# Symbolic Bisimulation <br> for the Applied Pi Calculus * 

Stéphanie Delaune ${ }^{1} \quad$ Steve Kremer ${ }^{1}$<br>Mark D. Ryan ${ }^{2}$<br>${ }^{1}$ LSV, ENS Cachan \& CNRS \& INRIA, France<br>${ }^{2}$ School of Computer Science, University of Birmingham, UK


#### Abstract

We propose a symbolic semantics for the finite applied pi calculus. The applied pi calculus is a variant of the pi calculus with extensions for modelling cryptographic protocols. By treating inputs symbolically, our semantics avoids potentially infinite branching of execution trees due to inputs from the environment. Correctness is maintained by associating with each process a set of constraints on terms. We define a symbolic labelled bisimulation relation, which is shown to be sound but not complete with respect to standard bisimulation. We explore the lack of completeness and demonstrate that the symbolic bisimulation relation is sufficient for many practical examples. This work is an important step towards automation of observational equivalence for the finite applied pi calculus, e.g. for verification of anonymity or strong secrecy properties.


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## 1 Introduction

The applied pi calculus [2] is a derivative of the pi calculus [21] that is specialised for modelling cryptographic protocols. Participants in a protocol are modelled as processes, and the communication between them is modelled by means of channels, names and message passing. The main difference with the pi calculus is that the applied pi calculus allows one to manipulate complex data, instead of just names. These data are generated by a term algebra and equality is treated modulo an equational theory. For instance the equation $\operatorname{dec}(\operatorname{enc}(x, y), y)=x$ models the fact that encryption and decryption with the same key cancel out in the style of the Dolev-Yao model [16]. Such complex data requires the use of a special kind of processes called active substitutions. As an example consider the following process and reduction step:

$$
\nu a, k . \operatorname{out}(c, \operatorname{enc}(a, k)) . P \xrightarrow{\nu x . \operatorname{out}(c, x)} \nu a, k .\left(P \mid\left\{{ }^{\operatorname{enc}(a, k)} / x\right\}\right) .
$$

The process outputs a secret name $a$ which has been encrypted with the secret key $k$ on a public channel $c$. The active substitution $\{\operatorname{enc}(a, k) / x\}$ gives the environment the ability to access the term enc $(a, k)$ via the fresh variable $x$ without revealing $a$ or $k$. The applied pi calculus also generalizes the spi calculus [3] which only allows a fixed set of built-in primitives (symmetric and public-key encryption), while the applied pi calculus allows one to define a variety of primitives by means of an equational theory.

One of the difficulties in automating the proof of properties of systems is the infinite number of possible behaviours of the attacker, even in the case that the process itself is finite. When the process requests an input from the environment, the attacker can give any term which can be constructed from freely available data and the terms it has learned so far in the protocol, and therefore the execution tree of the process is potentially infinite-branching. To address this problem, researchers have proposed symbolic abstractions of processes, in which terms input from the environment are represented as symbolic variables, together with some constraints. These constraints describe the knowledge of the attacker (and therefore, the range of possible values of the symbolic variable) at the time the input was performed.

Reachability properties can be verified by deciding satisfiability of constraint systems resulting from symbolic executions of process algebras (e.g. [20, 4]). Similarly, off-line guessing attacks coded as static equivalence between process states [5] can be decided using such symbolic executions, but this requires one to check the equivalence of constraint systems, rather than satisfiability. Decision procedures for both satisfiability [11] and equivalence [5] of constraint systems exist for significant families of equational theories. Observational equivalence properties, which can be characterized as a bisimulation, express the inability of the attacker to distinguish between two processes no matter how it interacts with them. These properties are useful for modelling anonymity and privacy properties (e.g. [12]), as well as strong secrecy. In the spi calculus [3] properties were actually expressed as a testing relation and bisimulation was used as a proof
technique. Symbolic methods have also been used for bisimulation in process algebras [18, 9]. In particular, Borgström et al. [10] define a sound symbolic bisimulation for the spi calculus.

In this paper we propose a symbolic semantics for the applied pi calculus together with a sound symbolic bisimulation. To show that a symbolic bisimulation implies the concrete one, we generally need to prove that the symbolic semantics is both sound and complete. The semantics of the applied pi calculus is not well suited for defining such a symbolic semantics. In particular, we argue at the beginning of Part I that defining a symbolic structural equivalence which is both sound and complete seems impossible. The absence of sound and complete symbolic structural equivalence significantly complicates the proof of our main result. We therefore split it into two parts. We define a more restricted semantics which will provide an intermediate representation of applied pi calculus processes (Part I). These intermediate processes are a selected (but sufficient) subset of the original processes. One may think of them as being processes in some kind of normal form. We equip these intermediate processes with a labelled bisimulation that coincides with the original one. Then we present a symbolic semantics which is both sound and complete with respect to the intermediate one and give a sound symbolic bisimulation (Part II).

To keep track of the constraints on symbolic variables we associate a constraint system to each symbolic process. Keeping these constraint systems separate from the process allows us to have a clean division between the bisimulation and the constraint solving part. In particular we can directly build on existing work [5] and obtain a decision procedure for our symbolic bisimulation for a significant family of equational theories whenever the constraint system does not contain disequalities. This corresponds to the fragment of the applied pi calculus without else branches in the conditional. For this fragment, one may also notice that our symbolic semantics can be used to verify reachability properties using the constraint solving techniques from [11]. Another side-effect of the separation between the processes and the constraint system is that we forbid $\alpha$-conversion on symbolic processes as we lose the scope of names in the constraint system, but allow explicit renaming when necessary (using naming environments). We believe that the simplicity of our intermediate calculus (especially the structural equivalence) and the absence of $\alpha$-conversion is appealing in view of an implementation.

Finally, one may note that as in $[10,8]$, our technique for deciding bisimulation is incomplete. However, we argue that our technique works for many interesting cases. This is the purpose of Part III. Most of the proofs are in Appendix. Those that are omitted can be found in [15].

## 2 The Applied Pi Calculus

The applied pi calculus [2] is a language for describing concurrent processes and their interactions. It is based on the pi calculus [21], but is intended to be less pure and therefore more convenient to use. In this paper we only consider the
finite applied pi calculus which does not have replication.

### 2.1 Syntax and Informal Semantics

To describe processes in the applied pi calculus, one starts with a set of names (which are used to name communication channels or other constants), a set of variables, and a signature $\Sigma$ which consists of the function symbols which will be used to define terms. In the case of security protocols, typical function symbols will include enc for encryption, which takes a plaintext and a key and returns the corresponding ciphertext, and dec for decryption, taking a ciphertext and a key and returning the plaintext (if the decryption key matches the encryption). Terms are defined as names, variables, and function symbols applied to other terms. We write $\operatorname{vars}(T)$ for the set of variables occurring in $T$. When $\operatorname{vars}(T)=$ $\emptyset$ we say that the term $T$ is ground.

We rely on a sort system for terms. It includes a universal base type and a channel type. We denote by $\mathcal{N}$ the set of names and among those names we distinguish the set $\mathcal{N}_{c h}$ of channel names. Similarly, we denote by $\mathcal{X}$ the set of variables. Among those variables, we distinghuish two disjoint sets: $\mathcal{X}_{b}$ the set of variables of base type and $\mathcal{X}_{c h}$ the set of variables of channel type. Of course function symbol application must respect sorts and arities. Function symbols cannot be applied to variables or names of channel sort, and cannot return terms of that sort, so in fact the only terms of channel sort are variables and names of that sort.

We define the equations which hold on terms constructed from the signature as an equational theory E . We denote $=_{\mathrm{E}}$ the equivalence relation induced by E .

Example 2.1 A typical example of an equational theory is defined by the equation $\operatorname{dec}(\operatorname{enc}(x, k), k)=x$. Let $T_{1}=\operatorname{dec}\left(\operatorname{enc}\left(\operatorname{enc}\left(n, k_{1}\right), k_{2}\right), k_{2}\right)$ and $T_{2}=\operatorname{enc}\left(n, k_{1}\right)$. We have that $T_{1}={ }_{\mathrm{E}} T_{2}$ (while obviously the syntactic equality $T_{1}=T_{2}$ does not hold).

In the applied pi calculus, one has plain processes, denoted by $P, Q, R$ and extended processes, denoted by $A, B, C$. Plain processes are built up in a similar way to processes in the pi calculus, except that messages can contain terms (rather than just names). In the grammar described below, $M$ and $N$ are terms, $n$ is a name, $x$ a variable and $u$ is a metavariable, standing either for a name or a variable. Extended processes add active substitutions, and restriction on names and variables.

| $P, Q, R:=$ plain processes | $A, B, C:=$ extended processes |
| :---: | :---: |
| 0 | $P$ |
| $P \mid Q$ | $A \mid B$ |
| $\nu n . P$ | $\nu n . A$ |
| if $M=N$ then $P$ else $Q$ | $\nu x . A$ |
| in $(u, x) . P$ | $\left\{{ }^{M} / x\right\}$ |
| $\operatorname{out}(u, N) . P$ |  |

The substitution $\left\{{ }^{M} / x\right\}$ replaces the variable $x$ with the term $M(x$ and $M$ have the same sort which is required to be a base sort). Active substitutions generalise "let". The process $\nu x .\left(\left\{{ }^{M} / x\right\} \mid P\right)$ corresponds exactly to the process "let $x=M$ in $P$ ". As usual, names and variables have scopes, which are delimited by restrictions and by inputs. We write $f v(A), b v(A), f n(A)$ and $b n(A)$ for the sets of free and bound variables and free and bound names of $A$, respectively. In an extended process, there is at most one substitution for each variable, and there is exactly one when the variable is restricted. We say that an extended process is closed if all its variables are either bound or defined by an active substitution. We also allow the usual abuse of notations: we omit trailing 0 processes and "else 0 " branches in conditionals and write $\nu u_{1}, u_{2}, \ldots, u_{n}$ instead of $\nu u_{1} \cdot \nu u_{2} . \ldots . \nu u_{n}$.

Active substitutions are useful because they allow us to map an extended process $A$ to its frame $\phi(A)$ by replacing every plain process in $A$ with 0 . A frame is an extended process built up from 0 and active substitutions by parallel composition and restriction. The frame $\phi(A)$ can be viewed as an approximation of $A$ that accounts for the static knowledge $A$ exposes to its environment, but not $A$ 's dynamic behaviour. The domain of a frame $\varphi$ denoted by dom $(\varphi)$, is the set of variables for which $\varphi$ defines a substitution (those variables $x$ for which $\varphi$ contains a substitution $\left\{{ }^{M} / x\right\}$ not under a restriction on $x$ ). We also define the domain of an extended process $A$, written $\operatorname{dom}(A)$ to be the domain of its frame, i.e., $\operatorname{dom}(A)=\operatorname{dom}(\phi(A))$.

An evaluation context $C[-]$ is an extended process with a hole instead of an extended process.

### 2.2 Semantics

The operational semantics of processes in the applied pi calculus is defined by structural rules defining two relations: structural equivalence and internal reduction.

Structural equivalence, noted $\equiv$, is the smallest equivalence relation on extended processes that is closed under $\alpha$-conversion on names and variables, application of evaluation contexts, and such that:

| Par-0 | $A \mid 0 \equiv$ | A |  |
| :---: | :---: | :---: | :---: |
| Par-A | $A \mid(B \mid C) \equiv$ | $(A \mid B) \mid C$ |  |
| Par-C | $A \mid B \equiv$ | $B \mid A$ |  |
| New-0 | $\nu n .0$ 三 | 0 |  |
| New-C | $\nu u . \nu v . A \equiv$ | עv. $\nu u . A$ |  |
| New-Par | $A \mid \nu u . B \equiv$ | $\nu u .(A \mid B)$ | if $u \notin f n(A) \cup f v(A)$ |
| Alias | $\nu x .\left\{{ }^{M} / x\right\} \equiv$ | 0 |  |
| Subst | $\left\{{ }^{M} / x\right\} \mid A \equiv$ | $\left\{{ }^{M} / x\right\} \mid A\left\{{ }^{M} / x\right\}$ |  |
| Rewrite | $\left\{{ }^{M / x}\right\} \equiv$ | $\{N / x\}$ | if $M={ }_{\mathrm{E}} N$ |

We also define $={ }_{\alpha}$ for equality closed under $\alpha$-renaming.
Example 2.2 Let $P=\nu s, k$.(out $\left(c_{1}, \operatorname{enc}(s, k)\right) \mid \operatorname{in}\left(c_{1}, y\right)$.out $\left.\left(c_{2}, \operatorname{dec}(y, k)\right)\right)$. The first component publishes the message enc $(s, k)$ by sending it on $c_{1}$. The second one receives a message on $c_{1}$, uses the secret key $k$ to decrypt it, and forwards the resulting plaintext on $c_{2}$. The process $P$ is structurally equivalent to the following extended process $A$ :

$$
A=\nu s, k, x_{1} .\left(\operatorname{out}\left(c_{1}, x_{1}\right)\left|\operatorname{in}\left(c_{1}, y\right) \cdot \operatorname{out}\left(c_{2}, \operatorname{dec}(y, k)\right)\right|\left\{\operatorname{enc}(s, k) / x_{1}\right\}\right)
$$

We have $\phi(A)=\nu s, k, x_{1} \cdot\left\{{ }^{\operatorname{enc}(s, k)} / x_{1}\right\} \equiv 0 \quad$ (since $x_{1}$ is under a restriction).
As already noted in [2], any closed frame is structurally equivalent to a sequence of active substitutions under some restricted names $\nu \tilde{n} .\left\{{ }^{M_{1}} / x_{1}\right\}|\ldots|$ $\left\{{ }^{M_{k}} / x_{k}\right\}$. Therefore, we sometimes refer to such a frame as $\nu \tilde{n} . \sigma$ where $\sigma$ is the substitution of terms for variables obtained by taking the union of the active substitutions.

Internal reduction, noted $\rightarrow$, is the smallest relation on extended processes closed under structural equivalence and application of evaluation contexts such that

| Comm | $\operatorname{out}(a, M) \cdot P \mid \operatorname{in}(a, x) \cdot Q$ | $\rightarrow P \mid Q\left\{{ }^{M} / x\right\}$ |
| :--- | ---: | :--- |
| Then | if $M=N$ then $P$ else $Q$ | $\rightarrow P$ |
| ElSE | if $M=N$ then $P$ else $Q$ | $\rightarrow Q$ |
|  | for any ground terms $M$ |  |
|  | and $N$ such that $M \neq \mathrm{E} N$ |  |

Note that the presentation of the communication rule (COMM) slightly differs from the one given in [2], but our presentation is easily shown to be equivalent to theirs. The above presentation is closer to our symbolic semantics and therefore more convenient for the purpose of this paper. Comparisons (Then and Else) are kept unchanged and directly depend on the underlying equational theory; using Else sometimes requires that active substitutions in the context be applied first, to yield ground terms $M$ and $N$. Terms $M$ and $N$ are required to be ground in the rule ELSE because disequality is not stable under substitution of terms for variables, unlike equality which explains the absence of this condition in the Then rule.

The operational semantics is extended by a labelled operational semantics enabling us to reason about processes that interact with their environment. Labelled operational semantics defines the relation $\xrightarrow{\alpha}$ where $\alpha$ is either in $(a, M)$ ( $a$ is a channel name and $M$ is a term that can contain names and variables), or $\nu x$.out $(a, x)$ ( $x$ is variable of base type), or out $(a, c)$ or $\nu c$. out $(a, c)(c$ is a channel name). We adopt the following rules in addition to the internal reduction rules:

IN

$$
\operatorname{in}(a, x) \cdot P \xrightarrow{i n(a, M)} P\left\{{ }^{M} / x\right\}
$$

Out-Ch

Open-Ch

$$
\operatorname{out}(a, c) . P \xrightarrow{\text { out }(a, c)} P
$$

$$
\frac{A \xrightarrow{\text { out }(a, c)} A^{\prime} \quad c \neq a}{\nu c . A \xrightarrow{\nu c . \text { out }(a, c)} A^{\prime}}
$$

Out-T

$$
\operatorname{out}(a, M) . P \xrightarrow{\nu x . \operatorname{out}(a, x)} P \mid\left\{^{M} / x\right\} \quad x \notin f v(P) \cup f v(M)
$$

Scope

$$
\frac{A \xrightarrow{\alpha} A^{\prime} \quad u \text { does not occur in } \alpha}{\nu u \cdot A \xrightarrow{\alpha} \nu u \cdot A^{\prime}}
$$

PAR

$$
\begin{gathered}
A \xrightarrow{\alpha} A^{\prime} \quad b v(\alpha) \cap f v(B)=b n(\alpha) \cap f n(B)=\emptyset \\
A\left|B \xrightarrow{\alpha} A^{\prime}\right| B \\
\frac{A \equiv B \quad B \stackrel{\alpha}{\longrightarrow} B^{\prime} A^{\prime} \equiv B^{\prime}}{A \xrightarrow{\alpha} A^{\prime}}
\end{gathered}
$$

Example 2.3 Consider the process $P$ defined in Example 2.2. We have

$$
\begin{aligned}
& P \xrightarrow{\text { in(c.ox } \left., x_{1}\right)} \nu s, k .\left(\operatorname{in}\left(c_{1}, y\right) \cdot \operatorname{out}\left(c_{2}, \operatorname{dec}(y, k)\right) \mid\left\{\operatorname{enc}(s, k) / x_{1}\right\}\right) \\
& \xrightarrow{\nu x_{2} . \text { out }\left(c_{1}, x_{2}\right)} \nu s, k .\left(\operatorname{out}\left(c_{2}, \operatorname{dec}\left(x_{1}, k\right)\right) \mid\left\{\operatorname{enc}(s, k) / x_{1}\right\}\right) \\
& \nu s, k .\left(\left\{\operatorname{enc}(s, k) / x_{1}\right\} \mid\left\{\operatorname{dec}\left(x_{1}, k\right) / x_{2}\right\}\right)
\end{aligned}
$$

Let $B$ be the extended process obtained after this sequence of reduction steps. We have that $\phi(B) \equiv \nu s, k .\left\{\operatorname{enc}(s, k) / x_{1},{ }^{s} / x_{2}\right\}$.

Our rules differ slightly from those described in [2]. Our rules Out-Ch and Open-Ch can be used only when $c$ is a channel name, whereas in [2] there are identical rules Out-Atom and Open-Atom which can be used to output a channel name or a variable of base type. To handle variables of base types, we have the rule Out-T instead. Out-T can easily be derived from the rules in [2], and, conversely, any application of Out-Atom or Open-Atom involving a variable of base type can be replaced by an application of Out-T, though the label out $(c, x)$ will be replaced by a label $\nu y . o u t(c, y)$ where $y$ is a fresh variable not appearing in the process. Any transition in our semantics is also a transition in [2], but they also allow output of free variables directly. For example, notice that in [2], the process out $(c, M) . P \mid\left\{{ }^{M} / x\right\}$ can transition by label $\nu y$.out $(c, y)$ to $P\left|\left\{{ }^{M} / x\right\}\right|\left\{{ }^{M} / y\right\}$, or by label out $(c, x)$ to $P \mid\left\{{ }^{M} / x\right\}$ (since out $(c, M) . P\left|\left\{^{M} / x\right\} \equiv \operatorname{out}(c, x) . P\right|\left\{{ }^{M} / x\right\}$ ). Our semantics only allows the former transition. In [15], we prove that labelled bisimulation in our system coincides with labelled bisimulation in [2].

### 2.3 Equivalences

We can now define what it means for two frames to be statically equivalent [2].
Definition 2.4 (static equivalence ( $\sim$ ) ) Two closed frames $\varphi_{1}$ and $\varphi_{2}$ are statically equivalent, written $\varphi_{1} \sim \varphi_{2}$, if and only if for some names $\tilde{n}_{1}, \tilde{n}_{2}$ and substitutions $\sigma_{1}, \sigma_{2}$, such that $\varphi_{1} \equiv \nu \tilde{n}_{1} \sigma_{1}, \varphi_{2} \equiv \nu \tilde{n}_{2} \sigma_{2}$, and $\operatorname{dom}\left(\sigma_{i}\right) \cap$ $\operatorname{vars}\left(\operatorname{img}\left(\sigma_{i}\right)\right)=\emptyset$ for $i=1,2$, we have
(i) $\operatorname{dom}\left(\varphi_{1}\right)=\operatorname{dom}\left(\varphi_{2}\right)$,
(ii) for all terms $M, N$ with variables included in $\operatorname{dom}\left(\varphi_{i}\right)$ and using no names occurring in $\tilde{n}_{1}$ or $\tilde{n}_{2}, M \sigma_{1}=\mathrm{E} N \sigma_{1}$ is equivalent to $M \sigma_{2}={ }_{\mathrm{E}} N \sigma_{2}$.

Extended processes $A$ and $B$ are statically equivalent, noted by $A \sim B$, if we have that $\phi(A) \sim \phi(B)$.

Example 2.5 Let $\varphi_{0}=\nu k . \sigma_{0}$ and $\varphi_{1}=\nu k . \sigma_{1}$ where $\sigma_{0}=\left\{\operatorname{enc}\left(s_{0}, k\right) / x_{1}, k / x_{2}\right\}$, $\sigma_{1}=\left\{\operatorname{enc}\left(s_{1}, k\right) / x_{1}, k / x_{2}\right\}$ and $s_{0}, s_{1}$ and $k$ are names. Let E be the theory defined by the axiom $\operatorname{dec}(\operatorname{enc}(x, k), k)=x$. We have $\operatorname{dec}\left(x_{1}, x_{2}\right) \sigma_{0}=\mathrm{E} s_{0}$ but not $\operatorname{dec}\left(x_{1}, x_{2}\right) \sigma_{1}=\mathrm{E} s_{0}$. Therefore we have $\varphi_{0} \nsim \varphi_{1}$. However, note that we have $\nu k .\left\{\operatorname{enc}\left(s_{0}, k\right) / x_{1}\right\} \sim \nu k .\left\{\operatorname{enc}\left(s_{1}, k\right) / x_{1}\right\}$.

Definition 2.6 (labelled bisimilarity $(\approx)$ ) Labelled bisimilarity is the largest symmetric relation $\mathcal{R}$ on closed extended processes, such that $A \mathcal{R} B$ implies

1. $A \sim B$,
2. if $A \rightarrow A^{\prime}$, then $B \rightarrow^{*} B^{\prime}$ and $A^{\prime} \mathcal{R} B^{\prime}$ for some $B^{\prime}$,
3. if $A \xrightarrow{\alpha} A^{\prime}$ and $f v(\alpha) \subseteq \operatorname{dom}(A)$ and bn $(\alpha) \cap f n(B)=\emptyset$, then $B \rightarrow{ }^{*} \xrightarrow{\alpha} \rightarrow^{*}$ $B^{\prime}$ and $A^{\prime} \mathcal{R} B^{\prime}$ for some $B^{\prime}$.

The definition of labelled bisimilarity is like the usual definition of bisimilarity, except that at each step one additionally requires that the processes are statically equivalent. In [2], it is shown that labelled bisimilarity coincides with observational equivalence, which is a relation capturing the fact that two given processes cannot be distinguished by any context. In general, it is easier to work with labelled bisimilarity rather than observational equivalence because of the quantification over all contexts. As mentioned in the introduction, contextually defined equivalences are useful to formalize many security properties, in particular anonymity properties, such as those studied in [12].

## - PART I: Intermediate Calculus -

The idea of a symbolic semantics is to have a notion of process in which terms that have been input from the environment are represented as variables. This allows us to reason in a way that abstracts away from the particular term that was input. Given such a process $P_{s}$, we can create a concrete process (an "instance") $P_{s} \sigma$ by applying a substitution $\sigma$ that maps the input variables to terms. We define the symbolic semantics by means of counterparts $\equiv_{s}, \rightarrow_{s}$, $\xrightarrow{\alpha}_{s}$ for the concrete relations $\equiv, \rightarrow, \xrightarrow{\alpha}$ of applied pi calculus, and aim to show soundness and completeness results relating the symbolic and concrete semantics. Structural equivalence occupies a crucial role in our calculi because the transition relations are closed under structural equivalence; therefore, we would ideally like a notion of symbolic structural equivalence which is sound and complete in the following (informal) sense:

Soundness: $P_{s} \equiv{ }_{s} Q_{s}$ implies for any valid instantiation $\sigma, P_{s} \sigma \equiv Q_{s} \sigma$;
Completeness: $P_{s} \sigma \equiv Q$ implies there exists $Q_{s}$ s.t. $P_{s} \equiv{ }_{s} Q_{s}$ and $Q_{s} \sigma=Q$.
Unfortunately, completeness in this sense appears to be unachievable. To see this, consider the following example:

Example 2.7 Consider the following process:

$$
P=\operatorname{in}(c, x) \cdot \operatorname{in}(c, y) \cdot \operatorname{out}(c, f(x)) \cdot \mathrm{out}(c, g(y)) .
$$

The process $P$ can be reduced to $P^{\prime}=\operatorname{out}\left(c, f\left(M_{1}\right)\right)$.out $\left(c, g\left(M_{2}\right)\right)$ where $M_{1}$ and $M_{2}$ are two arbitrary terms provided by the environment. In the case that $f\left(M_{1}\right)=\mathrm{E} g\left(M_{2}\right)$ we have $P^{\prime} \equiv \nu z .\left(\operatorname{out}(c, z) . \operatorname{out}(c, z) \mid\left\{f\left(M_{1}\right) / z\right\}\right)$, but this structural equivalence does not hold whenever $f\left(M_{1}\right) \neq \mathrm{E} g\left(M_{2}\right)$. The aim of symbolic semantics is to avoid instantiating the variables $x$ and $y$; the process $P$ would reduce symbolically to $P_{s}^{\prime}=\operatorname{out}(c, f(x))$.out $(c, g(y))$. In this case we need to keep auxiliary information that allows us to infer that $x$ and $y$ may take arbitrary values. The process $P_{s}^{\prime}$ represents the two cases in which $x$ and $y$ are equal or distinct. Hence, the question of whether the symbolic structural equivalence $P_{s}^{\prime} \equiv_{s} \nu z$.(out $\left.(c, z) . \operatorname{out}(c, z) \mid\left\{{ }^{f(x)} / z\right\}\right)$ is valid cannot be decided, as it depends on the concrete values of $x$ and $y$.

Therefore, the notion of symbolic structural equivalence that we will introduce is sound but not complete in the sense above (we will give a weaker completeness result). This seems to be an inherent problem and it propagates to internal and labelled reduction, since they are closed under structural equivalence. In Example 2.7, the control flow is not affected by whether $f(x)=\mathrm{E} g(y)$. When control flow is affected by conditions on input variables, we maintain those conditions as a set of constraints. This allows us to give a soundness result for symbolic labelled bisimulation.

Unfortunately, the fact that we are unable to have a notion of symbolic structural equivalence which is both sound and complete in the sense mentioned above
significantly complicates the proof of our main result. We therefore split it into two parts. In this part, we define a more restricted semantics which will provide an intermediate representation of applied pi calculus processes (Section 3). These intermediate processes are a selected (but sufficient) subset of the original processes. One may think of them as being processes in some kind of normal form. We equip these intermediate processes with a labelled bisimulation that coincides with the original one (Section 5).

## 3 Syntax and Semantics

### 3.1 Syntax

One has intermediate plain processes (denoted by $P, Q, R$ ), intermediate framed processes $(F, G, H)$, and intermediate extended processes $(A, B, C)$.

| $P, Q, R:=$ inter. plain process | $F, G, H:=$ | inter. framed process |
| :---: | :---: | :---: |
| 0 | $P$ |  |
| $P \mid Q$ | $\left\{{ }^{M} / x\right\}$ |  |
| if $M=N$ then $P$ else $Q$ | $F \mid G$ |  |
| $\operatorname{in}(u, x) . P$ | $A, B, C:=$ | inter. extended process |
| $\operatorname{out}(u, N) . P$ | $F$ |  |
|  | $\nu n . A$ |  |

Additionally, we require intermediate extended processes to be

- name and variable distinct (nv-distinct): $b n(A) \cap f n(A)=b v(A) \cap f v(A)=\emptyset$ and any name and variable is at most bound once; and
- applied, meaning that each variable in $\operatorname{dom}(A)$ occurs only once in $A$ (the occurrence in the substitution is the only one).

Intuitively, an intermediate process is applied if all active substitutions have been applied. Intermediate extended processes are a kind of normal form for extended processes. Because they are applied and nv-distinct, we do not need restriction $\nu x$ on variables $x$, and all $\nu n$ for names $n$ occur at the beginning of the process (which is possible as our language does not have replication).

Example 3.1 The extended process out $(c, x) \mid\left\{{ }^{M} / x\right\}$ is not applied, as $x$ occurs twice. The corresponding intermediate process would be out $(c, M) \mid\left\{{ }^{M} / x\right\}$.

As expected, an intermediate context is an intermediate extended process with a hole and similarly an intermediate framed context is an intermediate framed process with a hole. An intermediate (framed) evaluation context is a (framed) context whose hole is not under a conditional, an input or an output. We say that such a context $C[-]$ is a context w.r.t. an extended intermediate process $A$ if and only if $C[A]$ is an extended intermediate process. For instance, the context $\nu n .\left(B \mid \_\right)$would not be a context for any $A$ such that $n \in f n(A) \cup$ $b n(A)$ as $\nu n .(B \mid A)$ would violate nv-distinctness.

As we do not allow $\alpha$-conversion we explicitly run intermediate extended processes in a naming environment.

Definition 3.2 (naming environment) $A$ naming environment

$$
\mathrm{N}: \mathcal{N} \cup \mathcal{X} \rightarrow\{\mathrm{n}, \mathrm{f}, \mathrm{~b}\}
$$

is a function which maps each name and variable to one of n , $\mathrm{f}, \mathrm{b}$ (standing for "new", "free" and "bound" respectively), such that there are infinitely many names and infinitely many variables that are mapped to each of $\mathrm{n}, \mathrm{f}$ and b . (More precisely, the sets $\mathrm{N}^{-1}(\mathrm{n}) \cap \mathcal{X}, \mathrm{N}^{-1}(\mathrm{n}) \cap \mathcal{N}, \mathrm{N}^{-1}(\mathrm{f}) \cap \mathcal{X}, \mathrm{N}^{-1}(\mathrm{f}) \cap \mathcal{N}$, $\mathrm{N}^{-1}(\mathrm{~b}) \cap \mathcal{X}$, and $\mathrm{N}^{-1}(\mathrm{~b}) \cap \mathcal{N}$ are all infinite.)

Intuitively, $\mathrm{N}(u)=\mathrm{f}$ if the name or variable $u$ occurs free in $A$, and $\mathrm{N}(u)=\mathrm{b}$ if the name or variable $u$ has been bound and will not be used again. $\mathrm{N}(u)=\mathrm{n}$ means that the name or variable is new and has not been used before, either as free or bound. This discipline helps us avoid name and variable conflicts. We use standard notation for function updating: if $\mathrm{N}(u)=t$ then the naming environment $\mathrm{N}^{\prime}=\mathrm{N}\left[u \mapsto t^{\prime}\right]$ is defined to be the same as N except that $\mathrm{N}^{\prime}(u)=$ $t^{\prime}$; and $\mathrm{N}\left[U \mapsto t^{\prime}\right]$ is defined as $\mathrm{N}\left[u_{1} \mapsto t^{\prime}, \ldots, u_{n} \mapsto t^{\prime}\right]$ if $U=\left\{u_{1}, \ldots, u_{n}\right\}$. If $U$ is a set of names and variables then $\mathrm{N}(U)=\{\mathrm{N}(u) \mid u \in U\}$ and we write $\mathrm{N}(U)=t$ if $\mathrm{N}(U) \subseteq\{t\}$.

Definition 3.3 (compatible) We say that a naming environment N is compatible with an nv-distinct process $A$ if $\mathrm{N}(b n(A) \cup b v(A))=\mathrm{b}$ and $\mathrm{N}(f n(A) \cup f v(A))=\mathrm{f}$. A naming environment N is compatible with a label $\alpha$ if $\mathrm{N}(b n(\alpha) \cup b v(\alpha))=\mathrm{n}$ and $\mathrm{N}(f n(\alpha) \cup f v(\alpha))=\mathrm{f}$.

Requesting that $\mathrm{N}(b n(\alpha) \cup b v(\alpha))=\mathrm{n}$ may seem strange with respect to the original semantics. However, the intermediate semantics, that we present in the following subsection, should clarify this point.

We define an intermediate process to be a pair $(A ; \mathrm{N})$ where $A$ is an intermediate extended process and N a naming environment, compatible with $A$. Moreover, $(A ; \mathbf{N})$ is closed if $A$ is closed. We denote by $\psi(A)$ the substitution obtained by taking the union of the active substitutions $\left\{{ }^{M} / x\right\}$ occurring in $A$. Note that $\phi(A)$ denotes the frame of the process including the name restrictions, while $\psi(A)$ only refers to the substitution.

Throughout the paper we always suppose that substitutions are cycle-free and use the following notational conventions for substitution. Given substitutions $\sigma_{1}=\left\{{ }^{M_{1}} / x_{1}, \ldots,{ }^{M_{p}} / x_{p}\right\}$ and $\sigma_{2}=\left\{{ }^{N_{1}} / y_{1}, \ldots,{ }^{N_{q}} / y_{q}\right\}$ we write $\sigma_{1} \cup \sigma_{2}$ for $\left\{{ }^{M_{1}} / x_{1}, \ldots,{ }^{M_{p}} / x_{p},{ }^{N_{1}} / y_{1}, \ldots,{ }^{N_{q}} / y_{q}\right\}$ and $\sigma_{1} \sigma_{2}$ for $\left\{{ }^{M_{1} \sigma_{2}} / x_{1}, \ldots,{ }^{M_{p} \sigma_{2}} / x_{p}\right\}$. We define $\operatorname{img}(\sigma)$ to be the image of $\sigma$, e.g., $\operatorname{img}\left(\sigma_{1}\right)=\left\{M_{1}, \ldots, M_{p}\right\}$. Moreover, we write $\sigma^{\star}$ to emphasize that we iterate the substitution until obtaining idempotence. This is needed when $\operatorname{dom}(\sigma) \cap \operatorname{vars}(\operatorname{img}(\sigma)) \neq \emptyset$.

We now define the $\downarrow$ operator which transforms an nv-distinct extended processes into an intermediate extended process.

Definition $3.4(A \downarrow)$ Given an nv-distinct extended process $A$, the intermediate extended process $A \downarrow$ is defined inductively as follows:

$$
\begin{aligned}
& 0 \downarrow=0 \quad \operatorname{in}(u, x) \cdot P \downarrow=\nu \tilde{n} \cdot \operatorname{in}(u, x) \cdot P^{\prime} \quad(\nu n . A) \downarrow=\nu n .(A \downarrow) \\
& \left\{{ }^{M} / x\right\} \downarrow=\left\{{ }^{M} / x\right\} \quad \operatorname{out}(u, N) \cdot P \downarrow=\nu \tilde{n} . \operatorname{out}(u, N) . P^{\prime} \quad(\nu x \cdot A) \downarrow=\tilde{A} \\
& \text { if } M=N \text { then } P \text { else } Q \downarrow=\nu \tilde{n} . \nu \tilde{m} \text {.if } M=N \text { then } P^{\prime} \text { else } Q^{\prime} \\
& (A \mid B) \downarrow=\nu \tilde{n} . \nu \tilde{m} .\left(A^{\prime} \mid B^{\prime}\right)\left(\psi\left(A^{\prime}\right) \cup \psi\left(B^{\prime}\right)\right)^{\star}
\end{aligned}
$$

where $P \downarrow=\nu \tilde{n} . P^{\prime}, Q \downarrow=\nu \tilde{m} . Q^{\prime}, A \downarrow=\nu \tilde{n} . A^{\prime}, B \downarrow=\nu \tilde{m} . B^{\prime}$, and $\tilde{A}$ is $A \downarrow$ but with the unique occurrence of $\left\{{ }^{M} / x\right\}$ replaced by 0 .

The transformation $\downarrow$ consists of:

1. applying active substitutions as much as possible and allows us to get rid of restrictions on variables. This operation preserves structural equivalence since the rules SUBST and ALIAS allows us to do this.
2. pushing the restrictions on names in front of the process. This operation does not preserve structural equivalence (see Example 3.5) but only labelled bisimilarity (Lemma 3.6).

This operation is extended as expected to context. If $C[-]$ is an evaluation context, then $C[-] \downarrow$ is the intermediate evaluation context obtained by applying the above rules, with the additional rule $\downarrow \downarrow=$.

Example 3.5 Let $A=\nu x .\left(\operatorname{in}(c, y) . \nu b_{1} . \operatorname{out}\left(a, b_{1}\right) . \operatorname{out}(a, x) \mid\left\{f\left(b_{2}\right) / x\right\}\right)$. We have that

$$
A \downarrow=\nu b_{1} \cdot\left(\operatorname{in}(c, y) \cdot \operatorname{out}\left(a, b_{1}\right) \cdot \operatorname{out}\left(a, f\left(b_{2}\right)\right) \mid 0\right.
$$

Lemma 3.6 Let $A$ be an nv-distinct extended process. We have that $A \downarrow \approx A$.

### 3.2 Semantics

Structural equivalence $\equiv_{i}$ is the smallest equivalence relation on intermediate processes such that:

| PaR-0 ${ }_{i}$ | $(A ; \mathrm{N})$ | 三 ${ }_{i}$ | $(A \mid 0 ; \mathrm{N})$ |
| :---: | :---: | :---: | :---: |
| Par- ${ }_{i}$ | $(A \mid(B \mid C) ; \mathrm{N})$ | $\equiv{ }_{i}$ | $((A \mid B) \mid C ; \mathrm{N})$ |
| Par-C ${ }_{i}$ | $(A \mid B ; \mathrm{N})$ | $\equiv_{i}$ | $(B \mid A ; \mathrm{N})$ |
| New-C ${ }_{i}$ | ( $\nu n . \nu m . A ; \mathrm{N}$ ) | $\equiv{ }_{i}$ | ( $\nu \mathrm{m} . \nu n . A ; \mathrm{N})$ |

and that is closed by application of intermediate evaluation context, i.e.

$$
\frac{(A ; \mathrm{N}) \equiv_{i}(B ; \mathrm{N})}{(C[A] ; \mathrm{N}[b n(C[0]) \mapsto \mathrm{b}]) \equiv_{i}(C[B] ; \mathrm{N}[b n(C[0]) \mapsto \mathrm{b}])}
$$

Note that, in this intermediate semantics, we have removed several structural equivalence rules such as SUBSt, Rewrite and we do not allow $\alpha$-renaming. In particular, Example 2.7 is not problematic anymore.

Internal reduction $\rightarrow_{i}$ is the smallest relation on intermediate processes closed by structural equivalence ( $\equiv_{i}$ ), by application of intermediate evaluation contexts and such that:

$$
\begin{array}{llll}
\operatorname{Comm}_{i} & (\operatorname{out}(a, M) \cdot P \mid \operatorname{in}(a, x) \cdot Q ; \mathrm{N}) & \rightarrow_{i} & \left(P \mid Q\left\{{ }^{M} / x\right\} ; \mathrm{N}\right) \\
\operatorname{THEN}_{i} & (\text { if } M=N \text { then } P \text { else } Q ; \mathrm{N}) & \rightarrow_{i} & (P ; \mathrm{N}) \quad \text { where } M=\mathrm{E} N \\
\operatorname{ELSE}_{i} & (\text { if } M=N \text { then } P \text { else } Q ; \mathrm{N}) & \rightarrow_{i} & (Q ; \mathrm{N})
\end{array}
$$

for any ground terms $M$ and $N$ such that $M \neq \mathrm{E} N$
Labelled transition $\xrightarrow{\alpha}$. We also extend our intermediate semantics with the following labelled transition relation.
$\mathrm{IN}_{i}$

$$
(\operatorname{in}(a, x) \cdot P ; \mathrm{N}) \xrightarrow{i n(a, M)} i\left(P\left\{{ }^{M} / x\right\} ; \mathrm{N}\right)
$$

where $\mathbf{N}(f n(M) \cup f v(M))=\mathrm{f}$
$\mathrm{Out}^{-\mathrm{CH}_{i}}$

$$
(\operatorname{out}(a, c) \cdot P ; \mathrm{N}) \xrightarrow{\operatorname{out}(a, c)} i(P ; \mathrm{N})
$$

Out- $\mathrm{T}_{i}$

$$
(\operatorname{out}(a, M) . P ; \mathrm{N}) \xrightarrow{\nu x . \operatorname{out}(a, x)} i\left(P \mid\left\{^{M} / x\right\}, \mathrm{N}[x \mapsto \mathrm{f}]\right)
$$

$$
\text { where } x \in \mathcal{X}_{b} \text { and } \mathrm{N}(x)=\mathrm{n}
$$

Open- $^{2} H_{i} \quad \frac{(A ; \mathrm{N}) \xrightarrow{\text { out }(a, c)}{ }_{i}\left(A^{\prime} ; \mathrm{N}^{\prime}\right) \quad c \neq a, d \in \mathcal{N}_{c h}, \mathrm{~N}(d)=\mathrm{n}}{(\nu c . A, \mathrm{~N}[c \mapsto \mathrm{~b}]) \xrightarrow{\nu d . o u t(a, d)}_{i}\left(A^{\prime}\{d / c\}, \mathrm{N}^{\prime}[c \mapsto \mathrm{~b}, d \mapsto \mathrm{f}]\right)}$
$\mathrm{SCOPE}_{i}$

$$
\begin{array}{lc} 
& \frac{(A ; \mathrm{N}) \stackrel{\alpha}{\rightarrow}_{i}\left(A^{\prime}, \mathrm{N}^{\prime}\right) \quad n \text { does not occur in } \alpha}{(\nu n . A ; \mathrm{N}[n \mapsto \mathrm{~b}]) \xrightarrow{\alpha}_{i}\left(\nu n . A^{\prime}, \mathrm{N}^{\prime}[n \mapsto \mathrm{~b}]\right)} \\
\mathrm{PAR}_{i} & \frac{(A ; \mathrm{N}) \xrightarrow{\alpha \psi(B)}}{(A \mid B ; \mathrm{N}) \xrightarrow{\alpha}_{i}\left(A^{\prime} \mid B, \mathrm{~N}^{\prime}\right)} \\
\mathrm{STRUCT}_{i} & \frac{(A ; \mathrm{N}) \equiv_{i}(B ; \mathrm{N}) \xrightarrow{\alpha}_{i}\left(B^{\prime}, \mathrm{N}^{\prime}\right) \equiv_{i}\left(A^{\prime}, \mathrm{N}^{\prime}\right)}{(A ; \mathrm{N}) \xrightarrow{\alpha}\left(A^{\prime}, \mathrm{N}^{\prime}\right)}
\end{array}
$$

One may note two particularities in this semantics. The Open-CH ${ }_{i}$ rule requires an "on-the-fly renaming" at the point that we reveal a bound name. This will be needed in the bisimulation because we require both the left- and right-hand processes to use the same label without allowing $\alpha$-conversion. The second unusual detail is the $\alpha \psi(B)$ label in the $\mathrm{PAR}_{i}$ rule which is needed to keep processes applied. Note that $\psi(B)$ can only affect labels that are of the form $\operatorname{in}(c, M)$ since for the other ones, the variables in $\operatorname{dom}(\psi(B))$ do not occur in the label $\alpha$.

Example 3.7 Let $A=\nu a$.(in $(c, x) \cdot P(x) \mid\{a / y\})$ and $B=\nu a .(P(a) \mid\{a / y\})$. We have that $A \xrightarrow{i n(c, y)} B$. Let N be a naming environment compatible with $A \downarrow$ and $\operatorname{in}(c, y)$. We have also that $(A \downarrow ; \mathrm{N}) \xrightarrow{\text { in }(c, y)}(B \downarrow ; \mathrm{N})$. The derivation witnessing this reduction uses the fact that the label in the $\mathrm{PAR}_{i}$ rule can be instantiated along the derivation.

$$
\frac{\frac{(\operatorname{in}(c, x) \cdot P(x) ; \mathrm{N}) \xrightarrow{i n(c, a)}(P(a) ; \mathrm{N})}{\left(\operatorname{in}(c, x) \cdot P(x) \mid\left\{^{a} / y\right\} ; \mathrm{N}\right) \xrightarrow{\text { in(c,y)}}\left(P(a) \mid\left\{^{a} / y\right\} ; \mathrm{N}\right)}}{\left(\nu a \cdot\left(\operatorname{in}(c, x) \cdot P(x) \mid\left\{^{a} / y\right\}\right) ; \mathrm{N}[a \mapsto \mathrm{~b}]\right) \xrightarrow{i n(c, y)}\left(\nu a \cdot\left(P(a) \mid\left\{^{a} / y\right\}\right) ; \mathrm{N}[a \mapsto \mathrm{~b}]\right)}
$$

In particular we note that if the first label had been in $(c, y)$ the obtained process would have been $(P(y) ; \mathrm{N})$ and the $\mathrm{PAR}_{i}$ rule could not have been used because $P(y) \mid\left\{{ }^{a} / y\right\}$ would not have been an intermediate process (as it is not applied).

## 4 Soundness and Completeness

We now introduce the relation $\approx$ on intermediate processes. Intuitively, $\approx$ captures the structural equivalences that are "missing" in $\equiv_{i}$ with respect to $\equiv$. We show completeness of the intermediate semantics up to $\approx$. Note that the rule $\mathrm{NEW}-\mathrm{C}_{i}$ is in the relation $\approx$ because of some tricky interactions between the transformation $\downarrow$ and the relation $\equiv$ (see Example 4.2 given below).

Definition $4.1(\approx)$ We define $\approx$ to be the smallest equivalence relation on intermediate processes closed under bijective renaming of bound names and variables and such that

$$
\begin{array}{lcll}
\text { NEW-N }_{i} & (\nu \tilde{n} . \nu m \cdot A ; \mathrm{N}) & \approx(\nu \tilde{n} \cdot A ; \mathrm{N}) & \text { if } m \notin f n(A) \\
\mathrm{REW}^{2}-\mathrm{N}_{i} & \left(A\left\{{ }^{M} / x\right\} ; \mathrm{N}\right) & \approx\left(A\left\{{ }^{N} / x\right\} ; \mathrm{N}\right) & \text { if } M=\mathrm{E} N \\
\mathrm{NEW}_{i} & (\nu n \cdot \nu m \cdot A ; \mathrm{N}) & (\nu m \cdot \nu n \cdot A ; \mathrm{N}) &
\end{array}
$$

Example 4.2 Consider the processes: $A=\operatorname{out}\left(c, n_{1}\right) . \nu n_{2} . \nu n_{2}^{\prime} . \operatorname{out}\left(c,\left\langle n_{2}, n_{2}^{\prime}\right\rangle\right)$ and $C=\nu n_{2}^{\prime} . \nu n_{2}$.out $\left(c, n_{1}\right)$.out $\left(c,\left\langle n_{2}, n_{2}^{\prime}\right\rangle\right)$. We have that

$$
A \downarrow=\nu n_{2} . \nu n_{2}^{\prime} .\left(\operatorname{out}\left(c, n_{1}\right) \cdot \operatorname{out}\left(c,\left\langle n_{2}, n_{2}^{\prime}\right\rangle\right) \quad \text { and } \quad A \downarrow \equiv C .\right.
$$

Note that there is no $B$ such that $A \equiv B$ and $B \downarrow=C$. Nevertheless, because of the rule $\mathrm{NEW}-\mathrm{C}_{i}$ there exists $B^{\prime}$ (e.g. $B^{\prime}=A$ ) such that $A \equiv$ $B^{\prime}$ and $\left(B^{\prime} \downarrow ; \mathrm{N}\right) \approx(C ; \mathrm{N})$ for any compatible naming environment N . This property is needed in the proof of Proposition 5.5.

Lemma 4.3 Let $(A ; \mathrm{N})$ and $\left(A^{\prime} ; \mathrm{N}\right)$ be two intermediate processes such that $(A ; \mathrm{N}) \cong\left(A^{\prime} ; \mathrm{N}\right)$. Then we have that $A \equiv A^{\prime}$.

We now show that our intermediate semantics is sound with respect to the original semantics: any structural equivalence and (labelled) reduction that holds in the intermediate context also holds in the original semantics.

Proposition 4.4 (soundness) Let $\left(A_{i} ; \mathrm{N}\right)$ and $\left(B_{i} ; \mathrm{N}^{\prime}\right)$ be two intermediate processes such that $\left(A_{i} ; \mathrm{N}\right) \bowtie_{i}\left(B_{i} ; \mathrm{N}^{\prime}\right)$ with $\bowtie \in\{\equiv, \rightarrow, \xrightarrow{\alpha}\}$. Then we have that $A_{i} \bowtie B_{i}$.

The proofs when $\bowtie \in\{\equiv, \rightarrow\}$ are straightforward and are sketched in Appendix A. The proof for $\xrightarrow{\alpha}$ is more involved and detailed in Appendix A.

We also introduce a useful commutation lemma. As we show completeness for one step of each of these relations up to $\approx$ the commutation lemmas will allow us to lift the result to sequences of steps.

Lemma 4.5 (commutation) Let $(A ; \mathrm{N}),\left(A^{\prime} ; \mathrm{N}\right)$ and $\left(B ; \mathrm{N}^{\prime}\right)$ be three intermediate processes such that $\left(A^{\prime} ; \mathrm{N}\right) \approx(A ; \mathrm{N}) \bowtie\left(B ; \mathrm{N}^{\prime}\right)$ with $\bowtie \in\left\{\equiv_{i}, \rightarrow_{i}, \xrightarrow{\alpha}_{i}\right\}$. Then there exists $\left(B^{\prime} ; \mathrm{N}^{\prime}\right)$ such that $\left(A^{\prime} ; \mathrm{N}\right) \bowtie\left(B^{\prime} ; \mathrm{N}^{\prime}\right) \cong\left(B ; \mathrm{N}^{\prime}\right)$.

Proof.(sketch) This result can be proved by considering proofs in "linear form", i.e., by applying the rules directly under the evaluation context, resulting into a sequence of processes rather than a proof tree. Similarly, the proof of $\left(A^{\prime}\right.$; $\mathrm{N}) \approx(A ; \mathrm{N})$ can be written as a sequence of steps. Now, it is easy to show, by case analysis on each pair of rules, that each time there is an application of $\approx$ occurring immediately to the left of an application of $\equiv_{i}$, this pair of rule applications can be commuted.

Next we show completeness of the intermediate semantics: any structural equivalence and (labelled) reduction that holds in the original semantics should also hold for corresponding intermediate processes in the new semantics. As discussed previously completeness seems difficult to achieve. We therefore show completeness up to $\approx$.

Proposition 4.6 (completeness) Let $A$ and $B$ be two nv-distinct extended processes such that $A \bowtie B$ with $\bowtie \in\{\equiv, \rightarrow, \xrightarrow{\alpha}\}$. Let N be a naming environment compatible with $A \downarrow$ and also with $\alpha$ when $\bowtie=\xrightarrow{\alpha}$. Let $\mathrm{N}^{\prime}$ be a naming environment compatible with $B \downarrow$ and such that:

- $\mathrm{N}^{\prime}=\mathrm{N}[x \mapsto \mathrm{f}]$ when $\bowtie=\xrightarrow{\alpha}$ and $\alpha$ is of the form $\nu x \operatorname{cout}(a, x)$;
- $\mathrm{N}^{\prime}=\mathrm{N}[d \mapsto \mathrm{f}]$ when $\bowtie=\stackrel{\alpha}{\longrightarrow}$ and $\alpha$ is of the form $\nu$ d.out $(a, d)$;
- $\mathrm{N}^{\prime}=\mathrm{N}$ otherwise.

Then there exists an intermediate process $\left(D_{i} ; \mathrm{N}^{\prime}\right)$ such that

- $(A \downarrow ; \mathrm{N}) \bowtie_{i}\left(D_{i} ; \mathrm{N}^{\prime}\right)$, and
- $\left(D_{i} ; \mathrm{N}^{\prime}\right) \approx\left(B \downarrow ; \mathrm{N}^{\prime}\right)$.

Note that, when $\bowtie \in\{\equiv, \rightarrow\}$, we have that $\mathrm{N}^{\prime}=\mathrm{N}$. The proofs are done in Appendix A.

From Propositions 4.4 and 4.6 and the commutation lemma stated above, we derive the following corollaries. (Corollary 4.8 also requires Lemmas A. 5 and A. 8 in the appendix.)

Corollary 4.7 (soundness of $\rightarrow_{i}^{*}$ and $\left.\rightarrow_{i}^{*} \xrightarrow{\alpha} \rightarrow_{i}^{*}\right)$ Let $\left(A_{i} ; \mathrm{N}\right)$ and ( $\left.B_{i} ; \mathrm{N}^{\prime}\right)$ be two intermediate processes such that $\left(A_{i} ; \mathrm{N}\right) \rightarrow_{i}^{*}\left(B_{i} ; \mathrm{N}^{\prime}\right)\left(\operatorname{resp} .\left(A_{i} ; \mathrm{N}\right) \rightarrow_{i}^{*}\right.$ $\left.{ }^{\alpha} \rightarrow_{i}^{*}\left(B_{i} ; \mathrm{N}^{\prime}\right)\right)$. Then we have that $A_{i} \rightarrow^{*} B_{i}\left(\right.$ resp. $\left.A_{i} \rightarrow^{*} \xrightarrow{\alpha} \rightarrow^{*} B_{i}\right)$.

Corollary 4.8 (completeness of $\rightarrow_{i}^{*}$ and $\rightarrow_{i}^{*} \xrightarrow{\alpha}{ }_{i} \rightarrow_{i}^{*}$ ) Let $A$ and $B$ be two nv-distinct extended processes such that $A \rightarrow^{*} B$ (resp. $A \rightarrow^{*} \xrightarrow{\alpha} \rightarrow^{*} B$ ) and N be a naming environment compatible with $A \downarrow$ (resp., and $\alpha$ ). Let $\mathrm{N}^{\prime}$ be a naming environment compatible with $B \downarrow$ and such that:

- $\mathrm{N}^{\prime}=\mathrm{N}[x \mapsto \mathrm{f}]$ in the case $\rightarrow_{i}^{*}{ }^{\alpha}{ }_{i} \rightarrow_{i}^{*}$ when $\alpha$ is of the form $\nu x$.out $(a, x)$;
- $\mathrm{N}^{\prime}=\mathrm{N}[d \mapsto \mathrm{f}]$ in the case $\rightarrow_{i}^{*} \xrightarrow{\alpha} \rightarrow_{i}^{*}$ when $\alpha$ is of the form $\nu d$ d.out $(a, d)$;
- $\mathrm{N}^{\prime}=\mathrm{N}$ otherwise.

Then there exists an intermediate process $\left(D_{i} ; \mathrm{N}^{\prime}\right)$ such that $(A \downarrow ; \mathrm{N}) \rightarrow_{i}^{*}\left(D_{i} ;\right.$ $\left.\mathrm{N}^{\prime}\right)\left(\operatorname{resp} .(A \downarrow ; \mathrm{N}) \rightarrow_{i}^{*} \xrightarrow{\alpha} \rightarrow_{i}^{*}\left(D_{i} ; \mathrm{N}^{\prime}\right)\right)$ and $\left(D_{i} ; \mathrm{N}^{\prime}\right) \cong\left(B \downarrow ; \mathrm{N}^{\prime}\right)$.

## 5 Intermediate Bisimulation

We now define the intermediate labelled bisimulation. The definition is similar to the original one, but is stated with respect to our intermediate semantics. Moreover, note that the side condition $b n(\alpha) \cap f n(B)=\emptyset$ has been removed since the fact that both processes are running in the same naming environment ensures this condition.

Definition 5.1 (Intermediate labelled bisimilarity $\left(\approx_{i}\right)$ ) Intermediate labelled bisimilarity is the largest symmetric relation $\mathcal{R}$ on closed intermediate processes with same naming environment, such that $\left(A_{i}, \mathrm{~N}\right) \mathcal{R}\left(B_{i} ; \mathrm{N}\right)$ implies

1. $A_{i} \sim B_{i}$,
2. if $\left(A_{i} ; \mathrm{N}\right) \rightarrow_{i}\left(A_{i}^{\prime} ; \mathrm{N}\right)$, then $\left(B_{i} ; \mathrm{N}\right) \rightarrow_{i}^{*}\left(B_{i}^{\prime} ; \mathrm{N}\right)$ and $\left(A_{i}^{\prime} ; \mathrm{N}\right) \mathcal{R}\left(B_{i}^{\prime} ; \mathrm{N}\right)$ for some $B_{i}^{\prime}$,
3. if $\left(A_{i} ; \mathrm{N}\right) \xrightarrow{\alpha}{ }_{i}\left(A_{i}^{\prime} ; \mathrm{N}^{\prime}\right)$ and $f v(\alpha) \subseteq \operatorname{dom}\left(A_{i}\right)$, then $\left(B_{i} ; \mathrm{N}\right) \rightarrow_{i}^{*}{ }_{i}^{\alpha} \rightarrow_{i}^{*}\left(B_{i}^{\prime} ; \mathrm{N}^{\prime}\right)$ and $\left(A_{i}^{\prime} ; \mathrm{N}^{\prime}\right) \mathcal{R}\left(B_{i}^{\prime} ; \mathrm{N}^{\prime}\right)$ for some $B_{i}^{\prime}$.

The following theorem states that the intermediate and the original bisimulations coincide.

Theorem 5.2 Let $A$ and $B$ be two nv-distinct extended processes and N be a naming environment compatible with $A \downarrow$ and $B \downarrow$. We have that

$$
A \approx B \text { if and only if }(A \downarrow ; \mathrm{N}) \approx_{i}(B \downarrow ; \mathrm{N})
$$

Both directions of this result are proved separately by the following propositions.

Proposition 5.3 Let $A$ and $B$ be two nv-distinct extended processes. We have

$$
A \approx B \text { implies }(A \downarrow ; \mathrm{N}) \approx_{i}(B \downarrow ; \mathrm{N})
$$

for any naming environment N compatible with $A \downarrow$ and $B \downarrow$.
Proof. To prove this result, first we define a new relation $\mathcal{R}$. Next we will show that $\mathcal{R}$ is an intermediate labelled bisimulation witnessing $(A \downarrow ; \mathrm{N}) \approx_{i}(B \downarrow ; \mathrm{N})$.
(i) Definition of $\mathcal{R}$.

We define $\mathcal{R}$ as follows: $\left(A_{i} ; \mathrm{N}\right) \mathcal{R}\left(B_{i} ; \mathrm{N}\right)$ if $A_{i} \approx B_{i}$ and N is a naming environment compatible with $A_{i}$ and $B_{i}$.
(ii) $\mathcal{R}$ is an intermediate bisimulation relation witnessing $(A \downarrow ; N) \approx_{i}(B \downarrow ; \mathrm{N})$. First we have to show that $(A \downarrow ; \mathrm{N}) \mathcal{R}(B \downarrow ; \mathrm{N})$. We have that $A \approx B$ and hence $A \downarrow \approx B \downarrow$ (by Lemma 3.6) and N is a naming environment compatible with $A \downarrow$ and $B \downarrow$. Hence, by definition of $\mathcal{R}$, we easily conclude.

Now, we have to show that $\mathcal{R}$ satisfies the three points of the definition of intermediate labelled bisimilarity. Let $\left(A_{i} ; \mathrm{N}\right)$ and $\left(B_{i} ; \mathrm{N}\right)$ be two closed intermediate processes such that $\left(A_{i} ; \mathrm{N}\right) \mathcal{R}\left(B_{i} ; \mathrm{N}\right)$. By definition of $\mathcal{R}$, we have that $A_{i} \approx B_{i}$.
We have to show that:

1. $A_{i} \sim B_{i}$. By hypothesis, we have that $A_{i} \approx B_{i}$ which implies $A_{i} \sim B_{i}$.
2. If $\left(A_{i} ; \mathrm{N}\right) \rightarrow_{i}\left(A_{i}^{\prime} ; \mathrm{N}\right)$ then there exists $\left(B_{i}^{\prime} ; \mathrm{N}\right)$ with $\left(B_{i} ; \mathrm{N}\right) \rightarrow_{i}^{*}\left(B_{i}^{\prime} ; \mathrm{N}\right)$ and $\left(A_{i}^{\prime} ; \mathrm{N}\right) \mathcal{R}\left(B_{i}^{\prime} ; \mathrm{N}\right)$.
By Proposition 4.4, we have that $A_{i} \rightarrow A_{i}^{\prime}$. Since $A_{i} \approx B_{i}$ and $A_{i} \rightarrow A_{i}^{\prime}$ there exists an extended process $B^{\prime}$ such that $B_{i} \rightarrow^{*} B^{\prime}$ and $A_{i}^{\prime} \approx B^{\prime}$. In the remainder, we assume w.l.o.g. that $B^{\prime}$ is nv-distinct and compatible with N. By Corollary 4.8, there exists an intermediate extended process ( $D ; \mathrm{N}$ ) such that

- $\left(B_{i} \downarrow ; \mathrm{N}\right) \rightarrow_{i}^{*}(D ; \mathrm{N})$, and
- $(D ; \mathrm{N}) \approx\left(B^{\prime} \downarrow ; \mathrm{N}\right)$.

As $B_{i}$ is an intermediate process we have that $B_{i} \downarrow=B_{i}$. Let $B_{i}^{\prime}=D$. It remains to show that $\left(A_{i}^{\prime} ; \mathrm{N}\right) \mathcal{R}\left(B_{i}^{\prime} ; \mathrm{N}\right)$. As $A_{i}^{\prime} \approx B^{\prime}, B^{\prime} \approx B^{\prime} \downarrow$ (by Lemma 3.6), and $B_{i}^{\prime} \equiv B^{\prime} \downarrow$ (by Lemma 4.3 and the fact that $\left(B_{i}^{\prime} ; \mathrm{N}\right)=$ $\left.(D ; \mathrm{N}) \approx\left(B^{\prime} \downarrow ; \mathrm{N}\right)\right)$ we have that $A_{i}^{\prime} \approx B_{i}^{\prime}$. By definition of $\mathcal{R}$ we deduce that $\left(A_{i}^{\prime} ; \mathrm{N}\right) \mathcal{R}\left(B_{i}^{\prime} ; \mathrm{N}\right)$.
3. If $\left(A_{i} ; \mathrm{N}\right) \xrightarrow{\alpha}{ }_{i}\left(A_{i}^{\prime} ; \mathrm{N}^{\prime}\right)$ with $f v(\alpha) \subseteq \operatorname{dom}\left(A_{i}\right)$ then there exists $\left(B_{i}^{\prime} ; \mathrm{N}^{\prime}\right)$ such that $\left(B_{i} ; \mathrm{N}\right) \rightarrow_{i}^{*} \xrightarrow{\alpha} \rightarrow_{i}^{*}\left(B_{i}^{\prime} ; \mathrm{N}^{\prime}\right)$ and $\left(A^{\prime} ; \mathrm{N}^{\prime}\right) \mathcal{R}^{\prime}\left(B_{i}^{\prime} ; \mathrm{N}^{\prime}\right)$.
This case is similar to the previous one.

To show the converse direction, we need an additional lemma.

Lemma 5.4 Let $(A ; \mathrm{N})$ and $(B ; \mathrm{N})$ be two intermediate processes, and $\mathrm{N}^{\prime}$ a naming environment compatible with $A$ and $B$. Then:

1. $(A ; \mathrm{N}) \approx_{i}(B ; \mathrm{N})$ implies $\left(A ; \mathrm{N}^{\prime}\right) \approx_{i}\left(B ; \mathrm{N}^{\prime}\right) ;$ and
2. $(A ; \mathrm{N}) \cong(B ; \mathrm{N})$ implies $\left(A ; \mathrm{N}^{\prime}\right) \cong\left(B ; \mathrm{N}^{\prime}\right)$.

To see that the first part of the lemma holds it is sufficient to note that ( $A$; $\mathrm{N}) \bowtie_{i}\left(A^{\prime} ; \mathrm{N}^{\prime}\right)$ if and only if $(A \rho ; \mathrm{N} \rho) \bowtie_{i}\left(A^{\prime} \rho ; \mathrm{N}^{\prime} \rho\right)$ where $\rho$ is a bijective renaming of names and variables, $\bowtie \in\{\equiv, \rightarrow, \xrightarrow{\alpha}\}$ and $\left.\mathrm{N} \rho(u)=\mathrm{N}\left(\rho^{-1}(u)\right)\right)$. The second part is immediate.

Proposition 5.5 Let $\left(A_{i} ; \mathrm{N}\right)$ and $\left(B_{i} ; \mathrm{N}\right)$ be two intermediate processes. We have that

$$
\left(A_{i} ; \mathrm{N}\right) \approx_{i}\left(B_{i} ; \mathrm{N}\right) \text { implies } A_{i} \approx B_{i}
$$

Proof. To prove this result, we first define a new relation $\mathcal{R}$ and then we will show that $\mathcal{R}$ witnesses $\approx$.
(i) Definition of $\mathcal{R}$.
$A \mathcal{R} B$ if there exist two intermediate processes $(\hat{A} ; \mathrm{N})$ and $(\hat{B} ; \mathrm{N})$, and two nv-distinct extended processes $A_{\alpha}$ and $B_{\alpha}$ such that

- $(\hat{A} ; \mathrm{N}) \approx_{i}(\hat{B} ; \mathrm{N})$,
- $(\hat{A} ; \mathrm{N}) \cong\left(A_{\alpha} \downarrow ; \mathrm{N}\right)$ and $(\hat{B} ; \mathrm{N}) \approx\left(B_{\alpha} \downarrow ; \mathrm{N}\right)$,
- $A_{\alpha}={ }_{\alpha} A$ and $B_{\alpha}={ }_{\alpha} B$.
(ii) $\mathcal{R}$ witnesses $\approx$.

First we show that $A_{i} \mathcal{R} B_{i}$. Let $\hat{A}=A_{\alpha}=A_{i}$ and $\hat{B}=B_{\alpha}=B_{i}$. By definition of $\mathcal{R}$ we easily conclude as $\left(A_{i} ; \mathrm{N}\right) \approx_{i}\left(B_{i} ; \mathrm{N}\right)$.

Now, we show that $\mathcal{R}$ satisfies the three points of the definition of $\approx$. Let $A$ and $B$ be two closed intermediate extended processes such that $A \mathcal{R} B$. By definition of $\mathcal{R}$, we know that there exist two intermediate processes $(\hat{A} ; \mathrm{N})$ and $(\hat{B} ; \mathrm{N})$ such that

- $(\hat{A} ; \mathrm{N}) \approx_{i}(\hat{B} ; \mathrm{N})$,
- $(\hat{A} ; \mathrm{N}) \cong\left(A_{\alpha} \downarrow ; \mathrm{N}\right)$ and $(\hat{B} ; \mathrm{N}) \cong\left(B_{\alpha} \downarrow ; \mathrm{N}\right)$, and
- $A_{\alpha}={ }_{\alpha} A$ and $B_{\alpha}={ }_{\alpha} B$.

We have to show that:

1. $A \sim B$. Since $(\hat{A} ; \mathrm{N}) \approx_{i}(\hat{B} ; \mathrm{N})$, we have that $\hat{A} \sim \hat{B}$ by definition of $\approx_{i}$. As $A_{\alpha}={ }_{\alpha} A$ and $B_{\alpha}={ }_{\alpha} B$, we have that $\hat{A} \sim A$ and $\hat{B} \sim B$. We conclude by transitivity of $\sim$.
2. If $A \rightarrow A^{\prime}$ for some extended process $A^{\prime}$ then there exists $B^{\prime}$ such that $B \rightarrow^{*} B^{\prime}$ and $A^{\prime} \mathcal{R} B^{\prime}$.
If $A \rightarrow A^{\prime}$ we also have that $A_{\alpha} \rightarrow A_{\alpha}^{\prime}$ for some $A_{\alpha}^{\prime}$ such that $A_{\alpha}^{\prime}={ }_{\alpha} A^{\prime}$ and $A_{\alpha}^{\prime}$ compatible with N. By Proposition 4.6, there exists an extended process $(D ; \mathrm{N})$ such that

- $\left(A_{\alpha} \downarrow ; \mathrm{N}\right) \rightarrow_{i}(D ; \mathrm{N})$, and
- $(D ; \mathrm{N}) \approx\left(A_{\alpha}^{\prime} \downarrow ; \mathrm{N}\right)$.

We have that $(\hat{A} ; \mathrm{N}) \approx\left(A_{\alpha} \downarrow ; \mathrm{N}\right) \rightarrow_{i}(D ; \mathrm{N}) \approx\left(A_{\alpha}^{\prime} \downarrow ; \mathrm{N}\right) . \quad \mathrm{By}$ Lemma 4.5, there exists $\left(D^{\prime}, \mathrm{N}\right)$ such that

$$
(\hat{A} ; \mathrm{N}) \rightarrow_{i}\left(D^{\prime} ; \mathrm{N}\right) \approx(D ; \mathrm{N}) \approx\left(A_{\alpha}^{\prime} \downarrow ; \mathrm{N}\right)
$$

Since $(\hat{A} ; \mathrm{N}) \approx_{i}(\hat{B} ; \mathrm{N})$ and $(\hat{A} ; \mathrm{N}) \rightarrow_{i}\left(D^{\prime} ; \mathrm{N}\right)$, we have that there exists $\left(B_{i}^{\prime} ; \mathrm{N}\right)$ such that $(\hat{B} ; \mathrm{N}) \rightarrow_{i}^{*}\left(B_{i}^{\prime} ; \mathrm{N}\right)$ and $\left(D^{\prime} ; \mathrm{N}\right) \approx_{i}\left(B_{i}^{\prime} ; \mathrm{N}\right)$. By Corollary 4.7, we have that $\hat{B} \rightarrow^{*} B_{i}^{\prime}$. Thus, we deduce that $B \rightarrow^{*} B_{i}^{\prime \prime}$, for some $B_{i}^{\prime \prime}$ such that $\left(B_{i}^{\prime \prime} \downarrow ; \mathrm{N}\right) \approx\left(B_{i}^{\prime} ; \mathrm{N}\right)$. Let $B^{\prime}=B_{i}^{\prime \prime}, B_{\alpha}^{\prime}=B^{\prime}$, $\hat{B}^{\prime}=B_{i}^{\prime}$ and $\hat{A}^{\prime}=D^{\prime}$. We have that $B \rightarrow^{*} B^{\prime}$ and by definition of $\mathcal{R}$, we have that $A^{\prime} \mathcal{R} B^{\prime}$. Indeed, we have that:

- $\left(\hat{A}^{\prime} ; \mathrm{N}\right) \approx_{i}\left(\hat{B}^{\prime} ; \mathrm{N}\right)$, i.e. $\left(D^{\prime} ; \mathrm{N}\right) \approx_{i}\left(B_{i}^{\prime} ; \mathrm{N}\right)$,
- $\left(\hat{A}^{\prime} ; \mathrm{N}\right) \approx\left(A_{\alpha}^{\prime} \downarrow ; \mathrm{N}\right)$ and $\left(\hat{B}^{\prime} ; \mathrm{N}\right) \approx\left(B_{\alpha}^{\prime} \downarrow ; \mathrm{N}\right)$, and
- $A_{\alpha}^{\prime}={ }_{\alpha} A^{\prime}$ and $B_{\alpha}^{\prime}={ }_{\alpha} B^{\prime}$.

3. If $A \xrightarrow{\alpha} A^{\prime}$ and $f v(\alpha) \subseteq \operatorname{dom}(A)$ and $b n(\alpha) \cap f n(B)=\emptyset$ for some extended process $A^{\prime}$ then $B \rightarrow^{*} \xrightarrow{\alpha} \rightarrow^{*} B^{\prime}$ and $A^{\prime} \mathcal{R} B^{\prime}$ for some process $B^{\prime}$.

First, we can assume w.l.o.g. that $(f n(\alpha) \cup b n(\alpha)) \cap\left(b n\left(A_{\alpha}\right) \cup b n\left(B_{\alpha}\right)\right)=\emptyset$ and $(f n(\alpha) \cup b n(\alpha)) \cap(b n(\hat{A}) \cup b n(\hat{B}))=\emptyset\left(\right.$ since $A_{\alpha}, B_{\alpha} \hat{A}, \hat{B}$ can be chosen to make this true). For the same reason, we can assume that $b v(\alpha) \cap\left(b v\left(A_{\alpha}\right) \cup b v\left(B_{\alpha}\right)\right)=\emptyset$ and $b v(\alpha) \cap(b v(\hat{A}) \cup b v(\hat{B}))=\emptyset$. Let $\hat{\mathrm{N}}=\mathrm{N}[f n(\alpha) \mapsto \mathrm{f}][b n(\alpha), b v(\alpha) \mapsto \mathrm{n}]$. Note that $\hat{\mathrm{N}}$ is now compatible with $A_{\alpha}, B_{\alpha} \hat{A}, \hat{B}$ and $\alpha$. Let $A_{\alpha}^{\prime}$ be an nv-distinct extended process such that $A_{\alpha} \xrightarrow{\alpha} A_{\alpha}^{\prime}$ and $A_{\alpha}^{\prime}$ compatible with $\hat{\mathrm{N}}^{\prime}$ where $\hat{\mathrm{N}}^{\prime}$ is defined as follows:

$$
\hat{\mathrm{N}}^{\prime}= \begin{cases}\hat{\mathrm{N}}[x \mapsto \mathrm{f}] & \text { when } \alpha \text { is of the form } \nu x \operatorname{cout}(a, x) ; \\ \hat{\mathrm{N}}[d \mapsto \mathrm{f}] & \text { when } \alpha \text { is of the form } \nu \operatorname{d.out}(a, d) ; \\ \hat{\mathrm{N}} & \text { otherwise. }\end{cases}
$$

By Proposition 4.6, there exists an extended process $\left(D ; \hat{\mathrm{N}}^{\prime}\right)$ such that

- $\left(A_{\alpha} \downarrow ; \hat{\mathrm{N}}\right) \xrightarrow{\alpha}{ }_{i}\left(D ; \hat{\mathrm{N}}^{\prime}\right)$, and
- $\left(D ; \hat{\mathrm{N}}^{\prime}\right) \cong\left(A_{\alpha}^{\prime} \downarrow ; \hat{\mathrm{N}}^{\prime}\right)$.

We have that $(\hat{A} ; \mathbf{N}) \approx\left(A_{\alpha} \downarrow ; \mathbf{N}\right)$ and thus $(\hat{A} ; \hat{\mathrm{N}}) \approx\left(A_{\alpha} \downarrow ; \hat{\mathrm{N}}\right)$ (Lemma 5.4). Moreover, we have that $\left(A_{\alpha} \downarrow ; \hat{\mathrm{N}}\right) \xrightarrow{\alpha}_{i}\left(D ; \hat{\mathrm{N}}^{\prime}\right) \approx\left(A_{\alpha}^{\prime} \downarrow ;\right.$ $\left.\hat{\mathrm{N}}^{\prime}\right)$. By Lemma 4.5, there exists $\left(D^{\prime}, \hat{\mathrm{N}}^{\prime}\right)$ such that

$$
(\hat{A} ; \hat{\mathrm{N}}) \xrightarrow[\rightarrow]{\alpha}_{i}\left(D^{\prime} ; \hat{\mathrm{N}}^{\prime}\right) \cong\left(D ; \hat{\mathrm{N}}^{\prime}\right) \cong\left(A_{\alpha}^{\prime} \downarrow ; \hat{\mathrm{N}}^{\prime}\right)
$$

Since $(\hat{A} ; \mathrm{N}) \approx_{i}(\hat{B} ; \mathrm{N})$, we have also that $(\hat{A} ; \hat{\mathrm{N}}) \approx_{i}(\hat{B} ; \hat{\mathrm{N}})$ (Lemma 5.4). Moreover, we have that $(\hat{A} ; \hat{\mathrm{N}}) \xrightarrow{\alpha}_{i}\left(D^{\prime} ; \hat{\mathrm{N}}^{\prime}\right)$, thus there exists $\left(B_{i}^{\prime} ; \hat{\mathrm{N}}^{\prime}\right)$ such that $(\hat{B} ; \hat{\mathrm{N}}) \rightarrow_{i}^{*} \xrightarrow{\alpha} \rightarrow_{i}^{*}\left(B_{i}^{\prime} ; \hat{\mathrm{N}}^{\prime}\right)$ and $\left(D^{\prime} ; \hat{\mathrm{N}}^{\prime}\right) \approx_{i}\left(B_{i}^{\prime} ; \hat{\mathrm{N}}^{\prime}\right)$. By Corollary 4.7, we have that $\hat{B} \rightarrow{ }^{*} \xrightarrow{\alpha} \rightarrow^{*} B_{i}^{\prime}$. Thus, we deduce that $B \rightarrow{ }^{*} \xrightarrow{\alpha} \rightarrow^{*} B_{i}^{\prime \prime}$ for some $B_{i}^{\prime \prime}$ such that $\left(B_{i}^{\prime \prime} \downarrow ; \hat{\mathrm{N}}^{\prime}\right) \approx\left(B_{i}^{\prime} ; \hat{\mathrm{N}}^{\prime}\right)$. Let $B^{\prime}=B_{i}^{\prime \prime}, B_{\alpha}^{\prime}=B^{\prime}, \hat{B}^{\prime}=B_{i}^{\prime}$ and $\hat{A}^{\prime}=D^{\prime}$. We have that $B \rightarrow{ }^{*} \xrightarrow{\alpha} B^{\prime}$ and by definition of $\mathcal{R}$, we have that $A^{\prime} \mathcal{R} B^{\prime}$. Indeed, we have that:

- $\left(\hat{A}^{\prime} ; \hat{\mathrm{N}}^{\prime}\right) \approx_{i}\left(\hat{B}^{\prime} ; \hat{\mathrm{N}}^{\prime}\right)$, i.e. $\left(D^{\prime} ; \hat{\mathrm{N}}^{\prime}\right) \approx_{i}\left(B_{i}^{\prime} ; \hat{\mathrm{N}}^{\prime}\right)$,
- $\left(\hat{A}^{\prime} ; \hat{\mathrm{N}}^{\prime}\right) \cong\left(A_{\alpha}^{\prime} \downarrow ; \hat{\mathrm{N}}^{\prime}\right)$ and $\left(\hat{B}^{\prime} ; \hat{\mathrm{N}}^{\prime}\right) \cong\left(B_{\alpha}^{\prime} \downarrow ; \hat{\mathrm{N}}^{\prime}\right)$, and
- $A_{\alpha}^{\prime}={ }_{\alpha} A^{\prime}$ and $B_{\alpha}^{\prime}={ }_{\alpha} B^{\prime}$.


## - PART II: Symbolic Calculus -

A symbolic process is an intermediate process together with a constraint system. The aim of a symbolic semantics is to avoid the infinite branching due to the inputs of the environment. This is achieved by keeping variables rather than the input terms. The constraint system gives a finite representation of the value that these variables are allowed to take.

## 6 Constraint systems

Definition 6.1 (constraint system) $A$ constraint system $\mathcal{C}$ is a set of constraints where every constraint is of one of the following forms:

- " $\varphi \Vdash x$ ", where $\varphi=\nu \tilde{u} . \sigma$ for some tuple of names and variables $\tilde{u}$ and some substitution $\sigma$, and $x$ is a variable which does not appear under a restriction of any frame nor in the domain of any frame;
- " $M=N "$, where $M$ and $N$ are terms;
- " $M \neq N$ ", where $M$ and $N$ are terms;
- " $\operatorname{gd}(M) "$ where $M$ is a term;

The constraint $\varphi \Vdash x$ is useful for specifying the information $\varphi$ held by the environment when it supplies an input $x$. As we will see in the following section, these variables will be taken from a special set of variables. The constraint $\operatorname{gd}(M)$ means that the term $M$ is ground. We denote by $\mathcal{D e d}(\mathcal{C})$ the $d e$ ducibility constraints of $\mathcal{C}$, i.e. $\{\varphi \Vdash x \mid " \varphi \Vdash x " \in \mathcal{C}\}$. When $\operatorname{Ded}(\mathcal{C})=\left\{\varphi_{1} \Vdash x_{1}, \ldots, \varphi_{\ell} \Vdash x_{\ell}\right\}$, we define $\operatorname{cv}(\mathcal{C})=\left\{x_{1}, \ldots, x_{\ell}\right\}$ to be the constraint variables of $\mathcal{C}$. Moreover, we write $\operatorname{names}(\mathcal{C})($ resp. $\operatorname{vars}(\mathcal{C}))$ for the names (resp. variables) of $\mathcal{C}$.

The constraint systems that we consider arise while executing symbolic processes. We therefore restrict ourselves to well-formed constraint systems, capturing the fact that the knowledge of the environment always increases along the execution: we allow it to use more names and variables (less restrictions) or give it access to more terms (larger substitution). The fact that the constraint system is not arbitrary is useful when solving the constraints such as in [20].

Definition 6.2 (ordering on frames $\preceq$ ) Let $\varphi_{1}=\nu \tilde{u}_{1} . \sigma_{1}$ and $\varphi_{2}=\nu \tilde{u}_{2} . \sigma_{2}$ be two frames. The frame $\varphi_{1}$ is smaller than or equal to $\varphi_{2}$, denoted by $\varphi_{1} \preceq \varphi_{2}$, if $\tilde{u}_{1} \supseteq \tilde{u}_{2}, \operatorname{dom}\left(\sigma_{1}\right) \subseteq \operatorname{dom}\left(\sigma_{2}\right)$ and $y \sigma_{1}=y \sigma_{2}$ for any $y \in \operatorname{dom}\left(\sigma_{1}\right)$.

Definition 6.3 (well-formed constraint system) A constraint system $\mathcal{C}$ is well-formed if $\operatorname{Ded}(\mathcal{C})$ can be ordered $\varphi_{1} \Vdash x_{1}, \ldots, \varphi_{\ell} \Vdash x_{\ell}$ in such a way that:

1. (monotonicity) for every $i$ such that $1 \leq i<\ell$, we have $\varphi_{i} \preceq \varphi_{i+1}$, and
2. (origination) for every $i$ such that $1 \leq i \leq \ell$, we have

$$
\text { for all } x \in \operatorname{vars}\left(\operatorname{img}\left(\varphi_{i}\right)\right) \cap \operatorname{cv}(\mathcal{C}), \text { there exists } j<i \text { such that } x=x_{j}
$$

Moreover, if " $M \neq N " \in \mathcal{C}$ then $" \operatorname{gd}(M) " \in \mathcal{C}$ and $" \operatorname{gd}(N) " \in \mathcal{C}$.
In the remainder, when we consider a well-formed constraint system $\mathcal{C}$ and we write, for $\mathcal{D} e d(\mathcal{C})$, the sequence $\varphi_{1} \Vdash x_{1}, \ldots, \varphi_{\ell} \Vdash x_{\ell}$, this implicitly means that we consider the ordering given by the monotonicity condition.

We say that two well-formed constraint systems $\mathcal{C}$ and $\mathcal{C}^{\prime}$ have same basis if $\mathcal{D e d}(\mathcal{C})=\left\{\varphi_{1} \Vdash x_{1}, \ldots, \varphi_{\ell} \Vdash x_{\ell}\right\}$ and $\mathcal{D e d}\left(\mathcal{C}^{\prime}\right)=\left\{\varphi_{1}^{\prime} \Vdash x_{1}^{\prime}, \ldots, \varphi_{\ell}^{\prime} \Vdash x_{\ell}^{\prime}\right\}$ are such that $x_{i}=x_{i}^{\prime}$ and $\operatorname{dom}\left(\varphi_{i}\right)=\operatorname{dom}\left(\varphi_{i}^{\prime}\right)$ for $1 \leq i \leq \ell$.

We now define the solutions of a well-formed constraint system. Intuitively, each solution defines an intermediate process which corresponds to a concrete instance of the corresponding symbolic process.

Definition 6.4 (E-solution) Let $\mathcal{C}$ be a well-formed constraint system such that $\operatorname{Ded}(\mathcal{C})=\left\{\varphi_{1} \Vdash x_{1}, \ldots, \varphi_{\ell} \Vdash x_{\ell}\right\}$ where each $\varphi_{i}=\nu \tilde{u}_{i} . \sigma_{i}$ for some $\tilde{u}_{i}$ and some substitution $\sigma_{i}$. An E-solution of $\mathcal{C}$ is a substitution $\theta$ whose domain is $c v(\mathcal{C})$ and such that

- $\operatorname{vars}\left(x_{i} \theta\right) \cap \operatorname{cv}(\mathcal{C})=\emptyset$ and $\operatorname{vars}\left(x_{i} \theta\right) \cap\left(\operatorname{dom}\left(\varphi_{\ell}\right) \backslash \operatorname{dom}\left(\varphi_{i}\right)\right)=\emptyset ;$
- names $\left(x_{i} \theta\right) \cap \tilde{u}_{i}=\emptyset$ and vars $\left(x_{i} \theta\right) \cap \tilde{u}_{i}=\emptyset$;
- for every constraint " $M=N$ " $\in \mathcal{C}$, we have $M\left(\theta \sigma_{\ell}\right)^{\star}={ }_{\mathrm{E}} N\left(\theta \sigma_{\ell}\right)^{\star}$;
- for every constraint " $M \neq N$ " $\in \mathcal{C}$, we have $M\left(\theta \sigma_{\ell}\right)^{\star} \neq \mathrm{E} N\left(\theta \sigma_{\ell}\right)^{\star}$;
- for every constraint $" \operatorname{gd}(M) " \in \mathcal{C}$, the term $M\left(\theta \sigma_{\ell}\right)^{\star}$ is ground.

We denote by $\operatorname{Sol}_{\mathrm{E}}(\mathcal{C})$ the set of E -solutions of $\mathcal{C}$. An E -solution $\theta$ of $\mathcal{C}$ is closed if vars $\left(x_{i} \theta\right) \subseteq \operatorname{dom}\left(\varphi_{i}\right)$ for any $i \in\{1, \ldots, \ell\}$. We denote by $\operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}(\mathcal{C})$ the set of closed E -solutions of $\mathcal{C}$.

The condition that $\operatorname{vars}\left(x_{i} \theta\right) \cap \operatorname{cv}(\mathcal{C})=\emptyset$ states that the image of $\theta$ should not use any variables that are in the domain of $\theta$. The second condition, $\operatorname{vars}\left(x_{i} \theta\right) \cap$ $\left(\operatorname{dom}\left(\varphi_{\ell}\right) \backslash \operatorname{dom}\left(\varphi_{i}\right)\right)=\emptyset$, ensures that the environment does not use information that will only be revealed "in the future"; it can use only the entries of the frame that have previously been added. The conditions names $\left(x_{i} \theta\right) \cap \tilde{u}_{i}=\emptyset$ and $\operatorname{vars}\left(x_{i} \theta\right) \cap \tilde{u}_{i}=\emptyset$ dissallow the environment to use restricted names and variables which are supposed to be secret; thus, they ensure that the value $x_{i} \theta$ can be deduced from public data. (These conditions are related to the definition of deduction given in [1].) The meaning of the remaining conditions should be clear.

Example 6.5 Let $\mathcal{C}=\left\{\nu k . \nu s .\left\{\operatorname{enc}(s, k) / y_{1},{ }^{k} / y_{2}\right\} \Vdash x^{\prime}, \operatorname{gd}(c), x^{\prime}=s\right\}$. Let E be the equational theory $\operatorname{dec}(\operatorname{enc}(x, y), y)=x$ and $\theta=\left\{\operatorname{dec}\left(y_{1}, y_{2}\right) / x^{\prime}\right\}$. We have that $\theta$ is a closed E -solution of $\mathcal{C}$. Note that $\theta^{\prime}=\left\{\operatorname{dec}\left(y_{1}, k\right) / x^{\prime}\right\}$ is not an E solution of $\mathcal{C}$. Indeed, names $\left(x^{\prime} \theta^{\prime}\right) \cap\{k, s\}=\{k\}$ and thus is not empty.

We also define what it means to apply an evaluation context on a constraint system. This is needed because we define the semantics in a compositional way.

Definition $6.6(C[\mathcal{C}])$ Let $C=\nu \tilde{n} .(-\mid D)$ be an intermediate evaluation context and e be a constraint. We have that

- $C[e]=e$ when $e$ is a constraint of the form $M=N, M \neq N$ or $\operatorname{gd}(M)$;
- $C[\nu \tilde{v} . \sigma \Vdash x]=\nu \tilde{n} . \nu \tilde{v} .(\sigma \cup \psi(D)) \Vdash x$ otherwise.

Similarly, for a variable $y \in \mathcal{X}$

- $\nu y . e=e$ when $e$ is a constraint of the form $M=N, M \neq N$ or $\operatorname{gd}(M)$;
- $\nu y . e=\nu y, \tilde{v}, \sigma \Vdash x$ when $e=\nu \tilde{v} . \sigma \Vdash x$.

Given a constraint system $\mathcal{C}$, we have that $C[\mathcal{C}]=\{C[e] \mid e \in \mathcal{C}\}$ and $\nu y \cdot \mathcal{C}=$ $\{\nu y . e \mid e \in \mathcal{C}\}$.

## 7 Syntax and Semantics

### 7.1 Syntax

We first need to extend naming environments used in the intermediate semantics to the symbolic setting. For this, we introduce an infinite set $\mathcal{Y}$ of variables, to be used as constraint variables, disjoint from the set $\mathcal{X}$. We also distinghuish two disjoint subsets: $\mathcal{Y}_{b}$ for variables of base type and $\mathcal{Y}_{c h}$ for those of channel type. The functions vars and $f v$ are updated to also return variables from $\mathcal{Y}$.

Definition 7.1 (Symbolic naming environment) $A$ symbolic naming environment $\mathrm{N}_{\mathrm{s}}: \mathcal{N} \cup \mathcal{X} \cup \mathcal{Y} \rightarrow\{\mathrm{n}, \mathrm{f}, \mathrm{b}, \mathrm{c}\}$ is a function which maps each name and variable in $\mathcal{N} \cup \mathcal{X}$ to one of $\mathrm{n}, \mathrm{f}$ and b and each variable in $\mathcal{Y}$ to one of n or c. It extends naming environments with an infinite set $\mathcal{Y}$ of variables that can be mapped to c (which stands for "constraint") or n . As before, we require that there are infinitely many names and infinitely many variables that are mapped to each of $\mathrm{n}, \mathrm{f}$ and b .

We say that a symbolic naming environment $\mathrm{N}_{s}$ is compatible with an intermediate extended process $A$ and a constraint system $\mathcal{C}$ if

$$
-\mathrm{N}_{s}(f n(A))=\mathrm{f} \quad-\mathrm{N}_{s}(b n(A) \cup b v(A))=\mathrm{b} \quad-\mathrm{N}_{s}(\operatorname{names}(\mathcal{C})) \subseteq\{\mathrm{f}, \mathrm{~b}\}
$$

$$
-\mathrm{N}_{s}(f v(A)) \subseteq\{\mathrm{f}, \mathrm{c}\} \quad-\mathrm{N}_{s}(y)=\mathrm{c} \text { iff } y \in \operatorname{cv}(\mathcal{C}) \quad-\mathrm{N}_{s}(\operatorname{vars}(\mathcal{C})) \subseteq\{\mathrm{f}, \mathrm{c}, \mathrm{~b}\}
$$

Intuitively, $\mathrm{N}_{s}(y)=\mathrm{c}$ means that the variable $y$ is a constraint variable (i.e., an input from the environment subject to constraints in $\mathcal{C}$ ).

We are now ready to precisely define a symbolic process.
Definition 7.2 (Symbolic process) $A$ symbolic process is a triple $(A ; \mathcal{C}$; $\mathrm{N}_{s}$ ) where $A$ is an intermediate extended process, $\mathcal{C}$ is a constraint system and $\mathrm{N}_{s}$ is a symbolic naming environment. We say that $\left(A ; \mathcal{C} ; \mathrm{N}_{\mathrm{s}}\right)$ is well-formed if

- $\mathrm{N}_{s}$ is compatible with A and C ;
- If $\mathcal{D e d}(\mathcal{C})=\left\{\varphi_{1} \Vdash x_{1}, \ldots, \varphi_{\ell} \Vdash x_{\ell}\right\} \neq \emptyset$ then $\phi(A) \succeq \varphi_{\ell}$ and $\operatorname{bv}\left(\varphi_{1}\right) \subseteq$ $\operatorname{dom}(A)$;
- for all $M, N$ such that $M=N, M \neq N$ or $\operatorname{gd}(M)$ is in $\mathcal{C}$ we have that $\operatorname{vars}(M, N) \cap \operatorname{dom}(A)=\emptyset$.
$\left(A ; \mathcal{C} ; \mathrm{N}_{\mathrm{s}}\right)$ is said to be closed if $f v(A) \subseteq \operatorname{dom}(A) \cup c v(\mathcal{C})$.
Given a well-formed symbolic process $\left(A ; \mathcal{C} ; \mathrm{N}_{\mathbf{s}}\right)$ we define by $\operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C} ; \mathrm{N}_{s}\right)$ the set of solutions of $\mathcal{C}$ which are compatible with $\mathrm{N}_{s}$, i.e.

$$
\operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}, \mathrm{~N}_{s}\right)=\left\{\theta \mid \theta \in \operatorname{Sol}_{\mathrm{E}}(\mathcal{C}), \mathrm{N}_{s}(\operatorname{names}(\operatorname{img}(\theta)) \cup \operatorname{vars}(\operatorname{img}(\theta)))=\mathrm{f}\right\} .
$$

We denote by $\operatorname{Sol}_{\mathrm{E}}^{\mathrm{c}}\left(\mathcal{C}\right.$; Ns) the subset of $\operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}, \mathrm{N}_{s}\right)$ containing closed Esolutions of $\mathcal{C}$.

Each of these solutions $\theta$ defines a corresponding (closed) intermediate process which we call the $\theta$-concretization.

Definition 7.3 ( $\theta$-concretization) Let $\left(A_{s} ; \mathcal{C} ; \mathrm{N}_{s}\right)$ be a well-formed symbolic process. Let $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}, \mathrm{N}_{s}\right)$. We say that an intermediate process $(A ; \mathrm{N})$ is the $\theta$-concretization of $\left(A_{s} ; \mathcal{C} ; \mathrm{N}_{s}\right)$ if $A=A_{s}(\theta \sigma)^{\star}$ where $\sigma$ is the maximal frame of $\mathcal{C}$ and $\mathrm{N}=\mathrm{N}_{s} \mid \mathcal{N} \cup \mathcal{X}$.

Example 7.4 Let $A_{s}=\nu b$.(out $\left.(c, x) \mid\left\{{ }^{b} / y\right\}\right), \mathcal{C}=\{\nu a . \nu b .\{b / y\} \Vdash x, x \neq$ $c, \operatorname{gd}(x)\}$ and $\mathrm{N}_{s}$ be a naming environment compatible with $A_{s}$ and $\mathcal{C}$ such that $\mathrm{N}_{s}(d)=\mathrm{f}$. Let $\theta_{1}=\left\{{ }^{d} / x\right\}, \theta_{2}=\{y / x\}$ and $\mathrm{N}=\left.\mathrm{N}_{s}\right|_{\mathcal{N} \cup \mathcal{X}}$. We have that $\theta_{1}, \theta_{2} \in$ Sol $_{\mathrm{E}}^{c}\left(\mathcal{C}, \mathbf{N}_{s}\right)$. Hence $\left(\nu b .\left(\operatorname{out}(c, d) \mid\left\{{ }^{b} / y\right\}\right) ; \mathbf{N}\right)\left(\operatorname{resp} .\left(\nu b .\left(\operatorname{out}(c, b) \mid\left\{{ }^{b} / y\right\}\right) ; \mathbf{N}\right)\right)$ is the $\theta_{1}$ (resp. $\theta_{2}$ ) concretization of $\left(A_{s} ; \mathcal{C} ; \mathbf{N}_{s}\right)$. However, $\nu b$.(out $(c, a) \mid$ $\left.\left\{{ }^{b} / y\right\}\right)$ is not a concretization of $\left(A_{s} ; \mathcal{C} ; \mathrm{N}_{s}\right)$ since no $\theta \in \operatorname{Sol}_{\mathbf{E}}^{\mathrm{d}}\left(\mathcal{C}, \mathrm{N}_{s}\right)$ can have a in its image.

### 7.2 Symbolic semantics

Symbolic structural equivalence $\left(\equiv_{s}\right)$ is the smallest equivalence relation on wellformed symbolic processes such that:

$$
\begin{array}{lrl}
\text { Par- } 0_{s} & \left(A ; \mathcal{C} ; \mathrm{N}_{\mathrm{s}}\right) & \equiv_{s} \\
\mathrm{PAR}^{2}-A_{s} & \left(A \mid(B \mid D) ; \mathcal{C} ; \mathrm{N}_{\mathrm{s}}\right) & \equiv_{s}\left((A \mid B) \mid D ; \mathrm{N}_{\mathrm{s}}\right) \\
\mathrm{PAR-C}_{s} & \left(A \mid B ; \mathcal{C} ; \mathrm{N}_{\mathrm{s}}\right) \\
\text { NEW-C }_{s} & \left(\nu n . \nu m . A ; \mathcal{C} ; \mathrm{N}_{\mathrm{s}}\right) \equiv_{s}\left(B \mid A ; \mathcal{C} ; \mathrm{E}_{s}\right) \\
& \left(\nu m . \nu n . A ; \mathcal{C} ; \mathrm{N}_{\mathrm{s}}\right) \\
& \left(A ; \mathcal{C}_{A} ; \mathrm{N}_{\mathrm{s}}\right) \equiv_{s}\left(B ; \mathcal{C}_{B} ; \mathrm{N}_{\mathrm{s}}\right) \\
\hline\left(C[A] ; C\left[\mathcal{C}_{A}\right] ; \mathrm{N}_{\mathrm{s}}[b n(C[0]) \mapsto \mathrm{b}]\right) \equiv_{s}\left(C[B] ; C\left[\mathcal{C}_{B}\right] ; \mathrm{N}_{\mathrm{s}}[b n(C[0]) \mapsto \mathrm{b}]\right)
\end{array}
$$

Symbolic internal reduction $\rightarrow_{s}$ is the smallest relation on well-formed symbolic processes such that:
$\operatorname{Comm}_{s} \quad\left(\right.$ out $\left.(u, M) \cdot P \mid \operatorname{in}(v, x) \cdot Q ; \mathcal{C} ; \mathbf{N}_{\mathrm{s}}\right) \rightarrow_{s}$
$\left(P \mid Q\left\{{ }^{M} / x\right\} ; \mathcal{C} \cup\{u=v, \operatorname{gd}(u), \operatorname{gd}(v)\} ; \mathrm{N}_{\mathrm{s}}\right)$ where $u, v \in \mathcal{N}_{c h} \cup\left(c v(\mathcal{C}) \cap \mathcal{Y}_{c h}\right)$.

Then $_{s} \quad\left(\right.$ if $M=N$ then $P$ else $\left.Q ; \mathcal{C} ; \mathbf{N}_{\mathbf{s}}\right) \rightarrow_{s}\left(P ; \mathcal{C} \cup\{M=N\} ; \mathbf{N}_{\mathbf{s}}\right)$

$$
\begin{aligned}
& \left.\quad \text { (if } M=N \text { then } P \text { else } Q ; \mathcal{C} ; \mathrm{N}_{\mathrm{s}}\right) \rightarrow_{s} \\
& \left(Q ; \mathcal{C} \cup\{M \neq N ; \operatorname{gd}(M) ; \operatorname{gd}(N)\} ; \mathrm{N}_{\mathrm{s}}\right) \\
& \frac{\left(A ; \mathcal{C}_{A} ; \mathrm{N}_{\mathrm{s}}\right) \rightarrow_{s}\left(B ; \mathcal{C}_{B} ; \mathrm{N}_{\mathrm{s}}\right)}{\left(C[A] ; C\left[\mathcal{C}_{A}\right] ; \mathrm{N}_{\mathrm{s}}[b n(C[0]) \mapsto \mathrm{b}]\right) \rightarrow_{s}\left(C[B] ; C\left[\mathcal{C}_{B}\right] ; \mathrm{N}_{\mathrm{s}}[b n(C[0]) \mapsto \mathrm{b}]\right)} \\
& \frac{\left(A ; \mathcal{C}_{A} ; \mathrm{N}_{\mathrm{s}}\right) \equiv_{s}\left(B ; \mathcal{C}_{B} ; \mathrm{N}_{\mathrm{s}}\right) \rightarrow_{s}\left(B^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{\mathrm{s}}\right) \equiv_{s}\left(B^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{\mathrm{s}}\right)}{\left(A ; \mathcal{C}_{A} ; \mathrm{N}_{\mathrm{s}}\right) \rightarrow_{s}\left(A^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{\mathrm{s}}\right)}
\end{aligned}
$$

In addition to the rules for symbolic structural equivalence and internal reduction, we adopt the following rules:
$\mathrm{IN}_{s}$

$$
\begin{aligned}
& \left(\text { in }(u, x) . P ; \mathcal{C} ; \mathrm{N}_{\mathrm{s}}\right) \xrightarrow{i n(u, y)}{ }_{s}\left(P\left\{{ }^{y} / x\right\} ; \mathcal{C} \cup\{0 \Vdash y, \operatorname{gd}(u)\} ; \mathrm{N}_{\mathrm{s}}[y \mapsto \mathrm{c}]\right) \\
& \text { where } u \in \mathcal{N}_{c h} \cup\left(\mathcal{Y}_{c h} \cap c v(\mathcal{C})\right), y \in \mathcal{Y}, \mathrm{~N}_{s}(y)=\mathrm{n} \text {. } \\
& \text { Out-Ch } \operatorname{CH}_{s} \quad\left(\text { out }(u, v) . P ; \mathcal{C} ; \mathrm{N}_{\mathbf{s}} \xrightarrow{\text { out }(u, v)}{ }_{s}\left(P ; \mathcal{C} \cup\{\operatorname{gd}(u), \operatorname{gd}(v)\} ; \mathrm{N}_{\mathbf{s}}\right)\right. \\
& \text { where } u, v \in \mathcal{N}_{c h} \cup\left(\mathcal{Y}_{c h} \cap c v(\mathcal{C})\right) \text {. }
\end{aligned}
$$

## Out- $\mathrm{T}_{s}$

$$
\begin{array}{r}
\left(\operatorname{out}(u, M) . P ; \mathcal{C} ; \mathrm{N}_{\mathrm{s}}\right) \xrightarrow{\nu x . \text { out }(u, x)}{ }_{s}\left(P \mid\left\{{ }^{M} / x\right\} ;\right. \\
\left.; \nu x . \mathcal{C} \cup\{\operatorname{gd}(u)\} ; \mathrm{N}_{\mathrm{s}}[x \mapsto \mathrm{f}]\right) \\
\text { where } x \in \mathcal{X}_{b}, \mathrm{~N}_{s}(x)=\mathrm{n} .
\end{array}
$$

Open-Ch ${ }_{s}$
$\frac{\left(A ; \mathcal{C} ; \mathrm{N}_{\mathrm{s}}\right) \xrightarrow{\operatorname{out}(u, c)} s_{s}\left(A^{\prime} ; \mathcal{C}^{\prime} ; \mathrm{N}_{\mathrm{s}}^{\prime}\right) \quad u \neq c, d \in \mathcal{N}_{c h}, \mathrm{~N}_{s}(d)=\mathrm{n}}{\left(\nu c . A ; \nu c . \mathcal{C} ; \mathrm{N}_{\mathrm{s}}[c \mapsto \mathrm{~b}]\right) \xrightarrow{\nu d . o u t(u, d)} s\left(A^{\prime}\{d / c\} ; \nu d .\left(\mathcal{C}^{\prime}\{d / c\}\right) ; \mathrm{N}_{\mathrm{s}}^{\prime}[c \mapsto \mathrm{~b}, d \mapsto \mathrm{f}]\right)}$
$\mathrm{SCOPE}_{s} \quad \frac{\left(A ; \mathcal{C} ; \mathrm{N}_{\mathrm{s}}\right) \xrightarrow{\alpha}{ }_{s}\left(A^{\prime} ; \mathcal{C}^{\prime} ; \mathrm{N}_{\mathrm{s}}^{\prime}\right) \quad n \text { does not occur in } \alpha}{\left(\nu n . A ; \nu n . \mathcal{C} ; \mathrm{N}_{\mathrm{s}}[n \mapsto \mathrm{~b}]\right) \xrightarrow{\alpha}_{s}\left(\nu n . A^{\prime} ; \nu n . \mathcal{C}^{\prime} ; \mathrm{N}_{\mathbf{s}}[n \mapsto \mathrm{~b}]\right)}$
$\mathrm{PAR}_{s}$

$$
\frac{\left(A ; \mathcal{C} ; \mathrm{N}_{\mathrm{s}}\right) \xrightarrow[\rightarrow]{\alpha}\left(A^{\prime} ; \mathcal{C}^{\prime} ; \mathrm{N}_{\mathrm{s}}^{\prime}\right)}{\left(A|B ; \mathcal{C}| \psi(B) ; \mathrm{N}_{\mathrm{s}}\right) \xrightarrow{\alpha}{ }_{s}\left(A^{\prime}\left|B ; \mathcal{C}^{\prime}\right| \psi(B) ; \mathrm{N}_{\mathrm{s}}^{\prime}\right)}
$$

$\operatorname{STRUCT}_{s} \quad \frac{\left(A ; \mathcal{C}_{A} ; \mathrm{N}_{\mathrm{s}}\right) \equiv_{s}\left(B ; \mathcal{C}_{B} ; \mathrm{N}_{\mathrm{s}} \xrightarrow{\alpha}{ }_{s}\left(B^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{\mathrm{s}}^{\prime}\right) \equiv_{s}\left(B^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{\mathrm{s}}^{\prime}\right)\right.}{\left(A ; \mathcal{C}_{A} ; \mathrm{N}_{\mathrm{s}}\right) \xrightarrow{\alpha}\left(A^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{\mathrm{s}}^{\prime}\right)}$
For reasons similar to those cited for Open- $\mathrm{CH}_{i}$, the rules $\mathrm{In}_{s}$ and Open$\mathrm{CH}_{s}$ require on-the-fly renaming. When a transition is executed under a context (by the rules $\mathrm{Scope}_{s}$ and $\mathrm{PAR}_{s}$ ) the constraint system must also be put in the context (according to Definition 6.6). In $\mathrm{PAR}_{s}$ we avoid the substitution $\psi(B)$
which appears on a label in $\mathrm{PAR}_{i}$ since here we always have that the variables in $\operatorname{dom}(\psi(B))$ do not occur in the label $\alpha$. In the rule OPEN- $\mathrm{CH}_{s}$, the restriction $\nu d .\left(\mathcal{C}^{\prime}\left\{{ }^{d} / c\right\}\right)$ is needed to ensure that the name $d$ is not used to instantiate the previous inputs: those that are done before the disclosure of this name.

Example 7.5 To illustrate our symbolic semantics, consider the process $\left(A ; \emptyset ; \mathbf{N}_{s}\right)$ where $A=\nu k . \nu s$. $\operatorname{in}(c, x)$.if $x=s$ then out $\left.(c, o k)\left|\left\{\operatorname{enc}(s, k) / y_{1}\right\}\right|\left\{{ }^{k} / y_{2}\right\}\right)$ and $\mathrm{N}_{s}$ is a symbolic environment compatible with $A$. Let $x^{\prime} \in \mathcal{Y}_{b}$ be a variable such that $\mathrm{N}_{s}\left(x^{\prime}\right)=\mathrm{n}$.

$$
\begin{array}{rll}
\left(A ; \emptyset ; \mathbf{N}_{s}\right) \quad \xrightarrow{i n\left(c, x^{\prime}\right)}{ }_{s} & \left(A^{\prime} ;\left\{\nu k . \nu s .\left\{\operatorname{enc}(s, k) / y_{1}{ }^{k} / y_{2}\right\} \Vdash x^{\prime}, \operatorname{gd}(c)\right\} ; \mathbf{N}_{s}\left[x^{\prime} \mapsto \mathrm{c}\right]\right) \\
& \longrightarrow{ }_{s} & \left(\nu k . \nu s .\left(\operatorname{out}(c, o k)\left|\left\{{ }^{\operatorname{enc}(s, k)} / y_{1}\right\}\right|\left\{{ }^{k} / y_{2}\right\}\right) ; \mathcal{C} ; \mathbf{N}_{s}\left[x^{\prime} \mapsto \mathrm{c}\right]\right)
\end{array}
$$

where $A^{\prime}=\nu k . \nu s$. (if $x^{\prime}=s$ then out $\left.(c, o k)\left|\left\{\operatorname{enc}(s, k) / y_{1}\right\}\right|\left\{{ }^{k} / y_{2}\right\}\right)$ and $\mathcal{C}$ is the system

$$
\left\{\nu k . \nu s .\left\{{ }^{\operatorname{enc}(s, k)} / y_{1},{ }^{k} / y_{2}\right\} \Vdash x^{\prime}, \operatorname{gd}(c), x^{\prime}=s\right\}
$$

Let $\theta=\left\{\operatorname{dec}\left(y_{1}, y_{2}\right) / x^{\prime}\right\}$. We have $\theta \in \operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C} ; \mathrm{N}_{s}\left[x^{\prime} \mapsto \mathrm{c}\right]\right.$ ) (see Example 6.5) and

$$
(A ; \mathrm{N}) \xrightarrow{i n\left(c, x^{\prime} \theta\right)} \rightarrow_{i}\left(A^{\prime} \theta^{\prime} ; \mathrm{N}\right)
$$

where $\mathrm{N}=\left.\mathrm{N}_{s}\right|_{\mathcal{N} \cup \mathcal{X}}$.

## 8 Soundness and Completeness

We now show soundness of $\equiv_{s}, \rightarrow_{s}$ and ${ }^{\alpha}{ }_{s}$ with respect to their counterparts in the intermediate semantics: whenever one of these relations holds between two symbolic processes, the corresponding relation in the intermediate semantics holds for each $\theta$-concretization. The proofs can be found in Appendix B.1.

Proposition 8.1 (soundness of $\equiv_{s}$ and $\left.\rightarrow_{s}\right) \operatorname{Let}\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ be two well-formed symbolic processes such that $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \bowtie_{s}\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ with $\bowtie \in\{\equiv, \rightarrow\}$. Let $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}\right)$. We have that $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $(A ; \mathrm{N}) \bowtie_{i}(B ; \mathrm{N})$ where $(A ; \mathrm{N})(\operatorname{resp} .(B ; \mathrm{N}))$ is the $\theta$-concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)\left(\operatorname{resp} .\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)\right)$.

Proposition 8.2 (soundness of $\left.{ }^{\alpha}{ }_{s}\right)$ Let $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime}\right)$ be two well-formed symbolic processes such that $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \xrightarrow{\alpha_{s}}\left(B_{s} ; \mathcal{C}_{B} ;\right.$ $\left.\mathrm{N}_{s}^{\prime}\right)$. Let $\theta_{B} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}^{\prime}{ }_{s}\right)$ and $\theta_{A}=\left.\theta_{B}\right|_{c v\left(\mathcal{C}_{A}\right)}$. We have that $\theta_{A} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} ;\right.$ $\left.\mathrm{N}_{s}\right)$ and $(A ; \mathrm{N}) \xrightarrow{\alpha_{s} \theta_{B}} i\left(B ; \mathrm{N}^{\prime}\right)$, where $(A ; \mathrm{N})$ and $\left(B ; \mathrm{N}^{\prime}\right)$ are respectively the $\theta_{A}$-concretization and the $\theta_{B}$-concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime}\right)$.

We also show completeness of the symbolic semantics with respect to the intermediate one: each time a $\theta$-concretization of a symbolic process is structurally equivalent, respectively reduces, to another intermediate process, the
symbolic process too is structurally equivalent, respectively reduces, to a corresponding symbolic process. The proofs of these two following propositions can be found in Appendix B.2.

Proposition 8.3 (completeness of $\equiv_{s}$ and $\left.\rightarrow_{s}\right)$ Let $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ be a well-formed symbolic process and $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$. Let $(A ; \mathrm{N})$ be the $\theta$ concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $\left(A^{\prime}, \mathrm{N}\right)$ be an intermediate process such that $(A ; \mathrm{N}) \bowtie_{i}\left(A^{\prime} ; \mathrm{N}\right)$ with $\bowtie \in\{\equiv, \rightarrow\}$. Then there exists a well-formed symbolic process $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$ such that:

1. $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \bowtie_{s}\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$,
2. $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$,
3. $\left(A^{\prime} ; \mathrm{N}\right)$ is the $\theta$-concretization of $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$.

Proposition 8.4 (completeness of $\left.{ }^{\alpha}{ }_{s}\right)$ Let $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ be a well-formed symbolic process and $\theta_{A} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$. Let $(A ; \mathrm{N})$ be the $\theta_{A}$-concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $\left(A^{\prime} ; \mathrm{N}^{\prime}\right)$ be an intermediate process such that $(A ; \mathrm{N}) \xrightarrow{\alpha}{ }_{i}$ $\left(A^{\prime} ; \mathrm{N}^{\prime}\right)$. Then there exists a well-formed symbolic process $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ and a substitution $\theta_{A}^{\prime}$ such that:

1. $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \xrightarrow{\alpha_{s}}{ }_{s}\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$,
2. $\theta_{A}^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ and $\left.\theta_{A}^{\prime}\right|_{c v\left(\mathcal{C}_{A}\right)}=\theta_{A}$,
3. $\left(A^{\prime} ; \mathrm{N}^{\prime}\right)$ is the $\theta_{A}^{\prime}$-concretization of $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$, and
4. $\alpha_{s} \theta_{A}^{\prime}=\alpha$.

From the propositions stated above, we easily derive the following corollaries.
Corollary 8.5 (soundness of $\left.\rightarrow_{s}^{*}\right)$ Let $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ be two well-formed symbolic processes such that $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \rightarrow_{s}^{*}\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$. Let $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}\right)$. We have that $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $(A ; \mathrm{N}) \rightarrow_{i}^{*}(B ; \mathrm{N})$ where $(A ; \mathrm{N})$ (resp. $(B ; \mathrm{N})$ ) is the $\theta$-concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ (resp. $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ ).

Corollary 8.6 (soundness of $\left.\rightarrow_{s}^{*} \xrightarrow{\alpha}{ }_{s} \rightarrow_{s}^{*}\right) \operatorname{Let}\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime}\right)$ be two well-formed symbolic processes such that $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \rightarrow_{s}^{*} \xrightarrow{\alpha_{s}}{ }_{s} \rightarrow_{s}^{*}$ $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime}\right)$. Let $\theta_{B} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}^{\prime}{ }_{s}\right)$ and $\theta_{A}=\left.\theta_{B}\right|_{c v\left(\mathcal{C}_{A}\right)}$. We have that $\theta_{A} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $(A ; \mathrm{N}) \rightarrow_{i}^{*} \xrightarrow{\alpha_{s} \theta_{B}}{ }_{i} \rightarrow_{i}^{*}\left(B ; \mathrm{N}^{\prime}\right)$, where $(A ; \mathrm{N})$ and $\left(B ; \mathrm{N}^{\prime}\right)$ are respectively the $\theta_{A}$-concretization and the $\theta_{B}$-concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime}\right)$.

## 9 Symbolic Equivalences

In this section, we define our notion of symbolic static equivalence and our notion of symbolic bisimulation. We also show the soundness of these equivalences w.r.t. their intermediate counterparts. We also show in Section 10 that our symbolic bisimulation is not complete.

We define symbolic static equivalence using an encoding similar to the one in [5]. The tests used to distinguish two frames in the definition of static equivalence are encoded by means of two additional deduction constraints on fresh variables $x, y$ and by the equation $x=y$.

Definition 9.1 (symbolic static equivalence) We say that two closed wellformed symbolic processes $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ are symbolically statically equivalent, written $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \sim_{s}\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ if for some variables $x, y \in \mathcal{Y}_{b}$, the constraint systems $\mathcal{C}_{A}^{\prime}, \mathcal{C}_{B}^{\prime}$ have the same basis and $\operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)=\operatorname{Sol}_{\mathrm{E}}^{\mathrm{c}}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ where

- $\mathrm{N}_{s}(\{x, y\})=\mathrm{n}$,
- $\mathrm{N}_{s}^{\prime}=\mathrm{N}_{s}[x, y \mapsto \mathrm{c}]$,
- $\mathcal{C}_{A}^{\prime}=\mathcal{C}_{A} \cup\left\{\phi\left(A_{s}\right) \Vdash x, \phi\left(A_{s}\right) \Vdash y, x=y\right\}$, and
- $\mathcal{C}_{B}^{\prime}=\mathcal{C}_{B} \cup\left\{\phi\left(B_{s}\right) \Vdash x, \phi\left(B_{s}\right) \Vdash y, x=y\right\}$.

The following proposition states the correctness of the symbolic static equivalence with respect to the concrete one.

Proposition 9.2 (soundness of symbolic static equivalence) $\operatorname{Let}\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ be two closed and well-formed symbolic processes such that $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \sim_{s}\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$. Then we have that:

1. $\operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)=\operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}\right)$, and
2. for all $\theta \in \operatorname{Sol}_{\mathrm{E}}^{\mathrm{L}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ we have that $\phi\left(A_{s}\left(\theta \sigma_{A}\right)^{\star}\right) \sim \phi\left(B_{s}\left(\theta \sigma_{B}\right)^{\star}\right)$, where $\sigma_{A}\left(\right.$ resp. $\left.\sigma_{B}\right)$ is the substitution corresponding to the maximal frame of $\mathcal{C}_{A}\left(\right.$ resp. $\left.\mathcal{C}_{B}\right)$.

## Proof.

1. We show one direction, i.e., $\operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right) \subseteq \operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}\right)$. The other one can be proved in a similar way. Let $\theta \in \operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$. Since $\left(A_{s}\right.$; $\left.\mathcal{C}_{A} ; \mathrm{N}_{s}\right) \sim_{s}\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$, we know that $\mathcal{C}_{A}^{\prime}, \mathcal{C}_{B}^{\prime}$ have same basis and $\operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)=\operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ where

- $x, y \in \mathcal{Y}_{b}$ and $\mathrm{N}_{s}(\{x, y\})=\mathrm{n}$,
- $\mathrm{N}_{s}^{\prime}=\mathrm{N}_{s}[x, y \mapsto \mathrm{c}]$,
- $\mathcal{C}_{A}^{\prime}=\mathcal{C}_{A} \cup\left\{\phi\left(A_{s}\right) \Vdash x, \phi\left(A_{s}\right) \Vdash y, x=y\right\}$, and
- $\mathcal{C}_{B}^{\prime}=\mathcal{C}_{B} \cup\left\{\phi\left(B_{s}\right) \Vdash x, \phi\left(B_{s}\right) \Vdash y, x=y\right\}$.

Let $\rho=\{x \mapsto a, y \mapsto a\}$ for some name $a$ such that $\mathrm{N}_{s}(a)=\mathrm{f}$ and that does not occur in $A_{s}, \mathcal{C}_{A}, B_{s}, \mathcal{C}_{B}$. It is easy to see that $\theta \cup \rho \in \operatorname{Sol}_{\mathrm{E}}^{\text {cl }}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$. Since $\operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)=\operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$, we deduce that $\theta \cup \rho \in \operatorname{Sol}_{\mathrm{E}}^{\text {cl }}\left(\mathcal{C}_{B}^{\prime} ;\right.$ $\left.\mathrm{N}_{s}^{\prime}\right)$. It remains to check that $\theta \in \operatorname{Sol}_{\mathrm{E}}^{\mathrm{c}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}\right)$.
Let $\phi\left(B_{s}\right)=\nu \tilde{n}_{B}^{\prime} \cdot \sigma_{B}^{\prime}$. By hypothesis, we know that the idempotent substitution $\sigma$ obtained by iterating $(\theta \cup \rho) \sigma_{B}^{\prime}$ satisfies the constraints in $\mathcal{C}_{B}^{\prime}$. Let $\nu \tilde{n}_{A} . \sigma_{A}$ be the maximal frame in $\mathcal{C}_{A}$ and $\nu \tilde{n}_{B} \cdot \sigma_{B}$ be the maximal frame in $\mathcal{C}_{B}$. Since $\mathcal{C}_{A}$ and $\mathcal{C}_{B}$ have same basis, we have that $\operatorname{dom}\left(\sigma_{A}\right)=\operatorname{dom}\left(\sigma_{B}\right)$. Moreover, since $\theta \in \operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$, we know that $\operatorname{vars}(\operatorname{img}(\theta)) \subseteq \operatorname{dom}\left(\sigma_{A}\right)=\operatorname{dom}\left(\sigma_{B}\right)$. Since $\sigma=\left((\theta \cup \rho) \sigma_{B}^{\prime}\right)^{\star}$, we deduce that $\sigma=\left((\theta \cup \rho) \sigma_{B}\right)^{\star}$, and actually $\sigma=\left(\theta \sigma_{B}\right)^{\star} \cup \rho$. This means that $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ since $x$ and $y$ do not appear in $\mathcal{C}_{B}$.
2. Let $\theta \in \operatorname{Sol}_{\mathrm{E}}^{\mathrm{c}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$. Let $\sigma_{A}$ be the substitution corresponding to the maximal frame of $\mathcal{C}_{A}$. Let $A=A_{s}\left(\theta \sigma_{A}\right)^{\star}$. Note that $A$ is a closed intermediate extended process and $\phi(A)$ is a closed frame. Thanks to the previous point, we also have that $\theta \in \operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}\right)$. Let $\sigma_{B}$ be the substitution corresponding to the maximal frame of $\mathcal{C}_{B}$. Let $B=$ $B_{s}\left(\theta \sigma_{B}\right)^{\star}$. We have that $B$ is a closed intermediate extended process and $\phi(B)$ is a closed frame. Assume that $\phi(A) \nsim \phi(B)$. Since we have $\operatorname{dom}(\phi(A))=\operatorname{dom}(\phi(B))$, this means that there exist two terms $M$ and $N$ such that

- $f v(M, N) \subseteq \operatorname{dom}(\phi(A))=\operatorname{dom}\left(\phi\left(A_{s}\right)\right)$,
- $f n(M, N) \cap(b n(A) \cup b n(B))=\emptyset$, and
- $\left(M \sigma_{A}^{\prime}\right)\left(\theta \sigma_{A}\right)^{\star}=\mathrm{E}\left(N \sigma_{A}^{\prime}\right)\left(\theta \sigma_{A}\right)^{\star}$ and $\left(M \sigma_{B}^{\prime}\right)\left(\theta \sigma_{B}\right)^{\star} \neq \mathrm{E}\left(N \sigma_{B}^{\prime}\right)\left(\theta \sigma_{B}\right)^{\star}$ (or vice-versa), where $\phi\left(A_{s}\right)=\nu \tilde{n}_{A}^{\prime} \cdot \sigma_{A}^{\prime}$ and $\phi\left(B_{s}\right)=\nu \tilde{n}_{B}^{\prime} \cdot \sigma_{B}^{\prime}$.

Hence, we have that $\mathrm{N}_{s}^{\prime}(f v(M, N))=\mathrm{f}$ and we can also assume w.l.o.g. that $\mathrm{N}_{s}^{\prime}(f n(M, N))=\mathrm{f}$. Now, let $\rho=\{x \mapsto M, y \mapsto N\}$. First note that $\theta \cup \rho$ is closed w.r.t. $\mathcal{C}_{A}^{\prime}$ and $\mathcal{C}_{B}^{\prime}$. It remains to show that $\theta \cup \rho \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime}\right.$; $\left.\mathrm{N}_{s}^{\prime}\right)$ whereas $\theta \cup \rho \notin \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ obtaining in this way a contradiction.

- $\theta \cup \rho \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$.

We want to show that $\left((\theta \cup \rho) \sigma_{A}^{\prime}\right)^{\star}$ satisfies the constraints in $\mathcal{C}_{A}^{\prime}$. We have that $\left((\theta \cup \rho) \sigma_{A}^{\prime}\right)^{\star}=\left(\theta \sigma_{A}\right)^{\star} \cup\left(\rho \sigma_{A}^{\prime}\right)\left(\theta \sigma_{A}\right)^{\star}$. By hypothesis, we know that $\left(\theta \sigma_{A}\right)^{\star}$ satisfies the constraints in $\mathcal{C}_{A}$. Hence, we conclude for the constraint in $\mathcal{C}_{A}$. We have also that $x\left((\theta \cup \rho) \sigma_{A}^{\prime}\right)^{\star}={ }_{\mathrm{E}} y((\theta \cup$ $\left.\rho) \sigma_{A}^{\prime}\right)^{\star}$, since we know that $\left(M \sigma_{A}^{\prime}\right)\left(\theta \sigma_{A}\right)^{\star}=\mathrm{E}\left(N \sigma_{A}^{\prime}\right)\left(\theta \sigma_{A}\right)^{\star}$.

- $\theta \cup \rho \notin \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$.

We show that $\left((\theta \cup \rho) \sigma_{B}^{\prime}\right)^{\star}$ does not satisfy the constraint $x=y$. We have that $\left.x\left((\theta \cup \rho) \sigma_{B}^{\prime}\right)^{\star}=\left(M \sigma_{B}^{\prime}\right)\left(\theta \sigma_{B}\right)\right)^{\star}$ and $y\left((\theta \cup \rho) \sigma_{B}^{\prime}\right)^{\star}=$ $\left(N \sigma_{B}^{\prime}\right)\left(\theta \sigma_{B}\right)^{\star}$. We know that $\left.\left(M \sigma_{B}^{\prime}\right)\left(\theta \sigma_{B}\right)^{\star}\right) \neq \mathrm{E}\left(N \sigma_{B}^{\prime}\right)\left(\theta \sigma_{B}\right)^{\star}$. This allows us to conclude.

Although we do not need completeness of symbolic static equivalence for our result, we may note that it follows from Baudet's result [5]. By completeness we mean that $A \sim B$ implies that $\left(A ; \emptyset ; \mathrm{N}_{s}\right) \sim_{s}\left(B ; \emptyset ; \mathrm{N}_{s}\right)$ for any compatible naming environment $\mathrm{N}_{s}$.
We now define symbolic labelled bisimulation using our symbolic semantics.
Definition 9.3 (Symbolic labelled bisimilarity $\left(\approx_{s}\right)$ ) Symbolic labelled bisimilarity is the largest symmetric relation $\mathcal{R}$ on closed well-formed symbolic processes with same naming environment, such that $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \mathcal{R}\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ implies

1. $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \sim_{s}\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$
2. if $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \rightarrow_{s}\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$ with $\operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right) \neq \emptyset$, then there exists a symbolic process $\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}\right)$ such that

- $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right) \rightarrow_{s}^{*}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}\right)$, and
- $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{\mathrm{s}}\right) \mathcal{R}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}\right)$;

3. if $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \xrightarrow{\alpha_{s}}{ }_{s}\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ with $\operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right) \neq \emptyset$, then there exists a symbolic process $\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ such that

- $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right) \rightarrow_{s}^{*} \xrightarrow{\alpha_{s}}{ }_{s} \rightarrow_{s}^{*}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$, and
- $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right) \mathcal{R}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$.

The side condition $\operatorname{Sol}_{\mathrm{E}}^{\text {cl }}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right) \neq \emptyset$ ensures that we only consider symbolic executions that correspond to at least one concrete execution. The following theorem states the soundness of the symbolic bisimulation with respect to the intermediate one.

Theorem 9.4 (soundness of symbolic labelled bisimilarity) Let ( $A$; N ) and $(B ; \mathrm{N})$ be two intermediate processes. Let $\mathrm{N}_{s}$ be a symbolic naming environment such that $\left.\mathrm{N}_{s}\right|_{\mathcal{N} \cup \mathcal{X}}=\mathrm{N}$ and $\mathrm{N}_{s}(y)=\mathrm{n}$ for all $y \in \mathcal{Y}$. We have that

$$
\left(A ; \emptyset ; \mathrm{N}_{s}\right) \approx_{s}\left(B ; \emptyset ; \mathrm{N}_{s}\right) \Rightarrow(A ; \mathrm{N}) \approx_{i}(B ; \mathrm{N})
$$

Proof. To prove this result, first we define a new relation $\mathcal{R}^{\prime}$ and then we will show that $\mathcal{R}^{\prime}$ is an intermediate labelled bisimulation witnessing $(A ; \mathrm{N}) \approx_{i}(B ; \mathrm{N})$. Let $\mathcal{R}$ be the relation witnessing $\left(A ; \emptyset ; \mathbf{N}_{s}\right) \approx_{s}\left(B ; \emptyset ; \mathrm{N}_{s}\right)$.
(i) Definition of $\mathcal{R}^{\prime}$.
$(A ; \mathrm{N}) \mathcal{R}^{\prime}(B ; \mathrm{N})$ if there exists two closed well-formed symbolic processes $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ such that

- $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \mathcal{R}\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ with $\mathrm{N}=\left.\mathrm{N}_{s}\right|_{\mathcal{N} \cup \mathcal{X}}$, and
- there exists $\theta \in \operatorname{Sol}_{\mathrm{E}}^{c}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ such that $A_{s}\left(\theta \sigma_{A}\right)^{\star}=A$ and $B_{s}\left(\theta \sigma_{B}\right)^{\star}=B$ where $\sigma_{A}$ (resp. $\sigma_{B}$ ) is the maximal frame of $\mathcal{C}_{A}$ (resp. $\mathcal{C}_{B}$ ).
(ii) $\mathcal{R}^{\prime}$ is an intermediate bisimulation relation witnessing $(A ; \mathrm{N}) \approx_{i}(B ; \mathrm{N})$.

First we have to show that $(A ; \mathrm{N}) \mathcal{R}^{\prime}(B ; \mathrm{N})$. To do this, it is sufficient to see that the two well-formed symbolic processes $\left(A ; \emptyset ; \mathrm{N}_{s}\right)$ and $\left(B ; \emptyset ; \mathrm{N}_{s}\right)$ satisfy the required conditions.

Now, we have to show that $\mathcal{R}^{\prime}$ satisfies the three points of the definition of intermediate labelled bisimilarity. Let $(A ; \mathrm{N})$ and $(B ; \mathrm{N})$ be two closed intermediate processes such that $(A ; \mathrm{N}) \mathcal{R}^{\prime}(B ; \mathrm{N})$. By definition of $\mathcal{R}^{\prime}$, we know that there exists two closed well-formed symbolic processes $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ such that

- $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \mathcal{R}\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$, with $\mathrm{N}=\left.\mathrm{N}_{s}\right|_{\mathcal{N} \cup \mathcal{X}}$, and
- there exists $\theta \in \operatorname{Sol}_{\mathbf{E}}^{\mathrm{cl}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ such that $A_{s}\left(\theta \sigma_{A}\right)^{\star}=A$ and $B_{s}\left(\theta \sigma_{B}\right)^{\star}=B$.

We have to show that:

1. $\phi(A) \sim \phi(B)$.

Thanks to Proposition 9.2, we deduce that

- $\operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)=\operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}\right)$, and
- for all $\theta^{\prime} \in \operatorname{Sol}_{\mathrm{E}}^{\mathrm{c}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ we have $\phi\left(A_{s}\left(\theta^{\prime} \sigma_{A}\right)^{\star}\right) \sim \phi\left(B_{s}\left(\theta^{\prime} \sigma_{B}\right)^{\star}\right)$.

Since $\theta \in \operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ we deduce that $\phi\left(A_{s}\left(\theta \sigma_{A}\right)^{\star}\right) \sim \phi\left(B_{s}\left(\theta \sigma_{B}\right)^{\star}\right)$, i.e $\phi(A) \sim \phi(B)$.
2. If $(A ; \mathrm{N}) \rightarrow_{i}\left(A^{\prime} ; \mathrm{N}\right)$, then there exists $\left(B^{\prime} ; \mathrm{N}\right)$ such that $(B ; \mathrm{N}) \rightarrow_{i}^{*}\left(B^{\prime} ; \mathrm{N}\right)$ and $\left(A^{\prime} ; \mathrm{N}\right) \mathcal{R}^{\prime}\left(B^{\prime} ; \mathrm{N}\right)$.
By definition of $\mathcal{R}^{\prime}$, we know that $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ is a closed well-formed symbolic process such that $A_{s}\left(\theta \sigma_{A}\right)^{\star}=A$ and $\theta \in \operatorname{Sol}_{\mathrm{E}}^{\mathrm{c}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$. Hence, thanks to Proposition 8.3, we know that there exists a well-formed symbolic process $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$ such that

- $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \rightarrow_{s}\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$,
- $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$, and
- $A_{s}^{\prime}\left(\theta \sigma_{A}^{\prime}\right)^{\star}=A^{\prime}$.

We have that $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \mathcal{R}\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ and $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \rightarrow{ }_{s}\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$. Moreover $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$, and actually $\theta \in \operatorname{Sol}_{\mathrm{E}}^{\text {cl }}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$, thus we know that $\operatorname{Sol}_{\mathrm{E}}^{\mathrm{c}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right) \neq \emptyset$. Hence, there exists a closed well-formed symbolic process $\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}\right)$ such that

- $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right) \rightarrow_{s}^{*}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}\right)$, and
- $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right) \mathcal{R}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}\right)$.

Since $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right) \mathcal{R}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}\right)$, we deduce that $\operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)=\operatorname{Sol}_{\mathrm{E}}^{\text {cl }}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}\right)$ by using Proposition 9.2. We have that $\theta \in \operatorname{Sol}_{\mathrm{E}}^{\mathrm{c}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$ and hence, we deduce that $\theta \in \operatorname{Sol}_{\mathrm{E}}^{\text {cl }}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}\right)$. Now, by Corollary 8.5, we deduce that $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ and $\left(B_{s}\left(\theta \sigma_{B}\right)^{\star} ; \mathrm{N}\right) \rightarrow^{*}\left(B_{s}^{\prime}\left(\theta \sigma_{B}^{\prime}\right)^{\star} ; \mathrm{N}\right)$. Let
$B^{\prime}=B_{s}^{\prime}\left(\theta \sigma_{B}^{\prime}\right)^{\star}$. As $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$ and $\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}\right)$ are two closed wellformed symbolic processes such that $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right) \mathcal{R}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}\right)$ and $A_{s}^{\prime}\left(\theta \sigma_{A}^{\prime}\right)^{\star}=A^{\prime}$ and $B_{s}^{\prime}\left(\theta \sigma_{B}^{\prime}\right)^{\star}=B^{\prime}$, we have that $\left(A^{\prime} ; \mathrm{N}\right) \mathcal{R}^{\prime}\left(B^{\prime} ; \mathrm{N}\right)$.
3. If $(A ; \mathrm{N}) \xrightarrow{\alpha}{ }_{i}\left(A^{\prime} ; \mathrm{N}^{\prime}\right)$ with $f v(\alpha) \subseteq \operatorname{dom}(A)$ then $(B ; \mathrm{N}) \rightarrow_{i}^{*}{ }^{\alpha} \rightarrow_{i}^{*}\left(B^{\prime} ; \mathrm{N}^{\prime}\right)$ and $\left(A^{\prime} ; \mathrm{N}^{\prime}\right) \mathcal{R}^{\prime}\left(B^{\prime} ; \mathrm{N}^{\prime}\right)$ for some $B^{\prime}$.

By definition of $\mathcal{R}^{\prime}$, we know that $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ is a closed well-formed symbolic process such that $A_{s}\left(\theta \sigma_{A}\right)^{\star}=A$ and $\theta \in \operatorname{Sol}_{\mathrm{E}}^{\mathrm{c}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$. Hence, thanks to Proposition 8.4, we know that there exist a well-formed symbolic process $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$, a substitution $\theta^{\prime}$ and a label $\alpha_{s}$ such that

- $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \xrightarrow{\alpha_{s}}{ }_{s}\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ and $\mathrm{N}^{\prime}=\left.\mathrm{N}_{s}^{\prime}\right|_{\mathcal{N} \cup \mathcal{X}}$,
- $\theta^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ and $\left.\theta^{\prime}\right|_{c v\left(\mathcal{C}_{A}\right)}=\theta$,
- $A_{s}^{\prime}\left(\theta^{\prime} \sigma_{A}^{\prime}\right)^{\star}=A^{\prime}$ where $\sigma_{A}^{\prime}$ is the substitution corresponding to the maximal frame in $\mathcal{C}_{A}^{\prime}$, and
- $\alpha_{s} \theta^{\prime}=\alpha$.

Actually, we have that $\theta^{\prime} \in \operatorname{Sol}_{\mathrm{E}}^{\mathrm{c}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$, i.e. $\theta^{\prime}$ is a closed solution. This is clear when the label $\alpha$ is not an input. In the case of an input, $\alpha_{s}$ is of the form $\operatorname{in}(c, y)$ and we conclude by relying on the fact that $\operatorname{vars}\left(y \theta^{\prime}\right)=f v(\alpha) \subseteq \operatorname{dom}(A)$.
We have that $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \mathcal{R}\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ and $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \xrightarrow{\alpha}{ }_{s}\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$. Since $\theta^{\prime} \in \operatorname{Sol}_{\mathrm{E}}^{\mathrm{c}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$, we know that $\operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right) \neq \emptyset$. Hence, there exists a closed well-formed symbolic process $\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ such that

- $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right) \rightarrow_{s}^{*} \xrightarrow{\alpha_{s}}{ }_{s}{ }_{s}^{*}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$, and
- $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right) \mathcal{R}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$.

Since $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right) \mathcal{R}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$, thanks to Proposition 9.2, we have that $\operatorname{Sol}_{\mathrm{E}}^{\mathrm{c}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)=\operatorname{Sol}_{\mathrm{E}}^{c \mathrm{c}}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$. We have that $\theta^{\prime} \in \operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ and hence, we deduce that $\theta^{\prime} \in \operatorname{Sol}_{\mathrm{E}}^{\mathrm{c}}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$. Now, by Corollary 8.6, we deduce that $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ and $\left(B_{s}\left(\theta \sigma_{B}\right)^{\star} ; \mathrm{N}\right) \rightarrow^{*}\left(B_{s}^{\prime}\left(\theta^{\prime} \sigma_{B}^{\prime}\right)^{\star} ; \mathrm{N}\right)$.
As $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ and $\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ are two closed well-formed symbolic processes such that $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right) \mathcal{R}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ and $A_{s}^{\prime}\left(\theta^{\prime} \sigma_{A}^{\prime}\right)^{\star}=A^{\prime}$ and $B_{s}^{\prime}\left(\theta^{\prime} \sigma_{B}^{\prime}\right)^{\star}=B^{\prime}$, we have that $\left(A^{\prime} ; \mathrm{N}\right) \mathcal{R}^{\prime}\left(B^{\prime} ; \mathrm{N}\right)$. This allows us to conclude.

## PART III <br> - Soundness of Symbolic Bisimulation

We now put the results of the previous section together (Theorem 5.2 and Theorem 9.4) to prove our main result.

Theorem 9.5 (Soundness of symbolic bisimulation) Let $A$ and $B$ be two closed, nv-distinct extended processes. For any symbolic naming environment $\mathrm{N}_{s}$ compatible with $A \downarrow, B \downarrow$ and the empty constraint system we have that

$$
\left(A \downarrow ; \emptyset ; \mathrm{N}_{s}\right) \approx_{s}\left(B \downarrow ; \emptyset ; \mathrm{N}_{s}\right) \text { implies } A \approx B
$$

Note that limiting the theorem to nv-distinct processes is not an onerous restriction. If we want to prove that $A \approx B$, we can construct by $\alpha$-conversion two nv-distinct processes $A^{\prime}, B^{\prime}$ such that $A^{\prime} \equiv A$ and $B^{\prime} \equiv B$. Showing $A^{\prime} \approx B^{\prime}$ implies that $A \approx B$, since $\approx$ is closed under structural equivalence.

## 10 Discussion

Our techniques suffer from the same sources of incompleteness as the ones described for the spi calculus in [10]. In a symbolic bisimulation the instantiation of input variables is postponed until the point at which they are actually used, leading to a finer relation. We illustrate this point on an example, similar to one given in [10].

Example 10.1 Consider the two following processes:

$$
\begin{aligned}
P_{1} & =\nu c_{1} \cdot \operatorname{in}\left(c_{2}, x\right) \cdot\left(\operatorname{out}\left(c_{1}, b\right)\left|\operatorname{in}\left(c_{1}, y\right)\right| \text { if } x=a \text { then } \operatorname{in}\left(c_{1}, z\right) \cdot o u t\left(c_{2}, a\right)\right) \\
Q_{1} & =\nu c_{1} \cdot \operatorname{in}\left(c_{2}, x\right) \cdot\left(\operatorname{out}\left(c_{1}, b\right)\left|\operatorname{in}\left(c_{1}, y\right)\right| \operatorname{in}\left(c_{1}, z\right) \cdot \text { if } x=a \text { then out }\left(c_{2}, a\right)\right)
\end{aligned}
$$

We have that $P_{1} \approx Q_{1}$ whereas $\left(P_{1} ; \emptyset ; \mathbf{N}_{s}\right) \not \boldsymbol{z}_{s}\left(Q_{1} ; \emptyset ; \mathbf{N}_{s}\right)$ for any compatible naming environment $\mathrm{N}_{s}$. To see the latter inequivalence, observe that $\left(Q_{1} ; \emptyset ; \mathrm{N}_{s}\right)$ can make the transition $\xrightarrow{\mathrm{in}\left(c_{2}, x^{\prime}\right)}$ s and then an internal transition to $\left(\nu c_{1}\right.$. (in $\left(c_{1}, y\right) \mid$ if $x^{\prime}=a$ then $\left.\left.\operatorname{out}\left(c_{2}, a\right)\right) ; \mathcal{C} ; \mathrm{N}_{s}^{\prime}\right)$ with $\mathcal{C}=\left\{0 \Vdash x^{\prime}\right.$, $\left.\left.\operatorname{gd}\left(c_{2}\right)\right\}\right)$; this process is still undecided about whether $x^{\prime}=a$ or not. $\left(P_{1} ; \emptyset\right.$; $\mathrm{N}_{s}$ ) can make the transition $\xrightarrow{\mathrm{in}\left(c_{2}, x^{\prime}\right)}$ s but then cannot make the corresponding internal transition without committing either to the constraint $x^{\prime}=a$ or to the constraint $x^{\prime} \neq a$. Whichever one it does, $Q_{1}$ can do the opposite, showing the inequivalence.

The second example shows that the requirement that the constraint systems must have the same solutions gives rise to some incompleteness.

Example 10.2 Consider the two following processes:

$$
\begin{aligned}
P_{2} & =\operatorname{in}(c, x) \cdot \text { out }(c, a) \\
Q_{2} & =\operatorname{in}(c, x) \cdot \text { if } x=a \text { then } \text { out }(c, a) \text { else out }(c, a)
\end{aligned}
$$

We have that $P_{2} \approx Q_{2}$ whereas $\left(P_{2} ; \emptyset ; \mathbf{N}_{s}\right) \not \approx s\left(Q_{2} ; \emptyset ; \mathbf{N}_{s}\right)$ for any compatible naming environment $\mathrm{N}_{s}$. Indeed, we have that $\left(P_{2} ; \emptyset ; \mathrm{N}_{s}\right) \xrightarrow{\operatorname{in}\left(c, x^{\prime}\right)}{ }_{s}(\operatorname{out}(c, a)$; $\left.\mathcal{C} ; \mathrm{N}_{s}^{\prime}\right)$ with $\left.\mathcal{C}=\left\{0 \Vdash x^{\prime}, \operatorname{gd}(c)\right\}\right)$ whereas $\left(Q_{2} ; \emptyset ; \mathbf{N}_{s}\right) \xrightarrow{\operatorname{in}\left(c, x^{\prime}\right)}$ if $x=$ a then out $(c, a)$ else out $(c, a)$ and then can move to either (out $(c, a) ; \mathcal{C}_{1} ; \mathrm{N}_{s}^{\prime}$ ) or (out $\left.(c, a) ; \mathcal{C}_{2} ; \mathrm{N}_{s}^{\prime}\right)$ where $\mathcal{C}_{1}=\left\{0 \Vdash x^{\prime}, \operatorname{gd}(c), x^{\prime}=a\right\}$ and $\mathcal{C}_{2}=\left\{0 \Vdash x^{\prime}\right.$, $\left.\operatorname{gd}(c), \operatorname{gd}\left(x^{\prime}\right), x^{\prime} \neq a\right\}$. However, neither $\mathcal{C}_{1}$ nor $\mathcal{C}_{2}$ is equivalent to $\mathcal{C}$.

Although our symbolic bisimulation is not complete, as shown above, we are able to prove labelled bisimulation on interesting examples for which the method implemented in the state-of-the-art ProVerif tool [7] fails. For instance, ProVerif is unable to establish labelled bisimilarity between out $(c, a) \mid \operatorname{out}(c, b)$ and out $(c, b) \mid \operatorname{out}(c, a)$ whereas of course we are able to deal with such examples. A more interesting example, for which our symbolic semantics plays an important role is as follows.

Example 10.3 Consider the following two processes.

$$
\begin{aligned}
P & =\nu c_{1} \cdot\left(\operatorname{in}\left(c_{2}, x\right) . \operatorname{out}\left(c_{1}, x\right) \cdot \text { out }\left(c_{2}, a\right) \mid \operatorname{in}\left(c_{1}, y\right) . \text { out }\left(c_{2}, y\right)\right) \\
Q & =\nu c_{1} \cdot\left(\operatorname{in}\left(c_{2}, x\right) . \operatorname{out}\left(c_{1}, x\right) . \operatorname{out}\left(c_{2}, x\right) \mid \operatorname{in}\left(c_{1}, y\right) \cdot \text { out }\left(c_{2}, a\right)\right)
\end{aligned}
$$

These two processes are labelled bisimilar and our symbolic labelled bisimulation is complete enough to prove this. In particular, let $P^{\prime}=\nu c_{1}$.(out $\left(c_{1}, x^{\prime}\right) . \operatorname{out}\left(c_{2}, a\right) \mid$ $\operatorname{in}\left(c_{1}, y\right)$.out $\left.\left(c_{2}, y\right)\right)$ and $Q^{\prime}=\nu c_{1}$. (out $\left(c_{1}, x^{\prime}\right)$. out $\left(c_{2}, x^{\prime}\right) \mid \operatorname{in}\left(c_{1}, y\right)$. out $\left.\left(c_{2}, a\right)\right)$. The relation $\mathcal{R}$, that witnesses the symbolic bisimulation, includes

$$
\begin{array}{rcc}
\left(P ; \emptyset ; \mathbf{N}_{s}\right) & \mathcal{R} & \left(Q ; \emptyset ; \mathbf{N}_{s}\right) \\
\left(P^{\prime} ;\left\{\nu c_{1} .0 \Vdash x^{\prime}, \operatorname{gd}\left(c_{2}\right)\right\} ; \mathbf{N}_{s}^{\prime}\right) & \mathcal{R} & \left(Q^{\prime} ;\left\{\nu c_{1} .0 \Vdash x^{\prime}, \operatorname{gd}\left(c_{2}\right)\right\} ; \mathrm{N}_{s}^{\prime}\right) \\
\left(\nu c_{1} .\left(\operatorname{out}\left(c_{2}, a\right) \mid \operatorname{out}\left(c_{2}, x^{\prime}\right)\right) ;\right. & & \left(\nu c_{1} \cdot\left(\operatorname{out}\left(c_{2}, x^{\prime}\right) \mid \operatorname{out}\left(c_{2}, a\right)\right) ;\right. \\
\left.\left\{\nu c_{1} .0 \Vdash x^{\prime}, \operatorname{gd}\left(c_{2}\right), \operatorname{gd}\left(c_{1}\right)\right\} ; \mathbf{N}_{s}^{\prime}\right) & \mathcal{R} & \left.\left\{\nu c_{1} .0 \Vdash x^{\prime}, \operatorname{gd}\left(c_{2}\right), \operatorname{gd}\left(c_{1}\right)\right\} ; \mathrm{N}_{s}^{\prime}\right)
\end{array}
$$

The example above is inspired by the problems we encountered when we analysed a bisimulation representing the privacy property in an electronic voting protocol [19]. ProVerif is not able to prove this kind of equivalence; its algorithm is limited to cases that the two processes $P, Q$ have the same structure, and differ only in the terms that are output. In this example, the processes differ in their structure, providing the motivation for our methods. Our symbolic bisimulation seems to be "sufficiently" complete to deal with examples of privacy and anonymity properties arising in protocol analysis. We demonstrate that more fully with the next example, which considers the privacy property of voting systems in more detail, and illustrates the equational reasoning aspects of the calculus.

Example 10.4 We consider a simplified version of the voting protocol due to Fujioka, Okamoto and Ohta (see [17]) that is analysed in [19, 12]. In the simplification we consider here, the voter casts a vote in the first phase of the voting process by blinding his selected candidate $v$ with a random value $r$, and signing the result with his private key. He sends this signature to the collector. Using this signature, the collector is able to check that the voter is entitled to vote, and the collector sends back his signature on the blinded choice of the voter. The voter now unblinds this value, obtaining the collector's signature on his vote. In the second phase, he anonymously sends this signature to the collector for counting.
$\left.\begin{array}{ccc}\text { Voter } \\ \text { newr }\end{array}\right) \quad$ Collector

The blinding operation allows signatures to be performed blindly. Here, the collector signs the vote, but is not able to see its value. This helps to achieve the property of vote-privacy for the voter. To avoid traffic analysis attacks, the protocol is in two phases; the voter synchronises with other voters between the two phases (represented by "sync." in the figure). This synchronisation can easily be modelled using private channels, but we prefer to omit that detail to keep the example simple. Although it satisfies vote-privacy, this simple protocol would allow a voter to vote multiple times by repeatedly sending the last message. That problem is easily fixed, but we prefer to keep the protocol simple for the purpose of illustration.

We assume a signature containing the binary functions sign, getmess, blind, unblind, and the unary function pk with the equations:

$$
\begin{aligned}
\operatorname{getmess}_{\mathrm{pk}(x)}\left(\operatorname{sign}_{x}(y)\right) & =y \\
\operatorname{unblind}_{x}\left(\operatorname{sign}_{y}\left(\operatorname{blind}_{x}(z)\right)\right) & =\operatorname{sign}_{y}(z)
\end{aligned}
$$

Note that key arguments are written as subscripts, to aid readability. A voter with signing key skv casting the vote $v$ for the collector with public key pkc runs the process $P$ described below. (Since all the communications take place over a public channel, we do not mention it for sake of readability.)

$$
\left.\begin{array}{l}
P(s k v, v, p k c)=\nu r .\left(\operatorname{out}^{\left(\operatorname{sign}_{s k v}\left(\operatorname{blind}_{r}(v)\right)\right) \cdot \operatorname{in}(x) .}\right. \\
\quad \text { if getmess } \\
p k c
\end{array}(x)=\operatorname{blind}_{r}(v) \text { then out }\left(\operatorname{unblind}_{r}(x)\right)\right)
$$

The anonymity property we want to prove says that an observer (which may include the collector) cannot distinguish a situation in which the voter $A$ votes $v_{a}$ and the voter $B$ votes $v_{b}$, from another one in which they vote the other way around. Roughly speaking, it is the following labelled bisimilarity:

```
\nuka, skb(out(pk(ska)).out(pk(skb)).(P(ska, va, pk (skc))|P(skb, vb, pk(skc))))
    \approx
\nukka,skb(out(pk(ska)).out(pk(skb)).(P(ska, vb, pk(skc))|P(skb,\mp@subsup{v}{a}{\prime},\textrm{pk}(skc))))
```

with the proviso that the voters $A$ and $B$ have to synchronise at the "sync." point. Note that we treat the collector's private key skc as a public name; we prove privacy property even in presence of a corrupted collector who disclosed his private key.

Below, we illustrate some of the calculations to establish this equivalence (of course we prove $\approx_{s}$ to establish $\approx$ ). We will only consider deducibility and equality constraints and we do not give the naming environment associated to each symbolic process.

| intermediate process | some of the constraints |
| :---: | :---: |
| $P\left(s k a, v_{a}, \operatorname{pk}(s k c)\right)$ | $\emptyset$ |
| $\xrightarrow{\nu x_{1} \text {.out }\left(x_{1}\right)}$ s |  |
| $\begin{aligned} & \nu r .\left(\operatorname{in}(x) . \text { if } \operatorname{getmess}_{\mathrm{pk}(s k c)}(x)=\operatorname{blind}_{r}\left(v_{a}\right)\right. \\ & \text { then out } \left.\left(\operatorname{unblind}_{r}(x)\right) \mid\left\{M_{1} / x_{1}\right\}\right) \end{aligned}$ | $\emptyset$ |
| $\begin{array}{r} \xrightarrow{i n(y)} s \quad \nu r .\left(\text { if } \operatorname{getmess}_{\mathrm{pk}(s k c)}(y)=\operatorname{blind}_{r}\left(v_{a}\right)\right. \\ \text { then out } \left.\left(\operatorname{unblind}_{r}(y)\right) \mid\left\{M_{1} / x_{1}\right\}\right) \end{array}$ | $\nu r .\left\{{ }^{M_{1}} / x_{1}\right\} \Vdash y$ |
| $\rightarrow_{s} \quad \nu r .\left(\operatorname{out}\left(\operatorname{unblind}_{r}(y)\right) \mid\left\{{ }^{\left.M_{1} / x_{1}\right\}}\right\}\right)$ | $\begin{gathered} \nu r .\left\{{ }^{M_{1}} / x_{1}\right\} \Vdash y \\ \text { getmess }_{\mathrm{pk}(s k c)}(y)=\operatorname{blind}_{r}\left(v_{a}\right) \end{gathered}$ |
| $\xrightarrow{\nu x_{2} . \operatorname{out}\left(x_{2}\right)}{ }_{s} \quad \nu r .\left(\left\{{ }^{M_{1}} / x_{1}\right\} \mid\left\{{ }^{\left.M_{2} / x_{2}\right\}}\right\}\right)$ | $\begin{gathered} \nu r . \nu x_{2} \cdot\left\{\begin{array}{l} \left.M_{1} / x_{1}\right\} \Vdash y \\ \operatorname{getmess}_{\mathrm{pk}(s k c)}(y)=\operatorname{blind}_{r}\left(v_{a}\right) \end{array}\right. \end{gathered}$ |

where $M_{1}=\operatorname{sign}_{\text {ska }}\left(\operatorname{blind}_{r}\left(v_{a}\right)\right)$ and $M_{2}=\operatorname{unblind}_{r}(y)$. Note that to derive the first step, we use the rule $\mathrm{OuT}-\mathrm{T}_{s}$ and $\mathrm{Scope}_{s}$ to add the restriction $\nu r$. in front of the process. To derive the other steps, for instance $\nu x_{2}$. out $\left(x_{2}\right)$ we also use the rule $\mathrm{PAR}_{s}$ to put $\left\{{ }^{M_{1}} / x_{1}\right\}$ in parallel. About the naming environment, we have assumed among others that $x_{1}, x_{2}$ and $y$ are marked as new (namely n ) at the beginning. At the end, the variables $x_{1}, x_{2}$ are marked as f whereas $y$ is marked as c.

We can now consider some example evolutions for the two processes in the equivalence (1) we want to establish. One of the expected evolutions of the left hand side is as follows. The process $P\left(s k a, v_{a}, \mathrm{pk}(s k c)\right)$ will first do an action directly followed by the corresponding action of the process $P\left(s k b, v_{b}, \mathrm{pk}(s k c)\right)$. The $\downarrow$ operator allows us to put the restrictions in front of the process to have an intermediate process.

$$
\begin{aligned}
& \text { ( } \nu s k a, s k b .(\text { out }(\mathrm{pk}(s k a)) . \text { out }(\mathrm{pk}(s k b)) \text {. } \\
& \left.\left.\left(P\left(s k a, v_{a}, \operatorname{pk}(s k c)\right) \mid P\left(s k b, v_{b}, \operatorname{pk}(s k c)\right)\right)\right) \downarrow ; \emptyset ; \mathrm{N}_{s}\right) \\
& \left.\xrightarrow{\nu x_{0} . \text { out }\left(x_{0}\right)} s \xrightarrow{\nu x_{0}^{\prime} . \text { out }\left(x_{0}^{\prime}\right)} s \quad \quad \text { (* outputs of the public keys }{ }^{*}\right) \\
& \xrightarrow{\nu x_{1} . \text { out }\left(x_{1}\right)} s \xrightarrow{\nu x_{1}^{\prime} . \text { out }\left(x_{1}^{\prime}\right)} s \quad \quad(* \text { outputs of the first message } *) \\
& \xrightarrow{i n(y)}{ }_{s} \xrightarrow{i n\left(y^{\prime}\right)}{ }_{s} \quad\left(* \text { inputs of the second message }{ }^{*}\right) \\
& \rightarrow_{s} \rightarrow_{s} \quad\left(* \text { conditional - then branch }{ }^{*}\right) \\
& \xrightarrow{\nu x_{2} . \text { out }\left(x_{2}\right)}{ }_{s} \xrightarrow{\nu x_{2}^{\prime} . \text { out }\left(x_{2}^{\prime}\right)} s \quad\left(\varphi ; \mathcal{C} ; \mathrm{N}_{s}^{\prime}\right)
\end{aligned}
$$

where $\varphi=\nu$ ska, skb,ra,rb. $\left(\left\{\operatorname{pk}(s k a) / x_{0}\right\}\left|\left\{\operatorname{pk}(s k b) / x_{0}^{\prime}\right\}\right|\left\{\operatorname{sign}_{s k a}\left(\operatorname{blind}_{r a}\left(v_{a}\right)\right) / x_{1}\right\} \mid\right.$
$\left\{\operatorname{sign}_{s k b}\left(\operatorname{blind}_{r b}\left(v_{b}\right)\right) / x_{1}^{\prime}\right\}\left|\left\{\operatorname{unblind}_{r a}(y) / x_{2}\right\}\right|\left\{\right.$ unblind $\left.\left._{r b}\left(y^{\prime}\right) / x_{2}^{\prime}\right\}\right)$.
Among the constraints in $\mathcal{C}$, we have the following deducibility and equality constraints.

$$
\begin{array}{ll}
\nu x_{2}, x_{2}^{\prime} \cdot \varphi \Vdash y & \text { getmess }_{\mathrm{pk}(s k c)}(y)=\operatorname{blind}_{r a}\left(v_{a}\right) \\
\nu x_{2} \cdot x_{2}^{\prime} \cdot \varphi \Vdash y^{\prime} & \text { getmess }_{\mathrm{pk}(s k c)}\left(y^{\prime}\right)=\operatorname{blind}_{r b}\left(v_{b}\right)
\end{array}
$$

The right hand side of equivalence (1) can evolve in a similar way, i.e. with the same labels, to the symbolic process $\left(\varphi^{\prime} ; \mathcal{C}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ where

- $\varphi^{\prime}=\nu s k a, s k b, r a, r b .\left(\left\{{ }^{\mathrm{pk}(s k a)} / x_{0}\right\}\left|\left\{\mathrm{pk}(s k b) / x_{0}^{\prime}\right\}\right|\left\{\operatorname{sign}_{s k a}\left(\operatorname{blind}_{r a}\left(v_{b}\right)\right) / x_{1}\right\} \mid\right.$
$\left.\left\{\operatorname{sign}_{s k b}\left(\operatorname{blind}_{r b}\left(v_{a}\right)\right) / x_{1}^{\prime}\right\}\left|\left\{\operatorname{unblind}_{r b}\left(y^{\prime}\right) / x_{2}\right\}\right|\left\{\operatorname{unblind}_{r a}(y) / x_{2}^{\prime}\right\}\right)$.
- the system $\mathcal{C}^{\prime}$ contains $\nu x_{2}, x_{2}^{\prime} \cdot \varphi^{\prime} \Vdash y, \quad \operatorname{getmess}_{\mathrm{pk}(s k c)}(y)=\operatorname{blind}_{r a}\left(v_{b}\right)$

$$
\nu x_{2}, x_{2}^{\prime} \cdot \varphi^{\prime} \Vdash y^{\prime}, \operatorname{getmess}_{\mathrm{pk}(s k c)}\left(y^{\prime}\right)=\operatorname{blind}_{r b}\left(v_{a}\right) .
$$

To fully show that the two processes are in symbolic bisimulation, we would have to consider other possible evolutions as well. We omit that here. To complete the picture for this path, we illustrate the calculations to show static equivalence for the final processes along the paths. Consider the extended constraint systems $\tilde{\mathcal{C}}$ and $\tilde{\mathcal{C}}^{\prime}$ as defined in Definition 9.1.

- $\tilde{\mathcal{C}}=\mathcal{C} \cup\left\{\varphi \Vdash z_{1} ; \varphi \Vdash z_{2} ; z_{1}=z_{2}\right\}$, and
- $\tilde{\mathcal{C}}^{\prime}=\mathcal{C}^{\prime} \cup\left\{\varphi^{\prime} \Vdash z_{1} ; \varphi^{\prime} \Vdash z_{2} ; z_{1}=z_{2}\right\}$.

Let $\tilde{\mathrm{N}}_{s}=\mathrm{N}_{s}^{\prime}\left[z_{1}, z_{2} \mapsto \mathrm{f}\right]$ where $z_{1}, z_{2}$ are constraint variables that are marked as n in $\mathrm{N}_{s}^{\prime}$. We have to establish that $\operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\tilde{\mathcal{C}} ; \tilde{\mathrm{N}}_{s}\right)=\operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\tilde{\mathcal{C}}^{\prime} ; \tilde{\mathrm{N}}_{s}\right)$. We don't prove this fully, but just illustrate with an expected solution. A solution is a map $\theta$ from the constraint variables $\left\{y, y^{\prime}, z_{1}, z_{2}\right\}$ to terms not including the constraint variables or the restricted names ska, skb, ra, rb, and in the case of $y, y^{\prime}$, not including $x_{2}, x_{2}^{\prime}$. Consider for instance the solution

$$
\theta:=\left\{\begin{array}{lllll}
y & \mapsto & \operatorname{sign}_{s k c}\left(\operatorname{getmess}_{x_{0}}\left(x_{1}\right)\right) & z_{1} & \mapsto \\
x_{2} \\
y^{\prime} & \mapsto & \operatorname{sign}_{s k c}\left(\operatorname{getmess}_{x_{0}^{\prime}}\left(x_{1}^{\prime}\right)\right) & z_{2} & \mapsto
\end{array} v_{a}\right.
$$

We have that $\theta \in \operatorname{Sol}_{\mathrm{E}}^{\mathrm{cl}}\left(\tilde{\mathcal{C}} ; \tilde{\mathrm{N}}_{s}\right)$ and also $\theta \in \operatorname{Sol}_{\mathrm{E}}^{\text {cl }}\left(\tilde{\mathcal{C}}^{\prime} ; \tilde{\mathrm{N}}_{s}\right)$.
ProVerif can handle the equational theory of this example, but it is not able to prove the privacy property. The reason is that ProVerif is not able to construct the bisimulation that is required. In the first phase, the behaviour of voter $A$ must be matched with the behaviour of voter $A$, and $B$ 's behaviour with $B$ 's behaviour, so that the signatures respect the static equivalence; while in the second phase, $A$ 's behaviour must be matched with $B$ 's behaviour, and $B$ 's behaviour with $A$ 's behaviour, so that the votes output respect the static equivalence. (However, our algorithms are not yet implemented!)

## 11 Related and Future Work

Pioneering work in symbolic bisimulations has been done by Henessy and Lin [18] for value-passing CCS. However, the result which is most closely related to ours is by Borgström et al. [10]: they define a symbolic bisimulation for the spi calculus with the same sources of incompleteness as we have. However, our treatment of general equational theories is non trivial as illustrated by the problems implied for structural equivalence.

For many important equational theories, static equivalence has been shown to be decidable in [1]. More interestingly, some work has also been done to automate observational equivalence. The ProVerif tool [7] automates observational equivalence checking for the applied pi calculus (with process replication), but since the problem is undecidable the technique it uses is necessarily incomplete. The tool aims at proving a finer equivalence relation and relies on easily matching up the execution paths of the two processes [8]. In his thesis, Baudet [6] presents a decision procedure for a similar equivalence, called diff-equivalence, in a simplified process calculus. Examples where this equivalence relation is too fine occur when proving the observational equivalence required to show voteprivacy [19, 12]. Although our symbolic bisimulation is not complete, we are able to conclude on examples where ProVerif fails (see Section 10).

The technique used in ProVerif will generally fail in the case where the two processes take different branches at some point. This is the case in Example 10.3: after a synchronisation (modelled by a communication on the private channel $c_{1}$ ) between the two parallel components of process $P$ (resp. $Q$ ), the output action of the left component of $P$ matches the output action of the right component of $Q$.

Concerning future work, the obvious next step is to study the equivalence of solutions for constraint systems under different equational theories. Promising results have already been shown in [5] for a significant class of equational theories but for constraint systems that do not have disequalities. These results readily apply for deciding our symbolic bisimulation on the fragment without else branches in conditionals. We plan to implement an automated tool for checking observational equivalence. In particular we aim at automating proofs
arising in case studies of electronic voting protocols which currently rely on hand proofs [12].

Another direction for future work is how to include process replication (the "!" operator), which is omitted entirely from this paper. Since we require to put the $\nu$ operator in outermost position in intermediate extended processes, one could first try to include replications that do not have $\nu$ in their scope. This corresponds to processes that may not terminate, but can only create finitely many names. Including replication having $\nu$ in its scope is certainly more challenging.

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## A Proofs of Part I - Intermediate Calculus

## A. 1 Soundness Results

Proposition A. 1 (soundness of $\equiv_{i}$ ) Let $\left(A_{i} ; \mathrm{N}\right)$ and ( $\left.B_{i} ; \mathrm{N}\right)$ be two intermediate processes such that $\left(A_{i} ; \mathrm{N}\right) \equiv_{i}\left(B_{i} ; \mathrm{N}\right)$. Then we have that $A_{i} \equiv B_{i}$.

Proof. This proof is straightforward and can be done by induction on the proof tree witnessing $\left(A_{i} ; \mathrm{N}\right) \equiv_{i}\left(B_{i} ; \mathrm{N}\right)$. The only point where we have to pay attention is closure by application of intermediate evaluation context. However, to deal with this case, it is sufficient to note that any intermediate evaluation context w.r.t. an intermediate extended process $A$ is also an evaluation context w.r.t. $A$.

Proposition A. 2 (soundness of $\rightarrow_{i}$ ) Let $\left(A_{i} ; \mathrm{N}\right)$ and ( $B_{i} ; \mathrm{N}$ ) be two intermediate processes such that $\left(A_{i} ; \mathrm{N}\right) \rightarrow_{i}\left(B_{i} ; \mathrm{N}\right)$. Then we have that $A_{i} \rightarrow B_{i}$.

Proof. This proof is straightforward and can be done by induction on the proof tree witnessing $\left(A_{i} ; \mathrm{N}\right) \rightarrow_{i}\left(B_{i} ; \mathrm{N}\right)$. The base case, i.e. $\mathrm{Comm}_{i}, \mathrm{THEN}_{i}$ and $\mathrm{ELSE}_{i}$ are obvious since corresponding rules exist in the initial semantics. To deal with closure by application of evaluation context, it is sufficient to note that any intermediate evaluation context w.r.t. an intermediate extended process $A$ is also an evaluation context w.r.t. $A$. Lastly, closure by structural equivalence can be easily done thanks to Proposition A.1.

Proposition A. 3 (soundness of $\xrightarrow{\alpha}{ }_{i}$ ) Let $\left(A_{i} ; \mathrm{N}\right)$ and ( $\left.B_{i} ; \mathrm{N}^{\prime}\right)$ be two intermediate processes such that $\left(A_{i} ; \mathrm{N}\right) \xrightarrow{\alpha}{ }_{i}\left(B_{i} ; \mathrm{N}^{\prime}\right)$. Then we have that $A_{i} \xrightarrow{\alpha} B_{i}$.

Proof. To prove this result, we distinguish two cases depending on the fact whether $\alpha$ is an output or an input. In both cases, we perform the proof by induction on the prooftree witnessing the fact that $\left(A_{i} ; \mathrm{N}\right) \xrightarrow{\alpha}{ }_{i}\left(B_{i} ; \mathrm{N}^{\prime}\right)$. However, if $\alpha$ is an input, we need to show an intermediate result in order to be able to deal with the inductive case $\operatorname{PAR}_{i}$. Note that in the case where $\alpha$ is a label of the form out $(a, c), \nu d$.out $(a, d)$ or $\nu x$.out $(a, x)$, we do not have such a problem since the rule $\mathrm{PAR}_{i}$ is equivalent to the rule described below. This is due to the fact that $f v(\alpha)=\emptyset$.

$$
\text { Par-OuT }_{i} \frac{(A ; \mathrm{N}) \stackrel{\leftrightarrow}{\rightarrow}_{i}\left(A^{\prime}, \mathrm{N}^{\prime}\right)}{(A \mid B ; \mathrm{N}) \xrightarrow[\rightarrow]{\alpha}_{i}\left(A^{\prime} \mid B, \mathrm{~N}^{\prime}\right)}
$$

First case: $\alpha$ is of the form out $(a, c)$, $\nu d$.out $(a, d)$ or $\nu x$.out $(a, x)$. The two base cases, Out- $\mathrm{CH}_{i}$ and $\mathrm{Out}^{2}-\mathrm{T}_{i}$, are trivial. We only need to pay attention that the side condition of Out-T is satisfied. This is due to the fact that $\mathrm{N}(x)=\mathrm{n}$ whereas $\mathrm{N}(f v(P) \cup f v(M))=\mathrm{f}$. Hence, we have that $x \notin f v(P) \cup f v(M)$. Now, we have to deal with the inductive cases.

Case Open- $\mathrm{CH}_{i}$. In such a case, we have that the prooftree witnessing the fact that $\left(A_{i} ; \mathrm{N}\right) \xrightarrow{\alpha}{ }_{i}\left(B_{i} ; \mathrm{N}^{\prime}\right)$ ends with the following inference rule.

$$
\left.\frac{\left(A^{\prime} ; \mathrm{N}^{\prime \prime}\right) \xrightarrow{\text { out }(a, c)} i\left(B^{\prime} ; \mathrm{N}^{\prime \prime \prime}\right) \quad c \neq a, \mathrm{~N}^{\prime \prime}(d)=\mathrm{n}}{\left(\nu c . A^{\prime}, \mathrm{N}\right) \xrightarrow{\nu d . o u t(a, d)}} i\left(B^{\prime}\{d / c\}, \mathrm{N}^{\prime}\right)\right)
$$

By induction hypothesis, we know that $A^{\prime} \xrightarrow{\operatorname{out}(a, c)} B^{\prime}$ and we deduce that $A^{\prime}\{d / c\} \xrightarrow{\text { out }(a, d)} B^{\prime}\{d / c\}$ since $A^{\prime}$ and $B^{\prime}$ are nv-distinct and $d$ is fresh (it does not appear in $A^{\prime}$ nor in $B^{\prime}$ ). By application of the rule Open-Ch, we obtain $\nu d . A^{\prime}\left\{{ }^{d} / c\right\} \xrightarrow{\nu d . o u t(a, d)} B^{\prime}\left\{{ }^{d} / c\right\}$. Since $\nu d . A^{\prime}\left\{{ }^{d} / c\right\} \equiv \nu c . A^{\prime}$, we deduce that $\nu c . A^{\prime} \xrightarrow{\nu \text { d.out }(a, d)} B^{\prime}\{d / c\}$, i.e. exactly what we want.
Case $\mathrm{SCOPE}_{i}$. This case is completely straightforward.
Case $\mathrm{Par}^{\mathrm{CO}} \mathrm{Out}_{i}$. The proof tree ends with the following inference rule

$$
{\operatorname{PaR}-\mathrm{OuT}_{i}}^{\left(A^{\prime} ; \mathrm{N}\right) \stackrel{\rightarrow}{a}_{i}\left(B^{\prime}, \mathrm{N}^{\prime}\right)}\left(A^{\prime} \mid D ; \mathrm{N}\right) \xrightarrow{\alpha}_{i}\left(B^{\prime} \mid D, \mathrm{~N}^{\prime}\right)
$$

In such a case, we need to pay attention that the side condition of the rule Par is satisfied. Since $\mathbf{N}(b n(\alpha) \cup b v(\alpha))=\mathrm{n}$ and $\mathrm{N}(f n(D) \cup f v(D))=\mathrm{f}$, we deduce that $b n(\alpha) \cap f n(D)=b v(\alpha) \cap f v(D)=\emptyset$.
Case $\operatorname{Struct}_{i}$. We easily conclude for this case by using Proposition A.1.
Second case: $\alpha$ is of the form $\operatorname{in}(a, M)$. To deal with this case, we rely on the claim stated below.

Claim: Let $\left(A_{i} ; \mathrm{N}\right)$ and $\left(B_{i} ; \mathrm{N}^{\prime}\right)$ be two extended processes such that $A_{i}$ and $B_{i}$ are intermediate framed processes and $\left(A_{i}\right.$; $\mathrm{N}) \xrightarrow{i n(a, M)} i\left(B_{i} ; \mathrm{N}^{\prime}\right)$. Let $D_{i}$ be an intermediate framed process such that $\left(A_{i} \mid D_{i} ; \mathrm{N}\right)$ and $\left(B_{i} \mid D_{i} ; \mathrm{N}^{\prime}\right)$ are also intermediate processes. Then, for any term $M^{\prime}$ such that $M=M^{\prime} \psi\left(D_{i}\right)$, we have that $A_{i}\left|D_{i} \xrightarrow{i n\left(a, M^{\prime}\right)} B_{i}\right| D_{i}$.

Note that this result will allow us to conclude. Our claim allows us to deal with the case where $A_{i}$ and $B_{i}$ are intermediate framed processes. For this it is sufficient to apply the claim above with $D_{i}=0$ and $M^{\prime}=M$. Then it remains to notice that $A_{i} \mid 0 \equiv A_{i}$ and $B_{i} \mid 0 \equiv B_{i}$ in order to conclude. Now, let us consider the case where $\left(A_{i} ; \mathrm{N}\right),\left(B_{i} ; \mathrm{N}^{\prime}\right)$ are not intermediate framed processes. We show the result by induction on the prooftree witnessing $\left(A_{i} ; \mathrm{N}\right) \xrightarrow{i n(a, M)}{ }_{i}\left(B_{i} ; \mathrm{N}^{\prime}\right)$. In such a case, this prooftree ends either with an instance of $\mathrm{SCOPE}_{i}$ or an instance of $\mathrm{STRUCT}_{i}$. In both cases, we easily conclude by using the induction hypothesis and applying the corresponding rules, that is either Scope or Struct and using Proposition A.1.
It remains to establish the claim.

Proof of the claim. We show this result by induction on the prooftree witnessing $\left(A_{i} ; \mathrm{N}\right) \xrightarrow{i n(a, M)}{ }_{i}\left(B_{i} ; \mathrm{N}^{\prime}\right)$. First, we consider the base case, i.e. the rule $\mathrm{In}_{i}$. In such a case, we have that $A_{i}=\operatorname{in}(a, x) . P, B_{i}=P\left\{{ }^{M} / x\right\}$ and $\mathrm{N}^{\prime}=\mathrm{N}$. We have that

$$
\frac{\left.\frac{\operatorname{in}(a, x) . P \xrightarrow{i n\left(a, M^{\prime}\right)} P\left\{\left\{^{M^{\prime}} / x\right\}\right.}{\operatorname{in}(a, x) . P \mid D_{i} \xrightarrow{i n\left(a, M^{\prime}\right)} P\left\{\left\{^{M^{\prime}} / x\right\} \mid D_{i}\right.} \equiv P\left\{{ }^{M} / x\right\} \right\rvert\, D_{i}}{A_{i}\left|D_{i} \xrightarrow{i n\left(a, M^{\prime}\right)} B_{i}\right| D_{i}}
$$

Now, we have to deal with the inductive cases, that is $\mathrm{Struct}_{i}$ and $\mathrm{PAR}_{i}$ since the other rules do not allow us to derive framed processes. For $\mathrm{Struct}_{i}$ the result can be easily obtained by applying the induction hypothesis and Proposition A.1. Hence, we focus on $\mathrm{PAR}_{i}$. In such a case, we have that the proof tree witnessing $\left(A_{i} ; \mathrm{N}\right) \xrightarrow{i n(a, M)} i\left(B_{i} ; \mathrm{N}^{\prime}\right)$ ends with the following rule:

$$
\frac{\left(A_{i}^{\prime} ; \mathrm{N}\right) \xrightarrow{i n(a, M \psi(D))}_{i}\left(B_{i}^{\prime} ; \mathrm{N}^{\prime}\right)}{\left(A_{i}^{\prime} \mid D ; \mathrm{N}\right) \xrightarrow{i n(a, M)}_{i}\left(B_{i}^{\prime} \mid D ; \mathrm{N}^{\prime}\right)}
$$

Recall that $D_{i}$ is an intermediate framed process such that $\left(A_{i}^{\prime}|D| D_{i} ; \mathrm{N}\right)$ and $\left(B_{i}^{\prime}|D| D_{i} ; \mathrm{N}^{\prime}\right)$ are also intermediate framed processes. Let $M^{\prime}$ be a term such that $M=M^{\prime} \psi\left(D_{i}\right)$. By induction hypothesis and since $M \psi(D)=M^{\prime} \psi\left(D \mid D_{i}\right)$, we have that $A_{i}^{\prime}\left|\left(D_{i} \mid D\right) \xrightarrow{i n\left(a, M^{\prime}\right)} B_{i}^{\prime}\right|\left(D_{i} \mid D\right)$ and we easily conclude by using the fact that $\xrightarrow{\alpha}$ is closed by structural equivalence.

## A. 2 Completeness Results

Given a nv-distinct extended process $A$ containing an active substitution $\left\{{ }^{M} / x\right\}$. The process $A_{\backslash x}$ is $A$ but with the unique occurrence of $\left\{{ }^{M} / x\right\}$ replaced by 0 . This notation is extended as expected to sequences of variables. Now, we introduce a lemma which allows us to describe the process $C[A] \downarrow$ from $C \downarrow$ and $A \downarrow$.

Lemma A. 4 Let $C$ be an evaluation context which is nv-distinct. Let $\tilde{x}$ be the tuple of variables such that the hole is in the scope of an occurrence of " $\nu x$ " in $C$. Then there exists some sequences of names $\tilde{n}_{1}, \tilde{n}_{2}$ and an intermediate framed evaluation context $G$ such that

- $C \downarrow=\nu \tilde{n}_{1} \cdot \nu \tilde{n}_{2} \cdot G$, and
- for all extended process $A$ such that $C[A]$ is nv-distinct, we have that

$$
C[A] \downarrow=\nu \tilde{n}_{1} . \nu \tilde{m} . \nu \tilde{n}_{2} . G\left[F_{\widehat{x}}\right](\psi(G) \cup \psi(F))^{\star}
$$

where $A \downarrow=\nu \tilde{m} . F$ for some sequence of names $\tilde{m}$ and some intermediate framed process $F$.

Proof. We prove this result by induction on the structure of $C$. In the base case, i.e. $C==_{\text {, }}$, we can show that $\tilde{n}_{1}=\emptyset, \tilde{n}_{2}=\emptyset$ and $G={ }_{\text {_ }}$ satisfy the requirements. Indeed, let $A$ be an extended process such that $A \downarrow=\nu \tilde{m} . F$, we have $\nu \tilde{n}_{1} . \nu \tilde{m} . \nu \tilde{n}_{2} \cdot G\left[F F_{\tilde{x}}\right](\psi(G) \cup \psi(F))^{\star}=\nu \tilde{m} \cdot F \psi(F)^{\star}=\nu \tilde{m} . F=A \downarrow=C[A] \downarrow$.

The inductive cases are $C=C^{\prime}|B, C=B| C^{\prime}, C=\nu n . C^{\prime}$ and $C=\nu x . C^{\prime}$. Let $\tilde{x}^{\prime}$ be the tuple of variables $x^{\prime}$ such that the hole of $C^{\prime}$ is in the scope of an occurrence of $\nu x^{\prime}$ in $C^{\prime}$. By induction hypothesis, we know that there exists some sequences of names $\tilde{n}_{1}^{\prime}$ and $\tilde{n}_{2}^{\prime}$ and an intermediate framed evaluation context $G^{\prime}$ such that

- $C^{\prime} \downarrow=\nu \tilde{n}_{1}^{\prime} \cdot \nu \tilde{n}_{2}^{\prime} \cdot G^{\prime}$, and
- for all extended process $A$ such that $C^{\prime}[A]$ is nv-distinct, we have that

$$
C^{\prime}[A] \downarrow=\nu \tilde{n}_{1}^{\prime} . \nu \tilde{m} . \nu \tilde{n}_{2}^{\prime} \cdot G^{\prime}\left[F \backslash \tilde{x}^{\prime}\right]\left(\psi\left(G^{\prime}\right) \cup \psi(F)\right)^{\star} \text { where } A \downarrow=\nu \tilde{m} . F .
$$

Inductive case $1: C=C^{\prime} \mid B$. Let $B \downarrow=\nu \tilde{b} . B^{\prime}$. In such a case, we have that

$$
\begin{aligned}
C[A] \downarrow & =\left(C^{\prime}[A] \mid B\right) \downarrow \\
& =\nu \tilde{n}_{1}^{\prime} \cdot \nu \tilde{m} . \nu \tilde{n}_{2}^{\prime} \cdot \nu \tilde{b} .\left(G^{\prime}\left[F_{\tilde{x}^{\prime}}\right]\left(\psi\left(G^{\prime}\right) \cup \psi(F)\right)^{\star} \mid B^{\prime}\right)\left(\psi\left(C^{\prime}[A]\right) \cup \psi\left(B^{\prime}\right)\right)^{\star}
\end{aligned}
$$

Let $\tilde{n}_{1}=\tilde{n}_{1}^{\prime}, \tilde{n}_{2}=\tilde{n}_{2}^{\prime}, \tilde{b}$ and $G=G^{\prime} \mid B^{\prime}$. As $\tilde{x}=\tilde{x}^{\prime}$ and $\psi\left(G^{\prime}\right) \cup \psi(F)=\psi\left(C^{\prime}[A]\right)$ we obtain the expected result.

Inductive case 2: $C=B \mid C^{\prime}$. This case is similar to the previous one.
Inductive case 3: $C=\nu n . C^{\prime}$. In such a case, we have that

$$
\begin{aligned}
C[A] \downarrow & =\nu n \cdot\left(C^{\prime}[A] \downarrow\right) \\
& =\nu n . \nu \tilde{n}_{1}^{\prime} \cdot \nu \tilde{m} \cdot \nu \tilde{n}_{2}^{\prime} \cdot G^{\prime}\left[F_{\tilde{x}^{\prime}}\right]\left(\psi\left(G^{\prime}\right) \cup \psi(F)\right)^{\star}
\end{aligned}
$$

Let $\tilde{n}_{1}=n, \tilde{n}_{1}^{\prime}, \tilde{n}_{2}=\tilde{n}_{2}^{\prime}$ and $G^{\prime}=G$. We obtain the expected result.
Inductive case 4: $C=\nu x . C^{\prime}$. In such a case, we have that

$$
\begin{aligned}
C[A] \downarrow & =\left(C^{\prime}[A] \downarrow\right)_{\backslash x} \\
& =\left(\nu \tilde{n}_{1}^{\prime} \cdot \nu \tilde{m} \cdot \nu \tilde{n}_{2}^{\prime} \cdot G^{\prime}\left[F_{\backslash \tilde{x}^{\prime}}\right]\left(\psi\left(G^{\prime}\right) \cup \psi(F)\right)^{\star}\right)_{\backslash x}
\end{aligned}
$$

Let $\tilde{n}_{1}=\tilde{n}_{1}^{\prime}, \tilde{n}_{2}=\tilde{n}_{2}^{\prime}$ and $G^{\prime}=G$. We obtain the expected result since we have that $\tilde{x}=\tilde{x}^{\prime}, x$.

The following lemma relies on the notion of linear proof defined below. A proof in linear form of $A \equiv B$ is a sequence $A=A_{1}, \ldots, A_{n}=B$ such that for every $1 \leq j \leq n$, there exist an evaluation context $C_{j}$, two extended processes $A_{j}^{\prime}$ and $A_{j+1}^{\prime}$ such that:

- $A_{j}=C_{j}\left[A_{j}^{\prime}\right], A_{j+1}=C_{j}\left[A_{j+1}^{\prime}\right]$, and
- either $A_{j}^{\prime} \equiv A_{j+1}^{\prime}\left(\right.$ or $\left.A_{j+1}^{\prime} \equiv A_{j}^{\prime}\right)$ is an instance of PAR-0, PAR-A, PAR-C, New-0, New-C, New-Par, Alias, Subst, or Rewrite,
- or $A_{j}^{\prime}={ }_{\alpha} A_{j+1}^{\prime}$.

Similarly, a proof in linear form of $A \rightarrow^{*} B$ is a sequence $A=A_{1}, \ldots, A_{n}=B$ such that for every $1 \leq j \leq n$, there exist an evaluation context $C_{j}$, two extended processes $A_{j}^{\prime}$ and $A_{j+1}^{\prime}$ such that:

- $A_{j}=C_{j}\left[A_{j}^{\prime}\right], A_{j+1}=C_{j}\left[A_{j+1}^{\prime}\right]$, and
- either $A_{j}^{\prime} \equiv A_{j+1}^{\prime}\left(\right.$ or $\left.A_{j+1}^{\prime} \equiv A_{j}^{\prime}\right)$ is an instance of PAR-0, PAR-A, PAR-C, New-0, New-C, New-Par, Alias, Subst, or Rewrite,
- or $A_{j}^{\prime}={ }_{\alpha} A_{j+1}^{\prime}$,
- or $A_{j}^{\prime} \rightarrow A_{j+1}^{\prime}$ is an instance of Comm, Then or Else.

Moreover, there must exist at least one $j$ such that $A_{j}^{\prime} \rightarrow A_{j+1}^{\prime}$ is an instance of Comm, Then or Else.

Lemma A. 5 Let $A$ and $B$ be two nv-distinct extended processes such that $A \bowtie$ $B$ with $\bowtie \in\left\{\equiv, \rightarrow^{*}\right\}$ and N be a naming environment compatible with $A$ and $B$. Then there exists a proof in linear form such that every process in the proof is $n v$-distinct and compatible with N .

Proposition A. 6 (completeness of $\equiv_{i}$ ) Let $A$ and $B$ be two nv-distinct extended processes such that $A \equiv B$ and N be a naming environment compatible with $A \downarrow$ and $B \downarrow$. Then there exists an intermediate process $\left(D_{i} ; \mathrm{N}\right)$ such that $(A \downarrow ; \mathrm{N}) \equiv_{i}\left(D_{i} ; \mathrm{N}\right) \cong(B \downarrow ; \mathrm{N})$.

Proof. Let $A$ and $B$ be two nv-distinct extended processes such that $A \equiv$ $B$. We consider the proof of structural equivalence in linear form. Thanks to Lemma A.5, we can assume that extended processes involved in this derivation are nv-distinct and compatible with $N$. We show the result by induction on the length $\ell$ of the derivation. We first show the result when $\ell=1$ by considering each rule of structural equivalence in turn. Then, we show the inductive case, i.e. $\ell>1$. We denote by $C$ the evaluation context under which the structural equivalence rule is applied. We denote by $\tilde{n}_{1}, \tilde{n}_{2}$, (resp. $\tilde{x}$ ) and $G$ the sequences of names (resp. variables) and the intermediate framed evaluation context which satisfy the condition stated in Lemma A.4.
Case Par-0: $C[D] \equiv C[D \mid 0]$.
Let $D_{i}=B \downarrow$. Clearly, we have that $\left(D_{i} ; \mathrm{N}\right) \approx(B \downarrow ; \mathrm{N})$. Now, let $\tilde{m}$ be the sequence of names and $F$ be the framed process such that $D \downarrow=\nu \tilde{m}$.F. We have that $(D \mid 0) \downarrow=\nu \tilde{m} .(F \mid 0)$ and thanks to Lemma A. 4 we have

- $(A \downarrow ; \mathrm{N})=(C[D] \downarrow ; \mathrm{N})=\left(\nu \tilde{n}_{1} . \nu \tilde{m} . \nu \tilde{n}_{2} \cdot G\left[F_{\tilde{x}}\right](\psi(G) \cup \psi(F))^{\star} ; \mathrm{N}\right)$, and
- $(B \downarrow ; \mathrm{N})=(C[D \mid 0] \downarrow ; \mathrm{N})=\left(\nu \tilde{n}_{1} . \nu \tilde{m} . \nu \tilde{n}_{2} . G\left[(F \mid 0)_{\backslash \tilde{x}}\right](\psi(G) \cup \psi(F \mid 0))^{\star} ; \mathrm{N}\right)$.

Hence, we have that $(A \downarrow ; \mathbf{N}) \equiv_{i}(B \downarrow ; \mathbf{N})$.
A similar reasoning allows us to conclude for Par-A, Par-C. For the rule New-C, if the commutation involves two names, we conclude as in the previous case since this rule has a counterpart in the intermediate semantics. Otherwise, we have that $A \downarrow=B \downarrow$ and we easily conclude.

The rule New-0, New-Par, Subst, Alias and Rewrite are also straightforward. Note also that if $A \equiv B$ is a renaming step, then $D_{i}=A \downarrow$ satisfies the requirement. This concludes the base cases.

Now, it remains to show the inductive case. Let $A$ and $A^{\prime}$ be two extended processes such that $A \equiv A^{\prime}$ by a derivation of length $\ell>1$. Then there exists $B$ such that $A \equiv B$ by a derivation of length 1 and $B \equiv A^{\prime}$ by a derivation of length $\ell^{\prime}<\ell$. Firstly, we know that there exists an intermediate extended process $\left(D_{i} ; \mathrm{N}\right)$ such that $(A \downarrow ; \mathrm{N}) \equiv_{i}\left(D_{i} ; \mathrm{N}\right)$ and $\left(D_{i} ; \mathrm{N}\right) \cong(B \downarrow ; \mathrm{N})$. By using our induction hypothesis, we also know that there exists an intermediate extended $\operatorname{process}\left(D_{i}^{\prime} ; \mathrm{N}\right)$ such that $(B \downarrow ; \mathrm{N}) \equiv_{i}\left(D_{i}^{\prime} ; \mathrm{N}\right)$ and $\left(D_{i}^{\prime} ; \mathrm{N}\right) \cong\left(A^{\prime} \downarrow ; \mathrm{N}\right)$. Hence by using Lemma 4.5 , we deduce that there exists an intermediate extended process $\left(D_{i}^{\prime \prime} ; \mathrm{N}\right)$ such that $\left(D_{i} ; \mathrm{N}\right) \equiv_{i}\left(D_{i}^{\prime \prime} ; \mathrm{N}\right)$ and $\left(D_{i}^{\prime \prime} ; \mathrm{N}\right) \approx\left(D_{i}^{\prime} ; \mathrm{N}\right)$. Hence, the process $\left(D_{i}^{\prime \prime} ; \mathrm{N}\right)$ satisfies the requirements.

Proposition A. 7 (completeness of $\rightarrow_{i}$ ) Let $A$ and $B$ be two nv-distinct extended processes such that $A \rightarrow^{*} B$ (resp. $A \rightarrow B$ ) and N be a naming environment compatible with $A \downarrow$ and $B \downarrow$. Then there exists an extended process $\left(D_{i} ; \mathrm{N}\right)$ such that:

- $(A \downarrow ; \mathrm{N}) \rightarrow_{i}^{*}\left(D_{i} ; \mathrm{N}\right)\left(\operatorname{resp} .(A \downarrow ; \mathrm{N}) \rightarrow_{i}\left(D_{i} ; \mathrm{N}\right)\right)$ and,
- $\left(D_{i} ; \mathrm{N}\right) \cong(B \downarrow ; \mathrm{N})$.

Proof. Let $A$ and $B$ be two nv-distinct extended processes such that $A \rightarrow^{*} B$. The case where $B=A$ (reflexivity) is trivial. Otherwise we consider the proof of $A \rightarrow^{*} B$ in linear form. Each step of this proof will be either a single reduction step or a sequence of steps of structural equivalence. Thanks to Lemma A.5, we can assume that extended processes involved in this derivation are nv-distinct and compatible with N . We show the result by induction on the length $\ell$ of the derivation. We first show the result when $\ell=1$. In the case of structural equivalence, Proposition A. 6 allows us to conclude. Hence, we only consider the three rules of internal reduction in turn. Then, we show the inductive case, i.e. $\ell>1$. We denote by $C$ the evaluation context under which the rule is applied. We denote by $\tilde{n}_{1}, \tilde{n}_{2}$, (resp. $\tilde{x}$ ) and $G$ the sequences of names (resp. variables) and the intermediate framed evaluation context which satisfy the condition stated in Lemma A.4.
Case Comm: out $(a, M) \cdot P|\operatorname{in}(a, x) \cdot Q \rightarrow P| Q\left\{{ }^{M} / x\right\}$. We have that $A=$ $C[\operatorname{out}(a, M) . P \mid \operatorname{in}(a, x) \cdot Q]$ and $B=C\left[P \mid Q\left\{{ }^{M} / x\right\}\right]$. Let $P \downarrow=\nu \tilde{n}_{p} . F_{p}$ and $Q \downarrow=\nu \tilde{n}_{q} \cdot F_{q}$. By using Lemma A.4, we obtain

- $(A \downarrow ; \mathrm{N})=\left(\nu \tilde{n}_{1} \cdot \nu \tilde{n}_{p} \cdot \nu \tilde{n}_{q} \cdot \nu \tilde{n}_{2} \cdot G\left[\operatorname{out}(a, M) \cdot F_{p} \mid \operatorname{in}(a, x) \cdot F_{q}\right] \psi(G)^{\star} ; \mathrm{N}\right)$,
- $(B \downarrow ; \mathrm{N})=\left(\nu \tilde{n}_{1} \cdot \nu \tilde{n}_{p} \cdot \nu \tilde{n}_{q} \cdot \nu \tilde{n}_{2} \cdot G\left[F_{p} \mid F_{q}\left\{{ }^{M} / x\right\}\right] \psi(G)^{\star} ; \mathrm{N}\right)$.

Note that $F_{p}$ and $F_{q}$ are intermediate plain processes (as $P$, resp. $Q$, are prefixed by an input, resp. output) and hence $\psi\left(F_{p}\right)$ and $\psi\left(F_{q}\left\{{ }^{M} / x\right\}\right)$ are empty. Let $D_{i}=B \downarrow$. It is easy to see that $D_{i}$ satisfies the requirements.

We deal with the rules Then and Else in a similar way.
Now, it remains to show the inductive case. Let $A$ and $A^{\prime}$ be two extended processes such that $A \rightarrow^{*} A^{\prime}$ by a derivation of length $\ell>1$. Then there exists $B$ such that $A \equiv B$ (or $A \rightarrow B$ ) and $B \rightarrow^{*} A^{\prime}$ by a derivation of length $\ell^{\prime}<\ell$. In both case we conclude thanks to Lemma 4.5 and the induction hypothesis on $B \rightarrow^{*} A^{\prime}$.

Lemma A. 8 Let $A$ and $B$ be two nv-distinct extended processes such that $A \xrightarrow{\alpha}$ $B$ and N be a naming environment compatible with $A$ and $\alpha$. Let $\mathrm{N}^{\prime}$ be a naming environment compatible with $B$ and such that:

- $\mathrm{N}^{\prime}=\mathrm{N}[x \mapsto \mathrm{f}]$ when $\alpha$ is of the form $\nu x \operatorname{cout}(a, x)$;
- $\mathrm{N}^{\prime}=\mathrm{N}[d \mapsto \mathrm{f}]$ when $\alpha$ if of the form $\nu d$ d.out $(a, d)$;
- $\mathrm{N}^{\prime}=\mathrm{N}$ otherwise.

Then there exist two nv-distinct extended processes $A^{\prime}$ and $B^{\prime}$ such that:

- $A \equiv A^{\prime} \xrightarrow{\alpha} B^{\prime} \equiv B$ (where $A^{\prime} \xrightarrow{\alpha} B^{\prime}$ does not rely on some structural equivalence steps); and
- N is compatible with $A^{\prime}$, and $\mathrm{N}^{\prime}$ is compatible with $B^{\prime}$.

Proposition A. 9 (completeness of ${ }^{\alpha} i$ ) Let $A$ and $B$ be two nv-distinct extended processes such that $A \xrightarrow{\alpha} B$ and N be a naming environment compatible with $A \downarrow$ and $\alpha$. Let $\mathrm{N}^{\prime}$ be a naming environment compatible with $B \downarrow$ such that:

- $\mathrm{N}^{\prime}=\mathrm{N}[x \mapsto \mathrm{f}]$ when $\alpha$ is of the form $\nu x \operatorname{cout}(a, x)$;
- $\mathrm{N}^{\prime}=\mathrm{N}[d \mapsto \mathrm{f}]$ when $\alpha$ if of the form $\nu$ d.out $(a, d)$;
- $\mathrm{N}^{\prime}=\mathrm{N}$ otherwise.

Then there exists an intermediate process $\left(D_{i} ; \mathrm{N}^{\prime}\right)$ such that

$$
(A \downarrow ; \mathrm{N}) \xrightarrow{\alpha}_{i}\left(D_{i} ; \mathrm{N}^{\prime}\right) \cong\left(B \downarrow ; \mathrm{N}^{\prime}\right) .
$$

Proof. Thanks to Lemma A.8, we can assume that $A$ and $B$ are two nv-distinct extended processes such that $A \xrightarrow{\alpha} B$ without involving any structural equivalence step. Otherwise, we will have that $A \equiv A^{\prime} \xrightarrow{\alpha} B^{\prime} \equiv B$ and we can easily conclude, thanks to Lemma 4.5, by applying the result on $A^{\prime} \xrightarrow{\alpha} B^{\prime}$ and by using Proposition A. 6 on $A \equiv A^{\prime}$ and $B \equiv B^{\prime}$. We consider the different kind of labels in turn: out $(a, c), \nu x \operatorname{cout}(a, x), \operatorname{in}(a, M)$ and $\nu c$.out $(a, c)$.

We denote by $C$ the evaluation context (constructed by successive applications of the rules $\mathrm{PAR}_{i}$ and $\mathrm{SCOPE}_{i}$ ) under which the rule is applied. We denote by $\tilde{n}_{1}, \tilde{n}_{2}$, (resp. $\tilde{x}$ ) and $G$ the sequences of names (resp. variables) and the intermediate framed evaluation context which satisfy the condition stated in Lemma A. 4 .
Case Out-CH: out $(a, c) \cdot P \xrightarrow{\text { out }(a, c)} P$.
We have that $A=C[\operatorname{out}(a, c) . P]$ and $B=C[P]$. Note that $a, c \notin b n(C[\operatorname{out}(a, c) . P])$.
Let $P \downarrow=\nu \tilde{n}_{p} . F_{p}$. By using Lemma A.4, we obtain

- $(A \downarrow ; \mathrm{N})=\left(\nu \tilde{n}_{1} \cdot \nu \tilde{n}_{p} \cdot \nu \tilde{n}_{2} \cdot G\left[\operatorname{out}(a, c) \cdot F_{p}\right] \psi(G)^{\star} ; \mathrm{N}\right)$,
- $\left(B \downarrow ; \mathrm{N}^{\prime}\right)=\left(\nu \tilde{n}_{1} \cdot \nu \tilde{n}_{p} \cdot \nu \tilde{n}_{2} \cdot G\left[F_{p}\right] \psi(G)^{\star} ; \mathrm{N}^{\prime}\right)$.

Let $D_{i}=B \downarrow$. Obviously, $\left(D_{i} ; \mathrm{N}^{\prime}\right) \approx\left(B \downarrow ; \mathrm{N}^{\prime}\right)$. Moreover, we see that (out $\left.(a, c) \cdot F_{p}\right) \psi(G)^{\star} \xrightarrow{\text { out }(a, c)}{ }_{i} F_{p} \psi(G)^{\star}$. By successive applications of rules $\mathrm{PAR}_{i}$ and $\operatorname{SCOPE}_{i}$ we obtain that $(A \downarrow ; \mathrm{N}) \xrightarrow{\text { out }(a, c)} i\left(D_{i} ; \mathrm{N}^{\prime}\right)$.

Case Out-T: out $(a, M) . P \xrightarrow{\nu x . o u t(a, x)} P \mid\left\{{ }^{M} / x\right\} \quad x \notin f v(P) \cup f v(M)$. We have that $A=C[\operatorname{out}(a, M) . P]$ and $B=C\left[P \mid\left\{{ }^{M} / x\right\}\right]$. Let $P \downarrow=\nu \tilde{n}_{p} . F_{p}$. By using Lemma A.4, we obtain

- $(A \downarrow ; \mathrm{N})=\left(\nu \tilde{n}_{1} \cdot \nu \tilde{n}_{p} \cdot \nu \tilde{n}_{2} \cdot G\left[\operatorname{out}(a, M) \cdot F_{p}\right] \psi(G)^{\star} ; \mathrm{N}\right)$
- $\left(B \downarrow ; \mathrm{N}^{\prime}\right)=\left(\nu \tilde{n}_{1} \cdot \nu \tilde{n}_{p} \cdot \nu \tilde{n}_{2} \cdot G\left[F_{p} \mid\left\{{ }^{M} / x\right\}\right] \psi(G)^{\star} ; \mathrm{N}^{\prime}\right)$.

Note that applying the substitution $\psi(G)$ is sufficient as $\psi\left(F_{p}\right)$ is empty and $x$ is a fresh variable. Let $D_{i}=B \downarrow$. Obviously, we have that $\left(D_{i} ; \mathrm{N}^{\prime}\right) \cong\left(B \downarrow ; \mathrm{N}^{\prime}\right)$. Similarly to the previous case we show that $(A \downarrow ; \mathrm{N}) \xrightarrow{\nu x . o u t(a, x)} i\left(D_{i} ; \mathrm{N}^{\prime}\right)$.

Case In: in $(a, x) . P \xrightarrow{i n(a, M)} P\left\{{ }^{M} / x\right\}$.
We have that $A=C[\operatorname{in}(a, x) . P]$ and $B=C\left[P\left\{{ }^{M} / x\right\}\right]$. Let $P \downarrow=\nu \tilde{n}_{p} . F_{p}$. By using Lemma A.4, we obtain

- $(A \downarrow ; \mathrm{N})=\left(\nu \tilde{n}_{1} \cdot \nu \tilde{n}_{p} \cdot \nu \tilde{n}_{2} \cdot G\left[\operatorname{in}(a, x) . F_{p}\right] \psi(G)^{\star} ; \mathrm{N}\right)$
- $\left(B \downarrow ; \mathrm{N}^{\prime}\right)=\left(\nu \tilde{n}_{1} \cdot \nu \tilde{n}_{p} \cdot \nu \tilde{n}_{2} \cdot G\left[F_{p}\left\{{ }^{M} / x\right\}\right] \psi(G)^{\star} ; \mathrm{N}^{\prime}\right)$.

Let $D_{i}=B \downarrow$. Obviously, we have that $\left(D_{i} ; \mathrm{N}^{\prime}\right) \cong\left(B \downarrow ; \mathrm{N}^{\prime}\right)$. Moreover, we see that (we omit the naming environment for the moment)

$$
\left(\operatorname{in}(a, x) \cdot F_{p}\right) \psi(G)^{\star} \xrightarrow{i n\left(a, M \psi(G)^{\star}\right)} i\left(F_{p}\left\{{ }^{M} / x\right\}\right) \psi(G)^{\star} .
$$

By application of the rule $\mathrm{PAR}_{i}$ we obtain

$$
\begin{gathered}
\left(\operatorname{in}(a, x) \cdot F_{p}\right) \psi(G)^{\star}\left|G \psi(G)^{\star} \xrightarrow{i n(a, M)}_{i}\left(F_{p}\left\{{ }^{M} / x\right\}\right) \psi(G)^{\star}\right| G \psi(G)^{\star} \text {,i.e. } \\
G\left[\operatorname{in}(a, x) \cdot F_{p}\right] \psi(G)^{\star} \xrightarrow{i n(a, M)}_{i} G\left[F_{p}\left\{{ }^{M} / x\right\}\right] \psi(G)^{\star} .
\end{gathered}
$$

Note that $G \psi(G)^{\star}$ is an intermediate framed process and $\psi\left(G \psi(G)^{\star}\right)=\psi(G)^{\star}$. By successive applications of $\operatorname{SCOPE}_{i}$, we obtain that $(A \downarrow ; \mathrm{N}) \xrightarrow{i n(a, M)}(B \downarrow ; \mathrm{N})$. Note that since N is compatible with $A \downarrow$ and $\alpha=i n(a, M)$, we have that $\tilde{n}_{1}, \tilde{n}_{2}$ and $\tilde{n}_{p}$ are marked as bound, i.e. b, whereas names that occur in $M$ are marked as f , and thus $\tilde{n}_{1}, \tilde{n}_{2}$ and $\tilde{n}$ do not occur in $\alpha$.

Case Open-Ch. Here, we assume that $A=\nu d . C[$ out $(a, d) . P]$ and $B=C[P]$. Otherwise this can be obtained using structural equivalence. These structural equivalence steps are handled as explained above. Let $P \downarrow=\nu \tilde{n}_{p} . F_{p}$. By using Lemma A.4, we obtain

- $(A \downarrow ; \mathrm{N})=\left(\nu d . \nu \tilde{n}_{1} \cdot \nu \tilde{n}_{p} \cdot \nu \tilde{n}_{2} \cdot G\left[\operatorname{out}(a, d) . F_{p}\right] \psi(G)^{\star} ; \mathrm{N}\right)$,
- $\left(B \downarrow ; \mathrm{N}^{\prime}\right)=\left(\nu \tilde{n}_{1} \cdot \nu \tilde{n}_{p} \cdot \nu \tilde{n}_{2} \cdot G\left[F_{p}\right] \psi(G)^{\star} ; \mathrm{N}^{\prime}\right)$.

Let $D_{i}=B \downarrow$. Obviously, we have that $\left(D_{i} ; \mathrm{N}^{\prime}\right) \cong\left(B \downarrow ; \mathrm{N}^{\prime}\right)$. As above we show that $(A \downarrow ; \mathrm{N}) \xrightarrow{\nu d . o u t(a, d)} i\left(D_{i} ; \mathrm{N}^{\prime}\right)$. This allows us to conclude.

## B Proofs of Part II - Symbolic Calculus

We first show a useful lemma which allows us to transfer solutions of symbolic processes when we apply evaluation contexts to these processes.

Lemma B. 1 Let $\left(A ; \mathcal{C} ; \mathrm{N}_{s}\right)$ be a symbolic process and $C=\nu \tilde{u} .(-\mid D)$ an intermediate evaluation context such that $\left(C[A] ; C[\mathcal{C}] ; \mathrm{N}_{s}[b n(C[0]) \mapsto \mathrm{b}]\right)$ is a symbolic process. We have that

$$
\begin{gathered}
\theta \in \operatorname{Sol}_{\mathrm{E}}\left(C[\mathcal{C}], \mathrm{N}_{s}[b n(C[0]) \mapsto \mathrm{b}]\right) \\
\text { iff } \\
(\theta \psi(C[0]))^{\star} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}, \mathrm{~N}_{s}\right) \text { and bn }(C[0]) \cap \operatorname{names}(\operatorname{img}(\theta))=\emptyset
\end{gathered}
$$

Proof. Let $\left.\mathrm{N}_{s}^{\prime}=\mathrm{N}_{s}[b n(C[0]) \mapsto \mathrm{b}]\right)$.
$(\Rightarrow) \quad$ We need to consider two cases.

## Case $C[-]=\nu \tilde{n} . .$.

We have that $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\nu \tilde{n} . \mathcal{C}, \mathrm{N}_{s}^{\prime}\right)$. Let $\operatorname{Ded}(\mathcal{C})=\left\{\phi_{i} \Vdash x_{i} \mid 1 \leq i \leq\right.$ $\ell\}$ with $\phi_{i}=\nu \tilde{u}_{i} \cdot \sigma_{i}$. We have that $(\theta \psi(\nu n .0))^{\star}=\theta^{\star}=\theta\left(\operatorname{as} \operatorname{vars}\left(x_{i} \theta\right) \cap\right.$ $c v(\mathcal{C})=\emptyset$ and $\operatorname{dom}(\theta)=c v(\mathcal{C}))$. It is easy to check that $\theta$ is an E-solution of $\mathcal{C}$. As $\mathrm{N}_{s}^{\prime}(\operatorname{names}(\operatorname{img}(\theta)))=\mathrm{f}$ and $\mathrm{N}_{s}^{\prime}(\operatorname{vars}(\operatorname{img}(\theta)))=\mathrm{f}$ we also have that $\mathrm{N}_{s}(\operatorname{names}(\operatorname{img}(\theta)))=\mathrm{f}$ and $\mathrm{N}_{s}(\operatorname{vars}(\operatorname{img}(\theta)))=\mathrm{f}$. Hence, $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}, \mathrm{N}_{s}\right)$ and $\tilde{n} \cap \operatorname{names}(\operatorname{img}(\theta))=\emptyset\left(\right.$ as $\left.\mathrm{N}_{s}^{\prime}(\tilde{n})=\mathrm{b}\right)$.
Case $C[-]={ }_{-} \mid D$.
We have that $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C} \mid D, \mathrm{~N}_{s}^{\prime}\right)$. Let $\operatorname{Ded}(\mathcal{C})=\left\{\phi_{i} \Vdash x_{i} \mid 1 \leq i \leq \ell\right\}$ with $\phi_{i}=\nu \tilde{u}_{i} . \sigma_{i}$ and let $\theta^{\prime}=\theta \psi(D)$. We have to show that $\theta^{\prime \star} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}, \mathrm{N}_{s}\right)$. For this, we need to show that:

- $\operatorname{vars}\left(x_{i} \theta^{\prime \star}\right) \cap \operatorname{cv}(\mathcal{C})=\emptyset$. Actually we have that $\operatorname{dom}\left(\theta^{\prime}\right)=\operatorname{dom}(\theta)=$ $c v(\mathcal{C})=c v(\mathcal{C} \mid D)=\left\{x_{1}, \ldots, x_{\ell}\right\}$. Hence the result.
- $\operatorname{vars}\left(x_{i} \theta^{\prime \star}\right) \cap\left(\operatorname{dom}\left(\phi_{\ell}\right) \backslash \operatorname{dom}\left(\phi_{i}\right)\right)=\emptyset$. By hypothesis we have that $\operatorname{vars}\left(x_{i} \theta\right) \cap\left(\operatorname{dom}\left(\phi_{\ell} \cup \psi(D)\right) \backslash \operatorname{dom}\left(\phi_{i} \cup \psi(D)\right)\right)=\emptyset$. We have that $\operatorname{dom}\left(\phi_{\ell} \cup \psi(D)\right) \backslash \operatorname{dom}\left(\phi_{i} \cup \psi(D)\right)=\operatorname{dom}\left(\phi_{\ell}\right) \backslash \operatorname{dom}\left(\phi_{i}\right)$ and $\operatorname{vars}\left(x_{i} \theta^{\prime \star}\right) \subseteq$ $\operatorname{vars}\left(x_{i} \theta\right) \cup \operatorname{vars}(\operatorname{img}(\psi(D)))$.
As $A \mid D$ is applied we have that $\operatorname{vars}(\operatorname{img}(\psi(D))) \cap \operatorname{dom}\left(\phi_{\ell}\right)=\emptyset$. Hence $\operatorname{vars}\left(x_{i} \theta^{\prime \star}\right) \cap\left(\operatorname{dom}\left(\phi_{\ell}\right) \backslash \operatorname{dom}\left(\phi_{i}\right)\right)=\emptyset$.
- $\operatorname{names}\left(x_{i} \theta^{\prime *}\right) \cap \tilde{u}_{i}=\emptyset$. By definition of an intermediate process we have that $b n(0 \mid D)=\emptyset$. Hence, $\tilde{u}_{i}$ is a sequence of variables and this condition trivially holds.
- $\operatorname{vars}\left(x_{i} \theta^{\prime *}\right) \cap \tilde{u}_{i}=\emptyset$. As the process $A \mid D$ is applied we have that $\operatorname{vars}(\operatorname{img}(\psi(D))) \cap \operatorname{dom}(A)=\emptyset$. As for all $x \in \tilde{u}_{i}$ we have that $x \in \operatorname{dom}(A)$ we conclude that $\operatorname{vars}\left(x_{i} \theta^{\prime *}\right) \cap \tilde{u}_{i}=\emptyset$.
- For any constraint $\operatorname{gd}(M) \in \mathcal{C}$ we need to show that $M\left(\theta^{\prime \star} \sigma_{\ell}\right)^{\star}$ is ground. By hypothesis we have that $M\left(\theta \sigma_{\ell}\right)^{\star}$ is ground. Hence, as $\operatorname{dom}(\psi(D)) \cap$ $\operatorname{dom}\left(\sigma_{\ell}\right)=\emptyset$ we have that $M(\theta \psi(D))^{\star}=M \theta$ which allows us to conclude.
- For any constraint $M=N \in \mathcal{C}$ we need to show that $M\left(\theta^{\prime \star} \sigma_{\ell}\right)^{\star}=\mathrm{E}$ $N\left(\theta^{\prime \star} \sigma_{\ell}\right)^{\star}$. By hypothesis $M\left(\theta \sigma_{\ell}\right)^{\star}={ }_{\mathrm{E}} N\left(\theta \sigma_{\ell}\right)^{\star}$. As E is closed under substitution of terms for variables we conclude.
- For any constraint $M \neq N \in \mathcal{C}$ we need to show that $M\left(\theta^{\prime \star} \sigma_{\ell}\right)^{\star} \neq \mathrm{E}$ $N\left(\theta^{\prime \star} \sigma_{\ell}\right)^{\star}$. By hypothesis $M\left(\theta \sigma_{\ell}\right)^{\star} \neq \mathrm{E} N\left(\theta \sigma_{\ell}\right)^{\star}$. Moreover, we have that $\operatorname{gd}(M) \in \mathcal{C}$ and $\operatorname{gd}(N) \in \mathcal{C}$. Hence, we have that $M \theta^{\prime *}=M \theta$ and $N \theta^{\prime *}=$ $N \theta$ which allows us to conclude.
- $\mathrm{N}_{s}\left(\operatorname{names}\left(\operatorname{img}\left(\theta^{\prime}\right)\right) \cup \operatorname{vars}\left(\operatorname{img}\left(\theta^{\prime}\right)\right)\right)=\mathrm{f}$. By hypothesis we have that $\mathrm{N}_{s}(n a m e s(\operatorname{img}(\theta)) \cup \operatorname{vars}(\operatorname{img}(\theta)))=\mathrm{f}$. Moreover, as $b n(D)=\emptyset$ we have that $\mathrm{N}_{s}^{\prime}(\operatorname{names}(\operatorname{img}(\psi(D))))=\mathrm{f}$ which implies that $\mathrm{N}_{s}(\operatorname{names}(\operatorname{img}(\psi(D))))=$ f . Hence we conclude that $\mathrm{N}_{s}\left(\right.$ names $\left.\left(\operatorname{img}\left(\theta^{\prime *}\right)\right)\right)=\mathrm{f}$. We similarly conclude that $\mathrm{N}_{s}\left(\operatorname{vars}\left(\operatorname{img}\left(\theta^{\prime *}\right)\right)\right)=\mathrm{f}$.

In order to conclude, it remains to show that $b n(D) \cap \operatorname{names}(\operatorname{img}(\theta))=\emptyset$. This trivially holds since $b n(D)=\emptyset$.
$(\Leftarrow) \quad$ We again consider two cases
Case $C[-]=\nu \tilde{n}$._.
By hypothesis, $(\theta \psi(C[0]))^{\star}=\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}, \mathrm{N}_{s}\right)$. We need to show that $\theta \in$ $\operatorname{Sol}_{\mathrm{E}}\left(\nu \tilde{n} \cdot \mathcal{C}, \mathrm{~N}_{s}^{\prime}\right)$. The only tricky case is to show that $\tilde{n} \cap \operatorname{names}(\operatorname{img}(\theta))=\emptyset$. However this is directly implied by the additional hypothesis, i.e. $b n(C[0]) \cap$ $\operatorname{names}(\operatorname{img}(\theta))=\emptyset$.
Case $C[]=-\mid D$.

By hypothesis we have that $(\theta \psi(D))^{\star} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}, \mathrm{N}_{s}\right)$. As $C[A]$ is an extended intermediate process, we have that $b n(C[0])=\emptyset$. Hence, $\mathrm{N}_{s}=\mathrm{N}_{s}^{\prime}$. Let $\operatorname{Ded}(\mathcal{C})=\left\{\phi_{i} \Vdash x_{i} \mid 1 \leq i \leq \ell\right\}$ with $\phi_{i}=\nu \tilde{u}_{i} . \sigma_{i}$. Then $\operatorname{Ded}(\mathcal{C} \mid D)=$ $\left\{\nu \tilde{u}_{i} . \sigma_{i} \cup \psi(D) \Vdash x_{i} \mid 1 \leq i \leq \ell\right\}$. We have to show that $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(C[\mathcal{C}], \mathrm{N}_{s}^{\prime}\right)$. For this, we need to show that:

- $\operatorname{vars}\left(x_{i} \theta\right) \cap c v(\mathcal{C} \mid D)=\emptyset$. By hypothesis $\operatorname{vars}\left(x_{i}(\theta \psi(D))^{\star}\right) \cap c v(\mathcal{C})=\emptyset$. As $\operatorname{dom}(\psi(D)) \cap c v(\mathcal{C})=\emptyset$ and $c v(\mathcal{C} \mid D)=c v(\mathcal{C})$ we conclude.
- $\operatorname{vars}\left(x_{i} \theta\right) \cap\left(\operatorname{dom}\left(\phi_{\ell} \cup \psi(D)\right) \backslash \operatorname{dom}\left(\phi_{i} \cup \psi(D)\right)\right)=\emptyset$. By hypothesis we have that $\operatorname{vars}\left(x_{i}(\theta \psi(D))^{\star}\right) \cap\left(\operatorname{dom}\left(\phi_{\ell}\right) \backslash \operatorname{dom}\left(\phi_{i}\right)\right)=\emptyset$. Moreover, $\operatorname{dom}\left(\phi_{\ell}\right) \backslash$ $\operatorname{dom}\left(\phi_{i}\right)=\operatorname{dom}\left(\phi_{\ell} \cup \psi(D)\right) \backslash \operatorname{dom}\left(\phi_{i} \cup \psi(D)\right)$. Hence it is sufficient to show that $\left(\operatorname{vars}\left(x_{i} \theta\right) \backslash \operatorname{vars}\left(x_{i}(\theta \psi(D))^{\star}\right)\right) \cap\left(\operatorname{dom}\left(\phi_{\ell}\right) \backslash \operatorname{dom}\left(\phi_{i}\right)\right)=\emptyset$. We have that $\left(\operatorname{vars}\left(x_{i} \theta\right) \backslash \operatorname{vars}\left(x_{i}(\theta \psi(D))^{\star}\right)\right) \subseteq \operatorname{dom}(\psi(D))$. As dom $(\psi(D)) \cap$ $\operatorname{dom}\left(\phi_{\ell}\right)=\emptyset$ and $\operatorname{dom}\left(\phi_{\ell}\right) \supseteq \operatorname{dom}\left(\phi_{\ell}\right) \backslash \operatorname{dom}\left(\phi_{i}\right)$ we conclude.
- names $\left(x_{i} \theta\right) \cap \tilde{u}_{i}=\emptyset$. By hypothesis we have that names $\left(x_{i}(\theta \psi(D))^{\star}\right) \cap$ $\tilde{u}_{i}=\emptyset$. As names $\left(x_{i} \theta\right) \subseteq$ names $\left(x_{i}(\theta \psi(D))^{\star}\right)$ we conclude.
- $\operatorname{vars}\left(x_{i} \theta\right) \cap \tilde{u}_{i}=\emptyset$. By hypothesis we have that $\operatorname{vars}\left(x_{i}(\theta \psi(D))^{\star}\right) \cap \tilde{u}_{i}=\emptyset$. We also have that $\operatorname{vars}\left(x_{i} \theta\right) \backslash \operatorname{vars}\left(x_{i}(\theta \psi(D))^{\star}\right) \subseteq \operatorname{vars}(\operatorname{img}(\psi(D)))$. We have that $\tilde{u}_{i} \subseteq \operatorname{dom}(A \mid D)$ and, as $(A \mid D)$ is applied, $\operatorname{vars}(\operatorname{img}(\psi(D))) \cap$ $\operatorname{dom}(A \mid D)=\emptyset$. Hence $\operatorname{vars}(\operatorname{img}(\psi(D))) \cap \tilde{u}_{i}=\emptyset$ and we conclude.
- For any constraint $\operatorname{gd}(M) \in C[\mathcal{C}]$ we need to show that $M\left(\theta\left(\sigma_{\ell} \cup \psi(D)\right)\right)^{\star}$ is ground. Note that $\operatorname{gd}(M) \in \mathcal{C}$. By hypothesis we have that $M\left((\theta \psi(D))^{\star} \sigma_{\ell}\right)^{\star}$ is ground. As $C[A]$ is applied we have that $\operatorname{dom}\left(\sigma_{\ell}\right) \cap \operatorname{vars}(\operatorname{img}(\psi(D)))=$ $\operatorname{dom}(\psi(D)) \cap \operatorname{vars}\left(\operatorname{img}\left(\sigma_{\ell}\right)\right)=\emptyset$. Hence, $M\left((\theta \psi(D))^{\star} \sigma_{\ell}\right)^{\star}=M\left(\theta\left(\sigma_{\ell} \cup\right.\right.$ $\psi(D)))^{\star}$ and we conclude. The cases for $M=N$ and $M \neq N$ are similar.

Finally, as $b n(C[0])=\emptyset$ we obtain that $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C} \mid D, \mathrm{~N}_{s}^{\prime}\right)$. This allows us to conclude the proof.

## B. 1 Soundness Results

Proposition B. 2 (soundness of $\equiv_{s}$ ) Let $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ be two well-formed symbolic processes such that $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \equiv_{s}\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$. Then $\mathcal{C}_{A}=\mathcal{C}_{B}$ and for all $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$, we have that $(A ; \mathrm{N}) \equiv_{i}(B ; \mathrm{N})$ where $(A ; \mathrm{N})$ (resp. $(B ; \mathrm{N})$ ) is the $\theta$-concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ (resp. $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ ).

Proof. We show this result by induction on the proof tree witnessing the fact that $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \equiv_{s}\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$. First we need to consider the following base cases:

Case PaR- $0_{s}:\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \equiv_{s}\left(A_{s} \mid 0 ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$.
Trivially, $\mathcal{C}_{A}=\mathcal{C}_{B}$. Let $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $(A ; \mathrm{N})(\operatorname{resp} .(B ; \mathrm{N}))$ be the $\theta$-concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ (resp. $\left(A_{s} \mid 0 ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ ). Let $\sigma$
be the substitution corresponding to the maximal frame in $\mathcal{C}_{A}$. We have that $(A ; \mathrm{N})=\left(A_{s}(\theta \sigma)^{\star} ; \mathrm{N}\right) \equiv_{i}\left(A_{s}(\theta \sigma)^{\star} \mid 0 ; \mathrm{N}\right)=\left(\left(A_{s} \mid 0\right)(\theta \sigma)^{\star} ; \mathrm{N}\right)=(B ; \mathrm{N})$.

We can deal with the rules $\mathrm{PaR}-\mathrm{A})_{s}, \mathrm{PaR} \mathrm{C}_{s}$, and $\mathrm{NEW}-\mathrm{C}_{s}$ in a similar way.
We now consider the inductive case, i.e. application of an evaluation context. The proof tree witnessing the fact that $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \equiv_{s}\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ ends with an application of the following inference rule.

$$
\frac{\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right) \equiv_{s}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)}{\left(C\left[A_{s}^{\prime}\right] ; C\left[\mathcal{C}_{A}^{\prime}\right] ; \mathrm{N}_{s}\right) \equiv_{s}\left(C\left[B_{s}^{\prime}\right] ; C\left[\mathcal{C}_{B}^{\prime}\right] ; \mathrm{N}_{s}\right)}
$$

We have that $\mathrm{N}_{s}=\mathrm{N}_{s}^{\prime}[b n(C[0]) \mapsto \mathrm{b}]$. As $\mathcal{C}_{A}^{\prime}=\mathcal{C}_{B}^{\prime}$ we directly have that $C\left[\mathcal{C}_{A}^{\prime}\right]=C\left[\mathcal{C}_{B}^{\prime}\right]$. Let $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(C\left[\mathcal{C}_{A}^{\prime}\right] ; \mathrm{N}_{s}\right)$ and $(A ; \mathrm{N})$ (resp. $(B ; \mathrm{N})$ ) be the $\theta$ concretization of $\left(C\left[A_{s}^{\prime}\right] ; C\left[\mathcal{C}_{A}^{\prime}\right] ; \mathrm{N}_{s}\right)$ (resp. $\left(C\left[B_{s}^{\prime}\right] ; C\left[\mathcal{C}_{B}^{\prime}\right] ; \mathrm{N}_{s}\right)$ ). Let $\sigma$ be the substitution corresponding to the maximal frame in $\mathcal{C}_{A}=C\left[\mathcal{C}_{A}^{\prime}\right]$. We have to show that $(A ; \mathrm{N}) \equiv_{i}(B ; \mathrm{N})$, i.e. $\left(C(\theta \sigma)^{\star}\left[A_{s}^{\prime}(\theta \sigma)^{\star}\right] ; \mathrm{N}\right) \equiv_{i}\left(C(\theta \sigma)^{\star}\left[B_{s}^{\prime}(\theta \sigma)^{\star}\right]\right.$; $\mathrm{N})$. Since $\equiv_{i}$ is closed under application of evaluation context, it is sufficient to show that $\left(A_{s}^{\prime}(\theta \sigma)^{\star} ; \mathrm{N}^{\prime}\right) \equiv_{i}\left(B_{s}^{\prime}(\theta \sigma)^{\star} ; \mathrm{N}^{\prime}\right)$ where $\mathrm{N}^{\prime}=\left.\mathrm{N}_{s}^{\prime}\right|_{\mathcal{N} \cup \mathcal{X}}$.

Let $\theta^{\prime}=(\theta \psi(C[0]))^{\star}$. By Lemma B. 1 we have that $\theta^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ and $\left(A^{\prime} ; \mathrm{N}^{\prime}\right) \equiv_{i}\left(B^{\prime} ; \mathrm{N}^{\prime}\right)$ where $\left(A^{\prime} ; \mathrm{N}^{\prime}\right)\left(\right.$ resp. $\left.\left(B^{\prime} ; \mathrm{N}^{\prime}\right)\right)$ is the $\theta^{\prime}$-concretization of $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)\left(\right.$ resp. $\left.\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)\right)$. We have that $A^{\prime}=A_{s}^{\prime}\left(\theta^{\prime} \sigma^{\prime}\right)^{\star}$ and $B^{\prime}=B_{s}^{\prime}\left(\theta^{\prime} \sigma^{\prime}\right)^{\star}$ where $\sigma^{\prime}$ is the maximal frame of $\mathcal{C}_{A}^{\prime}$. This allows us to conclude since $\left(\theta^{\prime} \sigma^{\prime}\right)^{\star}=\left((\theta \psi(C[0]))^{\star} \sigma^{\prime}\right)^{\star}=\left(\theta\left(\psi(C[0]) \sigma^{\prime}\right)\right)^{\star}=(\theta \sigma)^{\star}$.

Proposition B. 3 (soundness of $\rightarrow_{s}$ ) Let $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ be two well-formed symbolic processes such that $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \rightarrow_{s}\left(B_{s} ; \mathcal{C}_{B} ;\right.$ $\left.\mathrm{N}_{s}\right)$. Let $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}\right)$. We have that $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $(A ; \mathrm{N}) \rightarrow_{i}$ $(B ; \mathrm{N})$ where $(A ; \mathrm{N})(\operatorname{resp} .(B ; \mathrm{N}))$ is the $\theta$-concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ (resp. $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ ).

Proof. The proof is done by induction on the proof witnessing $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \rightarrow_{s}$ $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$. We first consider the three base cases.
Case $\mathrm{Comm}_{s}$. We have that $A_{s}=\operatorname{out}(u, M) \cdot P_{s}\left|\operatorname{in}(v, x) \cdot Q_{s}, B_{s}=P_{s}\right|$ $Q_{s}\left\{{ }^{M} / x\right\}$ and $\mathcal{C}_{B}=\mathcal{C}_{A} \cup\{u=v, \operatorname{gd}(u), \operatorname{gd}(v)\}$. Let $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} \cup\{u=v\right.$, $\left.\operatorname{gd}(u), \operatorname{gd}(v)\} ; \mathrm{N}_{s}\right)$. We also have that $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$. Let $\sigma_{A}$ (resp. $\sigma_{B}$ ) be the substitution corresponding to the maximal frame of $\mathcal{C}_{A}$ (resp. $\mathcal{C}_{B}$ ). Trivially, we have that $\sigma_{A}=\sigma_{B}$. Let $\rho=\left(\theta \sigma_{A}\right)^{\star}$.

$$
\begin{aligned}
& (A ; \mathrm{N})=\left(A_{s} \rho ; \mathrm{N}\right) \\
& =\left(\operatorname{out}(u \rho, M \rho) \cdot P_{s} \rho \mid \operatorname{in}(v \rho, x) \cdot Q_{s} \rho ; \mathrm{N}\right) \quad \text { as } x \notin \operatorname{dom}(\rho) \\
& =\quad\left(\operatorname{out}(u \rho, M \rho) \cdot P_{s} \rho \mid \operatorname{in}(u \rho, x) \cdot Q_{s} \rho ; \mathrm{N}\right) \quad \text { as } \theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}\right) \\
& \rightarrow_{i} \quad\left(P_{s} \rho \mid Q_{s} \rho\left\{{ }^{M \rho} / x\right\} ; \mathrm{N}\right) \\
& =\left(\left(P_{s} \mid Q_{s}\left\{{ }^{M} / x\right\}\right) \rho ; \mathrm{N}\right) \\
& =\left(B_{s} \rho ; \mathrm{N}\right) \\
& =(B ; \mathbf{N}) \quad \text { as } \sigma_{A}=\sigma_{B}
\end{aligned}
$$

Again, the rules $\mathrm{THEN}_{s}$ and $\mathrm{ELSE}_{s}$ are similar to the previous case.
We now consider the two inductive cases.
The case of the structural equivalence rule is straightforward.
Case Application of an evaluation context
The proof witnessing the fact that $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \rightarrow_{s}\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ ends with an application of the following inference rule.

$$
\frac{\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right) \rightarrow_{s}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)}{\left(C\left[A_{s}^{\prime}\right] ; C\left[\mathcal{C}_{A}^{\prime}\right] ; \mathrm{N}_{s}\right) \rightarrow_{s}\left(C\left[B_{s}^{\prime}\right] ; C\left[\mathcal{C}_{B}^{\prime}\right] ; \mathrm{N}_{s}\right)}
$$

We have that $\mathrm{N}_{s}=\mathrm{N}_{s}^{\prime}[b n(C[0]) \mapsto \mathrm{b}]$. Let $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ and $(A ; \mathrm{N})$ (resp. $(B ; \mathrm{N})$ ) be the $\theta$-concretization of $\left(C\left[A_{s}^{\prime}\right] ; C\left[\mathcal{C}_{A}^{\prime}\right] ; \mathrm{N}_{s}\right)$ (resp. ( $C\left[B_{s}^{\prime}\right]$; $\left.C\left[\mathcal{C}_{B}^{\prime}\right] ; \mathrm{N}_{s}\right)$ ). Let $\sigma_{A}^{\prime}\left(\right.$ resp. $\left.\sigma_{B}^{\prime}\right)$ be the substitution corresponding to the maximal frame in $\mathcal{C}_{A}^{\prime}$ and $\sigma_{A}$ (resp. $\sigma_{B}$ ) be the substitution corresponding to the maximal frame in $\mathcal{C}_{A}=C\left[\mathcal{C}_{A}^{\prime}\right]$ (resp. $\mathcal{C}_{B}=C\left[\mathcal{C}_{B}^{\prime}\right]$ ). Note that since $\rightarrow_{s}$ does never add deduction constraints we have that $\sigma_{A}^{\prime}=\sigma_{B}^{\prime}$ and hence $\sigma_{A}=\sigma_{B}$. We have to show that $(A ; \mathrm{N}) \rightarrow_{i}(B ; \mathrm{N})$, i.e. $\left(C\left(\theta \sigma_{A}\right)^{\star}\left[A_{s}^{\prime}\left(\theta \sigma_{A}\right)^{\star}\right] ; \mathrm{N}\right) \rightarrow_{i}$ $\left(C\left(\theta \sigma_{B}\right)^{\star}\left[B_{s}^{\prime}\left(\theta \sigma_{B}\right)^{\star}\right] ; \mathrm{N}\right)$. Since $\rightarrow_{i}$ is closed under application of evaluation context, it is sufficient to show that $\left(A_{s}^{\prime}\left(\theta \sigma_{A}\right)^{\star} ; \mathrm{N}^{\prime}\right) \rightarrow_{i}\left(B_{s}^{\prime}\left(\theta \sigma_{B}\right)^{\star} ; \mathrm{N}^{\prime}\right)$ where $\mathrm{N}^{\prime}=\left.\mathrm{N}_{s}^{\prime}\right|_{\mathcal{N} \cup \mathcal{X}}$.

Let $\theta^{\prime}=(\theta \psi(C[0]))^{\star}$. By Lemma B. 1 we have that $\theta^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ and hence by induction hypothesis, we deduce that $\theta^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ and $\left(A^{\prime} ; \mathrm{N}\right) \rightarrow_{i}\left(B^{\prime} ; \mathrm{N}\right)$ where $\left(A^{\prime} ; \mathrm{N}^{\prime}\right)\left(\right.$ resp. $\left.\left(B^{\prime} ; \mathrm{N}^{\prime}\right)\right)$ is the $\theta^{\prime}$-concretization of $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ (resp. $\left.\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)\right)$. Hence, by Lemma B. 1 we deduce that $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)=\operatorname{Sol}_{\mathrm{E}}\left(C\left[\mathcal{C}_{A}^{\prime}\right] ; \mathrm{N}_{s}\right)$. We have that $A^{\prime}=A_{s}^{\prime}\left(\theta^{\prime} \sigma_{A}^{\prime}\right)^{\star}$ and $B^{\prime}=B_{s}^{\prime}\left(\theta^{\prime} \sigma_{B}^{\prime}\right)^{\star}$. This allows us to conclude since $\left(\theta^{\prime} \sigma_{A}^{\prime}\right)^{\star}=\left(\theta \sigma_{A}\right)^{\star}$ and $\left(\theta^{\prime} \sigma_{B}^{\prime}\right)^{\star}=\left(\theta \sigma_{B}\right)^{\star}$.

Proposition 8.2 (soundness of $\left.{ }^{\alpha}{ }_{s}\right)$ Let $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime}\right)$ be two well-formed symbolic processes such that $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \xrightarrow{\alpha_{s}}{ }_{s}\left(B_{s} ; \mathcal{C}_{B} ;\right.$ $\left.\mathrm{N}_{s}^{\prime}\right)$. Let $\theta_{B} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}^{\prime}{ }_{s}\right)$ and $\theta_{A}=\left.\theta_{B}\right|_{c v\left(\mathcal{C}_{A}\right)}$. We have that $\theta_{A} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}\right.$; $\left.\mathrm{N}_{s}\right)$ and $(A ; \mathrm{N}) \xrightarrow{\alpha_{s} \theta_{B}}{ }_{i}\left(B ; \mathrm{N}^{\prime}\right)$, where $(A ; \mathrm{N})$ and $\left(B ; \mathrm{N}^{\prime}\right)$ are respectively the $\theta_{A}$-concretization and the $\theta_{B}$-concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime}\right)$.

Proof. The proof is done by induction on the proof tree witnessing the following reduction step $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \xrightarrow{\alpha_{s}}{ }_{s}\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime}\right)$. We first consider the three base cases.

Case $\mathrm{In}_{s}$. We have that $A_{s}=\operatorname{in}(u, x) . P_{s}, B_{s}=P_{s}\left\{{ }^{y} / x\right\}, \alpha_{s}=i n(u, y)$ for some $y \in \mathcal{Y}$ such that $\mathrm{N}_{s}(y)=\mathrm{n}$ and $\left.\mathcal{C}_{B}=\mathcal{C}_{A} \cup\{0 \Vdash y, \operatorname{gd}(u)\}\right)$. Moreover, we have that $\mathrm{N}_{s}^{\prime}=\mathrm{N}_{s}[y \mapsto \mathrm{c}]$. Note that we have that $\mathrm{N}=\mathrm{N}^{\prime}$. Let $\theta_{B} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B}\right.$; $\mathrm{N}_{s}^{\prime}$ ) and $\theta_{A}=\left.\theta_{B}\right|_{c v\left(\mathcal{C}_{A}\right)}$. As $\mathcal{C}_{A} \subset \mathcal{C}_{B}$ we have that $\theta_{A} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$. Let $\sigma_{A}$ (resp. $\sigma_{B}$ ) be the substitution corresponding to the maximal frame of $\mathcal{C}_{A}$ (resp. $\mathcal{C}_{B}$ ). Trivially, we have that $\operatorname{dom}\left(\sigma_{A}\right)=\operatorname{dom}\left(\sigma_{B}\right)=\emptyset$ since $\phi\left(P_{s}\right)=0$ and $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ is well-formed.

$$
\begin{aligned}
& (A ; \mathrm{N}) \quad=\quad\left(A_{s} \theta_{A} ; \mathrm{N}\right) \\
& =\quad\left(\operatorname{in}\left(u \theta_{A}, x\right) \cdot P_{s} \theta_{A} ; \mathrm{N}\right) \quad \text { as } x \notin \operatorname{dom}\left(\theta_{A}\right) \\
& \xrightarrow{i n(u, y) \theta_{B}} i \quad\left(P_{s} \theta_{A}\left\{y \theta_{B} / x\right\} ; \mathrm{N}^{\prime}\right) \\
& \text { as } u \theta_{B} \in \mathcal{N}_{c h}, \\
& \mathrm{~N}\left(f v\left(y \theta_{B}\right) \cup f n\left(y \theta_{B}\right)\right)=\mathrm{f} \\
& =\left(P_{s} \theta_{A}\left\{{ }^{y} / x\right\}\left\{{ }^{y \theta_{B}} / y\right\} ; \mathrm{N}^{\prime}\right) \\
& =\quad\left(B_{s} \theta_{B} ; \mathrm{N}^{\prime}\right) \quad \text { as } \theta_{B}=\theta_{A} \cup\left\{y \mapsto y \theta_{B}\right\} \\
& =\quad\left(B ; \mathrm{N}^{\prime}\right)
\end{aligned}
$$

Case Out- $\mathrm{CH}_{s}$. This case is similar to the previous one.
Case Out-T ${ }_{s}$. We have that $A_{s}=\operatorname{out}(u, M) . P_{s}, B_{s}=P_{s} \mid\left\{{ }^{M} / x\right\}, \alpha_{s}=$ $\nu x$.out $(u, x)$ where $x \in \mathcal{X}_{b}$ and $\mathrm{N}_{s}(x)=\mathrm{n}$. We have also that $\mathcal{C}_{B}=\nu x . \mathcal{C}_{A} \cup$ $\{\operatorname{gd}(u)\}$ and $\mathrm{N}_{s}^{\prime}=\mathrm{N}_{s}[x \mapsto \mathrm{f}]$. Let $\theta_{B} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime}\right)$ and $\theta_{A}=\left.\theta_{B}\right|_{c v\left(\mathcal{C}_{A}\right)}$, i.e. $\theta_{B}=\theta_{A}$. As $\nu x . \mathcal{C}_{A} \subset \mathcal{C}_{B}$ we have that $\theta_{A} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$. Let $\sigma_{A}$ (resp. $\sigma_{B}$ ) be the substitution corresponding to the maximal frame of $\mathcal{C}_{A}$ (resp. $\mathcal{C}_{B}$ ). Trivially, we have that $\operatorname{dom}\left(\sigma_{A}\right)=\operatorname{dom}\left(\sigma_{B}\right)=\emptyset$ since $\phi\left(P_{s}\right)=0$ and $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ is well-formed.

$$
\begin{array}{rlll}
(A ; \mathrm{N}) & = & \left(A_{s} \theta_{A} ; \mathrm{N}\right) & \\
& = & \left(\operatorname{out}\left(u \theta_{A}, M \theta_{A}\right) \cdot P_{s} \theta_{A} ; \mathrm{N}\right) & \\
\xrightarrow{\nu x . o u t(u, x) \theta_{B}}{ }_{i} & \left(P_{s} \theta_{A} \mid\left\{{ }^{M \theta_{A}} / x\right\} ; \mathrm{N}^{\prime}\right) & \text { as } x \notin \operatorname{dom}\left(\theta_{B}\right) \\
= & \left(P_{s} \theta_{B} \mid\left\{M \theta_{B} / x\right\} ; \mathrm{N}^{\prime}\right) & \text { as } \theta_{A}=\theta_{B} \\
= & \left(B_{s} \theta_{B} ; \mathrm{N}\right) & \\
= & (B ; \mathrm{N}) &
\end{array}
$$

Moreover, as $\theta_{B} \in \operatorname{Sol}_{\mathrm{E}}\left(\nu x . \mathcal{C}_{A}\right)$ we have that $x \notin \operatorname{img}\left(\theta_{B}\right)$ and hence, $x$ occurs only once in $B$.
We now consider the inductive cases.
Case Open-CH ${ }_{s}$.

$$
\frac{\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime \prime}\right) \xrightarrow{\text { out }(u, c)}{ }_{s}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime \prime \prime}\right) \quad u \neq c, \mathrm{~N}_{s}^{\prime \prime}(d)=\mathrm{n}, d \in \mathcal{N}_{c h}}{\left(\nu c . A_{s}^{\prime} ; \nu c . \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right) \xrightarrow{\nu d . o u t(u, d)} s\left(B_{s}^{\prime}\{d / c\} ; \nu d .\left(\mathcal{C}_{B}^{\prime}\{d / c\}\right) ; \mathrm{N}_{s}^{\prime}\right)}
$$

We have that $A_{s}=\nu c . A_{s}^{\prime}, B_{s}=B_{s}^{\prime}\left\{d^{d} / c\right\}, \alpha_{s}=\nu d . o u t(u, d), \mathcal{C}_{A}=\nu c . \mathcal{C}_{A}^{\prime}$ and $\mathcal{C}_{B}=\nu d \cdot \mathcal{C}_{B}^{\prime}\left\{{ }^{d} / c\right\}$. Moreover, we have that

- $\mathrm{N}_{s}=\mathrm{N}_{s}^{\prime \prime}[c \mapsto \mathrm{~b}]$, and
- $\mathrm{N}_{s}^{\prime}=\mathrm{N}_{s}^{\prime \prime \prime}[c \mapsto \mathrm{~b}, d \mapsto \mathrm{f}]$.

Let $\theta_{B} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime}\right)$. We also have that $\theta_{B} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime \prime \prime}\right)$ and $c, d \notin$ names $\left(\operatorname{img}\left(\theta_{B}\right)\right)$ and $u \theta_{B} \neq c$. Let $\theta_{A}=\left.\theta_{B}\right|_{c v\left(\mathcal{C}_{A}\right)}$, i.e. $\theta_{B}=\theta_{A}$. By induction hypothesis we deduce that $\left(A^{\prime} ; \mathrm{N}^{\prime \prime}\right) \xrightarrow{\text { out }(u, c) \theta_{B}}{ }_{i}\left(B^{\prime} ; \mathrm{N}^{\prime \prime \prime}\right)$ where $\left(A^{\prime} ; \mathrm{N}^{\prime \prime}\right)$ (resp. $\left(B^{\prime} ; \mathrm{N}^{\prime \prime \prime}\right)$ ) are the $\theta_{B}$-concretization of $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime \prime}\right)$ (resp. ( $B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime}$; $\left.\mathrm{N}_{s}^{\prime \prime \prime}\right)$ ) and $\theta_{B} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime \prime}\right)$. As $c \notin \operatorname{names}\left(\operatorname{img}\left(\theta_{B}\right)\right)$, we also have that
$c \notin \operatorname{names}\left(\operatorname{img}\left(\theta_{A}\right)\right)$ and hence $\theta_{A} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$. Since $\left(A^{\prime} ; \mathrm{N}^{\prime \prime}\right) \xrightarrow{\text { out }(u, c) \theta_{B}}{ }_{i}$ $\left(B^{\prime} ; \mathrm{N}^{\prime \prime \prime}\right)$, we deduce that $\left(\nu c . A^{\prime} ; \mathrm{N}\right) \xrightarrow{\nu d . o u t\left(u \theta_{B}, d\right)} i\left(B^{\prime}\left\{{ }^{d} / c\right\} ; \mathrm{N}^{\prime \prime \prime}\right)$. Note that $c \neq u \theta_{B}$ and $d \in \mathcal{N}_{c h}$ and $\mathrm{N}^{\prime \prime}(d)=\mathrm{n}$.
Case $\mathrm{SCOPE}_{s}$.

$$
\frac{\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime \prime}\right) \xrightarrow{\alpha}{ }_{s}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime \prime \prime}\right) \quad n \text { does not occur in } \alpha}{\left(\nu n \cdot A_{s}^{\prime} ; \nu n \cdot \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right) \xrightarrow{\alpha}\left(\nu n . B_{s}^{\prime} ; \nu n \cdot \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)}
$$

We have that $A_{s}=\nu n . A_{s}^{\prime}, B_{s}=\nu n . B_{s}^{\prime}, \mathcal{C}_{A}=\nu n \cdot \mathcal{C}_{A}^{\prime}$ and $\mathcal{C}_{B}=\nu n . \mathcal{C}_{B}^{\prime}$. Moreover, we have that $\mathrm{N}_{s}=\mathrm{N}_{s}^{\prime \prime}[n \mapsto \mathrm{~b}]$ and $\mathrm{N}_{s}^{\prime}=\mathrm{N}_{s}^{\prime \prime \prime}[n \mapsto \mathrm{~b}]$. Let $\theta_{B} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ;\right.$ $\left.\mathrm{N}_{s}^{\prime}\right)$. We have that $n \notin$ names $\left(\operatorname{img}\left(\theta_{B}\right)\right)$. Let $\theta_{B}^{\prime}=\theta_{B}$. By Lemma B. 1 we have that $\theta_{B}^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime \prime \prime}\right)$. Let $\theta_{A}^{\prime}=\left.\theta_{B}^{\prime}\right|_{c v\left(\mathcal{C}_{A}^{\prime}\right)}$. By induction hypothesis, we have that $\left(A^{\prime} ; \mathrm{N}^{\prime \prime}\right) \xrightarrow{\alpha \theta_{B}^{\prime}} i\left(B^{\prime} ; \mathrm{N}^{\prime \prime \prime}\right)$ where $\left(A^{\prime} ; \mathrm{N}^{\prime \prime}\right)$ and $\left(B^{\prime} ; \mathrm{N}^{\prime \prime \prime}\right)$ are respectively the $\theta_{A}^{\prime}$ and the $\theta_{B}^{\prime}$-concretization of $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime \prime}\right)$ and $\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime \prime \prime}\right)$. As $n \notin \operatorname{names}\left(\operatorname{img}\left(\theta_{B}\right)\right), n$ does not occur in $\alpha \theta_{B}^{\prime}$ and $\theta_{A}=\theta_{A}^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ by Lemma B.1. Since $\left(A^{\prime} ; \mathrm{N}^{\prime \prime}\right) \xrightarrow{\alpha \theta_{B}^{\prime}}{ }_{i}\left(B^{\prime} ; \mathrm{N}^{\prime \prime \prime}\right), \theta_{B}=\theta_{B}^{\prime}$ and $n$ does not occur in $\alpha \theta_{B}$, we deduce that $\left(\nu n . A^{\prime} ; \mathrm{N}\right) \xrightarrow{\alpha \theta_{B}} i\left(\nu n . B^{\prime} ; \mathrm{N}^{\prime}\right)$
Case $\mathrm{PAR}_{s}$.

$$
\frac{\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right) \xrightarrow[\rightarrow]{\alpha}_{s}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)}{\left(A_{s}^{\prime}\left|D_{s} ; \mathcal{C}_{A}^{\prime}\right| \psi\left(D_{s}\right) ; \mathrm{N}_{s}\right) \xrightarrow[\rightarrow]{\alpha}_{s}\left(B_{s}^{\prime}\left|D_{s} ; \mathcal{C}_{B}^{\prime}\right| \psi\left(D_{s}\right) ; \mathrm{N}_{s}^{\prime}\right)}
$$

We have that $A_{s}=A_{s}^{\prime}\left|D_{s}, B_{s}=B_{s}^{\prime}\right| D_{s}, \mathcal{C}_{A}=\mathcal{C}_{A}^{\prime} \mid \psi\left(D_{s}\right)$ and $\mathcal{C}_{B}=$ $\mathcal{C}_{B}^{\prime} \mid \psi\left(D_{s}\right)$. Let $\theta_{B} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime}\right)$. Then, by Lemma B. 1 we also have that $\theta_{B}^{\prime}=\left(\theta_{B} \psi\left(D_{s}\right)\right)^{\star} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$. Let $\theta_{A}^{\prime}=\left.\theta_{B}^{\prime}\right|_{c v\left(\mathcal{C}_{A}^{\prime}\right)}$. By induction hypothesis we have that $\theta_{A}^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$ and $\left(A^{\prime} ; \mathrm{N}\right) \xrightarrow{\alpha \theta_{B} \psi\left(D_{s}\right)}{ }_{i}\left(B^{\prime} ; \mathrm{N}^{\prime}\right)$ where $\left(A^{\prime} ; \mathrm{N}\right)$ and $\left(B^{\prime} ; \mathrm{N}^{\prime}\right)$ are respectively the $\theta_{A}^{\prime}$ and the $\theta_{B}^{\prime}$ concretization of $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$ and $\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$.

Let $\theta_{A}=\left.\theta_{B}\right|_{c v\left(\mathcal{C}_{A}\right)}$. We have $\theta_{A}^{\prime}=\left.\theta_{B} \psi\left(D_{s}\right)\right|_{c v\left(\mathcal{C}_{A}\right)}$ and $\theta_{A}^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime}\right.$; $\mathrm{N}_{s}$ ). Hence by Lemma B. 1 we have that $\left.\theta_{B}\right|_{c v\left(\mathcal{C}_{A}\right)} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime} \mid \psi\left(D_{s}\right) ; \mathrm{N}_{s}\right)$, i.e. $\theta_{A} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$. Let $\sigma_{A}$ (resp. $\sigma_{B}, \sigma_{A}^{\prime}$ and $\left.\sigma_{B}^{\prime}\right)$ be the substitution corresponding to the maximal frame of $\mathcal{C}_{A}$ (resp. $\mathcal{C}_{B}, \mathcal{C}_{A}^{\prime}$ and $\mathcal{C}_{B}^{\prime}$ ), We also have that $\sigma_{A}=\sigma_{A}^{\prime} \cup \psi\left(D_{s}\right)$ and $\sigma_{B}=\sigma_{B}^{\prime} \cup \psi\left(D_{s}\right)$. As $\mathrm{N}_{s}^{\prime}\left(\operatorname{dom}\left(\psi\left(D_{s}\right)\right)\right)=\mathrm{f}$ and $\mathrm{N}_{s}^{\prime}(f v(\alpha))=\mathrm{c}$, we have that $\alpha \theta_{B} \psi\left(D_{s}\right)=\alpha \theta_{B}$. Hence, we have that $(A ; \mathrm{N}) \xrightarrow{\alpha \theta_{B}}{ }_{i}\left(B ; \mathrm{N}^{\prime}\right)$ where $(A ; \mathrm{N})$ and $\left(B ; \mathrm{N}^{\prime}\right)$ are respectively the $\theta_{A}$ and the $\theta_{B}$ concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime}\right)$.
Case $\mathrm{Struct}_{s}$. This case is straightforward by relying on Proposition B.2.

## B. 2 Completeness Results

Proposition B. 4 (completeness of $\equiv_{s}$ ) Let $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ be a well-formed symbolic process and $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}, \mathrm{~N}_{s}\right)$. Let $(A ; \mathrm{N})$ be the $\theta$-concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $B$ be a process such that $(A ; \mathrm{N}) \equiv_{i}(B ; \mathrm{N})$. Then there exists a well-formed symbolic process $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{\mathrm{s}}\right)$ such that:

1. $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{\mathrm{s}}\right) \equiv_{s}\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{\mathrm{s}}\right)$,
2. $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}\right)$, and
3. $(B ; \mathrm{N})$ is the $\theta$-concretization of $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{\mathrm{s}}\right)$.

Proof. We show this result by induction on the proof tree witnessing the fact that $(A, \mathrm{~N}) \equiv_{i}(B, \mathrm{~N})$. First we need to consider the following base cases:
Case Par- $0_{i}:(D, N) \equiv_{i}(D \mid 0, \mathrm{~N})$. In such a case, we have that $A=D$ and $B=D \mid 0$. Moreover, since $(A ; \mathrm{N})$ is the $\theta$-concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ we have that $A=A_{s}\left(\theta \sigma_{A}\right)^{\star}$. Hence, we know that $A_{s}=D_{s}$ for some process $D_{s}$ such that $D_{s}\left(\theta \sigma_{A}\right)^{\star}=D$. Let $B_{s}=D_{s} \mid 0$ and $\mathcal{C}_{B}=\mathcal{C}_{A}$. The symbolic process ( $B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}$ ) is well-formed. Moreover, we have

1. $\left(A_{s} ; \mathcal{C}_{A} ; \mathbf{N}_{s}\right) \equiv_{s}\left(B_{s} ; \mathcal{C}_{B} ; \mathbf{N}_{s}\right)$,
2. $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}\right)$,
3. $B_{s}\left(\theta \sigma_{B}\right)^{\star}=\left(D_{s} \mid 0\right)\left(\theta \sigma_{A}\right)^{\star}=D \mid 0=B$, i.e., $(B ; \mathrm{N})$ is the $\theta$ concretization of $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$.

Symmetrically, we have to consider the case where $A=D \mid 0$ and $B=D$. We know that $A=A_{s}\left(\theta \sigma_{A}\right)^{\star}$ and we deduce that $A_{s}=D_{s} \mid 0$ for some process $D_{s}$ such that $D_{s}\left(\theta \sigma_{A}\right)^{\star}=D$. Let $B_{s}=D_{s}$ and $\mathcal{C}_{B}=\mathcal{C}_{A}$. We easily conclude.

We can deal with the rules Par-A, Par-C and New-C in a similar way.
Now, we show the inductive case, i.e. application of an evaluation context. In such a case, we have that the proof tree witnessing the fact that $(A ; \mathrm{N}) \equiv_{i}$ ( $B ; \mathrm{N}$ ) ends with an application of the following inference rule.

$$
\frac{\left(A^{\prime} ; \mathrm{N}^{\prime}\right) \equiv_{i}\left(B^{\prime} ; \mathrm{N}^{\prime}\right)}{\left(C\left[A^{\prime}\right] ; \mathrm{N}\right) \equiv_{i}\left(C\left[B^{\prime}\right] ; \mathrm{N}\right)}
$$

Moreover, since $(A ; \mathrm{N})$ is the $\theta$-concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ we have that $A_{s}\left(\theta \sigma_{A}\right)^{\star}=C\left[A^{\prime}\right]$. Hence, we deduce that $A_{s}=C_{s}\left[A_{s}^{\prime}\right]$ for some evaluation context $C_{s}$ and some process $A_{s}^{\prime}$ such that $C_{s}\left(\theta \sigma_{A}\right)^{\star}=C$ and $A_{s}^{\prime}\left(\theta \sigma_{A}\right)^{\star}=A^{\prime}$. Since $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ is well-formed, we have also that $\mathcal{C}_{A}=C_{s}\left[\mathcal{C}_{A}^{\prime}\right]$ for some constraint system $\mathcal{C}_{A}^{\prime}$. Let

$$
\mathrm{N}_{s}^{\prime}(u)= \begin{cases}\mathrm{N}^{\prime}(u) & \text { if } u \in \mathcal{N} \cup \mathcal{X} \\ \mathrm{~N}_{s}(u) & \text { if } u \in \mathcal{Y} .\end{cases}
$$

Let $\theta^{\prime}=\left(\theta \psi\left(C_{s}\right)\right)^{\star}$. By Lemma B. 1 we have that $\theta^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$. We can apply our induction hypothesis on $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ and $\left(A^{\prime} ; \mathrm{N}^{\prime}\right) \equiv_{i}\left(B^{\prime} ; \mathrm{N}^{\prime}\right)$.

We deduce that there exists a well-formed symbolic process $\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ such that $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right) \equiv_{s}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right), \theta^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ and $B_{s}^{\prime}\left(\theta^{\prime} \sigma_{B}^{\prime}\right)^{\star}=B^{\prime}$. Let $B_{s}=C_{s}\left[B_{s}^{\prime}\right]$ and $\mathcal{C}_{B}=C_{s}\left[\mathcal{C}_{B}^{\prime}\right]$. We have that

1. $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \equiv\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$,
2. $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}_{\mathrm{s}}\right)$ (by Lemma B.1),
3. $B_{s}\left(\theta \sigma_{B}\right)^{\star}=C_{s}\left(\theta \sigma_{B}\right)^{\star}\left[B_{s}^{\prime}\left(\theta \sigma_{B}\right)^{\star}\right]=C\left[B_{s}^{\prime}\left(\theta^{\prime} \sigma_{B}^{\prime}\right)^{\star}\right]=C\left[B^{\prime}\right]=B$, i.e., $(B ; \mathrm{N})$ is the $\theta$-concretization of $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$.

This concludes our proof.
Proposition B. 5 (completeness of $\left.\rightarrow_{s}\right)$ Let $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ be a well-formed symbolic process and $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$. Let $(A ; \mathrm{N})$ be the $\theta$-concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $\left(A^{\prime}, \mathrm{N}\right)$ be an intermediate process such that $(A ; \mathrm{N}) \rightarrow_{i}\left(A^{\prime} ; \mathrm{N}\right)$. Then there exists a well-formed symbolic process $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$ such that:

1. $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \rightarrow_{s}\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$,
2. $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$,
3. $\left(A^{\prime} ; \mathrm{N}\right)$ is the $\theta$-concretization of $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$.

Proof. We show this result by induction on the proof tree witnessing the fact that $(A ; \mathrm{N}) \rightarrow_{i}\left(A^{\prime} ; \mathrm{N}\right)$. First, we need to consider the three base cases, i.e. the rules Then, Else and Comm. We detail the case of the rule Else, the two other ones are very similar.
Case Else: (if $M=N$ then $P$ else $Q ; \mathrm{N}) \rightarrow_{i}(Q ; \mathrm{N})$ with $M, N$ ground terms such that $M \neq \mathrm{E} N$. In such a case, we have that

- $A=$ if $M=N$ then $P$ else $Q$ for some ground terms $M, N$ such that $M \neq \mathrm{E} N$ and some processes $P$ and $Q$, and
- $A^{\prime}=Q$.

Moreover, since $(A ; \mathrm{N})$ is the $\theta$-concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ we have that $A=A_{s}\left(\theta \sigma_{A}\right)^{\star}$. Hence, we deduce that

- $A_{s}=$ if $M_{s}=N_{s}$ then $P_{s}$ else $Q_{s}$ for some terms $M_{s}, N_{s}$, some processes $P_{s}$ and $Q_{s}$ such that
- $M_{s}\left(\theta \sigma_{A}\right)^{\star}=M, N_{s}\left(\theta \sigma_{A}\right)^{\star}=N, P_{s}\left(\theta \sigma_{A}\right)^{\star}=P$ and $Q_{s}\left(\theta \sigma_{A}\right)^{\star}=Q$.

Let $A_{s}^{\prime}=Q_{s}$ and $\mathcal{C}_{A}^{\prime}=\mathcal{C}_{A} \cup\left\{M_{s} \neq N_{s}, \operatorname{gd}\left(M_{s}\right), \operatorname{gd}\left(N_{s}\right)\right\}$. The symbolic process $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$ is well-formed. Moreover, we have

1. $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \rightarrow_{s}\left(Q_{s} ; \mathcal{C}_{A} \cup\left\{M_{s} \neq N_{s}, \operatorname{gd}\left(M_{s}\right), \operatorname{gd}\left(N_{s}\right)\right\} ; \mathrm{N}_{s}\right)$
2. $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$. Indeed, by hypothesis, we know that $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$. We know also that $M_{s}\left(\theta \sigma_{A}\right)^{\star}$ and $N_{s}\left(\theta \sigma_{A}\right)^{\star}$ are ground terms which are not equal modulo E .
3. $A_{s}^{\prime}\left(\theta \sigma_{A}\right)^{\star}=Q_{s}\left(\theta \sigma_{A}\right)^{\star}=Q=A^{\prime}$, i.e., $\left(A^{\prime} ; \mathrm{N}\right)$ is the $\theta$-concretization of $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}\right)$.

Now, we show the inductive cases. In case of the structural equivalence inductive rule, we easily conclude by induction and thanks to Proposition B.4.
Case Application of an evaluation context. In such a case, we have that the tree witnessing the fact that $(A ; \mathrm{N}) \rightarrow_{i}(B ; \mathrm{N})$ ends with an application of the following inference rule.

$$
\frac{\left(A^{\prime} ; \mathrm{N}^{\prime}\right) \rightarrow_{i}\left(B^{\prime} ; \mathrm{N}^{\prime}\right)}{\left(C\left[A^{\prime}\right] ; \mathrm{N}\right) \rightarrow_{i}\left(C\left[B^{\prime}\right] ; \mathrm{N}\right)}
$$

Moreover, since $(A ; \mathrm{N})$ is the $\theta$-concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ we have that $A_{s}\left(\theta \sigma_{A}\right)^{\star}=C\left[A^{\prime}\right]$. Hence, we deduce that $A_{s}=C_{s}\left[A_{s}^{\prime}\right]$ for some evaluation context $C_{s}$ and some process $A_{s}^{\prime}$ such that $C_{s}\left(\theta \sigma_{A}\right)^{\star}=C$ and $A_{s}^{\prime}\left(\theta \sigma_{A}\right)^{\star}=A^{\prime}$. Since $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ is well-formed, we have also that $\mathcal{C}_{A}=C_{s}\left[\mathcal{C}_{A}^{\prime}\right]$ for some constraint system $\mathcal{C}_{A}^{\prime}$. Let

$$
\mathrm{N}_{s}^{\prime}(u)= \begin{cases}\mathrm{N}^{\prime}(u) & \text { if } u \in \mathcal{N} \cup \mathcal{X} \\ \mathrm{~N}_{s}(u) & \text { if } u \in \mathcal{Y}\end{cases}
$$

Let $\theta^{\prime}=\left(\theta \phi\left(C_{s}\right)\right)^{\star}$. By Lemma B. 1 we have that $\theta^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$.
We can apply our induction hypothesis on $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ and $\left(A^{\prime} ; \mathrm{N}^{\prime}\right) \rightarrow_{i}$ $\left(B^{\prime} ; \mathrm{N}^{\prime}\right)$. We deduce that there exists a well-formed symbolic process $\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime}\right.$; $\left.\mathrm{N}_{s}^{\prime}\right)$ such that $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right) \rightarrow_{s}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right), \theta^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ and $\left(B^{\prime} ; \mathrm{N}^{\prime}\right)$ is the $\theta$-concretization of $\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}^{\prime}{ }_{s}\right)$. Let $B_{s}=C_{s}\left[B_{s}^{\prime}\right]$ and $\mathcal{C}_{B}=C_{s}\left[\mathcal{C}_{B}^{\prime}\right]$. We have that

1. $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \rightarrow_{s}\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$,
2. $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ (by Lemma B.1),
3. $B_{s}\left(\theta \sigma_{B}\right)^{\star}=C_{s}\left(\theta \sigma_{B}\right)^{\star}\left[B_{s}^{\prime}\left(\theta \sigma_{B}\right)^{\star}\right]=C\left[B_{s}^{\prime}\left(\theta^{\prime} \sigma_{B}^{\prime}\right)^{\star}\right]=C\left[B^{\prime}\right]=B$ i.e., $(B$; $\mathrm{N})$ is the $\theta$-concretization of $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$.
This concludes our proof.
Proposition 8.4 (completeness of $\left.{ }^{\alpha}{ }_{s}\right)$ Let $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ be a well-formed symbolic process and $\theta_{A} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$. Let $(A ; \mathrm{N})$ be the $\theta_{A}$-concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ and $\left(A^{\prime} ; \mathrm{N}^{\prime}\right)$ be an intermediate process such that $(A ; \mathrm{N}) \xrightarrow{\alpha}{ }_{i}$ $\left(A^{\prime} ; \mathrm{N}^{\prime}\right)$. Then there exists a well-formed symbolic process $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ and a substitution $\theta_{A}^{\prime}$ such that:
4. $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \xrightarrow{\alpha_{s}}{ }_{s}\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$,
5. $\theta_{A}^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ and $\left.\theta_{A}^{\prime}\right|_{c v\left(\mathcal{C}_{A}\right)}=\theta_{A}$,
6. $\left(A^{\prime} ; \mathrm{N}^{\prime}\right)$ is the $\theta_{A}^{\prime}$-concretization of $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$, and
7. $\alpha_{s} \theta_{A}^{\prime}=\alpha$.

Proof. We show this result by induction on the tree witnessing the fact that $(A ; \mathrm{N}) \xrightarrow{\alpha}{ }_{i}\left(A^{\prime} ; \mathrm{N}^{\prime}\right)$. First, we need to consider the following base cases:

Case $\mathrm{IN}_{i}:(\operatorname{in}(a, x) . P ; \mathrm{N}) \xrightarrow{i n(a, M)}{ }_{i}\left(P\left\{{ }^{M} / x\right\} ; \mathrm{N}\right)$. In such a case, we have that

- $A=\operatorname{in}(a, x) . P$ for some channel name $a$, some variable $x$ and some $P$,
- $A^{\prime}=P\left\{{ }^{M} / x\right\}$,
- $\alpha=\operatorname{in}(a, M)$ for some term $M$, and
- $\mathrm{N}(f n(M) \cup f v(M))=\mathrm{f}$.

Since $(A ; \mathrm{N})$ is the $\theta$-concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ we have that $A_{s}\left(\theta \sigma_{A}\right)^{\star}=A$.
Hence, we know that

- $A_{s}=\operatorname{in}(u, x) . P_{s}$ for some metavariable $u$ and some process $P_{s}$ such that
- $u\left(\theta \sigma_{A}\right)^{\star}=a$ and $P_{S}\left(\theta \sigma_{A}\right)^{\star}=P$.

We have that $u$ is either a channel name or a constraint variable of channel type since $u\left(\theta \sigma_{A}\right)^{\star}=a$ and $a$ is a channel name.

Let $y \in \mathcal{Y}$ having the same type than $M$ and such that $\mathrm{N}_{s}(y)=\mathrm{n}$. Let $A_{s}^{\prime}=P_{s}\{y / x\}, \mathcal{C}_{A}^{\prime}=\mathcal{C}_{A} \cup\{0 \Vdash y, \operatorname{gd}(u)\}, \alpha_{s}=\operatorname{in}(u, y), \theta^{\prime}=\theta \cup\{y \mapsto M\}$ and $\mathrm{N}_{s}^{\prime}=\mathrm{N}_{s}[y \mapsto \mathrm{c}]$. The symbolic process $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ is well-formed, and we have:

1. $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)=\left(\operatorname{in}(u, x) . P_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$

$$
\begin{aligned}
& \xrightarrow{\alpha_{s}} s\left(P_{s}\left\{{ }^{y} / x\right\} ; \mathcal{C}_{A} \cup\{0 \Vdash y, \operatorname{gd}(u)\} ; \mathrm{N}_{s}^{\prime}\right) \\
& =\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}^{\prime}{ }_{s}\right)
\end{aligned}
$$

2. We know that $\theta \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A} ; \mathrm{N}_{s}\right)$. It remains to check that $\theta^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$, i.e. $\theta^{\prime}$ satisfies the constraints $\Vdash y$ and $\operatorname{gd}(u)$. This is clearly true due to the fact that $\mathbf{N}_{s}(f n(M) \cup f v(M))=\mathrm{f}$ and $u\left(\theta \sigma_{A}\right)^{\star}=a$. Lastly, by definition of $\theta^{\prime}$, we have that $\left.\theta^{\prime}\right|_{c v\left(\mathcal{C}_{A}\right)}=\theta$.
3. We have $A_{s}^{\prime}\left(\theta^{\prime} \sigma_{A}^{\prime}\right)^{\star}=P_{s}\left\{{ }^{y} / x\right\}\left(\theta \sigma_{A}\right)^{\star}[y \mapsto M]=P\left\{{ }^{M} / x\right\}=A^{\prime}$ since $\operatorname{dom}\left(\sigma_{A}\right)=\operatorname{dom}\left(\sigma_{A}^{\prime}\right)=\emptyset$, i.e., $\left(A^{\prime} ; \mathrm{N}^{\prime}\right)$ is the $\theta^{\prime}$-concretization of $\left(A_{s}^{\prime} ;\right.$ $\left.\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$, and
4. $\alpha_{s} \theta^{\prime}=\operatorname{in}(u, y) \theta^{\prime}=\operatorname{in}\left(u \theta^{\prime}, y \theta^{\prime}\right)=\operatorname{in}(a, M)=\alpha$.

We can deal with the rules Out- $\mathrm{CH}_{i}$ and Out- $\mathrm{T}_{i}$ in a rather similar way.
We now consider the inductive cases.
Case Open- $\mathrm{CH}_{i}$ : In such a case, we have that the tree witnessing the fact that $(A ; \mathrm{N}) \xrightarrow{\alpha}{ }_{i}\left(A^{\prime} ; \mathrm{N}^{\prime}\right)$ ends with an application of the following inference rule

$$
\frac{\left(B ; \mathrm{N}^{\prime \prime}\right) \xrightarrow{\text { out }(a, c)} i\left(B^{\prime} ; \mathrm{N}^{\prime \prime \prime}\right) \quad c \neq a, \mathrm{~N}^{\prime \prime}(d)=\mathrm{n} \text { and } d \in \mathcal{N}_{c h}}{(\nu c . B ; \mathrm{N}) \xrightarrow{\nu d . o u t(a, d)} i\left(B^{\prime}\left\{{ }^{d} / c\right\} ; \mathrm{N}^{\prime}\right)}
$$

Since $(\nu c . B ; \mathrm{N})$ is the $\theta_{A}$-concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ we have that $A_{s}\left(\theta_{A} \sigma_{A}\right)^{\star}=\nu c . B$. Hence, we know that $A_{s}=\nu c . B_{s}$ for some process $B_{s}$ such that $B_{s}\left(\theta_{A} \sigma_{A}\right)^{\star}=B$. Since $\left(\nu c . B_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ is well-formed, we know that $\mathcal{C}_{A}=\nu c \cdot \mathcal{C}_{B}$ for some well-formed constraint system $\mathcal{C}_{B}$. Let $\mathrm{N}_{s}^{\prime \prime}$ be the symbolic naming environment such that

$$
\mathrm{N}_{s}^{\prime \prime}(u)= \begin{cases}\mathrm{N}^{\prime \prime}(u) & \text { if } u \in \mathcal{N} \cup \mathcal{X} \\ \mathrm{~N}_{s}(u) & \text { if } u \in \mathcal{Y}\end{cases}
$$

Firstly, we have that $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime \prime}\right)$ is well-formed. We have also that $\theta_{A} \in$ $\operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime \prime}\right)$. We can apply our induction hypothesis on $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime \prime}\right)$, $\theta_{A},\left(B ; \mathrm{N}^{\prime \prime}\right) \xrightarrow{\text { out }(a, c)} i\left(B^{\prime} ; \mathrm{N}^{\prime \prime \prime}\right)$. We deduce that there exist a well-formed symbolic process $\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime \prime \prime}\right)$, a substitution $\theta_{B}^{\prime}$ and a label $\alpha_{s}^{B}$ such that

1. $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime \prime}\right) \xrightarrow{\alpha_{s}^{B}}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime \prime \prime}\right)$ and $\mathrm{N}^{\prime \prime \prime}=\mathrm{N}_{s}^{\prime \prime \prime}\left[\mathrm{N}_{s}^{\prime \prime \prime}-1(\mathrm{c}) \mapsto \mathrm{b}\right]$,
2. $\theta_{B}^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime \prime \prime}\right)$ and $\left.\theta_{B}^{\prime}\right|_{c v\left(\mathcal{C}_{B}\right)}=\theta_{A}$ and $\left.\theta_{B}^{\prime}\right|_{c v\left(\mathcal{C}_{B}\right)}=\theta_{B}^{\prime}$ since constraint variables increase only after an input action.
3. $B_{s}^{\prime}\left(\theta_{A} \sigma_{A}\right)^{\star}=B^{\prime}$, i.e., $\left(B^{\prime} ; \mathrm{N}^{\prime \prime \prime}\right)$ is the $\theta_{B}^{\prime}$-concretization of $\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime \prime \prime}\right)$ and
4. $\alpha_{s}^{B} \theta_{A}=\operatorname{out}(a, c)$. Note also that since $c \notin \operatorname{names}\left(\operatorname{img}\left(\theta_{A}\right)\right)$, we have that $\alpha_{s}^{B}=\operatorname{out}(u, c)$ for some metavariable $u$ such that $u \theta_{A}=a$.

Let $A_{s}^{\prime}=B_{s}^{\prime}\left\{{ }^{d} / c\right\}, \mathcal{C}_{A}^{\prime}=\nu d .\left(\mathcal{C}_{B}^{\prime}\left\{{ }^{d} / c\right\}\right), \mathrm{N}_{s}^{\prime}=\mathrm{N}_{s}^{\prime \prime \prime}[c \mapsto \mathrm{~b}, d \mapsto \mathrm{f}]$. Let $\theta_{A}^{\prime}=\theta_{B}^{\prime}=\theta_{A}$ and $\alpha_{s}=\nu d$.out $(u, d)$. We have that

1. $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \xrightarrow{\alpha_{s}}{ }_{s}\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$. Indeed, we have that

$$
\frac{\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime \prime}\right) \xrightarrow{\text { out }(u, c)}{ }_{s}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime \prime \prime}\right)}{\left(\nu c . B_{s} ; \nu c . \mathcal{C}_{B} ; \mathrm{N}_{s}\right) \xrightarrow{\nu d . o u t(u, d)}\left(B_{s}^{\prime}\left\{{ }^{d} / c\right\} ; \nu d .\left(\mathcal{C}_{B}^{\prime}\left\{{ }^{d} / c\right\}\right) ; \mathrm{N}_{s}^{\prime}\right)}
$$

2. $\theta_{A}^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ since $\theta_{B}^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime \prime \prime}\right)$ and $c, d \notin \operatorname{names}\left(\operatorname{img}\left(\theta_{B}^{\prime}\right)\right)$. We have also that $\left.\theta_{A}^{\prime}\right|_{c v\left(\mathcal{C}_{A}\right)}=\left.\theta_{B}^{\prime}\right|_{c v\left(\mathcal{C}_{B}\right)}=\theta_{A}$,
3. We have that $A_{s}^{\prime}\left(\theta_{A}^{\prime} \sigma_{A}^{\prime}\right)^{\star}=\left(B_{s}^{\prime}\{d / c\}\right)\left(\theta_{A} \sigma_{A}^{\prime}\right)^{\star}=\left(B_{s}^{\prime}\{d / c\}\right)\left(\theta_{A}\left(\sigma_{A}\left\{{ }^{d} / c\right\}\right)\right)^{\star}=$ $B_{s}^{\prime}\left(\theta_{A} \sigma_{A}\right)^{\star}\left\{{ }^{d} / c\right\}=B^{\prime}\left\{{ }^{d} / c\right\}=A^{\prime}$, i.e., $\left(A^{\prime} ; \mathrm{N}^{\prime}\right)$ is the $\theta_{A^{\prime}}^{\prime}$-concretization of $\left(A^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$,
4. $\alpha_{s} \theta_{A}^{\prime}=(\nu d . o u t(u, d)) \theta_{A}=\nu d . o u t(a, d)=\alpha$.

Case $\mathrm{SCOPE}_{i}$ : In such a case, we have that the proof tree witnessing the fact that $(A ; \mathrm{N}) \xrightarrow{\alpha}\left(A^{\prime} ; \mathrm{N}^{\prime}\right)$ ends with an application of the following inference rule

$$
\frac{\left(B ; \mathrm{N}^{\prime \prime}\right) \xrightarrow{\alpha}_{i}\left(B^{\prime} ; \mathrm{N}^{\prime \prime \prime}\right)}{(\nu n \cdot B ; \mathrm{N}) \xrightarrow[\rightarrow]{\alpha}_{i}\left(\nu n \cdot B^{\prime} ; \mathrm{N}^{\prime}\right)} \quad \text { with } n \text { does not occur in } \alpha
$$

Hence, we know that there exist a name $n$, a label $\alpha$ such that $n$ does not occur in $\alpha$ and two intermediate extended processes $\left(B ; \mathrm{N}^{\prime \prime}\right)$ and $\left(B^{\prime} ; \mathrm{N}^{\prime \prime \prime}\right)$ such that $A=\nu n \cdot B, A^{\prime}=\nu n \cdot B^{\prime}$ and $\left(B ; \mathrm{N}^{\prime \prime}\right) \xrightarrow{\alpha}\left(B^{\prime} ; \mathrm{N}^{\prime \prime \prime}\right)$. Since $(\nu n . B ; \mathrm{N})$ is the $\theta_{A}$-concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ we have that $A_{s}\left(\theta_{A} \sigma_{A}\right)^{\star}=\nu n . B$. Hence, we know that $A_{s}=\nu n . B_{s}$ for some process $B_{s}$ such that $B_{s}\left(\theta_{A} \sigma_{A}\right)^{\star}=B$. Since $\left(\nu n . B_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ is well-formed, we know that $\mathcal{C}_{A}=\nu n . \mathcal{C}_{B}$ for some well-formed constraint system $\mathcal{C}_{B}$. Let $\mathrm{N}_{s}^{\prime \prime}$ be the symbolic naming environment such that

$$
\mathrm{N}_{s}^{\prime \prime}(u)= \begin{cases}\mathrm{N}^{\prime \prime}(u) & \text { if } u \in \mathcal{N} \cup \mathcal{X} \\ \mathrm{~N}_{s}(u) & \text { if } u \in \mathcal{Y} .\end{cases}
$$

Firstly, we have $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime \prime}\right)$ is well-formed. By Lemma B. 1 we have $\theta_{A} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime \prime}\right)$. We apply our induction hypothesis on $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime \prime}\right)$, $\theta_{A},\left(B ; \mathrm{N}^{\prime \prime}\right) \xrightarrow{\alpha}\left(B^{\prime} ; \mathrm{N}^{\prime \prime \prime}\right)$. We deduce that there exist a well-formed symbolic process $\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime \prime \prime}\right)$, a substitution $\theta_{B}^{\prime}$ and a label $\alpha_{s}^{B}$ such that:

1. $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime \prime}\right) \xrightarrow{\alpha_{s}^{B}}{ }_{s}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime \prime \prime}\right)$ and $\mathrm{N}^{\prime \prime \prime}=\left.\mathrm{N}_{s}^{\prime \prime \prime}\right|_{\mathcal{N} \cup \mathcal{X}}$.
2. $\theta_{B}^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime \prime \prime}\right)$ and $\left.\theta_{B}^{\prime}\right|_{c v\left(\mathcal{C}_{B}\right)}=\theta_{A}$,
3. $B_{s}^{\prime}\left(\theta_{B}^{\prime} \sigma_{B}^{\prime}\right)^{\star}=B^{\prime}$, i.e., $\left(B^{\prime} ; \mathrm{N}^{\prime \prime \prime}\right)$ is the $\theta_{B}^{\prime}$-concretization of $\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime \prime \prime}\right)$,
4. $\alpha_{s}^{B} \theta_{B}^{\prime}=\alpha$.

Let $A_{s}^{\prime}=\nu n . B_{s}^{\prime}, \mathcal{C}_{A}^{\prime}=\nu n \cdot \mathcal{C}_{B}^{\prime}, \mathrm{N}_{s}^{\prime}=\mathrm{N}_{s}^{\prime \prime \prime}[n \mapsto \mathrm{~b}]$. Let $\theta_{A}^{\prime}=\theta_{B}^{\prime}$ and $\alpha_{s}=\alpha_{s}^{B}$. Note that the symbolic process $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ is well-formed. Moreover, we have

1. $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \xrightarrow{\alpha_{s}}\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$. Indeed, we have that

$$
\frac{\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}^{\prime \prime}\right){\xrightarrow{\alpha_{s}}}_{s}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime \prime \prime}\right)}{\left(\nu n \cdot B_{s} ; \nu n \cdot \mathcal{C}_{B} ; \mathrm{N}_{s}\right){\xrightarrow{\alpha_{s}}}_{s}\left(\nu n \cdot B_{s}^{\prime} ; \nu n \cdot \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)}
$$

2. $\theta_{A}^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ by Lemma B. 1 since $\theta_{B}^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime \prime \prime}\right)$ and $n \notin$ names $\left(\operatorname{img}\left(\theta_{B}^{\prime}\right)\right)$. We have also that $\left.\theta_{A}^{\prime}\right|_{c v\left(\mathcal{C}_{A}\right)}=\left.\theta_{B}^{\prime}\right|_{c v\left(\mathcal{C}_{B}\right)}=\theta_{A}$,
3. We have that $A_{s}^{\prime}\left(\theta_{A}^{\prime} \sigma_{A}^{\prime}\right)^{\star}=\left(\nu n . B_{s}^{\prime}\right)\left(\theta_{B}^{\prime} \sigma_{B}^{\prime}\right)^{\star}=\nu n . B^{\prime}=A^{\prime}$, i.e., $\left(A^{\prime} ; \mathrm{N}^{\prime}\right)$ is the $\theta_{A}^{\prime}$-concretization of $\left(A_{s}^{\prime} ; \mathcal{C}_{A} ; \mathrm{N}_{s}^{\prime}\right)$,
4. $\alpha_{s} \theta_{A}^{\prime}=\left(\alpha_{s}^{B}\right) \theta_{B}^{\prime}=\alpha$.

Case $\mathrm{PAR}_{i}$ : In such a case, we have that the proof tree witnessing the fact that $(A ; \mathrm{N}) \xrightarrow{\alpha} i\left(A^{\prime} ; \mathrm{N}^{\prime}\right)$ ends with an application of the following inference rule.

$$
\frac{(B ; \mathrm{N}) \xrightarrow{\alpha \psi(D)}_{i}\left(B^{\prime} ; \mathrm{N}^{\prime}\right)}{(B \mid D ; \mathrm{N}) \xrightarrow{\alpha}_{i}\left(B^{\prime} \mid D ; \mathrm{N}^{\prime}\right)}
$$

Since $\left(A_{s} ; \mathrm{N}\right)$ is the $\theta_{A}$-concretization of $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ we have that $A=B \mid$ $D=A_{s}\left(\theta_{A} \sigma_{A}\right)^{\star}$. Hence, we know that

- $A_{s}=B_{s} \mid D_{s}$ for some processes $B_{s}$ and $D_{s}$ such that
- $B_{s}\left(\theta_{A} \sigma_{A}\right)^{\star}=B$ and $D_{s}\left(\theta_{A} \sigma_{A}\right)^{\star}=D$.

Since $\left(B_{s} \mid D_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right)$ is well-formed, we deduce that $\mathcal{C}_{A}=\mathcal{C}_{B} \mid \psi\left(D_{s}\right)$ for some well-formed constraint system $\mathcal{C}_{B}$. We have that $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right)$ is wellformed. Let $\theta_{B}=\left(\theta_{A} \psi\left(D_{s}\right)\right)^{\star}$. By Lemma B. 1 we have that $\theta_{B} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B} ; \mathrm{N}_{s}\right)$. We can apply our induction hypothesis. We deduce that there exists a wellformed symbolic process $\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$, a substitution $\theta_{B}^{\prime}$ and a label $\alpha_{s}^{B}$ such that:

1. $\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right) \xrightarrow{\alpha_{s}^{B}}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ and

$$
\mathrm{N}_{s}^{\prime}(u)= \begin{cases}\mathrm{N}^{\prime}(u) & \text { if } u \in \mathcal{N} \cup \mathcal{X} \\ \mathrm{~N}_{s}(u) & \text { if } u \in \mathcal{Y}\end{cases}
$$

2. $\theta_{B}^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ and $\left.\theta_{B}^{\prime}\right|_{c v\left(\mathcal{C}_{B}\right)}=\theta_{B}$,
3. $B_{s}^{\prime}\left(\theta_{B}^{\prime} \sigma_{B}^{\prime}\right)^{\star}=B^{\prime}$, i.e., $\left(B^{\prime} ; \mathrm{N}^{\prime}\right)$ is the $\theta_{B}^{\prime}$-concretization of $\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$,
4. $\alpha_{s}^{B} \theta_{B}^{\prime}=\alpha \psi(D)$.

Let $A_{s}^{\prime}=B_{s}^{\prime}\left|D_{s}, \mathcal{C}_{A}^{\prime}=\mathcal{C}_{B}^{\prime}\right| \psi\left(D_{s}\right)$. To define $\theta_{A}^{\prime}$, we distinguish two cases.

1. Either $\alpha$ is of the form $i n(c, M)$ and $\alpha_{s}^{B}=i n(u, y)$ for some metavariable $u$ and some variable $y$ with $\mathrm{N}_{s}(y)=\mathrm{n}$ such that $u \theta_{A}=u \theta_{B}=c$. In such a case, let $\theta_{A}^{\prime}=\theta_{A} \cup\{y \mapsto M\}$. Moreover, as $\theta_{B}=\left(\theta_{A} \psi\left(D_{s}\right)\right)^{\star},\left.\theta_{B}^{\prime}\right|_{c v\left(\mathcal{C}_{B}\right)}=$ $\theta_{B}, \alpha_{s}^{B} \theta_{B}^{\prime}=\alpha \psi(D)$ and $D_{s}\left(\theta_{A} \sigma_{A}\right)^{\star}=D$ we have that $\theta_{B}^{\prime}=\left(\theta_{A}^{\prime} \psi\left(D_{s}\right)\right)^{\star}$.
2. Otherwise, $\theta_{A}^{\prime}=\theta_{A}$. Moreover in this case we have that $\theta_{B}^{\prime}=\theta_{B}=$ $\left(\theta_{A} \psi\left(D_{s}\right)\right)^{\star}=\left(\theta_{A}^{\prime} \psi\left(D_{s}\right)\right)^{\star}$.

Let $\alpha_{s}=\alpha_{s}^{B}$. Note that the symbolic process $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ is well-formed. Moreover, we have

1. $\left(A_{s} ; \mathcal{C}_{A} ; \mathrm{N}_{s}\right) \xrightarrow{\alpha_{s}}\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$. Indeed, we have that

$$
\frac{\left(B_{s} ; \mathcal{C}_{B} ; \mathrm{N}_{s}\right){\xrightarrow{\alpha_{s}}}_{s}\left(B_{s}^{\prime} ; \mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)}{\left(B_{s}\left|D_{s} ; \mathcal{C}_{B}\right| \psi\left(D_{s}\right) ; \mathrm{N}_{s}\right){\xrightarrow{\alpha_{s}}}_{s}\left(B_{s}^{\prime}\left|D_{s} ; \mathcal{C}_{B}^{\prime}\right| \psi\left(D_{s}\right) ; \mathrm{N}_{s}^{\prime}\right)}
$$

2. We have to show that $\theta_{A}^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$. As $\theta_{B}^{\prime}=\left(\theta_{A}^{\prime} \psi\left(D_{s}\right)\right)^{\star} \in$ $\operatorname{Sol}\left(\mathcal{C}_{B}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$ we have by Lemma B. 1 that $\theta_{A}^{\prime} \in \operatorname{Sol}_{\mathrm{E}}\left(\mathcal{C}_{B}^{\prime} \mid \psi\left(D_{s}\right) ; \mathrm{N}_{s}^{\prime}\right)$. It is clear that we have also $\left.\theta_{A}^{\prime}\right|_{c v\left(\mathcal{C}_{A}\right)}=\theta_{A}$.
3. We have that $A_{s}^{\prime}\left(\theta_{A}^{\prime} \sigma_{A}^{\prime}\right)^{\star}=\left(B_{s}^{\prime} \mid D_{s}\right)\left(\theta_{A}^{\prime} \sigma_{A}^{\prime}\right)^{\star}=B_{s}^{\prime}\left(\theta_{A}^{\prime} \sigma_{A}^{\prime}\right)^{\star} \mid D_{s}\left(\theta_{A}^{\prime} \sigma_{A}^{\prime}\right)^{\star}=$ $B_{s}^{\prime}\left(\theta_{B}^{\prime} \sigma_{B}^{\prime}\right)^{\star}\left|D_{s}\left(\theta_{A} \sigma_{A}\right)^{\star}=B^{\prime}\right| D=A^{\prime}$, i.e., $\left(B^{\prime} \mid D ; \mathrm{N}^{\prime}\right)$ is a $\theta_{A}^{\prime}$ concretization of $\left(A_{s}^{\prime} ; \mathcal{C}_{A}^{\prime} ; \mathrm{N}_{s}^{\prime}\right)$,
4. In the case where $\alpha=i n(c, M)$, we have that $\alpha_{s} \theta_{A}^{\prime}=i n(u, y) \theta_{A}^{\prime}=$ in $(c, M)=\alpha$. Otherwise, the equality holds since $\psi(D)$ and $\psi\left(D_{s}\right)$ do not affect variables which occurs in a label since those variables are of type channel.

Lastly, we can deal with the rule $\mathrm{STRUCT}_{i}$ by relying on our Proposition B.4.
This allows us to conclude.


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