$ in case $\mathcal{N}_{G_{1}}=\emptyset$.

Proposition 1. $E_{B P}$ is reducible for e if $\mathcal{N}_{G_{1}}=\emptyset$.
Proof. Let $n$ be an integer. We define $m=n+\frac{n *(n+1)}{2}$ contexts

$$
\begin{aligned}
& T_{i}=\lambda x_{1} \ldots . \lambda x_{n} \cdot e\left(x_{i}, \exp _{1}\left(1_{R}\right)\right) \text { for } 1 \leq i \leq n \\
& T_{i j}=\lambda x_{1} \ldots . \lambda x_{n} \cdot e\left(x_{i}, x_{j}\right) \quad \text { for } 1 \leq i \leq j \leq n
\end{aligned}
$$

Every public context $C_{i}\left[x_{1}, \ldots, x_{n}\right]$ of arity $G_{1} \times \cdots \times G_{1} \rightarrow G_{1}$ is of the form $\lambda x_{1} \ldots . \lambda x_{n} . x_{1}^{e_{i 1}} * \cdots * x_{n}^{e_{i n}} * \exp _{1}\left(p_{i}\right)$ where $p_{i}={ }_{E_{\mathrm{BP}}} 1_{R}+\cdots+1_{R}$ ( $l_{i}$ times). Hence $\exp _{1}\left(p_{i}\right)={ }_{E_{\mathrm{BP}}} \exp _{1}\left(1_{R}\right)^{l_{i}}$.

Let us show by induction on the size of the contexts $C_{i}$ that there exists a context $D$ such that for any sequence of ground terms $t_{1}, \ldots, t_{n}$

$$
e\left(C_{1}, C_{2}\right)\left[t_{1}, \ldots t_{n}\right]==_{E_{\mathrm{BP}}} D\left[T_{1}, \ldots, T_{n}, T_{11}, \ldots, T_{n n}\right]\left[t_{1}, \ldots, t_{n}\right]
$$

Base case. We distinguish four cases:

1. $C_{1}=\lambda x_{1} \ldots . \lambda x_{n} . x_{i}$ and $C_{2}=\lambda x_{1} \ldots . \lambda x_{n} \cdot x_{j}$

For any sequence of terms $t_{1}, \ldots, t_{n}$ we have that $e\left(C_{1}, C_{2}\right)\left[t_{1}, \ldots, t_{n}\right]=$ $e\left(t_{i}, t_{j}\right)$. As $\mathcal{N}_{G_{1}}=\emptyset$ there exist terms $t_{i}^{\prime}$ and $t_{j}^{\prime}$ of sort $R$ such that $t_{i}=E_{E_{\mathrm{BP}}}$ $\exp _{1}\left(t_{i}^{\prime}\right)$ and $t_{j}=E_{E_{\mathrm{BP}}} \exp _{1}\left(t_{j}^{\prime}\right)$. Hence

$$
\begin{aligned}
e\left(C_{1}, C_{2}\right)\left[t_{1}, \ldots, t_{n}\right] & =E_{E_{\mathrm{BP}}} e\left(\exp _{1}\left(t_{i}^{\prime}\right), \exp _{1}\left(t_{j}^{\prime}\right)\right) \\
& =E_{E_{\mathrm{BP}}} \exp _{2}\left(t_{i}^{\prime} \cdot t_{j}^{\prime}\right)=_{E_{\mathrm{BP}}} T_{i j}\left[t_{1}, \ldots, t_{n}\right]
\end{aligned}
$$

Let $D=\lambda y_{1} \ldots . \lambda y_{n} \cdot \lambda y_{11} \ldots . \lambda y_{n n} . y_{i j}$. We have that $e\left(C_{i}, C_{j}\right)\left[t_{1}, \ldots, t_{n}\right]=E_{E_{\mathrm{BP}}}$ $D\left[T_{1}, \ldots, T_{n}, T_{11}, \ldots, T_{n n}\right]\left[t_{1}, \ldots, t_{n}\right]$.
2. $C_{1}=\lambda x_{1} \ldots \ldots \lambda x_{n} \cdot x_{i}$ and $C_{2}=\exp _{1}\left(1_{R}\right)^{l}$

For any sequence of terms $t_{1}, \ldots, t_{n}$ we have that $e\left(C_{1}, C_{2}\right)\left[t_{1}, \ldots, t_{n}\right]=$ $e\left(t_{i}, \exp \left(1_{R}\right)^{l}\right)$. As $\mathcal{N}_{G_{1}}=\emptyset$ there exists a term $t_{i}^{\prime}$ of sort $R$ such that $t_{i}=E_{\mathrm{BP}}$ $\exp _{1}\left(t_{i}^{\prime}\right)$. Hence

$$
\begin{aligned}
e\left(C_{1}, C_{2}\right)\left[t_{1}, \ldots, t_{n}\right] & =E_{E_{\mathrm{BP}}} e(\exp _{1}\left(t_{i}^{\prime}\right), \exp _{1}(\underbrace{1_{R}+\cdots+1_{R}}_{l \times})) \\
& =E_{E_{\mathrm{BP}}} \exp _{2}(t_{i}^{\prime} \cdot(\underbrace{1_{R}+\cdots+1_{R}}_{l \times})) \\
& =E_{E_{\mathrm{BP}}} \exp _{2}\left(t_{i}^{\prime}\right)^{l}=_{E_{\mathrm{BP}}}\left(T_{i}\left[t_{1}, \ldots, t_{n}\right]\right)^{l}
\end{aligned}
$$

Let $D=\lambda y_{1} \ldots . \lambda y_{n} \cdot \lambda y_{11} \ldots . \lambda y_{n n} . y_{i}^{l}$. We have that $e\left(C_{i}, C_{j}\right)\left[t_{1}, \ldots, t_{n}\right]={ }_{E_{\mathrm{BP}}}$ $D\left[T_{1}, \ldots, T_{n}, T_{11}, \ldots, T_{n n}\right]\left[t_{1}, \ldots, t_{n}\right]$.
3. $C_{1}=\exp _{1}\left(1_{R}\right)^{l}$ and $C_{2}=\lambda x_{1} \ldots . \lambda x_{n} \cdot x_{i}$

As $C_{1} * C_{2}={ }_{E_{\mathrm{BP}}} C_{2} * C_{1}$ this case is similar to case 2.
4. $C_{1}=\exp _{1}\left(1_{R}\right)^{l_{1}}$ and $C_{2}=\exp _{1}\left(1_{R}\right)^{l_{2}}$

We immediately conclude by defining $D=\exp _{2}\left(1_{R}\right)^{l_{1} \cdot l_{2}}$.
Inductive case : $C_{i}=C_{i 1} * C_{i 2}$. Let $i=1$. The case where $i=2$ is similar. We note that every term of sort $R$ can be written as a sum of products of names of sort $R$. More formally for any contexts $C_{11}\left[x_{1}, \ldots, x_{n}\right], C_{12}\left[x_{1}, \ldots, x_{n}\right]$, $C_{2}\left[x_{1}, \ldots, x_{n}\right]$, for any term $t_{1}, \ldots t_{n}$ we have that $C_{11}\left[t_{1}, \ldots t_{n}\right]=\exp _{1}\left(p_{11}\right)$, $C_{12}\left[t_{1}, \ldots t_{n}\right]=\exp _{1}\left(p_{12}\right)$ and $C_{2}\left[t_{1}, \ldots t_{n}\right]=\exp _{1}\left(p_{2}\right)$, for some elements of sort $R$ described as above. We note that the equational theory implies that $e\left(C_{11} * C_{12}, C_{2}\right)=e\left(C_{11}, C_{2}\right) * e\left(C_{12}, C_{2}\right)$.

By induction there are $D_{1}$ and $D_{2}$ such that $e\left(C_{11} * C_{2}\right)\left[t_{1}, \ldots, t_{n}\right]={ }_{E}$ $D_{1}\left[T_{1}, \ldots, T_{m}\right]\left[t_{1}, \ldots, t_{n}\right]$ and $e\left(C_{12} * C_{2}\right)\left[t_{1}, \ldots, t_{n}\right]={ }_{E} D_{2}\left[T_{1}, \ldots, T_{m}\right]\left[t_{1}, \ldots, t_{n}\right]$. Hence defining $D$ as $D_{1} * D_{2}$ we conclude.

Example 3. For $n=2$ we have that

$$
\begin{gathered}
T_{1}=e\left(x_{1}, \exp _{1}(1)\right) \quad T_{2}=e\left(x_{2}, \exp _{1}(1)\right) \\
T_{1,1}=e\left(x_{1}, x_{1}\right) \quad T_{1,2}=e\left(x_{1}, x_{2}\right) \quad T_{2,2}=e\left(x_{2}, x_{2}\right)
\end{gathered}
$$

Let $C_{1}=\lambda x_{1} \lambda x_{2} \cdot x_{1}$ and $C_{2}=\lambda x_{1} \lambda x_{2} \cdot x_{2} * x_{2} * \exp _{1}(1+1)$. We define

$$
D=\lambda y_{1} \lambda y_{2} \lambda y_{1,1} \lambda y_{1,2} \lambda y_{2,2} \cdot y_{1,2} * y_{1,2} * y_{1} * y_{1}
$$

since $e\left(t_{1}, t_{2} * t_{2} * \exp _{1}(1+1)\right)=e\left(t_{1}, t_{2}\right) * e\left(t_{1}, t_{2}\right) * e\left(t_{1}, \exp _{1}(1)\right) * e\left(t_{1}, \exp _{1}(1)\right)$ for any ground terms $t_{1}, t_{2}$.

Remark 1. Proposition 1 requires that we do not have names of sort $G_{1}$. We argue that this is not restrictive in the context of protocols. As we expect that terms of sort $G_{1}$ represent the elements of a group with a given generator each element of the group $G_{1}$ can indeed be written as $\exp _{1}(r)$ for some element of $R$.

One might have expected reducibility for a symbol $f$ to be related to being sufficiently complete w.r.t. $f$ as defined in [8].

Definition 6 (sufficiently complete). $E$ is a sufficiently complete equational theory with respect to $f \in \mathcal{F}$ if for every ground term $t \in T(\mathcal{F}, \mathcal{N})$ there exists a ground term $u \in T(\mathcal{F} \backslash\{f\}, \mathcal{N})$ such that $t={ }_{E} u$.

The next two lemmas show, however, that these two notions are in fact independent of each other.

Lemma 1. Reducibility of an equational theory $E$ for a symbol $f$ does not imply sufficient completeness of $E$ w.r.t. $f$.

Proof. Let $\mathcal{S}=\{r, s\}$ and $\mathcal{F}=\{f\}$, with $\operatorname{sort}(f)=r \rightarrow s$, and $E=\emptyset$. We show that $E$ is reducible for $f$ but not sufficiently complete w.r.t. $f$. Consider an integer $n$ and the contexts $T_{1}=\lambda x_{1} \ldots \lambda x_{n} . f\left(x_{1}\right), \ldots, T_{n}=\lambda x_{1} \ldots \lambda x_{n} . f\left(x_{n}\right)$.

As the only ground terms $t_{i}$ of sort $r$ are names $n_{i}$, we consider w.l.o.g. that any sequence of terms $t_{1}, \ldots, t_{n}$ is equal to $n_{1}, \ldots, n_{n}$, and as the only possible contexts $C$ of sort $r$ are of the form $\lambda x_{1} \ldots \lambda x_{n} . x_{i}$, we have $f\left(C\left[t_{1}, \ldots, t_{n}\right]\right)=$ $f\left(n_{i}\right)$. Hence we only have to verify that for any $i$ there exists a context $D$ such that $f\left(n_{i}\right)={ }_{E} D\left[T_{1}, \ldots, T_{n}\right]\left[n_{1}, \ldots, n_{n}\right]$. We choose $D=\lambda y_{1} \ldots \lambda y_{n} . y_{i}$.

To show that $E$ is not sufficiently complete w.r.t. $f$, we note that as $f$ is free, for any $i$ the term $f\left(n_{i}\right)$ is not equivalent to a term without $f$.

Lemma 2. Sufficient completeness of $E$ w.r.t. a symbol $f$ does not imply reducibility of $E$ for $f$.

Proof. We define a signature with two sorts $r$ and $s$, no names, and the function symbols $0_{r}: r, s_{r}: r \rightarrow r, f: r \rightarrow s, 0_{s}: s, s_{s}: s \rightarrow s$. The function symbol $f$ is the valve. We have the following equational theory:

$$
\left.f\left(s_{r}(x), y\right)\right)=s_{s}(f(x, y)) \quad f\left(0_{r}, s_{r}(y)\right)=f\left(s_{r}(y), y\right) \quad f\left(0_{r}, 0_{r}\right)=0_{s}
$$

Identifying any ground term of sort $r$ or $s$ with a natural number, the function $f$ satisfies $f(n, m)=n+\frac{m *(m+1)}{2}$. Since there are no names $E$ is sufficiently complete for $f$. The fact that $f$ has a quadratic growth contradicts reducibility. A detailed proof can be found in [15].

## 5 Getting rid of reducible symbols

We now present the central result of our work and show that if an equational theory $E$ is reducible for $f$ then it is possible to get rid of $f$ when deciding static equivalence.

First, we show that deciding static equivalence on $\{r, s\}$-sorted frames in the presence of a valve from $r$ to $s$ can be reduced to deciding two equivalences, one on $r$-sorted frames and one on $s$-sorted frames (Lemma 4).

Second, we show that under some conditions on the equational theory, deciding static equivalence for a given equational theory can be reduced to deciding static equivalence for an equational theory that does not involve a reducible symbol (Theorem 1). As a corollary we get the possibility of splitting the equational theory into simpler equational theories.

Definition 7 (reduction). Let the equational theory $E$ be reducible for $f$, where $f$ is a valve from $r$ to $s$, and let $\phi=\nu \tilde{n}\left\{x_{1} \mapsto t_{1}, \ldots, x_{n} \mapsto t_{n}\right\}$ be a frame of sort $\{r\}$. The reduction of $\phi$ is defined as $\bar{\phi}=\nu \tilde{n}\left\{y_{1} \mapsto T_{1}\left[t_{1}, \ldots t_{n}\right], \ldots, y_{m} \mapsto\right.$ $\left.T_{m}\left[t_{1}, \ldots t_{n}\right]\right\}$ where $T_{i}$ are contexts as defined in Definition 5.

We note that $\bar{\phi}$ is $\{s\}$-sorted. Before giving an example illustrating the construction of $\bar{\phi}$ we define the following useful notation.

Definition 8 (s-restriction). Let $\phi=\nu \tilde{n} . \sigma_{\phi}$ be an $\left\{s_{1}, \ldots, s_{n}\right\}$-sorted frame. The $s_{i}$-restriction of $\phi$, denoted $\phi_{\mid s_{i}}$ is the frame $\nu \tilde{n} . \sigma_{\phi_{\mid s_{i}}}$ where $\sigma_{\phi_{\mid s_{i}}}$ is the substitution $\sigma_{\phi}$ restricted to the variables of sort $s_{i}$.

Example 4. Let $\phi_{B D H}$ be the $G_{1}$-restriction of the frames presented in Example 1: $\phi_{B D H}=\nu a, b, c, r$. $\left\{x_{1} \mapsto \exp _{1}(a), x_{2} \mapsto \exp _{1}(b), x_{3} \mapsto \exp _{1}(c)\right\}$. Using the set of terms $T_{i}$ and $T_{i j}$ defined in the proof of Proposition 1, we get

$$
\left.\begin{array}{rl}
\bar{\phi}_{B D H}=\nu a, b, c, r \cdot\{ & y_{1} \mapsto e\left(\exp _{1}(a), \exp _{1}(1)\right), y_{12} \mapsto e\left(\exp _{1}(a), \exp _{1}(b)\right), \\
y_{2} & \mapsto e\left(\exp _{1}(b), \exp _{1}(1)\right), y_{13} \mapsto e\left(\exp _{1}(a), \exp _{1}(c)\right), \\
y_{3} & \mapsto e\left(\exp _{1}(c), \exp _{1}(1)\right), y_{23} \mapsto e\left(\exp _{1}(b), \exp _{1}(c)\right)
\end{array}\right\}, ~ \$
$$

We now prove a technical lemma which will be used to transfer tests on a frame to tests on its reduction.

Lemma 3. Let $(\mathcal{S}, \mathcal{F})$ be a signature such that $f \in \mathcal{F}$ is a valve from $r$ to $s$, and $E$ an equational theory that is reducible for $f$. For any integer $n$, and for any public context $M$ of sort s there exists a public context $M^{\prime}$ such that for any $\{r, s\}$-sorted frame $\phi$ of size $n, M \phi==_{E} M^{\prime} \phi_{\mid r} \phi_{\mid s}$.
Proof. Let us show this by induction on the height of $M$. If $M$ is a variable or a constant then we define $M^{\prime}=M$. If $M=y \in \mathcal{X}$ then $y\left(\overline{\phi_{\mid r}} \phi_{\mid s}\right)=y \phi$ since the sort of $y$ is $s$. If $M=c$ is a constant then $M \phi={ }_{E} M^{\prime} \overline{\phi_{\mid r}} \phi_{\left.\right|_{s}}$ holds trivially.

If the height of $M$ is non-null then the top symbol of $M$ can be the valve $f$, or some function symbol $f^{\prime} \neq f$.

If $M=f\left(C_{1}\left[x_{1}, \ldots, x_{n}\right], \ldots, C_{k}\left[x_{1}, \ldots, x_{n}\right]\right)$ then all variables of $M$ are of sort $r$, and hence $M \phi=M \phi_{\mid r}$ where $\phi_{\mid r}=\left\{x_{1} \mapsto t_{1}, \ldots, x_{n^{\prime}} \mapsto t_{n^{\prime}}\right\}$. As $E$ is reducible for $f$, we can define $\overline{\phi_{\mid r}}$ as $\left\{y_{1} \mapsto T_{1}\left[t_{1}, \ldots t_{n^{\prime}}\right], \ldots, y_{m} \mapsto T_{m}\left[t_{1}, \ldots t_{n^{\prime}}\right]\right\}$. By Definition 5 there exists a public context $D\left[y_{1}, \ldots, y_{m}\right]$ such that

$$
f\left(C_{1}, \ldots, C_{k}\right)\left[t_{1}, \ldots, t_{n^{\prime}}\right]=D\left[T_{1}, \ldots, T_{m}\right]\left[t_{1}, \ldots, t_{n^{\prime}}\right]
$$

With $M^{\prime}=D$ we have that $M \phi_{\mid r}={ }_{E} M^{\prime} \overline{\phi_{\mid r}}$, and hence $M \phi={ }_{E} M^{\prime} \overline{\phi_{\mid r}} \phi_{\mid s}$.
If $M=f^{\prime}\left(C_{1}\left[x_{1}, \ldots, x_{n}, y_{1}, \ldots, y_{m}\right], \ldots, C_{k^{\prime}}\left[x_{1}, \ldots, x_{n}, y_{1}, \ldots, y_{m}\right]\right)$ with $f^{\prime} \neq$ $f$ then $\operatorname{sort}\left(C_{i}\right)=s$. By induction there exist public contexts $M_{1} \ldots M_{k^{\prime}}$ such that for any $\{r, s\}$-sorted frame $\phi$ of size $n, C_{i^{\prime}} \phi={ }_{E} M_{i^{\prime}} \overline{\phi_{\mid r}} \phi_{\mid s}$. We define $M^{\prime}=f^{\prime}\left(M_{1} \ldots M_{k^{\prime}}\right)$, and obtain $M \phi={ }_{E} M^{\prime} \overline{\phi_{\mid r}} \phi_{\mid s}$.

The following lemma allows us to split the decision of static equivalence of $\{r, s\}$-sorted frames into two equivalences on $r$-sorted frames and $s$-sorted frames.

Lemma 4. For any $\{r, s\}$-sorted frames $\phi_{1}$ and $\phi_{2}$ built on $(\mathcal{S}, \mathcal{F})$, and for a valve $f$ from $r$ to $s$, if $E$ is a reducible equational theory for $f$ then $\phi_{1} \approx_{E} \phi_{2}$ iff $\phi_{1 \mid r} \approx_{E} \phi_{2 \mid r}$ and $\overline{\phi_{1 \mid r}} \phi_{1 \mid s} \approx_{E} \overline{\phi_{2 \mid r}} \phi_{2 \mid s}$.

Proof (Sketch). We prove the two directions of the equivalence separately.
$(\Rightarrow)$ If $\phi_{1} \approx_{E} \phi_{2}$, then $\phi_{1 \mid r} \approx_{E} \phi_{2 \mid r}$ and $\overline{\phi_{1 \mid r}} \phi_{1 \mid s} \approx_{E} \overline{\phi_{2 \mid r}} \phi_{2 \mid s}$. The proof is done by contraposition. We obviously have that $\phi_{1 \mid r} \not z_{E} \phi_{2 \mid r}$ implies $\phi_{1} \not \boldsymbol{z}_{E} \phi_{2}$ as $M \phi_{i \mid r}=M \phi_{i}$ for any term $M$ having only variables of sort $r$. Furthermore, we have that $\overline{\phi_{1 \mid r}} \phi_{1 \mid s} \not z_{E} \overline{\phi_{2 \mid r}} \phi_{2 \mid s}$ implies $\phi_{1} \not \chi_{E} \phi_{2}$. The proof uses the fact that the elements $\overline{\phi_{i \mid r}}$ are obtained by some fixed contexts $T_{i}$ in order to build distinguishers for $\phi_{1}$ and $\phi_{2}$.
$(\Leftarrow)$ If $\phi_{1 \mid r} \approx_{E} \phi_{2 \mid r}$ and $\overline{\phi_{1 \mid r}} \phi_{1 \mid s} \approx_{E} \overline{\phi_{2 \mid r}} \phi_{2 \mid s}$ then $\phi_{1} \approx_{E} \phi_{2}$. The proof is done by contraposition. Suppose that $\phi_{1} \not \ddot{z}_{E} \phi_{2}$ and consider the two possibilities for the sorts of the distinguishers $M$ and $N$. If $\operatorname{sort}(M)=r$, by the fact that $f$ is a valve, we have that $M$ and $N$ distinguish $\phi_{1 \mid r}$ and $\phi_{2 \mid r}$. If $\operatorname{sort}(M)=s$, by invoking Lemma 3, we infer the existence of distinguishers for $\overline{\phi_{1 \mid r}} \phi_{1 \mid s}$ and $\overline{\phi_{2 \mid r}} \phi_{2 \mid s}$.

A detailed proof can be found in [15].
By the following definition we identify a sufficient condition to get rid of the symbol $f$ for deciding static equivalence between frames that do not involve this symbol. In the following section we exhibit a syntactic condition that is sufficient to obtain such a theory.

Definition 9 (sufficient equational theory). Let $(\mathcal{S}, \mathcal{F} \uplus\{f\})$ be a sorted signature and $E$ an equational theory. An equational theory $E^{\prime}$ is sufficient for $E$ without $f$ iff for any terms $u, v \in T(\mathcal{F}, \mathcal{N}), u=E_{E} v$ iff $u=E_{E^{\prime}} v$ and $E^{\prime}$ does not involve $f$.

Theorem 1. Let $E$ be an equational theory on the sorted signature $(\mathcal{S}, \mathcal{F} \uplus\{f\})$ such that

- $f$ is a valve,
$-E$ is a reducible equational theory for $f$,
- $E$ is sufficiently complete w.r.t. $\{f\}$.

If there exists an equational theory $E^{\prime}$ sufficient for $E$ without $f$ then for any $\{r, s\}$-sorted frames $\phi_{1}$ and $\phi_{2}$, we have that $\phi_{1} \approx_{E} \phi_{2}$ iff $\phi_{1 \mid r} \approx_{E^{\prime}} \phi_{2 \mid r}$ and $\overline{\phi_{1 \mid r}} \phi_{1 \mid s} \approx_{E^{\prime}} \overline{\phi_{2 \mid r}} \phi_{2 \mid s}$.

The proof of Theorem 1 relies on Lemma 5.
Lemma 5. Let $\phi_{1}$ and $\phi_{2}$ be two $\{r\}$-sorted frames, $E$ an equational theory, and $f$ a valve from $r$ to a distinct sort $s$, which is free in $E$. If for any two terms $M, N$ of sort $r\left(M==_{E} N\right) \phi_{1}$ iff $\left(M==_{E} N\right) \phi_{2}$, then for any two terms $M$ and $N$ of sort s, $\left(M={ }_{E} N\right) \phi_{1}$ iff $\left(M={ }_{E} N\right) \phi_{2}$.

Proof (sketch). We will exhibit two replacements functions $\sigma_{1}$ (resp. $\sigma_{2}$ ) defined on pairs $(\alpha, p)$ where $\alpha$ identifies $M$ or $N$ and $p$ is a position in $M \phi_{1}$ or $N \phi_{1}$ (resp. $M \phi_{2}, N \phi_{2}$ ) such that $\left.M \phi_{1}\right|_{p}$ or $\left.N \phi_{1}\right|_{p}$ is headed by $f$. The co-domain of $\sigma_{1}\left(\right.$ resp. $\left.\sigma_{2}\right)$ is a set of fresh names w.r.t. $\phi_{1}\left(\right.$ resp. $\left.\phi_{2}\right)$. We show the two following assertions

1. $M \phi_{1} \sigma_{1}={ }_{E} M \phi_{2} \sigma_{2}$ and $N \phi_{1} \sigma_{1}={ }_{E} N \phi_{2} \sigma_{2}$,
2. $M \phi_{i}={ }_{E} N \phi_{i}$ iff $M \phi_{i} \sigma_{i}={ }_{E} N \phi_{i} \sigma_{i}$ for $i \in\{1,2\}$.

Their conjunction implies that for any two terms $M, N$ of sort $s,\left(M=E_{E} N\right) \phi_{1}$ iff $\left(M={ }_{E} N\right) \phi_{2}$.

To show that $M \phi_{1} \sigma_{1}={ }_{E} M \phi_{2} \sigma_{2}$ and $N \phi_{1} \sigma_{1}=_{E} N \phi_{2} \sigma_{2}$ we rely on the hypothesis that for any two terms $M, N$ of sort $r$ we have that $\left(M={ }_{E} N\right) \phi_{1}$ iff $\left(M={ }_{E} N\right) \phi_{2}$ as well as the construction of $\sigma_{1}$ and $\sigma_{2}$.

To show that $M \phi_{i}={ }_{E} N \phi_{i}$ implies $M \phi_{i} \sigma_{i}={ }_{E} N \phi_{i} \sigma_{i}$, we use the notion of cut function introduced in [6]. Showing that $\sigma_{1}$ (resp. $\sigma_{2}$ ) corresponds to a sequence of applications of a cut function allows us to conclude using Lemma 15 of [6]. To show that $M \phi_{i} \sigma_{i}={ }_{E} N \phi_{i} \sigma_{i}$ implies $M \phi_{i}={ }_{E} N \phi_{i}$ we use the fact that $\sigma_{1}$ and $\sigma_{2}$ are bijective.

A complete proof is given in in [15].
Proof (of Theorem 1). We suppose that $\phi_{1} \approx_{E} \phi_{2}$. By Lemma 4 we have that $\phi_{1 \mid r} \approx_{E} \phi_{2 \mid r}$ and $\overline{\phi_{1 \mid r}} \phi_{1 \mid s} \approx_{E} \overline{\phi_{2 \mid r}} \phi_{2 \mid s}$.

We will show that

$$
\begin{aligned}
\phi_{1 \mid r} \approx_{E} \phi_{2 \mid r}(p) & \wedge \overline{\phi_{1 \mid r}} \phi_{1 \mid s} \approx_{E} \overline{\phi_{2 \mid r}} \phi_{2 \mid s}(q) \\
& \Leftrightarrow \\
\phi_{1 \mid r} \approx_{E^{\prime}} \phi_{2 \mid r}\left(p_{1}\right) & \wedge \overline{\phi_{1 \mid r}} \phi_{1 \mid s} \approx_{E^{\prime}} \overline{\phi_{2 \mid r}} \phi_{2 \mid s}\left(q_{1}\right)
\end{aligned}
$$

We will prove the three following assertions separately :

$$
\text { (1) } \neg q \Leftrightarrow \neg q_{1} \quad(2) \neg p \Rightarrow \neg p_{1} \vee \neg q_{1} \quad(3) \neg p_{1} \Rightarrow \neg p
$$

The conjunction of these three assertions implies the fact that $(p \wedge q) \Leftrightarrow\left(p_{1} \wedge q_{1}\right)$.
(1) $\overline{\phi_{1 \mid r}} \phi_{1 \mid s} \not \not_{E} \overline{\phi_{2 \mid r}} \phi_{2 \mid s}$ iff $\overline{\phi_{1 \mid r}} \phi_{1 \mid s} \not \not_{E^{\prime}} \overline{\phi_{2 \mid r}} \phi_{2 \mid s}$

As $\overline{\phi_{1 \mid r}} \phi_{1 \mid s} \not \chi_{E} \overline{\phi_{2 \mid r}} \phi_{2 \mid s}$ there exist two terms $M$ and $N$ distinguishing $\overline{\phi_{1 \mid r}} \phi_{1 \mid s}$ and $\overline{\phi_{2 \mid r}} \phi_{2 \mid s}$. As $f$ is a valve, there exist $M$ and $N$ that do not involve any symbol $f$. As $E$ is sufficiently complete w.r.t. $\{f\}$ we can suppose that frames $\overline{\phi_{1 \mid r}} \phi_{1 \mid s}$ and $\overline{\phi_{2 \mid r}} \phi_{2 \mid s}$ do not involve $f$. Hence $M \overline{\phi_{i \mid r}} \phi_{i \mid s}$ and $N \overline{\phi_{i \mid r}} \phi_{i \mid s}$ also do not involve $f$. As $E^{\prime}$ is sufficient for $E$ without $f$ we have that $M \overline{\phi_{i \mid r}} \phi_{i \mid s}=E N \overline{\phi_{i \mid r}} \phi_{i \mid s}$ iff $M \overline{\phi_{i \mid r}} \phi_{i \mid s}=E_{E^{\prime}} N \overline{\phi_{i \mid r}} \phi_{i \mid s}$. Hence $\overline{\phi_{1 \mid r}} \phi_{1 \mid s} \not \nsim E_{E^{\prime}} \overline{\phi_{2 \mid r}} \phi_{2 \mid s}$.
(2) if $\phi_{1 \mid r} \not \approx_{E} \phi_{2 \mid r}$ then $\phi_{1 \mid r} \not z_{E^{\prime}} \phi_{2 \mid r}$ or $\overline{\phi_{1 \mid r}} \phi_{1 \mid s} \not z_{E^{\prime}} \overline{\phi_{2 \mid r}} \phi_{2 \mid s}$

Let $M$ and $N$ be two terms distinguishing $\phi_{1 \mid r}$ and $\phi_{2 \mid r}$.
If $M$ is of sort $r$, as $f$ is a valve, we can suppose w.l.o.g. that $M, N, \phi_{1 \mid r}$ and $\phi_{2 \mid r}$ do not involve any $f$. Hence $M \phi_{i \mid r}$ and $N \phi_{i \mid r}$ do not involve $f$. As $E^{\prime}$ is sufficient for $E$ without $f$ we have that $M \phi_{i \mid r}={ }_{E} N \phi_{i \mid r}$ iff $M \phi_{i \mid r}=E_{E^{\prime}} N \phi_{i \mid r}$. Hence $\phi_{1 \mid r} \not \approx_{E^{\prime}} \phi_{2 \mid r}$.
If $M$ is of sort $s$, by Lemma 3 there exist terms $M^{\prime}$ and $N^{\prime}$ such that $M \phi_{i \mid r}=M_{E} M^{\prime} \overline{\phi_{i \mid r}}$ and $N \phi_{i \mid r}={ }_{E} N^{\prime} \overline{\phi_{i \mid r}}$. As $f$ is a valve, $M^{\prime}$ and $N^{\prime}$ do not involve any symbol $f$. By sufficient completeness of $E$ w.r.t. $\{f\}$, we can consider frames $\overline{\phi_{1 \mid r}}$ and $\overline{\phi_{2 \mid r}}$ that do not involve $f, M^{\prime} \overline{\phi_{i \mid r}}$ and $N^{\prime} \overline{\phi_{i \mid r}}$ do not involve $f$ either. As $E^{\prime}$ is sufficient without $f$ we have that $M^{\prime} \overline{\phi_{i \mid r}}={ }_{E} N^{\prime} \overline{\phi_{i \mid r}}$ iff $M^{\prime} \overline{\phi_{i \mid r}}={ }_{E^{\prime}} N^{\prime} \overline{\phi_{i \mid r}}$. Hence $\overline{\phi_{1 \mid r}} \not \chi_{E^{\prime}} \overline{\phi_{2 \mid r}}$ and $\overline{\phi_{1 \mid r}} \phi_{1 \mid s} \not \not_{E^{\prime}} \overline{\phi_{2 \mid r}} \phi_{2 \mid s}$.
(3) if $\phi_{1 \mid r} \not \mathscr{E}_{E^{\prime}} \phi_{2 \mid r}$ then $\phi_{1 \mid r} \not \mathscr{z}_{E} \phi_{2 \mid r}$

As $\phi_{1 \mid r} \not \overbrace{E^{\prime}} \phi_{2 \mid r}$ there exist terms $M$ and $N$ distinguishing $\phi_{1 \mid r}$ and $\phi_{2 \mid r}$.
If there are no terms $M$ and $N$ of sort $r$ distinguishing $\phi_{1 \mid r}$ and $\phi_{2 \mid r}$, by Lemma 5 there are no terms of sort $s$ distinguishing $\phi_{1 \mid r}$ and $\phi_{2 \mid r}$. Hence if $\phi_{1 \mid r} \not \boldsymbol{z}_{E^{\prime}} \phi_{2 \mid r}$ then there are terms $M$ and $N$ distinguishing $\phi_{1 \mid r}$ and $\phi_{2 \mid r}$ of sort $r$.

If $M$ is of sort $r$, as $f$ is a valve, $M, N, \phi_{1 \mid r}$ and $\phi_{2 \mid r}$ do not involve any $f$. Hence $M \phi_{i \mid r}$ and $N \phi_{i \mid r}$ do not involve $f$. As $E^{\prime}$ is sufficient without $f$ we have that $M \phi_{i \mid r}=E_{E^{\prime}} N \phi_{i \mid r}$ iff $M \phi_{i \mid r}={ }_{E} N \phi_{i \mid r}$. Hence $\phi_{1 \mid r} \not \approx_{E} \phi_{2 \mid r}$.

We denote by $E^{-r}$ the equational theory $E$ without equations of sort $r$.
Corollary 1. Let $E$ be an equational theory on the sorted signature $(\mathcal{S}, \mathcal{F} \cup\{f\})$ such that (i) $f$ is a valve, (ii) $E$ is a reducible equational theory for $f$, and (iii) $E$ is sufficiently complete w.r.t. $\{f\}$. If there exists an equational theory $E^{\prime}$ sufficient for $E$ without $f$ then for any $\{r, s\}$-sorted frames $\phi_{1}$ and $\phi_{2}$, we have that $\phi_{1} \approx_{E} \phi_{2}$ iff $\phi_{1 \mid r} \approx_{E^{\prime-s}} \phi_{2 \mid r}$ and $\overline{\phi_{1 \mid r}} \phi_{1 \mid s} \approx_{E^{\prime-r}} \overline{\phi_{2 \mid r}} \phi_{2 \mid s}$.

Proof. By Theorem 1, we have $\phi_{1} \approx_{E} \phi_{2}$ iff $\phi_{1 \mid r} \approx_{E^{\prime}} \phi_{2 \mid r}$ and $\overline{\phi_{1 \mid r}} \phi_{1 \mid s} \approx_{E^{\prime}}$ $\overline{\phi_{2 \mid r}} \phi_{2 \mid s}$.

By Lemma 5, we have that if for any two terms $M$ and $N$ of sort $r\left(M={ }_{E}\right.$ $N) \phi_{1} \operatorname{iff}\left(M={ }_{E} N\right) \phi_{2}$, then for any two terms $M$ and $N$ of sort $s,\left(M={ }_{E} N\right) \phi_{1}$ iff $\left(M={ }_{E} N\right) \phi_{2}$. Hence it is sufficient to consider terms of sort $r$ to decide static equivalence between $\phi_{1 \mid r}$ and $\phi_{2 \mid r}$. As $f$ is a valve for any term $M$, no subterms of $M$ are of sort $s$. We can consider only $E^{\prime-r}$ to decide static equivalence between $\phi_{1 \mid r}$ and $\phi_{2 \mid r}$.

Let us show that $\overline{\phi_{1 \mid r}} \phi_{1 \mid s} \approx_{E^{\prime}} \overline{\phi_{2 \mid r}} \phi_{2 \mid s}$ iff $\overline{\phi_{1 \mid r}} \phi_{1 \mid s} \approx_{E^{\prime-r}} \overline{\phi_{2 \mid r}} \phi_{2 \mid s}$.
$\overline{\phi_{1 \mid r}} \phi_{1 \mid s} \not \nsim E_{E^{\prime}} \overline{\phi_{2 \mid r}} \phi_{2 \mid s}$ iff there are two terms $M$ and $N$ distinguishing $\overline{\phi_{1 \mid r}} \phi_{1 \mid s}$ and $\overline{\phi_{2 \mid r}} \phi_{2 \mid s}$. As $f$ is a valve, there exist $M$ and $N$ that do not involve any symbol $f$. As $E$ is sufficiently complete w.r.t. $\{f\}$ we can suppose that frames $\overline{\phi_{1 \mid r}} \phi_{1 \mid s}$ and $\overline{\phi_{2 \mid r}} \phi_{2 \mid s}$ do not involve $f$. Hence $M \overline{\phi_{i \mid r}} \phi_{i \mid s}$ and $N \overline{\phi_{i \mid r}} \phi_{i \mid s}$ do not involve $f$ either. As $f$ is a valve $M \overline{\phi_{i \mid r}} \phi_{i \mid s}$ and $N \overline{\phi_{i \mid r}} \phi_{i \mid s}$ do not involve subterms of sort $r$ we have that $M \overline{\phi_{i \mid r}}=E_{E^{\prime}} N^{\prime} \overline{\phi_{i \mid r}}$ iff $M \overline{\phi_{i \mid r}} \phi_{i \mid s}={ }_{E^{\prime-r}} N \overline{\phi_{i \mid r}} \phi_{i \mid s}$. Hence $\overline{\phi_{1 \mid r}} \phi_{1 \mid s} \not \overbrace{E^{\prime-r}} \overline{\phi_{2 \mid r}} \phi_{2 \mid s}$.

## 6 A criterion for sufficient equational theories

In this section we make a first attempt to find sufficient criteria for applying Theorem 1. Future work includes finding broader criteria. We also briefly explain how our running example fits this criterion.

Definition 10 (decomposition). A pair $\left(\mathcal{R}, E^{\prime}\right)$ is a decomposition of an equational theory $E$ iff
$-E^{\prime}$ is an equational theory,
$-\mathcal{R}$ is a rewriting system convergent modulo $E^{\prime}$,

- for any terms $u$ and $v u=_{E} v$ iff $u \downarrow_{\mathcal{R} / E^{\prime}}=v \downarrow_{\mathcal{R} / E^{\prime}}$.

Definition 11 (exclusively define). Let $(\mathcal{S}, \mathcal{F} \uplus\{f\})$ be a sorted signature. A rewriting system $\mathcal{R}$ exclusively defines $f$ if any term in normal form modulo $\mathcal{R} / E^{\prime}$ is in $T(\mathcal{F}, \mathcal{N})$ and if for any rewrite rule $l \rightarrow r \in \mathcal{R}$, $f$ appears in $l$.

Lemma 6. Let $(\mathcal{S}, \mathcal{F} \uplus\{f\})$ be a signature. If a theory $E$ on this signature has a decomposition $\left(\mathcal{R}, E^{\prime}\right)$ and if $\mathcal{R}$ exclusively defines $f$ then $E^{\prime}$ is sufficient for $E$ without $f$.

Proof. Let $u$ and $v$ be two terms not involving $f$. As $\mathcal{R}$ exclusively defines $f$ and as $u$ and $v$ do not involve any $f$ symbol, no rule of $\mathcal{R}$ can be applied. Hence $u={ }_{E} v$ iff $u=E_{E^{\prime}} v$.

Example 5 (continued). We define $\mathcal{R}_{\mathrm{BP}}$ to be the rewriting system obtained by orienting the rule $e\left(\exp _{1}(x), \exp _{1}(y)\right)=\exp _{2}(x \cdot y)$ from left to right, and $E_{\mathrm{BP}}^{\prime}$ the equational theory $E_{\mathrm{BP}}$ without this rule. We remark that $\left(\mathcal{R}, E_{\mathrm{BP}}^{\prime}\right)$ is a decomposition of $E_{\mathrm{BP}}$ and it is easy to see that $\mathcal{R}$ exclusively defines $e$.

Corollary 2. If the set of names of sorts $G_{1}$ and $G_{2}$ are empty, static equivalence for $E_{B P}$ is decidable for $\left\{G_{1}, G_{2}\right\}$-sorted frames.

Proof. As $\mathcal{R}_{\mathrm{BP}}$ exclusively defines $e$, by Lemma 6, we have that $E_{\mathrm{BP}}^{\prime}$ is sufficient for $E_{\mathrm{BP}}$ without $e$. By Proposition 1 we have that $E_{\mathrm{BP}}$ is reducible for $f$. Finally, as the set of names of sorts $G_{1}$ and $G_{2}$ is empty, $E_{\mathrm{BP}}$ is sufficiently complete for $e$. Hence by Corollary 1, for two frames $\phi_{1}$ and $\phi_{2}, \phi_{1} \approx_{E} \phi_{2}$ iff $\phi_{1 \mid G_{1}} \approx_{E_{\mathrm{BP}}^{\prime}-G_{2}} \phi_{2 \mid G_{1}}$ and $\overline{\phi_{1 \mid G_{1}}} \phi_{1 \mid G_{2}} \approx_{E_{\mathrm{BP}}^{\prime}-G_{1}} \overline{\phi_{2 \mid G_{1}}} \phi_{2 \mid G_{2}}$.

As $E_{\mathrm{BP}}^{\prime-G_{2}}$ and $E_{\mathrm{BP}}^{\prime-G_{1}}$ correspond both to the classical equational theory modelling Diffie-Hellman, which is known to be decidable [13] for frames whose only names are of sort $R$ we have that static equivalence is decidable for $E_{\mathrm{BP}}$ on $\left\{G_{1}, G_{2}\right\}$-sorted frames.

## 7 Conclusion and future work

In this paper we have defined the notions of valve and reducibility which allow to simplify equational theories for the decision of static equivalence. This constitutes a first step towards finding generic criteria. Our results apply to the case of bilinear pairing. We believe that this result may apply to other situations where several algebraic structures are used in the model of the same cryptographic operator. In the short term we are investigating the following directions:
(1) We are trying to identify criteria for reducibility which are easier to decide. Even on our quite simple example, proving reducibility is a bit technical. Hence we are trying to determine either syntactic criteria on the equational theory, or more classical properties as a constrained form of sufficient completeness, that would imply reducibility.
(2) In this paper we have analyzed the case where there is only one reducible valve in an equational theory. Extending reducibility to the case where several valves belong to the theory seems possible. However it requires defining a priority order on the reductions of the different valves.
(3) We are also trying to widen the notion of valve. In the definition we propose here, a valve is defined from a given sort to another. Yet cases where
a valve takes as argument terms of different sorts can be considered. We think that such a notion could give rise to a wider notion of reducibility than the one we have analyzed. It seems that we need conditions on the links between the arguments of such valves.

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